

Advanced Macro II
The reference answer to homework 1

Xuxiu March 30, 2012

Note: The answer is just used for reference.

A simple real business cycle model

Consider the following model where a representative household solves

$$\max_{C_t, K_t} E_0 \left\{ \sum_{t=0}^{\infty} \beta^t [\ln(C_t) - \lambda N_t] \right\} \quad (1)$$

$$C_t + K_t = Z_t K_{t-1}^\theta N_t^{1-\theta} + (1 - \delta) K_{t-1} \quad (2)$$

where C_t, N_t, K_t denote consumption, labor and capital. Z_t is a stochastic process for technology with $\varepsilon_t \sim N(0, \sigma_\varepsilon^2)$, and $0 \leq \rho < 1$. λ, β, θ are parameters with $0 < \beta < 1, 0 < \theta < 1$. It might be useful to define the expression for output as:

$$Y_t = Z_t K_{t-1}^\theta N_t^{1-\theta} \quad (3)$$

1. Describe the economy briefly. Comment on the preference, endowment, technology and information. (1 point)

ANS:

The economic environment:

1) Preference:

$$U = E_0 \left\{ \sum_{t=0}^{\infty} \beta^t [\ln(C_t) - \lambda N_t] \right\}$$

2) Technology:

$$\begin{aligned} C_t + K_t &= Z_t K_{t-1}^\theta N_t^{1-\theta} + (1 - \delta) K_{t-1} \\ \ln Z_t &= (1 - \rho) \ln \bar{Z} + \rho \ln Z_{t-1} + \varepsilon_t \end{aligned}$$

where Z_t is a stochastic process for technology with $\varepsilon_t \sim N(0, \sigma_\varepsilon^2)$, and $0 \leq \rho < 1$.

3) Endowment: $K_{-1} > 0$

4) Information: decision made based on all information I_t up to time t .

2. Find the first order necessary conditions of the representative agent. (2 points)

ANS:

The social planner's problem:

$$\max_{C_t, K_t} E_0 \left\{ \sum_{t=0}^{\infty} \beta^t [\ln(C_t) - \lambda N_t] \right\}$$

$$\begin{aligned} C_t + K_t &= Z_t K_{t-1}^\theta N_t^{1-\theta} + (1 - \delta) K_{t-1} \\ \ln Z_t &= (1 - \rho) \ln \bar{Z} + \rho \ln Z_{t-1} + \varepsilon_t \\ \varepsilon_t &\stackrel{iid}{\sim} N(0, \sigma_\varepsilon^2) \end{aligned}$$

The Lagrangian:

$$L = \max_{(C_t, K_t)_{t=0}^{\infty}} E_0 \sum_{t=0}^{\infty} \left\{ \beta^t [\ln(C_t) - AN_t - \lambda_t (C_t + K_t - Z_t K_{t-1}^{\theta} N_t^{1-\theta} - (1-\delta)K_{t-1})] \right\}$$

The necessary FOCs:

$$\frac{\partial L}{\partial C_t} : 0 \stackrel{!}{=} \frac{1}{C_t} - \lambda_t$$

$$\begin{aligned} \frac{\partial L}{\partial K_t} & : \quad 0 \stackrel{!}{=} \beta^t [-\lambda_t] + \beta^{t+1} E_t [(-\lambda_{t+1}) [-\theta Z_{t+1} K_t^{\theta-1} N_{t+1}^{1-\theta} - (1-\delta)]] \\ \Rightarrow \quad 0 & \stackrel{!}{=} -\lambda_t + \beta E_t [\lambda_{t+1} (\theta Z_{t+1} K_t^{\theta-1} N_{t+1}^{1-\theta} + (1-\delta))] \end{aligned}$$

$$\begin{aligned} \frac{\partial L}{\partial N_t} & : \quad 0 \stackrel{!}{=} -A - \lambda_t [-(1-\theta) Z_t K_{t-1}^{\theta} N_t^{-\theta}] \\ \Rightarrow \quad 0 & \stackrel{!}{=} -A + (1-\theta) \lambda_t Z_t K_{t-1}^{\theta} N_t^{-\theta} \end{aligned}$$

$$\frac{\partial L}{\partial \lambda_t} : 0 \stackrel{!}{=} C_t + K_t - Z_t K_{t-1}^{\theta} N_t^{1-\theta} - (1-\delta)K_{t-1}$$

3. Write down the model in six equations, including output and the langrange multiplier λ_t (0.6 point)

ANS:

Firstly, collect all the necessary coditions and exogenous process:

$$\lambda_t = \frac{1}{C_t}$$

$$Y_t = Z_t K_{t-1}^{\theta} N_t^{1-\theta}$$

$$C_t = Y_t + (1-\delta)K_{t-1} - K_t$$

$$1 = E_t \left[\beta \frac{C_t}{C_{t+1}} \left(\theta \frac{Y_{t+1}}{K_t} + (1-\delta) \right) \right] \text{ or } 1 = E_t \left[\beta \frac{\lambda_{t+1}}{\lambda_t} \left(\theta \frac{Y_{t+1}}{K_t} + (1-\delta) \right) \right]$$

$$A = (1-\theta) \frac{1}{C_t} \frac{Y_t}{N_t} \text{ or } A = (1-\theta) \lambda_t \frac{Y_t}{N_t}$$

$$\ln Z_t = (1-\rho) \ln \bar{Z} + \rho \ln Z_{t-1} + \varepsilon_t, \varepsilon_t \stackrel{iid}{\sim} N(0, \sigma_{\varepsilon}^2)$$

4. Solve for the steady state, i.e. provide formulas for $\bar{C}, \bar{\lambda}, \bar{K}, \bar{N}$ and \bar{Y} ,

given \bar{Z} and other parameters. (Show the steps that you solve these values subsequently.)
(1 point)

ANS:

To find the s.s of economy, drop time indices:

$$\bar{\lambda} = \frac{1}{\bar{C}} \quad (1)$$

$$\bar{Y} = \bar{Z}\bar{K}^\theta \bar{N}^{1-\theta} \quad (2)$$

$$\bar{C} = \bar{Y} + (1 - \delta)\bar{K} - \bar{K} \quad (3)$$

$$1 = \beta \left(\theta \frac{\bar{Y}}{\bar{K}} + (1 - \delta) \right) \quad (4)$$

$$A = (1 - \theta) \frac{1}{\bar{C}} \frac{\bar{Y}}{\bar{N}} \quad (5)$$

Five variables need to be solved for $(\bar{C}, \bar{\lambda}, \bar{K}, \bar{N}, \bar{Y})$ given the parameters $(\bar{Z}, \theta, \delta, A, \rho)$.

firstly from (4), $\frac{\bar{Y}}{\bar{K}} = \frac{1-\beta(1-\delta)}{\beta\theta}$

so $\bar{Y} = \frac{1-\beta+\beta\delta}{\beta\theta} \bar{K}$, substituting into (2) and (3) respectively,

$$\bar{N} = \left(\frac{\beta\theta\bar{Z}}{1-\beta+\beta\delta} \right)^{\frac{1}{\theta-1}} \bar{K}$$

$$\bar{C} = \bar{Y} - \delta\bar{K} = \left(\frac{1-\beta+\beta\delta}{\beta\theta} - \delta \right) \bar{K} = \frac{1-\beta+\beta\delta-\beta\delta\theta}{\beta\theta} \bar{K}$$

Then we solve (5) with the above equations, we can get that

$$\bar{N} = \frac{(1-\theta)(1-\beta+\beta\delta)}{A(1-\beta+\beta\delta-\beta\delta\theta)}$$

$$\bar{K} = \left(\frac{\beta\theta\bar{Z}}{1-\beta+\beta\delta} \right)^{\frac{1}{1-\theta}} \bar{N}$$

$$\bar{Y} = \frac{1-\beta+\beta\delta}{\beta\theta} \bar{K},$$

$$\bar{C} = \bar{Y} - \delta\bar{K}$$

$$\bar{\lambda} = \frac{1}{\bar{C}}$$

5. Now suppose \bar{N} is given, while A needs to be calculated together with $\bar{C}, \bar{\lambda}, \bar{K}, \bar{Y}$. solve for the steady state again. (1 point)

ANS:

If \bar{N} is given, firstly from (4), $\bar{Y} = \frac{1-\beta+\beta\delta}{\beta\theta} \bar{K}$,

substituting into (2), we can get that

$$\bar{K} = \left(\frac{\beta\theta\bar{Z}}{1-\beta+\beta\delta} \right)^{\frac{1}{1-\theta}} \bar{N}$$

$$\bar{Y} = \frac{1-\beta+\beta\delta}{\beta\theta} \bar{K}$$

$$\bar{C} = \bar{Y} - \delta\bar{K}$$

$$\bar{\lambda} = \frac{1}{\bar{C}}$$

$$\bar{A} = (1 - \theta) \frac{\bar{Y}}{\bar{C}\bar{N}}$$

6. Log-linearize the equations. Define log-deviation of variable X_t as $\hat{x}_t = \log X_t / \bar{X}$. Write down all necessary log-linearized equations characterizing the equilibrium in the notation of log-deviation term \hat{x}_t . (2 points)

ANS:

Using $X_t = \bar{X} e^{\hat{x}_t}$ we loglinearize as follows:

Consumption:

$$\begin{aligned}\lambda_t &= \frac{1}{C_t} \\ \bar{\lambda} e^{\hat{\lambda}_t} &= \frac{1}{\bar{C} e^{\hat{c}_t}}\end{aligned}$$

$$\hat{\lambda}_t = -\hat{c}_t$$

Budget constraint:

$$\begin{aligned}C_t &= Y_t + (1 - \delta)K_{t-1} - K_t \\ \bar{C} e^{\hat{c}_t} &= \bar{Y} e^{\hat{y}_t} + (1 - \delta)\bar{K} e^{\hat{k}_{t-1}} - \bar{K} e^{\hat{k}_t} \\ \bar{C} \hat{c}_t &= \bar{Y} \hat{y}_t + (1 - \delta)\bar{K} \hat{k}_{t-1} - \bar{K} \hat{k}_t\end{aligned}$$

$$\hat{c}_t = \frac{\bar{Y}}{\bar{C}} \hat{y}_t + (1 - \delta) \frac{\bar{K}}{\bar{C}} \hat{k}_{t-1} - \frac{\bar{K}}{\bar{C}} \hat{k}_t$$

Euler equation:

$$\begin{aligned}1 &= E_t \left[\beta \frac{C_t}{C_{t+1}} \left(\theta \frac{Y_{t+1}}{K_t} + (1 - \delta) \right) \right] \\ 1 &= E_t \left[\beta \frac{\bar{C} e^{\hat{c}_t}}{\bar{C} e^{\hat{c}_{t+1}}} \left(\theta \frac{\bar{Y} e^{\hat{y}_{t+1}}}{\bar{K} e^{\hat{k}_t}} + (1 - \delta) \right) \right] \\ 1 &= E_t \left[\theta \beta \frac{\bar{Y}}{\bar{K}} e^{\hat{c}_t - \hat{c}_{t+1} + \hat{y}_{t+1} - \hat{k}_t} + (1 - \delta) \beta e^{\hat{c}_t - \hat{c}_{t+1}} \right] \\ 0 &= E_t \left[\theta \beta \frac{\bar{Y}}{\bar{K}} \left(\hat{c}_t - \hat{c}_{t+1} + \hat{y}_{t+1} - \hat{k}_t \right) + (1 - \delta) \beta \left(\hat{c}_t - \hat{c}_{t+1} \right) \right] \\ \text{with } 1 &= \beta \left(\theta \frac{\bar{Y}}{\bar{K}} + (1 - \delta) \right)\end{aligned}$$

$$\hat{c}_t - \theta \beta \frac{\bar{Y}}{\bar{K}} \hat{k}_t = E_t \left[\hat{c}_{t+1} - \theta \beta \frac{\bar{Y}}{\bar{K}} \hat{y}_{t+1} \right]$$

Output:

$$\begin{aligned}Y_t &= Z_t K_{t-1}^\theta N_t^{1-\theta} \\ \bar{Y} e^{\hat{y}_t} &= \bar{Z} e^{\hat{z}_t} \bar{K}^\theta e^{\theta \hat{k}_{t-1}} \bar{N}^{1-\theta} e^{(1-\theta) \hat{n}_t}\end{aligned}$$

$$\hat{y}_t = \hat{z}_t + \theta \hat{k}_{t-1} + (1 - \theta) \hat{n}_t$$

Labor equation:

$$A = (1 - \theta) \frac{1}{C_t} \frac{Y_t}{N_t}$$

$$A = (1 - \theta) \frac{1}{\overline{C} e^{\hat{c}_t}} \frac{\overline{Y} e^{\hat{y}_t}}{\overline{N} e^{\hat{n}_t}}$$

$$\hat{y}_t = \hat{c}_t + \hat{n}_t$$

Technology process

$$\ln \overline{Z} e^{\hat{z}_t} = (1 - \rho) \ln \overline{Z} + \rho \ln \overline{Z} e^{\hat{z}_t} + \varepsilon_t$$

$$\hat{z}_t = \rho \hat{z}_{t-1} + \varepsilon_t.$$

Collect all the four L.L. equations, which form a system of linear and homogeneous equations.

$$\hat{\lambda}_t = -\hat{c}_t$$

$$\hat{c}_t = \frac{\overline{Y}}{\overline{C}} \hat{y}_t + (1 - \delta) \frac{\overline{K}}{\overline{C}} \hat{k}_{t-1} - \frac{\overline{K}}{\overline{C}} \hat{k}_t$$

$$\hat{c}_t - \theta \beta \frac{\overline{Y}}{\overline{K}} \hat{k}_t = E_t \left[\hat{c}_{t+1} - \theta \beta \frac{\overline{Y}}{\overline{K}} \hat{y}_{t+1} \right]$$

$$\hat{y}_t = \hat{z}_t + \theta \hat{k}_{t-1} + (1 - \theta) \hat{n}_t$$

$$\hat{y}_t = \hat{c}_t + \hat{n}_t$$

$$\hat{z}_t = \rho \hat{z}_{t-1} + \varepsilon_t$$

7. Sort all your variables in the above equations, classify what are exogenous state variable, endogenous state variable and other endogenous variables. (0.4 point)

ANS:

The exogenous state variable: \hat{z}_t

The endogenous state variable: \hat{k}_{t-1}

The other endogenous variables: $\hat{c}_t, \hat{y}_t, \hat{n}_t$

8. Now reduce the above equations into three equations with three variables \hat{z}_t, \hat{k}_t and λ_t . Following the instructions step by step: 1) Substitute out \hat{c}_t by λ_t in the log-linearized budget constraint, then combine the linearized FOC of labor and the production function to reduce \hat{n}_t and possibly \hat{y}_t to get the form of equation (5) below. 2) Substitute \hat{n}_t (or \hat{y}_t) depending on your early steps) in the Euler equation to obtain a function of the form (6) below. Please state clearly your steps to get the solutions. Now you can obtain the following two-dimensional stochastic difference equation together with exogenous technology process

$$0 = -\hat{k}_t + a_1\hat{k}_{t-1} + a_2\hat{\lambda}_t + a_3\hat{z}_t \quad (4)$$

$$0 = E_t \left[-\hat{\lambda}_t + a_4\hat{k}_t + a_5\hat{\lambda}_{t+1} + a_6\hat{z}_{t+1} \right] \quad (5)$$

$$\hat{z}_t = \rho\hat{z}_{t-1} + \varepsilon_t \quad (6)$$

what are $a_1, a_2, a_3, a_4, a_5, a_6$ in terms of the original parameters? (3 points)

ANS:

Collect all the focs:

$$\hat{c}_t = \frac{\bar{Y}}{\bar{C}}\hat{y}_t + (1 - \delta)\frac{\bar{K}}{\bar{C}}\hat{k}_{t-1} - \frac{\bar{K}}{\bar{C}}\hat{k}_t \quad (1)$$

$$\hat{y}_t = \hat{z}_t + \theta\hat{k}_{t-1} + (1 - \theta)\hat{n}_t \quad (2)$$

$$\hat{y}_t = \hat{c}_t + \hat{n}_t \quad (3)$$

$$\hat{\lambda}_t = -\hat{c}_t \quad (4)$$

$$\hat{c}_t - \theta\beta\frac{\bar{Y}}{\bar{K}}\hat{k}_t = E_t \left[\hat{c}_{t+1} - \theta\beta\frac{\bar{Y}}{\bar{K}}\hat{y}_{t+1} \right] \quad (5)$$

Firstly, we combine (2) and (3),

$$\hat{y}_t = \frac{1}{\theta}\hat{z}_t + \hat{k}_{t-1} - \frac{(1-\theta)}{\theta}\hat{c}_t \quad (6)$$

substitute (6) into (1) and combining (4),

$$0 = -\hat{k}_t + \left[\frac{\bar{Y}}{\bar{K}} + (1 - \delta) \right] \hat{k}_{t-1} + \left[\frac{\bar{C}}{\bar{K}} + \frac{\bar{Y}}{\bar{K}} \frac{(1-\theta)}{\theta} \right] \hat{\lambda}_t + \frac{\bar{Y}}{\bar{K}} \frac{1}{\theta} \hat{z}_t$$

also, substitute (6) into (5) and combining (4),

$$0 = E_t \left[-\hat{\lambda}_t + \left[1 + (1 - \theta)\beta\frac{\bar{Y}}{\bar{K}} \right] \hat{\lambda}_{t+1} + \beta\frac{\bar{Y}}{\bar{K}}\hat{z}_{t+1} \right]$$

So we can conclude that:

$$a_1 = \frac{\bar{Y}}{\bar{K}} + (1 - \delta)$$

$$a_2 = \frac{\bar{C}}{\bar{K}} + \frac{\bar{Y}}{\bar{K}} \frac{(1-\theta)}{\theta}$$

$$a_3 = \frac{\bar{Y}}{\bar{K}} \frac{1}{\theta}$$

$$a_4 = 0$$

$$a_5 = 1 + (1 - \theta)\beta\frac{\bar{Y}}{\bar{K}}$$

$$a_6 = \beta\frac{\bar{Y}}{\bar{K}}$$

9. According to your results in step 4, calculate steady state values of $\bar{C}, \bar{\lambda}, \bar{K}, \bar{N}$ and \bar{Y} , and calculate a_1 to a_6 given the following parameter values:

$\beta = 0.98, \rho = 0.95, \theta = 0.4, \delta = 0.025, \bar{z} = 1, A = 3.44, \sigma_\epsilon^2 = 0.712.$

Assume that your model parameters are calibrated from quarterly data. (1 point)

ANS:

$$\bar{N} = \frac{(1-\theta)(1-\beta+\beta\delta)}{A(1-\beta+\beta\delta-\beta\delta\theta)} = 0.2237$$

$$\bar{K} = \left(\frac{\beta\theta\bar{Z}}{1-\beta+\beta\delta} \right)^{\frac{1}{1-\theta}} \bar{N} = 8.4043$$

$$\bar{Y} = \frac{1-\beta+\beta\delta}{\beta\theta} \bar{K} = 0.9541$$

$$\bar{C} = \bar{Y} - \delta\bar{K} = 0.7439$$

$$\bar{\lambda} = \frac{1}{\bar{C}} = 1.3442$$

$$a_1 = \frac{\bar{Y}}{\bar{K}} + (1 - \delta) = 1.0885$$

$$a_2 = \frac{\bar{C}}{\bar{K}} + \frac{\bar{Y}}{\bar{K}} \frac{(1-\theta)}{\theta} = 0.2588$$

$$\begin{aligned}
a_3 &= \frac{\bar{Y}}{\bar{K}} \frac{1}{\theta} = 0.2838 \\
a_4 &= 0 \\
a_5 &= 1 + (1 - \theta) \beta \frac{\bar{Y}}{\bar{K}} = 1.0668 \\
a_6 &= \beta \frac{\bar{Y}}{\bar{K}} = 0.1113
\end{aligned}$$

10. According to your results in step 5, calculate steady state values of $A, \bar{C}, \bar{\lambda}, \bar{K}$ and \bar{Y} , and calculate a_1 to a_6 given the following parameter values:

$\beta = 0.98, \rho = 0.95, \theta = 0.4, \delta = 0.025, \bar{z} = 1, \bar{N} = 1/3, \sigma_\epsilon^2 = 0.712$. In what follows, take the parameter values given here. (1 point)

ANS:

$$\bar{K} = \left(\frac{\beta \theta \bar{z}}{1 - \beta + \beta \delta} \right)^{\frac{1}{1 - \theta}} \bar{N} = 12.5244$$

$$\bar{Y} = \frac{1 - \beta + \beta \delta}{\beta \theta} \bar{K} = 1.4218$$

$$\bar{C} = \bar{Y} - \delta \bar{K} = 1.1087$$

$$\bar{\lambda} = \frac{1}{\bar{C}} = 0.9020$$

$$\bar{A} = (1 - \theta) \frac{\bar{Y}}{\bar{C} \bar{N}} = 2.3084$$

$$a_1 = \frac{\bar{Y}}{\bar{K}} + (1 - \delta) = 1.0885$$

$$a_2 = \frac{\bar{C}}{\bar{K}} + \frac{\bar{Y}}{\bar{K}} \frac{(1 - \theta)}{\theta} = 0.2588$$

$$a_3 = \frac{\bar{Y}}{\bar{K}} \frac{1}{\theta} = 0.2838$$

$$a_4 = 0$$

$$a_5 = 1 + (1 - \theta) \beta \frac{\bar{Y}}{\bar{K}} = 1.0668$$

$$a_6 = \beta \frac{\bar{Y}}{\bar{K}} = 0.1113$$

11. Guess the recursive law of motion of the above system in step 8 as:

$$\hat{\lambda}_t = \eta_{\lambda k} \hat{k}_{t-1} + \eta_{\lambda z} \hat{z}_t \quad (7)$$

$$\hat{k}_t = \eta_{kk} \hat{k}_{t-1} + \eta_{kz} \hat{z}_t \quad (8)$$

and exploit $E_t [\hat{z}_{t+1}] = \rho \hat{z}_t$. Using the undetermined coefficient method, insert these expressions into (5) and (6) and collect terms on \hat{k}_{t-1} and \hat{z}_t , to get two transformed equations. (Note that you may insert (8) and (9) twice into (6) to eventually reduce the equation to a function of only \hat{k}_{t-1} and \hat{z}_t . (0.4 point)

ANS:

$$0 = [-\eta_{kk} + a_1 + a_2 \eta_{\lambda k}] \hat{k}_{t-1} + [-\eta_{kz} + a_3 + a_2 \eta_{\lambda z}] \hat{z}_t$$

$$0 = [-\eta_{\lambda k} + a_5 \eta_{\lambda k} \eta_{kk}] \hat{k}_{t-1} + [-\eta_{\lambda z} + a_5 \eta_{\lambda z} \rho + a_5 \eta_{\lambda k} \eta_{kz} + a_6 \rho] \hat{z}_t$$

12. By comparing the coefficients on \hat{k}_{t-1} , you can get a characteristic quadratic equation η_{kk} as $a\eta_{kk}^2 + b\eta_{kk} + c = 0$, where a, b, and c are determined by a_1 to a_6 . What are a, b, and c? Solve this equation, what are the roots? Which root should you choose and why? Use your chosen value of η_{kk} to calculate $\eta_{\lambda k}$. (1.2 points)

ANS:

Comparing the coefficients on \hat{k}_{t-1} ,

$$\begin{cases} -\eta_{kk} + a_1 + a_2\eta_{\lambda k} = 0 \\ -\eta_{\lambda k} + a_5\eta_{\lambda k}\eta_{kk} = 0 \end{cases} \Rightarrow \begin{cases} \eta_{\lambda k} = (\eta_{kk} - a_1)/a_2 \\ (a_5\eta_{kk} - 1)(\eta_{kk} - a_1) = 0 \\ a_5\eta_{kk}^2 - (a_5a_1 + 1)\eta_{kk} + a_1 = 0 \end{cases} \Rightarrow a = a_5, b = -a_5a_1 - 1, c = a_1;$$

$$\begin{cases} \eta_{kk} = 1/a_5 = 0.9374 \\ \eta_{\lambda k} = (\eta_{kk} - a_1)/a_2 = -0.5838 \end{cases}$$

13. By comparing the coefficients on \hat{z}_t , solve for $\eta_{\lambda z}$ and η_{kz} . (0.4 points).

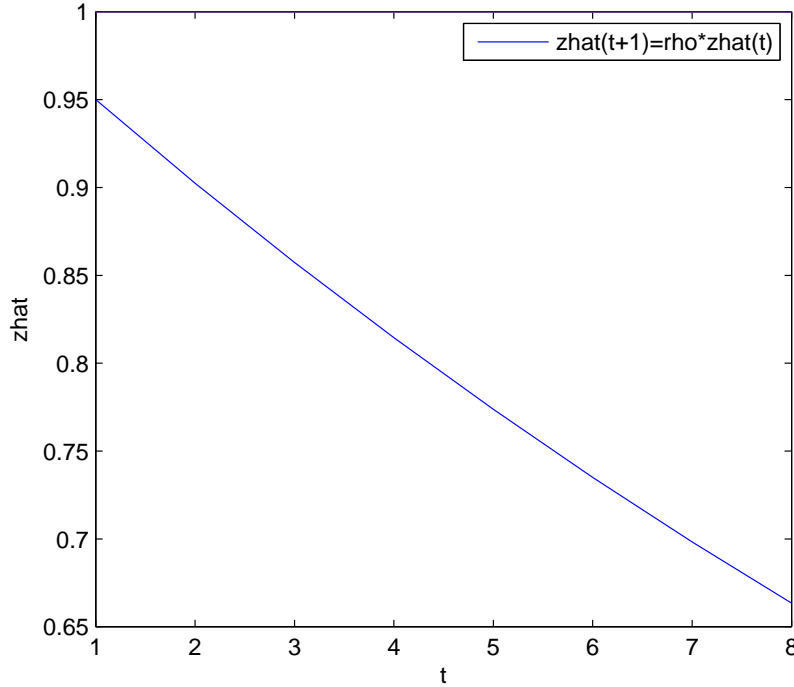
ANS:

Comparing the coefficients on \hat{z}_t ,

$$\begin{cases} -\eta_{kz} + a_3 + a_2\eta_{\lambda z} = 0 \\ -\eta_{\lambda z} + a_5\eta_{\lambda z}\rho + a_5\eta_{\lambda k}\eta_{kz} + a_6\rho = 0 \end{cases} \Rightarrow \begin{cases} \eta_{kz} = a_3 + a_2\eta_{\lambda z} \\ -\eta_{\lambda z} + a_5\eta_{\lambda z}\rho + a_5\eta_{\lambda k}\eta_{kz} + a_6\rho = 0 \end{cases} \Rightarrow \begin{cases} \eta_{kz} = a_3 + a_2\eta_{\lambda z} \\ -\eta_{\lambda z} + a_5\eta_{\lambda z}\rho + a_5\eta_{\lambda k}\eta_{kz} + a_6\rho = 0 \end{cases} \Rightarrow \begin{cases} \eta_{\lambda z} = \frac{a_3a_5\eta_{\lambda k} + a_6\rho}{1 - a_5\rho - a_2a_5\eta_{\lambda k}} = -0.4809 \\ \eta_{kz} = a_3 + a_2\eta_{\lambda z} = 0.1593 \end{cases}$$

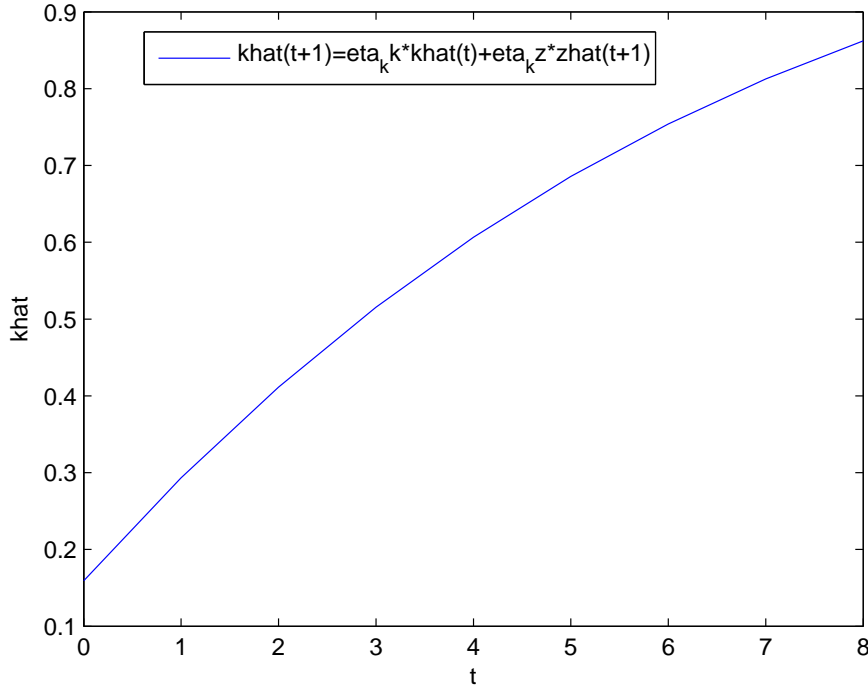
14. Assume $\hat{z}_{-1} = 0$, $\varepsilon_0 = 1$, and $\varepsilon_t = 0$ for $t = 1, 2, \dots, \infty$. Calculate \hat{z}_t recursively and plot the impulse response of \hat{z}_t for $t = 1, 2, \dots, 8$. (0.4 points)

ANS:



15. Assume $\hat{k}_{-1} = 0$, given the above technology shock, calculate \hat{k}_t recursively and plot the impulse response of \hat{k}_t for $t = 1, 2, \dots, 8$. (0.6 points)

ANS:



16. According to your loglinearized system in step 6, solve the law of motion for $\hat{n}_t = \eta_{nk}\hat{k}_{t-1} + \eta_{nz}\hat{z}_t$ (10)

what are the values of η_{nk} and η_{nz} given the parameter values? Notice the difference in their signs, and discuss the economic interpretation. (2 points)

ANS:

$$\begin{aligned}\hat{n}_t &= \frac{\theta + \eta_{\lambda k}}{\theta} \hat{k}_{t-1} + \frac{1 + \eta_{\lambda z}}{\theta} \hat{z}_t \\ \eta_{nk} &= \frac{\theta + \eta_{\lambda k}}{\theta} = -0.4596 \\ \eta_{nz} &= \frac{1 + \eta_{\lambda z}}{\theta} = 1.2977\end{aligned}$$

η_{nk} is negative, meaning that the increase in capital may squeeze out the input of labor. In the contrast, the sign of η_{nz} is positive, indicating that any positive technological impulse implies positive labor input.