5.4 Bipartite matching polytope

G = (V, E) $M \le 2^E$: all matchings in G

Theorem 5.12

The bipartite matching polytope $P_{\mathcal{M}}$ is given by

$$P_{\mathcal{M}} = \{ x \in \mathbb{R}^{E}_{\geq 0} \colon x(\delta(v)) \le 1 \ \forall v \in V \} \ . \tag{5.7}$$

We prove the statement by showing (ii) and (iii) of the "recipe".

Proof of point (ii) — Pu contains correct set of integral points.

5.4.1 Integrality through TU-ness

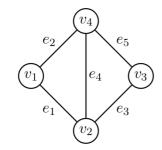
$$P = \{x \in \mathbb{R}^{E} : x(b(v)) \leq 1 \ \forall \ v \in V \} = \{x \in \mathbb{R}^{E} : Ax \leq b, x \geq 0 \}$$

-> We will show that A is TU and then invoke:

Theorem 5.8

Let $A \in \mathbb{Z}^{m \times n}$. Then,

 $A \text{ is TU} \quad \Leftrightarrow \quad P = \{x \in \mathbb{R}^n \colon Ax \leq b, x \geq 0\} \text{ is integral } \forall \, b \in \mathbb{Z}^m.$



$$A = \begin{pmatrix} v_1 & e_2 & e_3 & e_4 & e_5 \\ v_2 & 1 & 1 & 0 & 0 & 0 \\ v_2 & 1 & 0 & 1 & 1 & 0 \\ v_3 & 0 & 0 & 1 & 0 & 1 \\ v_4 & 0 & 1 & 0 & 1 & 1 \end{pmatrix}$$

Theorem 5.13

Let G=(V,E) be an undirected graph with vertex-edge incidence matrix A. Then,

G is bipartite $\Leftrightarrow A$ is TU.

5.4.3 Some implications coming from inequality description of Pu

Perfect bipartite matching polytope

Theorem 5.14

The perfect matching polytope of a bipartite graph G = (V, E) is given by

$$P = \left\{ x \in \mathbb{R}^E_{\geq 0} \colon x(\delta(v)) = 1 \; \forall v \in V \right\} \; .$$

Corollary 1.14

Let P be a polyhedron. Then a face of a face of P is itself a face of P.

Perfect matchings in bipartite d-regular graphs

Theorem 5.15

Let $d \in \mathbb{Z}_{\geq 1}$. Every d-regular bipartite graph admits a perfect matching.

5.5 Polyhedral description of short s-t paths

Consider directed graph G=(V,A) and $s,t\in V$, $s\neq t$.

Consider:

$$P = \left\{ x \in [0, 1]^A \mid x(\delta^+(v)) - x(\delta^-(v)) = \left\{ \begin{array}{ll} 1 & \text{if } v = s, \\ -1 & \text{if } v = t, \\ 0 & \text{if } v \in V \setminus \{s, t\}, \end{array} \right. \forall v \in V \right\}$$

$$P = \left\{ x \in [0, 1]^A \,\middle|\, x(\delta^+(v)) - x(\delta^-(v)) = \left\{ \begin{array}{ll} 1 & \text{if } v = s, \\ -1 & \text{if } v = t, \\ 0 & \text{if } v \in V \setminus \{s, t\}, \end{array} \right. \quad \forall v \in V \right\}$$

Theorem 5.16

The vertex-arc incidence matrix $D \in \{-1,0,1\}^{V \times A}$ of any directed (loopless) graph G = (V,A) is TU.

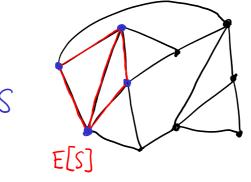
5.6.1 Spanning tree polytope

Theorem 5.17

The spanning tree polytope of an undirected loopless graph G=(V,E) is given by

$$P = \left\{ x \in \mathbb{R}^E_{\geq 0} \mid \begin{array}{c} x(E) = |V| - 1 \\ x(E[S]) \leq |S| - 1 & \forall S \subsetneq V, |S| \geq 2 \end{array} \right\} .$$

All edges with both endpoints in S.



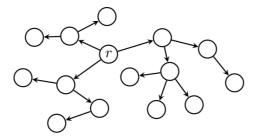
- > Exponentially many constraints.
- -> Problem sets: All constraints can be facet defining (depending on input graph G).

Definition 5.18: Arborescence, r-arborescence

Let G = (V, A) be a directed graph. An arborescence in G is an arc set $T \subseteq A$ such that

- (i) T is a spanning tree (when disregarding the arc directions), and
- (ii) there is one vertex r from which all arcs are directed away, i.e., every vertex $v \in V$ can be reached from r using a directed path in T.

The vertex r in condition (ii) is called the *root* of the arborescence, and T is called an r-arborescence.



Theorem 5.19

The arborescence polytope of a directed loopless graph G=(V,A) is given by

$$P = \left\{ x \in \mathbb{R}^A_{\geq 0} \middle| \begin{array}{c} x(A) = |V| - 1 \\ x(A[S]) \leq |S| - 1 \quad \forall S \subsetneq V, |S| \geq 2 \\ x(\delta^-(v)) \leq 1 \qquad \forall v \in V \end{array} \right\} ,$$

where $A[S] \subseteq A$ for $S \subseteq V$ denotes all arcs with both endpoints in S.

Theorem 5.20

The dominant of the r-arborescence polytope is given by

$$P = \left\{ x \in \mathbb{R}^A_{>0} \colon x(\delta^-(S)) \ge 1 \quad \forall S \subseteq V \setminus \{r\}, S \ne \emptyset \right\} .$$