

ON THE GENERATIVE UTILITY OF CYCLIC CONDITIONALS

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THE QUESTION

Can we determine a **joint** distribution p(x,z) only using two **conditional** distributions p(x|z) and q(z|x) that form a cycle?

- Compatibility: is there a common joint that induces both conditionals?
- **Determinacy**: is the common joint unique?

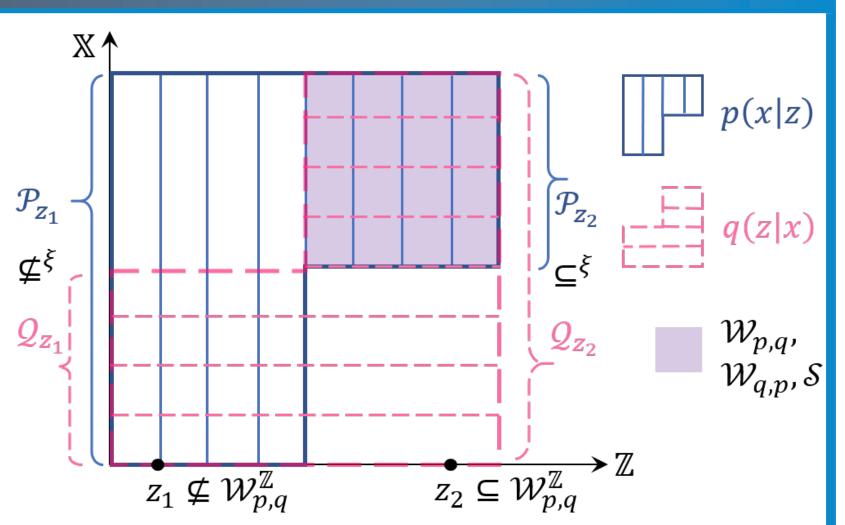
THE ANSWER: THEORY

Absolutely-Continuous Case:

"smooth" distr. on continuous spaces, all distr. on discrete spaces.



• Thm: Compatibility is achieved, iff on a suit-



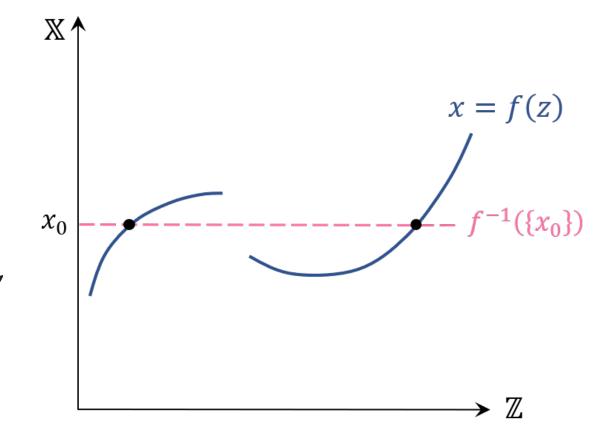
able set $S \subseteq \mathbb{X} \times \mathbb{Z}$ constructed from the conditional densities, $\frac{p(x|z)}{q(z|x)}$ a.e. factorizes as a(x)b(z), where a(x) is integrable.

- Equivalence condition, operable, self-contained.
- Why complicated: conditionals can be arbitrary on a set of marginal measure zero (e.g., outside the marginal support).
- Thm: Determinacy is achieved on S, if S is "rectangular": $\mathcal{S}_z \stackrel{\text{a.s.}}{=} \mathcal{S}^{\mathbb{X}}, \forall \text{ a.e. } z \in \mathcal{S}^{\mathbb{Z}} \text{ and } \mathcal{S}_x \stackrel{\text{a.s.}}{=} \mathcal{S}^{\mathbb{Z}}, \forall \text{ a.e. } x \in \mathcal{S}^{\mathbb{X}}.$
- Determinacy is only possible on each S.
- If both densities have *full support*, $\mathbb{X} \times \mathbb{Z}$ is the only S.

Dirac Case:

$$p(\mathcal{X}|z) = \delta_{f(z)}(\mathcal{X}) := \mathbb{I}[f(z) \in \mathcal{X}].$$

- Incl. BiGAN, flow-based.
- Thm: Compatibility is achieved, iff $\exists x_0 \text{ s.t. } q(f^{-1}(\{x_0\})|x_0) = 1$: q puts mass only on the pre-image.



- Only one x_0 suffices: $\delta_{(x_0,f(x_0))}$ is a common joint.
- When $q(\mathbf{Z}|x) = \delta_{q(x)}(\mathbf{Z})$, min. cycle-consistency loss $\mathbb{E}_{p_{\text{ref}}(x)}\ell(x, f(g(x)))$ is sufficient.
- Flow-based models are natually compatible.
- Determinacy:
- On each $\{x_0\}$, the joint $\delta_{(x_0,f(x_0))}$ is unique.
- If such x_0 is not unique, the joint is not unique on $\mathbb{X} \times \mathbb{Z}$: compatible p, q only determine a curve in $\mathbb{X} \times \mathbb{Z}$ but not a distribution on it.

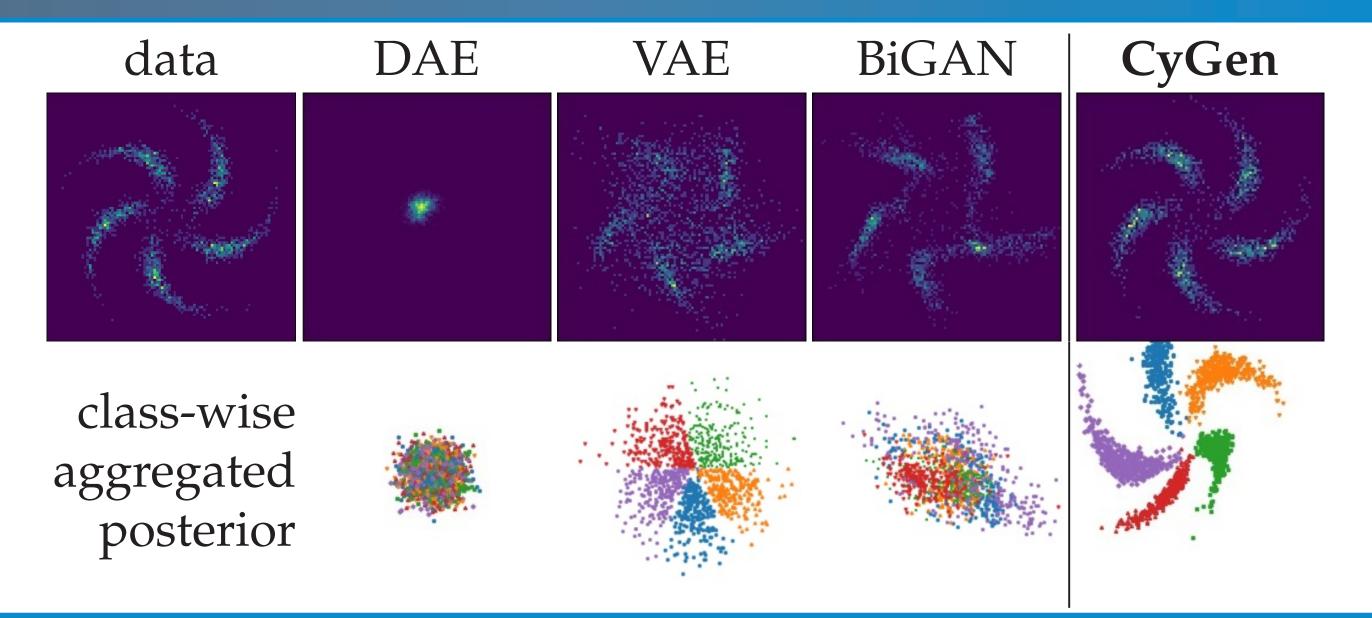
PROBLEMS OF CURRENT GENERATIVE MODELS

VAE, (Bi)GAN, flow/diffusion-based:

- Need p(x|z) for generation, q(z|x) for representation.
- Use a prior p(z) to define joint p(x,z) = p(z)p(x|z).

Specifying a prior leads to:

- Manifold mismatch (hinders generation): the modeled p(x) is restricted to a simply-connected support.
- Posterior collapse (hinders representation): representations of different x are squeezed together.



THE NEW FRAMEWORK: CYCLIC-CONDITIONAL GENERATIVE MODEL (CYGEN)

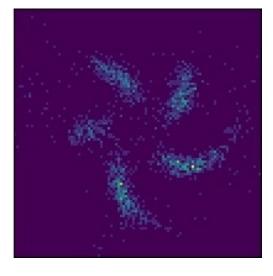
Eligibility as a generative model:

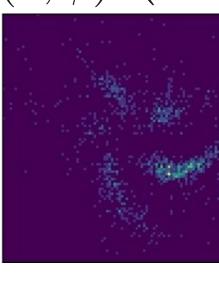
- Determinacy: Use absolutely-continuous conditionals, modeled by fully-supported densities $p_{\theta}(x|z)$, $q_{\phi}(z|x)$ (like VAE).
- Compatibility:

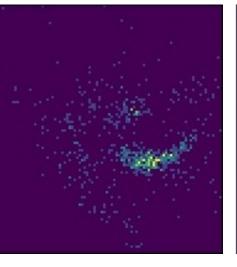
 $(\min_{\theta,\phi}) \ C(\theta,\phi) := \mathbb{E}_{p_{\text{ref}}(x,z)} \|\nabla_x \nabla_z^\top \log \left(p_{\theta}(x|z) / q_{\phi}(z|x) \right)\|_F^2.$

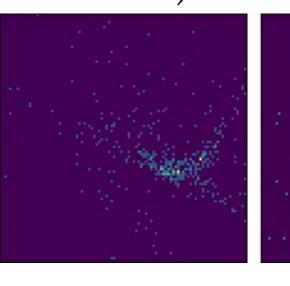
- $C(\theta, \phi) = 0 \iff p_{\theta}(x|z)/q_{\phi}(z|x)$ a.e. factorizes.
- Generalizes cycle-consistency loss to *probabilistic* conditionals.
- Gaussian VAE: $C(\theta, \phi) = 0 \iff$ mean fun. of p, q are affine! For nonlinear repr., one conditional must not be Gaussian.
- Scalable unbiased stochastic estimate: $\mathbb{E}_{p_{\text{ref}}} \mathbb{E}_{p(\eta):\mathbb{E}[\eta]=0,\text{Cov}[\eta]=I} \|\nabla_z (\eta^\top \nabla_x \log \left(p_\theta(x|z) / q_\phi(z|x) \right))\|_2^2.$ Reduce $O(d_{\mathbb{X}}d_{\mathbb{Z}})$ to $O(d_{\mathbb{X}}+d_{\mathbb{Z}})$.

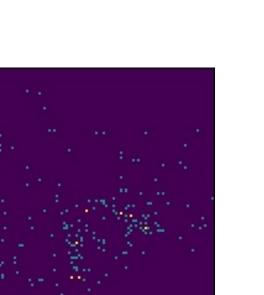
In absence of $C(\theta, \phi)$: (after pretrained as a VAE)











Usage as a generative model:

- Fit data: max. likelihood est. $\log p_{\theta,\phi}(x) = -\log \mathbb{E}_{q_{\phi}(z'|x)}[1/p_{\theta}(x|z')].$
- Est. expect. by reparameterization and logsumexp.
- Denoising auto-encoder (DAE) objective $\mathbb{E}_{q_{\phi}(z'|x)}[\log p_{\theta}(x|z')]$ is improper: (1) $\geqslant \log p_{\theta,\phi}(x)$; (2) mode-collapses q thus hurts determinacy.
- Generate data: dynamics-based MCMC.
- More efficient than Gibbs sampling:
- Only requires unnormalized density: $p_{\theta,\phi}(x) \propto \frac{p_{\theta}(x|z)}{q_{\phi}(z|x)}, \forall z.$
- E.g., Stochastic Gradient Langevin Dynamics: $x^{(t+1)} = x^{(t)} + \varepsilon \nabla_{x^{(t)}} \log \frac{p_{\theta}(x^{(t)}|z^{(t)})}{q_{\phi}(z^{(t)}|x^{(t)})} + \sqrt{2\varepsilon} \eta^{(t)},$ where $z^{(t)} \sim q_{\phi}(z|x^{(t)}), \eta^{(t)} \sim \mathcal{N}(0, I)$.

REAL-WORLD EXPERIMENTS

Data generation and classification accuracy (%) using representation:



