

National Institute of Technology Karnataka, Surathkal Department of Electronics and Communication Engineering

Final Report: IP mini project

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Title of the Project

Industry Welding defects in radiographic images



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Objectives

- The main objective of this project is to take the X-rays from the industry and determine the type of defect.
- We are going to deal with 30 types of defects.(roughly)
- Few of them are:
- 1) Toe Crack
- 2) Transverse Crack
- 3) Crater Crack
- 4) Root Crack

- 5) Weld Spatter
- 6) Undercut
- 7) Excess Cap
- 8) Concave Crack

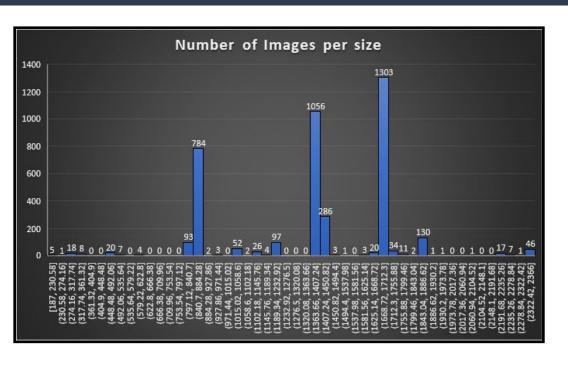
Technology Stack (needed)

Tech Stack used(to be used) in this project:

- 1. OpenCV (module)
- 2. Python (language)
- 3. Jupyter Notebook(ide)
- 4. Keras, Tensorflow
- 5. ResNet-50 model architecture
- 6. Inception_V3
- 7. Tensorflow hub
- 8. Data set received from the Industry through our guide deepu

Methodology

Results



Task 1

Analysing the data set for number of vertically stacked images.

As the number of X-rays that are stacked in each image is different.

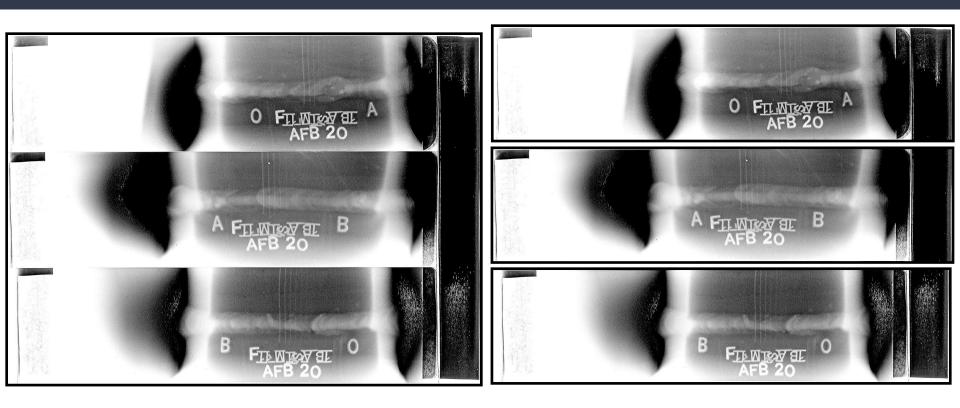
But what we observed is that the based on the bin analysis shown on the left there were 4 classes, single staked, doubly, triple and quadruple stacked.

Methodology

Task 2

- Splitting the images. And taking all the lines from above that horizontal line we were able to split.
- We initially tried to determine the horizontal line using hough transform and morphology but It worked only as guidance to see the location of stacked images
- Then we noticed a symmetry among the images that each were split equally among each other so we developed a function that can be seen in the next slide how we cut the images in a systematic way.

Spliting Images



Algo for task-2

Task 2

- There were 2 different methods to finding horizontal lines the images
- The first one was using edge detection and hough transform
- The second one was using morphology, This gave us a better result
- For splitting the images each bin had a fixed number of images that were stacked so to the function that we developed we passed the number of x-rays present and the bin limits so we find images only present in the bin and we cut the images so our program was flexible.

Methodology

Task 3

- Now after the data is split we need to start classifying the images. But the
 problem at hand is that we don't have labeled data, so we decided to tackle this
 problem by using the 30 images that were given to us, as sample defects as
 labels along with the 30 non defective images and the feature vectors were
 found for all the images
- But before we could use the images we noticed that the images needed to be resized as the model takes in around 299*299. We initially just resized the images directly from the original size to the target size. Results in next slide.

Getting proper size

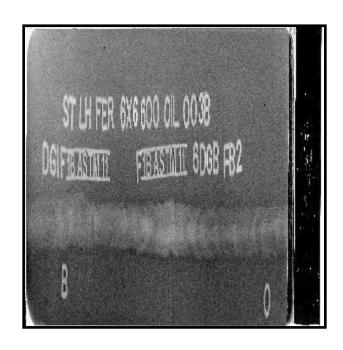


Fig: Resized from original image

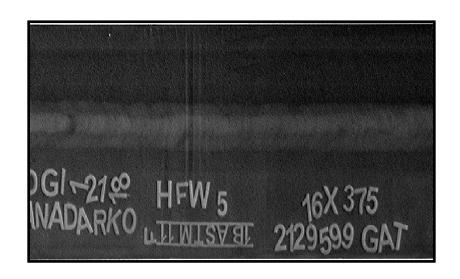
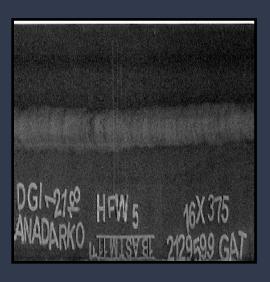


Fig: Cut from original image

Results



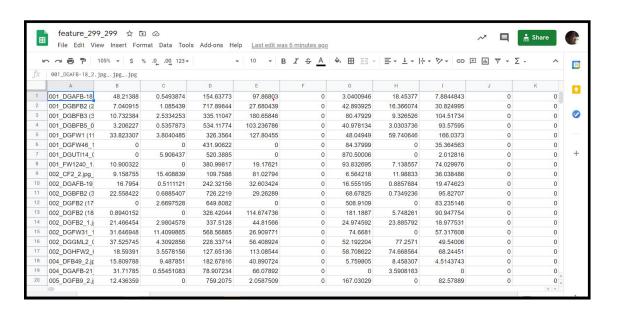
- So what observed was that the most information required for us was in the middle region of the image, so we decided to cut the image to about three different sizes.
- After which we resized to the required size of 299*299 and 299*500.
- This way the most amount of data can be in the image as well as we can run the model.
- Now the data is ready for feature extraction.

Methodology

Task-4

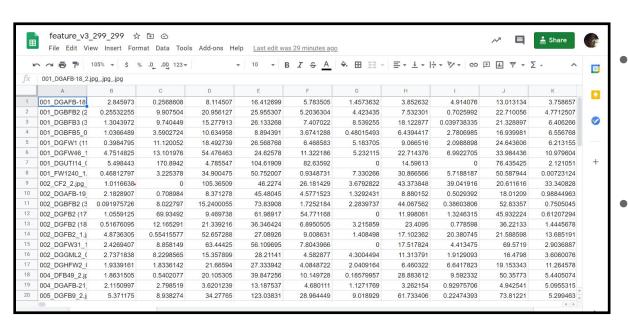
- We do not have labeled data which makes it hard to progress with the project, we will be
 getting the labeled data but that may take some time, so we have decided to use transfer
 learning and determine the features from a pretrained model, upon which we will run 100
 test images and find the mean least square error from each label image and the one with
 the least distance will be considered as the classified one
- 2 models were obtained from the Tensorflow hub which are called resnet_v2_50 and inception_v3 which has been trained on imagenet data set.
- both give us a feature vector of size 2048
 Links :
- https://tfhub.dev/google/imagenet/resnet_v2_50/feature_vector/4
- https://tfhub.dev/google/imagenet/inception_v3/feature_vector/4

Feature vector of Resnet50



- On the left are the first 10 Feature vectors of the first 20 sample images we took.
- These are the feature vectors obtained for images of size 299*299 we have not displayed the feature vectors for the other set of images as it will be redundant, but have been included in the report.
- From quick scan through the vectors it was observed that Resnet50 had lots of columns with 0 values, this makes me believe that that it was successful in determining the features properly

Feature vector of InceptionV3



- On the left are the first 10 Feature vectors of the first 20 sample images we took.
- These are the feature vectors obtained for images of size 299*299 we have not displayed the feature vectors for the other set of images as it will be redundant, but have been included in the report.
- From quick scan through the vectors it was observed that Inceptionv3 had values in the columns with lower values, this makes me believe that that it was not successful in determining the features properly, as compared to Resnet50.

Distance or mean square error

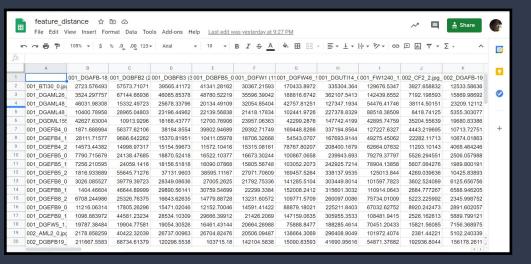
```
disfeatures=[]
for i in range(0,100):
    dis=[]
    for j in range(0,73):
        add=0
        for k in range(0,2047):
        sub = (12[i][0][k]-1[j][0][k])**2
        add = add + sub
        add=add/2048
        dis.append(add)
        disfeatures.append(dis)
```

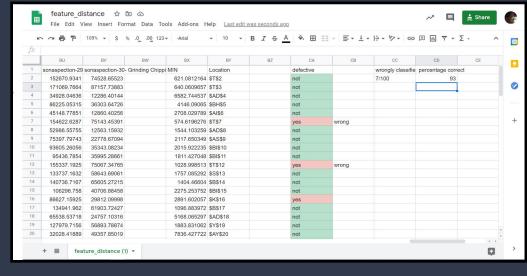
 On the left we have a code snippet of the code used for finding the distance or the mean square error.

So each test image is taken which has 2048 features, similarly the sample labels have 2048 features, the respective features difference is found and then squared and it is added into a sum. This sum keep on increasing until the last features are subtracted squared and added.

The final sum is divided by 2048 as to get an average value and this is repeated for the next sample image. And these process are repeated for all test images.

 Then the least of the distances is taken and it is classified as that image, and then we compared the images to see if they were right and wrong

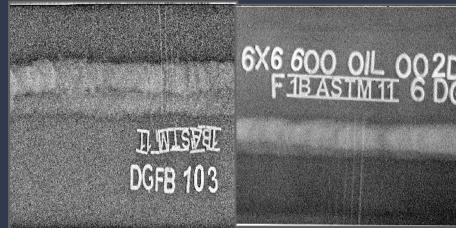




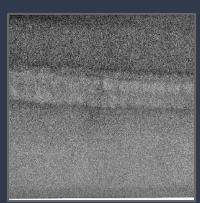
Final Results

	299*299_resnet50	299*500_resnet50	299*299_inception_v3	299*500_inception_v3
#Defective samples	21	24	21	24
#Non defective	79	76	79	76
#Wrongly classified	7	6	8	6
Accuracy %	93	94	92	94





Correctly Classified



Sample Defect

Wrongly Classified

Confusion Matrix

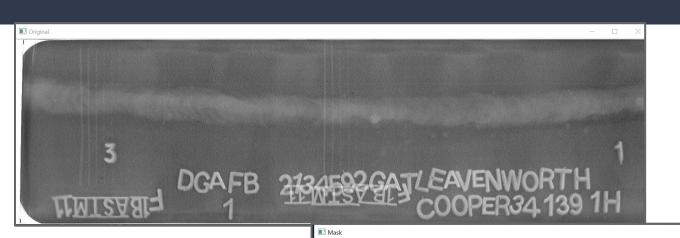
299*299_Resnet50	Predicted Non-Defective	Predicted Defective
Actual Non-Defective	79	0
Actual Defective	7	14

299*500_Resnet50	Predicted Non-Defective	Predicted Defective
Actual Non-Defective	76	0
Actual Defective	6	18

299*299_Inception_v3	Predicted Non-Defective	Predicted Defective
Actual Non-Defective	79	0
Actual Defective	8	13

299*500_Inception_v3	Predicted Non-Defective	Predicted Defective
Actual Non-Defective	76	0
Actual Defective	6	18

Future work



We look to remove the letters present on the images so that they do not wrongly classify the image

Reference paper links

- 1. Tensorflow hub from google
- 2. Keras from google
- 3. Imagenet models- ResNet50,Inception_v3
- 4. Moghaddam, Alireza Azari (2015). [IEEE 2015 2nd International Conference on Knowledge-Based Engineering and Innovation (KBEI) Tehran, Iran (2015.11.5-2015.11.6)] 2015 2nd International Conference on Knowledge-Based Engineering and Innovation (KBEI) Image processing technique for classification of linear welding defects..

Thank You!!