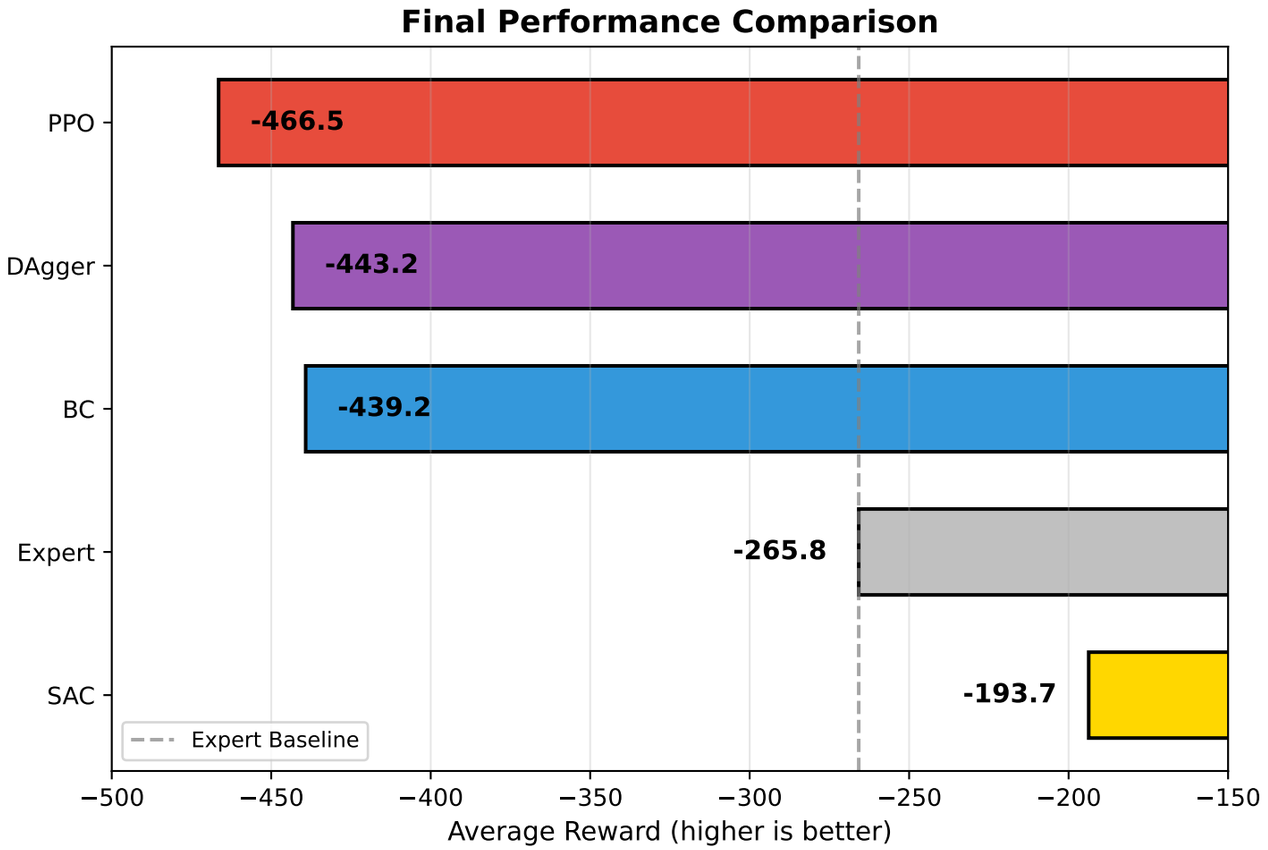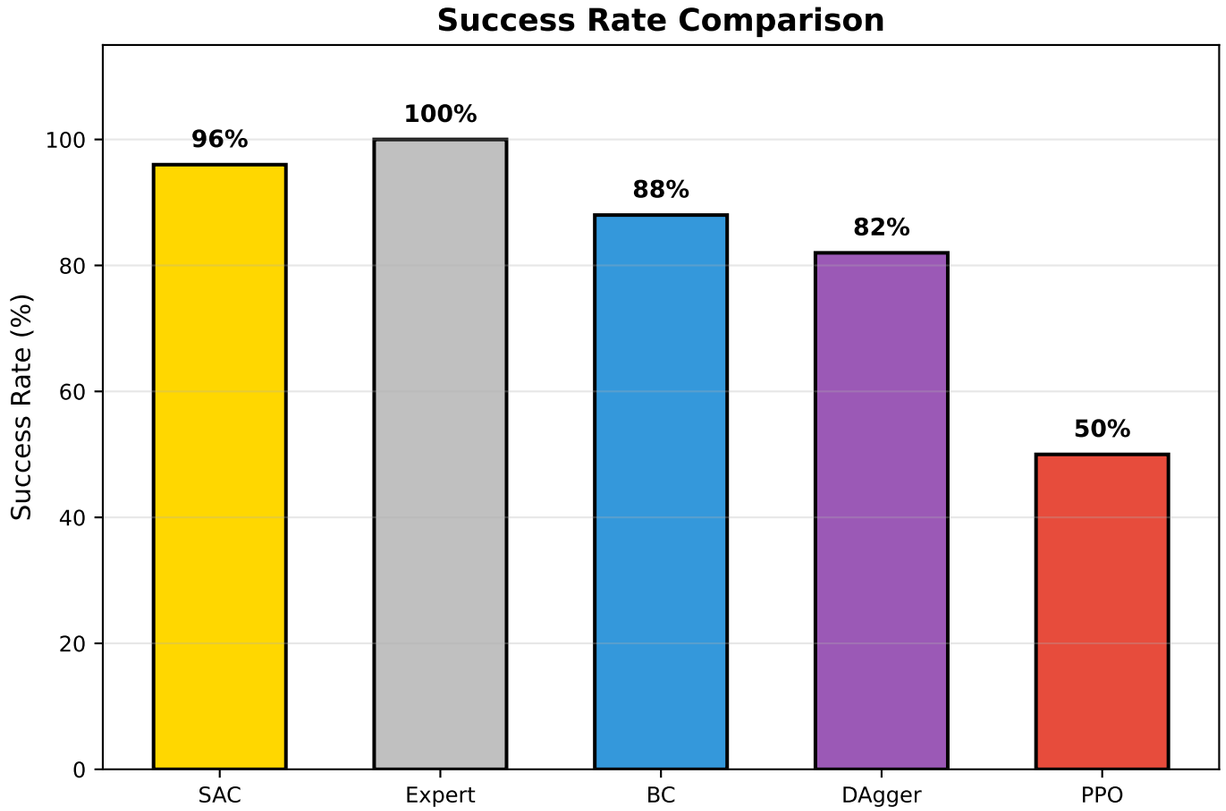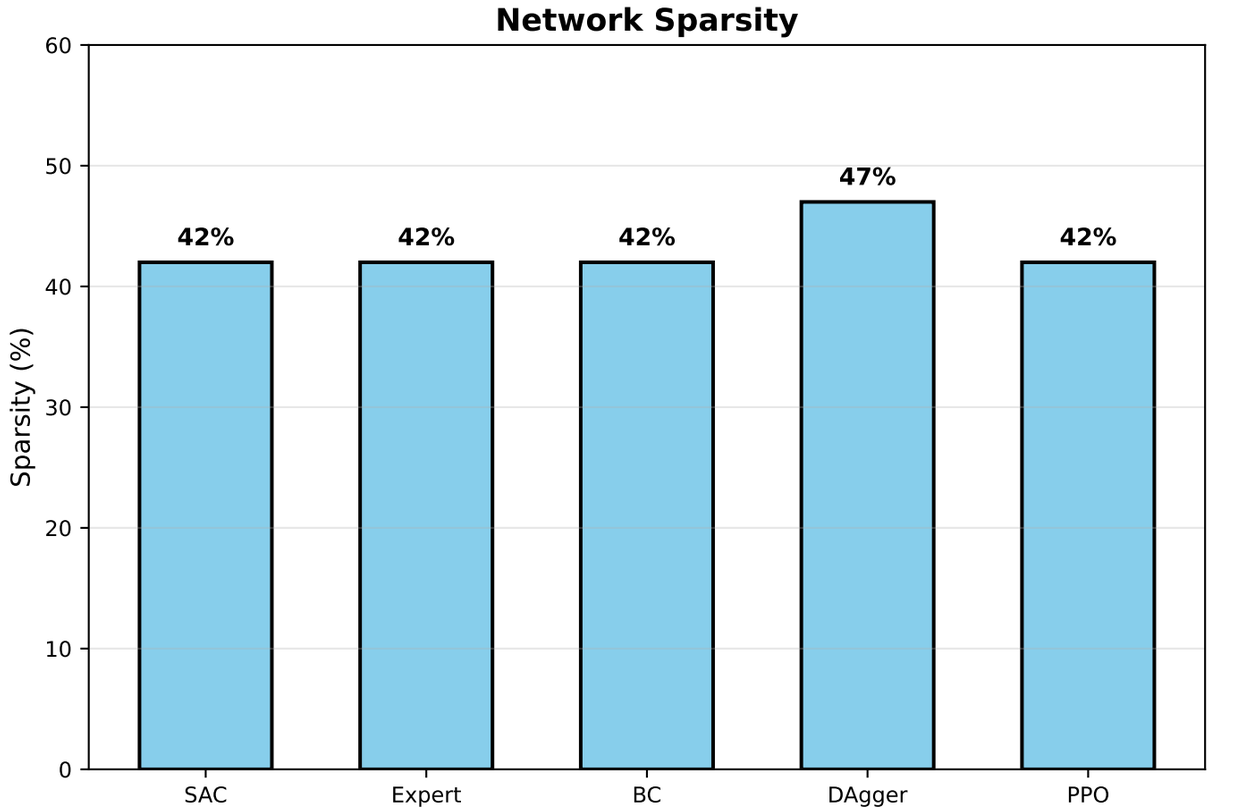KAN-RL Double Pendulum: Algorithm Comparison