Regularization of covariance matrix

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Graphical Models Reading Group

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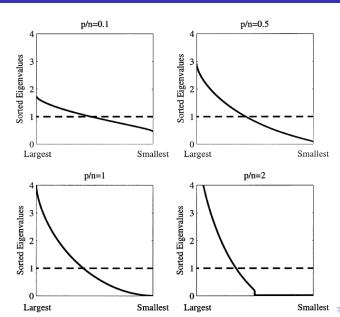
Distorted eigenstructure

• Sample covariance matrix

$$S = \frac{1}{n}X'X.$$

- The eigenstructure of **S** tends to be systematically distorted unless p/n is small.
- Larger eigenvalues are overestimated; smaller eigenvalues are underestimated.

Distorted eigenstructure



Loss and risk functions

• Two commonly used loss functions when n > p

$$egin{aligned} \mathcal{L}_1(\hat{oldsymbol{\Sigma}}, oldsymbol{\Sigma}) &= \operatorname{tr}(\hat{oldsymbol{\Sigma}} oldsymbol{\Sigma}^{-1}) - \log |\hat{oldsymbol{\Sigma}} oldsymbol{\Sigma}^{-1}| -
ho, \ & \mathcal{L}_2(\hat{oldsymbol{\Sigma}}, oldsymbol{\Sigma}) &= \operatorname{tr}[(\hat{oldsymbol{\Sigma}} oldsymbol{\Sigma}^{-1} - oldsymbol{I})^2], \end{aligned}$$

where $\hat{\boldsymbol{\Sigma}} = \hat{\boldsymbol{\Sigma}}(\boldsymbol{\mathsf{S}})$ is an estimator.

Risk functions

$$R_i(\hat{\boldsymbol{\Sigma}}, \boldsymbol{\Sigma}) = \mathbb{E}(L_i(\hat{\boldsymbol{\Sigma}}, \boldsymbol{\Sigma})), \quad i = 1, 2.$$

• Among all the estimators $\hat{\mathbf{\Sigma}} = a\mathbf{S}$ where a is a scalar, \mathbf{S} is optimal under L_1 and $\frac{n}{n+p+1}\mathbf{S}$ is optimal under L_2 .

Shrinking sample eigenvalues

The spectral decomposition of S is

$$S = \mathbf{Q}\mathrm{diag}(\lambda_1, \dots, \lambda_p)\mathbf{Q}',$$

where $\lambda_1 \ge \cdots \ge \lambda_p \ge 0$ are the eigenvalues of **S**, and **Q** is an orthogonal matrix whose columns are corresponding eigenvectors.

• Stein (1956) proposed the class of Steinian shrinkage estimators:

$$\hat{\mathbf{\Sigma}} = \mathbf{Q} \operatorname{diag}(\varphi_1, \dots, \varphi_p) \mathbf{Q}',$$

where $\varphi_j = \varphi_j(\lambda)$ estimates the *j*th largest eigenvalue of Σ .

Shrinking sample eigenvalues

Stein's estimator

- $\hat{\mathbf{\Sigma}}_{\text{Stein}} = \mathbf{Q} \text{diag}(\varphi_1, \dots, \varphi_p) \mathbf{Q}'.$
- $\varphi_j = \lambda_j/\alpha_j$, where

$$\alpha_j = \frac{n - p + 1 + 2\lambda_j \sum_{i \neq j} (\lambda_j - \lambda_i)^{-1}}{n}.$$

• $\hat{\Sigma}_{\mathrm{Stein}}$ approximately minimizes the L_1 risk.

Modified Frobenius norm and inner product:

$$\|\mathbf{A}\| = \sqrt{
ho^{-1} \mathrm{tr}(\mathbf{A}\mathbf{A}')}.$$

$$\langle \mathbf{A}_1, \mathbf{A}_2 \rangle = \rho^{-1} \mathrm{tr}(\mathbf{A}_1 \mathbf{A}_2').$$

 Ledoit and Wolf (2004) used a modified Frobenius norm as the loss function.

$$L_3(\hat{\boldsymbol{\Sigma}},\boldsymbol{\Sigma}) = \|\hat{\boldsymbol{\Sigma}} - \boldsymbol{\Sigma}\|^2 = p^{-1} \mathrm{tr}[(\hat{\boldsymbol{\Sigma}} - \boldsymbol{\Sigma})^2]$$

To ensure non-singularity, they proposed a shrinkage estimator

$$\hat{\mathbf{\Sigma}}_{\mathrm{LW}} = \alpha_1 \mathbf{I} + \alpha_2 \mathbf{S}.$$



To minimize L₃ risk,

$$\hat{\mathbf{\Sigma}}_{LW} = \frac{\beta^2}{\delta^2} \mu \mathbf{I} + \frac{\alpha^2}{\delta^2} \mathbf{S},$$

where

$$\begin{split} \boldsymbol{\mu} &= \langle \mathbf{\Sigma}, \mathbf{I} \rangle, \quad \boldsymbol{\alpha}^2 = \|\mathbf{\Sigma} - \boldsymbol{\mu} \mathbf{I}\|^2, \\ \boldsymbol{\beta}^2 &= \mathbb{E} \|\mathbf{S} - \mathbf{\Sigma}\|^2, \quad \boldsymbol{\delta}^2 = \mathbb{E} \|\mathbf{S} - \boldsymbol{\mu} \mathbf{I}\|^2. \end{split}$$

•

$$\mathbb{E}\|\hat{\mathbf{\Sigma}}_{\mathrm{LW}} - \mathbf{\Sigma}\|^2 = \frac{\alpha^2 \beta^2}{\delta^2}$$

• Since $\alpha^2 + \beta^2 = \delta^2$, $\hat{\Sigma}_{LW}$ is a convex combination of μI and S.

Geometric interpretation

• A Hilbert space. Norm: $\sqrt{\mathbb{E}(\|\mathbf{A}\|^2)}$. Inner product: $\mathbb{E}(\langle \mathbf{A}_1, \mathbf{A}_2 \rangle)$.

$$\hat{\mathbf{\Sigma}}_{\mathrm{LW}} = \frac{\beta^2}{\delta^2} \mu \mathbf{I} + \frac{\alpha^2}{\delta^2} \mathbf{S},$$

$$\mu = \langle \mathbf{\Sigma}, \mathbf{I} \rangle, \alpha^2 = \|\mathbf{\Sigma} - \mu \mathbf{I}\|^2, \ \beta^2 = \mathbb{E}\|\mathbf{S} - \mathbf{\Sigma}\|^2, \delta^2 = \mathbb{E}\|\mathbf{S} - \mu \mathbf{I}\|^2.$$

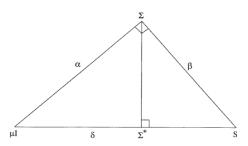


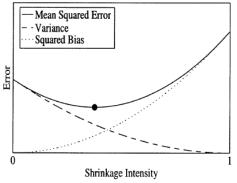
Fig. 1. Theorem 2.1 interpreted as a projection in Hilbert space.

Bias-variance trade-off:

$$\mathbb{E}(\|\hat{\boldsymbol{\Sigma}} - \boldsymbol{\Sigma}\|^2) = \mathbb{E}(\|\hat{\boldsymbol{\Sigma}} - \mathbb{E}(\hat{\boldsymbol{\Sigma}})\|^2) + \|\mathbb{E}(\hat{\boldsymbol{\Sigma}}) - \boldsymbol{\Sigma}\|^2$$

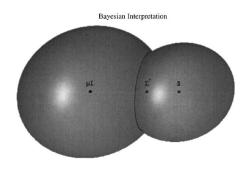
• μ I: all bias no variance.

S: all variance no bias.



Bayesian interpretation

- Prior information: Σ lies on the sphere centered around μ I with radius α .
- Sample information: Σ lies on the sphere centered around S with radius β .



Shrinkage of sample eigenvalues

$$\hat{\mathbf{\Sigma}}_{\mathrm{LW}} = \frac{\beta^2}{\delta^2} \mu \mathbf{I} + \frac{\alpha^2}{\delta^2} \mathbf{S},$$

- Shrinking the sample eigenvalues towards their grand mean.
- Steinian shrinkage estimator:

$$\varphi_j = \varphi_j(\lambda_j) = \frac{\beta^2}{\delta^2} \mu + \frac{\alpha^2}{\delta^2} \lambda_j.$$

$$\hat{\mathbf{\Sigma}}_{\mathrm{LW}}^* = \frac{b^2}{d^2} m \mathbf{I} + \frac{a^2}{d^2} \mathbf{S},$$

where

- $m = \langle \mathbf{S}, \mathbf{I} \rangle$ is a consistent estimator of μ ,
- $d = \|\mathbf{S} m\mathbf{I}\|^2$ is a consistent estimator of δ^2 ,
- $b^2 = \min(d^2, \bar{b}^2)$ is a consistent estimator of β^2 , where

$$\bar{b}^2 = \frac{1}{n^2} \sum_{k=1}^n \|\mathbf{X}'_{k\cdot} \mathbf{X}_{k\cdot} - \mathbf{S}\|^2,$$

• $a^2 = d^2 - b^2$ is a consistent estimator of α^2 .



Ridge estimation of correlation matrix

Warton (2008)

The sample correlation matrix is regularized as

$$\hat{\mathbf{R}}_{\alpha} = \alpha \hat{\mathbf{R}} + (1 - \alpha)\mathbf{I},$$

where $\hat{\mathbf{R}}$ is the sample correlation matrix.

• Properties: shrinkage to I, bias-variance trade-off.

Ridge estimation of correlation matrix

Estimation of α : K-fold cross validation

- Split the data into K parts $\mathbf{X}' = (\mathbf{X}'_1, \dots, \mathbf{X}'_K)$.
- \mathbf{X}_j is reserved as the validation data and all others \mathbf{X}^{-j} are used as training data.
- ullet Estimate lpha to maximize the cross-validated log-likelihood function.

$$\hat{\alpha} = \operatorname{argmax}_{\alpha} \sum_{j=1}^{K} \log L(\hat{\boldsymbol{\mu}}^{-j}, \hat{\boldsymbol{\Sigma}}_{\alpha}^{-j}; \boldsymbol{\mathsf{X}}_{j})$$

Condition number regularization

Won et al. (2013)

ullet The condition number of a positive definite matrix $oldsymbol{\Sigma}$ is

$$\operatorname{cond}(\mathbf{\Sigma}) = \frac{\lambda_{\mathsf{max}}(\mathbf{\Sigma})}{\lambda_{\mathsf{min}}(\mathbf{\Sigma})}$$

Constrained maximum likelihood estimation:

maximize
$$I(\Sigma)$$

s.t.
$$\operatorname{cond}(\mathbf{\Sigma}) \leq \kappa_{\mathsf{max}}$$
.

Condition number regularization

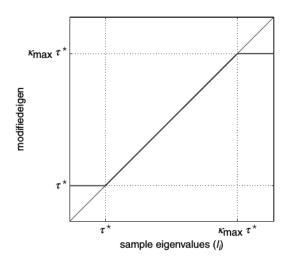
• Steinian shrinkage estimator:

$$\varphi_{j} = \min\{\max\{\tau^{*}, \lambda_{j}\}, \kappa_{\max}\tau^{*}\} = \begin{cases} \tau^{*}, & \lambda_{j} \leq \tau^{*}, \\ \lambda_{j}, & \tau^{*} < \lambda_{j} < \kappa_{\max}\tau^{*}, \\ \kappa_{\max}\tau^{*}, & \lambda_{j} \geq \kappa_{\max}\tau^{*}, \end{cases}$$

for some τ^* , which is determined by the data and κ_{\max} .

• τ^* can be found exactly and easily in O(p) time.

Condition number regularization



References



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