VE527

Computer-Aided Design of Integrated Circuits

Multi-level Logic Synthesis: Factor Operation

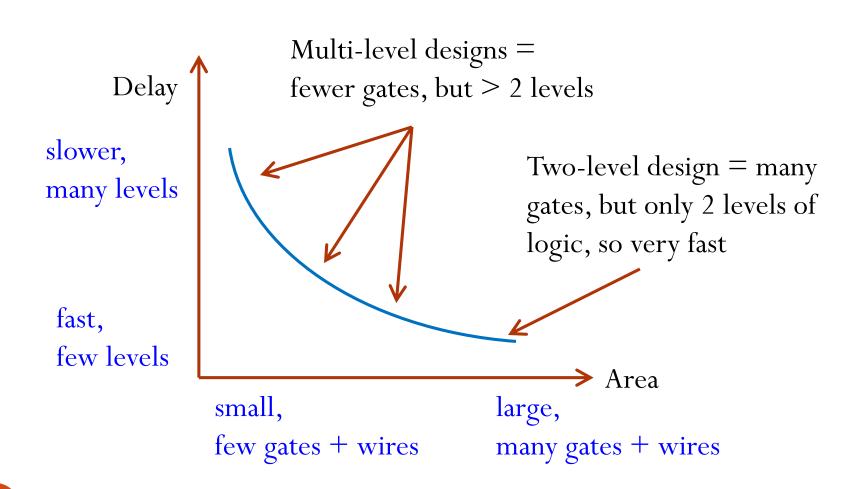
Outline

- Introduction to Multi-Level Logic Synthesis
- Factor operation
 - Algebraic Division
 - Kernels
 - Obtaining Kernels

Why Multi-level Logic?

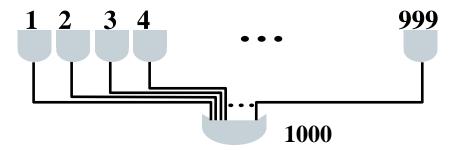
- Two-level forms are too **restrictive**
- It has small delay but large area
 - **Area** = gates + literals (wires), i.e., things that take space on a chip
 - **Delay** = maximum levels of logic gates

Area versus Delay Tradeoff



Why Multi-level Logic?

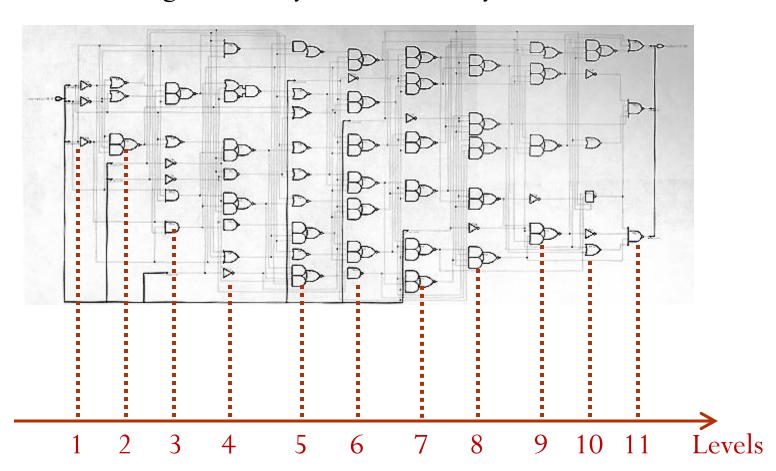
- Rarely see 2-level designs for really big things...
 - We use 2-level logic mostly for **components** of bigger things.
 - Even small things routinely done as **multi-level**.
- What does a 2-level design with 1000 gates look like?



This is just **NOT** going to be the preferred logic network structure...

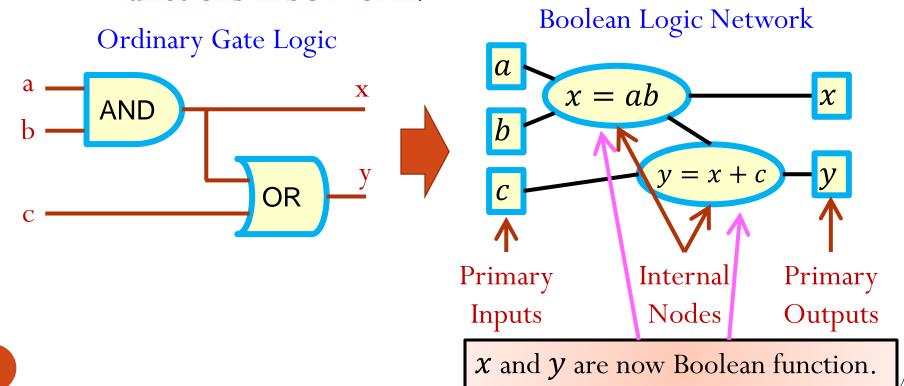
Real Multilevel Example

• A small design, done by commercial synthesis tool.



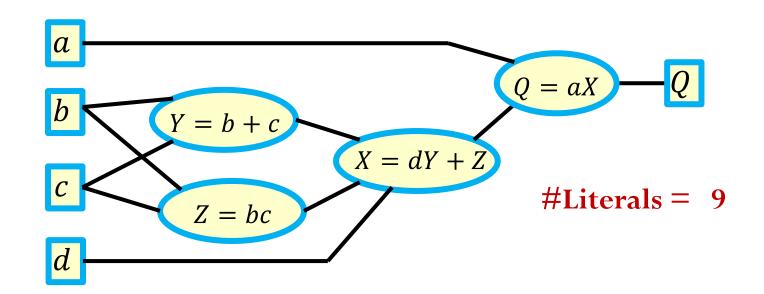
Boolean Logic Network Model

- Need more sophisticated model: **Boolean Logic Network**
 - Idea: it's a **graph** of connected blocks, like any logic diagram, but now individual component blocks is **2-level Boolean functions in SOP form**.



Multilevel Logic: What to Optimize?

- A simplistic but surprisingly useful metric: **Total literal count**
 - Count every appearance of every variable on <u>right hand</u>
 <u>side</u> of "=" in every internal node.
 - Delays also matter, but for our lecture, only focus on area.



Optimizing Multilevel Logic: Big Ideas

- Boolean logic network is a data structure. So, what operators do we need?
- 3 basic kinds of operators:
 - **Simplify** network nodes: **no change** in # of nodes, just simplify insides, which are **SOP form**.
 - Remove network nodes: take "too small" nodes, substitute them back into fanouts.
 - This is not too hard. This is mostly manipulating the graph, simple SOP edits.
 - Add new network nodes: this is **factoring**. Take big nodes, split into smaller nodes.
 - This is a big deal. This is new. This is what we will show you...

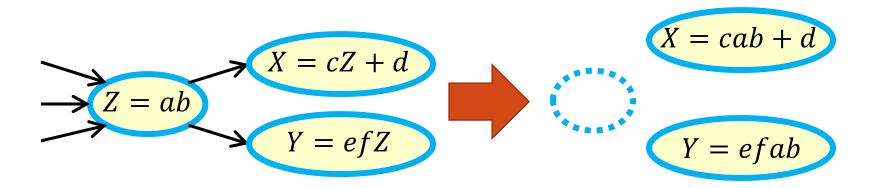
Simplifying a Node

- You already know this! This is **2-level synthesis**.
- Just run ESPRESSO on 2-level form **inside** the node, to reduce # literals.
- As structural changes happen across network, "insides" of nodes may present opportunity to simplify.



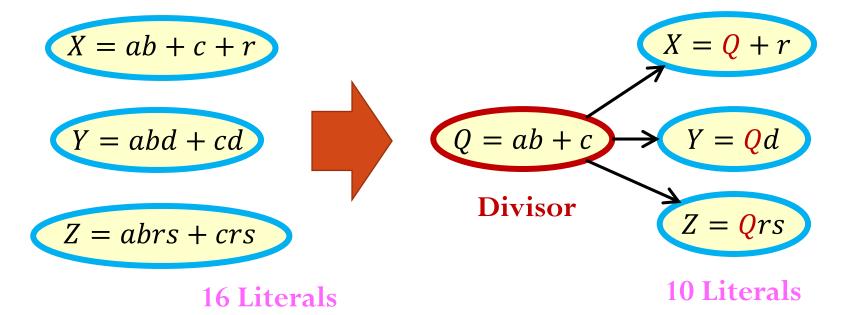
Removing a Node

- Typical case is you have a "small" factor which doesn't seem to be worth making it a separate node.
- "Push" it back into its fanouts, make those nodes bigger, and hope you can use 2-level simplification on them.



Adding new Nodes

- This is Factoring, this is new, and hard.
 - Look at existing nodes, identify **common divisors**, extract them, connect as **fanins**.
 - Tradeoff: **more** delay (another level of logic), but **fewer literals** (less gate area).



Multilevel Synthesis Scripts

- Multilevel synthesis like 2-level synthesis is **heuristic**.
- ...but it's also more complex. Write scripts of basic operators.
 - Do several passes of different optimizations over the Boolean logic network.
 - Do some "cleanup" steps to get rid of "too small" nodes (**remove** nodes).
 - Look for "easy" **factors**: just look at existing nodes, and try to use them.
 - Look for "hard" factors: do some work to extract them, try them, and keep the good ones.
 - Do 2-level optimization of insides of each logic node in network (simplify nodes by ESPRESSO).
 - Lots of "art" in the engineering of these scripts.
- For us, the one big thing you don't know: **How to factor**...

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Another New Model: Algebraic Model

- Factoring: How do we really do it?
 - Develop another model for Boolean functions, cleverly designed to let us do this
 - Tradeoff: lose some "expressivity" some aspects of Boolean behavior and some Boolean optimizations we just **cannot do**, but we **gain practical factoring**.
- New model: Algebraic model
 - Term "algebraic" comes from **pretending** that Boolean expressions behave like **polynomials of real numbers**, not like Boolean algebra.
 - Big new Boolean operator: Algebraic Division (also known as "Weak" Division).

Algebraic Model

• Idea: keep just those **rules** that work for **BOTH** polynomials of reals **AND** Boolean algebra, but **get rid of** the rest.

Real numbers

$$a \cdot b = b \cdot a \quad a + b = b + a$$

$$a \cdot (b \cdot c) = (a \cdot b) \cdot c$$

$$a + (b + c) = (a + b) + c$$

$$a \cdot (b + c) = a \cdot b + a \cdot c$$

$$a \cdot 1 = a \quad a \cdot 0 = 0$$

$$a + 0 = a$$







Boolean algebra

$$a \cdot b = b \cdot a \quad a + b = b + a$$

$$a \cdot (b \cdot c) = (a \cdot b) \cdot c$$

$$a + (b + c) = (a + b) + c$$

$$a \cdot (b + c) = a \cdot b + a \cdot c$$

$$a \cdot 1 = a \quad a \cdot 0 = 0$$

$$a + 0 = a$$

$$a \cdot \overline{a} = 0 \quad a + \overline{a} = 1$$

$$a \cdot a = a \quad a + a = a$$

$$a + 1 = 1$$

$$(a + b)(a + c) = a + b \cdot c$$

Algebraic Model

- If we only get to use algebra rules from real numbers...
 - <u>Consequence</u>: A variable and its complement must be treated as **totally unrelated**.
 - Since no expression like $a + \bar{a} = 1$ allowed.

$$F = ab + \bar{a}x + \bar{b}y$$

$$Let R = \bar{a}, S = \bar{b}$$

$$F = ab + Rx + Sy$$

• <u>Aside</u>: this is one of the losses of "expressive power" of Boolean algebra.

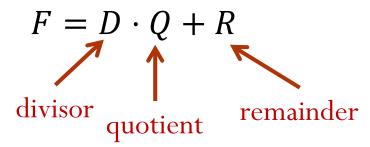
Algebraic Model: Representation

Boolean functions manipulated in SOP form like polynomials.

- Each product term in such an expression is just **a set of** variables, e.g., abRy is the set (a, b, R, y).
- SOP expression itself is just a **list of these products** (cubes), e.g., ab + Rx is the list ((a, b), (R, x)).

Algebraic Division: Our Model for Factoring

• Given function F, we want to factor it as:



• If remainder R = 0, we call the divisor as a "factor".

Example:
$$F = ac + ad + bc + bd + e$$

$$= (a + b)(c + d) + e$$

$$\uparrow \qquad \uparrow \qquad \uparrow$$
divisor quotient remainder

Algebraic Division

• Example: F = ac + ad + bc + bd + e

• Want: $F = D \cdot Q + R$.

Divisor is a **factor** if R = 0.

Divisor (D)	Quotient ($oldsymbol{Q}$)	Remainder (R)	Is D Factor?
$ac + ad + bc \\ +bd + e$	1	0	Yes
a + b	c+d	e	No
c+d	a + b	e	No
а	c+d	bc + bd + e	No
b	c+d	ac + ad + e	No
С	a+b	ad + bd + e	No
d	a+b	ac + bc + e	No
e	1	ac + ad + bc + bd	No

Algebraic Division: Very Nice Algorithm

• Inputs: A Boolean expression F and a divisor D, represented as lists of cubes (and each cube as a set of literals).

Output

- Quotient Q = F/D as a cube list, or **empty** if Q = 0.
- Remainder R as a cube list, or **empty** if D was a **factor**.

• <u>Strategy</u>

- ullet Cube-wise walk through cubes in divisor D, trying to divide each of them into F.
- ... intersect all the division results.

Algebraic Division Algorithm

```
Example:
AlgebraicDivision(F, D) { // divide D into F
                                                       Cube xyzw contains
                                                       product term yz
  for (each cube d in divisor D) {
    let C = \{ \text{ cubes in } F \text{ that contain this product term } d \};
    if (C is empty) return (quotient = 0, remainder = F);
    let C = cross out literals of cube d in each cube of C;
    if (d is the first cube we have looked at in divisor D) let Q = C;
     else Q = Q \cap C;
                                            Example:
                                            Suppose C = xyz + yzw + pqyz
  R = F - (Q \cdot D);
                                            and d = yz. Then crossing
  return (quotient = Q, remainder = R);
                                            out all the yz parts yields
                                            x + w + pq
```

Algebraic Division: Example

F = axc + axd + axe + bc + bd + de, D = ax + b

F cube	D cube: ax	D cube: b
axc	$axc \rightarrow c$	_
axd	$axd \rightarrow d$	
axe	$axe \rightarrow e$	
bc	_	$bc \rightarrow c$
bd	_	$bd \rightarrow d$
de		

$$C = c + d + e \qquad C = c + d$$

$$Q = (c + d + e) \cap (c + d) = c + d$$

$$R = F - QD = axe + de$$

Algebraic Division: Warning

- Remember: No "Boolean" simplification, only "algebraic".
 - So what? Well, suppose you have this

$$F = a\bar{b}\bar{c} + ab + ac + bc, D = ab + \bar{c}$$
 and you want F/D .

• You must let $X = \overline{b}$ and $Y = \overline{c}$ and transform F and D to something like

$$F = aXY + ab + ac + bc, D = ab + Y$$

• Because we must treat the true and complement forms of variables as **totally unrelated**.

One More Constraint: Redundant Cubes

- To do F/D, function F must have no **redundant** cubes
 - Technical definition is: **minimal** with respect to **single-cube containment**.
 - <u>Means</u>: no one cube is <u>completely</u> covered by <u>one of the</u> <u>other</u> cubes in SOP cover.
 - ullet E.g., abcd is completely covered by ab.
- Why <u>no</u> redundant cubes?
 - Consider: F = a + ab + bc and D = a.
 - Note: F has redundant cube ab.
 - What is F/D by our algebraic division algorithm?

$$Q = F/D = 1 + b$$

However, we don't have 1+stuff operation in algebraic model!

One More Constraint: Redundant Cubes

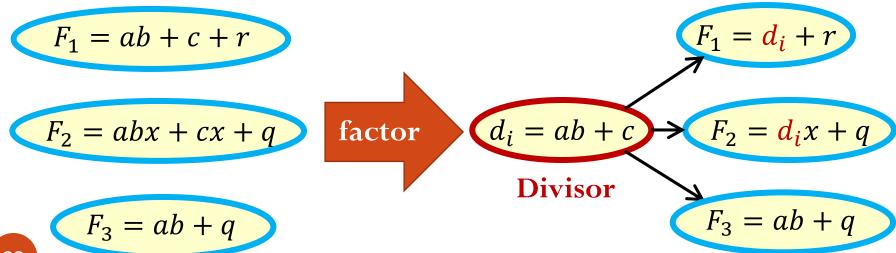
- ... So, we should remove redundant cubes to make the SOP minimal with respect to single-cube containment.
 - Not hard.

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Multilevel Logic Synthesis: Where are We?

- For Boolean function F and D, can compute $F = Q \cdot D + R$ via algebraic model.
 - It is great, but still $\underline{not\ enough}$: don't know how to \underline{find} a good divisor D.
 - Another problem: given n functions $F_1, F_2, ..., F_n$, find a set of good common divisors.

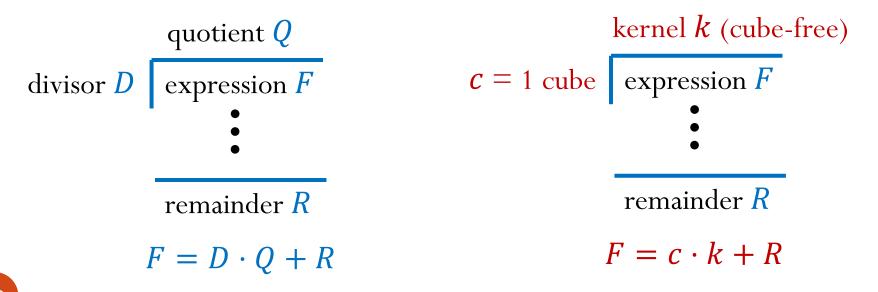


Where To Look For Good Divisors?

- Surprisingly, the **algebraic model** has a beautiful answer.
- Where to look for divisors of function F?
 - In the set of **kernels** of F, denoted K(F).
 - K(F) is another set of 2-level SOP forms which are the special, foundational structure of any function F
- How to find a kernel $k \in K(F)$?
 - Algebraically divide F by one of its co-kernels, c.

Kernels and Co-Kernels of Function F

- **Kernel** of a Boolean expression *F* is:
 - A cube-free quotient k obtained by algebraically dividing F by a single cube C.
 - This single cube *c* also has a name: it is a **co-kernel** of function *F*.



Kernels Are Cube-Free...

- Cube-free means...?
 - You cannot factor out a <u>single</u> cube divisor that <u>leaves no</u> remainder.
 - Technically: has no **one cube** that is a **factor** of expression.
 - Pick a cube C. If you can "cross out" C in <u>each</u> product term of F, then F is **not** a **kernel**.
 - Note: cubes "1" and "a" are **NOT** cube-free

Expression F	$F = D \cdot Q + R$	F Cube-free?
а	$a \cdot 1 + 0$	No
a+b		Yes
ab + ac	$a \cdot (b+c) + 0$	No
abc + abd	$ab \cdot (c+d) + 0$	No
ab + acd + bd		Yes

Some Kernel Examples

• Suppose F = abc + abd + bcd

Divisor cube d	Q = F/d	Is Q a kernel of F ?
1	abc + abd + bcd	No, has cube $= b$ as factor
a	bc + bd	No, has cube $= b$ as factor
b	ac + ad + cd	Yes! co-kernel = b
ab	c+d	Yes! co-kernel = ab

- ullet Any Boolean function F can have many different kernels.
 - The <u>set</u> of kernels of F is denoted as K(F).

Kernels: Why Are They Important?

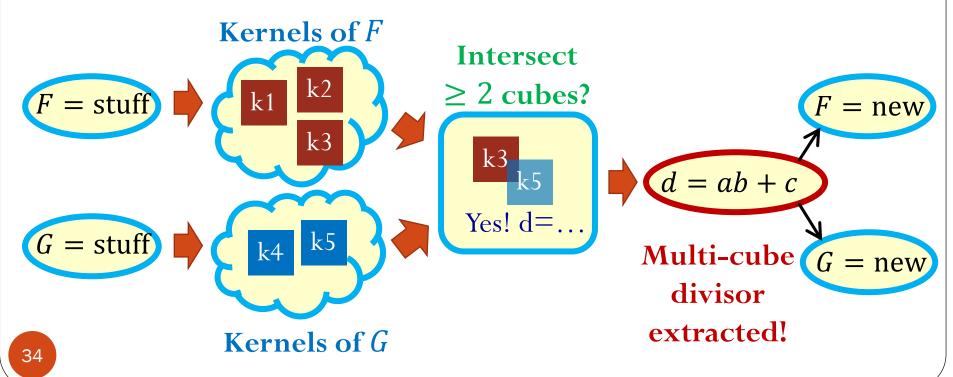
- Big result: Brayton & McMullen Theorem
 - <u>From</u>: R. Brayton and C. McMullen, "The decomposition and factorization of Boolean expressions." In *IEEE International Symposium on Circuits and Systems*, pages 49–54, 1982.

Expressions F and G have a common multiple-cube divisor d if and only if:

there are kernels $k1 \in K(F)$ and $k2 \in K(G)$ such that $d = k1 \cap k2$ and d is an expression with **at least 2** cubes in it (i.e., k1 and k2 have **common cubes**).

Multiple-Cube Divisors and Kernels

- Brayton & McMullen Theorem <u>in words</u>:
 - The <u>only</u> place to look for <u>multiple-cube divisors</u> is in the intersection of kernels!
 - Indeed, this intersection of kernels contains <u>all</u> divisors.



Brayton-McMullen: Informal Illustration

```
F = \text{cube} 1 \cdot \text{kernel} 1 + \text{remainder} 1
                                                                Assume:
                                                                kernel1 \cap kernel2 = X + Y
G = \text{cube} ? \bullet \text{kernel} 2 + \text{remainder} ?
F = \text{cube } 1 \cdot [X + Y + \text{stuff } 1] + \text{remainder } 1
G = \text{cube 2} \cdot [X + Y + \text{stuff2}] + \text{remainder 2}
 F = \text{cube} 1 \cdot [X + Y] + [\text{cube} 1 \cdot \text{stuff} 1 + \text{remainder} 1]
G = \text{cube } 2 \cdot [X + Y] + [\text{cube } 2 \cdot \text{stuff } 2 + \text{remainder } 2]
                                                                  F = \text{cube} 1 \cdot \mathbf{d} + \dots
                               d = X + Y
```

 $G = \text{cube } 2 \cdot \mathbf{d} + \dots$

Kernels: Real Example

$$F = ae + be + cde + ab$$

$$F = ae + be + cde + ab$$
 $G = ad + ae + bd + be + bc$

Kernels	Co-kernel
a+b+cd	e
b + e	а
a + e	b
ae + be + cde + ab	1

Kernels	Co-kernel
a+b	d or e
d + e	а
c + d + e	b
ab + ae + bd + be + bc	1

Intersecting these 2 kernels: $(a + b + cd) \cap (a + b) = a + b$

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Kernels: Very Useful, But How To Find?

- Another **recursive** algorithm ("recursive" again!)
 - There are 2 more useful properties of kernels we need to see first...
- Start with a function F and a kernel k1 in K(F)

$$F = \text{cube} 1 \cdot \text{k} 1 + \text{remainder} 1$$

- Then: a new, interesting question: what about K(k1)?
 - *k*1 is a perfectly nice Boolean expression, so it has got **its own** kernels.
 - Do these k1's kernels have anything interesting to say about K(F)?

How K(k1) Relates to K(F)...

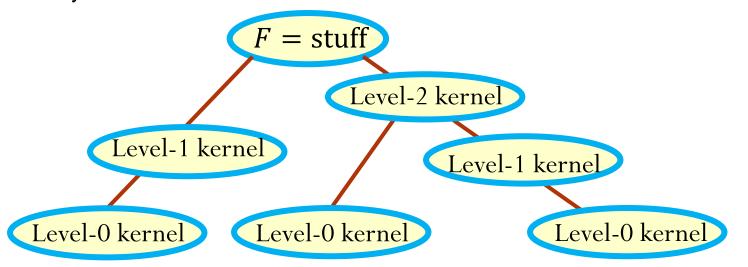
- We know this: $F = \text{cube} 1 \cdot \text{k} 1 + \text{remainder} 1$
- Suppose k2 is a kernel in K(k1), then we know

```
k1 = \text{cube} 2 \cdot k2 + \text{remainder} 2
```

- Substitute this expression for k1 in original expression for F
 F = cube1•[cube2•k2 + remainder2] + remainder1
- Since cube1•cube2 is itself just another **single cube**, we have: $F = (\text{cube1•cube2}) \cdot [k2] + [\text{cube1•remainder2} + \text{remainder1}]$
- <u>Conclusion</u>: k2 is also a kernel of original F (with co-kernel cube1•cube2)

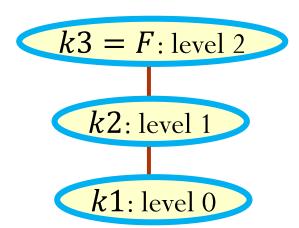
There is a Hierarchy of Kernels Inside F

- **Definition**: $k \in K(F)$ is
 - A **level-0 kernel** if it contains no kernels inside it except itself.
 - In words: Only cube you can pull out to get a cube-free quotient is "1".
 - A **level-n kernel** if it contains **at least one** level-(n-1) kernel, and no other level-n kernels except itself.
 - In words: a level-1 kernel only has level-0 kernels inside it. A level-2 kernel only has level-1 and level-0 kernels in it, etc...



Kernel Hierarchy: Example

- F = abe + ace + de + gh has three kernels:
 - k1 = b + c, with co-kernel ae.
 - k2 = ab + ac + d, with co-kernel e.
 - k3 = F with co-kernel 1.
- Note: k1 is level 0, k2 is level 1, and k3 is level 2.



Kernels

- Second useful result [by Brayton et al.]:
 - Co-kernels of a Boolean expression in SOP form correspond to intersections of 2 or more cubes in this SOP form.
- <u>Note</u>: <u>Intersections</u> here means that we regard a cube as a set of literals, and look at common subsets of literals.
 - This is not like "AND" for products. This just extracts **common** literals.
 - Example: ace + bce + de + g $ace \cap bce = ce \longrightarrow ce \text{ is a potential co-kernel}$ $ace \cap bce \cap de = e \longrightarrow e \text{ is a potential co-kernel}$

How to Find Kernels Using These 2 Results?

- Find the kernels **recursively**.
 - Whenever find one kernel, call **FindKernels()** on that kernel, to find (if any) lower level kernels inside.
- Use **algebraic division** to divide function by potential co-kernels, to drive recursion.
 - Use 2nd result co-kernels are **intersections** of the cubes: If there're at least 2 cubes, then look at the intersection of those cubes, and use that intersected result as our potential co-kernel cube.
- One technical point: need to start with a **cube-free function** F to make things work right.
 - If not cube-free, just divide by biggest common cube to simplify F.

Kernel Algorithm

```
FindKernels( cube-free SOP expression F ) {
 K = empty;
 for (each variable x in F) {
    if (there are at least 2 cubes in F that have variable x) {
      let S = \{ \text{ cubes in } \mathbf{F} \text{ that have variable } \mathbf{x} \text{ in them } \};
      let co = cube that results from intersection of all cubes in S,
                  this will be the product of those literals
                  that appear in each of these cubes in S;
      K = K \cup FindKernels(F/co);
 K = K \cup F;
                         Cube-free F is always its own
 return(K);
                         kernel, with trivial co-kernel = 1
```

Kernelling Example

```
FindKernels( F ):
for (each var x in F ) {
    if (x in ≥ 2 cubes in F) {
        co = intersection of cubes;
        K=K∪FindKernels(F/co);
    }
}
K = K ∪ F;
return( K );
```

```
F = ace + bce + de + g
```

- a: only 1 cube with a, no work.
- b: only 1 cube with b, no work.
- c: two cubes ace and bce with c.
 - $co = ace \cap bce = ce$
 - \bullet F/co = a + b
 - Recurse on a + b
- d: only 1 cube with d, no work.
- e: three cubes ace, bce, and de with e.
 - $co = ace \cap bce \cap de = e$
 - F/co = ac + bc + d
 - Recurse on ac + bc + d
- g: only 1 cube with g, no work.

Kernelling Example (cont.)

- Recurse on a + b
 - No work for variables a and b, since one cube with a/b.
- Recurse on ac + bc + d
 - No work for variables a, b, d, since one cube with a/b/d.
 - c: two cubes ac and bc with c.
 - $co = ac \cap bc = c$
 - \bullet F/co = a + b
 - Recurse on a + b (the same as above)

Kernelling Example (cont.)

$$F = ace + bce + de + g$$

b

no work no work no work co = ce; recurse on F/co = a + b

> \boldsymbol{a} no work no work

F/co = ac + bc + d

co = e; recurse on

no work no work

no work

no work

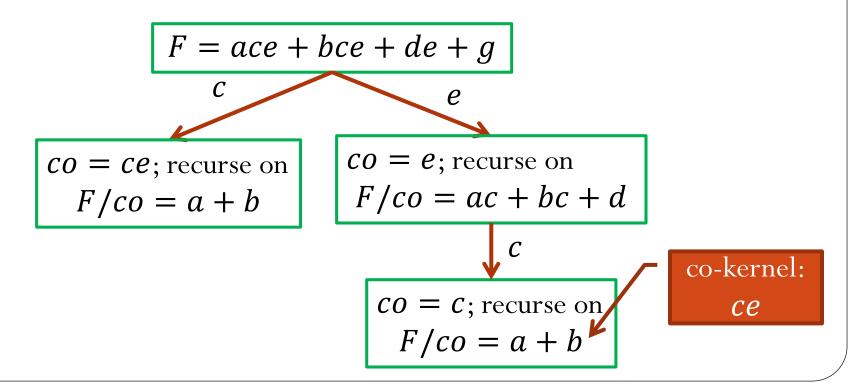
co = c; recurse on F/co = a + bno work no work

Kernelling Example (cont.)

```
FindKernels(F):
for (each var x in F) {
                           F = ace + bce + de + g
K=K \cup FindKernels(F/co);
                                                      return K = \{a + b,
                           Kernels K = \{a + b,
                                                         ac + bc + d
                                ac + bc + d
\mathbf{K} = \mathbf{K} \cup \mathbf{F};
                            ace + bce + de + g
return(K);
                                                co = e; recurse on
                        return K = \{a + b\}
                                                 F/co = ac + bc + d
      co = ce; recurse on
                                   return K = \{a + b\}
        F/co = a + b
                                                   co = c; recurse on
                                                    F/co = a + b
```

Get Co-Kernels

- With this algorithm ...
 - Can find all the kernels and co-kernels too.
 - Get co-kernels by **ANDing** the divisor *co* cubes **up recursion tree**.



One Tiny Problem

$$F = ace + bce + de + g$$

$$c$$

$$F/co = a + b$$

$$F/co = ac + bc + d$$

$$c$$

$$F/co = a + b$$

- The algorithm will revisit same (co-kernel, kernel) pair multiple times.
 - Why? Kernel you get for co-kernel *abc* is same as for *cba*, but current algorithm **doesn't know this** and will find same kernel for both co-kernels.
- <u>Solution</u>: remember which variables already tried in cokernels. A little extra book keeping solves this.

Multilevel Synthesis Models: Summary

- Boolean network model
 - Like a gate network, but each node in network is an SOP form.
 - Supports many operations to add, reduce, simplify nodes in network.
- Algebraic model & algebraic division
 - Simplifies Boolean functions to behave like polynomials of reals.
 - Divides one Boolean function by another:

```
F = (divisor D) \cdot (quotient Q) + remainder R
```

- **Kernels** / **Co-kernels** of a function F
 - **Kernel** = **cube-free** quotient obtained by dividing by a single cube (**co-kernel**)
 - Intersections of kernels of two functions give all <u>multiple-cube common divisors</u> (Brayton & McMullen theorem).

Notes

- The **algebraic model** (and **division**) are not the only options.
 - There are also "Boolean division" models and algorithms that don't lose expressivity.
 - ..but they are more complex.
 - Rich universe of models & methods here.

Good References

- R.K. Brayton, R. Rudell, A. Sangiovanni-Vincentelli, A.R. Wang, "MIS: A Multiple-Level Logic Optimization System," *IEEE Transactions on CAD of ICs*, vol. CAD-6, no. 6, November 1987, pp. 1062-1081.
- Giovanni De Micheli, Synthesis and Optimization of Digital Circuits, McGraw-Hill, 1994.