

# 🌟 **MODULE 3 – Knowledge Representation, Reasoning & Knowledge-Based Agents**

***(VERY SIMPLE + DETAILED)***

## ✅ **1. What is Knowledge Representation (KR)?**

KR means **how a computer stores knowledge so it can think like humans.**

Humans store knowledge in:

- Brain
- Notes
- Photos
- Experience

Computers store knowledge in:

- Logic
- Rules
- Graphs
- Semantic networks
- Databases

**Purpose of KR:**

- To let AI understand the world
- To let AI make decisions

- To let AI reason (think)
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## ✓ 2. Types of Knowledge Representation

### A) Propositional Logic (Simple Statements)

- Used to represent simple TRUE/FALSE facts.
- Example:  
"It is raining" = True  
"2+2=5" = False

Uses symbols like P, Q, R.

### B) First Order Logic (FOL)

More powerful than propositional logic.

It can represent:

- Objects
- Relations
- Functions

Example:

Father(Ram, Rohan)

Means: Ram is father of Rohan.

### C) Semantic Networks

Knowledge is stored in a **graph**:

- Nodes = concepts
- Links = relationships

Example:

Animal

↓ (is-a)

Bird

↓ (is-a)  
Sparrow

Useful for inheritance:  
If Bird can fly → Sparrow can fly.

## D) Rule-Based Knowledge (IF-THEN rules)

Example:  
IF fever AND cough  
THEN flu

Used in expert systems.

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## ✓ 3. Knowledge-Based Agents (KBA)

A Knowledge-Based Agent works like a **thinking machine**.

**It has:**

- ✓ Knowledge Base (KB) → stores facts, rules
- ✓ Inference Engine → applies logic
- ✓ TELL-ASK-ACT cycle

**Working:**

- 1 **TELL** – Add new information to KB
- 2 **ASK** – Ask KB: “What should I do?”
- 3 **ACT** – Perform that action

Example:  
A medical agent gets symptoms → finds disease → gives advice.

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## ✓ 4. Inference – How AI thinks?

### A) Forward Chaining (Fact → Goal)

- Starts from known facts
- Applies rules
- Reaches conclusion

Example:

Rule: If Bird  $\rightarrow$  CanFly

Fact: Bird(Tweety)

Conclusion: Tweety can fly

Used in expert systems.

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## **B) Backward Chaining (Goal $\rightarrow$ Facts)**

- Starts from goal
- Checks which rules support goal
- Moves backward until facts match

Example:

Goal: Can Tweety fly?

Rule: Bird  $\rightarrow$  Fly

Check: Is Tweety a bird?

Yes  $\rightarrow$  proven

Used in PROLOG.

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## **5. Inference Rules Explained Simple**

### **Modus Ponens:**

If  $P \rightarrow Q$

And P is true

Then Q is true

### **Modus Tollens:**

If  $P \rightarrow Q$

And Q is false

Then P is false

### **Resolution:**

Used for proving things by eliminating contradictions.

Very important for exams.

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## MODULE 3 – Final Summary

- KR = storing knowledge
  - KBA = agent with knowledge + reasoning
  - Forward chaining = facts → goal
  - Backward chaining = goal → facts
  - Semantic nets = graph of concepts
  - Rules = IF-THEN
  - Inference rules = ways of reasoning
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## MODULE 4 – Artificial Neural Networks (ANN)

***(DETAILED + SIMPLE)***

### 1. What is ANN?

ANN is a model inspired by the **human brain**.

Human brain → neurons

ANN → artificial neurons (perceptrons)

ANN learns from examples.

Example:

You show many cat images → ANN learns what a cat looks like.

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### 2. Structure of ANN

#### 1. Input Layer

Takes raw inputs.  
Example: pixel values of image.

## 2. Hidden Layers

They do calculations and feature extraction.  
More hidden layers = more learning power.

## 3. Output Layer

Gives final result.  
Example:  
“Cat” or “Dog”

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## 3. Artificial Neuron (Perceptron)

A perceptron takes:

- Inputs
- Weights
- Bias
- Applies activation
- Gives output

Formula:

$$Y = f(w_1 x_1 + w_2 x_2 + \dots + b)$$

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## 4. Types of Neural Networks

### Single-Layer NN

- Only one layer
- Simple problems

- Uses Perceptron Rule
- Can only solve linear problems

## Multi-Layer NN

- Has hidden layers
  - Can learn complex patterns
  - Uses Backpropagation
  - Used everywhere today
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## ✓ 5. Activation Functions (Why needed?)

They add **non-linearity** → helps ANN learn complex patterns.

### a) Sigmoid

Smooth S-shaped

Output: 0 to 1

Used in binary classification.

### b) Tanh

Output: -1 to 1

Better than sigmoid because it is zero-centered.

### c) ReLU

If  $x < 0 \rightarrow 0$

If  $x > 0 \rightarrow x$

Fastest, most used.

### d) Softmax

Used for multi-class classification.

Turns numbers into probabilities.

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## ✓ 6. Perceptron Learning Rule

```
[  
w = w + \eta (t - o) x  
]  
[  
b = b + \eta (t - o)  
]
```

Where:

- $t$  = target output
- $o$  = predicted output
- $\eta$  = learning rate

Perceptron learns by fixing its mistakes.

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## **MODULE 4 – Final Summary**

- ANN = small artificial brain
  - Neuron = weighted sum + activation
  - Layers = input → hidden → output
  - Activation = decides firing
  - Perceptron = simplest ANN
  - Softmax = multiclass
  - ReLU = fastest
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## **MODULE 5 – Uncertainty, Fuzzy, Bayesian Networks**

***(DETAILED + SIMPLE)***



## 1. Why uncertainty occurs?

Because we don't always have perfect information.

Examples:

- Weather predictions
  - Medical diagnosis
  - Stock market
  - Human behaviour
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## 2. Non-Monotonic Reasoning (NMR)

Normal logic: once true  $\rightarrow$  always true

NMR: truth can change with new info.

Example:

"Birds can fly"

But new fact: "Penguin is a bird"  $\rightarrow$  cannot fly

Used for real-world reasoning.

NMR Types:

- Default Logic
  - Circumscription
  - Autoepistemic Logic
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## 3. Fuzzy Logic (Simple)

Fuzzy logic deals with **partial truth**.

Example:

Is a person tall?

Height 150 cm  $\rightarrow$  0.2

Height 170 cm  $\rightarrow$  0.6

Height 190 cm  $\rightarrow$  0.9

Used in:

- AC
- Washing machine
- Fan speed controller

Uses **membership functions** (triangle, trapezoid, Gaussian etc.)

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## 4. Probability & Bayes Theorem

Bayes helps us update our belief when new evidence comes.

Formula:

$$P(H|E) = \frac{P(E|H)P(H)}{P(E)}$$

Example:

Probability of disease increases when test is positive.

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## 5. Bayesian Networks (BN)

BN is a **graph showing cause → effect**.

**Example:**

Smoking → Lung Cancer → Cough

Pollution → Lung Cancer

**Components:**

- Nodes = variables
- Arrows = dependencies
- CPT = Conditional Probability Table for each node

Used in:

- ✓ Medical diagnosis
- ✓ Fault detection

- ✓ Machine learning
  - ✓ Decision making
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## **MODULE 5 – Final Summary**

- NMR = truth changes with new facts
  - Fuzzy logic = partial truth (0 to 1)
  - Probability = uncertain events
  - Bayes theorem = update beliefs
  - Bayesian networks = DAG of causes
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**Great Chandril!**

Here are the **FULL ANSWERS** for the Expected CT-2 Question Paper I gave you.  
The answers are written in simple language, exam-friendly, and exactly enough for full marks.

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## **SECTION – A (2 Marks Answers)**

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### **1. What is Knowledge Representation?**

Knowledge Representation (KR) is the method of storing knowledge inside a computer in a structured way so that the system can think, reason, and make decisions like humans.

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### **2. Define Knowledge-Based Agent.**

A Knowledge-Based Agent is an AI agent that uses a Knowledge Base (facts + rules) and an Inference Engine to decide what action to take.  
It works using TELL, ASK, ACT cycle.

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### **3. What is Forward Chaining?**

Forward Chaining is a data-driven reasoning method where we start from facts and apply rules to reach the goal.

Example:

If  $A \rightarrow B$ , and  $A$  is true  $\rightarrow B$  becomes true.

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### **4. What is Backward Chaining?**

Backward Chaining is a goal-driven reasoning method.

We start with the goal, and check what facts/rules can prove that goal.

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### **5. Define heuristic function in A\* search.**

A heuristic function  $h(n)$  is a guess of how close a node is to the goal.

It helps A\* search choose the best path faster.

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### **6. What is Hill Climbing?**

Hill Climbing is a local search method where the algorithm always moves to the next better (higher valued) state.

Problem: It may get stuck in local maxima.

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### **7. Define Perceptron.**

A Perceptron is the simplest artificial neuron used for binary classification.

It takes inputs, multiplies with weights, applies activation, and gives output.

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### **8. What is an Activation Function?**

Activation function decides whether a neuron should fire or not by converting the input into output.

Example: Sigmoid, ReLU, Tanh.

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### **9. Define Fuzzy Set.**

A fuzzy set allows partial membership between 0 and 1.

Example:

Height 180 cm  $\rightarrow$  Tall = 0.8 (not full true)

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## 10. What is Bayes Theorem?

Bayes Theorem updates probability when new evidence comes.

[

$$P(H|E) = \frac{P(E|H)P(H)}{P(E)}$$

]

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## SECTION – B (3 Marks Answers)

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## 11. Explain Semantic Networks with an example.

A semantic network is a graph-based representation of knowledge.

- Nodes = Concepts
- Edges = Relationships

Example:

Animal  $\rightarrow$  Bird  $\rightarrow$  Sparrow

Here, Bird “is-a” Animal, Sparrow “is-a” Bird.

It supports inheritance:

If Birds can fly  $\rightarrow$  Sparrow can fly.

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## 12. Difference between Propositional Logic & First Order Logic.

Propositional Logic	First Order Logic
Uses simple True/False statements	Represents objects & relationships
Less expressive	More expressive
Example: P = “It rains”	Example: Father(John, Alex)

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### 13. Explain TELL–ASK–ACT cycle.

A Knowledge-Based Agent works in this cycle:

1. TELL: Add new percepts/information to Knowledge Base.
  2. ASK: Agent queries KB for the best action.
  3. ACT: Agent performs the chosen action.
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### 14. Write a short note on Min–Max Algorithm.

Min-Max is used in two-player games.

- MAX player tries to maximize score.
- MIN player tries to minimize score.

It looks at all possible moves and chooses the best one.  
Often used with Alpha–Beta Pruning to make it faster.

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### 15. Explain A\* Search with formula.

A\* search selects node with lowest  $f(n)$  value:

$$\begin{bmatrix} f(n) = g(n) + h(n) \end{bmatrix}$$

- $g(n)$ : cost so far
- $h(n)$ : estimated cost

A\* is both optimal and complete, if heuristic is admissible.

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### 16. Describe structure of an Artificial Neuron.

It has:

- Inputs ( $x_1, x_2 \dots$ )

- Weights ( $w_1, w_2 \dots$ )
- Bias ( $b$ )
- Summation
- Activation function
- Output

Formula:

$$y = f(w \cdot x + b)$$


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## 17. Types of activation functions.

- Sigmoid: 0 to 1 output
  - Tanh:  $-1$  to  $+1$  output
  - ReLU:  $\max(0, x)$
  - Softmax: used for multiclass
  - Softplus: smooth version of ReLU
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## 18. Explain Perceptron Learning Rule.

Perceptron updates its weights based on error:

$$w = w + \eta (t - o)x$$

$$b = b + \eta (t - o)$$

Where

$t$  = target output,

$o$  = predicted output,

$\eta$  = learning rate.

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## 19. What is Non-Monotonic Reasoning?

Non-monotonic reasoning allows truth to change when new information comes.

Example:

Birds fly  $\rightarrow$  Tweety is bird  $\rightarrow$  Tweety flies

New info: Tweety is penguin  $\rightarrow$  cannot fly

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## 20. Explain Bayesian Network.

A Bayesian Network is a graphical model (DAG) representing probabilistic relationships.

- Nodes = Variables
- Edges = Causal links
- Each node has a CPT (Conditional Probability Table)

Example:

Smoking  $\rightarrow$  Lung Cancer  $\rightarrow$  Cough

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## SECTION – C (5 Marks Answers)

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## 21. Knowledge-Based Agent architecture with diagram.

A KBA has:

1. Knowledge Base (KB): Stores facts & rules
2. Inference Engine: Applies logic rules
3. TELL-ASK-ACT system:
  - TELL: add percept
  - ASK: query best action
  - ACT: perform action



**Levels:**

- **Knowledge Level** → what agent knows
- **Logical Level** → how knowledge is represented
- **Implementation Level** → actual data structures

**Working Example:**

**Agent enters Wumpus World → gets percept → adds to KB → queries KB → decides safe path.**

*A diagram is typically:*

**Environment → Percept → TELL → KB ↔ Inference Engine → ASK → Action selection → ACT → Environment**

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## **22. Forward & Backward Chaining with examples.**

**Forward Chaining:**

- **Data-driven**
- **Starts with facts**
- **Applies rules to reach new facts**

**Example:**

**Rule: If A → B**

**Fact: A**

**Conclusion: B**

**Used in Expert Systems.**

**Backward Chaining:**

- **Goal-driven**
- **Starts with desired goal**
- **Checks rules that support goal**

**Example:**

**Goal: B**

**Rule: If  $A \rightarrow B$**

**Check: Is A true? If yes  $\rightarrow$  proven**

**Used in PROLOG.**

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## **23. Single Layer vs Multi Layer Neural Network.**

### **Single Layer NN:**

- Only input + output
- Can solve only linearly separable problems
- Uses perceptron rule
- Simple, fast

### **Multi Layer NN:**

- Input + hidden + output
- Can solve complex, non-linear problems
- Uses backpropagation
- Basis of Deep Learning

### **Advantages of MLNN:**

- Learns complex patterns
- High accuracy
- Used in vision, NLP, speech

### **Disadvantages:**

- Slow
- Requires more data
- Hard to interpret

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## 24. A\* and AO\* Search Algorithm.

### A\* Search:

- Uses  $f(n) = g(n) + h(n)$
- Optimal & complete
- Widely used (GPS, games)

### AO\* Search:

- Works on AND–OR graphs
- Used when tasks require multiple sub-tasks
- Finds best combination of AND & OR paths
- Used in expert systems and hierarchical planning

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## 25. Fuzzy Logic, Membership Functions & Applications.

### Fuzzy Logic:

Allows partial truth (0 to 1).

Real-world not always true/false.

### Membership Functions:

- Triangular
- Trapezoidal
- Gaussian
- Singleton

### Applications:

- Air conditioners

- Washing machines
  - Traffic control
  - Robots
  - Medical decision systems
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## 26. Bayesian Networks (Structure + CPT + Example).

A Bayesian Network is:

- A Directed Acyclic Graph (DAG)
- Nodes represent variables
- Edges show cause → effect
- Each node has a CPT showing probability of the node given its parents

**Example:**

Smoking → Lung Cancer → Cough  
 Pollution → Lung Cancer

**CPT Example:**

Lung Cancer	Smokin g	Pollution	P
Yes	Yes	High	0.8
Yes	No	Low	0.2
No	Yes	High	0.4

Used for diagnosis, prediction, risk analysis.