Windowed Green Function method for layered-media scattering

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Abstract

This paper introduces a new Windowed Green Function (WGF) method for the numerical integral-equation solution of problems of electromagnetic scattering by obstacles in presence of dielectric or conducting half-planes. The WGF method, which is based on use of smooth windowing functions and integral kernels that can be expressed directly in terms of the free-space Green function, does not require evaluation of expensive Sommerfeld integrals. The proposed approach is fast, accurate, flexible and easy to implement. In particular, straightforward modifications of existing (accelerated or unaccelerated) solvers suffice to incorporate the WGF capability. The mathematical basis of the method is simple: the method relies on a certain integral equation posed on the union of the boundary of the obstacle and a small flat section of the interface between the penetrable media. Numerical experiments demonstrate that both the near- and far-field errors resulting from the proposed approach decrease faster than any negative power of the window size. In the examples considered in this paper the proposed method is up to thousands of times faster, for a given accuracy, than a corresponding method based on the layer-Green-function.

1 Introduction

The solution of problems of scattering by obstacles or defects in presence of planar layered dielectric or conducting media has typically required use of Sommerfeld integrals and associated layer Green functions—which automatically enforce the relevant transmission conditions on the unbounded flat surfaces and thus reduce the scattering problems to integral equations on the obstacles and/or defects. As is well known, however, the numerical evaluation of layer Green functions and their derivatives, which amounts to computation of certain challenging Fourier integrals [8, 20], are extremely expensive and give rise to a significant bottleneck in layer-media simulations (see e.g. [6] for details). This paper presents a novel integral-equation approach for problems involving layered media. The new approach, which is based on use of certain "windowing" functions and considerations associated with the method of stationary phase, does not require use of expensive Sommerfeld

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integrals. Numerical experiments demonstrate that both the near- and far-field errors resulting from the proposed approach decrease faster than any negative power of the window size.

A variety of methods have been provided for the solution of problems of scattering by obstacles in presence of layered media. Amongst the most effective such approaches we mention 1) Methods which evaluate Sommerfeld integrals on the basis of path-integration in the complex plane [17, 7, 6, 18] (such approaches require numerical evaluation of integrals of functions that oscillate, grow exponentially in a bounded section of the integration path and, depending on the relative position of the source and observation points to the interface between the two media, may decay slowly at infinity); 2) The complex images method reviewed in [1] (a discussion indicating certain instabilities and inefficiencies in this method is presented in [7, section 5.5]); and 3) The steepest descent method [9, 10] which, provided the steepest descent path is known, reduces the Sommerfeld integral to an integral of an exponentially decaying function (unfortunately, however, the determination of steepest descent paths for each observation point can be challenging and expensive). As is well known, in any case, all of these methods entail significant computational costs [6].

The approach proposed in this paper bears similarities with certain "finite-section" methods in the field of rough-surface scattering. These methods utilize approximations based on truncated portions of a given unbounded rough surface [14, 22, 19] and, in some cases, they incorporate a "taper" [22, 21, 15] to eliminate artificial reflections from the edges of the finite sections. In fact the smooth taper function utilized in [15] (Figure 2 in that reference) resembles the smooth windowing function we use (Figure 2 below and reference [3]). But as indicated in comments provided in section 2 below in regards to certain slow-rise windowing functions, essential differences exist between the finite-section approaches and the methods proposed in this paper. In particular, with exception of the slow-rise windowing function method [3, 16], none of the previous tapered rough surface algorithms has demonstrated high-order convergence as the width of the finite sections tend to infinity.

In section 4 the proposed WGF method is compared against the high-order integral equation method recently introduced in [18], which is based on the accurate and efficient evaluation of the Sommerfeld integrals. In the examples considered in that section the proposed method is up to thousands of times faster, for a given accuracy, than a corresponding method based on the layer-Green-function. A much larger improvement in the computational cost is expected for problems of electromagnetic scattering by defects and obstacles in multi-layer structures in two- and three-dimensional spaces, which will be addressed in future contributions.

The proposed methodology is presented in sections 2 and 3. A variety of numerical results presented in sections 2 and 4 demonstrate the accuracy and speed of the proposed approach.

2 Windowed Green Function Method

We consider two-dimensional TE and TM polarized dielectric transmission problems. As is well known, the z components $u=E_z$ and $u=H_z$ of the total electric and magnetic fields satisfy the Helmholtz equation $\Delta u + k_j^2 u = 0$ in Ω_j , j=1,2 (see Figure 1), where, letting $\omega>0$, $\varepsilon_j>0$, $\mu_0>0$, and $\sigma_j\geq 0$ denote the angular frequency, the electric permittivity, the magnetic permeability of vacuum, and the electrical conductivity, the wavenumber k_j is defined by $k_j^2 = \omega^2(\varepsilon_j + i\sigma_j/\omega)\mu_0$, j=1,2. In either case the total field is given by

$$u = \begin{cases} u_1 + u^{\text{inc}} & \text{in } \Omega_1, \\ u_2 & \text{in } \Omega_2, \end{cases}$$
 (1)

where denoting by $\alpha \in (-\pi, 0)$ the incidence angle measured from the horizontal (see Figure 1), $u^{\text{inc}}(\boldsymbol{x}) = \mathrm{e}^{ik_1(x_1\cos\alpha + x_2\sin\alpha)}$, u_1 and u_2 denote the incident plane-wave and the reflected and transmitted waves, respectively. As is known (see e.g. [11]), the scattered and transmitted fields u_1 and u_2 admit the representations

$$u_1 = \mathcal{D}_1[\varphi] - \mathcal{S}_1[\psi] \quad \text{in} \quad \Omega_1,$$
 (2a)

$$u_2 = -\mathcal{D}_2[\varphi] + \mathcal{S}_2[\psi] \quad \text{in} \quad \Omega_2,$$
 (2b)

in terms of the total field $\varphi = u|_{\Gamma}$ and its normal derivative $\psi = \frac{\partial u}{\partial n}$ on Γ , where letting $G_j(\boldsymbol{x}, \boldsymbol{y}) = iH_0^{(1)}(k_j|\boldsymbol{x}-\boldsymbol{y}|)/4$, j=1,2 denote the free-space Green function for the Helmholtz equation with wavenumber k_j , the single- and double-layer potentials in equation (2) are defined by

$$S_{j}[\eta](\boldsymbol{x}) = \int_{\Gamma} G_{j}(\boldsymbol{x}, \boldsymbol{y}) \eta(\boldsymbol{y}) \, \mathrm{d}s_{\boldsymbol{y}}, \quad \text{and}$$

$$D_{j}[\eta](\boldsymbol{x}) = \int_{\Gamma} \frac{\partial G_{j}}{\partial n_{\boldsymbol{y}}}(\boldsymbol{x}, \boldsymbol{y}) \eta(\boldsymbol{y}) \, \mathrm{d}s_{\boldsymbol{y}},$$
(3)

respectively. By evaluating the fields (2) and their normal derivatives on Γ and using the transmission conditions

$$u_2 - u_1 = u^{\text{inc}}, \quad \nu \frac{\partial u_2}{\partial n} - \frac{\partial u_1}{\partial n} = \frac{\partial u^{\text{inc}}}{\partial n} \text{ on } \Gamma,$$

(with $\nu = 1$ and $\nu = \varepsilon_1/\varepsilon_2$ in TE- and TM-polarizations respectively) we obtain the second-kind system of integral equations [12]

$$E\phi + T\phi = \phi^{\rm inc}$$
 on Γ (4)

for the surface currents ϕ , where

$$E = \begin{bmatrix} 1 & 0 \\ 0 & \frac{1+\nu}{2} \end{bmatrix}, \quad \phi = \begin{bmatrix} u|_{\Gamma} \\ \frac{\partial u}{\partial n}|_{\Gamma} \end{bmatrix}, \quad \phi^{\mathrm{inc}} = \begin{bmatrix} u^{\mathrm{inc}}|_{\Gamma} \\ \frac{\partial u^{\mathrm{inc}}}{\partial n}|_{\Gamma} \end{bmatrix},$$

and where

$$T = \begin{bmatrix} D_2 - D_1 & -\nu S_2 + S_1 \\ N_2 - N_1 & -\nu K_2 + K_1 \end{bmatrix}$$
 (5)

is defined in terms of the boundary integral operators defined by the expressions $S_j[\eta](\boldsymbol{x})$ and $D_j[\eta](\boldsymbol{x})$ as well as

$$N_j[\eta](\boldsymbol{x}) = \frac{\partial \mathcal{D}_j \eta}{\partial n}(\boldsymbol{x})$$
 and $K_j[\eta](\boldsymbol{x}) = \int_{\Gamma} \frac{\partial G_j}{\partial n_{\boldsymbol{x}}}(\boldsymbol{x}, \boldsymbol{y}) \eta(\boldsymbol{y}) \, \mathrm{d}s_{\boldsymbol{y}}$

for $x \in \Gamma$ and for j = 1, 2.

Instead of solving the problem on the entire infinite plane a locally windowed problem could be used in an attempt to obtain local currents over relevant portions of the geometry. To pursue this idea we introduce a smooth windowing function w_A (which is depicted in Figure 2) which is non-zero in an interval of length 2A, and which has a slow rise: $w_A(x_1) = f(x_1/A)$ for some fixed window function f. (Note that, with such a definition, w_A rises from zero to one in a region of length proportional to A; see [3, 16]. As demonstrated in those references, the slow rise of the window function is essential to ensure fast convergence of the approximation.) For notational simplicity, the subindex A will be dropped in what follows, and we will thus write $w(x_1)$ instead of $w_A(x_1)$. The parts of the boundary Γ where $w(x_1) \neq 0$ and $\widetilde{w}(x_1) = 1 - w(x_1) \neq 0$, further, will be

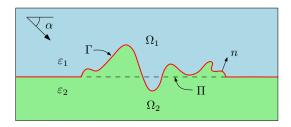


Figure 1: Description of the problem under consideration: scattering by a defect in a dielectric or conducting plane. Γ denotes the interface between the two media while Π denotes the interface between the upper- and lower-half planes.

denoted by Γ_A and $\widetilde{\Gamma}_A$, respectively. The width 2A > 0 of the support of the window function w is selected in such a way that $\widetilde{w}(x_1)$ vanishes on any corrugations that exist on the surface Γ , as well as on any additional obstacles that may exist above and/or below Γ . (For notational simplicity our derivations are presented for cases for which the corrugations on the surface Γ are the only departures from planarity, but, as demonstrated by Figure 12, our algorithms are also applicable in cases in which additional scatterers exist.)

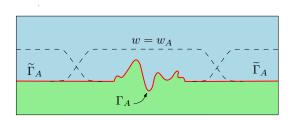


Figure 2: Window function $w = w_A$ and the windowed sections Γ_A and $\widetilde{\Gamma}_A$ of the unbounded curve Γ .

Utilizing the windowing function w and letting $W = w \cdot I$, where I is the 2×2 identity matrix, we consider the preliminary approximate equation

$$E\phi^* + TW\phi^* = \phi^{\text{inc}} \quad \text{on} \quad \Gamma_A \tag{6}$$

(where the new unknown ϕ^* is defined on Γ_A), and, in order to assess the errors inherent in this approximation, the form

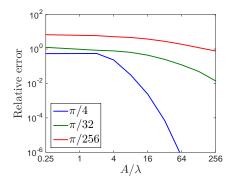
$$E\phi + TW\phi = \phi^{\rm inc} - T(I - W)\phi$$
 on Γ_A (7)

of the exact equation (4). Using integration-by-parts and employing the method of stationary-phase, it follows [5] that the term $T(I-W)\phi$ is super-algebraically small (i.e., smaller than $C_p(kA)^{-p}$ for any positive integer p as $kA \to \infty$, where C_p is a p-dependent constant) in the region $\{w=1\}$, and, thus, as shown in [5], that the solution ϕ^* of (6) is a highly accurate approximation of ϕ throughout the center region $\{w=1\}$ of the surface Γ_A provided A is large enough. However, it is easy to see that, to correctly take into account fields reflected from the planar portions of the surface, the needed window sizes may be very large—especially so for incidence angles approaching grazing.

To demonstrate this fact we use equation (6) to approximate the solution of the TE problem of scattering of a plane-wave by a semi-circular bump of radius a = 1 placed directly on top of a

planar dielectric surface. The problem was discretized using a graded mesh over the surface of the bump and on the windowed portion of the planar interface, on the basis of a direct generalization of the Nyström method presented in [13] with p = 3. For this example the wavenumbers k_1 and k_2 in the regions above and below the plane were set to 4π and 8π , respectively, and approximately 20 points per unit length of the surface of the bump and the surrounding were used.

As shown in Figure 3, the naive windowing approach embodied in (6) requires large regions of the planar interface to be discretized as the incidence angle decreases. For accurate calculations at even moderate angles, a large number of wavelengths must be present in the window region, well beyond the extent of the non-planar local geometry.



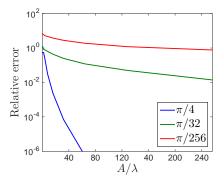
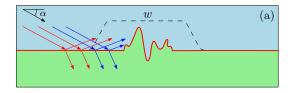


Figure 3: Errors in the integral densities resulting from numerical solution of (6) by means of a naive implementation of the WGF method for a semi-circular bump-shaped defect, for various window sizes and angles of incidence. Left: log-log scale. Right: semi-log scale. Clearly, the window size required by the naive method to produce a given accuracy increases dramatically as the angle of incidence approaches grazing.

In order to provide an insight into the source of the errors displayed in Figure 3 we present Figure 4. Figure 4(a) presents rays incident on the left planar region as well as their reflection and transmission. Clearly, in view of the incidence angle considered these reflected fields subsequently illuminate the defect. The blue rays, for example, represent the reflections that are correctly taken into account in the solution of equation (6) (since they lie within the windowed region), while the red arrows represent reflections that are neglected. Figure 4(b), on the other hand, represents reflections by the defect. The color-code in the left figure carries over to the right figure: the blue (resp. red) rays in Figure 4(b) represent the fields scattered by the defect which arise from the blue (resp. red) arrows in Figure 4(a). We remark that the scattering of the field represented by the red arrows is not taken into account by (6), which gives rise to the errors observed in Figure 3. We also note that the relatively fast convergence demonstrated by the blue curves in Figure 3 is explained by the fact that for near normal incidence ($\alpha \approx -\pi/2$) there is not much "red field" interacting with the defect. In contrast, for incidence near grazing ($\alpha \approx 0$), "red fields" from regions far away from the windowed area do interact with the defect. This explains the poor convergence properties demonstrated by the green and red curves in Figure 3: the fields neglected in the naive approach give rise to important contributions as α decreases.

To address this difficulty we consider again the exact integral equation (7) and we substitute the unknown density ϕ on the right-hand side of this equation by the corresponding (known) density ϕ^f associated with the problems of scattering and transmission of a plane-wave by a perfectly flat infinite plane. Since a superalgebraically small portion of the field reflected by the windowed region reflects back into the windowed region upon reflection from the plane outside the windowed region,



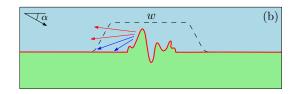


Figure 4: Physical elements underlying the WGF method.

we conclude that the error arising from the substitution of ϕ by ϕ^f results in superalgebraically small errors in equation (7) throughout the region $\{w=1\}$. We thus obtain the approximate equation

$$E\phi^w + TW\phi^w = \phi^{\text{inc}} - T(I - W)\phi^f \quad \text{on} \quad \Gamma_A, \tag{8}$$

whose solution ϕ^w is a superalgebraically close approximation of the exact solution ϕ throughout the region $\{w=1\}$. In order to evaluate the term $T(I-W)\phi^f$ we note that since $(I-W)\phi^f$ is zero everywhere Γ_A deviates from the planar boundary $\Pi = \{(x_1, x_2) \in \mathbb{R}^2 : x_2 = 0\}$ (depicted in Figure 1), we have

$$T(I-W)\phi^f = T_{\Pi}(I-W)\phi^f,$$

where letting the layer potentials \mathcal{S}_i^{Π} and \mathcal{D}_i^{Π} be given by

$$S_{j}^{\Pi}[\eta](\boldsymbol{x}) = \int_{\Pi} G_{j}(\boldsymbol{x}, \boldsymbol{y}) \eta(\boldsymbol{y}) \, \mathrm{d}s_{\boldsymbol{y}}, \quad \text{and}$$

$$\mathcal{D}_{j}^{\Pi}[\eta](\boldsymbol{x}) = \int_{\Pi} \frac{\partial G_{j}}{\partial n_{\boldsymbol{y}}}(\boldsymbol{x}, \boldsymbol{y}) \eta(\boldsymbol{y}) \, \mathrm{d}s_{\boldsymbol{y}},$$
(9)

the operator T_{Π} is defined as

$$T_{\Pi} = \left[\begin{array}{cc} D_2^{\Pi} - D_1^{\Pi} & -\nu S_2^{\Pi} + S_1^{\Pi} \\ N_2^{\Pi} - N_1^{\Pi} & -\nu K_2^{\Pi} + K_1^{\Pi} \end{array} \right]$$

in terms of the boundary integral operators defined by the expressions $S_j^{\Pi}[\eta](\boldsymbol{x})$ and $D_j^{\Pi}[\eta](\boldsymbol{x})$ as well as

$$N_j^{\Pi}[\eta](\boldsymbol{x}) = \frac{\partial \mathcal{D}_j^{\Pi} \eta}{\partial n}(\boldsymbol{x}) \Big|_{\Gamma} \quad \text{and} \quad K_j^{\Pi}[\eta](\boldsymbol{x}) = \int_{\Pi} \frac{\partial G_j}{\partial n_{\boldsymbol{x}}}(\boldsymbol{x}, \boldsymbol{y}) \eta(\boldsymbol{y}) \, \mathrm{d}s_{\boldsymbol{y}}$$

for $x \in \Gamma$ and for j = 1, 2. Thus equation (8) becomes

$$E\phi^w + TW\phi^w = \phi^{\text{inc}} - T_{\Pi}\phi^f + T_{\Pi}W\phi^f \quad \text{on} \quad \Gamma_A.$$
 (10)

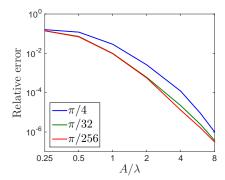
Clearly the expression $T_{\Pi}W\phi^f$ can be evaluated by means of integration on the bounded region $\Pi \cap \{(x_1, x_2) \in \mathbb{R}^2 : w(x_1) \neq 0\}$, and the expression $T_{\Pi}\phi^f$ can be computed in closed form:

$$T_{\Pi}\phi^{f} = \begin{cases} \left[u^{\text{inc}} - u^{f}, \frac{\partial (u^{\text{inc}} - u^{f})}{\partial n} \right]^{T} & \text{on } \Gamma \setminus \Pi, \\ \left[u^{\text{inc}} - u^{f}, \frac{\partial (u^{\text{inc}} - (1 + \nu)u^{f}/2)}{\partial n} \right]^{T} & \text{on } \Gamma \cap \Pi, \end{cases}$$

$$(11)$$

where u^f is the total field resulting from the solution of the problem of scattering by the flat dielectric plane with boundary Π [8, Chapter 2].

From the discussion above we see that, on the set $\{w = 1\}$, the (superalgebraically high) accuracy of the solution ϕ^w of (10) does not deteriorate as the incidence angle α tends to zero. As shown in section 3 below, further, the solution ϕ^w can be used to produce the total field u everywhere in space as well as the associated far field pattern. To conclude this section, in Figure 5 we demonstrate the fast and angle-independent convergence of ϕ^w to ϕ : clearly the value of A required to obtain an accurate approximation of the exact solution has been reduced substantially and the errors are uniformly small as the incidence angle decreases to zero.



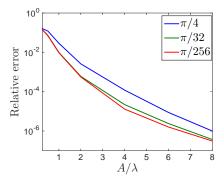


Figure 5: Errors in the integral densities ϕ^w on the surface of the defect resulting from numerical solution of (10), for a semi-circular bump-shaped defect, and for various window sizes and angles of incidence—including extremely shallow incidences. Left: log-log scale. Right: semi-log scale. Clearly, this version of the WGF method computes integral densities with super-algebraically high accuracy uniformly for all angles of incidence (cf. Figure 3).

3 Field evaluation

An analysis similar to the one presented in section 2 for the density $\phi^w = [\varphi^w, \psi^w]^T$ shows that substitution of $\phi = [\varphi, \psi]^T$ by $[w\varphi^w + (1-w)\varphi^f, w\psi^w + (1-w)\psi^f]^T$ in (2) produces the fields u_1 and u_2 with superalgebraically high accuracy in a neighborhood of the region $\{w=1\}$ in \mathbb{R}^2 , and, in particular, on a closed disc D such as the one depicted in Figure 7. After some manipulations similar to those presented in the derivation of (11) above, the resulting formula can be re-expressed into a formula for the total field in terms of surface potentials defined on both Γ and Π , namely

$$u(\boldsymbol{x}) = \mathcal{D}_{1} \left[w \varphi^{w} \right] (\boldsymbol{x}) - \mathcal{S}_{1} \left[w \psi^{w} \right] (\boldsymbol{x}) - \mathcal{D}_{1}^{\Pi} \left[w \varphi^{f} \right] (\boldsymbol{x}) + \mathcal{S}_{1}^{\Pi} \left[w \psi^{f} \right] (\boldsymbol{x}) + \begin{cases} u^{f}(\boldsymbol{x}), & \boldsymbol{x} \in \{x_{2} \geq 0\}, \\ 0, & \boldsymbol{x} \in \{x_{2} < 0\} \end{cases}$$

$$(12a)$$

for $\boldsymbol{x} \in \Omega_1$, and

$$u(\boldsymbol{x}) = -\mathcal{D}_{2} \left[w\varphi^{w}\right](\boldsymbol{x}) + \mathcal{S}_{2} \left[\nu w\psi^{w}\right](\boldsymbol{x}) + \mathcal{D}_{2}^{\Pi} \left[w\varphi^{f}\right](\boldsymbol{x}) - \mathcal{S}_{2}^{\Pi} \left[\nu w\psi^{f}\right](\boldsymbol{x}) + \begin{cases} 0, & \boldsymbol{x} \in \{x_{2} \geq 0\}, \\ u^{f}(\boldsymbol{x}), & \boldsymbol{x} \in \{x_{2} < 0\} \end{cases}$$

$$(12b)$$

for $\boldsymbol{x} \in \Omega_2$.

Figure 6 compares the total field obtained by means of the WGF method and the layer-Greenfunction method [18] for the solution of the problem of scattering of a plane-wave by a semi-circular bump of radius a=1 in TE-polarization for wavenumbers $k_1=10$ and $k_2=15$ for $\alpha=-\pi/2$ and $\alpha=-\pi/6$ incidences. The WGF solution, in particular, was obtained from the solution of the integral equation (10) followed by evaluation of field values on the basis of (12). Figures 6c and 6f, which display the absolute value of the difference of the total fields computed using the WGF method and the layer-Green-function method on a bounded portion of the strip $\{w=1\}$ demonstrate the accuracy of the computed solutions in the near field.

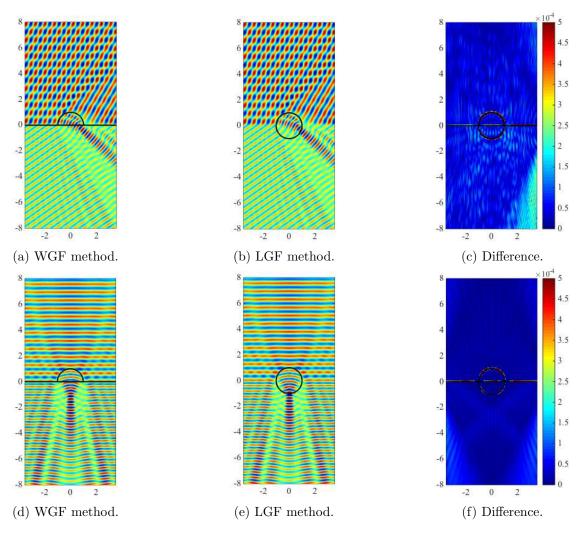


Figure 6: Real part of the total fields produced by the WGF method (first column) and the layer-Green-function method [18] (second column), and absolute value of the difference of the fields computed using the WGF method and layer-Green-function method (third column) for the problem of scattering of plane-wave by a semi-circular bump for $\alpha = -\pi/2$ (first row) and $\alpha = -\pi/6$ (second row) incidences. The width of the support of the selected window function is $2A = 16\lambda \approx 10.053$ in all these calculations. The black lines represent the domains of the respective integral equation formulations.

As may be expected, however, formulae (12) do not generally provide an accurate approximation

of either far fields or near fields outside a neighborhood of Γ_A . In order to tackle this difficulty we consider the boundary S of the disc D mentioned above and depicted in Figure 7: S encloses the portion of Γ that differs from the flat interface Π and, as indicated above, it lies within a fixed region within which superalgebraic convergence of the fields u_1 and u_2 takes place. Application of the Green identities, integrating over the region exterior to S and utilizing the layer Green function leads to the following integral representation of scattered field $u^s = u - u^f$:

$$u^{s}(\boldsymbol{x}) = \int_{S} \left\{ \frac{\partial G_{2}^{1}}{\partial n_{\boldsymbol{y}}} (\boldsymbol{x}, \boldsymbol{y}) u^{s}(\boldsymbol{y}) - G_{2}^{1}(\boldsymbol{x}, \boldsymbol{y}) \frac{\partial u^{s}}{\partial n} (\boldsymbol{y}) \right\} ds_{\boldsymbol{y}}$$
(13)

outside the region enclosed by S, where G_2^1 denotes the layer Green function for the Helmholtz equation with wavenumbers k_1 in $\{x_2 \geq 0\}$ and k_2 in $\{x_2 < 0\}$ that satisfies homogeneous transmission conditions on the flat interface Π (see Appendix A). Note that the scattered field u^s and its normal derivative on S can be computed directly utilizing (12) since by construction S lies inside the region where (12) provides an accurate approximation of the total field u.

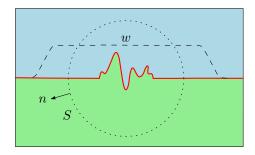


Figure 7: Surface S utilized in (13).

The far-field pattern $u_{\infty}(\hat{x})$, which is related to the scattered field by the asymptotic formula

$$u^s(\boldsymbol{x}) = \frac{e^{ik_1r}}{\sqrt{r}}u_{\infty}(\hat{\boldsymbol{x}}) + \mathcal{O}(r^{-3/2}), \quad r = |\boldsymbol{x}| \to \infty, \quad \hat{\boldsymbol{x}} = \frac{\boldsymbol{x}}{|\boldsymbol{x}|},$$

can be obtained from (13) in a straightforward manner by replacing G_2^1 by its asymptotic expansion as $|x| \to \infty$. The first order term of the asymptotic expansion of the Sommerfeld integrals Φ_1 and Φ_2 (equation 20) in a given direction $\hat{x} = (\cos \alpha, \sin \alpha)$, $0 < \alpha < \pi$ can be obtained by the method of steepest descent by taking into account the contribution of the saddle point [9] (branch point singularities and poles do not contribute to the first term of the asymptotic expansion of the two-layer Green function). Substitution of the result in equation (13) gives rise to the expression

$$u_{\infty}(\hat{\boldsymbol{x}}) = \int_{S} \left\{ \frac{\partial H}{\partial n_{\boldsymbol{y}}} (\hat{\boldsymbol{x}}, \boldsymbol{y}) u^{s}(\boldsymbol{y}) - H(\hat{\boldsymbol{x}}, \boldsymbol{y}) \frac{\partial u^{s}}{\partial n} (\boldsymbol{y}) \right\} ds_{\boldsymbol{y}}$$
(14)

for the far field $u_{\infty}(\hat{x})$, where

$$H(\hat{\boldsymbol{x}}, \boldsymbol{y}) = \frac{\nu(k_2^2 - k_1^2)}{\sqrt{2\pi k_1}(1+\nu)} \frac{e^{-ik_1\hat{\boldsymbol{x}}\cdot\boldsymbol{y}} e^{-2y_2\eta_1 + i\pi/4}}{(\eta_2 + \eta_1)(\eta_1 + \nu\eta_2)} + \frac{e^{-ik_1\hat{\boldsymbol{x}}\cdot\boldsymbol{y} + i\pi/4}}{\sqrt{8\pi k_1}} + \left(\frac{1-\nu}{1+\nu}\right) \frac{e^{-ik_1\hat{\boldsymbol{x}}\cdot\boldsymbol{y} + i\pi/4}}{\sqrt{8\pi k_1}}$$
(15a)

for $\mathbf{y} \in \{y_2 \ge 0\}$ and

$$H(\hat{x}, y) = \frac{\nu k_1}{\sqrt{2\pi k_1}} \frac{\sin(\alpha - \beta) e^{-ik_1 \hat{x} \cdot y} e^{y_2(\eta_2 - \eta_1) - i\pi/4}}{\eta_1 + \nu \eta_2}$$
(15b)

for $\mathbf{y} \in \{y_2 < 0\}$, where $\hat{\mathbf{x}} = \bar{\mathbf{x}}/|\mathbf{x}| = (\cos \alpha, -\sin \alpha)$, $\mathbf{y} = |\mathbf{y}|(\cos \beta, \sin \beta)$, $\eta_1 = \gamma_1(k_1 \cos(\alpha - \beta))$ and $\eta_2 = \gamma_2(k_1 \cos(\alpha - \beta))$ (see Appendix A for the definition of γ_1 and γ_2). Thus, unlike the layer Green function G_2^1 itself, the far field associated with G_2^1 can be computed inexpensively by means of the explicit expressions (15). Figure 8 provides a comparison of the far-field patterns computed using the layer-Green-function method and the WGF method proposed in this paper for the example problem considered above in the present section 3.

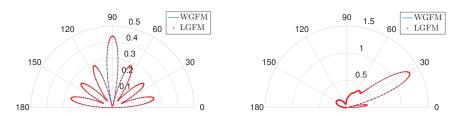


Figure 8: Far-field patterns obtained using the layer-Green-function method [18] (red dotted curve) and the WGF method (continuous blue line) for the solution of the problem of scattering considered in this section at incidences $\alpha = -\pi/2$ (left) and $\alpha = -\pi/6$ (right).

In view of this discussion, equations (12) and (13) can be used to accurately and efficiently evaluate near-fields and far-fields, respectively. These are typically the quantities of interest in scattering simulations involving layered media. The evaluation of the fields in an intermediate region, such as a domain outside the neighborhood of Γ_A where (12) yields an accurate approximation, can also be approximated efficiently on the basis of equation (13). Indeed, in such cases, for which source points y lie on S and observation points x are at a certain distance away from S, the Sommerfeld integrals (20) and (22) (which contain highly oscillatory and/or exponentially decaying integrands) can be obtained by means of asymptotic numerical methods [2, 4] based on localization around critical points [9, 18].

4 Numerical Experiments

This section illustrates the proposed methodology with a variety of numerical results concerning dielectric and conducting media, including relevant efficiency and accuracy studies.

In our first example we consider once again the configuration associated with Figure 5 (i.e. the problem of scattering by a semi-circular bump defect on a dielectric plane in TE-polarization). Here we compare the computing times required to create the systems of equations (which is the operation that dominates the computing time in all the examples considered) that stem from the discretization of the relevant integral equations by means of the WGF method (10) and the layer-Green-function method [18, Eq. 7]. Figure 9 displays the computing times for various wavenumbers k_1 and $k_2 = 2k_1$ for each method. The discretization density was held proportional to k_1 to properly resolve the oscillatory character of the integrands and the same discretization was used for both methods on the bump, allowing for a point by point comparison of the solutions. In all these examples the WGF method was optimized to produce a maximum error of approximately 5×10^{-5} in the computation of the density ϕ^w on the surface of the bump. Similarly, the key parameters in the implementation of layer-Green-function method (including the parameters associated to the numerical evaluation of the Sommerfeld integrals) were adjusted to yield the fastest possible solution within an error of 5×10^{-5} . Note that the last data points around $k_1 = 8\pi \approx 25.1$ in Figure 9 (which is the last data

point presented for the layer-Green-function method) shows that, for such frequencies the WGF is approximately three orders of magnitude faster than the layer-Green-function method [18].

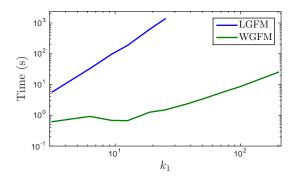


Figure 9: Computing times required by the WGF method (green line) and the layer-Green-function method [18] (blue line) to create the linear systems of equations resulting from the Nyström discretization of the relevant integral equations.

The problem of scattering by the city-like structure depicted in Figure 10 is considered next. Figure 10 also displays the window function utilized in this example, which has been amplified by a factor 8 for visualization purposes. In contrast with the results presented previously in this paper, the case of TM-polarization is considered for this test. In order to properly account for the singular behavior of the fields near corners, the necessary graded meshes were generated utilizing the value p=4 in the method described in [13]. Table 1 reports the computing times required to form the relevant system matrices for both the WGF method and the layer-Green-function method. Both solvers were optimized to produce a maximum error of 5×10^{-3} in the solutions of the integral equation, and the same computational grids were utilized to discretize the buildings for both methods.

Table 1 compares the computing times required by the WGF method and the layer-Green-function method for two values of k_2 . In particular we note that, not only is the new method much faster than the previous approach, but also that the speed-up factor grows: a speed up factor in the hundreds for the value $k_2 = 2\pi$ is doubled as k_2 is itself doubled to the value $k_2 = 4\pi$. Additionally, application of the layer-Green-function method in this context requires use of fictitious curves underneath each building [18] each one of which (curves) must itself be discretized, while the WGF method requires discretization of the ground between the buildings and in the region where the windowing takes place. In the present case the layer-Green-function method produced a system of 2384 unknowns while the WGF method produced a nearly identical sized system of 2406 unknowns. At higher frequencies, the WGF method requires fewer unknowns than the layer-Green-function method, since, as demonstrated in Table 2, at higher frequencies the width of the windowing function can be decreased while maintaining accuracy.

As an additional example we consider once again the city-like structure depicted in Figure 10 but assuming an absorbing media in the ground and buildings: here we thus take $k_1 = 2\pi$ and $k_2 = 4\pi(1+i/100)$. Figure 11 demonstrates the convergence of both the naive windowing algorithm (6) and the full WGF method (10). The advantages provided by the full WGF approach can be appreciated clearly in this figure: in the naive method convergence near grazing is extremely slow while for the full WGF method the convergence is actually faster near grazing than for non-grazing configurations. In particular, the WGF method requires no more than 5 wavelengths of ground for a full four digits of accuracy, independently of the incidence angle.

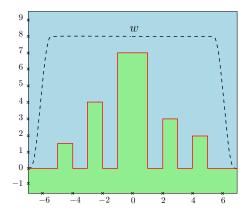


Figure 10: City-like geometry and windowing function used.

ſ	k_1	k_2	LGFM time	WGFM time	ratio
Ī	π	2π	588 s.	$3.07 \mathrm{s}.$	192
	π	4π	3579 s.	9.10 s.	393

Table 1: Computing times required by the layer-Green-function method and the WGF method to produce integral equation solutions with an accuracy better than 5×10^{-3} for the city-like geometry displayed in Figure 10.

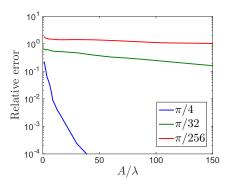
k_1	k_2	A
π	2π	6.5
2π	4π	3.5
4π	8π	1.75
8π	16π	1.1875

Table 2: Extent of the windowed region required by the WGF method (10) to maintain an accuracy of 5×10^{-5} in the approximation of the surface fields for the problem of scattering from a semi-circular bump of unit radius with various wavenumbers. The angle of incidence was taken to equal $\alpha = -\pi/8$.

For our last numerical example we consider an obstacle above the ground, but not connected to it, with a finite number of indentations under the ground level. Figure 12 displays the geometry under consideration, together with a selection of window function which yields an error of approximately 1% in the integral equation solution and corresponding near fields for a plane-wave illumination with incidence angle equal to $\alpha = -\pi/8$ from the horizontal under TE polarization. Once again, as demonstrated in Figure 13 exponential convergence is observed as A/λ grows.

Acknowledgments

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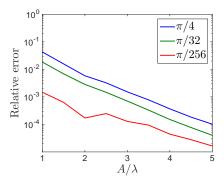


Figure 11: Errors in the integral densities resulting from numerical solution by means of the layer-Green-function method (6) (left) and the WGF method (10) (right) for the city-like structure depicted in Figure 10, for various window sizes and angles of incidence—including extremely shallow incidences. Clearly, the WGF method computes integral densities with super-algebraically high accuracy uniformly for all angles of incidence.

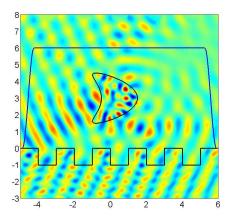


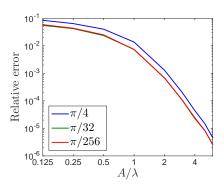
Figure 12: Scattering geometry containing a kite structure above a finite rectangular grating in an otherwise undisturbed planar ground. A windowing function large enough to produce an error smaller than 1% in the integral equation solution is shown along with the corresponding near fields; $k_1 = 2\pi$ and $k_2 = 4\pi$.

A Green function for a two-layer medium

Consider the Helmholtz equation in the regions $\Omega_1 = \{(x_1, x_2) \in \mathbb{R}^2, x_2 > 0\}$ and $\Omega_2 = \{(x_1, x_2) \in \mathbb{R}^2, x_2 < 0\}$ with respective wavenumbers k_1 and k_2 . The Green function of the problem satisfies:

$$\Delta_{x}G + k_{j}^{2}G = -\delta_{y} \quad \text{in} \quad \Omega_{j},
G|_{x_{2}=0^{+}} = G|_{x_{2}=0^{-}} \quad \text{on} \quad \{x_{2}=0\},
\frac{\partial G}{\partial x_{2}}|_{x_{2}=0^{+}} = \nu \frac{\partial G}{\partial x_{2}}|_{x_{2}=0^{-}} \quad \text{on} \quad \{x_{2}=0\},$$
(16)

and the Sommerfeld radiation condition at infinity, where δ_y denotes the Dirac delta distribution supported at the point y. As is known G can be computed explicitly in terms of Sommerfeld



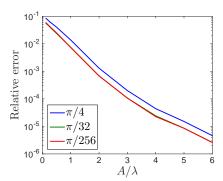


Figure 13: Errors in the integral densities resulting from numerical solution of (10) for the structure depicted in Figure 12 by means of the full WGF method, for various window sizes and angles of incidence—including extremely shallow incidences. Left: log-log scale. Right: semi-log scale. Once again we see that, the WGF method computes integral densities with super-algebraically high accuracy uniformly for all angles of incidence.

integrals. To obtain such explicit expressions, given a fixed point \mathbf{y} we define the functions $\varphi_j(\mathbf{x}) = G(\mathbf{x}, \mathbf{y}), \mathbf{x} \in \Omega_j$. Expressing φ_j as inverse Fourier transforms

$$\varphi_j(x_1, x_2) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \widehat{\varphi}_j(\xi, x_2) e^{i\xi(x_1 - y_1)} d\xi$$
(17)

and replacing (17) in (16) a system of ordinary differential equations for the unknown functions $\widehat{\varphi}_j$ is obtained which can be solved analytically. Two cases arise. For $\mathbf{y} \in \Omega_1$, the solution of the ODE system is given by

$$\widehat{\varphi}_{1}(\xi, x_{2}) = \frac{e^{-\gamma_{1}|x_{2}-y_{2}|}}{2\gamma_{1}} + \left(\frac{1-\nu}{1+\nu}\right) \frac{e^{-\gamma_{1}|x_{2}+y_{2}|}}{2\gamma_{1}} + \frac{\nu(k_{2}^{2}-k_{1}^{2})}{(\gamma_{1}+\nu\gamma_{2})(1+\nu)} \frac{e^{-\gamma_{1}(x_{2}+y_{2})}}{\gamma_{1}(\gamma_{1}+\gamma_{2})},$$

$$\widehat{\varphi}_{2}(\xi, x_{2}) = \frac{e^{-\gamma_{1}(y_{2}-x_{2})}}{(1+\nu)\gamma_{1}} + \left(\frac{e^{\gamma_{2}x_{2}-\gamma_{1}y_{2}}}{\gamma_{1}+\nu\gamma_{2}} - \frac{e^{-\gamma_{1}(y_{2}-x_{2})}}{(1+\nu)\gamma_{1}}\right),$$
(18)

where $\gamma_j = \sqrt{\xi^2 - k_j^2}$. The determination of physically admissible branches of the functions $\gamma_j(\xi) = \sqrt{\xi - k_j} \sqrt{\xi + k_j}$ require selection of branch cuts for each one of the two associated square root functions. The relevant branches are $-3\pi/2 \le \arg(\xi - k_j) < \pi/2$ for $\sqrt{\xi - k_j}$ and $-\pi/2 \le \arg(\xi + k_j) < 3\pi/2$ for $\sqrt{\xi + k_j}$. Taking the inverse Fourier transform (17) of $\widehat{\varphi}_j$ and using the identity

$$\int_{-\infty}^{\infty} \frac{e^{-\gamma_j |x_2 - y_2|}}{4\pi \gamma_j} e^{i\xi(x_1 - y_1)} d\xi = \frac{i}{4} H_0^{(1)}(k_j |\boldsymbol{y} - \boldsymbol{x}|),$$

we obtain

$$\varphi_{1}(\boldsymbol{x}) = \frac{i}{4} H_{0}^{(1)}(k_{1}|\boldsymbol{x} - \boldsymbol{y}|) + \frac{i}{4} \left(\frac{1-\nu}{1+\nu}\right) H_{0}^{(1)}(k_{1}|\overline{\boldsymbol{x}} - \boldsymbol{y}|)
+ \Phi_{1}(\boldsymbol{x}, \boldsymbol{y}),$$

$$\varphi_{2}(\boldsymbol{x}) = \frac{i}{2} \frac{1}{1+\nu} H_{0}^{(1)}(k_{1}|\boldsymbol{x} - \boldsymbol{y}|) + \Phi_{2}(\boldsymbol{x}, \boldsymbol{y}),$$
(19)

where the functions Φ_j are given by

$$\Phi_{1}(\boldsymbol{x}, \boldsymbol{y}) = \frac{\nu(k_{2}^{2} - k_{1}^{2})}{\pi(1 + \nu)} \int_{0}^{\infty} \frac{e^{-\gamma_{1}(x_{2} + y_{2})} \cos(\xi(x_{1} - y_{1}))}{\gamma_{1}(\gamma_{2} + \gamma_{1})(\gamma_{1} + \nu\gamma_{2})} d\xi,
\Phi_{2}(\boldsymbol{x}, \boldsymbol{y}) = \frac{1}{\pi} \int_{0}^{\infty} \left(\frac{e^{\gamma_{2}x_{2} - \gamma_{1}y_{2}}}{\gamma_{1} + \nu\gamma_{2}} - \frac{e^{\gamma_{1}(x_{2} - y_{2})}}{(1 + \nu)\gamma_{1}} \right) \cos(\xi(x_{1} - y_{1})) d\xi,$$
(20)

Similarly, the solution of the ODE system for $y \in \Omega_2$ is given by

$$\widehat{\varphi}_{1}(\xi, x_{2}) = \frac{\nu e^{-\gamma_{2}(x_{2} - y_{2})}}{(1 + \nu)\gamma_{2}} + \left(\frac{\nu e^{-\gamma_{1}x_{2} + \gamma_{2}y_{2}}}{\gamma_{1} + \nu\gamma_{2}} - \frac{\nu e^{-\gamma_{2}(x_{2} - y_{2})}}{(1 + \nu)\gamma_{2}}\right),$$

$$\widehat{\varphi}_{2}(\xi, x_{2}) = \frac{e^{-\gamma_{2}|x_{2} - y_{2}|}}{2\gamma_{2}} + \left(\frac{\nu - 1}{\nu + 1}\right)\frac{e^{-\gamma_{2}|x_{2} + y_{2}|}}{2\gamma_{2}} + \frac{\nu(k_{1}^{2} - k_{2}^{2}) e^{\gamma_{2}(x_{2} + y_{2})}}{(\gamma_{1} + \nu\gamma_{2})(1 + \nu)\gamma_{2}(\gamma_{2} + \gamma_{1})}.$$

Taking inverse Fourier transform (17) we now obtain

$$\varphi_{1}(\boldsymbol{x}) = \frac{i}{2} \frac{\nu}{1+\nu} H_{0}^{(1)}(k_{2}|\boldsymbol{x}-\boldsymbol{y}|) + \Psi_{1}(\boldsymbol{x},\boldsymbol{y}),$$

$$\varphi_{2}(\boldsymbol{x}) = \frac{i}{4} H_{0}^{(1)}(k_{2}|\boldsymbol{x}-\boldsymbol{y}|) + \frac{i}{4} \left(\frac{\nu-1}{\nu+1}\right) H_{0}^{(1)}(k_{2}|\overline{\boldsymbol{x}}-\boldsymbol{y}|)$$

$$+ \Psi_{2}(\boldsymbol{x},\boldsymbol{y}),$$
(21)

where the functions Ψ_i are given by

$$\Psi_{1}(\boldsymbol{x}, \boldsymbol{y}) = \frac{\nu}{\pi} \int_{0}^{\infty} \left(\frac{e^{\gamma_{2}y_{2} - \gamma_{1}x_{2}}}{\gamma_{1} + \nu \gamma_{2}} - \frac{e^{-\gamma_{2}(x_{2} - y_{2})}}{(1 + \nu)\gamma_{2}} \right) \cos(\xi(x_{1} - y_{1})) d\xi,
\Psi_{2}(\boldsymbol{x}, \boldsymbol{y}) = \frac{\nu(k_{1}^{2} - k_{2}^{2})}{\pi(1 + \nu)} \int_{0}^{\infty} \frac{e^{\gamma_{2}(x_{2} + y_{2})} \cos(\xi(x_{1} - y_{1}))}{\gamma_{2}(\gamma_{1} + \gamma_{2})(\gamma_{1} + \nu \gamma_{2})} d\xi.$$
(22)

The gradient of the Green function is evaluated from the expressions above by differentiation under the integral sign.

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