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ECCV'16

EUROPEAN CONFERENCE
ON COMPUTER VISION

October 8 – 16, 2016 | Amsterdam | the Netherlands



ImageNet and COCO Visual Recognition Challenges Workshop

Sunday, October 9th, ECCV 2016



Keypoints

Dataset

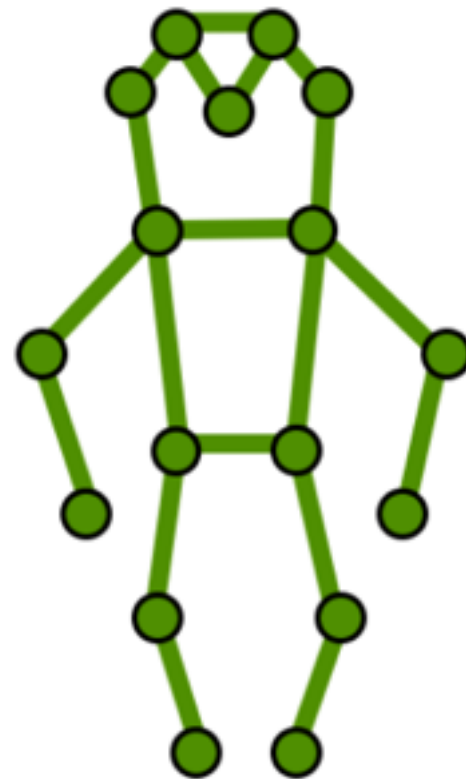




Dataset Statistics (I)



Keypoints Dataset



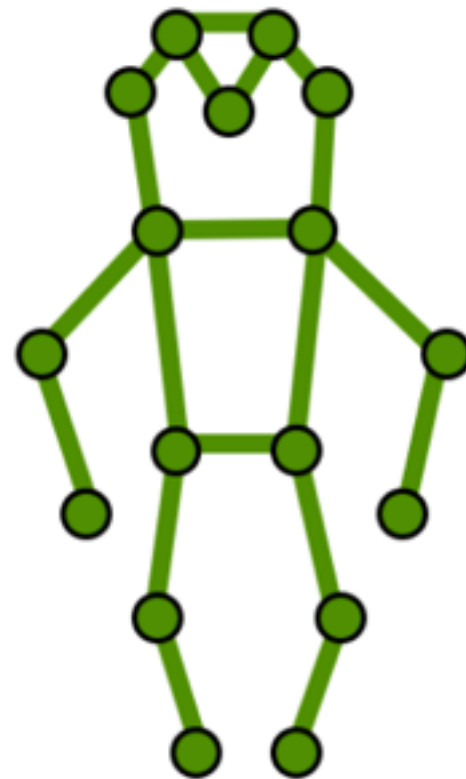


Dataset Statistics (I)



- 17 types of keypoints.

Keypoints Dataset



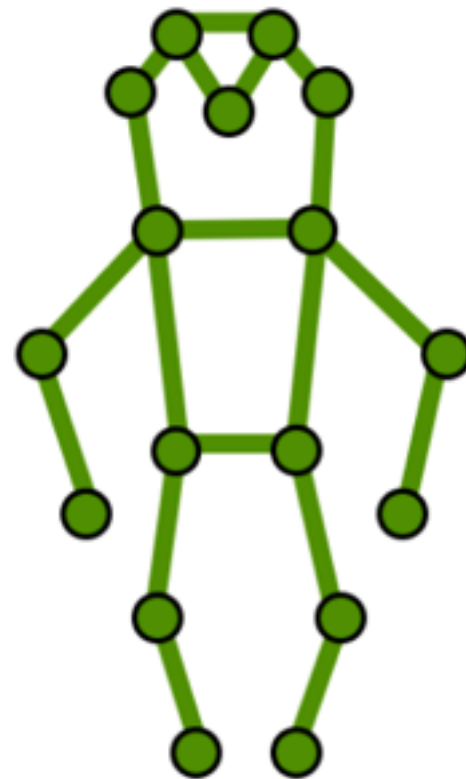


Dataset Statistics (I)



- 17 types of keypoints.
- Visibility flag annotations.

Keypoints Dataset



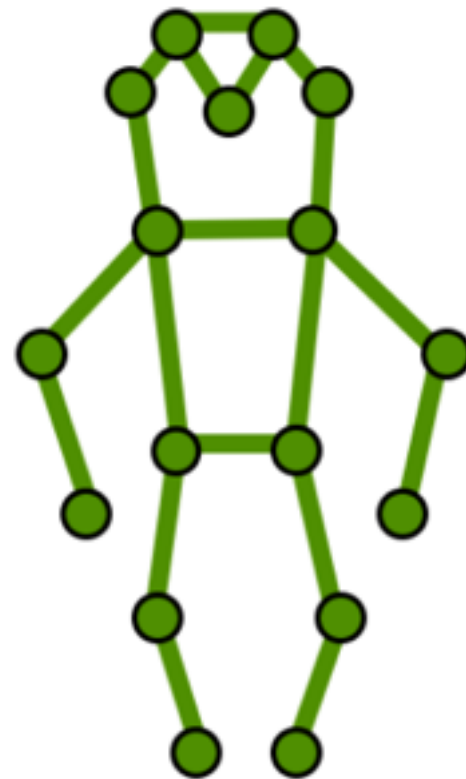


Dataset Statistics (I)



- 17 types of keypoints.
- Visibility flag annotations.
- 105,698 annotated people.

Keypoints Dataset



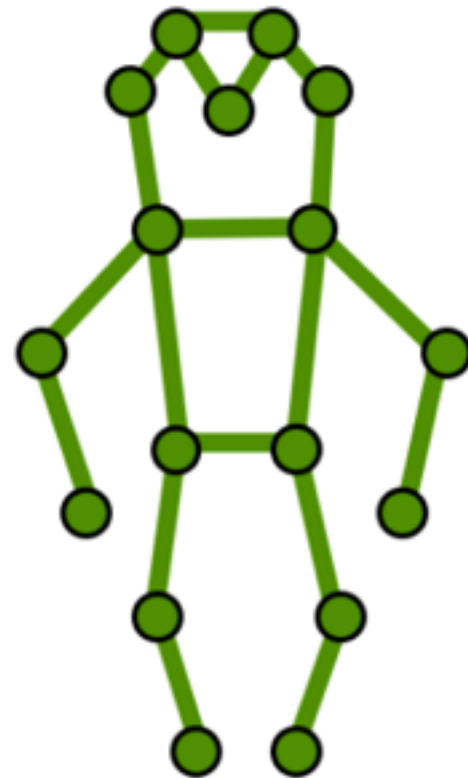


Dataset Statistics (I)



- 17 types of keypoints.
- Visibility flag annotations.
- 105,698 annotated people.
- 1,161,667 annotated keypoints.

Keypoints Dataset



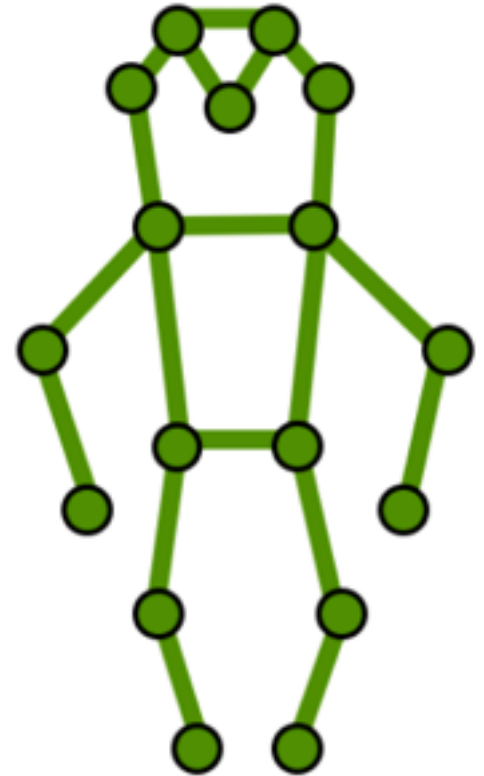


Dataset Statistics (I)



- 17 types of keypoints.
- Visibility flag annotations.
- 105,698 annotated people.
- 1,161,667 annotated keypoints.
- 45,174 unique images (train/val)

Keypoints Dataset



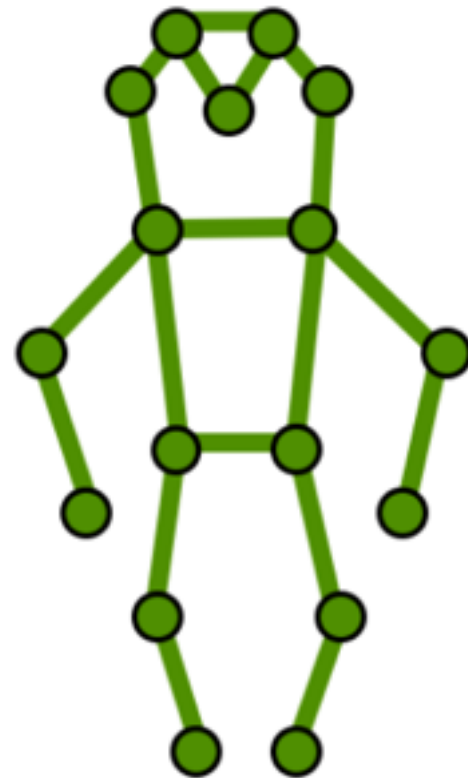


Dataset Statistics (I)



Keypoints Dataset

- 17 types of keypoints.
- Visibility flag annotations.
- 105,698 annotated people.
- 1,161,667 annotated keypoints.
- 45,174 unique images (train/val)
- Only medium and large size people annotated

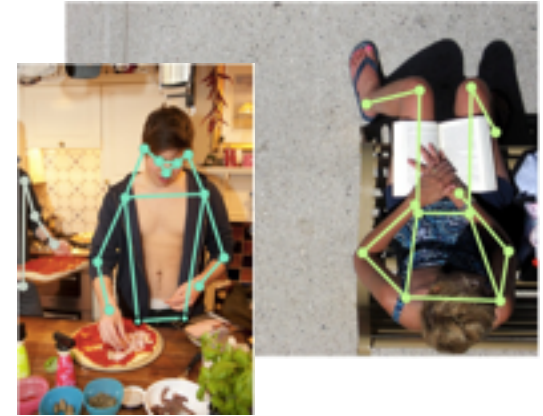




Dataset Statistics (II)



- Max people per image: **13**
- Mean people per image: **2.65**



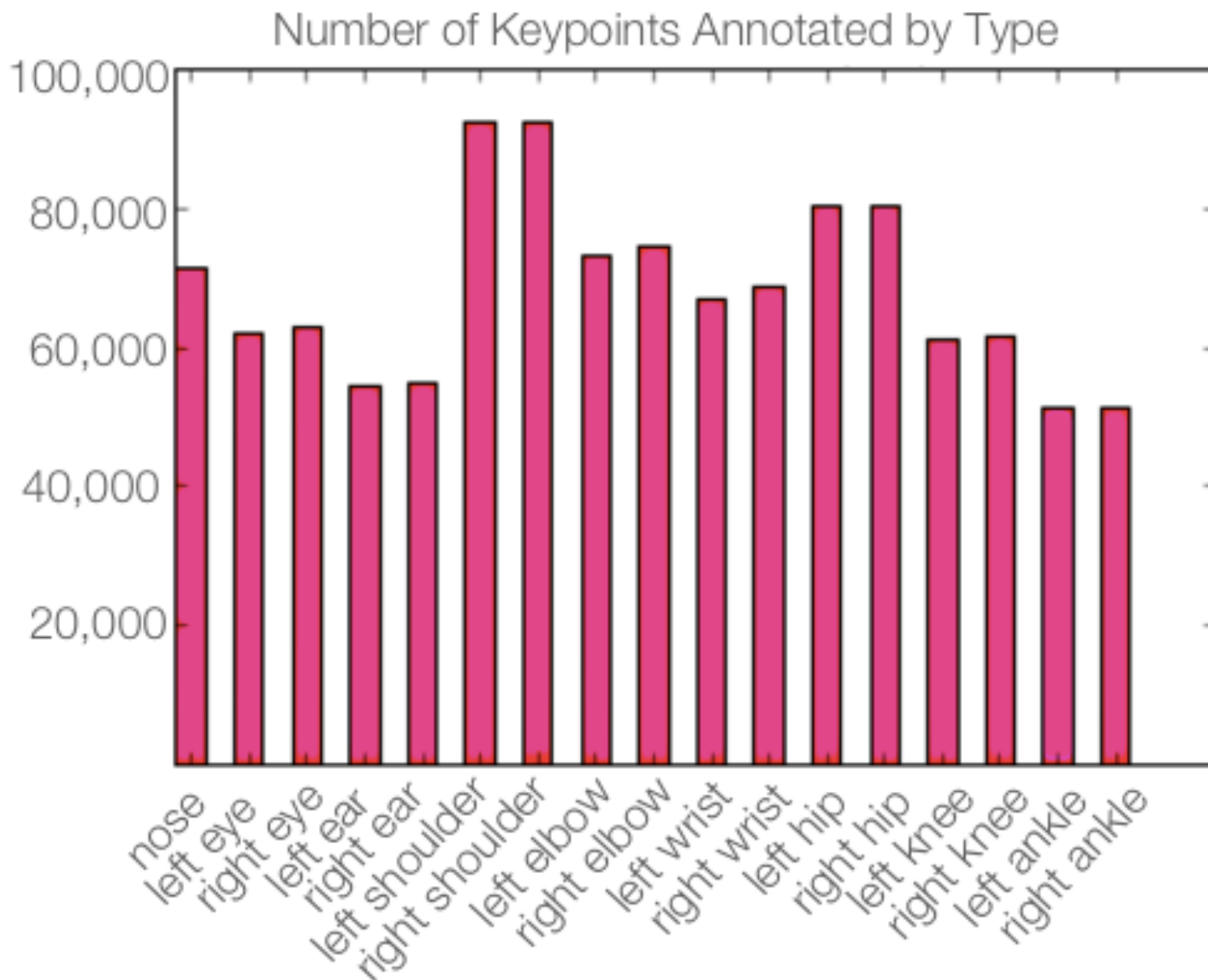
Visibility Flag v_i

- Mean annotations per person: **11**
- 6,000 people with > 17 annotations
- 2,300 people with only 1 keypoint
- shoulders, hips, elbows, noses most popular





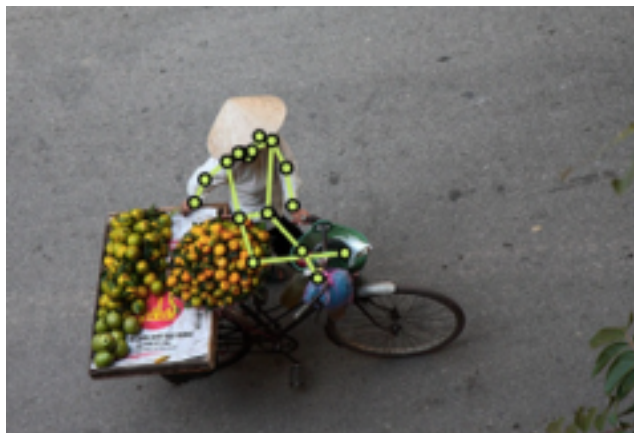
Dataset Statistics (III)





2016 COCO Keypoints Challenge

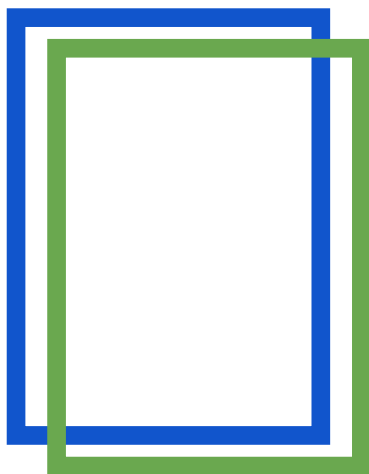
- New Task - Keypoint Detection and Localization
- New Metric - Object Keypoint Similarity (OKS)



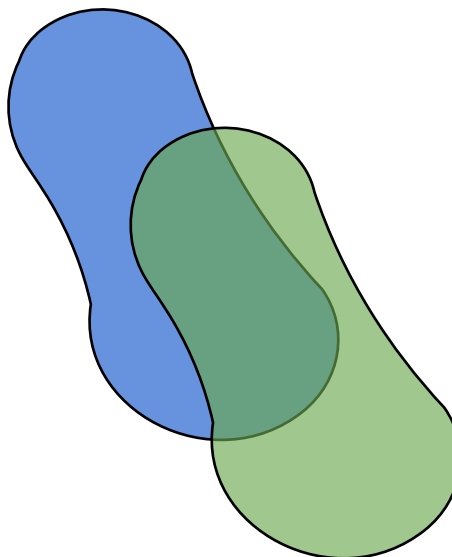


Evaluating BBoxes, Segmentations and Keypoints

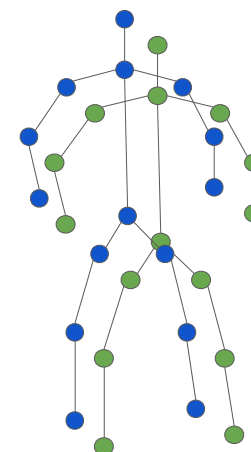
To calculate AP we need:



Bounding Box IoU



Mask IoU

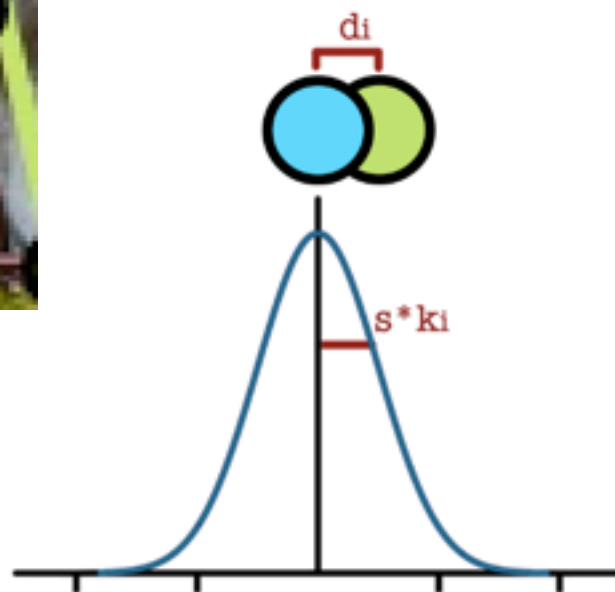


Object
Keypoint
Similarity



Keypoints Evaluation Metric

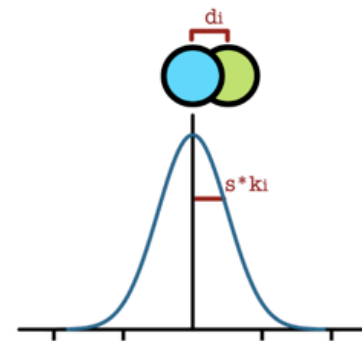
Object Keypoint Similarity -OKS





Object Keypoint Similarity

$$OKS = \frac{\sum_i e^{-\frac{d_i^2}{2s^2k_i^2}} \delta(v_i > 0)}{\sum_i \delta(v_i > 0)}$$



- d_i are the Euclidean distances between each ground truth and detected keypoint
- v_i are the visibility flags of the ground truth
- $s * k_i$ (scale * keypoint constant) is the standard deviation of this gaussian
- Scale and Keypoint constant needed to equalize the importance of each keypoint
 - Eye location more precise than Hip location
- Perfect predictions will have OKS=1
- Predictions with keypoints wrong by more than a few standard deviations will have OKS~0



Scale and Standard Deviation

S scale



k_i keypoint





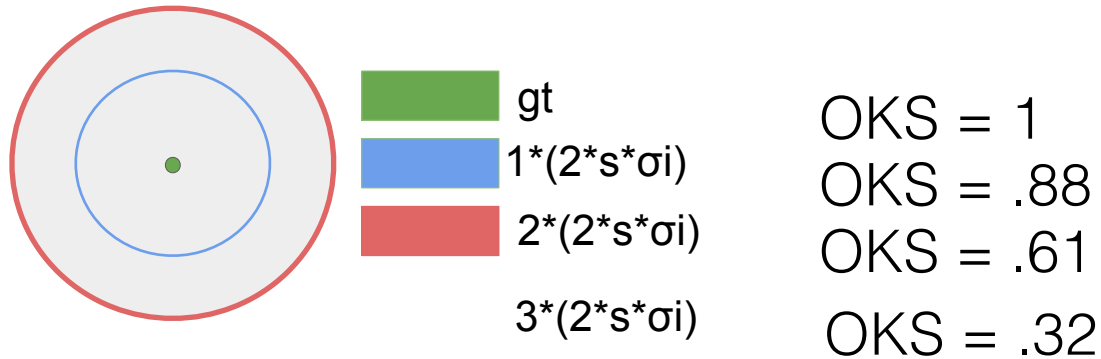
Standard Deviation per Keypoint type

Keypoint	k_i
hips	0.107
ankles	0.089
knees	0.087
shoulders	0.079
elbows	0.072
wrists	0.062
ears	0.035
nose	0.026
eyes	0.025

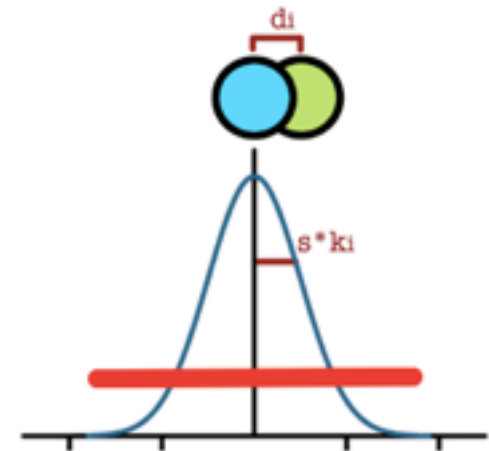




OKS Cut-off



- Minimum OKS value is 0.5
- We analyze only keypoints that lie within ~ 2.77 of their standard deviation





From OKS to COCO AP



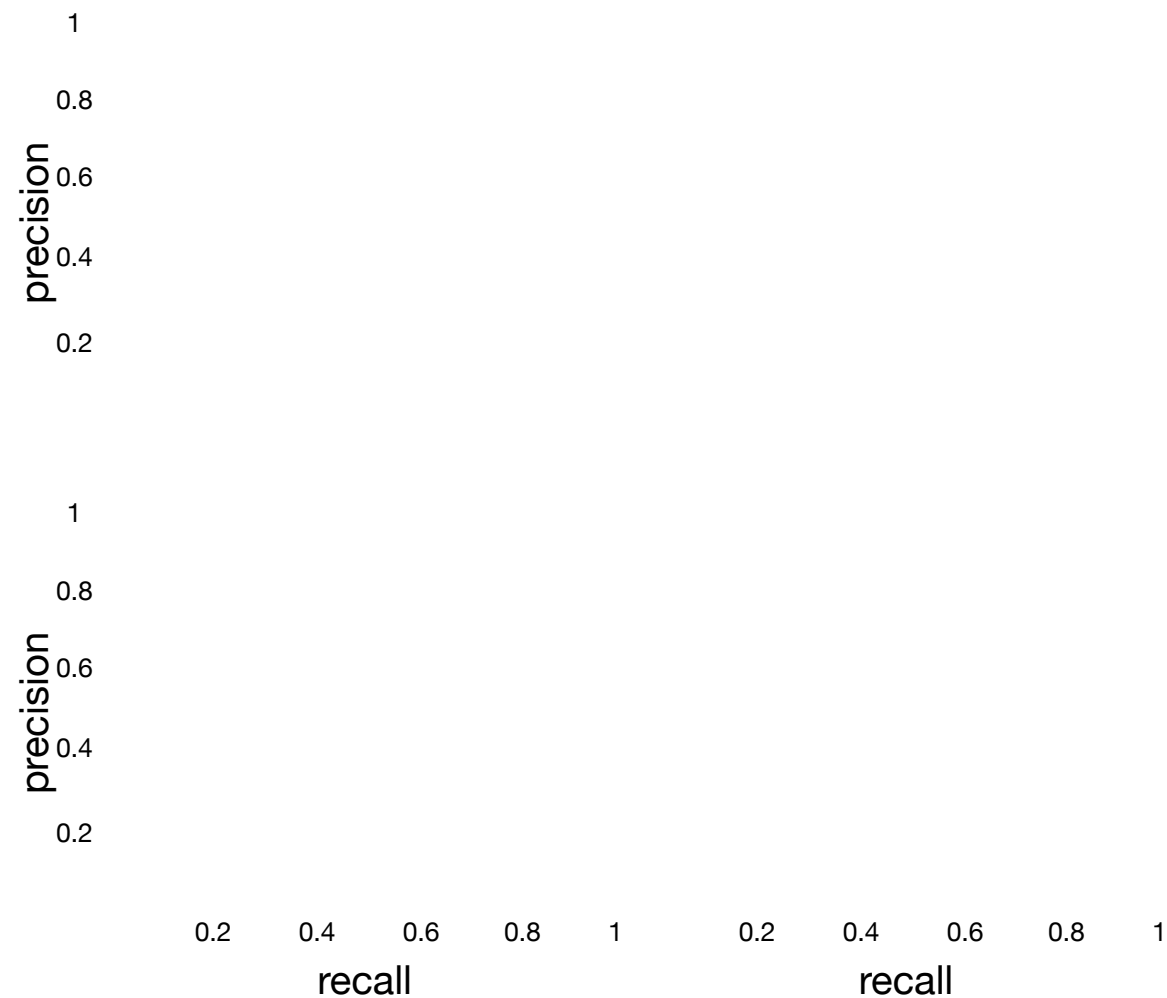
From OKS to COCO AP

COCO AP is the area under the PR curve



From OKS to COCO AP

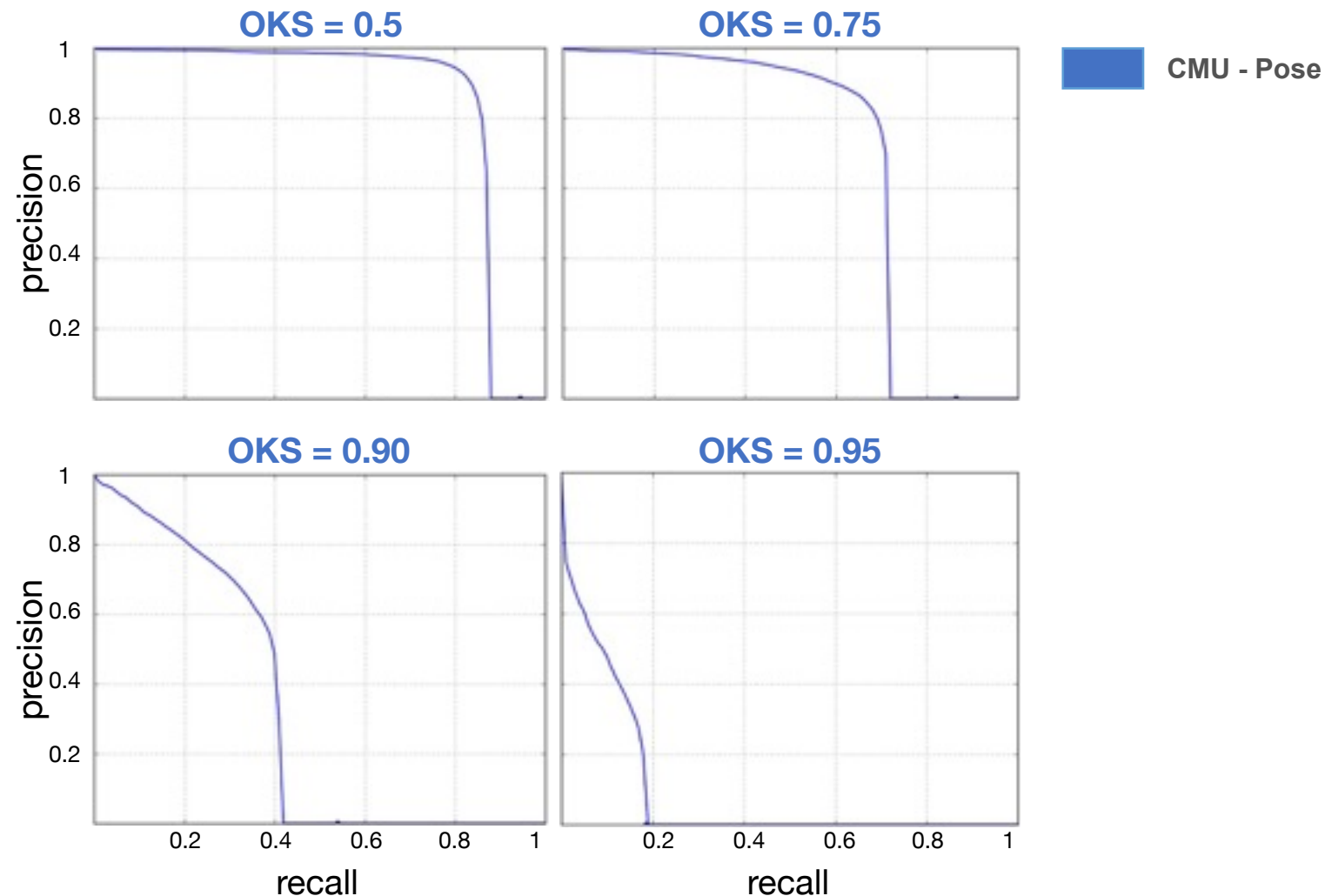
COCO AP is the area under the PR curve





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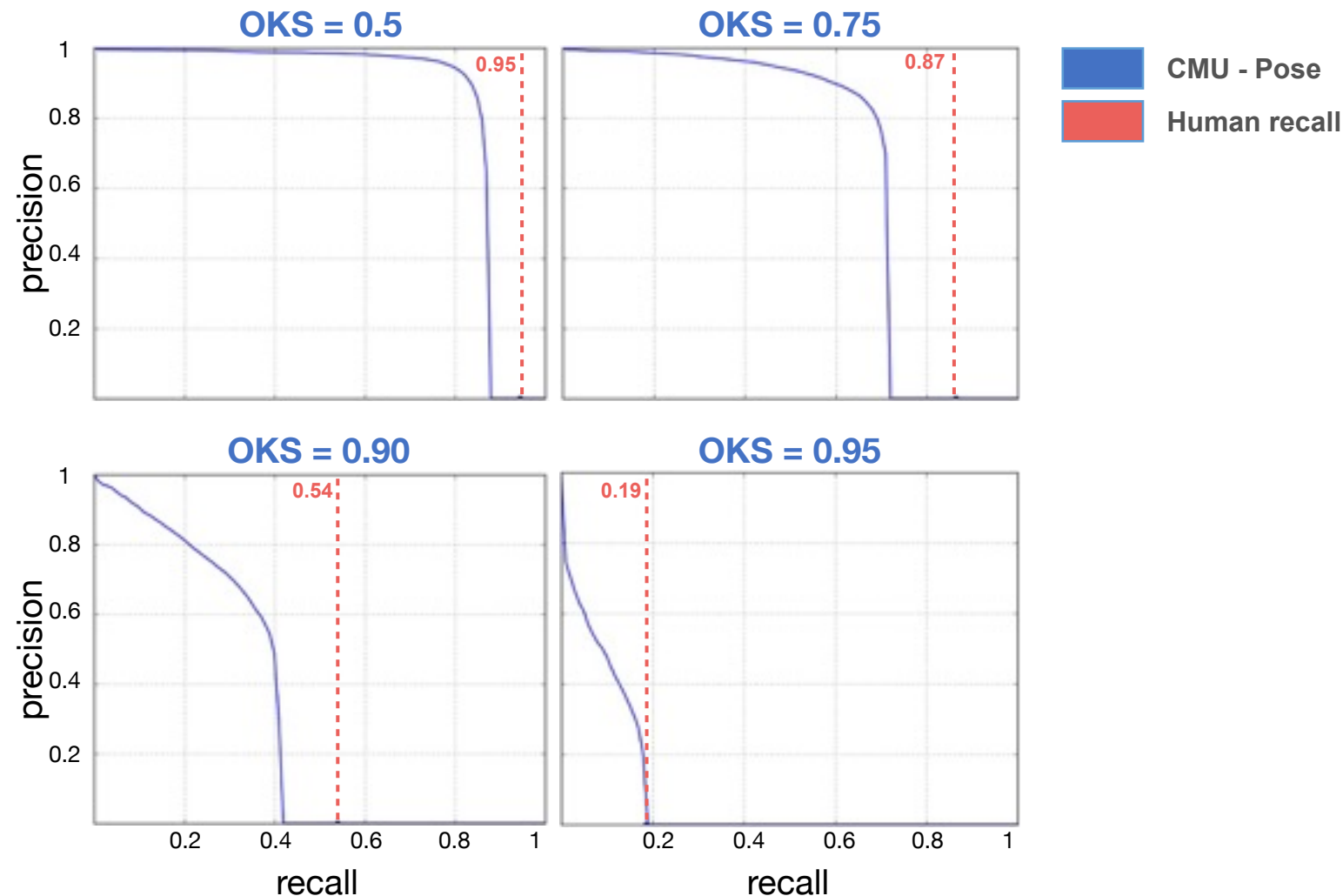
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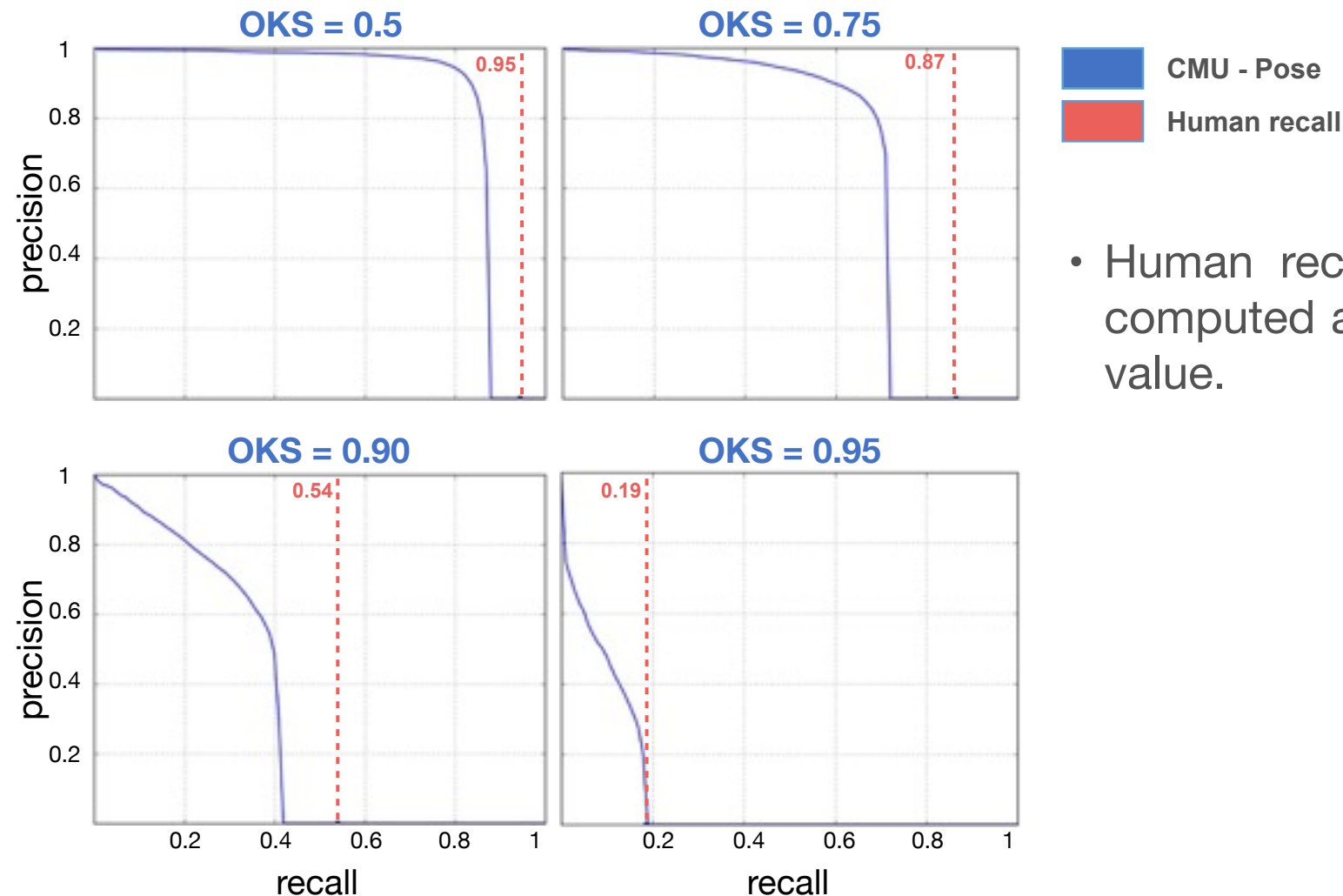
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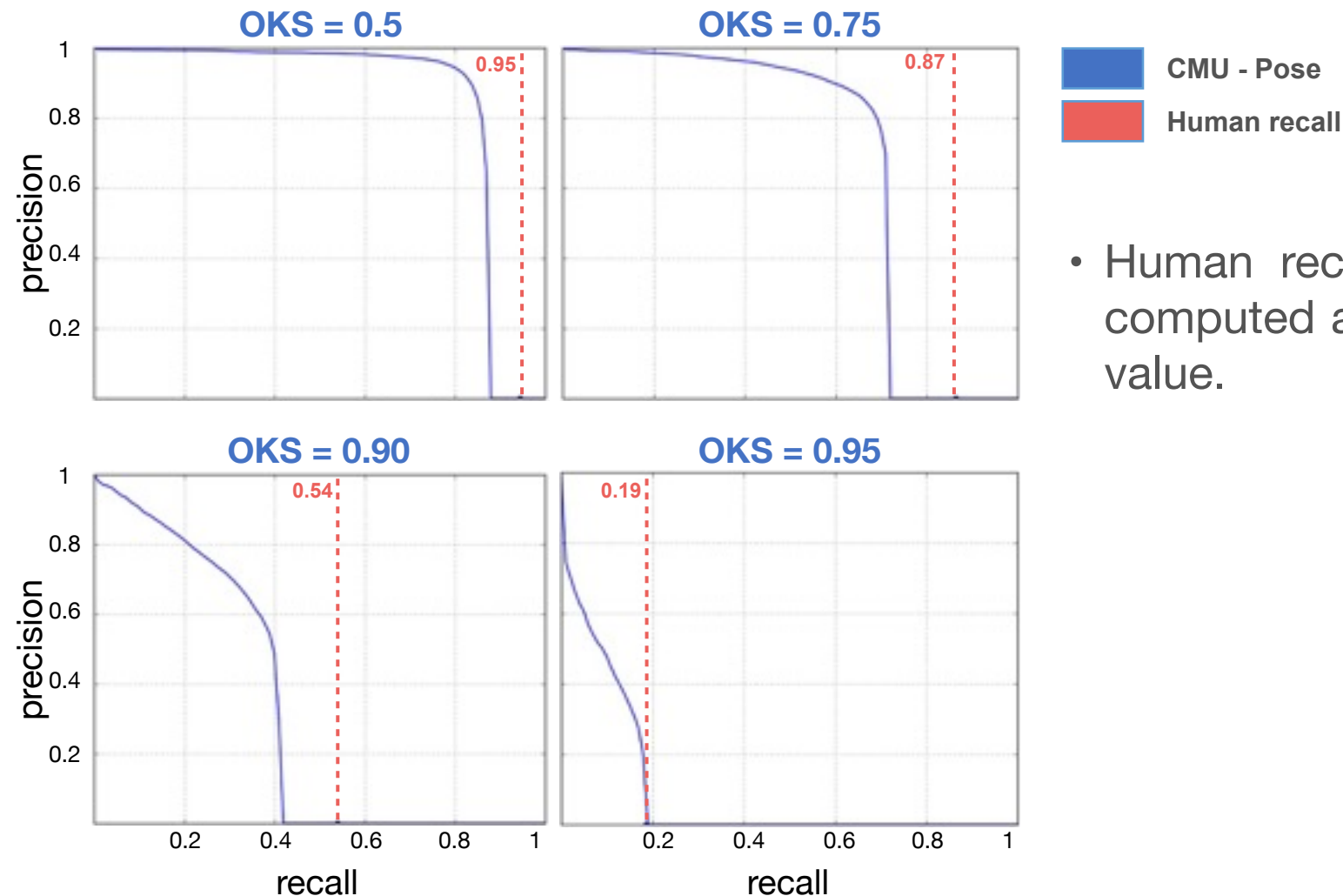


- Human recall can be computed at any OKS value.



From OKS to COCO AP

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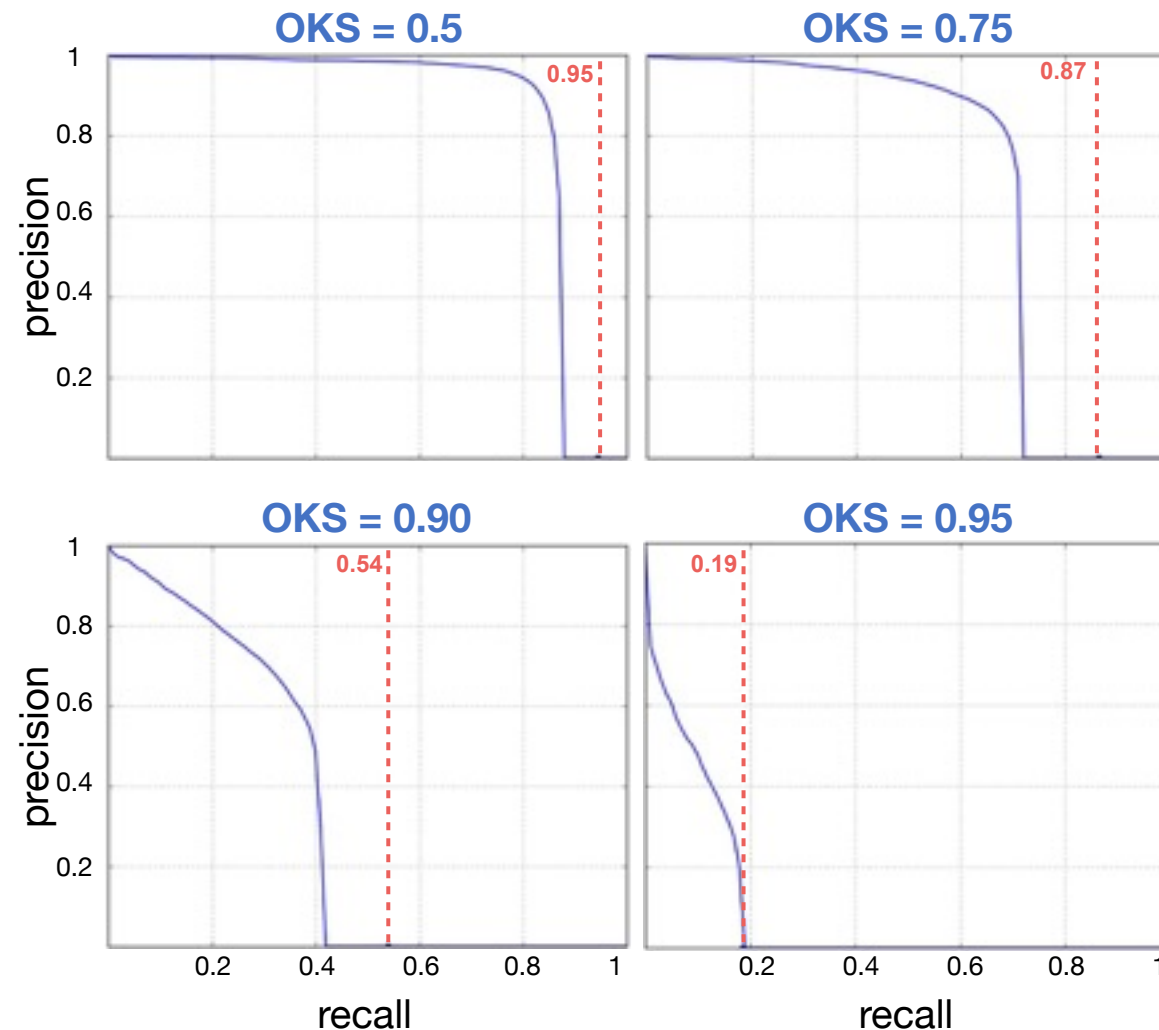


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From OKS to COCO AP

COCO AP is the area under the PR curve



CMU - Pose
Human recall

- Human recall can be computed at any OKS value.
- Algorithm has smooth precision drop-off but trails in recall.



COCO Challenge Results



Keypoints





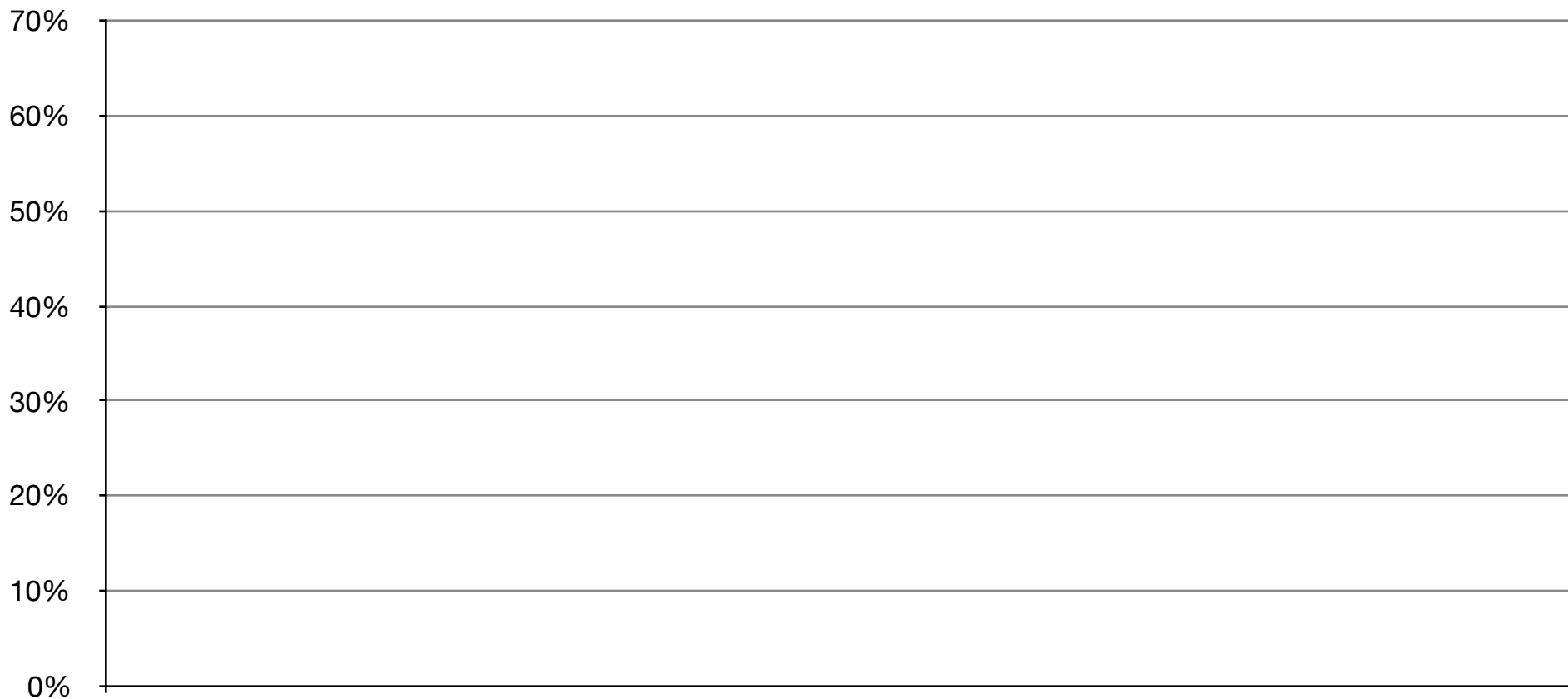
Keypoints Leaderboard (I)

COCO AP (over all OKS)



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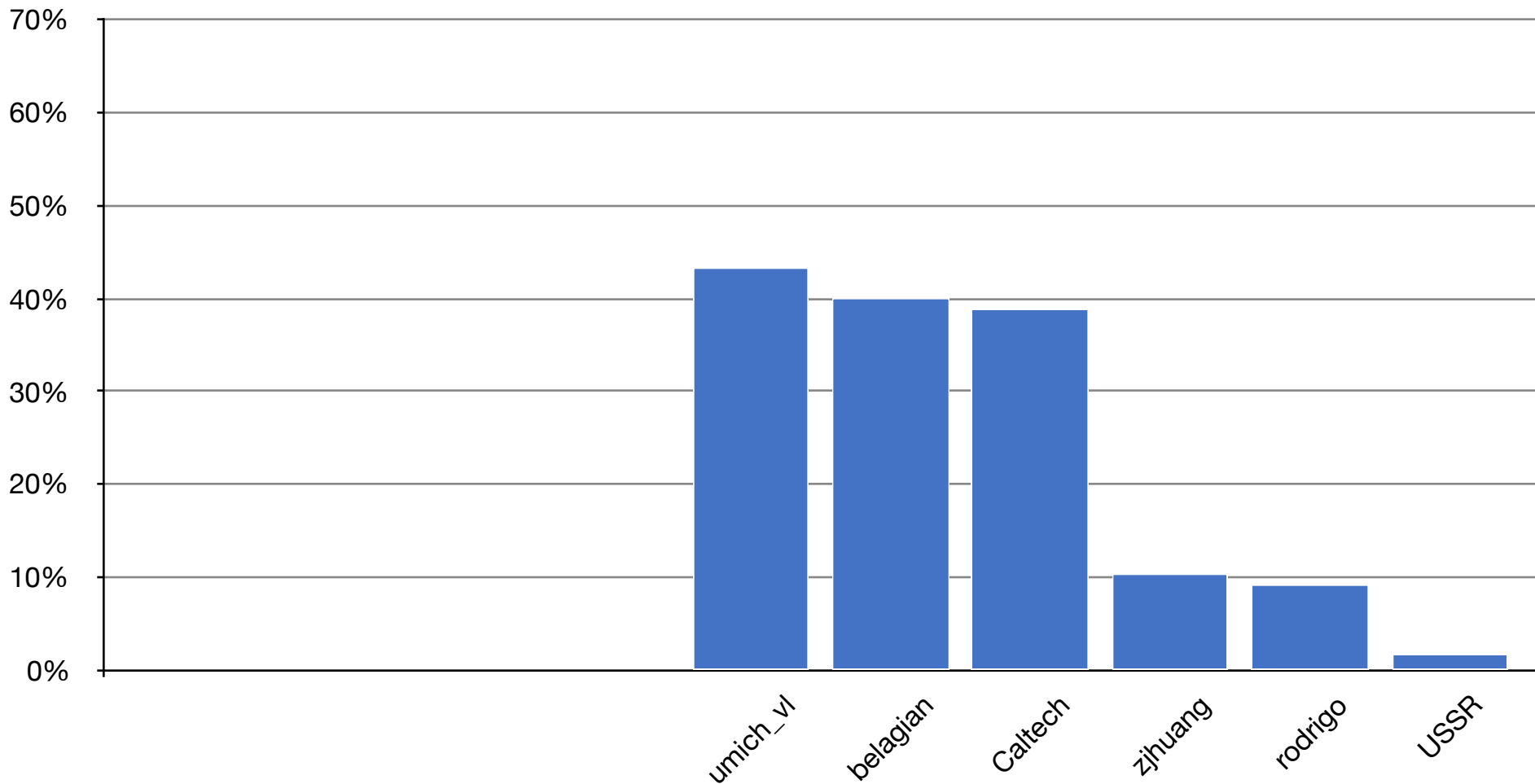
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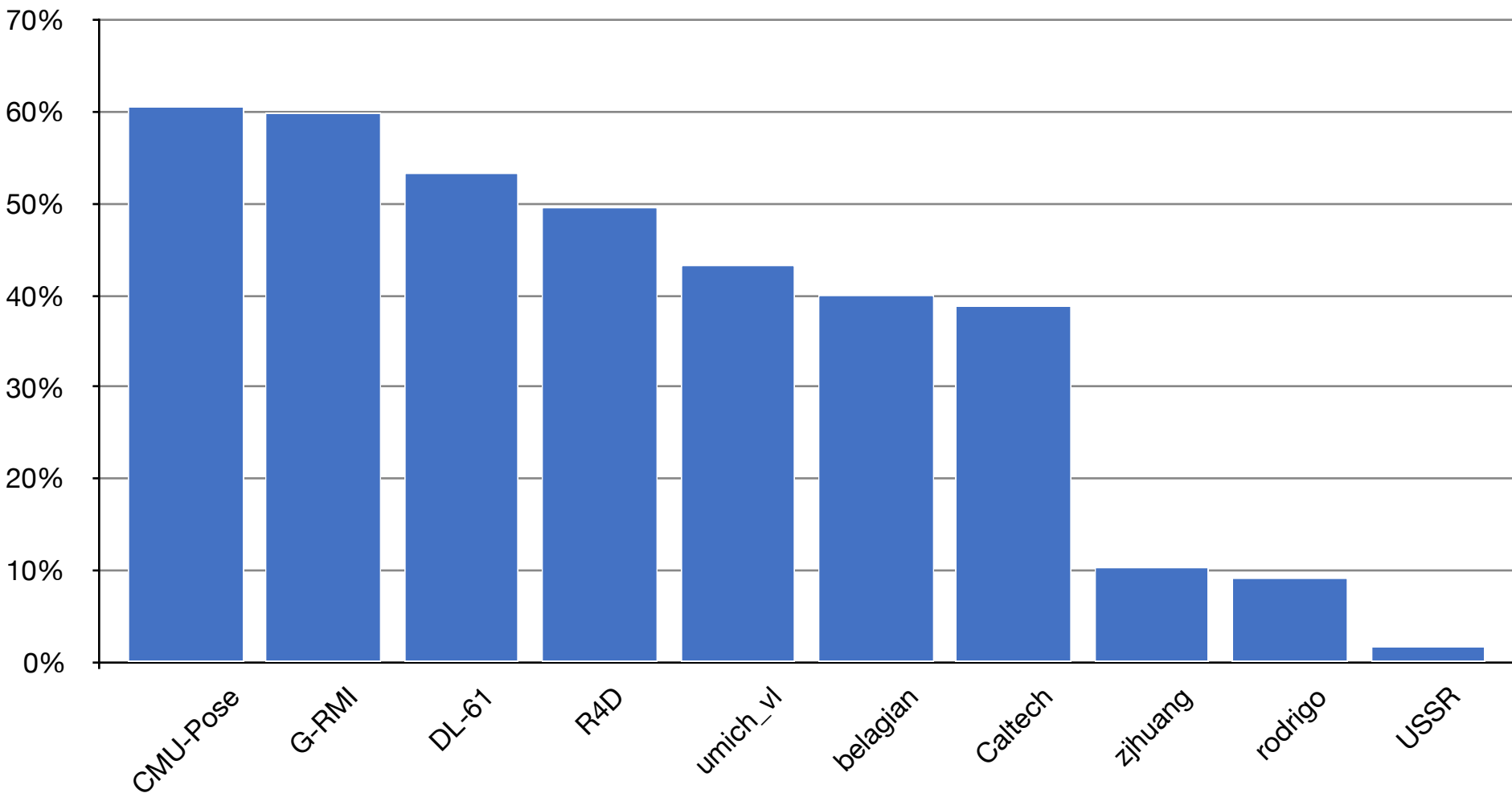
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Keypoints Leaderboard (I)

COCO AP (over all OKS)





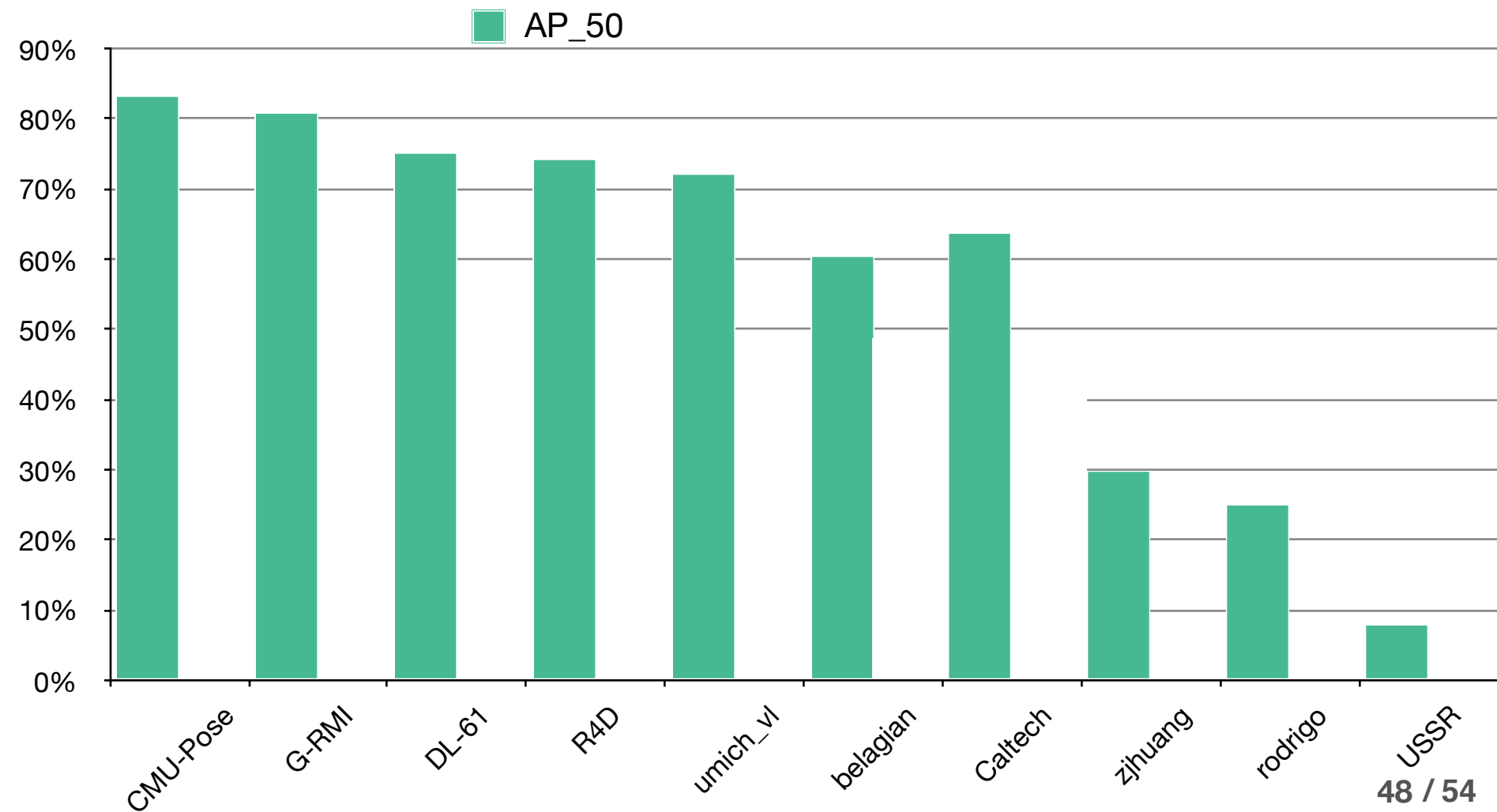
Keypoints Leaderboard (II)

Instance localization affects also keypoints



Keypoints Leaderboard (II)

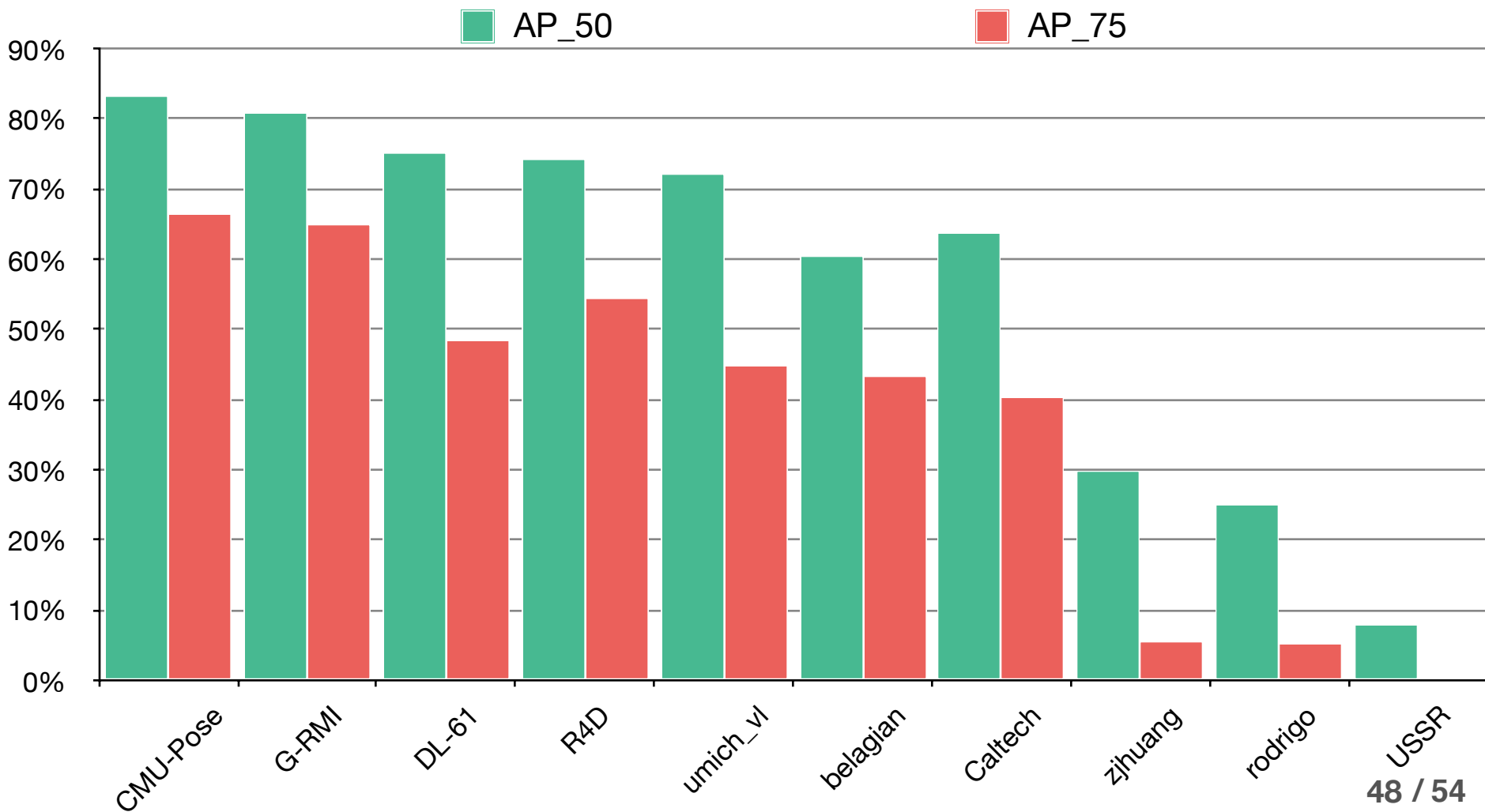
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Keypoints Leaderboard (II)

Instance localization affects also keypoints





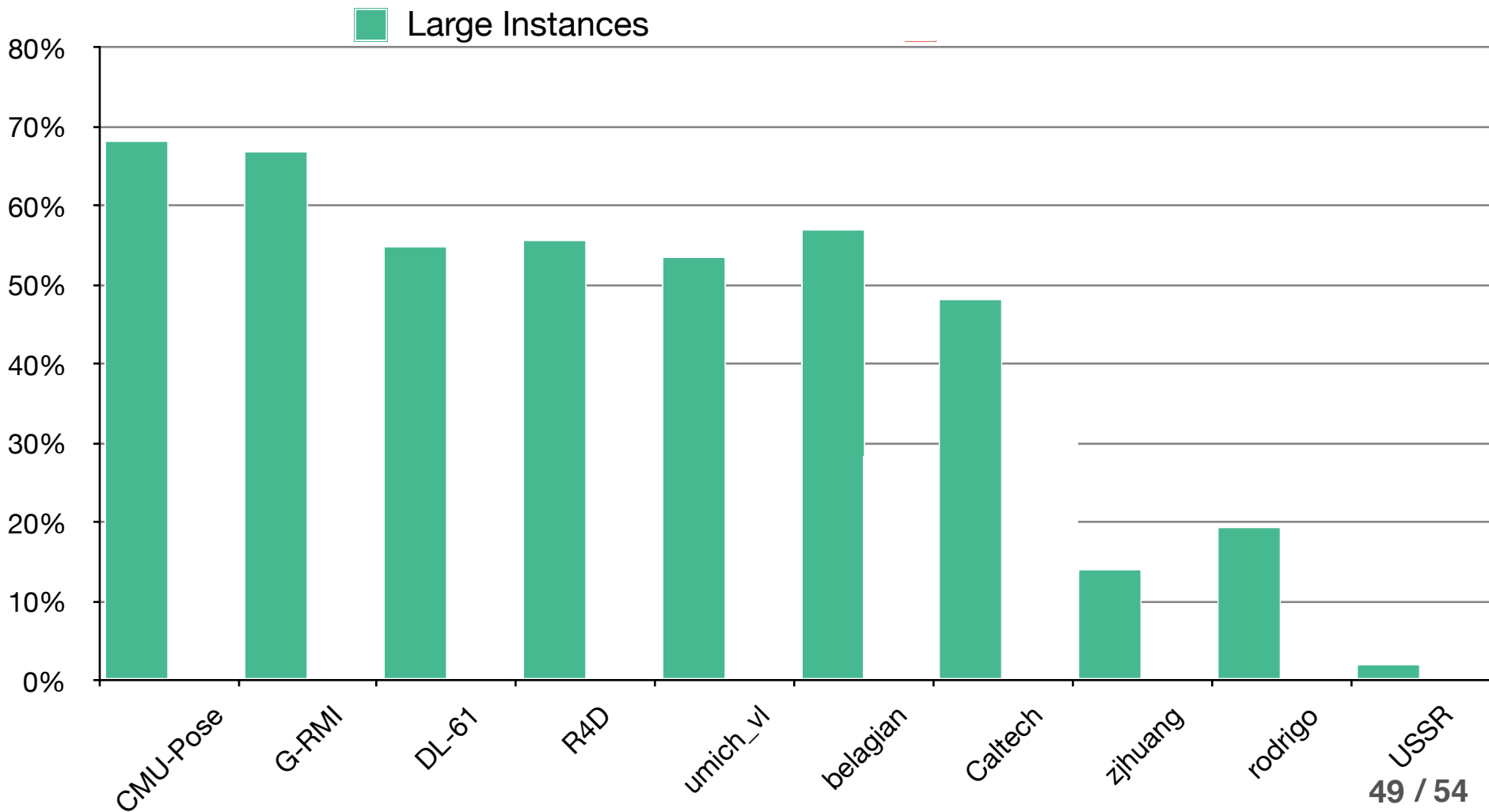
Keypoints Leaderboard (III)

Instance scale is an important factor



Keypoints Leaderboard (III)

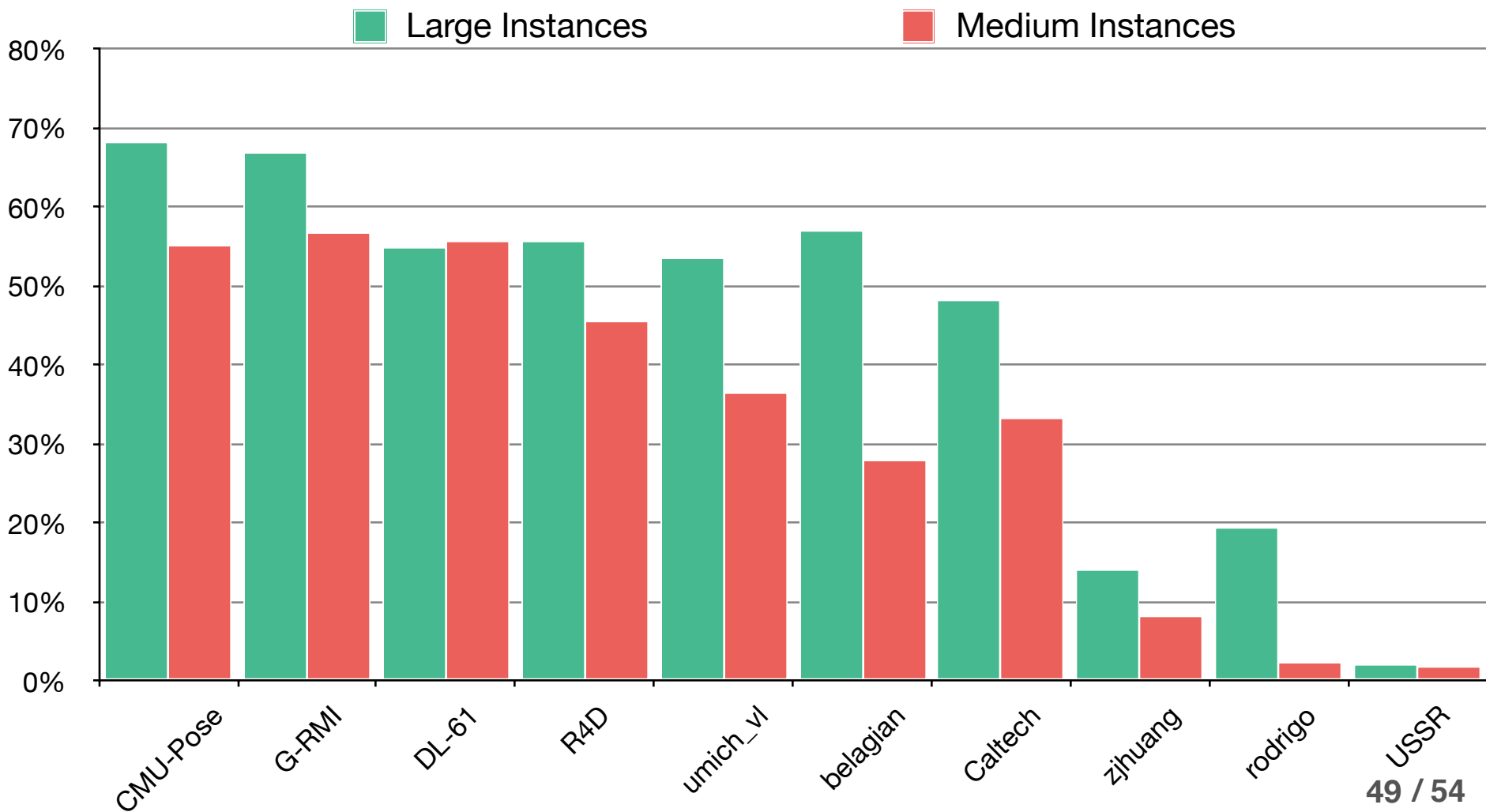
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Keypoints Leaderboard (III)

Instance scale is an important factor





Performance Breakdown (I)

COCO AP varies across keypoints

- CMU-Pose
- G-RMI
- DL-61
- R4D
- umich_vl
- belagian
- Caltech

100%

75%

50%

25%

0%



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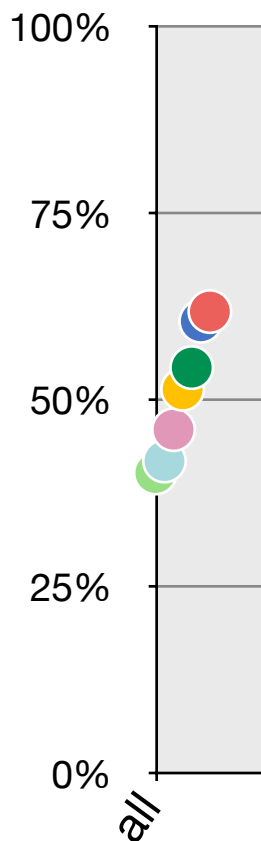




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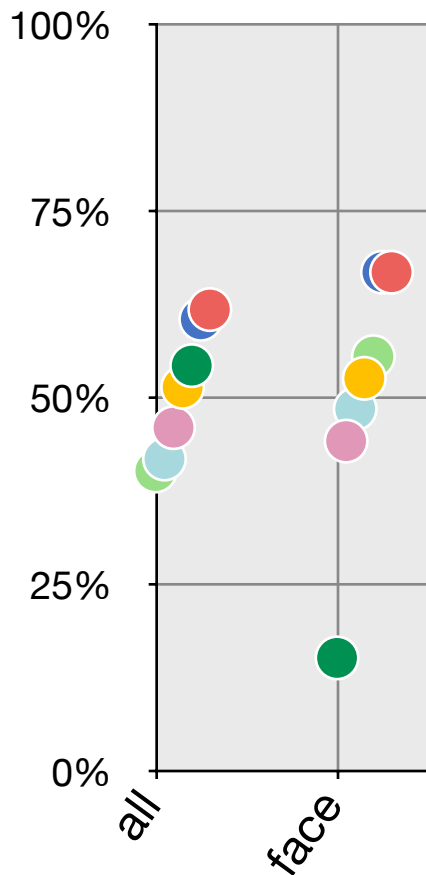




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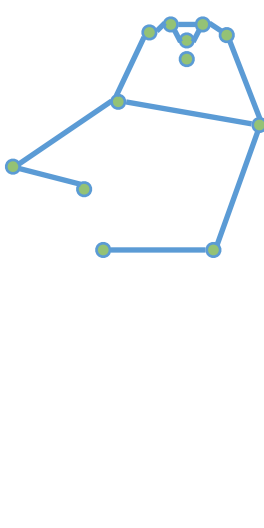
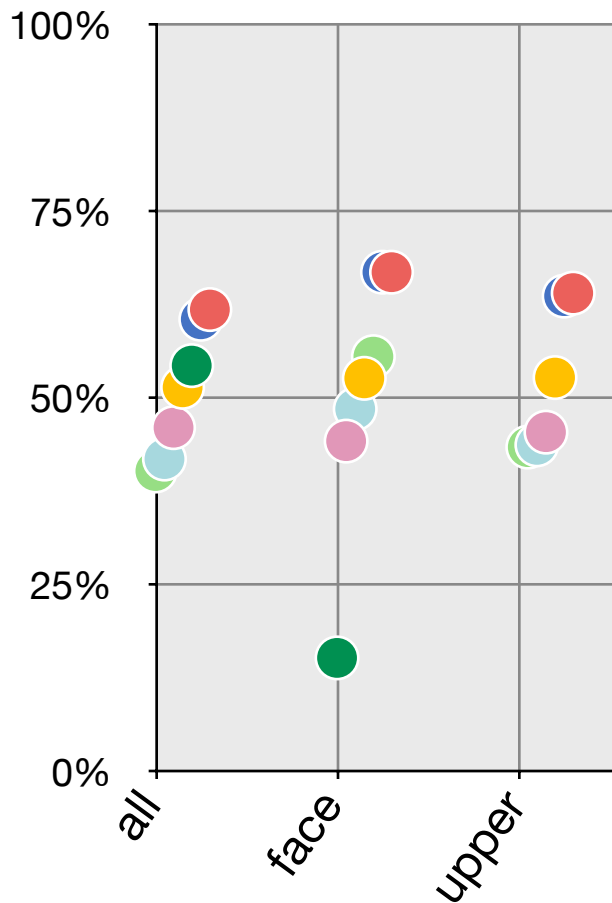




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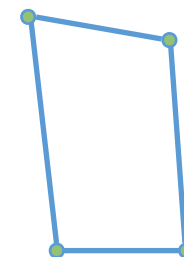
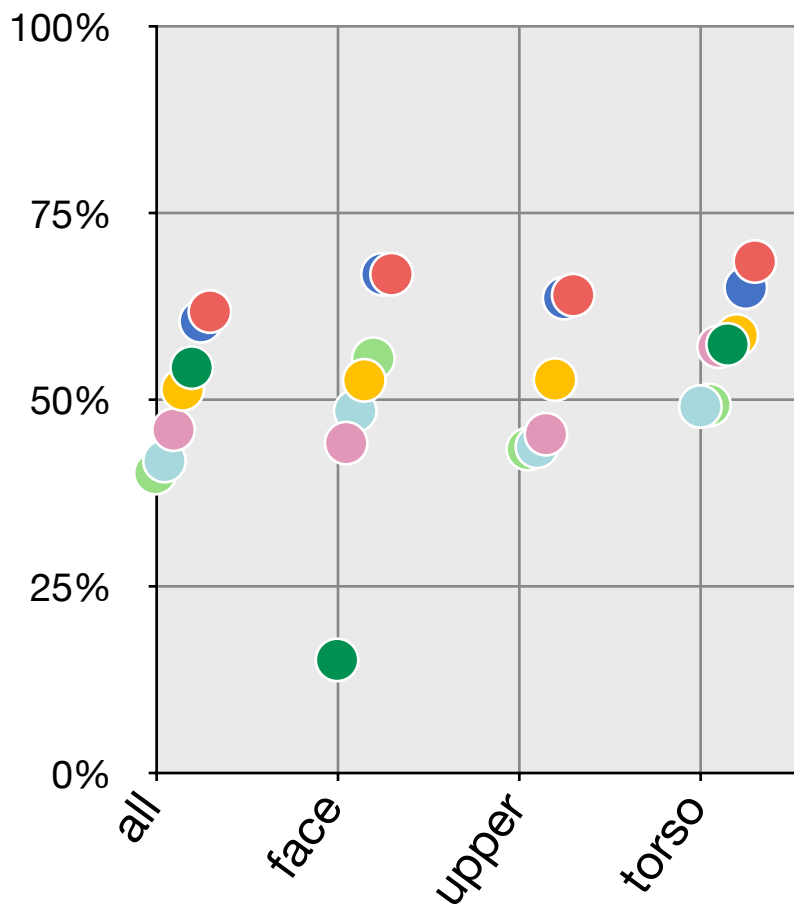




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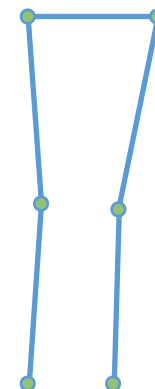
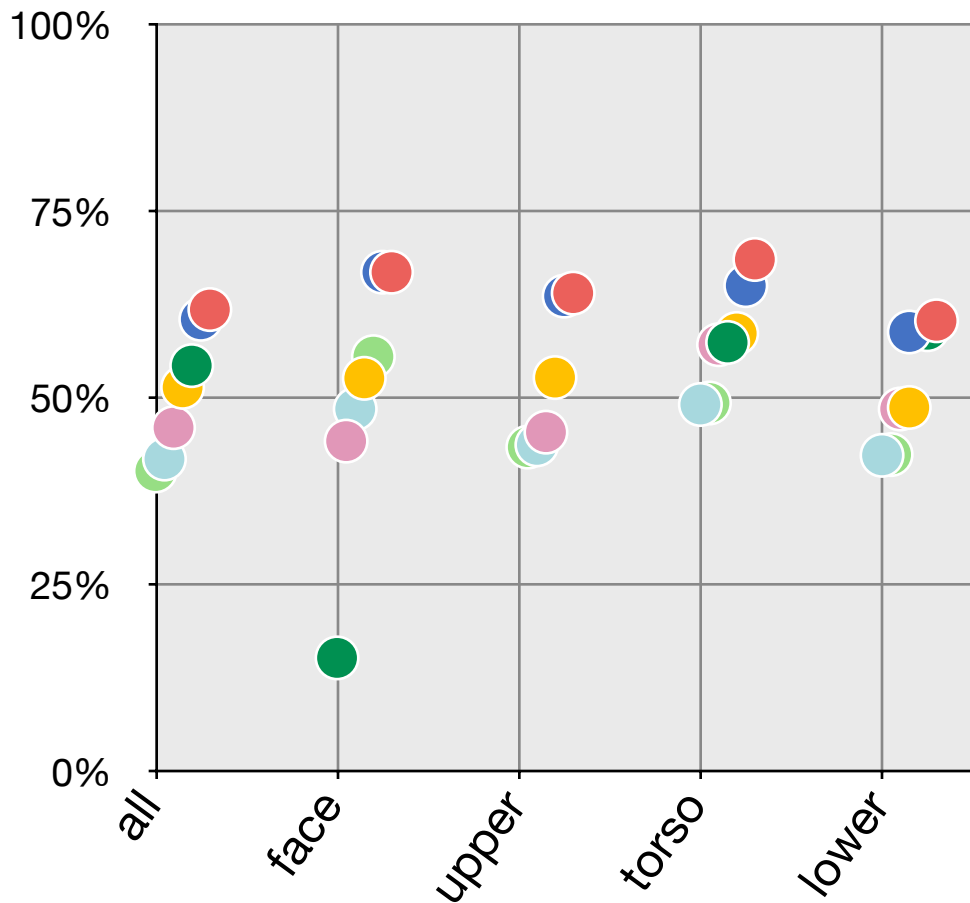




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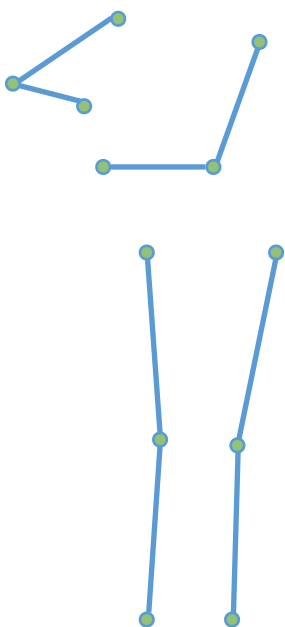
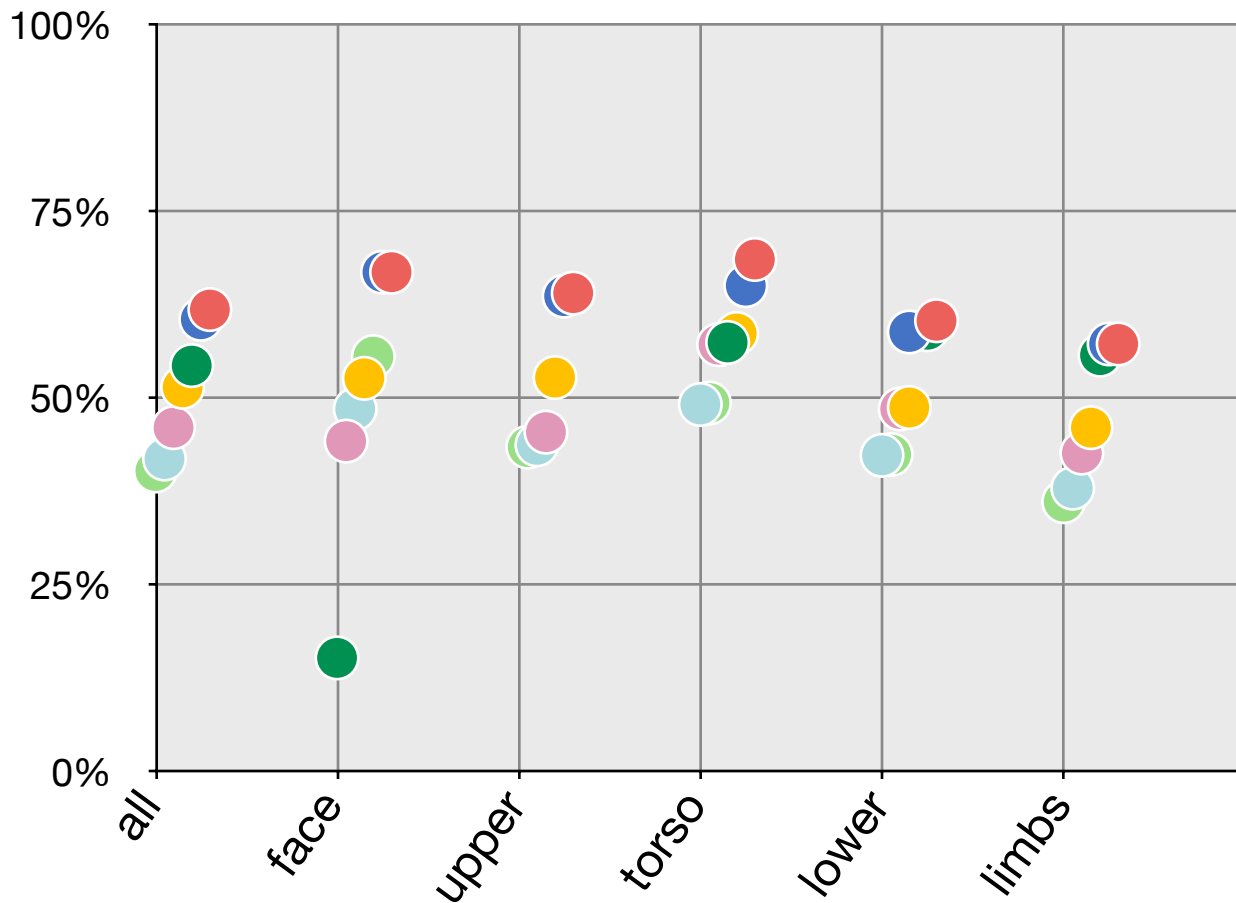




Performance Breakdown (I)

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Correlation between methods



Correlation between methods

How similarly do algorithms perform?



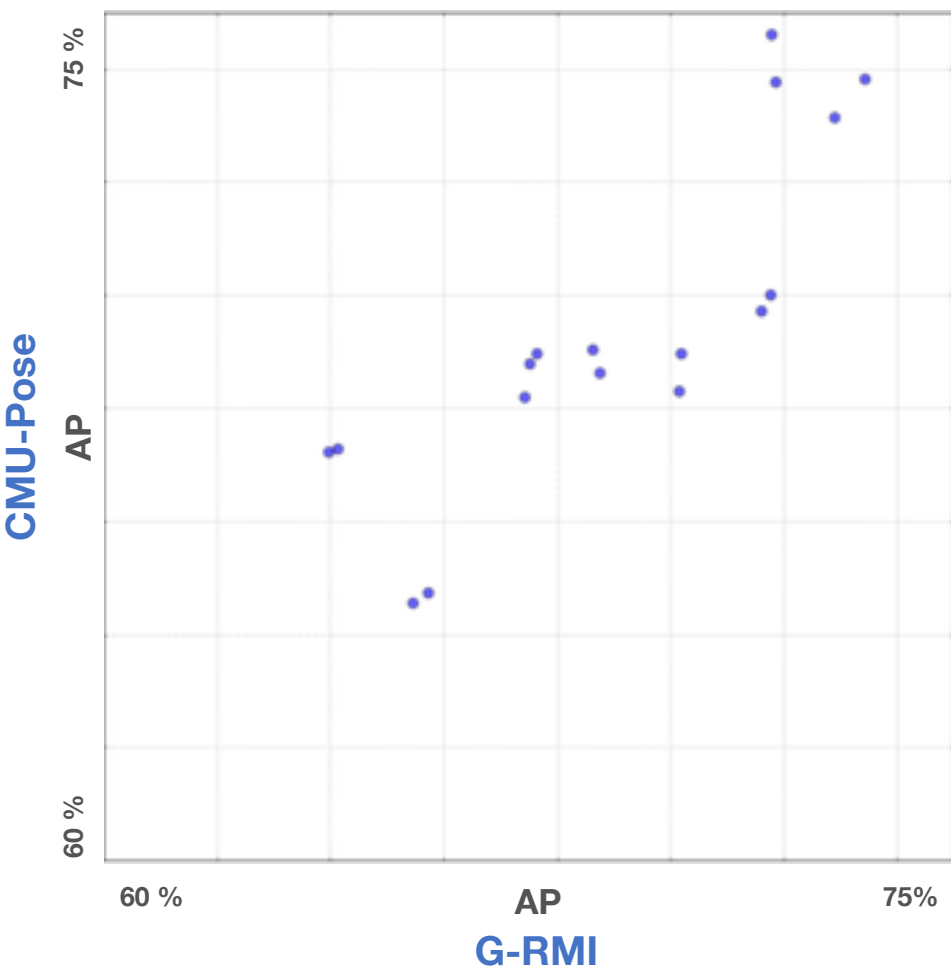
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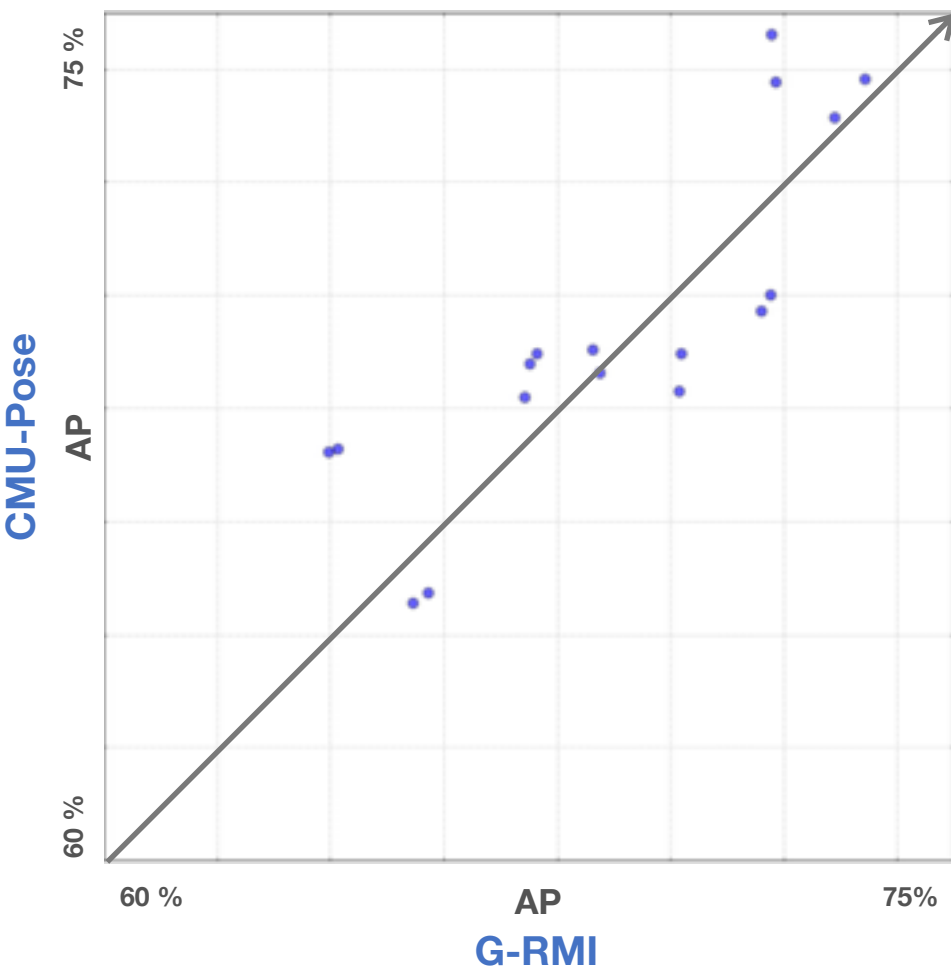
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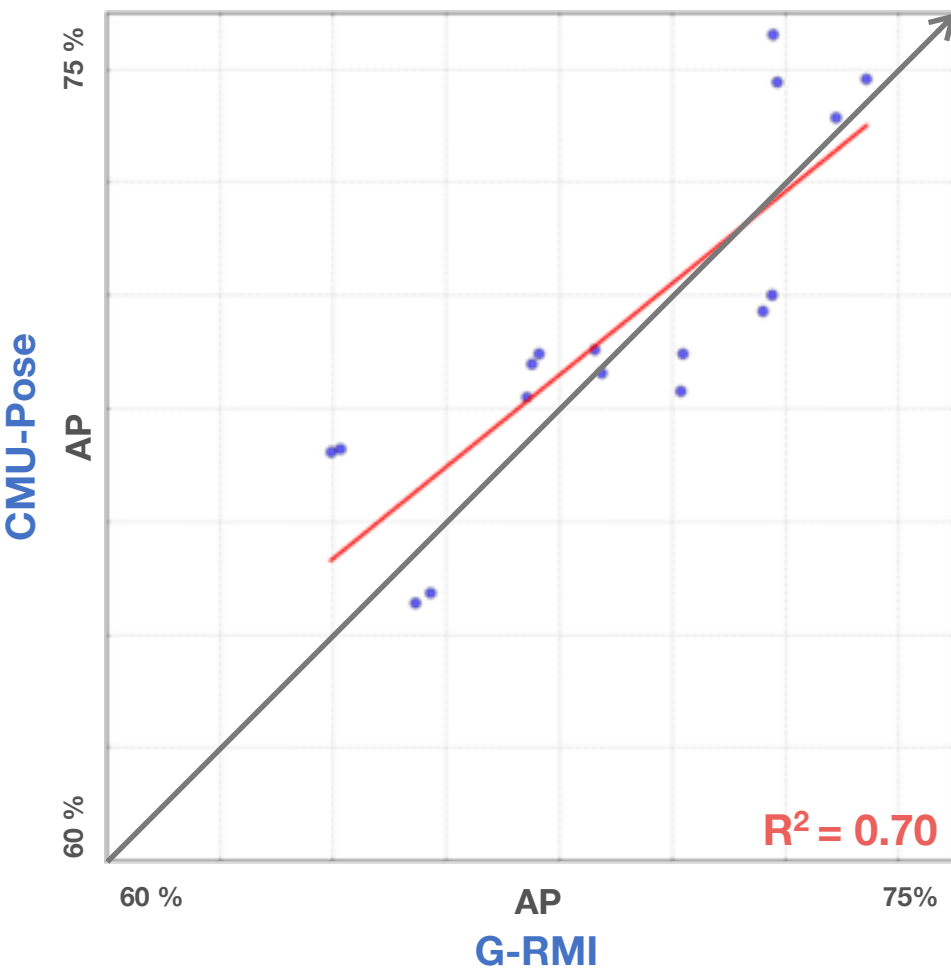
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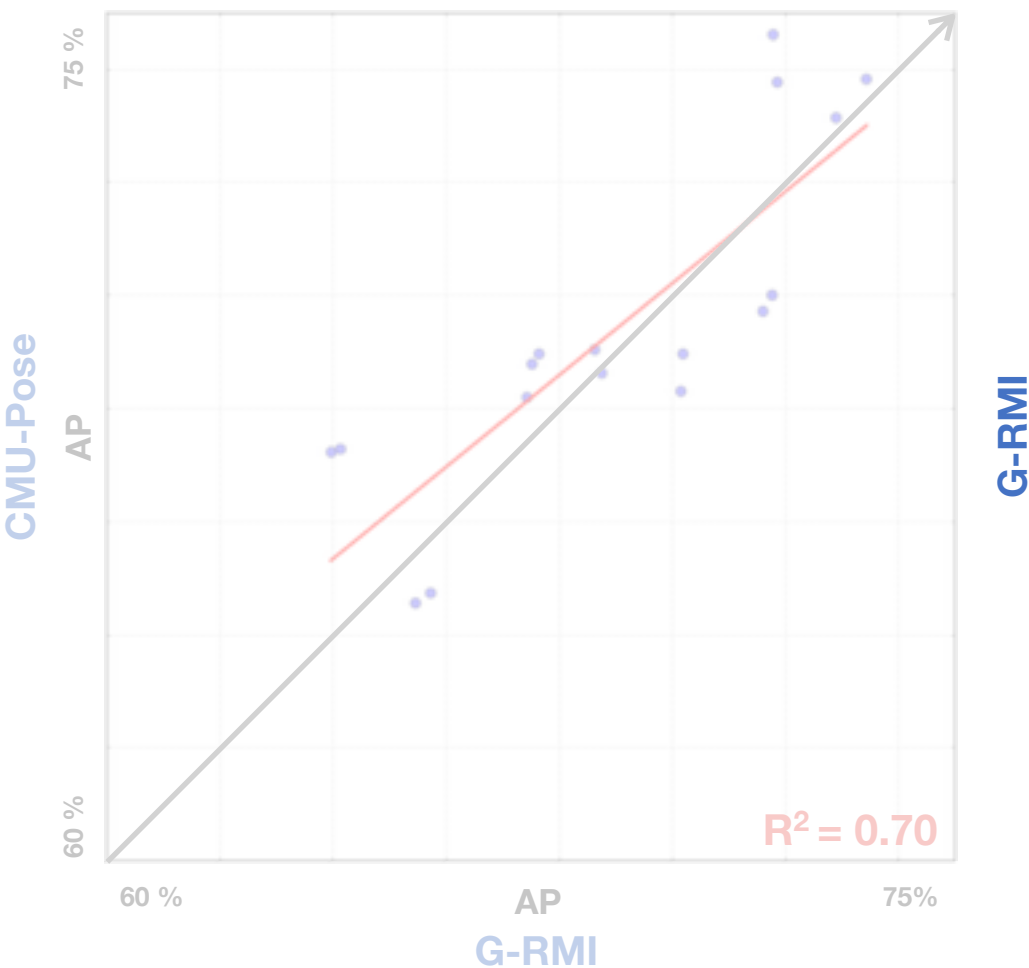
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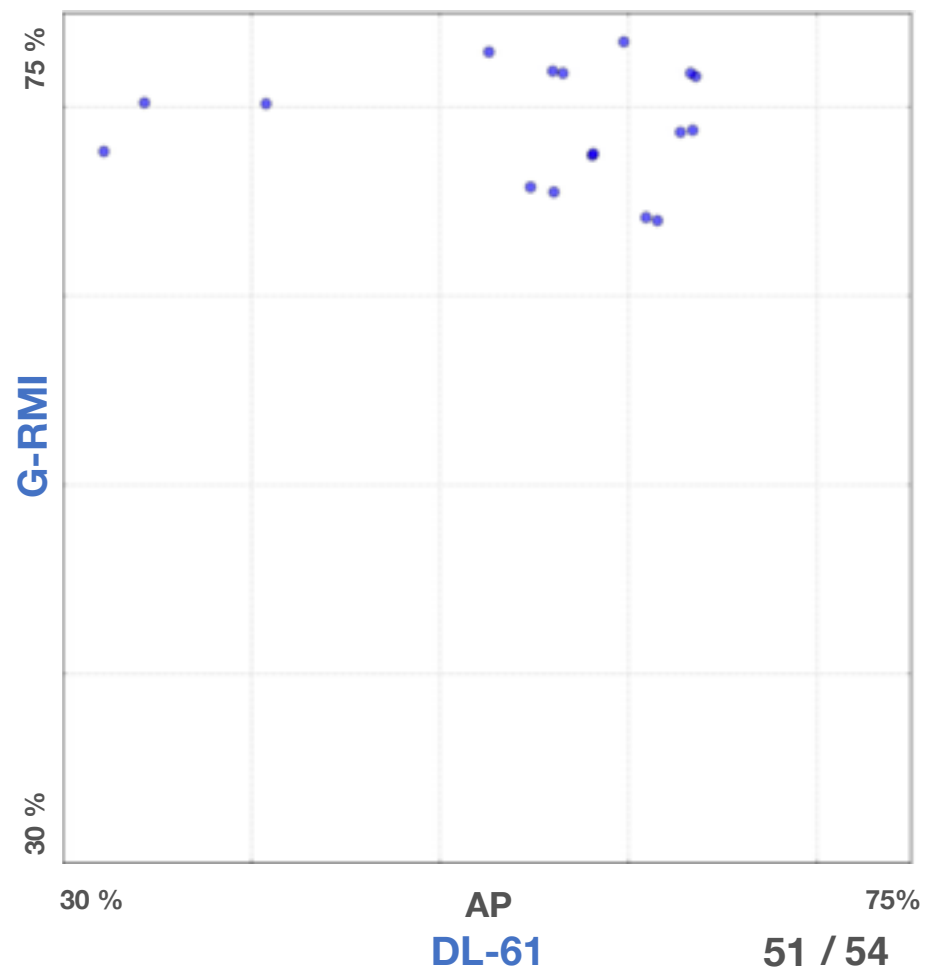
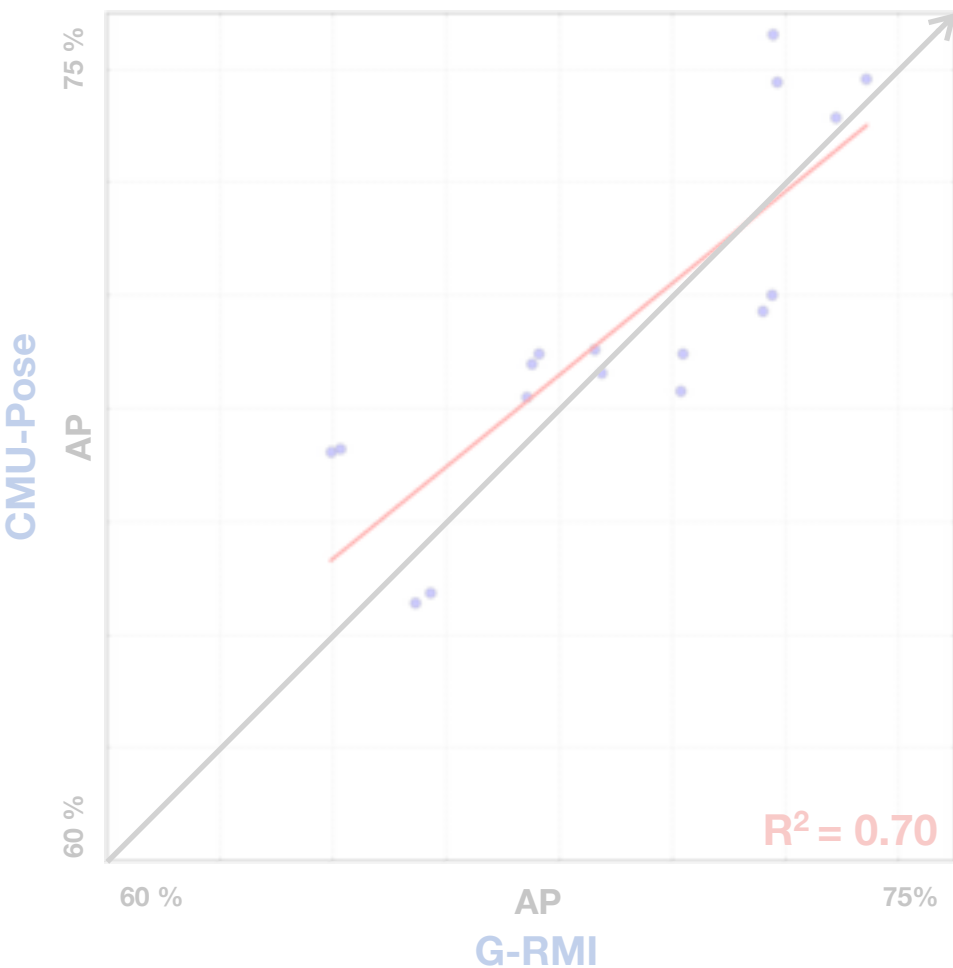
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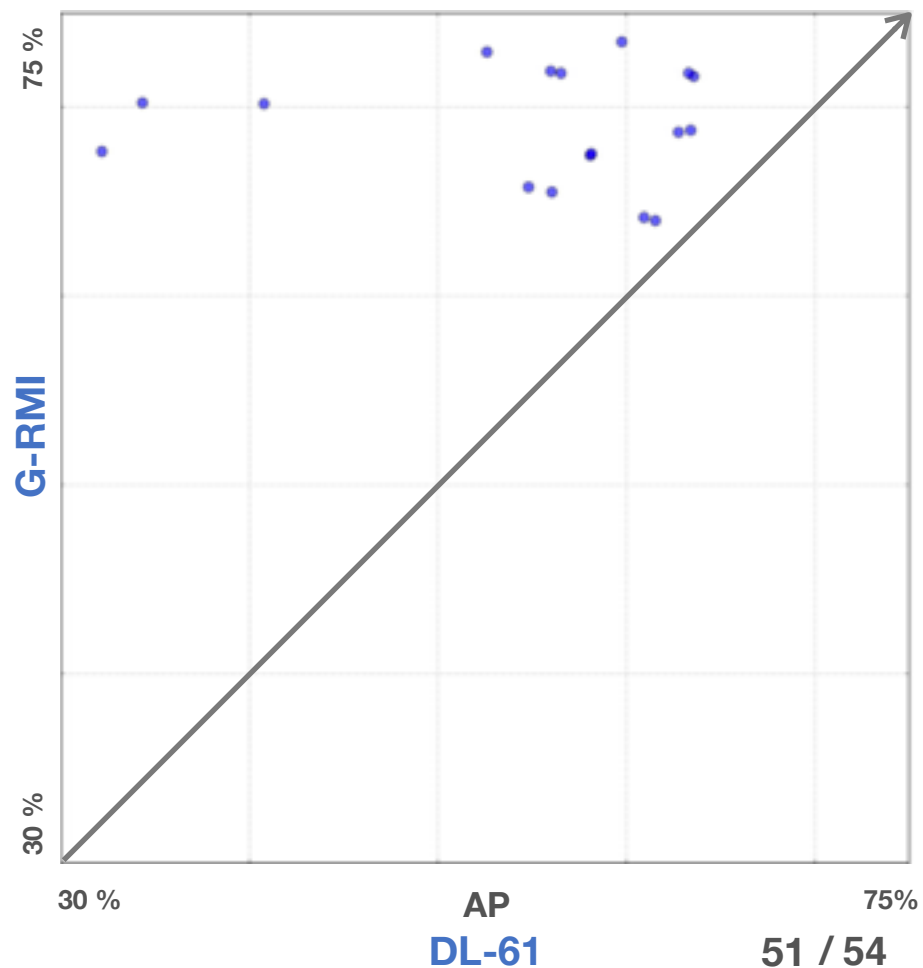
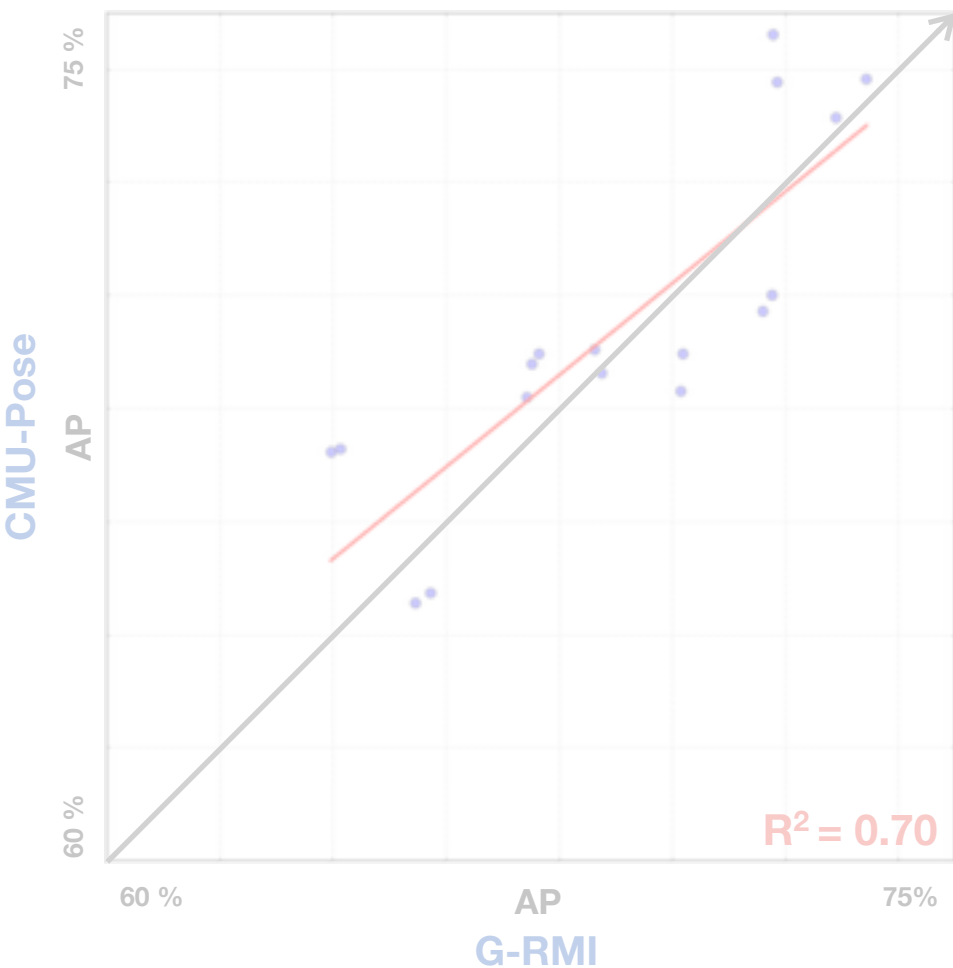
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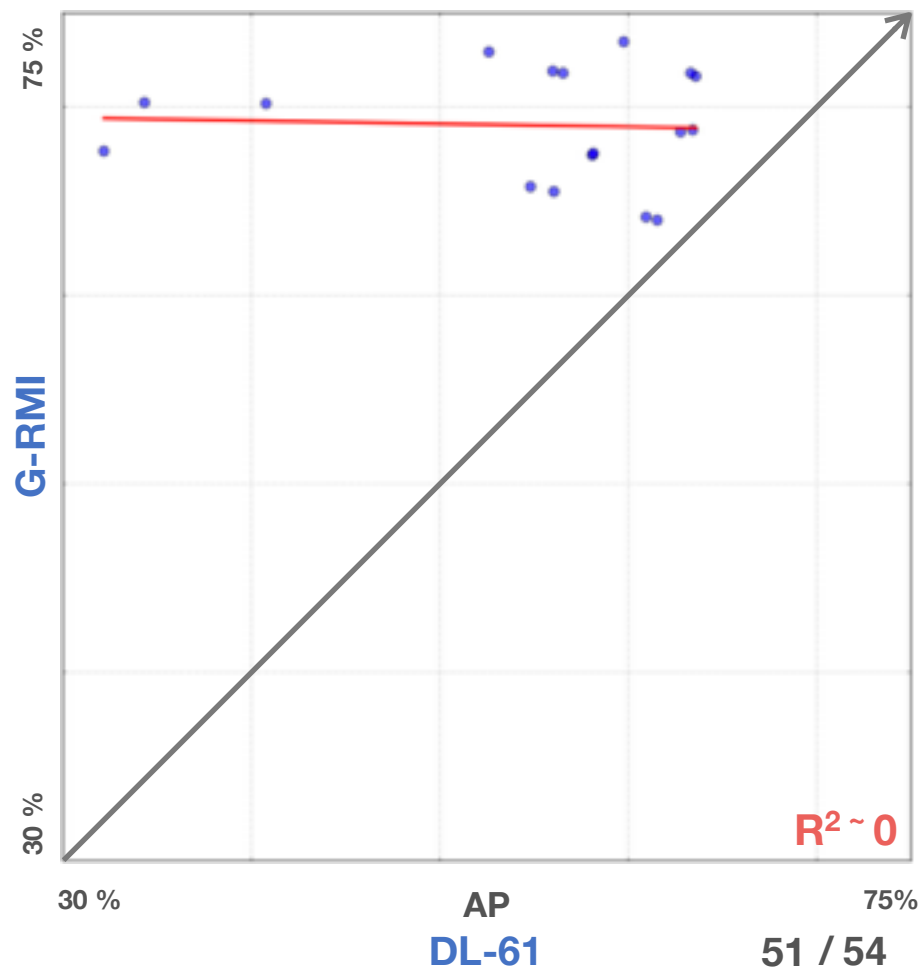
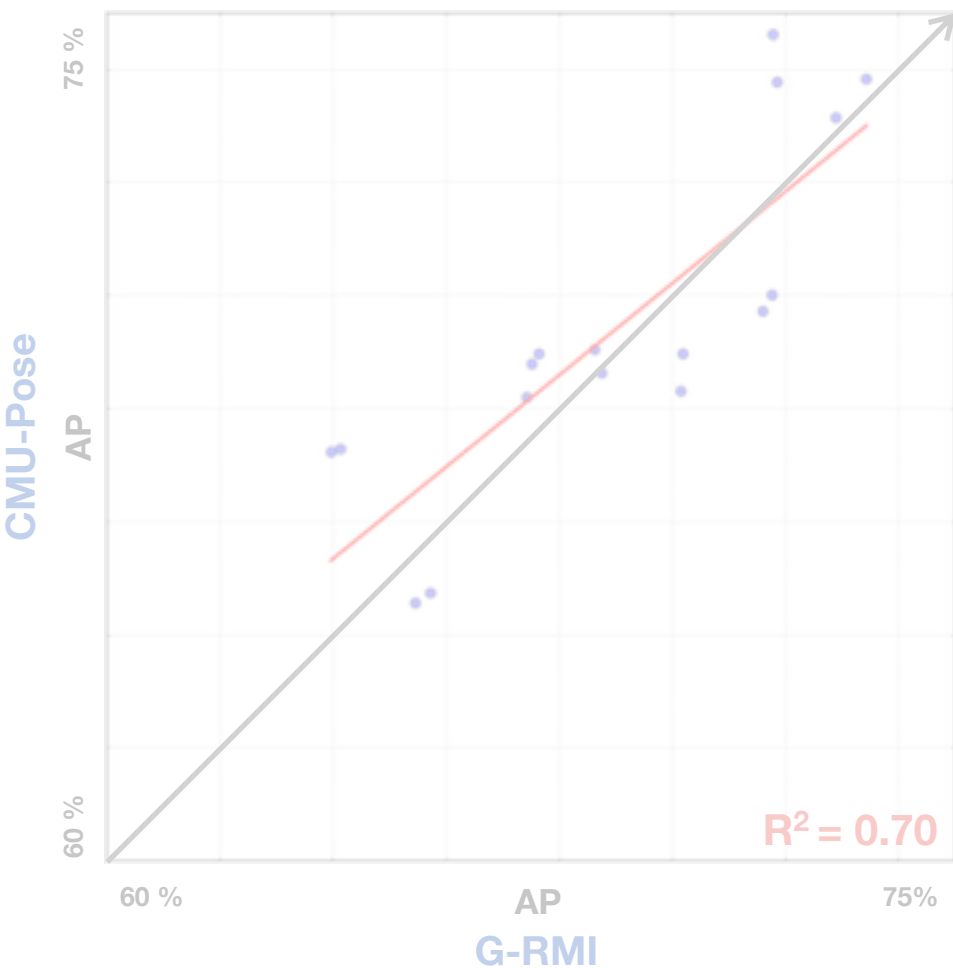
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Types of Keypoint Errors



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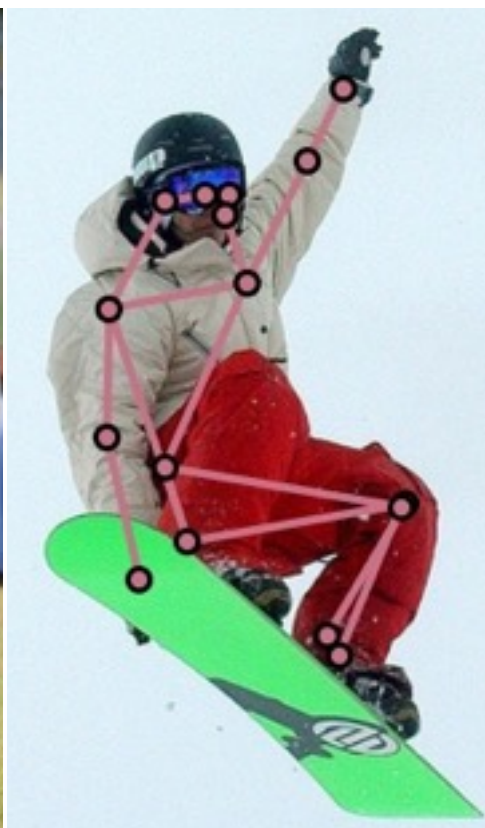
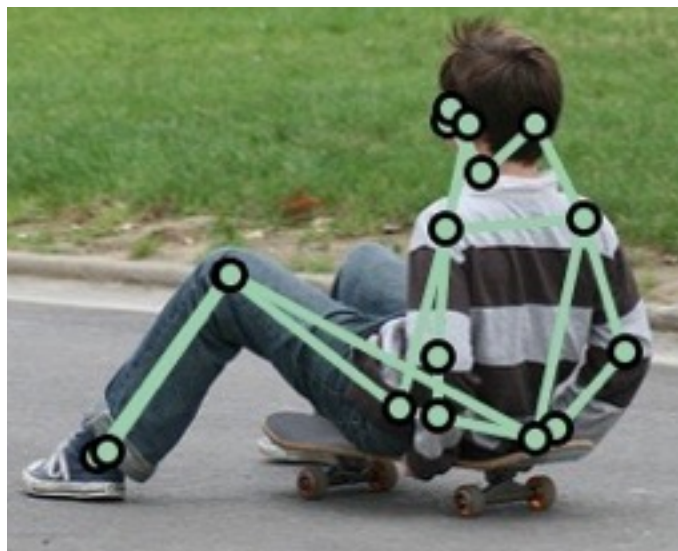
Excusable false positives.





Types of Keypoint Errors

Errors with high OKS impact.





Types of Keypoint Errors

Errors with low OKS impact.





Summary of Findings



Summary of Findings

2016 Keypoint Challenge Take-aways



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- OKS is a new distance metric designed to equalize contribution of all keypoints.



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- Localization errors are predominant.



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2016 Keypoint Challenge Take-aways

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2016 Keypoint Challenge Take-aways

- OKS is a new distance metric designed to equalize contribution of all keypoints.
- Localization errors are predominant.
- Size of instances is impactful on performance.
- Performance can vary greatly across different keypoint sets.



Summary of Findings

2016 Keypoint Challenge Take-aways

- OKS is a new distance metric designed to equalize contribution of all keypoints.
- Localization errors are predominant.
- Size of instances is impactful on performance.
- Performance can vary greatly across different keypoint sets.
- Human baselines are coming soon!



Challenge Ranking



Challenge Ranking

Team	Keypoints
CMU-Pose	1 st
G-RMI	2 nd
DL-61	3 rd



Challenge Ranking

Team	Keypoints
CMU-Pose	1 st
G-RMI	2 nd
DL-61	3 rd

Invited Speakers:

- CMU-Pose / (4:00pm - 4:15pm)
- G-RMI / (4:15pm - 4:30pm)