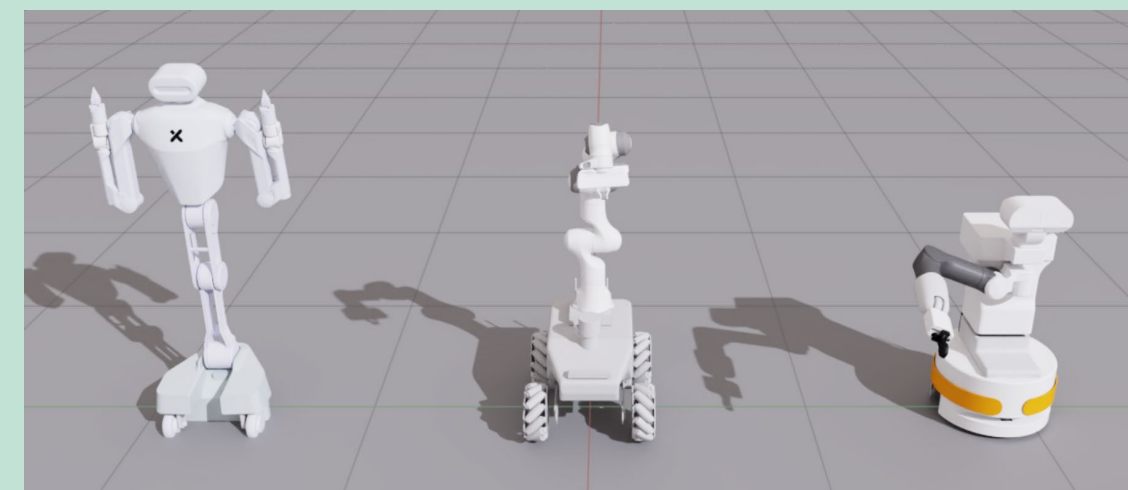
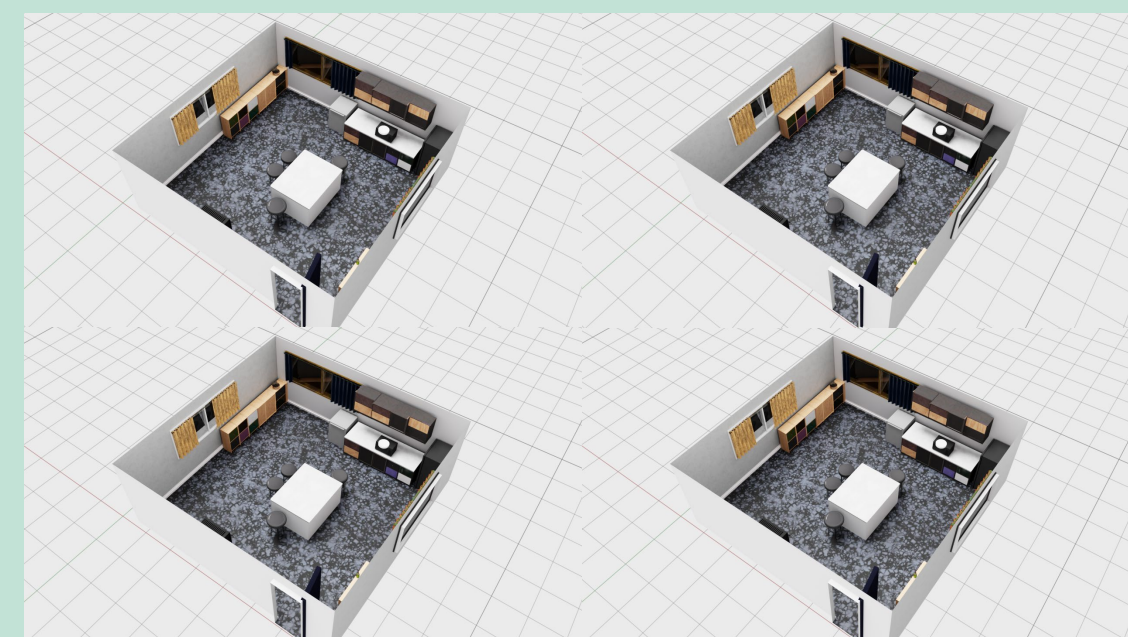


AutoMoMa Pipeline

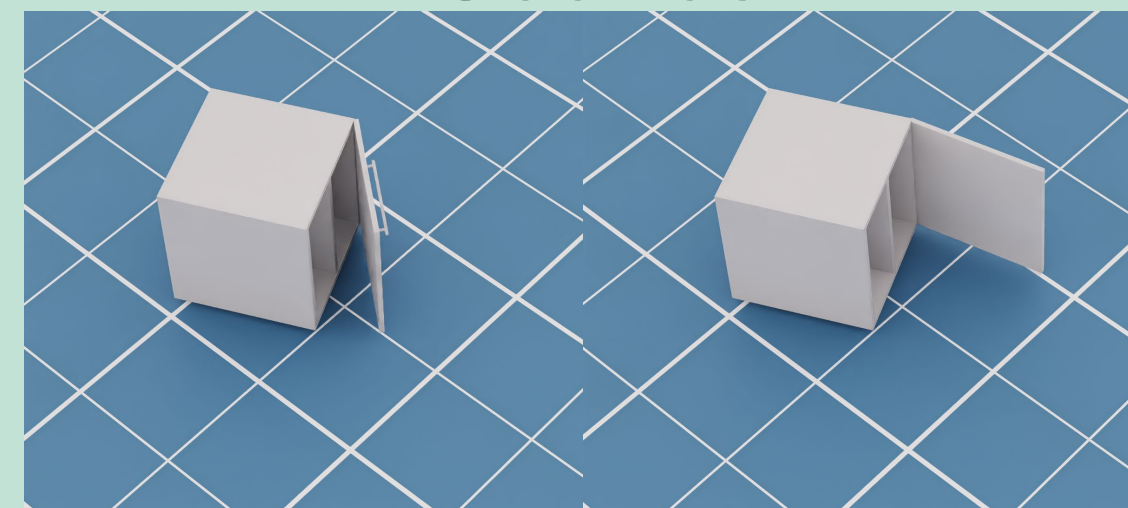
Task Description



Robot Embodiments

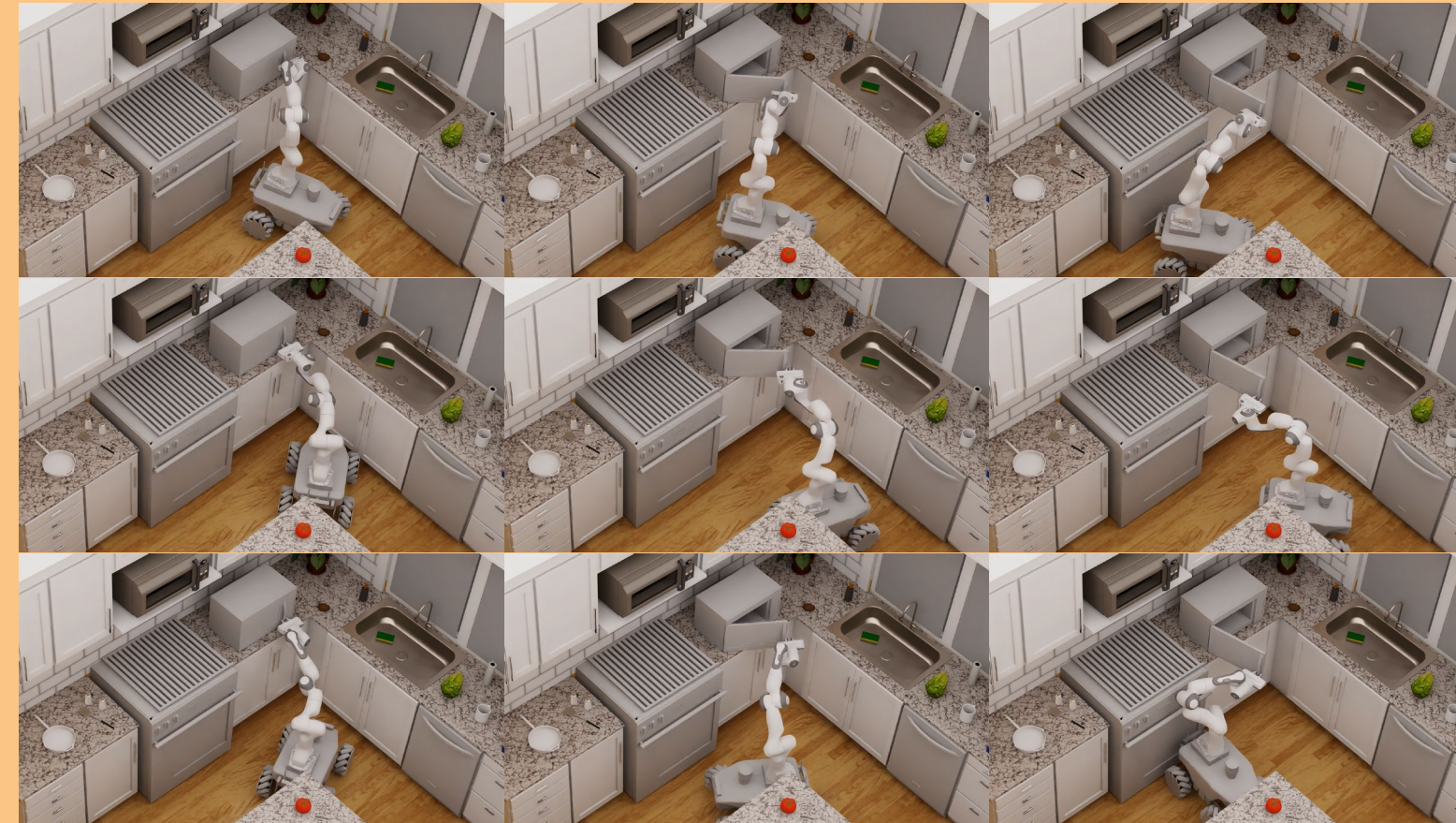


Generated Interactive Scenes



Task Objective

Mobile Manipulation Trajectory Data



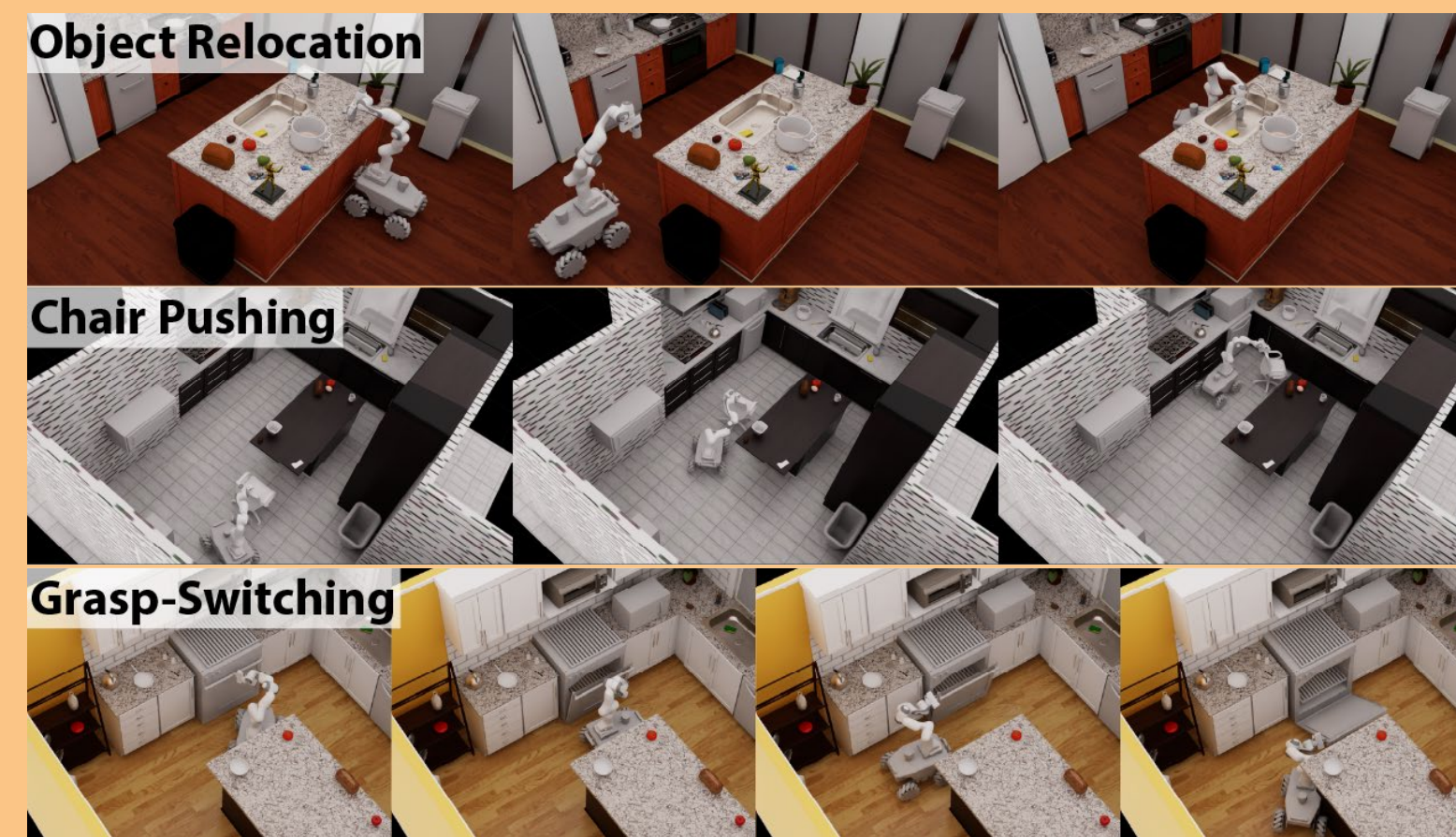
Diverse Solutions



Diverse Embodiments



Diverse Scenes

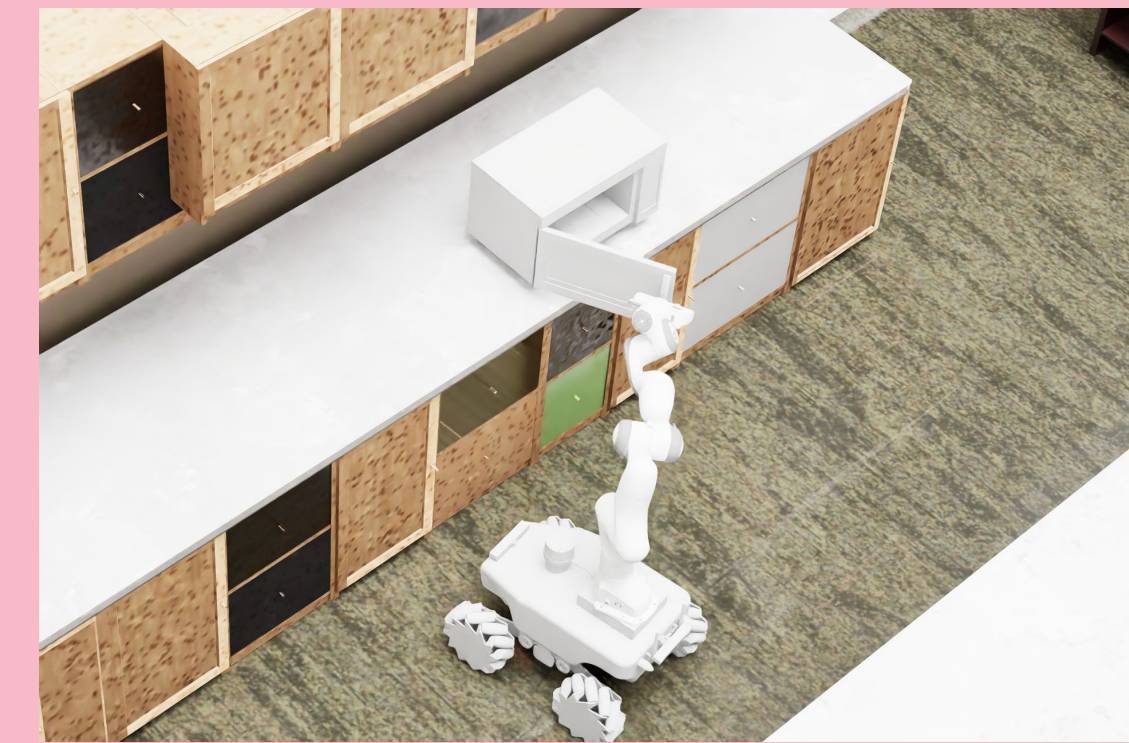


Diverse Tasks

Learned Policies



Robot in Unseen Environment



Coordinated Motion