

Recurrent Network

11-785 Introduction to Deep Learning
– lecture 14 & 15 –

TAVE Research DL001

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Contents

1. Benefits of RNN
2. Stability
3. Exploding/Vanishing Gradient Problems
4. LSTMs and variants
5. Loss Functions for RNN
6. Sequence prediction

Contents

1. Benefits of RNN

2. Stability

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4. LSTMs and variants

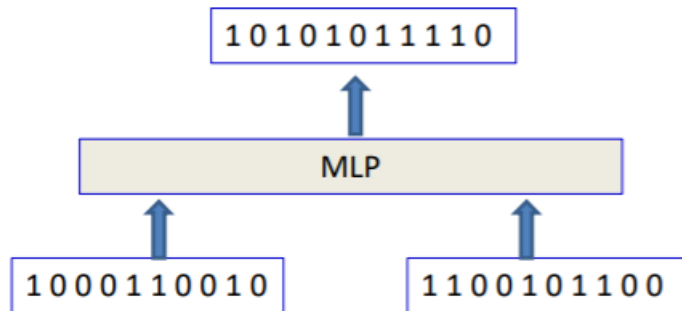
5. Loss Functions for RNN

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01. Benefits of RNN

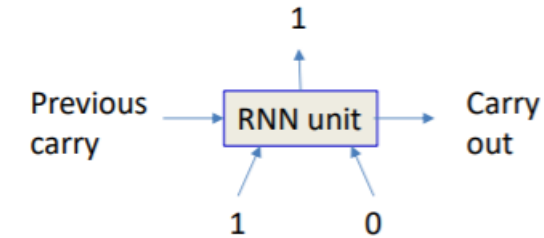
- Examples

- Add two N-bit number to produce N+1-bit number
- Input is binary



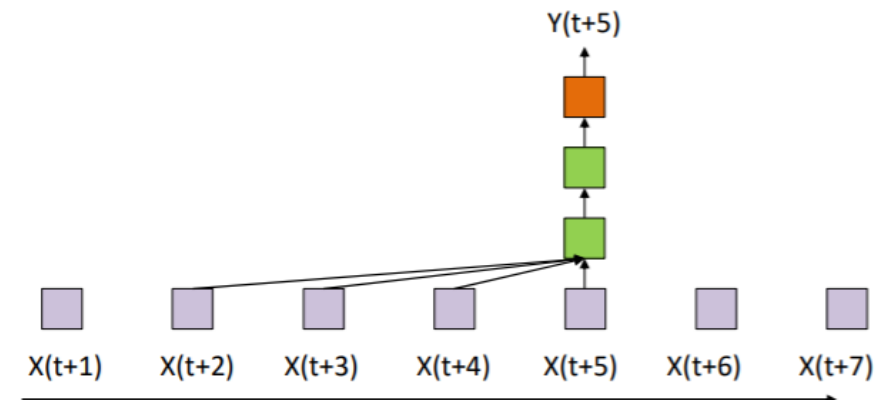
- ✓ Require large number of training instances ($2^N \times 2^N$)
- ✓ not work for N+1 bit numbers

- How about RNN?



- ✓ Needs very little training data ($2 \times 2 \times 2$)
- ✓ Can add two numbers of any size

- RNN



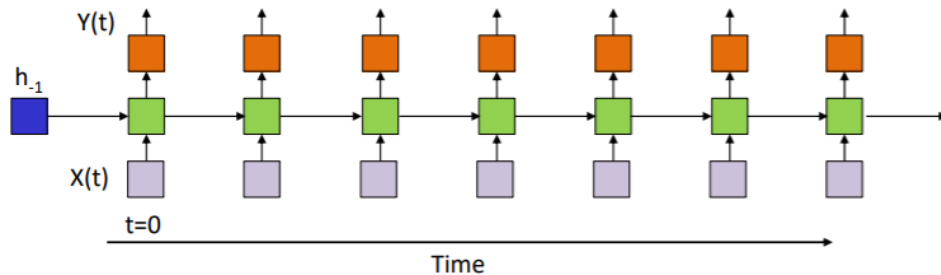
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02. Stability

- "BIBO" Stability

- "Bounded Input Bounded Output" stability
- Guaranteed if output and hidden activation are bounded
- do



✓ But will it saturate

"Streetlight effect"



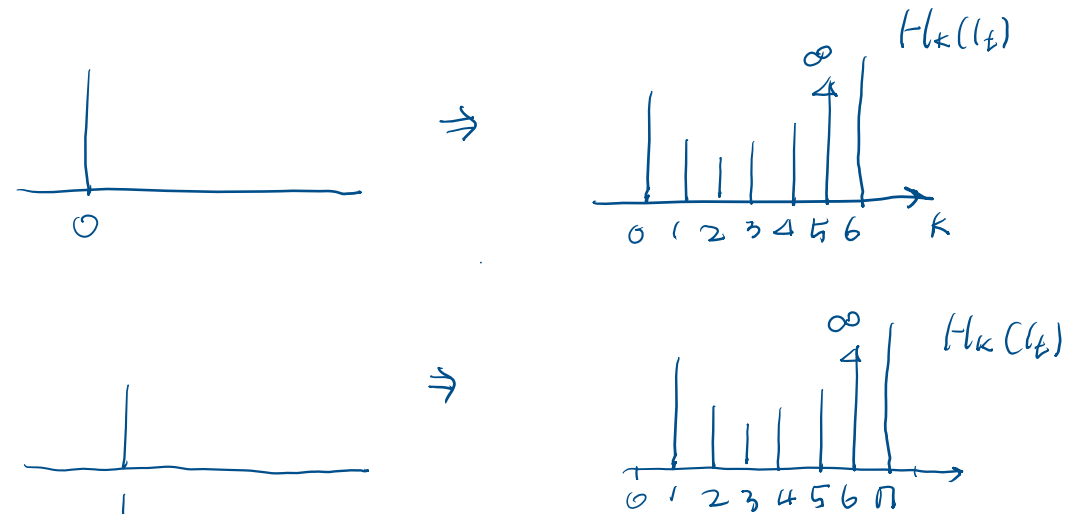
- Linear systems

$$h_k = W_h h_{k-1} + W_x x_k$$

$$= W_h^{k+1} h_{-1} + W_h^k W_x x_0 + W_h^{k-1} W_x x_1 + W_h^{k-2} W_x x_2 + \dots$$

$$= H_k(h_{-1}) + H_k(x_0) + H_k(x_1) + H_k(x_2) + \dots$$

$$= h_{-1} H_k(1_{-1}) + \boxed{x_0 H_k(1_0)} + x_1 H_k(1_1) + x_2 H_k(1_2) + \dots$$



✓ Focus on second term ($W_h^k W_x x_0$)!

02. Stability

- The rate of blow up or vanishing

$$h_k = W_h^{k+1}h_{-1} + \underbrace{W_h^k W_x x_0}_{\text{focus on this term}} + W_h^{k-1}W_x x_1 + W_h^{k-2}W_x x_2 + \dots$$

$$W_h = U\Lambda U^{-1} \Leftrightarrow W_h u_i = \lambda_i u_i$$

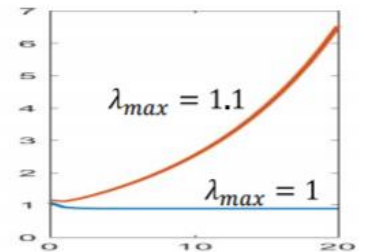
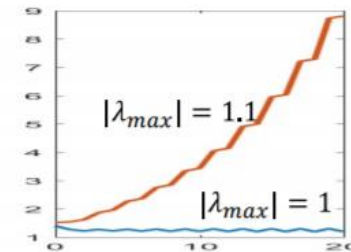
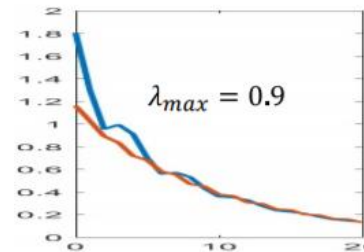
$$x' = W_x x = a_1 u_1 + a_2 u_2 + \dots + a_n u_n$$

$$W_h x' = a_1 \lambda_1 u_1 + a_2 \lambda_2 u_2 + \dots + a_n \lambda_n u_n$$

$$W_h^t x' = a_1 \lambda_1^t u_1 + a_2 \lambda_2^t u_2 + \dots + a_n \lambda_n^t u_n$$

$$\lim_{t \rightarrow \infty} |W_h^t x'| = a_m \lambda_m^t u_m \quad \text{where } m = \operatorname{argmax}_j \lambda_j$$

- ✓ If $|\lambda_{\max}| > 1$ it will **blow up**, otherwise it will contract and shrink to 0 rapidly
- ✓ The rate of blow up or vanishing depends only on the **Eigen values** (not on the input)



02. Stability

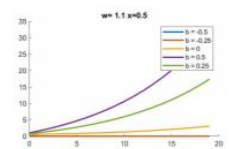
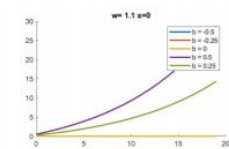
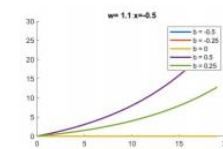
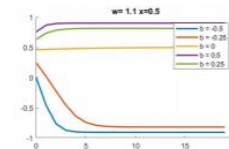
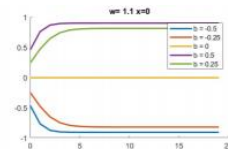
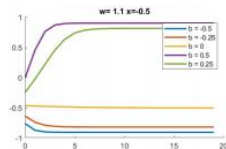
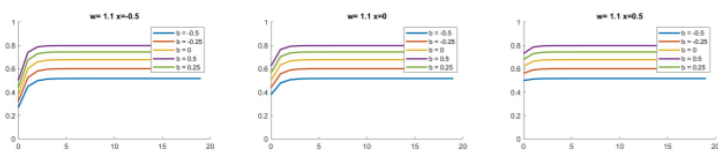
- How about non-linear activations?

<Sigmoid>

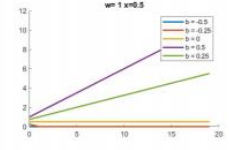
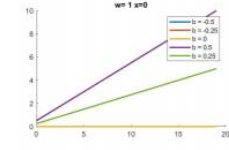
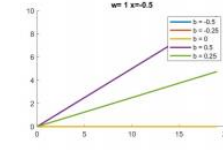
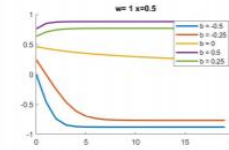
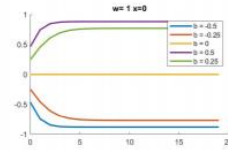
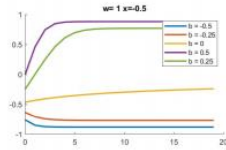
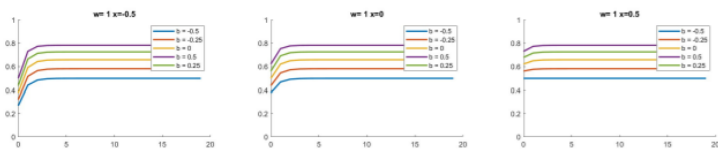
<tanh>

<RELU>

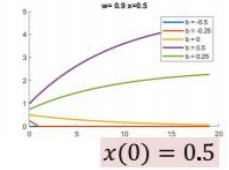
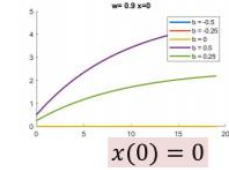
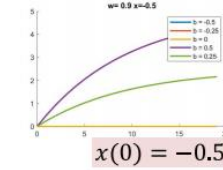
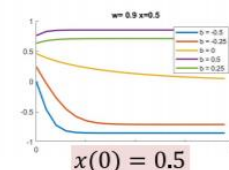
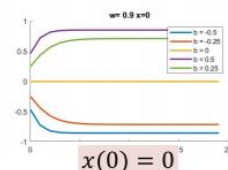
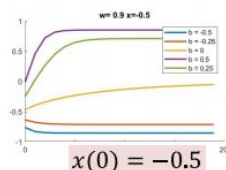
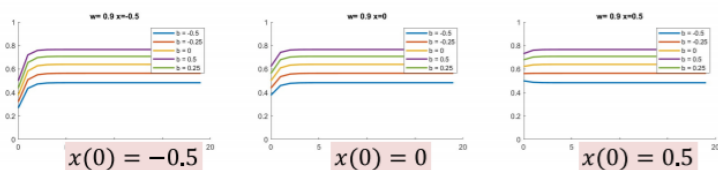
$w = 1.1$



$w = 1.0$



$w = 0.9$



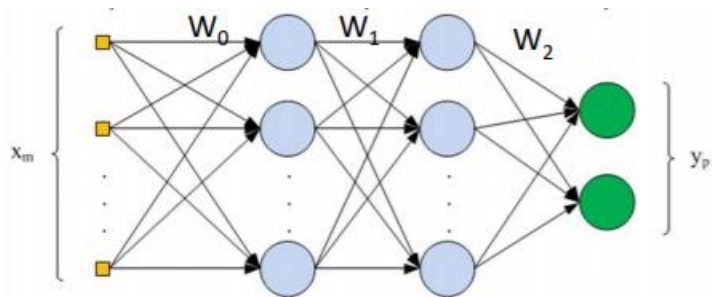
- Sigmoid activations saturate and the network becomes unable to retain new information
- RELU activations blow up or vanish rapidly
- Tanh activations are the slightly more effective at storing memory, but for not very long

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03. Vanishing gradient problems

- Training deep networks

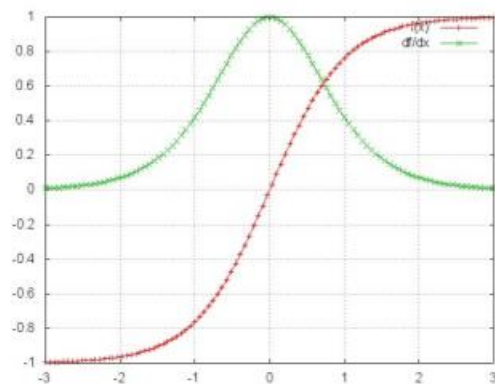


$$Y = f_N(W_N f_{N-1}(W_{N-1} f_{N-2}(\dots W_1 X)))$$

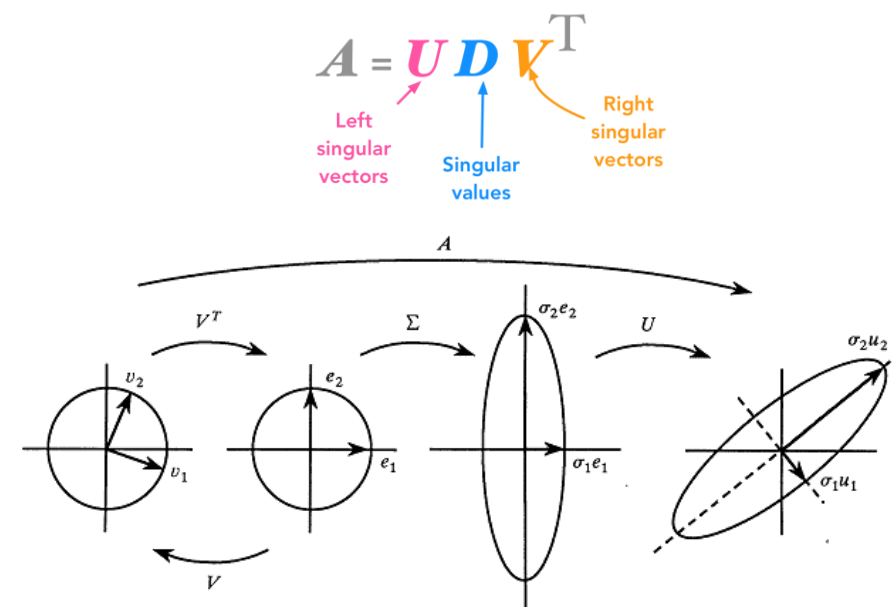
$$\nabla_{f_k} Div = \nabla D \cdot \nabla f_N \cdot W_N \cdot \nabla f_{N-1} \cdot W_{N-1} \dots \nabla f_{k+1} W_{k+1}$$

bounded

$$\nabla f_t(z_i) = \begin{bmatrix} f'_{t,1}(z_1) & 0 & \dots & 0 \\ 0 & f'_{t,2}(z_2) & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & f'_{t,N}(z_N) \end{bmatrix}$$



$$\nabla_{f_k} Div = \nabla D \cdot \nabla f_N \cdot W_N \cdot \nabla f_{N-1} \cdot W_{N-1} \dots \nabla f_{k+1} W_{k+1}$$

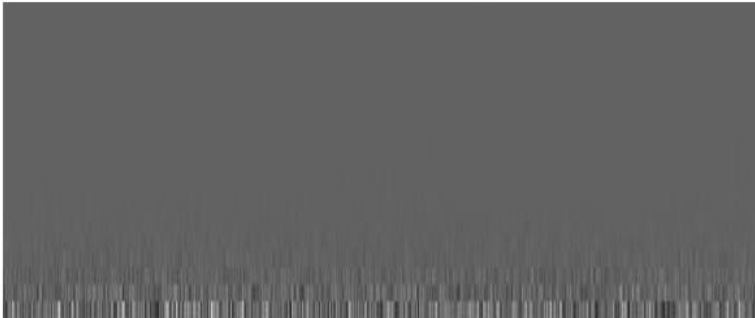


- Expand ∇D along directions in which the singular values of the weight matrices are greater than 1
- Shrink ∇D in directions where the singular values are less than 1

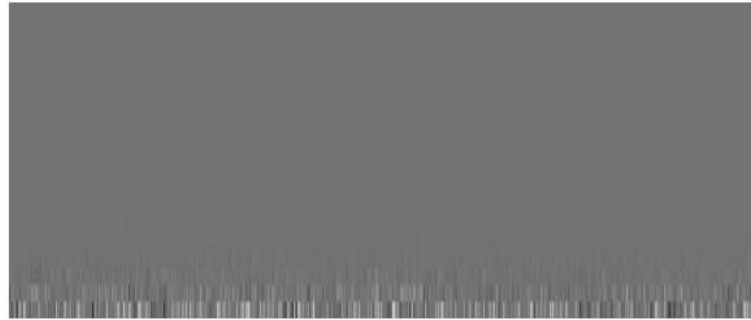
03. Vanishing gradient problems

- Vanishing gradient examples

ELU activation, Batch gradients



RELU activation, Batch gradients



Sigmoid activation, Batch gradients

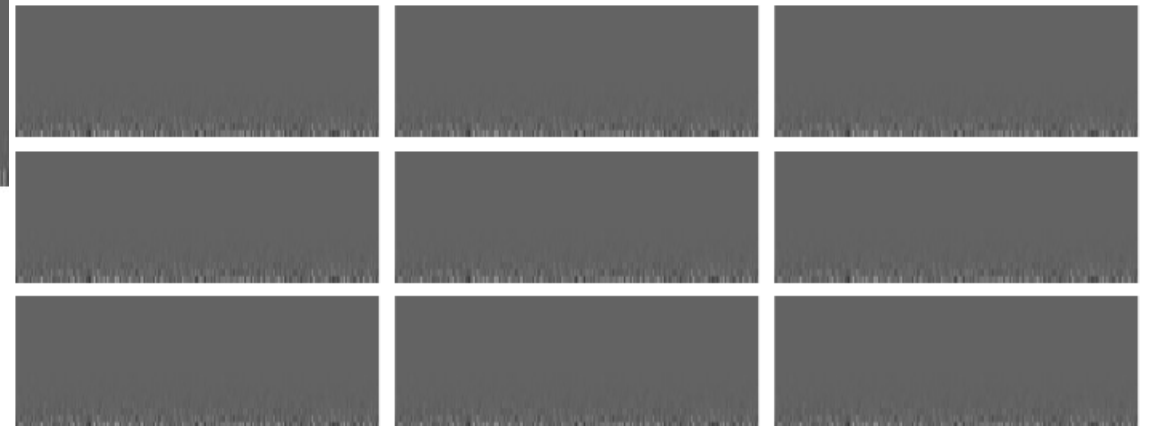


Tanh activation, Batch gradients



- ELU activations maintain gradients longest
- But in all cases gradient effectively vanish after 10 layers

ELU activation, Individual instances



Problems of RNN

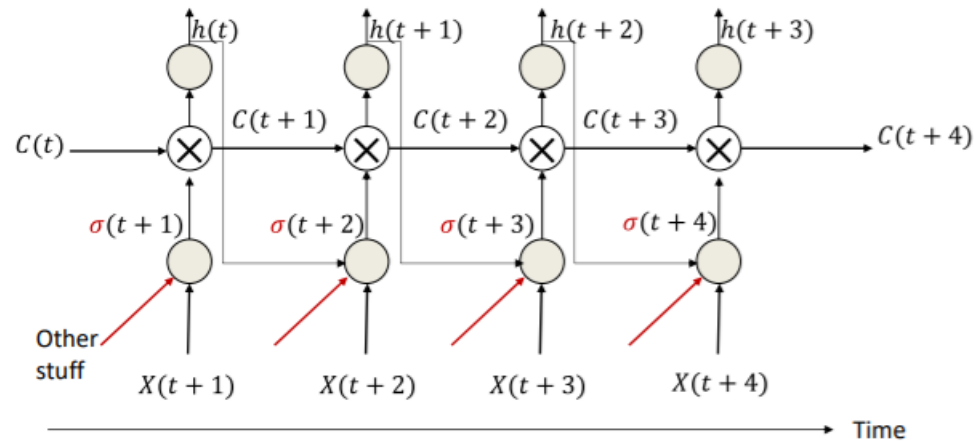
- ✓ Vanishing gradient problems
- ✓ Loss of memories over time

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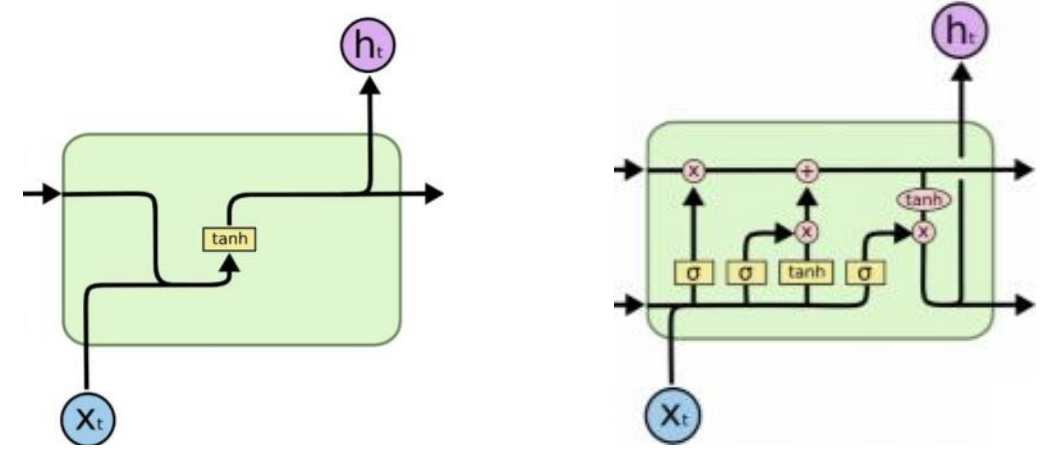
04. LSTMs and variants

- LSTM's basic idea
 - the constant error carousel



- The gate σ depends on current input, current hidden state and so on

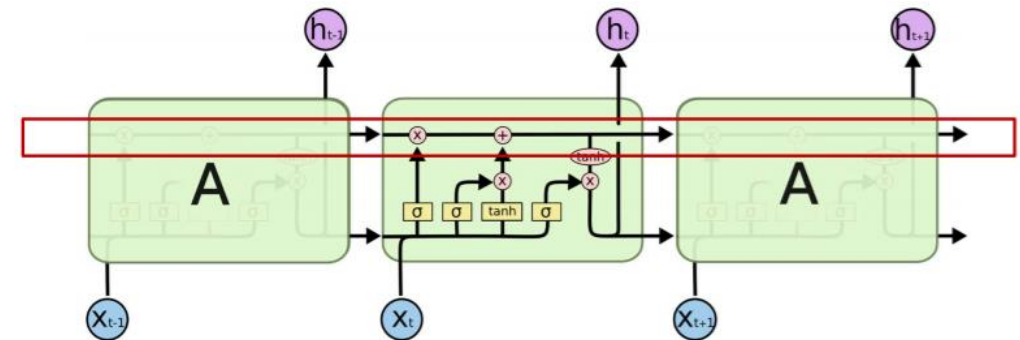
- LSTM



<Standard RNN>

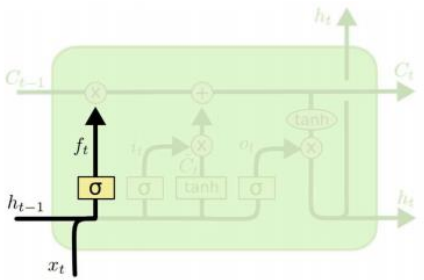
<LSTM>

- Constant Error Carousel



04. LSTMs and variants

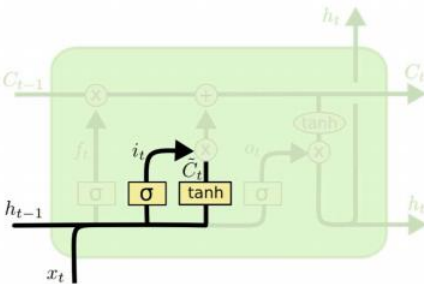
- Forget gate



$$f_t = \sigma(W_f \cdot [h_{t-1}, x_t] + b_f)$$

- determines whether to carry over the history or to forget it

- Input gate

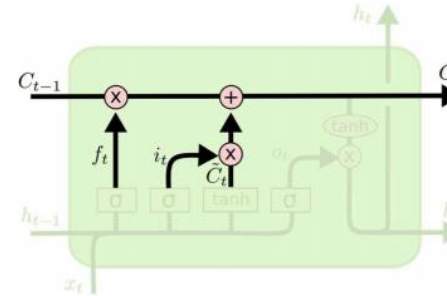


$$i_t = \sigma(W_i \cdot [h_{t-1}, x_t] + b_i)$$

$$\tilde{C}_t = \tanh(W_C \cdot [h_{t-1}, x_t] + b_C)$$

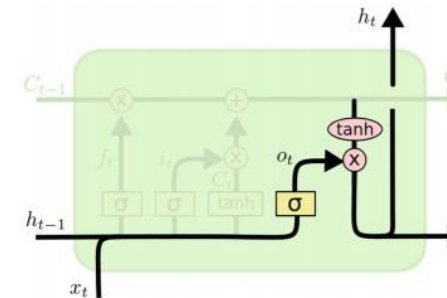
- A layer determines if there's something new in the input
- A gate decides if its worth remembering

- Memory cell update



$$C_t = f_t * C_{t-1} + i_t * \tilde{C}_t$$

- Output gate



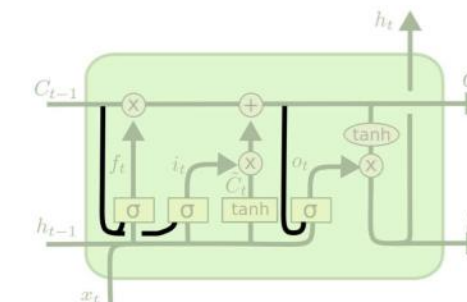
$$o_t = \sigma(W_o [h_{t-1}, x_t] + b_o)$$

$$h_t = o_t * \tanh(C_t)$$

compressed

➤ Peephole connection

using both C and h



$$f_t = \sigma(W_f \cdot [C_{t-1}, h_{t-1}, x_t] + b_f)$$

$$i_t = \sigma(W_i \cdot [C_{t-1}, h_{t-1}, x_t] + b_i)$$

$$o_t = \sigma(W_o \cdot [C_t, h_{t-1}, x_t] + b_o)$$

04. LSTMs and variants

- Forward

Gates

$$f_t = \sigma(W_f \cdot [C_{t-1}, h_{t-1}, x_t] + b_f)$$

$$i_t = \sigma(W_i \cdot [C_{t-1}, h_{t-1}, x_t] + b_i)$$

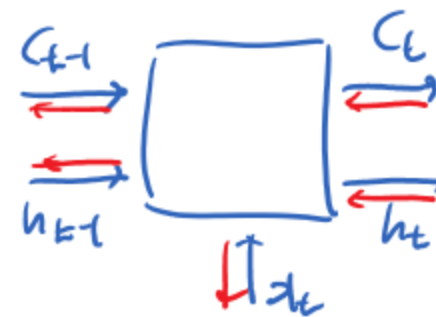
$$o_t = \sigma(W_o \cdot [C_t, h_{t-1}, x_t] + b_o)$$

Variables

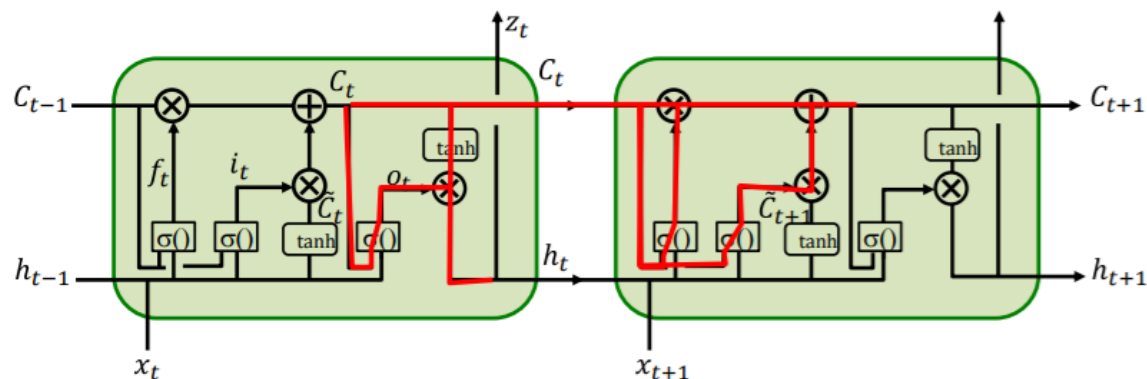
$$\tilde{C}_t = \tanh(W_C \cdot [h_{t-1}, x_t] + b_C)$$

$$C_t = f_t * C_{t-1} + i_t * \tilde{C}_t$$

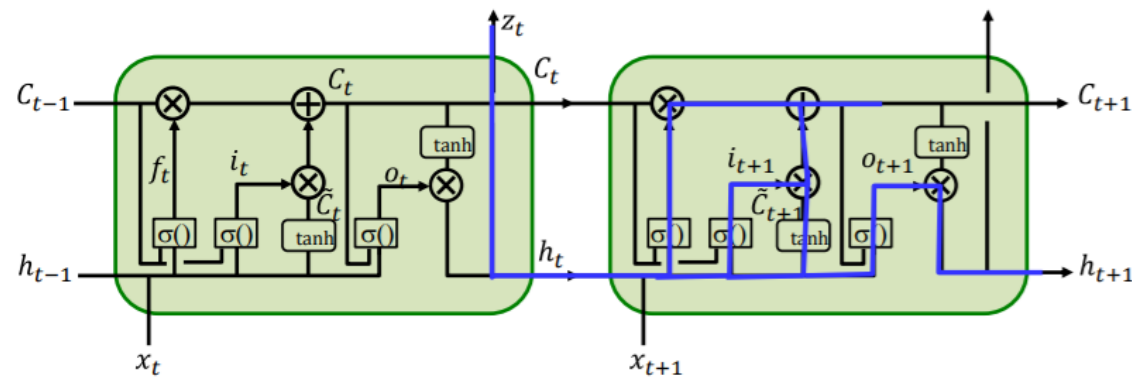
$$h_t = o_t * \tanh(C_t)$$



- backward



$$\begin{aligned} \nabla_{C_t} \text{Div} &= \nabla_{h_t} \text{Div} \circ (o_t \circ \tanh'(\cdot) + \tanh(\cdot) \circ \sigma'(\cdot) W_{Co}) + \\ &\nabla_{C_{t+1}} \text{Div} \circ (f_{t+1} + C_t \circ \sigma'(\cdot) W_{Cf} + \tilde{C}_{t+1} \circ \sigma'(\cdot) W_{Ci} \circ \tanh(\cdot) \dots) \end{aligned}$$

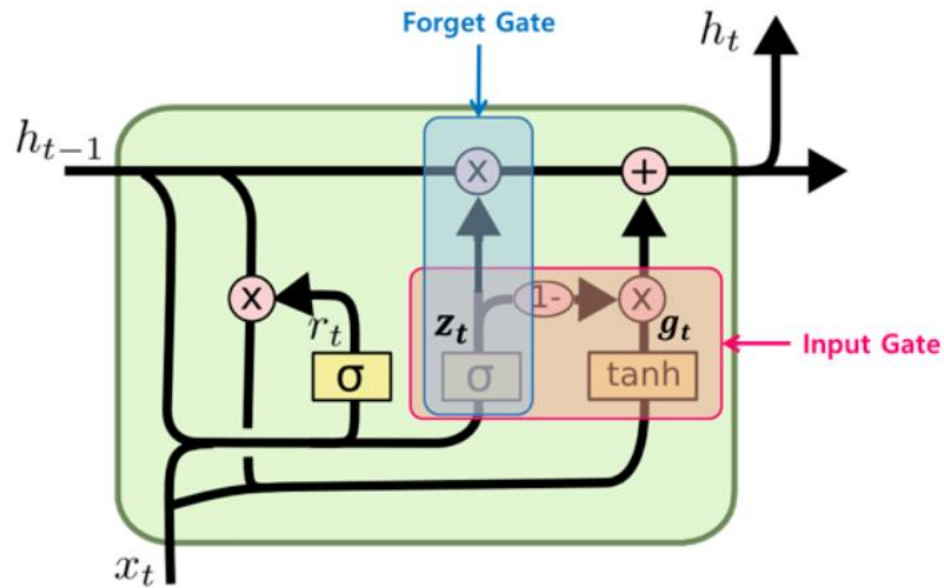


$$\begin{aligned} \nabla_{h_t} \text{Div} &= \nabla_{z_t} \text{Div} \nabla_{h_t} z_t + \nabla_{C_{t+1}} \text{Div} \circ (C_t \circ \sigma'(\cdot) W_{hf} + \tilde{C}_{t+1} \circ \sigma'(\cdot) W_{hi}) + \\ &\nabla_{C_{t+1}} \text{Div} \circ o_{t+1} \circ \tanh'(\cdot) W_{ho} + \nabla_{h_{t+1}} \text{Div} \circ \tanh(\cdot) \circ \sigma'(\cdot) W_{ho} \end{aligned}$$

04. LSTMs and variants

- GRU

- Simplified version of LSTM



$$\mathbf{r}_t = \sigma(\mathbf{W}_{xr}^T \cdot \mathbf{x}_t + \mathbf{W}_{hr}^T \cdot \mathbf{h}_{t-1} + \mathbf{b}_r)$$

$$\mathbf{z}_t = \sigma(\mathbf{W}_{xz}^T \cdot \mathbf{x}_t + \mathbf{W}_{hz}^T \cdot \mathbf{h}_{t-1} + \mathbf{b}_z)$$

$$\mathbf{g}_t = \tanh(\mathbf{W}_{xg}^T \cdot \mathbf{x}_t + \mathbf{W}_{hg}^T \cdot (\mathbf{r}_t \otimes \mathbf{h}_{t-1}) + \mathbf{b}_g)$$

$$\mathbf{h}_t = \mathbf{z}_t \otimes \mathbf{h}_{t-1} + (1 - \mathbf{z}_t) \otimes \mathbf{g}_t$$

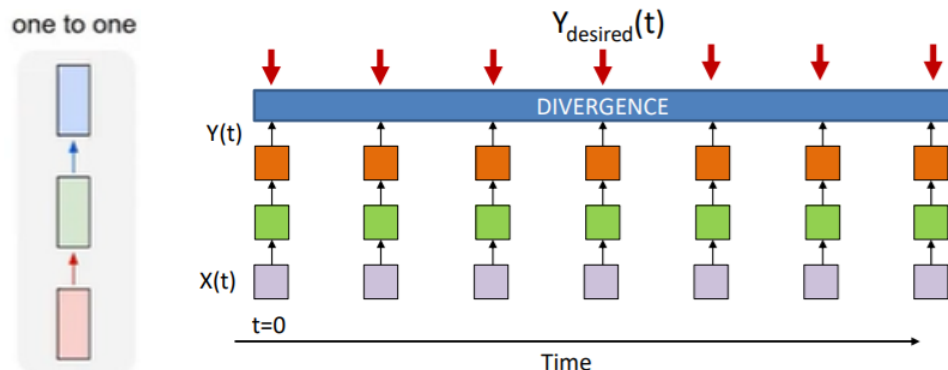
- ✓ One cell state, \mathbf{h}_t
- ✓ Two gates, Reset gate(\mathbf{r}_t) and Update gate(\mathbf{z}_t)
- ✓ Reset gate control how much information of \mathbf{h}_{t-1} will be considered
- ✓ Update gate control forget gate and input gate
- If output of \mathbf{z}_t is 1, open **forget** gate and close input gate
- If output of \mathbf{z}_t is 0, close forget gate and open **input** gate

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05. Loss functions for RNN

- Regular MLP



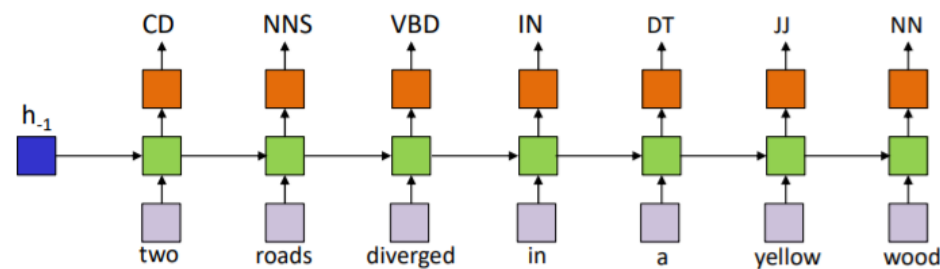
- No recurrence
- The output at time t is related to the output at $t' \neq t$

$$Div(Y_{target}(1 \dots T), Y(1 \dots T)) = \sum_t w_t Div(Y_{target}(t), Y(t))$$

$$\nabla_{Y(t)} Div(Y_{target}(1 \dots T), Y(1 \dots T)) = w_t \nabla_{Y(t)} Div(Y_{target}(t), Y(t))$$

Typical Divergence for classification: $Div(Y_{target}(t), Y(t)) = KL(Y_{target}(t), Y(t))$

- Time synchronous network



- Input : symbols as one-hot vectors
- Output : Probability distribution over symbols

$$Y(t, i) = P(V_i | w_0 \dots w_{t-1})$$

- Training : BPTT
- Divergence

$$Div(Y_{target}(1 \dots T), Y(1 \dots T)) = \sum_t Div(Y_{target}(t), Y(t)) = - \sum_t \log Y(t, w_{t+1})$$

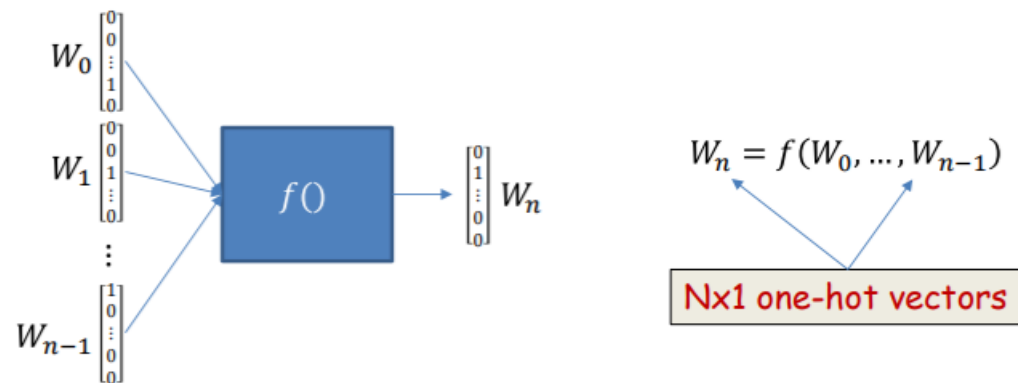
$$\nabla_{Y(t)} Div(Y_{target}(1 \dots T), Y(1 \dots T)) = \nabla_{Y(t)} Div(Y_{target}(t), Y(t))$$

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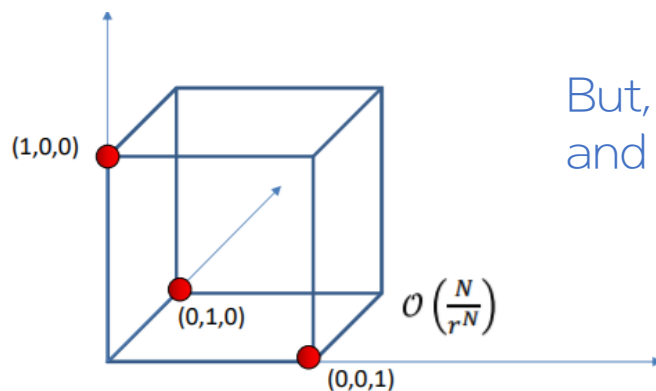
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06. Sequence prediction

- One-hot vectors



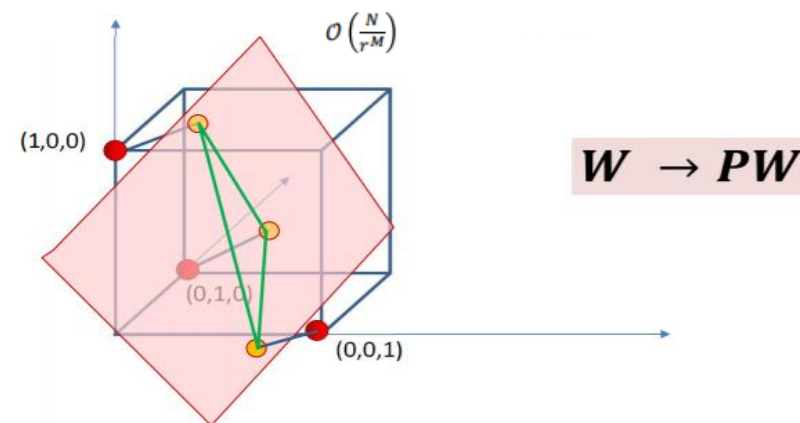
- makes no assumptions about relative importance and relationships



But, very high-dimension and sparse

wasteful!

- Projection



learn a subspace plane which capture semantic relations between the words

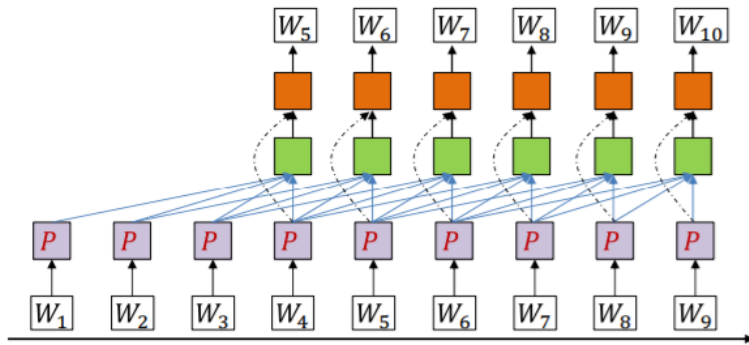
embedding vector

$$PW = \begin{bmatrix} | & | & | & | & | \\ | & | & | & | & | \\ | & | & | & | & | \\ | & | & | & | & | \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

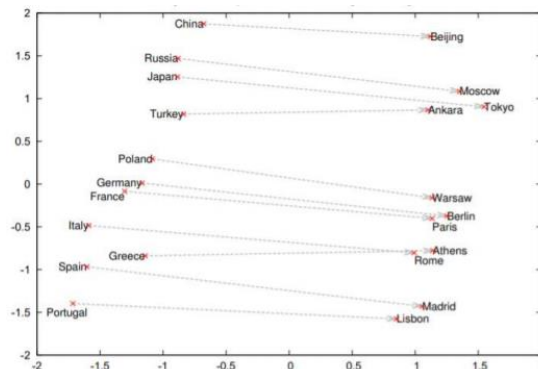
linear transform

06. Sequence prediction

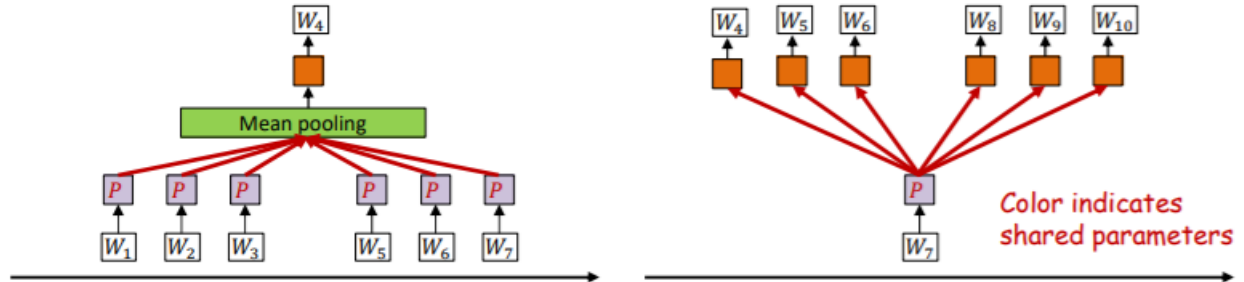
- The TDNN model



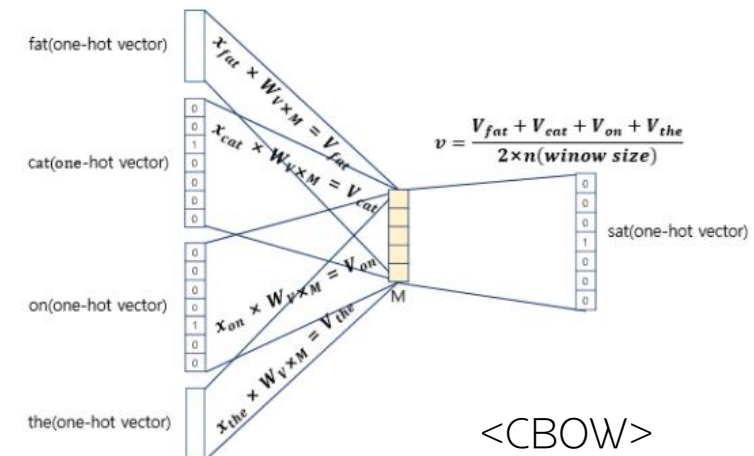
- predict each word based on the past N words
- also learn low-dimensional representations PW of words
- examples



- Alternative models to learn projections



- Soft bag of words : Predict word based on words in immediate context
- Skip-grams: Predict adjacent words based on current word



Thank you