$$\begin{aligned} & \mathcal{I}_{x}(1) & \underbrace{ \langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle } \\ & \mathcal{I}_{x}(i_{in}) & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \mathcal{I}_{x}(i_{in}) & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \mathcal{I}_{x}(i_{in}) & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \mathcal{I}_{x}(i_{in}) & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \mathcal{I}_{x}(i_{in}) & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \mathcal{I}_{x}(i_{in}) & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \mathcal{I}_{x}(i_{in}) & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \mathcal{I}_{x}(i_{in}) & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \mathcal{I}_{x}(i_{in}) & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \mathcal{I}_{x}(i_{in}) & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \mathcal{I}_{x}(i_{in}) & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle \Theta(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle G(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle G(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle G(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle G(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \underbrace{ \langle G_{x}(i_{unit}) = \mathbf{1}_{\{\langle G(i_{unit}), \mathcal{I}_{x} \rangle > 0\}} } \\ & \underbrace{ \langle G_{x}(i_$$