

Updating TOPLATS with Fortran 2003

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1 Introduction

Land surface hydrologic models are used to simulate the interaction between the atmosphere and land surface. Their main objective is to model the water and energy balances and also to accurately partition the surface fluxes. Their ability to simulate these fluxes from limited data is key for monitoring the hydrologic cycle at continental and global scales. One of the models used at a regional scale is TOPLATS which was developed at Princeton University during the 1990's. Time has shown that this model is an excellent bridge between coarse scale models and very fine resolution models, making it a candidate to replace coarse scale models to study global hydrology. This is also due, in part, to the large increase in computational power over the past two decades.

The model was originally written in Fortran 77 and it falls along the lines of "spaghetti code". It was never developed with the intent of making it easy to switch components of the models. Some of the inherent deficiencies were the lack of proper decoupling between the I/O and the model through an appropriate interface and the fact that the parameterizations of physical processes (evaporation, infiltration, and runoff) were not appropriately modularized, making it practically impossible to quickly and efficiently update the model with new research. With a desire to now update this model and run it over much larger spatial scales than what it was originally intended for, we see this as a perfect opportunity to gravitate towards object-oriented programming in Fortran 2003.

The main goals of this project included: 1) Modularize the code based on the physics so that it will be easy to swap physics; 2) Improve data structures by introducing derived data types; 3) Add parallel computing using OpenMP; 4) Make tests to ensure subroutines as well as the whole model produce the same results as the original model.

2 Tools used during development

Table 1: Tools used in the project

Purpose	Tools
Language	Fortran 2003
Compiler	gfortran 4.46+
Parallelizaton	OpenMP
Testing	FRUIT
Version control	Git and Github
Memory debugger	Valgrind
Profiler	gprof and gprof2dot
Editor	Vi, Kate, and Gedit
Operating system	Centos and Fedora
Documentation	Doxygen

3 Interface

The original model in Fortran 77 had a very complicated interface defined in main.f. It was around 1500 lines of code which mostly consisted of arguments passed into each of the subroutines. This situation was problematic for several reasons. On one hand, the large number of arguments passed to each subroutine made it impossible to decipher what the model was actually doing. The tests, cell model, and catchment models were all mixed together making it impossible to change individual components of the model.

To address these problems, we constructed a completely new interface with the modularization as will be discussed in the next section. This allowed us to make a very clean program that only adds to the interface the subroutines that it needs from each module. The model first reads in the initial model parameters and the filenames for the rest of the input files. It then initializes the variables and runs all the time steps as defined by the user. Within each time step, it reads in the necessary forcing data (boundary conditions), updates all the grid cells in the region, updates the catchments, produces averages over the region, and outputs data to disk. To finish the model, it deallocates memory and closes all the files being used. Conceptually, the same process was happening in the original model but it was extremely hard to decipher making it impossible to access and update the model.

4 Modularization

One of the main tasks in the project was modularization. To this end, we took the original 100+ files written in F77 and split their functions and subroutines according to their purpose. We set up 11 modules that are combined and used by the interface (TOPLATS_DRIVER.f90) to run the model. Each module is written in a separate file, allowing us to reduce the number of files significantly down to 11. The new TOPLATS model files are shown in Figure 1.

The model consists of three main parts: MODULE_CELL, MODULE_CATCHMENT, and MODULE_REGIONAL. MODULE_CELL uses MODULE_LAND, MODULE_ATMOS, MODULE_CANOPY and MODULE_SNOW. The program's IO was placed in MODULE_IO and variables and data structures are defined in MODULE_VARIABLES. Using modularization, swapping physics in the model becomes much easier because we are able to replace the subroutine or module instead of making changes to every related variable and function throughout the model. It also allows us to take an object-oriented programming approach and choose what physics we want to use at runtime.

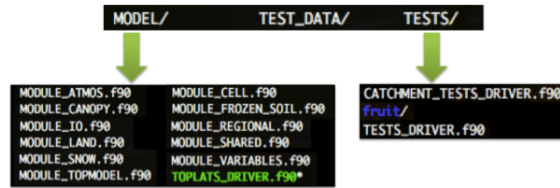


Figure 1: New TOPLATS model

Within each module, as shown in Figure 2, we first list shared variables and structures from other modules, defined structures being shared by subroutines in the module if there are any, and then list the subroutines that are related to the module.

5 Variables

In the original version of TOPLATS, the variables were stored in one lengthy list. Hundreds of variables were passed into subroutines individually, causing extremely large subroutine calls. For the updated version of TOPLATS developed in this project, these hundreds of variables were organized into derived data types (structures) based upon function or purpose. In this way, structures could be passed into the modules and subroutines in

```

MODULE MODULE_CELL
USE MODULE_VARIABLES
USE MODULE_LAND
USE MODULE_ATMOS
USE MODULE_CANOPY
USE MODULE_SNOW

contains

!#####
!
!           subroutine Update_Cells
!
!#####
! Solve the water and energy budget for all land surface area
!
!#####

subroutine Update_Cells(GRID,CAT,GLOBAL,i)

implicit none

```

Figure 2: Snapshot of MODULE_CELL.f90

relevant groups, thereby cleaning up the otherwise unmanageable code. In each larger subroutine, such as Atmos, the variables used in the code were replaced with the corresponding member of the structure. For each smaller subroutine, the members of the structures were passed into the subroutine individually to avoid passing in more variables than necessary.

Not only was the original version of TOPLATS crippled by the massive subroutine calls, but it was also impaired by the unreasonable number of help files storing the initialized variables with their corresponding types. Each subroutine was associated with a help file which initialized new variables in each subroutine but which also re-initialized all variables which were passed into the subroutine. This process of re-initializing variables over and over was cumbersome and unnecessary. In the updated version of TOPLATS, the variables in structures are initialized within the structure, and the rest of the variables are only initialized within the larger subroutine in which they are used. In this way, hundreds of files were removed.

Another limitation of the original version of TOPLATS was the use of static memory allocation. Using this method, the size of all arrays needed to be provided at compile time, meaning that the users needed to alter the source files every time they used the model for a different domain. In order to improve upon this, the dynamic memory allocation features implemented in Fortran 90 were used. By dynamically allocating the arrays, the user is able to specify dimensions at run time, allowing for the model to be used across multiple domains without maintaining and compiling multiple versions of the model code.

6 Tests

The FORTRAN Unit Test Framework (FRUIT) is used for testing. We have included two test programs: CATCHMENT_TESTS_DRIVER and TESTS_DRIVER, each serving a different purpose.

The CATCHMENT_TESTS_DRIVER runs the model and compares all the output variables with the original model over a test catchment. Although written in a messy way, the original model's results have been validated, so starting from scratch seemed unnecessary. To this end, by using the validated output from a sample input data set, all we need to ensure in the catchment tests is that our modified model reproduces the output at every time step. These tests were the first thing we wrote, which we ran every time before we made a commit to ensure we did not change any essential physics or algorithms.

<pre> 41 / ----- 42 / Actual energy fluxes. 43 / ----- 44 45 call set_unit_name (i_str//: '//i_str//: '//lswb.f90: rnsun') 46 call assert_equals (REG_OLDXrnsun,REG_NEWXrnsun) 47 call set_unit_name (i_str//: '//lswb.f90: xlesum') 48 call assert_equals (REG_OLDXxlesum,REG_NEWXxlesum) 49 call set_unit_name (i_str//: '//lswb.f90: hsum') 50 call assert_equals (REG_OLDXhsum,REG_NEWXhsum) 51 call set_unit_name (i_str//: '//lswb.f90: gsum') 52 call assert_equals (REG_OLDXgsum,REG_NEWXgsum) 53 call set_unit_name (i_str//: '//lswb.f90: tksum') 54 call assert_equals (REG_OLDXtksum,REG_NEWXtksum) 55 call set_unit_name (i_str//: '//lswb.f90: tkwidsum') 56 call assert_equals (REG_OLDXtkwidsum,REG_NEWXtkwidsum) 57 call set_unit_name (i_str//: '//lswb.f90: tkdeepsum') 58 call assert_equals (REG_OLDXtkdeepsum,REG_NEWXtkdeepsum) 59 60 / ----- 61 / Canopy water balance. 62 / ----- 63 64 call set_unit_name (i_str//: '//lswb.f90: wclipsum') 65 call assert_equals (REG_OLDXwclipsum,REG_NEWXwclipsum) </pre>	<p>SUCCESSFUL!</p> <p>No messages</p> <p>Total asserts : 16250</p> <p>Successful : 16250</p> <p>Failed : 0</p> <p>Successful rate: 100.00%</p> <p>Successful asserts / total asserts : [16250 / 16250]</p> <p>Successful cases / total cases : [0 / 0]</p>
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Figure 3: Catchment tests example code (left) and its corresponding assertions output (right)

One of the major downfalls of testing the model against old output is the inability to then swap physics. To this end, a set of unit tests were developed in TESTS_DRIVER.90 to run tests on the individual subroutines by using random input values. Considering the amount of subroutines and functions and that the model was previously validated, we only tested about 50 of them. Random values were given to the subroutine or function being tested, and the resulting value was compared with the true value. The true value was previously calculated by the original subroutine or function. As we move to the next step and we implement new subroutines, we need to ensure that the unit tests capture the same errors as the CATCHMENT_TESTS.f90 does. This will allow to eventually completely replace those tests with the

subroutine unit tests.

<pre> 1 MODULE MODULE_UNIT_TESTS 2 3 USE FRUIT 4 5 USE MODULE_ATMOS 6 7 USE MODULE_LAND 8 9 USE MODULE_CANOPY 10 11 implicit none 12 13 contains 14 15 subroutine clcfipar_test1() 16 implicit none 17 real*8 :: fipar_result,fipar_true 18 call set_unit_name ('clcfipar_test1') 19 fipar_result = clcfipar(0.3d0,5.0d0,500.0d0,100.0d0,5000.0d0,100 20 fipar_true = 2.2405063029073640d0 21 call assert_equals (fipar_true,fipar_result) 22 end subroutine 23 </pre>	<pre> Test module initialized . : successful assert, F : failed assert Start of FRUIT summary: SUCCESSFUL! No messages Total asserts : 83 Successful : 83 Failed : 0 Successful rate: 100.00% Successful asserts / total asserts : [83 / 83] Successful cases / total cases : [0 / 0] </pre>
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Figure 4: Subroutines tests example code (left) and its corresponding assertions output (right)

7 I/O

The original model's I/O was a disaster. A general file contained a reference to 20+ files that contained the data and parameters. The parameters themselves were split into 10 files, some files having less than 10 parameters. Furthermore, many of the soil and vegetation properties were defined in ascii files which would be too massive when the model is taken to global scales.

For these reasons, a concerted effort is placed on revamping the model's I/O. First, the input file is redefined as the general parameters file. In this file all the parameters are defined and the user can access the README or manual online to learn about the parameters. The soil and vegetation properties were converted to a flat binary format. The files can be prepared using GrADS, a tool commonly used in meteorology and hydrology. This speeds up the read time, and allows much smaller files. The input forcing data (boundary conditions) are now given through one large layered flat binary file also following the GrADS format. This allows the model to run without having to open/close files every time step. The output data also follows the GrADS format and can be accessed from either GrADS, python, or matlab, among others, given that the user understands how to read flat binary files using these programs. In the near future, we are looking to move towards a netCDF or HDF5 format which is more universal and easier to manage.

8 Parallelization

Parallelization is currently implemented using OpenMP. The user can define at runtime how many cores to use. In order to do this, for each time step, the domain is split up into equal sized blocks and then is distributed among the threads. Calculations are then performed for each cell before the domain is reassembled and the regional processes are calculated. For the domain size that we are using the parallelization does not have a significant impact on the calculation time. It should be noted though that for future work, as the domain size increases, we believe that we will find that parallelization becomes increasingly important. In order to run the model on a global scale, we plan to implement parallelization through MPI in order to maximize the computational power of each node.

9 Variable Initialization

The current version of TOPLATS was checked for memory leaks and other issues using valgrind. This process identified a number of uninitialized variables which were passed into a subroutine. If the variables were reasigned, this structure would not be an issue, but the variables were often used as sums, and if the variables were not initialized to zero, the variables could have any value.

These issues were fixed initially by using the `-finit-local-zero` option available in gfortran. This option set all uninitialized values to 0 at runtime, which temporarily fixed the problem. However, because we would like to use this model with other compilers, these issues were identified and removed from the code manually using valgrind. After solving these issues, we were successfully able to remove the `-finit-local-zero` option, and the valgrind analysis found that no memory leaks were occurring in our model.

10 Profiling

We used gprof to examine the run time statistics and determine what portions of the code are taking the most time to run. We then used gprof2dot to convert the ascii output into a call graph visualization as shown in Figure 5.

As expected, the model spends a large amount of its time in the `Update_Cell` module (90%). This result is mainly caused by the need to ensure energy balance closure. Energy balance closure means that the surface energy balance equation for each grid cell at each time step needs to be minimized.

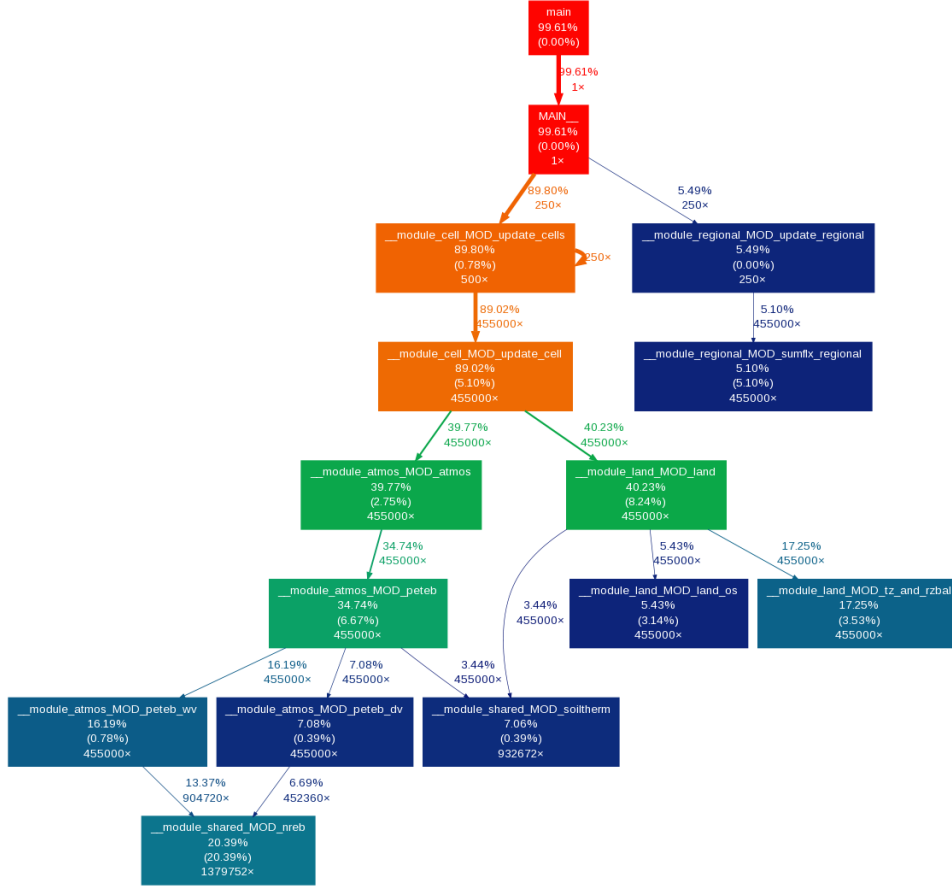


Figure 5: Schematic of the call-graph of TOPLATS. We define a threshold of 5%, below which all subroutines are discarded. This offers a detailed view on where the model is spending most of its time.

Any future improvement in performance (excluding parallelization) will need to address the nreb subroutine and use more efficient algorithms. Although there is room for improvement, we are happy with the performance of the model. The current runtime for 250 time steps over a 60X66 domain is around 5 seconds. In comparison, this runtime is much faster than most other hydrologic models that thoroughly solve the groundwater interactions between cells.

11 Conclusion

As described above, we have accomplished our major goals for this project. The changes to the original model included that derived data types were im-

plemented (although not completely), modules were set up to simplify the code and make it simple to swap physics in the future, the I/O components were separated from other routines and enhanced, parallelization using OpenMP was added, and the main program was replaced with a much cleaner interface.

The changes will enable us to use this outdated model for future hydrologic studies. Current work is looking at adding the MPI capability for massive parallelization. We are currently developing a global model run at a 500 meter spatial resolution on the Blue Waters supercomputer in Illinois.

This project and this course have been beneficial to everyone in the project. We have learned how to effectively collaborate on the same program with great help from github. Testing has become an important part of our programming practices, which was almost absent before taking this course. Learning how to use valgrind has been extremely useful as it also serves as a debugger. In conclusion, all the tools we have used, github, Doxygen, Valgrind, gprof, etc... will continue to serve as our programming companions in the future.