

No.

Date

高等代数期中模拟考试

一. 选择题

1. False. If \vec{u} and \vec{v} are multiples, the $\text{Span}\{\vec{u}, \vec{v}\}$ is a line, and \vec{w} need not be on that line.
2. True. For the transformation $\vec{x} \mapsto A\vec{x}$ to map \mathbb{R}^5 onto \mathbb{R}^6 , the matrix A would have to have a pivot in every row and hence have six pivot columns. This is impossible because A has only five columns.
3. False. Every equation $A\vec{x} = \vec{0}$ has the trivial solution whether or not some variables are free.
4. True. An non elementary matrix is obtained by a row operation on I_n .
5. False. A must be square in order to conclude from the equation $AB = I$ that A is invertible.
6. False. Take the zero matrix for B . Or, construct a matrix B such that the equation $B\vec{x} = \vec{0}$ has nontrivial solutions, and construct C and D so that $C \neq D$ and the columns of $(C-D)$ satisfied the equation $B\vec{x} = \vec{0}$. Then $B(C-D) = \vec{0}$ and $BC = BD$.
7. True. $\det A^T A = (\det A)^2 \geq 0$
8. True. $\det A^3 = 0 \Rightarrow (\det A)^3 = 0 \Rightarrow \det A = 0$.
9. True. If A is a square matrix and a multiple of one row of A is added to another row to produce a matrix B , the $\det B = \det A$.
10. False. Nonpivot columns need not to be linearly dependent as a subset of the matrix columns but nonpivot columns are linear combinations of the pivot columns.

二. 填空题

$$11. AB = \begin{bmatrix} 2 & 3 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 9 \\ -3 & k \end{bmatrix} = \begin{bmatrix} -7 & 18+3k \\ -4 & -9+k \end{bmatrix}$$

$$\text{while } BA = \begin{bmatrix} 1 & 9 \\ -3 & k \end{bmatrix} \begin{bmatrix} 2 & 3 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} -7 & 12 \\ -6-k & -9+k \end{bmatrix}$$

Then $AB = BA$ if and only if $18+3k=12$ and $-4=-6-k$, which happens if and only if $k=-2$.

12. It's easy to know that the change-of-coordinates matrix from I to B is $[\vec{b}_1 \ \vec{b}_2]^T$. And the B -coordinate vector of \vec{a} is $[\vec{b}_1 \ \vec{b}_2]^T \vec{a}$.

13. Expanding along the first row:

$$\begin{vmatrix} 3 & 0 & 4 \\ 2 & 3 & 2 \\ 0 & 5 & -1 \end{vmatrix} = 3 \begin{vmatrix} 3 & 2 \\ 5 & -1 \end{vmatrix} + 4 \begin{vmatrix} 2 & 3 \\ 0 & 5 \end{vmatrix} = 3(-13) + 4(10) = 1.$$

14. T is one-to-one

\Leftrightarrow The columns of A are linearly independent.

$\Leftrightarrow A$ has n pivot columns.

15. T maps \mathbb{R}^n onto \mathbb{R}^m .

\Leftrightarrow The columns of A span \mathbb{R}^m .

$\Leftrightarrow A$ has a pivot position in each row.

$\Leftrightarrow A$ has m pivot columns.

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16. Consider the augmented matrix of corresponding system:

$$\begin{bmatrix} 2 & 4 & -2 & b_1 \\ -5 & 1 & 1 & b_2 \\ 7 & -5 & 3 & b_3 \end{bmatrix} \sim \begin{bmatrix} 2 & 4 & -2 & b_1 \\ 0 & -9 & -4 & \frac{5}{2}b_1 + b_2 \\ 0 & 9 & 4 & b_3 - \frac{5}{2}b_1 \end{bmatrix} \sim \begin{bmatrix} 2 & 4 & -2 & b_1 \\ 0 & -9 & -4 & \frac{5}{2}b_1 + b_2 \\ 0 & 0 & 0 & b_2 + b_3 - b_1 \end{bmatrix}$$

The system is consistent if and only if $b_2 + b_3 - b_1 = 0$.

17. Since $A^{-1}B$ is the solution of $AX=B$, row reduction of $[AB]$ to $[IX]$ will produce $X=A^{-1}B$.

$$[AB] = \begin{bmatrix} 1 & 3 & 8 & 3 & 5 \\ 2 & 4 & 11 & 1 & 5 \\ 1 & 2 & 5 & 3 & 4 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 10 & -1 \\ 0 & 1 & 0 & 15 & 10 \\ 0 & 0 & 1 & -5 & 3 \end{bmatrix} = [IX].$$

Thus $A^{-1}B$ is $\begin{bmatrix} 10 & -1 \\ 9 & 10 \\ -5 & 3 \end{bmatrix}$

$$18. \det T = \begin{vmatrix} 1 & a & a^2 \\ 1 & b & b^2 \\ 1 & c & c^2 \end{vmatrix} = \begin{vmatrix} 1 & a & a^2 \\ 0 & b-a & b^2-a^2 \\ 0 & c-a & c^2-a^2 \end{vmatrix} = \begin{vmatrix} 1 & a & a^2 \\ 0 & b-a & (b-a)(b+a) \\ 0 & c-a & (c-a)(c+a) \end{vmatrix}$$

$$= (b-a)(c-a) \begin{vmatrix} 1 & a & a^2 \\ 0 & 1 & b+a \\ 0 & 1 & c+a \end{vmatrix} = (b-a)(c-a) \begin{vmatrix} 1 & a & a^2 \\ 0 & 1 & b+a \\ 0 & 0 & c-b \end{vmatrix} = (b-a)(c-a)(c-b).$$

$$19. \begin{bmatrix} 1 & 3 & 4 & -1 & 2 \\ 2 & 6 & 6 & 0 & 3 \\ 3 & 9 & 3 & 6 & -3 \\ 3 & 9 & 0 & 9 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & 4 & -1 & 2 \\ 0 & 0 & 1 & -1 & 1 \\ 0 & 0 & 0 & 0 & -5 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} = B \sim \begin{bmatrix} 1 & 3 & 0 & 3 & 0 \\ 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

It's easy to see from B that:

$$\text{Col } A: \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \\ 3 \end{bmatrix}, \begin{bmatrix} 3 \\ 6 \\ 9 \\ 9 \end{bmatrix}, \begin{bmatrix} 4 \\ 6 \\ 3 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 6 \\ 9 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ -3 \\ 0 \end{bmatrix} \right\}$$

$$\text{Row } A: \{(1, 3, 4, -1, 2), (0, 0, 1, -1, 1), (0, 0, 0, 0, -5)\}.$$

It's easy to see from C that: $x_1 = -3x_2 - 3x_4$, $x_3 = x_4$, $x_5 = 0$. Thus:

$$\text{Nul } A: \left\{ \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \\ 1 \\ 1 \\ 0 \end{bmatrix} \right\}.$$

20. $A = \begin{bmatrix} 5 & 3 & 2 & -6 & -8 \\ 4 & 1 & 3 & -8 & -7 \\ 5 & 1 & 4 & 5 & 19 \\ -7 & -5 & -2 & 8 & 5 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$

The pivot columns of A form the basis for $\text{Col } A$: $\begin{bmatrix} 5 \\ 4 \\ 5 \\ -7 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \\ 1 \\ -5 \end{bmatrix}, \begin{bmatrix} -6 \\ -8 \\ 5 \\ 8 \end{bmatrix}, \begin{bmatrix} -8 \\ -7 \\ 19 \\ 5 \end{bmatrix}$.

For $\text{Nul } A$, solve $A\vec{x} = \vec{0}$ and get that:

$$x_1 = -x_3, \quad x_2 = x_3, \quad x_3 \text{ is free}, \quad x_4 = 0, \quad x_5 = 0.$$

$$\text{So } \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = x_3 \begin{bmatrix} -1 \\ 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} = x_3 \vec{u}, \quad \text{and } \vec{u} \text{ is the basis for } \text{Nul } A.$$

⑩. 证明题.

21. $(A - AX)^T = X^T B \Rightarrow X(A - AX)^T = B$.

Since X , $A - AX$ are invertible, B is invertible.

22. Suppose that the subspace $H = \text{Span}\{\vec{v}_1, \dots, \vec{v}_3\}$ is four dimensional. If $\vec{v}_1, \dots, \vec{v}_3$ were linearly independent, it would be a basis for H . This is impossible by the statement just before the definition of dimension in Section 2.9, which essentially says that every basis of a p -dimensional subspace consists of p vectors. Thus, $\vec{v}_1, \dots, \vec{v}_3$ must be linearly dependent.