

Bayesian Learning

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Slides are partially based on the materials from Mitchel's book and Stanford's NLP lectures

Maximum Likelihood and Least-Squared Error

Maximum Likelihood and Least-Squared Objective

- Problem: learning continuous-valued target functions (e.g. neural networks, linear regression, etc.)
- Problem setting:
 - Given a data set D containing m training examples of the form $\langle x_i, y_i \rangle$
 - Let's say there exists an unknown function $f: X \rightarrow \mathbb{R}$ that describes how exactly the features maps to the target value.
 - $(\forall h \in H)[h: X \rightarrow \mathbb{R}]$, our goal is to find the best hypothesis h^* to approximate f
 - We assume the target value y_i is corrupted by random noise drawn from a Normal distribution with zero mean $y_i = f(x_i) + \epsilon$, $\epsilon \sim \text{Normal}(0, \sigma^2)$
 - This is equivalent to say y_i follows a Normal distribution with mean equals $f(x_i)$, i.e., $y_i \sim \text{Normal}(f(x_i), \sigma^2)$.

Maximum Likelihood and Least-Squared Objective

- Maximum likelihood for regression problem

$$h_{ML} = \operatorname{argmax}_{h \in H} p(D|h)$$

$$= \operatorname{argmax}_{h \in H} \prod_{i=1}^m p(x_i, y_i | h) \quad \text{Assuming each instance is independent given } h$$

- What is probability of $p(x_i, y_i | h)$?

$$p(x_i, y_i | h) = p(y_i | x_i, h)p(x_i | h) = \underbrace{p(y_i | h(x_i))}_{\text{red bracket}} \underbrace{p(x_i | h)}_{\text{red bracket}}$$

$$p(y_i | h(x_i)) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y_i - h(x_i))^2}{2\sigma^2}}$$

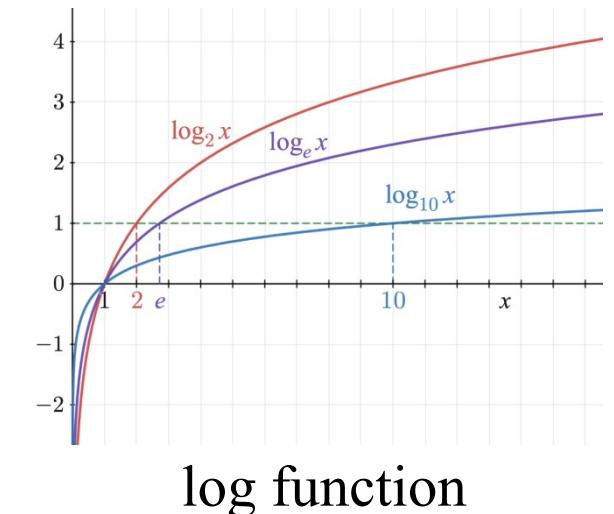
The value of x_i doesn't depend on h , so
 $p(x_i | h) = p(x_i)$

Maximum Likelihood and Least-Squared Objective

- Maximum likelihood for regression problem

$$\begin{aligned}
 h_{ML} &= \operatorname{argmax}_{h \in H} \prod_{i=1}^m p(y_i | h(x_i)) \prod_{i=1}^m p(x_i) \\
 &= \operatorname{argmax}_{h \in H} \prod_{i=1}^m \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y_i - h(x_i))^2}{2\sigma^2}}
 \end{aligned}$$

- How to find the best h from the above?
 - $\log(\cdot)$ is a monotonically non-decreasing function, taking log of the likelihood does not affect the choose of the most probable hypothesis
 - We often compute log-likelihood instead of likelihood to make computation easier!



Maximum Likelihood and Least-Squared Objective

- Maximum likelihood for regression problem

$$h_{ML} = \operatorname{argmax}_{h \in H} \prod_{i=1}^m p(y_i | h(x_i)) \prod_{i=1}^m p(x_i)$$

Assuming each instance is independent given h

$$= \operatorname{argmax}_{h \in H} \prod_{i=1}^m \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y_i - h(x_i))^2}{2\sigma^2}}$$

Substitute the normal distribution density function

$$= \operatorname{argmax}_{h \in H} \log \prod_{i=1}^m \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y_i - h(x_i))^2}{2\sigma^2}}$$

Take log of the likelihood

$$= \operatorname{argmax}_{h \in H} \sum_{i=1}^m \log \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y_i - h(x_i))^2}{2\sigma^2}}$$

Apply rules of log function

$$= \operatorname{argmax}_{h \in H} \sum_{i=1}^m -\frac{(y_i - h(x_i))^2}{2\sigma^2} + \boxed{\log \frac{1}{\sqrt{2\pi\sigma^2}}}$$

This term is irrelevant to h

Maximum Likelihood and Least-Squared Objective

- Maximum likelihood for regression problem

$$h_{ML} = \operatorname{argmax}_{h \in H} - \sum_{i=1}^m \frac{(y_i - h(x_i))^2}{2\sigma^2}$$

- Maximizing the above equation is equivalent to minimizing the following

$$h_{ML} = \operatorname{argmin}_{h \in H} \sum_{i=1}^m \frac{(y_i - h(x_i))^2}{2\sigma^2}$$

⇒ the h_{ML} is one that minimizes the sum of the squared errors

Maximum Likelihood and Least-Squared Objective

$$h_{ML} = \operatorname{argmin}_{h \in H} \sum_{i=1}^m (y_i - h(x_i))^2$$

- Why is it reasonable to choose the Normal distribution to characterize noise?
 - Good approximation of many types of noise in physical systems
 - Central Limit Theorem shows that the sum of a sufficiently large number of independent, identically distributed random variables itself obeys a Normal distribution
- Only noise in the target value is considered, not in the attributes describing the instances themselves

Minimum Description Length

Minimum Description Length Principle

- Occam's razor: choose the shortest explanation for the observed data
- Here, we consider a Bayesian perspective on this issue and a closely related principle
- Minimum Description Length (MDL) Principle
 - Motivated by interpreting the definition of h_{MAP} in the light of information theory concepts

$$\begin{aligned} h_{MAP} &= \operatorname{argmax}_{h \in H} P(D|h)P(h) \\ &= \operatorname{argmax}_{h \in H} \log_2 P(D|h) + \log_2 P(h) \\ &= \operatorname{argmin}_{h \in H} -\log_2 P(D|h) - \log_2 P(h) \end{aligned}$$

Minimum Description Length Principle

- Introduction to a basic result of information theory
 - Consider the problem of designing a code C to transmit messages drawn at random
 - Probability of encountering message i is p_i
 - Interested in the most compact code C
 - Shannon and Weaver (1949) showed that the optimal code assigns $-\log_2 p_i$ bits to encode message i
 - $L_C(i) \approx$ description length of message i with respect to C

Minimum Description Length Principle

$$h_{MAP} = \operatorname{argmin}_{h \in H} -\log_2 P(D|h) - \log_2 P(h)$$

- By information theory
 - $L_{C_H}(h) = -\log_2 P(h)$, where C_H is the optimal code for hypothesis space H
 - $L_{C_{D|h}}(D|h) = -\log_2 P(D|h)$, where $C_{D|h}$ is the optimal code for describing data D assuming that both the sender and receiver know hypothesis h

⇒ Minimum description length principle

$$h_{MAP} = \operatorname{argmin}_{h \in H} L_{C_H}(h) + L_{C_{D|h}}(D|h)$$

Minimum Description Length Principle

- To apply this principle in practice, **specific encodings or representations** appropriate for the given learning task must be chosen
- **Application to decision tree learning**
 - C_H might have some obvious encoding, in which the description length grows with **the number of nodes** and with **the number of edges**
 - Choice of $C_{D|h}$?
 - For simplicity, assume both sender and receiver know the m examples $\langle x_1, \dots, x_m \rangle$
 - Under this assumption, what message do we need to transmit?
 - If the hypothesis can correctly predict the class of an example, nothing is needed to transmit
 - Otherwise, the **example** and the **correct class label** needs to transmit to the sender

$$\underbrace{(\log_2 m \text{ bits} + \log_2 k \text{ bits})}_{\text{example and correct class label}} \times \# \text{missclassification}$$

Minimum Description Length Principle

- C_H - the number of nodes and the number of edges Model complexity
- $C_{D|h}$ - $(\log_2 m \text{ bits} + \log_2 k \text{ bits}) \times \# \text{missclassification}$ Errors created
- MDL principle provides a way for trading off hypothesis complexity for the number of errors committed by the hypothesis
 - The shorter C_H for hypothesis, the more likely we make mistakes, and hence $C_{D|h}$ might be longer
- One way of dealing with the issue of overfitting

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Example of MDL – Decision Tree Pruning

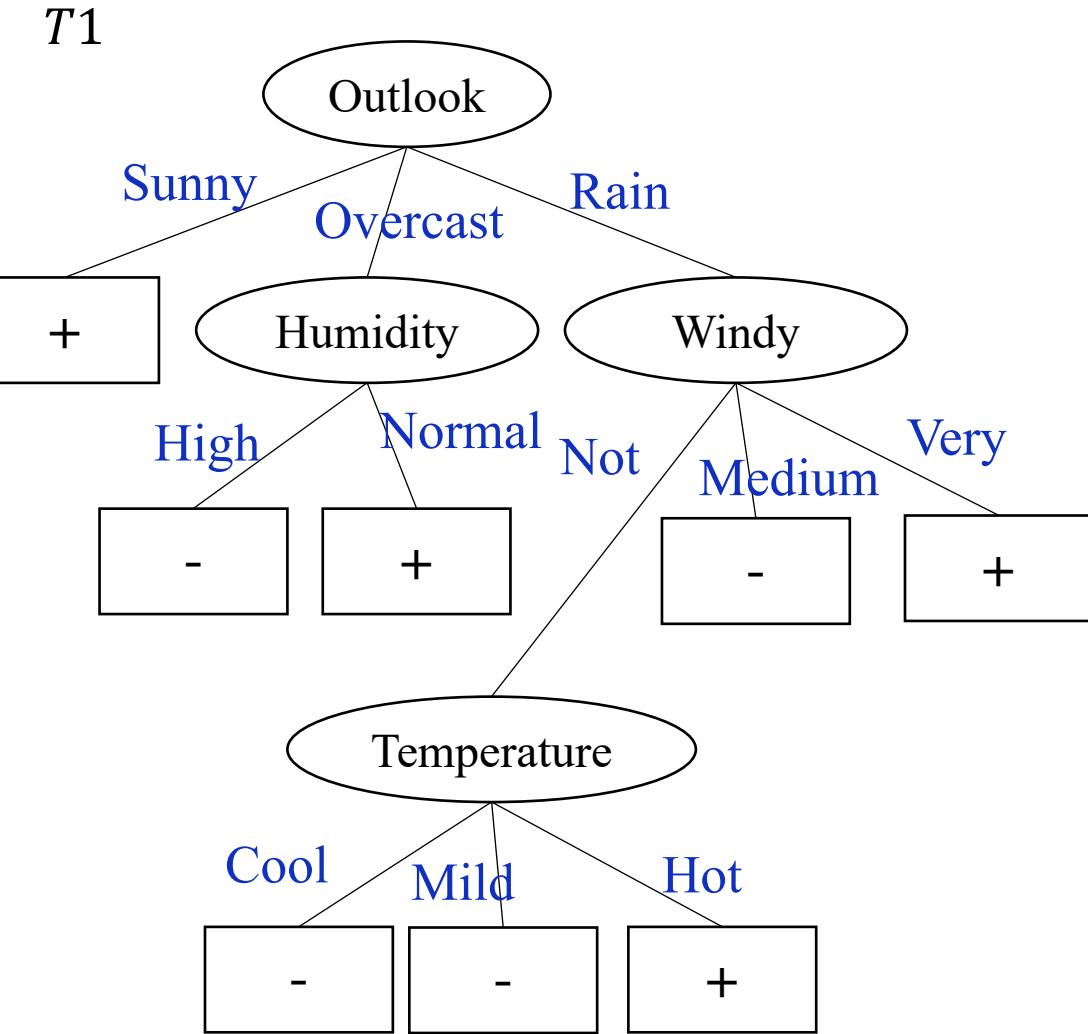
Table 1 – An example classification dataset

Outlook	Temperature	Humidity	Windy	Class
Overcast	Hot	High	Not	-
Sunny	Mild	Normal	Very	+
...
Rain	Hot	High	Medium	-
...

We have 32 instances, and the decision tree on the right hand side achieves 100% accuracy

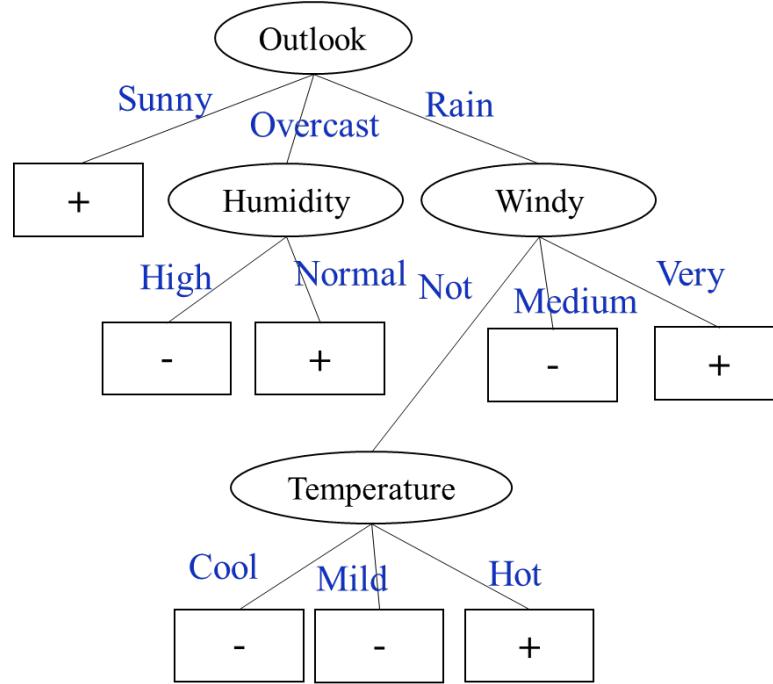
Let's say we encode the tree with each row denoting a split. We can use 2 bits to encode the attribute and 1 bit to record a leaf node, e.g.

- Outlook: +, Humidity, Windy
- Humidity: -, +
- ...



Example of MDL – Decision Tree Pruning

T_1

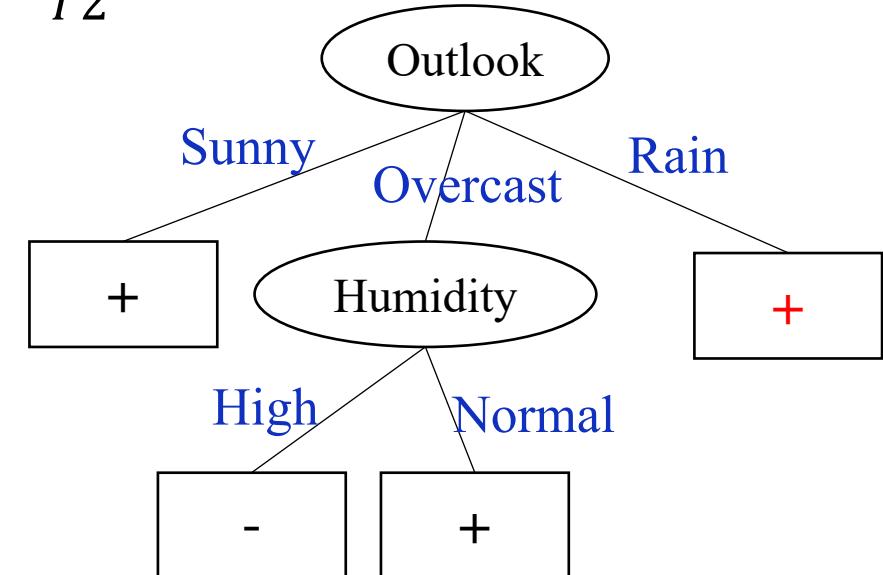


$$L_{C_H}(h) = \#\text{leaf} + 2\#\text{non-leaf} = 8 + 6 = 14$$

$$L_{C_D|h}(D|h) = 0$$

$$L_{C_H}(h) + L_{C_D|h}(D|h) = 14 \text{ bits}$$

T_2



Let T_2 misclassifies one of the instances in Table 1 (in red)

$$L_{C_H}(h) = \#\text{leaf} + 2\#\text{non-leaf} = 4 + 2 = 6$$

$$L_{C_D|h}(D|h) = \log_2 32 + \log_2 2 = 6$$

$$L_{C_H}(h) + L_{C_D|h}(D|h) = 12 \text{ bits}$$