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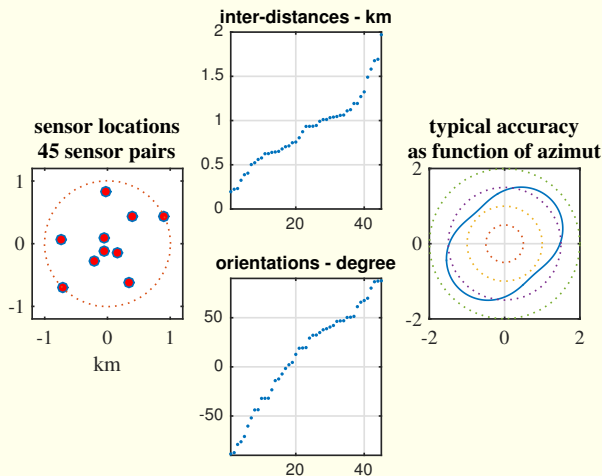
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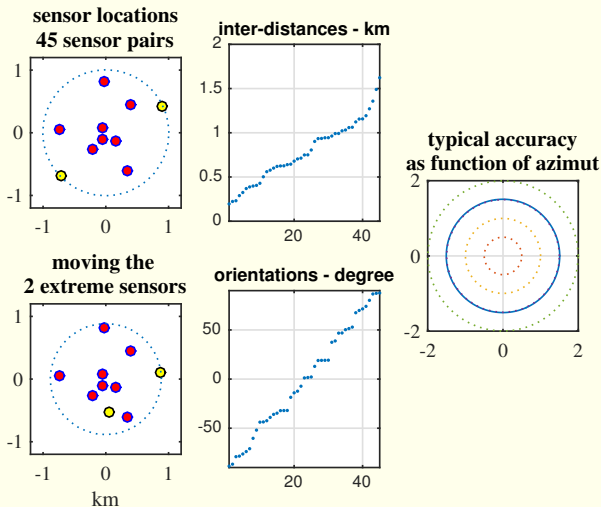
## Features for a station design



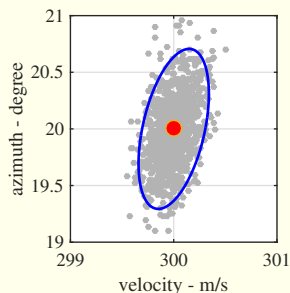
Elements of interest:

- the aperture
- the relative locations of the sensors
  - uniformity of ...
  - accuracy isotropy

## By moving the 2 most distant sensors



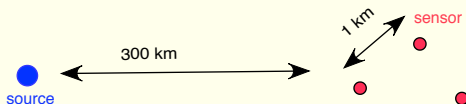
## CRB as an index of accuracy



- Depending on the noise we observe different couples of values (grey points).
- A good estimator has to provide a set of values located around the true value with a dispersion as low as possible.
- The CRB provides a lower bound for the dispersion.
- A good estimator converges asymptotically to the CRB.

- the CRB is used to determine the confidence region (ellipse)
- it is worth to notice that the CRB does depend on the true values of the parameters that are unknown. Usually we replace by the estimated value.

## Loss of coherence



- usually the sensors of the same station are very far from the source of interest, several hundreds of km compared to 1 km.
- however the signals arriving on the two sensors are not fully coherent. But in the absence of clear explanations a “black box” model is considered:

$$\log \text{MSC}(f) \approx -\beta f^2 \times d^2$$

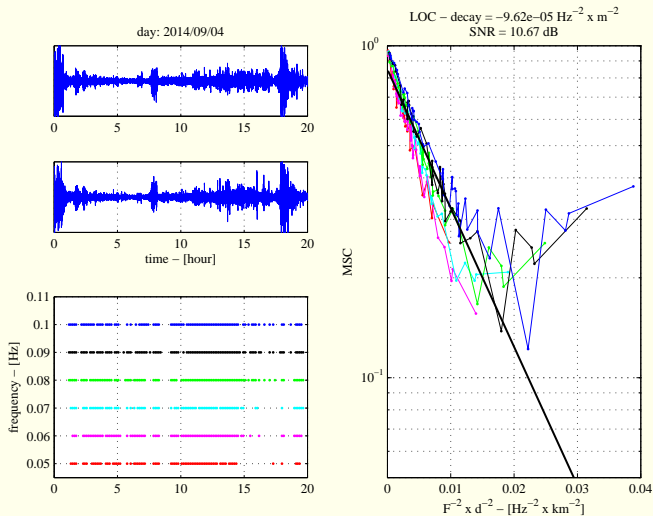
where  $d$  is the distance between deux points of observation,  $f$  the frequency and  $\beta$  a LOC decay factor.

This simple model does not take into account the orientation of the sensor axis w.r.t. the direction of arrivals.

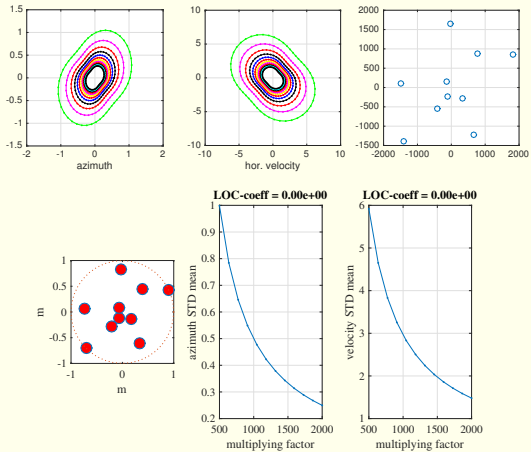
## Protocol

- For a given frequency in the selected bandwidth of interest  $B$  and for a given time window  $T$ , we perform the MSCs for each pairs of sensors. If the two closest sensors have an MSC over 0.8 in a certain T/F cell, we keep this T/F cell for all combinations of interdistances.
  - We average on the duration of the file.
- 
- Bandwidth  $[0.05 \quad 0.11]$  Hz,
  - Time window duration  $T = 500$  seconds,
  - Time duration about 20 hours, i.e. about 144 windows.
  - In the selected bandwidth the acceptance rate is ..

# IS37, with 10 sensors then 45 interdistances

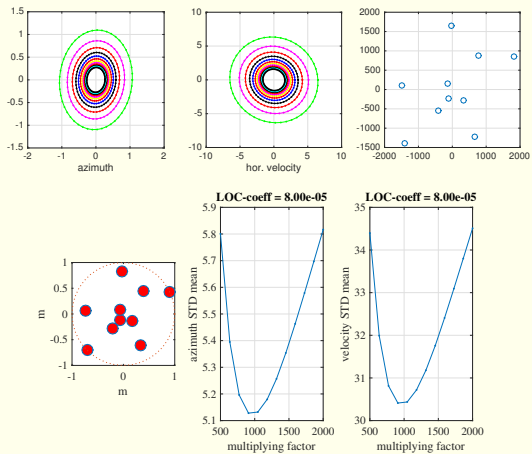


# No LOC





# with LOC



## Conclusion