

15.455x Mathematical Methods of Quantitative Finance

Week 8: Optimization

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Finance at MIT

Where ingenuity drives results

Critical points

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Taylor's theorem

Recall that for a function of a single variable, Taylor's theorem

$$f(x) = f(x_0) + (x - x_0)f'(x_0) + \frac{1}{2!}(x - x_0)^2 f''(x_0) + \frac{1}{3!}(x - x_0)^3 f'''(x_0) + \cdots$$

means that near a **critical point** where the first derivative vanishes,

$$f(x) - f(x_0) \approx \frac{1}{2}f''(x_0)(x - x_0)^2, \quad \text{provided } f''(x_0) \neq 0$$

In higher dimensions, this approximation generalizes so that the neighborhood of a critical point is described by a **quadratic form**.

Taylor's theorem

- For a function of several variables,

$$f(\mathbf{x}) = f(\mathbf{x}_0) + (\nabla f)^\top (\mathbf{x} - \mathbf{x}_0) + \frac{1}{2}(\mathbf{x} - \mathbf{x}_0)^\top Q(\mathbf{x} - \mathbf{x}_0) + \cdots,$$

$$\text{where } \nabla f = \begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \vdots \end{pmatrix}, \quad Q = \begin{pmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} & \cdots \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} & \cdots \\ \vdots & \vdots & \ddots \end{pmatrix} = Q^\top$$

so that

$$f(\mathbf{x}) - f(\mathbf{x}_0) \approx \frac{1}{2}(\mathbf{x} - \mathbf{x}_0)^\top Q(\mathbf{x} - \mathbf{x}_0)$$

where the matrix Q of second derivatives is a symmetric matrix.

Critical points: eigenvalues determine type

- If the **eigenvalues** of Q are all **positive**, the function is convex up and the critical point is a **minimum**.
- If the eigenvalues of Q are all **negative**, the function is concave and the critical point is a **maximum**.
- If Q has both positive and negative eigenvalues, then there are **saddle points**, which are both maximum and minimum, along different directions.
- If any eigenvalues are zero, there are **flat directions**.
- The **eigenvectors** determine the axes of orientation

Critical points

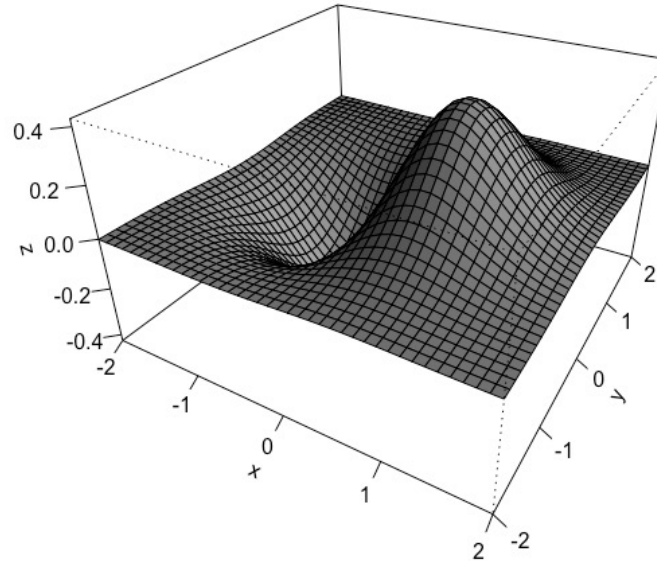
- Classification of critical points for continuous functions

```
f <- function(x,y) x*exp(-x^2-y^2)

x <- seq(-2,2, length=40)
y <- seq(-2,2, length=40)
z <- outer(x,y,f)

persp(x,y,z,
      theta=30, phi=30, expand=0.6,
      col='gray', shade=0.75,
      ltheta=120,
      ticktype='detailed')

filled.contour(x,y,z, nlevels=9,
              color=gray.colors)
```



$$f(x,y) = x e^{-(x^2+y^2)}$$

Critical points

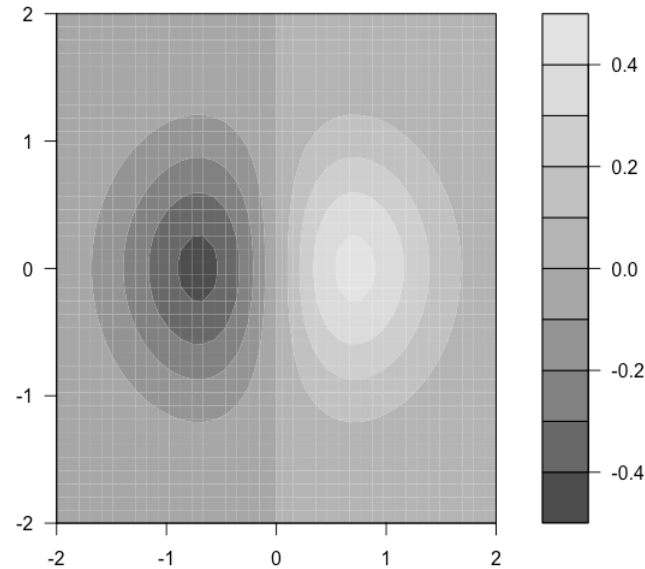
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```

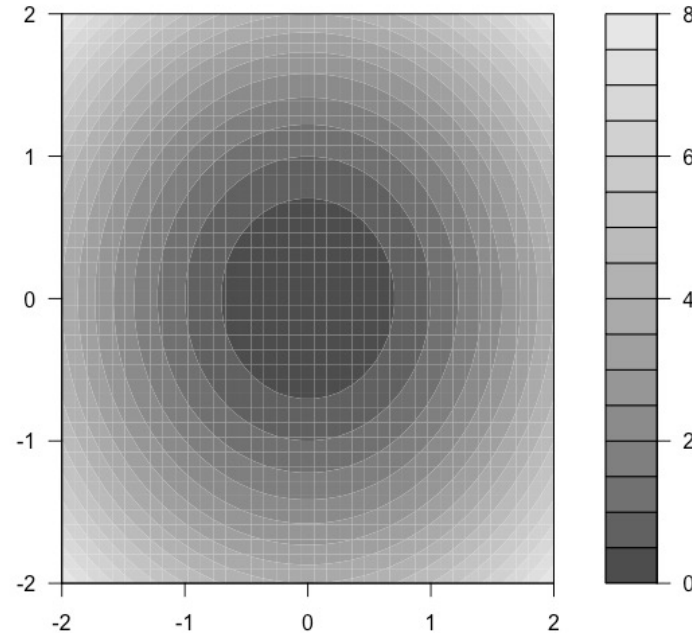


$$f(x, y) = x e^{-(x^2 + y^2)}$$

Critical points

- Classification of critical points for continuous functions

```
f <- function(x,y) x^2 + y^2  
  
z <- outer(x,y,f)  
  
filled.contour(x,y,z, nlevels=17,  
color=gray.colors)  
  
persp(x,y,z,  
theta=30, phi=30, expand=0.6,  
col='gray', shade=0.75,  
ltheta=120,  
ticktype='detailed')
```

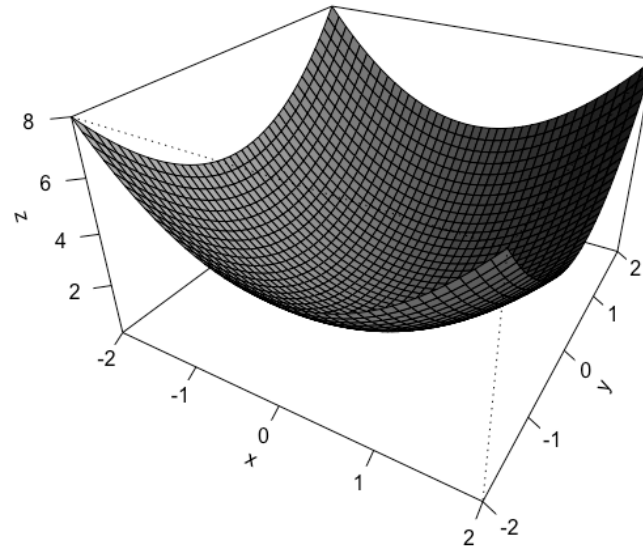


$$f(x, y) = x^2 + y^2$$

Critical points

- Classification of critical points for continuous functions

```
f <- function(x,y) x^2 + y^2  
  
z <- outer(x,y,f)  
  
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color=gray.colors)  
  
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col='gray', shade=0.75,  
ltheta=120,  
ticktype='detailed')
```

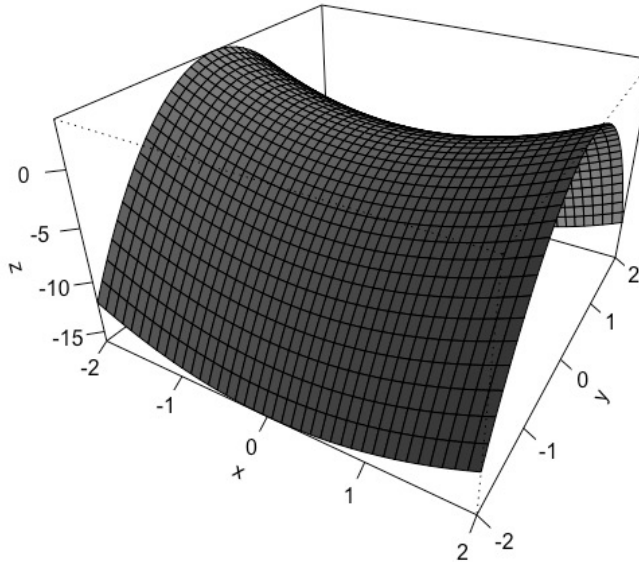


$$f(x, y) = x^2 + y^2$$

Critical points: saddle point

- Classification of critical points for continuous functions

```
f <- function(x,y) x^2 - 4* y^2  
  
z <- outer(x,y,f)  
  
persp(x,y,z,  
      theta=30, phi=30, expand=0.6,  
      col='gray', shade=0.75,  
      ltheta=120,  
      ticktype='detailed')  
  
filled.contour(x,y,z, nlevels=9,  
              color=gray.colors)
```

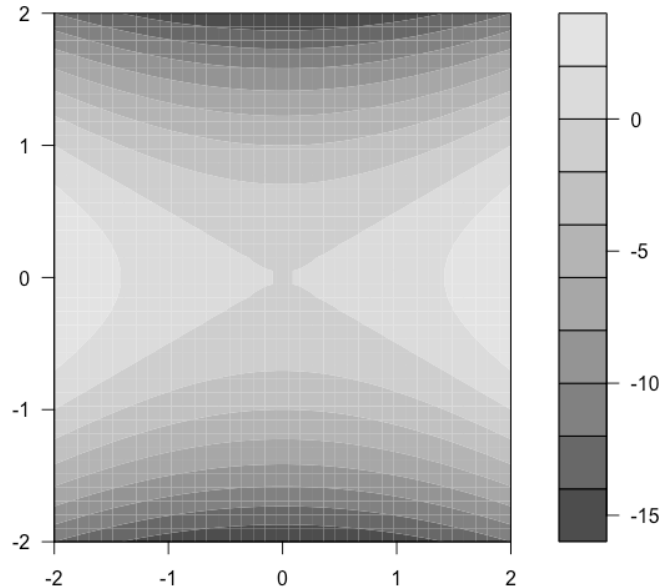


$$f(x, y) = x^2 - 4y^2$$

Critical points: saddle point

- Classification of critical points for continuous functions

```
f <- function(x,y) x^2 - 4* y^2  
  
z <- outer(x,y,f)  
  
persp(x,y,z,  
      theta=30, phi=30, expand=0.6,  
      col='gray', shade=0.75,  
      ltheta=120,  
      ticktype='detailed')  
  
filled.contour(x,y,z, nlevels=9,  
              color=gray.colors)
```

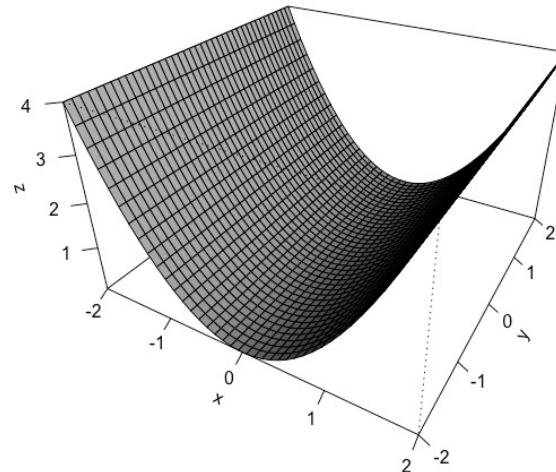


$$f(x, y) = x^2 - 4y^2$$

Critical points: flat directions

- Classification of critical points for continuous functions

```
f <- function(x,y) x^2  
  
z <- outer(x,y,f)  
  
persp(x,y,z,  
      theta=30, phi=30,  
      expand=0.6,  
      col='gray', shade=0.75,  
      ltheta=120,  
      ticktype='detailed')
```



$$f(x, y) = x^2$$

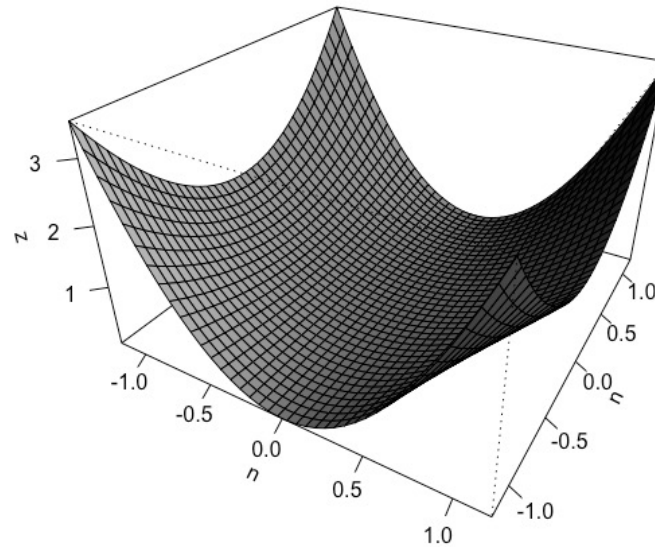
Critical points: symmetry breaking

- Classification of critical points for continuous functions

```
f <- function(x,y) x^2*(1+y^2)

z <- outer(x,y,f)

persp(x,y,z,
      theta=30, phi=30,
      expand=0.6,
      col='gray', shade=0.75,
      ltheta=120,
      ticktype='detailed')
```



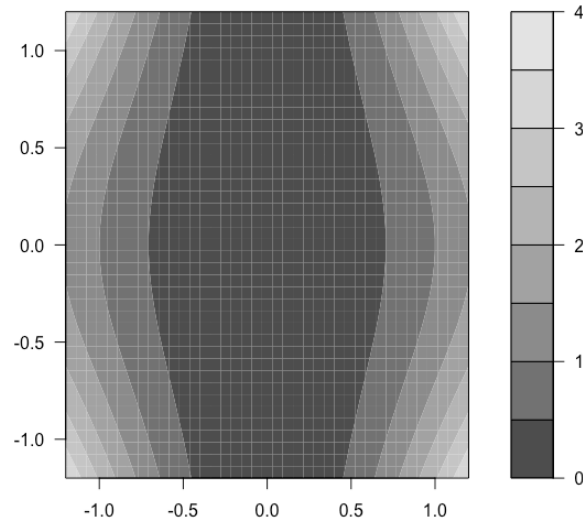
$$f(x,y) = x^2(1+y^2)$$

Critical points: symmetry breaking

- Classification of critical points for continuous functions

```
f <- function(x,y) x^2*(1+y^2)
z <- outer(x,y,f)

persp(x,y,z,
      theta=30, phi=30,
      expand=0.6,
      col='gray', shade=0.75,
      ltheta=120,
      ticktype='detailed')
```



$$f(x,y) = x^2(1+y^2)$$

Constrained optimization and Lagrange multipliers

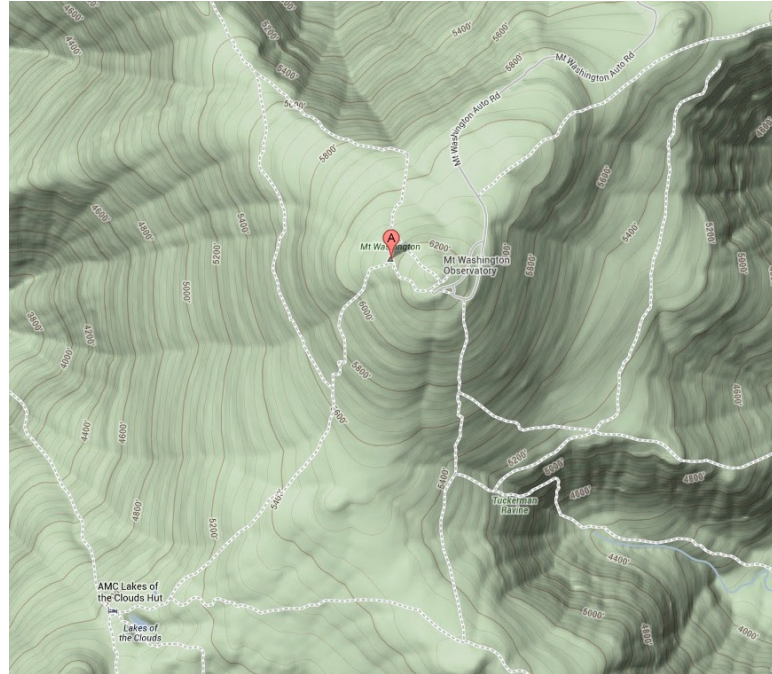
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Maximum along a path

Consider the height function $h(x,y)$ around Mt. Washington

- **Contour lines** are curves of constant h .
- The maximum **along a path** occurs if the path is **tangent** to a contour line: the height will be stationary.



Lagrange multipliers

This observation leads to the method of Lagrange multipliers for solving **constrained optimization** problems.

- Let h and g be continuous, differentiable functions. Consider the extrema of $h(x,y)$, subject to the **constraint** $g(x,y) = c$, where c is a constant.
- Define the **Lagrange function**

$$L(x, y, \lambda) \equiv h(x, y) - \lambda(g(x, y) - c)$$

- The extrema occur where **all the partial derivatives** of L vanish.

$$\frac{\partial L}{\partial x} = \frac{\partial L}{\partial y} = \frac{\partial L}{\partial \lambda} = 0 \iff \nabla h \propto \nabla g$$

the direction of my constraint is along the direction of the level sets

Lagrange multiplier method

- Introduce one constant, called a **Lagrange multiplier**, per constraint.
- Define Lagrange function, linear in constraints
 - Depends on **more variables** than original function
 - Has **simpler** solution (compared to alternatives like elimination)
 - Constraint function is not unique, need not be linear itself
- Find all critical points.
- Substitute and verify that they solve the problem. Often the **location** of an extremum is more interesting than its **value**.

Lagrange multipliers: example

$$h(x, y) = x + y,$$

$$g(x, y) = x^2 + y^2 = r^2,$$

$$L(x, y, \lambda) = x + y - \lambda(x^2 + y^2 - r^2).$$

$$\frac{\partial L}{\partial x} = 1 - 2\lambda x = 0 \implies x = \frac{1}{2\lambda},$$

$$\frac{\partial L}{\partial y} = 1 - 2\lambda y = 0 \implies y = \frac{1}{2\lambda} \implies y = x,$$

$$\frac{\partial L}{\partial \lambda} = -x^2 - y^2 + r^2 = 0 \implies x = y = \pm \frac{r}{\sqrt{2}},$$

$$h_{\max} = \sqrt{2}r, \quad h_{\min} = -\sqrt{2}r$$

Lagrange multipliers: example

$$h(x, y) = 8x^2 + 12xy + 17y^2,$$

$$g(x, y) = x^2 + y^2 = 1, \quad (\text{How about } g(x, y) = (x^2 + y^2)^4?)$$

$$L(x, y, \lambda) = 8x^2 + 12xy + 17y^2 - \lambda(x^2 + y^2 - 1).$$

$$\frac{\partial L}{\partial x} = 16x + 12y - 2\lambda x = 0,$$

$$\frac{\partial L}{\partial y} = 12x + 34y - 2\lambda y = 0,$$

$$\frac{\partial L}{\partial \lambda} = -(x^2 + y^2 - 1) = 0.$$

$$\begin{pmatrix} x \\ y \end{pmatrix} = \pm \begin{pmatrix} 1/\sqrt{5} \\ 2/\sqrt{5} \end{pmatrix}, \quad \begin{pmatrix} x \\ y \end{pmatrix} = \pm \begin{pmatrix} -2/\sqrt{5} \\ 1/\sqrt{5} \end{pmatrix}.$$

$$h_{\max} = 20, \quad h_{\min} = 5.$$

Portfolio optimization

- Mean variance optimization
- Start with expected asset mean returns and covariance matrix
 - (Where do these come from?)
 - (Are they well-estimated?)
 - (Log-normal? Robust? Stationary?)
- Constraints, e.g., budget, full-investment, beta, factor exposures.

- *Portfolio returns and variance*

$$\mu_p = \mu^\top \mathbf{w}$$

$$\sigma_p^2 = \mathbf{w}^\top C \mathbf{w}$$

- *Maximize return, minimize risk*

- *Budget constraint*

$$\sum_{i \in P} w_i = 1$$

Portfolio risk

Under the assumption of (log) normal returns,

$$\sigma_p^2 = \mathbf{w}^\top C \mathbf{w} = \sum w_i^2 \sigma_i^2 + 2 \sum_{i < j} w_i w_j \sigma_i \sigma_j \rho_{ij}$$

The **covariance matrix** is

- symmetric
- positive-definite
 - excluding risk-free assets
 - excluding linearly dependent assets

Therefore it defines

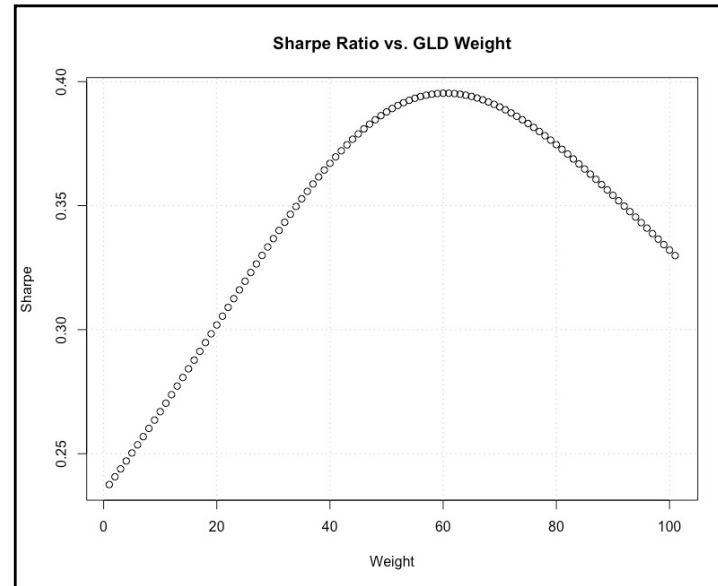
- positive-definite **quadratic form** on W
- **inner product** on W : $\langle \mathbf{w}, \mathbf{w}' \rangle \equiv \mathbf{w}^\top C \mathbf{w}' = (C \mathbf{w})^\top \mathbf{w}'$
- norm on W identified with **risk**

Example: two assets

- Estimation from historical data; construction; rebalancing
- Example:
 - Portfolio of SPX and GLD
 - Expected Sharpe ratio vs. past realized Sharpe ratio
 - **Averaging** time series implies rebalancing 50:50

```
port <- r$SPX
for (w in seq(.01,1,.01))
  port <- cbind(port,
    w*r$GLD + (1-w)*r$SPX)

plot(apply(port,2,mean)/apply(port,2,sd)
  *sqrt(252))
```



Portfolio optimization – minimum variance

- Minimum-variance portfolio: All risk, no return

$$\mathcal{L}(\mathbf{w}, \ell) = \frac{1}{2} \mathbf{w}^\top C \mathbf{w} + \ell(1 - \boldsymbol{\iota}^\top \mathbf{w}) \quad \begin{cases} C & \text{covariance matrix} \\ \boldsymbol{\iota} & \text{unit exposure vector,} \\ \ell & \text{Lagrange multiplier} \end{cases} \quad \boldsymbol{\iota} = \begin{pmatrix} 1 \\ 1 \\ \vdots \end{pmatrix}$$

- Solution solves the constrained problem

$$\frac{\partial \mathcal{L}}{\partial w_i} = \frac{\partial \mathcal{L}}{\partial \ell} = 0$$

Portfolio optimization - minimum variance

- Vary the weights:

$$\frac{\partial \mathcal{L}}{\partial w_i} = \sum_j C_{ij} w_j - \ell \iota_i = 0$$

- Solve for the weights by inverting matrix

$$\mathbf{w} = \ell C^{-1} \boldsymbol{\iota}$$

- Solve for and eliminate Lagrange multiplier

$$\boldsymbol{\iota}^\top \mathbf{w} = \ell (\boldsymbol{\iota}^\top C^{-1} \boldsymbol{\iota}) = 1$$

- Solution is $\mathbf{w}_{min} = \ell C^{-1} \boldsymbol{\iota} = \frac{C^{-1} \boldsymbol{\iota}}{\boldsymbol{\iota}^\top C^{-1} \boldsymbol{\iota}},$ assume no co-variance, weight on asset i is proportional to $1/\sigma_i^2$

notice that Lagrange part is eliminated

$$\sigma_{min}^2 = \ell = 1 / (\boldsymbol{\iota}^\top C^{-1} \boldsymbol{\iota})$$

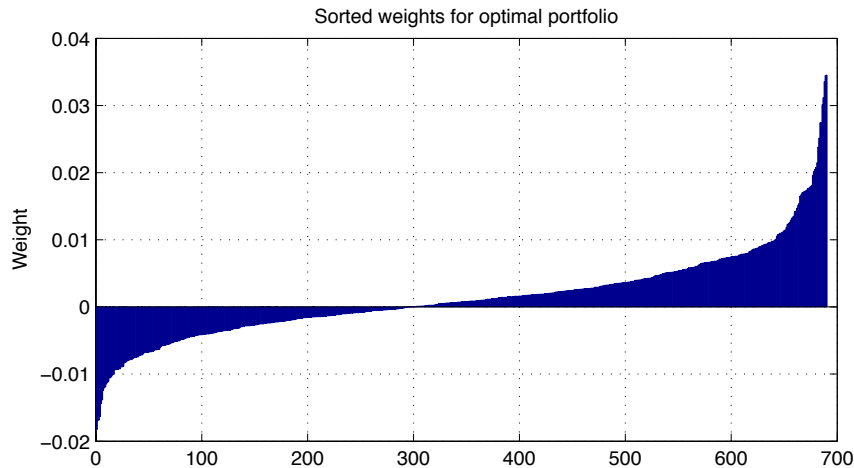
$\mathbf{w}^\top C \mathbf{w}$

Portfolio optimization – minimum variance solution

■ Example:

- CRSP data set of daily returns for 690 US stocks
- Estimate covariance matrix from historical data
- Solve for weights of minimum variance portfolio

```
sigma_min <- sqrt(1/(t(Iota) %*% solve(Covariance) %*% Iota))  
w_min = (solve(Covariance) %*% Iota) %*% sigma_min^2  
sigma_min * sqrt(252) = 0.0436
```



Portfolio optimization - risk & return

- Now let's include return....How much return can we get? How little risk?
- What results are mathematically feasible? Are they achievable in practice?
- Given *any* portfolio, where does it sit relative to the efficient frontier?
- Generalize Lagrange function to for a given level of return that we're demanding, what is the portfolio that has the least amount of risk

$$\mathcal{L}(\mathbf{w}, \ell, m) = \frac{1}{2} \mathbf{w}^\top C \mathbf{w} + \ell(1 - \mathbf{1}^\top \mathbf{w}) + m(\mu_p - \boldsymbol{\mu}^\top \mathbf{w})$$

Budget constraint

Return constraint

Portfolio optimization - risk & return solution

- Vary the weights

$$\frac{\partial \mathcal{L}}{\partial w_i} = \sum_j C_{ij} w_j - \ell \iota_i - m \mu_i = 0$$

- Solve for the weights by inverting the covariance matrix

$$\mathbf{w} = C^{-1}(\ell \boldsymbol{\iota} + m \boldsymbol{\mu})$$

- Solve for Lagrange multipliers by imposing constraints

$$\begin{aligned} \boldsymbol{\iota}^\top \mathbf{w} &= \ell(\boldsymbol{\iota}^\top C^{-1} \boldsymbol{\iota}) + m(\boldsymbol{\mu}^\top C^{-1} \boldsymbol{\iota}) = 1 \\ \boldsymbol{\mu}^\top \mathbf{w} &= \ell(\boldsymbol{\mu}^\top C^{-1} \boldsymbol{\iota}) + m(\boldsymbol{\mu}^\top C^{-1} \boldsymbol{\mu}) = \mu_p \end{aligned} \implies \begin{pmatrix} 1 \\ \mu_p \end{pmatrix} = M \begin{pmatrix} \ell \\ m \end{pmatrix}$$

Portfolio optimization - risk & return solution

- Solve for Lagrange multipliers by inverting 2x2 matrix $M = \begin{pmatrix} a & b \\ b & c \end{pmatrix}$

$$\begin{pmatrix} \ell \\ m \end{pmatrix} = M^{-1} \begin{pmatrix} 1 \\ \mu_p \end{pmatrix}$$

$$\begin{aligned} a &\equiv \iota^\top C^{-1} \iota \\ b &\equiv \mu^\top C^{-1} \iota \\ c &\equiv \mu^\top C^{-1} \mu \end{aligned}$$

- Eliminate Lagrange multipliers to obtain variance as a function of return:

We will show that $\mathbf{w}^\top C \mathbf{w} = (\ell \quad m) M \begin{pmatrix} \ell \\ m \end{pmatrix}$. By the definition of M , $M \begin{pmatrix} \ell \\ m \end{pmatrix} = \begin{pmatrix} 1 \\ \mu_p \end{pmatrix}$, so

$$\sigma_p^2 = \mathbf{w}^\top C \mathbf{w} = (\ell \quad m) M \begin{pmatrix} \ell \\ m \end{pmatrix} \qquad (\ell \quad m) M \begin{pmatrix} \ell \\ m \end{pmatrix} = (\ell \quad m) \begin{pmatrix} 1 \\ \mu_p \end{pmatrix} = \ell + m\mu_p.$$

Because $\mathbf{w} = C^{-1} (\ell \iota + m \mu)$, we have

$$\mathbf{w}^\top C \mathbf{w} = \mathbf{w}^\top C C^{-1} (\ell \iota + m \mu) = \mathbf{w} (\ell \iota + m \mu) = \ell (\iota^\top \mathbf{w}) + m (\mu^\top \mathbf{w}) = \ell + m\mu_p,$$

where the last equality follows from the budget constraint and the return constraint. We can conclude that

$$\mathbf{w}^\top C \mathbf{w} = (\ell \quad m) M \begin{pmatrix} \ell \\ m \end{pmatrix}.$$

Portfolio optimization – risk & return solution

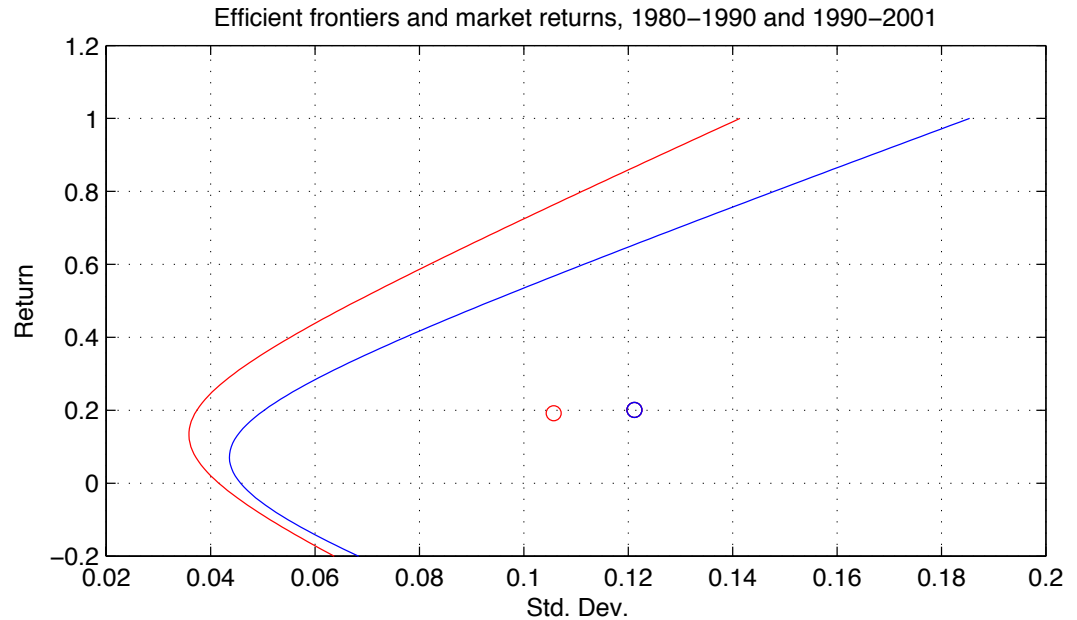
- Results of minimum-variance portfolio for a given return:

$$\sigma_p^2 = \left(\frac{1}{ac - b^2} \right) (a\mu_p^2 - 2b\mu_p + c)$$

- Hyperbola in $\sigma_p - \mu_p$ space
- Asymptotic behavior $\sigma_p \propto \mu_p$ $\mu_p \rightarrow \infty$

Efficient frontier

- Boundary of feasible portfolios
 - Maps N -vectors of weights to 2-dimensional space
- Assumes normal returns, single-period horizons
- Changes over time
- Can always plot non-MVO portfolios in the space of feasible portfolios
- Sensitivity to inputs
- Stability



Characteristic portfolios and the efficient frontier

- Solution for efficient frontier, the set of fully-invested minimum-variance portfolios:

$$\mathbf{w} = C^{-1}(\ell\iota + m\mu)$$

- This is a **linear combination** of two characteristic portfolios, with weights given by the Lagrange multipliers as determined for a given value of expected return.
 - Global minimum variance portfolio
 - Portfolio of maximum Sharpe ratio

Portfolio optimization - with constraints

- If there are additional **linear constraints**, solution is easily generalized... Beta, factor loadings, industry exposure, etc. Add one Lagrange multiplier per constraint.
- If there are range **inequalities** on the weights themselves, then use **quadratic programming**.
- The solution space is a **subset** of unconstrained problem, so set of feasible portfolios lies **inside** unconstrained efficient frontier.
- Example: **long-only**, unlevered portfolio.

- Minimize

$$\mathcal{L}(\mathbf{w}) = \frac{1}{2} \mathbf{w}^\top C \mathbf{w}$$

subject to

$$\sum_i w_i = 1, \quad 0 \leq w_i \leq 1$$

Quadratic programming

- Mean-variance optimization in practice is usually performed under **investment constraints**.
 - Position size (min, max)
 - Leverage
 - Factor exposure
 - Long/short neutrality
 - *VaR, Drawdown,...*
- *Many of these can be handled using quadratic programming.*

R: Solve a Quadratic Programming Problem Find in Topic

solve.QP (quadprog) R Documentation

Solve a Quadratic Programming Problem

Description

This routine implements the dual method of Goldfarb and Idnani (1982, 1983) for solving quadratic programming problems of the form $\min(-d^T b + 1/2 b^T D b)$ with the constraints $A^T b \geq b_0$.

Usage

```
solve.QP(Dmat, dvec, Amat, bvec, meq=0, factorized=FALSE)
```

Arguments

Dmat	matrix appearing in the quadratic function to be minimized.
dvec	vector appearing in the quadratic function to be minimized.
Amat	matrix defining the constraints under which we want to minimize the quadratic function.
bvec	vector holding the values of b_0 (defaults to zero).
meq	the first meq constraints are treated as equality constraints, all further as inequality constraints (defaults to 0).
factorized	logical flag: if TRUE, then we are passing $R^T(-1)$ (where $D = R^T R$) instead of the matrix D in the argument Dmat.

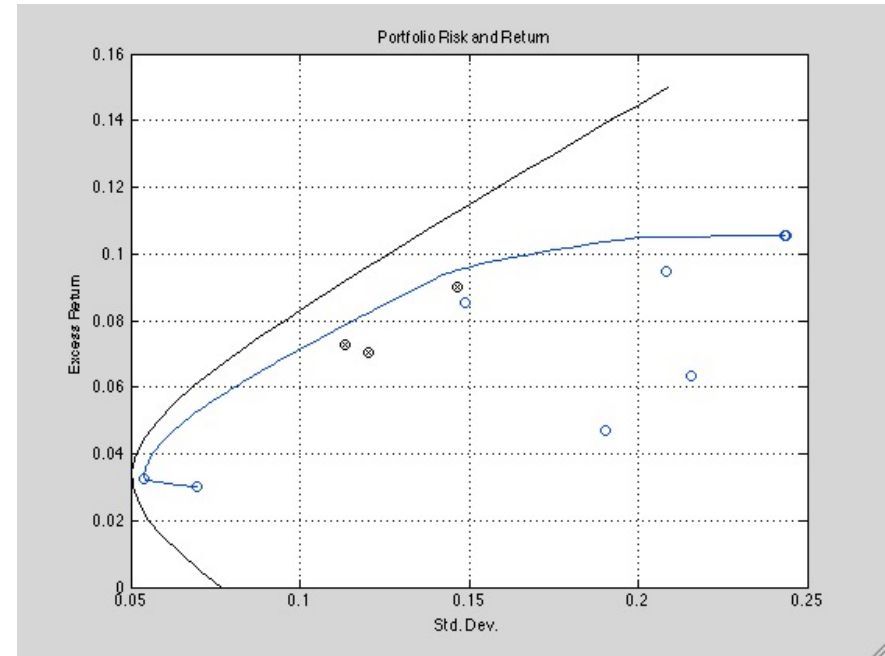
Value

a list with the following components:

solution	vector containing the solution of the quadratic programming
----------	---

Case: Optimal asset allocation

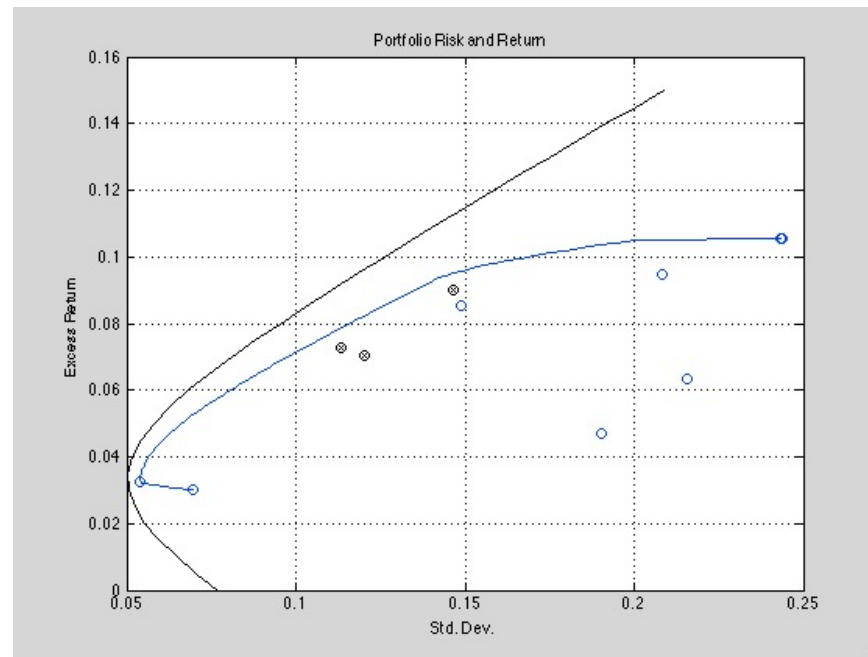
- Country asset allocation
 - 8 assets - blue circles
 - Mean and vol of excess returns
- Unconstrained frontier
 - Black curve
- Constrained mean-variance efficient frontier
 - Blue line
- Typical portfolios
 - Black filled circles
 - Equal, index, "current"



Case: Optimal asset allocation

Of note:

- Constrained frontier **strictly bounded** by min and max mean return of inputs; note endpoint portfolios w/ 100% allocation.
- Some non-optimized portfolios end up near the frontier (e.g., equal weighted) on their own. It is informative to **plot your portfolios** vs. the frontier -- even if they are not constructed with optimization.
- Optimizer is **extremely sensitive** to inputs -- and their errors. In this numerical example, two assets are nearly identical, yet endpoint goes "all in" rather than diversifying; note flatness.



References

- Books

- Campbell, Lo, and MacKinlay (1997) – "*Econometrics of Financial Markets*," Princeton
- Fabozzi, Facardi, and Kolm (2006) – "*Financial Modeling of the Equity Market*," Wiley
- Grinold and Kahn (2000) – "*Active Portfolio Management*," McGraw-Hill
- Michaud (1998) – "*Efficient Asset Management*," Harvard Business School Press