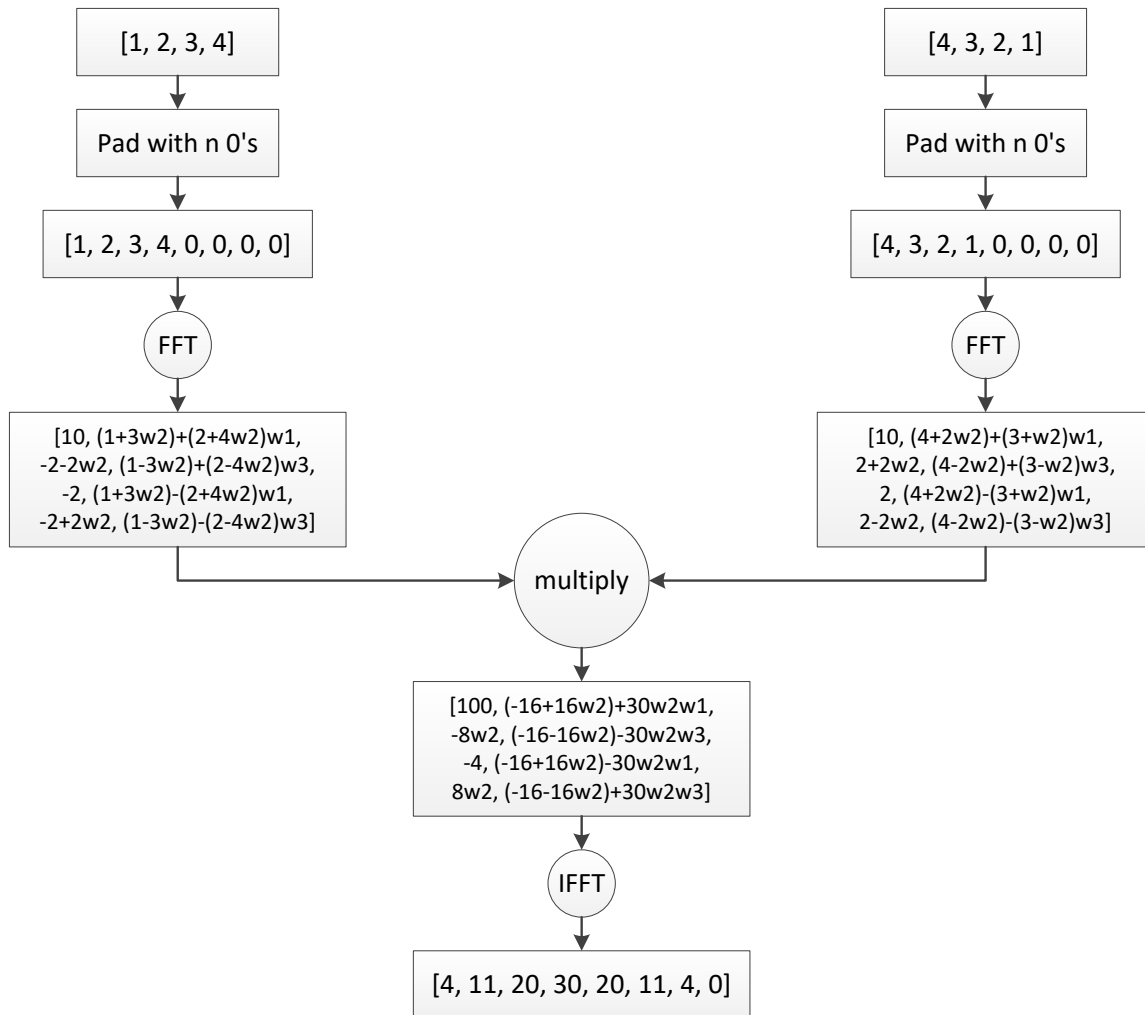


R-10.18

Use the FFT and inverse FFT to compute the convolution of $a = [1, 2, 3, 4]$ and $b = [4, 3, 2, 1]$. Show the output of each component as Figure 10.15.

For easily understanding, I use the following expression for the eighth root of unity.

$$w_8^n = \{w_8^0, w_8^1, w_8^2, w_8^3, w_8^4, w_8^5, w_8^6, w_8^7\} = \{1, w_1, w_2, w_3, w_4, w_5, w_6, w_7\}$$



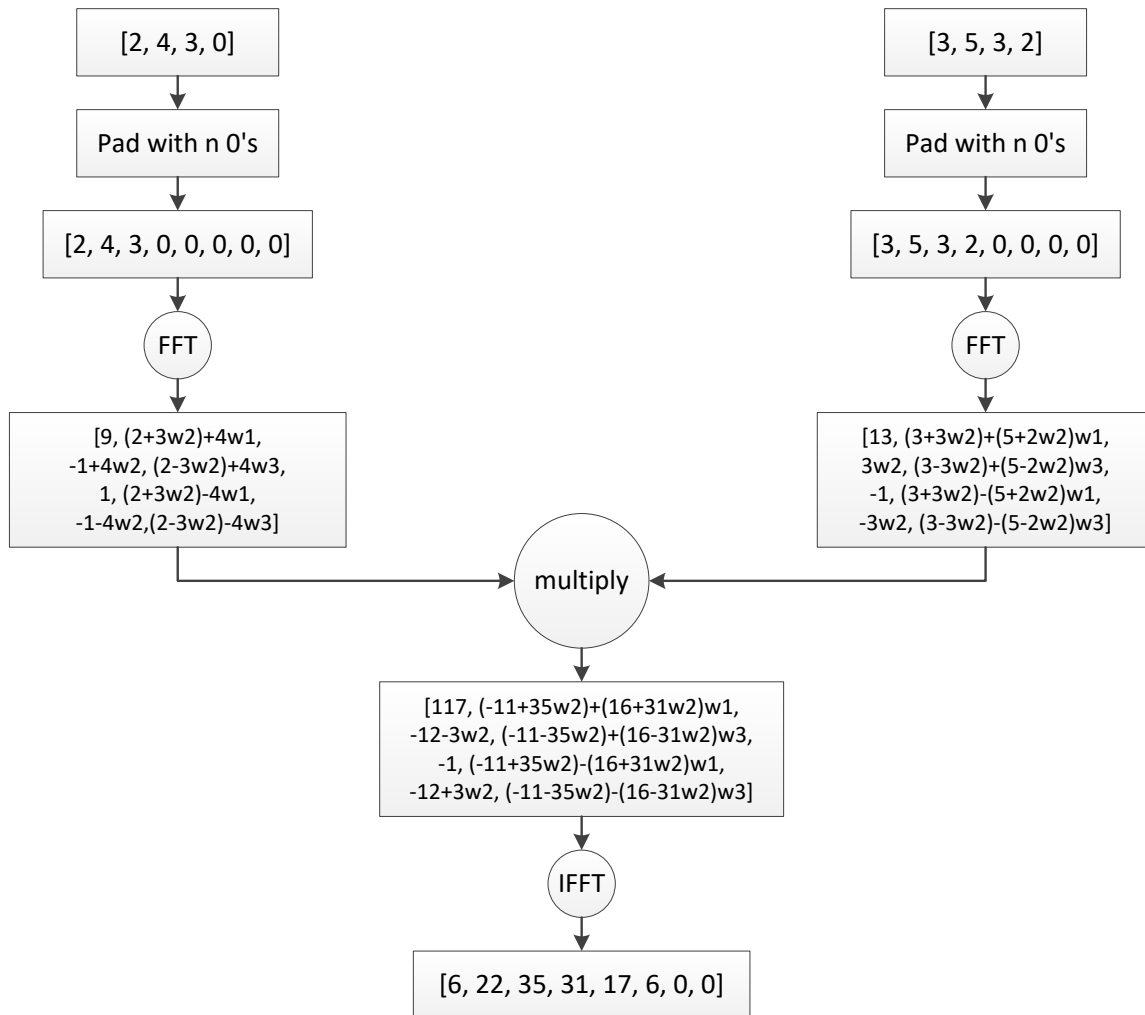
The result is $[4, 11, 20, 30, 20, 11, 4, 0]$.

R-10.19

Use the convolution theorem to compute the product of the polynomials $p(x) = 3x^2 + 4x + 2$ and $q(x) = 2x^3 + 3x^2 + 5x + 3$.

For easily understanding, I use the following expression for the eighth root of unity.

$$w_8^n = \{w_8^0, w_8^1, w_8^2, w_8^3, w_8^4, w_8^5, w_8^6, w_8^7\} = \{1, w_1, w_2, w_3, w_4, w_5, w_6, w_7\}$$



The result is $p(x) \cdot q(x) = 6 + 22x + 35x^2 + 31x^3 + 17x^4 + 6x^5$.

C-10.9

Given degree- n polynomials $p(x)$ and $q(x)$, describe an $O(n \log n)$ -time method for multiplying the derivative of $p(x)$ by the derivative of $q(x)$.

First, we can use the standard calculus rule to compute the derivative of $p(x)$ and $q(x)$ and get $p'(x)$ and $q'(x)$. Second, we can use the FFT to compute the product of $p'(x)$ and $q'(x)$.

R-12.7

Provide a complete proof of Theorem 12.12.

Theorem 12.12:

Let S be a set of points in the plane, and let a be a point of S that is a vertex of the convex hull H of S . The next vertex of H , going counterclockwise from a , is the point p , such that triplet (a, p, q) makes a left turn with every other point q of S .

Because point a and p are the vertices of the convex hull, all the other points of S are contained on one side of the line through a and p , and all the angle are smaller than π .

And because p is the next vertex of H , going counterclockwise from a , all the point q are on the left side.

Totally, triplet (a, p, q) makes a left turn.

C-12.12

Design an $O(n)$ -time algorithm to test whether a given n -vertex polygon is convex. You should not assume that P is nonintersecting.

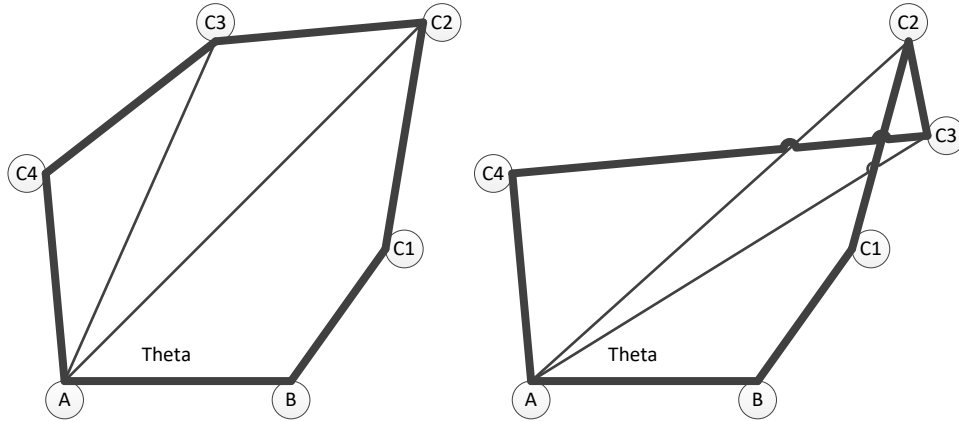
Algorithm:

To test if a polygon is convex, we must test this polygon twice.

First, we must test if each vertex is convex. We can traverse this polygon in a counterclockwise order, and test if each turn is a left turn.

Second, we must test if each line is not intersect. We need to scan this polygon. We can choose one vertex A as the apex of an angle. Next, we can traverse this polygon in a counterclockwise order. We can choose the first vertex B and AB is as one line of this

angle. For each vertex C in this polygon, AC is as the other line of this angle, and we will compute the angle in degree. With this traverse, this angle would increase. If there is a decrease of this angle, there must be intersect lines in the polygon. For example, in the following graph 1, $\angle BAC3 > \angle BAC2$, so there might not be intersect lines in the polygon. And in graph 2, $\angle BAC3 < \angle BAC2$, so there must be intersect lines in the polygon.



Running time:

For the each step, it will take $O(n)$ -time to traverse the polygon. As a result, the total running time is $O(n)$.