

No. \_\_\_\_\_

Date \_\_\_\_\_

## 高等代数期中模拟考试.

### 一. 选择题.

1. False. If  $\vec{u}$  and  $\vec{v}$  are multiples, the  $\text{Span}(\vec{u}, \vec{v})$  is a line, and  $\vec{w}$  need not be on that line.
2. True. For the transformation  $\vec{x} \mapsto A\vec{x}$  to map  $\mathbb{R}^5$  onto  $\mathbb{R}^6$ , the matrix  $A$  would have to have a pivot in every row and hence have six pivot columns. This is impossible because  $A$  has only five columns.
3. False. Every equation  $A\vec{x} = \vec{0}$  has the trivial solution whether or not some variables are free.
4. True. An  $n \times n$  elementary matrix is obtained by a row operation on  $I_n$ .
5. False.  $A$  must be square in order to conclude from the equation  $AB = I$  that  $A$  is invertible.
6. False. Take the zero matrix for  $B$ . Or, construct a matrix  $B$  such that the equation  $B\vec{x} = \vec{0}$  has nontrivial solutions, and construct  $C$  and  $D$  so that  $C \neq D$  and the columns of  $(C-D)$  satisfied the equation  $B\vec{x} = \vec{0}$ . Then  $B(C-D) = D$  and  $BC = BD$ .
7. True.  $\det A^T A = (\det A)^2 \geq 0$
8. True.  $\det A^3 = 0 \Rightarrow (\det A)^3 = 0 \Rightarrow \det A = 0$ .
9. True. If  $A$  is a square matrix and a multiple of one row of  $A$  is added to another row to produce a matrix  $B$ , then  $\det B = \det A$ .
10. False. Nonpivot columns need not be linearly dependent as a subset of the matrix columns but nonpivot columns are linear combinations of the pivot columns.

二、填空题

$$11. AB = \begin{bmatrix} 2 & 3 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 9 \\ -3 & k \end{bmatrix} = \begin{bmatrix} -7 & 18+3k \\ -4 & -9+k \end{bmatrix}$$

$$\text{while } BA = \begin{bmatrix} 1 & 9 \\ -3 & k \end{bmatrix} \begin{bmatrix} 2 & 3 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} -7 & 12 \\ -6-k & -9+k \end{bmatrix}$$

Then  $AB = BA$  if and only if  $18+3k=12$  and  $-4=-6-k$ , which happens if and only if  $k = -2$ .

12. It's easy to know that the change-of-coordinates matrix from I to B is  $[b_1 \ b_2]^{-1}$ . And the B-coordinate vector of  $\vec{v}$  is  $[b_1^T \ b_2^T]^T \vec{v}$ .

13. Expanding along the first row:

$$\begin{vmatrix} 3 & 0 & 4 \\ 2 & 3 & 2 \\ 0 & 5 & 1 \end{vmatrix} = 3 \begin{vmatrix} 3 & 2 \\ 5 & 1 \end{vmatrix} + 4 \begin{vmatrix} 2 & 3 \\ 0 & 5 \end{vmatrix} = 3(-13) + 4(10) = 1$$

14. T is one-to-one

$\Leftrightarrow$  The columns of A are linearly independent.

$\Leftrightarrow$  A has n pivot columns.

15. T maps  $\mathbb{R}^n$  onto  $\mathbb{R}^m$ .

$\Leftrightarrow$  The columns of A span  $\mathbb{R}^m$ .

$\Leftrightarrow$  A has a pivot position in each row.

$\Leftrightarrow$  A has m pivot columns.

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16. Consider the augmented matrix of corresponding system:

$$\left[ \begin{array}{ccc|c} 2 & -4 & -2 & b_1 \\ -3 & 1 & 1 & b_2 \\ 7 & -5 & -3 & b_3 \end{array} \right] \sim \left[ \begin{array}{ccc|c} 2 & -4 & -2 & b_1 \\ 0 & -9 & -4 & \frac{5}{2}b_1 + b_2 \\ 0 & 9 & 4 & b_3 - \frac{7}{2}b_1 \end{array} \right] \sim \left[ \begin{array}{ccc|c} 2 & -4 & -2 & b_1 \\ 0 & -9 & -4 & \frac{5}{2}b_1 + b_2 \\ 0 & 0 & 0 & b_2 + b_3 - b_1 \end{array} \right]$$

The system is consistent if and only if  $b_2 + b_3 - b_1 = 0$ .

17. Since  $A^T B$  is the solution of  $A\bar{x} = B$ , row reduction of  $[A B]$  to

$[I \bar{x}]$  will produce  $\bar{x} = A^T B$ .

$$[A B] = \left[ \begin{array}{ccc|cc} 1 & 3 & 8 & 1 & 3 & 5 \\ 2 & 4 & 11 & 0 & 1 & 5 \\ 1 & 2 & 5 & 0 & 0 & 4 \end{array} \right] \sim \left[ \begin{array}{ccc|cc} 1 & 0 & 0 & 1 & 0 & -1 \\ 0 & 1 & 0 & 15 & 9 & 10 \\ 0 & 0 & 1 & -5 & 3 & 3 \end{array} \right] = [I \bar{x}]$$

Thus  $A^T B$  is  $\begin{bmatrix} 1 & 0 & -1 \\ 9 & 10 & 3 \\ -5 & 3 & 3 \end{bmatrix}$

$$18. \det T = \begin{vmatrix} 1 & a & a^2 \\ 1 & b & b^2 \\ 1 & c & c^2 \end{vmatrix} = \begin{vmatrix} 1 & a & a^2 \\ 0 & b-a & b^2-a^2 \\ 0 & c-a & c^2-a^2 \end{vmatrix} = \begin{vmatrix} 1 & a & a^2 \\ 0 & b-a & (b-a)(b+a) \\ 0 & c-a & (c-a)(c+a) \end{vmatrix}$$

$$= (b-a)(c-a) \begin{vmatrix} 1 & a & a^2 \\ 0 & 1 & b+a \\ 0 & 1 & c+a \end{vmatrix} = (b-a)(c-a) \begin{vmatrix} 1 & a & a^2 \\ 0 & 1 & b+a \\ 0 & 0 & c-b \end{vmatrix} = (b-a)(c-a)(c-b).$$

$$19. \left[ \begin{array}{ccccc} 1 & 3 & 4 & -1 & 2 \\ 2 & 6 & 6 & 0 & 3 \\ 3 & 9 & 3 & 6 & -3 \\ 3 & 9 & 0 & 9 & 0 \end{array} \right] \sim \left[ \begin{array}{ccccc} 1 & 3 & 4 & -1 & 2 \\ 0 & 0 & 1 & -1 & 1 \\ 0 & 0 & 0 & 0 & -5 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] = B \sim \left[ \begin{array}{ccccc} 1 & 3 & 0 & 3 & 0 \\ 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

It's easily to see from B that:

$$\text{Col } A : \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ 6 \\ 3 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ -3 \\ -3 \\ 0 \end{bmatrix} \right\}$$

$$\text{Row } A : \{(1, 3, 4, -1, 2), (0, 0, 1, -1, 1), (0, 0, 0, 0, -5)\}.$$

It's easily to see from C that:  $x_1 = -3x_2 - 3x_4$ ,  $x_3 = x_4$ ,  $x_5 = 0$ . Thus:

$$\text{Null } A : \left\{ \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} \right\}$$

20.  $A = \begin{bmatrix} 5 & 3 & 2 & -6 & -8 \\ 4 & 1 & 3 & -8 & -7 \\ 5 & 1 & 4 & 5 & 19 \\ -7 & -5 & -2 & 8 & 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$

The pivot columns of  $A$  form the basis for  $\text{Col } A$ :  $\begin{bmatrix} 5 \\ 4 \\ 5 \\ -7 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \\ -5 \\ -5 \end{bmatrix}, \begin{bmatrix} -6 \\ -8 \\ 5 \\ 8 \end{bmatrix}, \begin{bmatrix} -8 \\ -7 \\ 19 \\ 5 \end{bmatrix}$ .

For  $\text{Nul } A$ , solve  $A\vec{x} = \vec{0}$  and get that:

$$x_1 = -x_3, \quad x_2 = x_3, \quad x_3 \text{ is free}, \quad x_4 = 0, \quad x_5 = 0.$$

$$\text{So } \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = x_3 \begin{bmatrix} -1 \\ 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} = x_3 \vec{u}, \quad \text{and } \vec{u} \text{ is the basis for } \text{Nul } A.$$

④. 例題解.

21.  $(A - AX)^{-1} = X^{-1}B \Rightarrow X(A - AX)^{-1} = B$ .

Since  $X$ ,  $A - AX$  are invertible,  $B$  is invertible.

22. Suppose that the subspace  $H = \text{Span}\{\vec{v}_1, \dots, \vec{v}_3\}$  is four dimensional. If  $\vec{v}_1, \dots, \vec{v}_3$  were linearly independent, it would be a basis for  $H$ . This is impossible, by the statement just before the definition of dimension in Section 2.9, which essentially says that every basis of a  $p$ -dimensional subspace consists of  $p$  vectors. Thus,  $\vec{v}_1, \dots, \vec{v}_3$  must be linearly dependent.