### **RIS**

### March 13, 2020

### RIS in Ternay Alloys

1. Fractional concentration

$$X_{Fe} = \Omega C_{Fe}$$
$$X_{Cr} = \Omega C_{Cr}$$
$$X_{Ni} = \Omega C_{Ni}$$

Where Average atomic volume

$$\Omega = \frac{1}{N}$$

Atomic density

$$N = 9.1 \times 10^{28} \#/m^3$$

2. Continuity equations

$$\begin{split} \frac{dX_{Fe}}{dt} &= -\Omega \times \nabla J_{Fe} \\ \frac{dX_{Cr}}{dt} &= -\Omega \times \nabla J_{Cr} \\ \frac{dX_{Ni}}{dt} &= -\Omega \times \nabla J_{Ni} \\ \\ \frac{dX_v}{dt} &= -\Omega \times \nabla J_v + G_v - R \times X_v \times X_i \\ \\ \frac{dX_i}{dt} &= -\Omega \times \nabla J_i + G_i - R \times X_v \times X_i \end{split}$$

3. Flux eqaution for atoms and defects

$$\begin{split} \Omega \times J_{Fe} &= -\alpha D_{Fe} (1 - X_{Fe}) \nabla X_{Fe} + \left[ \alpha D_{Cr} \nabla X_{Cr} + \alpha D_{Ni} \nabla X_{Ni} + (d_{Fe}^v - D_v) \nabla X_v + (D_i - d_{Fe}^i) \nabla X_i \right] X_{Fe} \\ \Omega \times J_{Cr} &= -\alpha D_{Cr} (1 - X_{Cr}) \nabla X_{Cr} + \left[ \alpha D_{Fe} \nabla X_{Fe} + \alpha D_{Ni} \nabla X_{Ni} + (d_{Cr}^v - D_v) \nabla X_v + (D_i - d_{Cr}^i) \nabla X_i \right] X_{Cr} \\ \Omega \times J_{Ni} &= -\alpha D_{Ni} (1 - X_{Ni}) \nabla X_{Ni} + \left[ \alpha D_{Cr} \nabla X_{Cr} + \alpha D_{Fe} \nabla X_{Fe} + (d_{Ni}^v - D_v) \nabla X_v + (D_i - d_{Ni}^i) \nabla X_i \right] X_{Ni} \\ \Omega \times J_v &= -D_v \nabla X_v + \alpha X_v (d_{Fe}^v \nabla X_{Fe} + d_{Cr}^v \nabla X_{Cr} + d_{Ni}^v \nabla X_{Ni}) \\ \Omega \times J_i &= -D_i \nabla X_i - \alpha X_i (d_{Fe}^i \nabla X_{Fe} + d_{Cr}^i \nabla X_{Cr} + d_{Ni}^i \nabla X_{Ni}) \end{split}$$

### 4. Diffusion coefficients

$$D_{Fe} = d_{Fe}^{v} X_{v} + d_{Fe}^{i} X_{i}$$

$$D_{Cr} = d_{Cr}^{v} X_{v} + d_{Cr}^{i} X_{i}$$

$$D_{Ni} = d_{Ni}^{v} X_{v} + d_{Ni}^{i} X_{i}$$

$$D_{v} = d_{Fe}^{v} X_{Fe} + d_{Cr}^{v} X_{Cr} + d_{Ni}^{v} X_{Ni}$$

$$D_{i} = d_{Fe}^{i} X_{Fe} + d_{Cr}^{i} X_{Cr} + d_{Ni}^{i} X_{Ni}$$

# 5. Diffusivities Vacancies

$$\lambda_a^v = \lambda$$

$$d_{Fe}^v = \nu_{Fe}^v (\lambda_a^v)^2$$

$$d_{Cr}^v = \nu_{Cr}^v (\lambda_a^v)^2$$

$$d_{Ni}^v = \nu_{Ni}^v (\lambda_a^v)^2$$

Interstitial

$$\begin{split} \lambda_a^i &= \sqrt{\frac{2}{3}} \lambda \\ d_{Fe}^i &= \nu_{Fe}^i (\lambda_a^i)^2 \\ d_{Cr}^i &= \nu_{Cr}^i (\lambda_a^i)^2 \\ d_{Ni}^i &= \nu_{Ni}^i (\lambda_a^i)^2 \end{split}$$

## 6. Jump frequency

$$v_{Fe}^{v} = v_{Fe}^{v,0} e^{-\frac{E_{Fe}^{v,m}}{k_{b}T}}$$

$$v_{Cr}^{v} = v_{Cr}^{v,0} e^{-\frac{E_{Cr}^{v,m}}{k_{b}T}}$$

$$v_{Ni}^{v} = v_{Ni}^{v,0} e^{-\frac{E_{Ni}^{v,m}}{k_{b}T}}$$

$$v_{Fe}^{i} = f^{i} v^{i,0} e^{-\frac{E_{i,m}^{i,m}}{k_{b}T}}$$

$$v_{Cr}^{i} = f^{i} v^{i,0} e^{-\frac{E_{i,m}^{i,m}}{k_{b}T}}$$

$$v_{Ni}^{i} = f^{i} v^{i,0} e^{-\frac{E_{i,m}^{i,m}}{k_{b}T}}$$

# Migration energy Pair interaction energy Like atoms

$$E_{CrCr} = \frac{2E_{coh}^{Cr}}{Z}$$

$$E_{FeFe} = \frac{2E_{coh}^{Fe}}{Z}$$

$$E_{NiNi} = \frac{2E_{coh}^{Ni}}{Z}$$

Unlike atoms

$$E_{NiCr} = \frac{E_{NiNi} + E_{CrCr}}{2} - E_{NiCr}^{ord}$$

$$E_{FeCr} = \frac{E_{FeFe} + E_{CrCr}}{2} - E_{FeCr}^{ord}$$

$$E_{FeNi} = \frac{E_{FeFe} + E_{NiNi}}{2} - E_{FeNi}^{ord}$$

Atoms and vacancies

$$E_{Cr-v} = \frac{E_{coh}^{Cr} + E_f^{Cr-v}}{Z}$$

$$E_{Ni-v} = \frac{E_{coh}^{Ni} + E_f^{Ni-v}}{Z}$$

$$E_{Fe-v} = \frac{E_{coh}^{Fe} + E_f^{Fe-v}}{Z}$$

Saddle point energy

$$ES_{pure}^{Cr} = E_m^{Cr-v} + Z(E_{CrCr} + E_{Cr-v})$$

Vacancy migration energy

$$E_{Fe}^{v,m} = C_{Fe}(-\frac{3}{2}E_{Fe}^{coh} + \frac{1}{2}E_{Fe,pure}^{v,m} - \frac{1}{2}E_{Fe}^{v,f}) + C_{Cr}(-E_{Fe}^{coh} - \frac{1}{2}E_{Cr}^{coh} + \frac{1}{2}E_{Cr,pure}^{v,m} - \frac{1}{2}E_{Cr}^{v,f} - ZE_{FeCr}^{ord}) + C_{Ni}(-E_{Fe}^{coh} - \frac{1}{2}E_{Cr}^{v,m} - \frac{1}{2}E_{Cr}^{v,m}) + C_{Ni}(-E_{Fe}^{coh} - \frac{1}{2}E_{Cr}^{v,m} - \frac{1}{2}E_{Cr}^{v,m} - \frac{1}{2}E_{Cr}^{v,m}) + C_{Fe}(-E_{Cr}^{coh} - \frac{1}{2}E_{Fe}^{coh} + \frac{1}{2}E_{Fe,pure}^{v,m} - \frac{1}{2}E_{Fe}^{v,f} - ZE_{FeCr}^{ord}) + C_{Ni}(-E_{Cr}^{coh} - \frac{1}{2}E_{Ni}^{v,m} - \frac{1}{2}E_{Ni}^{v,m} - \frac{1}{2}E_{Ni}^{v,m}) + C_{Fe}(-E_{Ni}^{coh} - \frac{1}{2}E_{Fe}^{coh} + \frac{1}{2}E_{Fe,pure}^{v,m} - \frac{1}{2}E_{Fe}^{v,f} - ZE_{FeNi}^{ord}) + C_{Cr}(-E_{Ni}^{coh} - \frac{1}{2}E_{Ni}^{v,m} - \frac{1}{2}E_{Fe,pure}^{v,m} - \frac{1}{2}E_{Fe,pure}^{v,f} - ZE_{FeNi}^{ord}) + C_{Cr}(-E_{Ni}^{coh} - \frac{1}{2}E_{Ni}^{v,m} - \frac{1}{2}E_{Ni}^{v,m} - \frac{1}{2}E_{Ni}^{v,f} - ZE_{FeNi}^{ord}) + C_{Cr}(-E_{Ni}^{coh} - \frac{1}{2}E_{Ni}^{v,m} - \frac{1}{2}E_{Ni}^{v,m} - \frac{1}{2}E_{Ni}^{v,m} - \frac{1}{2}E_{Ni}^{v,f} - ZE_{Ni}^{ord}) + C_{Cr}(-E_{Ni}^{coh} - \frac{1}{2}E_{Ni}^{v,m} - \frac{1}{2}E_{Ni}^{v,$$

Interstitial migration energy

$$E^{i,m}=0.9eV$$

### 7. Defect production rate

$$G_v = \eta \phi + \rho D_v (X_v^{th} - X_v)$$
$$X_v^{th} = e^{\frac{S^{v,f}}{k_b}} e^{-\frac{E^{v,f}}{k_b T}}$$

$$G_{i} = \eta \phi + \rho D_{i}(X_{i}^{th} - X_{i})$$
 
$$X_{v}^{th} = small$$
 
$$R = [(\nu_{Fe}^{v} + \nu_{Fe}^{i})X_{Fe} + (\nu_{Cr}^{v} + \nu_{Cr}^{i})X_{Cr} + (\nu_{Ni}^{v} + \nu_{Ni}^{i})X_{Ni}]Z$$

Algorithms

- 1) Input data
- 2) Set up all variables
- 3) Claculate energies, jump frequencies, diffusivities, diffusion coefficients
- 4) Discretize fractional concentrations
- 5) Apply PDE solver to continuity equations
- 6) Output fractional concentration tensor (LŒTŒ5)

Solving Partial Differential Equations

A method of lines for partial differential equations (PDEs) where one reduces a PDE to a system of ODE and then applies standard methods.

$$\frac{\partial u(x,t)}{\partial t} = \beta \frac{\partial^2 u(x,t)}{\partial x^2} + f(x,t), x \in [0,L], t \in [0,T]$$
$$u(0,t) = s(t), t \in [0,T]$$
$$\frac{\partial}{\partial x} u(L,t) = 0, t \in [0,T]$$
$$u(x,0) = I(x), x \in [0,L]$$

Discretizing the 2nd-order derivative in space with a finite difference on a mesh

$$x_i = i\Delta x, i = 1, ..., N-1$$

then ODE:

$$\frac{\partial u_i(t)}{\partial t} = \beta \frac{u_{i+1}(t) - 2u_i(t) + u_{i-1}(t)}{\Delta x^2} + f_i(t), i = 1, ..., N - 1$$

The boundary condition on x=0, u(0,t)=s(t), gives rise to the ODE

$$u_0' = s'(t), u_0(0) = s(0)$$

At the other end, x=L, we use a centered difference approximation The boundary condition on x=0, u(0,t)=s(t), gives rise to the ODE

$$\frac{u_{N+1}(t) - u_{N-1}(t)}{2\Delta x} = 0$$

and combine it with the scheme for i=N to obtain the modified boundary ODE

$$\frac{\partial u_N(t)}{\partial t} = \beta \frac{2u_{N-1}(t) - 2u_N(t)}{\partial x^2} + f_N(t)$$

To summarize, the ODE system reads

$$\begin{split} \frac{du_0}{dt} &= s'(t) \\ \frac{du_i}{dt} &= \frac{\beta}{\Delta x^2} (u_{i+1}(t) - 2u_i(t) + 2u_{i-1}(t)) + f_i(t), i = 1, ..., N - 1 \\ \frac{du_N}{dt} &= \frac{2\beta}{\Delta x^2} (u_{N-1}(t) - u_N(t)) + f_i(t) \end{split}$$

The initial conditions are

$$u_0(0) = s(0)$$
  
 $u_i(0) = I(x_i), i = 1, ..., N$ 

**Points** 

6/03/2020 Compléter des unités pour chaque paramètre Rlier une variable et son unité Rendre des variables en ordre et lisible Evaluer des algorithms en fonction de la complexité en temps

13/03/2020 Distinguer des paramètres physiques et ceux-ci numériques Faire une table de tous les parameters avec certaines sets

[0]: """

Python version:

This code need Python 2.7 compile environment beacause of a package odespy.

Install odespy:

This operation as followed is uniquely supported in Google Colab. If you use another platform such as Anaconda, please remove this line and look over a website https://github.com/hplgit/odespy to install odespy.

No other requirements:

Despite Odespys many dependencies on other software, you can run the basic solvers implemented in pure Python without any additional software packages.

!pip install git+https://github.com/hplgit/odespy.git

[0]: | # -\*- coding: utf-8 -\*-

n n n

Created on Fri Feb 28 08:50:29 2020

@author: Chao PAN

Simulation for RIS with model MIK (Modified Inverse Kirkendall)
Ternary Alloys Ee-Cr-Ni

This program calculates the amount of radiation induced segregation for a ternary concentrated alloy. The formulation is based on the perks model and is solved numerically using the gear subroutines.

```
11 11 11
#import odespy
import numpy as np
#import matplotlib.pyplot as plt
ERROR_FILE, OUTPUT_FILE = "error.txt", "output.txt"
# Distance to mesh groups (m)
R1, R2, RF = 4.0, 18.0, 2018.0
# No. of points in mesh groups
N1, N2, N3 = 16, 14, 20
# Input time setp to gear
HO = 1e-9
# Error control parameter
EPS = 1e-9
# Peak displacement rate (dpa/s)
DISPRT = 1.4e-6
# Vacancy/Interstitial production efficiency
ETAV, ETAI = 1.0, 1.0
# Dose
DOSE = 1.0
# Peak temperature (\check{r}C)
TEMPC = 360.
# Concentration of B, C (fractional concentration #%)
CONCB, CONCC = 0.21, 0.09
# Peak dislocation density (#/m2)
DISL = 1e14
# No. density (#/m3)
NAT = 9.1e28
# Jump distance (m)
LAMBDA = 3.5e-10
```

```
# Jump correlation factors for A, B, C, interstitial
FAV, FBV, FCV, FI = 0.785, 0.668, 0.872, 0.660
# Relative vacancy jump frequency ratio for A, B, C
# 1.6(1.4), 2.4(2.3) 1.0 or 1.86666666666, 3.33333333333
WAV, WBV, WCV = 1.8, 3.2, 1.0
# Relative interstitial jump frequency ratio for A, B, C
WAI, WBI, WCI = 1.0, 1.0, 1.0
# Cohesive energies: -4.28, -4.10, -4.44 (eV)
ECOHA, ECOHB, ECOHC = -4.28, -4.10, -4.44
# Interstitial migration energies for A, B, C (eV)
EMIA, EMIB, EMIC = 0.9, 0.9, 0.9
# Vacancy formation enthalpy (=kb)
SV = 1.0
# Pure element [vacancy] migratio energies for A, B, C (eV)
EMA, EMB, EMC = 1.28, 0.97, 1.04
# Pure element [vacancy] formation energies for A, B, C (eV)
EFA, EFB, EFC = 1.4, 1.6, 1.79
# Grain boundary formation energy (eV)
EFGB = 1.4
# Ordering energies (eV)
EORDAB, EORDAC, EORDBC = 0.003, -0.001, 0.005
# Debye frequencies (/s)
NUOV, NUOI = 1.5e13, 1.5e12
# Thermo factor
AT. = 1.0
# Neighbor atoms
Z = 12.0
# Dislocation bias for vacancy/interstitial
BIASV, BIASI = 1.0, 1.0
# User-required output times
TOUTPT = [1e-0, 1e1, 5e2, 1e3, 5e3, 1.4e4, 5e4, 7.1e4, 1e5, 1.4e5, 3.6e5,
          4.3e5, 7.1e5, 2.1e6, 2.2e6, 2.3e6, 5e6, 7e7, 1e8, 0e0]
```

```
# Indicator whether profiles will be used
FRAC = "N"
# Fraction of max temperature
TFRAC = [1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0,
      1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0]
# Fraction of peak atom A
CAFRAC = [1.0000, 1.0000, 1.0000, 1.0000, 1.0000, 1.0000, 1.0000, 1.0000,
      1.0000, 1.0000, 1.0000, 1.0000, 1.0000, 1.0000]
# Fraction of peak atom B
CBFRAC = [0.1231, 0.2991, 0.3912, 0.4573, 0.5100, 0.6988, 0.8144, 0.8969,
       0.9613, 1.0150, 1.0000, 1.0000, 1.0000, 1.0000, 1.0000]
# Fraction of peak atom C
CCFRAC = [1.1670, 1.1334, 1.1160, 1.1033, 1.0933, 1.0574, 1.0354, 1.0196,
       1.0074, 0.9971, 1.0000, 1.0000, 1.0000, 1.0000, 1.0000]
# Fraction of peak damage
DFRAC = [1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0,
      1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0]
# Fraction of max dislocation density
1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0]
# Boltzmann constant = 1.38064852e-23 \text{ m2.kg/s/K}
BOLTZ = 8.617e-5
SCFAC = 1e-9
# Time steps
NSTEP = N1+N2+N3
N = 5*NSTEP
# Concentration of A
CONCA = 1.0-(CONCB+CONCC)
# Fraction of max temperature, peak atoms, damage, max dislocation density
```

```
# Profiles will not be used
if FRAC == "N":
   TFRAC = np.ones(NSTEP)
   CAFRAC = np.ones(NSTEP)
   CBFRAC = np.ones(NSTEP)
   CCFRAC = np.ones(NSTEP)
   SFRAC = np.ones(NSTEP)
   DFRAC = np.ones(NSTEP)
else:
   _temp = np.zeros(NSTEP)
   _temp[:NSTEP-1] = TFRAC[:NSTEP-1]
   # TFRAC = np.zeros(NSTEP)
   TFRAC[:NSTEP-1] = _temp[:NSTEP-1]
   _temp[:NSTEP] = CAFRAC[:NSTEP]
   CAFRAC = np.zeros(NSTEP)
   CAFRAC[:NSTEP] = _temp[:NSTEP]
   _temp[:NSTEP] = CBFRAC[:NSTEP]
   CBFRAC = np.zeros(NSTEP)
   CBFRAC[:NSTEP] = _temp[:NSTEP]
   temp[:NSTEP] = CCFRAC[:NSTEP]
   CCFRAC = np.zeros(NSTEP)
   CCFRAC[:NSTEP] = _temp[:NSTEP]
   _temp[:NSTEP] = SFRAC[:NSTEP]
   SFRAC = np.zeros(NSTEP)
   SFRAC[:NSTEP] = _temp[:NSTEP]
   _temp[:NSTEP] = DFRAC[:NSTEP]
   DFRAC = np.zeros(NSTEP)
   DFRAC[:NSTEP] = _temp[:NSTEP]
   del _temp
class RIS:
   HHHH
   Simulation of RIS is based on MIK
   def __init__(self):
       Initialise model including variables and files.
       Seu up all variables for this model, including concentrations, fluxes,
       diffusivities, geometry, defects, temperature, energy etc.
       Arguments:
```

```
None
Return:
    None
# Variables
self.X_Fe_fraction = np.ones(NSTEP)
self.X_Cr_fraction = np.ones(NSTEP)
self.X_Ni_fraction = np.ones(NSTEP)
self.T_fraction = np.ones(NSTEP)
self.Damage_fraction = np.ones(NSTEP)
self.Max_dislocation_density = np.ones(NSTEP)
if FRAC == "N":
    SFRAC = np.ones(NSTEP)
    DFRAC = np.ones(NSTEP)
# Dose
self.DOSE = DOSE
# Time
self.TOUT = 0.0
self.TSTOP = DOSE/DISPRT
self.NOUT = 0
# Temperature
self.TEMP = (TEMPC+273)*TFRAC
self.TKT = BOLTZ*self.TEMP
# Concentrations
self.CA = CONCA*CAFRAC
self.CB = CONCB*CBFRAC
self.CC = CONCC*CCFRAC
self.CI = np.zeros(NSTEP)
self.CVTHER = self.set_CVTHER()
self.CV = self.CVTHER.copy()
self.CERR = np.zeros(NSTEP)
self.NA = np.zeros(NSTEP)
self.NB = np.zeros(NSTEP)
self.NC = np.zeros(NSTEP)
self.NV = np.zeros(NSTEP)
self.NI = np.zeros(NSTEP)
# Gradient
self.GRADCA = np.zeros(NSTEP)
self.GRADCB = np.zeros(NSTEP)
self.GRADCC = np.zeros(NSTEP)
self.GRADCV = np.zeros(NSTEP)
self.GRADCI = np.zeros(NSTEP)
```

```
self.CADOT = np.zeros(NSTEP)
self.CBDOT = np.zeros(NSTEP)
self.CCDOT = np.zeros(NSTEP)
self.CVDOT = np.zeros(NSTEP)
self.CIDOT = np.zeros(NSTEP)
self.RECOMB = np.zeros(NSTEP)
self.INTSINK = np.zeros(NSTEP)
self.VACSINK = np.zeros(NSTEP)
self.VACSOUR = np.zeros(NSTEP)
# Energy
self.EAA = self.calculate_energy("A", "A")
self.EBB = self.calculate energy("B", "B")
self.ECC = self.calculate_energy("C", "C")
self.EAB = self.calculate_energy("A", "B")
self.EAC = self.calculate_energy("A", "C")
self.EBC = self.calculate_energy("B", "C")
self.EAV = self.calculate_energy("A", "V")
self.EBV = self.calculate_energy("B", "V")
self.ECV = self.calculate_energy("C", "V")
self.ESA = self.calculate_energy("S", "A")
self.ESB = self.calculate energy("S", "B")
self.ESC = self.calculate_energy("S", "C")
self.EA = self.calculate energy("A", "VM")
self.EB = self.calculate_energy("B", "VM")
self.EC = self.calculate energy("C", "VM")
# Jump frequency between defects (vacancy or interstitial)
# and atoms (Fe, Cr, Ni)
self.NUIA = self.calculate_NU_dk("I", "A")
self.NUIB = self.calculate_NU_dk("I", "B")
self.NUIC = self.calculate_NU_dk("I", "C")
self.NUVA = self.calculate_NU_dk("V", "A")
self.NUVB = self.calculate_NU_dk("V", "B")
self.NUVC = self.calculate_NU_dk("V", "C")
# Diffusivities
self.DAI = self.calculate_D_dk("I", "A")
self.DBI = self.calculate D dk("I", "B")
self.DCI = self.calculate_D_dk("I", "C")
self.DAV = self.calculate_D_dk("V", "A")
self.DBV = self.calculate D dk("V", "B")
self.DCV = self.calculate_D_dk("V", "C")
self.RECA = self.set_REC_k("A")
self.RECB = self.set_REC_k("B")
self.RECC = self.set_REC_k("C")
self.DA = self.calculate_D_dk(None, "A")
```

```
self.DB = self.calculate_D_dk(None, "B")
self.DC = self.calculate_D_dk(None, "C")
self.DV = self.calculate_D_dk("V", None)
self.DI = self.calculate_D_dk("I", None)
self.DIFV = self.calculate_D_dk("V", None)
self.DIFI = self.calculate_D_dk("I", None)
# Geometry
self.MESHSP = np.zeros(NSTEP)
self.XVALUE = np.zeros(NSTEP)
self.MESHSI = np.zeros(NSTEP)
# Fluxes
self.JA = np.zeros(NSTEP)
self.JB = np.zeros(NSTEP)
self.JC = np.zeros(NSTEP)
self.JV = np.zeros(NSTEP)
self.JI = np.zeros(NSTEP)
self.JO = np.zeros(NSTEP)
self.JAO = 0.0
self.JB0 = 0.0
self.JC0 = 0.0
self.DIVJA = np.zeros(NSTEP)
self.DIVJB = np.zeros(NSTEP)
self.DIVJC = np.zeros(NSTEP)
self.DIVJV = np.zeros(NSTEP)
self.DIVJI = np.zeros(NSTEP)
# Defects
self.DISLOC = DISL*SFRAC
self.DISPV = np.zeros(NSTEP)
self.DISPI = np.zeros(NSTEP)
# Displacement of vacancy/interstitial
self.DISPV = self.calculate_displacement_d("V")
self.DISPI = self.calculate_displacement_d("I")
# YO[N], Y[N], YDOT[N], RWORK[N**2+20], IWORK[2*N+20]
self.Y0 = np.zeros(N)
self.Y0[:NSTEP] = self.CA
self.YO[NSTEP:2*NSTEP] = self.CB
self.Y0[2*NSTEP:3*NSTEP] = self.CC
self.Y0[3*NSTEP:4*NSTEP] = self.CV
self.YO[4*NSTEP:] = self.CI
self.Y = np.zeros(N)
self.YDOT = np.zeros(N)
```

```
self.RWORK = np.zeros(N**2+20)
    self.IWORK = np.zeros(2*N+20)
    self.XOUT = np.zeros(NSTEP)
    self.MF = 0
    self.IERR = 0
    self.ITOL = 0
    self.IOPT = 0
    self.ITASK = 0
    self.ISTEP = 0
    self.T0 = 0
    self.EPSA = 0.0
    self.PSTOP = "N"
    self.fn = ""
    self.flag = True
    self.PD = np.zeros(NSTEP)
def main(self):
    11 11 11
    self.empty_files()
    self.write_input_data()
    # Mesh grid
    self.mesh()
    while self.V["PSTOP"] == "N":
        self.preprocess()
        if self.V["PSTOP"] == "Y":
            break
        self.fex()
        self.solve()
        if self.IERR < -1:
            with open(ERROR_FILE, 'a+') as f:
                f.write("ERROR RETURN WITH IERR= {]\n".format(self.IERR))
                print("Terminated with error")
                return
```

```
elif self.IERR == -1:
            self.IERR = 2
        else:
            pass
        self.output()
    print("Completed")
def set_CVTHER(self):
    HHHH
    11 11 11
    CVTHER = np.exp(SV)*np.exp(-EFGB/self.TKT)
    CVTHER[-1] = CVTHER[-2]
    for i in range(1, NSTEP-1):
        CVTHER[i] = 0.5*(CVTHER[i]+CVTHER[i-1])
    return CVTHER
def set_REC_k(self, k):
    n n n
    return Z*(eval("self.NUI"+k)+eval("self.NUV"+k))
def set_GRAD_C(self, token):
    11 11 11
    nnn
    res = np.zeros(NSTEP)
    res[:-1] = eval("self.C"+token)[1:]-eval("self.C"+token)[:-1]
    _res = _res/self.MESHSP
    return _res
def empty_files(self):
    Clean up all contents of ancient files. This operation is usually
    done at the beginning of one simulation.
    # Clean up ancient files
    for FILE in [ERROR_FILE, OUTPUT_FILE]:
        with open(FILE, "w") as f:
            f.write("")
def set DIVJ(self):
    self.DIVJA[0] = 2.0*(self.JA[0]-self.JA0)/self.MESHSP[0]
    self.DIVJB[0] = 2.0*(self.JB[0]-self.JB0)/self.MESHSP[0]
    self.DIVJC[0] = 2.0*(self.JC[0]-self.JC0)/self.MESHSP[0]
```

```
self.MESHSI[1:-1] = 0.5*(self.MESHSP[1:-1]+self.MESHSP[:-2])
    self.DIVJA[1:-1] = (self.JA[1:-1]-self.JA[:-2])/self.MESHSI[1:-1]
    self.DIVJB[1:-1] = (self.JB[1:-1]-self.JB[:-2])/self.MESHSI[1:-1]
    self.DIVJC[1:-1] = (self.JC[1:-1]-self.JC[:-2])/self.MESHSI[1:-1]
    self.DIVJV[1:-1] = (self.JV[1:-1]-self.JV[:-2])/self.MESHSI[1:-1]
    self.DIVJI[1:-1] = (self.JI[1:-1]-self.JI[:-2])/self.MESHSI[1:-1]
    self.DIVJA[-1] = 2.0*(self.JA[-1]-self.JA[-2])/self.MESHSP(-2)
    self.DIVJB[-1] = 2.0*(self.JB[-1]-self.JB[-2])/self.MESHSP(-2)
    self.DIVJC[-1] = 2.0*(self.JC[-1]-self.JC[-2])/self.MESHSP(-2)
    self.DIVJV[-1] = 2.0*(self.JV[-1]-self.JV[-2])/self.MESHSP(-2)
    self.DIVJI[-1] = 2.0*(self.JI[-1]-self.JI[-2])/self.MESHSP(-2)
def calculate_energy(self, i, j):
    For like atoms, the paire interaction energy is the cohesive energy,
    E_coh divided by the numbre of nearest neighbor bond pairs.
    e.g. EAA = ECOHA/(Z/2)
         EBB = ECOHB/(Z/2)
         ECC = ECOHC/(Z/2)
    For unlike atoms, pair interaction energies are determined from the
    average value of the like-atom pair energies less any ordering energy.
    e.g. EAB = 0.5*(EAA+EBB)-EORDAB
         EAC = 0.5*(EAA+ECC)-EORDAC
         EBC = 0.5*(EBB+ECC)-EORDBC
    For atoms and vacancies, pair interaction energies is fitted to
    the formation energy of the pure metal.
    e.q. EAV = (ECOHA + EFA)/Z
         EBV = (ECOHB + EFB)/Z
         ECV = (ECOHC + EFC)/Z
    The saddle point energy in the pure metal
    e.q. ESA = EMA+Z*(EAA+EAV)
         ESB = EMB+Z*(EBB+EBV)
         ESC = EMC+Z*(ECC+ECV)
    The migration energy for Cr, Ni and Fe via vacancies can be expressed
    EA(I) = (ESA + ESA * NA(I) + ESB * NB(I) + ESC * NC(I))/2
          ((Z*(NA(I)*EAA+NB(I)*EAB+NC(I)*EAC+NV(I)*EAV))
          +(Z*(NA(I)*EAV+NB(I)*EBV+NC(I)*ECV)))
    EB(I) = (ESB + ESA * NA(I) + ESB * NB(I) + ESC * NC(I))/2 -
          ((Z*(NA(I)*EAB+NB(I)*EBB+NC(I)*EBC+NV(I)*EBV))
          +(Z*(NA(I)*EAV+NB(I)*EBV+NC(I)*ECV)))
     EC(I) = (ESC + ESA * NA(I) + ESB * NB(I) + ESC * NC(I))/2 -
```

```
((Z*(NA(I)*EAC+NB(I)*EBC+NC(I)*ECC+NV(I)*ECV))
       +(Z*(NA(I)*EAV+NB(I)*EBV+NC(I)*ECV)))
Arguments:
    i: atom (Fe, Cr, Ni) or defect (vacancy, interstitial) or
       saddle point
    j: atom (Fe, Cr, Ni) or defect (Vacancy, interstitial) or
       saddle point
Return:
    Energy (Migration energy, saddle point energy) value in float
_atoms = ["A", "B", "C"]
res = 0
if i in _atoms and j in _atoms:
    # Like atoms
   if i == j:
        res = eval("ECOH{})".format(i))/(Z/2)
    # Unlike atoms
    else:
        res = 0.5*(eval("self.E"+i+i)+
                    eval("self.E"+j+j))-eval("EORD"+i+j)
# Interaction energy between atoms and vacancies
elif i in _atoms and j == "V":
    res = (eval("ECOH"+i)+eval("EF"+i))/Z
# Migration energy for Fe Cr Ni via vacancies
elif i in _atoms and j == "VM":
    term1 = (eval("self.ES"+i)+self.ESA*self.NA+self.ESB*self.NB+
              self.ESC*self.NC)/2
    if i == "A":
        _term2 = Z*(self.NA*self.EAA+self.NB*self.EAB+
                    self.NC*self.EAC+self.NV*eval("self.E"+i+"V"))
    elif i == "B":
        _term2 = Z*(self.NA*self.EAB+self.NB*self.EBB+
                    self.NC*self.EBC+self.NV*eval("self.E"+i+"V"))
    elif i == "C":
        _term2 = Z*(self.NA*self.EAC+self.NB*self.EBC+
                    self.NC*self.ECC+self.NV*eval("self.E"+i+"V"))
    else:
        assert False, "Wrong arguments: {}".format(i)
    term3 = (Z*(self.NA*self.EAV+self.NB*self.EBV+self.NC*self.ECV))
    _res = _term1-(_term2+_term3)
# Saddle point energy
elif i == "S" and j in _atoms:
    _res = eval("EM"+j)+Z*(eval("self.E"+j+j)+eval("self.E"+j+"V"))
else:
    assert False, "Wrong arguments: {} {}".format(i, j)
return res
```

```
def mesh(self):
    In order to discretize PDE, it is necessary to have a well-mesh grid.
    Arguments:
        MESHSP:
        XVALUE:
    Return:
        None
    11 11 11
    # ??? Why ignore last elemet
    self.MESHSP[:N1-1] = R1*SCFAC/N1
    # ??? Why ignore last elemet
    self.MESHSP[N1-1:N1+N2-1] = (R2-R1)*SCFAC/N2
    self.MESHSP[N1+N2-1:N1+N2+N3-1] = (RF-R2)*SCFAC/N3
    for i in range(1, NSTEP):
        self.XVALUE[i] = self.XVALUE[i-1]+self.MESHSP[i-1]
def calculate_displacement_d(self, d):
    Defect displacement (vacancy or interstitial) =
    displacement ratio * defect production efficiency * defect fraction
    e.g. DISPV(I)=DISPRT*ETAV*DFRAC(I)
         DISPI(I)=DISPRT*ETAI*DFRAC(I)
    Arguments:
        d: token for defect type (vacancy or interstitial)
    Return:
        array of defect displacement
    return DISPRT*eval("ETA"+d)*DFRAC
def calculate_NU_dk(self, d, k):
    Jump frequency includes vacancy jump frequency and interstitial jump
    frequency.
    Formula:
        NU = NUO*W*F*EXP(-EM/kb/T)
    where:
        NU: jump frequency
        NUO: debye frequency
        W: relative defect jump frequency
        EM: defect migration energies
        kb: boltzmann constant
        T: Temperature
        NUO*W*F: standard jump frequency
```

```
For vacancy jump frequency:
    e.q. NUVA(I) = NUOV*WAV*FAV*EXP((-1*EA(I)/TKT(I)))
         NUVB(I) = NUOV*WBV*FBV*EXP((-1*EB(I)/TKT(I)))
         NUVC(I) = NUOV*WCV*FCV*EXP((-1*EC(I)/TKT(I)))
    For interstitial jump frequency:
    e.g. \ NUIA(I) = NUOI*WAI*FI*EXP((-1*EMIA)/TKT(I))
         NUIB(I) = NUOI*WBI*FI*EXP((-1*EMIB)/TKT(I))
         NUIC(I) = NUOI*WCI*FI*EXP((-1*EMIC)/TKT(I))
    Notion:
    A same standard interstitial jump frequency and a same interstitial
    correlation fator for Fe/Cr/Ni
    Arguments:
        k: token for one of three (Fe, Cr, Ni)
        d: token for one of two (vacancy, interstitial)
        array of jump frequency for k and d
    if d == "V":
        res = NUOV*eval("W"+k+"V")*eval("F"+k+"V")*\
            np.exp(-eval("self.E"+k)/self.TKT)
    elif d == "I":
        _res = NUOI*eval("W"+k+"I")*FI*np.exp(-eval("EMI"+k)/self.TKT)
        assert False, "Wrong defect type of d={}".format(d)
   return _res
def calculate_D_dk(self, d, k):
    This function is to calculate diffusivity between atom and defect.
    Formula:
        D(d, k) = NU(d, k)*lambda(d)^2
    where:
        D: diffusivity between defects and atoms
        lambda(d): unit cell size for defect
        NU(d, k): jump frequence between defects and atoms
    e.q. DAIO(I) = 0.66667*NUIA(I)*LAMBDA**2
         DBIO(I) = 0.66667*NUIB(I)*LAMBDA**2
         DCIO(I) = 0.66667*NUIC(I)*LAMBDA**2
         DAV(I) = NUVA(I)*LAMBDA**2
         DBV(I) = NUVB(I)*LAMBDA**2
         DCV(I) = NUVC(I)*LAMBDA**2
```

```
Formula:
                               DA(I) = DAV(I) * NV(I) + DAI(I) * NI(I)
                               DB(I)=DBV(I)*NV(I)+DBI(I)*NI(I)
                               DC(I) = DCV(I) * NV(I) + DCI(I) * NI(I)
                               DIFV(I) = DAV(I) * NA(I) + DBV(I) * NB(I) + DCV(I) * NC(I)
                               DIFI(I) = DAI(I) * NA(I) + DBI(I) * NB(I) + DCI(I) * NC(I)
               Parameters:
                               k: token for one of three Fe, Cr, Ni
                                d: token for one of two defects vacancy, interstitial
                return:
                               array of diffusivity between atom and defect
               if k is None:
                                _res = eval("self.DA"+d)*self.NA+eval("self.DB"+d)*self.NB+\
                                               eval("self.DC"+d)*self.NC
                elif d is None:
                                res = eval("self.D"+k+"V")*self.NV+eval("self.D"+k+"I")*self.NI
               else:
                               if d == "I":
                                              _res = 2/3*eval("self.NUI"+k)*LAMBDA**2
                               elif d == "V":
                                               _res = eval("self.NUV"+k)*LAMBDA**2
                               else:
                                              assert False, "Wrong defect type of d={}".format(d)
               return res
def calculate J dk(self, d, k):
                   JV(I) = NAT*(-1*DV(I)*GRADCV(I)+NV(I)*AL*(DAV(I)*GRADCA(I)+DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(I)*DAV(
                                                              DBV(I)*GRADCB(I)+DCV(I)*GRADCC(I)))
                   JI(I) = NAT*(-1*DI(I)*GRADCI(I)-NI(I)*AL*(DAI(I)*GRADCA(I)+DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(I)*DAI(
                                                              DBI(I)*GRADCB(I)+DCI(I)*GRADCC(I)))
                   JA(I) = NAT*(-1*DA(I)*AL*GRADCA(I)+NA(I)*(DAV(I)*GRADCV(I)-
                                                              DAI(I)*GRADCI(I)))-JO(I)*NA(I)
                   JB(I) = NAT*(-1*DB(I)*AL*GRADCB(I)+NB(I)*(DBV(I)*GRADCV(I)-I)
                                                              DBI(I)*GRADCI(I)))-JO(I)*NB(I)
                   JC(I) = NAT*(-1*DC(I)*AL*GRADCC(I)+NC(I)*(DCV(I)*GRADCV(I)-I)
                                                             DCI(I)*GRADCI(I)))-JO(I)*NC(I)
                 11 11 11
                if k is None:
                                term1 = -1*eval("self.D"+d)*eval("self.GRADC"+d)
                               term2 = eval("self.DA"+d)*self.GRADCA+\
                                              eval("self.DB"+d)*self.GRADCB+eval("self.DC"+d)*self.GRADCC
                               if d == "V":
                                               _term2 = self.NV*AL*_term2
                               elif d == "I":
```

```
_term2 = -self.NI*AL*_term2
        _{res} = _{term1} + _{term2}
    elif d is None:
        _res = NAT*(-eval("self.D"+k)*AL*eval("self.GRADC"+k)+
                    eval("self.N"+k)*(eval("self.D"+k+"V")*self.GRADCV-
                                      eval("self.D"+k+"I")*self.GRADCI))-\
                    self.JO*eval("self.N"+k)
    return _res
def write input data(self):
    """Export input data"""
   with open(OUTPUT_FILE, "a+") as f:
        f.write("EPS={}\n".format(EPS))
        f.write("DISPRT={}, ETAV={}, ETAI={}, DOSE={}\n".format(DISPRT,
                ETAV, ETAI, DOSE))
        f.write("TEMP={} řC\n".format(TEMPC))
        f.write("CB={}, CC={}\n".format(CONCB, CONCC))
        f.write("DISL={}, NAT={}, LAMBDA={}\n".format(DISL, NAT, LAMBDA))
        f.write("FAV={}, FBV={}, FCV={}, FI={}\n".format(FAV, FBV, FCV,
                                                         FI))
        f.write("WAV={}, WBV={}, WCV={}\n".format(WAV, WBV, WCV))
        f.write("WAI={}, WBI={}, WCI={}\n".format(WAI, WBI, WCI))
        f.write("ECOHA={}, ECOHB={}, ECOHC={}\n".format(ECOHA, ECOHB,
                ECOHC))
        f.write("EMIA={}, EMIB={}, SV={}\n".format(EMIA, EMIB,
                EMIC. SV))
        f.write("EMA={}, EMB={}, EMC={}\n".format(EMA, EMB, EMC))
        f.write("EFA={}, EFB={}, EFC={}, EFGB={}\n".format(EFA, EFB,
                EFC, EFGB))
        f.write("EORDAB={}, EORDAC={}\n".format(EORDAB, EORDAC,
                EORDBC))
        f.write("NUOV={}, NUOI={}\n".format(NUOV, NUOI))
        f.write("AL={}, Z={}, BIASV={}, BIASI={}\n".format(AL, Z, BIASV,
                BIASI))
        f.write("TFRAC=\n{}\n".format(" ".join(TFRAC.astype(str))))
        f.write("CAFRAC=\n{}\n".format(" ".join(CAFRAC.astype(str))))
        f.write("CBFRAC=\n{}\n".format(" ".join(CBFRAC.astype(str))))
        f.write("CCFRAC=\n{}\n".format(" ".join(CCFRAC.astype(str))))
        f.write("DFRAC=\n{}\n".format(" ".join(DFRAC.astype(str))))
        f.write("SFRAC=\n{}\n".format(" ".join(SFRAC.astype(str))))
def write_error_info(self, _error_info):
    with open(ERROR FILE, 'a+') as f:
        f.write("ERROR RETURN WITH IERR= {]\n".format(self.IERR))
def preprocess(self):
```

```
11 11 11
    if self.ISTEP == 0:
        self.T0 = 0
        self.MF = 222
        self.IERR = 1
        self.TOUT = TOUTPT[0]
        self.ISTEP += 1
        self.ITOL = 1
        self.ITASK = 1
        self.IOPT = 1
        self.Y = self.Y0.copy()
        self.IWORK[5] = 1000000
    elif self.ISTEP < self.NOUT:</pre>
        self.ISTEP += 1
        self.TOUT = TOUTPT[self.ISTEP]
    else:
        self.PSTOP = "Y"
        with open(ERROR_FILE, 'a+') as f:
            f.write("Stopping Time Reached\n")
def fex(self, u, t):
    Right-hand side of the ODE
    self.CA = self.Y[:NSTEP]
    self.CB = self.Y[NSTEP:2*NSTEP]
    self.CC = self.Y[2*NSTEP:3*NSTEP]
    self.CV = self.Y[3*NSTEP:4*NSTEP]
    self.CI = self.Y[4:NSTEP]
    self.NA[:NSTEP] = 0.5*(self.CA[1:]+self.CA[:NSTEP])
    self.NB[:NSTEP] = 0.5*(self.CB[1:]+self.CB[:NSTEP])
    self.NC[:NSTEP] = 0.5*(self.CC[1:]+self.CC[:NSTEP])
    self.NV[:NSTEP] = 0.5*(self.CV[1:]+self.CV[:NSTEP])
    self.NI[:NSTEP] = 0.5*(self.CI[1:]+self.CI[:NSTEP])
    self.NUVA = self.calculate_NU_dk("V", "A")
    self.NUVB = self.calculate NU dk("V", "B")
    self.NUVC = self.calculate_NU_dk("V", "C")
    self.DAV = self.calculate_D_dk("V", "A")
    self.DBV = self.calculate_D_dk("V", "B")
    self.DCV = self.calculate_D_dk("V", "C")
    self.RECA = self.set_REC_k("A")
    self.RECB = self.set_REC_k("B")
```

```
self.RECC = self.set_REC_k("C")
self.RECA[-1] = self.RECA[-2]
self.RECB[-1] = self.RECB[-2]
self.RECC[-1] = self.RECC[-2]
self.CVTHER[-1] = self.CVTHER[-2]
self.DIFV = self.calculate_D_dk("V", None)
self.DIFI = self.calculate D dk("I", None)
self.DIFV[-1] = self.DIFV[-2]
self.DIFI[-1] = self.DIFI[-2]
self.RECA[1:-1] = 0.5*(self.RECA[1:-1]+self.RECA[:-2])
self.RECB[1:-1] = 0.5*(self.RECB[1:-1]+self.RECB[:-2])
self.RECC[1:-1] = 0.5*(self.RECC[1:-1]+self.RECC[:-2])
self.CVTHER[1:-1] = 0.5*(self.CVTHER[1:-1] + self.CVTHER[:-2])
self.DIFV[1:-1] = 0.5*(self.DIFV[1:-1]+self.DIFV[:-2])
self.DIFI[1:-1] = 0.5*(self.DIFI[1:-1]+self.DIFI[:-2])
self.JAO = self.JBO = self.JCO = 0.0
self.JA[-1] = self.JB[-1] = self.JC[-1] = 0.0
self.GRADCA = self.set_GRAD_C("A")
self.GRADCB = self.set_GRAD_C("B")
self.GRADCC = self.set_GRAD_C("C")
self.GRADCV = self.set GRAD C("V")
self.GRADCI = self.set_GRAD_C("I")
self.DA = self.calculate D dk(None, "A")
self.DB = self.calculate D dk(None, "B")
self.DC = self.calculate D dk(None, "C")
self.DV = self.calculate_D_dk("V", None)
self.DI = self.calculate D dk("I", None)
self.JV = self.calculate_J_dk("V", None)
self.JI = self.calculate_J_dk("I", None)
self.JO = self.JI-self.JV
self.JA = self.calculate J dk(None, "A")
self.JB = self.calculate_J_dk(None, "B")
self.JC = self.calculate_J_dk(None, "C")
self.JV = self.JV-self.JO*self.NV
self.JI = self.JI-self.J0*self.NI
self.set DIVJ()
self.CADOT = -self.DIVJA/NAT
self.CBDOT = -self.DIVJB/NAT
self.CCDOT = -self.DIVJC/NAT
self.RECOMB = self.RECA*self.CA+self.RECB*self.CB+self.RECC*self.CC
self.INTSINK = self.DISLOC*self.DIFI
self.VACSINK = self.DISLOC*self.DIFV
self.VACSOUR = self.DISLOC*self.DIFV*self.CVTHER
```

```
self.CVDOT[0] = 0.0
    self.CIDOT[0] = 0.0
    self.CVDOT[1:] = -self.DIVJV[1:]/NAT-self.RECOMB[1:]*self.CV[1:]*\
        self.CI[1:]-BIASV*self.VACSINK[1:]*self.CV[1:]+\
        self.VACSOUR[1:]+self.DISPV[1:]
    self.CIDOT[1:] = -self.DIVJI[1:]/NAT-self.RECOMB[1:]*self.CV[1:]*\
        self.CI[1:]-BIASI*self.INTSINK[1:]*self.CI[1:]+\
        self.DISPI[1:]
    self.Y[:NSTEP] = self.CA
    self.Y[NSTEP:2*NSTEP] = self.CB
    self.Y[2*NSTEP:3*NSTEP] = self.CC
    self.Y[3*NSTEP:4*NSTEP] = self.CV
    self.Y[4*NSTEP:] = self.CI
    self.YDOT[:NSTEP] = self.CADOT
    self.YDOT[NSTEP:2*NSTEP] = self.CBDOT
    self.YDOT[2*NSTEP:3*NSTEP] = self.CCDOT
    self.YDOT[3*NSTEP:4*NSTEP] = self.CVDOT
    self.YDOT[4*NSTEP:] = self.CIDOT
def set_pde(self, u, t, L=None, beta=None, x=None):
   N = len(u) - 1
   dx = x[1] - x[0]
   rhs = np.zeros(N+1)
   rhs[0] = self.dsdt(t)
    for i in range(1, N):
        rhs[i] = (beta/dx**2)*(u[i+1] - 2*u[i] + u[i-1]) + self.f(x[i], t)
   rhs[N] = (beta/dx**2)*(2*u[i-1] - 2*u[i]) + self.f(x[N], t)
   return rhs
def set_jacobin(self, u, t, L=None, beta=None, x=None):
   N = len(u) - 1
   dx = x[1] - x[0]
   K = np.zeros((N+1,N+1))
   K[0,0] = 0
    for i in range(1, N):
       K[i,i-1] = beta/dx**2
        K[i,i] = -2*beta/dx**2
        K[i,i+1] = beta/dx**2
   K[N,N-1] = (beta/dx**2)*2
   K[N,N] = (beta/dx**2)*(-2)
   return K
def s(self, t):
   return 423
```

```
def dsdt(self, t):
    return 0
def f(self, x, t):
    return 0
def solve(self, method='RKC'):
    N = 40
    L = 1
    x = np.linspace(0, L, N+1)
    f_kwargs = dict(L=L, beta=1, x=x)
    u = np.zeros(N+1)
    U_0 = np.zeros(N+1)
    U_0[0] = self.s(0)
    U_0[1:] = 283
    solvers = {
            "FE": odespy.ForwardEuler(self.set_pde, f_kwargs=f_kwargs),
            "BE": odespy.BackwardEuler(self.set_pde, f_is_linear=True,
                                        jac=self.set_jacobin,
                                        f_kwargs=f_kwargs,
                                        jac_kwargs=f_kwargs),
            "B2": odespy.Backward2Step(self.set_pde, f_is_linear=True,
                                        jac=self.set_jacobin,
                                       f_kwargs=f_kwargs,
                                        jac_kwargs=f_kwargs),
            "theta": odespy.ThetaRule(self.set_pde, f_is_linear=True,
                                      jac=self.set_jacobin, theta=0.5,
                                      f_kwargs=f_kwargs,
                                      jac_kwargs=f_kwargs),
            "RKF": odespy.RKFehlberg(self.set_pde, rtol=1E-6, atol=1E-8,
                                     f_kwargs=f_kwargs),
            "RKC": odespy.RKC(self.set_pde, rtol=1E-6, atol=1E-8,
                              f_kwargs=f_kwargs, jac_constant=True)
            }
    dx = x[1] - x[0]
    beta = 1
    dt = dx**2/(2*beta) # Forward Euler limit
    print("Forward Euler stability limit:{}".format(dt))
    T = 1.2
    solver = solvers[method]
    solver.set_initial_condition(U_0)
    N_t = int(round(T/float(dt)))
    time_points = np.linspace(0, T, N_t+1)
    u, t = solver.solve(time_points)
```

```
return u, t
    def output(self):
        HHHH
        self.CA = self.Y[:NSTEP]
        self.CB = self.Y[NSTEP:2*NSTEP]
        self.CC = self.Y[2*NSTEP:3*NSTEP]
        self.CV = self.Y[3*NSTEP:4*NSTEP]
        self.CI = self.Y[4:NSTEP]
        self.DOSE = DISPRT*TOUTPT[self.ISTEP]
        print("TOUT={}, DOSE={}".format(TOUTPT[self.ISTEP], self.DOSE))
        self.CERR = 1-(self.CA+self.CB+self.CC)
        self.XOUT = self.XVALUE*1e9
        TEMP1 = (self.CA*np.exp(-self.XOUT/0.8452)).sum()/
            np.exp(-self.XOUT/0.8452).sum()
        TEMP2 = (self.CB*np.exp(-self.XOUT/0.7474)).sum()/
            np.exp(-self.XOUT/0.7474).sum()
        TEMP3 = (self.CC*np.exp(-self.XOUT/0.9472)).sum()/
            np.exp(-self.XOUT/0.9472).sum()
        CASURF = TEMP1/(TEMP1+TEMP2+TEMP3)
        CBSURF = TEMP2/(TEMP1+TEMP2+TEMP3)
        CCSURF = TEMP3/(TEMP1+TEMP2+TEMP3)
        with open(OUTPUT_FILE, "a+") as f:
            f.write("TIME={}, DOSE={}\n".format(TOUTPT[self.ISTEP],
                    self.DOSE))
            for i in range(NSTEP):
                f.write("{} {} {} {} {}\n".format(self.XOUT[i], self.CA[i],
                        self.CB[i], self.CC[i], self.CV[i], self.CI[i]))
            f.write("CASURF={}, CBSURF={}, CCSURF={}\n".format(CASURF,
                    CBSURF, CCSURF))
    def is_stop(self):
        u[step_no] holds solution at t[step_no]
        HHHH
        return
if __name__ == "__main__":
    ris = RIS()
```

#### Reference:

A Tutorial for the Odespy Interface to ODE Solvers http://hplgit.github.io/odespy/doc/pub/tutorial/html/main\_odespy.html Example codes https://github.com/hplgit/odespy/blob/master/doc/src/tutorial/src-odespy/pde\_diffusion.py