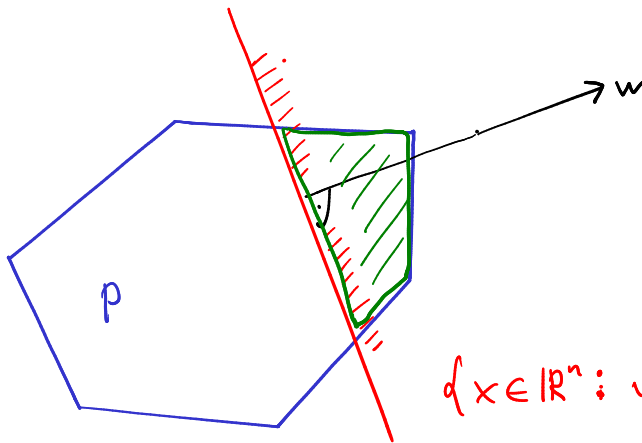


6.4 Ellipsoid Method for finding point in full-dimensional $\{0,1\}$ -polytope

We start with simpler question (checking feasibility):

Given a separation oracle for a polytope $P \subseteq \mathbb{R}^n$ with $\dim(P)=n$,
find a point $x \in P$.

Checking feasibility is closely related to optimization



$$\max_{x \in P} w^T x$$

$$H_v \cap P$$

$$\{x \in \mathbb{R}^n : w^T x \geq v\} = H_v$$

Basics on ellipsoids

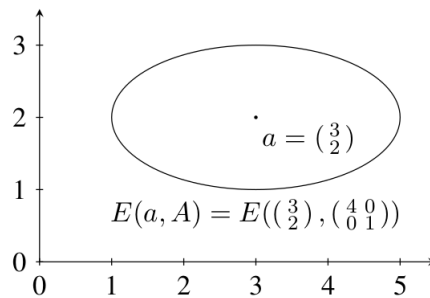
Definition 6.3: Ellipsoid

An ellipsoid in \mathbb{R}^n is a set

$$E(a, A) := \{x \in \mathbb{R}^n : (x - a)^\top A^{-1} (x - a) \leq 1\},$$

where $a \in \mathbb{R}^n$ and $A \in \mathbb{R}^{n \times n}$ is a positive definite matrix. The point a is called the center of the ellipsoid $E(a, A)$.

this implies that A is symmetric



$$x^\top A x > 0 \quad \forall x \in \mathbb{R}^n \setminus \{0\}$$

Equivalently, an ellipsoid is the image of the unit ball under an affine bijection:

$A \in \mathbb{R}^{n \times n}$ positive definite $\iff A = Q Q^\top$ for some full-rank matrix $Q \in \mathbb{R}^{n \times n}$.

$$E(a, A) = \{x \in \mathbb{R}^n : (x - a)^\top A^{-1} (x - a) \leq 1\}$$

$$= \{x \in \mathbb{R}^n : (x - a)^\top (Q^{-1})^\top Q^{-1} (x - a) \leq 1\}$$

$$y = Q^{-1}(x - a) \Rightarrow \{x \in \mathbb{R}^n : \|Q^{-1}(x - a)\|_2^2 \leq 1\}$$

$$x = Q y + a \Rightarrow \{Q y + a : y \in \mathbb{R}^n, \|y\|_2^2 \leq 1\}$$

$$= \{Q y + a : y \in \mathbb{R}^n, \|y\|_2 \leq 1\}$$

$$\begin{aligned} A^{-1} &= (Q Q^\top)^{-1} \\ &= (Q^\top)^{-1} Q^{-1} \end{aligned}$$

6.4.1 (High-level) description of Ellipsoid Method

Algorithm 8: Ellipsoid Method

Input : Separation oracle for a polytope $P \subseteq \mathbb{R}^n$ with $\dim(P) = n$, and an ellipsoid $E_0 = E(a_0, A_0)$ with $P \subseteq E_0$.

Output: A point $y \in P$.

$i = 0$.

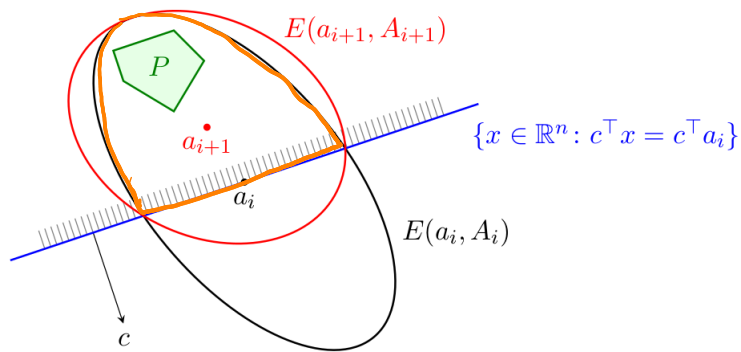
while $a_i \notin P$ (checked with separation oracle) **do**

 Get $c \in \mathbb{R}^n$ such that $P \subseteq \{x \in \mathbb{R}^n : c^\top x < c^\top a_i\}$, using separation oracle.

 Find min. volume ellipsoid $E_{i+1} = E(a_{i+1}, A_{i+1})$ containing $E_i \cap \{x \in \mathbb{R}^n : c^\top x \leq c^\top a_i\}$.

$i = i + 1$.

return a_i .



Two key questions :

- (How quickly) does the Ellipsoid Method terminate ?
- How to compute $E_{i+1} = E(a_{i+1}, A_{i+1})$?

6.4.2 Getting a bound on the number of iterations

Lemma 6.4

$$\frac{\text{vol}(E_{i+1})}{\text{vol}(E_i)} < e^{-\frac{1}{2(n+1)}}.$$

Before proving Lemma 6.4, we show that it implies following bound on number of iterations.

Lemma 6.5

The Ellipsoid Method will stop after at most $2(n+1) \ln \left(\frac{\text{vol}(E_0)}{\text{vol}(P)} \right)$ iterations.

Proof

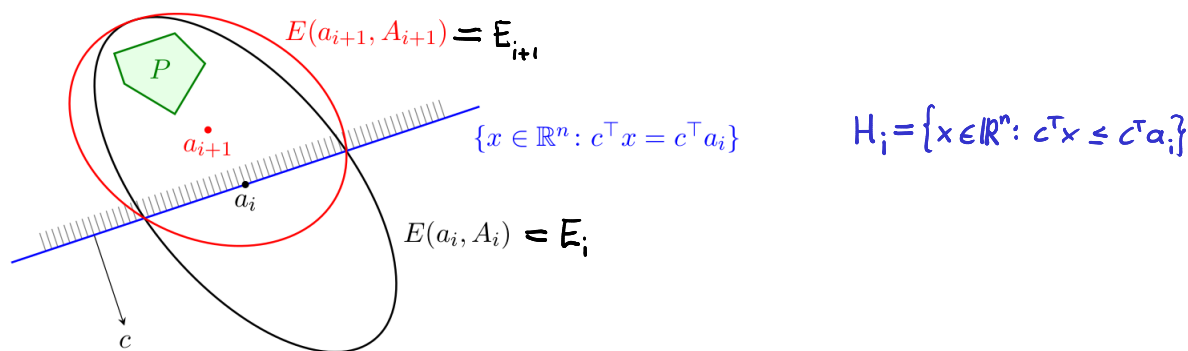
Let $L \in \mathbb{Z}_{\geq 0}$ be last iteration of Ellipsoid Method, i.e., value of i when it terminates.

$$P \subseteq E_L \quad \Rightarrow \quad \text{vol}(P) \leq \text{vol}(E_L) \stackrel{\text{Lemma 6.4}}{\leq} \text{vol}(E_0) \cdot e^{-\frac{L}{2(n+1)}}$$

$$\Rightarrow L \leq 2(n+1) \ln \left(\frac{\text{vol}(E_0)}{\text{vol}(P)} \right).$$

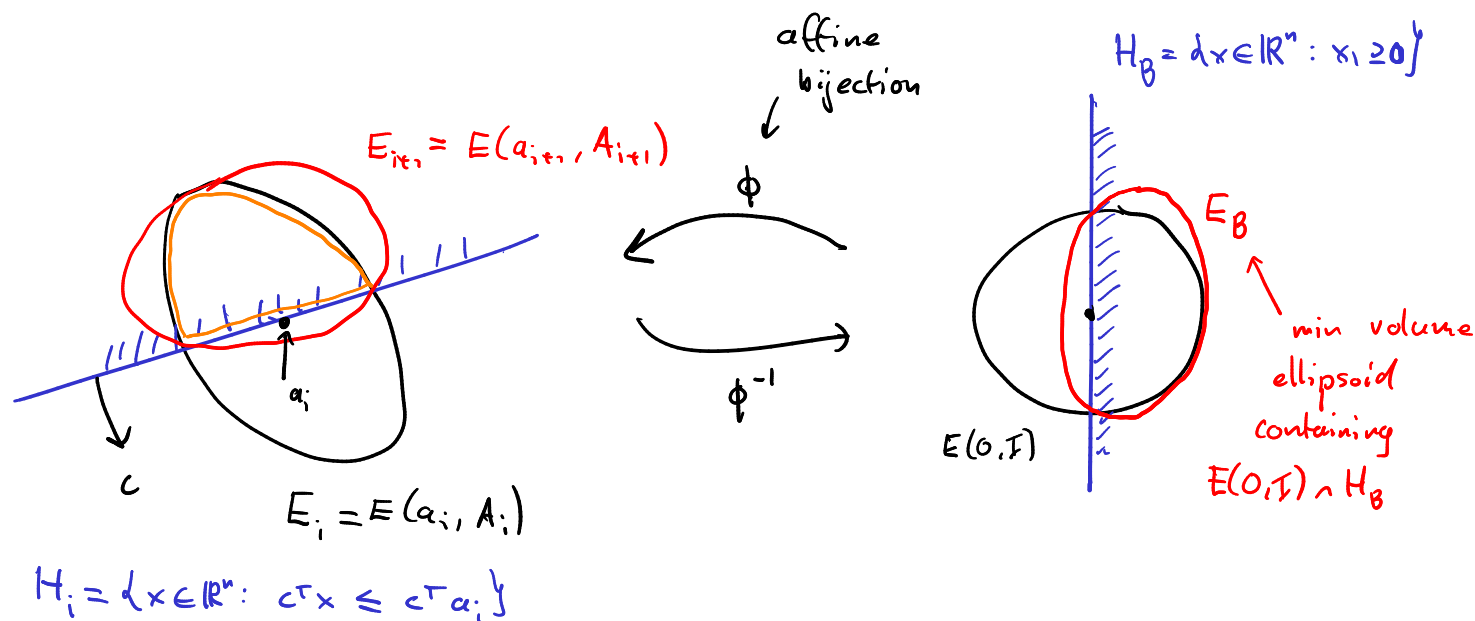
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Proof of Lemma 6.4 and explicit description for E_{i+1}



What is ratio between $\text{vol}(E_{i+1})$ and $\text{vol}(E_i)$?

This question can be reduced to unit ball case



\exists affine bijection $\phi : \mathbb{R}^n \rightarrow \mathbb{R}^n$ s.t.

- (i) $\phi(E(0, I)) = E_i$
- (ii) $\phi(H_B) = H_i$

Claim

$\phi(E_B)$ is minimum volume ellipsoid containing $E_i \cap H_i$.

Proof

$$E(0, I) \cap H_B \subseteq E_B \Rightarrow \phi(E_B) \supseteq \phi(E(0, I) \cap H_B) = \underbrace{\phi(E(0, I))}_{= E_i} \cap \underbrace{\phi(H_B)}_{= H_i}$$

ϕ is injection

Analogous reasoning implies

$$\phi^{-1}(E_{i+1}) \supseteq E(0, I) \cap H_B$$

↑
min volume ellipsoid
containing $E_i \cap H_i$.

E_B is smallest volume
ellipsoid containing $E(0, I) \cap H_B$

$$\text{vol}(E_B) \leq \text{vol}(\phi^{-1}(E_{i+1}))$$

An affine transformation scales
all volumes by same
non-negative factor.

$$\text{vol}(\phi(E_B)) \leq \text{vol}(E_{i+1})$$

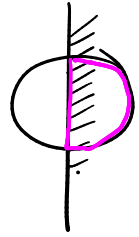
claim

Lemma 6.7

Let $H_B = \{x \in \mathbb{R}^n : x_1 \geq 0\}$. Then the ellipsoid

$$E_B = \left\{ x \in \mathbb{R}^n \mid \left(\frac{n+1}{n} \right)^2 \left(x_1 - \frac{1}{n+1} \right)^2 + \frac{n^2-1}{n^2} \sum_{j=2}^n x_j^2 \leq 1 \right\} \quad (6.7)$$

contains $E(0, I) \cap H_B$.



Proof

Let $x \in E(0, I) \cap H_B$.

$$\left(\frac{n+1}{n} \right)^2 \left(x_1 - \frac{1}{n+1} \right)^2 + \frac{n^2-1}{n^2} \sum_{j=2}^n x_j^2$$

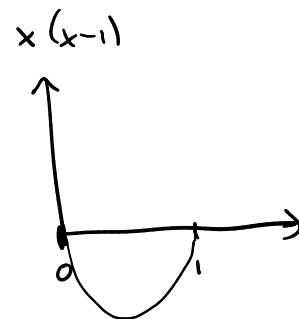
$$= \frac{1}{n^2} x_1^2 \left((n+1)^2 - n^2 + 1 \right) - \frac{2}{n^2} x_1 (n+1) + \frac{1}{n^2} + \underbrace{\frac{n^2-1}{n^2} \sum_{j=2}^n x_j^2}_{\leq 1} \quad \begin{matrix} \uparrow \\ x \in E(0, I) \end{matrix}$$

≤ 1

$$\leq \frac{1}{n^2} x_1^2 (2n+2) - \frac{2}{n^2} x_1 (n+1) + 1$$

$$= \frac{2}{n^2} (n+1) \underbrace{x_1 (x_1 - 1)}_{\leq 0} + 1 \leq 1$$

$$\begin{matrix} \leq 0 \\ \uparrow \\ 0 \leq x_1 \leq 1 \\ \uparrow \quad \quad \quad \uparrow \\ x \in H_B \quad \quad x \in E(0, I) \end{matrix}$$



#

E_B is actually min volume ellipsoid containing $E(0, I) \cap H_B$.
(see problem sets)

Proof of Lemma 6.4

Lemma 6.4

$$\frac{\text{vol}(E_{i+1})}{\text{vol}(E_i)} < e^{-\frac{1}{2(n+1)}}.$$

By above results: $\frac{\text{vol}(E_{i+1})}{\text{vol}(E_i)} \leq \frac{\text{vol}(E_B)}{\text{vol}(E(0, I))}$, where

$$E_B = \left\{ x \in \mathbb{R}^n : \left(\frac{n+1}{n}\right)^2 \left(x_1 - \frac{1}{n+1}\right)^2 + \frac{n^2-1}{n^2} \sum_{j=2}^n x_j^2 \leq 1 \right\}$$

(defined as in Lemma 6.7)

$$E_B = E(a, A) := \{x \in \mathbb{R}^n : (x-a)^T A^{-1} (x-a) \leq 1\}$$

$$\psi(x) = Qx + a \quad \text{where } Q \in \mathbb{R}^{n \times n} \text{ s.t.}$$

$$A = QQ^T$$

$$\Rightarrow E(a, A) = \psi(E(0, I))$$

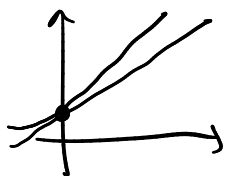
$$a = \left(\frac{1}{n+1}, 0, 0, \dots, 0 \right)$$

$$A^{-1} = \begin{pmatrix} \left(\frac{n+1}{n}\right)^2 & & 0 \\ & \frac{n^2-1}{n^2} & \\ 0 & & \ddots \\ & & & \frac{n^2-1}{n^2} \end{pmatrix} \Rightarrow A = \begin{pmatrix} \left(\frac{n}{n+1}\right)^2 & & 0 \\ & \frac{n^2}{n^2-1} & \\ 0 & & \ddots \\ & & & \frac{n^2}{n^2-1} \end{pmatrix}$$

$$\Rightarrow \frac{\text{vol}(E_B)}{\text{vol}(E(0, I))} = \frac{\text{vol}(\psi(E(0, I)))}{\text{vol}(E(0, I))} = |\det Q|$$

$$= \sqrt{\det A} = \frac{n}{n+1} \cdot \left(\frac{n^2}{n^2-1}\right)^{\frac{n-1}{2}}$$

\nearrow
 $A = QQ^T$



$e^x > 1 + x$
 $x \in \mathbb{R} \setminus \{0\}$

$$\begin{aligned}
 &= \left(1 - \frac{1}{n+1}\right) \cdot \left(1 + \frac{1}{n^2-1}\right)^{\frac{n-1}{2}} \\
 &< e^{-\frac{1}{n+1}} \cdot e^{\frac{n-1}{2(n^2-1)}} \\
 &= e^{-\frac{1}{n+1}} \cdot e^{\frac{1}{2(n+1)}} = e^{-\frac{1}{2(n+1)}}
 \end{aligned}$$

#

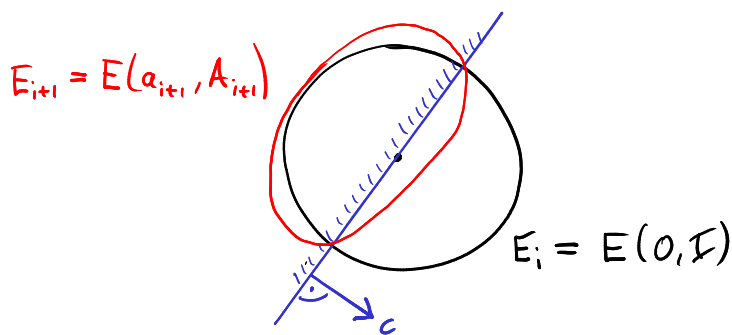
6.4.3 From the unit ball to the general case

We obtained explicit description of E_{i+1} if

- $E_i = E(0, \mathcal{I})$, and
- $H_i = \{x \in \mathbb{R}^n : x_i \geq 0\}$

From this we obtain explicit description of E_{i+1} for the general case by transforming description of this special case through an appropriate affine bijection.

General half-space cutting $E(0, \mathcal{I})$



$$E_i = E(0, \mathcal{I})$$

$$H_i = \{x \in \mathbb{R}^n : c^T x \leq 0\},$$

with $\|c\|_2 = 1$

→ see problem sets

$$E_{i+1} = E(a_{i+1}, A_{i+1}), \text{ where}$$

$$a_{i+1} = -\frac{1}{n+1} c$$

$$A_{i+1} = \frac{n^2}{n^2-1} \left(\mathcal{I} - \frac{2}{n+1} c c^T \right)$$

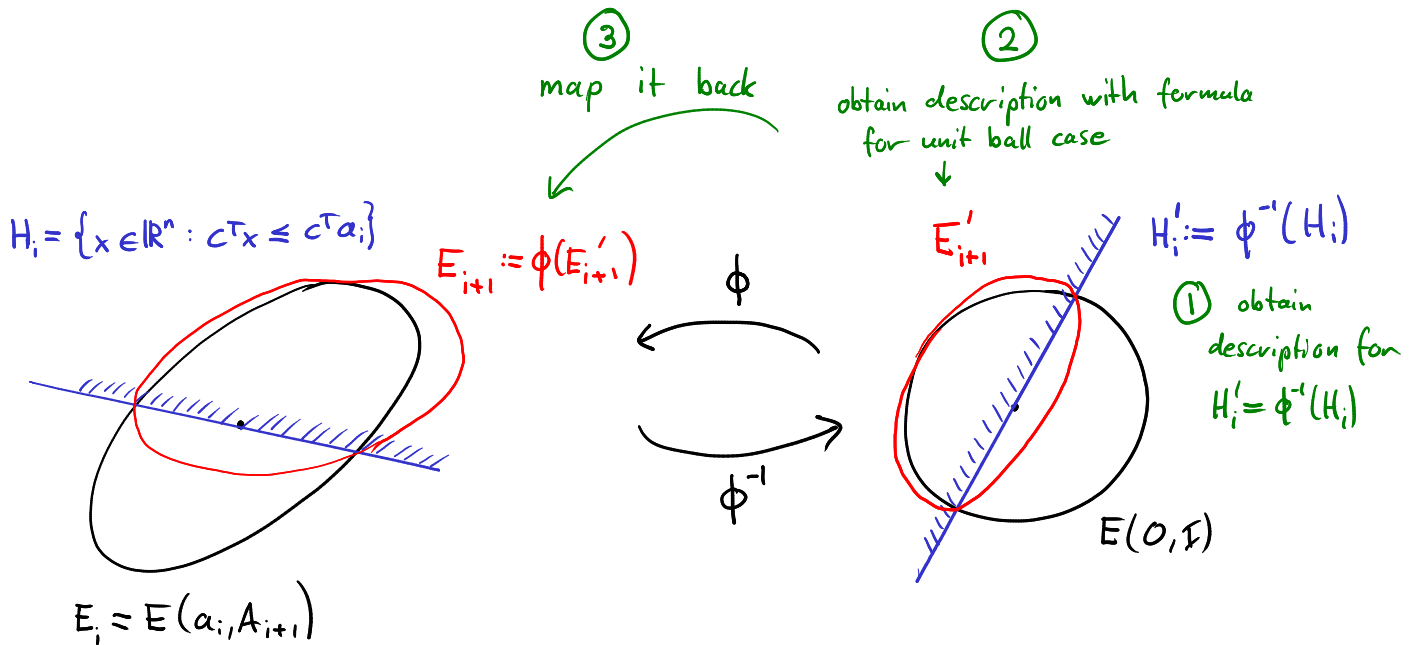
General case

Let $E_i = E(a_i, A_i)$ be a general ellipsoid, and let

$H_i = \{x \in \mathbb{R}^n : c^T x \leq c^T a_i\}$ be a general halfspace going through a_i .

$$\left. \begin{array}{l} \text{Let } Q_i \in \mathbb{R}^{n \times n} \text{ s.t. } A_i = Q_i Q_i^T. \\ \phi(x) := Q_i x + a_i. \end{array} \right\} \Rightarrow \phi(E(0, I)) = E_i.$$

Plan:



$$\phi(x) = Q_i x + a_i$$

$$\phi^{-1}(x) = Q_i^{-1}(x - a_i)$$

$$\textcircled{1} H'_i := \phi^{-1}(H_i) = \{ Q_i^{-1}(x-a) : x \in \mathbb{R}^n, c^T x \leq c^T a_i \}$$

$$\begin{aligned} &\xrightarrow{\quad} = \{ y \in \mathbb{R}^n : c^T (Q_i y + a) \leq c^T a_i \} \\ y = Q_i^{-1}(x-a) &= \{ y \in \mathbb{R}^n : (Q_i^T c)^T y \leq 0 \} \end{aligned}$$

$$\Rightarrow H'_i = \{ x \in \mathbb{R}^n : d^T x \leq 0 \} \text{ with } d := \frac{Q_i^T c}{\sqrt{c^T Q_i Q_i^T c}}$$

$\textcircled{2}$ B_y unit ball case:

$$E'_{i+1} = E(a'_{i+1}, A'_{i+1}), \text{ where}$$

$$a'_{i+1} = -\frac{1}{n+1} d$$

$$A'_{i+1} = \frac{n^2}{n^2-1} \left(I - \frac{2}{n+1} d d^T \right)$$

$$\textcircled{3} E_{i+1} = \phi(E'_{i+1}) = \{ \phi(x) : x \in \mathbb{R}^n, (x - a'_{i+1})^T (A'_{i+1})^{-1} (x - a'_{i+1}) \leq 1 \}$$

$$\xrightarrow{\quad} = \{ y \in \mathbb{R}^n : (Q_i^{-1}(y - a_i) - a'_{i+1})^T (A'_{i+1})^{-1} (Q_i^{-1}(y - a_i) - a'_{i+1}) \leq 1 \}$$

$$\phi(x) = Q_i x + a_i$$

$$\phi^{-1}(x) = Q_i^{-1}(x - a_i)$$

$$= \{ y \in \mathbb{R}^n : (y - a_i - Q_i a'_{i+1})^T (Q_i^{-1})^T (A'_{i+1})^{-1} Q_i^{-1} (y - a_i - Q_i a'_{i+1}) \leq 1 \}$$

$$= \{ y \in \mathbb{R}^n : (y - a_i - Q_i a'_{i+1})^T (Q_i A'_{i+1} Q_i^T)^{-1} (y - a_i - Q_i a'_{i+1}) \leq 1 \}$$

Recall: $a'_{i+1} = -\frac{1}{n+1} d$

$$\underline{a_{i+1}} = a_i + Q_i a'_{i+1} = a_i - \frac{1}{n+1} Q_i d = \underline{a_i - \frac{1}{n+1} b},$$

where $\underline{b} = Q_i d = Q_i \frac{Q_i^T c}{\sqrt{c^T Q_i Q_i^T c}} = \underline{\frac{A_i c}{\sqrt{c^T A_i c}}}$

$$\left(A_{i+1}^{-1} = (Q_i^{-1})^T (A'_{i+1})^{-1} Q_i^{-1} \right) \quad A'_{i+1} = \frac{n^2}{n^2-1} \left(I - \frac{2}{n+1} d d^T \right)$$

$$\begin{aligned} \Rightarrow \underline{A_{i+1}} &= Q_i A'_{i+1} Q_i^T = \frac{n^2}{n^2-1} \left(A_i - \frac{2}{n+1} Q_i d d^T Q_i^T \right) \\ &= \underline{\frac{n^2}{n^2-1} \left(A_i - \frac{2}{n+1} b b^T \right)} \end{aligned}$$

Hence, we can now write more explicitly how an iteration of the Ellipsoid Method looks.

Algorithm 9: Ellipsoid Method

Input : Separation oracle for a polytope $P \subseteq \mathbb{R}^n$ with $\dim(P) = n$, and an ellipsoid $E_0 = E(a_0, A_0)$ with $P \subseteq E_0$.

Output: A point $y \in P$.

$i = 0$.

while $a_i \notin P$ (checked with separation oracle) **do**

 Get $c \in \mathbb{R}^n$ such that $P \subseteq \{x \in \mathbb{R}^n : c^T x < c^T a_i\}$, using separation oracle.

 Let $b = \frac{A_i c}{\sqrt{c^T A_i c}}$.

 Let $a_{i+1} = a_i - \frac{1}{n+1} b$.

 Let $A_{i+1} = \frac{n^2}{n^2-1} (A_i - \frac{2}{n+1} b b^T)$.

$i = i + 1$.

return a_i .

6.4.4 From checking feasibility to optimization over {0,1}-polytopes

Let $P \subseteq \mathbb{R}^n$ be a full-dimensional {0,1}-polytope.

We want to solve :

$$\max_{x \in P} w^T x$$

for some $w \in \mathbb{Z}^n$.

Getting optimal LP value $v^* = \max\{w^T x : x \in P\}$

Starting ellipsoid

Bounding number of iterations

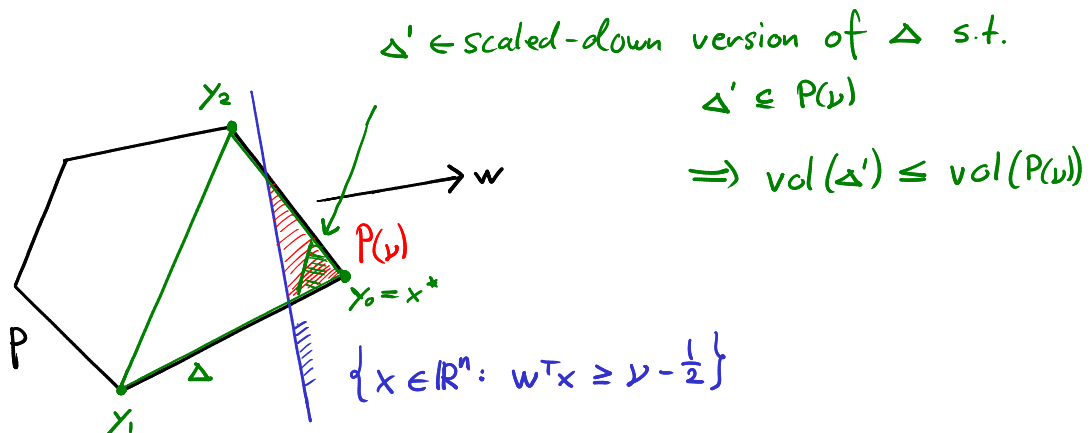
Recall:

Lemma 6.4

$$\frac{\text{vol}(E_{i+1})}{\text{vol}(E_i)} < e^{-\frac{1}{2(n+1)}}.$$

Assuming $P(v) \neq \emptyset$, we need lower bound on $\text{vol}(P(v))$.

Plan



Determining an optimal $\{0,1\}$ -solution x^*

One can determine x^* coordinate-wise from x_1^*, x_2^* to x_n^* , by repeatedly solving LPs over P with slightly modified objectives.

To check whether there exists optimal solution x^* to $\max \{w^T x : x \in P\}$ with $x^* = 1, \dots$

**Theorem 6.9**

Let $P \subseteq \mathbb{R}^n$ be a full-dimensional $\{0, 1\}$ -polytope for which we are given a separation oracle. Furthermore, let $w \in \mathbb{Z}^n$. Then the Ellipsoid Method allows for finding an optimal vertex solution to the linear program $\max\{w^\top x : x \in P\}$ using a polynomial number of elementary operations and calls to the separation oracle for P .

6.5 Comments on the non-full-dimensional case

Theorem 6.2

Let $P \subseteq \mathbb{R}^n$ be a $\{0, 1\}$ -polytope for which we are given a separation oracle. Furthermore, let $w \in \mathbb{Z}^n$. Then the Ellipsoid Method allows for finding an optimal vertex solution to the linear program $\max\{w^\top x : x \in P\}$ using a polynomial number (in n) of elementary operations and calls to the separation oracle for P .