

# Bayesian Learning

Kaiqi Zhao

The University of Auckland

*Slides are partially based on the materials from Mitchel's book and Stanford's NLP lectures*

# Maximum Likelihood and Least-Squared Error

# Maximum Likelihood and Least-Squared Objective

- Problem: learning continuous-valued target functions (e.g. neural networks, linear regression, etc.)
- Problem setting:
  - Given a data set  $D$  containing  $m$  training examples of the form  $\langle x_i, y_i \rangle$
  - Let's say there exists an unknown function  $f: X \rightarrow \mathbb{R}$  that describes how exactly the features maps to the target value.
  - $(\forall h \in H)[h: X \rightarrow \mathbb{R}]$ , our goal is to find the best hypothesis  $h^*$  to approximate  $f$
  - We assume the target value  $y_i$  is corrupted by random noise drawn from a Normal distribution with zero mean  $y_i = f(x_i) + \epsilon, \epsilon \sim \text{Normal}(0, \sigma^2)$ 
    - This is equivalent to say  $y_i$  follows a Normal distribution with mean equals  $f(x_i)$ , i.e.,  $y_i \sim \text{Normal}(f(x_i), \sigma^2)$ .

# Maximum Likelihood and Least-Squared Objective

- Maximum likelihood for regression problem

$$h_{ML} = \operatorname{argmax}_{h \in H} p(D|h)$$

$$= \operatorname{argmax}_{h \in H} \prod_{i=1}^m p(x_i, y_i|h) \quad \text{Assuming each instance is independent given } h$$

- What is probability of  $p(x_i, y_i|h)$ ?

$$p(x_i, y_i|h) = p(y_i|x_i, h)p(x_i|h) = \underbrace{p(y_i|h(x_i))}_{\text{conditional}} \underbrace{p(x_i|h)}_{\text{marginal}}$$

$$p(y_i|h(x_i)) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y_i-h(x_i))^2}{2\sigma^2}} \quad \text{The value of } x_i \text{ doesn't depend on } h, \text{ so } p(x_i|h) = p(x_i)$$

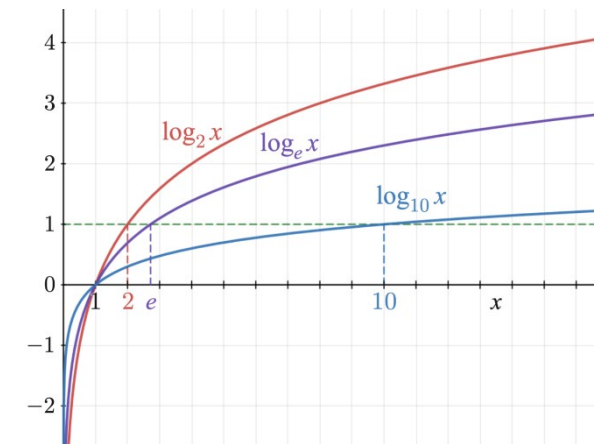
# Maximum Likelihood and Least-Squared Objective

- Maximum likelihood for regression problem

$$h_{ML} = \operatorname{argmax}_{h \in H} \prod_{i=1}^m p(y_i | h(x_i)) \prod_{i=1}^m p(x_i)$$

$$= \operatorname{argmax}_{h \in H} \prod_{i=1}^m \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y_i - h(x_i))^2}{2\sigma^2}}$$

- How to find the best  $h$  from the above?
  - $\log(\cdot)$  is a monotonically non-decreasing function, taking log of the likelihood does not affect the choice of the most probable hypothesis
  - We often compute log-likelihood instead of likelihood to make computation easier!



log function

# Maximum Likelihood and Least-Squared Objective

- Maximum likelihood for regression problem

$$\begin{aligned}
 h_{ML} &= \operatorname{argmax}_{h \in H} \prod_{i=1}^m p(y_i | h(x_i)) \prod_{i=1}^m p(x_i) && \text{Assuming each instance is independent given } h \\
 &= \operatorname{argmax}_{h \in H} \prod_{i=1}^m \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y_i - h(x_i))^2}{2\sigma^2}} && \text{Substitute the normal distribution density function} \\
 &= \operatorname{argmax}_{h \in H} \log \prod_{i=1}^m \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y_i - h(x_i))^2}{2\sigma^2}} && \text{Take log of the likelihood} \\
 &= \operatorname{argmax}_{h \in H} \sum_{i=1}^m \log \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y_i - h(x_i))^2}{2\sigma^2}} && \text{Apply rules of log function} \\
 &= \operatorname{argmax}_{h \in H} \sum_{i=1}^m -\frac{(y_i - h(x_i))^2}{2\sigma^2} + \boxed{\log \frac{1}{\sqrt{2\pi\sigma^2}}} && \text{This term is irrelevant to } h
 \end{aligned}$$

# Maximum Likelihood and Least-Squared Objective

- Maximum likelihood for regression problem

$$h_{ML} = \operatorname{argmax}_{h \in H} - \sum_{i=1}^m \frac{(y_i - h(x_i))^2}{2\sigma^2}$$

- Maximizing the above equation is equivalent to minimizing the following

$$h_{ML} = \operatorname{argmin}_{h \in H} \sum_{i=1}^m \frac{(y_i - h(x_i))^2}{2\sigma^2}$$

$\Rightarrow$  the  $h_{ML}$  is one that minimizes the sum of the squared errors

# Maximum Likelihood and Least-Squared Objective

$$h_{ML} = \operatorname{argmin}_{h \in H} \sum_{i=1}^m (y_i - h(x_i))^2$$

- Why is it reasonable to choose the Normal distribution to characterize noise?
  - Good approximation of many types of noise in physical systems
  - Central Limit Theorem shows that the sum of a sufficiently large number of independent, identically distributed random variables itself obeys a Normal distribution
- Only noise in the target value is considered, not in the attributes describing the instances themselves

# Minimum Description Length

# Minimum Description Length Principle

- Occam's razor: choose the shortest explanation for the observed data
- Here, we consider a Bayesian perspective on this issue and a closely related principle
- Minimum Description Length (MDL) Principle
  - Motivated by interpreting the definition of  $h_{MAP}$  in the light of information theory concepts

$$\begin{aligned}h_{MAP} &= \operatorname{argmax}_{h \in H} P(D|h)P(h) \\&= \operatorname{argmax}_{h \in H} \log_2 P(D|h) + \log_2 P(h) \\&= \operatorname{argmin}_{h \in H} -\log_2 P(D|h) - \log_2 P(h)\end{aligned}$$

# Minimum Description Length Principle

- Introduction to a basic result of information theory
  - Consider the problem of designing a code  $C$  to transmit messages drawn at random
  - Probability of encountering message  $i$  is  $p_i$
  - Interested in the most compact code  $C$
  - Shannon and Weaver (1949) showed that the optimal code assigns  $-\log_2 p_i$  bits to encode message  $i$
  - $L_C(i) \approx$  description length of message  $i$  with respect to  $C$

# Minimum Description Length Principle

$$h_{MAP} = \operatorname{argmin}_{h \in H} -\log_2 P(D|h) - \log_2 P(h)$$

- By information theory
  - $L_{C_H}(h) = -\log_2 P(h)$ , where  $C_H$  is the optimal code for hypothesis space  $H$
  - $L_{C_{D|h}}(D|h) = -\log_2 P(D|h)$ , where  $C_{D|h}$  is the optimal code for describing data  $D$  assuming that both the sender and receiver know hypothesis  $h$

⇒ Minimum description length principle

$$h_{MAP} = \operatorname{argmin}_{h \in H} L_{C_H}(h) + L_{C_{D|h}}(D|h)$$

# Minimum Description Length Principle

- To apply this principle in practice, **specific encodings or representations** appropriate for the given learning task must be chosen
- **Application to decision tree learning**
  - $C_H$  might have some obvious encoding, in which the description length grows with **the number of nodes** and with **the number of edges**
  - Choice of  $C_{D|h}$ ?
    - For simplicity, assume both sender and receiver know the  $m$  examples  $\langle x_1, \dots, x_m \rangle$
    - Under this assumption, what message do we need to transmit?
      - If the hypothesis can correctly predict the class of an example, nothing is needed to transmit
      - Otherwise, the **example** and the **correct class label** needs to transmit to the sender

$$(\underbrace{\log_2 m \text{ bits}} + \underbrace{\log_2 k \text{ bits}}) \times \text{\#missclassification}$$

# Minimum Description Length Principle

- $C_H$  - the number of nodes and the number of edges Model complexity
- $C_{D|h}$  -  $(\log_2 m \text{ bits} + \log_2 k \text{ bits}) \times \text{\#missclassification}$  Errors created
- MDL principle provides a way for trading off hypothesis complexity for the number of errors committed by the hypothesis
  - The shorter  $C_H$  for hypothesis, the more likely we make mistakes, and hence  $C_{D|h}$  might be longer
- One way of dealing with the issue of overfitting

# Minimum Description Length Principle

- $C_H$  - the number of nodes and the number of edges Model complexity
- $C_{D|h}$  -  $(\log_2 m \text{ bits} + \log_2 k \text{ bits}) \times \text{\#missclassification}$  Errors created
- MDL principle provides a way for trading off hypothesis complexity for the number of errors committed by the hypothesis
  - The shorter  $C_H$  for hypothesis, the more likely we make mistakes, and hence  $C_{D|h}$  might be longer
- One way of dealing with the issue of overfitting

# Example of MDL – Decision Tree Pruning

Table 1 – An example classification dataset

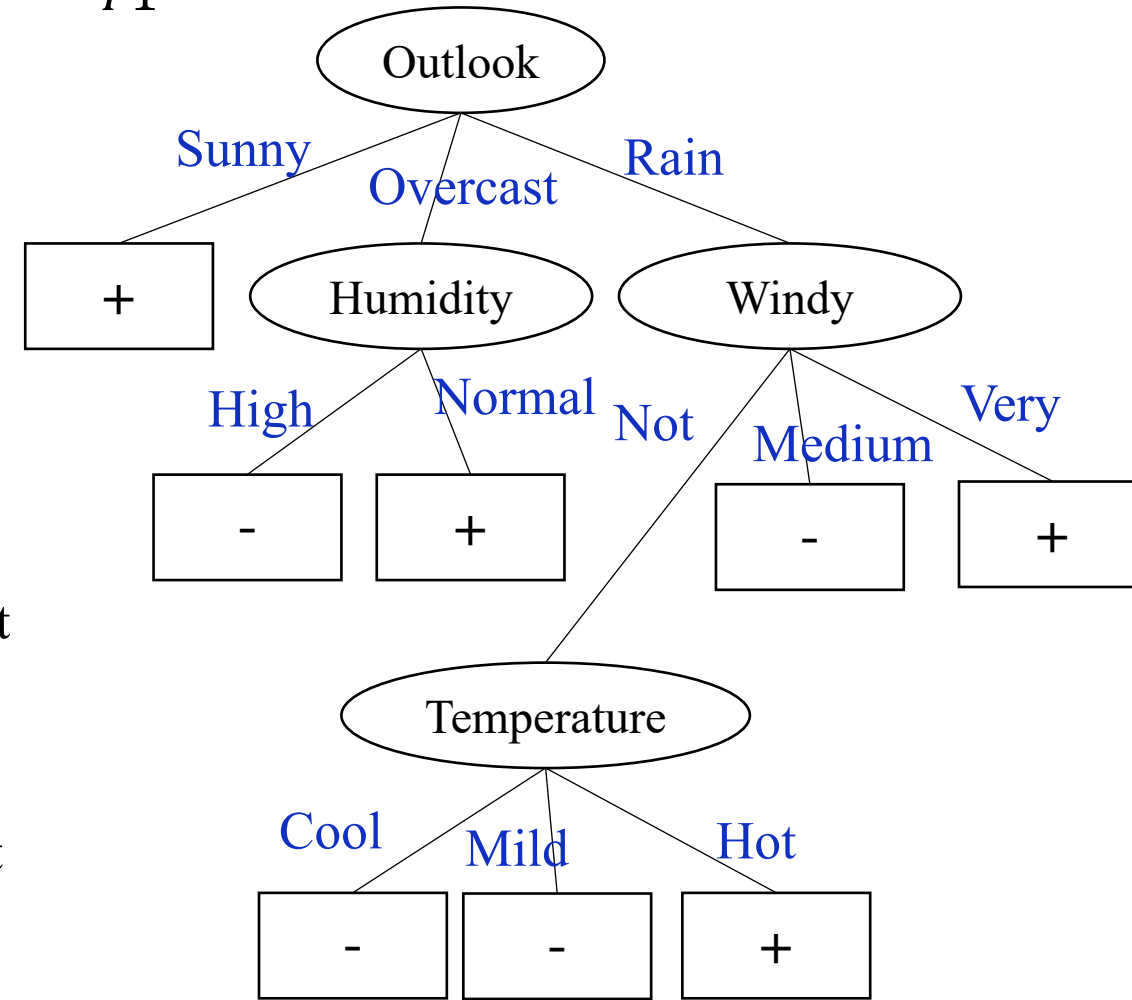
Outlook	Temperature	Humidity	Windy	Class
Overcast	Hot	High	Not	-
Sunny	Mild	Normal	Very	+
...	...	...	...	...
Rain	Hot	High	Medium	-
...	...	...	...	...

We have 32 instances, and the decision tree on the right hand side achieves 100% accuracy

Let's say we encode the tree with each row denoting a split. We can use 2 bits to encode the attribute and 1 bit to record a leaf node, e.g.

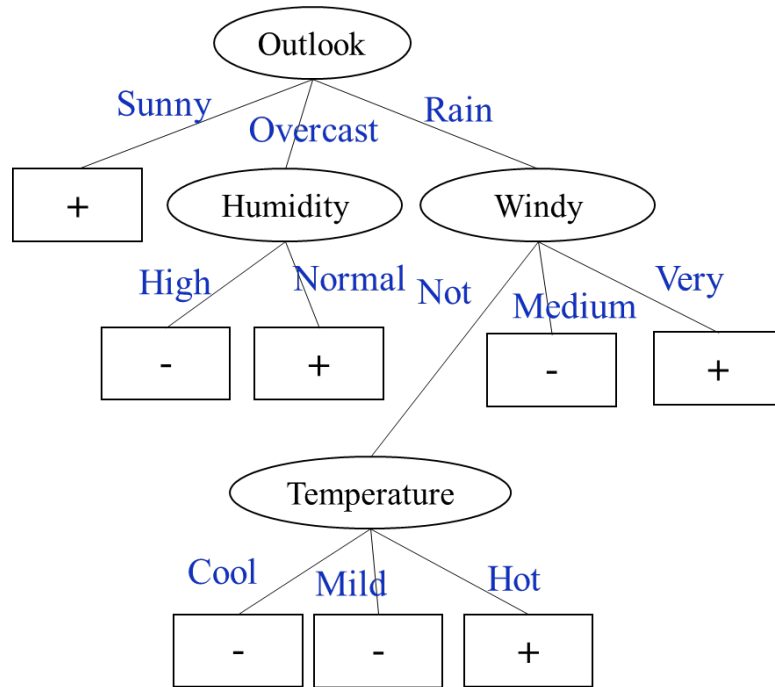
- Outlook: +, Humidity, Windy
- Humidity: -, +
- ...

T1



# Example of MDL – Decision Tree Pruning

$T1$

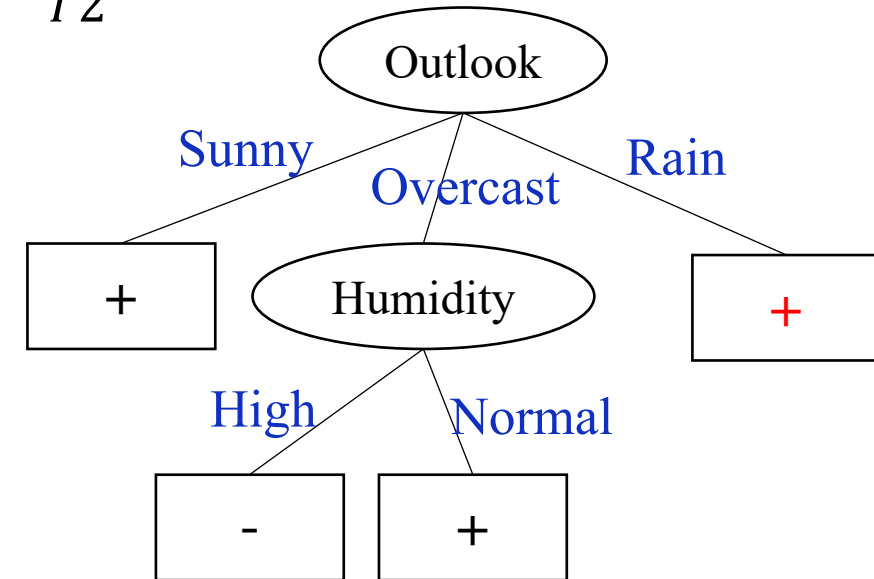


$$L_{C_H}(h) = \# \text{leaf} + 2\# \text{non-leaf} = 8 + 6 = 14$$

$$L_{C_{D|h}}(D|h) = 0$$

$$L_{C_H}(h) + L_{C_{D|h}}(D|h) = 14 \text{ bits}$$

$T2$



Let  $T2$  misclassifies one of the instances in Table 1 (in red)

$$L_{C_H}(h) = \# \text{leaf} + 2\# \text{non-leaf} = 4 + 2 = 6$$

$$L_{C_{D|h}}(D|h) = \log_2 32 + \log_2 2 = 6$$

$$L_{C_H}(h) + L_{C_{D|h}}(D|h) = 12 \text{ bits}$$