

# VE527

Computer-Aided Design of Integrated Circuits

Binary Decision Diagram

# Outline

- Binary Decision Diagram (BDD): Introduction
- BDD Reduction
- BDDs for Common Functions
- Sharing in BDD
- Real Way to Build BDD
- Applications and Issues of BDD

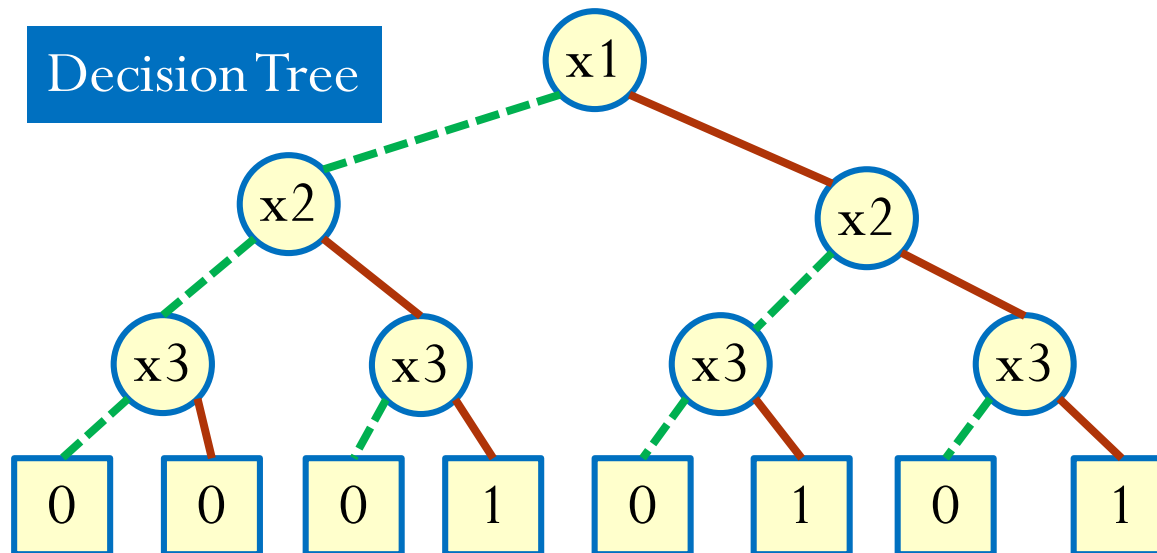
# Binary Decision Diagrams (BDD)

- Originally studied by several people
- ... got **practically useful** in 1986
  - Randal Bryant of CMU made breakthrough on **Reduced Ordered BDD (ROBDD)**.
- Reference
  - R. Bryant, “Symbolic Boolean manipulation with ordered binary decision diagrams,” ACM Computing Surveys, vol. 24, no. 3, pp. 293–318, 1992.

# Binary Decision Diagrams for Truth Tables

- Big Idea #1: **Binary Decision Diagram**
  - Turn a truth table for the Boolean function into a **Decision Diagram**.
  - In simplest case, graph is just a **tree**.
  - Vertex represents a variable.

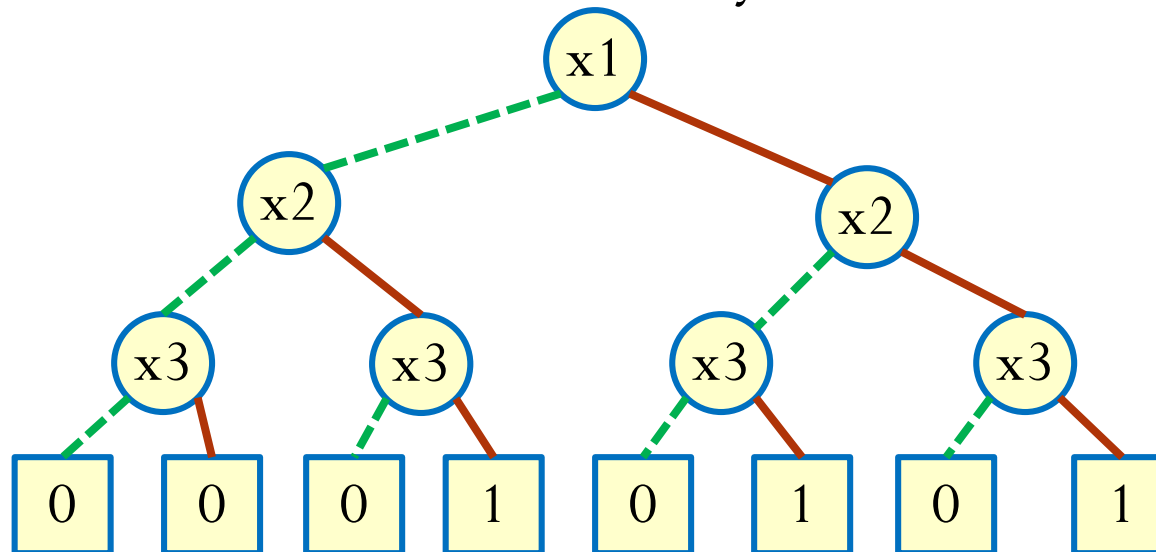
x1	x2	x3	f
0	0	0	0
0	0	1	0
0	1	0	0
0	1	1	1
1	0	0	0
1	0	1	1
1	1	0	0
1	1	1	1



# Binary Decision Diagrams

- **Edge** out of a vertex is a **decision** (0 or 1) on that variable.
  - Follow **green dashed** line for 0.
  - Follow **red solid** line for 1.
  - By convention, don't draw arrows on the edges, we know where they go.
- Function value determined by **leaf value**.

x1	x2	x3	f
0	0	0	0
0	0	1	0
0	1	0	0
0	1	1	1
1	0	0	0
1	0	1	1
1	1	0	0
1	1	1	1



# Binary Decision Diagrams

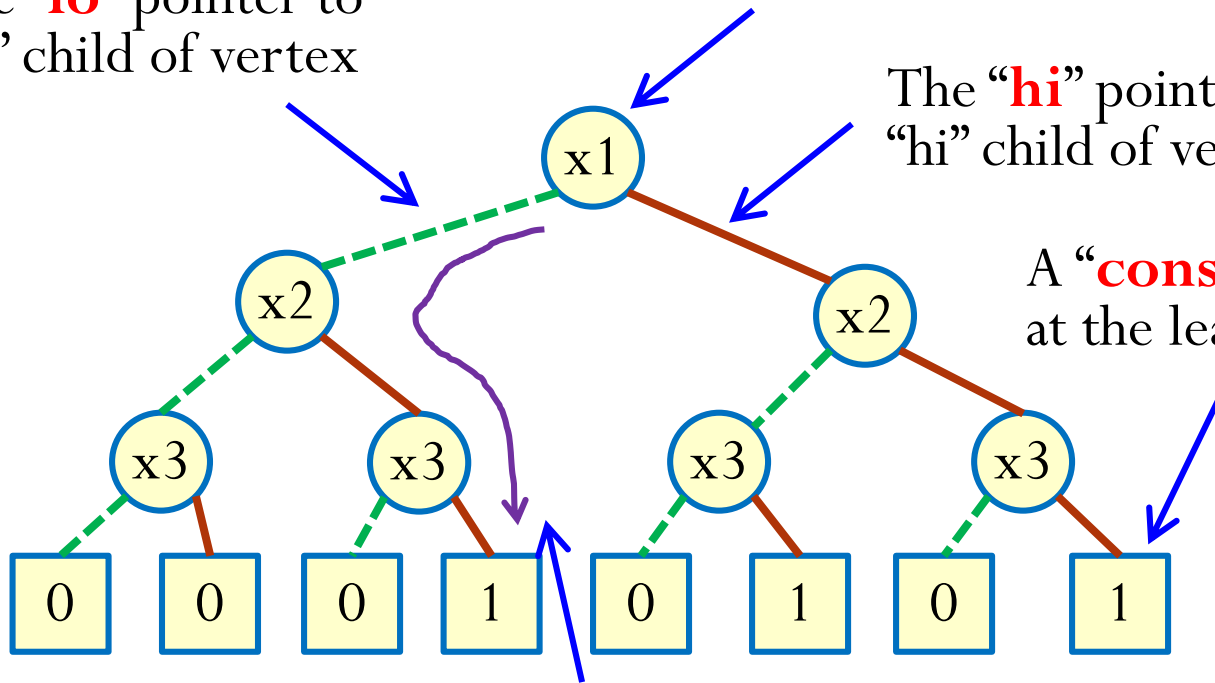
## Some Terminology

The “**lo**” pointer to  
“lo” child of vertex

A “**variable**” vertex

The “**hi**” pointer to  
“hi” child of vertex

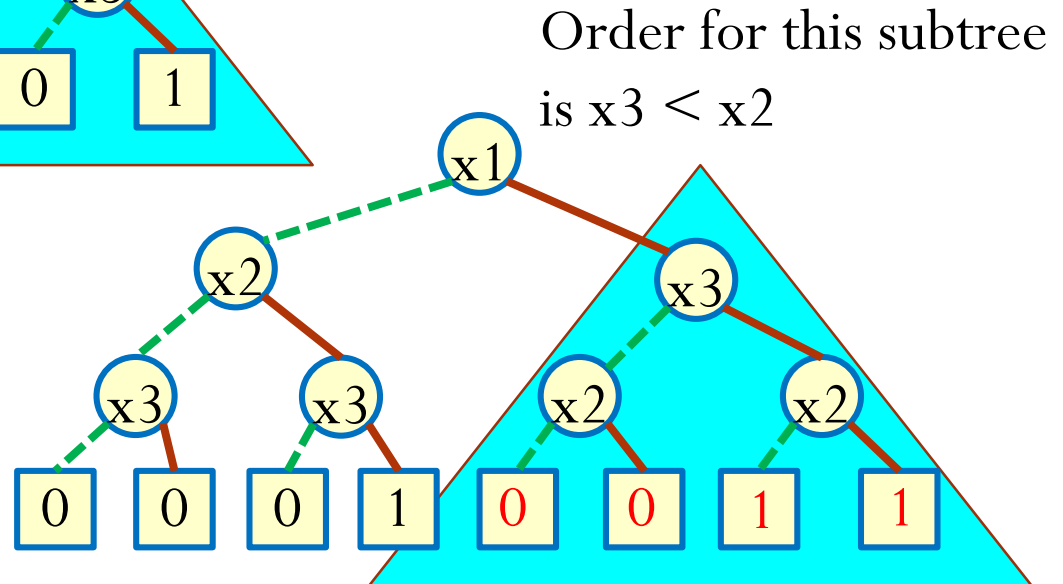
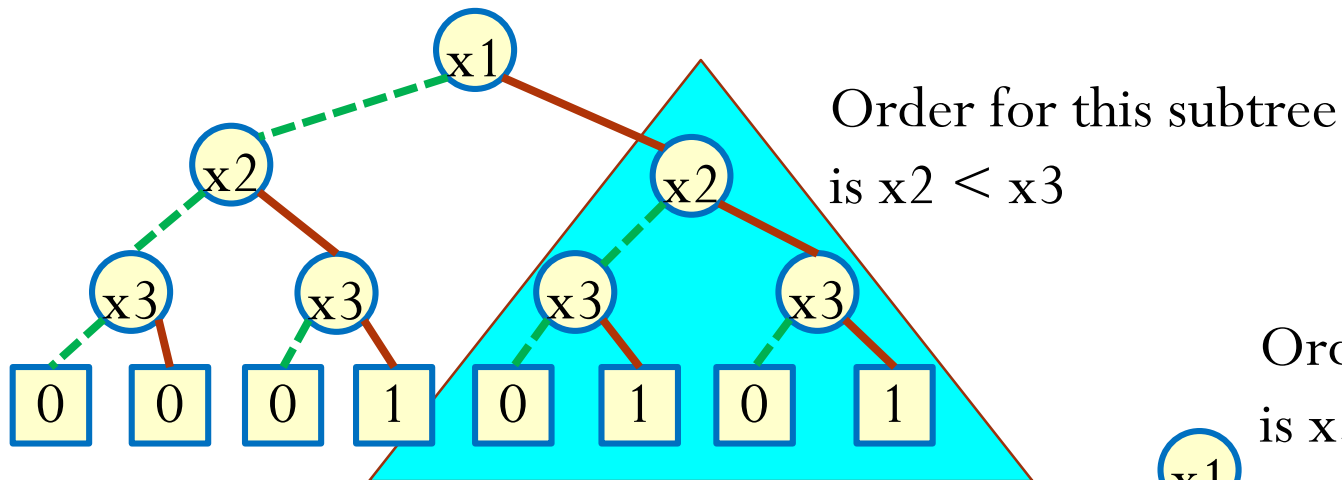
A “**constant**” vertex  
at the leaf of the tree



The ‘**variable ordering**’, which is the order in which decisions about variables are made. Here, it is  $x1 < x2 < x3$ .

# Ordering

- Different variable orders are possible.



# Binary Decision Diagrams

## Observations

- Each path from root to leaf traverses variables in **some** order.
- Each such path constitutes **a row** of the truth table, i.e., a decision about what output is when variables take these particular values.
- However, we have not yet specified anything about the **order** of decisions.
- The decision diagram is **NOT unique** for this function.

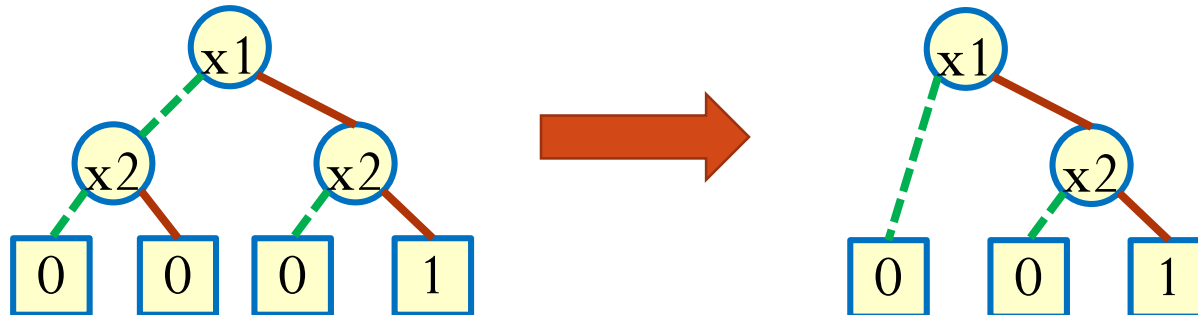


# Terminology: Canonical form

- A representation of Boolean function that is unique for each Boolean function
  - Same function of same variables always produces this exact **same** representation.
  - Does not depend on gate-level implementation
- Example: a truth table is **canonical** (up to variable order).
- We want a canonical-form data structure(!)
  - Very useful! E.g., verification

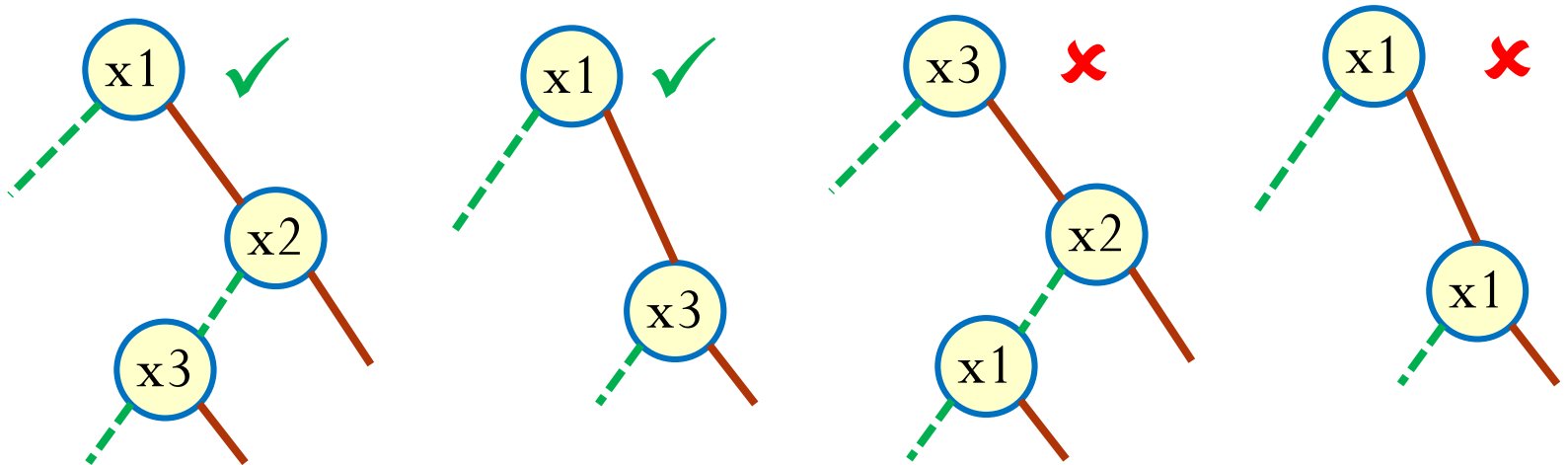
# Binary Decision Diagrams

- What's wrong with this diagram representation?
  - It is **not canonical**, and it is way **too big** to be useful (it is as big as truth table!)
- Big idea #2: **ordering**
  - Restrict **global ordering** of variables.
  - It means: **every path** from root to a leaf visits variables in the **SAME** order.
  - Note: it is OK to **omit** a variable if you don't need to check it to decide which leaf node to reach for final value of function.



# Ordering BDD Variables: Example

- Assign (an arbitrary) **global ordering** to vars:  
 $x1 < x2 < x3$ 
  - Variables must appear in this specific order along all paths; ok to skip vars



- Property: each variable assignment corresponds to only one path from the root to the leaf. Thus, no **conflicting** result.

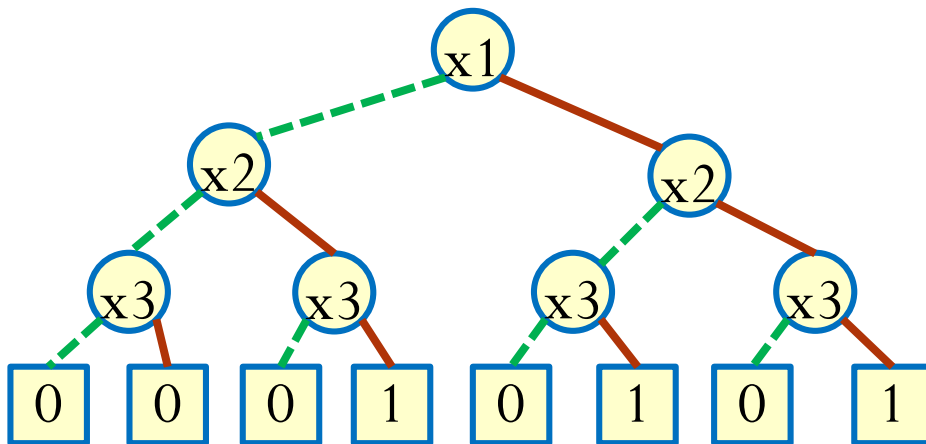
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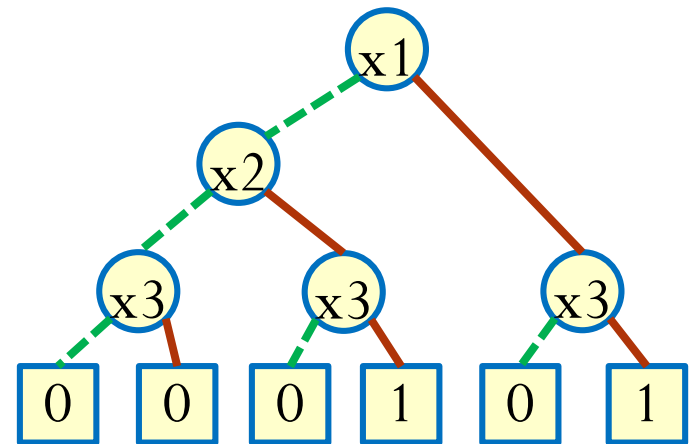
# Binary Decision Diagrams

- OK, now what's wrong with it?
  - Variable ordering simplifies things, but still **too big**, and **not canonical**.

Original Decision Diagram

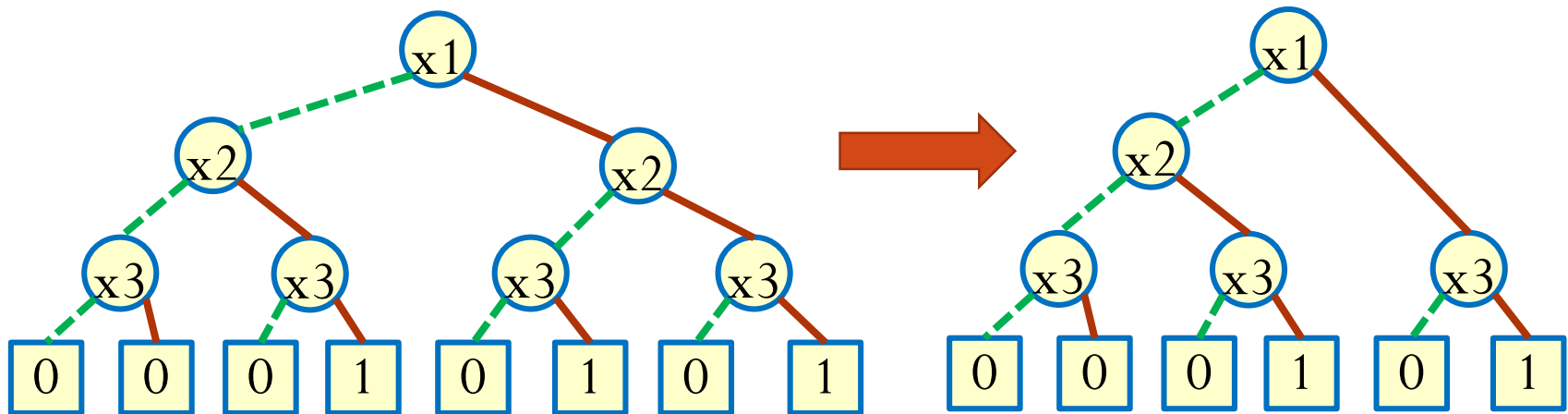


Equivalent, but Different Decision Diagram



# Binary Decision Diagrams

- Big Idea #3: **Reduction**
  - Identify **redundancies** in the graph that can remove unnecessary nodes and edges.
  - Removal of x2 node and its children, replace with x3 node is an example of this.



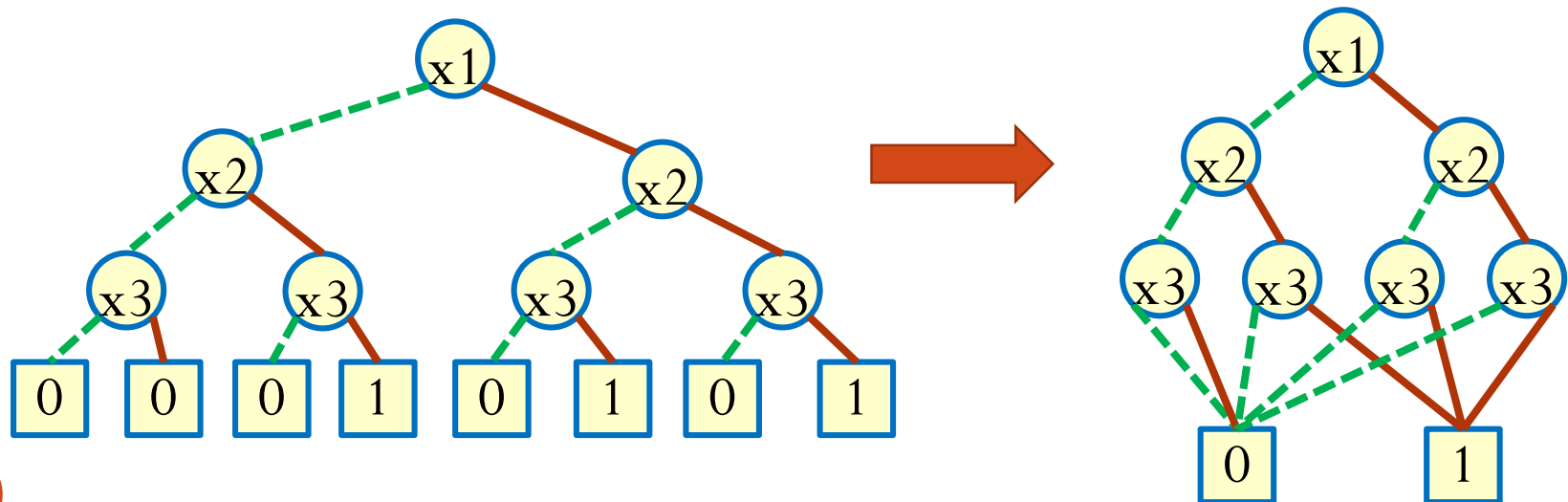
# Binary Decision Diagrams

## Reduction

- Why are we doing this?
  - **Graph size**: Want result as small as possible.
  - **Canonical form**: For **same function**, given **same variable order**, want there to be exactly one graph that represents this function.

# Reduction Rules

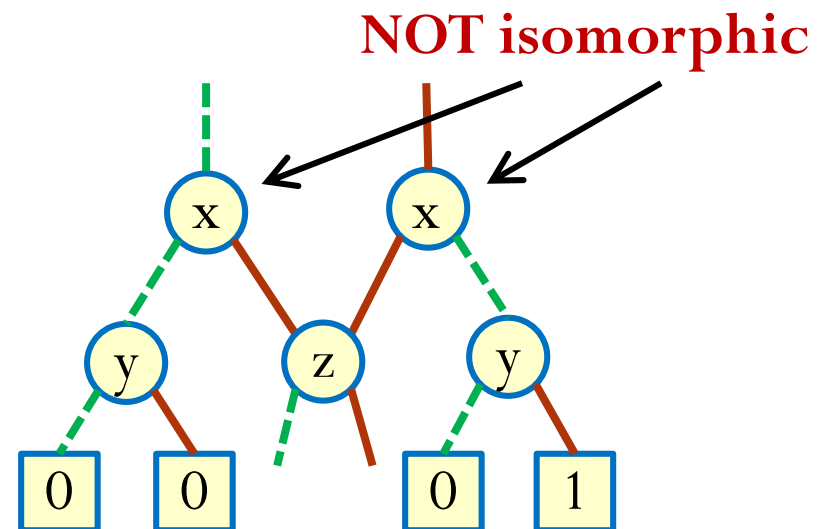
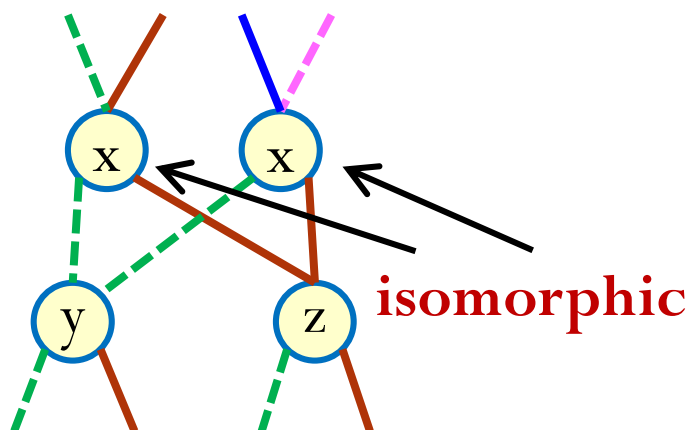
- **Reduction Rule 1: Merge equivalent leaves**
  - Just keep one copy of each **constant leaf** – anything else is totally wasteful.
  - Redirect all edges that went into the redundant leaves into this one kept node.
- Apply Rule 1 to our example...





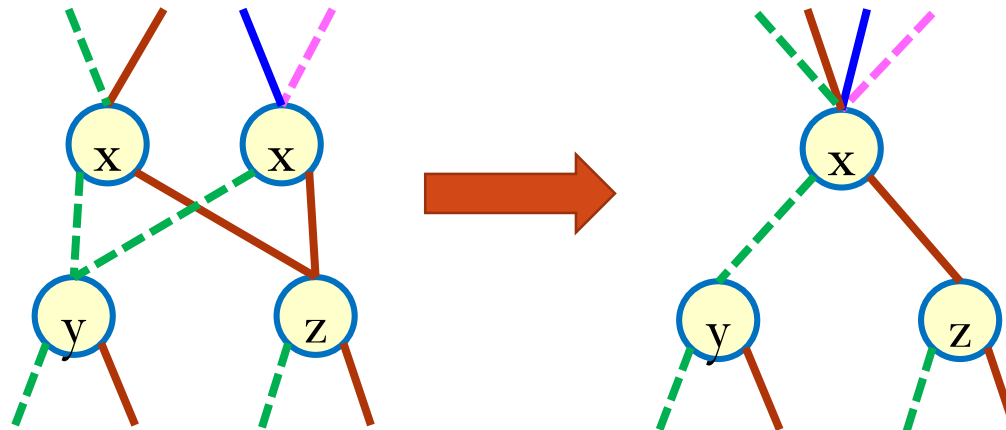
# Reduction Rules

- **Reduction Rule 2: Merge isomorphic nodes**
- Isomorphic = 2 nodes with **same** variable and **identical** children
  - Cannot distinguish these nodes on how they contribute to decisions in graph.
  - Note: means exact same physical child nodes, not just children with same label.



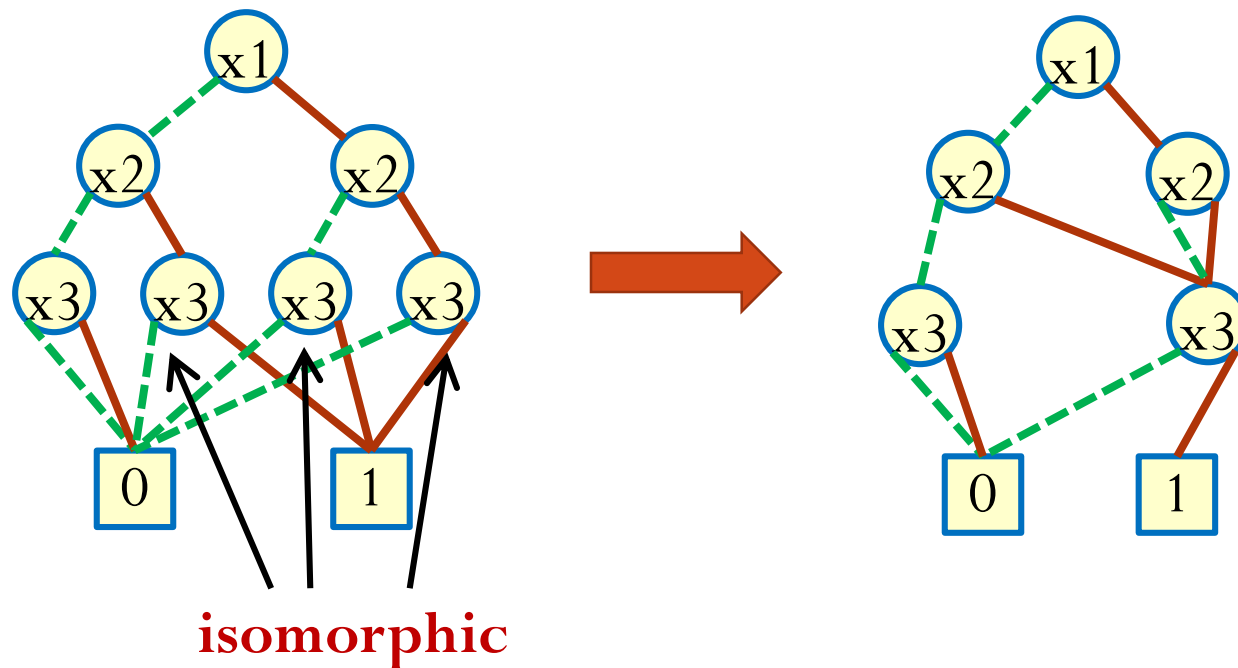
# Steps of Merging Isomorphic Nodes

1. Remove **redundant** node.
  2. Redirect all edges that went into the **redundant** node into the one copy that you kept.
- For the example below, edges into right “x” node now are moved into left.



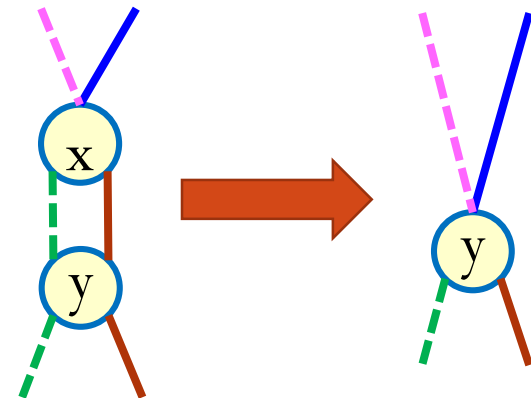
# Reduction Rules

- Apply Rule 2, merging redundant nodes, to our example.



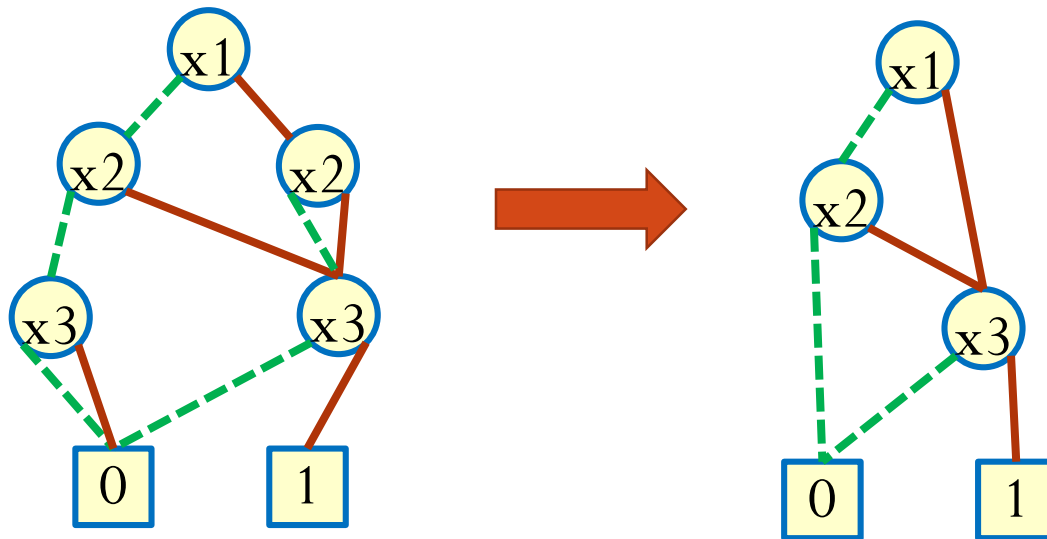
# Reduction Rules

- **Reduction Rule 3: Eliminate Redundant Tests**
- **Redundant test:** both children of a node (x) go to the same node (y)
  - ... so we don't care what value x node takes.
- Steps
  1. Remove redundant node.
  2. Redirect all edges into redundant node (x) into child (y) of the removed node.



# Reduction Rules

- Apply Rule 3, eliminating redundant tests, to our example.



**We are done!**

# Reduction Rules

- The above is a simple example.
  - The reduction process terminates by applying each rule *once*.
- ... But in real case, you may need to **iteratively** apply Rule 2 and 3.
  - It is only done when you cannot find any match of rule 2 or 3.
- Is this how programs really do it?
  - **No!!** We will talk about that later...

# Binary Decision Diagrams (BDDs)

## Big Results

- Recap: What did we do?
  - Start with a decision diagram in the form of a tree, order the variables, and reduce the diagram
  - Name: **Reduced Ordered BDD (ROBDD)**
- Big result: ROBDD is a canonical form data structure for any Boolean function.
  - **Same function** always generates exactly **same graph**... for **same variable ordering**.
  - Two functions identical if and only if ROBDD graphs are isomorphic (i.e., same).
- Nice property: **Simplest** form of graph is **canonical**.

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# BDDs: Representing Simple Things

- NOTE: In an ROBDD, a Boolean function is really just **a pointer to the root node** of the graph.

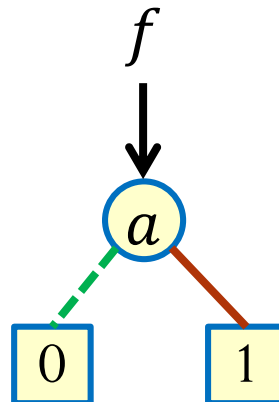
ROBDD for  $f(a, b, \dots, z) = 0$



ROBDD for  $f(a, b, \dots, z) = 1$

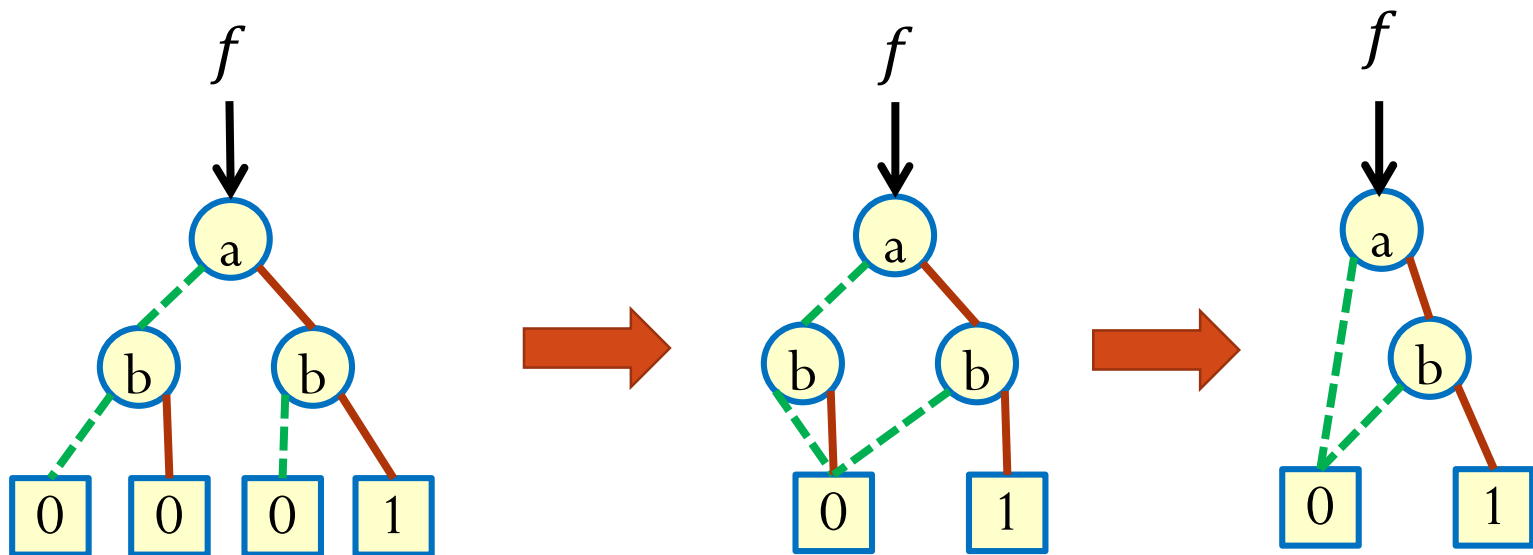


ROBDD for  $f(a, b, \dots, z) = a$



# ROBDD for AND

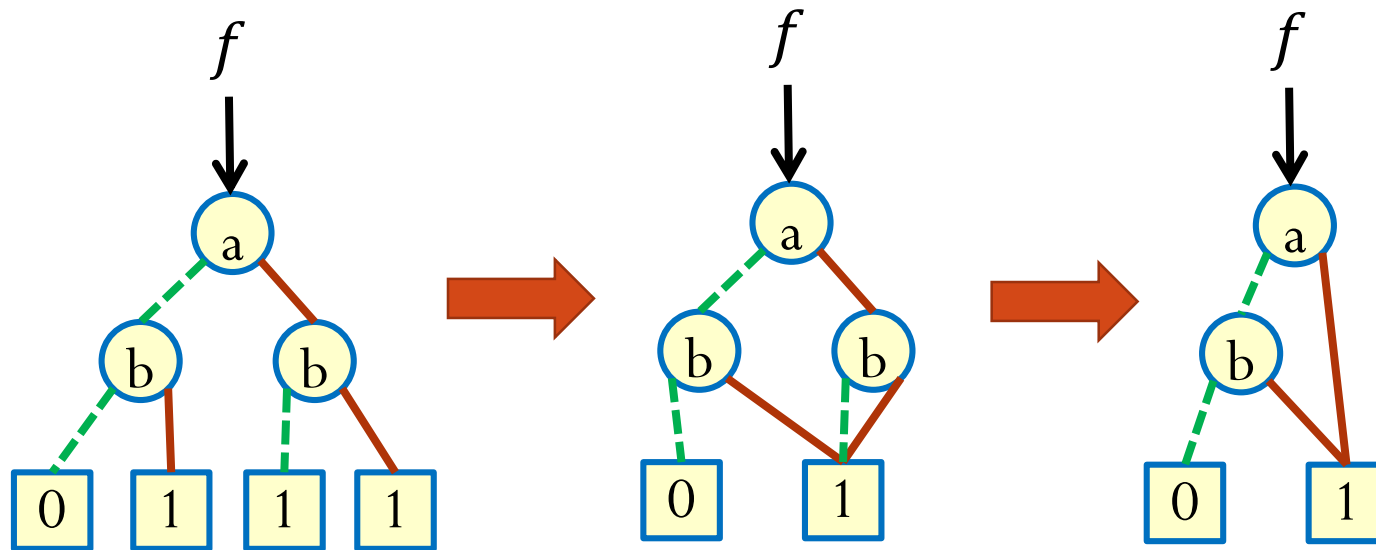
$$f(a, b) = ab$$



Same graph for  $f(a, b, \dots, z) = ab$

# ROBDD for OR

$$f(a, b) = a + b$$

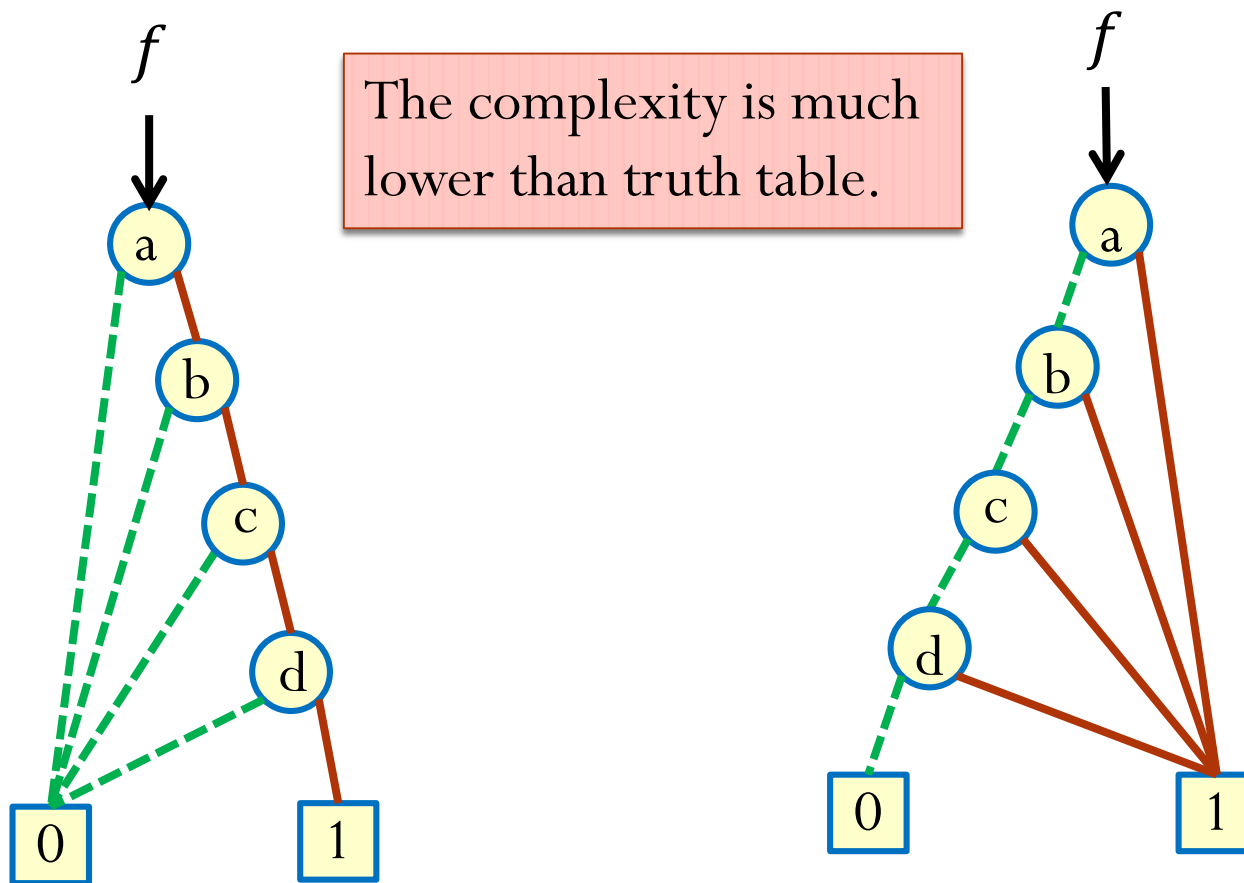


Same graph for  $f(a, b, \dots, z) = a + b$

# ROBDD for AND/OR on Multiple Inputs

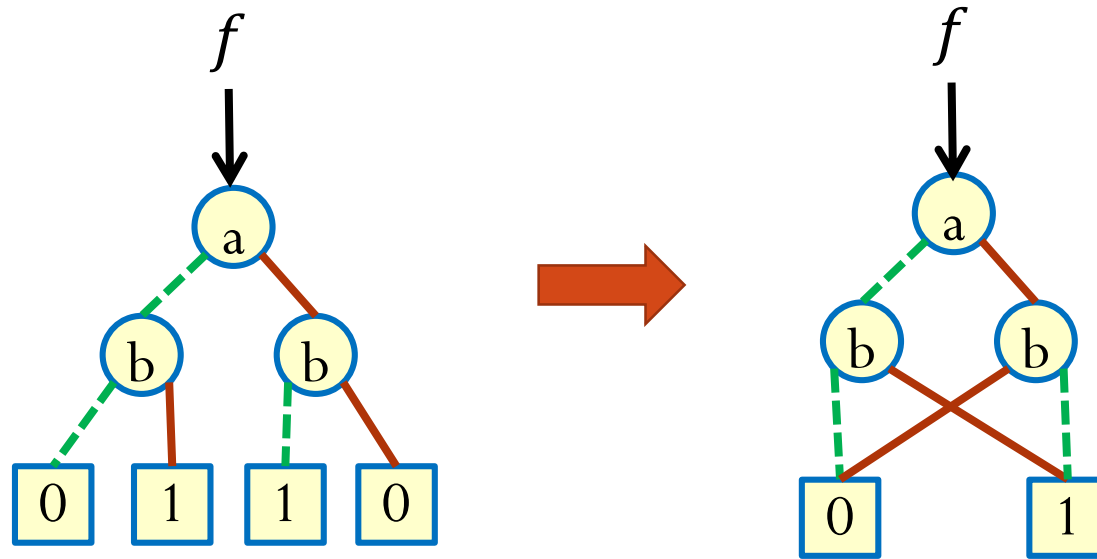
$$f(a, b, c, d) = abcd$$

$$f(a, b, c, d) = a + b + c + d$$



# ROBDD for XOR

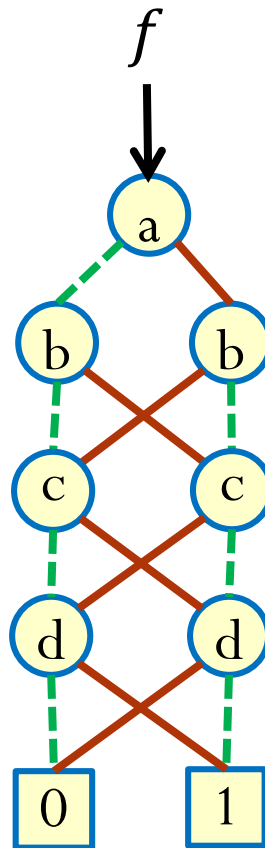
$$f(a, b) = a \oplus b$$



Same graph for  $f(a, b, \dots, z) = a \oplus b$

# ROBDD for XOR on Multiple Inputs

$$f(a, b, c, d) = a \oplus b \oplus c \oplus d$$

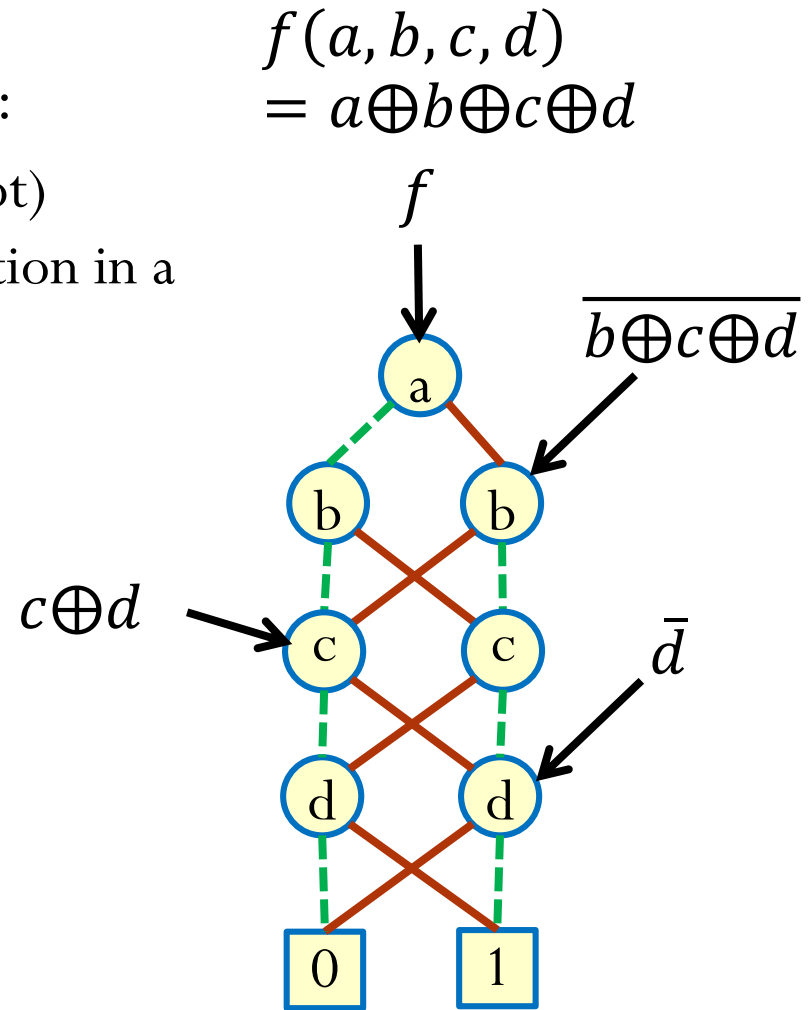


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# Sharing in BDDs

- Very important technical point:
  - **Every** BDD node (not *just* root) represents **some** Boolean function in a **canonical** way.
  - BDD is good at extracting & representing **sharing of subfunctions** in subgraphs.





# BDD Sharing: Multi-Rooted BDD

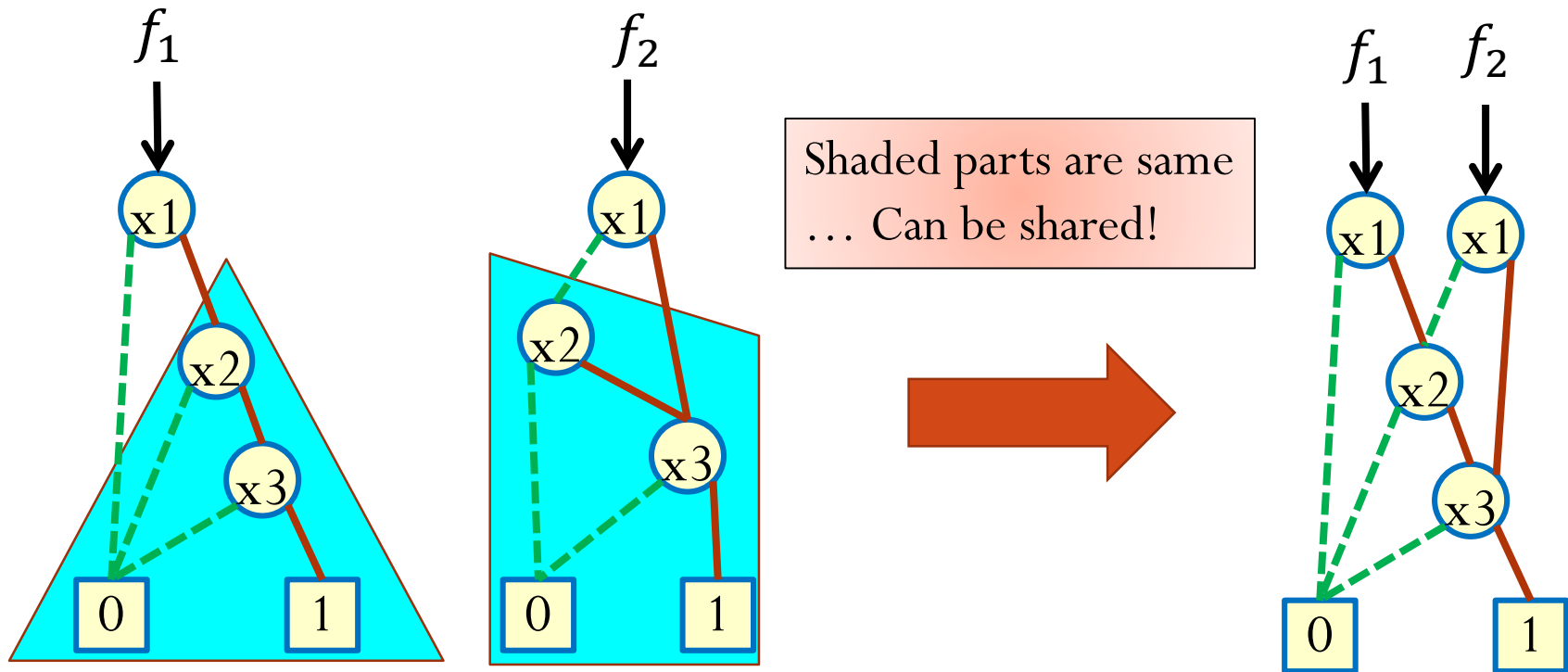
- If we are building BDDs for multiple functions,
  - ...then there may be **same subgraphs** among different BDDs.
  - Don't represent same things multiple times; share them!
- As a result of sharing, the BDD can have multiple “entry points”, or **roots**.
  - Called a **multi-rooted BDD**.

# Multi-Rooted BDD: Example

- Build BDDs for two functions

$$f_1(x_1, x_2, x_3) = x_1 x_2 x_3$$

$$f_2(x_1, x_2, x_3) = (x_1 + x_2)x_3$$



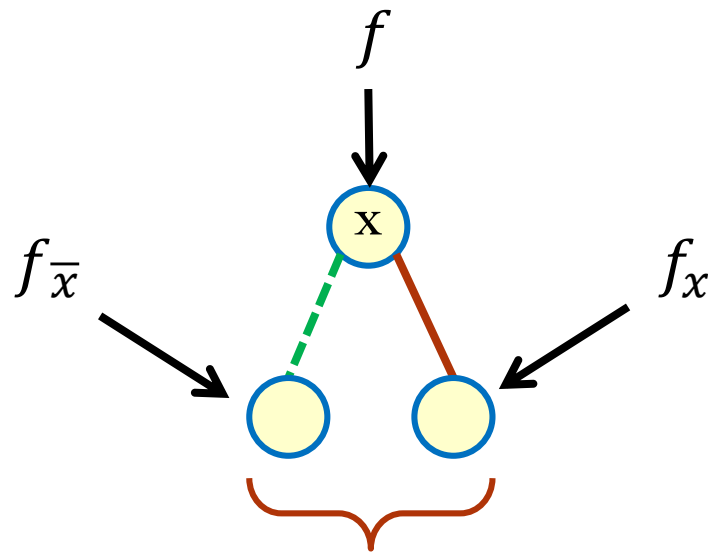
# Multi-Rooted BDD: Example

- Sharing among several separate BDDs reduces the size of BDD!
- Real example: Adders
  - Separately
    - **4-bit** adder: **51** nodes
    - **64-bit** adder: **12,481** nodes
  - Shared
    - **4-bit** adder: **31** nodes
    - **64-bit** adder: **571** nodes

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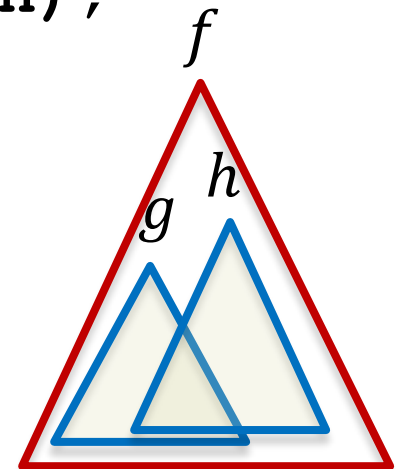
# BDD and Cofactors



What are these two functions?

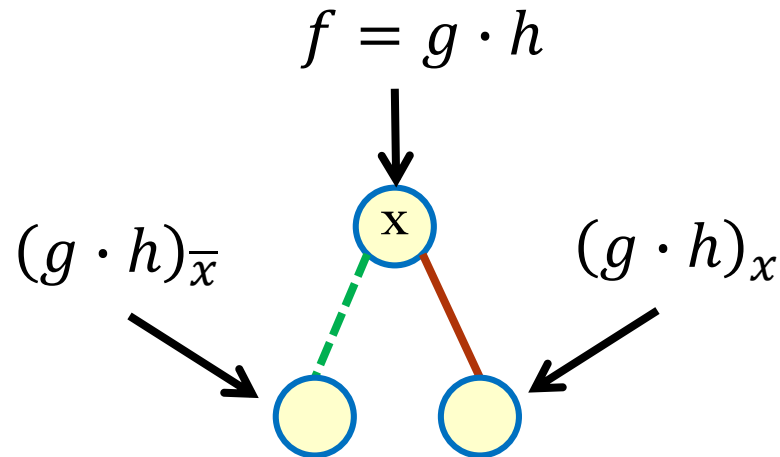
# How Are BDDs Really Implemented?

- Recursively!
  - Cofactor and divide-and-conquer are two keys.
- Note: Boolean function can be decomposed:  $f = op(g, h)$ 
  - $op$  can be either AND, OR, XOR, NOT, ...
- Idea: build ROBDD for  $g$  and ROBDD for  $h$ , then build ROBDD for  $f$  from the previous two ROBDDs.
  - $op$  looks like: **BDD** **op** (**BDD** **g**, **BDD** **h**) ;
  - BDDs for  $g$ ,  $h$ , and  $f$  can share.
  - Start from the base cases: ROBDDs for constants 0 and 1 and a single variable.



# How to Implement OP?

- Example:  $op = \text{AND}$
- BDD and cofactors:



- Therefore, we only need to obtain BDDs for  $(g \cdot h)_{\bar{x}}$  and  $(g \cdot h)_x$ 
  - Property of cofactors:
    - $(g \cdot h)_{\bar{x}} = g_{\bar{x}} \cdot h_{\bar{x}}$
    - $(g \cdot h)_x = g_x \cdot h_x$

Since we are given BDDs for  $g$  and  $h$ , it is easy to get BDDs for  $g_{\bar{x}}$ ,  $g_x$ ,  $h_{\bar{x}}$ , and  $h_x$ . We **recursively** apply  $op$  on  $(g_{\bar{x}}, h_{\bar{x}})$  and  $(g_x, h_x)$  first.

# Algorithm for Implementing OP

```
BDD op(BDD g, BDD h) {  
    if (g is a leaf or h is a leaf) // termination condition:  
        // either g = 0 or 1, or h = 0 or 1  
        return proper BDD;  
    var x = min(root(g), root(h)) // get the lowest order var  
    BDD fLo = op( negCofBDD(g, x), negCofBDD(h, x) );  
    BDD fHi = op( posCofBDD(g, x), posCofBDD(h, x) );  
    return combineBDD(x, fLo, fHi);  
}
```

Note:

$$\begin{aligned} \text{negCofBDD}(g, x) = g_{\bar{x}} &= \begin{cases} g & \text{if } x < \text{root}(g) \\ \text{lo}(g) & \text{if } x = \text{root}(g) \end{cases} \\ \text{posCofBDD}(g, x) = g_x &= \begin{cases} g & \text{if } x < \text{root}(g) \\ \text{hi}(g) & \text{if } x = \text{root}(g) \end{cases} \end{aligned}$$

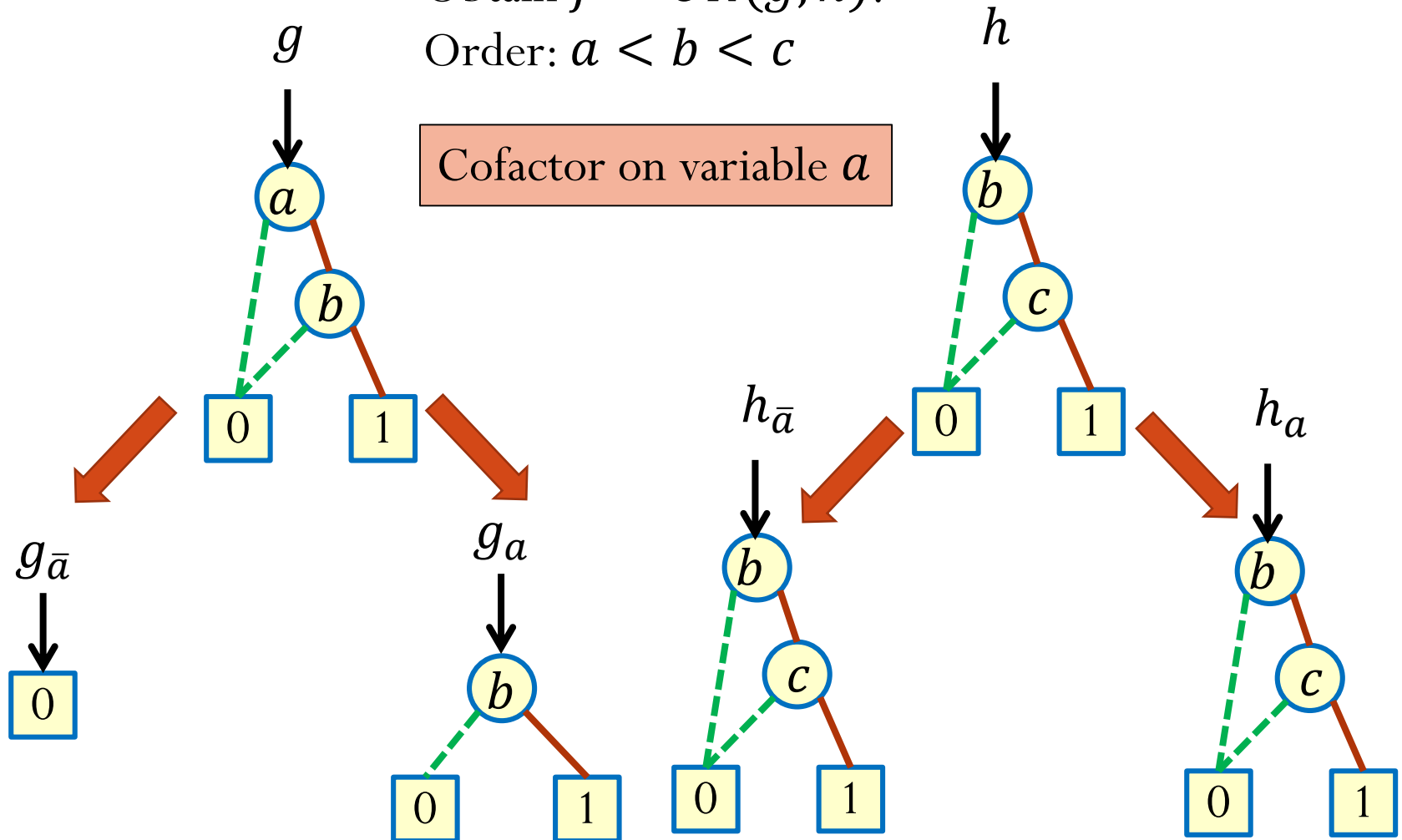


# Example of OP

Obtain  $f = OR(g, h)$ .

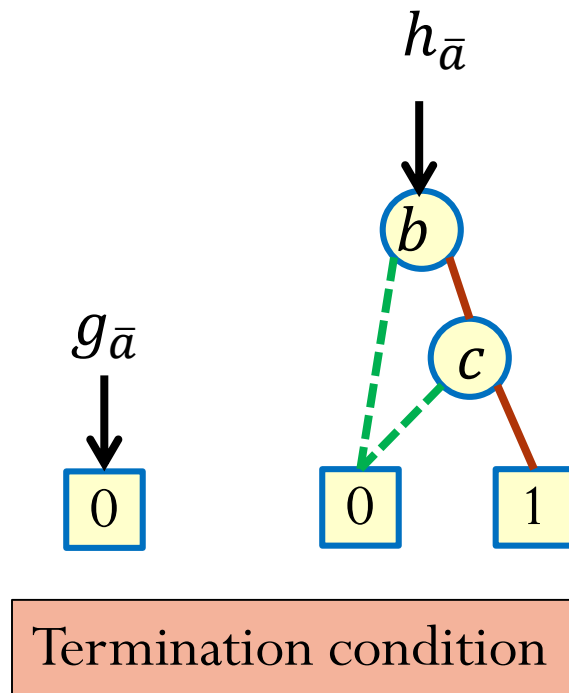
Order:  $a < b < c$

Cofactor on variable  $a$

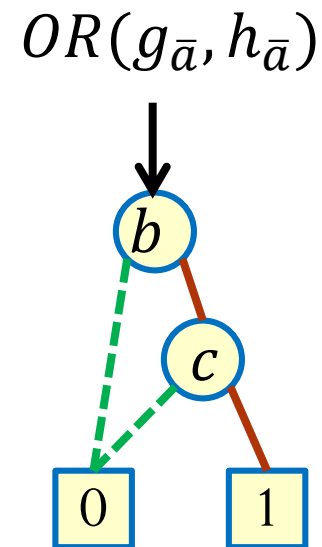


# Example of OP (cont.)

- Recursively compute  $OR(g_{\bar{a}}, h_{\bar{a}})$

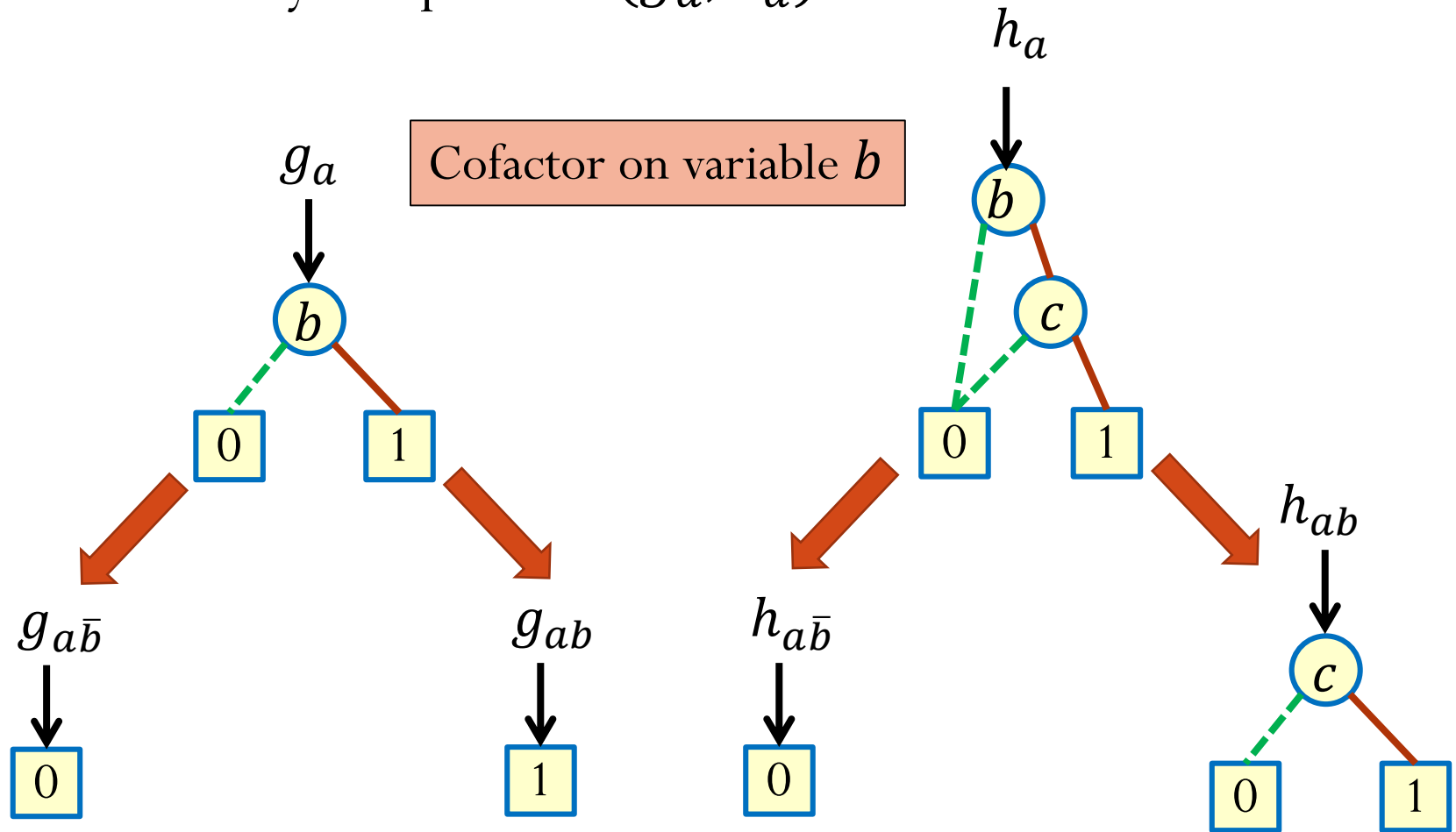


We obtain:



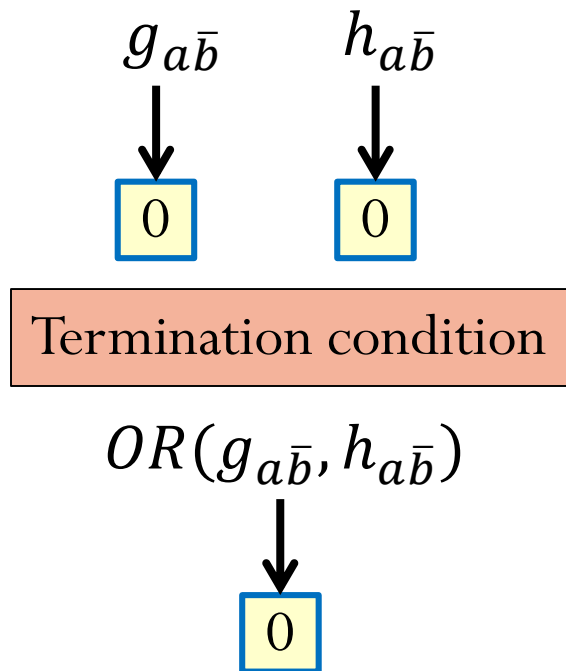
# Example of OP (cont.)

- Recursively compute  $OR(g_a, h_a)$

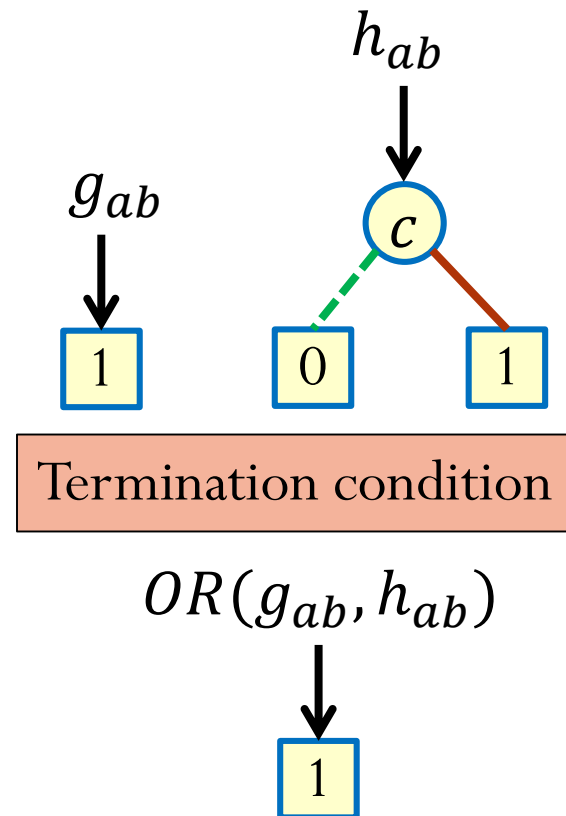


# Example of OP (cont.)

Recursively compute  $OR(g_{a\bar{b}}, h_{a\bar{b}})$

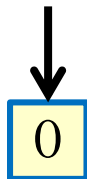


Recursively compute  $OR(g_{ab}, h_{ab})$

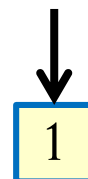


## Example of OP (cont.)

$$OR(g_{a\bar{b}}, h_{a\bar{b}})$$

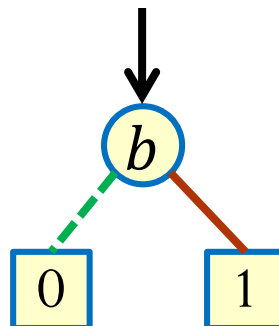


$$OR(g_{ab}, h_{ab})$$



- Based on the recursion results, obtain  $OR(g_a, h_a)$ 
  - Note:** we cofactor on  $b$ .

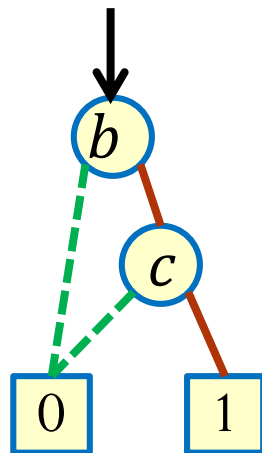
$$OR(g_a, h_a)$$



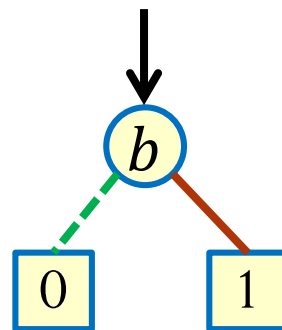
# Example of OP (cont.)

- Based on the recursion results, obtain  $OR(g, h)$ 
  - Note:** we cofactor on  $a$ .

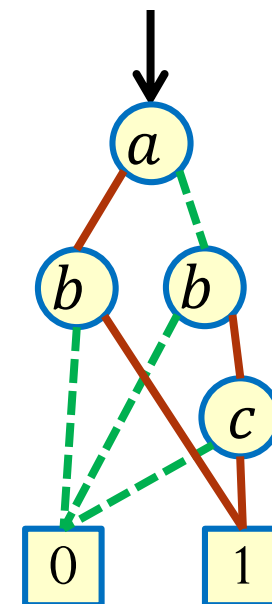
$OR(g_{\bar{a}}, h_{\bar{a}})$



$OR(g_a, h_a)$



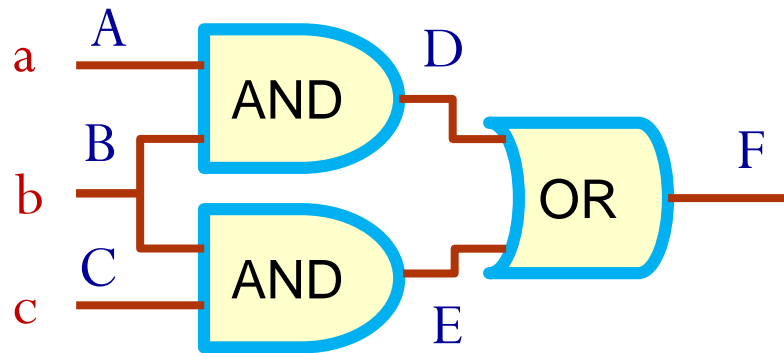
$OR(g, h)$



**Done!**

# BDDs: Build Up Incrementally...

- For a gate-level network, build the BDD for the output incrementally.

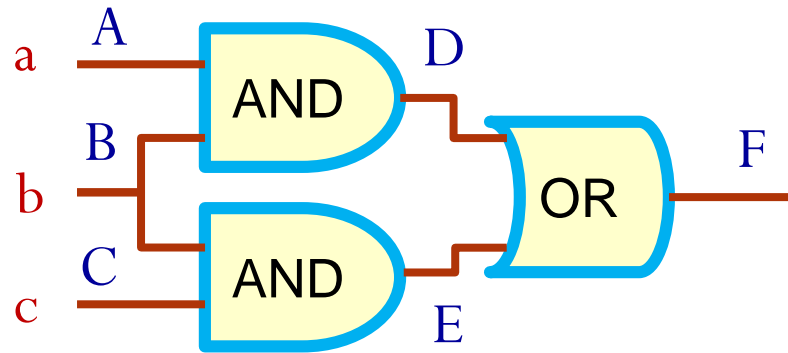


- Each **input** is a BDD. Each **gate** becomes an **operator** *op* that produces a new **output** BDD.
- Build BDD for **F** as a **script** of **calls** to basic BDD operators.
- Stick to a global ordering.

## BDD operator script

1. `A = CreateVar("a")`
2. `B = CreateVar("b")`
3. `C = CreateVar("c")`
4. `D = AND(A, B)`
5. `E = AND(B, C)`
6. `F = OR(D, E)`

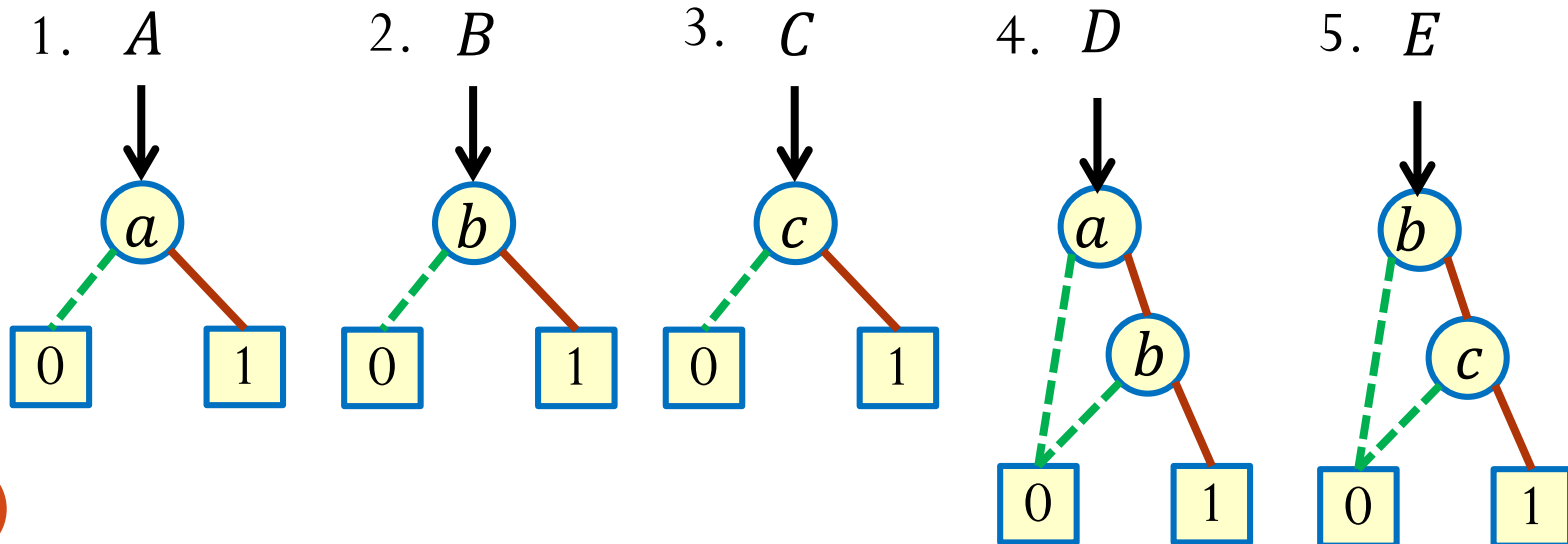
# Example: Build BDD Incrementally



Global ordering:  $a < b < c$

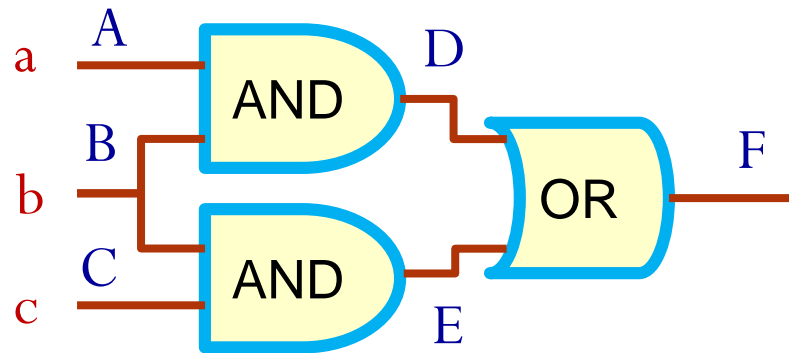
## BDD operator script

1.  $A = \text{CreateVar}("A")$
2.  $B = \text{CreateVar}("B")$
3.  $C = \text{CreateVar}("C")$
4.  $D = \text{AND}(A, B)$
5.  $E = \text{AND}(B, C)$
6.  $F = \text{OR}(D, E)$





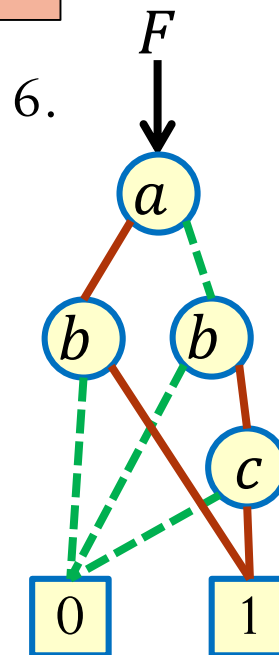
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Global ordering:  $a < b < c$

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4.  $D = \text{AND}(A, B)$
5.  $E = \text{AND}(B, C)$
6.  $F = \text{OR}(D, E)$



# Outline

- Binary Decision Diagram (BDD): Introduction
- BDD Reduction
- BDDs for Common Functions
- Sharing in BDD
- Real Way to Build BDD
- Applications and Issues of BDD

# Application of BDD

## Tautology checking

- Solution:
  - Build BDD for  $f$ .
  - Check if the BDD is just the BDD for  $f = 1$ .



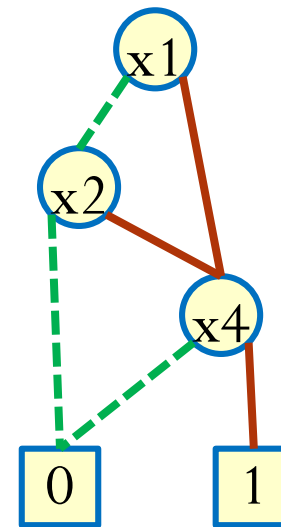
# Application of BDD

## Satisfiability (SAT)

- Satisfiability (SAT): Does there exist an input pattern for variables that lets  $F = 1$ ? If yes, return one pattern.
  - Recall: In network repair problem, we want to find  $(d_0, d_1, d_2, d_3)$  so that  $(\forall ab z)(d_0, d_1, d_2, d_3) = 1$

- Solution:

- If the BDD for  $F$  is not the BDD for  $f = 0$ . Then, SAT answer is yes.
- Otherwise, no.
- If yes, any path from root to “1” leaf is a solution.



SAT? Yes.

SAT pattern?

$$(x_1, x_2, x_3, x_4) \\ = (0, 1, *, 1) \\ (1, *, *, 1)$$

# Application of BDD

## Comparing Logic Implementations

- Are two given Boolean functions  $F$  and  $G$  the same?
- Solution #1:
  - Build BDD for  $F$ . Build BDD for  $G$
  - Compare pointers to roots of  $F$  and  $G$
  - If and only if pointers are **same**,  $F = G$ .
- Solution #2:
  - Build BDD for function  $F \bar{\oplus} G$
  - Check if the BDD is just the BDD for  $f = 1$ .



# Application of BDD

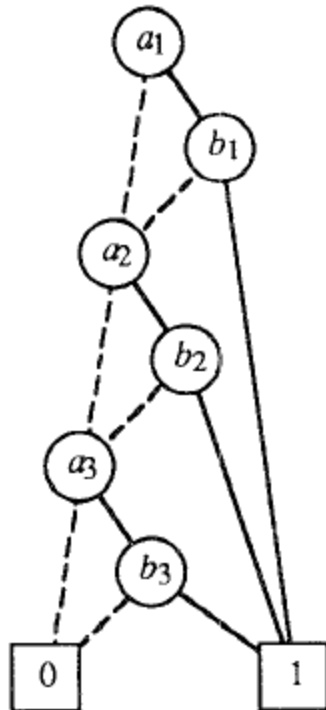
## Comparing Logic Implementations

- What inputs make functions  $F$  and  $G$  give **different answers**?
- Solution:
  - Build BDD for  $H = F \oplus G$ .
  - Ask “**SAT**” question for  $H$ .

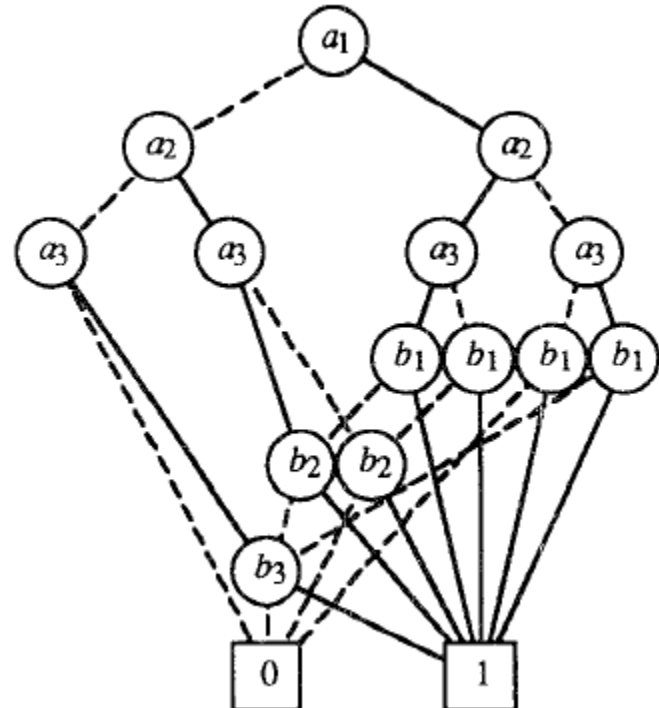
# BDDs: Seem Too Good To Be True?!

- Problem : Variable ordering **matters**.
- Example:  $a1 \cdot b1 + a2 \cdot b2 + a3 \cdot b3$

Good ordering:  $a1 < b1 < a2$   
 $< b2 < a3 < b3$



Bad ordering:  $a1 < a2 < a3$   
 $< b1 < b2 < b3$



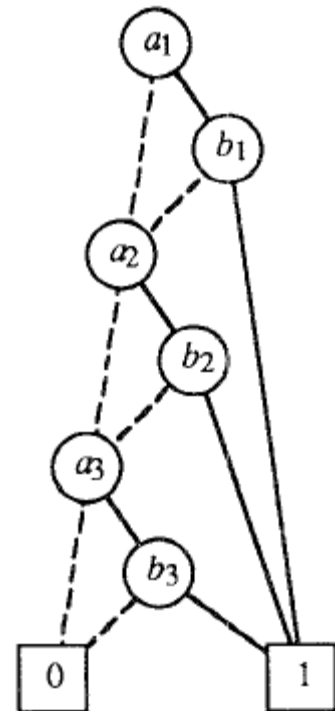
# Variable Ordering: How to Handle?

- **Variable ordering heuristics:** how to order to get smaller BDDs?
- **Characterization:** which problems never make simple BDDs (e.g., multipliers)?
- **Dynamic ordering:** let the BDD program pick the order on the fly.



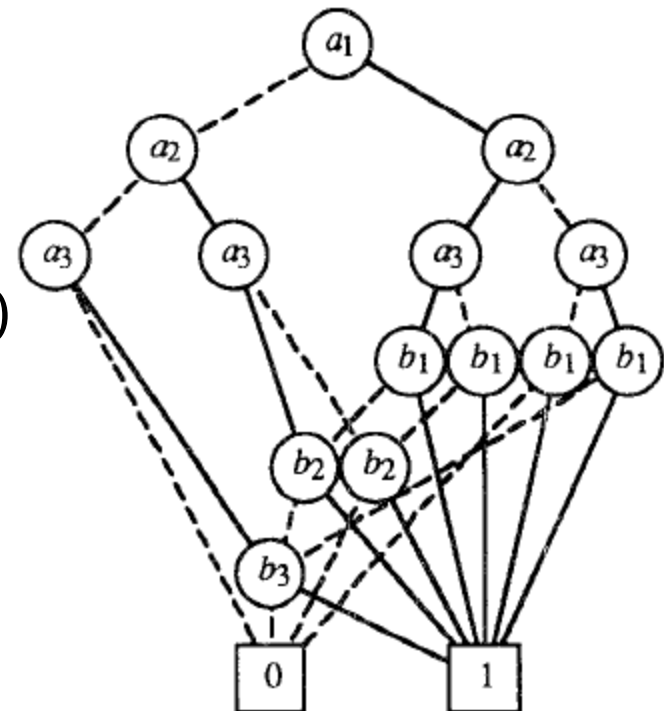
# Variable Ordering: Intuition

- Rules of thumb for BDD ordering
  - **Groups** of inputs that can determine function by themselves should be (i) close together, and (ii) near top of BDD.
- Example:  $a1 \cdot b1 + a2 \cdot b2 + a3 \cdot b3$ 
  - **Good ordering:**  
 $a1 < b1 < a2 < b2 < a3 < b3$
  - Why?
    - $a_i$  and  $b_i$  together can sometimes determine the function value



# Variable Ordering: Intuition

- Rules of thumb for BDD ordering
  - **Groups** of inputs that can determine function by themselves should be (i) close together, and (ii) near top of BDD.
- Example:  $a1 \cdot b1 + a2 \cdot b2 + a3 \cdot b3$ 
  - **Bad ordering:**  
 $a1 < a2 < a3 < b1 < b2 < b3$
  - Why?
    - We need to remember  $(a1, a2, a3)$  before we see any  $b$ 's.



# Variable Ordering: Practice

- Arithmetic circuits are important logic; how are their BDDs?
  - Many **carry chain circuits** have easy **linear sized** ROBDD orderings: Adders, Subtractors, Comparators.
  - Rule is to **alternate** variables in the BDD order:  $a_0, b_0, a_1, b_1, a_2, b_2, \dots, a_n, b_n$ .
- Are all arithmetic circuits easy?
  - No! Multiplication is exponential in number of nodes for any order.
- General experience with BDDs
  - Many tasks have reasonable ROBDD sizes; algorithms are practical to about 100M nodes.

# BDD Summary

- Reduced, Ordered, Binary Decision Diagrams, ROBDDs
  - Canonical form – a data structure – for Boolean functions.
  - Two Boolean functions are the same if and only if they have identical BDD.
  - A Boolean function is just a pointer to the root node of the BDD graph.
  - Every node in a (shared) BDD represents some function.
  - Basis for much of today's general manipulation of Boolean stuff.
- Problems
  - Variable ordering matters; sometimes BDD is just too big.
  - Often, we just want to know **SAT** – don't need to build the whole function.