

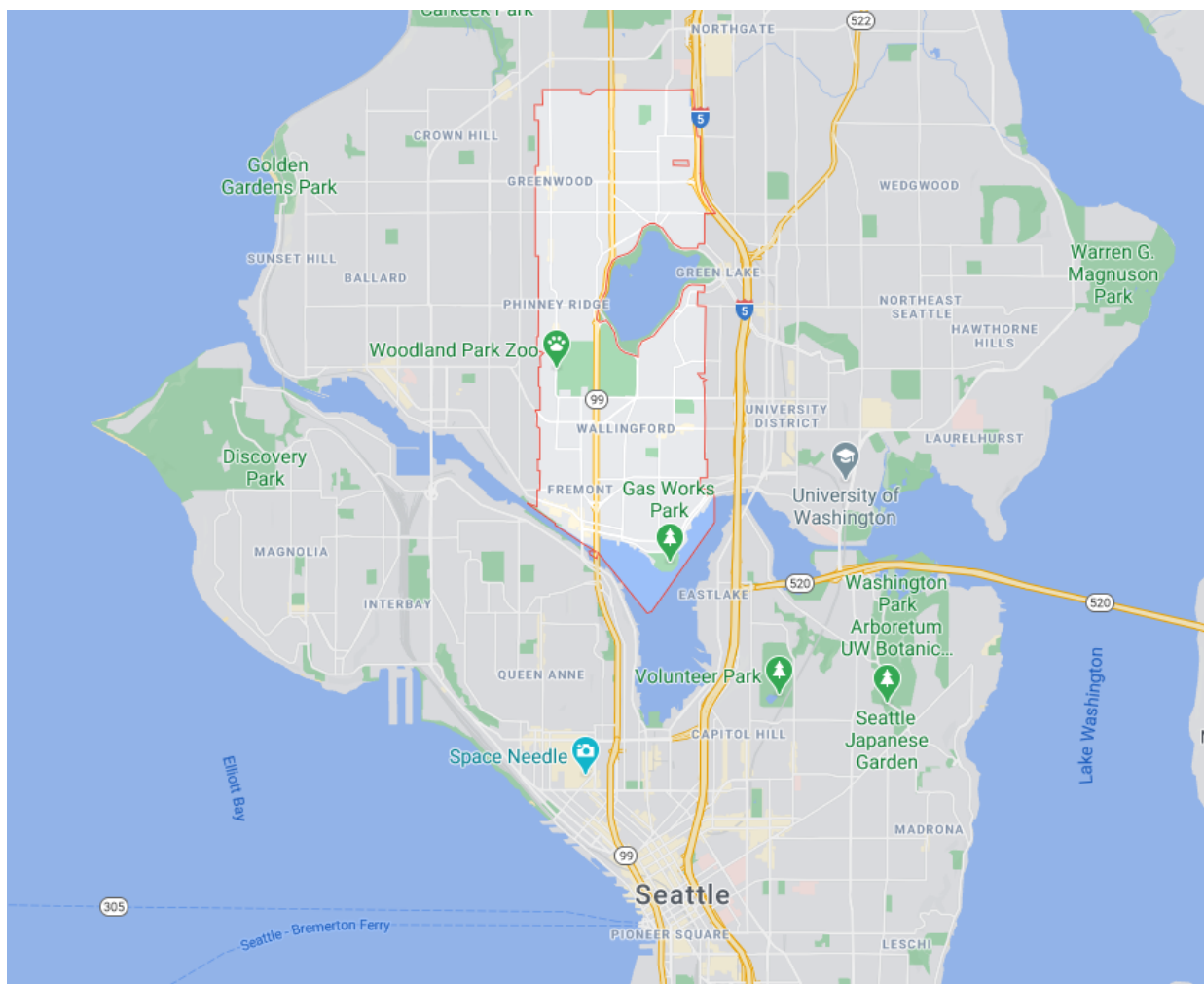
```
In [1]: import copy
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
import matplotlib.style as style
import matplotlib.gridspec as gridspec
import seaborn as sns
from mpl_toolkits import mplot3d
from scipy import stats
%matplotlib inline
```

```
In [95]: df = pd.read_csv('./data_mod_1.csv')
```

## Exploring State Zip WA 98103

The 148 samples in WA 98103 is a comfortable amount of work with, to verify our machine learning algorithm results with hand calculations. After verifying the algorithm, the algorithm will be extended to the rest of the 4550 samples in the original dataframe, that comprises the entire Seattle region.

### State ZIP WA 98103 on the map



```
df_4 = df.loc[ (df['statezip'] == 'WA 98103'), ['bedrooms', 'bathrooms', 'sqft_living'],
```

In [96]:

We chose the features in dataframe\_4 because, intuitively, these would seem as the most significant. In other words, if I was to purchase a house, the size (sqft), the condition and the location would be the most important features.

In [97]:

```
X_ = df_4.sqft_living # sqft is the most telling of price
X = X_.to_numpy() # we want to convert from series to a numpy array
ones = np.ones(len(X)) # adding a ones column in front
X_with_ones_col = np.column_stack((ones, X)) # Data Preprocessing

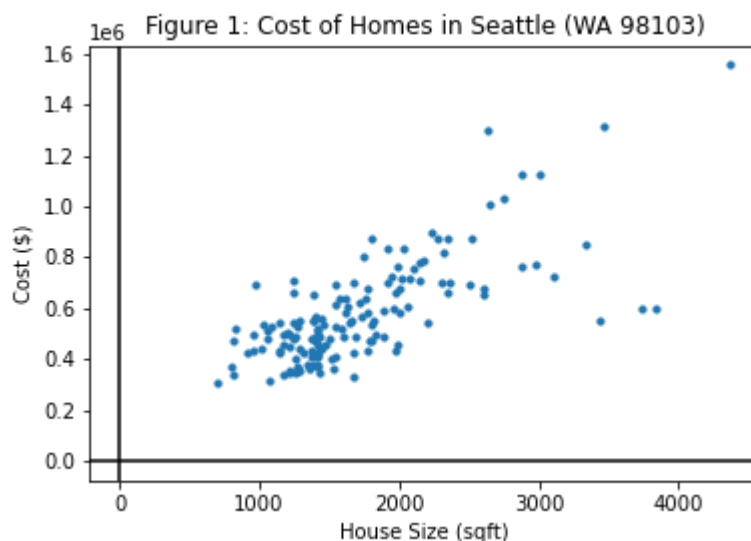
y_ = df_4.price # target
y = y_.to_numpy()
```

## §1.0 Applying Machine Learning Models

In [805...]

```
fig4, ax4 = plt.subplots()

ax4.scatter(X, y, s=10) # plot looks fine
ax4.axhline(0, color='black')
ax4.axvline(0, color='black')
ax4.set_title("Figure 1: Cost of Homes in Seattle (WA 98103)")
ax4.set_xlabel("House Size (sqft)")
ax4.set_ylabel("Cost ($)")
```



Out[805... Text(0, 0.5, 'Cost (\$)')

In Figure 1, there is a trend of cost increasing with sqft. This is a typical linear regression problem. In more detail, this is a univariate linear regression model and we are trying to fit a hypothesis.

Our aim is to find the line of best fit for Figure 1. A line of best fit is also called a hypothesis. We can represent this hypothesis, by determining the slope and y-intercept. The intercept and slopes are weights  $w_0$  and  $w_1$  respectively. These weights are the values that stabilize the hyp

1. In §1.1, we use sklearn's LinearRegression library to determine the weights.

2. In §1.2, we use an analytic approach. These weights will be compared to the weights determined by the sklearn library.
3. In §1.3, we determine a cost function and apply a gradient descent learning algorithm on the cost function.

The weights from the second approach will be compared to the weights determined by an analytic solution. We compare it this manner because there are less moving parts in an analytic approach. You just need to ensure the design matrix and target are sized appropriately, and apply a series of basic linear algebra techniques such as inversion, multiplication on the design matrix and the target.

, a more visual approach. A cost function is calculated and plotted §1.4,. An iterative gradient descent algorithm applied to the cost function will descend to the lowest point and yields the weights in §1.5

## §1.1 Linear Regression with the sklearn Library

```
In [21]: from sklearn import datasets
         from sklearn import linear_model
         from sklearn.model_selection import train_test_split
```

```
In [108... model = l_reg.fit(X_with_ones_col, y)
```

```
In [109... l_reg.coef_
```

```
Out[109... array([ 0.          , 229.49521863])
```

```
In [80]: l_reg.intercept_
```

```
Out[80]: 184435.24482113082
```

From the sklearn, the weights for  $w_0$  and  $w_1$  are 184435.2 and 229.5 respectively.

```
In [77]: test_val = np.array([[1, 2000]])
         model.predict(test_val)
```

```
Out[77]: array([643425.6820888])
```

The model generated by sklearn predicts a housing value of \$643425.

## §1.2 An Analytic Approach

If we wanted to do this at a lower level, there are two ways to solve this. After determining the weights from with the linear regression machine learning model provided by the sklearn package, we will find the weights 'by hand' as well. There are many ways to do this. In this project, we will be employing the following two approaches to find the weights, similar to Lab 2.

Its very convenient to be able to calculate the weights with the following approach. In fact this is the best way to solve this problem for this situation (excluding sklearn)

As mentioned above, since there's only one feature to consider (sqft), we can solve for the weights with an analytic approach. Essentially, this means using basic linear algebra techniques, to solve for our weight, weights being our slope and intercept in this single-featured example.

The advantages of an analytic approach:

- no need for gradient descent
- no need to perform thousands of iterations
- no need for learning rate guesswork
- no need for feature scaling

In fact, the entire solution can be solved with an analytic approach. If the code is vectorized, an analytic approach would work up to even 10,000 features.

```
In [86]: def normal_equation(X, y):
        return np.linalg.inv(X.T @ X) @ X.T @ y
```

```
In [556... normal_equation(X_with_ones_col, y)
```

```
Out[556... array([184435.24482113,    229.49521863])
```

From our analytic approach, the weights for  $w_0$  and  $w_1$  are 184435.2 and 229.5 respectively. These values are exactly the same as the values from sklearn.

## Test with 2000 sqft

These are our weights. If we run a test. if we have 2000 sqft. then ...

```
In [782... 184435.2448 + 229.4952 * 2000
```

```
Out[782... 643425.6448
```

comparing the answer \$643435 with Figure 1, the answer looks reasonable and therefore the weights are reasonable.

## §1.3 Developing a Cost Function

Approach 2 is more involved, for example, one has to adjust the number of iterations, guess the learning rate and more (more discussed below). Since more things can go wrong with gradient descent than the analytic solution, the results from gradient descent+cost function is compared to the analytic solution.

We explore how to solve for the weights with gradient descent on a cost function because in some situation, gradient descent works where the normal equation cannot be applied, like for example in logistic regression, knn.

### §1.3.1 Scaling Down

For plotting purposes, it would be ideal to have weights close in value so that the cost function looks decent. I'm going to scale the X by 1000 and the scale the y by 100,000.

The cost function can be contrived with the original values, and the weights correctly come out as  $w_0=184435.2$  and  $w_1= 229.5$ , but the cost function does not look good.

Note that, I could scale down with standard feature scaling techniques as well ( subtracting the mean and divide by the standard deviation from each value) but I've opted not to because I want to get a scaled down value by tens (ie 184435 -> 1.84) of what we got from sklearn and from the analytic solution, so that all three approaches are comparable.

```
In [112... X_scaled = X/1000
X_scaled_with_ones_col = np.column_stack((np.ones(len(X_scaled)), X_scaled))
y_scaled = y/100000
```

If we use the normal equation, we get the following weights

```
In [116... normal_equation(X_scaled_with_ones_col, y_scaled)
```

```
Out[116... array([1.84435245, 2.29495219])
```

Note that, the weight values changed from

$w_0=184435.2$  and  $w_1= 229.5$  to  **$w_0=1.84$  and  $w_1= 2.29$**

are much closer in value now, it will be much easier to visualize in a plot.

If the cost function and gradient descent are done correctly below, it will yield  $w_0=1.84$  and  $w_1= 2.29$ .

## §1.4 Plotting the Cost Function

The cost function, tests all pairs of weights  $w_0$  and  $w_1$  and plot them in a specified range.

### §1.4.1 Contour Plot of the Cost Function

```
In [804... def plot(g):
    g2 = g*g
    steps = np.linspace(-4, 6, g)
    w0, w1 = np.meshgrid(steps, steps)
    w0_ = w0.ravel()
    w1_ = w1.ravel()
    w = np.column_stack([w0_, w1_])

    def calculateCostArray(X, y, i):
        return computeCost(X, y, w[i])

    def computeCost(X, y, w):
        t = X @ w - y
        t_squared = t * t # vectorized. element wise squaring
        cost = 1/(2*len(X)) * sum(t_squared)
        return cost

    costs = np.zeros(g2)
    for i in range(g2):
        costs[i] = calculateCostArray(X_scaled_with_ones_col, y_scaled, i)

    costs = costs.reshape(g, g, -1)
    costs = costs.squeeze()
```

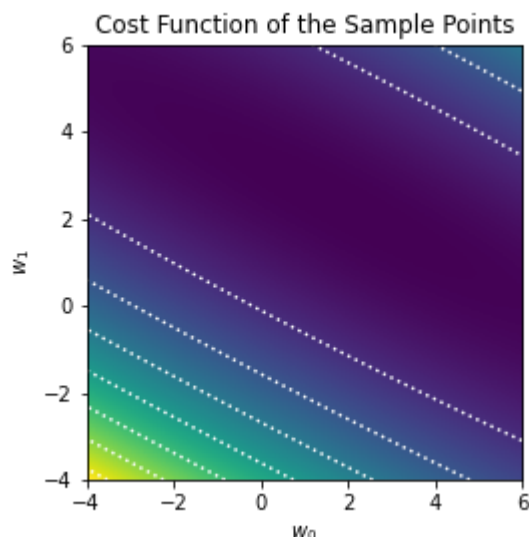
```

fig3, ax3 = plt.subplots()

ax3.imshow(costs, origin='lower', extent=(w0.min(), w0.max(), w1.min(), w1.max()))
ax3.set_title("Cost Function of all the Samples in Figure 1")
ax3.set_xlabel('$w_0$')
ax3.set_ylabel('$w_1$')
ax3.contour(w0, w1, costs, colors='white', linestyle=':')

plot(100)

```



this looks good. Upon visual inspection the cost function, I can see that  $w_0=1.84$  and  $w_1=2.29$  does seem to lie in the darkest part of the cost function. The cost function will be a bowl like shape. Since there's only one feature, I'm aware that there will be only one global minimum. I know this because when I did my hand calculations with just three samples, I've noticed that, the cost function ends up as a 2nd degree polynomial, and that always has a shape of a bowl. Adding more samples to our cost function will still only produce a second degree polynomial, hence one global minimum.

The darkest region within this cost function represents the lowest point of our cost function. We want to let the algorithm know, that has to pay a cost, for the the pair of weights ( $w_0$ ,  $w_1$ ) it picks. Every pair of weights has an associated cost. An algorithm will pick the lowest point on the cost function as this corresponds to the lowest cost.

### §1.4.2 Interactive 3-D Plot of the Cost Function

we can also visualize the cost function in a 3D space, instead of a contour plot. I found this one more useful for understanding.

```

In [823... %matplotlib notebook

from mpl_toolkits.mplot3d import axes3d

bounds = 5

x1 = np.linspace(-bounds, bounds, 5)
x2 = np.linspace(-bounds, bounds, 5)

```

```

X1, X2 = np.meshgrid(x1, x2)

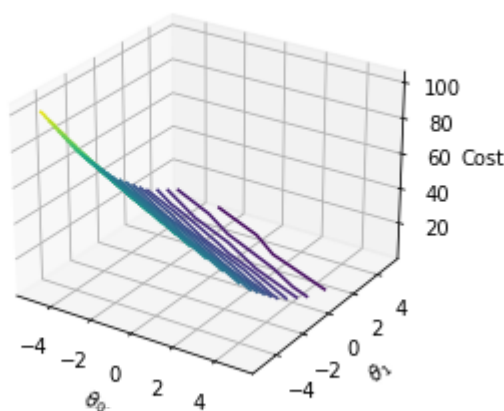
# Z = f(X1, X2)

fig1, ax1 = plt.subplots()
# fig = plt.figure()
ax1 = plt.axes(projection='3d')

ax1.contour3D(X1, X2, costs, 30)
# ax.plot_wireframe(X1, X2, Z, rstride=5, cstride=5)

ax1.set_xlabel(r'$\theta_0$')
ax1.set_ylabel(r'$\theta_1$')
ax1.set_zlabel('Cost')

```



Out[823... Text(0.5, 0, 'Cost')

We have a cost function representation as a contour and a surface plot. Now we need to apply gradient descent to our cost function and hopefully we get  $w_0=1.84$  and  $w_1= 2.29$

## §1.5 Gradient Descent

As can be seen in our function definition, we guess the weights as  $w_0=0$  and  $w_1= 0$ .

With gradient descent, our objective is to minimize the weights  $w_0$  and  $w_1$  such that the cost is the lowest. Essentially, the algorithm is paying a 'cost' for the parameters it picks, so it 'learns' by picking the weights with the lowest cost.

Basically you are instructing the algorithm, 'Find me the values of  $w_0$  and  $w_1$  that gives me the minimum of a cost function.'

Recap that from the normal equation, what we're supposed to be getting

$w_0=1.84$  and  $w_1=2.29$

To get started with gradient descent, we define a modified version from Lab 2

```
In [89]: def gradient_descent(X, y, learn_rate=0.00004, num_steps= 10000):
          w = np.array([0, 0]) # so instead of guessing x, we're guessing w
          for i in range(num_steps):
              grad = (X.T @ X) @ w - X.T @ y # so.. this is a very useful equation
              w = w - learn_rate*grad
          return w
```

I've noticed that, 0.0004 learning rate is quite low and 10000 iterations is quite high. But these are the values end up yielding the best results.

```
In [819... w_from_gradient_descent = gradient_descent(X_scaled_with_ones_col, y_scaled)
           w_from_gradient_descent
```

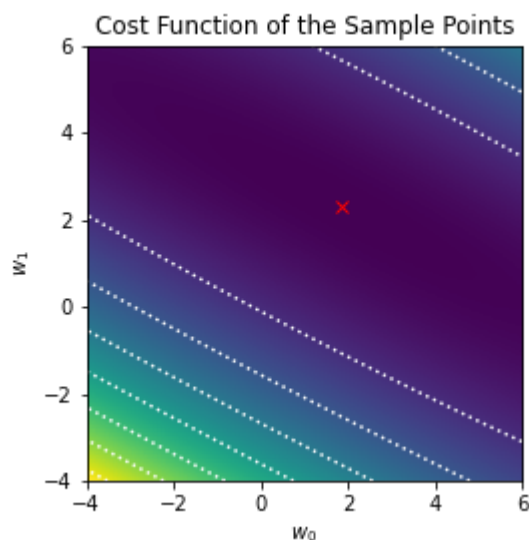
```
Out[819... array([1.84270283, 2.29581986])
```

With gradient descent, we come up with values  $w_0=1.84$  and  $w_1= 2.29$ , the same answer as our above approaches and the answer we were expecting.

## §1.6 Gradient Descent on our Cost Function

We can plot the weights on our contour plot we've created in §1.3.1

```
In [820... plot(100)
           plt.plot(*w_from_gradient_descent, 'xr')
```



```
Out[820... [<matplotlib.lines.Line2D at 0x1dfc9176cd0>]
```

## §2.0 Conclusion

Up to now, we have only considered a single feature, the size of the house (sqft). We are limited to only a single feature if we want to be able to plot. If we had more than one feature, we cannot visualize the cost function and gradient descent actually descending. When more features are added,  $\mathbb{R}$  moves into higher dimensions and we lose the visual aspect of it all because we cannot plot the cost function anymore. This is important because a visualizing this greatly helps understand the mechanics of gradient descent for other machine learning techniques.



The plan is to see if our weights make sense. the gradient descent to work and include all the features, such as bathrooms, condition of the house etc.