

CHIUW2023, June 2, 2023

Jisheng Zhao (Georgia Tech)

Akihiro Hayashi (Georgia Tech)

Brice Videau (ANL)

Vivek Sarkar (Georgia Tech)

MOTIVATION





GPU Programming in Chapel: no "intermediate" programming model

Highest-level Chapel-GPU Programming

```
1 forall i in 1..n {
2   A(i) = B(i) + alpha * C(i);
3 }
```



Research Question:
What is an appropriate and portable programming interface that bridges the "forall" and GPU versions?



Lowest-level Chapel-GPU Programming (C Interoperability only or GPUIterator)

```
// separate C file
     __global__ void stream(float *dA, float *dB, float *dC,
                              float alpha, int N) {
          int id = blockIdx.x * blockDim.x + threadIdx.x:
          if (id < N) {
                   dA\lceil id \rceil = dB\lceil id \rceil + alpha * dC\lceil id \rceil;
     void GPUST(float *A, float *B, float *C, float alpha,
                 int start, int end, int GPUN) {
10
       float *dA, *dB, *dC;
11
       CudaSafeCall(cudaMalloc(&dA, sizeof(float) * GPUN));
12
       CudaSafeCall(cudaMalloc(&dB, sizeof(float) * GPUN));
       CudaSafeCall(cudaMalloc(&dC, sizeof(float) * GPUN));
14
       CudaSafeCall(cudaMemcpy(dB, B + start, sizeof(float) *
15
                                 GPUN, cudaMemcpyHostToDevice));
16
       CudaSafeCall(cudaMemcpy(dC, C + start, sizeof(float) *
17
18
                                 GPUN, cudaMemcpyHostToDevice));
19
       stream<<<ceil(((float)GPUN)/1024), 1024>>>
20
21
                                         (dA, dB, dC, alpha, GPUN);
22
       CudaSafeCall(cudaDeviceSynchronize());
23
       CudaSafeCall(cudaMemcpy(A + start, dA, sizeof(float) *
                                 GPUN. cudaMemcpvDeviceToHost)):
24
25
       CudaSafeCall(cudaFree(dA));
       CudaSafeCall(cudaFree(dB)):
       CudaSafeCall(cudaFree(dC));
27
```

Big Picture: A Multi-level Chapel GPU Programming Model

HIGH-level:

The compiler compiles forall to CUDA, HIP, and OpenCL

forall

The missing link

Our proposal

Chapel programmer friendly GPU APIs:

MID-level

var dA = new GPUArray(A);
 dA.toDevice();

Thin wrappers for low-level GPU APIs:

MID-LOW-level

Malloc(); Memcpy();

Goal: increase productivity with no performance loss

LOW-level:

The user prepares full
GPU programs and
invokes them from Chapel
(w/ or w/o the GPUlterator)

GPUlterator [1]

Interoperability

CUDA/HIP/OpenCL

NVIDIA/AMD/Other GPUs





Contributions

- Why higher-level abstraction of GPU API?
 - For improving productivity
 - Our observation: The complexity in GPU programming comes not only from writing GPU kernels in the device part, but also from writing the host part
 - ✓ Our GPUAPI is designed to simplify the host part
 - For improving portability
 - Our observation: There are different GPU programming models from different vendors
 - ✓ Our GPUAPI is implemented to work on different platforms (NVIDIA, AMD, Intel, ...)
- ☐ Contribution (specific to this talk):
 - Enhance support for Intel GPUs by implementing a CHIP-SPV backend in the GPUAPI module





THE GPUAPI MODULE





Summary of the Chapel GPUAPI module

- ☐ Use case:
 - The user would like to 1) write GPU kernels, or 2) utilize highly-tuned GPU libraries, and would like to stick with Chapel for the other parts (allocation, data transfers)
- Provides two levels of GPU API
 - MID-LOW: Provides wrapper functions for raw GPU APIs Example: var ga: c_void_ptr = GPUAPI.Malloc(sizeInBytes);
 - MID: Provides more user-friendly APIs
 Example: var ga = new GPUArray(A);
- Note
 - The user is still supposed to write kernels in CUDA/HIP/SYCL (DPC++)
 - The APIs significantly facilitates the orchestration of:
 - ✓ Device memory (de)allocation, and host-to-device/device-to-host data transfers,
 - The use of the APIs does not involve any modifications to the Chapel compiler
 - The module can be utilized in real-world Chapel applications such as Champs and ChOp





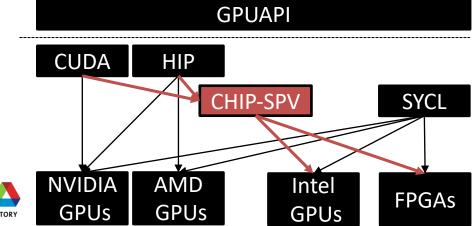


Example: Distributed execution of STREAM (MID-level w/ GPUlterator)

```
var D: domain(1) dmapped Block(boundingBox={1..n}) = {1..n};
   var A: [D] real(32); Chapel's
   var B: [D] real(32); | Distributed Array Allocation
    var C: [D] real(32); (n divided by # of nodes float elements)
                                                                                The user has the
    var GPUCallBack = lambda (lo: int, hi: int, nElems: int) {
                                                                                option of writing
      var dA = new GPUArray(A.localSlice(lo..hi));
                                                                                device functions.
      var dB = new GPUArray(B.localSlice(lo..hi));
                                                                               device lambdas, or
      var dC = new GPUArray(C.localSlice(lo..hi));
                                                                                  library calls
      toDevice(dB, dC);
10
      LaunchST(dA.dPtr(), dB.dPtr(),
11
               dC.dPtr(), alpha,
                                              // separate C file (CUDA w/ device lambda)
12
               dN: size_t);
                                              void LaunchST(float *dA, float *dB,
13
      DeviceSynchronize();
                                                             float *dC, float alpha, int N) {
14
      FromDevice(dA);
                                                 GPU_FUNCTOR(N, 1024, NULL,
15
      Free(dA, dB, dC);
                                                   [=] __device__ (int i) {
16
    forall i in GPU(D, GPUCallBack,
                                                 dA[i] = dB[i] + alpha * dC[i];
                                                   });
18
                       CPUPercent) {
19
     A(i) = B(i) + alpha * C(i);
20
```

Multi-platform Support: Module implementation

- Our module supports a wide variety of GPUs
- Our cmake-based build system detects types of GPUs and generate corresponding static and shared libraries
 - libGPUAPIX_static.a and libGPUAPIX.so

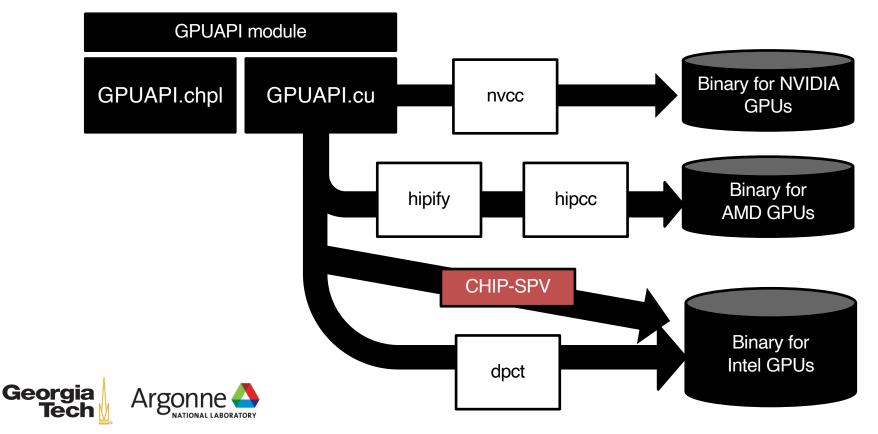








Multi-platform Support: Module implementation





Multi-platform Support: User-written kernels

Our multi-platform GPUAPI support allows the user to choose any GPU programming models to write their kernel code

	CUDA	HIP	SYCL
NVIDIA	Yes	Yes	Yes
AMD	Yes (hipify)	Yes	Yes
Intel	Yes (dpct or CHIP-SPV)	Yes (CHIP-SPV)	Yes





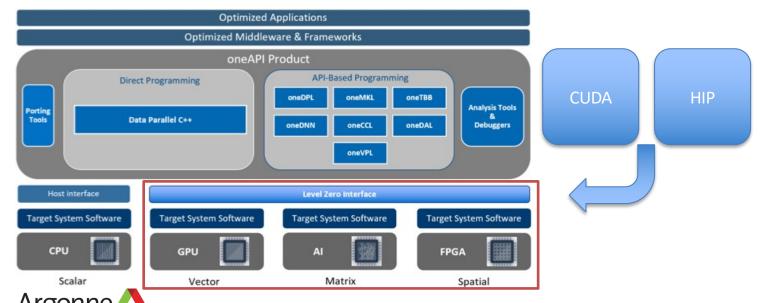
CHIP-SPV





CHIP-SPV

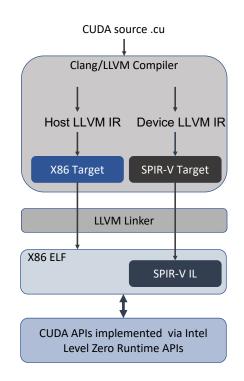
- □ Connect heterogeneous programming models (CUDA/HIP) to low-level Intel Level Zero runtime
- ☐ Intel Level Zero: A system level programming interface that bridges high level libraries to Intel devices

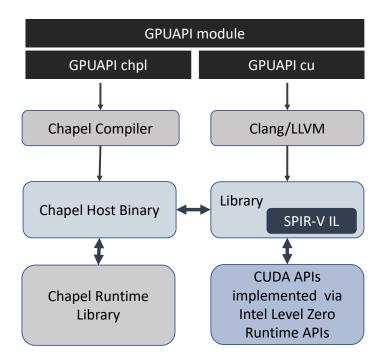






CHIP-SPV in the GPUAPI module









PRELIMINARY PERFORMANCE EVALUATIONS





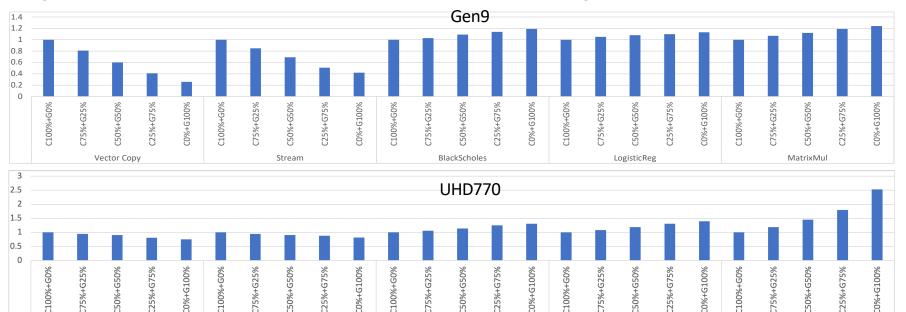
Performance Evaluations

- Platforms (Single-node, integrated-GPUs)
 - Intel Xeon Processor E5-1585 v5 (4-core) + Iris Pro P580 (Gen9)
 - Intel i7-12700 + UHD770
- Applications
 - Micro-benchmark: STREAM, BlackScholes, Matrix Multiplication, Logistic Regression
- ☐ Chapel Compilers & Options
 - Chapel Compiler 1.29.0 with the --fast option
 - Used with the GPUIterator (CPU+GPU execution)





Preliminary Performance Numbers (vs. forall execution on CPUs)



BlackScholes







Vector Copy

- Our end-to-end compilation flow with CHIP-SPV is verified
- Performance improvements are not significant due to integrated GPUs, but this is where the GPUlterator module comes into play

LogisticReg



MatrixMul

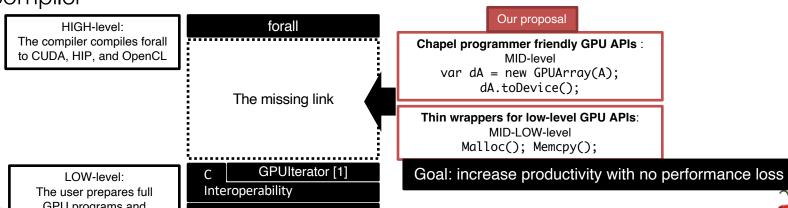
CONCLUSIONS





Conclusions

- ☐ Intel GPUs support in the GPUAPI module
 - Verified with microbenchmarks on two intel GPU platforms
- Future work:
 - Use discrete Intel GPUs
 - Discuss the possibility of using CHIP-SPV in the current Chapel compiler





The user prepares full GPU programs and invokes them from Chapel (w/ or w/o the GPUlterator)

CUDA/HIP/OpenCL

NVIDIA/AMD/Other GPUs

Join our community

- GPUAPI+GPUIterator:
 - The repository
 - ✓ https://github.com/ahayashi/chapel-gpu
 - Detailed Documents
 - ✓ https://ahayashi.github.io/chapel-gpu/index.html
- Our community is growing!

















Acknowledgements

This work was supported by the Argonne Leadership Computing Facility, which is a DOE Office of Science User Facility supported under Contract DE-AC02-06CH11357, and by the Exascale Computing Project (17-SC-20-SC), a collaborative effort of two U.S. Department of Energy organizations (Office of Science and the National Nuclear Security Administration). We also gratefully acknowledge the computing resources provided and operated by the Joint Laboratory for System Evaluation (JLSE) at Argonne National Laboratory.





BACKUP SLIDES





Chapel GPU API Design: MID-LOW GPU API

- Summary
 - Provides the same functionality as CUDA/HIP/OpenCL
 - The user is still supposed to write CUDA/HIP/OpenCL kernels
 - The user is supposed to handle both C types and Chapel types
- Key APIs
 - Device Memory Allocation
 - ✓ Malloc(...);
 - ✓ MallocPitch(...);
 - Host-to-device, and device-to-host data transfers
 - ✓ Memcpy(...);
 - ✓ Memcpy2D(...);
 - Ensuring the completion of GPU computations
 - ✓ DeviceSynchronize();
 - Device Memory deallocation
 - ✓ Free(...);







Chapel GPU API Design: MID GPU API

- Summary
 - More natural to Chapel programmers
 - The user is still supposed to write CUDA/HIP/OpenCL kernels
- Key APIs
 - Device Memory Allocation
 - ✓ var dA = new GPUArray(A);
 - ✓ var dA = new GPUJaggedArray(A);
 - Host-to-device, and device-to-host data transfers
 - ✓ ToDevice(dA:GPUArray, ...); FromDevice(dA: GPUArray, ...);
 - ✓ dA.ToDevice(); dA.fromDevice();
 - Implicit Device Memory deallocation
 - ✓ Automatically "freed" when a GPUArray/GPUJaggedArray object is deleted
 - Explicit Device Memory deallocation
 - √ delete







Chapel GPU API Design: MID-LOW/MID GPU API Example

```
MID-LOW Level
   use GPUAPI;
                                   Chapel's
  var A: [1..n] real(32); ]
   var B: [1..n] real(32); |-
                                Array Allocation
   var C: [1..n] real(32);
                                (n float elements)
   var dA, dB, dC: c_void_ptr;
   var size: size_t =
      (A.size:size_t * c_sizeof(A.eltType));
   Malloc(dA, size);
   Malloc(dB, size);
   Malloc(dC, size);
   Memcpy(dB, c_ptrTo(B), size, TODEVICE);
   Memcpy(dC, c_ptrTo(C), size, TODEVICE);
   LaunchST(dA, dB, dC, alpha, N: size_t);
   DeviceSynchronize();
15 Memcpy(c_ptrTo(A), dA, size, FROMDEVICE);
16 Free(dA); Free(dB); Free(dC);
```

```
MID-level
```

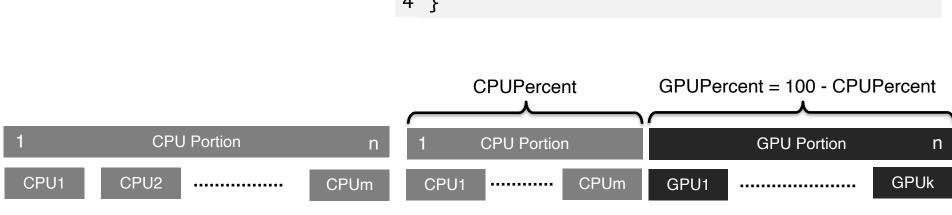
```
use GPUAPI;
                                 Chapel's
  var A: [1..n] real(32);
                               Array Allocation
  var B: [1..n] real(32); }
                              (n float elements)
   var C: [1..n] real(32); |
4 var dA = new GPUArray(A);
5 var dB = new GPUArray(B);
6 var dC = new GPUArray(C);
  toDevice(dB, dC);
  LaunchST(dA.dPtr(), dB.dPtr(),
            dC.dPtr(), alpha,
            dN: size_t);
10 DeviceSynchronize();
   FromDevice(dA);
12 Free(dA, dB, dC);
```





Our GPUIterator module facilitates running GPUAPI programs across CPUs+GPUs

```
function that includes
    a sequence of
    A(i) = B(i) + alpha * C(i);
    A(i) = B(i)
```







GPUCallBack is a