Sheng WANG

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Research Interests

Trajectory prediction, End-to-end planning, Generative model, Autonomous driving, Robotics, etc.

Education

2014–2018 Harbin Institute of Technology, China

Bachelor of Science: Optoelectronic Information Technology and Engineering, advised by Prof. Wenjun LIU.

2018–2020 **École Centrale de Nantes**, France

Master of Science: Advanced Robotics, advised by Prof. Olivier Kermorgant.

2021−now **The Hong Kong University of Science and Technology**, HongKong SAR

Doctor of Philosophy: *Robotics and Autonomous Systems*, supervised by Prof. Pedro V. SANDER and Prof. Junwei LIANG.

Intern Experience

02/2020–08/2020 PNC Group, Meituan-Dianping, Beijing
Research Intern, advised by Mr. Xiao LI and Dr. Yu BAI.

o6/2019 – o8/2019 Smart Factory Laboratory, AIIT, Peking University, Hangzhou Research Intern, advised by Dr. Xi CHEN.

Selected Publications

- **S. Wang**, Y. Tian, X. Mei, et al., Lhpf: Look back the history and plan for the future in autonomous driving, [Under review], 2024. **6** [Online]. Available: https://arxiv.org/abs/2411.17253.
- **S. Wang**, g. Sun, F. Ma, T. Hu, Y. Song, L. Zhu, *et al.*, "Dragtraffic: A non-expert interactive and point-based controllable traffic scene generation framework," in *IEEE/RSJ International Conference on Intelligent Robots and Systems*, [IROS Accepted], 2024.
- **S. Wang**, Y. Chen, J. Cheng, X. Mei, Y. Song, *et al.*, "Improving autonomous driving safety with pop: A framework for accurate partially observed trajectory predictions," in *IEEE International Conference on Robotics and Automation*, [ICRA], 2024.
- **S. Wang**, R. Xin, J. Cheng, X. Mei, *et al.*, "Fcus: Traffic rule-aware vehicle trajectory forecasting using continuous unlikelihood and signal temporal logic feature," in *IEEE International Conference on Robotics and Biomimetics*, [ROBIO], 2023.
- J. Cheng, R. Xin, **S. Wang**, et al., "Mpnp: Multi-policy neural planner for urban driving," in *IEEE/RSJ* International Conference on Intelligent Robots and Systems, [IROS], 2022.
- F. Ma, Y. Liu, **S. Wang**, J. Wu, W. Qi, et al., "Self-supervised drivable area segmentation using lidar's depth information for autonomous driving," in *IEEE/RSJ International Conference on Intelligent Robots and Systems*, [IROS], 2023.

- F. Ma, **S. Wang**, et al., "An automatic multi-lidar extrinsic calibration algorithm using corner planes," in *IEEE International Conference on Robotics and Biomimetics*, [ROBIO Best Paper Finalist], 2022.
- H. Ren, **S. Wang**, X. Yuan, J. Chen, Y. Zhang, and X. Xiang, "A flight test based deep learning method for transition heat flux prediction in hypersonic flow," in *Physics of Fluids*, [Physics of Fluids], 2022.
- 9 Y. Chen, J. Cheng, L. Gan, **S. Wang**, H. Liu, X. Mei, *et al.*, "Ir-stp: Enhancing autonomous driving with interaction reasoning in spatio-temporal planning," in *IEEE Transactions on Intelligent Transportation Systems*, [TITS], 2024.
- Y. Chen, J. Cheng, **S. Wang**, et al., "Enhancing campus mobility: Achievements and challenges of autonomous shuttle" snow lion"," in *IEEE Robotics Automation Magazine*, [RAM], 2024.
- R. Xin, H. Liu, Y. Chen, **S. Wang**, et al., "A generic trajectory planning method for constrained all-wheel-steering robots," in *IEEE/RSJ International Conference on Intelligent Robots and Systems*, [IROS Accepted], 2024.
- T. Hu, J. Jiao, Y. Xu, H. Liu, **S. Wang**, et al., "Dhp-mapping: A dense panoptic mapping system with hierarchical world representation and label optimization techniques," in *IEEE/RSJ International Conference on Intelligent Robots and Systems*, [IROS Accepted], 2024.
- G. Sun, **S. Wang**, L. Zhu, M. Liu, and J. Ma, Gdts: Goal-guided diffusion model with tree sampling for multi-modal pedestrian trajectory prediction, [Under review], 2024. arXiv: 2311.14922 [cs.CV].

Awards

- Second Prize of Provincial Physics Science and Technology Innovation Award, China, 2016.
- École Centrale de Nantes Elite Scholarship, ECN, France, 2018.
- Postgraduate Studentship, HKUST, Hongkong SRA, 2021-present.