

Accelerated Bayesian SED Modeling using Amortized Neural Posterior Estimation

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ABSTRACT

State-of-the-art spectral energy distribution (SED) analyses use a Bayesian framework to infer the physical properties of galaxies from observed photometry or spectra. They require sampling from a high dimensional space of SED model parameters and take $> 10 - 100$ CPU hours per galaxy, which renders them practically infeasible for analyzing the *billions* of galaxies that will be observed by upcoming galaxy surveys (*e.g.* DESI, PFS, Rubin, James Webb, and Roman). In this work, we present an alternative *scalable* approach for rigorous Bayesian inference using Amortized Neural Posterior Estimation (ANPE). ANPE is a simulation-based inference method that exploits neural network models to estimate the posterior probability distribution over the full range of observations. It requires no additional model evaluations to estimate the posterior after training. To demonstrate the advantages of an ANPE approach, we present SEDFLOW, an SED modeling method that uses ANPE with the recent [Hahn et al. \(2022\)](#) SED model and apply it to optical photometry. Once trained, deriving the posterior of galaxy properties with SEDFLOW takes ~ 1 *second per galaxy*. We validate SEDFLOW using posteriors derived from standard Markov Chain Monte Carlo (MCMC) sampling and synthetic observations, with known true parameter values. The SEDFLOW posteriors are in excellent agreement with both the MCMC estimates and the true posteriors. Lastly, we apply SEDFLOW to 33,887 galaxies in the NASA-Sloan Atlas and publicly release their posteriors.

Keywords: galaxies: evolution – galaxies: statistics

1. INTRODUCTION

The building blocks of our physical insight into galaxies are their physical properties measured from these observations: *e.g.* stellar mass (M_*), star formation rate (SFR), metallicity (Z), and age (t_{age}). The primary way for measuring these galaxy properties is by analyzing their spectral energy distribution (SED).

All of the physical processes in a galaxy leave an imprint on its SED. For instance, the SED over the ultraviolet to infrared wavelengths is primarily composed of light from the galaxy’s stellar

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populations and, thus, encodes the galaxy’s star formation and chemical enrichment histories. How some of this stellar light is reprocessed reflects the gas and dust content of the galaxy’s interstellar medium. The goal of SED modeling is to extract detailed physical properties of galaxies from their observed SEDs. There are three key components to SED modeling: the observations, a physical SED model, and a statistical inference framework for deriving physical properties from comparisons between the observations and models.

rework this here Over the past few decades, observations from large galaxy surveys such as the Sloan Digital Sky Survey (SDSS; York et al. 2000), DEEP2 (Davis et al. 2003), COSMOS and zCOSMOS (Scoville et al. 2007; Lilly et al. 2007), and GAMA (Baldry et al. 2018) have transformed our understanding of how galaxies form and evolve.

Current SED models are based on stellar population synthesis (SPS). Broadly speaking, they model the SED of a galaxy as a composite stellar population constructed from isochrones, stellar spectra, an initial mass function (IMF), a star formation and chemical evolution history, and dust attenuation (*e.g.* Bruzual & Charlot 2003; Maraston 2005; Conroy et al. 2009). Some models also include dust and nebular emissions as well as emissions from active galactic nuclei (*e.g.* Johnson et al. 2021). For a comprehensive review on SPS and SED modeling, we refer readers to Walcher et al. (2011) and Conroy (2013).

In this work, we focus on the third component of SED modeling: the statistical framework for comparing SED models to observations and inferring galaxy properties. State-of-the-art SED modeling uses a Bayesian inference framework. This approach has a number of key advantages over maximum-likelihood approaches (*e.g.* Cid Fernandes et al. 2005; Tojeiro et al. 2007; Koleva et al. 2008) that were often used in the past. In Bayesian inference, the goal is to estimate $p(\theta | \mathbf{x})$, the probability distribution of parameters θ , in our case galaxy properties, given observation \mathbf{x} . Inferring $p(\theta | \mathbf{x})$ provides an accurate estimate of parameter uncertainties and any degeneracies among them that can then be propagated for more accurate statistical analyses. The Bayesian framework also enables marginalization over nuisance parameters, which is necessary to model the effects of observational systematics (*e.g.* flux calibration). Bayesian inference also allows us to exploit informative priors based on previous observations to derive more precise constraints on galaxy properties.

Due to the high dimensionality of the parameter space, current Bayesian methods use Markov Chain Monte Carlo (MCMC) sampling techniques to explore and estimate the posterior (Acquaviva et al. 2011; Chevallard & Charlot 2016; Leja et al. 2017; Carnall et al. 2018). MCMC sampling enables more accurate posterior estimation and addresses the curse of dimensionality that restricts grid-based techniques often used in the past (Kauffmann et al. 2003; Burgarella et al. 2005; Salim et al. 2007; da Cunha et al. 2008). Grid-based techniques require SED models to be pre-computed over a grid in parameter space. Hence, as the dimensionality of model parameters increases for more sophisticated models, they require exponentially large number of model evaluations. Meanwhile for MCMC, the number of evaluations scales roughly linearly with the number of parameters. In Johnson et al. (2021), for instance, they use MCMC to sample a 16-dimensional parameter space.

Despite their advantages, current Bayesian SED modeling methods are *not scalable* as upcoming galaxy surveys will observe an unprecedented number of galaxies. The Dark Energy Spectroscopic

Survey (DESI; Collaboration et al. 2016), the Prime Focus Spectrograph (PFS; Takada et al. 2014), Rubin observatory (Ivezic et al. 2019), and Roman Space Telescope (Spergel et al. 2015) will all observe *millions or even billions* of galaxy SEDs. Meanwhile, current SED modeling takes 10-100 CPU hours per galaxy (*e.g.* Carnall et al. 2019; Tacchella et al. 2021). With current methods, inferring galaxy properties from rigorous Bayesian SED modeling for upcoming surveys would require *billions* of CPU hours.

The computational challenge is further exacerbated. First, more accurate and sophisticated SED models require additional parameter, for instance, to model nebular emission of observational systematics. As the dimensionality expands, conventional sampling techniques are less efficient. Second, it has recently come to light that the choice of prior can significantly impact the inferred galaxy properties (Carnall et al. 2018; Leja et al. 2017; Hahn et al. 2022). Hence, deriving robust galaxy properties requires validating the properties using different priors and investigating their impact. Lastly, current SED modeling make strong theoretical assumptions. They make explicit choices for stellar spectral library and initial mass function, but there is currently no consensus on the best choices for either. Relaxing these assumptions would involve flexibly parameterizing the uncertainties and variations as additional parameters in SED models (Conroy et al. 2009; Conroy & Gunn 2010) or deriving galaxy properties for multiple sets of assumptions. Both options increase the computational costs of current SED modeling.

Bayesian inference, however, does not require MCMC sampling. Simulation-based inference (SBI; also known as “likelihood-free inference”) is a rapidly developing class of inference methods that offers alternatives for many applications (see Cranmer et al. 2020, and reference therein). Many SBI methods leverage the latest developments in statistics and Machine Learning for more efficient posterior estimation (Papamakarios et al. 2017; Alsing et al. 2019; Hahn et al. 2019; Dax et al. 2021; Huppenkothen & Bachetti 2021; Zhang et al. 2021). One such SBI technique optimal for scalable Bayesian inference is Amortized Neural Posterior Estimation (ANPE).

ANPE utilizes a density estimation approach to SBI. Instead of using MCMC to sample the posterior, $p(\theta | \mathbf{x}_i)$, of a single galaxy, i , ANPE uses neural density estimators (NDE) and training data to estimate $p(\theta | \mathbf{x})$ over the full space of observables \mathbf{x} . NDEs are density models parameterized by neural networks that estimate density/probability distributions. The training data are $\{(\theta_i, \mathbf{x}'_i)\}$ pairs. In our application, θ is the SED model parameters, sampled from a prior, and \mathbf{x}'_i are synthetic observables, such as photometry, forward modeled using the SED model. Once the NDE is trained, generating the posterior requires no additional model evaluations and only requires plugging in the observation \mathbf{x}_i .

ANPE addresses one of the major drawbacks of MCMC: SED model evaluations used for one galaxy cannot be used for another. This is why MCMC sampling has to be performed on every galaxy. In ANPE, models evaluations are only used to construct the training data of the NDE. Although the training set typically requires more evaluations than for a single MCMC posterior, no additional evaluations are necessary after training. Hence, the computational cost is *amortized* and, at test time, only a minuscule fraction of the cost of performing MCMC. ANPE has recently been

applied to a wide range of applications in physics and astronomy with remarkable success (Stein et al. 2020; Wong et al. 2020; Dax et al. 2021; Zhang et al. 2021).

In this work, we present SEDFLOW, a method that applies ANPE to Bayesian galaxy SED modeling using the recent Hahn et al. (2022) SED model. We demonstrate that we can derive accurate posteriors with SEDFLOW and make Bayesian SED modeling fully scalable for the billions of galaxies that will be observed by upcoming surveys. As further demonstration, we apply ANPE to analyze optical photometry of $\sim 33,000$ galaxies in the NASA-Sloan Atlas (NSA¹). We begin in Section 2 by describing SBI using ANPE. We then present how we design and train SEDFLOW in Section 3. Afterwards, we describe the NSA observations in Section 4. We validate the accuracy of the posteriors from SEDFLOW in Section 5 and discuss the implications of our results and future steps in Section 6.

2. SIMULATION-BASED INFERENCE

The goal of Bayesian SED modeling, and probabilistic inference more broadly, is to infer the posterior probability distributions of galaxy properties, θ , given observations, \mathbf{x}_{obs} — $p(\theta | \mathbf{x}_{\text{obs}})$. For a specific θ and \mathbf{x} , we can evaluate the posterior using Bayes’ rule, $p(\theta | \mathbf{x}_{\text{obs}}) \propto p(\theta) p(\mathbf{x}_{\text{obs}} | \theta)$. $p(\theta)$ is the prior distribution, which we specify, and $p(\mathbf{x}_{\text{obs}} | \theta)$ is the likelihood, which is typically assumed to have a surrogate Gaussian functional form:

$$\ln p(\mathbf{x}_{\text{obs}} | \theta) = -\frac{1}{2}(\mathbf{x}_{\text{obs}} - m(\theta))^T \mathbf{C}^{-1}(\mathbf{x}_{\text{obs}} - m(\theta)). \quad (1)$$

$m(\theta)$ is the theoretical model, in our case a galaxy SED model from SPS. \mathbf{C} is the covariance matrix of the observations. In practice, off-diagonal terms are often ignored and measured uncertainties are used as estimates of the diagonal terms.

Simulation-based inference (SBI; also known as “likelihood-free” inference) offers an alternative that requires no assumptions about the form of the likelihood. Instead, SBI uses a generative model, *i.e.* a simulation F , to generate mock data \mathbf{x}' given parameters θ' : $F(\theta') = \mathbf{x}'$. With pairs of $\{(\theta', \mathbf{x}')\}$, it then seeks to directly estimate the posterior — $p(\theta | \mathbf{x})$, the likelihood — $p(\mathbf{x} | \theta)$, or the joint distribution of the parameters and data — $p(\theta, \mathbf{x})$. SBI has already been successfully applied to a number of Bayesian parameter inference problems in astronomy (*e.g.* Cameron & Pettitt 2012; Weyant et al. 2013; Hahn et al. 2017; Kacprzak et al. 2018; Alsing et al. 2018; Wong et al. 2020; Huppenkothen & Bachetti 2021; Zhang et al. 2021), and in physics (*e.g.* Brehmer et al. 2019; Cranmer et al. 2020).

2.1. Amortized Neural Posterior Estimation

SBI provides another a critical advantage over MCMC sampling-based inference methods — it enables *amortized inference*. For SED modeling using MCMC, each galaxy requires $>10^5$ model evaluations to accurately estimate $p(\theta | \mathbf{x}_{\text{obs}})$ (Hahn et al. 2022, Kwon et al. in prep.). Moreover, model evaluations for calculating the posterior of one galaxy cannot be used for another. For large

¹ <http://www.nsatlas.org/>

galaxy surveys with $>10^6$ galaxies (*e.g.* SDSS, Ahumada et al. 2020) this would require >100 billion model evaluations. Upcoming galaxy surveys will observe orders of magnitude more galaxies (*e.g.* DESI, PFS, Rubin, Roman). Bayesian SED modeling with MCMC sampling for these large galaxy surveys is *computationally infeasible*.

On the other hand, if we use density estimation SBI for SED modeling, we do not require a large number of model evaluations for each galaxy. An initial set of model evaluations ($\sim 10^6$) is necessary to train an NDE to accurately estimate $\hat{p}(\theta | \mathbf{x}_{\text{obs}})$ — *i.e.* Amortized Neural Posterior Estimation (ANPE). Once trained, $\hat{p}(\theta | \mathbf{x}_{\text{obs}})$ is estimated over the full θ and \mathbf{x}_{obs} -space so we can evaluate $\hat{p}(\theta | \mathbf{x}_{\text{obs},i})$ for each galaxy with minimal computational cost. The inference is amortized and no additional model evaluations are needed to generate the posterior for each galaxy. In total, SED modeling with ANPE for $>10^6$ galaxies requires the same number of model evaluations as analyzing tens of galaxies using MCMC.

ANPE has recently been applied to a broad range of astronomical applications from analyzing gravitational waves (*e.g.* Wong et al. 2020; Dax et al. 2021) to binary microlensing lensing (Zhang et al. 2021). They primarily use a class of NDE called normalizing flows (Tabak & Vanden-Eijnden 2010; Tabak & Turner 2013). Normalizing flow models use an invertible bijective transformation, f , to map a complex target distribution to a simple base distribution, $\pi(z)$, that is fast to evaluate. For ANPE, the target distribution is $p(\theta | \mathbf{x})$ and the $\pi(z)$ is typically a simple multivariate Gaussian, or mixture of Gaussians.

The transformation $f : z \rightarrow \theta$ must be invertible and have a tractable Jacobian. This is so that we can evaluate the target distribution from $\pi(z)$ by a change of variable:

$$p(\theta | \mathbf{x}) = \pi(z) \left| \det \left(\frac{\partial f^{-1}}{\partial \theta} \right) \right|. \quad (2)$$

Since the base distribution is easy to evaluate, we can also easily evaluate the target distribution. A neural network is trained to obtain f . The network typically consists of a series of simple transforms (*e.g.* shift and scale transforms) that are each invertible and whose Jacobians are easily calculated. By stringing together many such transforms, f provides an extremely flexible mapping from the base distribution.

Many different normalizing flow models are now available in the literature (*e.g.* Germain et al. 2015; Durkan et al. 2019). In this work, we use Masked Autoregressive Flow (MAF; Papamakarios et al. 2017). The autoregressive design (Uria et al. 2016) of MAF is particularly well-suited for modeling conditional probability distributions such as the posterior. Autoregressive models exploit chain rule to expand a joint probability of a set of random variables as products of one-dimensional conditional probabilities: $p(x) = \prod_i p(x_i | x_{1:i-1})$. They then use neural networks to describe each conditional probability, $p(x_i | x_{1:i-1})$. In this context, we can add a conditional variable y on both sides of the equation, $p(x | y) = \prod_i p(x_i | x_{1:i-1}, y)$, so that the autoregressive model describes a conditional probability $p(x | y)$. One drawback of autoregressive models is their sensitivity to the ordering of the variables. Masked Autoencoder for Distribution Estimation (MADE; Germain et al. 2015) models address this limitation by dropping out connections of a fully-connected autoencoder using weight matrices with binary masks. This ensures that the MADE model is autoregressive and

can be efficiently calculated. A MAF model is built by stacking multiple MADE models. Hence, it has the autoregressive structure of MADE but with more flexibility to describe complex probability distributions. In practice, we use the MAF implementation in the `sbi` Python package² (Greenberg et al. 2019; Tejero-Cantero et al. 2020).

3. SEDFLOW

In this section, we present SEDFLOW, which applies ANPE to SED modeling for a scalable and accelerated approach. For our SED model, we use the state-of-the-art PROVABGS model from Hahn et al. (2022). Although many SED models have been recently used in the literature (*e.g.* BAGPIPES, Carnall et al. 2018; PROSPECTOR, Leja et al. 2017; Johnson et al. 2021), we choose PROVABGS because it will be used to analyze >10 million galaxy spectrophotometry measured by the DESI Bright Galaxy Survey (Ruiz-Macias et al. 2021; Hahn et al. 2022). Below, we describe the PROVABGS model, the construction of the SEDFLOW training data using PROVABGS, and the training procedure for SEDFLOW.

3.1. SED Modeling: PROVABGS

We use the state-of-the-art SPS model of the PROVABGS (Hahn et al. 2022). The SED of a galaxy is modeled as a composite of stellar populations defined by stellar evolution theory (in the form of isochrones, stellar spectral libraries, and an initial mass function) and its star formation and chemical enrichment histories (SFH and ZH), attenuated by dust (see Walcher et al. 2011; Conroy 2013, for a review). The PROVABGS model, in particular, utilizes a non-parametric SFH with a starburst, a non-parametric ZH that varies with time, and a flexible dust attenuation prescription.

The SFH has two components: one based on non-negative matrix factorization (NMF) bases and the other, a starburst component. The SFH contribution from the NMF component is a linear combination of four NMF SFH basis functions, derived from performing NMF (Lee & Seung 1999; Cichocki & Phan 2009; Févotte & Idier 2011) on SFHs of galaxies in the Illustris cosmological hydrodynamical simulations (Vogelsberger et al. 2014; Genel et al. 2014; Nelson et al. 2015). The NMF SFH prescription provides a compact and flexible representation of the SFH. The second starburst component consists of a single stellar population (SSP) and adds stochasticity to the SFH.

The ZH is similar defined using two NMF bases dervied from Illustris. This ZH prescription enables us to flexibly model a wide range of ZHs and unlike most SED models, it does not assume constant metallicity over time, which can significantly bias inferred galaxy properties (Thorne et al. 2021). The stellar evolution theory is based on Flexible Stellar Population Synthesis (FSPS; Conroy et al. 2009; Conroy & Gunn 2010) with the MIST isochrones (Paxton et al. 2011, 2013, 2015; Choi et al. 2016; Dotter 2016), the Chabrier (2003) initial mass function (IMF), and a combination of the MILES (Sánchez-Blázquez et al. 2006) and BaSeL (Lejeune et al. 1997, 1998; Westera et al. 2002) libraries. The SFH and ZH are binned into 43 logarithmically-space time and SSPs are evaluated at each time bin using FSPS. The SSPs are summed up to get the unattenuated rest-frame galaxy SED.

² <https://github.com/mackelab/sbi/>

Lastly, PROVABGS attenuates the light from the composite stellar population using the two component [Charlot & Fall \(2000\)](#) dust attenuation model with diffuse-dust (ISM) and birth cloud (BC) components. All SSPs are attenuated by the diffuse dust using the [Kriek & Conroy \(2013\)](#) attenuation curve. Then, the BC component provides extra dust attenuation on SSPs younger than 100 Myr with young stars that are embedded in molecular clouds and HII regions. In total the PROVABGS SED model has 12 parameters: stellar mass (M_*), six SFH parameters ($\beta_1, \beta_2, \beta_3, \beta_4, t_{\text{burst}}, f_{\text{burst}}$), two ZH parameters (γ_1, γ_2), and three dust attenuation parameters ($\tau_{\text{BC}}, \tau_{\text{ISM}}, n_{\text{dust}}$). Each PROVABGS model evaluation takes ~ 340 ms.

3.2. Training Data

In this section, we describe how to we construct the training data for SEDFLOW using the PROVABGS SED model. First, we sample N_{train} SED model parameters from a prior: $\theta' \sim p(\theta)$. We use the same priors as [Hahn et al. \(2022\)](#): uniform priors over $M_*, t_{\text{burst}}, f_{\text{burst}}, \gamma_1, \gamma_2, \tau_{\text{BC}}, \tau_{\text{ISM}}, n_{\text{dust}}$ with broad conservative ranges and Dirichlet prior over $\beta_1, \beta_2, \beta_3, \beta_4$, chosen to normalize the NMF SFH. For each θ' , we also uniformly sample a redshift within the range of the NSA: $z' \sim \mathcal{U}(0., 0.2)$. Next, we forward model mock observables. We calculate the rest-frame galaxy SED from PROVABGS and redshift it: $F(\lambda; \theta', z)$. Afterwards, we convolve F with optical broadband filters, R_X , to generate noiseless photometric fluxes:

$$f_X(\theta', z') = \int F(\lambda; \theta', z') R_X(\lambda) d\lambda \quad (3)$$

The next step of the forward model is to apply noise. We assign photometric uncertainties, σ'_X , by sampling an estimate of the observed $p(\sigma_X | f_X)$ of NSA galaxies. Then, we apply Gaussian noise

$$\hat{f}_X(\theta', z', \sigma'_x) = f_X(\theta', z') + n_X \quad \text{where } n_X \sim \mathcal{N}(0, \sigma'_x) \quad (4)$$

to derive the forward modeled photometric flux.

For our estimate of $p(\sigma_X | f_X)$, we use an empirical estimate of $p(\sigma_X | f_X)$ based on NSA photometry and measured uncertainties. For each band, we separately estimate

$$\hat{p}(\sigma_X | f_X) = \mathcal{N}(\mu_{\sigma_X}(f_X), \sigma_{\sigma_X}(f_X)) \quad (5)$$

as a Gaussian in magnitude-space. μ_{σ_X} and σ_{σ_X} are the median and standard deviation of σ_X as a function of f_X that we estimate by evaluating them in f_X bin and interpolating over the bins. Any θ' that is assigned a negative σ'_X is removed from our training data. We also remove any training data with $f_X(\theta')$ outside the range of NSA photometry. Although this is a simplistic noise model, we emphasize that our choice of noise model does not strongly affect the accuracy of the posteriors from SEDFLOW. This is because we design SEDFLOW to include σ_X in the conditional statement of the posterior. Hence, our primary concern is that σ'_X spans the observed σ_X values. We discuss this further in Section 6.

In total, we construct $N_{\text{train}} = 1,131,561$ sets of SED parameters, redshift, photometric uncertainty, and mock NSA photometry. There are 12 SED parameters and photometry and uncertainties

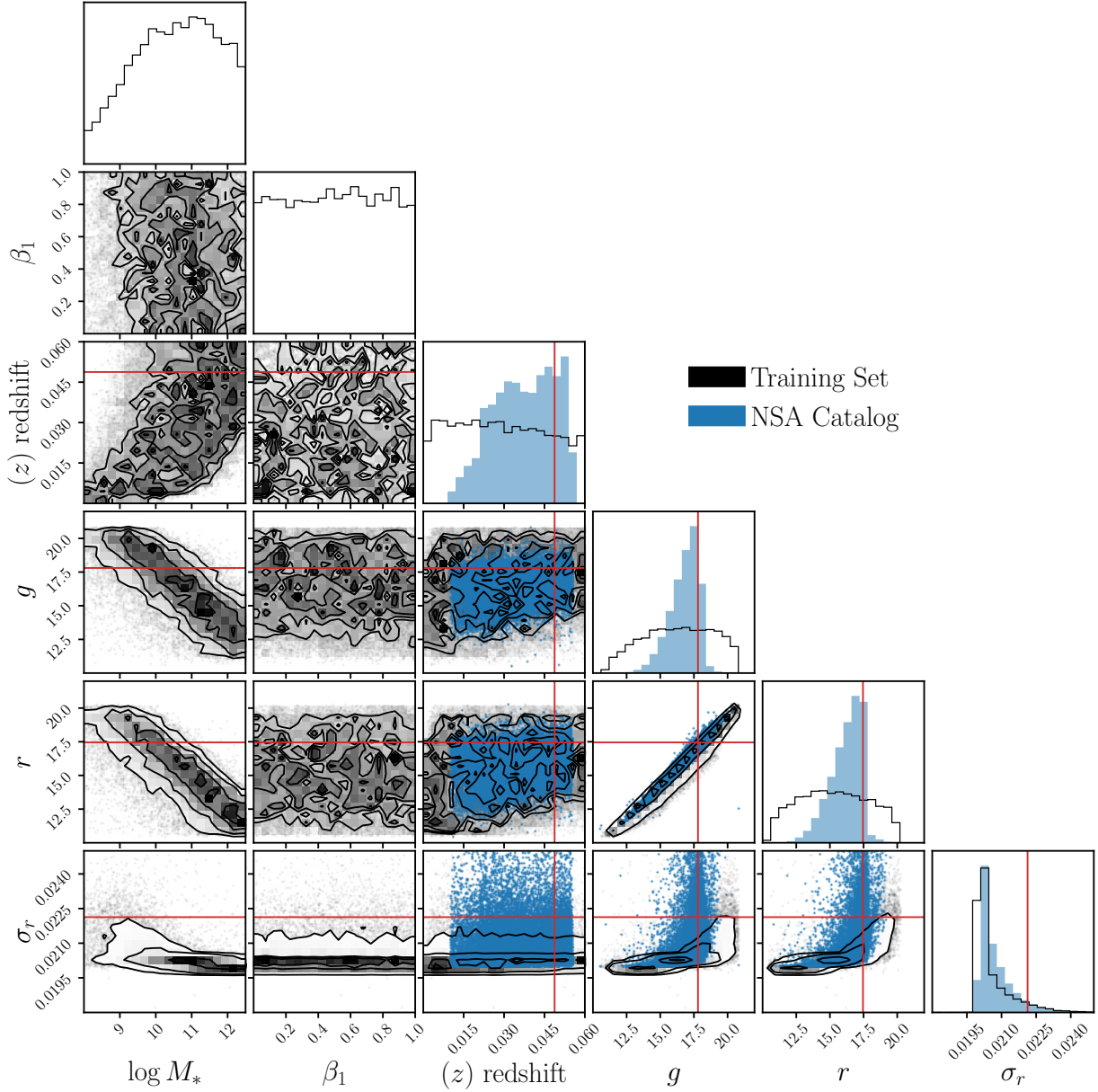


Figure 1. Joint distribution of SED model parameters, redshift, photometric magnitudes, and uncertainties of the data used to train SEDFLOW. We plot only a subset of the parameters ($\log M_*$, β_1) and photometric bands for clarity. The training data was constructed by sampling SED model parameter values from the prior and forward modeling optical photometry using the PROVABGS and noise models (Section 3). For comparison, we present the distribution of redshift, magnitudes, and uncertainties for galaxies in the NSA catalog (blue). *The training set fully encompasses the observations; thus, SEDFLOW can be used to infer the posterior for all NSA galaxies.*

in 5 NSA bands. In Figure 1, we present the training data through the joint distribution of a subset of $\{(\theta', z, \sigma'_X, \hat{f}_X)\}$ (black). We include select SED model parameters ($\log M_*$, β_1), redshift, photometry (g and r bands), and photometric uncertainty (r band). We also include the distribution of redshift, photometry, and uncertainty of NSA galaxies (blue). The photometry and uncertainties are in

magnitude-space. The distribution of the training data fully spans the distribution of NSA galaxies. Hence, the training data provides support over the full (f_X, σ_X, z) space of the NSA observations.

3.3. Training SEDFLOW

For SEDFLOW, we use a MAF normalizing flow model (Section 2.1) with 15 MADE blocks, each with 2 hidden layers and 500 hidden units. In total, the model has 7,890,330 parameters, \mathbf{h} . We determine this architecture through experimentation. Our goal is to determine \mathbf{h} of the MAF model, $q(\theta | \mathbf{x}, \mathbf{h})$, so that it accurately estimates the posterior probability distribution $p(\theta | \mathbf{x})$. θ represent the SED parameters and $\mathbf{x} = (f_X, \sigma_X, z)$. We do this by minimizing the KL divergence between $q(\theta | \mathbf{x}, \mathbf{h})$ and $p(\theta | \mathbf{x})$: $D_{\text{KL}}(p || q)$.

In practice, we split the training data (Section 3.2) into a training and validation set with a 90/10 split. Afterwards, we maximize the total log likelihood $\sum_i \log q(\theta_i | \mathbf{x}_i, \mathbf{h})$ over training set, which is equivalent to minimizing $D_{\text{KL}}(p || q)$. We use the ADAM optimizer (Kingma & Ba 2017) with a learning rate of 5×10^{-4} . To prevent overfitting, we evaluate the total log likelihood on the validation data at every training epoch and stop the training when the validation log likelihood fails to increase after 20 epochs. Training our model with a batch size of 50 takes roughly a day on a single 2.6 GHz Intel Skylake CPU. Given our small batch size, we find similar training times when using CPUs or GPUs.

4. NASA-SLOAN ATLAS

As a demonstration of its speed and accuracy, we apply SEDFLOW to optical photometry from the NASA-Sloan Atlas³ (NSA). The NSA catalog is a re-reduction of SDSS DR8 (Aihara et al. 2011) that includes an improved background subtraction (Blanton et al. 2011). We use SDSS photometry in the u , g , r , i , and z bands, which are corrected for galactic extinction using Schlegel et al. (1998). To ensure that the galaxy sample is not contaminated, we impose a number of additional quality cuts by excluding:

- objects where the centroiding algorithm reports the position of the peak pixel in a given band as the centroid. The SDSS photometric pipeline can struggle to accurately define the center of objects near the edge or at low signal-to-noise, so these cases are often associated with spurious objects.
- objects that have pixels that were not checked for peaks by the deblender.
- objects where more than 20% of point-spread function (PSF) flux is interpolated over as well as objects where the interpolation affected many pixels and the PSF flux error is inaccurate. The SDSS pipeline interpolates over pixels classified as bad (*e.g.* cosmic ray).
- objects where the interpolated pixels fall within 3 pixels of their center and they contain a cosmic ray that was interpolated over.

³ <http://nsatlas.org/>

- objects that were not detected at $\geq 5\sigma$ in the original frame, that contain saturated pixels, or where their radial profile could not be extracted.

By excluding these objects, we avoid complications from artifacts in the photometry that we do not model. For additional details on the quality flags, we refer readers to the SDSS documentation⁴. After the quality cuts, we have a total of 33,883 galaxies in our NSA sample.

5. RESULTS

Now that we have trained SEDFLOW, we can estimate the posterior, $p(\theta | \mathbf{x}_i)$, for any $\mathbf{x}_i = \{f_X, \sigma_X, z\}$. In practice, we do this by drawing samples from the SEDFLOW NDE model: $q(\theta | \mathbf{x}_i, \mathbf{h})$. Since we use a normalizing flow, this is trivial: we generate samples from the target distribution of the normalizing flow, a multivariate Gaussian distribution in our case, then we transform the samples using the bijective transformation in Eq. 2 that we trained. The transformed samples follow $q(\theta | \mathbf{x}_i, \mathbf{h})$ and estimate the posterior, $p(\theta | \mathbf{x}_i)$.

Next, we validate the accuracy of the SEDFLOW posterior estimates. As a first test, we compare the posterior from SEDFLOW to the posterior derived from MCMC sampling for a single arbitrarily chosen NSA galaxy in Figure 2. In the top, we present the the posterior distribution of the 12 SED model parameters (Section 3.1) for the SEDFLOW posterior (blue) and MCMC posterior (black). *The SEDFLOW posterior is in excellent agreement with the MCMC posterior for all of the SED parameters.*

In the bottom of Figure 2, we compare the SEDs of the best-fit parameter values from the SEDFLOW (blue) and MCMC posteriors (black dotted). We also include the NSA photometric flux of the selected galaxy (red). The best-fit SED from the SEDFLOW posterior is also in excellent agreement with both the MCMC best-fit SED and the NSA photometry.

The key advantage of ANPE is that it enables accurate Bayesian inference orders of magnitude faster than conventional methods. We derive the MCMC posterior using the ZEUS ensemble slice-sampler (Karamanis & Beutler 2020) with 30 walkers and 10,000 iterations. 2,000 of the iterations are discarded for burn-in. In total, the MCMC posterior requires $>100,000$ SED model evaluations. Since each evaluation takes ~ 340 ms, it ~ 10 CPU hours for a single MCMC posterior. Recently, SED modeling has adopted neural emulators to accelerate SED model evaluations (Alsing et al. 2020). In Hahn et al. (2022), for instance, the PROVABGS emulator takes only ~ 2.9 ms to evaluate, $>100\times$ faster than the original model. Yet, even with emulators, due to the number of evaluations necessary for convergence, an MCMC posterior takes ~ 10 CPU minutes. Meanwhile, after training, *the SEDFLOW posterior takes 1 second — $>10^4\times$ faster than MCMC.*

In addition to the NSA galaxy in Figure 2, the posteriors from SEDFLOW and MCMC are overall in excellent for NSA galaxies. However, we do not know the true SED parameters for these galaxies so to further validate SEDFLOW, we use test synthetic photometry, where we know the truth. We sample 1000 SED parameters from the prior, $\{\theta_i^{\text{test}}\} \sim p(\theta)$, and forward model synthetic NSA

⁴ https://www.sdss.org/dr16/algorithms/flags_detail

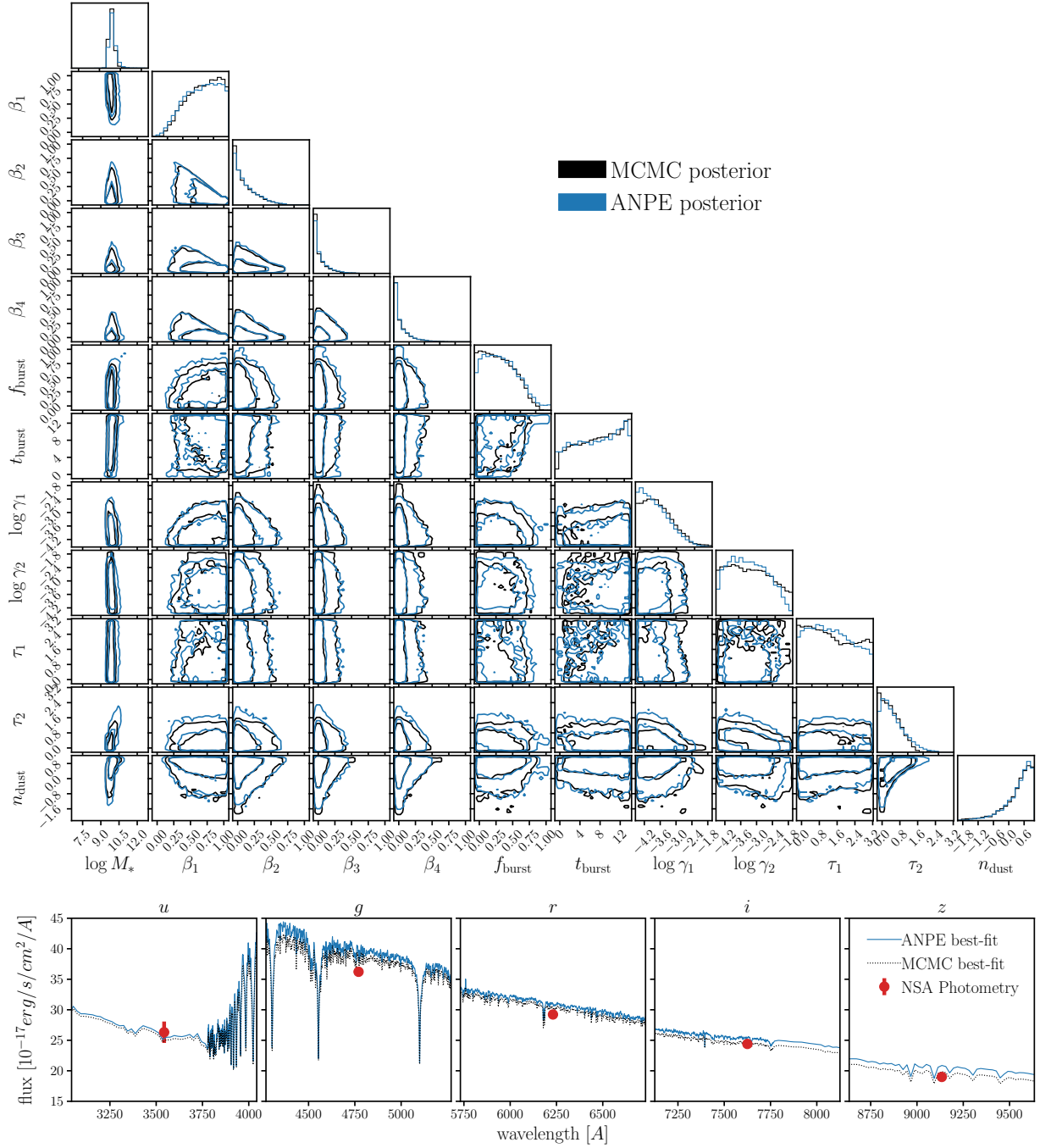


Figure 2. A comparison of the posteriors of the 12 SED model parameters derived from standard MCMC sampling (black) and our SEDFLOW (blue) for an arbitrarily selected NSA galaxy ($\text{NSAID} = 72$). The posteriors are in excellent agreement for all of the SED parameters. In the bottom panel, we present the SEDs of the the best-fit parameter values from the SEDFLOW (blue) and MCMC posteriors (black dotted), which are all in excellent agreement with the observed NSA photometric flux (red). We mark the optical broadband response curves (dashed) for reference. Estimating the posterior using MCMC sampling requires 10 CPU hours. Even using neural emulators to accelerate likelihood evaluations, MCMC sampling requires 10 CPU minutes. *With SEDFLOW, inferring the full posterior takes 1 second per galaxy.*

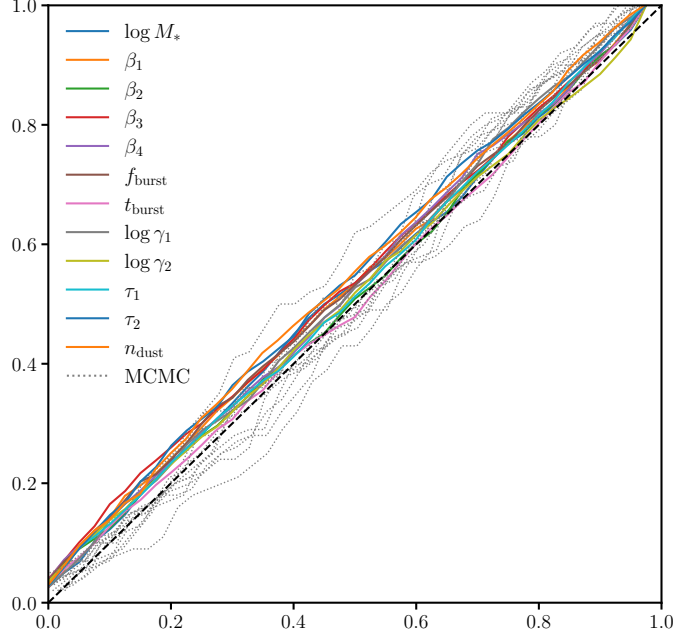


Figure 3. Probability-probability (p-p) plot of the SEDFLOW posteriors for 1000 synthetic test observations, with known true parameter values. We plot the CDFs of the percentile score of the true values within the marginalized SEDFLOW posteriors for each SED parameter. For the true posteriors, the percentile score is uniformly distributed so the CDF is diagonal (black dashed). The test data is constructed in the same way as the training data (Section 3.2). For reference, we include the p-p plot of the posterior estimated from MCMC sampling (gray). *The SEDFLOW posteriors are in excellent agreement the true posteriors.*

observations, $\{\mathbf{x}_i^{\text{test}}\}$, for them in the same way as the training data (Section 3.2). Afterwards, we generate posteriors for each of $\mathbf{x}_i^{\text{test}}$ using SEDFLOW: $\{p(\theta | \mathbf{x}_i^{\text{test}})\}$.

In Figure 3, we present the probability-probability (p-p) plot of the SEDFLOW posteriors for the test data. The p-p plot presents the cumulative distribution function (CDF) of the percentile score of the true value within the marginalized posterior for each parameter. For true posteriors, the percentiles are uniformly distributed so the CDF is a diagonal (black dashed). Overall, the CDFs for SEDFLOW lie close to the diagonal for each of the SED parameters. *Hence, the SEDFLOW posteriors are in excellent agreement with the true posteriors.*

In Figure 3, we also include the CDFs of the SED parameters for the MCMC posteriors derived for a subset of 100 test observations (gray dotted). Comparing the CDFs from the MCMC posteriors to those of SEDFLOW, we find that the SEDFLOW posteriors are actually in better agreement with the true posteriors. This is due to the fact that MCMC posteriors are also only estimates of the true posterior and are subject to limitations in initialization, sampling, and convergence. On the other hand, posteriors from SEDFLOW are not impacted by these limitations, so the comparison highlights additional advantages of an ANPE approach besides the $>10^4\times$ performance increase.

We examine another validation of the SEDFLOW posteriors using simulation-based calibration (SBC; Talts et al. 2020). Rather than using percentile scores, SBC examines the distribution of the rank statistics of the true parameter values within the marginalized posteriors. It addresses the

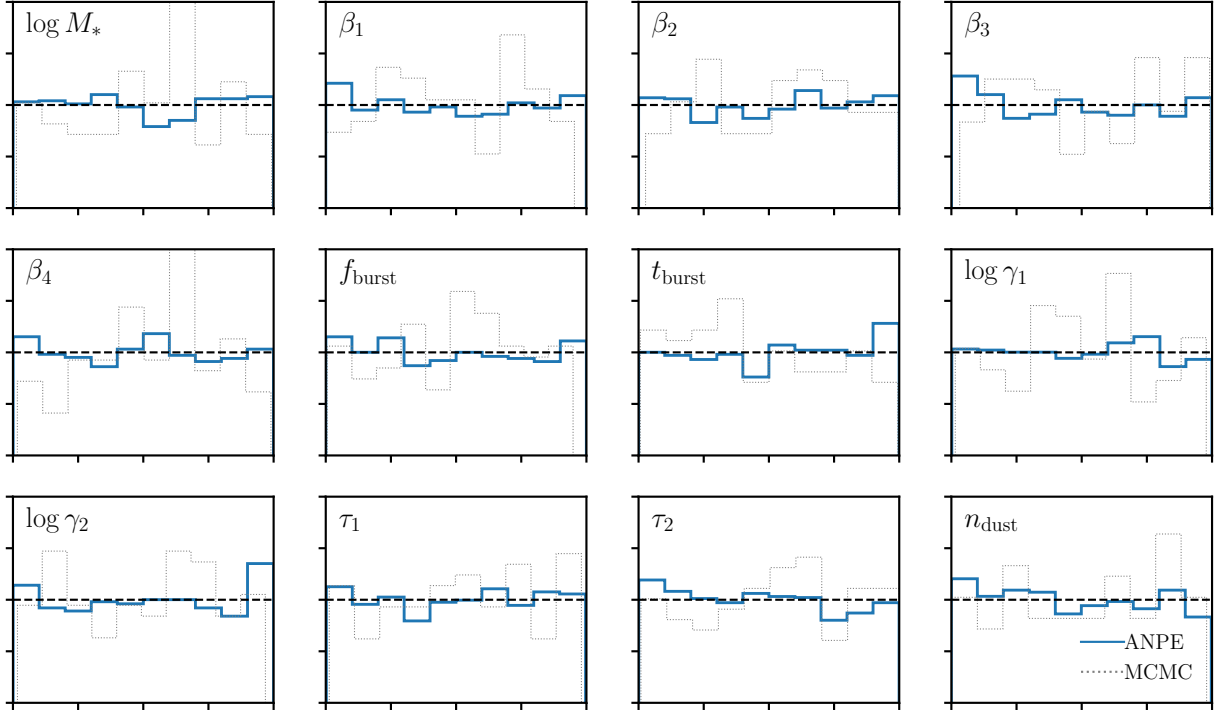


Figure 4. Simulation-based calibration plot of the SEDFLOW posteriors for 1000 synthetic test observations. The histogram in each panel represents the distribution of the rank statistic of the true value within the marginalized SEDFLOW posterior (blue) for each SED parameter. For the true posterior, the rank statistics will have a uniform distribution (black dashed). For reference, we include the rank distribution of the MCMC posteriors for a subset of 100 test data (gray dotted). The rank statistic distribution of SEDFLOW is nearly uniform for all of the SED parameters. Therefore, SEDFLOW provides unbiased and precise estimates of the true posteriors.

limitation that the CDFs only asymptotically approach the true values and that the discrete sampling of the posterior can cause artifacts in the CDFs. In Figure 4, we present SBC of each SED parameter for the SEDFLOW posteriors (blue) using the 1000 test observations. For comparison, we include the SBC for the MCMC posteriors (gray dotted). Similar to the percentile score, the distribution of the rank statistic is uniform for the true posterior (black dashed). The rank statistic distribution for the SEDFLOW posteriors are nearly uniform for all SED parameters. Hence, *we confirm that the SEDFLOW posteriors are in excellent agreement with the true posterior.*

An advantage of SBC is that by examining the deviation of rank statistics distribution from uniformity, we can determine how the posterior estimates deviate from the true posteriors. For instance, if the distribution has a U-shape where the true parameter values are more often at the lowest and highest ranks, then the posterior estimates are narrower than the true posteriors. If the distribution has a \cap -shape, then the posterior estimates are broader than the true posteriors. Any asymmetry in the distribution implies that the posterior estimates are biased. For the SEDFLOW posteriors, we find none of these features for any of the SED parameters. Hence, SEDFLOW provides unbiased and precise estimates of the true posteriors for all SED parameters.

With the accuracy SEDFLOW validated, we apply it to derive posteriors for all of our NSA galaxies (Section 4). Analyzing all 33,887 NSA galaxies takes X CPU hours. For each galaxy, we generate 10,000 samples of the 12-dimensional posterior, $p(\theta|\mathbf{x}_{\text{obs}})$. These posteriors on SED parameters represent posteriors on stellar mass, SFH, ZH, and dust content of the NSA galaxies. To maximize the utility of the posteriors further, we use them to derive posteriors on the following additional galaxy properties: SFR averaged over 1Gyr, mass-weighted metallicity, and mass-weighted stellar age. We refer readers to Section X of Hahn et al. (2022) for the exact calculation. We publicly release all of the posteriors for our NSA sample at [some-url-here](#). Furthermore, SEDFLOW model and all of the software used to train it are publicly available at <https://github.com/changhoonhahn/SEDflow/>.

6. DISCUSSION

6.1. Further Validation

In the previous section, we validated and demonstrated the accuracy of SEDFLOW posteriors. Nevertheless, a primary determining factor of SEDFLOW, and any ML model, is the quality of the training data. In our case, the training data is generated using a forward model with two components: the PROVABGS SED model and a noise model (Section 3.2). We first consider the noise model.

In our noise model, we assign noiseless photometric fluxes uncertainties based on an empirical estimate of $p(\sigma_X | f_X)$ for each band independently. Afterwards, the assigned σ_X is used to apply Gaussian noise to the photometric flux (Eq. 4). This is a simplistic noise model and, as the bottom right ($g - \sigma_r$ and $r - \sigma_r$) panels of Figure 1 reveal, there are discrepancies in the magnitude versus uncertainty distributions of the training data and observations. Despite these discrepancies, SEDFLOW provides excellent estimates of the true posterior. This is because we design our ANPE to include σ_X as a conditional variable (Section 3.3). The $f_X - \sigma_X$ distribution of our training data does not impact the accuracy of the posteriors as long as there is sufficient training data near \mathbf{x}_{obs} to properly train the NDE in the region.

A more accurate noise model will, in theory, improve the performance of SEDFLOW since the \mathbf{x} -space of the training data will more effectively span the observations. In other words, there will be fewer training data expended in regions of \mathbf{x} -space that are devoid of observations. However, for our application to SED modeling, we do not find significantly improved performance when we replace the noise model. This suggests that even with our simplistic forward model, the \mathbf{x} -space of observations is sufficiently covered by the training data. We note that when we decrease N_{train} below 500,000, SEDFLOW posteriors are significantly less accurate. A more realistic forward model may reduce this N_{train} threshold for accurate posteriors. However, generating $N_{\text{train}} \sim 1,000,000$ training has a negligible computational cost compared to MCMC SED modeling so we do not explore this further.

Next, we consider limitations in the PROVABGS SED model used in our forward model. One of its advantages is that it uses a compact and flexible prescription for SFH and ZH that can describe a broad range of SFHs and ZHs. However, the prescription was derived from simulated Illustris galaxies, whose SFHs and ZHs may not reflect the full range of SFHs and ZHs of real galaxies. If certain subpopulations of galaxies have SFHs and ZHs that cannot be described by the PROVABGS

prescriptions, they cannot be accurately forward modeled. Furthermore, even if the PROVABGS SFH and ZH prescriptions are sufficient, there are limitations in our understanding of stellar evolution.

There is currently no consensus in the stellar evolution, stellar spectral libraries, or IMF of galaxies (*e.g.* Treu et al. 2010; van Dokkum & Conroy 2010; Rosani et al. 2018; Ge et al. 2019; Sonnenfeld et al. 2019). The PROVABGS model uses MIST isochrones, Chabrier (2003) IMF, and the MILES + BaSeL spectral libraries. These choices limit the range of SED that can be produced by the training data. For instance, if galaxies have significant variations in their IMF, assuming a fixed IMF would reduce the range of our training data. A more flexible SED model that includes uncertainties in SPS would broaden the range of galaxy SEDs that can be modeled. Data-driven approaches may also enable SED models to be more descriptive (*e.g.* Hogg et al. 2016; Portillo et al. 2020). Improving SED models, however, is beyond the scope of this work. Our focus is on improving the Bayesian inference framework. In that regard, the limitations of the SED model equally impacts conventional approaches with MCMC.

Given the limitations of any forward model, we can construct additional tests of posteriors derived from ANPE. For instance, the χ^2 of the best-fit parameter value from the estimated posterior can be used to test whether the best-fit model accurately reproduces observations. This would only require one additional model evaluation. As another test of the posteriors, one can construct an Amortized Neural Likelihood Estimator (ANLE) using the same training data. Unlike the ANPE, which estimates $p(\theta | f_X, \sigma_X, z)$, the ANLE would estimate $p(f_X | \theta, \sigma_X, z)$. We can then further validate the posteriors by assessing whether the observed photometry lies within the ANLE. Based on the high level of accuracy of SEDFLOW posteriors in the previous section, we do not explore these additional tests; however, they can be used to further validate any ANPE posterior.

6.2. Additional Advantages

So far, we have primarily focused on the computational advantages of SEDFLOW for individual posterior estimation. However, there are other benefits to our ANPE approach. One of the key ingredients in Bayesian inference is the prior. For SED modeling, recent works have demonstrated that model priors play a crucial role in the derived galaxy properties (Carnall et al. 2018; Leja et al. 2019; Hahn et al. 2022). Even “uninformative” uniform priors on SED model parameters can impose undesirable priors on derived galaxy properties such as M_* , SFR, SFH, or ZH. This underscores the importance of carefully selecting priors and validating results using multiple different priors. For SED modeling with MCMC, selecting a different prior requires reevaluating every posterior and repeating all the SED model evaluations in the MCMC sampling. For ANPE, the prior is set by the distribution of parameters in the training data. For a new prior, instead of regenerating the training data, we can subsample it so that the parameters follow the new prior. Afterwards, the ANPE model can be re-trained, re-validated on the test data, and re-deployed on observations. Each of these steps require substantially less computational resources than generating a new set of training data or using MCMC methods. Hence, the ANPE approach also provides a way to efficiently vary the prior without multiplying computational costs.

In this work, we use SEDFLOW to perform SED modeling on galaxy photometry. We estimate a 12-dimensional probability distribution with an 11-dimensional conditional variable space. While

this dimensionality is already a limiting factor for current MCMC methods, ANPE has already been applied to higher dimensional applications. [Dax et al. \(2021\)](#), for instance, constructed an accurate ANPE for a 15-dimensional model parameter space and 128-dimensional conditional variable space. Furthermore, NDE is an actively developing field in ML and new methods are constantly emerging (*e.g.* [Wu et al. 2020](#); [Dhariwal & Nichol 2021](#)).

Without the limitations of current Bayesian inference methods, ANPE opens the doors to better SED modeling. As mention above, SED models currently do not account for uncertainties in stellar evolution, spectral libraries, or the IMF. Since ANPE approaches can handle higher dimensionality, SED models can include additional parameters that model these uncertainties as well as any observational systematics (*e.g.* zero-point calibration).

6.3. Next Applications

In this work, we apply the ANPE approach to optical photometry, photometric uncertainties, and redshifts from the NSA. Our approach can easily be extended beyond this application. For instance, we can include multi-wavelength photometry at ultra-violet (UV) or infrared (IR) wavelengths. We can also modify SEDFLOW to infer redshift from photometry. In SEDFLOW, we include redshift as a conditional variable, since NSA provides spectroscopic redshifts. However, redshift can be included as an inferred variable rather than a conditional one. Then, we can apply SEDFLOW to infer galaxy properties from photometric data sets without redshift measurements while marginalizing over the redshift prior. If we do not require spectroscopic redshifts, SEDFLOW can be extended to much larger data sets that span fainter and broader galaxy samples. Conversely, we can use SEDFLOW to infer more physically motivated photometric redshifts, where we marginalize over our understanding of galaxies rather than using templates.

The ANPE approach to SED modeling can also be extended to galaxy spectra. Constructing an ANPE for the full data space of spectra, however, requires estimating a dramatically higher dimensional probability distribution. SDSS spectra, for instance, have $\sim 3,600$ spectral elements. Furthermore, in our approach we include the uncertainties of observables as conditional variables, which double the curse of dimensionality. Recent works, however, have demonstrated that galaxy spectra can be represented in a compact low-dimensional space using autoencoders ([Portillo et al. 2020](#), ; [Melchior & Hahn in prep.](#)). In [Portillo et al. \(2020\)](#), they demonstrate that SDSS galaxy spectra can be compressed into 7-dimensional latent variable space with little loss of information. Such spectral compression dramatically reduces the dimensionality of the conditional variable space to dimensions that can be tackled by current ANPE methods. We will explore SED modeling of galaxy spectrophotometry using ANPE and spectral compression in a following work.

With SEDFLOW, we can generate accurate posteriors for SED modeling $>10^4$ faster than conventional MCMC methods. Analyzing 33,887 NSA galaxies only takes \times CPU hours. Analyzing the 10 million galaxies of DESI BGS would only take ~ 3000 CPU hours. An ANPE approach will enable rigorous SED modeling on the enormous galaxy samples that will be observed by DESI, PFS, Rubin, JWST, and Roman. The Rubin observatory, alone, will soon provide photometry from billions of galaxies. We will be able to construct probabilistic catalogs that provide accurate posteriors on the physical properties for all of these galaxies.

7. SUMMARY

By analyzing the SED of a galaxy, we can infer detailed physical properties such as its stellar mass, star formation rate, metallicity, and dust content. These properties serve as the building blocks of our understanding of how galaxies form and evolve. State-of-the-art SED modeling methods use MCMC sampling to perform Bayesian statistical inference. They derive posterior probability distributions of galaxy properties given observation that accurately estimate uncertainties and parameter degeneracies to enable more rigorous statistical analyses. For the dimensionality of current SED models, deriving a posterior requires $\gtrsim 100,000$ model evaluations and take $\gtrsim 10 - 100$ CPU hours per galaxy. Upcoming galaxy surveys, however, will observe *millions* of galaxies using *e.g.* DESI, PFS, Rubin observatory, James Webb Space Telescope, and the Roman Space Telescope. Analyzing all of these galaxies with current Bayesian SED models is infeasible and would require *billions* of CPU hours. Rigorous inference would be the major bottleneck for galaxy studies.

We demonstrate in this work that Amortized Neural Posterior Estimation (ANPE) provides an alternative *scalable* approach for Bayesian inference in SED modeling. ANPE is a simulation-based inference method that leverages the latest developments in ML. It formulates Bayesian inference into a density estimation problem and uses neural density estimators (NDE) to approximate the posterior over the full space of observations. The NDE is trained using parameter values drawn from the prior and mock observations forward modeled using them. Once trained, a posterior can be derived using the NDE by plugging in the observations as the conditional variables without any additional model evaluations.

In this work, we present SEDFLOW, a galaxy SED modeling method using ANPE and PROVABGS, a flexible SED model that uses a compact non-parameteric SFH and ZH prescriptions and was recently validated in [Hahn et al. \(2022\)](#). Furthermore, we apply SEDFLOW to optical photometry from the NASA-Sloan Atlas as demonstration and validation of our ANPE approach. We present the following key results from our analysis.

- We train SEDFLOW using a data set of ~ 1 million SED model parameters and forward model synthetic SEDs. The parameters are drawn from a prior and the forward model is based on the PROVABGS and noise models. We design the ANPE to estimate $p(\theta|f_X, \sigma_X, z)$, where f_X , σ_X , and z are the photometry, photometric uncertainty, and redshift respectively. For its architecture, we use a MAF normalizing flow with 15 MADE blocks each with 2 hidden layers and 500 hidden units. Training SEDFLOW requires roughly 1 day on a single CPU. Once trained, deriving posteriors of galaxy properties for a galaxy takes ~ 1 second — $> 10^4 \times$ faster than current methods.
- Posteriors derived using SEDFLOW show excellent agreement with posteriors derived from MCMC sampling. We further validate the accuracy of its posteriors by applying SEDFLOW to synthetic observations with known true parameter values. Based on statistical metrics used in the literature (p-p plot and SBC), we find excellent agreement between the SEDFLOW and the true posterior.

- Lastly, we demonstrate the advantages of SEDFLOW by applying it to the NASA-Sloan Atlas. Estimating the posterior of $\sim 34,000$ galaxies takes **X** CPU hours. We make the catalog of posteriors publicly available at [urlhere](#). For each galaxy, the catalog contains posteriors on all 12 PROVABGS SED model parameters. In terms of galaxy properties, the catalog includes posteriors of M_* , average SFR over 1Gyr, mass-weighted metallicity, mass-weighted age, and dust optical depth.

TODO

This work highlights the advantages of using an ANPE approach to Bayesian SED modeling. Our approach will enable us to analyze the millions of galaxies that will be observed by upcoming experiments and accurately measure their physical properties. In addition, the posteriors on galaxy properties for all these galaxies we will be able to construct probabilistic galaxy catalogs that will unlock a new level of statistical robustness in galaxy studies and more fully extract the statistical power of future observations.

In this work, we focus on SED modeling of optical photometry. The performance of ANPE has already been demonstrated on higher dimensional applications. This means that SEDFLOW can easily be extended to multi-wavelength photometry. In fact, with the latest developments in efficiently dimensionality reduction of spectra (Portillo et al. 2020, Melchior & Hahn 2022), SEDFLOW can even be extended to galaxy spectra. We will explore this in subsequent work.

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APPENDIX

A. OUTSIDE SEDFLOW SUPPORT

For a number of NSA galaxies, 591 out of 33,883, SEDFLOW does not produce valid posteriors. The normalizing flow of SEDFLOW generates posteriors that are entirely outside of the prior volume. This is driven by NSA galaxies that are outside of the support of the SEDFLOW training data. They lie outside of the support for two reasons: (1) some have unusually high photometric uncertainties that are accounted for in our noise model and (2) some have photometric colors that cannot be modeled by our SED model.

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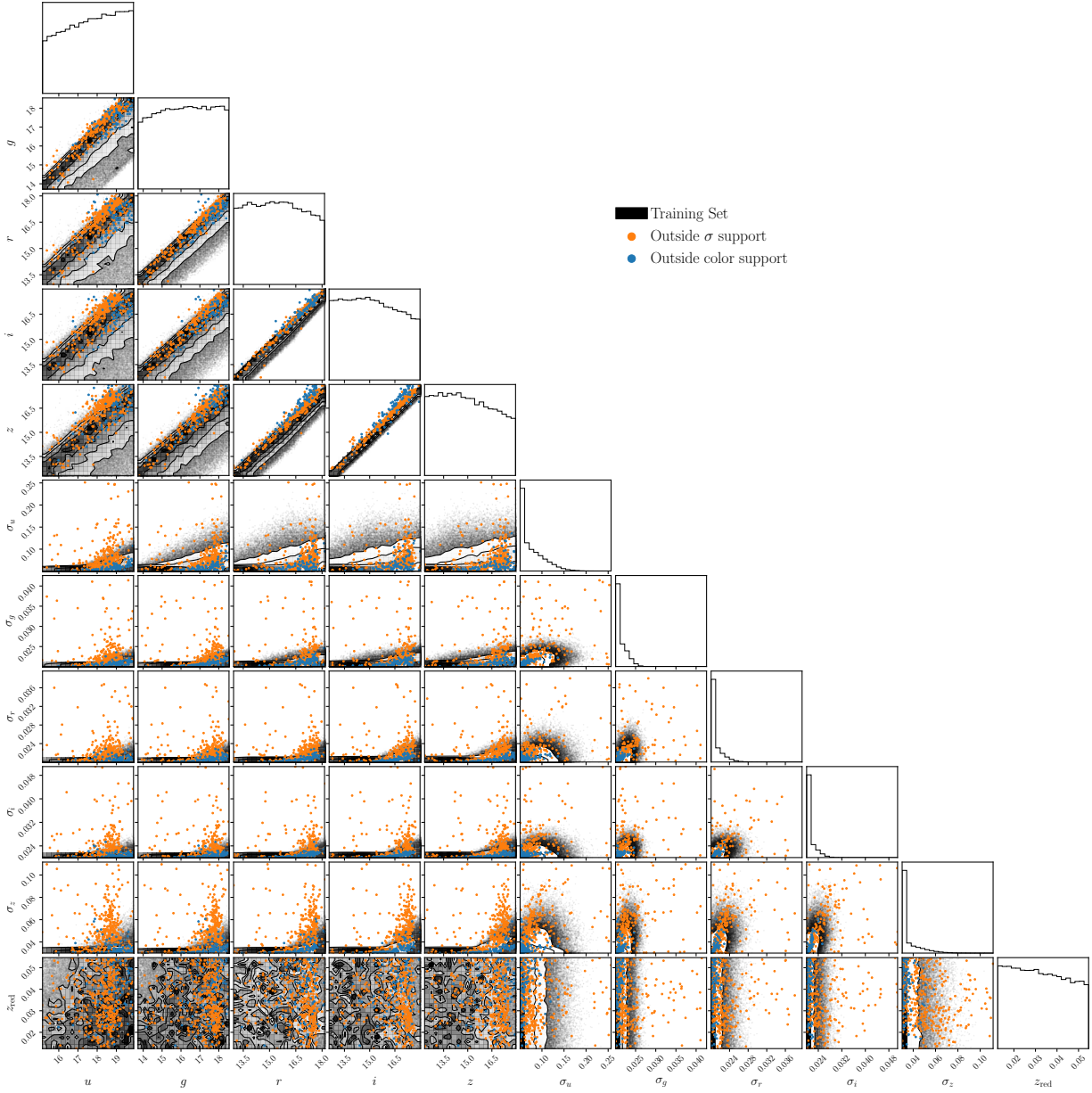


Figure 5.

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