00 fundamentals skimage

September 11, 2019

To participate, you'll need to git clone (or download the .zip from GitHub):

https://github.com/imagexd/2019-tutorial-skimage

You can do that in git using:

If you have already cloned the material, please issue git pull now and reload the notebook to ensure that you have the latest updates.

[1]: %matplotlib inline

- https://scikit-image.org
- Take a look at the gallery, API docs
- The underlying stack: NumPy, SciPy (especially scipy.ndimage), Cython

But, before we can start using scikit-image, we need to understand how images are represented. For this, we will use NumPy.

0.0.1 A quick 5-minute quiz, to refresh our NumPy skills!

Start with:

import numpy as np

Then answer:

- 1. What version of NumPy do you have installed? (Hint: np.__version__)
- 2. How do I construct a 300x500 array of zeros?
- 3. How do I generate an array with the numbers from 0 to 9?
- 4. How do I take the square of this array?
- 5. What is the data-type of this array? (Hint: x.dtype) What is the data-type of the array [1, 2, 3]?
- 6. What is the shape of the following array: [[1, 2, 3], [4, 5, 6]]
- 7. What, do you predict, is the result of [[1, 2, 3], [4, 5, 6]] + [10, 11, 12]? (Hint: broadcasting)
- 8. What, do you predict, is the result of np.array([1,2,3], dtype=np.uint8) 2? (Hint: the 'u' stands for unsigned)
- 9. What, do you predict, is the result of x = np.ones((5, 1)); x @ x.T (Hint: @ is matrix multiplication)
- 10. What, do you predict, is the result of x = np.array([1, 2, 3]); x[x < 3] (Hint: what is x > 3?)

1 Images are numpy arrays

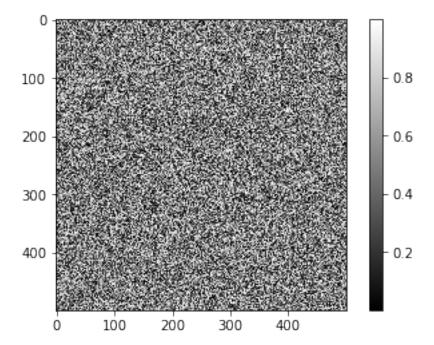
Images are represented in scikit-image using standard numpy arrays. This allows maximum inter-operability with other libraries in the scientific Python ecosystem, such as matplotlib and scipy.

Let's see how to build a grayscale image as a 2D array:

```
[2]: import numpy as np from matplotlib import pyplot as plt
```

```
[3]: random_image = np.random.random([500, 500])

plt.imshow(random_image, cmap='gray')
plt.colorbar();
```



The same holds for "real-world" images:

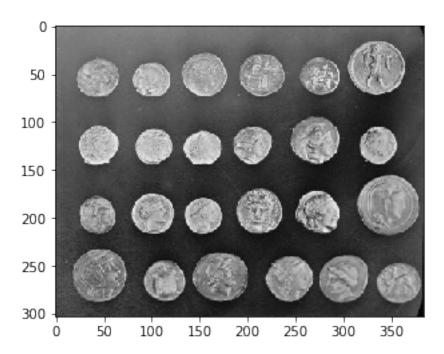
```
[4]: from skimage import data
    coins = data.coins()

    print('Type:', type(coins))
    print('dtype:', coins.dtype)
    print('shape:', coins.shape)
```

```
plt.imshow(coins, cmap='gray');
```

Type: <class 'numpy.ndarray'>

dtype: uint8
shape: (303, 384)



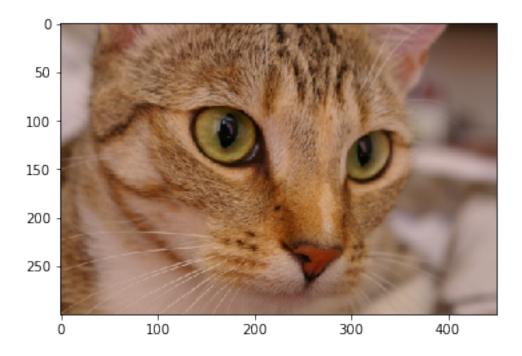
A color image is a 3D array, where the last dimension has size 3 and represents the red, green, and blue channels:

```
[5]: cat = data.chelsea()

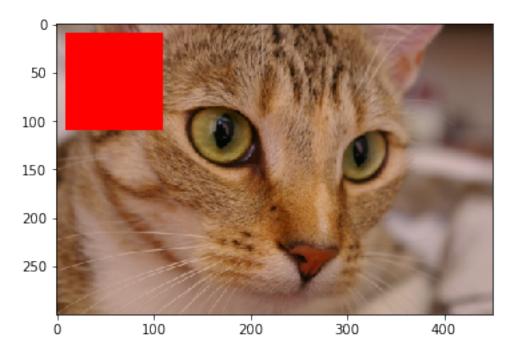
print("Shape:", cat.shape)
print("Values min/max:", cat.min(), cat.max())

plt.imshow(cat);
```

Shape: (300, 451, 3) Values min/max: 0 231



These are $just\ NumPy\ arrays$. E.g., we can make a red square by using standard array slicing and manipulation:



Images can also include transparent regions by adding a 4th dimension, called an alpha layer.

1.0.1 Other shapes, and their meanings

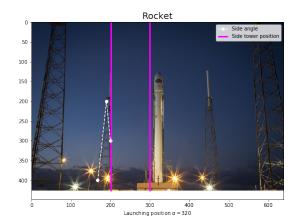
Image type	Coordinates
2D grayscale	(row, column)
2D multichannel	(row, column, channel)
3D grayscale (or volumetric)	(plane, row, column)
3D multichannel	(plane, row, column, channel)

1.1 Displaying images using matplotlib

```
[7]: from skimage import data

img0 = data.chelsea()
img1 = data.rocket()
```





For more on plotting, see the Matplotlib documentation and pyplot API.

1.2 Data types and image values

In literature, one finds different conventions for representing image values:

```
0-255 where 0 is black, 255 is white 0-1 where 0 is black, 1 is white
```

scikit-image supports both conventions—the choice is determined by the data-type of the array.

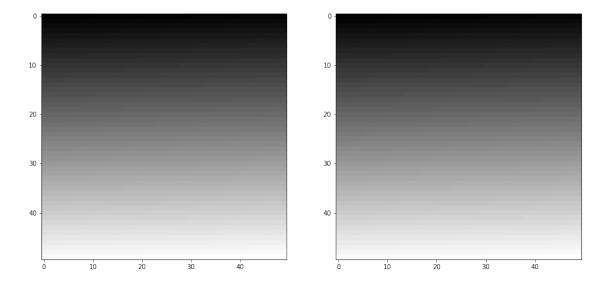
E.g., here, I generate two valid images:

```
[9]: linear0 = np.linspace(0, 1, 2500).reshape((50, 50))
linear1 = np.linspace(0, 255, 2500).reshape((50, 50)).astype(np.uint8)

print("Linear0:", linear0.dtype, linear0.min(), linear0.max())
print("Linear1:", linear1.dtype, linear1.min(), linear1.max())

fig, (ax0, ax1) = plt.subplots(1, 2, figsize=(15, 15))
ax0.imshow(linear0, cmap='gray')
ax1.imshow(linear1, cmap='gray');
```

Linear0: float64 0.0 1.0 Linear1: uint8 0 255



The library is designed in such a way that any data-type is allowed as input, as long as the range is correct (0-1 for floating point images, 0-255 for unsigned bytes, 0-65535 for unsigned 16-bit integers).

You can convert images between different representations by using img_as_float, img_as_ubyte, etc.:

```
[10]: from skimage import img_as_float, img_as_ubyte
      image = data.chelsea()
      image_ubyte = img_as_ubyte(image)
      image_float = img_as_float(image)
      print("type, min, max:", image_ubyte.dtype, image_ubyte.min(), image_ubyte.
       \rightarrowmax())
      print("type, min, max:", image_float.dtype, image_float.min(), image_float.
       \rightarrowmax())
      print()
      print("231/255 =", 231/255.)
     type, min, max: uint8 0 231
     type, min, max: float64 0.0 0.9058823529411765
     231/255 = 0.9058823529411765
     Your code would then typically look like this:
     def my_function(any_image):
        float_image = img_as_float(any_image)
         # Proceed, knowing image is in [0, 1]
```

We recommend using the floating point representation, given that scikit-image mostly uses that format internally.

1.3 Image I/O

Mostly, we won't be using input images from the scikit-image example data sets. Those images are typically stored in JPEG or PNG format. Since scikit-image operates on NumPy arrays, *any* image reader library that provides arrays will do. Options include imageio, matplotlib, pillow, etc.

scikit-image conveniently wraps many of these in the io submodule, and will use whichever of the libraries mentioned above are installed:

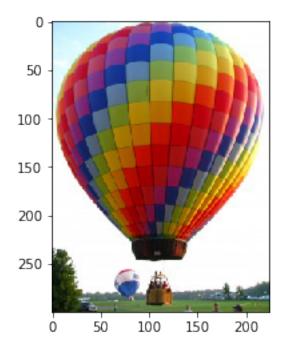
```
[11]: from skimage import io

image = io.imread('data/balloon.jpg')

print(type(image))
print(image.dtype)
print(image.shape)
print(image.min(), image.max())

plt.imshow(image);
```

```
<class 'numpy.ndarray'>
uint8
(300, 225, 3)
0 255
```



We also have the ability to load multiple images, or multi-layer TIFF images:

```
[12]: from skimage import data_dir
      !ls $data_dir
     __init__.py
                                        grass.png
                                        gray_morph_output.npz
     __pycache__
     _binary_blobs.py
                                        green_palette.png
     _blobs_3d_fiji_skeleton.tif
                                        horse.png
                                        hubble_deep_field.jpg
     _detect.py
     astronaut.png
                                        ihc.png
     astronaut_GRAY_hog_L1.npy
                                        lbpcascade_frontalface_opencv.xml
     astronaut_GRAY_hog_L2-Hys.npy
                                        lfw_subset.npy
     block.png
                                        logo.png
     brick.png
                                        microaneurysms.png
     bw_text.png
                                        moon.png
     bw_text_skeleton.npy
                                        motorcycle_disp.npz
                                        motorcycle_left.png
     camera.png
     cells_qpi.npz
                                        motorcycle_right.png
     cells_qpi_zipped.zip
                                        mssim_matlab_output.npz
     checker_bilevel.png
                                        multi.fits
     chelsea.png
                                        multipage.tif
     chessboard_GRAY.png
                                        multipage_rgb.tif
     chessboard_GRAY_U16.tif
                                        no_time_for_that_tiny.gif
                                        orb_descriptor_positions.txt
     chessboard_GRAY_U16B.tif
     chessboard_GRAY_U8.npy
                                        page.png
     chessboard_GRAY_U8.npz
                                        palette_color.png
     chessboard_RGB.png
                                        palette_gray.png
     chessboard_RGB_U8.npy
                                        phantom.png
     chessboard_RGB_U8.npz
                                        rank_filter_tests.npz
     clock_motion.png
                                        retina.jpg
     coffee.png
                                        rocket.jpg
                                        rough-wall.png
     coins.png
     color.png
                                        simple.fits
     diamond-matlab-output.npz
                                        tests
     disk-matlab-output.npz
                                        text.png
                                        truncated.jpg
     foo3x5x4indexed.png
[13]: | ic = io.ImageCollection(data_dir + '/*.png')
      print('Type:', type(ic))
      ic.files
```

Type: <class 'skimage.io.collection.ImageCollection'>

- [13]: ['/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/astronaut.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/block.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/brick.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/bw_text.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/camera.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/checker_bilevel.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/chelsea.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/chessboard_GRAY.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/chessboard_RGB.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/clock_motion.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/coffee.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/coins.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/color.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/foo3x5x4indexed.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/grass.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/green_palette.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/horse.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/ihc.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/logo.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/microaneurysms.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/moon.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/motorcycle_left.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-packages/skimage/data/motorcycle_right.png',
 - '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-

```
packages/skimage/data/page.png',
   '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-
packages/skimage/data/palette_color.png',
   '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-
packages/skimage/data/palette_gray.png',
   '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-
packages/skimage/data/phantom.png',
   '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-
packages/skimage/data/rough-wall.png',
   '/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-
packages/skimage/data/text.png']
```

```
[14]: import os

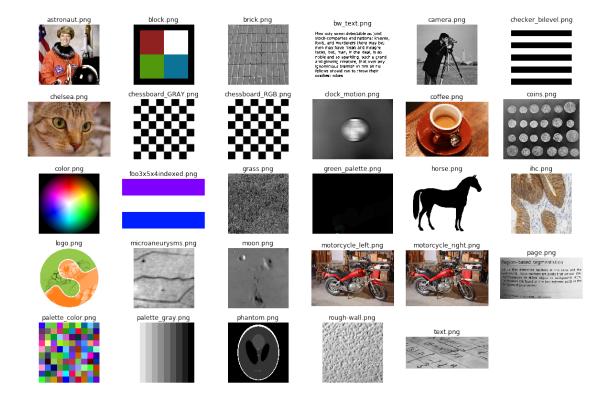
f, axes = plt.subplots(nrows=5, ncols=len(ic) // 5 + 1, figsize=(15, 10))

# subplots returns the figure and an array of axes
# we use `axes.ravel()` to turn these into a list
axes = axes.ravel()

for ax in axes:
    ax.axis('off')

for i, image in enumerate(ic):
    axes[i].imshow(image, cmap='gray')
    axes[i].set_title(os.path.basename(ic.files[i]))

plt.tight_layout()
```



1.4 Exercise: draw the letter H

Define a function that takes as input an RGB image and a pair of coordinates (row, column), and returns a copy with a green letter H overlaid at those coordinates. The coordinates point to the top-left corner of the H.

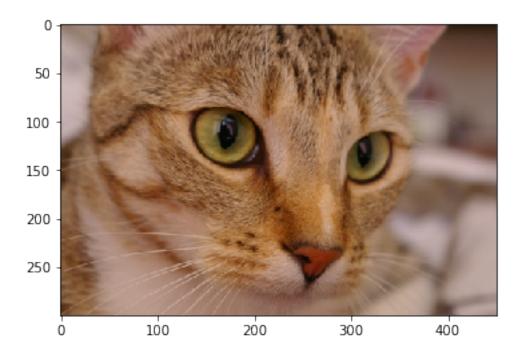
The arms and strut of the H should have a width of 3 pixels, and the H itself should have a height of 24 pixels and width of 20 pixels.

Start with the following template:

```
[15]: def draw_H(image, coords, color=(0, 255, 0)):
    out = image.copy()
    ...
    return out
```

Test your function like so:

```
[16]: cat = data.chelsea()
cat_H = draw_H(cat, (50, -50))
plt.imshow(cat_H);
```



1.5 Exercise: visualizing RGB channels

Display the different color channels of the image along (each as a gray-scale image). Start with the following template:

```
image = plt.imread('data/Bells-Beach.jpg')

# --- assign each color channel to a different variable ---

r = ...
g = ...
b = ...

# --- display the image and r, g, b channels ---

f, axes = plt.subplots(1, 4, figsize=(16, 5))

for ax in axes:
    ax.axis('off')

(ax_r, ax_g, ax_b, ax_color) = axes

ax_r.imshow(r, cmap='gray')
```

```
ax_r.set_title('red channel')
ax_g.imshow(g, cmap='gray')
ax_g.set_title('green channel')
ax_b.imshow(b, cmap='gray')
ax_b.set_title('blue channel')
# --- Here, we stack the R, G, and B layers again
# to form a color image ---
ax_color.imshow(np.stack([r, g, b], axis=2))
ax_color.set_title('all channels');
       TypeError
                                                Traceback (most recent call last)
       <ipython-input-17-e057ff15c311> in <module>
        18 (ax_r, ax_g, ax_b, ax_{color}) = axes
        19
   ---> 20 ax r.imshow(r, cmap='gray')
        21 ax_r.set_title('red channel')
        22
       ~/anaconda3/envs/imagexd19/lib/python3.7/site-packages/matplotlib/
→__init__.py in inner(ax, data, *args, **kwargs)
               def inner(ax, *args, data=None, **kwargs):
      1599
                   if data is None:
      1600
   -> 1601
                       return func(ax, *map(sanitize_sequence, args), **kwargs)
      1602
                   bound = new_sig.bind(ax, *args, **kwargs)
      1603
       ~/anaconda3/envs/imagexd19/lib/python3.7/site-packages/matplotlib/cbook/
→deprecation.py in wrapper(*args, **kwargs)
      367
                         f"%(removal)s. If any parameter follows {name!r}, they "
                           f"should be pass as keyword, not positionally.")
       368
   --> 369
                   return func(*args, **kwargs)
       370
       371
               return wrapper
       ~/anaconda3/envs/imagexd19/lib/python3.7/site-packages/matplotlib/cbook/
```

→deprecation.py in wrapper(*args, **kwargs)

```
f"%(removal)s. If any parameter follows {name!r}, they "
      367
       368
                           f"should be pass as keyword, not positionally.")
   --> 369
                   return func(*args, **kwargs)
       370
       371
               return wrapper
       ~/anaconda3/envs/imagexd19/lib/python3.7/site-packages/matplotlib/axes/
→ axes.py in imshow(self, X, cmap, norm, aspect, interpolation, alpha, vmin,
→vmax, origin, extent, shape, filternorm, filterrad, imlim, resample, url, u
→**kwargs)
      5669
                                         resample=resample, **kwargs)
      5670
  -> 5671
                   im.set_data(X)
      5672
                   im.set_alpha(alpha)
      5673
                   if im.get_clip_path() is None:
       ~/anaconda3/envs/imagexd19/lib/python3.7/site-packages/matplotlib/image.
→py in set_data(self, A)
       683
                           not np.can_cast(self._A.dtype, float, "same_kind")):
       684
                       raise TypeError("Image data of dtype {} cannot be⊔
→converted to "
  --> 685
                                       "float".format(self._A.dtype))
       686
       687
                   if not (self._A.ndim == 2
```

TypeError: Image data of dtype object cannot be converted to float

Now, take a look at the following R, G, and B channels. How would their combination look? (Write some code to confirm your intuition.)

```
[18]: from skimage import draw

red = np.zeros((300, 300))
green = np.zeros((300, 300))
blue = np.zeros((300, 300))

r, c = draw.circle(100, 100, 100)
red[r, c] = 1

r, c = draw.circle(100, 200, 100)
green[r, c] = 1

r, c = draw.circle(200, 150, 100)
blue[r, c] = 1

f, axes = plt.subplots(1, 3)
for (ax, channel) in zip(axes, [red, green, blue]):
    ax.imshow(channel, cmap='gray')
    ax.axis('off')
```



```
[19]: | # Hint: np.stack([...], axis=2)
```

1.6 Exercise: Convert to grayscale ("black and white")

The *relative luminance* of an image is the intensity of light coming from each point. Different colors contribute differently to the luminance: it's very hard to have a bright, pure blue, for example. So, starting from an RGB image, the luminance is given by:

$$Y = 0.2126R + 0.7152G + 0.0722B$$

Use Python 3.5's matrix multiplication, **©**, to convert an RGB image to a grayscale luminance image according to the formula above.

Compare your results to that obtained with skimage.color.rgb2gray.

Change the coefficients to 1/3 (i.e., take the mean of the red, green, and blue channels, to see how that approach compares with rgb2gray).

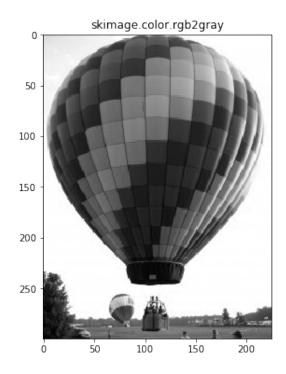
```
[20]: from skimage import color, img_as_float
  image = img_as_float(io.imread('data/balloon.jpg'))
  gray = color.rgb2gray(image)
  my_gray = ...
# --- display the results ---
  f, (ax0, ax1) = plt.subplots(1, 2, figsize=(10, 6))
  ax0.imshow(gray, cmap='gray')
  ax0.set_title('skimage.color.rgb2gray')
  ax1.imshow(my_gray, cmap='gray')
  ax1.set_title('my_rgb2gray')
```

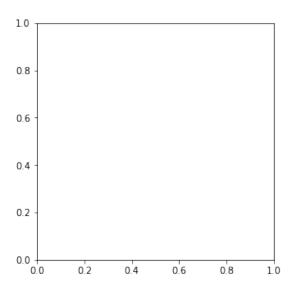
```
TypeError
                                                Traceback (most recent call last)
       <ipython-input-20-a5fdfebe8302> in <module>
       13 ax0.set_title('skimage.color.rgb2gray')
   ---> 15 ax1.imshow(my_gray, cmap='gray')
        16 ax1.set_title('my rgb2gray')
       ~/anaconda3/envs/imagexd19/lib/python3.7/site-packages/matplotlib/
→__init__.py in inner(ax, data, *args, **kwargs)
               def inner(ax, *args, data=None, **kwargs):
      1599
      1600
                   if data is None:
                       return func(ax, *map(sanitize_sequence, args), **kwargs)
  -> 1601
      1602
      1603
                   bound = new_sig.bind(ax, *args, **kwargs)
       ~/anaconda3/envs/imagexd19/lib/python3.7/site-packages/matplotlib/cbook/
→deprecation.py in wrapper(*args, **kwargs)
      367
                        f"%(removal)s. If any parameter follows {name!r}, they "
                           f"should be pass as keyword, not positionally.")
       368
                   return func(*args, **kwargs)
   --> 369
       370
```

371 return wrapper

```
~/anaconda3/envs/imagexd19/lib/python3.7/site-packages/matplotlib/cbook/
→deprecation.py in wrapper(*args, **kwargs)
      367
                        f"%(removal)s. If any parameter follows {name!r}, they "
       368
                           f"should be pass as keyword, not positionally.")
   --> 369
                   return func(*args, **kwargs)
       370
       371
               return wrapper
       ~/anaconda3/envs/imagexd19/lib/python3.7/site-packages/matplotlib/axes/
→ axes.py in imshow(self, X, cmap, norm, aspect, interpolation, alpha, vmin, u
→vmax, origin, extent, shape, filternorm, filterrad, imlim, resample, url,
→**kwargs)
      5669
                                         resample=resample, **kwargs)
      5670
  -> 5671
                   im.set_data(X)
      5672
                   im.set_alpha(alpha)
      5673
                   if im.get_clip_path() is None:
       ~/anaconda3/envs/imagexd19/lib/python3.7/site-packages/matplotlib/image.
→py in set_data(self, A)
       683
                           not np.can_cast(self._A.dtype, float, "same_kind")):
       684
                       raise TypeError("Image data of dtype {} cannot be_
→converted to "
   --> 685
                                       "float".format(self._A.dtype))
       686
                   if not (self._A.ndim == 2
       687
```

TypeError: Image data of dtype object cannot be converted to float





1.7 Just for fun

1.7.1 Demo: skimage + keras

```
[25]: from tensorflow.keras.applications.inception_v3 import InceptionV3, □

→preprocess_input, decode_predictions

net = InceptionV3()
```

```
/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-
packages/tensorflow/python/framework/dtypes.py:526: FutureWarning: Passing
(type, 1) or '1type' as a synonym of type is deprecated; in a future version of
numpy, it will be understood as (type, (1,)) / '(1,)type'.
  _np_qint8 = np.dtype([("qint8", np.int8, 1)])
/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-
packages/tensorflow/python/framework/dtypes.py:527: FutureWarning: Passing
(type, 1) or '1type' as a synonym of type is deprecated; in a future version of
numpy, it will be understood as (type, (1,)) / '(1,)type'.
  _np_quint8 = np.dtype([("quint8", np.uint8, 1)])
/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-
packages/tensorflow/python/framework/dtypes.py:528: FutureWarning: Passing
(type, 1) or '1type' as a synonym of type is deprecated; in a future version of
numpy, it will be understood as (type, (1,)) / '(1,)type'.
  _np_qint16 = np.dtype([("qint16", np.int16, 1)])
/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-
```

```
packages/tensorflow/python/framework/dtypes.py:529: FutureWarning: Passing
(type, 1) or '1type' as a synonym of type is deprecated; in a future version of
numpy, it will be understood as (type, (1,)) / '(1,)type'.
  _np_quint16 = np.dtype([("quint16", np.uint16, 1)])
/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-
packages/tensorflow/python/framework/dtypes.py:530: FutureWarning: Passing
(type, 1) or '1type' as a synonym of type is deprecated; in a future version of
numpy, it will be understood as (type, (1,)) / '(1,)type'.
  _np_qint32 = np.dtype([("qint32", np.int32, 1)])
/Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-
packages/tensorflow/python/framework/dtypes.py:535: FutureWarning: Passing
(type, 1) or '1type' as a synonym of type is deprecated; in a future version of
numpy, it will be understood as (type, (1,)) / '(1,)type'.
 np_resource = np.dtype([("resource", np.ubyte, 1)])
WARNING:tensorflow:From /Users/dani/anaconda3/envs/imagexd19/lib/python3.7/site-
packages/tensorflow/python/ops/resource_variable_ops.py:435: colocate_with (from
tensorflow.python.framework.ops) is deprecated and will be removed in a future
version.
Instructions for updating:
Colocations handled automatically by placer.
Downloading data from https://github.com/fchollet/deep-learning-
models/releases/download/v0.5/inception_v3_weights_tf_dim_ordering_tf_kernels.h5
```

```
[26]: from skimage import transform

def inception_predict(image):
    # Rescale image to 299x299, as required by InceptionV3
    image_prep = transform.resize(image, (299, 299, 3), mode='reflect')

# Scale image values to [-1, 1], as required by InceptionV3
    image_prep = (img_as_float(image_prep) - 0.5) * 2

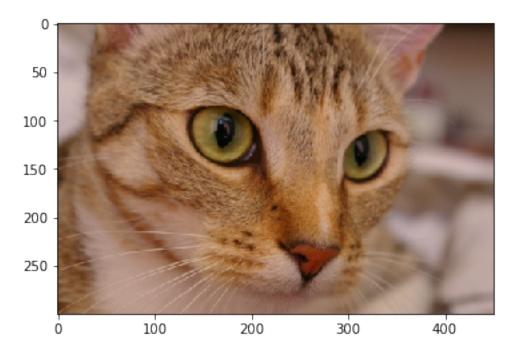
predictions = decode_predictions(
        net.predict(image_prep[None, ...])
    )

plt.imshow(image, cmap='gray')

for pred in predictions[0]:
        (n, klass, prob) = pred
        print(f'{klass:>15} ({prob:.3f})')
```

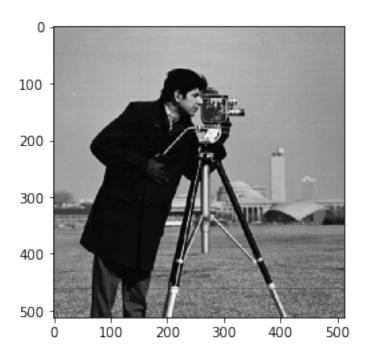
```
[27]: from skimage import data, img_as_float inception_predict(data.chelsea())
```

Downloading data from https://storage.googleapis.com/download.tensorflow.org/dat



[28]: inception_predict(data.camera())

tripod (0.937) crutch (0.002) binoculars (0.002) reflex_camera (0.001) backpack (0.000)



[29]: inception_predict(data.coffee())

espresso (0.982)

cup (0.002)

coffee_mug (0.001)

eggnog (0.001)

espresso_maker (0.001)



[]:[