



Abstract

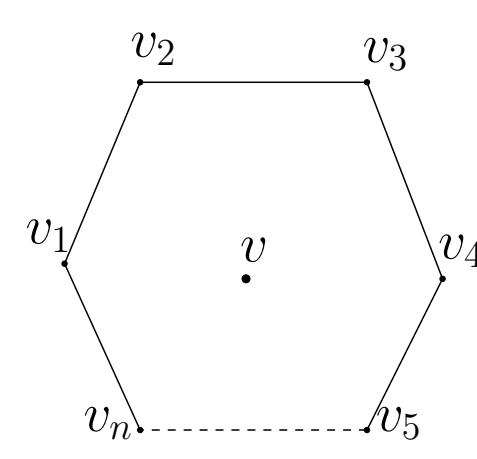
We present a modification of mean value coordinates that is based on the observation that the mean value coordinates of some point v inside a polygon can be negative if the central projection of the polygon onto the unit circle around v folds over. By iteratively smoothing the projected polygon and carrying over this smoothing procedure to the barycentric coordinates of v , these fold-overs as well as the negative coordinate values and shape deformation artefacts gradually disappear, and are guaranteed to completely vanish after a finite number of iterations.

Generalized barycentric coordinates (GBCs)

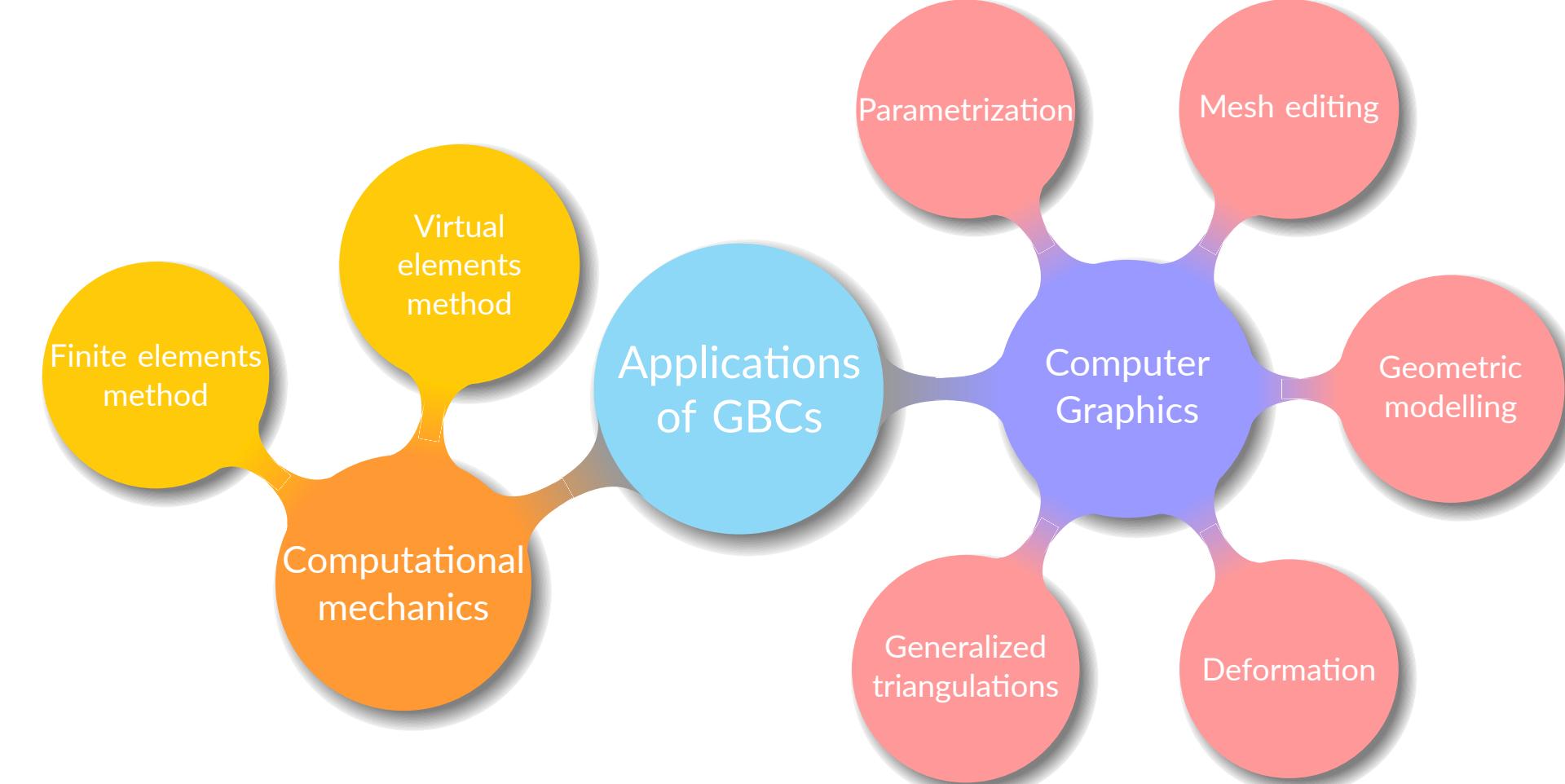
Given a polygon Ω with n vertices v_1, v_2, \dots, v_n and any $v \in \Omega$, find coordinates $\lambda(v) = [\lambda_1(v), \lambda_2(v), \dots, \lambda_n(v)]^T$ such that

$$\sum_{i=1}^n \lambda_i = 1,$$

$$\sum_{i=1}^n \lambda_i v_i = v.$$



- When the $n > 3$, such λ are usually not unique.



All these applications share a common data interpolation task. Given $f_1, \dots, f_n \in \mathbb{R}^m$ at the vertices v_1, \dots, v_n of a polytope $\Omega \subset \mathbb{R}^d$ with $n \geq d + 1$, these application utilize the barycentric interpolant

$$f : \Omega \rightarrow \mathbb{R}^m, \quad f(v) = \sum_{i=1}^n \lambda_i(v) f_i,$$

where the function $\lambda_i : \Omega \rightarrow \mathbb{R}$, $i = 1, \dots, n$ are *generalized barycentric coordinates* with most or even all of the following properties:

- Partition of unity: $\sum_{i=1}^n \lambda_i(v) = 1$ for $v \in \Omega$;
- Linear reproduction: $\sum_{i=1}^n \lambda_i(v) v_i = v$ for $v \in \Omega$;
- Lagrange property: $\lambda_i(v_j) = \delta_{i,j}$ for $i, j = 1, \dots, n$;
- Non-negativity: $\lambda_i(v) \geq 0$ for $v \in \Omega$ and $i = 1, \dots, n$;
- Smoothness: $\lambda_1(v), \dots, \lambda_n(v)$ vary smoothly with $v \in \Omega$;
- Linearity on the edges: λ_i is linear on the edges of Ω .

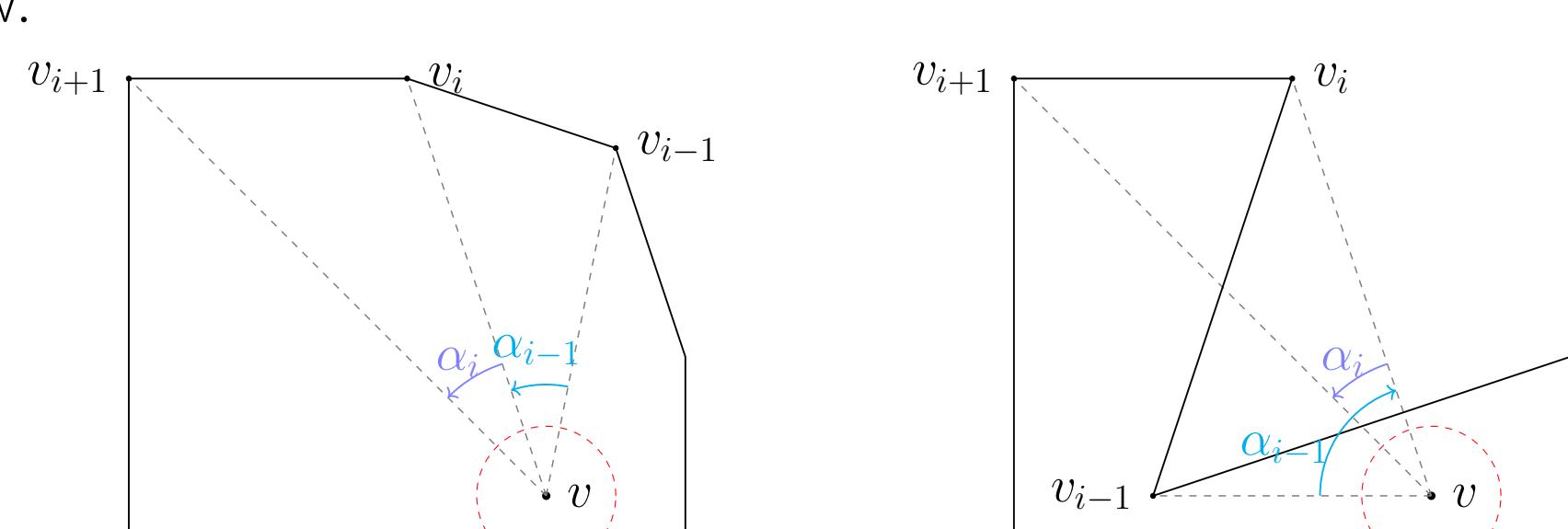
Mean value coordinates (MVCs)

In 2003, inspired by the mean value theorem for harmonic functions, Floater [1] derived *mean value coordinates* (MVCs), which are defined as

$$w_i(v) = \frac{\tan(\frac{\alpha_{i-1}}{2}) + \tan(\frac{\alpha_i}{2})}{\|v_i - v\|}, \quad (1)$$

$$\lambda_i(v) = w_i(v) / \sum_{j=1}^n w_j(v), \quad (2)$$

where $\alpha_i \in (-\pi, \pi]$ and $\|v_i - v\|$ denote the signed angle from edge $\overline{vv_i}$ to $\overline{vv_{i+1}}$ and the length of the segment $\overline{vv_i}$ respectively, see below.



It follows from (1) and (2) that MVCs may possess negative values, if $\alpha_{i-1} + \alpha_i < 0$, which may occur for concave polygons (above right), but they are always positive inside convex polygons.

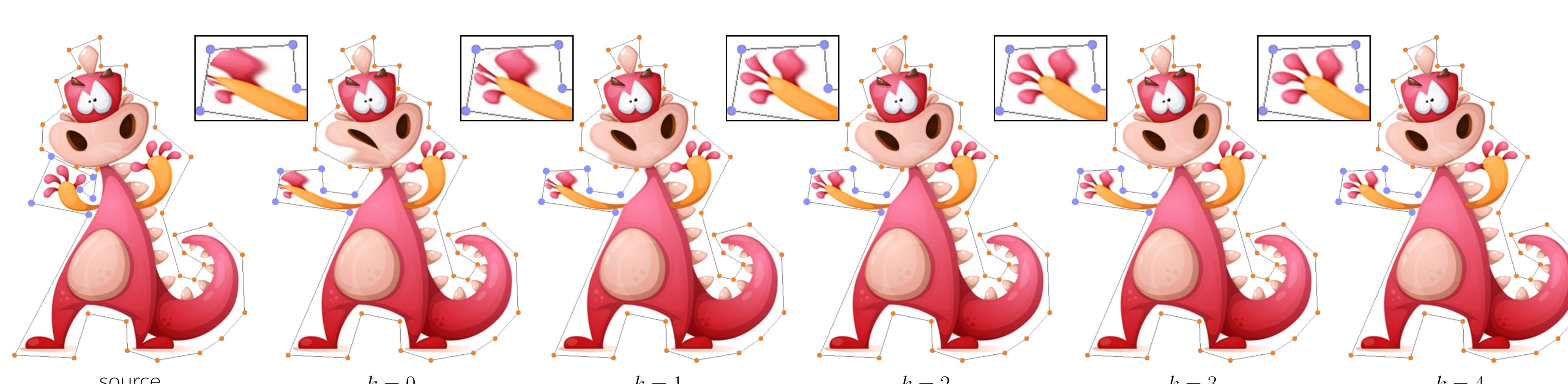


Figure 6: Deformation of a source image (left), obtained by moving six vertices (blue) of the control polygon. The deformation based on mean value coordinates ($k = 0$) exhibits severe artefacts, caused by negative coordinate values. Using iterative coordinates, these deformation artefacts gradually disappear as the number of iterations increases ($k = 1, 2, 3, 4$).

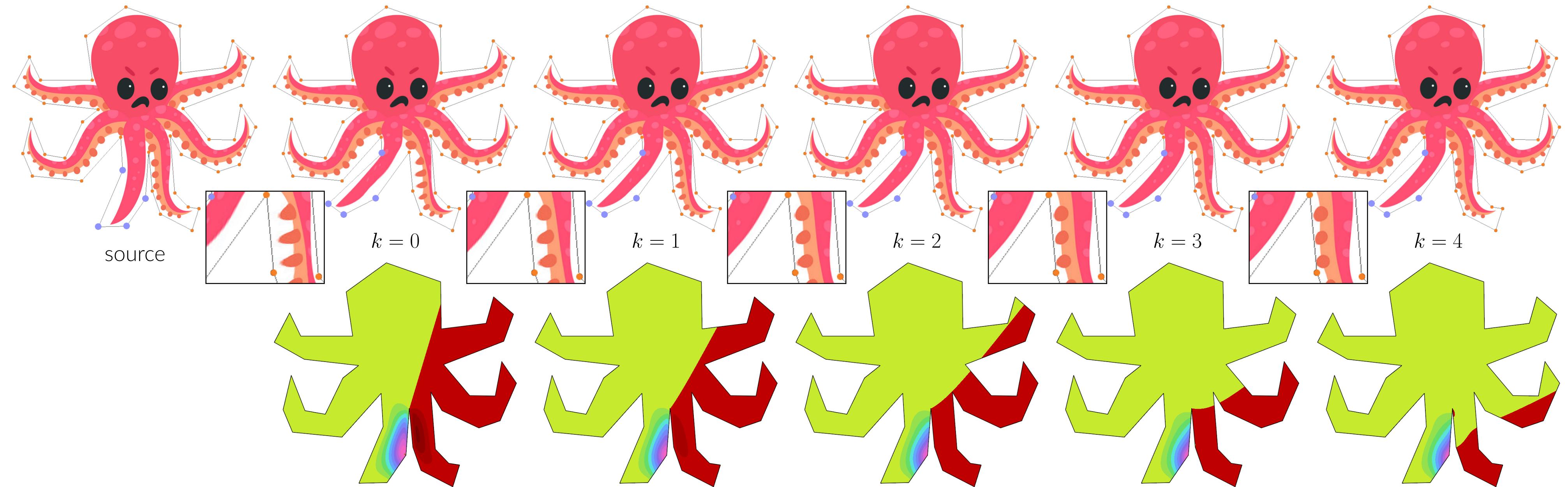


Figure 1: Deformation of a source image (left), obtained by moving four vertices (blue) of the control polygon, using iterative coordinates with respect to the source control polygon (top row). The deformation artefacts (see close-ups) are caused by the negative values (red) of the indicated coordinate function (bottom row), which are relatively large for mean value coordinates (i.e., $k = 0$), but quickly become negligible as the number of iterations increases (see $k = 1, 2, 3, 4$). Function values are visualized using the colour bar in Figure 4.

Iterative coordinates

We found a novel and easy-to-implement construction of *generalized barycentric coordinates* that is based on mean value coordinates and an iterative process. These *iterative coordinates* are guaranteed to be positive after a sufficient number of iterations.

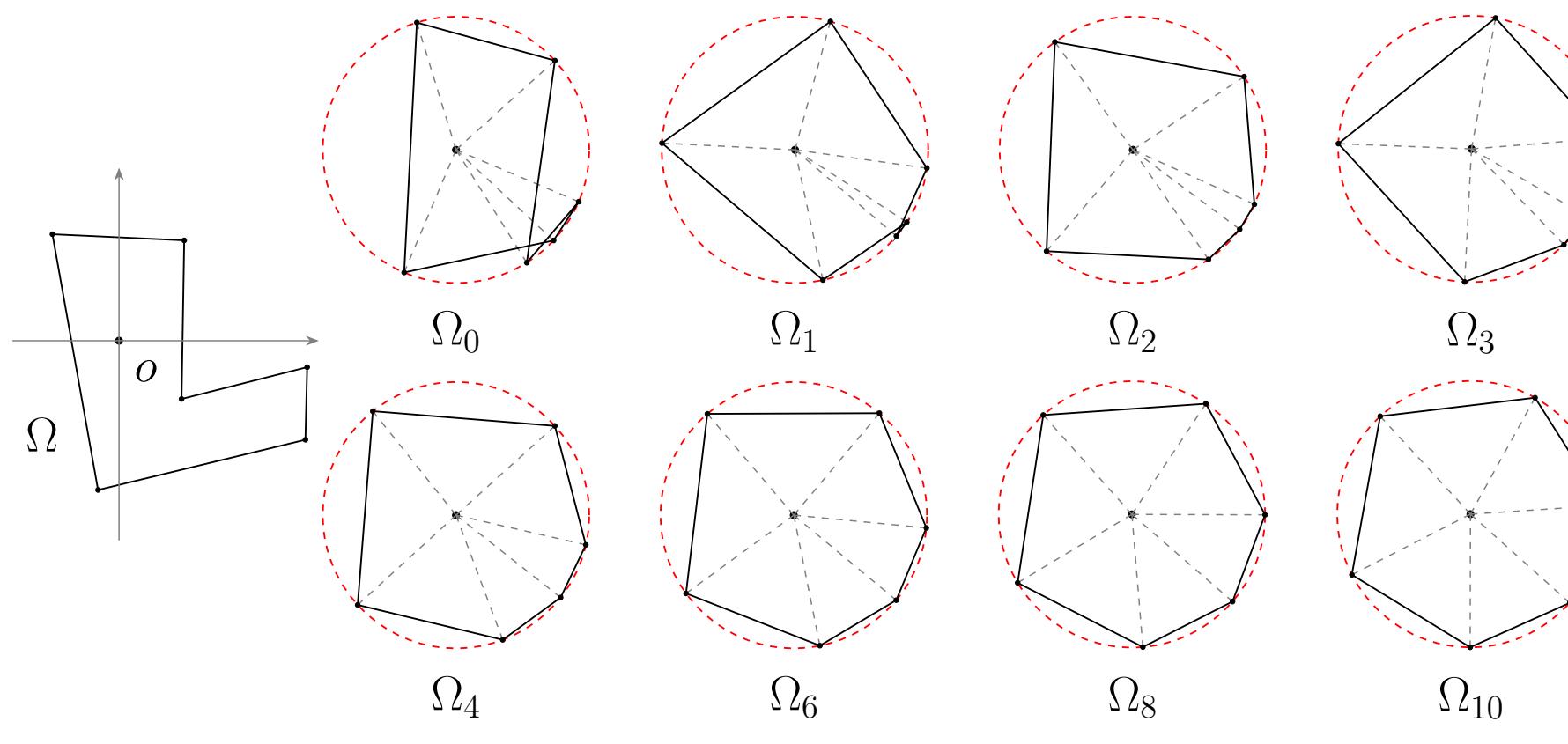


Figure 2: Illustration of the iterative process.

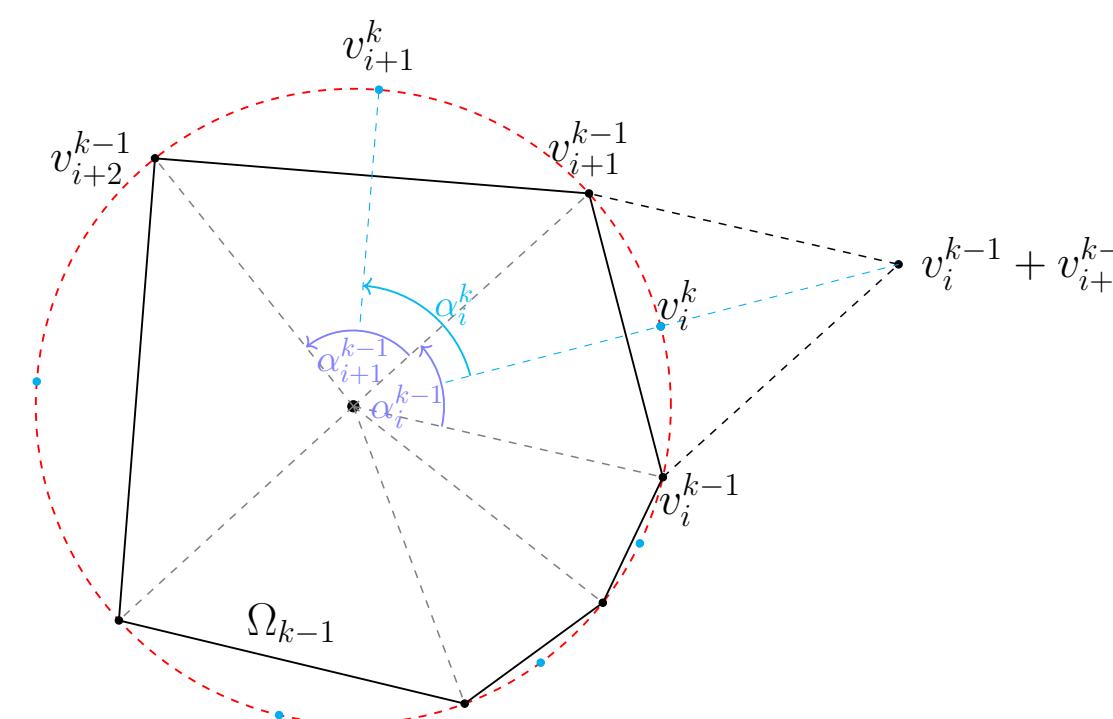


Figure 3: Iteration rules (untangle).

Given a simple polygon Ω with vertices $\mathbf{v} = [v_1, \dots, v_n]$ and a point v inside the polygon, we first shift the polygon Ω so that the point v becomes the origin O . Then we project the polygon Ω onto the unit circle centred at O and get a new polygon Ω_0 with vertices \mathbf{v}^0 on the unit circle. Next, we iteratively "smooth" the polygon Ω_0 as follows. Given Ω_{k-1} with vertices \mathbf{v}^{k-1} , we update the polygon by projecting the midpoints between every two adjacent points onto the unit circle as the new points of Ω_k , see Figure 3 and Figure 2. Defining the transformation matrix $\hat{\mathbf{T}} = \text{diag}\{1/r_1, 1/r_2, \dots, 1/r_n\}$ and

$$\mathbf{T}_k = \begin{bmatrix} 1 & & & \\ 1 & 1 & & \\ & 1 & 1 & \\ & & \ddots & \ddots \end{bmatrix} \begin{bmatrix} 1/r_1^k & & & \\ & 1/r_2^k & & \\ & & \ddots & \\ & & & 1/r_n^k \end{bmatrix}, \quad (3)$$

where $r_i = \|v_i\|$ and $r_i^k = \|v_i^k + v_{i+1}^k\|$.

- Projection: $\mathbf{v}^0 = \mathbf{v}^T$
- Untangle: $\mathbf{v}^k = \mathbf{v}^{k-1} \mathbf{T}_{k-1}$, $k = 1, 2, \dots$
- ⇒ $\mathbf{v}^k = \mathbf{v} \underbrace{\mathbf{T} \mathbf{T}_0 \mathbf{T}_1 \dots \mathbf{T}_{k-1}}_{\mathbf{T}} = \mathbf{v} \mathbf{T}$

After k iterations, we find the mean value coordinates $\hat{\mathbf{w}}$ of the v with respect to Ω_k . That is

$$\mathbf{w}^k = \mathbf{T} \hat{\mathbf{w}},$$

$$\lambda_i^k = w_i^k / \sum_j w_j^k.$$

Experiments and results

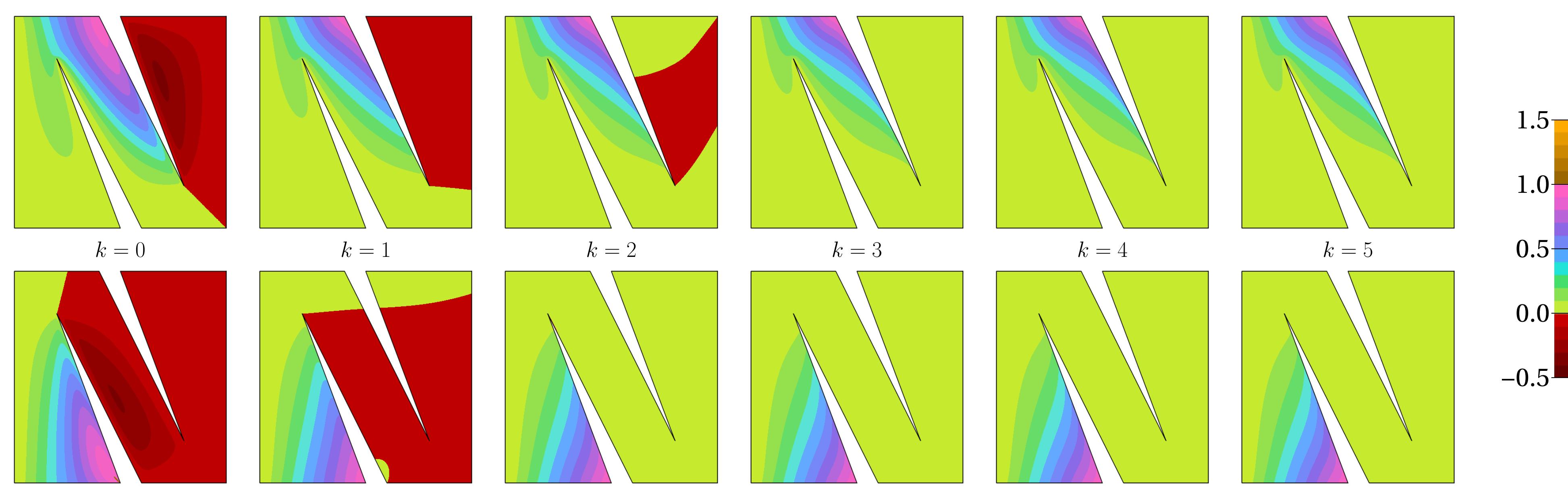


Figure 4: Comparison of iterative coordinates of two vertices (row-wise) for different values of k for a concave polygon.

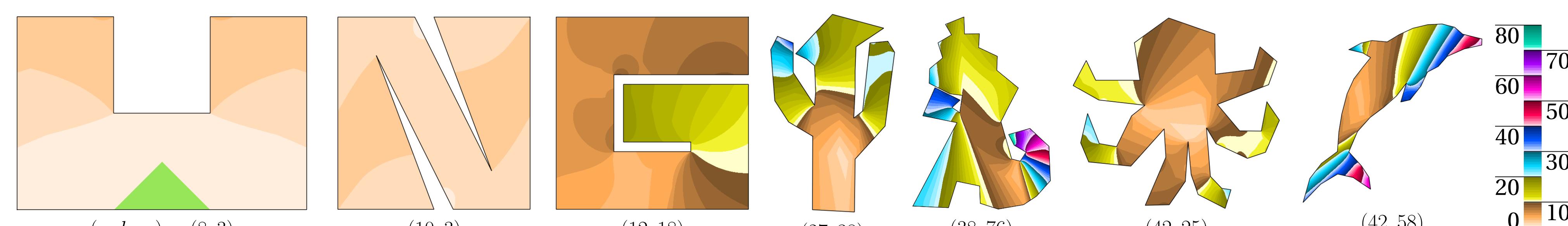


Figure 5: Examples of concave polygons with different numbers of n vertices, for which the iterative coordinates are non-negative after the stated number of k_{\min} iterations (determined by regularly sampling the polygon's bounding square and computing the coordinates for the interior sample points in double precision at a resolution of $10^3 \times 10^3$ for the whole square and an effective resolution of $10^6 \times 10^6$ in the regions where the largest number of iterations is needed). The colour-coding refers to the number of iterations required to get positive coordinates at the individual interior points.

Limitations

- Iterative coordinates do not have a simple closed form.
- We have not yet determined the minimum number of iterations K required to guarantee non-negativity.

Acknowledgements

- NSFC: 61872121, 61761136010
- SNSF: 200021-188577

References

- [1] Michael S. Floater. Mean value coordinates. *Computer Aided Geometric Design*, 20(1):19–27, 2003.

