

Course: Analysis of Algorithms

Code: CS33104

Branch: MCA -3rd Semester

Lecture 11 – Flow in Networks

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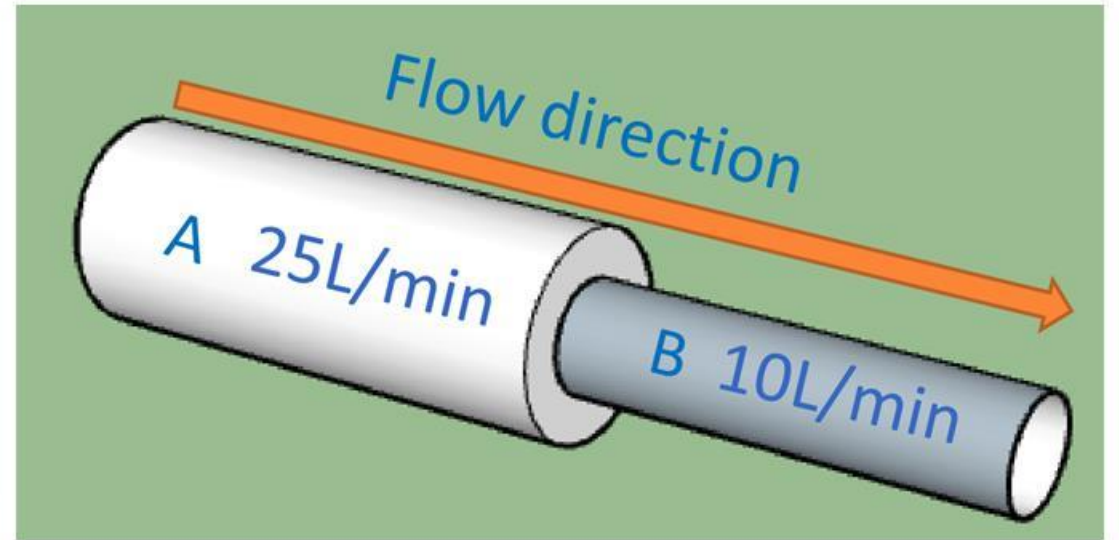
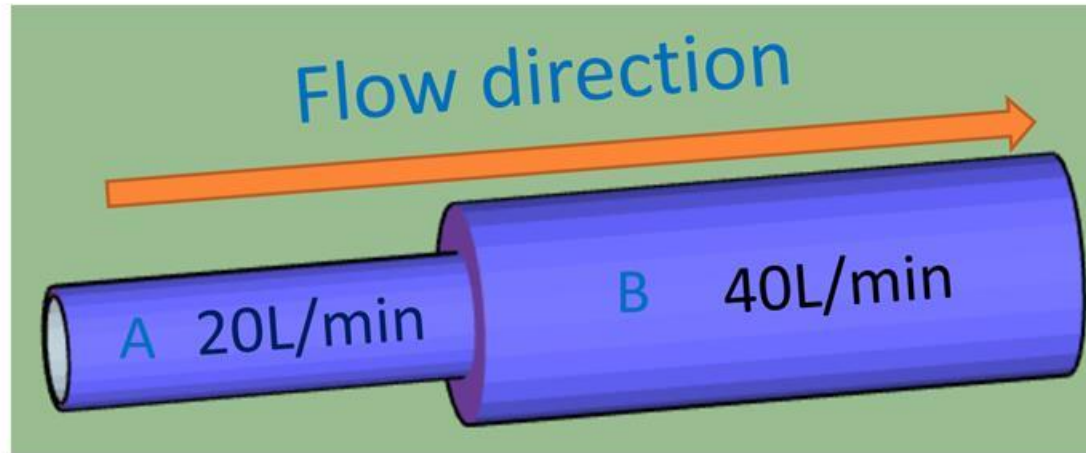
Flow in Networks

- Directed graph can be interpreted as a “flow network” and use it to answer questions about material flows.
 - Imagine a material coursing through a system from a source, where the material is produced, to a sink, where it is consumed.
 - The source produces the material at some steady rate, and the sink consumes the material at the same rate.
 - The “flow” of the material at any point in the system is intuitively the rate at which the material moves.
- Flow networks can model many problems, including
 - liquids flowing through pipes,
 - parts through assembly lines,
 - current through electrical networks, and
 - Information through communication networks.

Flow in Networks

- Each directed edge in a flow network as a conduit for the material.
- Each conduit has a stated capacity, given as a maximum rate at which the material can flow through the conduit, such as 200 gallons of liquid per hour through a pipe or 20 amperes of electrical current through a wire.
- Vertices are conduit junctions, and other than the source and sink, material flows through the vertices without collecting in them.
- In other words, the rate at which material enters a vertex must equal the rate at which it leaves the vertex.
- We call this property “flow conservation,” and it is equivalent to Kirchhoff’s current law when the material is electrical current.

Flow in Networks



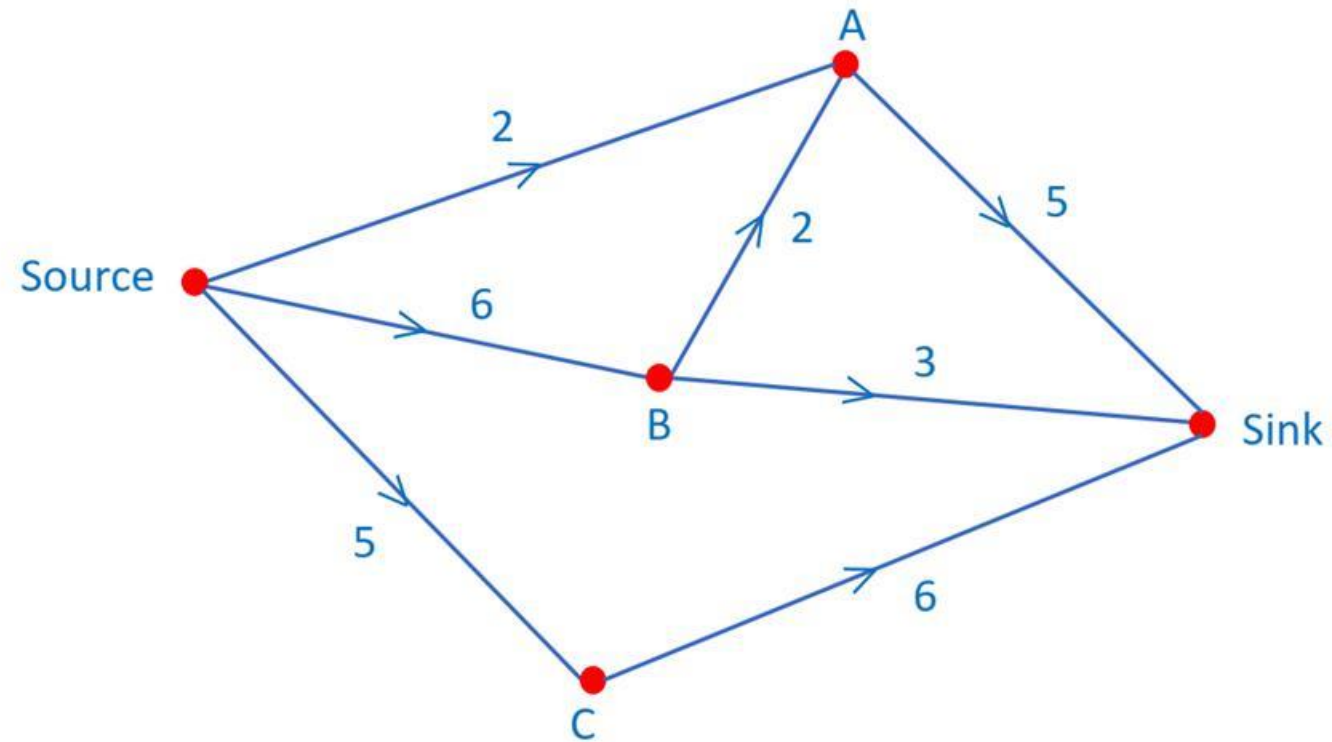
Maximum-flow problem

- In the maximum-flow problem, we wish to compute the greatest rate at which we can ship material from the source to the sink without violating any capacity constraints.
- It is one of the simplest problems concerning flow networks and, this problem can be solved by efficient algorithms.
- Moreover, we can adapt the basic techniques used in maximum-flow algorithms to solve other network-flow problems.
- Classical method of Ford and Fulkerson for finding maximum flows.
 - An application of this method, finding a maximum matching in an undirected bipartite graph

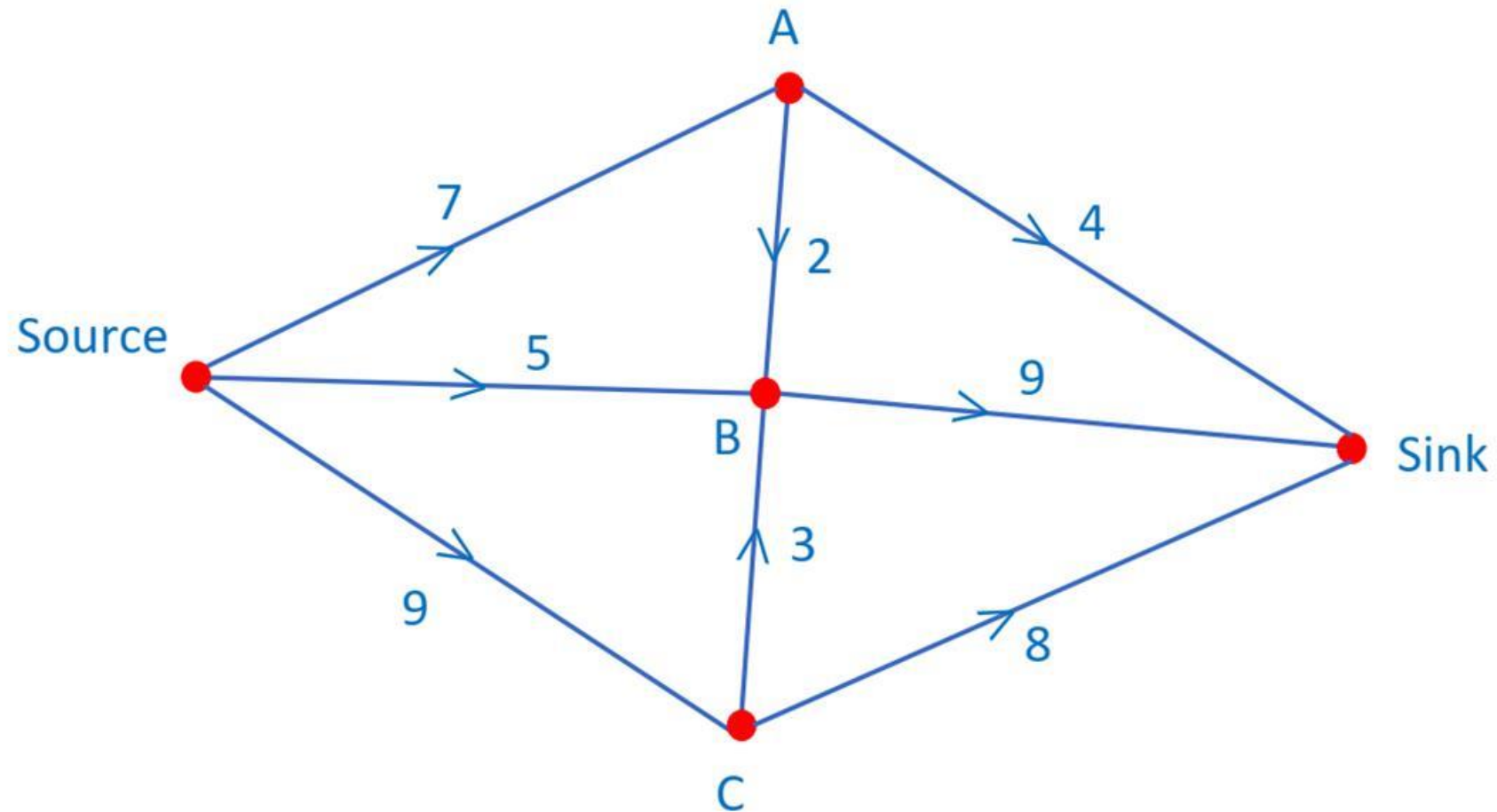
Flow networks and flows

- A **flow network** $G=(V, E)$ is a directed graph in which each edge $(u, v) \in E$ such that
 - Flowgraph: Directed graph with distinguished vertices s (source) and t (sink)
 - Capacities on the edges, $c(u,v) \geq 0$
- Problem, assign flows $f(u,v)$ to the edges such that:
 - $0 \leq f(u,v) \leq c(u,v)$
 - Flow is conserved at vertices other than s and t
 - Flow conservation: flow going into a vertex equals the flow going out
 - The flow leaving the source is as large as possible
 - Inflow is equal to outflow except source and sink

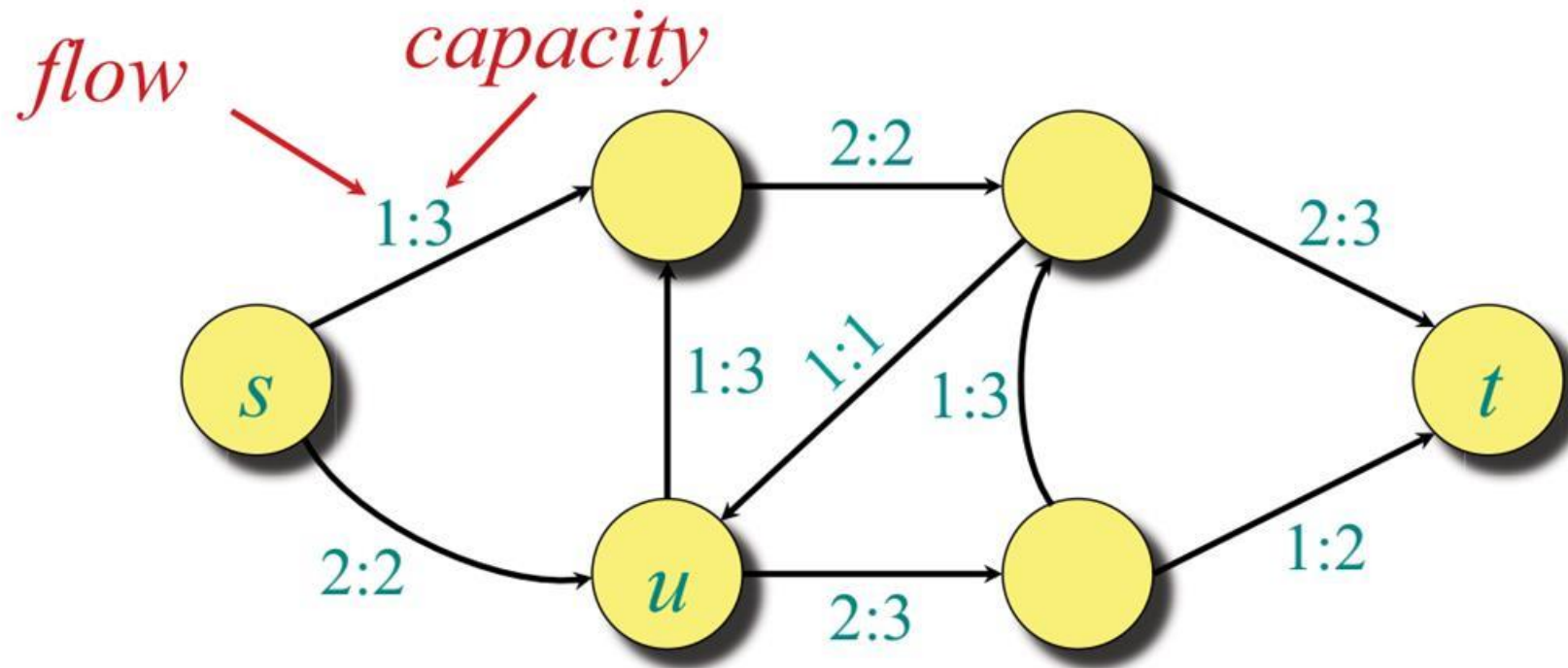
Flow networks and flows



Class Exercise #1



Flow networks and flows

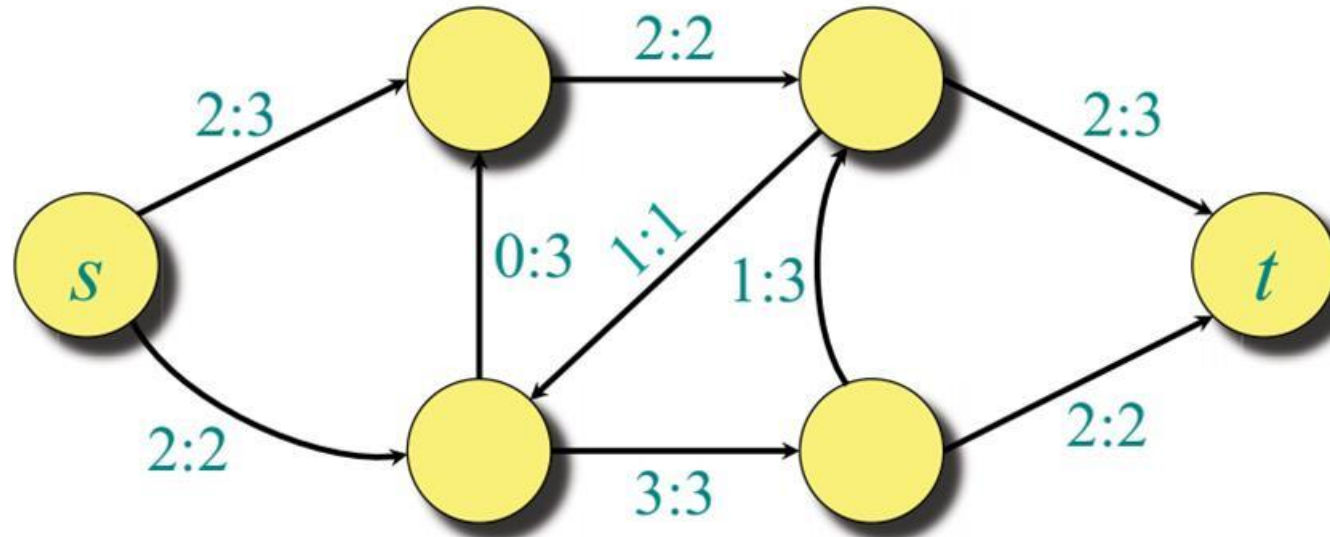


Flow conservation (like Kirchoff's law):

- Flow into u is $2 + 1 = 3$.
- Flow out of u is $1 + 2 = 3$.

The maximum-flow problem

- **Maximum-flow problem:** Given a flow network G , find a flow of maximum value on G .



The value of the maximum flow is 4

Flow in Networks

- Ford-Fulkerson method - 1956
 - $O(E f^*)$
- Edmond Karp method – Early 1970's
 - $O(E^2 V)$
- Dinic's method - 1970
 - $O(E V^2)$
- King, Rao , Tarjan method – 2011
 - $O(E \log_{E/V} V)$
- Orlin method-2013
 - $O(VE)$

Ford-Fulkerson method

FORD-FULKERSON-METHOD(G, s, t)

- 1 initialize flow f to 0
- 2 **while** there exists an augmenting path p in the residual network G_f
- 3 augment flow f along p
- 4 **return** f

Residual networks

- Given a flow network G and a flow f , the residual network G_f consists of edges with capacities that represent how we can change the flow on edges of G .
- An edge of the flow network can admit an amount of additional flow equal to the edge's capacity minus the flow on that edge.
- If that value is positive, we place that edge into G_f with a “residual capacity” of $c_f(u,v) = c(u,v) - f(u,v)$.
- The only edges of G that are in G_f are those that can admit more flow; those edges (u,v) whose flow equals their capacity have $c_f(u,v) = 0$, and they are not in G_f .

Residual networks

- As an algorithm manipulates the flow, with the goal of increasing the total flow, it might need to decrease the flow on a particular edge.
- In order to represent a possible decrease of a positive flow $f(u, v)$ on an edge in G , we place an edge (v, u) into G_f with residual capacity $c_f(v, u) = f(u, v)$ that is, an edge that can admit flow in the opposite direction to (u, v) , at most canceling out the flow on (u, v) .
- Sending flow back along an edge is equivalent to *decreasing* the flow on the edge, which is a necessary operation in many algorithms.

Residual networks

More formally, suppose that we have a flow network $G = (V, E)$ with source s and sink t . Let f be a flow in G , and consider a pair of vertices $u, v \in V$. We define the *residual capacity* $c_f(u, v)$ by

$$c_f(u, v) = \begin{cases} c(u, v) - f(u, v) & \text{if } (u, v) \in E, \\ f(v, u) & \text{if } (v, u) \in E, \\ 0 & \text{otherwise.} \end{cases}$$

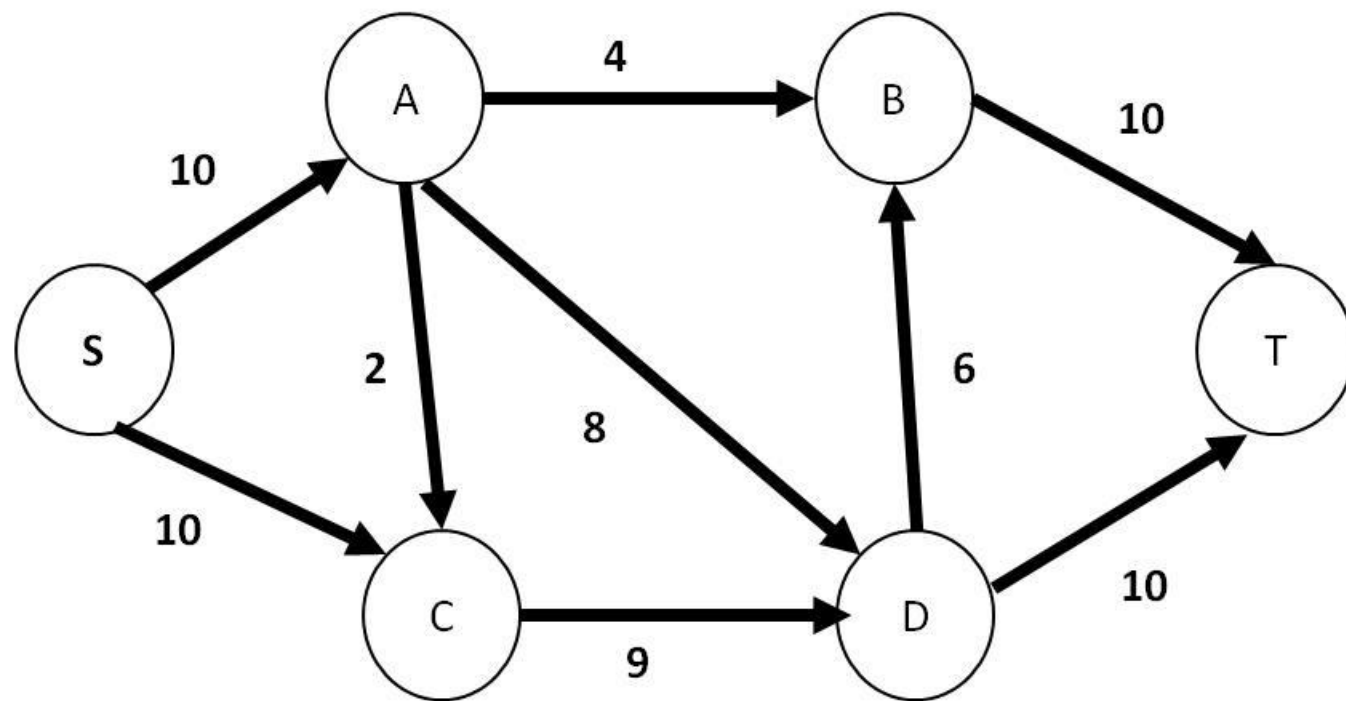
Residual networks

- Pushing flow on the reverse edge in the residual network is also known as ***cancellation***.
- For example, if we send 5 crates of hockey pucks from u to v and send 2 crates from v to u , we could equivalently (from the perspective of the final result) just send 3 crates from u to v and none from v to u .
- Cancellation of this type is crucial for any maximum-flow algorithm.

Augmenting paths

- Given a flow network $G = (V, E)$ and a flow f , an **augmenting path** p is a simple path from s to t in the residual network G_f .
- By the definition of the residual network, we may increase the flow on an edge (u, v) of an augmenting path by up to $c_f(u, v)$ without violating the capacity constraint on whichever of (u, v) and (v, u) is in the original flow network G .
- Consider
 - Non Full Forward Edge
 - Non Zero Backward Edge

Example



FORD-FULKERSON ALGORITHM

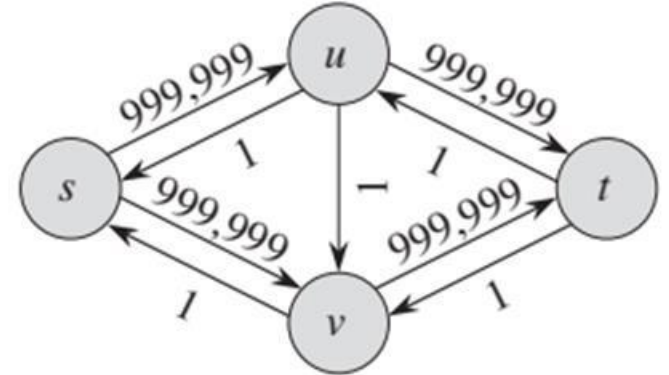
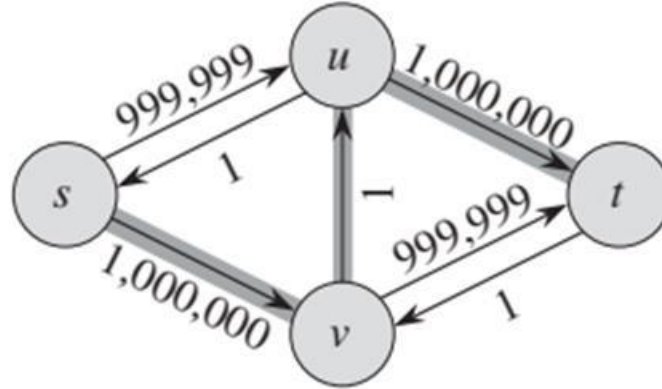
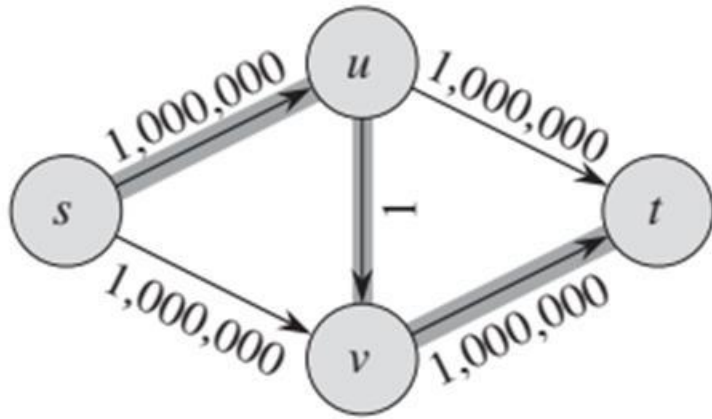
FORD-FULKERSON(G, s, t)

```
1  for each edge  $(u, v) \in G.E$ 
2       $(u, v).f = 0$ 
3  while there exists a path  $p$  from  $s$  to  $t$  in the residual network  $G_f$ 
4       $c_f(p) = \min \{c_f(u, v) : (u, v) \text{ is in } p\}$ 
5      for each edge  $(u, v)$  in  $p$ 
6          if  $(u, v) \in E$ 
7               $(u, v).f = (u, v).f + c_f(p)$ 
8          else  $(v, u).f = (v, u).f - c_f(p)$ 
```

FORD-FULKERSON ALGORITHM

- If f^* denotes a maximum flow in the transformed network, then a straightforward implementation of FORD-FULKERSON executes the **while** loop of lines 3–8 at most f^* times, since the flow value increases by at least one unit in each iteration.
- The time to find a path in a residual network is therefore $O(V + E') = O(E)$, if we use either depth-first search or breadth-first search.
- Each iteration of the **while** loop thus takes $O(E)$ time, as does the initialization in lines 1–2, making the total running time of the FORD-FULKERSON algorithm $O(E f^*)$

FORD-FULKERSON ALGORITHM

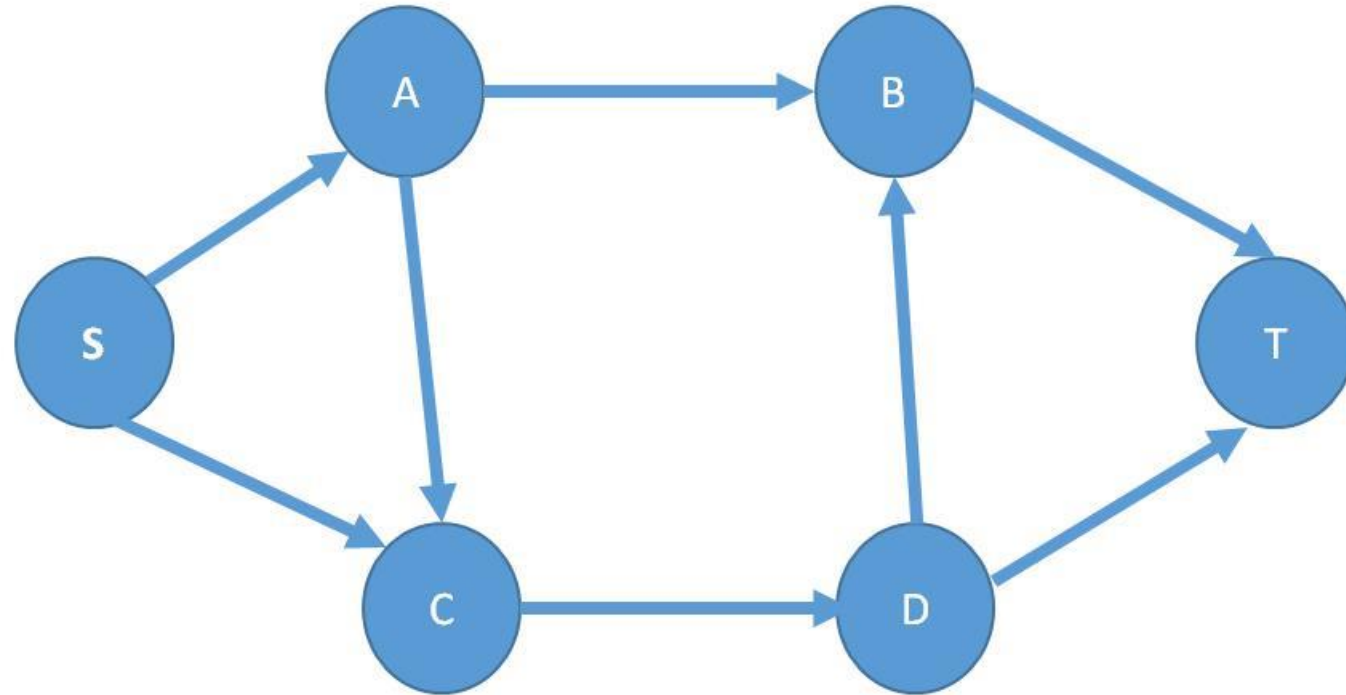


Choosing the augmenting path $s \rightarrow u \rightarrow v \rightarrow t$ in the odd-numbered iterations and the augmenting path $s \rightarrow v \rightarrow u \rightarrow t$ in the even-numbered iterations, leads to perform a total of 2,000,000 augmentations, increasing the flow value by only 1 unit in each.

Edmond Karp Method

- Disadvantages of Ford-Fulkerson method
 - Not determined how to choose an augmented path
 - It is observed that choosing an augmented path using DFS makes the situation worst.
 - It is also observed that choosing an augmented path using BFS makes the situation always better.
- Edmonds-Karp algorithm implemented based on Ford-Fulkerson method by applying BFS to choose the augmenting path as a *shortest* path from s to t in the residual network, where each edge has unit distance (weight).

Edmond Karp Method



Edmond Karp Method

1. $f = 0$;
2. $\text{res_graph} = \text{net_graph}$
3. while res_graph contains an $s - t$ path P do:
 4. Suppose P be an $s - t$ path in the residual_graph with of edges.
 5. $P = \text{Breadth-First-Search}(C, E, s, t, F)$
 6. Augment maximum_flow using P .
 7. $u = P[v]$
 8. $F[u, v] = F[u, v] - m$
 9. Update residual_graph
 10. $F[v, u] = F[v, u] + m$
 11. $v = u$
12. end while
13. return maximum_flow

Edmond Karp Method

- Because there are $O(|E|)$ total pairs of vertices that can, for the edge (u, v) , become critical $O(|V|)$ times, the total number of iterations that Edmonds-Karp can go through is $O(|V| \cdot |E|)$.
- Total Iterations is $O(VE)$, where V -vertices and E -Edges
- The time to find a path in a residual network is therefore $O(V + E') = O(E)$, if we use breadth-first search.
- Total time complexity = $O(VE^2)$

Dinic's method

- Dinic's method includes construction of level graphs and residual graphs and finding of augmenting paths along with blocking flow.
- Level graph is one where value of each node is its shortest distance from source.
- Blocking flow includes finding the new path from the bottleneck node.
- Residual graph and augmenting paths are same as earlier discussed.

Edmond Karp Method

- <https://www.educative.io/answers/what-is-the-edmonds-karp-algorithm>
- <https://jamieheller.github.io/theory.html>

Dinic's method

function: DinicMaxFlow(Graph G, Node S, Node T):

 Initialize flow in all edges to 0, $F = 0$

 Construct level graph

 while (there exists an augmenting path in level graph):

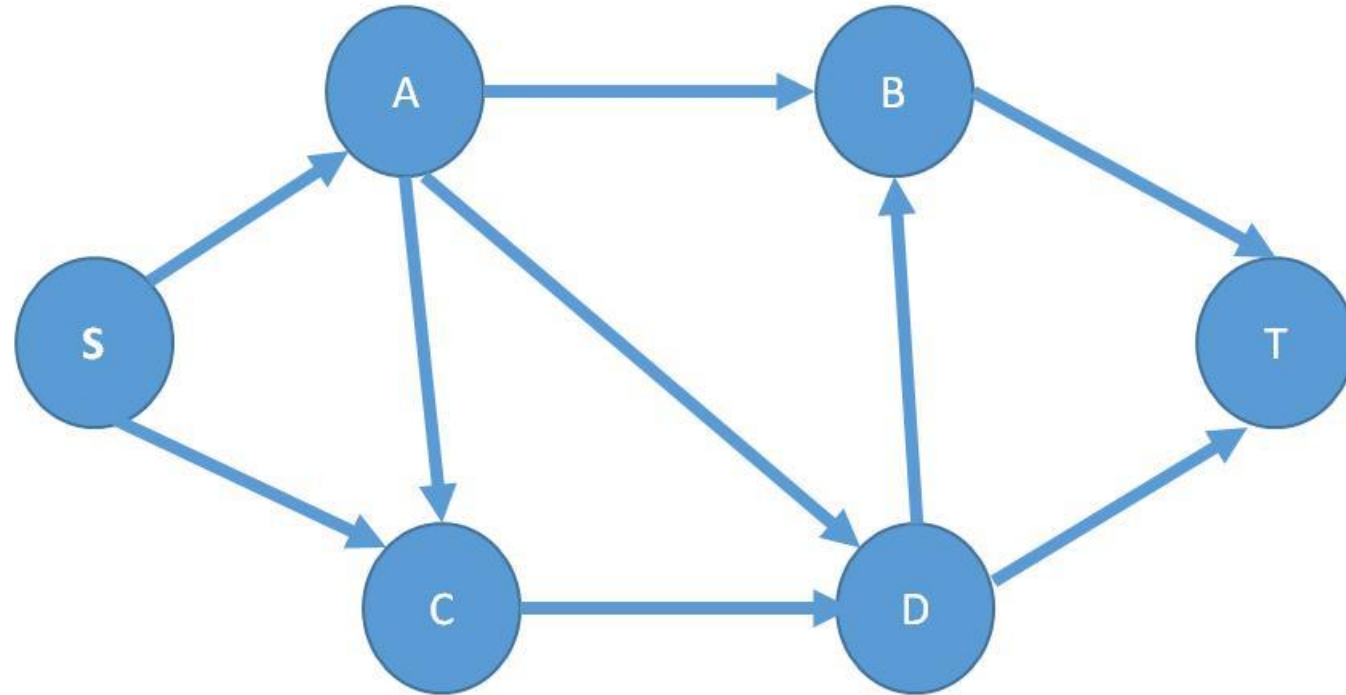
 find blocking flow f in level graph

$F = F + f$

 Update level graph

 return F

Dinic's method : Example



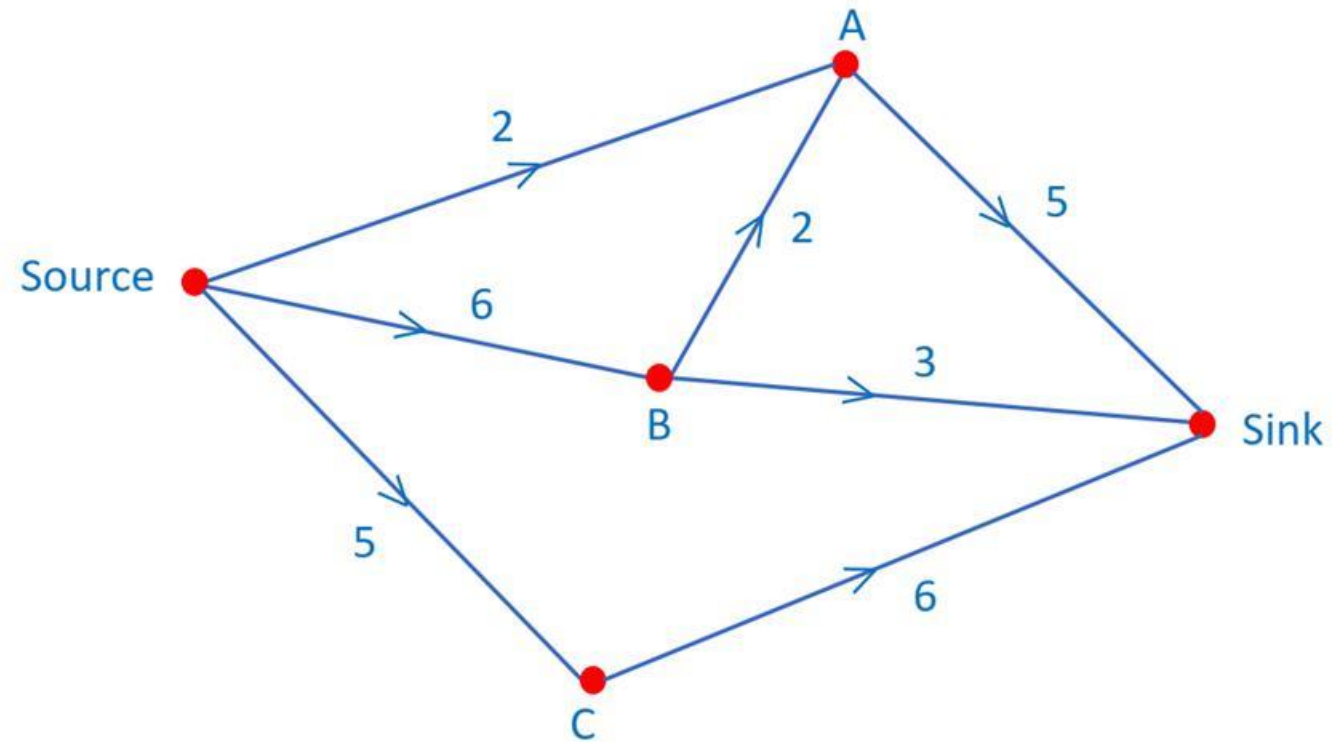
Dinic's method

- The number of layers in each blocking flow increases by at least 1 each time and thus there are at most $V-1$, blocking flows in the algorithm.
 - the level graph G_L can be constructed by BFS $O(E)$ time.
 - a blocking flow in the level graph G_L can be found in $O(VE)$.
 - Running time $O(E+VE)=O(VE)$.
- Total running time is $O((V-1) * VE)=O(V^2E)$

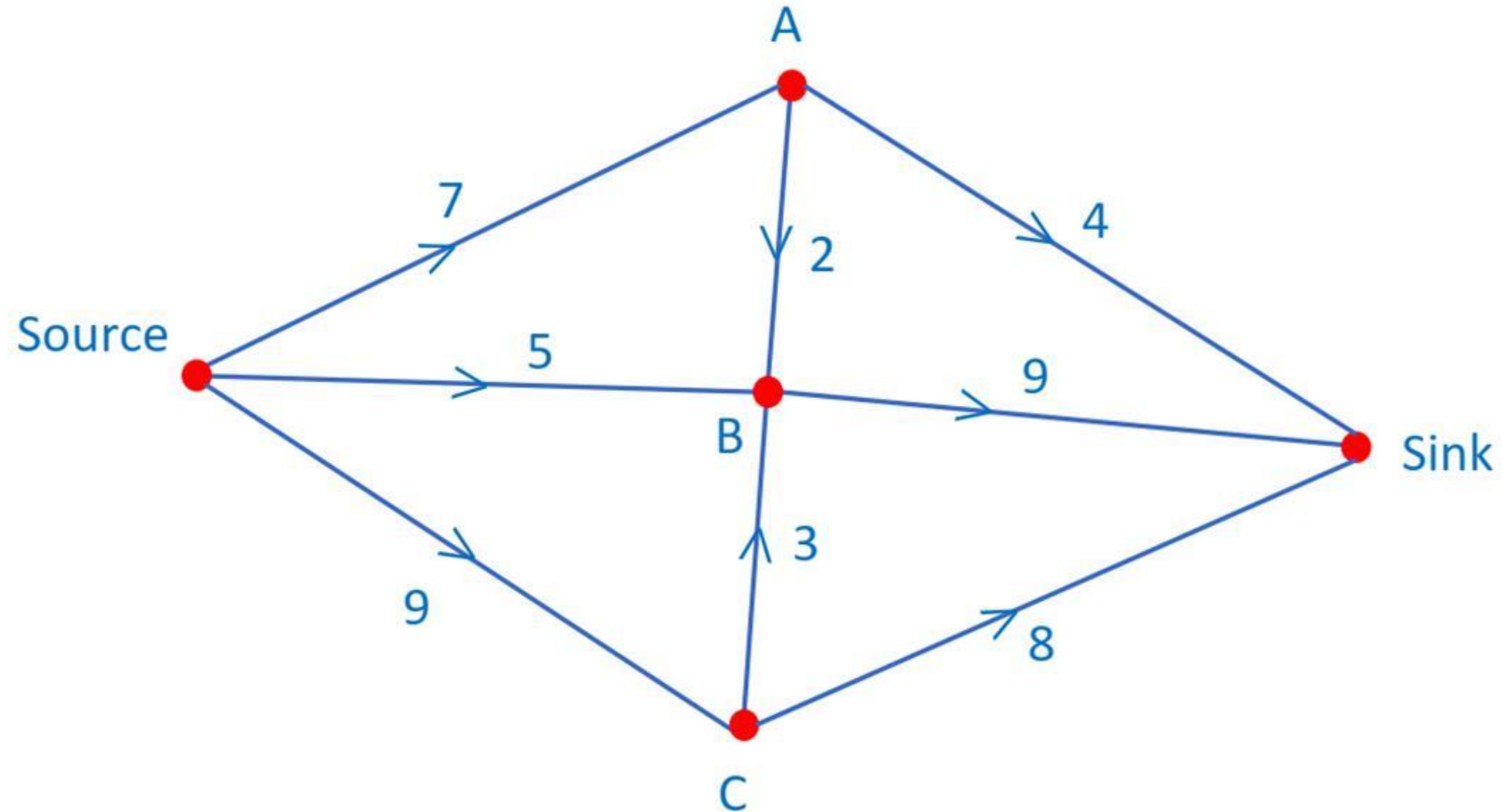
Cuts in a graph

- A **cut**(S, T) of flow network $G = (V, E)$ is a partition of V into S and $T = V - S$ such that $s \in S$ and $t \in T$.
- In other words, Cut: Partition of V into disjoint sets S, T with s in S and t in T .
- A **minimum cut** of a network is a cut whose capacity is minimum over all cuts of the network.
- There exists a flow which has the same value of the minimum cut
- If we want to find a minimum cut, we begin by looking for a maximum flow.

Flow networks and flows



Class Exercise #1



Latest Research Paper Assignments – Phase 2

- **Application: Healthcare Management using Blockchain**
- Explore papers that are recently published from 2021-2022 and 2023 from IEEE, ACM, Science Direct, Springer and other SCI Journals.
- Prepare the report on the following terms and submit
 - Paper Title
 - Problem Title
 - Complexity of the problem
 - Advantages of the problem
 - Limitations of the problem
 - Brief summary of the overall paper in your own words (approx 50-100)