Contents

1 Basic

1.1 vimrc

```
colo torte
syn on
se ai ar sm nu rnu is
se mouse=a bs=2 ww+=<,>,[,] so=6 ts=4 sw=4 ttm=100
se makeprg=g++\ -Wall\ -Wshadow\ -O2\ -std=c++0x\ -o\
    %<\ %
au BufNewFile *.cpp 0r ~/default.cpp | :1,$-7 fo
filetype indent on

map <F7> <ESC>:wa<CR>:make!<CR>
imap <F7> <ESC>:wa<CR>:make!<CR>
map <C-F7> <ESC>:tabe %<.in<CR>
map <F8> :cope <CR>
map <S-F8> :ccl <CR>
map <F9> :!./%< <CR>
map <C-F9> :!./%< < %<.in <CR>
```

1.2 IncreaseStackSize

```
//stack resize
asm( "mov %0,%%esp\n" ::"g"(mem+10000000) );
//change esp to rsp if 64-bit system

//stack resize (linux)
#include <sys/resource.h>
void increase_stack_size() {
  const rlim_t ks = 64*1024*1024;
  struct rlimit rl;
  int res=getrlimit(RLIMIT_STACK, &rl);
  if(res==0){
    if(rl.rlim_cur<ks){
      rl.rlim_cur=ks;
      res=setrlimit(RLIMIT_STACK, &rl);
    }
  }
}
```

1.3 Default Code

```
#pragma GCC optimize ("O2")
#include<bits/stdc++.h>
#include<unistd.h>
using namespace std;
#define FZ(n) memset((n),0,sizeof(n))
#define FMO(n) memset((n),-1,sizeof(n))
#define F first
#define S second
#define PB push_back
#define ALL(x) begin(x),end(x)
#define SZ(x) ((int)(x).size())
#define IOS ios_base::sync_with_stdio(0); cin.tie(0)
#define REP(i,x) for (int i=0; i<(x); i++)
#define REP1(i,a,b) for (int i=(a); i<=(b); i++)
#ifdef ONLINE_JUDGE
#define FILEIO(name) \
    freopen(name".in", "r", stdin); \
    freopen(name".out", "w", stdout);
#else
#define FILEIO(name)
#endif
template<typename A, typename B>
ostream& operator <<(ostream &s, const pair<A,B> &p) {
    return s<<"("<<p.first<<","<<p.second<<")";
}
template<typename T>
ostream& operator <<(ostream &s, const vector<T> &c) {
    s<<"[ ";
    for (auto it : c) s << it << " ";
    s<<"]";
    return s;
}
/*
我最近在研究腦控裝置是否與人工智慧連結
為了知道對方的意圖我已經打聽過外星機構
我知道有些外星機構有腦控裝置的伺服機櫃
```

```
對量子蟲洞照光時搖視太空會有相對應光波
特別是搭配擴散濾鏡綠光雷射照向乾淨灰塵
房間都是關閉門窗且24小時開啟空氣清淨機
在濾網沒有很髒的時候有大量灰塵怖滿桌面
可以合理的推論是由外星傳送技術灑進房間
這讓我回想起以前都是灑在空氣中而非表面
可見傳物監聽技術層級已提高到另一個層次
於是我開始練習反向地調整人工智慧的傾向
這與我們的歷史與大眾的傾向有許多的關聯
且人工智慧主機被我發現在地球外的飛船裡
這代表是有外星機構想要調控整體人類動向
因此可以合理推斷地球目前的政治也是如此
高中的時候常和家人一起看古代的宮廷戲劇
通常掌權者為了繼續延續與維持自己的王朝
會讓下臣及宰相互鬥而讓他們沒時間奪政權
我覺得地球上各國與各地方的爭鬥也是如此
這樣外星的領導們就可以永遠持續維持高位
而業力Karma就是自動腦控的Reward參數~
因此為了要試試看是否這類工智慧真實存在
我進行了以下試驗並檢驗了其真實性並公佈
首先我每次出門會有陌生面孔出現在地下室
我試了好幾次出門時只按電梯按鈕又回家中
再接下來一次出門就沒有人出現在地下室了
還有就是清晨時候最容易被換身體加強控制
我開始試驗著每天寅時卯時保持清醒不睡覺
通常那時段的感受到的地磁能量會擺動不穩
可見天空的外星飛船流量會影響地磁的脈動
因此我開始作另一項試驗就是躺著假裝睡著
我發現我的身體會被反重力提起並換個位置
還好我的能量夠強以致於沒有被蟲洞傳送走
於是我作了另一項實驗看看是否會被女生追
我們都知道有些漂亮女生會喜歡笨笨的男生
而有些很聰明的男生則會喜歡上笨笨的女生
於是我開始常到有監視器的賣場假裝我很笨
我會假裝自己是動物並到處觀看及精神分裂
從那天開始我就開始被一些漂亮的女生追隨
她們並非一些正常的人類似乎沒有國小同學
而這項實驗最後引來了一些非常漂亮的女生
她們有的有物質身體且幾乎都有失憶的傾向
我有時候會跟她們聊天但幾乎隔天就忘記了
再來就是會有些女生會用能量觸及我的身體
但我其實對外人表現的樣子應該是很笨很蠢
這類不合理的情況已可推論人工智慧的目標
可能要將家庭的平均智商降低致使發展變慢
我們都知道一個國家最重要的梁柱就是小孩
如果小孩擁有更好的教育環境整體發展更快

再來是一些人工智慧與影像辨識的反向操控
通常攝影機出錯時會停止影像分析避免異常
我在電腦上寫一支程式隨時跳出無意義字串
我發現那部電腦從那天開始沒有再被當機過

但是有一天我的正常電腦都被當機後我躺下
開始戴上眼罩並且只留一個小孔開始動眼球
我發現可以用一些特定的圖紋詐騙人工智慧
讓頭與眼不固定抖動與閉眼使人工智慧異常
通常在這種時候因為我已經被外星機構標記
他們會派飛船來檢查並且想要傳送我的身體
我猜可能是一種錯誤後修復的機制非常危險
最簡單的就是反覆閉眼並動頭掃描相似紋路
例如我的窗簾有許多個小熊都長的非常相似
這會讓人工智慧偵測到連續的畫面超出範圍
因為平常這種人工智慧就會偵測周遭的環境
若發現景物不同則有其他外星派系改變景物

從此之後我被外星機構列為需要攻擊的對象
我遭受到超級密集的電磁脈衝與反重力脈衝
*/
// Let's Fight!

int main() {
    IOS;

    return 0;
}
```

2 Data Structure

2.1 Bigint

```cpp
struct Bigint{
  static const int LEN = 60;
  static const int BIGMOD = 10000;

  int s;
  int vl, v[LEN];
  //  vector<int> v;
  Bigint() : s(1) { vl = 0; }
  Bigint(long long a) {
    s = 1; vl = 0;
    if (a < 0) { s = -1; a = -a; }
    while (a) {
      push_back(a % BIGMOD);
      a /= BIGMOD;
    }
  }
  Bigint(string str) {
    s = 1; vl = 0;
    int stPos = 0, num = 0;
    if (!str.empty() && str[0] == '-') {
      stPos = 1;
      s = -1;
    }
    for (int i=SZ(str)-1, q=1; i>=stPos; i--) {
      num += (str[i] - '0') * q;
      if ((q *= 10) >= BIGMOD) {
        push_back(num);
        num = 0; q = 1;
      }
    }
    if (num) push_back(num);
    n();
  }

  int len() const {
    return vl;
    //    return SZ(v);
  }
  bool empty() const { return len() == 0; }
  void push_back(int x) {
    v[vl++] = x;
    //    v.PB(x);
  }
  void pop_back() {
    vl--;
    //    v.pop_back();
  }
  int back() const {
    return v[vl-1];
    //    return v.back();
  }
  void n() {
    while (!empty() && !back()) pop_back();
  }
  void resize(int nl) {
    vl = nl;
    fill(v, v+vl, 0);
    //    v.resize(nl);
    //    fill(ALL(v), 0);
  }

  void print() const {
    if (empty()) { putchar('0'); return; }
    if (s == -1) putchar('-');
    printf("%d", back());
    for (int i=len()-2; i>=0; i--) printf("%.4d",v[i]);
  }
  friend std::ostream& operator << (std::ostream& out,
      const Bigint &a) {
    if (a.empty()) { out << "0"; return out; }
    if (a.s == -1) out << "-";
    out << a.back();
    for (int i=a.len()-2; i>=0; i--) {
      char str[10];
      snprintf(str, 5, "%.4d", a.v[i]);
      out << str;
    }
    return out;
  }
```

```
int cp3(const Bigint &b)const {
  if (s != b.s) return s - b.s;
  if (s == -1) return -(-*this).cp3(-b);
  if (len() != b.len()) return len()-b.len();//int
  for (int i=len()-1; i>=0; i--)
    if (v[i]!=b.v[i]) return v[i]-b.v[i];
  return 0;
}

bool operator < (const Bigint &b)const{ return cp3(b)
    <0; }
bool operator <= (const Bigint &b)const{ return cp3(b
    )<=0; }
bool operator == (const Bigint &b)const{ return cp3(b
    )==0; }
bool operator != (const Bigint &b)const{ return cp3(b
    )!=0; }
bool operator > (const Bigint &b)const{ return cp3(b)
    >0; }
bool operator >= (const Bigint &b)const{ return cp3(b
    )>=0; }

Bigint operator - () const {
  Bigint r = (*this);
  r.s = -r.s;
  return r;
}
Bigint operator + (const Bigint &b) const {
  if (s == -1) return -(-(*this)+(-b));
  if (b.s == -1) return (*this)-(-b);
  Bigint r;
  int nl = max(len(), b.len());
  r.resize(nl + 1);
  for (int i=0; i<nl; i++) {
    if (i < len()) r.v[i] += v[i];
    if (i < b.len()) r.v[i] += b.v[i];
    if(r.v[i] >= BIGMOD) {
      r.v[i+1] += r.v[i] / BIGMOD;
      r.v[i] %= BIGMOD;
    }
  }
  r.n();
  return r;
}
Bigint operator - (const Bigint &b) const {
  if (s == -1) return -(-(*this)-(-b));
  if (b.s == -1) return (*this)+(-b);
  if ((*this) < b) return -(b-(*this));
  Bigint r;
  r.resize(len());
  for (int i=0; i<len(); i++) {
    r.v[i] += v[i];
    if (i < b.len()) r.v[i] -= b.v[i];
    if (r.v[i] < 0) {
      r.v[i] += BIGMOD;
      r.v[i+1]--;
    }
  }
  r.n();
  return r;
}
Bigint operator * (const Bigint &b) {
  Bigint r;
  r.resize(len() + b.len() + 1);
  r.s = s * b.s;
  for (int i=0; i<len(); i++) {
    for (int j=0; j<b.len(); j++) {
      r.v[i+j] += v[i] * b.v[j];
      if(r.v[i+j] >= BIGMOD) {
        r.v[i+j+1] += r.v[i+j] / BIGMOD;
        r.v[i+j] %= BIGMOD;
      }
    }
  }
  r.n();
  return r;
}
Bigint operator / (const Bigint &b) {
  Bigint r;
  r.resize(max(1, len()-b.len()+1));
  int oriS = s;
  Bigint b2 = b; // b2 = abs(b)
  s = b2.s = r.s = 1;
  for (int i=r.len()-1; i>=0; i--) {
    int d=0, u=BIGMOD-1;
    while(d<u) {
      int m = (d+u+1)>>1;
      r.v[i] = m;
      if((r*b2) > (*this)) u = m-1;
      else d = m;
    }
    r.v[i] = d;
  }
  s = oriS;
  r.s = s * b.s;
  r.n();
  return r;
}
Bigint operator % (const Bigint &b) {
  return (*this)-(*this)/b*b;
}
};
```

2.2 unordered_map

```
struct Key {
  int first,second;
  Key () {}
  Key (int _x, int _y) : first(_x),  second(_y) {}
  bool operator == (const Key &b) const {
    return tie(F,S) == tie(b.F,b.S);
  }
};
struct KeyHasher {
  size_t operator()(const Key& k) const {
    return k.first + k.second*100000;
  }
};

typedef unordered_map<Key,int,KeyHasher> map_t;

int main(int argc, char** argv){
  map_t mp;
  for (int i=0; i<10; i++)
    mp[Key(i,0)] = i+1;
  for (int i=0; i<10; i++)
    printf("%d\n", mp[Key(i,0)]);

  return 0;
}
```

2.3 extc_heap

```
#include <bits/extc++.h>
typedef __gnu_pbds::priority_queue<int> heap_t;
heap_t a,b;

int main() {
  a.clear();
  b.clear();
  a.push(1);
  a.push(3);
  b.push(2);
  b.push(4);
  assert(a.top() == 3);
  assert(b.top() == 4);
  // merge two heap
  a.join(b);
  assert(a.top() == 4);
  assert(b.empty());

  return 0;
}
```

2.4 extc_balance_tree

```
#include <ext/pb_ds/assoc_container.hpp>
using namespace std;
using namespace __gnu_pbds;
typedef tree<int,null_type,less<int>,rb_tree_tag,
    tree_order_statistics_node_update> set_t;

#include <ext/pb_ds/assoc_container.hpp>
using namespace __gnu_pbds;
typedef cc_hash_table<int,int> umap_t;
```

```
int main()
{
  // Insert some entries into s.
  set_t s;
  s.insert(12);
  s.insert(505);

  // The order of the keys should be: 12, 505.
  assert(*s.find_by_order(0) == 12);
  assert(s.find_by_order(2) == end(s));

  // The order of the keys should be: 12, 505.
  assert(s.order_of_key(12) == 0);
  assert(s.order_of_key(505) == 1);

  // Erase an entry.
  s.erase(12);

  // The order of the keys should be: 505.
  assert(*s.find_by_order(0) == 505);

  // The order of the keys should be: 505.
  assert(s.order_of_key(505) == 0);
}
```

2.5 Disjoint Set

```
struct DisjointSet {
  // save() is like recursive
  // undo() is like return
  int n, fa[MXN], sz[MXN];
  vector<pair<int*,int>> h;
  vector<int> sp;
  void init(int tn) {
    n=tn;
    for (int i=0; i<n; i++) {
      fa[i]=i;
      sz[i]=1;
    }
    sp.clear(); h.clear();
  }
  void assign(int *k, int v) {
    h.PB({k, *k});
    *k=v;
  }
  void save() { sp.PB(SZ(h)); }
  void undo() {
    assert(!sp.empty());
    int last=sp.back(); sp.pop_back();
    while (SZ(h)!=last) {
      auto x=h.back(); h.pop_back();
      *x.F=x.S;
    }
  }
  int f(int x) {
    while (fa[x]!=x) x=fa[x];
    return x;
  }
  void uni(int x, int y) {
    x=f(x); y=f(y);
    if (x==y) return ;
    if (sz[x]<sz[y]) swap(x, y);
    assign(&sz[x], sz[x]+sz[y]);
    assign(&fa[y], x);
  }
}djs;
```

2.6 Treap

```
const int MEM = 16000004;
struct Treap {
  static Treap nil, mem[MEM], *pmem;
  Treap *l, *r;
  char val;
  int size;
  Treap () : l(&nil), r(&nil), size(0) {}
  Treap (char _val) :
    l(&nil), r(&nil), val(_val), size(1) {}
} Treap::nil, Treap::mem[MEM], *Treap::pmem = Treap::
    mem;
int size(const Treap *t) { return t->size; }
void pull(Treap *t) {
  if (!size(t)) return;
  t->size = size(t->l) + size(t->r) + 1;
}
Treap* merge(Treap *a, Treap *b) {
  if (!size(a)) return b;
  if (!size(b)) return a;
  Treap *t;
  if (rand() % (size(a) + size(b)) < size(a)) {
    t = new (Treap::pmem++) Treap(*a);
    t->r = merge(a->r, b);
  } else {
    t = new (Treap::pmem++) Treap(*b);
    t->l = merge(a, b->l);
  }
  pull(t);
  return t;
}
void split(Treap *t, int k, Treap *&a, Treap *&b) {
  if (!size(t)) a = b = &Treap::nil;
  else if (size(t->l) + 1 <= k) {
    a = new (Treap::pmem++) Treap(*t);
    split(t->r, k - size(t->l) - 1, a->r, b);
    pull(a);
  } else {
    b = new (Treap::pmem++) Treap(*t);
    split(t->l, k, a, b->l);
    pull(b);
  }
}

int nv;
Treap *rt[50005];

void print(const Treap *t) {
  if (!size(t)) return;
  print(t->l);
  cout << t->val;
  print(t->r);
}

int main(int argc, char** argv) {
  IOS;
  rt[nv=0] = &Treap::nil;
  Treap::pmem = Treap::mem;
  int Q, cmd, p, c, v;
  string s;
  cin >> Q;
  while (Q--) {
    cin >> cmd;
    if (cmd == 1) {
      // insert string s after position p
      cin >> p >> s;
      Treap *tl, *tr;
      split(rt[nv], p, tl, tr);
      for (int i=0; i<SZ(s); i++)
        tl = merge(tl, new (Treap::pmem++) Treap(s[i]))
            ;
      rt[++nv] = merge(tl, tr);
    } else if (cmd == 2) {
      // remove c characters starting at position
      Treap *tl, *tm, *tr;
      cin >> p >> c;
      split(rt[nv], p-1, tl, tm);
      split(tm, c, tm, tr);
      rt[++nv] = merge(tl, tr);
    } else if (cmd == 3) {
      // print c characters starting at position p, in
          version v
      Treap *tl, *tm, *tr;
      cin >> v >> p >> c;
      split(rt[v], p-1, tl, tm);
      split(tm, c, tm, tr);
      print(tm);
      cout << "\n";
    }
  }
  return 0;
}
```

2.7 Heavy Light Decomposition

```
// only one segment tree / 0-base
```

```cpp
// should call init after input N
// getPathSeg return the segment in order u->v
// fa[root] = root

typedef pair<int,int> pii;

int N,fa[MXN],belong[MXN],dep[MXN],sz[MXN],que[MXN];
int step,line[MXN],stPt[MXN],edPt[MXN];
vector<int> E[MXN], chain[MXN];

void init() {
  REP(i,N) {
    E[i].clear();
    chain[i].clear();
  }
}
void DFS(int u){
  vector<int> &c = chain[belong[u]];
  for (int i=c.size()-1; i>=0; i--){
    int v = c[i];
    stPt[v] = step;
    line[step++] = v;
  }
  for (int i=0; i<(int)c.size(); i++){
    u = c[i];
    for (auto v : E[u]){
      if (fa[u] == v || (i && v == c[i-1])) continue;
      DFS(v);
    }
    edPt[u] = step-1;
  }
}
void build_chain(int st){
  int fr,bk;
  fr=bk=0; que[bk++]=st; fa[st]=st; dep[st]=0;
  while (fr < bk){
    int u=que[fr++];
    for (auto v : E[u]){
      if (v == fa[u]) continue;
      que[bk++] = v;
      dep[v] = dep[u]+1;
      fa[v] = u;
    }
  }
  for (int i=bk-1,u,pos; i>=0; i--){
    u = que[i]; sz[u] = 1; pos = -1;
    for (auto v : E[u]){
      if (v == fa[u]) continue;
      sz[u] += sz[v];
      if (pos==-1 || sz[v]>sz[pos]) pos=v;
    }
    if (pos == -1) belong[u] = u;
    else belong[u] = belong[pos];
    chain[belong[u]].PB(u);
  }
  step = 0;
  DFS(st);
}
int getLCA(int u, int v){
  while (belong[u] != belong[v]){
    int a = chain[belong[u]].back();
    int b = chain[belong[v]].back();
    if (dep[a] > dep[b]) u = fa[a];
    else v = fa[b];
  }
  return sz[u] >= sz[v] ? u : v;
}
vector<pii> getPathSeg(int u, int v){
  vector<pii> ret1,ret2;
  while (belong[u] != belong[v]){
    int a = chain[belong[u]].back();
    int b = chain[belong[v]].back();
    if (dep[a] > dep[b]){
      ret1.PB({stPt[a],stPt[u]});
      u = fa[a];
    } else {
      ret2.PB({stPt[b],stPt[v]});
      v = fa[b];
    }
  }
  if (dep[u] > dep[v]) swap(u,v);
  ret1.PB({stPt[u],stPt[v]});
  reverse(ret2.begin(), ret2.end());
  ret1.insert(ret1.end(),ret2.begin(),ret2.end());
  return ret1;
}

// Usage
void build(){
  build_chain(0); //change root
  init(0,step,0); //init segment tree
}
int get_answer(int u, int v){
  int ret = -2147483647;
  vector<pii> vec = getPathSeg(u,v);
  for (auto it : vec)
    ; // check answer with segment [it.F, it.S]
  return ret;
}
```

2.8 Link-Cut Tree

```cpp
const int MXN = 100005;
const int MEM = 100005;

struct Splay {
  static Splay nil, mem[MEM], *pmem;
  Splay *ch[2], *f;
  int val, rev, size;
  Splay () : val(-1), rev(0), size(0) {
    f = ch[0] = ch[1] = &nil;
  }
  Splay (int _val) : val(_val), rev(0), size(1) {
    f = ch[0] = ch[1] = &nil;
  }
  bool isr() {
    return f->ch[0] != this && f->ch[1] != this;
  }
  int dir() {
    return f->ch[0] == this ? 0 : 1;
  }
  void setCh(Splay *c, int d) {
    ch[d] = c;
    if (c != &nil) c->f = this;
    pull();
  }
  void push() {
    if (rev) {
      swap(ch[0], ch[1]);
      if (ch[0] != &nil) ch[0]->rev ^= 1;
      if (ch[1] != &nil) ch[1]->rev ^= 1;
      rev=0;
    }
  }
  void pull() {
    size = ch[0]->size + ch[1]->size + 1;
    if (ch[0] != &nil) ch[0]->f = this;
    if (ch[1] != &nil) ch[1]->f = this;
  }
} Splay::nil, Splay::mem[MEM], *Splay::pmem = Splay::
    mem;
Splay *nil = &Splay::nil;

void rotate(Splay *x) {
  Splay *p = x->f;
  int d = x->dir();
  if (!p->isr()) p->f->setCh(x, p->dir());
  else x->f = p->f;
  p->setCh(x->ch[!d], d);
  x->setCh(p, !d);
  p->pull(); x->pull();
}

vector<Splay*> splayVec;
void splay(Splay *x) {
  splayVec.clear();
  for (Splay *q=x;; q=q->f) {
    splayVec.push_back(q);
    if (q->isr()) break;
  }
  reverse(begin(splayVec), end(splayVec));
  for (auto it : splayVec) it->push();
  while (!x->isr()) {
    if (x->f->isr()) rotate(x);
    else if (x->dir()==x->f->dir()) rotate(x->f),rotate
        (x);
    else rotate(x),rotate(x);
  }
}

Splay* access(Splay *x) {
```

```
  Splay *q = nil;
  for (;x!=nil;x=x->f) {
    splay(x);
    x->setCh(q, 1);
    q = x;
  }
  return q;
}
void evert(Splay *x) {
  access(x);
  splay(x);
  x->rev ^= 1;
  x->push(); x->pull();
}
void link(Splay *x, Splay *y) {
//  evert(x);
  access(x);
  splay(x);
  evert(y);
  x->setCh(y, 1);
}
void cut(Splay *x, Splay *y) {
//  evert(x);
  access(y);
  splay(y);
  y->push();
  y->ch[0] = y->ch[0]->f = nil;
}

int N, Q;
Splay *vt[MXN];

int ask(Splay *x, Splay *y) {
  access(x);
  access(y);
  splay(x);
  int res = x->f->val;
  if (res == -1) res=x->val;
  return res;
}
int main(int argc, char** argv) {
  scanf("%d%d", &N, &Q);
  for (int i=1; i<=N; i++)
    vt[i] = new (Splay::pmem++) Splay(i);
  while (Q--) {
    char cmd[105];
    int u, v;
    scanf("%s", cmd);
    if (cmd[1] == 'i') {
      scanf("%d%d", &u, &v);
      link(vt[v], vt[u]);
    } else if (cmd[0] == 'c') {
      scanf("%d", &v);
      cut(vt[1], vt[v]);
    } else {
      scanf("%d%d", &u, &v);
      int res=ask(vt[u], vt[v]);
      printf("%d\n", res);
    }
  }

  return 0;
}
```

3 Graph

3.1 BCC Edge

```
struct BccEdge {
  static const int MXN = 100005;
  struct Edge { int v,eid; };
  int n,m,step,par[MXN],dfn[MXN],low[MXN];
  vector<Edge> E[MXN];
  DisjointSet djs;
  void init(int _n) {
    n = _n; m = 0;
    for (int i=0; i<n; i++) E[i].clear();
    djs.init(n);
  }
  void add_edge(int u, int v) {
    E[u].PB({v, m});
    E[v].PB({u, m});
    m++;
  }
  void DFS(int u, int f, int f_eid) {
    par[u] = f;
    dfn[u] = low[u] = step++;
    for (auto it:E[u]) {
      if (it.eid == f_eid) continue;
      int v = it.v;
      if (dfn[v] == -1) {
        DFS(v, u, it.eid);
        low[u] = min(low[u], low[v]);
      } else {
        low[u] = min(low[u], dfn[v]);
      }
    }
  }
  void solve() {
    step = 0;
    memset(dfn, -1, sizeof(int)*n);
    for (int i=0; i<n; i++) {
      if (dfn[i] == -1) DFS(i, i, -1);
    }
    djs.init(n);
    for (int i=0; i<n; i++) {
      if (low[i] < dfn[i]) djs.uni(i, par[i]);
    }
  }
}graph;
```

3.2 BCC Vertex

```
struct BccVertex {
  int n,nBcc,step,root,dfn[MXN],low[MXN];
  vector<int> E[MXN], ap;
  vector<pii> bcc[MXN];
  int top;
  pii stk[MXN];
  void init(int _n) {
    n = _n;
    nBcc = step = 0;
    for (int i=0; i<n; i++) E[i].clear();
  }
  void add_edge(int u, int v) {
    E[u].PB(v);
    E[v].PB(u);
  }
  void DFS(int u, int f) {
    dfn[u] = low[u] = step++;
    int son = 0;
    for (auto v:E[u]) {
      if (v == f) continue;
      if (dfn[v] == -1) {
        son++;
        stk[top++] = {u,v};
        DFS(v,u);
        if (low[v] >= dfn[u]) {
          if(v != root) ap.PB(v);
          do {
            assert(top > 0);
            bcc[nBcc].PB(stk[--top]);
          } while (stk[top] != pii(u,v));
          nBcc++;
        }
        low[u] = min(low[u], low[v]);
      } else {
        if (dfn[v] < dfn[u]) stk[top++] = pii(u,v);
        low[u] = min(low[u],dfn[v]);
      }
    }
    if (u == root && son > 1) ap.PB(u);
  }
  // return the edges of each bcc;
  vector<vector<pii>> solve() {
    vector<vector<pii>> res;
    for (int i=0; i<n; i++) {
      dfn[i] = low[i] = -1;
    }
    ap.clear();
    for (int i=0; i<n; i++) {
      if (dfn[i] == -1) {
        top = 0;
        root = i;
        DFS(i,i);
      }
```

```
    }
    REP(i,nBcc) res.PB(bcc[i]);
    return res;
  }
}graph;
```

3.3 Strongly Connected Components

```
struct Scc{
  int n, nScc, vst[MXN], bln[MXN];
  vector<int> E[MXN], rE[MXN], vec;
  void init(int _n){
    n = _n;
    for (int i=0; i<n; i++){
      E[i].clear();
      rE[i].clear();
    }
  }
  void add_edge(int u, int v){
    E[u].PB(v);
    rE[v].PB(u);
  }
  void DFS(int u){
    vst[u]=1;
    for (auto v : E[u])
      if (!vst[v]) DFS(v);
    vec.PB(u);
  }
  void rDFS(int u){
    vst[u] = 1;
    bln[u] = nScc;
    for (auto v : rE[u])
      if (!vst[v]) rDFS(v);
  }
  void solve(){
    nScc = 0;
    vec.clear();
    for (int i=0; i<n; i++) vst[i] = 0;
    for (int i=0; i<n; i++)
      if (!vst[i]) DFS(i);
    reverse(vec.begin(),vec.end());
    for (int i=0; i<n; i++) vst[i] = 0;
    for (auto v : vec){
      if (!vst[v]){
        rDFS(v);
        nScc++;
      }
    }
  }
};
```

3.4 DMST_with_sol

```
const int INF = 1029384756;

struct edge_t{
  int u,v,w;
  set< pair<int,int> > add, sub;
  edge_t() : u(-1), v(-1), w(0) {}
  edge_t(int _u, int _v, int _w) {
    u = _u; v = _v; w = _w;
    add.insert({u, v});
  }
  edge_t& operator += (const edge_t& obj) {
    w += obj.w;
    FOR (it, obj.add) {
      if (!sub.count(*it)) add.insert(*it);
      else sub.erase(*it);
    }
    FOR (it, obj.sub) {
      if (!add.count(*it)) sub.insert(*it);
      else add.erase(*it);
    }
    return *this;
  }
  edge_t& operator -= (const edge_t& obj) {
    w -= obj.w;
    FOR (it, obj.sub) {
      if (!sub.count(*it)) add.insert(*it);
      else sub.erase(*it);
    }
    for (auto it : obj.add) {
      if (!add.count(it)) sub.insert(it);
      else add.erase(it);
    }
    return *this;
  }
}eg[MXN*MXN],prv[MXN],EDGE_INF(-1,-1,INF);
int N,M;
int cid,incyc[MXN],contracted[MXN];
vector<int> E[MXN];

edge_t dmst(int rt){
  edge_t cost;
  for (int i=0; i<N; i++){
    contracted[i] = incyc[i] = 0;
    prv[i] = EDGE_INF;
  }
  cid = 0;
  int u,v;
  while (true){
    for (v=0; v<N; v++){
      if (v != rt && !contracted[v] && prv[v].w == INF)
          break;
    }
    if (v >= N) break; // end
    for (int i=0; i<M; i++){
      if (eg[i].v == v && eg[i].w < prv[v].w)
        prv[v] = eg[i];
    }
    if (prv[v].w == INF) // not connected
      return EDGE_INF;
    cost += prv[v];
    for (u=prv[v].u; u!=v && u!=-1; u=prv[u].u);
    if (u == -1) continue;
    incyc[v] = ++cid;
    for (u=prv[v].u; u!=v; u=prv[u].u){
      contracted[u] = 1;
      incyc[u] = cid;
    }
    for (int i=0; i<M; i++){
      if (incyc[eg[i].u] != cid && incyc[eg[i].v] ==
          cid){
        eg[i] -= prv[eg[i].v];
      }
    }
    for (int i=0; i<M; i++){
      if (incyc[eg[i].u] == cid) eg[i].u = v;
      if (incyc[eg[i].v] == cid) eg[i].v = v;
      if (eg[i].u == eg[i].v) eg[i--] = eg[--M];
    }
    for (int i=0; i<N; i++){
      if (contracted[i]) continue;
      if (prv[i].u>=0 && incyc[prv[i].u] == cid)
        prv[i].u = v;
    }
    prv[v] = EDGE_INF;
  }
  return cost;
}

void solve(){
  edge_t cost = dmst(0);
  for (auto it : cost.add){ // find a solution
    E[it.F].PB(it.S);
    prv[it.S] = edge_t(it.F,it.S,0);
  }
}
```

3.5 Dominator Tree

```
// idom[n] is the unique node that strictly dominates n
     but does
// not strictly dominate any other node that strictly
    dominates n.
// idom[n] = 0 if n is entry or the entry cannot reach
    n.
struct DominatorTree{
  static const int MAXN = 200010;
  int n,s;
  vector<int> g[MAXN],pred[MAXN];
  vector<int> cov[MAXN];
  int dfn[MAXN],nfd[MAXN],ts;
  int par[MAXN];
  int sdom[MAXN],idom[MAXN];
  int mom[MAXN],mn[MAXN];
```

```
  inline bool cmp(int u,int v) { return dfn[u] < dfn[v
      ]; }

  int eval(int u) {
    if(mom[u] == u) return u;
    int res = eval(mom[u]);
    if(cmp(sdom[mn[mom[u]]],sdom[mn[u]]))
      mn[u] = mn[mom[u]];
    return mom[u] = res;
  }

  void init(int _n, int _s) {
    n = _n;
    s = _s;
    REP1(i,1,n) {
      g[i].clear();
      pred[i].clear();
      idom[i] = 0;
    }
  }
  void add_edge(int u, int v) {
    g[u].push_back(v);
    pred[v].push_back(u);
  }
  void DFS(int u) {
    ts++;
    dfn[u] = ts;
    nfd[ts] = u;
    for(int v:g[u]) if(dfn[v] == 0) {
      par[v] = u;
      DFS(v);
    }
  }
  void build() {
    ts = 0;
    REP1(i,1,n) {
      dfn[i] = nfd[i] = 0;
      cov[i].clear();
      mom[i] = mn[i] = sdom[i] = i;
    }
    DFS(s);
    for (int i=ts; i>=2; i--) {
      int u = nfd[i];
      if(u == 0) continue ;
      for(int v:pred[u]) if(dfn[v]) {
        eval(v);
        if(cmp(sdom[mn[v]],sdom[u])) sdom[u] = sdom[mn[
            v]];
      }
      cov[sdom[u]].push_back(u);
      mom[u] = par[u];
      for(int w:cov[par[u]]) {
        eval(w);
        if(cmp(sdom[mn[w]],par[u])) idom[w] = mn[w];
        else idom[w] = par[u];
      }
      cov[par[u]].clear();
    }
    REP1(i,2,ts) {
      int u = nfd[i];
      if(u == 0) continue ;
      if(idom[u] != sdom[u]) idom[u] = idom[idom[u]];
    }
  }
}dom;
```

3.6 Maximum Clique

```
class MaxClique {
public:
    static const int MV = 210;

    int V;
    int el[MV][MV/30+1];
    int dp[MV];
    int ans;
    int s[MV][MV/30+1];
    vector<int> sol;

    void init(int v) {
        V = v; ans = 0;
        FZ(el); FZ(dp);
    }

    /* Zero Base */
    void addEdge(int u, int v) {
        if(u > v) swap(u, v);
        if(u == v) return;
        el[u][v/32] |= (1<<(v%32));
    }

    bool dfs(int v, int k) {
        int c = 0, d = 0;
        for(int i=0; i<(V+31)/32; i++) {
            s[k][i] = el[v][i];
            if(k != 1) s[k][i] &= s[k-1][i];
            c += __builtin_popcount(s[k][i]);
        }
        if(c == 0) {
            if(k > ans) {
                ans = k;
                sol.clear();
                sol.push_back(v);
                return 1;
            }
            return 0;
        }
        for(int i=0; i<(V+31)/32; i++) {
            for(int a = s[k][i]; a ; d++) {
                if(k + (c-d) <= ans) return 0;
                int lb = a&(-a), lg = 0;
                a ^= lb;
                while(lb!=1) {
                    lb = (unsigned int)(lb) >> 1;
                    lg ++;
                }
                int u = i*32 + lg;
                if(k + dp[u] <= ans) return 0;
                if(dfs(u, k+1)) {
                    sol.push_back(v);
                    return 1;
                }
            }
        }
        return 0;
    }

    int solve() {
        for(int i=V-1; i>=0; i--) {
            dfs(i, 1);
            dp[i] = ans;
        }
        return ans;
    }
};
```

3.7 MinimumMeanCycle

```
/* minimum mean cycle */
const int MAXE = 1805;
const int MAXN = 35;
const double inf = 1029384756;
const double eps = 1e-6;
struct Edge {
  int v,u;
  double c;
};
int n,m,prv[MAXN][MAXN], prve[MAXN][MAXN], vst[MAXN];
Edge e[MAXE];
vector<int> edgeID, cycle, rho;
double d[MAXN][MAXN];
inline void bellman_ford() {
  for(int i=0; i<n; i++) d[0][i]=0;
  for(int i=0; i<n; i++) {
    fill(d[i+1], d[i+1]+n, inf);
    for(int j=0; j<m; j++) {
      int v = e[j].v, u = e[j].u;
      if(d[i][v]<inf && d[i+1][u]>d[i][v]+e[j].c) {
        d[i+1][u] = d[i][v]+e[j].c;
        prv[i+1][u] = v;
        prve[i+1][u] = j;
      }
    }
  }
}
double karp_mmc() {
  // returns inf if no cycle, mmc otherwise
```

```
  double mmc=inf;
  int st = -1;
  bellman_ford();
  for(int i=0; i<n; i++) {
    double avg=-inf;
    for(int k=0; k<n; k++) {
      if(d[n][i]<inf-eps) avg=max(avg,(d[n][i]-d[k][i])
          /(n-k));
      else avg=max(avg,inf);
    }
    if (avg < mmc) tie(mmc, st) = tie(avg, i);
  }
  for(int i=0; i<n; i++) vst[i] = 0;
  edgeID.clear(); cycle.clear(); rho.clear();
  for (int i=n; !vst[st]; st=prv[i--][st]) {
    vst[st]++;
    edgeID.PB(prve[i][st]);
    rho.PB(st);
  }
  while (vst[st] != 2) {
    int v = rho.back(); rho.pop_back();
    cycle.PB(v);
    vst[v]++;
  }
  reverse(ALL(edgeID));
  edgeID.resize(SZ(cycle));
  return mmc;
}
```

4 Flow

4.1 Dinic

```
struct Dinic{
  static const int MXN = 10000;
  struct Edge{ int v,f,re; };
  int n,s,t,level[MXN];
  vector<Edge> E[MXN];
  void init(int _n, int _s, int _t){
    n = _n; s = _s; t = _t;
    for (int i=0; i<n; i++) E[i].clear();
  }
  void add_edge(int u, int v, int f){
    E[u].PB({v,f,SZ(E[v])});
    E[v].PB({u,0,SZ(E[u])-1});
  }
  bool BFS(){
    for (int i=0; i<n; i++) level[i] = -1;
    queue<int> que;
    que.push(s);
    level[s] = 0;
    while (!que.empty()){
      int u = que.front(); que.pop();
      for (auto it : E[u]){
        if (it.f > 0 && level[it.v] == -1){
          level[it.v] = level[u]+1;
          que.push(it.v);
        }
      }
    }
    return level[t] != -1;
  }
  int DFS(int u, int nf){
    if (u == t) return nf;
    int res = 0;
    for (auto &it : E[u]){
      if (it.f > 0 && level[it.v] == level[u]+1){
        int tf = DFS(it.v, min(nf,it.f));
        res += tf; nf -= tf; it.f -= tf;
        E[it.v][it.re].f += tf;
        if (nf == 0) return res;
      }
    }
    if (!res) level[u] = -1;
    return res;
  }
  int flow(int res=0){
    while ( BFS() )
      res += DFS(s,2147483647);
    return res;
  }
}flow;
```

4.2 Cost Flow

```
typedef pair<long long, long long> pll;
struct CostFlow {
  static const int MXN = 205;
  static const long long INF = 102938475610293847LL;
  struct Edge {
    int v, r;
    long long f, c;
  };
  int n, s, t, prv[MXN], prvL[MXN], inq[MXN];
  long long dis[MXN], fl, cost;
  vector<Edge> E[MXN];
  void init(int _n, int _s, int _t) {
    n = _n; s = _s; t = _t;
    for (int i=0; i<n; i++) E[i].clear();
    fl = cost = 0;
  }
  void add_edge(int u, int v, long long f, long long c)
       {
    E[u].PB({v, SZ(E[v])  , f,  c});
    E[v].PB({u, SZ(E[u])-1, 0, -c});
  }
  pll flow() {
    while (true) {
      for (int i=0; i<n; i++) {
        dis[i] = INF;
        inq[i] = 0;
      }
      dis[s] = 0;
      queue<int> que;
      que.push(s);
      while (!que.empty()) {
        int u = que.front(); que.pop();
        inq[u] = 0;
        for (int i=0; i<SZ(E[u]); i++) {
          int v = E[u][i].v;
          long long w = E[u][i].c;
          if (E[u][i].f > 0 && dis[v] > dis[u] + w) {
            prv[v] = u; prvL[v] = i;
            dis[v] = dis[u] + w;
            if (!inq[v]) {
              inq[v] = 1;
              que.push(v);
            }
          }
        }
      }
      if (dis[t] == INF) break;
      long long tf = INF;
      for (int v=t, u, l; v!=s; v=u) {
        u=prv[v]; l=prvL[v];
        tf = min(tf, E[u][l].f);
      }
      for (int v=t, u, l; v!=s; v=u) {
        u=prv[v]; l=prvL[v];
        E[u][l].f -= tf;
        E[v][E[u][l].r].f += tf;
      }
      cost += tf * dis[t];
      fl += tf;
    }
    return {fl, cost};
  }
}flow;
```

4.3 Kuhn Munkres

```
struct KM{
// Maximum Bipartite Weighted Matching (Perfect Match)
  static const int MXN = 650;
  static const int INF = 2147483647; // long long
  int n,match[MXN],vx[MXN],vy[MXN];
  int edge[MXN][MXN],lx[MXN],ly[MXN],slack[MXN];
  // ^^^^ long long
  void init(int _n){
    n = _n;
    for (int i=0; i<n; i++)
      for (int j=0; j<n; j++)
        edge[i][j] = 0;
  }
  void add_edge(int x, int y, int w){ // long long
    edge[x][y] = w;
```

```
  }
  bool DFS(int x){
    vx[x] = 1;
    for (int y=0; y<n; y++){
      if (vy[y]) continue;
      if (lx[x]+ly[y] > edge[x][y]){
        slack[y] = min(slack[y], lx[x]+ly[y]-edge[x][y
            ]);
      } else {
        vy[y] = 1;
        if (match[y] == -1 || DFS(match[y])){
          match[y] = x;
          return true;
        }
      }
    }
    return false;
  }
  int solve(){
    fill(match,match+n,-1);
    fill(lx,lx+n,-INF);
    fill(ly,ly+n,0);
    for (int i=0; i<n; i++)
      for (int j=0; j<n; j++)
        lx[i] = max(lx[i], edge[i][j]);
    for (int i=0; i<n; i++){
      fill(slack,slack+n,INF);
      while (true){
        fill(vx,vx+n,0);
        fill(vy,vy+n,0);
        if ( DFS(i) ) break;
        int d = INF; // long long
        for (int j=0; j<n; j++)
          if (!vy[j]) d = min(d, slack[j]);
        for (int j=0; j<n; j++){
          if (vx[j]) lx[j] -= d;
          if (vy[j]) ly[j] += d;
          else slack[j] -= d;
        }
      }
    }
    int res=0;
    for (int i=0; i<n; i++)
      res += edge[match[i]][i];
    return res;
  }
}graph;
```

4.4 SW-Mincut

```
struct SW{ // O(V^3) 0-base
  static const int MXN = 514;
  int n,vst[MXN],del[MXN];
  int edge[MXN][MXN],wei[MXN];
  void init(int _n){
    n = _n;
    for (int i=0; i<n; i++) {
      for (int j=0; j<n; j++)
        edge[i][j] = 0;
      del[i] = 0;
    }
  }
  void add_edge(int u, int v, int w){
    edge[u][v] += w;
    edge[v][u] += w;
  }
  void search(int &s, int &t){
    for (int i=0; i<n; i++)
      vst[i] = wei[i] = 0;
    s = t = -1;
    while (true){
      int mx=-1, cur=0;
      for (int i=0; i<n; i++)
        if (!del[i] && !vst[i] && mx<wei[i])
          cur = i, mx = wei[i];
      if (mx == -1) break;
      vst[cur] = 1;
      s = t;
      t = cur;
      for (int i=0; i<n; i++)
        if (!vst[i] && !del[i]) wei[i] += edge[cur][i];
    }
  }
  int solve(){
    int res = 2147483647;
    for (int i=0,x,y; i<n-1; i++){
      search(x,y);
      res = min(res,wei[y]);
      del[y] = 1;
      for (int j=0; j<n; j++)
        edge[x][j] = (edge[j][x] += edge[y][j]);
    }
    return res;
  }
}graph;
```

4.5 Maximum Simple Graph Matching

```
struct GenMatch { // 1-base
  static const int MAXN = 514;
  int V;
  bool el[MAXN][MAXN];
  int pr[MAXN];
  bool inq[MAXN],inp[MAXN],inb[MAXN];
  queue<int> qe;
  int st,ed;
  int nb;
  int bk[MAXN],djs[MAXN];
  int ans;
  void init(int _V) {
    V = _V;
    for(int i = 0; i <= V; i++) {
      for(int j = 0; j <= V; j++) el[i][j] = 0;
      pr[i] = bk[i] = djs[i] = 0;
      inq[i] = inp[i] = inb[i] = 0;
    }
    ans = 0;
  }
  void add_edge(int u, int v) {
    el[u][v] = el[v][u] = 1;
  }
  int lca(int u,int v) {
    for(int i = 0; i <= V; i++) inp[i] = 0;
    while(1) {
      u = djs[u];
      inp[u] = true;
      if(u == st) break;
      u = bk[pr[u]];
    }
    while(1) {
      v = djs[v];
      if(inp[v]) return v;
      v = bk[pr[v]];
    }
    return v;
  }
  void upd(int u) {
    int v;
    while(djs[u] != nb) {
      v = pr[u];
      inb[djs[u]] = inb[djs[v]] = true;
      u = bk[v];
      if(djs[u] != nb) bk[u] = v;
    }
  }
  void blo(int u,int v) {
    nb = lca(u,v);
    for (int i=0; i<=V; i++) inb[i] = 0;
    upd(u); upd(v);
    if(djs[u] != nb) bk[u] = v;
    if(djs[v] != nb) bk[v] = u;
    for(int tu = 1; tu <= V; tu++)
      if(inb[djs[tu]]) {
        djs[tu] = nb;
        if(!inq[tu]){
          qe.push(tu);
          inq[tu] = 1;
        }
      }
  }
  void flow() {
    for(int i = 1; i <= V; i++) {
      inq[i] = 0;
      bk[i] = 0;
      djs[i] = i;
    }

    while(qe.size()) qe.pop();
```

```
    qe.push(st);
    inq[st] = 1;
    ed = 0;
    while(qe.size()) {
      int u = qe.front(); qe.pop();
      for(int v = 1; v <= V; v++)
        if(el[u][v] && (djs[u] != djs[v]) && (pr[u] !=
            v)) {
          if((v == st) || ((pr[v] > 0) && bk[pr[v]] >
              0))
            blo(u,v);
          else if(bk[v] == 0) {
            bk[v] = u;
            if(pr[v] > 0) {
              if(!inq[pr[v]]) qe.push(pr[v]);
            } else {
              ed = v;
              return;
            }
          }
        }
    }
  }
  void aug() {
    int u,v,w;
    u = ed;
    while(u > 0) {
      v = bk[u];
      w = pr[v];
      pr[v] = u;
      pr[u] = v;
      u = w;
    }
  }
  int solve() {
    for(int i = 0; i <= V; i++) pr[i] = 0;
    for(int u = 1; u <= V; u++)
      if(pr[u] == 0) {
        st = u;
        flow();
        if(ed > 0) {
          aug();
          ans ++;
        }
      }
    return ans;
  }
}G;

int main() {
  G.init(V);
  for(int i=0; i<E; i++) {
    int u, v;
    cin >> u >> v;
    G.add_edge(u, v);
  }
  cout << G.solve() << endl;
}
```

4.6 Minimum Weight Matching (Clique version)

```
struct Graph {
  // Minimum General Weighted Matching (Perfect Match)
      0-base
  static const int MXN = 105;

  int n, edge[MXN][MXN];
  int match[MXN],dis[MXN],onstk[MXN];
  vector<int> stk;

  void init(int _n) {
    n = _n;
    for (int i=0; i<n; i++)
      for (int j=0; j<n; j++)
        edge[i][j] = 0;
  }
  void add_edge(int u, int v, int w) {
    edge[u][v] = edge[v][u] = w;
  }
  bool SPFA(int u){
    if (onstk[u]) return true;
    stk.PB(u);
    onstk[u] = 1;
    for (int v=0; v<n; v++){
      if (u != v && match[u] != v && !onstk[v]){
        int m = match[v];
        if (dis[m] > dis[u] - edge[v][m] + edge[u][v]){
          dis[m] = dis[u] - edge[v][m] + edge[u][v];
          onstk[v] = 1;
          stk.PB(v);
          if (SPFA(m)) return true;
          stk.pop_back();
          onstk[v] = 0;
        }
      }
    }
    onstk[u] = 0;
    stk.pop_back();
    return false;
  }

  int solve() {
    // find a match
    for (int i=0; i<n; i+=2){
      match[i] = i+1;
      match[i+1] = i;
    }
    while (true){
      int found = 0;
      for (int i=0; i<n; i++)
        dis[i] = onstk[i] = 0;
      for (int i=0; i<n; i++){
        stk.clear();
        if (!onstk[i] && SPFA(i)){
          found = 1;
          while (SZ(stk)>=2){
            int u = stk.back(); stk.pop_back();
            int v = stk.back(); stk.pop_back();
            match[u] = v;
            match[v] = u;
          }
        }
      }
      if (!found) break;
    }
    int ret = 0;
    for (int i=0; i<n; i++)
      ret += edge[i][match[i]];
    ret /= 2;
    return ret;
  }
}graph;
```

4.7 (+1) SW-mincut $O(NM)$

```
// {{{ StoerWagner
const int inf=1000000000;
// should be larger than max.possible mincut
class StoerWagner {
  public:
    int n,mc; // node id in [0,n-1]
    vector<int> adj[MAXN];
    int cost[MAXN][MAXN];
    int cs[MAXN];
    bool merged[MAXN],sel[MAXN];
    // --8<-- include only if cut is explicitly needed
      DisjointSet djs;
    vector<int> cut;
    //--8<------------------------------------------
      StoerWagner(int _n):n(_n),mc(inf),djs(_n) {
        for(int i=0;i<n;i++)
          merged[i]=0;
        for(int i=0;i<n;i++)
          for(int j=0;j<n;j++)
            cost[i][j]=cost[j][i]=0;
      }
    void append(int v,int u,int c) {
      if(v==u) return;
      if(!cost[v][u]&&c) {
        adj[v].PB(u);
        adj[u].PB(v);
      }
      cost[v][u]+=c;
      cost[u][v]+=c;
    }
    void merge(int v,int u) {
      merged[u]=1;
      for(int i=0;i<n;i++)
```

```
      append(v,i,cost[u][i]);
    // --8<-- include only if cut is explicitly
        needed
      djs.merge(v,u);
    //
        --8<----------------------------------------
  }
  void phase() {
    priority_queue<pii> pq;
    for(int v=0;v<n;v++) {
      if(merged[v]) continue;
      cs[v]=0;
      sel[v]=0;
      pq.push({0,v});
    }
    int v,s,pv;
    while(pq.size()) {
      if(cs[pq.top().S]>pq.top().F) {
        pq.pop();
        continue;
      }
      pv=v;
      v=pq.top().S;
      s=pq.top().F;
      pq.pop();
      sel[v]=1;
      for(int i=0;i<adj[v].size();i++) {
        int u=adj[v][i];
        if(merged[u]||sel[u]) continue;
        cs[u]+=cost[v][u];
        pq.push({cs[u],u});
      }
    }
    if(s<mc) {
      mc=s;
      // --8<-- include only if cut is explicitly
      needed ------
        cut.clear();
      for(int i=0;i<n;i++)
        if(djs.getrep(i)==djs.getrep(v)) cut.PB(i);
      //--8<----------------------------------------
    }
    merge(v,pv);
  }
  int mincut() {
    if(mc==inf) {
      for(int t=0;t<n-1;t++)
        phase();

    return mc;
  }
  // --8<-- include only if cut is explicitly needed
  ------
    vector<int> getcut() { // return one side of the
        cut
      mincut();
      return cut;
    }
  //--8<----------------------------------------
};
// }}}
```

5 Math

5.1 ax+by=gcd

```
typedef pair<int, int> pii;

pii gcd(int a, int b){
  if(b == 0) return make_pair(1, 0);
  else{
    int p = a / b;
    pii q = gcd(b, a % b);
    return make_pair(q.second, q.first - q.second * p);
  }
}
```

5.2 Fast Fourier Transform

```
// const int MAXN = 262144;
// (must be 2^k)

typedef long double ld;
typedef complex<ld> cplx;
const ld PI = acosl(-1);
const cplx I(0, 1);

cplx omega[MAXN+1];
void pre_fft()
{
  for(int i=0; i<=MAXN; i++)
    omega[i] = exp(i * 2 * PI / MAXN * I);
}
void fft(int n, cplx a[], bool inv=false)
{
  int basic = MAXN / n;
  int theta = basic;
  for (int m = n; m >= 2; m >>= 1) {
    int mh = m >> 1;
    for (int i = 0; i < mh; i++) {
      cplx w = omega[inv ? MAXN-(i*theta%MAXN) : i*
          theta%MAXN];
      for (int j = i; j < n; j += m) {
        int k = j + mh;
        cplx x = a[j] - a[k];
        a[j] += a[k];
        a[k] = w * x;
      }
    }
    theta = (theta * 2) % MAXN;
  }
  int i = 0;
  for (int j = 1; j < n - 1; j++) {
    for (int k = n >> 1; k > (i ^= k); k >>= 1);
    if (j < i) swap(a[i], a[j]);
  }
  if (inv)
    for (i = 0; i < n; i++)
      a[i] /= n;
}
```

5.3 Fast Linear Recurrence

```
ll n,m,dp[N+N];
void pre_dp(){
  dp[0]= 1;
  ll bdr = min(m+m,n);
  for(ll i=1; i<=bdr; i++)
    for(ll j=i-1; j>=max(0ll,i-m); j--)
      dp[i]= add(dp[i],dp[j]);
}
vector<ll> Mul(const vector<ll>& v1,const vector<ll>&
    v2){
  int sz1 = (int)v1.size();
  int sz2 = (int)v2.size();
  assert(sz1 == m and sz2 == m);
  vector<ll> _v(m+m);
  for(int i=0; i<m+m; i++) _v[i]= 0;
  // expand
  for(int i=0; i<sz1; i++)
    for(int j=0; j<sz2; j++)
      _v[i+j+1]= add(_v[i+j+1],mul(v1[i],v2[j]));
  // shrink
  for(int i=0; i<m; i++)
    for(int j=1; j<=m; j++)
      _v[i + j]= add(_v[i + j],_v[i]);
  for(int i=0; i<m; i++)
    _v[i]= _v[i + m];
  _v.resize(m);
  return _v;
}
vector<ll> I,A;
ll solve(){
  pre_dp();
  if(n <= m+m)return dp[n];
  I.resize(m);
  A.resize(m);
  for(int i=0; i<m; i++) I[i]=A[i]=1;
  // dp[n]= /Sum_{i=0}^{m-1} A_i * dp[n - i - 1]
  ll dlt = (n - m) / m;
  ll rdlt = dlt * m;
  while(dlt){
    if(dlt & 1ll) I = Mul(I,A);
```

```
    A = Mul(A,A);
    dlt >>= 1;
  }
  ll ans = 0;
  for(int i=0; i<m; i++)
    ans = add(ans,mul(I[i],dp[n-i-1-rdlt]));
  return ans;
}
```

5.4 (+1) ntt

```
int P=605028353,root=3,MAXNUM=262144;
// Remember coefficient are mod P
/*
p=a*2^n+1
n   2^n         p             a     root
5   32          97            3     5
6   64          193           3     5
7   128         257           2     3
8   256         257           1     3
9   512         7681          15    17
10  1024        12289         12    11
11  2048        12289         6     11
12  4096        12289         3     11
13  8192        40961         5     3
14  16384       65537         4     3
15  32768       65537         2     3
16  65536       65537         1     3
17  131072      786433        6     10
18  262144      786433        3     10 (605028353,
    2308, 3)
19  524288      5767169       11    3
20  1048576     7340033       7     3
21  2097152     23068673      11    3
22  4194304     104857601     25    3
23  8388608     167772161     20    3
24  16777216    167772161     10    3
25  33554432    167772161     5     3 (1107296257, 33,
    10)
26  67108864    469762049     7     3
27  134217728   2013265921    15    31
*/
int bigmod(long long a,int b){
  if(b==0)return 1;
  return (bigmod((a*a)%P,b/2)*(b%2?a:1ll))%P;
}
int inv(int a,int b){
  if(a==1)return 1;
  return (((long long)(a-inv(b%a,a))*b+1)/a)%b;
}
std::vector<long long> ps(MAXNUM);
std::vector<int> rev(MAXNUM);
struct poly{
  std::vector<unsigned int> co;
  int n;//polynomial degree = n
  poly(int d){n=d;co.resize(n+1,0);}
  void trans2(int NN){
    int r=0,st,N;
    unsigned int a,b;
    while((1<<r)<(NN>>1))++r;
    for(N=2;N<=NN;N<<=1,--r){
      for(st=0;st<NN;st+=N){
        int i,ss=st+(N>>1);
        for(i=(N>>1)-1;i>=0;--i){
          a=co[st+i]; b=(ps[i<<r]*co[ss+i])%P;
          co[st+i]=a+b; if(co[st+i]>=P)co[st+i]-=P;
          co[ss+i]=a+P-b; if(co[ss+i]>=P)co[ss+i]-=P;
        }
      }
    }
  }
  void trans1(int NN){
    int r=0,st,N;
    unsigned int a,b;
    for(N=NN;N>1;N>>=1,++r){
      for(st=0;st<NN;st+=N){
        int i,ss=st+(N>>1);
        for(i=(N>>1)-1;i>=0;--i){
          a=co[st+i]; b=co[ss+i];
          co[st+i]=a+b; if(co[st+i]>=P)co[st+i]-=P;
          co[ss+i]=((a+P-b)*ps[i<<r])%P;
        }
      }
    }
  }
  poly operator*(const poly& _b)const{
    poly a=*this,b=_b;
    int k=n+b.n,i,N=1;
    while(N<=k)N*=2;
    a.co.resize(N,0); b.co.resize(N,0);
    int r=bigmod(root,(P-1)/N),Ni=inv(N,P);
    ps[0]=1;
    for(i=1;i<N;++i)ps[i]=(ps[i-1]*r)%P;
    a.trans1(N);b.trans1(N);
    for(i=0;i<N;++i)a.co[i]=((long long)a.co[i]*b.co[i
        ])%P
      ;
    r=inv(r,P);
    for(i=1;i<N/2;++i)std::swap(ps[i],ps[N-i]);
    a.trans2(N);
    for(i=0;i<N;++i)a.co[i]=((long long)a.co[i]*Ni)%P;
    a.n=n+_b.n; return a;
  }
};
```

5.5 Mod

```
/// _fd(a,b)  floor(a/b).
/// _rd(a,m)  a-floor(a/m)*m.
/// _pv(a,m,r) largest x s.t x<=a && x%m == r.
/// _nx(a,m,r) smallest x s.t x>=a && x%m == r.
/// _ct(a,b,m,r) |A| , A = { x : a<=x<=b && x%m == r }.

int _fd(int a,int b){ return a<0?(~a/b-1):a/b; }
int _rd(int a,int m){ return a-_fd(a,m)*m; }
int _pv(int a,int m,int r)
{
    r=(r%m+m)%m;
    return _fd(a-r,m)*m+r;
}
int _nt(int a,int m,int r)
{
    m=abs(m);
    r=(r%m+m)%m;
    return _fd(a-r-1,m)*m+r+m;
}
int _ct(int a,int b,int m,int r)
{
    m=abs(m);
    a=_nt(a,m,r);
    b=_pv(b,m,r);
    return (a>b)?0:((b-a+m)/m);
}
```

5.6 (+1) Miller Rabin

```
// n < 4,759,123,141        3 :  2, 7, 61
// n < 1,122,004,669,633    4 :  2, 13, 23, 1662803
// n < 3,474,749,660,383          6 :  pirmes <= 13
// n < 2^64                       7 :
// 2, 325, 9375, 28178, 450775, 9780504, 1795265022
// Make sure testing integer is in range [2, n-2] if
// you want to use magic.
long long power(long long x,long long p,long long mod){
  long long s=1,m=x;
  while(p) {
    if(p&1) s=mult(s,m,mod);
    p>>=1;
    m=mult(m,m,mod);
  }
  return s;
}
bool witness(long long a,long long n,long long u,int t)
    {
  long long x=power(a,u,n);
  for(int i=0;i<t;i++) {
    long long nx=mult(x,x,n);
    if(nx==1&&x!=1&&x!=n-1) return 1;
    x=nx;
  }
  return x!=1;
}
bool miller_rabin(long long n,int s=100) {
  // iterate s times of witness on n
  // return 1 if prime, 0 otherwise
  if(n<2) return 0;
```

```
  if(!(n&1)) return n==2;
  long long u=n-1;
  int t=0;
  // n-1 = u*2^t
  while(!(u&1)) {
    u>>=1;
    t++;
  }
  while(s--) {
    long long a=randll()%(n-1)+1;
    if(witness(a,n,u,t)) return 0;
  }
  return 1;
}
```

5.7 Pollard Rho

```
// does not work when n is prime
long long modit(long long x,long long mod) {
  if(x>=mod) x-=mod;
  //if(x<0) x+=mod;
  return x;
}
long long mult(long long x,long long y,long long mod) {
  long long s=0,m=x%mod;
  while(y) {
    if(y&1) s=modit(s+m,mod);
    y>>=1;
    m=modit(m+m,mod);
  }
  return s;
}
long long f(long long x,long long mod) {
  return modit(mult(x,x,mod)+1,mod);
}
long long pollard_rho(long long n) {
  if(!(n&1)) return 2;
  while (true) {
    long long y=2, x=rand()%(n-1)+1, res=1;
    for (int sz=2; res==1; sz*=2) {
      for (int i=0; i<sz && res<=1; i++) {
        x = f(x, n);
        res = __gcd(abs(x-y), n);
      }
      y = x;
    }
    if (res!=0 && res!=n) return res;
  }
}
```

5.8 Algorithms about Primes

```
/*
 * 12721
 * 13331
 * 14341
 * 75577
 * 123457
 * 222557
 * 556679
 * 999983
 * 1097774749
 * 1076767633
 * 100102021
 * 999997771
 * 1001010013
 * 1000512343
 * 987654361
 * 999991231
 * 999888733
 * 98789101
 * 987777733
 * 999991921
 * 1010101333
 * 1010102101
 * 1000000000039
 * 10000000000000037
 * 2305843009213693951
 * 4611686018427387847
 * 9223372036854775783
 * 18446744073709551557
 */
```

```
int mu[MX],p_tbl[MX];
vector<int> primes;
void sieve() {
  mu[1] = p_tbl[1] = 1;
  for (int i=2; i<MX; i++) {
    if (!p_tbl[i]) {
      p_tbl[i] = i;
      primes.PB(i);
      mu[i] = -1;
    }
    for (auto p : primes) {
      int x = i*p;
      if (x >= M) break;
      p_tbl[x] = p;
      mu[x] = -mu[i];
      if (i%p==0) {
        mu[x] = 0;
        break;
      }
    }
  }
}

vector<int> factor(int x) {
  vector<int> fac{1};
  while (x > 1) {
    int fn=SZ(fac), p=p_tbl[x], pos=0;
    while (x%p == 0) {
      x /= p;
      for (int i=0; i<fn; i++)
        fac.PB(fac[pos++]*p);
    }
  }
  return fac;
}
```

5.9 (+1) PolynomialGenerator

```
class PolynomialGenerator {
  /* for a nth-order polynomial f(x), *
   * given f(0), f(1), ..., f(n) *
   * express f(x) as sigma_i{c_i*C(x,i)} */
  public:
    int n;
    vector<long long> coef;
    // initialize and calculate f(x), vector _fx should
        be
    // filled with f(0) to f(n)
      PolynomialGenerator(int _n,vector<long long> _fx)
          :n(_n
          ),coef(_fx) {
        for(int i=0;i<n;i++)
          for(int j=n;j>i;j--)
            coef[j]-=coef[j-1];
      }
    // evaluate f(x), runs in O(n)
    long long eval(int x) {
      long long m=1,ret=0;
      for(int i=0;i<=n;i++) {
        ret+=coef[i]*m;
        m=m*(x-i)/(i+1);
      }
      return ret;
    }
};
```

5.10 Pseudoinverse of Square matrix

```
Mat pinv(Mat m)
{
  Mat res = I;

  FZ(used);
  for(int i=0; i<W; i++)
  {
    int piv = -1;
    for(int j=0; j<W; j++)
    {
      if(used[j]) continue;
      if(abs(m.v[j][i]) > EPS)
      {
```

```
        piv = j;
        break;
      }
    }
    if(piv == -1)
      continue;
    used[i] = true;
    swap(m.v[piv], m.v[i]);
    swap(res.v[piv], res.v[i]);

    ld rat = m.v[i][i];
    for(int j=0; j<W; j++)
    {
      m.v[i][j] /= rat;
      res.v[i][j] /= rat;
    }

    for(int j=0; j<W; j++)
    {
      if(j == i) continue;
      rat = m.v[j][i];
      for(int k=0; k<W; k++)
      {
        m.v[j][k] -= rat * m.v[i][k];
        res.v[j][k] -= rat * res.v[i][k];
      }
    }
  }

  for(int i=0; i<W; i++)
  {
    if(used[i]) continue;
    for(int j=0; j<W; j++)
      res.v[i][j] = 0;
  }

  return res;
}
```

5.11 Theorem

5.11.1 Lucas' Theorem

For non-negative integer n, m and prime p, $\binom{m}{n} \equiv \prod_{i=0}^{k} \binom{m_i}{n_i} \pmod{p}$
where m_i is the i-th digit of m in base p.

5.11.2 Sum of Two Squares Thm (Legendre)

For a given positive integer n, let
$D_1 =$ (# of positive integers d dividing N that $1 \equiv d \pmod 4$)
$D_3 =$ (# of positive integers d dividing N that $3 \equiv d \pmod 4$)
then n can be written as a sum of two squares in exactly
$R(n) = 4(D_1 - D_3)$ ways.

5.11.3 Difference of D1-D3 Thm

let $n = 2^t \cdot (p_1^{e_1} \cdot \ldots \cdot p_r^{e_r}) \cdots (q_1^{f_1} \cdot \ldots \cdot q_s^{f_s})$
where p_i, q_i are primes and $1 \equiv p_i \pmod 4, 3 \equiv q_i \pmod 4$
then $D_1 - D_3 = \begin{cases} (e_1+1)(e_2+1)\ldots(e_r+1), & \text{if } f_i \text{ all even} \\ 0, & \text{if any } f_i \text{ is odd} \end{cases}$

5.11.4 Krush–Kuhn–Tucker Conditions

Stationarity
For maximizing $f(x)$: $\nabla f(x^*) = \sum_{i=1}^{m} \mu_i \nabla g_i(x^*) + \sum_{j=1}^{l} \lambda_j \nabla h_j(x^*)$
For minimizing $f(x)$: $-\nabla f(x^*) = \sum_{i=1}^{m} \mu_i \nabla g_i(x^*) + \sum_{j=1}^{l} \lambda_j \nabla h_j(x^*)$

Primal feasibility
$g_i(x^*) \leq 0, \text{ for all } i = 1, \ldots, m$
$h_j(x^*) = 0, \text{ for all } j = 1, \ldots, l$

Dual feasibility
$\mu_i \geq 0, \text{ for all } i = 1, \ldots, m$

Complementary slackness
$\mu_i g_i(x^*) = 0, \text{for all } i = 1, \ldots, m$

5.11.5 Chinese remainder theorem

$x \equiv r_i \mod p_i$
$N = \prod p_i$
$N_i = N/p_i$
$x \equiv \sum r_i N_i (N_i)_{p_i}^{-1} \mod N$

5.12 Simplex

```
const int maxn = 111;
const int maxm = 111;
const double eps = 1E-10;

double a[maxn][maxm], b[maxn], c[maxm], d[maxn][maxm];
double x[maxm];
int ix[maxn + maxm]; // !!! array all indexed from 0
// max{cx} subject to {Ax<=b,x>=0}
// n: constraints, m: vars !!!
// x[] is the optimal solution vector
//
// usage :
// value = simplex(a, b, c, N, M);
double simplex(double a[maxn][maxm], double b[maxn],
    double c[maxm], int n, int m) {
    ++m;
    int r = n, s = m - 1;
    memset(d, 0, sizeof(d));
    for (int i = 0; i < n + m; ++i) ix[i] = i;
    for (int i = 0; i < n; ++i) {
        for (int j = 0; j < m - 1; ++j)
            d[i][j] = -a[i][j];
        d[i][m - 1] = 1;
        d[i][m] = b[i];
        if (d[r][m] > d[i][m]) r = i;
    }
    for (int j = 0; j < m - 1; ++j) d[n][j] = c[j];
    d[n + 1][m - 1] = -1;
    for (double dd;; ) {
        if (r < n) {
            int t = ix[s];
            ix[s] = ix[r + m]; ix[r + m] = t;
            d[r][s] = 1.0 / d[r][s];
            for (int j = 0; j <= m; ++j)
                if (j != s) d[r][j] *= -d[r][s];
            for (int i = 0; i <= n + 1; ++i)
                if (i != r) {
                    for (int j = 0; j <= m; ++j)
                        if (j != s)
                            d[i][j] += d[r][j]*d[i][s];
                    d[i][s] *= d[r][s];
                }
        }
        r = -1; s = -1;
        for (int j = 0; j < m; ++j)
            if (s < 0 || ix[s] > ix[j]) {
                if (d[n + 1][j] > eps || (d[n + 1][j] >
                      -eps && d[n][j] > eps)) s = j;
            }
        if (s < 0) break;
        for (int i=0; i<n; ++i) if (d[i][s] < -eps) {
            if (r < 0 || (dd = d[r][m] / d[r][s] - d[i
                ][m] / d[i][s]) < -eps || (dd < eps &&
                ix[r + m] > ix[i + m])) r = i;
        }
        if (r < 0) return -1; // not bounded
    }
    if (d[n + 1][m] < -eps) return -1; // not
        executable
    double ans = 0;
    for(int i=0; i<m; i++) x[i] = 0;
    for (int i = m; i < n + m; ++i) { // the missing
        enumerated x[i] = 0
        if (ix[i] < m - 1)
        {
            ans += d[i - m][m] * c[ix[i]];
            x[ix[i]] = d[i-m][m];
        }
    }
    return ans;
}
```

6 Geometry

6.1 Point operators

```
#define x first
#define y second

#define cpdd const pdd
```

```
struct pdd : pair<double, double> {
    using pair<double, double>::pair;

    pdd operator + (cpdd &p) const {
        return {x+p.x, y+p.y};
    }

    pdd operator - () const {
        return {-x, -y};
    }

    pdd operator - (cpdd &p) const {
        return (*this) + (-p);
    }

    pdd operator * (double f) const {
        return {f*x, f*y};
    }

    double operator * (cpdd &p) const {
        return x*p.x + y*p.y;
    }
};

double abs(cpdd &p) { return hypot(p.x, p.y); }
double arg(cpdd &p) { return atan2(p.y, p.x); }
double cross(cpdd &p, cpdd &q) { return p.x*q.y - p.y*q
    .x; }
double cross(cpdd &p, cpdd &q, cpdd &o) { return cross(
    p-o, q-o); }
pdd operator * (double f, cpdd &p) { return p*f; } //
    !! Not f*p !!
```

6.2 Intersection of two circles

```
using ld = double;
vector<pdd> interCircle(pdd o1, double r1, pdd o2,
    double r2) {
  ld d2 = (o1 - o2) * (o1 - o2);
  ld d = sqrt(d2);
  if (d < abs(r1-r2)) return {};
  if (d > r1+r2) return {};
  pdd u = 0.5*(o1+o2) + ((r2*r2-r1*r1)/(2*d2))*(o1-o2);
  double A = sqrt((r1+r2+d) * (r1-r2+d) * (r1+r2-d) *
      (-r1+r2+d));
  pdd v = A / (2*d2) * pdd(o1.S-o2.S, -o1.F+o2.F);
  return {u+v, u-v};
}
```

6.3 Intersection of two lines

```
const double EPS = 1e-9;

pdd interPnt(pdd p1, pdd p2, pdd q1, pdd q2, bool &res)
    {
  double f1 = cross(p2, q1, p1);
  double f2 = -cross(p2, q2, p1);
  double f = (f1 + f2);

  if(fabs(f) < EPS) {
    res = false;
    return {};
    }

  res = true;
  return (f2 / f) * q1 + (f1 / f) * q2;
}
```

6.4 Half Plane Intersection

```
const double EPS = 1e-9;

pdd interPnt(Line l1, Line l2, bool &res){
    pdd p1, p2, q1, q2;
    tie(p1, p2) = l1;
    tie(q1, q2) = l2;
  double f1 = cross(p2, q1, p1);
    double f2 = -cross(p2, q2, p1);
  double f = (f1 + f2);
    if(fabs(f) < EPS) {
        res = false;
        return {0, 0};
    }

    res = true;
  return (f2 / f) * q1 + (f1 / f) * q2;
}

bool isin(Line l0, Line l1, Line l2) {
    // Check inter(l1, l2) in l0
    bool res;
    pdd p = interPnt(l1, l2, res);
    return cross(l0.S, p, l0.F) > EPS;
}

/* If no solution, check: 1. ret.size() < 3
 * Or more precisely, 2. interPnt(ret[0], ret[1])
 * in all the lines. (use (l.S - l.F).cross(p - l.F) >
     0
 */
vector<Line> halfPlaneInter(vector<Line> lines) {
    int sz = lines.size();
    vector<double> ata(sz), ord(sz);
    for (int i=0; i<sz; i++) {
        ord[i] = i;
        pdd d = lines[i].S - lines[i].F;
        ata[i] = atan2(d.y, d.x);
    }
    sort(ALL(ord), [&](int i, int j) {
        if (abs(ata[i] - ata[j]) < EPS) {
            return cross(lines[i].S, lines[j].S, lines[
                i].F) < 0;
        }
        return ata[i] < ata[j];
    });
    vector<Line> fin;
    for (int i=0; i<sz; i++) {
        if (!i or fabs(ata[ord[i]] - ata[ord[i-1]]) >
            EPS) {
            fin.PB(lines[ord[i]]);
        }
    }

    deque<Line> dq;
    for (int i=0; i<SZ(fin); i++) {
        while(SZ(dq) >= 2 and
              not isin(fin[i], dq[SZ(dq)-2], dq[SZ(dq)
                  -1])) {
            dq.pop_back();
        }
        while(SZ(dq) >= 2 and
              not isin(fin[i], dq[0], dq[1])) {
            dq.pop_front();
        }
        dq.push_back(fin[i]);
    }

    while (SZ(dq) >= 3 and
           not isin(dq[0], dq[SZ(dq)-2], dq[SZ(dq)-1]))
               {
        dq.pop_back();
    }

    while (SZ(dq) >= 3 and
           not isin(dq[SZ(dq)-1], dq[0], dq[1])) {
        dq.pop_front();
    }
    vector<Line> res(ALL(dq));
    return res;
}
```

6.5 2D Convex Hull

```
vector<pdd> convex_hull(vector<pdd> pt){
  sort(pt.begin(),pt.end());
  int top=0;
  vector<pdd> stk(2*pt.size());
  for (int i=0; i<(int)pt.size(); i++){
    while (top >= 2 && cross(stk[top-1],pt[i],stk[top
        -2]) <= 0)
      top--;
    stk[top++] = pt[i];
```

```
  }
  for (int i=pt.size()-2, t=top+1; i>=0; i--){
    while (top >= t && cross(stk[top-1],pt[i], stk[top
        -2]) <= 0)
      top--;
    stk[top++] = pt[i];
  }
  stk.resize(top-1);
  return stk;
}
```

6.6 3D Convex Hull

```
// return the faces with pt indexes
int flag[MXN][MXN];
struct Point{
  ld x,y,z;
  Point operator - (const Point &b) const {
    return (Point){x-b.x,y-b.y,z-b.z};
  }
  Point operator * (const ld &b) const {
    return (Point){x*b,y*b,z*b};
  }
  ld len() const { return sqrtl(x*x+y*y+z*z); }
  ld dot(const Point &a) const {
    return x*a.x+y*a.y+z*a.z;
  }
  Point operator * (const Point &b) const {
    return (Point){y*b.z-b.y*z,z*b.x-b.z*x,x*b.y-b.x*y
        };
  }
};
Point ver(Point a, Point b, Point c) {
  return (b - a) * (c - a);
}
vector<Face> convex_hull_3D(const vector<Point> pt) {
  int n = SZ(pt);
  REP(i,n) REP(j,n)
    flag[i][j] = 0;

  vector<Face> now;
  now.push_back((Face){0,1,2});
  now.push_back((Face){2,1,0});
  int ftop = 0;
  for (int i=3; i<n; i++){
    ftop++;
    vector<Face> next;
    REP(j, SZ(now)) {
      Face& f=now[j];
      ld d=(pt[i]-pt[f.a]).dot(ver(pt[f.a], pt[f.b], pt
          [f.c]));
      if (d <= 0) next.push_back(f);
      int ff = 0;
      if (d > 0) ff=ftop;
      else if (d < 0) ff=-ftop;
      flag[f.a][f.b] = flag[f.b][f.c] = flag[f.c][f.a]
          = ff;
    }
    REP(j, SZ(now)) {
      Face& f=now[j];
      if (flag[f.a][f.b] > 0 and flag[f.a][f.b] != flag
          [f.b][f.a])
        next.push_back((Face){f.a,f.b,i});
      if (flag[f.b][f.c] > 0 and flag[f.b][f.c] != flag
          [f.c][f.b])
        next.push_back((Face){f.b,f.c,i});
      if (flag[f.c][f.a] > 0 and flag[f.c][f.a] != flag
          [f.a][f.c])
        next.push_back((Face){f.c,f.a,i});
    }
    now=next;
  }
  return now;
}
```

6.7 Minimum Covering Circle

```
struct Mcc{
  // return pair of center and r^2
  static const int MAXN = 1000100;
  int n;
  pdd p[MAXN],cen;
  double r2;

  void init(int _n, pdd _p[]){
    n = _n;
    memcpy(p,_p,sizeof(pdd)*n);
  }
  double sqr(double a){ return a*a; }
  double abs2(pdd a){ return a*a; }
  pdd center(pdd p0, pdd p1, pdd p2) {
    pdd a = p1-p0;
    pdd b = p2-p0;
    double c1=abs2(a)*0.5;
    double c2=abs2(b)*0.5;
    double d = a % b;
    double x = p0.x + (c1 * b.y - c2 * a.y) / d;
    double y = p0.y + (a.x * c2 - b.x * c1) / d;
    return pdd(x,y);
  }

  pair<pdd,double> solve(){
    random_shuffle(p,p+n);
    r2=0;
    for (int i=0; i<n; i++){
      if (abs2(cen-p[i]) <= r2) continue;
      cen = p[i];
      r2 = 0;
      for (int j=0; j<i; j++){
        if (abs2(cen-p[j]) <= r2) continue;
        cen = 0.5 * (p[i]+p[j]);
        r2 = abs2(cen-p[j]);
        for (int k=0; k<j; k++){
          if (abs2(cen-p[k]) <= r2) continue;
          cen = center(p[i],p[j],p[k]);
          r2 = abs2(cen-p[k]);
        }
      }
    }
    return {cen,r2};
  }
}mcc;
```

6.8 KDTree (Nearest Point)

```
const int MXN = 100005;

struct KDTree {
  struct Node {
    int x,y,x1,y1,x2,y2;
    int id,f;
    Node *L, *R;
  }tree[MXN];
  int n;
  Node *root;

  long long dis2(int x1, int y1, int x2, int y2) {
    long long dx = x1-x2;
    long long dy = y1-y2;
    return dx*dx+dy*dy;
  }
  static bool cmpx(Node& a, Node& b){ return a.x<b.x; }
  static bool cmpy(Node& a, Node& b){ return a.y<b.y; }
  void init(vector<pair<int,int>> ip) {
    n = ip.size();
    for (int i=0; i<n; i++) {
      tree[i].id = i;
      tree[i].x = ip[i].first;
      tree[i].y = ip[i].second;
    }
    root = build_tree(0, n-1, 0);
  }
  Node* build_tree(int L, int R, int dep) {
    if (L>R) return nullptr;
    int M = (L+R)/2;
    tree[M].f = dep%2;
    nth_element(tree+L, tree+M, tree+R+1, tree[M].f ?
        cmpy : cmpx);
    tree[M].x1 = tree[M].x2 = tree[M].x;
    tree[M].y1 = tree[M].y2 = tree[M].y;

    tree[M].L = build_tree(L, M-1, dep+1);
    if (tree[M].L) {
      tree[M].x1 = min(tree[M].x1, tree[M].L->x1);
      tree[M].x2 = max(tree[M].x2, tree[M].L->x2);
      tree[M].y1 = min(tree[M].y1, tree[M].L->y1);
```

```
      tree[M].y2 = max(tree[M].y2, tree[M].L->y2);
    }

    tree[M].R = build_tree(M+1, R, dep+1);
    if (tree[M].R) {
      tree[M].x1 = min(tree[M].x1, tree[M].R->x1);
      tree[M].x2 = max(tree[M].x2, tree[M].R->x2);
      tree[M].y1 = min(tree[M].y1, tree[M].R->y1);
      tree[M].y2 = max(tree[M].y2, tree[M].R->y2);
    }

    return tree+M;
  }
  int touch(Node* r, int x, int y, long long d2){
    long long dis = sqrt(d2)+1;
    if (x<r->x1-dis || x>r->x2+dis || y<r->y1-dis || y>
        r->y2+dis)
      return 0;
    return 1;
  }
  void nearest(Node* r, int x, int y, int &mID, long
      long &md2) {
    if (!r || !touch(r, x, y, md2)) return;
    long long d2 = dis2(r->x, r->y, x, y);
    if (d2 < md2 || (d2 == md2 && mID < r->id)) {
      mID = r->id;
      md2 = d2;
    }
    // search order depends on split dim
    if ((r->f == 0 && x < r->x) ||
        (r->f == 1 && y < r->y)) {
      nearest(r->L, x, y, mID, md2);
      nearest(r->R, x, y, mID, md2);
    } else {
      nearest(r->R, x, y, mID, md2);
      nearest(r->L, x, y, mID, md2);
    }
  }
  int query(int x, int y) {
    int id = 1029384756;
    long long d2 = 102938475612345678LL;
    nearest(root, x, y, id, d2);
    return id;
  }
}tree;
```

6.9 Triangulation

```
bool inCircle(pdd a, pdd b, pdd c, pdd d) {
    b = b - a;
    c = c - a;
    d = d - a;
    if (cross(b, c) < 0) swap(b, c);
    double m[3][3] = {
        {b.x, b.y, b*b},
        {c.x, c.y, c*c},
        {d.x, d.y, d*d}
    };

    double det = m[0][0] * (m[1][1]*m[2][2] - m[1][2]*m
        [2][1])
               + m[0][1] * (m[1][2]*m[2][0] - m[1][0]*m
                   [2][2])
               + m[0][2] * (m[1][0]*m[2][1] - m[1][1]*m
                   [2][0]);
    return det < 0;
}

bool intersect(pdd a, pdd b, pdd c, pdd d) {
    return cross(b, c, a) * cross(b, d, a) < 0 and
        cross(d, a, c) * cross(d, b, c) < 0;
}


const double EPS = 1e-12;
struct Triangulation {
    static const int MXN = 1e5+5;
    int N;
    vector<int> ord;
    vector<pdd> pts;
    set<int> E[MXN];
    vector<vector<int>> solve(vector<pdd> p) {
        N = SZ(p);
        ord.resize(N);
        for (int i=0; i<N; i++) {
            E[i].clear();
            ord[i] = i;
        }
        sort(ALL(ord), [&p](int i, int j) {
            return p[i] < p[j];
        });

        pts.resize(N);
        for (int i=0; i<N; i++) pts[i] = p[ord[i]];

        go(0, N);

        vector<vector<int>> res(N);
        for (int i=0; i<N; i++) {
            int o = ord[i];
            for (auto x: E[i]) {
                res[o].PB(ord[x]);
            }
        }
        return res;
    }

    void add_edge(int u, int v) {
        E[u].insert(v);
        E[v].insert(u);
    }

    void remove_edge(int u, int v) {
        E[u].erase(v);
        E[v].erase(u);
    }

    void go(int l, int r) {
        int n = r - l;

        if (n <= 3) {
            for (int i=l; i<r; i++)
                for (int j=i+1; j<r; j++) add_edge(i, j
                    );
            return;
        }
        int md = (l+r)/2;

        go(l, md);
        go(md, r);

        int il = l, ir = r-1;
        while (1) {
            int nx = -1;
            for (auto i: E[il]) {
                double cs = cross(pts[il], pts[i], pts[
                    ir]);
                if (cs > EPS ||
                    (abs(cs) < EPS and abs(pts[i]-pts[
                        ir]) < abs(pts[il]-pts[ir]))) {
                    nx = i;
                    break;
                }
            }
            if (nx != -1) {
                il = nx;
                continue;
            }
            for (auto i: E[ir]) {
                double cs = cross(pts[ir], pts[i], pts[
                    il]);
                if (cs < -EPS ||
                    (abs(cs) < EPS and abs(pts[i]-pts[
                        il]) < abs(pts[ir]-pts[il]))) {
                    nx = i;
                    break;
                }
            }

            if (nx != -1) {
                ir = nx;
            } else break;
        }

        add_edge(il, ir);

        while (1) {
            int nx = -1;
            bool is2 = false;
```

```
            for (int i: E[il]) {
                if (cross(pts[il], pts[i], pts[ir]) < -
                    EPS and
                    (nx == -1 or inCircle(pts[il], pts[
                        ir], pts[nx], pts[i]))) nx = i;
            }

            for (int i: E[ir]) {
                if (cross(pts[ir], pts[i], pts[il]) >
                    EPS and
                    (nx == -1 or inCircle(pts[il], pts[
                        ir], pts[nx], pts[i]))) nx = i,
                         is2 = 1;
            }


            if (nx == -1) break;

            int a = il, b = ir;
            if (is2) swap(a, b);

            for (auto i: E[a]) {
                if (intersect(pts[a], pts[i], pts[b],
                    pts[nx])) {
                    remove_edge(a, i);
                }
            }
            if (is2) {
                add_edge(il, nx);
                ir = nx;
            } else {
                add_edge(ir, nx);
                il = nx;
            }
        }
    }
} tri;
```

7 Stringology

7.1 Suffix Array

```
const int MAX = 1020304;
int ct[MAX], he[MAX], rk[MAX], sa[MAX], tsa[MAX], tp[
    MAX][2];

void suffix_array(char *ip){

  int len = strlen(ip);
  int alp = 256;

  memset(ct, 0, sizeof(ct));
  for(int i=0;i<len;i++) ct[ip[i]+1]++;
  for(int i=1;i<alp;i++) ct[i]+=ct[i-1];
  for(int i=0;i<len;i++) rk[i]=ct[ip[i]];

  for(int i=1;i<len;i*=2){
    for(int j=0;j<len;j++){
      if(j+i>=len) tp[j][1]=0;
      else tp[j][1]=rk[j+i]+1;

      tp[j][0]=rk[j];
    }
    memset(ct, 0, sizeof(ct));
    for(int j=0;j<len;j++) ct[tp[j][1]+1]++;
    for(int j=1;j<len+2;j++) ct[j]+=ct[j-1];
    for(int j=0;j<len;j++) tsa[ct[tp[j][1]]++]=j;

    memset(ct, 0, sizeof(ct));
    for(int j=0;j<len;j++) ct[tp[j][0]+1]++;
    for(int j=1;j<len+1;j++) ct[j]+=ct[j-1];
    for(int j=0;j<len;j++) sa[ct[tp[tsa[j]][0]]++]=tsa[
        j];

    rk[sa[0]]=0;
    for(int j=1;j<len;j++){
      if( tp[sa[j]][0] == tp[sa[j-1]][0] &&
        tp[sa[j]][1] == tp[sa[j-1]][1] )
        rk[sa[j]] = rk[sa[j-1]];
      else
        rk[sa[j]] = j;
    }
  }

  for(int i=0,h=0;i<len;i++){
    if(rk[i]==0) h=0;
    else{
      int j=sa[rk[i]-1];
      h=max(0,h-1);
      for(;ip[i+h]==ip[j+h];h++);
    }
    he[rk[i]]=h;
  }
}
```

7.2 Suffix Array (SAIS TWT514)

```
struct SA{
#define REP(i,n) for ( int i=0; i<int(n); i++ )
#define REP1(i,a,b) for ( int i=(a); i<=int(b); i++ )
    static const int MXN = 300010;
    bool _t[MXN*2];
    int _s[MXN*2], _sa[MXN*2], _c[MXN*2], x[MXN], _p[
        MXN], _q[MXN*2], hei[MXN], r[MXN];
    int operator [] (int i){ return _sa[i]; }
    void build(int *s, int n, int m){
        memcpy(_s, s, sizeof(int) * n);
        sais(_s, _sa, _p, _q, _t, _c, n, m);
        mkhei(n);
    }
    void mkhei(int n){
        REP(i,n) r[_sa[i]] = i;
        hei[0] = 0;
        REP(i,n) if(r[i]) {
            int ans = i>0 ? max(hei[r[i-1]] - 1, 0) :
                0;
            while(_s[i+ans] == _s[_sa[r[i]-1]+ans]) ans
                ++;
            hei[r[i]] = ans;
        }
    }
    void sais(int *s, int *sa, int *p, int *q, bool *t,
         int *c, int n, int z){
        bool uniq = t[n-1] = true, neq;
        int nn = 0, nmxz = -1, *nsa = sa + n, *ns = s +
             n, lst = -1;
#define MS0(x,n) memset((x),0,n*sizeof(*(x)))
#define MAGIC(XD) MS0(sa, n); \
        memcpy(x, c, sizeof(int) * z); \
        XD; \
        memcpy(x + 1, c, sizeof(int) * (z - 1)); \
        REP(i,n) if(sa[i] && !t[sa[i]-1]) sa[x[s[sa[i
            ]-1]]++] = sa[i]-1; \
        memcpy(x, c, sizeof(int) * z); \
        for(int i = n - 1; i >= 0; i--) if(sa[i] && t[
            sa[i]-1]) sa[--x[s[sa[i]-1]]] = sa[i]-1;
        MS0(c, z);
        REP(i,n) uniq &= ++c[s[i]] < 2;
        REP(i,z-1) c[i+1] += c[i];
        if (uniq) { REP(i,n) sa[--c[s[i]]] = i; return;
             }
        for(int i = n - 2; i >= 0; i--) t[i] = (s[i]==s
            [i+1] ? t[i+1] : s[i]<s[i+1]);
        MAGIC(REP1(i,1,n-1) if(t[i] && !t[i-1]) sa[--x[
            s[i]]]=p[q[i]=nn++]=i);
        REP(i, n) if (sa[i] && t[sa[i]] && !t[sa[i]-1])
             {
            neq=lst<0||memcmp(s+sa[i],s+lst,(p[q[sa[i
                ]]+1]-sa[i])*sizeof(int));
            ns[q[lst=sa[i]]]=nmxz+=neq;
        }
        sais(ns, nsa, p + nn, q + n, t + n, c + z, nn,
            nmxz + 1);
        MAGIC(for(int i = nn - 1; i >= 0; i--) sa[--x[s
            [p[nsa[i]]]]] = p[nsa[i]]);
    }
}sa;

void suffix_array(int* ip, int len) {
    // should padding a zero in the back
    // s is int array, n is array length
    // s[0..n-1] != 0, and s[n] = 0
    // resulting SA will be length n+1
    ip[len++] = 0;
    sa.build(ip, len, 128);
    // original 1-base
```

```
    for (int i=0; i<l; i++) {
        hei[i] = sa.hei[i + 1];
        sa[i] = sa._sa[i + 1];
    }
}
```

7.3 Aho-Corasick Algorithm

```
struct ACautomata{
  struct Node{
    int cnt,dp;
    Node *go[26], *fail;
    Node (){
      cnt = 0;
      dp = -1;
      memset(go,0,sizeof(go));
      fail = 0;
    }
  };

  Node *root, pool[1048576];
  int nMem;

  Node* new_Node(){
    pool[nMem] = Node();
    return &pool[nMem++];
  }
  void init(){
    nMem = 0;
    root = new_Node();
  }
  void add(const string &str){
    insert(root,str,0);
  }
  void insert(Node *cur, const string &str, int pos){
    if (pos >= (int)str.size()){
      cur->cnt++;
      return;
    }
    int c = str[pos]-'a';
    if (cur->go[c] == 0){
      cur->go[c] = new_Node();
    }
    insert(cur->go[c],str,pos+1);
  }
  void make_fail(){
    queue<Node*> que;
    que.push(root);
    while (!que.empty()){
      Node* fr=que.front();
      que.pop();
      for (int i=0; i<26; i++){
        if (fr->go[i]){
          Node *ptr = fr->fail;
          while (ptr && !ptr->go[i]) ptr = ptr->fail;
          if (!ptr) fr->go[i]->fail = root;
          else fr->go[i]->fail = ptr->go[i];
          que.push(fr->go[i]);
        }
      }
    }
  }
};
```

7.4 KMP

```
#include<bits/stdc++.h>
using namespace std;

void build_fail_function(string B, int *fail) {
    int len = B.length(), pos;
    pos = fail[0] = -1;
    for (int i = 1; i < len; i ++) {
        while (pos != -1 and B[pos + 1] != B[i])
            pos = fail[pos];
        if (B[pos + 1] == B[i]) pos ++;
        fail[i] = pos;
    }
}

void match(string A, string B, int *fail) {
    int lenA = A.length(), lenB = B.length();
    int pos = -1;
    for (int i = 0; i < lenA; i ++) {
        while (pos != -1 and B[pos + 1] != A[i])
            pos = fail[pos];

        if (B[pos + 1] == A[i]) pos ++;

        if (pos == lenB - 1) {
            // Match ! A[i - lenB + 1, i] = B
            pos = fail[pos];
        }
    }
}
```

7.5 Z value

```
void Zval(const char *s, int len, int *z) {
    z[0] = 0;
    for (int b=0, i=1; i<len; i++) {
        z[i] = max(min(z[i-b], z[b] + b - i), 0);
        while (s[i + z[i]] == s[z[i]]) z[i] ++;
        if (i+z[i] > b+z[b]) b=i;
    }
}
```

7.6 Z value (palindrome ver.)

```
void Zpal(const char *s, int len, int *z) {
    // Only odd palindrome len is considered
    // z[i] means that the longest odd palindrom
        centered at
    // i is [i-z[i] .. i+z[i]]
    z[0] = 0;
    for (int b=0, i=1; i<len; i++) {
        if (z[b] + b >= i) z[i] = min(z[2*b-i], b+z[b]-
            i);
        else z[i] = 0;
        while (i+z[i]+1 < len and i-z[i]-1 >= 0 and
               s[i+z[i]+1] == s[i-z[i]-1]) z[i] ++;
        if (z[i] + i > z[b] + b) b = i;
    }
}
```

7.7 palindromic tree

```
//bcw0x1bd2 {{{
#include<bits/stdc++.h>
#include<unistd.h>
using namespace std;
#define F first
#define S second
#define MP make_pair
#define PB push_back
#define IOS ios_base::sync_with_stdio(0); cin.tie(0);
#define SZ(x) ((int)((x).size()))
#define ALL(x) begin(x),end(x)
#define REP(i,x) for (int i=0; i<(x); i++)
#define REP1(i,a,b) for (int i=(a); i<=(b); i++)

typedef long long ll;
typedef pair<int,int> pii;
typedef pair<ll,ll> pll;
typedef long double ld;

#ifdef DARKHH
#define FILEIO(name)
#else
#define FILEIO(name) \
  freopen(name".in", "r", stdin); \
  freopen(name".out", "w", stdout);
#endif

#ifdef DARKHH
template<typename T>
void _dump( const char* s, T&& head ) { cerr<<s<<"="<<
    head<<endl; }

template<typename T, typename... Args>
void _dump( const char* s, T&& head, Args&&... tail ) {
```

```
  int c=0;
  while ( *s!=',' || c!=0 ) {
    if ( *s=='(' || *s=='[' || *s=='{' ) c++;
    if ( *s==')' || *s==']' || *s=='}' ) c--;
    cerr<<*s++;
  }
  cerr<<"="<<head<<", ";
  _dump(s+1,tail...);
}

#define dump(...) do { \
  fprintf(stderr, "%s:%d - ", __PRETTY_FUNCTION__,
      __LINE__); \
  _dump(#__VA_ARGS__, __VA_ARGS__); \
} while (0)

template<typename Iter>
ostream& _out( ostream &s, Iter b, Iter e ) {
  s<<"[";
  for ( auto it=b; it!=e; it++ ) s<<(it==b?"":" ")<<*it
      ;
  s<<"]";
  return s;
}

template<typename A, typename B>
ostream& operator <<( ostream &s, const pair<A,B> &p )
    { return s<<"("<<p.first<<","<<p.second<<")"; }
template<typename T>
ostream& operator <<( ostream &s, const vector<T> &c )
    { return _out(s,ALL(c)); }
template<typename T, size_t N>
ostream& operator <<( ostream &s, const array<T,N> &c )
     { return _out(s,ALL(c)); }
template<typename T>
ostream& operator <<( ostream &s, const set<T> &c ) {
    return _out(s,ALL(c)); }
template<typename A, typename B>
ostream& operator <<( ostream &s, const map<A,B> &c ) {
     return _out(s,ALL(c)); }
#else
#define dump(...)
#endif
// }}}

struct palindromic_tree{
  struct node{
    int next[26],fail,len;
    int cnt,num,st,ed;
    node(int l=0):fail(0),len(l),cnt(0),num(0){
      for(int i=0;i<26;++i)next[i]=0;
    }
  };
  vector<node> state;
  vector<char> s;
  int last,n;

  void init(){
    state.clear();
    s.clear();
    last=1;
    n=0;
    state.push_back(0);
    state.push_back(-1);
    state[0].fail=1;
    s.push_back(-1);
  }
  int get_fail(int x){
    while(s[n-state[x].len-1]!=s[n])x=state[x].fail;
    return x;
  }
  void add(int c){
    s.push_back(c-='a');
    ++n;
    int cur=get_fail(last);
    if(!state[cur].next[c]){
      int now=state.size();
      state.push_back(state[cur].len+2);
      state[now].fail=state[get_fail(state[cur].fail)].
          next[c];
      state[cur].next[c]=now;
      state[now].num=state[state[now].fail].num+1;
    }
    last=state[cur].next[c];
    ++state[last].cnt;
  }
  int size(){
    return state.size()-2;
  }
}pt;

int main() {
  string s;
  cin >> s;
  pt.init();
  for (int i=0; i<SZ(s); i++) {
    int prvsz = pt.size();
    pt.add(s[i]);
    if (prvsz != pt.size()) {
      int r = i;
      int l = r - pt.state[pt.last].len + 1;
      cout << "Find pal @ [" << l << " " << r << "] : "
           << s.substr(l,r-l+1) << endl;
    }
  }

  return 0;
}
```

7.8 Lexicographically Smallest Rotation

```
string mcp(string s){
  int n = s.length();
  s += s;
  int i=0, j=1;
  while (i<n && j<n){
    int k = 0;
    while (k < n && s[i+k] == s[j+k]) k++;
    if (s[i+k] <= s[j+k]) j += k+1;
    else i += k+1;
    if (i == j) j++;
  }
  int ans = i < n ? i : j;
  return s.substr(ans, n);
}
```

7.9 Suffix Automaton

```
// par : fail link
// val : a topological order ( useful for DP )
// go[x] : automata edge ( x is integer in [0,26) )

struct SAM{
  struct State{
    int par, go[26], val;
    State () : par(0), val(0){ FZ(go); }
    State (int _val) : par(0), val(_val){ FZ(go); }
  };
  vector<State> vec;
  int root, tail;

  void init(int arr[], int len){
    vec.resize(2);
    vec[0] = vec[1] = State(0);
    root = tail = 1;
    for (int i=0; i<len; i++)
      extend(arr[i]);
  }
  void extend(int w){
    int p = tail, np = vec.size();
    vec.PB(State(vec[p].val+1));
    for ( ; p && vec[p].go[w]==0; p=vec[p].par)
      vec[p].go[w] = np;
    if (p == 0){
      vec[np].par = root;
    } else {
      if (vec[vec[p].go[w]].val == vec[p].val+1){
        vec[np].par = vec[p].go[w];
      } else {
        int q = vec[p].go[w], r = vec.size();
        vec.PB(vec[q]);
        vec[r].val = vec[p].val+1;
        vec[q].par = vec[np].par = r;
        for ( ; p && vec[p].go[w] == q; p=vec[p].par)
          vec[p].go[w] = r;
      }
    }
    tail = np;
```

```
  }
};
```

8 Problems

8.1 Painter

```
#include<bits/stdc++.h>
using namespace std;
#define F first
#define S second
#define PB push_back
#define IOS ios_base::sync_with_stdio(0); cin.tie(0);
#define SZ(x) ((int)((x).size()))
#define ALL(x) begin(x),end(x)
#define REP(i,x) for (int i=0; i<(x); i++)
#define REP1(i,a,b) for (int i=(a); i<=(b); i++)

typedef long long ll;
typedef pair<ll,ll> pll;

typedef pll Point;
const int MXN = 100005;

Point operator + (const Point &a, const Point &b) {
    return Point(a.F+b.F, a.S+b.S); }
Point operator - (const Point &a, const Point &b) {
    return Point(a.F-b.F, a.S-b.S); }
ll operator * (const Point &a, const Point &b) { return
     a.F*b.F + a.S*b.S; }
ll operator % (const Point &a, const Point &b) { return
     a.F*b.S - a.S*b.F; }

struct Segment {
  int v,id;
  Point p,q;
  Segment () {}
  Segment (int _v, int _id, Point _p, Point _q) :
    v(_v), id(_id), p(_p), q(_q) {}
};
bool operator < (const Segment &a, const Segment &b) {
  if (a.p == b.q) return false;
  if (a.q == b.p) return true;
  if (a.p == b.p) return (a.q-a.p) % (b.q-a.p) > 0;
  if (a.q == b.q) return (a.p-a.q) % (b.p-a.q) < 0;
  if (a.p.F == b.p.F) return a.p.S < b.p.S;
  if (a.q.F == b.q.F) return a.q.S < b.q.S;
  if (a.p.F < b.p.F) return (a.q-a.p) % (b.p-a.p) > 0;
  else return (b.q-b.p) % (a.p-b.p) < 0;
}
bool operator == (const Segment &a, const Segment &b) {
  return tie(a.v,a.id,a.p,a.q) == tie(b.v,b.id,b.p,b.q)
      ;
}
struct Triangle {
  Point pt[3];
}ip[MXN];

const int MEM = 350004;
struct Treap {
  static Treap nil, mem[MEM], *pmem;
  Treap *l, *r;
  int sum,presum,size;
  Segment seg;
  Treap () : l(&nil), r(&nil), sum(0), presum(0), size
      (0), seg() {}
  Treap (Segment _val) :
    l(&nil), r(&nil), sum(_val.v), presum(max(_val.v,0)
        ), size(1), seg(_val) {}
} Treap::nil, Treap::mem[MEM], *Treap::pmem = Treap::
    mem;

int size(const Treap *t) { return t->size; }
void pull(Treap *t) {
  if (!size(t)) return;
  t->size = size(t->l) + size(t->r) + 1;
  t->sum = t->l->sum + t->seg.v + t->r->sum;
  t->presum = max(t->l->presum, t->l->sum + t->seg.v);
  t->presum = max(t->presum, t->l->sum + t->seg.v + t->
      r->presum);
}
Treap* merge(Treap *a, Treap *b) {
  if (!size(a)) return b;
  if (!size(b)) return a;
  Treap *t;
  if (rand() % (size(a) + size(b)) < size(a)) {
    t = a;
    t->r = merge(a->r, b);
  } else {
    t = b;
    t->l = merge(a, b->l);
  }
  pull(t);
  return t;
}
void split(Treap *t, int k, Treap *&a, Treap *&b) {
  if (!size(t)) a = b = &Treap::nil;
  else if (size(t->l) + 1 <= k) {
    a = t;
    split(t->r, k - size(t->l) - 1, a->r, b);
    pull(a);
  } else {
    b = t;
    split(t->l, k, a, b->l);
    pull(b);
  }
}
int get_rank(Treap *t, Segment x) {
  if (!size(t)) return 0;
  if (x < t->seg) return get_rank(t->l, x);
  return get_rank(t->r,x) + size(t->l) + 1;
}
Treap* find_leftist(Treap *t) {
  while (size(t->l)) t = t->l;
  return t;
}
Treap* find_rightist(Treap *t) {
  while (size(t->r)) t = t->r;
  return t;
}

int N;
vector<int> allx;
vector<Segment> _seg[3*MXN];
#define seg(x) _seg[(x)+100000]

inline void add_seg(Segment s) {
  seg(s.p.F).PB(s);
  if (s.q.F != s.p.F) seg(s.q.F).PB(s);
}
void predo() {
  allx.clear();
  REP(i,N) REP(j,3) {
    seg(ip[i].pt[j].F).clear();
    allx.PB(ip[i].pt[j].F);
  }
  sort(ALL(allx));
  allx.resize(unique(ALL(allx))-begin(allx));
  REP(i,N) {
    sort(ip[i].pt, ip[i].pt+3);
    Point *pt = ip[i].pt;
    Segment seg1 = Segment(1,i,pt[0],pt[1]);
    Segment seg2 = Segment(1,i,pt[0],pt[2]);
    Segment seg3 = Segment(1,i,pt[1],pt[2]);
    if (seg2 < seg1) seg1.v = -1;
    else seg2.v = -1;
    seg3.v = seg1.v;
    add_seg(seg1);
    add_seg(seg2);
    add_seg(seg3);
  }
}
inline int sgn(ll x) { return x < 0 ? -1 : x > 0; }
bool interPnt(Point p1, Point p2, Point q1, Point q2){
  ll c1 = (p2-p1)%(q1-p1), c2 = (p2-p1)%(q2-p1);
  ll c3 = (q2-q1)%(p1-q1), c4 = (q2-q1)%(p2-q1);
  return sgn(c1) * sgn(c2) <= 0 and sgn(c3) * sgn(c4)
      <= 0;
}
bool check_error(Segment a, Segment b) {
  if (a.id == b.id) return false;
  return interPnt(a.p,a.q,b.p,b.q);
}
int solve() {
  Treap::pmem = Treap::mem;
  Treap *rt = &Treap::nil;
  int res = 0;
  for (auto i:allx) {
```

```
    for (auto l:seg(i)) {
      int k = get_rank(rt, l);
      Treap *t,*tl,*tm,*tr;
      split(rt,k,tl,tr);
      t = find_rightist(tl);
      if (size(t) and check_error(t->seg,l)) return -1;
      t = find_leftist(tr);
      if (size(t) and check_error(t->seg,l)) return -1;
      rt = merge(tl,tr);
      if (l.p.F == i and l.p.F != l.q.F) {
        k = get_rank(rt, l);
        split(rt,k,tl,tr);
        tm = new (Treap::pmem++) Treap(l);
        rt = merge(merge(tl,tm),tr);
      }
    }
    for (auto l:seg(i)) {
      if (l.q.F == i and l.p.F != l.q.F) {
        Treap *tl,*tm,*tr;
        int k = get_rank(rt, l);
        split(rt,k-1,tl,tm);
        split(tm,1,tm,tr);
        Treap *t1=find_rightist(tl),*t2=find_leftist(tr
            );
        if (size(t1) and size(t2) and check_error(t1->
            seg,t2->seg)) return -1;
        rt = merge(tl,tr);
      }
    }
    res = max(res, rt->presum);
  }
  res++;
  return res;
}
int main() {
  IOS;
  int cas = 0;
  while (cin >> N) {
    if (N == -1) break;
    REP(i,N) {
      REP(j,3) cin >> ip[i].pt[j].F >> ip[i].pt[j].S;
    }
    predo();
    int ans = solve();
    cas++;
    cout << "Case " << cas << ": ";
    if (ans == -1) cout << "ERROR\n";
    else cout << ans << " shades\n";
  }

  return 0;
}
```

8.2 Mo-Algorithm on Tree

```
#include<bits/stdc++.h>
using namespace std;
#define IOS ios_base::sync_with_stdio(0); cin.tie(0);
#define SZ(x) ((int)((x).size()))

const int MX = 500005;
const int SQ = 1400;
const int LOG = 17;

struct BIT {
  int bit[MX];
  int lb(int x) { return x & -x; }
  void add(int p, int v) {
    p++;
    for (int i=p; i<MX; i+=lb(i)) bit[i] += v;
  }
  int qry() {
    int v = 0;
    for (int i=1<<LOG; i>0; i>>=1) {
      if ((v|i) < MX and bit[v|i]==i) v |= i;
    }
    return v;
  }
}bit;

struct Query {
  int l,r,qid;
}qry[MX];
struct Edge {
  int v,x;
};

int N,Q,timestamp[MX],ans[MX];
int in[MX],cnt[MX];
vector<Edge> E[MX];
vector<Edge> seq;

void DFS(int u, int f) {
  timestamp[u] = SZ(seq);
  for (auto it:E[u]) {
    if (it.v == f) continue;
    seq.push_back(it);
    DFS(it.v,u);
    seq.push_back(it);
  }
}
void poke(int id) {
  int v = seq[id].v;
  int x = seq[id].x;
  in[v] ^= 1;
  cnt[x] += in[v] ? 1 : -1;
  if (in[v] and cnt[x] == 1) bit.add(x, 1);
  if (!in[v] and cnt[x] == 0) bit.add(x, -1);
}
int main() {
  IOS;
  cin >> N >> Q;
  for (int i=0; i<N-1; i++) {
    int u,v,x;
    cin >> u >> v >> x;
    x = min(x,N);
    E[u].push_back({v,x});
    E[v].push_back({u,x});
  }
  DFS(1,1);
  for (int i=1; i<=Q; i++) {
    int u,v;
    cin >> u >> v;
    int l = timestamp[u], r = timestamp[v];
    if (l > r) swap(l,r);
    r--;
    qry[i] = {l,r,i};
  }
  sort(qry+1,qry+1+Q, [](Query a, Query b) {
      return make_pair(a.l/SQ,a.r) < make_pair(b.l/SQ,b
          .r);
      });

  int curL = 1, curR = 0;
  for (int i=1; i<=Q; i++) {
    int ql=qry[i].l,qr=qry[i].r;
    while (curL > ql) poke(--curL);
    while (curR < qr) poke(++curR);
    while (curL < ql) poke(curL++);
    while (curR > qr) poke(curR--);
    ans[qry[i].qid] = bit.qry();
  }

  for (int i=1; i<=Q; i++) cout << ans[i] << "\n";

  return 0;
}
```

8.3 Manhattan MST

```
#include<bits/stdc++.h>
#define REP(i,n) for(int i=0;i<n;i++)
using namespace std;
typedef long long LL;
const int N=200100;
int n,m;
struct PT {int x,y,z,w,id;}p[N];
inline int dis(const PT &a,const PT &b){return abs(a.x-
    b.x)+abs(a.y-b.y);}
inline bool cpx(const PT &a,const PT &b){return a.x!=b.
    x? a.x>b.x:a.y>b.y;}
inline bool cpz(const PT &a,const PT &b){return a.z<b.z
    ;}
struct E{int a,b,c;}e[8*N];
bool operator<(const E&a,const E&b){return a.c<b.c;}
struct Node{
  int L,R,key;
}node[4*N];
```

```
int s[N];
int F(int x){return s[x]==x?x:s[x]=F(s[x]);}
void U(int a,int b){s[F(b)]=F(a);}
void init(int id,int L,int R) {
  node[id]=(Node){L,R,-1};
  if(L==R)return;
  init(id*2,L,(L+R)/2);
  init(id*2+1,(L+R)/2+1,R);
}
void ins(int id,int x) {
  if(node[id].key==-1 || p[node[id].key].w>p[x].w)node[
      id].key=x;
  if(node[id].L==node[id].R)return;
  if(p[x].z<=(node[id].L+node[id].R)/2)ins(id*2,x);
  else ins(id*2+1,x);
}
int Q(int id,int L,int R){
  if(R<node[id].L || L>node[id].R)return -1;
  if(L<=node[id].L && node[id].R<=R)return node[id].key
      ;
  int a=Q(id*2,L,R),b=Q(id*2+1,L,R);
  if(b==-1 || (a!=-1 && p[a].w<p[b].w)) return a;
  else return b;
}
void calc() {
  REP(i,n) {
    p[i].z=p[i].y-p[i].x;
    p[i].w=p[i].x+p[i].y;
  }
  sort(p,p+n,cpz);
  int cnt=0,j,k;
  for(int i=0;i<n;i=j){
    for(j=i+1;p[j].z==p[i].z && j<n;j++);
    for(k=i,cnt++;k<j;k++)p[k].z=cnt;
  }
  init(1,1,cnt);
  sort(p,p+n,cpx);
  REP(i,n) {
    j=Q(1,p[i].z,cnt);
    if(j!=-1)e[m++]=(E){p[i].id,p[j].id,dis(p[i],p[j])
        };
    ins(1,i);
  }
}
LL MST() {
  LL r=0;
  sort(e,e+m);
  REP(i,m) {
    if(F(e[i].a)==F(e[i].b))continue;
    U(e[i].a,e[i].b);
    r+=e[i].c;
  }
  return r;
}
int main(){
  int ts;
  scanf("%d", &ts);
  while (ts--) {
    m = 0;
    scanf("%d",&n);
    REP(i,n) {
      scanf("%d%d",&p[i].x,&p[i].y);
      p[i].id=s[i]=i;
    }
    calc();
    REP(i,n)p[i].y= -p[i].y;
    calc();
    REP(i,n)swap(p[i].x,p[i].y);
    calc();
    REP(i,n)p[i].x=-p[i].x;
    calc();
    printf("%lld\n",MST()*2);
  }
  return 0;
}
```

9 YAKELI

9.1 Periodic Table