# Particle Swam & Electromagnetism-like Mechanism Optimization

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# Particle Swam and Electromagnetism-like Mechanism Optimization Methods

- Particle Swam Optimization, PSO
- Electromagnetism-like Mechanism, EM



#### Particle Swam Optimization, PSO

- Swam Intelligence
  - Characteristics of social animals or insects
  - Appears in swam behaviors of natural creature
    - ◆ Food search, food hunting, migration against the hostile environment, fight for survival, territory defense, etc.
    - Corporation between individuals
  - Might have a leader coordinates or instructs the flock
  - Might be a communicative and gregarious herd of creature

#### **PSO**

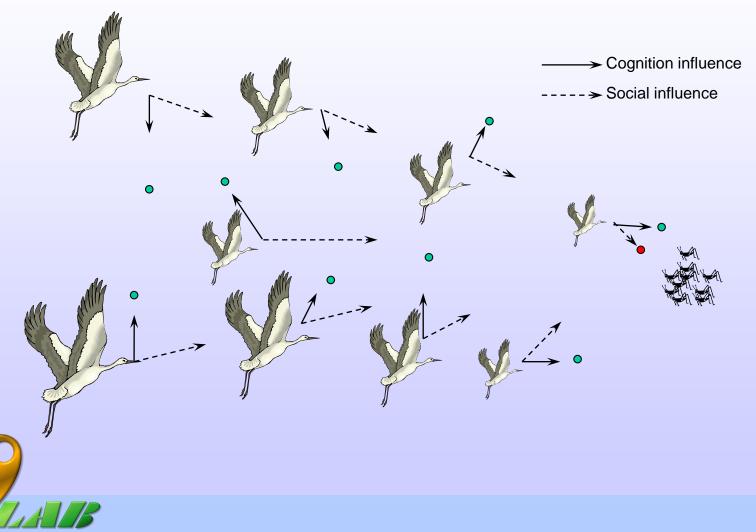
- Proposed by Eberhart and Kennedy (1995)
- Inspired by the food search and hunting behaviors of a flock of birds, fishes, wild animals or a swam of small creature
  - The individual refers to its own experience and the instruction from the swam
- These individuals are treated as particles
  - Each particle represents a solution search agent
  - The position of a particle in the environmental space of the swam is a solution to the optimization problem

#### Memory used in PSO to guide the search

- Particle has individual cognition
  - Knowing its own solution search experience
- Particle has social information or knowledge
  - Knowing the best solution search experience so far in the whole swam



## **Swam Behavior**



### **PSO Applications**

- Applied to continuous optimization problems
- General discrete PSO is not well-developed yet
  - Few methodologies were proposed for dealing with specific combinatorial optimization problems, such as TSPs, JSPs, etc.



#### **General POS for Continuous Problems**

A general continuous optimization problem without intervariable constraints

$$\min f(\mathbf{x})$$

where 
$$\mathbf{x} \in [\mathbf{l}, \mathbf{u}]; \mathbf{x}, \mathbf{l}, \mathbf{u} \in \mathbb{R}^n; l_i \le x_i \le u_i; i = 1, 2, ..., n$$

Particle swarm: a population of solution agents

$$X = \{\mathbf{x}^1, \mathbf{x}^2, ..., \mathbf{x}^m\}, \mathbf{x}^j = \begin{bmatrix} x_1^j x_2^j \cdots x_n^j \end{bmatrix},$$

$$V = \{\mathbf{v}^1, \mathbf{v}^2, ..., \mathbf{v}^m\}, \mathbf{v}^j = \begin{bmatrix} v_1^j v_2^j \cdots v_n^j \end{bmatrix}$$

 $\mathbf{x}^{j}$  is position vector and  $\mathbf{v}^{j}$  is velocity vector for a particle j

$$X' = \{\mathbf{x}'^{1}, \mathbf{x}'^{2}, \dots, \mathbf{x}'^{m}\}, \mathbf{x}'^{j} = [x_{1}'^{j} x_{2}'^{j} \cdots x_{n}'^{j}],$$

$$\mathbf{x}^{*} = [x_{1}^{*} x_{2}^{*} \cdots x_{n}^{*}]$$

 $\mathbf{x}^{\prime j}$ : Individual best position of particle j

x\*: Global best position; the best solution so far searched by the swam of particles

#### Three steps in PSO algorithm

- Assign a initial position and record it as the local best solution for each particle and assign the best solution so far for the swam
- Compute velocity vectors and move the particles to new positions
- Update the local and global best positions



#### **Algorithm of PSO**

```
Procedure Particle Swarm Optimization Algorithm
begin
 Initialization(X, \mathbf{u}, \mathbf{l})
 Iterations ← 1
 repeat while iterations < t
     MoveParticlestoNewPositions(X, V, c_1, c_2)
       // c_1, c_2 are cognition and social learning factors
    UpdateTheBestPositions(X)
       iterations ← iterations + 1
 end repeat
end
```

#### Initialization

- Assign an initial position to each particle
- Evaluate the objective function value for each particle and record the initial position as the local best solution for each particle
- Find the best solution from the local best solution of the particles and assign it as the best solution so far



#### Initialization

Procedure Initialization

for 
$$j = 1$$
 to  $m$  do

for 
$$i = 1$$
 to  $n$  do

$$x_i^j \leftarrow l_i + \sim U(0, 1) (u_i - l_i)$$

end for

$$\mathbf{x'}^j \leftarrow \mathbf{x}^j$$

$$f'^j \leftarrow f(\mathbf{x}'^j)$$

end for

$$f^* \leftarrow \min_{j=1,\dots,m} f'^{j}$$

$$\mathbf{x}^* \leftarrow \arg\min_{\forall \mathbf{x}^j} f(\mathbf{x}^j)$$

end



#### **Particle Movement**

- Refer to the local and global best positions (solutions) to decide the moving direction
  - $c_1$ : cognition factor
    - ◆Larger value → particle movement follows its own search experience
  - $c_2$ : social factor
    - ◆Larger value → particle movement follows the swam search experience
- Stochastically assign a moving distance to define the velocity vector for each particle
- Move the particles to their new positions using the computed velocity vectors

#### **Move Particles To New Positions**

Procedure MoveParticlesToNewPositions begin

for 
$$j = 1$$
 to  $m$  do
$$\alpha \leftarrow c_1 \cdot \sim U(0,1)$$

$$\beta \leftarrow c_2 \cdot \sim U(0,1)$$
for  $i = 1$  to  $n$  do
$$v_i^j \leftarrow \alpha(x_i'^j - x_i^j) + \beta(x_i^* - x_i^j)$$

$$x_i^j \leftarrow x_i^j + v_i^j$$

$$u_i, \text{if } x_i^j > u_i$$

$$x_i^j \leftarrow \begin{cases} u_i, \text{if } x_i^j > u_i \\ l_i, \text{if } x_i^j < l_i \\ x_i^j, \text{otherwise} \end{cases}$$

end for

end for



## **Update The Best Solution**

- Evaluate the objective function values of all particles
- Update local best position for each particle
- Update the best solution so far



#### **Update The Best Position**

```
Procedure UpdateTheBestPosition
begin
    for j = 1 to m do
        if f(\mathbf{x}^{j}) < f'^{j} then
             \mathbf{x}^{\prime j} \leftarrow \mathbf{x}^{j} \text{ and } f^{\prime j} \leftarrow f(\mathbf{x}^{j})
            if f'^j < f^* then
                 \mathbf{x}^* \leftarrow \mathbf{x}^j and f^* \leftarrow f'^j
             end if
         end if
    end for
end
```

#### **Discussion**

- **PSO** for Discrete optimization problems
  - A few research focused on specific problems
  - Specially tailored movement mechanism



# **PSO Demo**





#### **Electromagnetism-like Mechanism Optimization**

- Proposed by Birbil and Fang (2003)
- Is a multi-agent heuristic optimization method
- A population of solution agents are defined in the solution space
  - These agents are regarded as chargeable particles
  - The position of each particle represents a solution to the problem
- The position of each particle represents a solution to a continuous optimization problem
- Simulate the attraction and repulsion forces between electrical charged particles in an electromagnetism field

- Electrical charge is assigned to each particle based on the objective function value of the position vector
- Electromagnetic force exerted on each particle is calculated and defined
  - Attraction forces applied to particle with higher charge
  - Repulsion forces applied to particle with lower charge



- The direction of the net force applied to a particle is used to guide the particle movement
- Moving distance is determined stochastically
- Electromagnetic force exertion and particle movement are simulated iteratively until termination condition is met
- The best solution so far is kept updated and serves as the final answer to the problem
- Local search operation can be optionally applied

## **Primary Operations in EM Optimization**

- Initialization
- Local Search (optional)
- Compute Electromagnetic Forces
- Move Particles to New Positions
- Update The Best Solution So Far



Procedure *Electromagnetism* - *like Heuristic A* lg *orithm* begin

```
Initialization (X, \mathbf{u}, \mathbf{l})
iterations \leftarrow 1
repeat while iterations < t
   LocalSearch(X, \mathbf{u}, \mathbf{l}, s)
   F \leftarrow ComputeElectromagneticForces(X)
   MoveParticlesToNewPositions(X,F)
   UpdateTheBestSolutionSoFar( )
   iterations \leftarrow iterations + 1
end repeat
```

#### Initialization

- Assign initial position for each particle
- Evaluate the objective function values of particles to assign the best solution so far

Procedure Initialization

```
begin
     for j = 1 to m do
           for i = 1 to n do
                x_i^j \leftarrow l_i + \sim U(0, 1) (u_i - l_i)
           end for
     end for
    f^* \leftarrow \min_{\forall \mathbf{x}^j} f(\mathbf{x}^j)\mathbf{x}^* \leftarrow \arg\min_{\forall \mathbf{x}^j} f(\mathbf{x}^j)
```



#### **Local Search**

- Is an optional procedure
  - Executed to find tune the solution
  - Performed for each particle or the iteration-best particle
- Execute a finite number of neighborhood search trials for a better solution
  - Perturb a small distance in one dimension as a neighbor solution
    - ◆ Specify a neighboring step size *p*
  - For each component (coordinate) of each particle, a fix number, s, of perturbations are tried
  - Once a better solution for a particle is found the local search for the particle is complete

```
Procedure LocalSearch (For all particles)
begin
  for j = 1 to m do
      \phi \leftarrow f(\mathbf{x}^j)
      for i = 1 to n do
           localSearchTrials \leftarrow 1
           repeat while localSearchTrials < s
             z \leftarrow x_i^j
             if \sim U(0,1) < 0.5 then x_i^j \leftarrow x_i^j + \sim U(0, 1) \rho \max_{k=1} (u_k - l_k)
             else x_i^j \leftarrow x_i^j - \sim U(0, 1) \rho \max_{k=1,...n} (u_k - l_k)
             end if
             if f(\mathbf{x}^j) < \phi then
                if f(\mathbf{x}^j) < f(\mathbf{x}^*) \equiv f^* then x^* \leftarrow \mathbf{x}^j
                 enf if
                 jump to the next j //A better solution is found for particle j
             else x_i^j \leftarrow z //Resume the original coordinate
             end if
              localSearchTrials \leftarrow localSearchTrials + 1
           end repeat
     end for
```

## **Compute Electromagnetic Forces**

- First assign electrical charge to each particle based on the objective function values
- Higher electrical charge is assigned to the particle with better objective value
  - The best objective function value so far or iteration best value is used for the performance comparison

$$q^{j} = \exp\left(-n\frac{f(\mathbf{x}^{j}) - f(\mathbf{x}^{*})}{\sum_{k=1}^{m} \left(f(\mathbf{x}^{k}) - f(\mathbf{x}^{*})\right)}\right) \quad q^{j} = \exp\left(-n\frac{f(\mathbf{x}^{j}) - f'}{\sum_{k=1}^{m} \left(f(\mathbf{x}^{k}) - f'\right)}\right), f' = \min_{k=1,\dots,m} f(\mathbf{x}^{k})$$

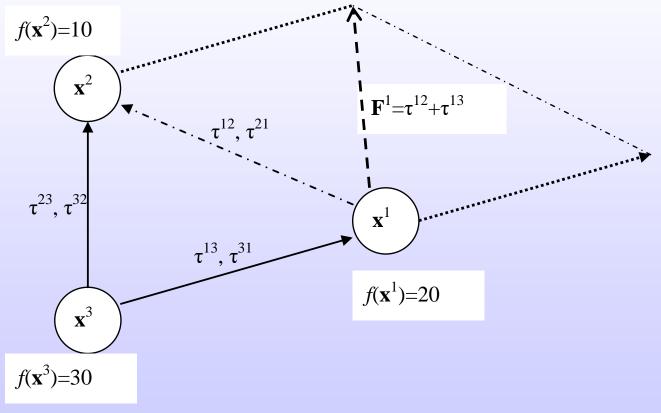
- n is used in the charge assignment equation
- An alternative is *m*



- Attraction force is applied from an lower charged particle to a higher one
- Repulsion force is applied from a higher charged particle to a lower one
- For each particle, exerted electromagnetism force is the sum of repulsion and attraction forces expelled from other particles
- Therefore, lower charged particle will move closer to higher one and higher one will escape from lower one

$$\mathbf{F}^{j} = \sum_{k=1, k \neq j}^{m} \tau^{jk}, \tau^{jk} = \begin{cases} \frac{q^{j}q^{k}(\mathbf{x}^{j} - \mathbf{x}^{k})}{\|\mathbf{x}^{j} - \mathbf{x}^{k}\| \|\mathbf{x}^{j} - \mathbf{x}^{k}\|}, & \text{if } f(\mathbf{x}^{j}) < f(\mathbf{x}^{k}) \\ \frac{q^{j}q^{k}(\mathbf{x}^{k} - \mathbf{x}^{j})}{\|\mathbf{x}^{j} - \mathbf{x}^{k}\| \|\mathbf{x}^{j} - \mathbf{x}^{k}\|}, & \text{otherwise} \end{cases}$$

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# Procedure ComputeElectromagneticForces begin

for j = 1 to m do

$$q^{j} = \exp\left(-n\frac{f(\mathbf{x}^{j}) - f(\mathbf{x}^{*})}{\sum_{k=1}^{m} \left(f(\mathbf{x}^{k}) - f(\mathbf{x}^{*})\right)}\right)$$

end for

for j = 1 to m do

$$\mathbf{F}^{j} = \mathbf{0}$$

for k = 1 to m and  $k \neq j$  and  $\mathbf{x}^j \neq \mathbf{x}^k$ do

if 
$$f(\mathbf{x}^j) < f(\mathbf{x}^k)$$
 then  $\tau^{jk} = \frac{q^j q^k (\mathbf{x}^j - \mathbf{x}^k)}{\|\mathbf{x}^j - \mathbf{x}^k\| \|\mathbf{x}^j - \mathbf{x}^k\|}$ 

else 
$$\tau^{jk} = \frac{q^j q^k (\mathbf{x}^k - \mathbf{x}^j)}{\|\mathbf{x}^j - \mathbf{x}^k\| \|\mathbf{x}^j - \mathbf{x}^k\|}$$

end if

$$\mathbf{F}^{j} \leftarrow \mathbf{F}^{j} + \tau^{jk}$$

end for

end for



- In physics the Coulomb's law states that the electromagnetism force is proportional to the inverse of distance square
- To reduce the computation cost, inverse of distance is used instead
- As noticed, the net force exerted on a particle is the sum of all unit forces expelled by other particles



#### **Move Particles to New Positions**

- Use the computed net force as the moving direction for each particle
- The moving distance is determine by a stochastic process
  - A moving factor is used to determine the moving range

$$x_i^j \leftarrow x_i^j + v \sim U(0,1) \cdot D_i^j \frac{F_i^j}{\|\mathbf{F}^j\|}, \forall i = 1, 2, ..., n; j = 1, 2, ..., m$$

$$D_{i}^{j} = \begin{cases} u_{i} - x_{i}^{j}, & if \ F_{i}^{j} \ge 0 \\ x_{i}^{j} - l_{i}, & otherwise \end{cases}$$

 $\gamma v$ : a moving factor 0 < v < 1

#### **Update The Best Solution So Far**

- After the particle movement, evaluate the objective function value for each particle
- If any position is better than the best position so far, update the best solution so far

$$\mathbf{x}^* \leftarrow \arg\min_{\forall \mathbf{x}^j} f(\mathbf{x}^j), if \min_{\forall \mathbf{x}^j} f(\mathbf{x}^j) < f(\mathbf{x}^*)$$



# **EM DEMO**





#### **Discussion**

- How to deal with general constrained continuous optimization problem?
  - Soft constraints
  - Hard constraint
- How to deal with complicated problems involving multiple electromagnetism fields
- Similar disadvantages in PSO, how to develop EM optimization for discrete optimization problems
  - Problem specific
  - Challenges:
    - How to define and calculate electromagnetic force
    - How to make particle move to a new position

## **Programming Assignment (optional)**

- Final project candidate
  - Develop a PSO and EM optimization system for general continuous problems (with constraints)
- Research challenge
  - For specific discrete optimization problems, develop pertinent EM operations



#### EMBOF, EMBOS-E, EMBOS-NET

- A programming framework of EM optimization method for .Net programming
- Developed in NTU GIIE CALB
- Practical applications
  - EMBOS-Excel
  - EMBOS-Net



#### **Final Discussion**

- Other meta heuristic optimization techniques
  - Derived from GA
    - Honey Bee
    - ◆Immune System
- Invent nature inspired heuristic optimization methods
  - For continuous or discrete optimization problems
    - Water flow like optimization
      - (Yang and Wang, 2008)
    - Others?
      - Amoeba Optimization ? (阿米巴)
      - Yours?



# Newly Developed Meta Heuristic Algorithms

- 師法動物習性或行為的啟發式演算法
  - 在近十年內蔚為風潮,上自飛禽下至走獸昆蟲甚至海 裡的魚蝦都有學者師法。包括:
  - 貓群優化法Cat Swarm Optimization (Saha, Ghoshal et al. 2013)
  - 磷蝦團演算法 Krill Herd algorithm (Gandomi and Alavi 2012)
  - 螢火蟲演算法 Firefly Algorithm (Wang, Guo et al. 2014)
  - 蝙蝠演算法 Bat Algorithm (Yang 2011)
  - 珊瑚優化演算法 Coral-reef Optimization Algorithm (Salcedo-Sanz, Del Ser et al. 2014)
  - 布穀鳥搜尋演算法 Cuckoo Search Algorithm (Nguyen, Vo et al. 2014)

# Newly Developed Meta Heuristic Algorithms (cont.)

- 灰狼優化 Grey Wolf Optimizer (Mirjalili, Mirjalili et al. 2014)
- 蛙跳演算法 Shuffled Frog Leaping Algorithm (Eusuff, Lansey et al. 2006)
- 海豚回音定位演算法 Dolphin Echolocation (Kaveh and Farhoudi 2013)
- 人工蜜蜂屯拓演算法 Artificial Bee Colony Algorithm (Mernik, Liu et al. 2015)
- 蜜蜂擇偶優化演算法 Honeybees Mating Optimization Algorithm (Haddad, Afshar et al. 2006)
- 蜜蜂結合優化演算法 Marriage in Honey Bees Optimization Algorithm (Dariane and Farahmandfar 2013)

# Newly Developed Meta Heuristic Algorithms (cont.)

- 部分啟發式演算法的創意來自自然界物理或生物演化定律的觀察
  - 人工免疫系統 Artificial Immune System (Ying and Lin 2014)
  - 重力搜尋演算法 Gravitational Search Algorithm (Shuaib, Kalavathi et al. 2015)
  - 化學反應優化法 Chemical Reaction Optimization (Szeto, Wang et al. 2014)
  - 協和搜尋演算法 Harmony Search Algorithm (Lee and Geem 2005)



# Newly Developed Meta Heuristic Algorithms (cont.)

- 荷電系統搜尋法 Charged System Search
- 雜草叢生優化法 Invasive Weed Optimization (Jolai, Tavakkoli-Moghaddam et al. 2014)
- 帝國競爭演算法 Imperialist Competitive Algorithm (Yousefikhoshbakht and Sedighpour 2013)
- 磁場荷電系統搜尋法 Magnetic Charged System Search (Kaveh, Share et al. 2013)
- 智慧水滴演算法Intelligent Water Drop Algorithm (Niu, Ong et al. 2013)
- 光跡優化法 Ray Optimization (Kaveh and Khayatazad 2012) 等。



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