| created to exceed the performance of GIF files. PNG offe. |
|---|
| rs not just lossless compression but also a much brouder |
| and brighter color pulette. |
| - It can handle graphics with transparent or semi-transparent |
| backgrounds. |
| PNG are the next evolution of the GIF format. |
| |
| ->BMP :- Bitmap |
| |
| The BMP formult is un uncompressed toster file designed |
| to display high quality images on windows and store printable |
| photos. |
| - Microsoft developed for its aindows 05 to maintain the |
| resolution of digital image across different screens so devices. |
| It can store 2D images either in color or black & white. |
| · Muc and android devices are now compatible with them. |
| - Storing high-quality digital photos supporting the photo |
| printing process. |
| |
| |
| 2 Write a note on sampling and quantization. |
| Ans. |
| -The output of the sensors is a continuous voltage that |
| hus to be digitized. This involves two processes: Sampling |
| and quantization. |
| -> 5amalina : |
| -> Sampling: |
| - Il is a process of diagitizing the spatial coordinate values. |
| It may be viewed as partitioning the x-y plane into a grid of |
| M rows and N columns with the coordinates the center of each |
| cell in the grid being a pair from the cartesion product 72 50 ((x,y) |
| |

| n . | | | |
|-----|----|--|--|
| Dal | 6: | | |

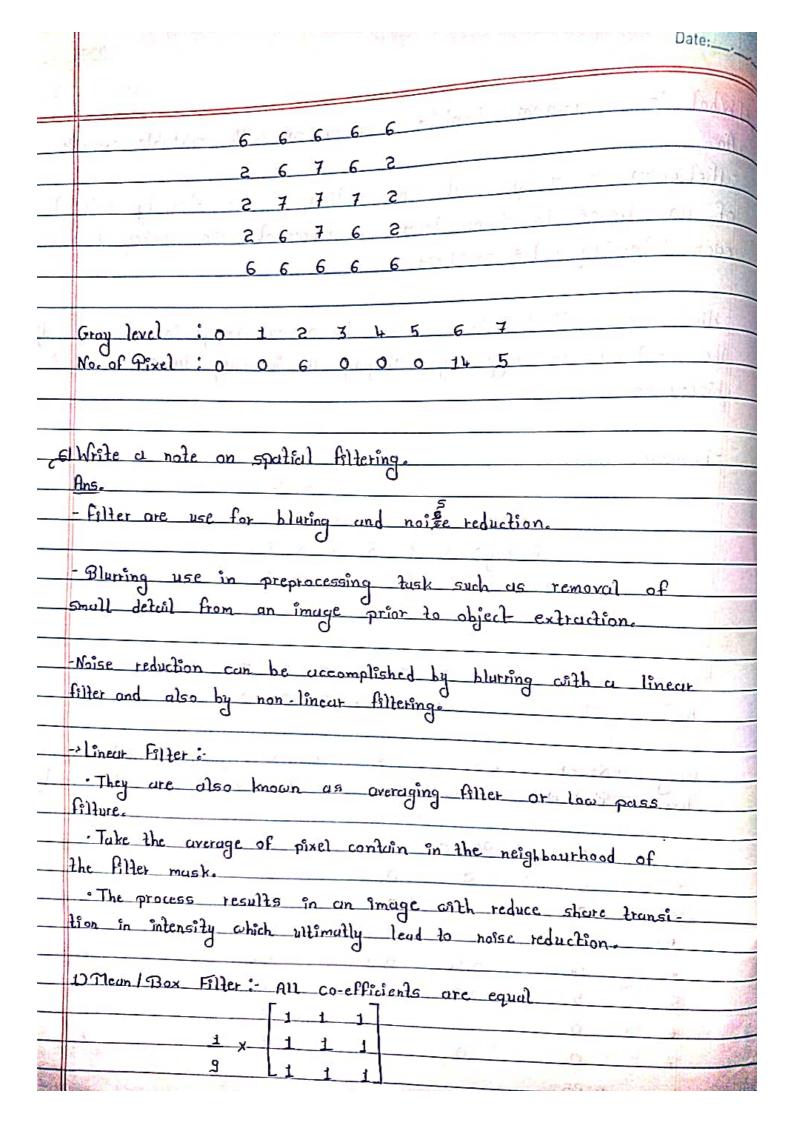
| | is a digital image if xy \in Ze. Each cell is called a picture element. |
|---|--|
| | We sample the continuous image into a e-D array fax, y) containing M rows and N columns, where (x, y) are discrete coordinates taking up integer values x=0, 1, M-1 and y=0, 1, N-1, so, f(0,1) indicates the second sample along the first row. Here a and 1 are not the values of physical coordinates when the image was sampled. |
| | -> Quantization: |
| | The fcs. 1) represent a continuous image function of two continuous variables and convert it to a digital image. The values of the above samples that span a continuous range of intensity values must be converted to discrete quantities. This is done by dividing the entire continuous intensity scale into L discrete intervals, ranging from black to white. Where black is represented by a value o and white represented by 1-1. Depending on the proximity of a sample to one of these L levels the continuous intensity levels are quantize in addition the number of discrete levels used the accuracy achived in quantization is highly dependent on the noise content of the sample. |
| 3 | Mention the fundamental steps used in digital image processing. Image Acquisition: Retrieving an image from some source usually hardcore based source for processing. Image acquisition involves pre-processing such as scaling. |
| | Page No.: |
| | |

| 7 | T - 1 - 1 - 1 |
|-------|---|
| - | - Image Enhancement: |
| | · Image Enhancement is a process or manipulation |
| ř. | Image Enhancement is a process of manipulating an image so that the result is more suitable than the original image for |
| | a specific application. |
| - | · It is application specific. |
| | Enhancement Techniques are problem oriented. |
| | · Viewer is the ultimate judge for image enhancement techniques |
| | - Image Restoration: |
| | · It is a process that aftemps to reconstruct or recover an |
| ¥ | image. |
| | |
| | Similar to enhancement improve the quality of the image. |
| 10 | removal of blur hy using a deblurring function is considered |
| | as a restoration techniques. |
| No. 1 | -Color image operated . |
| dri . | Color image processing: |
| | · Color is used as the busine for extracting features of interest |
| | |
| | · Color image processing is an area that has been gaining its |
| | importance because of the significant increase in the use digital |
| - | Live is |
| _ | Wavelets and Multiresolution Processing |
| | - Wavelets are the foundation for representing images in rations |
| | degree of resolution. |
| | - Image Compression: |
| | · Compression techniques are used to reduce the redundant |
| | information in the image duta in order to facilitate the storage |
| | transmission and distribution of image. |
| W. S. | O C |

| | - Morphological processing: |
|----|--|
| | ·Extract image components that are useful in the representation and |
| | des cription of region shape. |
| | · Morphological operations apply a structuring element to an input image. |
| | Creating an output image of the same size. |
| | 9 |
| | - Segmentation :- |
| | ·It is the process of partitioning of digital image into multiple segments. |
| | · Used to locate objects and boundries in an image. |
| | ·Autonomous segmentation is one of the most difficult task in image |
| | _ |
| | processing. |
| | - Image Operation and Obsertation: |
| | - Image Representation and Discription: |
| | After on image is segmented into regious the resulting aggregate of |
| | segmented pixels is represented & discribed for further computer |
| | processing |
| | |
| | Object Recognition: |
| | Object detection is the process of finding instances of objects in |
| | images. This allows for multiple objects to be identified and located within |
| | the same image. |
| | · Object recognition can be termed as identifying a specific object in |
| | a digital image or vidéo. |
| | |
| | |
| _ | 4) Describe the image sensing and acquisition process. |
| | Anse |
| | - Images are generated by the combination of an illumination source and |
| | the reflection lubsorption of energy from that source by the elements |
| | of the scene being imaged. |
| | O O |
| | control larger on what |
| J. | Page No.: |

-> Single imaging sensor: · This can be a photo diode which is constructed with sillicon material and its output voltage is proportional to the amount of falling on it. - Line Sensor: · It is consists of an in-line orrangement of sensors in the form of a sensor strip, which provides imagine element in one direction movement perpendicular to the strip provides imaging in the other direction. - Array Sensor · Here the single imaging sensor are arranged in the form of a 2-D array as the sensor array is 2-dimensional a complet image our be obtained by focusing the a pattern on to the surface of the array and hence movement in any direction is not hecesson. -> Image Acquisition :-·The response of each sensor is proportional to the integral of light energy projected onto the surface of the sensor. The sensor integrates this energy over minutes or hours to reduce the noise. · The energy from an illumination source is reflected from the scene element being imaged. · The imaging system & collects this reflected and focuses it onto the image plane. . The front end of the imaging system projects the viewed sence anto the lens focus punate plune The sensor array which is coincidental with the focal plane produces output proportional to the integral of light received at each sensor which are then digitized resulting in a digital output image.

| Ans. | | | 15 | ation with suitat | |
|----------|---------------|--------------|------------|--|------------------|
| Histor | tam is a | graphical r | epresental | ion of the intensi | ity distribution |
| Of_C | I mage In | simple_ter | ms . it | represents the nu | mber of pixels |
| _each_ | intensity val | we cosidered | 3 3 | 3 3 A | |
| _ | | | | 1 | |
| Histo | gram equliza | tion is a m | nethod to | process image in | order to adi |
| the_c | ontrust un | image by r | nodifying | the intensity dist | tribution of |
| — piejog | rcime | | | | |
| | | | | | |
| Exam | ple:- | | | · Carles are l' | = 15 L = |
| | | | 4 4 | <u> 4 4 </u> | |
| | | | | 5 4 3 | was all it |
| | | (x,y) = | 3 5 | 5 5 3 | |
| | | | 3 4 | 5 4 3 | |
| | | | 4 4 | 4 4 4 | will it a |
| | | | | | |
| II . U | level : | | 3 4 | 5 6 7 | |
| No. | of Pixel: | 0 0 0 | 6 14 | 5 0 0 | - 411 |
| | | | | | |
| Gray | | PDF | _CDF | maximum gray | Histogram_ |
| level | Pixel nk | Pk=nk/n | _sk_ | level C7) * sk | zeition leve |
| | | | | | V Ti Is |
| 0 | 0 | 0/52 = 0 | 0 | <u> </u> | 1 |
| 1 | 00 | 0 | 0 | 0 | 111 0 |
| 5 | 0 | 0 | 0 | . 0 | 0 |
| 3 | 6 | 0.24 | 0.5# | 1.68 | 20 |
| 4 | 14 | 0.56 | -0.8 | 5.6 | 6 |
| 5 | 5 | 0.2 | | 7 | -0.1 |
| 6_ | 0 | | | 7 | 7 |
| 7 | 0 | 0 | 4. | 7 | 7 |
| - 11 | | | | | |



1. Cyan (c): It is a blue-green color that absorbs red light. In the gran cry model cyan is considered a primary color meuning it cannot be created by mixing other colors. It is essential in subtractive color mixing because it is the complement of red. 2. Mugenta (M): Magenta is a purplish-red color that absorbs green light. Like eyan magenta is a primary color in the CMY model and annot be derived from other colors. It is the complement of green. 3. Yellow Cy): Yellow is a primary color in the CMY model obsorbing blue light. It complements blue. > In the cry model colors are created by subtracting varying amounts of these primary colors from white light when all three primary colors are combined, and their maximum intensity they theoretically absorb all colors resulting in black. However in proctical applications like printing a true bluck ink is typically added to improve the depth and richness of dark colors as the combination of Cyan, Magenta and Yellow alone often result in a dark brown color rather than true black. Exploin the psudo color image processing. > Psudo-color image processing also known us false-color. image processing is a technique use to enhance the visual representation of images by mapping pixel intensities to color in a way that may not directly correspond to the colors observed in the original scene. This method is particularly useful in situations where the human eye may have difficulty discering

| due to imitations in contras |
|---|
| - True Grand line |
| pstudo color image processing level of the original gray- |
| P This was to the |
| values of the original image on the predefined color map. |
| colors to Intentsity levels "sual contrast and highligh |
| Pa the original gray image |
| on the original gray image and scientific visualization |
| ng finds application in variou |
| and can gen |

| 77 | | | | | |
|----------|--|--|--|--|--|
| ASSES 1 | 10 3 10- with proper diagram. | | | | |
| - f - q | Describe Image degradation/Restoration with proper diagram. | | | | |
| | Ans. | | | | |
| | | | | | |
| Paris - | Image Degradation refers to the process by which | | | | |
| Marian I | the quality of an image deteriorates due to various factors the quality of an image deteriorates due to various factors | | | | |
| NES-ST. | the quality of an image determination of distoration. such as noise blurring, compression or other forms of distoration. transmi- | | | | |
| | This degredation can occure during image acquisition transmi- | | | | |
| | This degredation can occure auting made la image degredation. | | | | |
| Dr. | ssion of processing strings | | | | |
| 11- | | | | | |
| 200 | > Image Restoration: | | | | |
| R-P | Image restoration is the process of recovering the | | | | |
| edw. | original image form a degraded version by minimizing the effects | | | | |
| es come | of degradation factors. It involves various techniques aimed | | | | |
| | at enhancing image quality and improving visual fidelity. | | | | |
| eiu i | The first of the first of the state of the first of the f | | | | |
| nH(m-1) | Att although the aleman progress from the amount of | | | | |
| | | | | | |
| Farmer | Degradation g(x.y) Rectoration f(x.y) | | | | |
| WE PG | Pegradation g(x.y) Rectoration f(x.y) function f(x.y) | | | | |
| | CH) n coc.y) | | | | |
| | hoise | | | | |
| wed - | | | | | |
| ka -01 | Degradution Restoration | | | | |
| regi . | f(x,y) = original image | | | | |
| to blane | h(x,y) = degradution function | | | | |
| 2 | g(x,y) : degraded image | | | | |
| 14 | n(x,y) = Noise in the image | | | | |
| mai | The made | | | | |
| tin | -> Operator H Luc Charge | | | | |
| - | -> Operator H has following properties. | | | | |
| | Al II is a linear aperator | | | | |
| inter to | al It is position invarient | | | | |
| | III obeys the rules of homogeneity | | | | |

| | -> Pre-processing: Row image captured by the camera often |
|------------|---|
| | -> Pre-processing : Pow image captured py contain noise, distortion of other unwanted artifacts. pre- |
| £ = | contain noise, distartion of other unitarity up the image and |
| | processing technique are applied to alean up the image and |
| E I | enhance quality. |
| | 1 210 |
| | -> Feature Extraction: Once the images are pre-processed the |
| | 1 1 C I A DA TENIAL DE LA CONTRACTOR DE |
| | the image. This cloud include identifying edge shapes clors |
| | the image, this close includes that are important for |
| E. | texture or other visual aftributes that are important for |
| Elvi | the tust at hunds |
| | 1 1 1 Leafure are |
| <u> </u> | -> Pattern Recognition: In this step the extracted feature are |
| 14 | analyzed and compared to known patterns or models stored |
| | in the systems memory. This allow the system to recognize |
| | object detect classify items or perform other detest tasks |
| 1 | bused on the visual information contained in the image. |
| | |
| is. | -) Decision Making: Based on the result of patterns recogni- |
| 7-1 | tion the machine vision system makes decisions or takes |
| 42 | actions accordingly this cloud involve stating objects on a |
| 4. | production line guiding robotic arms to perform specific |
| | tusks tricaring clarm for quality control secure as a selection |
| | feedback to human operators. |
| | TO HUMAN SPONTON |
| r. | Have de la |
| of . | Here diagram of muchine vision system: |
| - | T |
| 30 | Image Acquisition |
| | Pre - Processing |
| i i | Feature Extraction |
| Maga. | Puttern - Recognition |
| | Decisionmaking |
| Deligna ve | |