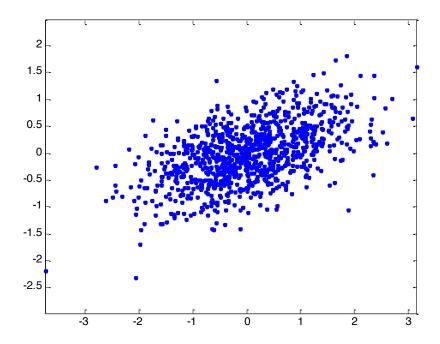
## **CSE 5524 – Homework #0**

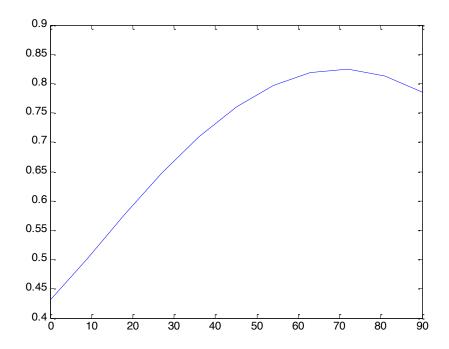
1/1/1900 John Smith

- 1) Test MATLAB's ability to load data from a text file. Use data.txt from the class webpage.
- 2) Plot the data, which consists of x,y-vectors with one vector per row. What can you say about the data from its appearance?



The data looks like it might be Gaussian-distributed but the variance in non-uniform and skewed.

- 3) Compute the dot product of all data vectors with the following vector. Then compute the mean of the absolute values of all the dot products. Use for loops. The mean was 0.4309.
- 4) Now compute the same value using MATLAB's vector arithmetic.
- **5)** Calculate the mean dot products for a number of vectors with varying angles. avgs=[ 0.4309 0.5020 0.5767 0.6474 0.7097 0.7598 0.7968 0.8194 0.8251 0.8136 0.7845 ]
- 6) Plot the mean values as a function of angle. What does this tell you about the variance of the data?



The direction of maximum variance for the data is where the plot peaks, roughly 70 degrees.

7) Turn in all code, test images, printouts of images, and discussion of results. Make a HW0.m script to do the above tasks and call needed functions. Upload your code and selected images to Carmen.

```
% John Smith
% CSE5524 - HW0
% 1/1/1900
% Problem 1
data = load('data.txt');
% Problem 2
plot(data(:,1),data(:,2),'.');
axis equal;
%print -dpng 'output/problem1.png'
print -dmeta 'output/problem1.emf' %Saving figure here to include in report
pause;
% Problem 3
vector=[ 0 1 ];
avg=0;
for j = 1:size(data,1)
 dot=0;
 for i = 1:2
  dot=dot+vector(i)*data(j,i);
 end
 avg=avg+abs(dot);
end
```

```
avg=avg/size(data,1)
% Problem 4
avg=mean(abs(sum(repmat(vector,size(data,1),1).*data,2)))
% Problem 5
vectors=[ sin(pi*(0:10)/20); cos(pi*(0:10)/20) ]';
avgs=zeros(1,size(vectors,1));
% % VERY SLOW
% for k = 1:size(vectors,1)
% avg=0;
% for j = 1:size(data,1)
%
    dot=0;
%
    for i = 1:2
      dot=dot+vectors(k,i)*data(j,i);
%
%
    end
%
    avg=avg+abs(dot);
% end
% avgs(k)=avg/size(data,1);
% end
```