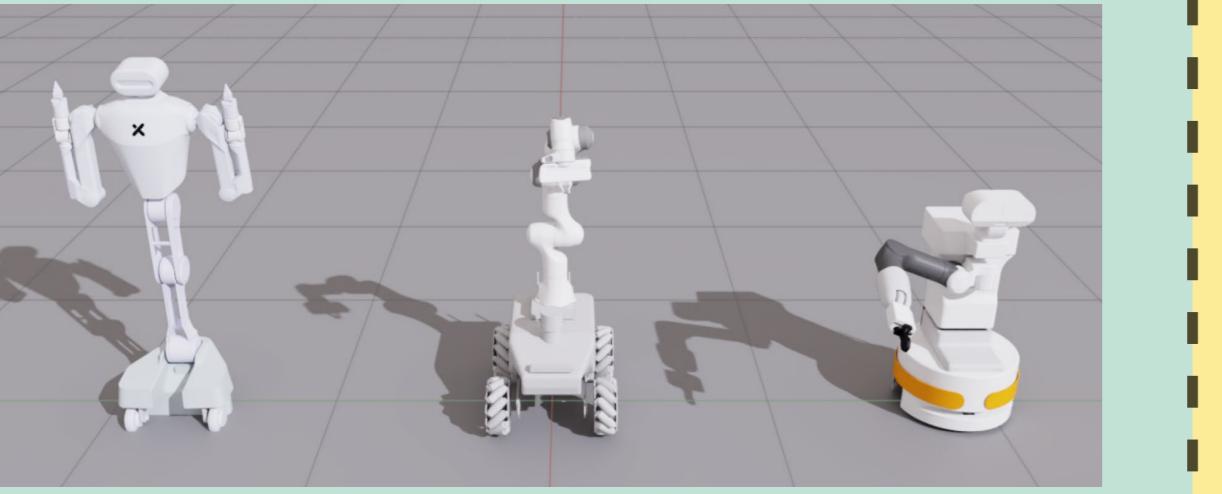
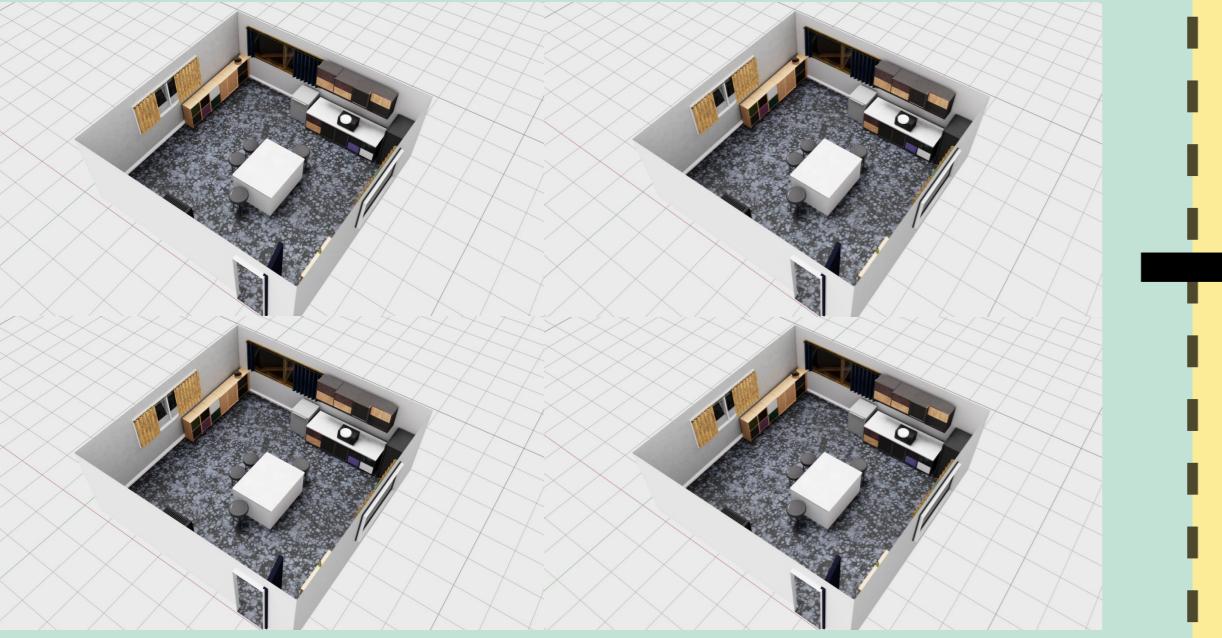


AutoMoMa Pipeline

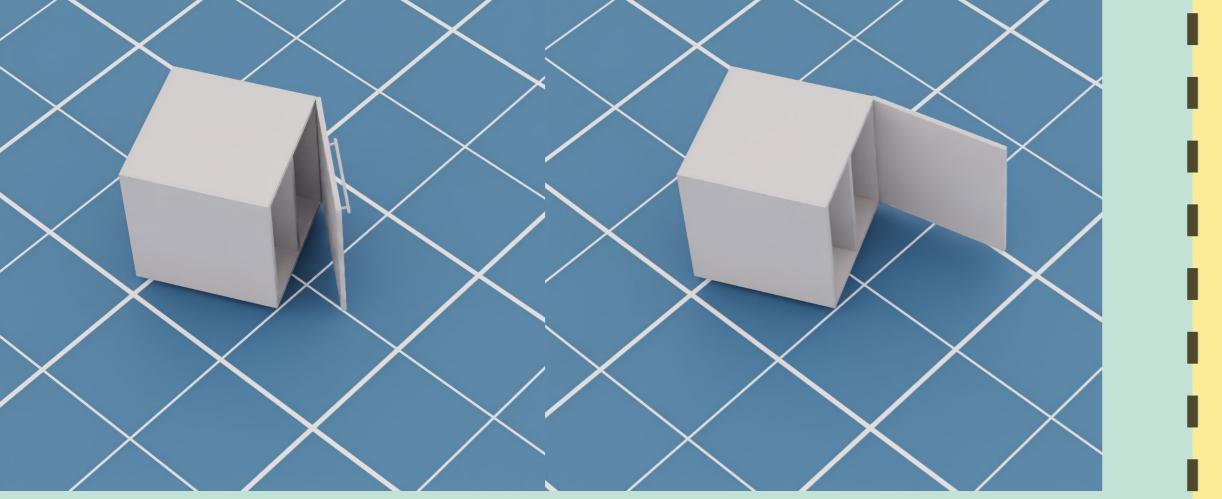
Task Description



Robot Embodiments

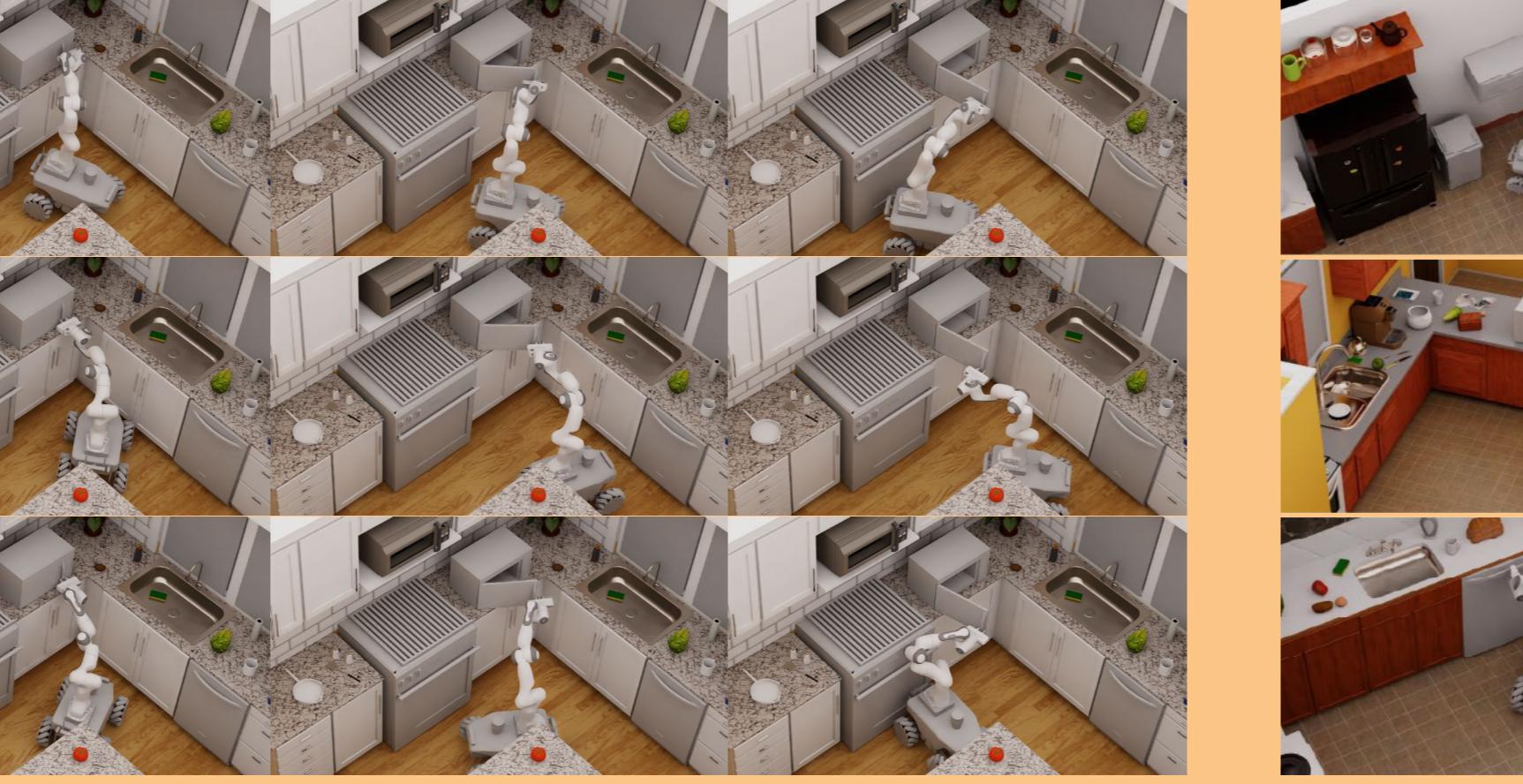


Generated Interactive Scenes

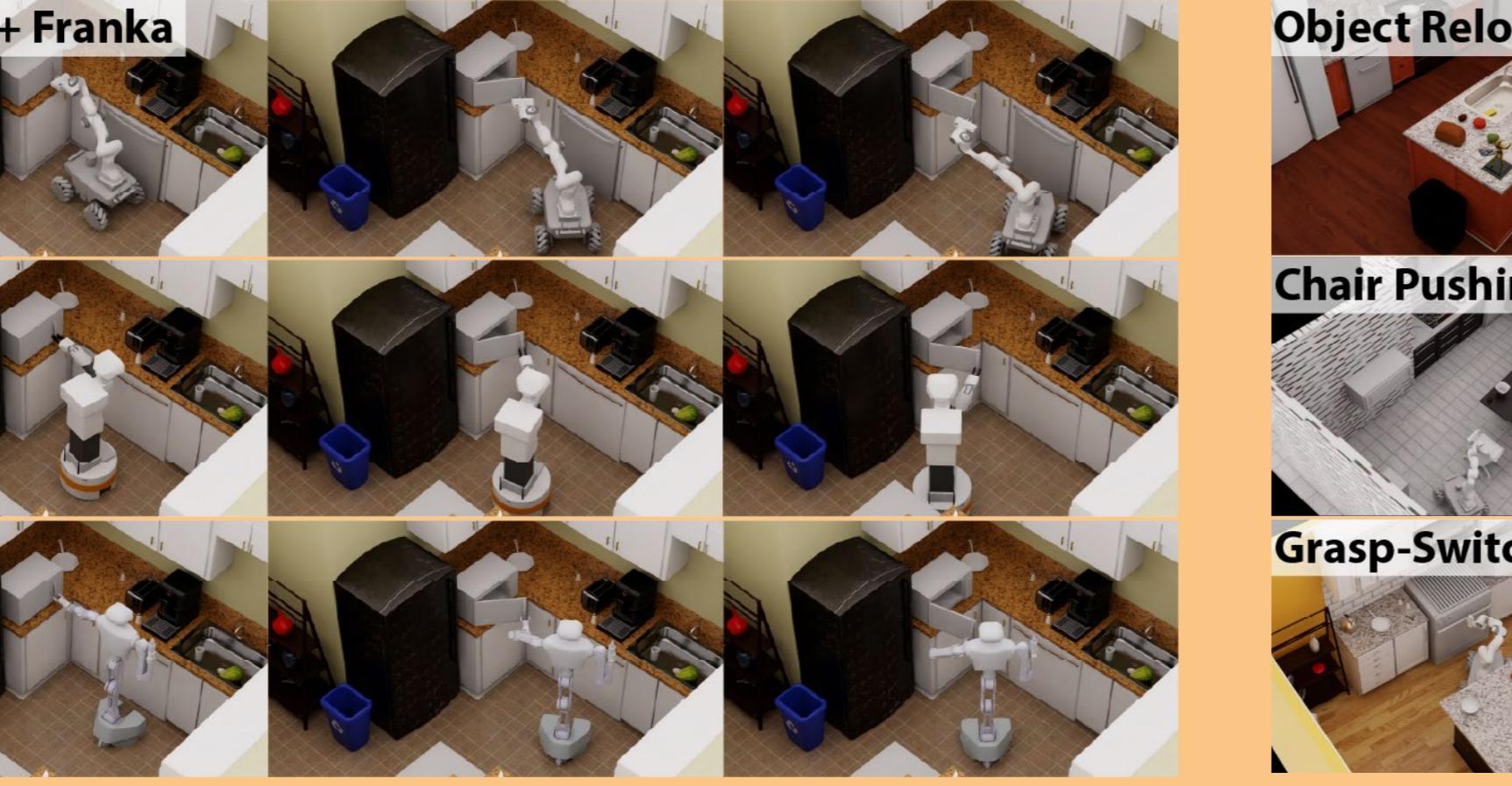


Task Objective

Mobile Manipulation Trajectory Data



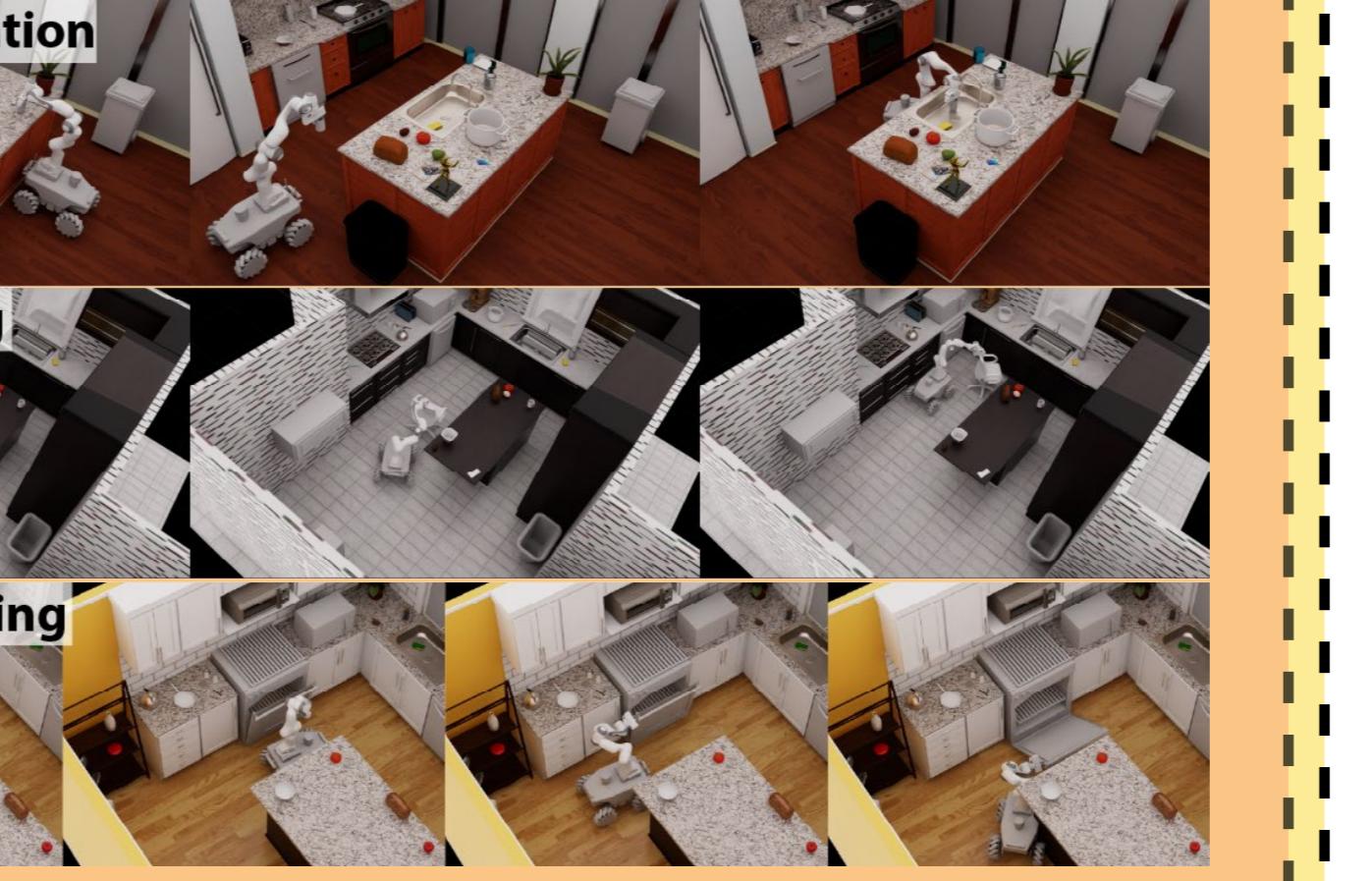
Diverse Solutions



Diverse Embodiments



Diverse Scenes



Diverse Tasks

Learned Policies



Robot in Unseen Environment



Coordinated Motion