

5 Polyhedral Approaches in Combinatorial Optimization

Combinatorial optimization problems can often be described by:

- (i) A finite set N , called ground set, $N = \{e_1, e_2, e_3\}$, $2^N = \{\emptyset, \{e_1\}, \{e_2\}, \{e_3\}, \{e_1, e_2\}, \{e_1, e_3\}, \{e_2, e_3\}, \{e_1, e_2, e_3\}\}$
- (ii) a family $\mathcal{F} \subseteq 2^N$ of feasible sets, also called solutions, and
- (iii) an objective function $w: N \rightarrow \mathbb{R}$ to maximize or minimize.
 weight -

corresponding
problem \rightarrow

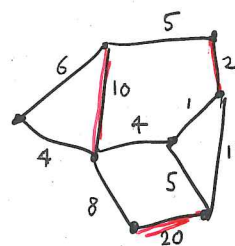
$$\max / \min \quad w(F) := \sum_{e \in F} w(e) \\ F \in \mathcal{F}$$

Examples

given is undirected graph $G=(V, E)$
with non-negative edge weights $w: E \rightarrow \mathbb{R}_{\geq 0}$

Maximum weight matchings:

- (i) Ground set: $N = E$
- (ii) Feasible sets: $\mathcal{F} = \{M \subseteq E : M \text{ is a matching}\}$
- (iii) Objective: maximize w



$G=(V, E)$

$w: E \rightarrow \mathbb{R}_{\geq 0}$

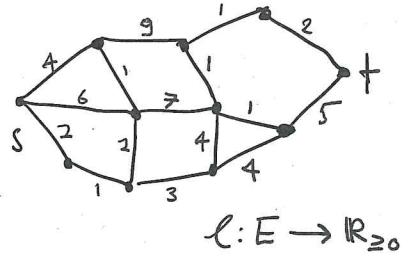
Well-known special cases:

- Maximum cardinality matching $\rightarrow w(e) = 1 \quad \forall e \in E$.
- Maximum cardinality/weight bipartite matchings $\rightarrow G$ is bipartite.

Shortest s-t path (in undir. graphs)

- (i) Ground set : $N = E$.
- (ii) Feasible sets : $\mathcal{F} = \{P \subseteq E : P \text{ is s-t path}\}$.
- (iii) Objective : minimize $w = \ell$.

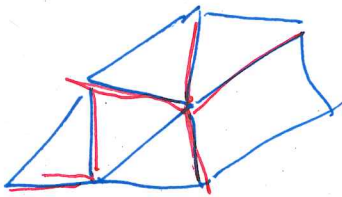
Given : • undir. graph $G=(V,E)$
 • vertices $s, t \in V$
 • non-neg. edge lengths
 $\ell: E \rightarrow \mathbb{R}_{\geq 0}$



Minimum weight spanning tree ?

- (i) Ground set : $N = E$.
- (ii) Feasible sets : $\mathcal{F} = \{F \subseteq E : F \text{ is a spanning tree in } G\}$.
- (iii) Objective : minimize w .

Given : • undir. graph $G=(V,E)$
 • edge weights $w: E \rightarrow \mathbb{R}_{\geq 0}$



5.1 Polyhedral descriptions of combinatorial optimization problems

Let N be a finite (ground) set.

Definition

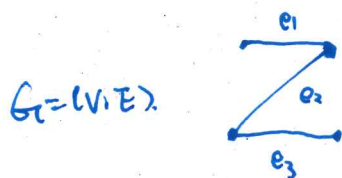
For $U \subseteq N$, we denote by x^U its characteristic vector (also called incidence vector):

$$x^U(e) = \begin{cases} 1 & \text{if } e \in U \\ 0 & \text{if } e \in N \setminus U \end{cases}$$

Let $\mathcal{F} \subseteq 2^N$ be all feasible sets to a combinatorial optimization problem.

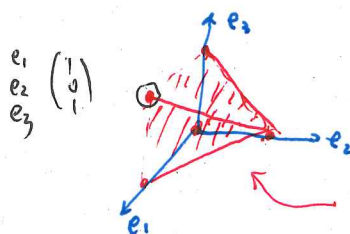
The (combinatorial) polytope that corresponds to \mathcal{F} is the polytope $P_{\mathcal{F}} \subseteq [0, 1]^N$ whose vertices are precisely $\{x^F : F \in \mathcal{F}\}$, i.e.,

$$P_{\mathcal{F}} = \text{conv}(\{x^F : F \in \mathcal{F}\}).$$



$$\mathcal{F} = \{M \subseteq E : M \text{ is a matching}\}$$

$$M = \{e_1\}, \{e_2\}, \{e_3\}, \{e_1, e_3\}.$$



• All matchings

matching polytope $P_{\mathcal{F}}$

$$\max c \cdot x \quad x \in P_{\mathcal{F}}$$

The combinatorial polytope allows for casting a combinatorial optimization problem into a linear program (and can be used for much more):

$$\boxed{\begin{array}{l} \max/\min \quad w(F) \\ F \in \mathcal{F} \end{array}} \quad \rightsquigarrow \quad \boxed{\begin{array}{l} \max/\min \quad w^T x \\ x \in P_{\mathcal{F}} \end{array}}$$

Optimal vertex solution to this LP
is characteristic vector of optimal solution
of combinatorial optimization problem.

Key challenge : Find explicit inequality description of $P_{\mathcal{F}}$.

$$\rightarrow P_{\mathcal{F}} = \{x \in \mathbb{R}^N : Ax \leq b\}$$

Some benefits of getting an inequality description: (let $n := |N|$)

- Often, $\# \text{ facets of } P_F = O(\text{poly } n)$.
 $\# \text{ vertices of } P_F = 2^{\Omega(n)}$.
- If we can solve LPs over P_F , then we can optimize any linear objective.
- Even when P_F has exponentially many facets, one can often get a description of them and even solve LPs over P_F .
 \uparrow for example, by using the Ellipsoid Method
- Being able to solve LPs over P_F often allows for solving related problems, for example by adding some extra constraints.

• The LP dual of $\max\{w^T x : x \in P_F\}$ can often be interpreted combinatorially. Possible implications:

- Natural optimality certificates through strong duality.

- Fast algorithms based on dual such as primal-dual methods.

- Elegant polyhedral proof techniques.

⋮

5.2 Meta-recipe for finding inequality-descriptions

① Determine candidate description $P = \{x \in \mathbb{R}^N : Ax \leq b\} \subseteq [0,1]^N$.

this
shows
 $P = P_F$

② Prove $P \cap \{0,1\}^N = \{x^F : F \in \mathcal{F}\}$.

③ Prove that P is integral.

\uparrow i.e., $\text{vertices}(P) \subseteq \mathbb{Z}^N$, which, because $P \subseteq [0,1]^N$,
is same as $\text{vertices}(P) \subseteq \{0,1\}^N$

P integral and $P \subseteq [0,1]^N$

(i)

$\Rightarrow \text{vertices}(P) \subseteq P \cap \{0,1\}^N$

(ii) moreover if $v \in P \cap \{0,1\}^N \Rightarrow v \in \text{vertices}(P)$.

(i) & (ii) $\Rightarrow \text{vertices}(P) = P \cap \{0,1\}^N \stackrel{(2)}{=} \{x^F : F \in \mathcal{F}\}$

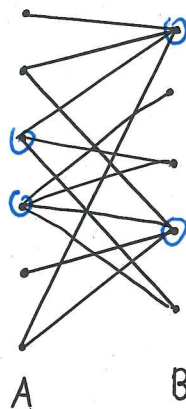
$\Rightarrow P = \text{conv}(\text{vertices}(P)) = \text{conv}(\{x^F : F \in \mathcal{F}\}) =: P_F$

$\hookrightarrow v \in \text{vertices}([0,1]^N)$.

5.2.1 Example : bipartite vertex cover

Definition 5.1: Vertex cover

Let $G = (V, E)$ be an undirected graph. A vertex cover of G is a subset $S \subseteq V$ such that for every edge $e \in E$, at least one of its endpoints is in S .



$$G = (V, E)$$

$$V = A \cup B$$

We follow the recipe.

1. ~~Find~~ Candidate description.

Theorem 5.2

The vertex cover polytope of a bipartite graph $G = (V, E)$ can be described by

$$P = \{x \in [0, 1]^V : x(u) + x(v) \geq 1 \forall \{u, v\} \in E\}.$$

1: pick the vertex
0: Not pick the vertex

Proof

②. Let $S \subseteq V$, S is a vertex cover $\Leftrightarrow \{u, v\} \cap S \neq \emptyset \quad \forall \{u, v\} \in E$

at least
one vertex
belongs to S

$$\Leftrightarrow x^S(u) + x^S(v) = 1 \quad \forall \{u, v\} \in E$$

$$\Leftrightarrow x^S \in P \quad \begin{cases} 1 & v \in S \\ 0 & v \in V \setminus S \end{cases}$$

$$P \cap \{0, 1\}^V = X^S$$

③. By sake of contradiction. assume has fraction vertex $y \in P \setminus \{0, 1\}^V$

let $V = A \cup B$ be bipartition of the bipartite graph

$$W_A := \{u \in A : y(u) \in (0, 1)\}$$

$$W_B := \{u \in B : y(u) \in (0, 1)\}$$

y is not integral $\Rightarrow W_A \cup W_B \neq \emptyset$

For $\delta \in \mathbb{R}$.

$$y^\delta := y + \delta(x^{W_A} - x^{W_B})$$

a vector $\begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix}$

$$y^\delta := y + \delta(x^{W_A} - x^{W_B})$$

Non-all zero vector

$$P := \{x \in [0, 1]^V : x(u) + x(v) = 1 \quad \forall \{u, v\} \in E\}$$

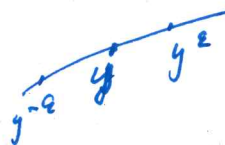
① vertex
② value of vertex $[0, 1]$

let $\epsilon := \min \{ \min \{ y(u), 1 - y(u) \} : u \in W_A \cup W_B \} > 0$

$$y^\epsilon, y^{-\epsilon} \in P$$

$$y = \frac{1}{2}(y^\epsilon + y^{-\epsilon})$$

Not a extremepoint



to show $y^\epsilon \in P$?

$$y^\epsilon \in [0, 1]^V$$

$$y^\epsilon(u) + y^\epsilon(v) = y(u) + y(v) \geq 1$$

