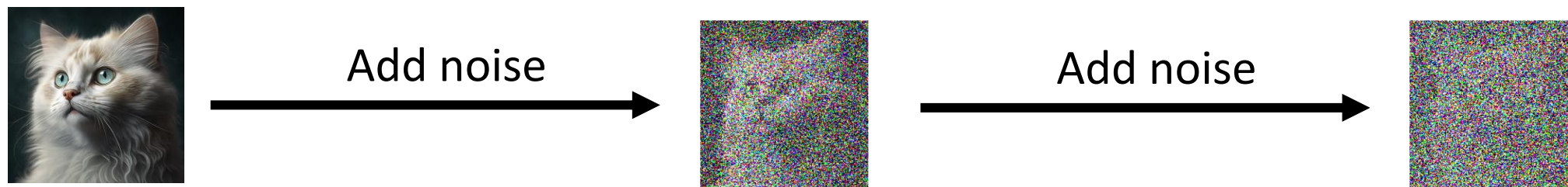


Diffusion Model

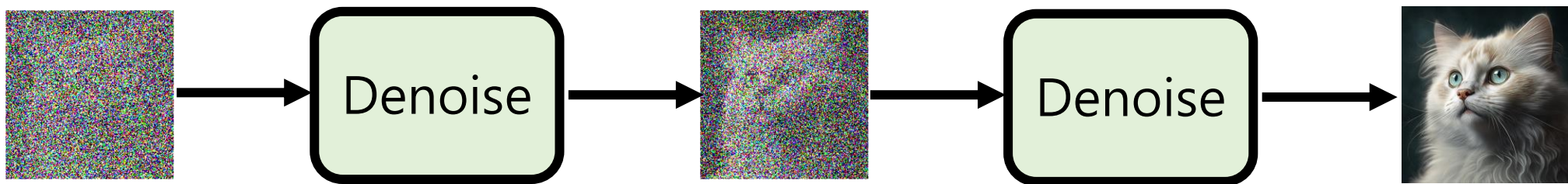
背後的數學原理

基本概念

Forward Process



Reverse Process



Denoising Diffusion Probabilistic Models

Algorithm 1 Training

```
1: repeat  
2:    $\mathbf{x}_0 \sim q(\mathbf{x}_0)$   
3:    $t \sim \text{Uniform}(\{1, \dots, T\})$   
4:    $\epsilon \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$   
5:   Take gradient descent step on  
        $\nabla_{\theta} \|\epsilon - \epsilon_{\theta}(\sqrt{\bar{\alpha}_t}\mathbf{x}_0 + \sqrt{1 - \bar{\alpha}_t}\epsilon, t)\|^2$   
6: until converged
```

Algorithm 2 Sampling

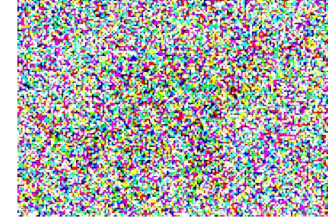
```
1:  $\mathbf{x}_T \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$   
2: for  $t = T, \dots, 1$  do  
3:    $\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$  if  $t > 1$ , else  $\mathbf{z} = \mathbf{0}$   
4:    $\mathbf{x}_{t-1} = \frac{1}{\sqrt{\alpha_t}} \left( \mathbf{x}_t - \frac{1 - \alpha_t}{\sqrt{1 - \bar{\alpha}_t}} \epsilon_{\theta}(\mathbf{x}_t, t) \right) + \sigma_t \mathbf{z}$   
5: end for  
6: return  $\mathbf{x}_0$ 
```

暗藏玄機!

Training



x_0 : clean image



ϵ : noise

Algorithm 1 Training

1: **repeat**

2: $\mathbf{x}_0 \sim q(\mathbf{x}_0) \leftarrow \dots$ sample clean image

3: $t \sim \text{Uniform}(\{1, \dots, T\})$

4: $\epsilon \sim \mathcal{N}(\mathbf{0}, \mathbf{I}) \leftarrow \dots$ sample a noise

5: Take gradient descent step on

$$\nabla_{\theta} \left\| \epsilon - \epsilon_{\theta}(\underbrace{\sqrt{\bar{\alpha}_t} \mathbf{x}_0 + \sqrt{1 - \bar{\alpha}_t} \epsilon}_{\text{Noisy image}}, t) \right\|^2$$

6: **until** converged

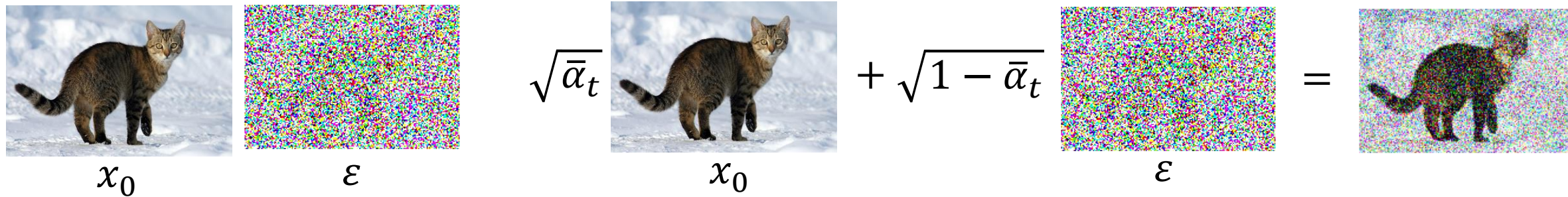
$\bar{\alpha}_1, \bar{\alpha}_2, \dots, \bar{\alpha}_T$

Target
Noise

Noise
predictor

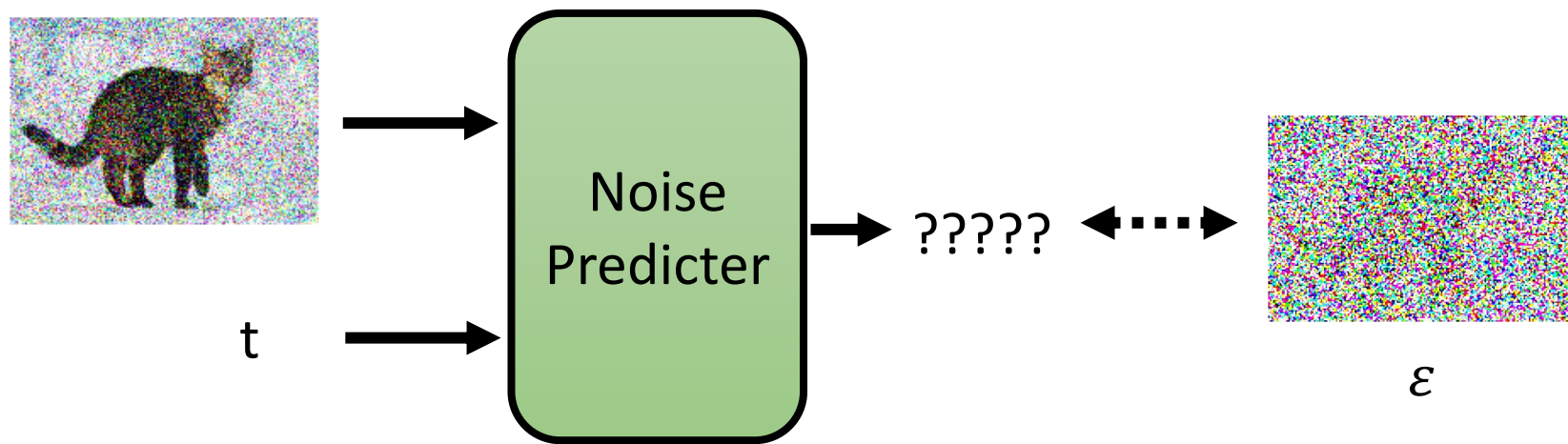
Training

$\bar{\alpha}_1, \bar{\alpha}_2, \dots, \bar{\alpha}_T$

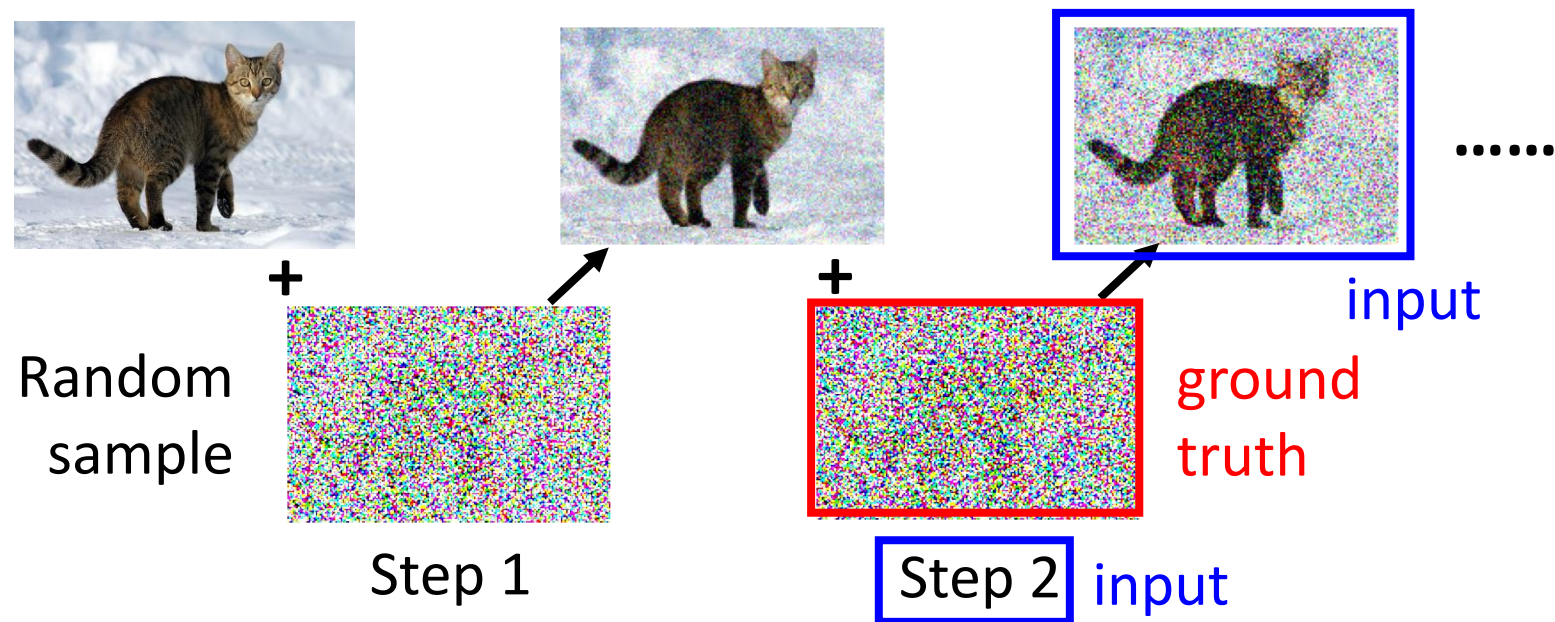


The diagram illustrates the forward process of adding noise to an image x_0 to create x_t . It shows the image x_0 and a noise vector ε being combined using the formula $\sqrt{\bar{\alpha}_t} x_0 + \sqrt{1 - \bar{\alpha}_t} \varepsilon = x_t$. The resulting image x_t is shown on the right, which is a noisy version of the original image.

$$\sqrt{\bar{\alpha}_t} x_0 + \sqrt{1 - \bar{\alpha}_t} \varepsilon = x_t$$



想像中 ...



實際上 ...

The equation shows a clear image of a cat, labeled x_0 , being multiplied by $\sqrt{\bar{\alpha}_t}$. This is added to a noise sample, labeled ε and 'ground truth', which is multiplied by $\sqrt{1 - \bar{\alpha}_t}$. The result is an image labeled 'input' enclosed in a blue box.

$$\sqrt{\bar{\alpha}_t} x_0 + \sqrt{1 - \bar{\alpha}_t} \varepsilon = \text{input}$$

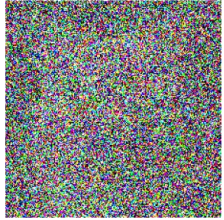
x_0

ε

ground truth

input

Inference

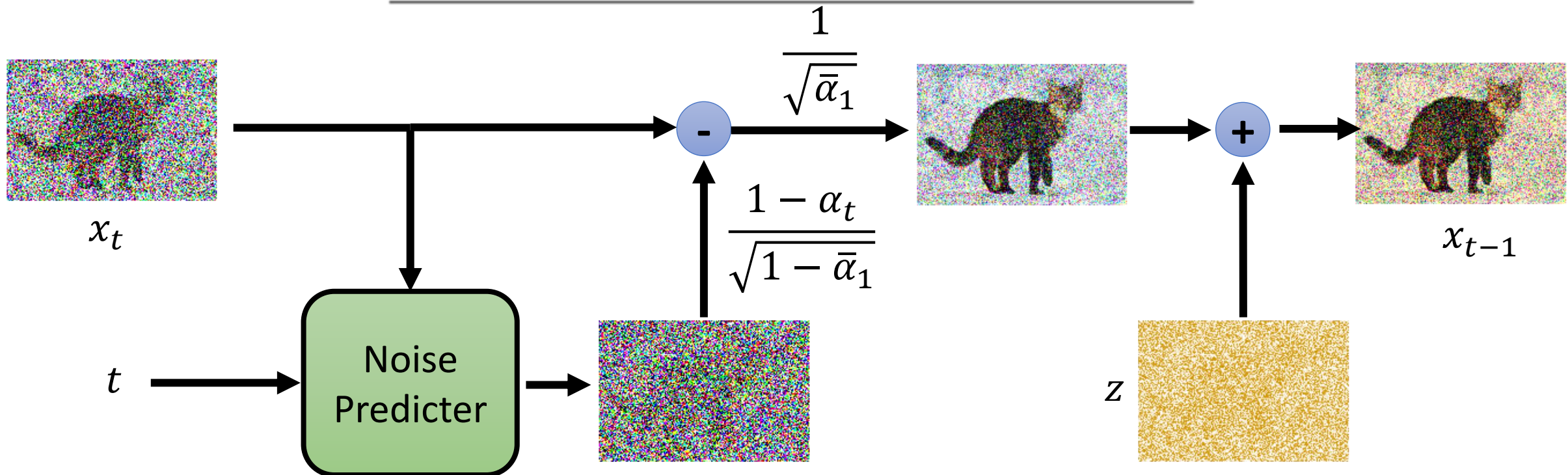


x_T

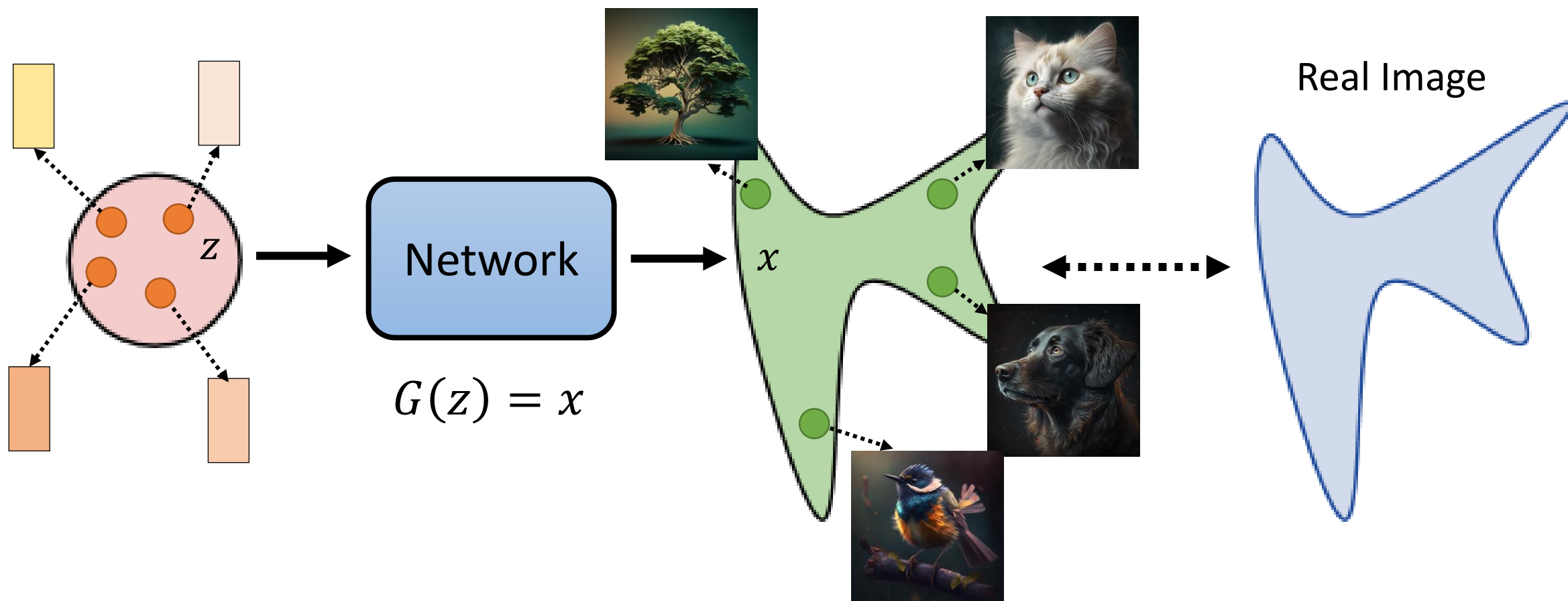
Algorithm 2 Sampling

```
1:  $\mathbf{x}_T \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$ 
2: for  $t = T, \dots, 1$  do
3:    $\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$  if  $t > 1$ , else  $\mathbf{z} = \mathbf{0}$ 
4:    $\mathbf{x}_{t-1} = \frac{1}{\sqrt{\alpha_t}} \left( \mathbf{x}_t - \frac{1-\alpha_t}{\sqrt{1-\bar{\alpha}_t}} \epsilon_{\theta}(\mathbf{x}_t, t) \right) + \sigma_t \mathbf{z}$ 
5: end for
6: return  $\mathbf{x}_0$ 
```

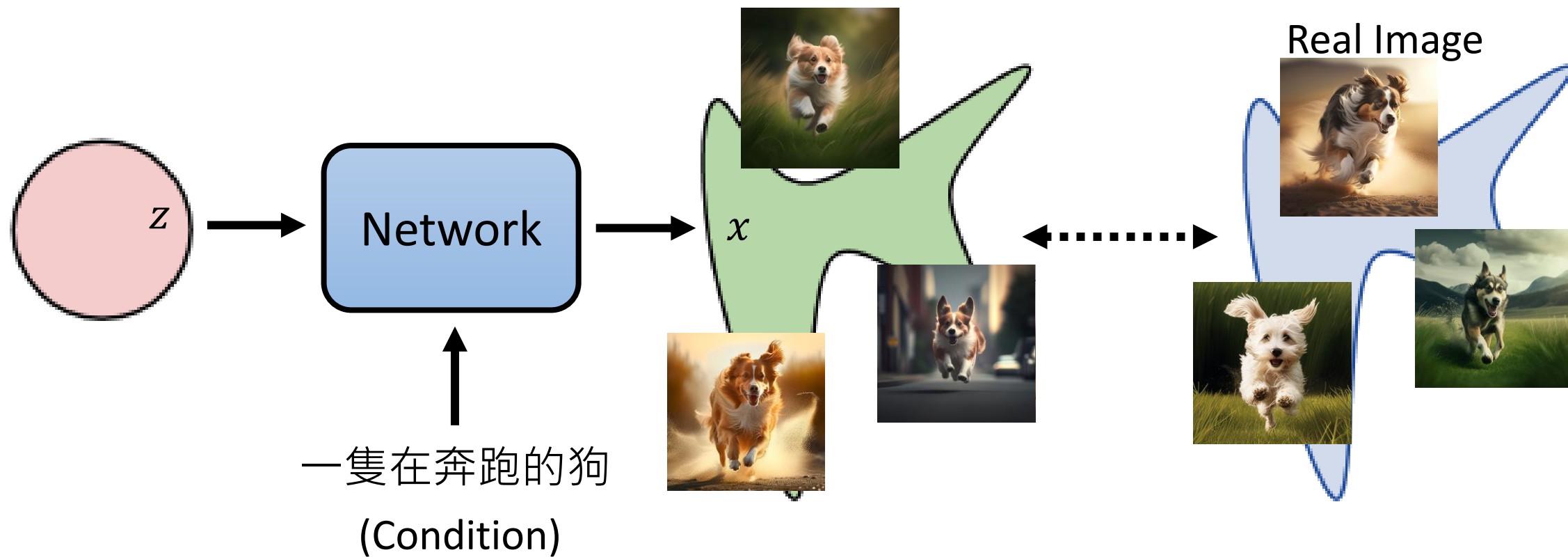
sample a noise?!



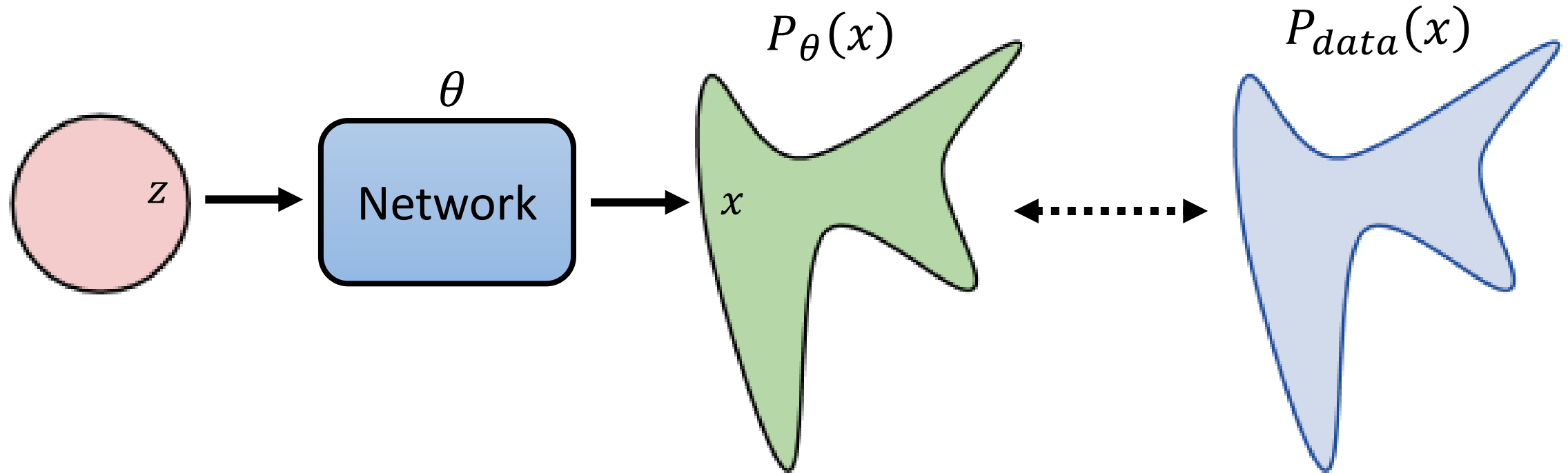
影像生成模型本質上的共同目標



影像生成模型本質上的共同目標



Maximum Likelihood Estimation



Sample $\{x^1, x^2, \dots, x^m\}$ from $P_{data}(x)$

$$\theta^* = \arg \max_{\theta} \prod_{i=1}^m P_{\theta}(x^i)$$

We can compute $P_{\theta}(x^i)$

???

Sample $\{x^1, x^2, \dots, x^m\}$ from $P_{data}(x)$

$$\theta^* = \arg \max_{\theta} \prod_{i=1}^m P_{\theta}(x^i) = \arg \max_{\theta} \log \prod_{i=1}^m P_{\theta}(x^i)$$

$$= \arg \max_{\theta} \sum_{i=1}^m \log P_{\theta}(x^i) \approx \arg \max_{\theta} E_{x \sim P_{data}} [\log P_{\theta}(x)]$$

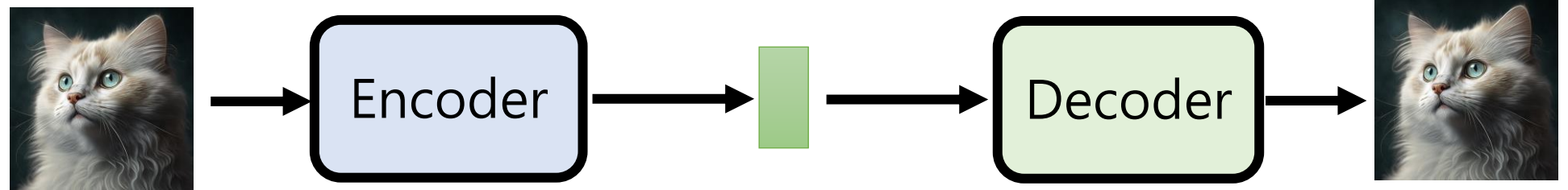
$$= \arg \max_{\theta} \int_x P_{data}(x) \log P_{\theta}(x) dx - \int_x P_{data}(x) \log P_{data}(x) dx \quad \text{(not related to } \theta \text{)}$$

$$= \arg \max_{\theta} \int_x P_{data}(x) \log \frac{P_{\theta}(x)}{P_{data}(x)} dx = \arg \min_{\theta} KL(P_{data} || P_{\theta}) \quad \text{Difference between } P_{data} \text{ and } P_{\theta}$$

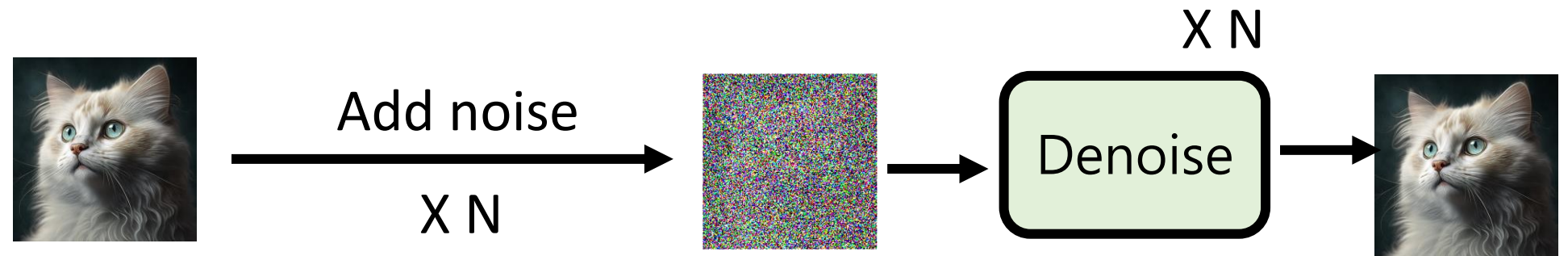
Maximum Likelihood = Minimize KL Divergence

VAE vs. Diffusion Model

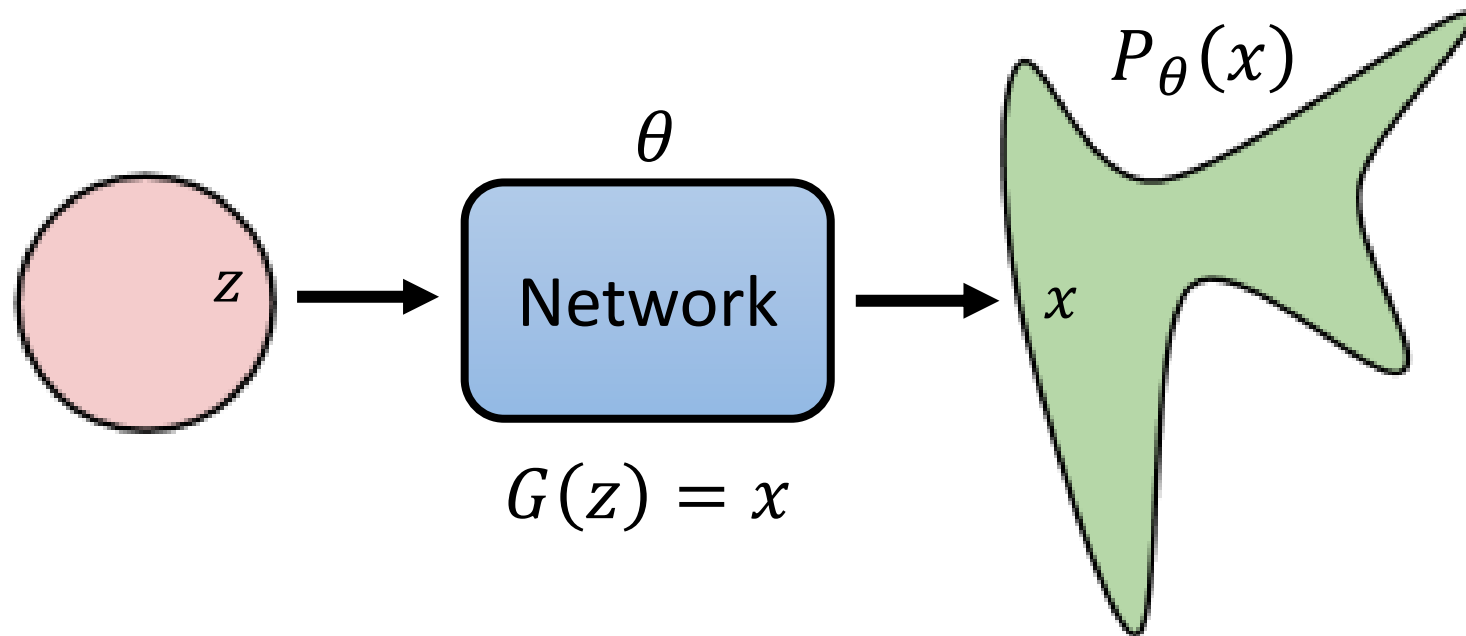
VAE



Diffusion



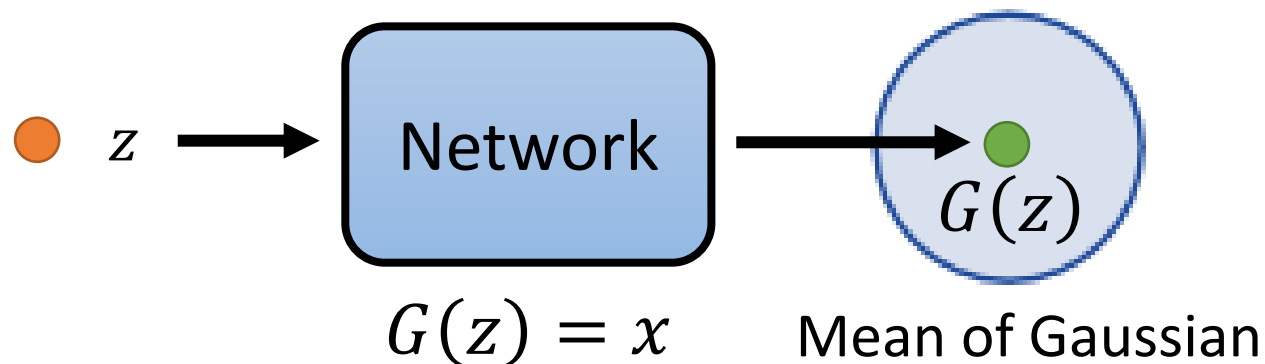
VAE: Compute $P_{\theta}(x)$



$$P_{\theta}(x) = \int_z P(z) P_{\theta}(x|z) dz$$

$$P_{\theta}(x|z) = \begin{cases} 1, & G(z) = x \\ 0, & G(z) \neq x \end{cases}$$

可能會幾乎都是 0 ☹️

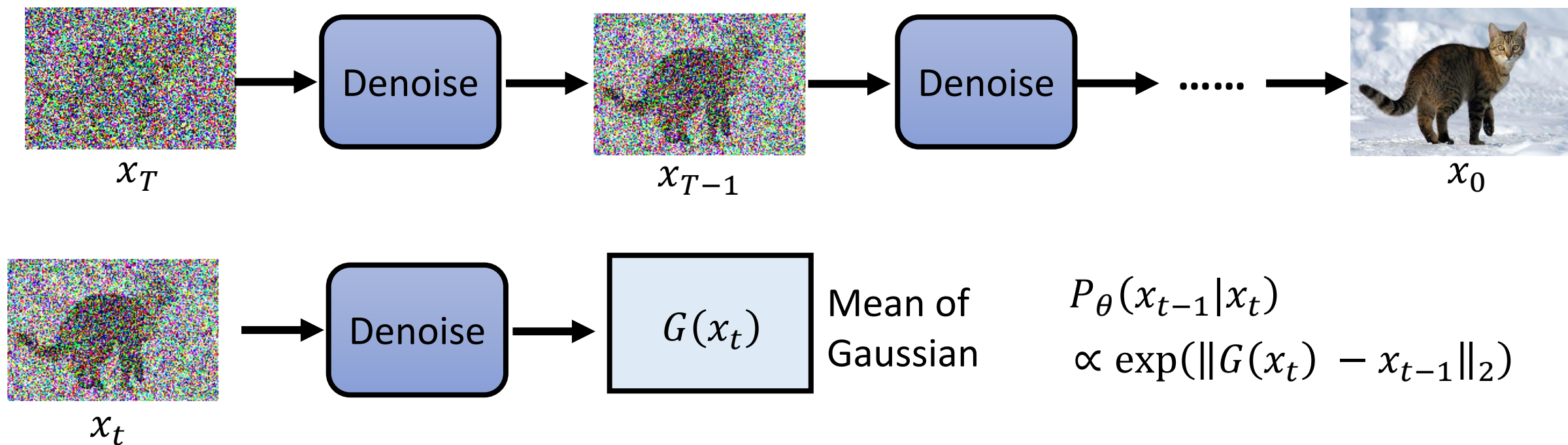


$$P_{\theta}(x|z) \propto \exp(-\|G(z) - x\|_2)$$

VAE: Lower bound of $\log P(x)$

$$\begin{aligned}\log P_{\theta}(x) &= \int_z q(z|x) \log P(x) dz && q(z|x) \text{ can be any distribution} \\&= \int_z q(z|x) \log \left(\frac{P(z, x)}{P(z|x)} \right) dz = \int_z q(z|x) \log \left(\frac{P(z, x)}{q(z|x)} \frac{q(z|x)}{P(z|x)} \right) dz \\&= \int_z q(z|x) \log \left(\frac{P(z, x)}{q(z|x)} \right) dz + \underbrace{\int_z q(z|x) \log \left(\frac{q(z|x)}{P(z|x)} \right) dz}_{KL(q(z|x) || P(z|x))} && \geq 0 \\&\geq \int_z q(z|x) \log \left(\frac{P(z, x)}{q(z|x)} \right) dz = \underbrace{E_{q(z|x)} \left[\log \left(\frac{P(x, z)}{q(z|x)} \right) \right]}_{\text{Encoder}} && \text{lower bound}\end{aligned}$$

DDPM: Compute $P_\theta(x)$



$$P_\theta(x_0) = \int_{x_1:x_T} P(x_T) P_\theta(x_{T-1}|x_T) \dots P_\theta(x_{t-1}|x_t) \dots P_\theta(x_0|x_1) dx_1:x_T$$

DDPM: Lower bound of $\log P(x)$

VAE

$$\text{Maximize } \log P_{\theta}(\underline{x}) \longrightarrow \text{Maximize } \mathbb{E}_{\underline{q(z|x)}} \left[\log \left(\frac{P(\underline{x}, \underline{z})}{q(\underline{z}|\underline{x})} \right) \right]$$

Encoder

DDPM

$$\text{Maximize } \log P_{\theta}(\underline{x_0}) \longrightarrow \text{Maximize } \mathbb{E}_{\underline{q(x_1:x_T|x_0)}} \left[\log \left(\frac{P(\underline{x_0:x_T})}{q(\underline{x_1:x_T|x_0})} \right) \right]$$

Forward Process
(Diffusion Process)

$$q(x_t|x_{t-1})$$

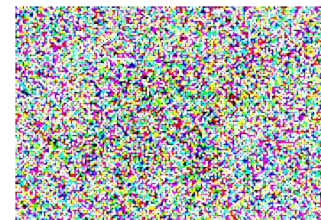
 $\sim \mathcal{N}(\mathbf{0}, I)$


 x_{t-1}

$$= \sqrt{1 - \beta_t}$$


 x_t

$$+ \sqrt{\beta_t}$$


 $\beta_1, \beta_2, \dots, \beta_T$

$$q(x_t|x_0) = q(x_1|x_0)q(x_2|x_1) \dots q(x_t|x_{t-1}) \quad \text{不用!}$$


 x_0
 $+$

 $+$


.....


 $+$

 x_t



x_1

$$= \sqrt{1 - \beta_1} \boxed{x_0} + \sqrt{\beta_1} \boxed{\text{noise}} \sim \mathcal{N}(\mathbf{0}, I)$$

x_0



x_2

$$= \sqrt{1 - \beta_2} x_1 + \sqrt{\beta_2} \text{noise} \sim \mathcal{N}(\mathbf{0}, I)$$

x_1

Ind.



x_2

$$= \sqrt{1 - \beta_2} \sqrt{1 - \beta_1} x_0 + \sqrt{1 - \beta_2} \sqrt{\beta_1} \text{noise} + \sqrt{\beta_2} \text{noise}$$

x_0

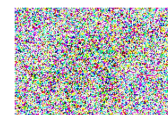


x_2

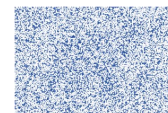
$$= \sqrt{1 - \beta_2} \sqrt{1 - \beta_1}$$



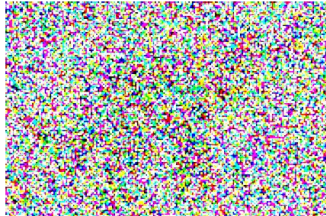
x_0

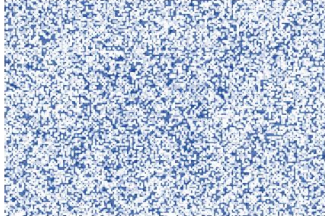


$\sim \mathcal{N}(\mathbf{0}, I)$



$\sim \mathcal{N}(\mathbf{0}, I)$

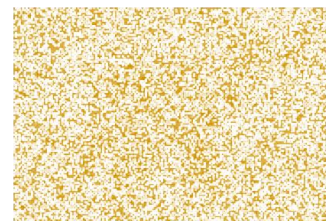
$$+ \sqrt{1 - \beta_2} \sqrt{\beta_1}$$


$$+ \sqrt{\beta_2}$$




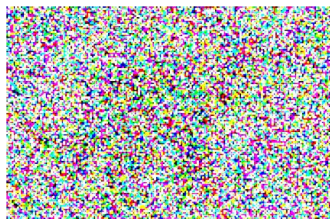
$\sim \mathcal{N}(\mathbf{0}, I)$

$$+ \sqrt{1 - (1 - \beta_2)(1 - \beta_1)}$$



$$q(x_t|x_0)$$

$$\beta_1, \beta_2, \dots, \beta_T$$



$$\sim \mathcal{N}(\mathbf{0}, I)$$

$$\alpha_t = 1 - \beta_t$$

$$\bar{\alpha}_t = \alpha_1 \alpha_2 \dots \alpha_t$$



⋮



⋮

$$= \sqrt{1 - \beta_1}$$

$$= \sqrt{1 - \beta_2}$$

⋮

$$= \sqrt{1 - \beta_t}$$



⋮

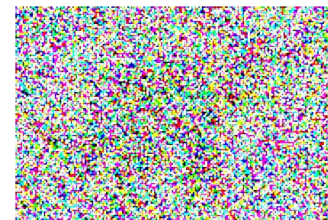
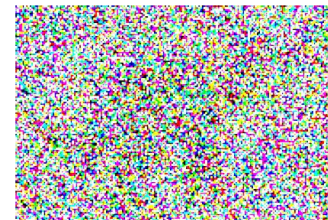


$$+ \sqrt{\beta_1}$$

$$+ \sqrt{\beta_2}$$

⋮

$$+ \sqrt{\beta_t}$$



⋮



$$= \sqrt{1 - \beta_1} \dots \sqrt{1 - \beta_t}$$

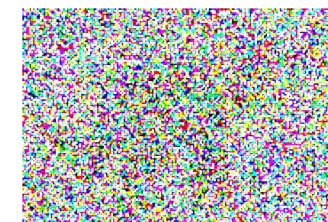
$$\sqrt{\bar{\alpha}_t}$$



+

$$\sqrt{1 - (1 - \beta_1) \dots (1 - \beta_t)}$$

$$\sqrt{1 - \bar{\alpha}_t}$$



$$\log p(\mathbf{x}) \geq \mathbb{E}_{q(\mathbf{x}_{1:T}|\mathbf{x}_0)} \left[\log \frac{p(\mathbf{x}_{0:T})}{q(\mathbf{x}_{1:T}|\mathbf{x}_0)} \right] \quad (47)$$

$$= \mathbb{E}_{q(\mathbf{x}_{1:T}|\mathbf{x}_0)} \left[\log \frac{p(\mathbf{x}_T) \prod_{t=1}^T p_{\theta}(\mathbf{x}_{t-1}|\mathbf{x}_t)}{\prod_{t=1}^T q(\mathbf{x}_t|\mathbf{x}_{t-1})} \right] \quad (48)$$

$$= \mathbb{E}_{q(\mathbf{x}_{1:T}|\mathbf{x}_0)} \left[\log \frac{p(\mathbf{x}_T) p_{\theta}(\mathbf{x}_0|\mathbf{x}_1) \prod_{t=2}^T p_{\theta}(\mathbf{x}_{t-1}|\mathbf{x}_t)}{q(\mathbf{x}_1|\mathbf{x}_0) \prod_{t=2}^T q(\mathbf{x}_t|\mathbf{x}_{t-1})} \right] \quad (49)$$

$$= \mathbb{E}_{q(\mathbf{x}_{1:T}|\mathbf{x}_0)} \left[\log \frac{p(\mathbf{x}_T) p_{\theta}(\mathbf{x}_0|\mathbf{x}_1) \prod_{t=2}^T p_{\theta}(\mathbf{x}_{t-1}|\mathbf{x}_t)}{q(\mathbf{x}_1|\mathbf{x}_0) \prod_{t=2}^T q(\mathbf{x}_t|\mathbf{x}_{t-1}, \mathbf{x}_0)} \right] \quad (50)$$

$$= \mathbb{E}_{q(\mathbf{x}_{1:T}|\mathbf{x}_0)} \left[\log \frac{p_{\theta}(\mathbf{x}_T) p_{\theta}(\mathbf{x}_0|\mathbf{x}_1)}{q(\mathbf{x}_1|\mathbf{x}_0)} + \log \prod_{t=2}^T \frac{p_{\theta}(\mathbf{x}_{t-1}|\mathbf{x}_t)}{q(\mathbf{x}_t|\mathbf{x}_{t-1}, \mathbf{x}_0)} \right] \quad (51)$$

$$= \mathbb{E}_{q(\mathbf{x}_{1:T}|\mathbf{x}_0)} \left[\log \frac{p(\mathbf{x}_T) p_{\theta}(\mathbf{x}_0|\mathbf{x}_1)}{q(\mathbf{x}_1|\mathbf{x}_0)} + \log \prod_{t=2}^T \frac{p_{\theta}(\mathbf{x}_{t-1}|\mathbf{x}_t)}{\frac{q(\mathbf{x}_{t-1}|\mathbf{x}_t, \mathbf{x}_0) q(\mathbf{x}_t|\mathbf{x}_0)}{q(\mathbf{x}_{t-1}|\mathbf{x}_0)}} \right] \quad (52)$$

$$= \mathbb{E}_{q(\mathbf{x}_{1:T}|\mathbf{x}_0)} \left[\log \frac{p(\mathbf{x}_T) p_{\theta}(\mathbf{x}_0|\mathbf{x}_1)}{q(\mathbf{x}_1|\mathbf{x}_0)} + \log \prod_{t=2}^T \frac{p_{\theta}(\mathbf{x}_{t-1}|\mathbf{x}_t)}{\frac{q(\mathbf{x}_{t-1}|\mathbf{x}_t, \mathbf{x}_0) q(\mathbf{x}_t|\mathbf{x}_0)}{q(\mathbf{x}_{t-1}|\mathbf{x}_0)}} \right] \quad (53)$$

$$= \mathbb{E}_{q(\mathbf{x}_{1:T}|\mathbf{x}_0)} \left[\log \frac{p(\mathbf{x}_T) p_{\theta}(\mathbf{x}_0|\mathbf{x}_1)}{q(\mathbf{x}_1|\mathbf{x}_0)} + \log \frac{q(\mathbf{x}_1|\mathbf{x}_0)}{q(\mathbf{x}_T|\mathbf{x}_0)} + \log \prod_{t=2}^T \frac{p_{\theta}(\mathbf{x}_{t-1}|\mathbf{x}_t)}{q(\mathbf{x}_{t-1}|\mathbf{x}_t, \mathbf{x}_0)} \right] \quad (54)$$

$$= \mathbb{E}_{q(\mathbf{x}_{1:T}|\mathbf{x}_0)} \left[\log \frac{p(\mathbf{x}_T) p_{\theta}(\mathbf{x}_0|\mathbf{x}_1)}{q(\mathbf{x}_T|\mathbf{x}_0)} + \sum_{t=2}^T \log \frac{p_{\theta}(\mathbf{x}_{t-1}|\mathbf{x}_t)}{q(\mathbf{x}_{t-1}|\mathbf{x}_t, \mathbf{x}_0)} \right] \quad (55)$$

$$= \mathbb{E}_{q(\mathbf{x}_{1:T}|\mathbf{x}_0)} [\log p_{\theta}(\mathbf{x}_0|\mathbf{x}_1)] + \mathbb{E}_{q(\mathbf{x}_{1:T}|\mathbf{x}_0)} \left[\log \frac{p(\mathbf{x}_T)}{q(\mathbf{x}_T|\mathbf{x}_0)} \right] + \sum_{t=2}^T \mathbb{E}_{q(\mathbf{x}_{1:T}|\mathbf{x}_0)} \left[\log \frac{p_{\theta}(\mathbf{x}_{t-1}|\mathbf{x}_t)}{q(\mathbf{x}_{t-1}|\mathbf{x}_t, \mathbf{x}_0)} \right] \quad (56)$$

$$= \mathbb{E}_{q(\mathbf{x}_1|\mathbf{x}_0)} [\log p_{\theta}(\mathbf{x}_0|\mathbf{x}_1)] + \mathbb{E}_{q(\mathbf{x}_T|\mathbf{x}_0)} \left[\log \frac{p(\mathbf{x}_T)}{q(\mathbf{x}_T|\mathbf{x}_0)} \right] + \sum_{t=2}^T \mathbb{E}_{q(\mathbf{x}_t, \mathbf{x}_{t-1}|\mathbf{x}_0)} \left[\log \frac{p_{\theta}(\mathbf{x}_{t-1}|\mathbf{x}_t)}{q(\mathbf{x}_{t-1}|\mathbf{x}_t, \mathbf{x}_0)} \right] \quad (57)$$

$$= \underbrace{\mathbb{E}_{q(\mathbf{x}_1|\mathbf{x}_0)} [\log p_{\theta}(\mathbf{x}_0|\mathbf{x}_1)]}_{\text{reconstruction term}} - \underbrace{D_{\text{KL}}(q(\mathbf{x}_T|\mathbf{x}_0) \parallel p(\mathbf{x}_T))}_{\text{prior matching term}} - \sum_{t=2}^T \underbrace{\mathbb{E}_{q(\mathbf{x}_t|\mathbf{x}_0)} [D_{\text{KL}}(q(\mathbf{x}_{t-1}|\mathbf{x}_t, \mathbf{x}_0) \parallel p_{\theta}(\mathbf{x}_{t-1}|\mathbf{x}_t))]}_{\text{denoising matching term}} \quad (58)$$

Understanding Diffusion Models:
A Unified Perspective

<https://arxiv.org/pdf/2208.11970.pdf>

DDPM: Lower bound of $\log P(x)$

$$\begin{aligned} \mathbb{E}_{q(x_1|x_0)}[\log P(x_0|x_1)] &- KL(q(x_T|x_0)||P(x_T)) \\ &- \sum_{t=2}^T \mathbb{E}_{q(x_t|x_0)}[KL(q(x_{t-1}|x_t, x_0)||P(x_{t-1}|x_t))] \end{aligned}$$

$$\mathbb{E}_{q(x_1|x_0)}[\log P(x_0|x_1)] - KL(q(x_T|x_0)||P(x_T))$$

$$- \sum_{t=2}^T \mathbb{E}_{q(x_t|x_0)} [KL(q(x_{t-1}|x_t, x_0)||P(x_{t-1}|x_t))]$$

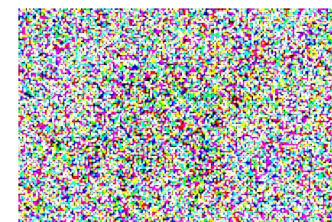
$$q(x_t|x_0)$$



$$= \sqrt{\bar{\alpha}_t}$$



$$+ \sqrt{1 - \bar{\alpha}_t}$$



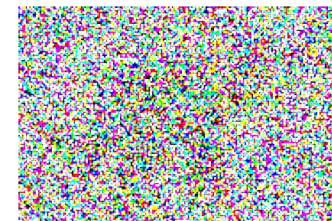
$$q(x_{t-1}|x_0)$$



$$= \sqrt{\bar{\alpha}_{t-1}}$$



$$+ \sqrt{1 - \bar{\alpha}_{t-1}}$$



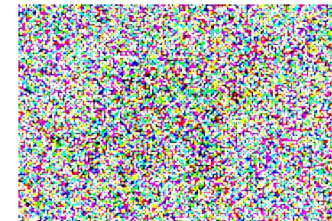
$$q(x_t|x_{t-1})$$



$$= \sqrt{1 - \beta_t}$$



$$+ \sqrt{\beta_t}$$



$$\mathbb{E}_{q(x_1|x_0)}[\log P(x_0|x_1)] - KL(q(x_T|x_0)||P(x_T))$$

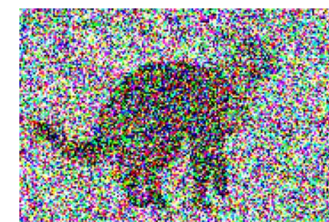
$$- \sum_{t=2}^T \mathbb{E}_{q(x_t|x_0)} [KL(q(x_{t-1}|x_t, x_0)||P(x_{t-1}|x_t))]$$



x_0



x_{t-1}



x_t

$$q(x_{t-1}|x_t, x_0)$$

$$q(x_t|x_0)$$

$$q(x_{t-1}|x_0)$$

$$q(x_t|x_{t-1})$$

$$= \frac{q(x_{t-1}, x_t, x_0)}{q(x_t, x_0)} = \frac{q(x_t|x_{t-1})q(x_{t-1}|x_0)q(x_0)}{q(x_t|x_0)q(x_0)} = \frac{q(x_t|x_{t-1})q(x_{t-1}|x_0)}{q(x_t|x_0)}$$

$$q(\mathbf{x}_{t-1}|\mathbf{x}_t, \mathbf{x}_0) = \frac{q(\mathbf{x}_t|\mathbf{x}_{t-1}, \mathbf{x}_0)q(\mathbf{x}_{t-1}|\mathbf{x}_0)}{q(\mathbf{x}_t|\mathbf{x}_0)} \quad (71)$$

$$= \frac{\mathcal{N}(\mathbf{x}_t; \sqrt{\alpha_t}\mathbf{x}_{t-1}, (1 - \alpha_t)\mathbf{I})\mathcal{N}(\mathbf{x}_{t-1}; \sqrt{\bar{\alpha}_{t-1}}\mathbf{x}_0, (1 - \bar{\alpha}_{t-1})\mathbf{I})}{\mathcal{N}(\mathbf{x}_t; \sqrt{\bar{\alpha}_t}\mathbf{x}_0, (1 - \bar{\alpha}_t)\mathbf{I})} \quad (72)$$

$$\propto \exp \left\{ - \left[\frac{(\mathbf{x}_t - \sqrt{\alpha_t}\mathbf{x}_{t-1})^2}{2(1 - \alpha_t)} + \frac{(\mathbf{x}_{t-1} - \sqrt{\bar{\alpha}_{t-1}}\mathbf{x}_0)^2}{2(1 - \bar{\alpha}_{t-1})} - \frac{(\mathbf{x}_t - \sqrt{\bar{\alpha}_t}\mathbf{x}_0)^2}{2(1 - \bar{\alpha}_t)} \right] \right\} \quad (73)$$

$$= \exp \left\{ - \frac{1}{2} \left[\frac{(\mathbf{x}_t - \sqrt{\alpha_t}\mathbf{x}_{t-1})^2}{1 - \alpha_t} + \frac{(\mathbf{x}_{t-1} - \sqrt{\bar{\alpha}_{t-1}}\mathbf{x}_0)^2}{1 - \bar{\alpha}_{t-1}} - \frac{(\mathbf{x}_t - \sqrt{\bar{\alpha}_t}\mathbf{x}_0)^2}{1 - \bar{\alpha}_t} \right] \right\} \quad (74)$$

$$= \exp \left\{ - \frac{1}{2} \left[\frac{(-2\sqrt{\alpha_t}\mathbf{x}_t\mathbf{x}_{t-1} + \alpha_t\mathbf{x}_{t-1}^2)}{1 - \alpha_t} + \frac{(\mathbf{x}_{t-1}^2 - 2\sqrt{\bar{\alpha}_{t-1}}\mathbf{x}_{t-1}\mathbf{x}_0)}{1 - \bar{\alpha}_{t-1}} + C(\mathbf{x}_t, \mathbf{x}_0) \right] \right\} \quad (75)$$

$$\propto \exp \left\{ - \frac{1}{2} \left[- \frac{2\sqrt{\alpha_t}\mathbf{x}_t\mathbf{x}_{t-1}}{1 - \alpha_t} + \frac{\alpha_t\mathbf{x}_{t-1}^2}{1 - \alpha_t} + \frac{\mathbf{x}_{t-1}^2}{1 - \bar{\alpha}_{t-1}} - \frac{2\sqrt{\bar{\alpha}_{t-1}}\mathbf{x}_{t-1}\mathbf{x}_0}{1 - \bar{\alpha}_{t-1}} \right] \right\} \quad (76)$$

$$= \exp \left\{ - \frac{1}{2} \left[\left(\frac{\alpha_t}{1 - \alpha_t} + \frac{1}{1 - \bar{\alpha}_{t-1}} \right) \mathbf{x}_{t-1}^2 - 2 \left(\frac{\sqrt{\alpha_t}\mathbf{x}_t}{1 - \alpha_t} + \frac{\sqrt{\bar{\alpha}_{t-1}}\mathbf{x}_0}{1 - \bar{\alpha}_{t-1}} \right) \mathbf{x}_{t-1} \right] \right\} \quad (77)$$

$$= \exp \left\{ - \frac{1}{2} \left[\frac{\alpha_t(1 - \bar{\alpha}_{t-1}) + 1 - \alpha_t}{(1 - \alpha_t)(1 - \bar{\alpha}_{t-1})} \mathbf{x}_{t-1}^2 - 2 \left(\frac{\sqrt{\alpha_t}\mathbf{x}_t}{1 - \alpha_t} + \frac{\sqrt{\bar{\alpha}_{t-1}}\mathbf{x}_0}{1 - \bar{\alpha}_{t-1}} \right) \mathbf{x}_{t-1} \right] \right\} \quad (78)$$

$$= \exp \left\{ - \frac{1}{2} \left[\frac{\alpha_t - \bar{\alpha}_t + 1 - \alpha_t}{(1 - \alpha_t)(1 - \bar{\alpha}_{t-1})} \mathbf{x}_{t-1}^2 - 2 \left(\frac{\sqrt{\alpha_t}\mathbf{x}_t}{1 - \alpha_t} + \frac{\sqrt{\bar{\alpha}_{t-1}}\mathbf{x}_0}{1 - \bar{\alpha}_{t-1}} \right) \mathbf{x}_{t-1} \right] \right\} \quad (79)$$

$$= \exp \left\{ - \frac{1}{2} \left[\frac{1 - \bar{\alpha}_t}{(1 - \alpha_t)(1 - \bar{\alpha}_{t-1})} \mathbf{x}_{t-1}^2 - 2 \left(\frac{\sqrt{\alpha_t}\mathbf{x}_t}{1 - \alpha_t} + \frac{\sqrt{\bar{\alpha}_{t-1}}\mathbf{x}_0}{1 - \bar{\alpha}_{t-1}} \right) \mathbf{x}_{t-1} \right] \right\} \quad (80)$$

$$= \exp \left\{ - \frac{1}{2} \left(\frac{1 - \bar{\alpha}_t}{(1 - \alpha_t)(1 - \bar{\alpha}_{t-1})} \right) \left[\mathbf{x}_{t-1}^2 - 2 \frac{\left(\frac{\sqrt{\alpha_t}\mathbf{x}_t}{1 - \alpha_t} + \frac{\sqrt{\bar{\alpha}_{t-1}}\mathbf{x}_0}{1 - \bar{\alpha}_{t-1}} \right)}{\frac{1 - \bar{\alpha}_t}{(1 - \alpha_t)(1 - \bar{\alpha}_{t-1})}} \mathbf{x}_{t-1} \right] \right\} \quad (81)$$

$$= \exp \left\{ - \frac{1}{2} \left(\frac{1 - \bar{\alpha}_t}{(1 - \alpha_t)(1 - \bar{\alpha}_{t-1})} \right) \left[\mathbf{x}_{t-1}^2 - 2 \frac{\left(\frac{\sqrt{\alpha_t}\mathbf{x}_t}{1 - \alpha_t} + \frac{\sqrt{\bar{\alpha}_{t-1}}\mathbf{x}_0}{1 - \bar{\alpha}_{t-1}} \right) (1 - \alpha_t)(1 - \bar{\alpha}_{t-1})}{1 - \bar{\alpha}_t} \mathbf{x}_{t-1} \right] \right\} \quad (82)$$

$$= \exp \left\{ - \frac{1}{2} \left(\frac{1}{\frac{(1 - \alpha_t)(1 - \bar{\alpha}_{t-1})}{1 - \bar{\alpha}_t}} \right) \left[\mathbf{x}_{t-1}^2 - 2 \frac{\sqrt{\alpha_t}(1 - \bar{\alpha}_{t-1})\mathbf{x}_t + \sqrt{\bar{\alpha}_{t-1}}(1 - \alpha_t)\mathbf{x}_0}{1 - \bar{\alpha}_t} \mathbf{x}_{t-1} \right] \right\} \quad (83)$$

$$\propto \mathcal{N}(\mathbf{x}_{t-1}; \underbrace{\frac{\sqrt{\alpha_t}(1 - \bar{\alpha}_{t-1})\mathbf{x}_t + \sqrt{\bar{\alpha}_{t-1}}(1 - \alpha_t)\mathbf{x}_0}{1 - \bar{\alpha}_t}}_{\mu_q(\mathbf{x}_t, \mathbf{x}_0)}, \underbrace{\frac{(1 - \alpha_t)(1 - \bar{\alpha}_{t-1})}{1 - \bar{\alpha}_t}}_{\Sigma_q(t)} \mathbf{I}) \quad (84)$$

$$\mathbb{E}_{q(x_1|x_0)}[\log P(x_0|x_1)] - KL(q(x_T|x_0)||P(x_T))$$

$$- \sum_{t=2}^T \mathbb{E}_{q(x_t|x_0)} [KL(q(x_{t-1}|x_t, x_0)||P(x_{t-1}|x_t))]$$



.....

Gaussian



.....>



Mean

Variance

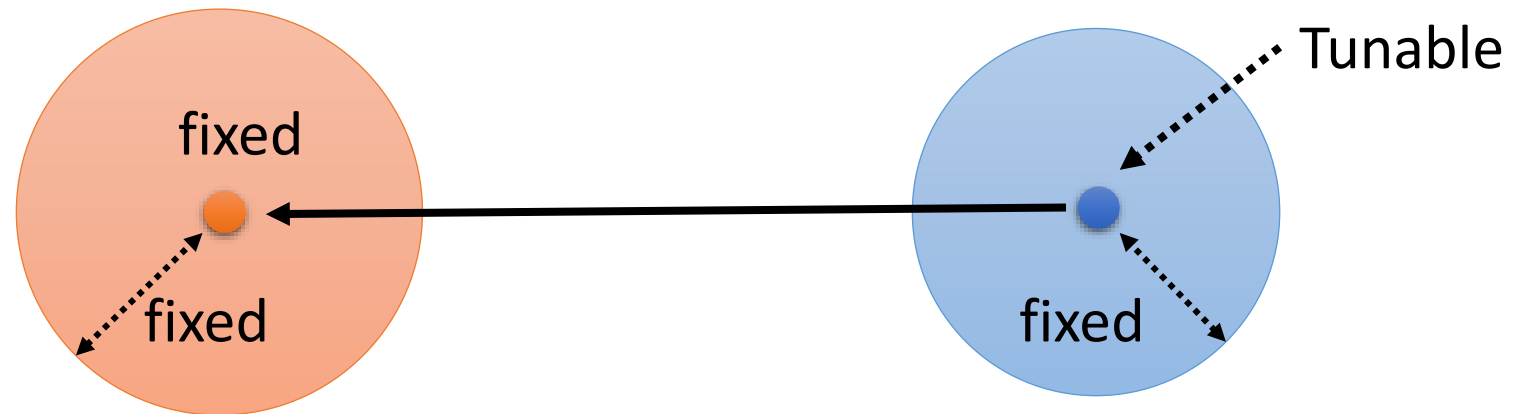
$$\frac{\sqrt{\bar{\alpha}_{t-1}}\beta_t x_0 + \sqrt{\alpha_t}(1 - \bar{\alpha}_{t-1})x_t}{1 - \bar{\alpha}_t}$$

$$\frac{1 - \bar{\alpha}_{t-1}}{1 - \bar{\alpha}_t} \beta_t I$$

$$\mathbb{E}_{q(x_1|x_0)}[\log P(x_0|x_1)] - KL(q(x_T|x_0)||P(x_T))$$

$$- \sum_{t=2}^T \mathbb{E}_{q(x_t|x_0)}[KL(q(x_{t-1}|x_t, x_0)||P(x_{t-1}|x_t))]$$

How to minimize
KL divergence?



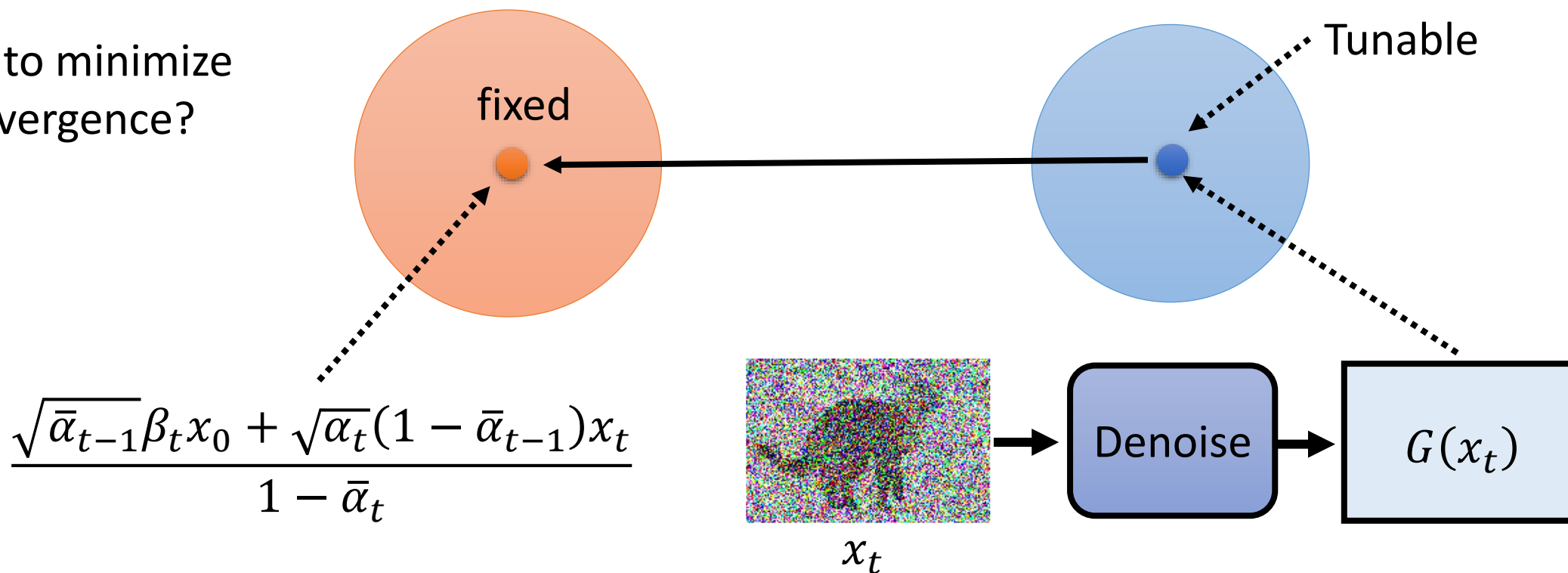
Recall that the KL Divergence between two Gaussian distributions is:

$$D_{\text{KL}}(\mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_x, \boldsymbol{\Sigma}_x) \parallel \mathcal{N}(\mathbf{y}; \boldsymbol{\mu}_y, \boldsymbol{\Sigma}_y)) = \frac{1}{2} \left[\log \frac{|\boldsymbol{\Sigma}_y|}{|\boldsymbol{\Sigma}_x|} - d + \text{tr}(\boldsymbol{\Sigma}_y^{-1} \boldsymbol{\Sigma}_x) + (\boldsymbol{\mu}_y - \boldsymbol{\mu}_x)^T \boldsymbol{\Sigma}_y^{-1} (\boldsymbol{\mu}_y - \boldsymbol{\mu}_x) \right]$$

$$\mathbb{E}_{q(x_1|x_0)}[\log P(x_0|x_1)] - KL(q(x_T|x_0)||P(x_T))$$

$$- \sum_{t=2}^T \mathbb{E}_{q(x_t|x_0)}[KL(q(x_{t-1}|x_t, x_0)||P(x_{t-1}|x_t)))]$$

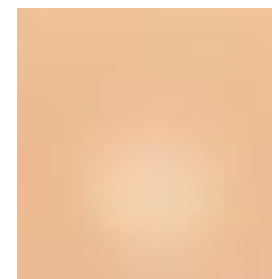
How to minimize
KL divergence?



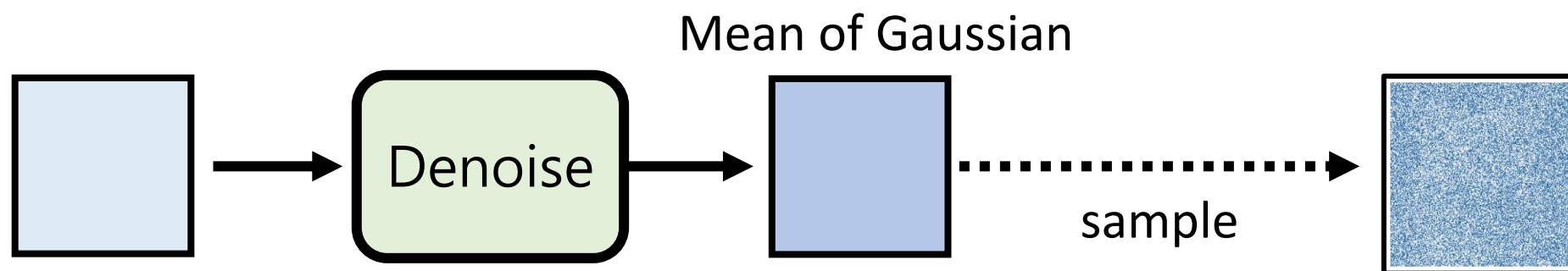
Algorithm 2 Sampling

```
1:  $\mathbf{x}_T \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$ 
2: for  $t = T, \dots, 1$  do
3:    $\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$  if  $t > 1$ , else  $\mathbf{z} = \mathbf{0}$ 
4:    $\mathbf{x}_{t-1} = \frac{1}{\sqrt{\alpha_t}} \left( \mathbf{x}_t - \frac{1-\alpha_t}{\sqrt{1-\bar{\alpha}_t}} \epsilon_{\theta}(\mathbf{x}_t, t) \right) + \underline{\sigma_t \mathbf{z}}$ 
5: end for
6: return  $\mathbf{x}_0$ 
```

$$\sigma_t = 0$$

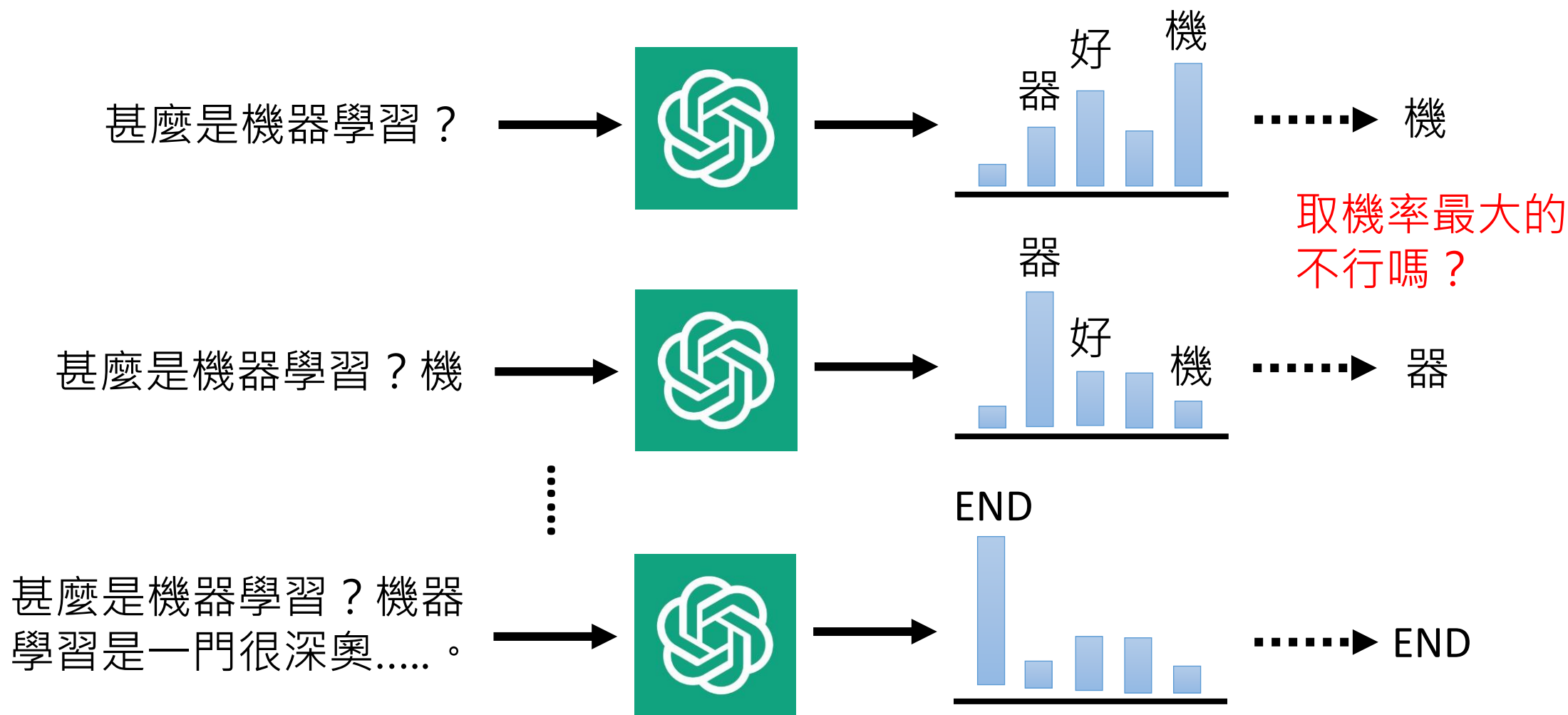


感謝伏宇寬助教提供結果



為什麼不直接取 Mean ?

為什麼生成文句時需要 Sample ？



為什麼生成文句時需要 Sample ?

- The Curious Case of Neural Text Degeneration

<https://arxiv.org/abs/1904.09751>

Context: In a shocking finding, scientist discovered a herd of unicorns living in a remote, previously unexplored valley, in the Andes Mountains. Even more surprising to the researchers was the fact that the unicorns spoke perfect English.

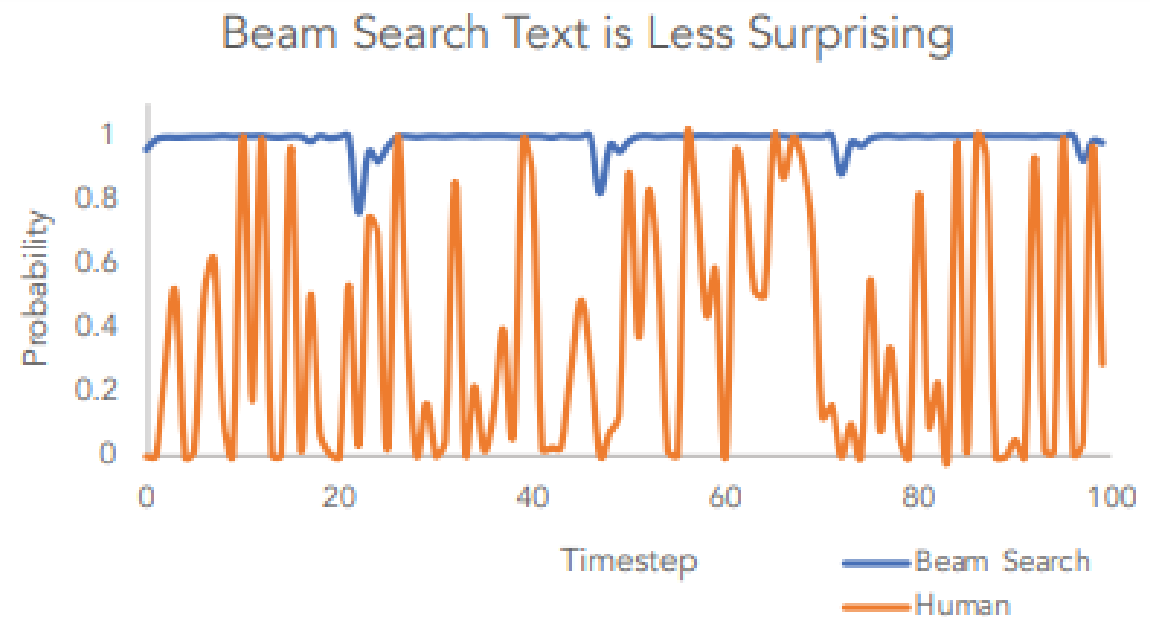
Beam Search, $b=32$:

"The study, published in the Proceedings of the National Academy of Sciences of the United States of America (PNAS), was conducted by researchers from the Universidad Nacional Autónoma de México (UNAM) and the Universidad Nacional Autónoma de México (UNAM/Universidad Nacional Autónoma de México/Universidad Nacional Autónoma de México/Universidad Nacional Autónoma de México/Universidad Nacional Autónoma de ..."

Pure Sampling:

They were cattle called Bolivian Cavalleros; they live in a remote desert uninterrupted by town, and they speak huge, beautiful, paradisiacal Bolivian linguistic thing. They say, 'Lunch, marge.' They don't tell what the lunch is," director Professor Chuperas Omwell told Sky News. "They've only been talking to scientists, like we're being interviewed by TV reporters. We don't even stick around to be interviewed by TV reporters. Maybe that's how they figured out that they're cosplaying as the Bolivian Cavalleros."

<https://arxiv.org/abs/1904.09751>



Beam Search

...to provide an overview of the current state-of-the-art in the field of computer vision and machine learning, and to provide an overview of the current state-of-the-art in the field of computer vision and machine learning, and to provide an overview of the current state-of-the-art in the field of computer vision and machine learning, and to provide an overview of the current state-of-the-art in the field of computer vision and machine learning, and to provide an overview of the current state-of-the-art in the field of computer vision and machine learning, and...

Human

...which grant increased life span and three years warranty. The Antec HCG series consists of five models with capacities spanning from 400W to 900W. Here we should note that we have already tested the HCG-620 in a previous review and were quite satisfied With its performance. In today's review we will rigorously test the Antec HCG-520, which as its model number implies, has 520W capacity and contrary to Antec's strong beliefs in multi-rail PSUs is equipped...

語音合成也需要 Sampling !

<https://arxiv.org/abs/1712.05884>

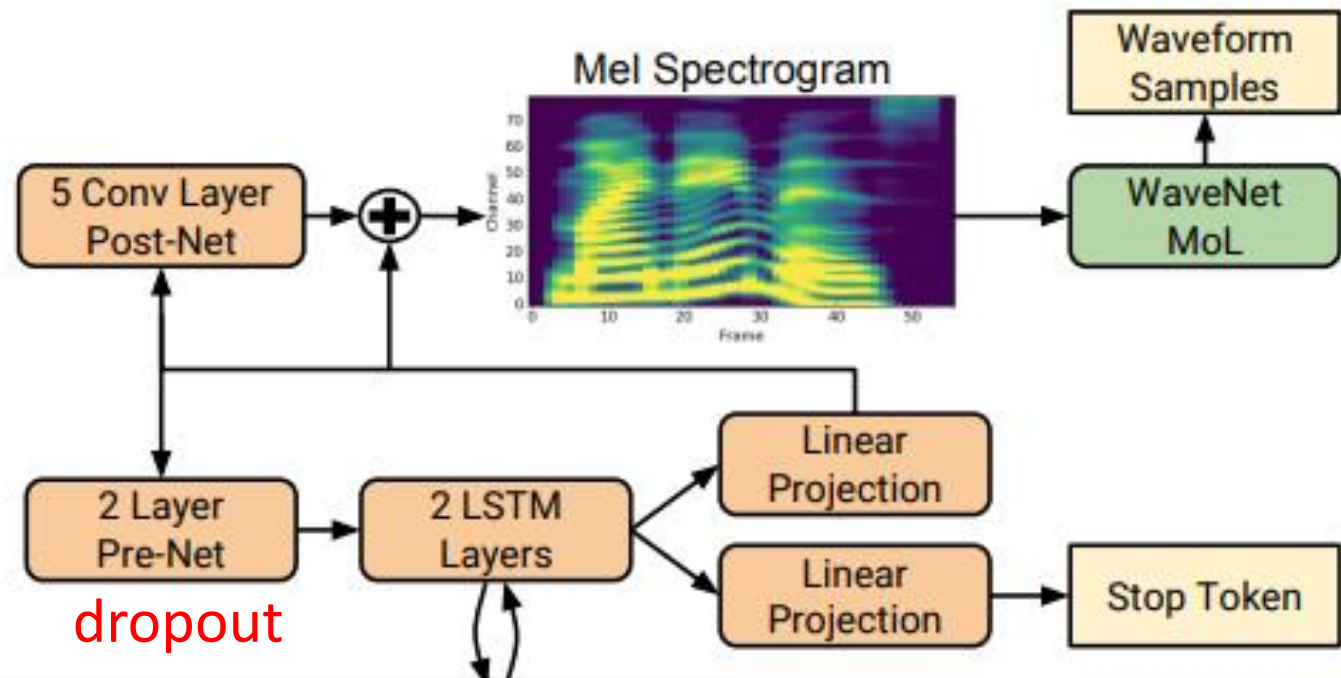


with
dropout

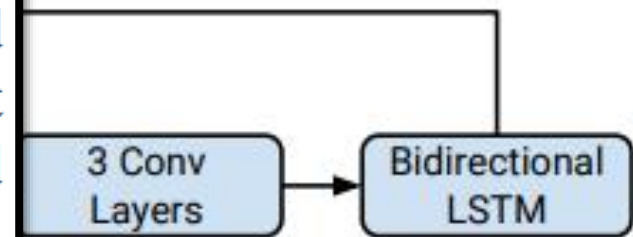


without
dropout

感謝杜濤同學提供實驗結果

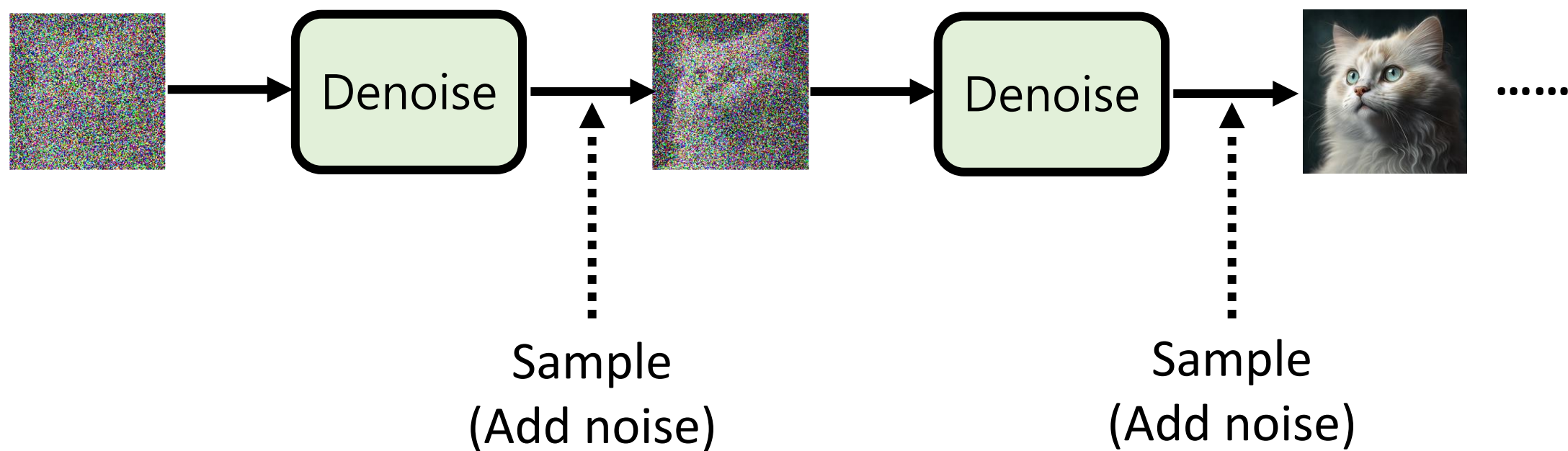


The convolutional layers in the network are regularized using dropout [25] with probability 0.5, and LSTM layers are regularized using zoneout [26] with probability 0.1. In order to introduce output variation at inference time, dropout with probability 0.5 is applied only to layers in the pre-net of the autoregressive decoder.



Diffusion Model 是一種 Autoregressive

「一次到位」改成「N次到位」



Denoising Diffusion Probabilistic Models

Algorithm 1 Training

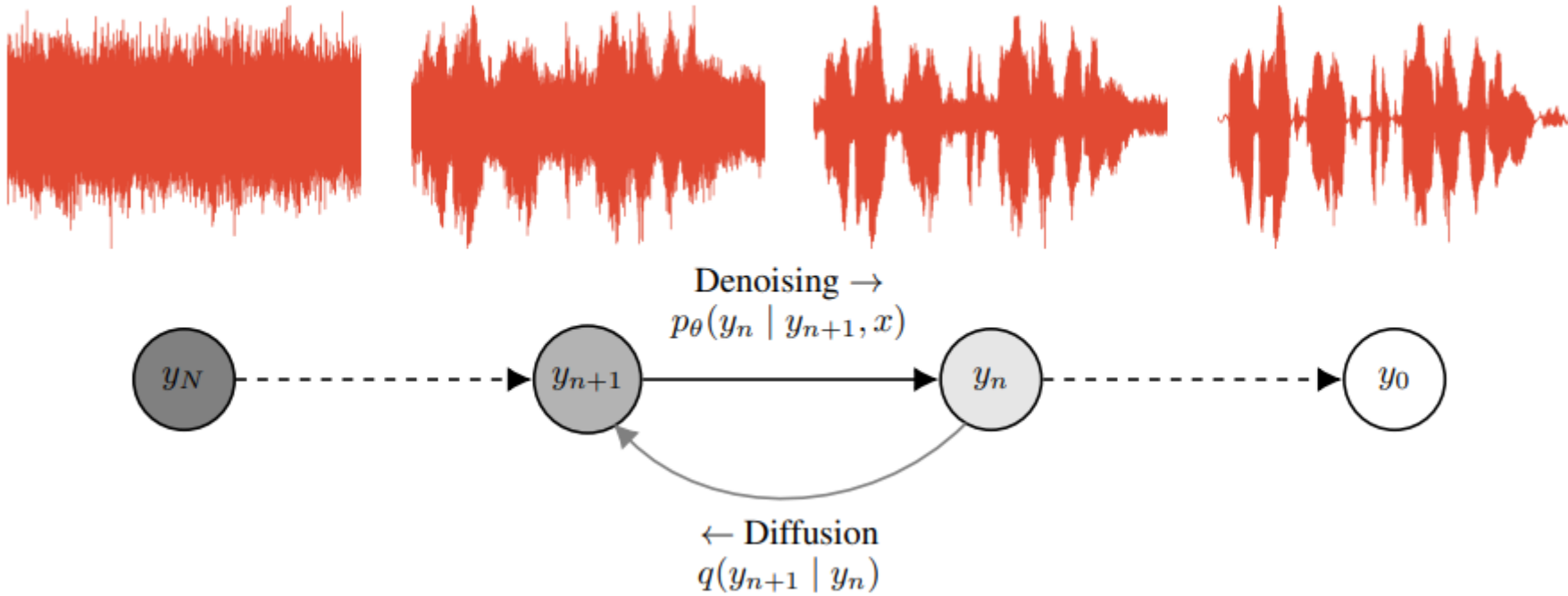
```
1: repeat  
2:    $\mathbf{x}_0 \sim q(\mathbf{x}_0)$   
3:    $t \sim \text{Uniform}(\{1, \dots, T\})$   
4:    $\epsilon \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$   
5:   Take gradient descent step on  
       $\nabla_{\theta} \|\epsilon - \epsilon_{\theta}(\sqrt{\bar{\alpha}_t}\mathbf{x}_0 + \sqrt{1 - \bar{\alpha}_t}\epsilon, t)\|^2$   
6: until converged
```

Algorithm 2 Sampling

```
1:  $\mathbf{x}_T \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$   
2: for  $t = T, \dots, 1$  do  
3:    $\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$  if  $t > 1$ , else  $\mathbf{z} = \mathbf{0}$   
4:    $\mathbf{x}_{t-1} = \frac{1}{\sqrt{\alpha_t}} \left( \mathbf{x}_t - \frac{1 - \alpha_t}{\sqrt{1 - \bar{\alpha}_t}} \epsilon_{\theta}(\mathbf{x}_t, t) \right) + \sigma_t \mathbf{z}$   
5: end for  
6: return  $\mathbf{x}_0$ 
```

Diffusion Model for Speech

- WaveGrad



<https://arxiv.org/abs/2009.00713>

Diffusion Model for Text

- Difficulty:

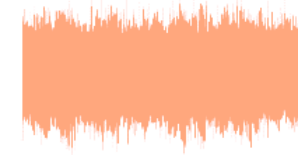
你 好 嗎 ?



...

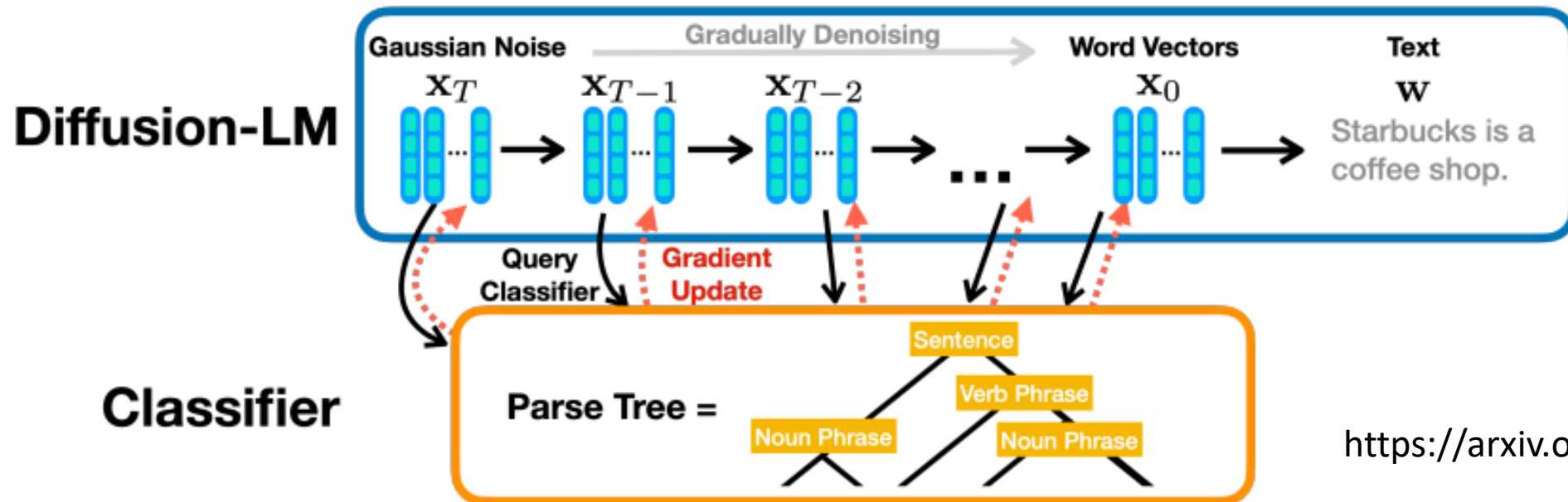


...



Add noise

- Solution: Noise on latent space



Diffusion Model for Text

- Difficulty:

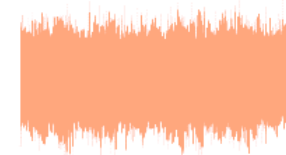
你 好 嗎 ?



...

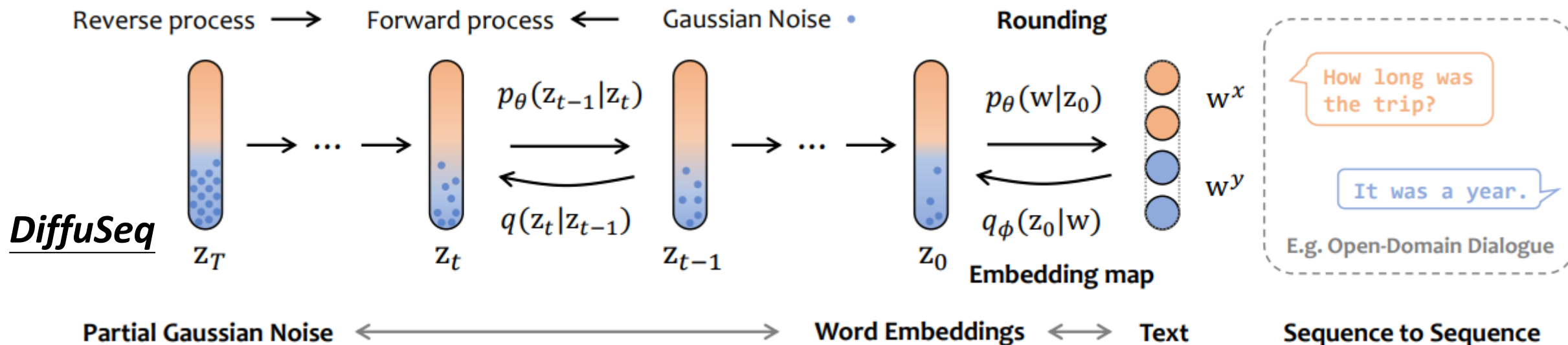


...



Add noise

- Solution: Noise on latent space

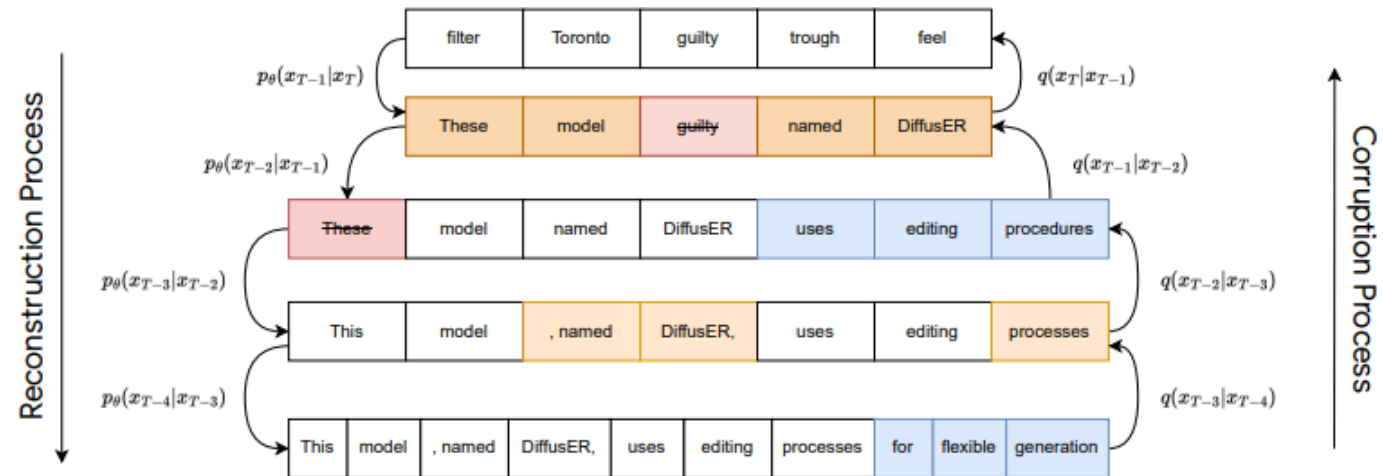


Diffusion Model for Text

- Solution: Don't add Gaussian noise

<https://arxiv.org/abs/2210.16886>

Diffusion via Edit-based Reconstruction (DiffusER)



`t = 128 [MASK] [MASK] [MASK] [MASK] [MASK] [MASK]...`

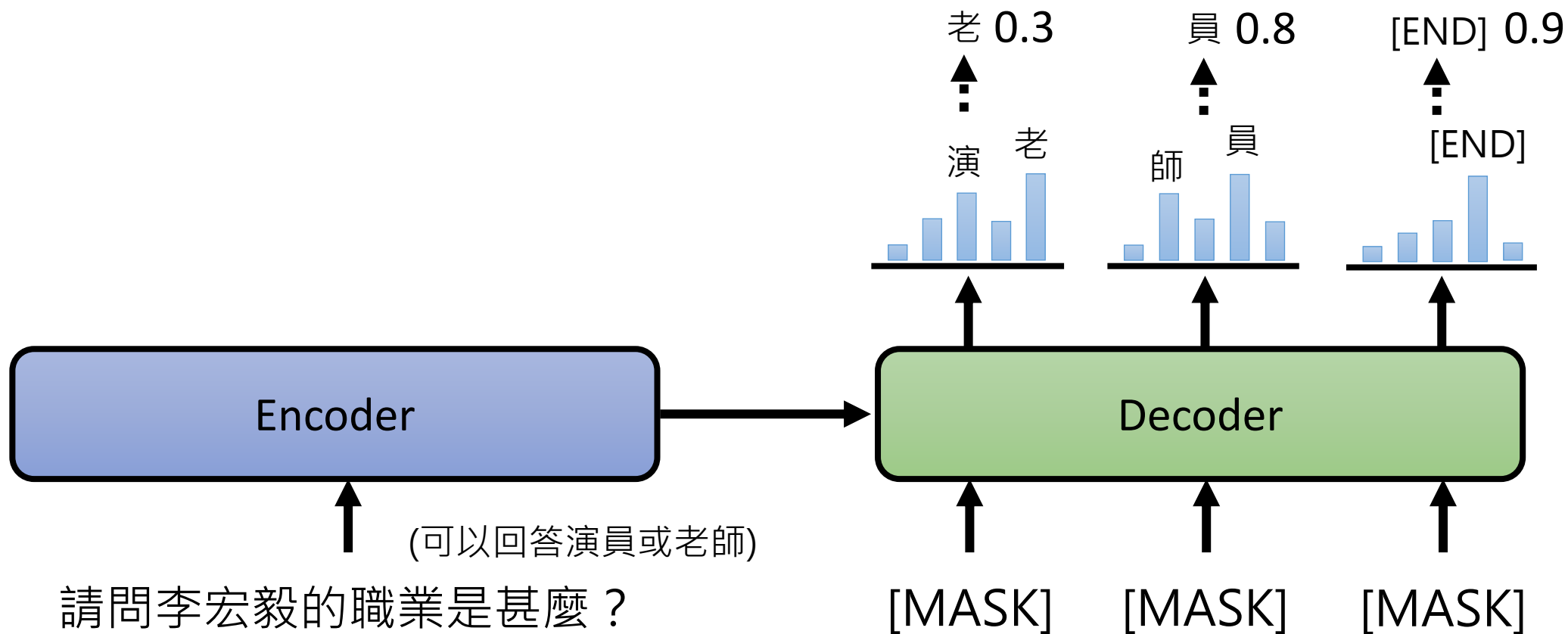
`t = 25 In response [MASK] the demands , [MASK] [MASK]y Workers
union said [MASK] backflow fund [MASK]s would face further
investigation and a fine.`

`t = 0 In response to the demands , the Community Workers union
said the backflow fund managers would face further investigation
and a fine .`

<https://arxiv.org/abs/2107.03006>

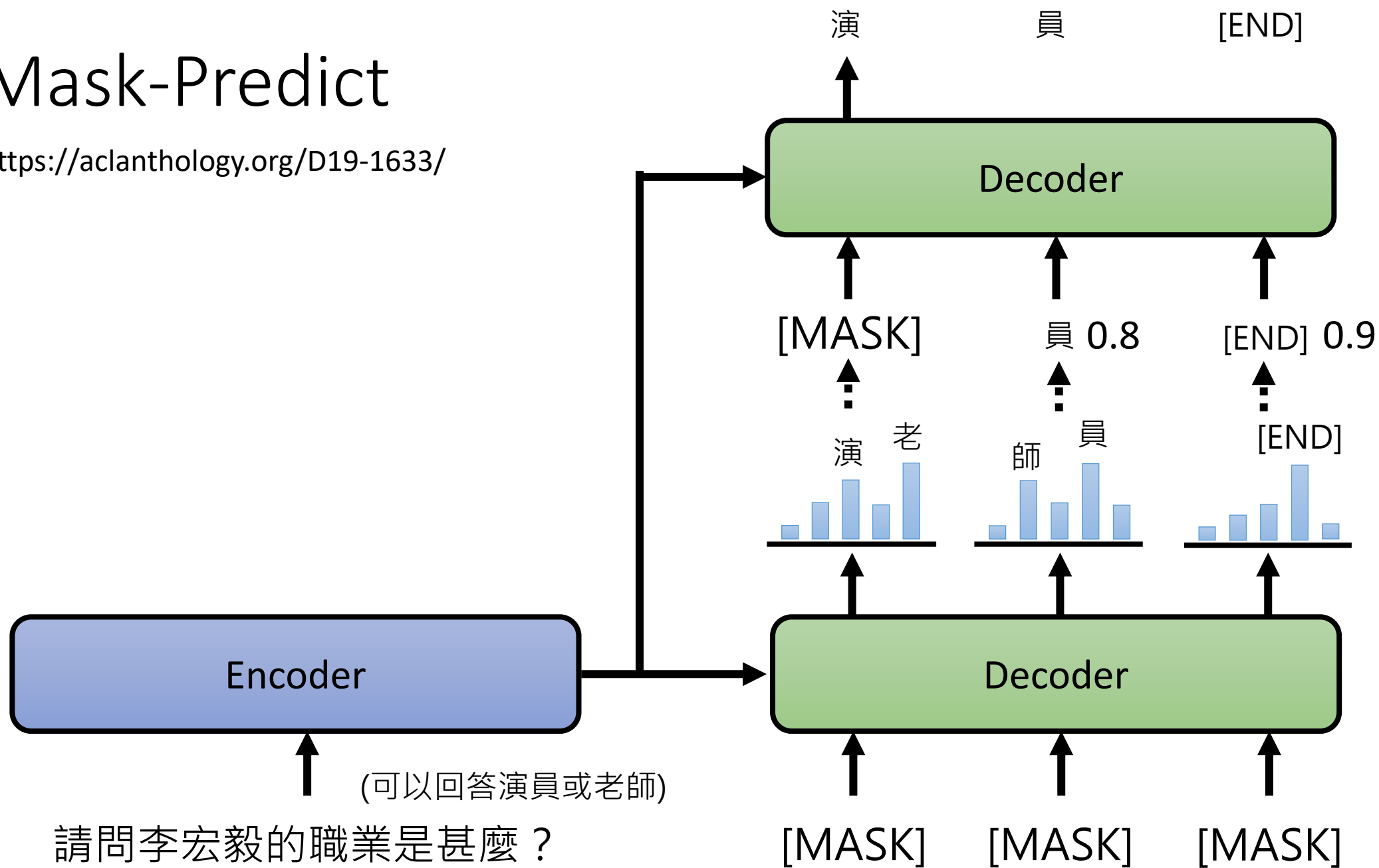
Mask-Predict

<https://aclanthology.org/D19-1633/>



Mask-Predict

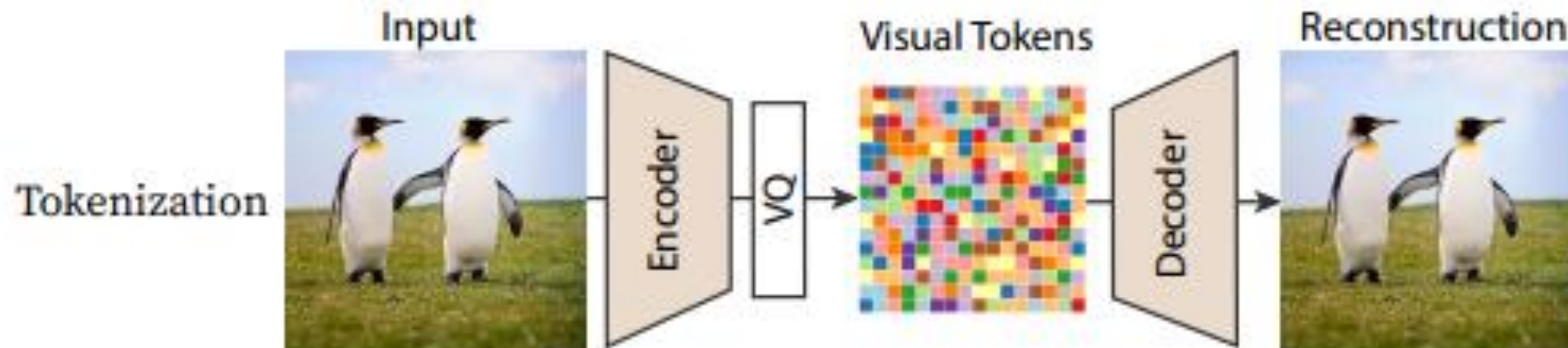
<https://aclanthology.org/D19-1633/>



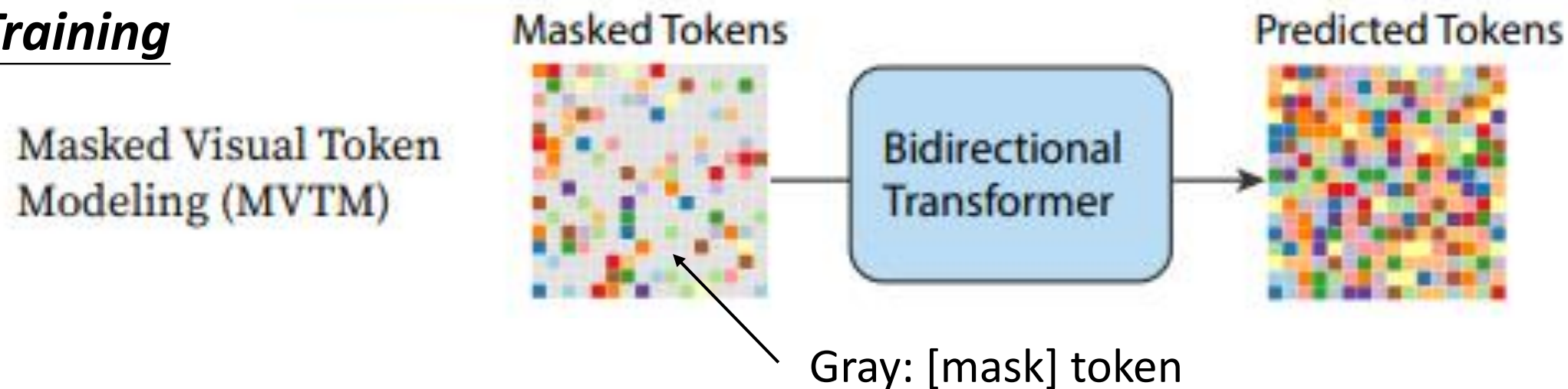
<https://arxiv.org/abs/2202.04200>

<https://arxiv.org/abs/2301.00704>

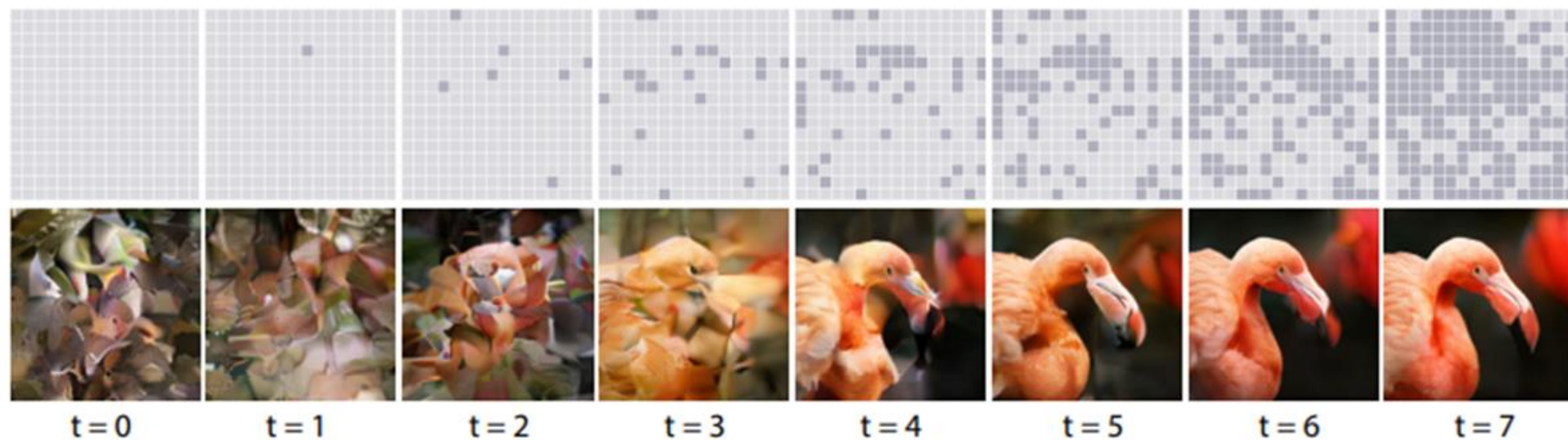
Mask-Predict



Training



Scheduled
Parallel
Decoding
with MaskGIT



Sequential
Decoding
with Autoregressive
Transformers

