

# temi GO Specs

	PARAMETER	VALUES
<b>WEIGHT</b>	Self weight	60kg
<b>MECHANICAL</b>	System outer diameter Body height Maximum height (with tablet) Center of mass XY Lidar height (emitter) Hubwheel diameter Castor wheel diameter	50cm 103cm 115cm Center 23.8cm 150mm 75mm
<b>PAYOUT</b>	Bottom tray max payload Bottom tray size Middle tray max payload Middle tray size Top tray max payload Top tray size Top shelf max payload Top shelf size	12kg D54 x 40.5cm 10kg D54 x 40.5cm D54 x 40.5cm 8kg 2kg D36cm
<b>MAPPING</b>	Max map size No. of locations	15000-20000m^2 1000
<b>FLOOR-CONDITIONS</b>	Max Step climbing Max Slope angle Max gap crossing	0.8cm 5° <4cm



**robo**  
**solutions**

temi

THE PERSONAL ROBOT



	PARAMETER	VALUES
<b>MOVEMENT</b>	Max Linear speed Spin Radius Location accuracy	1m/s 0cm 10cm
<b>CONNECTIVITY + REMOTE INTERFACE</b>	WiFi 4G / 5G BT SDK WEB-Center	WiFi 5 802.11 b/g/n/ac with both 2.4G / 5G 4G USB dongle / 5G module V5.0 BLE compatible See guidebook Temi center
<b>SENSING</b>	Height obs detection range Ground obs detection range Min ground obs height Min Cliff detection height Lidar range	15-150cm 1-150cm 2cm 2cm 35m
<b>BATTERY</b>	Working time - Normal usage Working time - heavy usage Standby Charging 0-100% powered ON Charging 0-100% powered OFF Cell type Output range Capacity Charging voltage	8Hrs 3.5Hrs 18Hrs 5Hrs 4Hrs Li-Ion 19.6-28.7V 500W 29.4V
<b>DISPLAY</b>	Size Resolution OS	13.3INCH 1920x1080 Android 11