Project NavCampus

Navigation made simple.



AS-IS

The current state of things

- Alice is a visually impaired student at Cal Poly Humboldt.
- She relies on her cane and auditory cues from people around her to find the correct building and room.
- She cannot use indoor maps.
 Furniture placement can change without her knowledge.
- Alice must memorize the layout of each building and remember the locations of her classrooms.



TO-BE

How can we do better?

- Alice uses the NavCampus app on her mobile device.
- She uses the audio input feature to specify her desired location, like a building and room number.
- The app's detection system alerts her to any obstacles in her path, and suggests an alternative route.
- The app provides clear audio directions, such as the nearest entrance/route to a desired location.
- In case of an unexpected fall, the app's detection system starts a cancelable countdown. In the worst case, the app alerts the uni police dept. to her location.

Questionnaire Overview / Multiple-Choice Questions

- How are you navigating on-campus?
 - Mostly between different buildings
 - Mostly within one building, on different floors
 - Mostly within one building, on the same floor
- What kind of mobile device do you use?
 - Smartphone
 - o Smartwatch
 - Tablet
- What senses do you use to operate your preferred mobile device?
 - Hearing
 - o Touch
 - Sight

- How do you interact with your preferred mobile device?
 - Braille Keyboard
 - Voice controls
 - Touch feedback/controls
- What do you value *most* in an interface?
 - High-contrast
 - No reliance on colors
 - Customization options
- What platform do you use?
 - o iOS
 - Android

Changes in the WRS

Clarified our definition of a "safe route":

Added functional requirements ->

- o RC8: Hallways that are hard to traverse shall be marked on the internal map.
- RC9: Hard to traverse shall be avoided if possible.

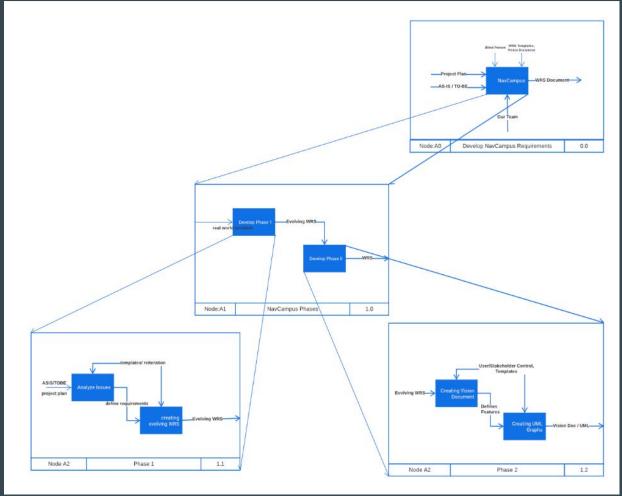
Added non-functional requirements —>

- NR5.4 The safest route is determined by avoiding hard to traverse routes and stairs.
- NR5.5. "Hard to traverse" is defined as environments posing significant obstacles, impeding smooth navigation.

Changes in other documents

- There were no changes in the Management plan
- There were no changes in the preliminary definition

Our Development Process



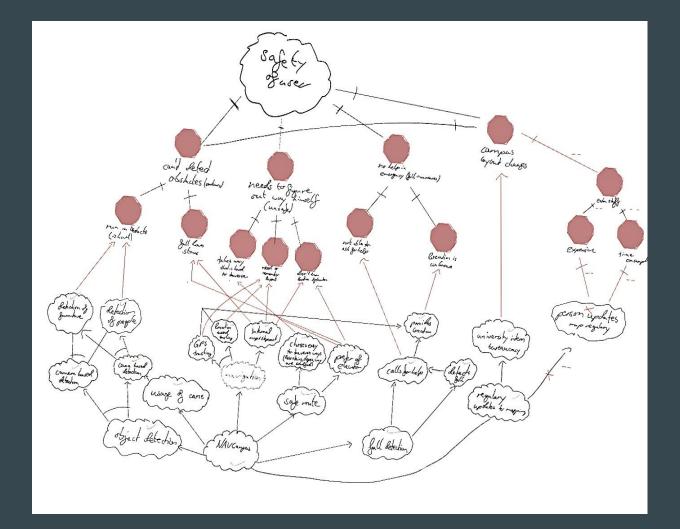
Phase I - Problem analysis

- Goal ->
 - An analysis of the real life problem
 - O Describe the necessary steps to solve this problem
 - Build requirements
- Result ->
 - Evolving WRS document

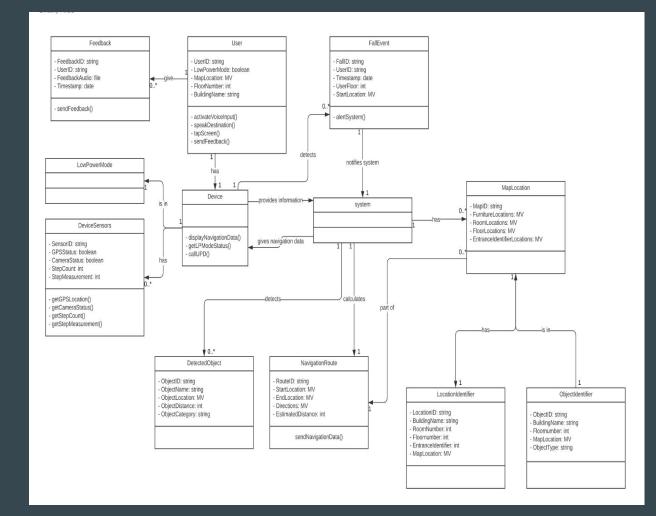
Phase II - Business Opportunity

- Goal ->
 - Propose a solution to the problem
 - Describe the system using UML
 - Describe the features in a vision document
 - Build a prototype
 - Finish WRS
- Result ->
 - Finished WRS
 - Finished Vision document
 - Functional Prototype
 - UML Graphs

Problem
Interdependency
Graph



UML Class
Diagram



Vision Problem Statement

The problem of	- Not being able to navigate on campus independently
affects	 Visually impaired students and staff members
the impact of which is	- The impacted could get lost on campus or be late to their classes or could decide to choose a different university
a successful solution would be	 a cheap and easy to distribute system that provides navigation as well as an object identifier to prevent collisions and accidents

Vision - Product Statement

For	- Visually impaired students
Who	- Making the university more attractive for those students and giving them the same opportunity's
The NavCampus App	- is a mobile application
That	- Offers navigation fall detection and object detection
Unlike	- The nonexistent system on the Cal Poly Campus
Our product	 Will be usable by all students but will be catered towards the blind ones

Vision - Stakeholders

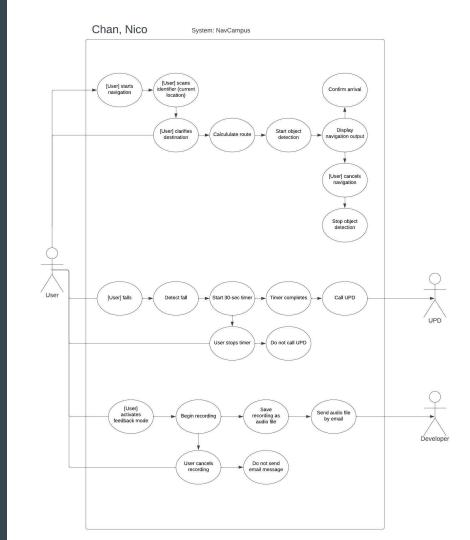
Name	Description	Responsibilities
- Cal Poly Humboldt University	- The main customer and cooperator of the project	- ensures that the system will be maintainable - promotes the project after publication - monitors the project's progress - approves funding - helps monitoring objects on campus - supports the project with the necessary hardware - gets the approval of being filmed from staff and students
- Team NavCampus	- The developers and designers of the system	- produces the product - monitors the project - overviews the project - ensures that the system will be maintainable - Making sure the system is safe

Name		Description		Responsibilities		Stakeholder	
-	Visually impaired student and staff	-	Target audience	-	In final testing phases giving feedback Using the app according to manual	-	advocates of blind students, help workers
-	Students and staff members	-	Secondary audience	-	Using the app according to manual Do not demand changes for seeing students with the feedback function	-	Because they are not the primary <u>audience</u> they will not be taken into account

NavCampus Vision

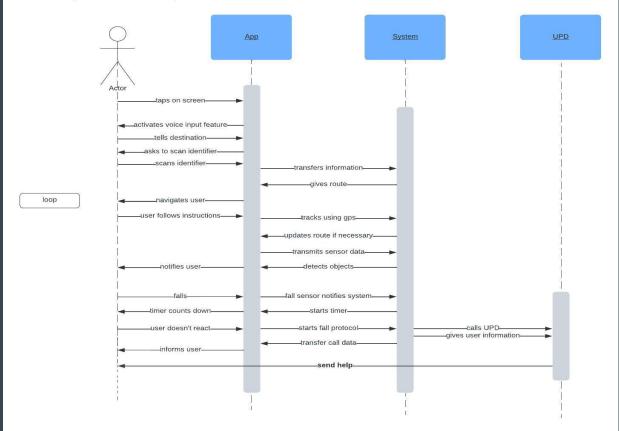
Feature	Functioning
Finding the location	An internal map has identifiers on every
000	room and entrance that can be scanned so
	the system knows the location
Object detection	The system can identify objects and the
	distance to them using the devices camera
Fall detection	The system uses the devices sensors to
	detect a fall and can call UPD if needed
Audio input and output	The system gives the navigation using
	audio files and can also understand the
	audio input of the user to find the
	destination
Safe route calculation	The system can find the safest route (less
	stairs) on campus between two identifiers
	and give the user the necessary
	instructions

Use Case



Functionality /
Sequence Diagram

Exception sequence: Fall (User unconscious)



Reference Model

D1: The university adds the identifiers to each clar D2: The user is able to find the sign and scan it D3: The users device has a Sunctioning canen

RB2: Every enhance shall have a unique identifier in form of a picture

51: If a identifier is scanned using Navangus the app can identify the location of the user on the internal app and tell the user the current breaton

C: The camea acts as a serion

P: The programs can detect the location on the internal map and uses it as the shiftpoint of minigation

eh: All activities of the user as well as the general presence of a identifier ev: When there is un identifier, the scanning of it us well as the users interactions with the device 5V: the algorithm to find the users bookin as well as well as the map itself the accustic confirmation of the bootion

Reference Model

D1: The user holds the phone shaight ar the camera can see everything in the front

Da: The Levice has a functioning camera

RD3: The system shall defect objects that are in the way of the use

S1: The system notifys the user is a Object in his way is delected.

SZ: The system provides a path around the object by playing an audioside

C - The camen acts as an sensor for the system

P - An machine learning approach is able to assess objects and their distance to the use - The system calculates an alteration math to evade the object

ch: The use uses the Levice correctly (straight) , the use is able to bear the system

eV: Objects / Path in Sout of the comera SV: Notification of detected object tinchactions of the alternale path

Sh: the algorith that calculate the distance, the detection and the alternative path

WRS/Vision - Finding the Location

Vision:

WRS:

5.1 Navigation

RC 2 to 7

RC3: The system shall take the GPS to detect the direction the user is phasing and in which direction he/she/they are moving.

5.8 Map Identifiers

RB 1 to 2

RB2: Every location (entrances, rooms) shall have a unique identifier in the form of a picture.

WRS/Vision - Object Detection

Vision:

5.2 Object detection

5.10 Machine learning

WRS:

RD 1 to 3

RD3: The system shall detect objects that are in the way of the user, excluding the cane.

RD4

RD4: The system shall have a machine learning algorithm to learn to detect objects and the distance to the user, using the camera of the device.

WRS/Vision - Fall Detection

Vision:

5.3 Fall detection and emergency call

WRS:

RE 1 to 4

RE1: The fall sensor shall be activated throughout the use of the app.

RE3: In case that the countdown is not deactivated, the system shall call the university police department to get help.

WRS/Vision - Audio Input and Output

Vision: WRS:

5.4 Voice input and output RA1, RA3, RA4, RA8

RA1: The app shall have an voice input feature, to give it the desired location.

RA4: The app shall give the navigation data via audio.

WRS/Vision - Safe Route Calculation

Vision: WRS:

5.5 Route Calculation RC1 and RC2:

RC2: The app shall prioritize elevators over stairs during navigation.

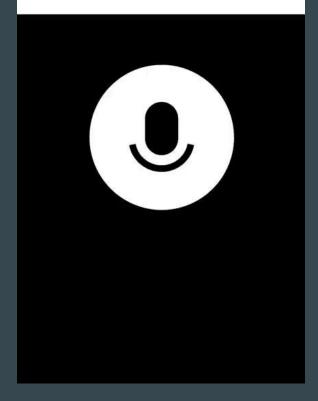
RC8: Hallways that are hard to traverse shall be marked on the internal map.

NavCampus - User Manual Overview

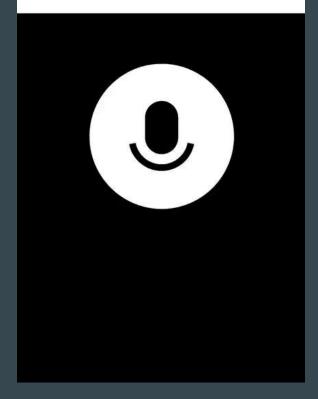
- Introduction
 - Explain what this document is about.
- System Requirements
 - Make sure the user's device meets a set of requirements.
- Installation Instructions
 - Tell the user how to go about accessing/installing the app.
- User Interface Overview
 - A tour of the user interface.

- Using NavCampus
 - Navigation
 - Fall Detected
 - Submitting Feedback
- Frequently Asked Questions
 - Answers to some common questions and issues.
- Contacting Support
 - Tell users how to reach out to our support team.

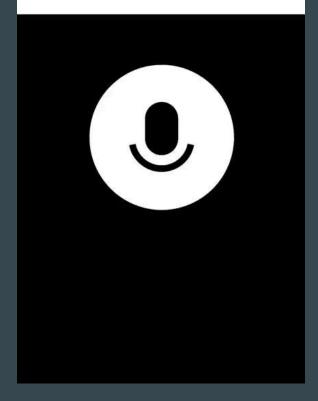
Fall Detection



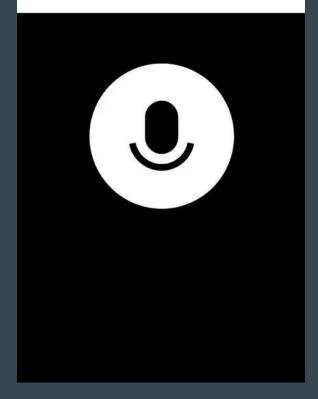
Navigation Demo



Object Detection Demo



User Feedback Demo



5%

Creeping Rate: Estimation vs Reality

Why NavCampus?

- The user interface is simple: tap, speak, or both
- Power efficient, doesn't do anything it doesn't need to
- Anyone can use it, regardless of vision impairment level
- Focused on the lowest common denominator; makes use of features most mobile devices already have
- Doesn't need external hardware for navigation and is therefore cheap

