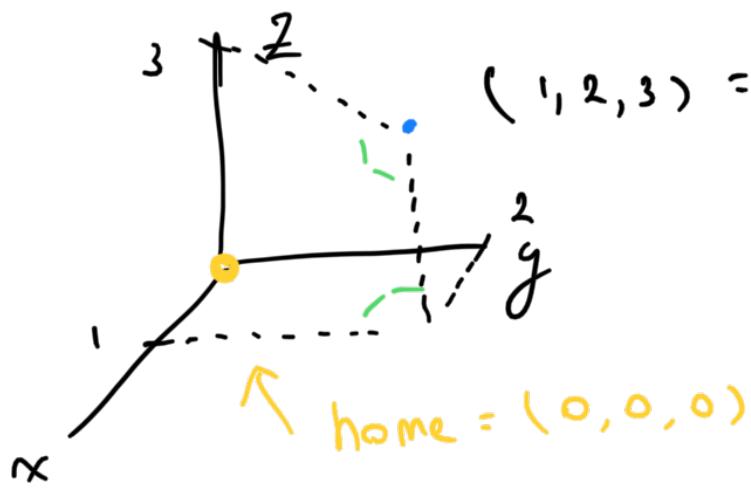


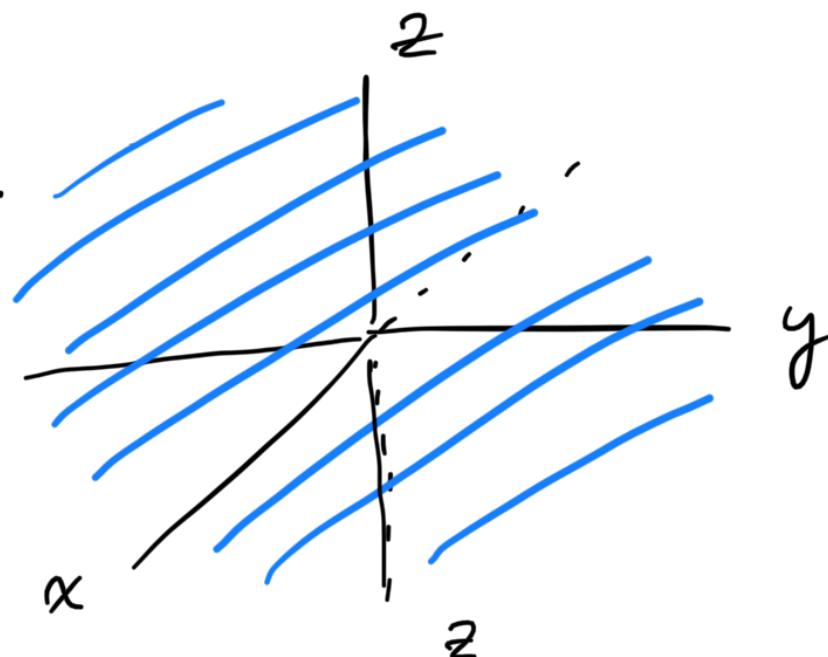
12.1 : 3D coordinates



describes all points in 3-space uniquely.

Coordinate planes :

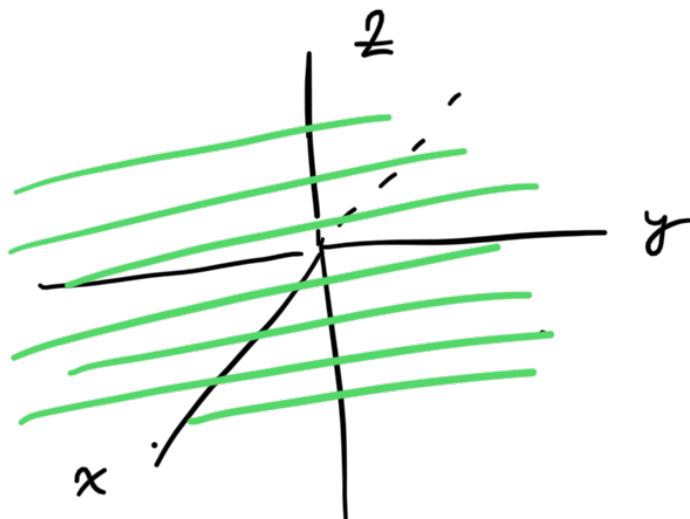
$$x = 0 \quad \text{blue}$$



$$y = 0 \quad \text{red}$$

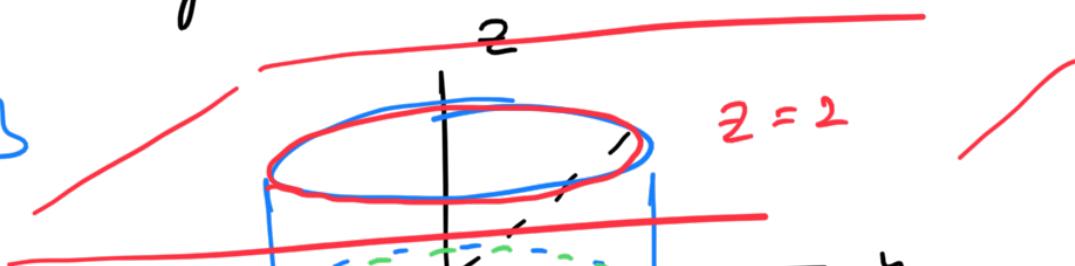


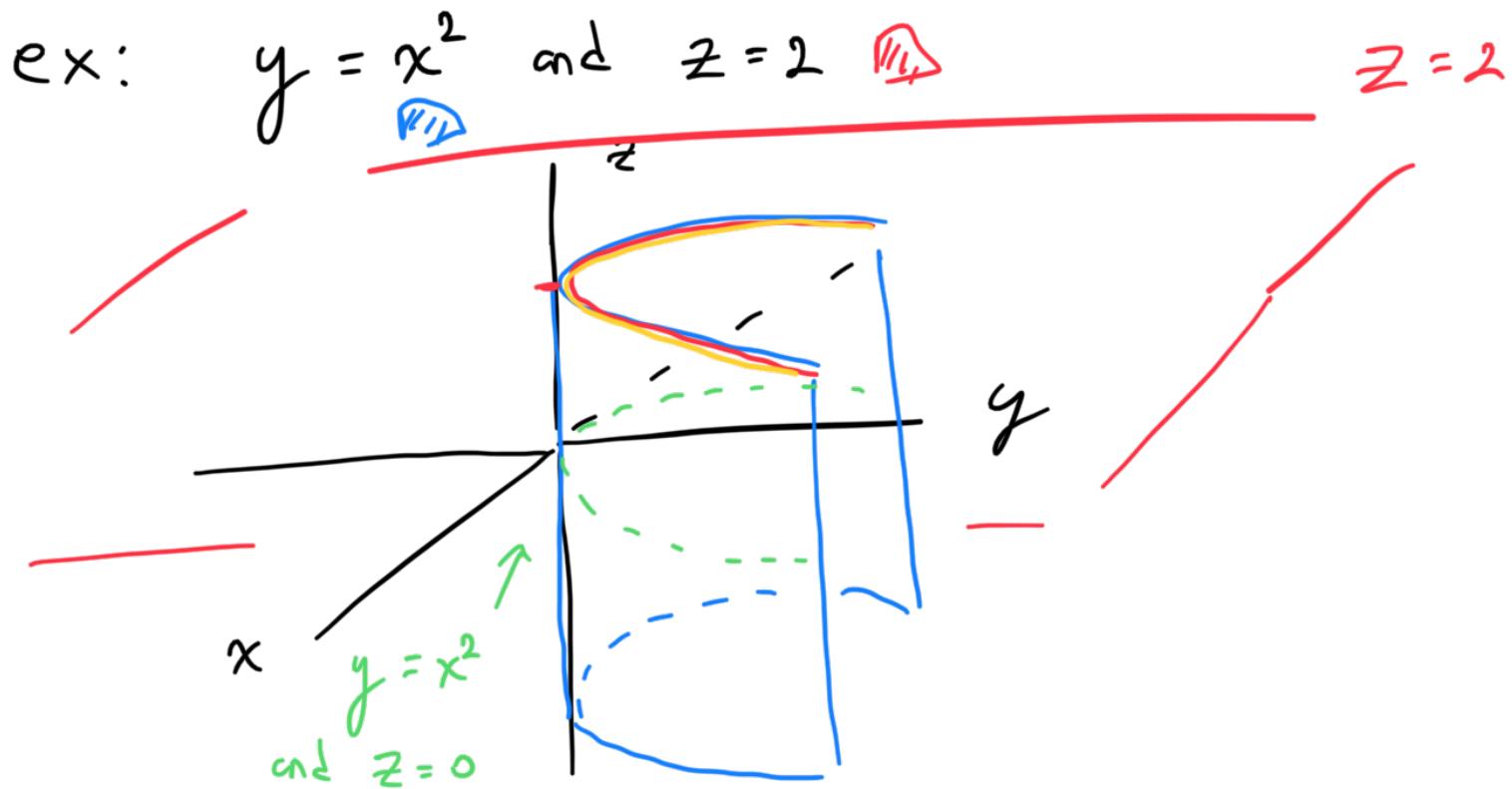
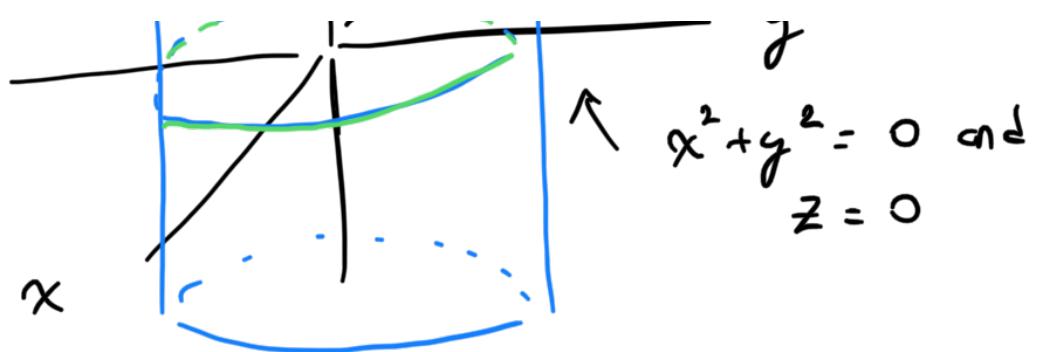
$$z = 0 \quad \text{green}$$



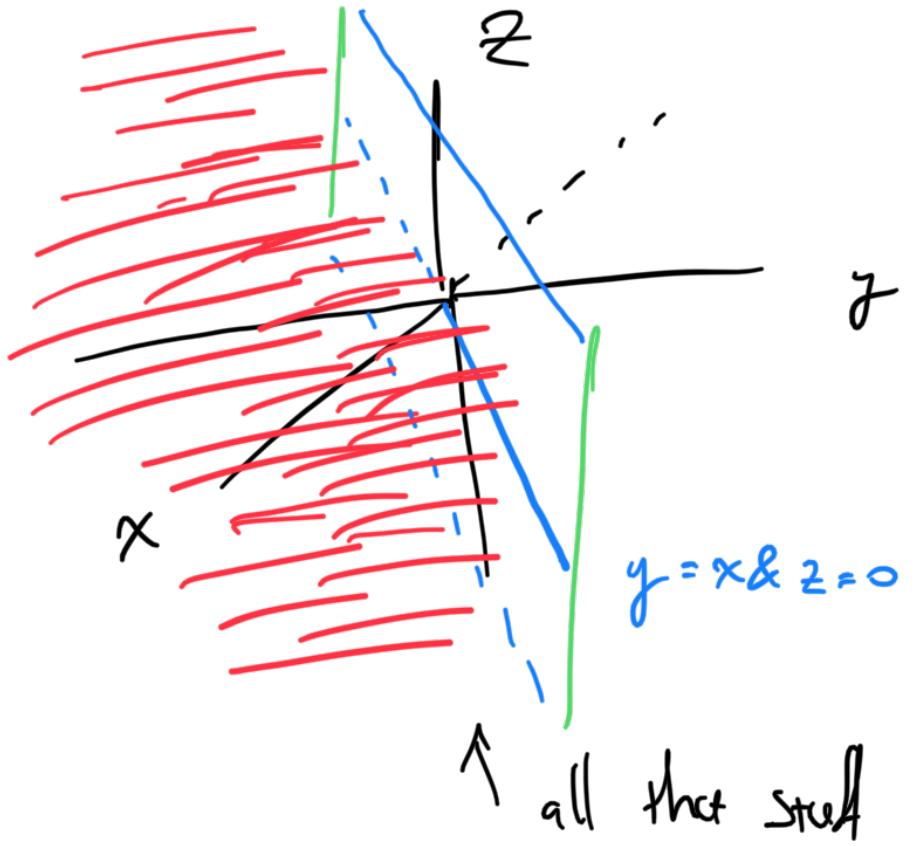
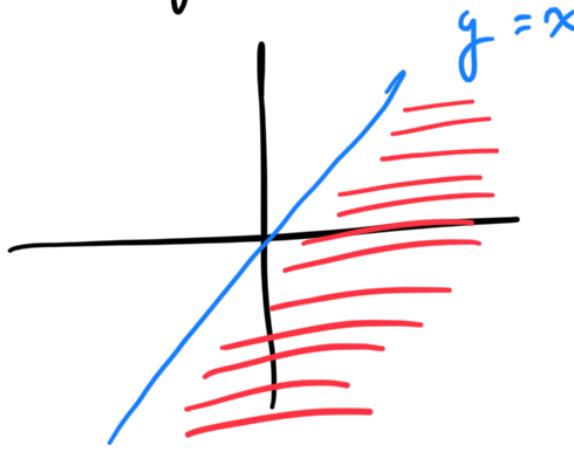
What about $x^2 + y^2 = 9$ and $z = 2$

$$x^2 + y^2 = 9 \quad \text{blue}$$



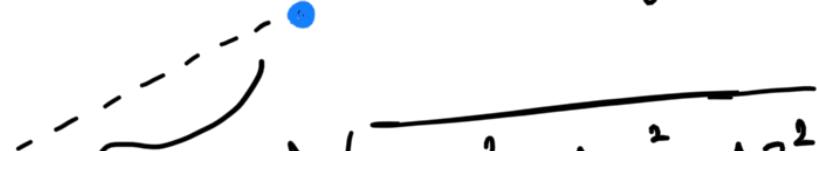


ex: $y \leq x$ in 2D



Distance in 3 space?

$$Q = (x_2, y_2, z_2)$$

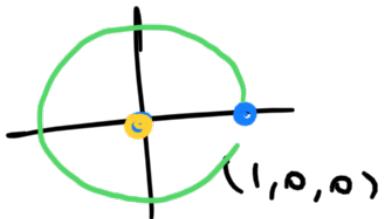


$$\Delta w = w_2 - w_1$$

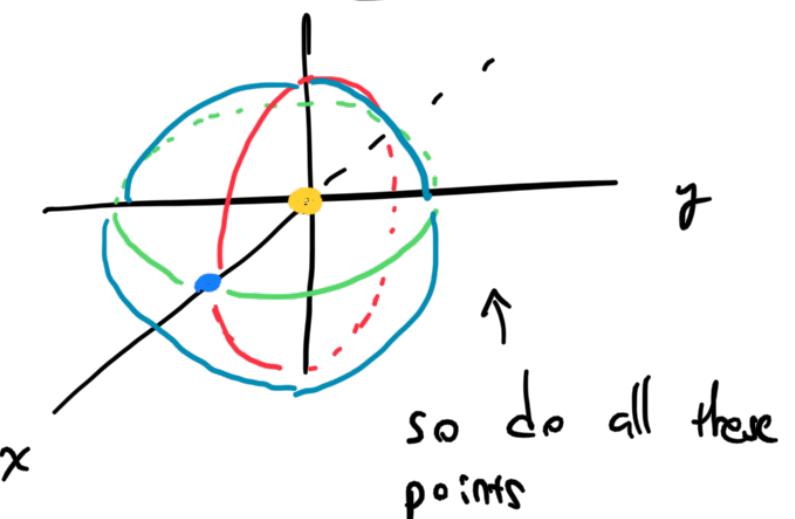
$$d = \sqrt{\Delta x^2 + \Delta y^2 + \Delta z^2}$$

$$P = (x_1, y_1, z_1)$$

$$\text{ex: } d((0,0,0), (1,0,0)) = \sqrt{\Delta^2 + \Delta^2 + \Delta^2} = \sqrt{1} = 1$$



all same distance
from $(0,0,0)$



so do all these
points

Observation: The set of all points a fixed distance
from a fixed point = Sphere!

$$\text{algebraically: } \sqrt{(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2} = r$$

$$\Leftrightarrow (x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2 = r^2$$

point (x_0, y_0, z_0) is center and r is the radius.

ex: Find the radius and center of

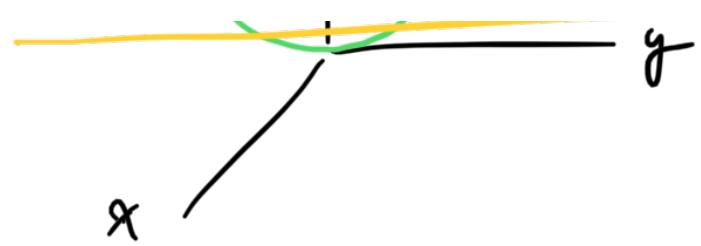
$$x^2 + y^2 + z^2 - 4z = 0 \quad -\frac{-4}{2} / 2 \rightarrow -2 \rightarrow r^2 = 4$$

$$x^2 + y^2 + z^2 - 4z = 0 \quad \text{center} = (0, 0, 2)$$

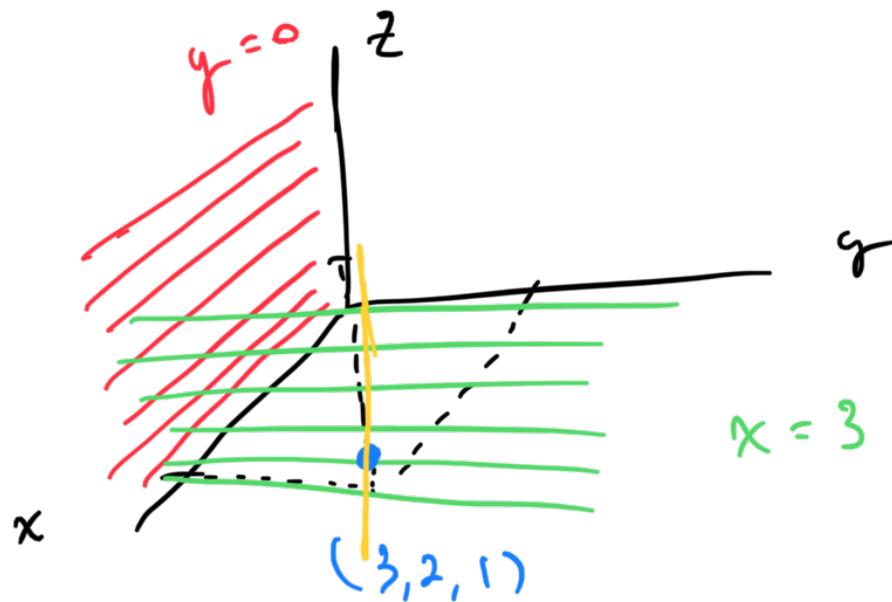
$$x^2 + y^2 + z^2 - 4z + 4 = 4$$

$$x^2 + y^2 + (z - 2)^2 = 4 \quad \text{radius} = 2$$





Ex: Find plane through $(3, 2, 1)$
perpendicular to xz -plane.



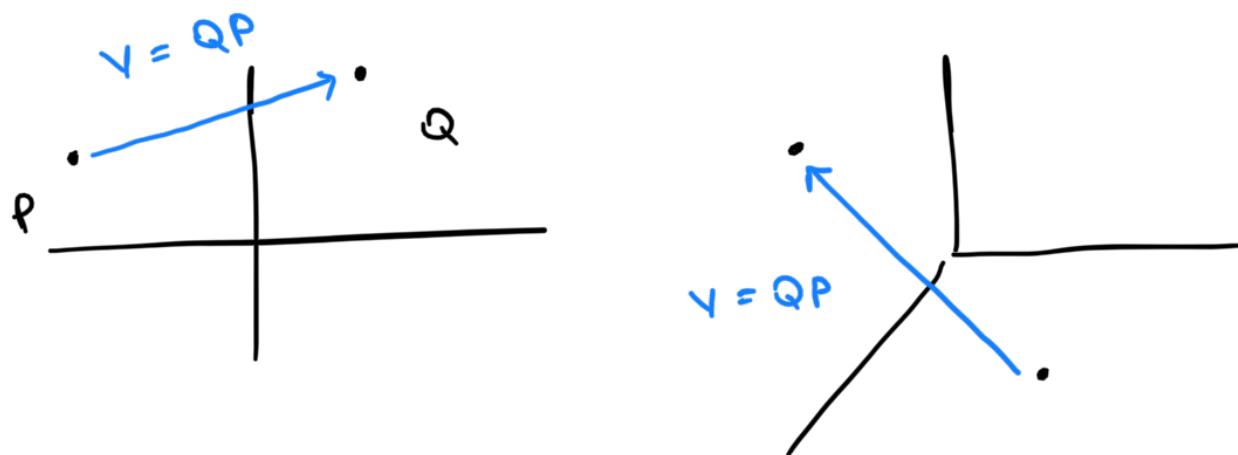
Line through $(3, 2, 1)$ parallel to \hat{z} -axis?

$$x = 3 \text{ and } y = 2$$

12.2 Vectors

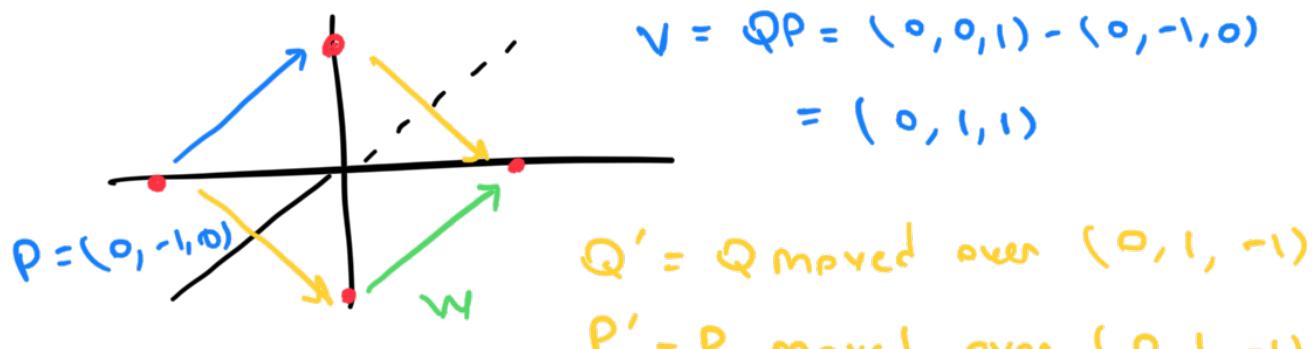
Vectors algebraically $v = (x, y) \in \mathbb{R}^2$ or $v = (x, y, z) \in \mathbb{R}^3$

Represent direction and magnitude



Book uses $< , >$ but I'm going to avoid that, just
stylistic choice.

Ex: $Q = (0, 0, 1)$



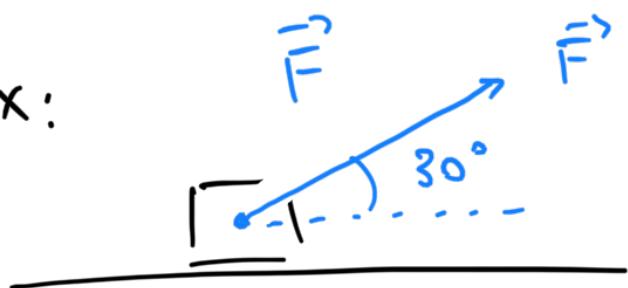
$$w = Q'P' = (0,1,0) - (0,0,-1)$$

$$= (0,1,1)$$

Every vector $v \in \mathbb{R}^3$ breaks up into components

$$v = (v_x, v_y, v_z)$$

ex:



$$\vec{F} \text{ is } 20 \text{ lb force then}$$

$$\vec{F} = (20 \cos 30^\circ, 20 \sin 30^\circ)$$

$$= (20 \cdot \frac{\sqrt{3}}{2}, 20 \cdot \frac{1}{2})$$

$$= (10\sqrt{3}, 10) \text{ lb}$$

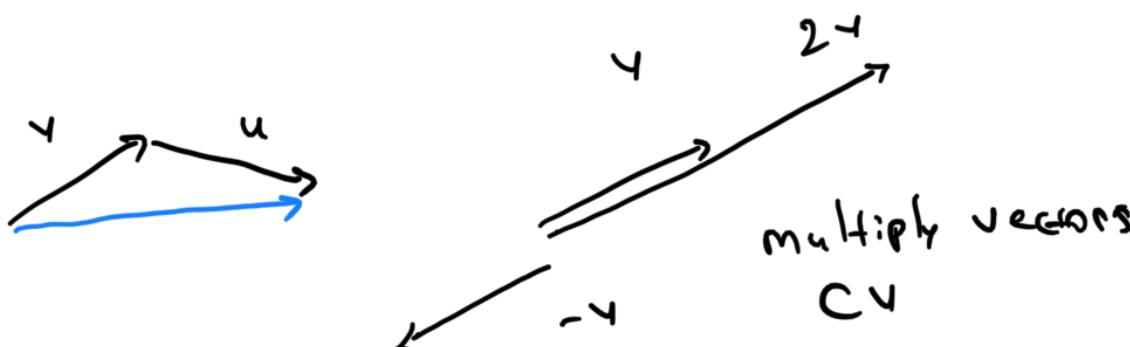
$$F_x = 10\sqrt{3} \quad F_y = 10 \quad (\text{lbs})$$

Each vector has a direction and magnitude (except 0)

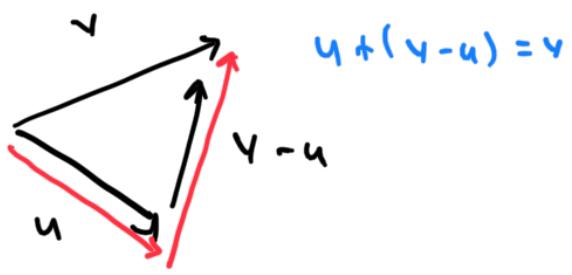
in previous example, $|F| = 20$, or $|v| = \sqrt{2}$

$$|v| = \sqrt{v_x^2 + v_y^2 + v_z^2} \leftarrow \text{magnitude}$$

Vector algebra:



get all nice things



UWOT, Pg. 718

$$u + v = v + u$$

$$(u + v) + w = v + (u + w)$$

$$u + 0 = u$$

$$u + (-u) = 0$$

$$0u = 0$$

$$1u = u$$

$$a(bu) = (ab)u \quad a(u+v) = au+av$$

$$(a+b)u = au + bu$$

$$= au + uv$$

P coordinate-wise
midpoint = $\frac{1}{2}(Q+P)$

direction:

$$\frac{v}{|v|} = \text{direction of } v$$

makes sense for all
 $v \neq 0$.

Mention some notation:
 $\vec{F} = (F_x, F_y, F_z)$
 $= F_x \hat{i} + F_y \hat{j} + F_z \hat{k}$

$$\hat{i} = (1, 0, 0)$$

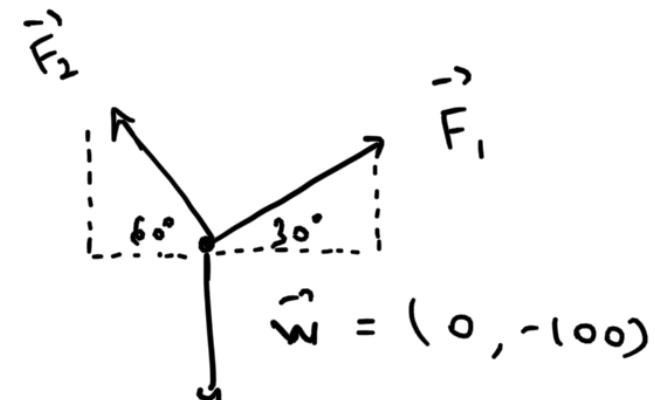
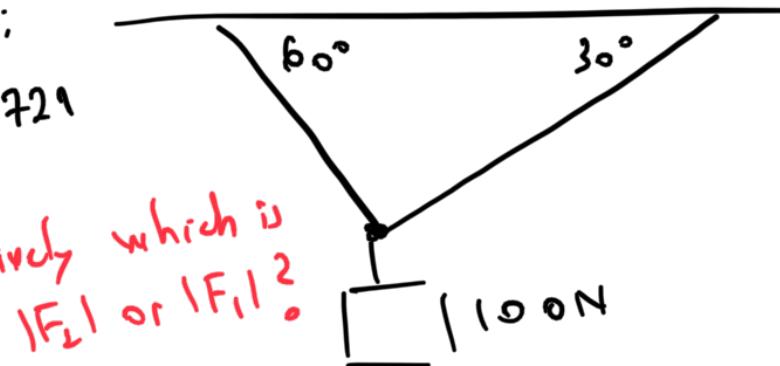
$$\hat{j} = (0, 1, 0)$$

$$\hat{k} = (0, 0, 1)$$

e.g.:

pg. 721

Intuitively which is
bigger $|F_1|$ or $|F_2|$?



Find magnitudes

$$(\Rightarrow) \vec{F}_1 + \vec{F}_2 + \vec{w} = \vec{0}$$

$$(F_{1x}, F_{1y}) + (F_{2x}, F_{2y}) = (0, +100)$$

$$F_{1x} + F_{2x} = 0$$

$$F_{1x} = |F_1| \cos 30^\circ$$

$$F_{1y} + F_{2y} \approx +100$$

$$F_{1y} = |F_1| \sin 30^\circ$$

$$F_{2x} = -|F_2| \cos 60^\circ$$

$$F_2 y = |F_2| \sin 60^\circ$$

$$|F_1| \left(\frac{\sqrt{3}}{2}\right) - |F_2| \left(\frac{1}{2}\right) = 0 , \quad |F_1| = \frac{1}{\sqrt{3}} |F_2|$$

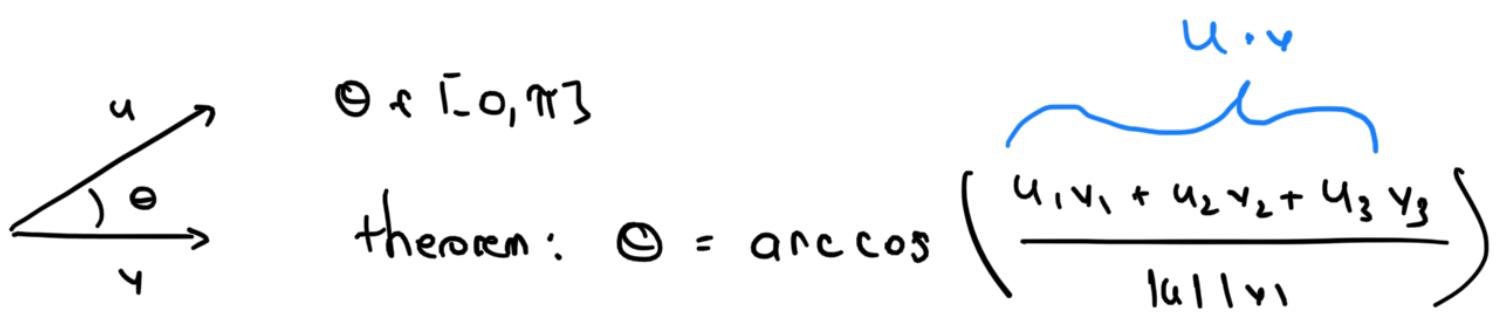
$$|F_1| \left(\frac{1}{2}\right) + |F_2| \left(\frac{\sqrt{3}}{2}\right) = 100 \quad \leftarrow$$

$$\left(\frac{1}{2\sqrt{3}} + \frac{\sqrt{3}}{2} \right) |F_2| = 100 \\ |F_2| = 100 / \text{mess}$$

$$|F_1| = \frac{1}{\sqrt{3}} |F_2|$$

12.3: Dot Product

Given two vectors $u, v \in \mathbb{R}^3$, how to find $\angle(u, v)$?



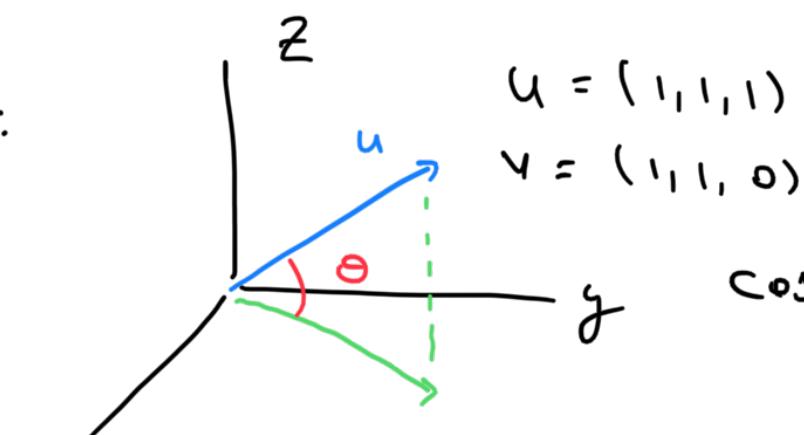
$$\theta \in [0, \pi]$$

theorem: $\theta = \arccos \left(\frac{u \cdot v}{|u| |v|} \right)$

$u \cdot v = u_1 v_1 + u_2 v_2 + u_3 v_3 \in \mathbb{R}$ no + another vector.

Another way of saying this is $\cos \theta = \frac{u \cdot v}{|u| |v|}$

ex:



$$\cos \theta = \frac{u \cdot v}{|u| |v|} = \frac{1+1+0}{\sqrt{3} \sqrt{2}}$$

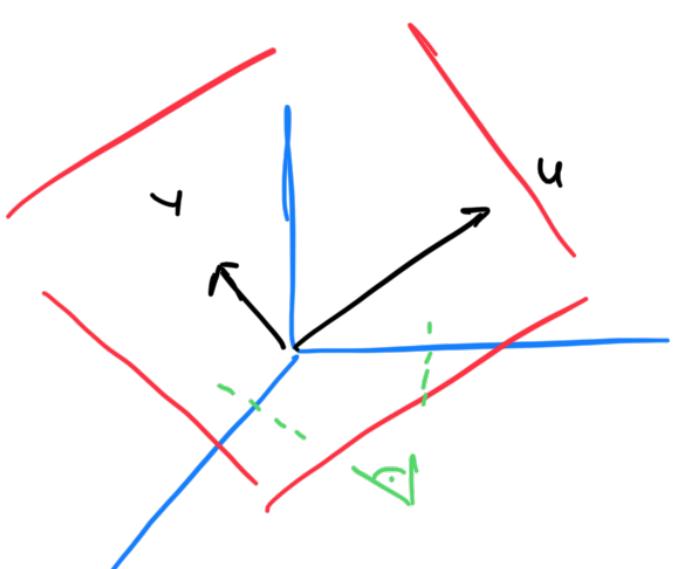
$$= \frac{\sqrt{2}}{\sqrt{3}}$$

$$\theta = \arccos \left(\frac{\sqrt{2}}{\sqrt{3}} \right) > 45^\circ \text{ or } < 45^\circ \\ \approx 35^\circ \quad \text{or } = 45^\circ ?$$

$$\theta = \arctan\left(\frac{|w|}{|v|}\right) \text{ more } v \text{ than } w.$$

$w = (0, 0, 1)$
 $v = (1, 1, 0)$

Why does $\cos \theta = \frac{u \cdot v}{\|u\| \|v\|}$? Use some trig on this picture.



law of cosines
 $|u-v|^2 = |u|^2 + |v|^2 - 2|u||v|\cos\theta$

Dot product gives us a nice way to see if two vectors are perpendicular (orthogonal).

$$\cos \theta = \frac{u \cdot v}{\|u\| \|v\|} = 0 \text{ iff } \underline{u \cdot v = 0}.$$

If want to see if $(1, 1)$ and $(1, -1)$ \perp just check with dot product!

Nice algebra : $u \cdot v = v \cdot u$ $(cu) \cdot v = c(u \cdot v)$

$$u \cdot (v+w) = u \cdot v + u \cdot w$$

$$u \cdot u = \|u\|^2 \quad \vec{0} \cdot u = 0$$

ex:



f/R vector

\sim \sim

$\text{proj}_{uv} = (\|v\| \cos \theta) (\text{direction } u)$

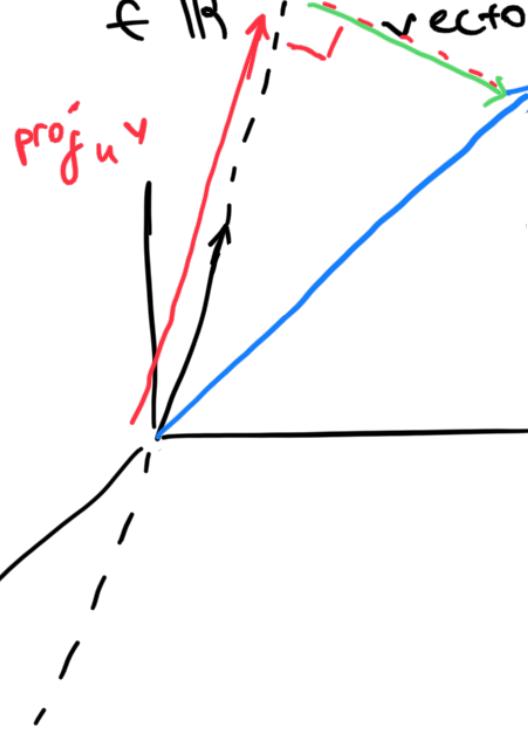
$\dots \parallel \perp \perp \perp \perp \perp \perp$

$$u = \|\mathbf{v}\| \left(\frac{\mathbf{v}}{\|\mathbf{v}\|} \right) \in \mathbb{R}$$

$$\text{proj}_{\mathbf{u}} \mathbf{v} = \left(\frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{u}\|} \right) \left(\frac{\mathbf{u}}{\|\mathbf{u}\|} \right) = \left(\frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{u}\|^2} \right) \mathbf{u} \in \mathbb{R}$$

ex: $\mathbf{u} = (1, 1, 2)$

$\mathbf{v} = (3, 3, 3)$



$$\text{proj}_{\mathbf{u}} \mathbf{v} = \left(\frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{u}\|} \right) \frac{\mathbf{u}}{\|\mathbf{u}\|} = \frac{(3+3+6)}{\sqrt{6}} \left(\frac{(1, 1, 2)}{\sqrt{6}} \right)$$

$$= \frac{12}{6} = 2 (1, 1, 2) = (2, 2, 4)$$

Want orthogonal part, then $\mathbf{v} - \text{proj}_{\mathbf{u}} \mathbf{v} = (3, 3, 3) - (2, 2, 4)$

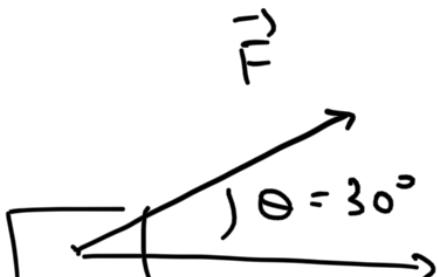
$$= (1, 1, -1) \quad \text{green arrow}$$

Scalitry check $(1, 1, -1) \perp \mathbf{u}$?

$$1+1-2=0 \quad \checkmark$$

Work: $W = \vec{F} \cdot \vec{D}$ where \vec{F} force over displacement \vec{D} .

ex:



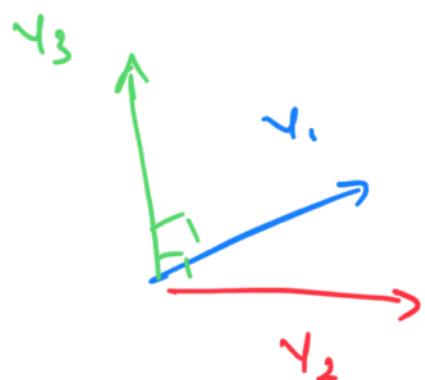
direction displacement

Say $|D| = \frac{4}{\sqrt{2}}$ m and $|\vec{F}| = 100$ N

$$\text{then } \vec{F} \cdot \vec{B} = |\vec{F}| |\vec{B}| \cos \theta = (100 \cdot \frac{4}{\sqrt{3}} \cdot (\frac{\sqrt{3}}{2})) \\ = 200 \text{ J Joules} = N \cdot m$$

12.4: Cross-Products

Given two vectors $\mathbf{v}_1, \mathbf{v}_2 \in \mathbb{R}^3$, they span a plane (typically). Then up to scale, there's a natural choice of a complementary vector. Just take one \perp to the plane. Here's a cartoon.



However, there's some ambiguity. There's a bunch of choices; let's agree on an orientation, let's say that

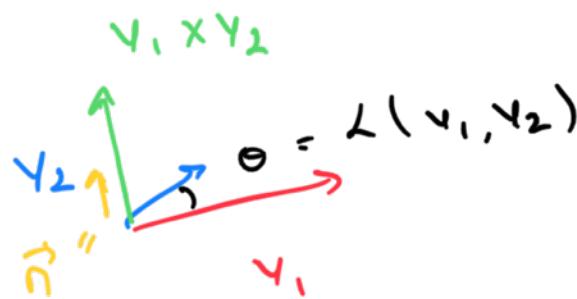
3-ordered vectors are standardly oriented or right-hand rule oriented if you can rotate, scale, shear, etc to agree with $(\hat{i}, \hat{j}, \hat{k})$. So the set $(\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3)$ depicted above is not standardly oriented.

(Show them the hand thing)

We define the cross product of $\mathbf{v}_1, \mathbf{v}_2$ to be

$\mathbf{v}_1 \times \mathbf{v}_2 = (\|\mathbf{v}_1\| \|\mathbf{v}_2\| \sin \theta) \vec{n}$ where \vec{n} is a unit vector so that $(\mathbf{v}_1, \mathbf{v}_2, \vec{n})$ is standard orientation, and $\theta = \angle(\mathbf{v}_1, \mathbf{v}_2)$.

Here's picture:



Here are some properties: (pg. +35)

$$(i). (ru) \times (sv) = (rs) u \times v$$

$$(ii). u \times (v+w) = u \times v + u \times w$$

$$(iii). v \times u = -(u \times v)$$

$$(iv). (v+w) \times u = v \times u + w \times u$$

$$(v). \vec{0} \times u = \vec{0}$$

$$(vi). u \times (v \times w) = (u \cdot w)v - (u \cdot v)w$$

(vii). $u \times v = 0$ for $u, v \neq 0$ iff u, v are parallel.

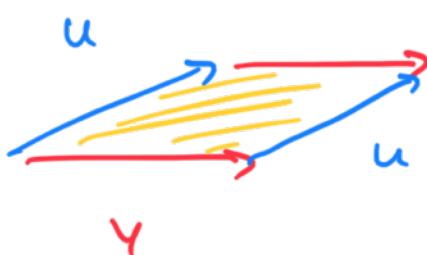
Most fundamental ones to remember are

$$\hat{i} \times \hat{j} = \hat{k} \quad \hat{j} \times \hat{k} = \hat{i} \quad \hat{k} \times \hat{i} = \hat{j}$$

Easy to remember by picture

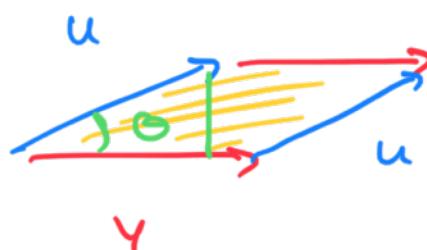


example: Let $u, v \in \mathbb{R}^3$. Form parallelogram as pictured below. Then $|u \times v| = \text{Area}(u, v)$.



$$\text{Area} = |u \times v|$$

Just because



$$\begin{aligned} \text{Area} &= \text{base} \parallel \text{height} \\ &= |v| (|u| \sin \theta) \\ &= |u \times v| \text{ bc } |\mathbf{n}| = 1 \end{aligned}$$

Similarly if have 3 generic points in \mathbb{R}^3 , then



form parallelogram take the area



and $\frac{1}{2}$ it to get area of triangle of $\triangle ABC$.

$$\text{That is, } \text{Area } \triangle ABC = \frac{1}{2} |\vec{AB} \times \vec{AC}|$$

How to actually calculate it? Before stating,
let us recall determinant of a 2×2 -matrix.

$$\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad - bc = \begin{vmatrix} a & b \\ c & d \end{vmatrix}$$

(actually the signed area of parallelogram formed by $\begin{pmatrix} a \\ c \end{pmatrix}$ and $\begin{pmatrix} b \\ d \end{pmatrix}$ in \mathbb{R}^2)

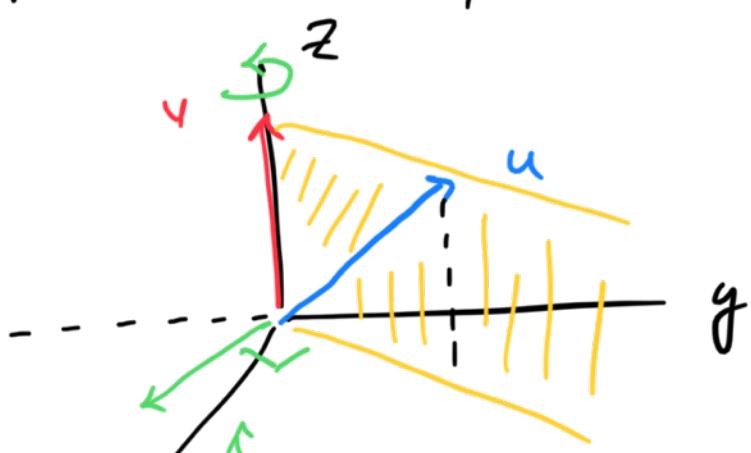
Okay, so $u = (u_1, u_2, u_3)$ and $v = (v_1, v_2, v_3)$

$$\text{then } u \times v = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix}$$

$$= \hat{i} \begin{vmatrix} u_2 & u_3 \\ v_2 & v_3 \end{vmatrix} - \hat{j} \begin{vmatrix} u_1 & u_3 \\ v_1 & v_3 \end{vmatrix} + \hat{k} \begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix}$$

(Show then how to see this as minors of matrix)

ex: Find a unit vector perpendicular to the plane generated by $(1, 1, 1)$ and $(0, 0, 2)$



\cancel{x} / this intuitively will do, say $w = (1, -1, 0)$
(kinda)

$$u \times v = \begin{vmatrix} i & j & k \\ 1 & 1 & 0 \\ 0 & 0 & 2 \end{vmatrix} = i \begin{vmatrix} 1 & 1 \\ 0 & 2 \end{vmatrix} - j \begin{vmatrix} 1 & 1 \\ 0 & 2 \end{vmatrix} + k \begin{vmatrix} 1 & 1 \\ 0 & 0 \end{vmatrix}$$

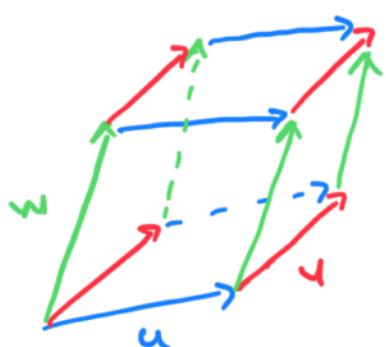
$$= (2, -2, 0)$$

then divide out by norm, $w = (2, -2, 0) / \sqrt{8}$

However, note, $w \parallel$ to our original choice $(1, -1, 0)$.

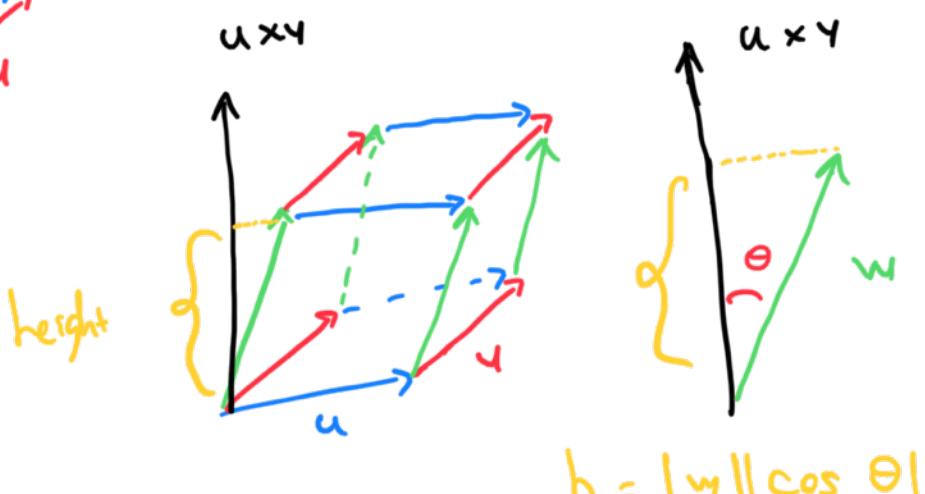
Also note right hand rule.

- 1 vector defines a line segment
- 2 vectors determine a parallelogram
- 3 vectors determine a ... parallelepiped



Want the volume of this.

Recall Volume = area \cdot height

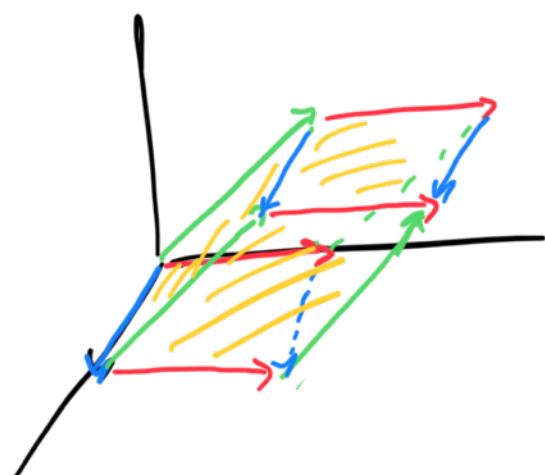


$$\begin{aligned} \text{thus } \text{Volume} &= (\text{Area of parallelogram } (u, v)) (\text{height}) \\ &= \|u \times v\| \|w\| \cos \theta = |(u \times v) \cdot w| \end{aligned}$$

if you work it out...

$$= \begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix}$$

Ex: $u = (1, 0, 0)$ $v = (0, 1, 0)$ $w = (0, 1, 1)$



Value = 1 (why?)

Verify:

$$v = \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{vmatrix}$$

$$= (1, 1, 0) - 0 + 0$$

$$= 1$$

Torque: Vector quantity that expresses turning (kinda)

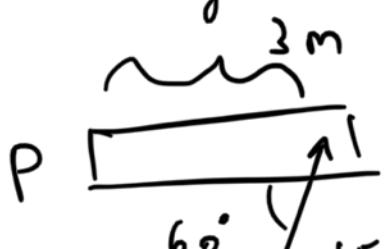
Just think of opening door.



if push is it easier to open at point A or B?

$$\vec{\tau} = \vec{r} \times \vec{F}$$

Calculate magnitude of torque generated by \vec{F} at pivot in figure (example 5 pg. 738)



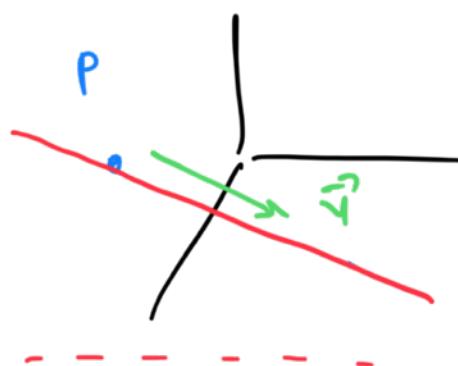
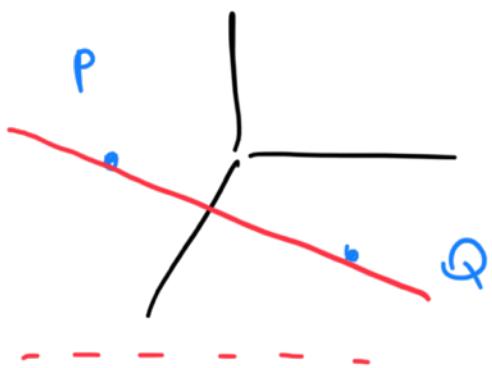
$$\begin{aligned} |\vec{\tau}| &= (\vec{r}) ||\vec{F}|| \sin \theta \\ &= 3(2)(1) \sin 60^\circ \end{aligned}$$

$$\therefore / \quad \| = 20 \text{ N} \quad = 60 \cdot \frac{\sqrt{3}}{2} \text{ Nm} \\ = 30\sqrt{3} \text{ Nm.}$$

12.5: Lines and Planes

A line is uniquely determined by either

- 2 distinct points
- 1 point and a non-zero vector.



Parametric equation for a line. Let v and P be as above. The line determined by P and v is algebraically given by $\vec{r}(t) = P + t v$ for $t \in \mathbb{R}$.

The idea being t is time along the line. $t=0$

↳ Starting point, namely P .

Another way of writing this is

$$x = x_0 + t v_1,$$

$$y = y_0 + t v_2 \quad \sim \quad \vec{r}(t) = P + t v$$

$$z = z_0 + t v_3 \quad \text{with } P = (x_0, y_0, z_0)$$

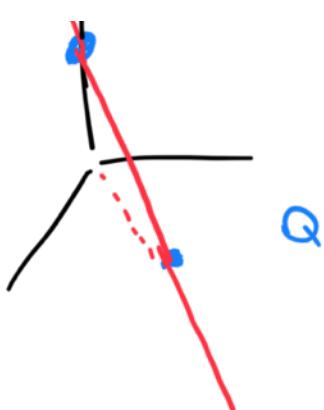
$$v = (v_1, v_2, v_3).$$

ex: Parameterize line joining $P = (0, 0, 1)$

$\| P$

$$Q = (1, 1, 0)$$

in such a way that \dots



... such that $a + \lambda = 0$,
located at the mid point of P and Q.

$$\text{midpoint } (P, Q) = \frac{1}{2} P + \frac{1}{2} Q = \left(\frac{1}{2}, \frac{1}{2}, \frac{1}{2}\right).$$

$$\text{Vector defined by } P, Q = \vec{PQ} = (1, 1, 0) - (0, 0, 1)$$

$$\text{Equation: } \vec{r}(t) = \left(\frac{1}{2}, \frac{1}{2}, \frac{1}{2}\right) + t(1, 1, -1) = (1, 1, -1)$$

unit speed motion $r(t) = P + t\vec{v}$ with $|\vec{v}| = 1$.

$$\vec{r}(t) = \left(\frac{1}{2}, \frac{1}{2}, \frac{1}{2}\right) + t\left(\frac{(1, 1, -1)}{\sqrt{3}}\right)$$

↑ unit vector

Places: Places are defined by

- 1 point, 2 vectors
- (typically) - 3 points
- 2 points, 1 vector
- 1 point, 1 vector ← (less obvious)
- etc

Algebraically they are described by the set of all $(x, y, z) \in \mathbb{R}^3$

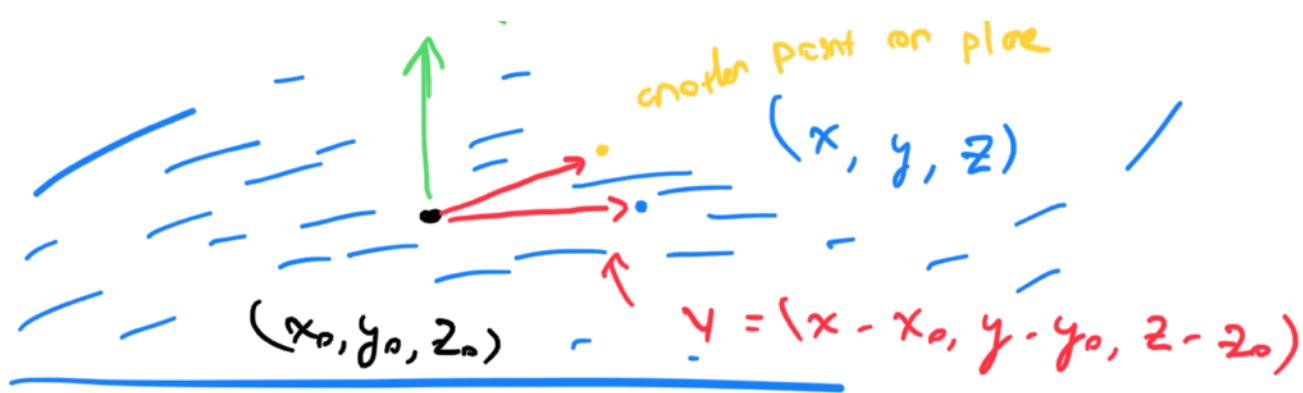
$$A(x - x_0) + B(y - y_0) + C(z - z_0) = 0$$

for fixed $A, B, C \in \mathbb{R}$ and a point $P = (x_0, y_0, z_0)$.

Not equation is \cong to

$$(A, B, C) \cdot (x - x_0, y - y_0, z - z_0) = 0$$

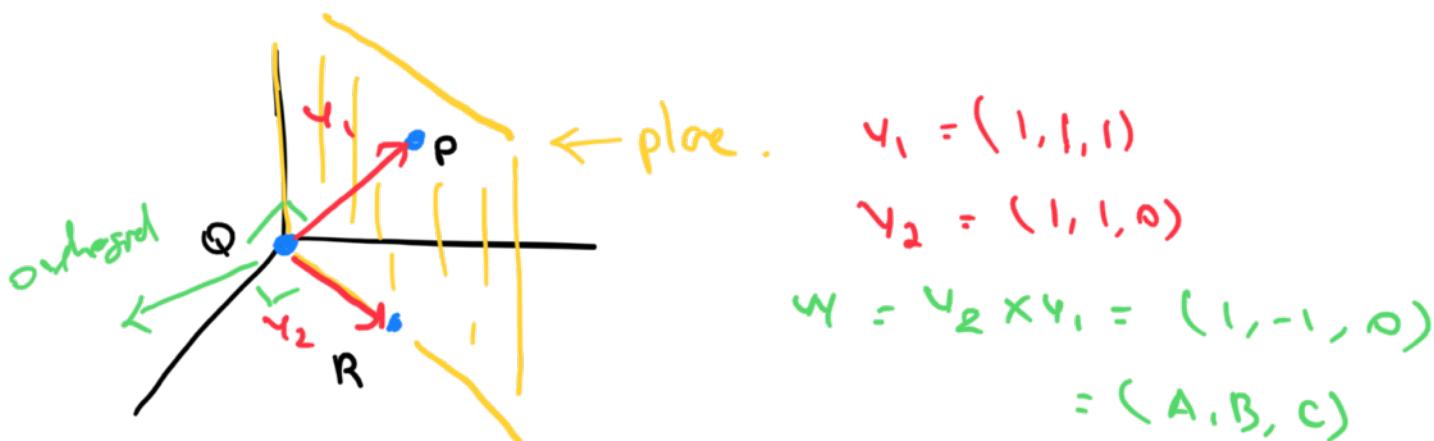
(A, B, C)



note vector $(A, B, C) \perp$ plane

ex: Find equation of plane containing points

$$P = (1, 1, 1) \quad Q = (0, 0, 0) \quad R = (1, 1, 0)$$



$$\text{equation: } A(x - x_0) + B(y - y_0) + C(z - z_0) = 0$$

$$\text{here chose point } (1)(x-1) + (-1)(y-1) + 0(z-0) = 0$$

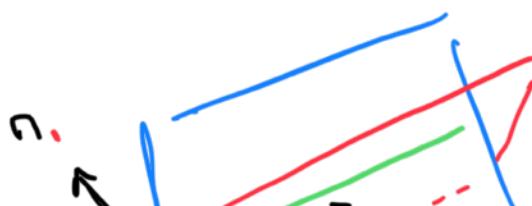
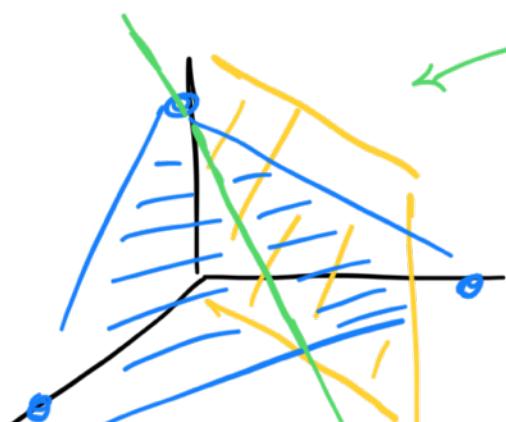
R, does it matter
the gh?

$$(x-1) - y + 1 = 0, \underline{\underline{x-y=0}}$$

ex: let plane 1 be defined by $P_1: x - y = 0$
plane 2 be defined by $P_2: x + y + z = 1$

determine the equation of the line intersecting these two planes.

we already know it!
However, here's another way.



$$\mathbf{n}_1 = (1, -1, 0)$$

$$\mathbf{n}_2 = (1, 1, 1)$$

$$\mathbf{n}_1 \times \mathbf{n}_2 = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & -1 & 0 \\ 1 & 1 & 1 \end{vmatrix}$$

$$\mathbf{v} = \mathbf{i}(-1) - \mathbf{j}(1) + \mathbf{k}(2) = (-1, -1, 2) \approx (1, 1, -2)$$

Quick sanity: $\mathbf{n}_1 \cdot \mathbf{v} = 0$ and $\mathbf{n}_2 \cdot \mathbf{v} = 0$

all we need is a point on both P_1 & P_2 .

$$\begin{aligned} x - y &= 0 \\ x + y + 2 &= 1 \end{aligned}$$

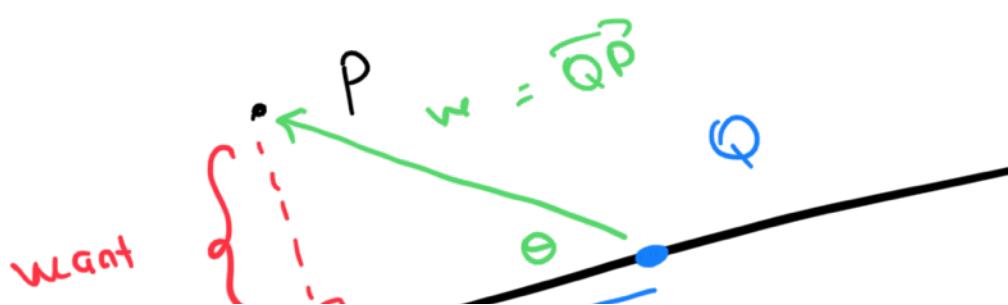
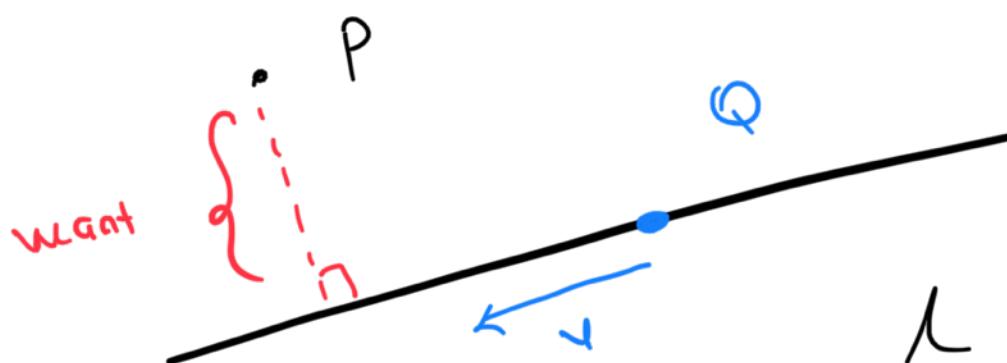
$$\mathbf{P} = (0, 0, 1) \text{ is good.}$$

$\ell: (0, 0, 1) + t(1, 1, -2)$. Good way to check?

ensure $\ell \subseteq P_1$ and $\ell \subseteq P_2$!

Distances:

ex: Point and a line

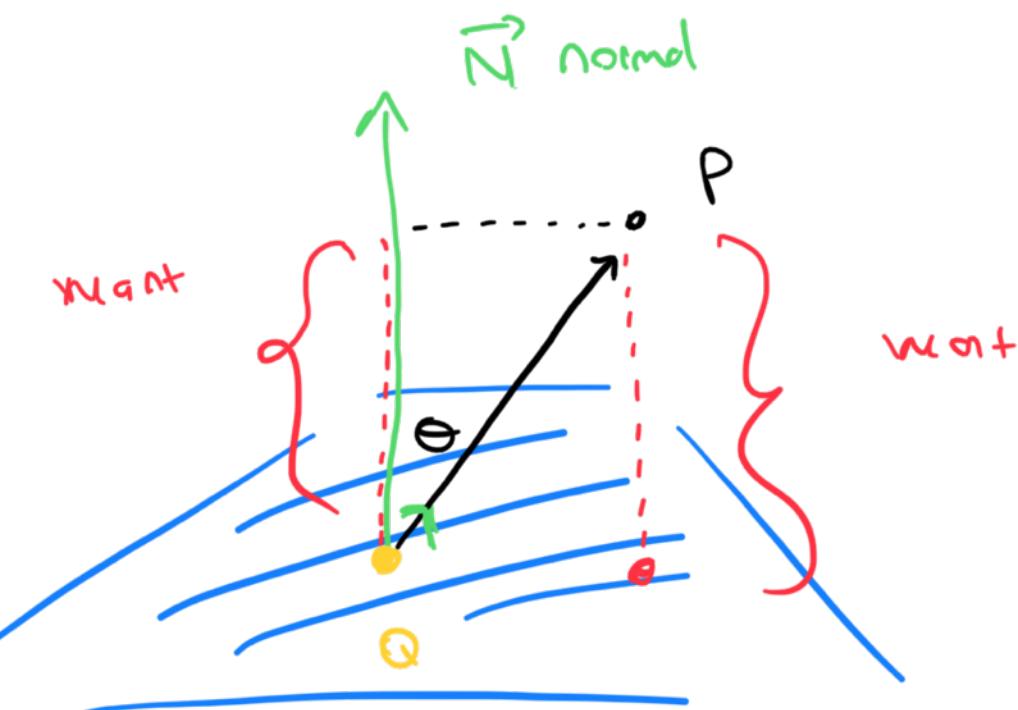
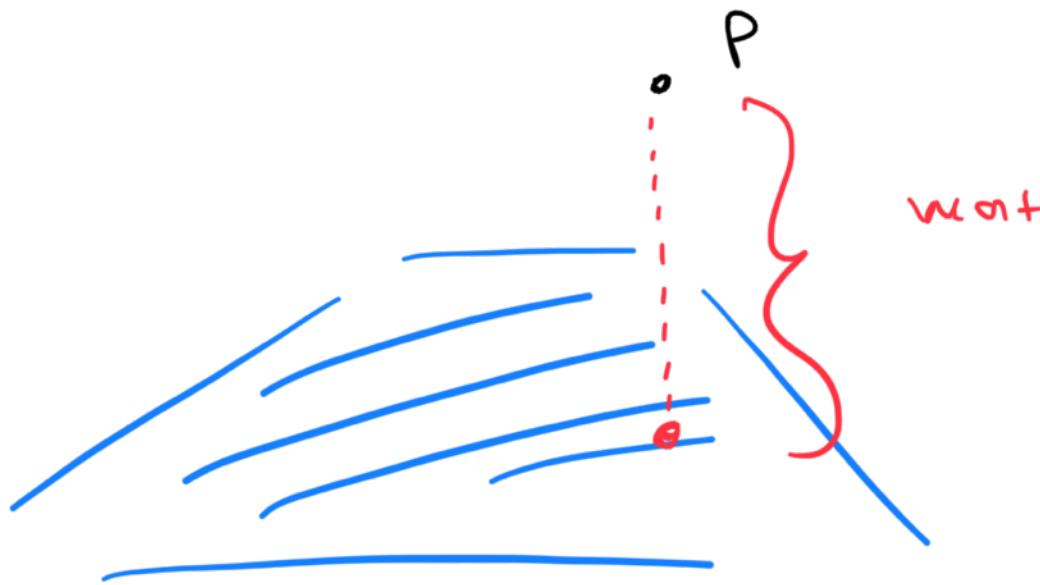


Want $|\vec{QP}| \sin \theta = \frac{|\vec{QP}| |v| |\sin \theta|}{|v|}$

$$d_{\text{int}}(P, l) = |\vec{QP} \times \vec{v}| / |\vec{v}|$$

\vec{v} parallel to l
and Q any
point on it

Ex: Distance between point and a plane?



distance is equal to $|\vec{QP}| |\cos \theta|$

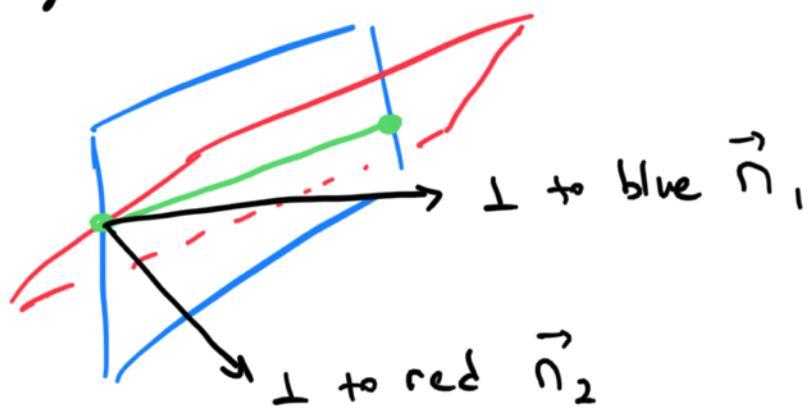
$$= \frac{|\vec{QP}| |\vec{N}| |\cos \theta|}{|\vec{N}|}$$

$$\text{dist}(P, \text{plane}) = |QP \cdot N| / |\vec{n}|$$

\vec{n} normal to plane
Q any point on it



ex: Angle between two planes



$$\cos(\theta(\text{plane}_1, \text{plane}_2)) = \frac{\vec{n}_1 \cdot \vec{n}_2}{|\vec{n}_1||\vec{n}_2|}$$

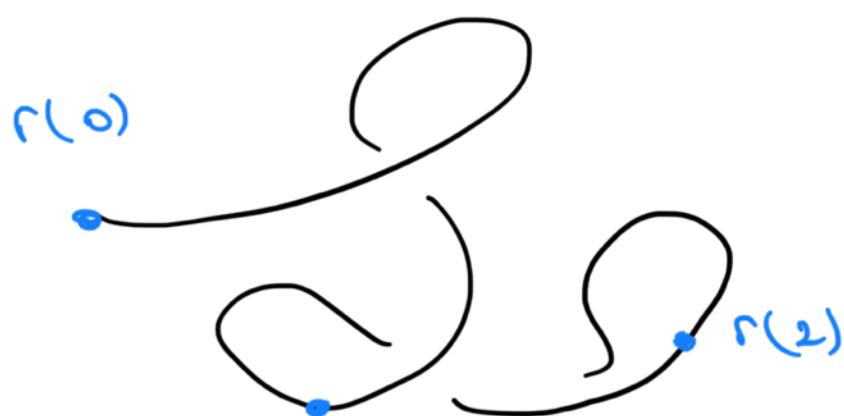
where \vec{n}_1, \vec{n}_2
normal to
plane 1, plane 2
respectively

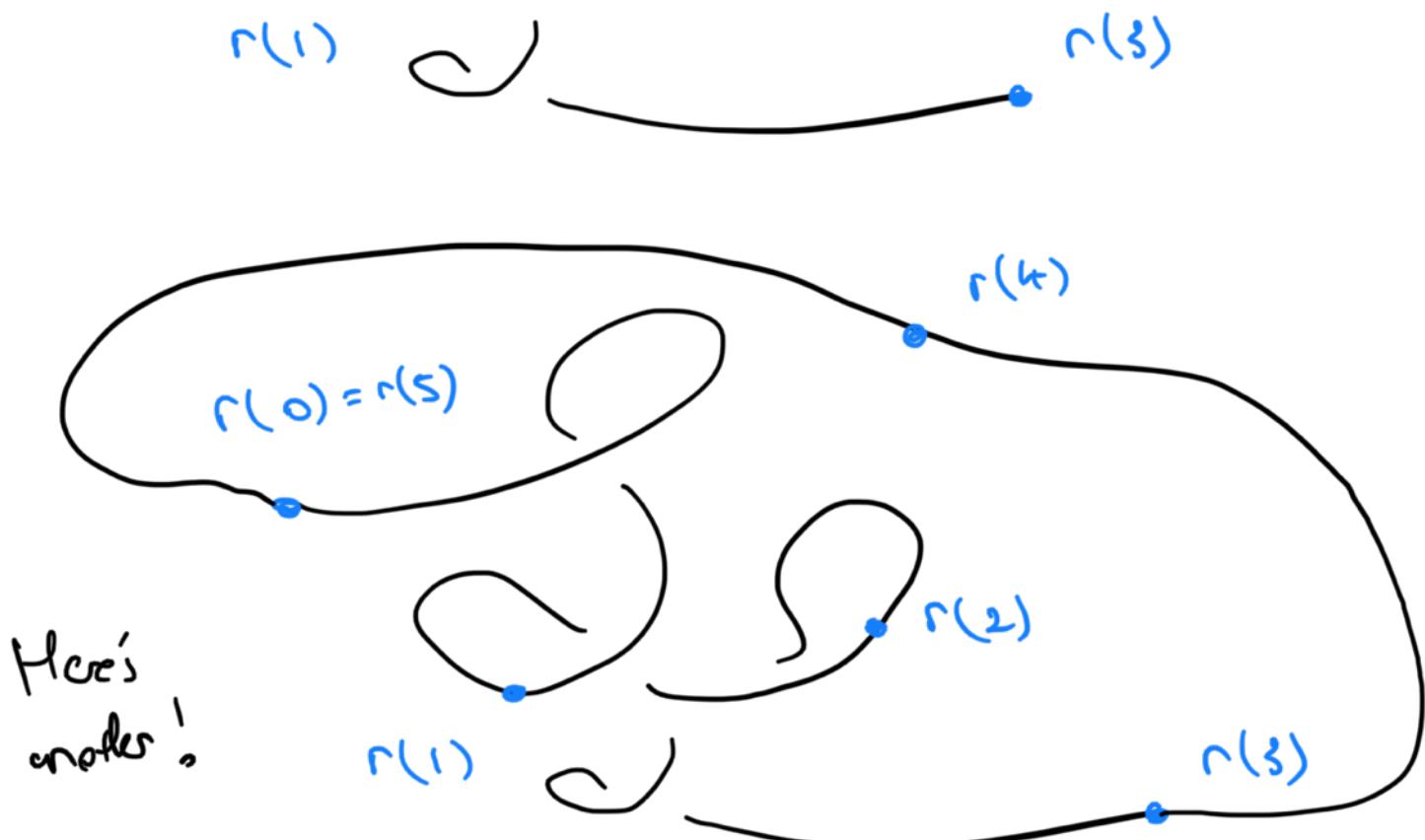
13.1: Curves in space and tangents

A curve in space is a map

$$\vec{r}: \mathbb{R} \longrightarrow \mathbb{R}^3 \text{ typically written as}$$

$\vec{r}(t) = (x(t), y(t), z(t))$. You imagine
the t -parameter is time. Here's a curve.





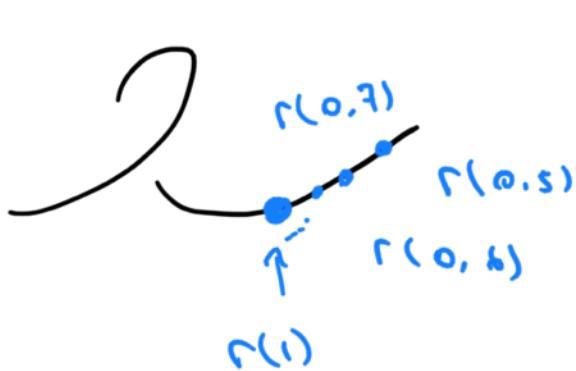
typically we want our curves to be smooth meaning differentiable. Want to avoid stuff like



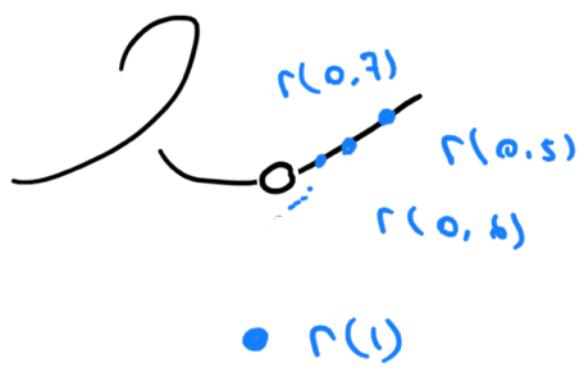
but it happens.

Just like in 2-dimensional calculus we have limits and derivatives.

ex:



$\lim_{t \rightarrow 1^-} r(t)$ exists



$\lim_{t \rightarrow 1^+} r(t)$ exists
but not

equal to $r(1)$.

continuous iff for each point $s \in \text{domain}$ $\lim_{s \rightarrow s} r(s) = r(s)$,

Above or right not cont.

Theorem: if $r(s) = (x(s), y(s), z(s))$
then $r(s)$ continuous at s iff
each $x(s), y(s), z(s)$ continuous
at s .

Ex: $r(s) = (s, s^2, s^3)$ good (also
interesting curve)

Ex: $r(s) = (\ln s, \sin(s), s^2)$ not cont
at $s=0$, however, good
everywhere else.

Derivatives: let $\vec{r}(s)$ be curve in \mathbb{R}^3 .

We say $\vec{r}'(s)$ is differentiable at s iff

$$\lim_{\Delta s \rightarrow 0} \frac{\vec{r}(s + \Delta s) - \vec{r}(s)}{\Delta s} \text{ exists.}$$

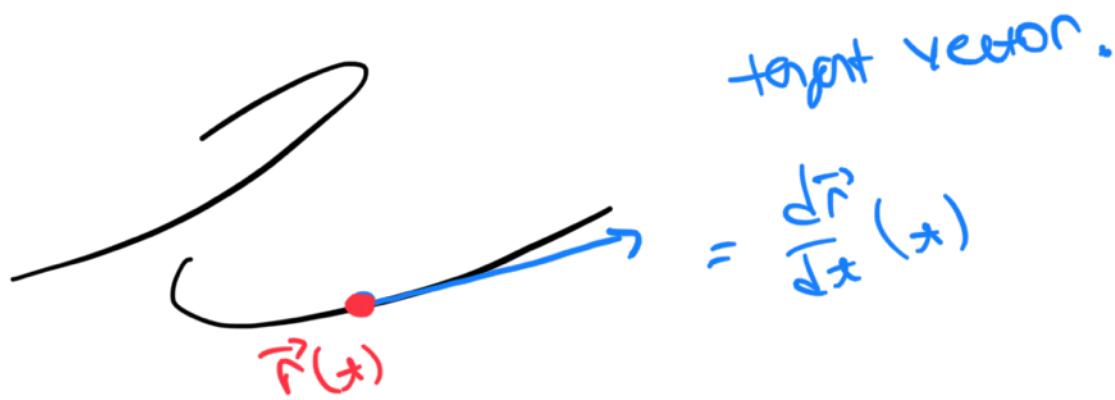
In this case we denote the limit by
 $\vec{r}'(s)$ or $\frac{d\vec{r}}{ds}(s)$.

Theorem: $\vec{r}(x)$ is differentiable at x if
each $x(x), y(x), z(x)$ is too.

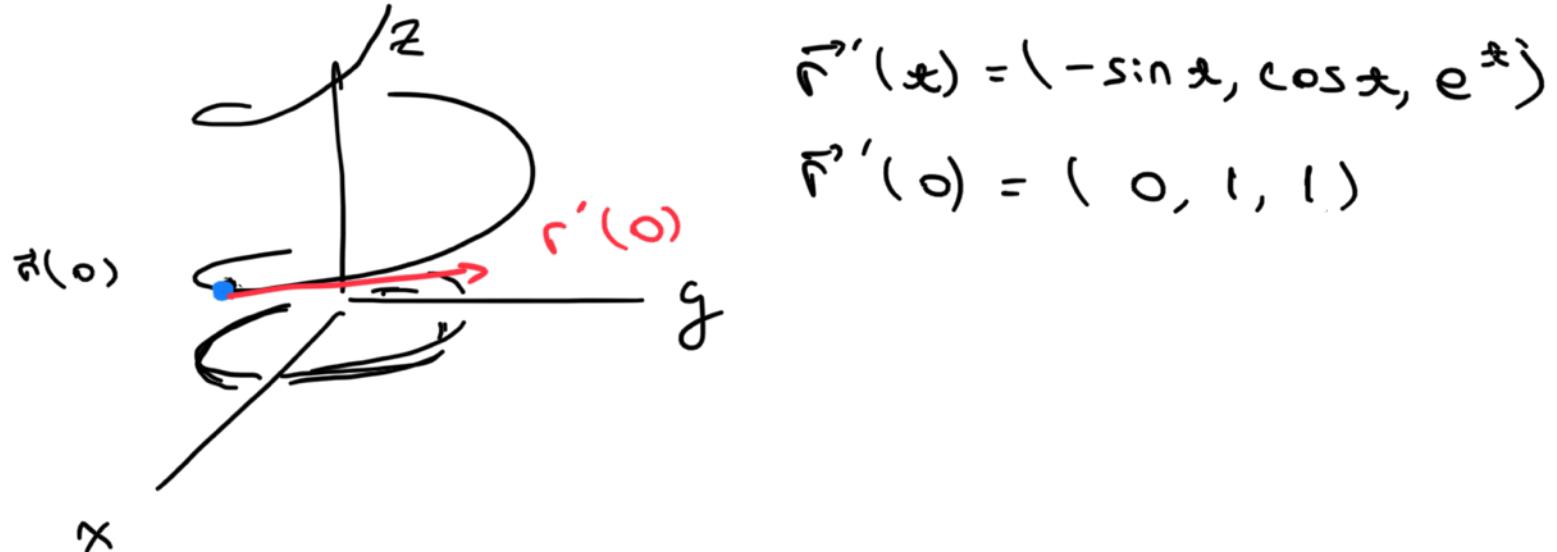
If so then $\vec{r}'(x) = (x'(x), y'(x), z'(x))$

Upshot: Just look at components.

Here's a picture:



Ex: $\vec{r}(x) = (\cos x, \sin x, e^x)$



Calculate the tangent line at $x=0$.

Tangent line should just be what was in 2D,
but now in 3D.

$$F(x) - F(a) \approx \frac{dF}{dx}(a)(x-a) \quad \text{now with vectors.}$$

$$\text{, ends} \rightarrow L(x) = F(a) + \frac{dF}{dx}(a)(x-a)$$

for linear.

$$\begin{aligned} \vec{r}(t) &= \vec{r}(0) + (0, 1, 1)(t - 0) \\ &= (1, 0, 1) + t(0, 1, 1) \end{aligned}$$

Acceleration: $\frac{d^2\vec{r}}{dt^2}(t) = \frac{d}{dt}(-\sin t, \cos t, e^t)$

$$= (-\cos t, -\sin t, e^t)$$

Here some helpful rules on pg. 765

(i). $\frac{d}{dt} \vec{C} = 0$ where \vec{C} constant

(ii). $\frac{d}{dt}(c \vec{u}(t)) = c \vec{u}'(t)$ c constant scalar

(iii). $\frac{d}{dt}(f(t) \vec{u}(t)) = f'(t) \vec{u}(t) + f(t) \vec{u}'(t)$
 $f(t)$ scalar function

(iv). $\frac{d}{dt}(\vec{u}(t) + \vec{v}(t)) = \vec{u}'(t) + \vec{v}'(t)$

(v). $\frac{d}{dt}(\vec{u}(t) - \vec{v}(t)) = \vec{u}'(t) - \vec{v}'(t)$

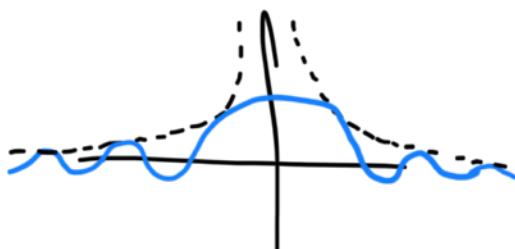
(vi). $\frac{d}{dt}(\vec{u}(t) \circ \vec{v}(t)) = \vec{u}'(t) \circ \vec{v}(t) + \vec{u}(t) \circ \vec{v}'(t)$

(vii). $\frac{d}{dt}(\vec{u}(t) \times \vec{v}(t)) = \vec{u}'(t) \times \vec{v}(t) + \vec{u}(t) \times \vec{v}'(t)$

(viii). $\frac{d}{dt}(\vec{u}(f(t))) = \vec{u}'(f(t)) f'(t)$

ex: $\vec{r}(t) = \left(t, \frac{\sin t}{t}, 1 \right)$

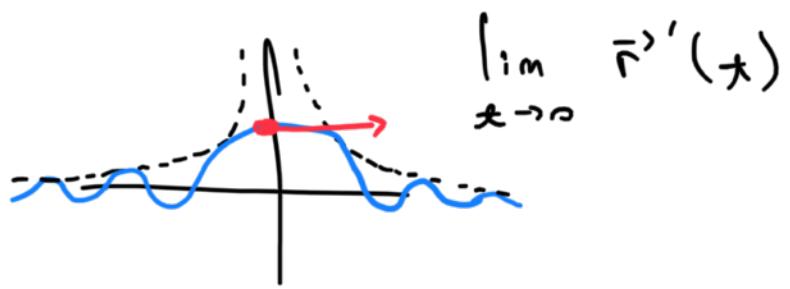
Want $\lim_{t \rightarrow 0} \vec{r}(t)$ and $\lim_{t \rightarrow 0} \vec{r}'(t)$



1. $\vec{r}(t) = (t, \sin t, 1) = t \cos t - \sin t$

$$\lim_{t \rightarrow 0} \vec{r}(t) = (0, 1, 1) \quad \vec{r}'(t) = (1, \frac{e^{-\frac{1}{t}} - e^{\frac{1}{t}}}{t}, 0)$$

$$\lim_{t \rightarrow 0} \vec{r}'(t) = (1, 0, 0)$$



13.2 : Integrals and projectile motion

Just like functions of a single variable, we say

$\vec{r}(t)$ has an anti-derivative $\vec{R}(t)$ if

$$\frac{d\vec{R}}{dt}(t) = \vec{r}(t). \text{ Or in integral notation,}$$

$$\vec{R}(t) = \int \vec{r}(t) dt.$$

Note just like 1-variable there's ambiguity.

$$\vec{s}(t) = \vec{R}(t) + \vec{C} \text{ where } \vec{C} \text{ constant}$$

is perfectly valid too.

(oops forgot

$$\int_a^b \frac{d\vec{F}}{dt}(t) dt = \vec{F}(b) - \vec{F}(a)$$

be sure to mention)

Motivated by physical quantities.

e.g.: $\vec{v}(t) = (-\sin t, \cos t, 1)$, velocity of particle. Want to find a particle's path whose velocity is $\vec{v}(t)$. Set up an integral.

$$\begin{aligned} \int \vec{v}(t) dt &= \int -\sin t dt \hat{i} + \int \cos t dt \hat{j} \\ &\quad + \int dt \hat{k} = (\cos t, \sin t, t) + \vec{C}. \end{aligned}$$

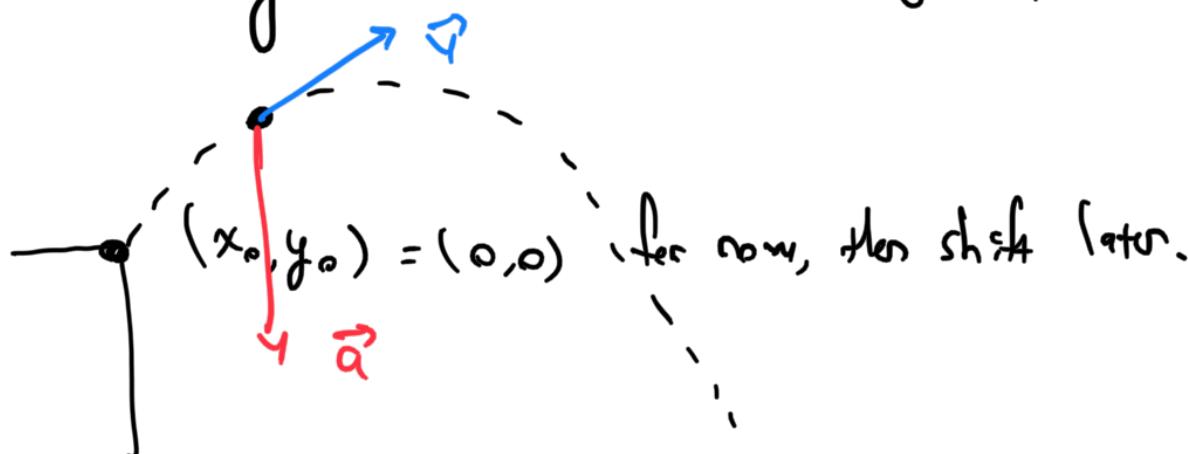
If our particle starts at point $(1, 0, 1)$ then solution is unique.

$$\vec{r}(t) = (\cos t, \sin t, t) + (c_1, c_2, c_3)$$

$$\vec{r}(0) = (1, 0, 1) = (1, 0, 0) + (c_1, c_2, c_3)$$

$$\text{so } \vec{r}(t) = (\cos t, \sin t, t+1)$$

ex: Say a ball thrown with initial velocity $\vec{v} = (v_x, v_y)$ at position $(x_0, y_0) = \vec{r}_0$. Calculate its trajectory assuming no forces other than gravity.



$$\frac{d^2\vec{r}}{dt^2}(t) = \vec{a} = (0, -g) \quad g = \text{gravitational constant} \approx 10 \text{ m/s}^2$$

$$\int_0^s \frac{d^2\vec{r}}{dt^2}(t) dt = \int_0^s 0 dt \hat{i} + \int_0^s -g dt \hat{j}$$

$$\vec{v}(s) - \vec{v}(0) = (0, -gs) \quad (\text{replace with } s)$$

$$\vec{v}(t) = \vec{v}(0) + (0, -gt) = (v_x, v_y - gt)$$

$$\int_0^s \vec{v}(t) dt = \int_0^s \frac{d\vec{r}}{dt}(t) dt = \vec{r}(s) - \vec{r}(0)$$

$$= \int_0^s v_x dt \hat{i} + \int_0^s (v_y - gt) dt \hat{j}$$

$$= (v_x s, v_y s - \frac{1}{2} g s^2)$$

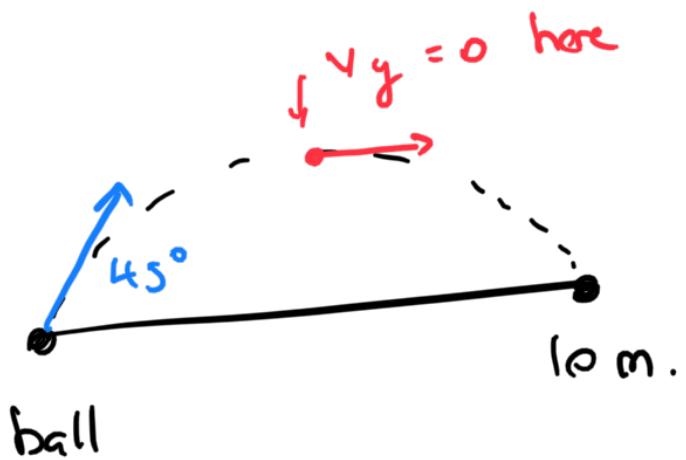
$$\text{So } \vec{r}(t) = (x_0 + v_x t, y_0 + v_y t - \frac{1}{2} g t^2) \quad (\text{---})$$

ex 13.2.27: Hit ball at $\theta = 45^\circ$ and it lands level 10 m away.

(i). What was balls initial speed?

(ii). Find 2 angles that make range 6m. why?

Speed is $|\vec{v}(t)|$. We want $|\vec{v}_0|$.



We can solve for half time by

$$v_y = 0$$

$$\vec{r}(t) = (v_x t, v_y t - \frac{1}{2} g t^2)$$

$$\vec{v}(t) = (v_x, v_y - g t)$$

$$\text{so } v_y - g t = 0 \text{ thus}$$

$$t^* = \frac{v_y}{g}.$$

this means total flight time is $2t^*$, thus range

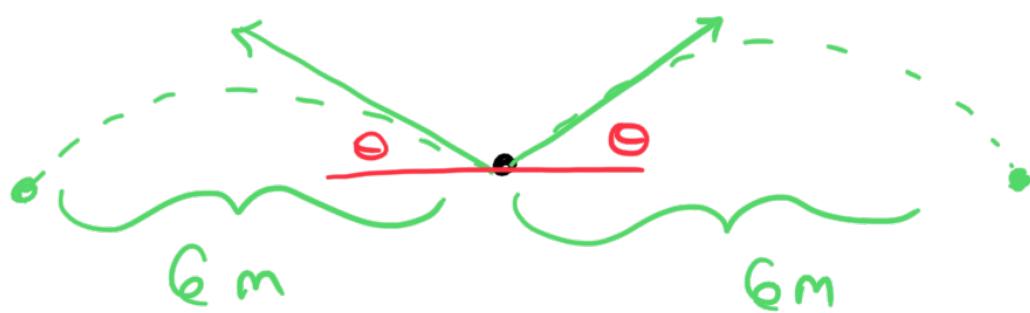
$$R = v_x (2t^*) = 2v_x v_y / g \quad (\text{---})$$

$$= 2v_0^2 \cos \theta \sin \theta / g = \frac{1}{2} v_0^2 \sin 2\theta$$

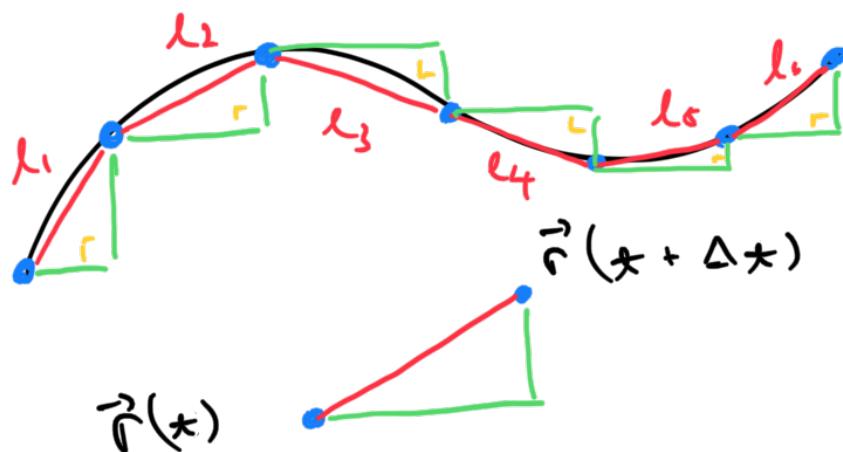
$$10 \text{ m} = \frac{1}{2} v_0^2 \sin(2 \cdot 45^\circ) \text{ so } |v_0| = \frac{\sqrt{20} \text{ m/s}}{10}$$

If however want range to be 6m at initial speed of $\sqrt{20} \text{ m/s}$, then

$$6m = \frac{1}{2} V_0^2 \sin(2\theta) \quad \frac{\pi}{20} = \sin(2\theta)$$



13.3 : Arc length



$|\vec{r}(t + \Delta t) - \vec{r}(t)| \approx \text{arc length}$

$$\approx \left| \frac{d\vec{r}}{dt}(t) \right| |\Delta t| = |\vec{v}(t)| |\Delta t|$$

So we define arc-length of a curve $\vec{r}(t)$ from $[a, b]$ to be

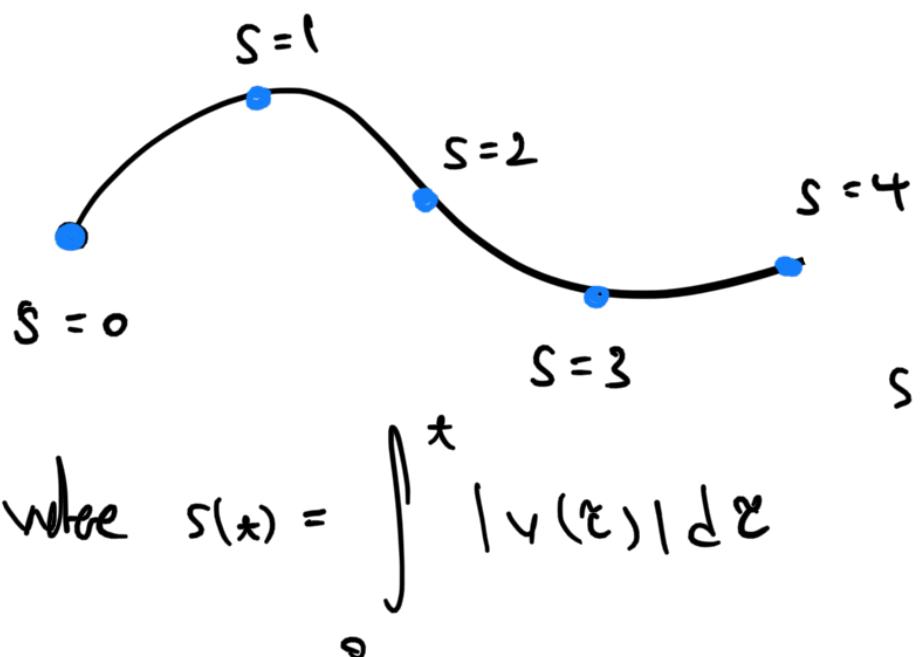
$$L = \int_a^b |\vec{v}(t)| dt = \int_a^b \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2} dt$$

Ex: $\vec{r}(t) = (\sin t, 2\sin t, \sin t)$

Want length of curve from $t = 0$ to $t = \pi/2$

$$\begin{aligned} L &= \int_0^{\pi/2} \sqrt{(x')^2 + (y')^2 + (z')^2} dt \\ &= \int_0^{\pi/2} \sqrt{\cos^2 t + 4\cos^2 t + \cos^2 t} dt \\ &= \int_0^{\pi/2} \sqrt{6} |\cos t| dt = \sqrt{6} \end{aligned}$$

Weird way of parametrizing, but okay. A 'natural' way
to parametrize a smooth curve is by arclength itself!



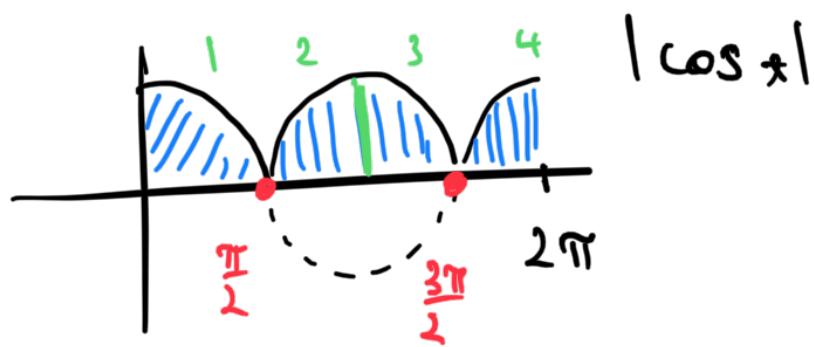
where $s(t) = \int_0^t |\nu(\xi)| d\xi$

s is a measure of how far you've gone.

Ex: $\vec{r}(t) = (\sin t, 2\sin t, \sin t)$ then after t -seconds we've traveled

$$\begin{aligned} s(t) &= \int_0^t \sqrt{\cos^2 \xi + 4\cos^2 \xi + \cos^2 \xi} d\xi \\ &= \sqrt{6} \int_0^t |\cos \xi| d\xi \end{aligned}$$

So for example after 2π , it's gone



So $s(2\pi) = \sqrt{6} \cdot 4$ and note that
 $\vec{r}(2\pi) = \vec{r}(0)$.

Unit tangent vectors: Let $\vec{r}(t)$ be some path. Unit tangent vector records direction of velocity vector (so long as $\vec{v}(t) \neq 0$).

denoted $\vec{\tau}(t) = \frac{\vec{v}(t)}{|\vec{v}(t)|}$

One property is that $\vec{\tau}(s) = \frac{d\vec{r}}{ds}(s)$
 (good exercise).

ex: $\vec{r}(t) = (C \cos t, C \sin t, 1)$ (C constant > 0)

$$\vec{v}(t) = (-C \sin t, C \cos t, 0)$$

$$|\vec{v}(t)| = |C| = C$$

so $\vec{\tau}(t) = (-\sin t, \cos t, 0)$ indeed

unit norm.

Also note, $s(\tau) = \int_0^\tau |v(t)| dt = Ct$ for $t \geq 0$.
 $s = Ct$ so

so $\vec{r}(s) = (C \cos(s/c), C \sin(s/c), 1)^T$.

$$\begin{aligned}\frac{d\vec{r}}{dt}(s) &= (-\sin(s/c), \cos(s/c), 0) \\ &= \vec{T}(s)\end{aligned}$$

14.1: Functions of several variables

Before: $t \in \mathbb{R} \mapsto (x(t), y(t), z(t)) \in \mathbb{R}^3$

Now: $(x, y, z) \in \mathbb{R}^3$
or $(x, y) \in \mathbb{R}^2 \mapsto f(x, y, z) \in \mathbb{R}$ or
 $f(x, y) \in \mathbb{R}$

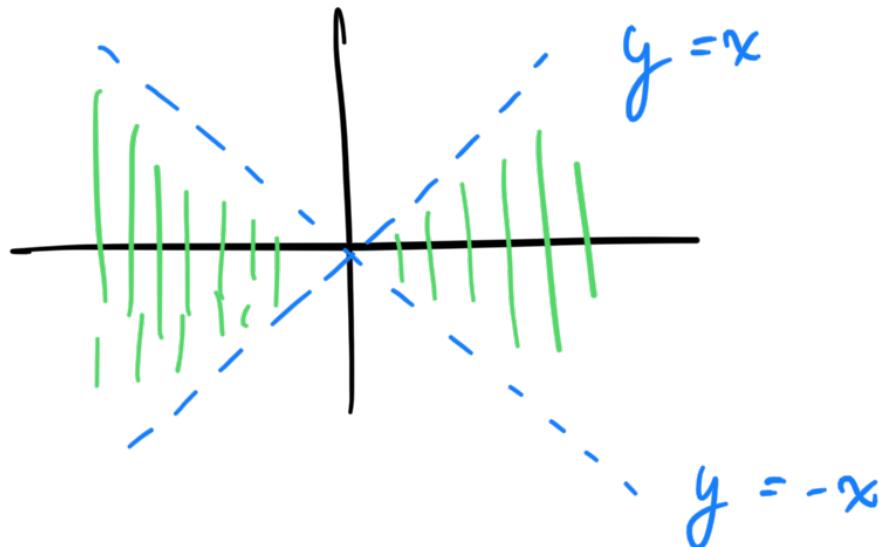
Real-valued functions. Can think of them as measurements of some variables, e.g. temperature along a plate of food or elevation as a function of position.

When you have a multivariate function typically defined by $f(x, y, z)$ or $f(x, y)$. The set of all points (x, y, z) for which f makes sense is called the domain.

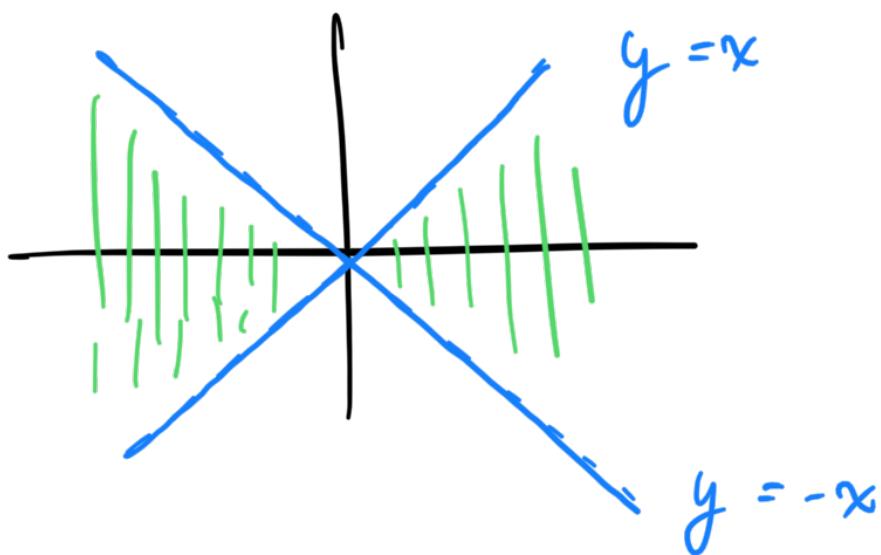
ex: Describe the domain of f

$$f(x,y) = \log(x^2 - y^2)$$

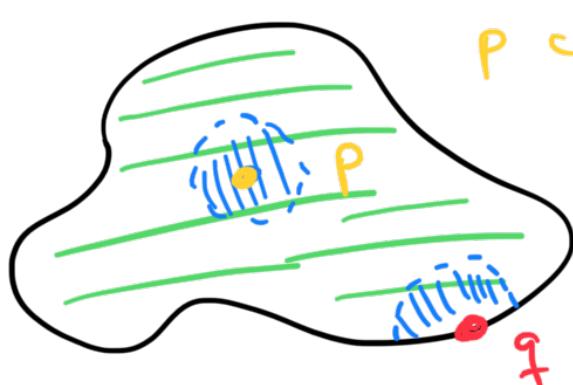
Need $x^2 - y^2 > 0$ (not equal)



What if $f(x,y) = \sqrt{x^2 - y^2}$? then



domain:

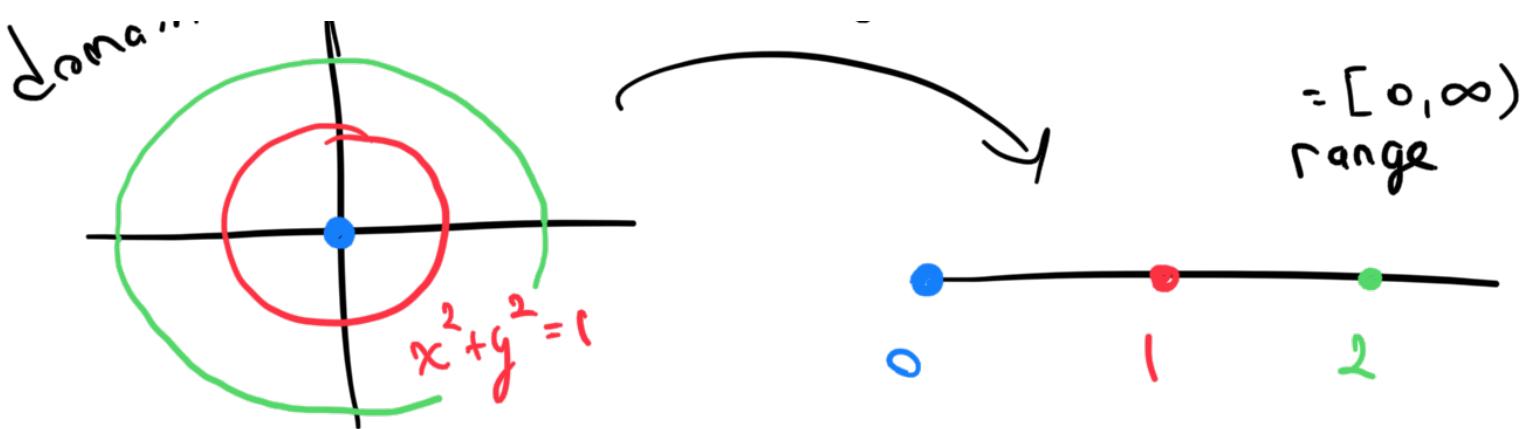


P called an interior point

Q called a boundary point

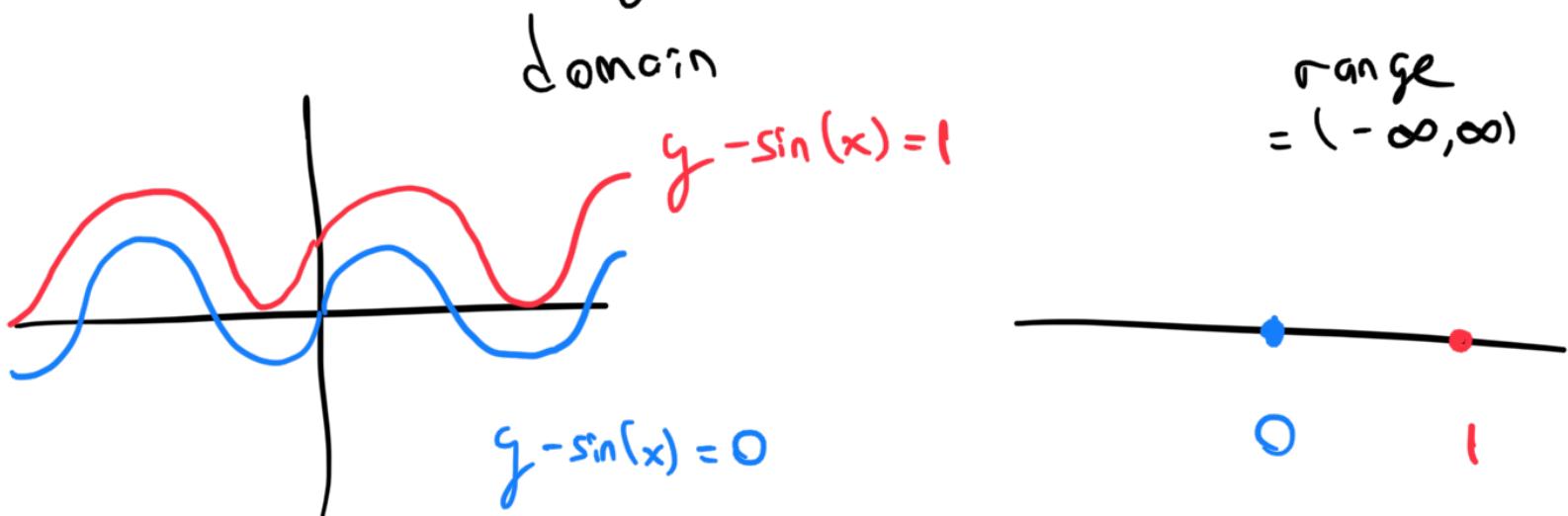
ex: $f(x,y) = x^2 + y^2$.

f

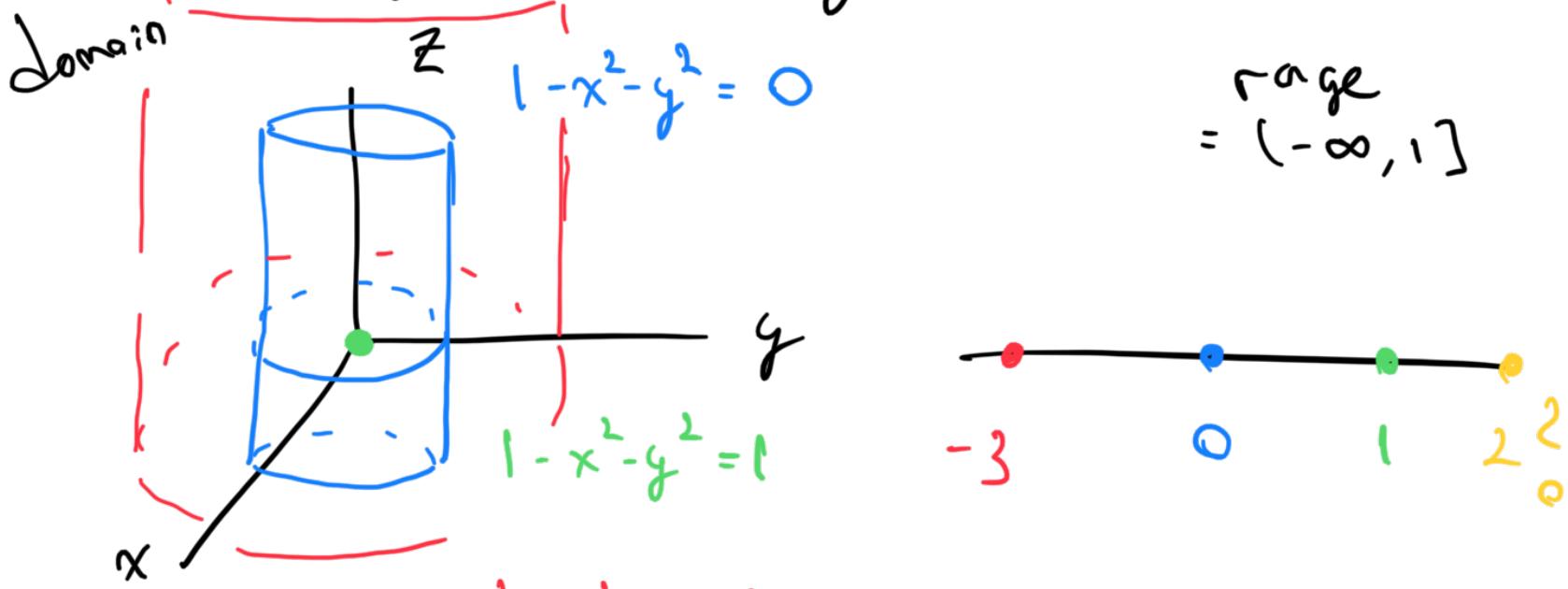


green/red/blue in domain are called 'level curves'. These are curves where the function has a constant value.
 Can define some notion of a 'level-surface'.

$$\text{ex: } f(x, y) = y - \sin(x)$$



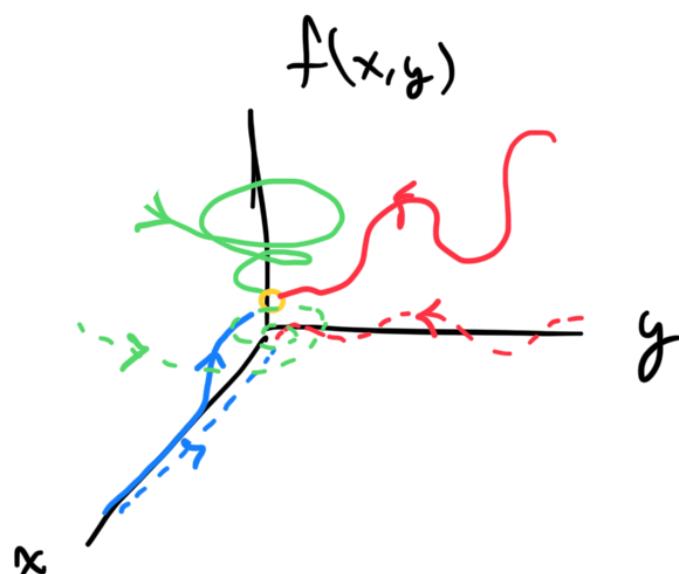
$$\text{ex: } f(x, y, z) = 1 - x^2 - y^2$$



$$1 - x^2 \cdot y^2 = -3$$

14.2 : limit and continuity

Limits in 2-variable are much more complicated than usual. Reason why is because you have a bunch of directions to approach now.



Let's not formally define limit, but instead use rules to figure out what limits are equal to.

However here's a piece of intuition.

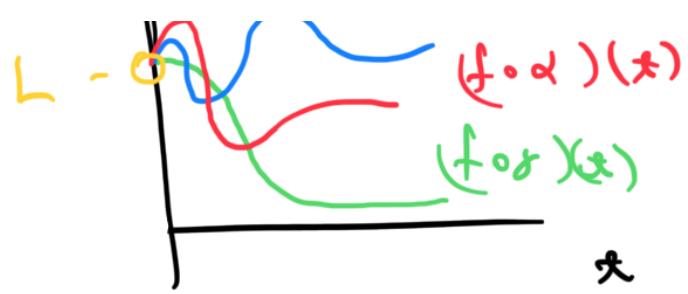
Let $f(x,y)$ be a function. Consider a point (a,b) . We say $\lim_{(x,y) \rightarrow (a,b)} f(x,y) = L$ if

for every smooth path $\gamma(t)$ in \mathbb{R}^2 with $\gamma(0) = (a,b)$

we have $\lim_{t \rightarrow 0} (f \circ \gamma)(t) = L$.

$$\downarrow \gamma(t)$$

$$L \sim (f \circ \gamma)(t)$$



Note in particular if we find two paths that disagree, then limit does not exist! that is if find on α and β so that

$$\lim_{x \rightarrow 0} (f \circ \alpha)(x) \neq \lim_{x \rightarrow 0} (f \circ \beta)(x) \text{ then } \lim$$

does not exist!

Bunch of rules on Pg. 812 look exactly like one you familiar with but now in 2-variables.

$$\text{e.g. if } \lim_{(x,y) \rightarrow (a,b)} f(x,y) = L \text{ & } \lim_{(x,y) \rightarrow (a,b)} g(x,y) = M$$

$$\text{then } \lim_{(x,y) \rightarrow (a,b)} f(x,y) + g(x,y) = L + M$$

$$\lim_{(x,y) \rightarrow (a,b)} f(x,y) \cdot g(x,y) = L \cdot M \quad \text{etc.}$$

We say a function is continuous if for every point (a, b) in the domain we have

$$\lim_{(x,y) \rightarrow (a,b)} f(x,y) = f(a,b).$$

$$\text{ex: } \lim_{\substack{(x,y) \rightarrow (1,1)}} \frac{x-y}{x^2-y^2} = \lim_{\substack{(x,y) \rightarrow (1,1)}} \frac{(x-y)(x+y)}{(x^2-y^2)}$$

$$= \lim_{\substack{(x,y) \rightarrow (1,1)}} x^2+y^2 = 1+1=2$$

ex: 14.2.19

$$\text{defn } f(x,y) = \begin{cases} \sqrt{2x-y} - 2 & \text{for } 2x-y-4 \neq 0 \\ 7 & \text{if } 2x-y-4 = 0 \end{cases}$$

is $f(x,y)$ continuous at $(2,0)$?

$$\lim_{\substack{(x,y) \rightarrow (2,0)}} \frac{\sqrt{2x-y} - 2}{2x-y-4}$$

$$= \lim_{\substack{(x,y) \rightarrow (2,0)}} \frac{(\sqrt{2x-y} - 2)}{(\sqrt{2x-y} - 2)(\sqrt{2x-y} + 2)} = \lim_{\substack{(x,y) \rightarrow (2,0)}} \frac{1}{\sqrt{2x-y} + 2}$$

$$= \frac{1}{2+2} = \frac{1}{4} \neq 7 \text{ so no, function not continuous at } (2,0)$$

ex: Just because a function has a limit along every line, doesn't mean it has a limit!

$$f(x,y) = \frac{2x^2y}{x^4+y^2} \text{ pg. 815}$$

note along y -axis $\alpha(x) = (0, x)$ for $x \neq 0$

$$(f \circ \alpha)(x) = \frac{0}{x^2} = 0 \text{ for } x \neq 0$$

However for $\beta(x) = (x, m+x)$

$$(f \circ g)(x) = \frac{2(x^2)(mx)}{x^4 + (mx)^2} = \frac{2mx^3}{m^2x^2 + x^4}$$

$$= \frac{2mx}{m^2 + x^2} \quad \text{for } x \neq 0$$

so $\lim_{x \rightarrow 0} (f \circ g)(x) = 0$ true for any m .

However limit is different for $g(x) = (x, kx^2)$
check is good exercise.

Ex: $\lim_{(x,y) \rightarrow (0,0)} \frac{\sin(x+y)}{xy+y^2}, \quad u = x+y$

$\lim_{u \rightarrow 0} \frac{\sin(u)}{u} = 1$ can do replacement
if function is a

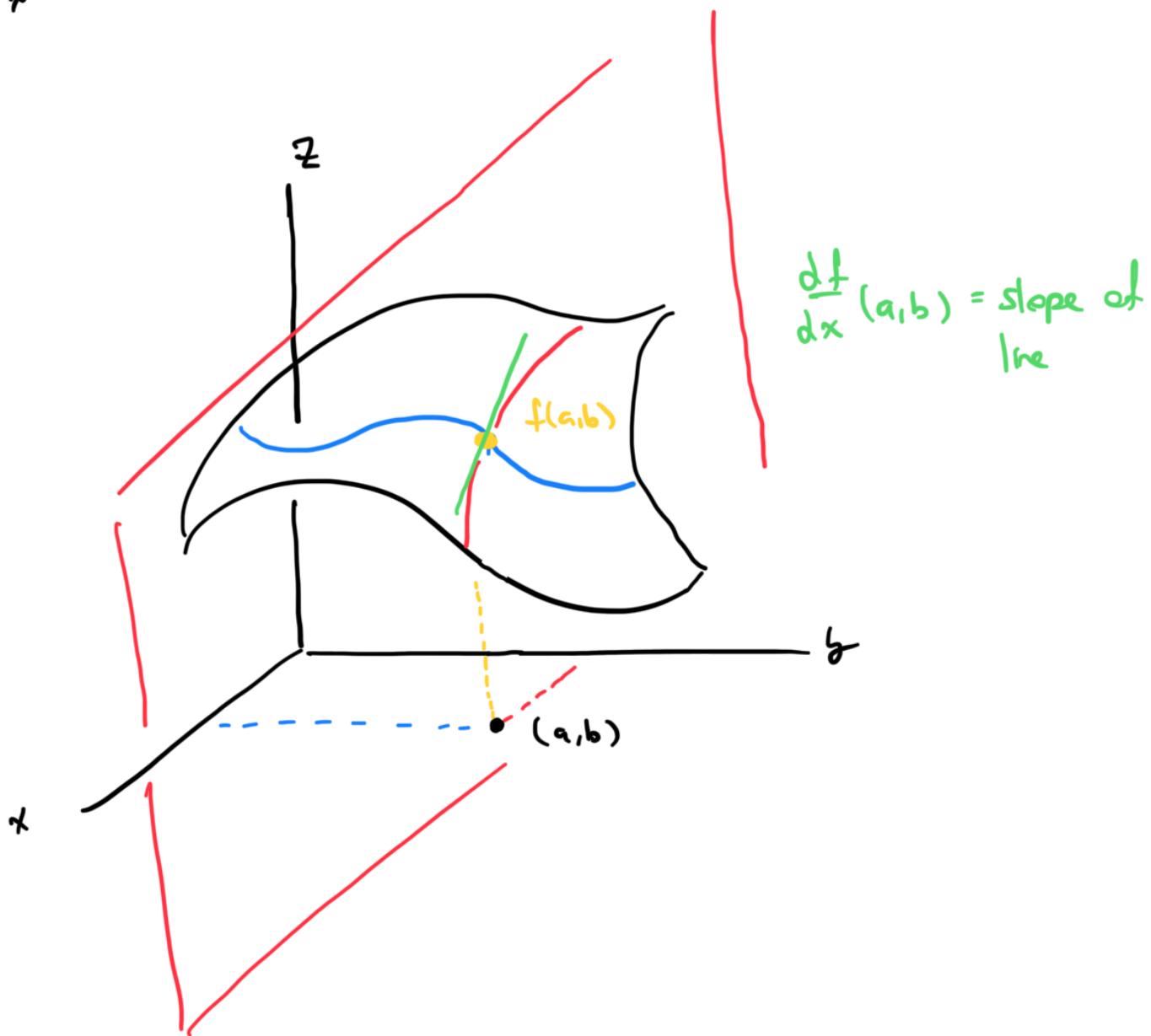
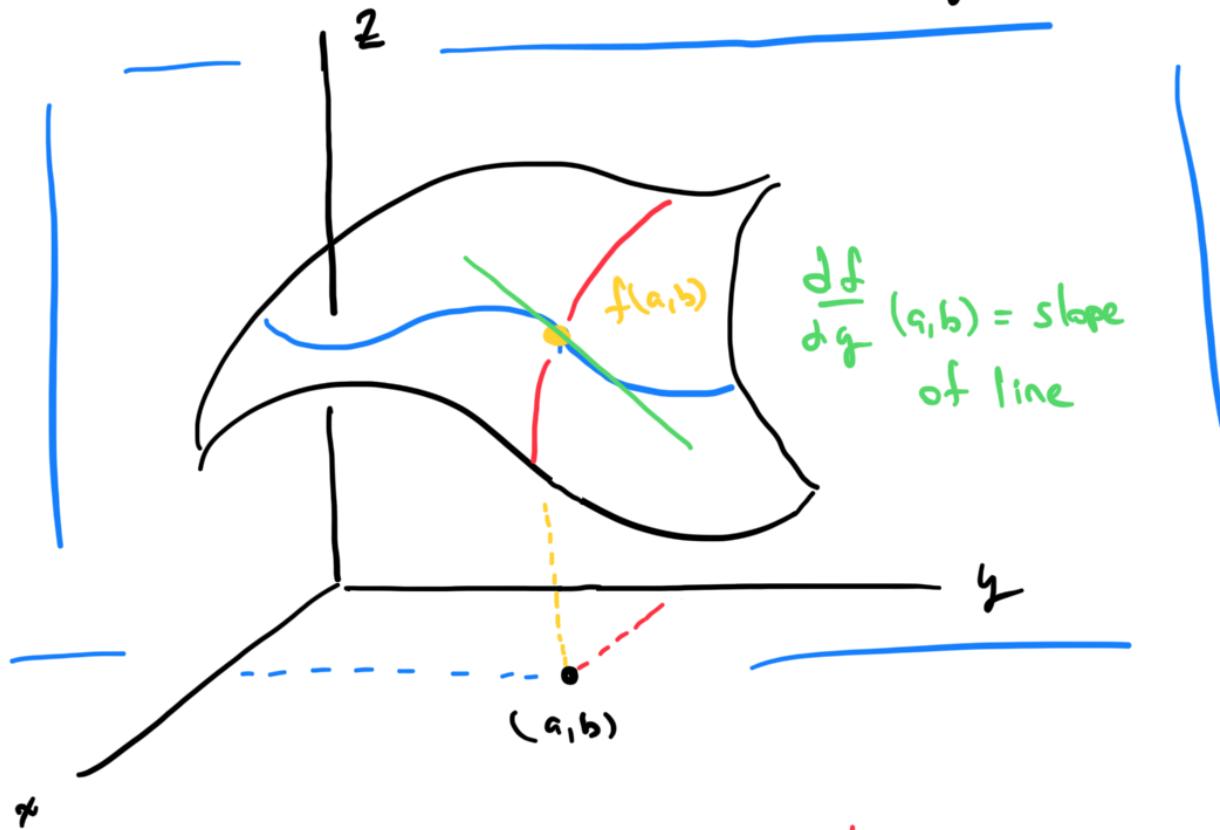
composition $(f \circ g)(x,y)$ where $f(u)$ continues
at $\lim g(x,y) \rightarrow L$

14.3: Partial derivatives

$z = f(x,y)$ then we can define partial derivatives
which measure how a function changes as one variable
changes and the other stays fixed.

$$\frac{\partial f}{\partial x}(a,b) := \lim_{\Delta x \rightarrow 0} \frac{f(a+\Delta x, b) - f(a, b)}{\Delta x}$$

$$\frac{\partial f}{\partial y}(a, b) := \lim_{\Delta y \rightarrow 0} \frac{f(a, b + \Delta y) - f(a, b)}{\Delta y}$$



$$\text{ex: } f(x, y) = x \cos(xy)$$

$$\frac{\partial f}{\partial x} = x \frac{\partial}{\partial x} \cos(xy) = x (-\sin(xy)) \frac{\partial}{\partial x} (xy)$$

$$\partial f / \partial x = -\alpha \sin(xy)(x) = -x^2 \sin(xy)$$

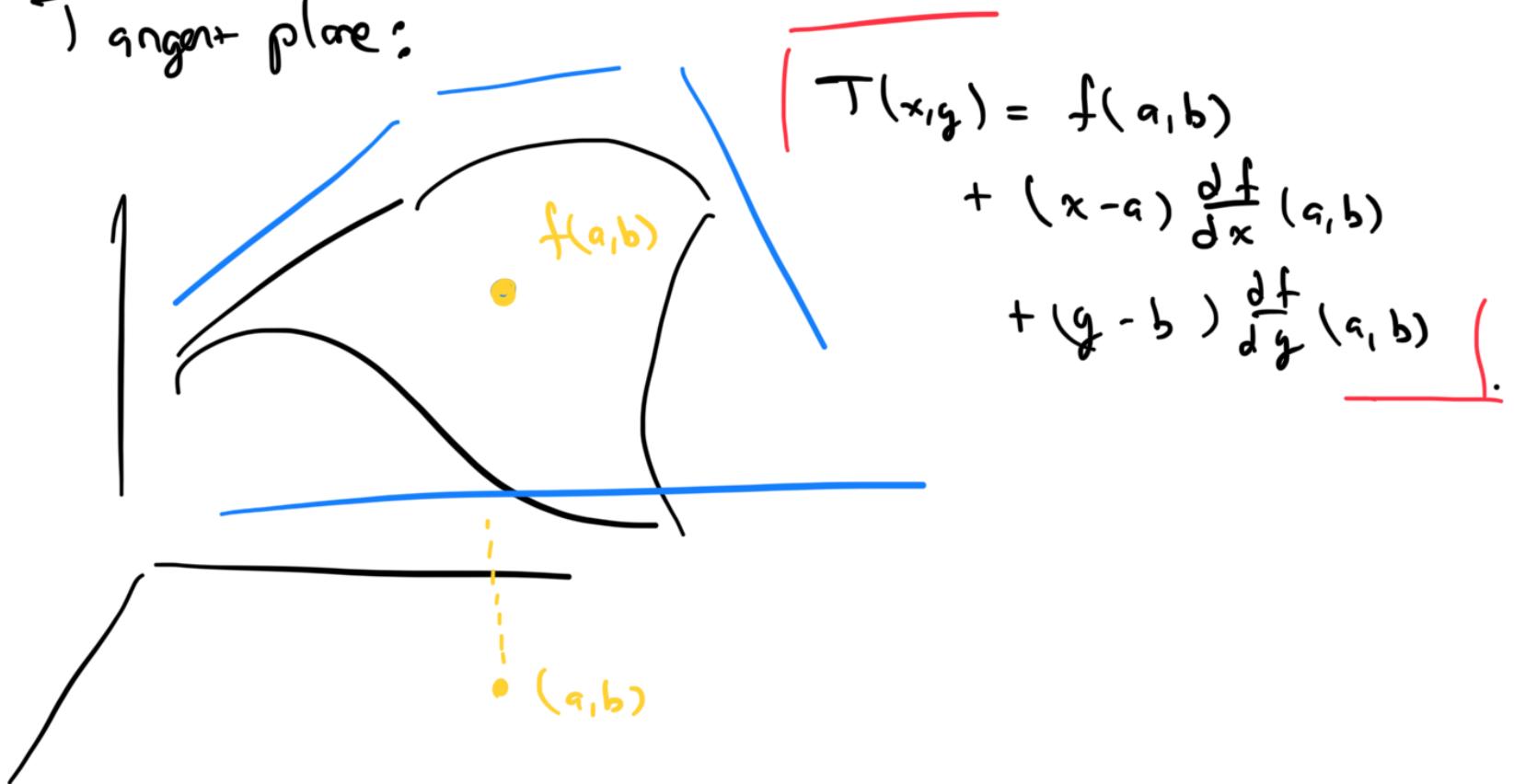
$$= -\alpha \sin(xy)(x) = -x^2 \sin(xy)$$

$$\frac{\partial f}{\partial x} = \frac{\partial}{\partial x} (x \cos(xy)) = (\frac{\partial}{\partial x} x) \cos(xy) + x \frac{\partial}{\partial x} (\cos(xy))$$

$$= 1 \cos(xy) + x (-\sin(xy) \frac{\partial}{\partial x} (xy))$$

$$= \cos(xy) - x \sin(xy)(y) = \cos(xy) - xy \sin(xy)$$

Tangent plane:



$$\text{ex: } f(x,y) = x e^{x \sin(y)}$$

Calculate tangent plane to $f(x,y)$ at point

$$(x,y) = (0,\pi)$$

$$\frac{\partial f}{\partial x} = \left(\frac{\partial}{\partial x} x \right) e^{x \sin(y)} + x \frac{\partial}{\partial x} (e^{x \sin(y)})$$

$$= e^{x \sin(y)} + x e^{x \sin(y)} \frac{\partial}{\partial x} (x \sin(y))$$

$$= e^{x \sin(y)} + x e^{x \sin(y)} \sin(y)$$

$$\begin{aligned}\frac{\partial f}{\partial y} &= \frac{\partial}{\partial y}(x e^{x \sin(y)}) = x \frac{\partial}{\partial y}(e^{x \sin(y)}) \\ &= x e^{x \sin(y)} \frac{\partial}{\partial y}(x \sin(y)) \\ &= x e^{x \sin(y)} x \cos(y) = x^2 e^{x \sin(y)} \cos(y)\end{aligned}$$

$$\begin{aligned}\frac{\partial f}{\partial x}(0, \pi) &= e^0 + 0 = 1 \quad \frac{\partial f}{\partial y}(0, \pi) = 0 \\ \text{So tangent plane is } &\quad \text{and } f(0, \pi) = 0\end{aligned}$$

$$\begin{aligned}T(x, y) &= f(0, \pi) + \frac{\partial f}{\partial x}(0, \pi)(x - 0) + \frac{\partial f}{\partial y}(0, \pi)(y - 0) \\ &= 0 + x + 0 = x\end{aligned}$$

ex : Is there a function $f(x, y)$ for which

$$\frac{\partial f}{\partial x}(x, y) = x^2 y \quad \text{and} \quad \frac{\partial f}{\partial y}(x, y) = x y^2 ?$$

Mixed partials (typically) agree.

$$\frac{\partial^2 f}{\partial y \partial x} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) = \frac{\partial}{\partial y}(x^2 y) = x^2 \quad \text{and}$$

$$\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right) = \frac{\partial}{\partial x}(x y^2) = y^2$$

so no!

$$\text{What if } \frac{\partial f}{\partial x} = 2xy + y^2 + x^2 \text{ and } \frac{\partial f}{\partial y} = x^2 + 2xy$$

$$\text{then quick check } \frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x}$$

$$\text{also notationally } f''_{xy} = f''_{yx}$$

How to find on f^2

$$\frac{df}{dy} = x^2 + 2xy \text{ so } f(x,y) = x^2 \int dy + 2x \int y dy \\ = x^2 y + xy^2 + \underline{\underline{h(x)}}$$

$$\frac{\partial f}{\partial x} = 2xy + y^2 + h'(x) = 2xy + y^2 + x^2$$

$$\text{get } h'(x) = x^2 \text{ so } h(x) = \frac{1}{3}x^3 + C$$

$$\text{and } f(x,y) = x^2 y + xy^2 + \frac{1}{3}x^3 + C$$

14.4 : Chain rule

Easiest explained by examples. However for now

let $z = f(x,y)$ and x be a function of t
 y be a function of t

$$\text{then } \frac{dz}{dt} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt}$$

$$\text{ex: } z = x^2 - y^2 \quad \text{and} \quad x(t) = \cos(t) \\ y(t) = \sin(t)$$

$$\text{then } \frac{dz}{dt} = \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt}$$

$$\frac{\partial z}{\partial x} = 2x \quad \frac{\partial z}{\partial y} = -2y \quad \frac{dx}{dt} = -\sin t \quad \frac{dy}{dt} = \cos t \\ = 2 \cos t \quad = -2 \sin t \quad \text{so}$$

$$\frac{dz}{dt} = 2 \cos t (-\sin t) + (-2 \sin t) (\cos t)$$

$$= -2 \sin(2x)$$

In fact, $z(x) = \cos^2 x - \sin^2 x = \cos(2x)$
 $\text{so } \frac{dz}{dx} = -\sin(2x)(2)$

ex: $f(x, y, z) = \sin x \cos y \tan z$ and want

$$\frac{df}{dx}(0) \text{ where } x(t) = t \quad y(t) = -t \quad \text{and} \\ z(t) = \tan^{-1}(t)$$

$$\frac{df}{dt} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} + \frac{\partial f}{\partial z} \frac{dz}{dt}$$

$$\frac{\partial f}{\partial x} = \cos x \cos y \tan z = (\cos^2 t) \tan(\tan^{-1}(t)) \\ = t \cos^2 t$$

$$\frac{\partial f}{\partial y} = -\sin x \sin y \tan z = -(\sin^2 t) t$$

$$\frac{\partial f}{\partial z} = \sin x \cos y \sec^2 z = \sin x \cos y (1 + \tan^2 z) \\ = \sin t \cos t (1 + \tan^2 t)$$

$$\frac{dx}{dt} = \cos t \quad \frac{dy}{dt} = -\sin t \quad \frac{dz}{dt} = \frac{1}{1+t^2}$$

$$\text{so } \frac{df}{dt}(0) = (0)(1) + (0)(0) + (0)(1) = 0$$

Can see this simply by

$$f(t) = (\sin t \cos t) t = \frac{1}{2} \sin(2t) t$$

$$\frac{df}{dt} = \left(\frac{1}{2} \cos(2t) \cdot 2 \right) \cdot t + \left(\frac{1}{2} \sin(2t) \right) \cdot 1$$

$$\frac{df}{dt}(0) = 0$$

What if have more than one variable, i.e. a surface?

ex: $w = f(x, y, z)$ where $x(u, v), y(u, v), z(u, v)$?

Pretty much the same thing.

$$\frac{\partial w}{\partial u} = \frac{\partial w}{\partial x} \frac{\partial x}{\partial u} + \frac{\partial w}{\partial y} \frac{\partial y}{\partial u} + \frac{\partial w}{\partial z} \frac{\partial z}{\partial u} \text{ and}$$

$$\frac{\partial w}{\partial v} = \frac{\partial w}{\partial x} \frac{\partial x}{\partial v} + \frac{\partial w}{\partial y} \frac{\partial y}{\partial v} + \frac{\partial w}{\partial z} \frac{\partial z}{\partial v}$$

ex: $w = x^2 + y^2 + z^2$ $x = \sin u \cos v$

Want $\frac{\partial w}{\partial u}$. $y = \sin u \sin v$
 $z = \cos u$

$$\frac{\partial w}{\partial x} = 2x \quad \frac{\partial w}{\partial y} = 2y \quad \frac{\partial w}{\partial z} = 2z$$

$$w_x = 2 \sin u \cos v \quad w_y = 2 \sin u \sin v \quad w_z = 2 \cos u$$

$$\frac{\partial x}{\partial u} = \cos u \cos v \quad \frac{\partial y}{\partial u} = \cos u \sin v \quad \frac{\partial z}{\partial u} = -\sin u$$

$$\begin{aligned} w_u &= (2 \sin u \cos v)(\cos u \cos v) \\ &\quad + (2 \sin u \sin v)(\cos u \sin v) \\ &\quad + (2 \cos u)(-\sin u) \end{aligned}$$

$$\begin{aligned} &= (2 \sin u \cos u) \underline{\cos^2 v} + (2 \sin u \cos u) \underline{\sin^2 v} \\ &\quad - 2 \cos u \sin u = 0 \end{aligned}$$

Let's try w_v . We already have some terms. Just

need $\frac{\partial x}{\partial v}, \frac{\partial y}{\partial v}, \frac{\partial z}{\partial v}$

$$\frac{\partial x}{\partial u} = -\sin u \sin v \quad \frac{\partial y}{\partial u} = \sin u \cos v \quad \frac{\partial z}{\partial u} = 0$$

$$\text{so } \frac{\partial w}{\partial u} = (\sin u \cos v)(-\sin u \sin v) + (\sin u \sin v)(\sin u \cos v) + 0 = 0$$

$$\text{so } w_u = 0$$

$$\begin{aligned}\text{In fact... } w(u, v) &= (\sin u \cos v)^2 + (\sin u \sin v)^2 \\ &\quad + (\cos u)^2 \\ &= (\sin^2 u)(\cos^2 v + \sin^2 v) + (\cos^2 u) \\ &= 1\end{aligned}$$

$$\text{so } \frac{\partial w}{\partial u} = 0 \text{ and } \frac{\partial w}{\partial v} = 0!$$

implied differentiation:

Say have z implicitly defined in terms of x, y , e.g. $x^2 + y^2 - z^2 = A3$

Want to calculate $\frac{\partial z}{\partial x}$ at a point, e.g. $(2, 0, 1)$

You do so by differentiating.

$$\frac{\partial}{\partial x}(x^2 + y^2 - z^2) = \frac{\partial}{\partial x} B3$$

$$2x + 0 - 2z \frac{\partial z}{\partial x} = 0 \text{ so}$$

$$\frac{\partial z}{\partial x} = \frac{x}{z} \quad \text{thus } \frac{\partial z}{\partial x}(2, 0) = \frac{2}{1} = 2$$

Ex: $\sin(xy^2) + e^z = 1$ calculate $\frac{\partial g}{\partial x}$ and $\frac{\partial g}{\partial z}$
at $(\pi, 1, 0)$.

$$\frac{\partial}{\partial x} (\sin(xy^2) + e^z) = \frac{\partial}{\partial x}(1)$$

$$\cos(xy^2) \frac{\partial}{\partial x}(xy^2) + 0 = 0$$

$$\cos(xy^2) (1 + x \cdot 2y \frac{\partial y}{\partial x}) = 0 \quad \text{plug in } (\pi, 1, 0)$$

$$\cos(\pi) (1 + 2\pi \frac{\partial y}{\partial x}) = 0 \quad \text{so} \quad \frac{\partial y}{\partial x}(\pi, 0) = -\frac{1}{2\pi}$$

$$\frac{\partial}{\partial z} (\sin(xy^2) + e^z) = \frac{\partial}{\partial z}(1)$$

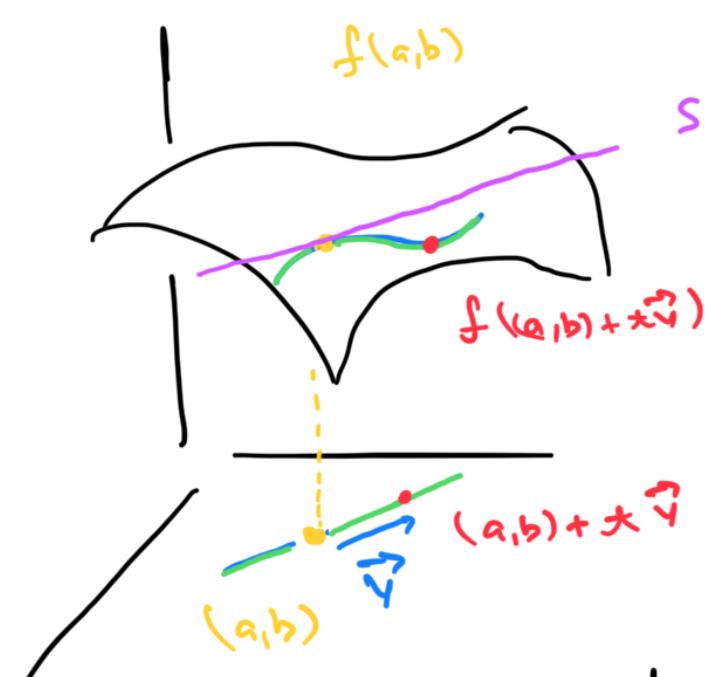
$$\cos(xy^2) \frac{\partial}{\partial z}(xy^2) + e^z = 0$$

$$\cos(xy^2) x (2y \frac{\partial y}{\partial z}) + e^z = 0 \quad \text{at } (\pi, 1, 0),$$

$$\cos(\pi)(\pi 2) \frac{\partial y}{\partial z}(\pi, 0) + 1 = 0 \quad \text{so}$$

$$\frac{\partial y}{\partial z}(\pi, 0) = +\frac{1}{2\pi}$$

14.5 : Directional derivatives and gradient



$$\text{slope} = \frac{df}{d\vec{v}}(a,b) \\ = \left(\frac{df}{ds} \right)_{(\vec{v}, (a,b))}$$

$$\text{slope} = \lim_{t \rightarrow 0} \frac{f((a,b) + t\vec{v}) - f(a,b)}{t}$$

= scalar quantity measure how fast
f is changing along the vector \vec{v} .

Warning: Book only defines this for unit vectors.

This is absurd, I have no idea why. //

So when they ask something like

"find the derivative of the direction f at (a,b)
in the direction of \vec{v} " they mean make \vec{v}
a unit vector first!

ex: find the derivative of $f(x,y) = xy^2$
at the point (1,1) along the vector $\vec{v} = (3,4)$.
(then do the same for the direction).

$$1. f((1,1) + t(3,4)) - f(1,1)$$

$$\begin{aligned}
 & \lim_{\lambda \rightarrow 0} \frac{f(1+3\lambda, 1+4\lambda) - f(1,1)}{\lambda} = \lim_{\lambda \rightarrow 0} \frac{(1+3\lambda)(1+4\lambda)^2 - 1}{\lambda} \\
 &= \lim_{\lambda \rightarrow 0} \frac{(1+3\lambda)(1+8\lambda+16\lambda^2) - 1}{\lambda} \\
 &= \lim_{\lambda \rightarrow 0} \frac{11\lambda + 40\lambda^2 + 48\lambda^3}{\lambda} = \lim_{\lambda \rightarrow 0} \frac{11\lambda}{\lambda} + \text{stuff} \cdot \lambda = 11
 \end{aligned}$$

If the book asks for direction, $\alpha = (\frac{3}{5}, \frac{4}{5})$

$$\begin{aligned}
 & \lim_{\lambda \rightarrow 0} \frac{f((1,1) + \lambda(\frac{3}{5}, \frac{4}{5})) - f(1,1)}{\lambda} = \frac{11}{5} \text{ why?} \\
 &= (D_{\vec{\alpha}} f)(1,1)
 \end{aligned}$$

In general note for a vector \vec{v} ,

$$(D_{\vec{v}} f)(a,b) = \frac{df}{d\vec{v}}(a,b) = \lim_{\lambda \rightarrow 0} \frac{f((a,b) + \lambda(v_x, v_y)) - f(a,b)}{\lambda}$$

$$f(\vec{x}) = (a,b) + \lambda(v_x, v_y) \text{ then}$$

$$(D_{\vec{v}} f)(a,b) = \left. \frac{df}{d\lambda} \right|_{\lambda=0} (f \circ g)(\vec{x}) \text{ which we may use chain-rule,}$$

$$= \frac{\partial f}{\partial x}(f(0)) \frac{\partial x}{\partial \lambda}(0) + \frac{\partial f}{\partial y}(f(0)) \frac{\partial y}{\partial \lambda}(0)$$

$$= \left(\frac{\partial f}{\partial x}(a,b), \frac{\partial f}{\partial y}(a,b) \right) \cdot (v_x, v_y)$$

$$\text{so } (D_{\vec{v}} f)(a,b) = \left(\frac{\partial f}{\partial x}(a,b), \frac{\partial f}{\partial y}(a,b) \right) \cdot \vec{v}$$

We have $(\nabla f)(a,b) = \vec{v}$ called

the gradient of f //

ex: Find the directional derivative of

$f(x,y) = x \sin(y)$ at $(1,\pi)$ along the vector $\vec{v} = (1,2)$.

$$\vec{u} = \left(\frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}} \right)$$

$$(D_{\vec{u}} f)(1,\pi) = \nabla f(1,\pi) \cdot \vec{u}$$

$$\begin{aligned} (\nabla f)(1,\pi) &= (\sin(y), x \cos(y)) \Big|_{(1,\pi)} \\ &= (0, -1) \end{aligned}$$

$$\text{so } (D_{\vec{u}} f)(1,\pi) = (0, -1) \cdot \left(\frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}} \right) = -\frac{2}{\sqrt{5}} < 0$$

The formula $(D_{\vec{v}} f)(a,b) = \nabla f(a,b) \cdot \vec{v}$ is very telling in so far as it gives us that

$$(D_{\vec{v}} f)(a,b) = \nabla f(a,b) \cdot \vec{v} = |\nabla f(a,b)| |\vec{v}| \cos \theta$$

$$\text{so } -|\nabla f(a,b)| |\vec{v}| \leq (D_{\vec{v}} f)(a,b) \leq |\nabla f(a,b)| |\vec{v}|$$

bc $-1 \leq \cos \theta \leq 1$. This quantity is maximized if $\cos \theta = 1$, i.e. $\theta = 0$, so \vec{v} and $\nabla f(a,b)$ point same direction.

$\cos \theta = -1$ i.e. $\theta = \pi$, so \vec{v} and $\nabla f(a,b)$ point opposite direction.

thus f increases most in direction of ∇f
 and f decreases most in direction of $-\nabla f$.

Similarly, $(D_{\vec{v}} f)(a, b) = \nabla f(a, b) \cdot \vec{v} = 0$

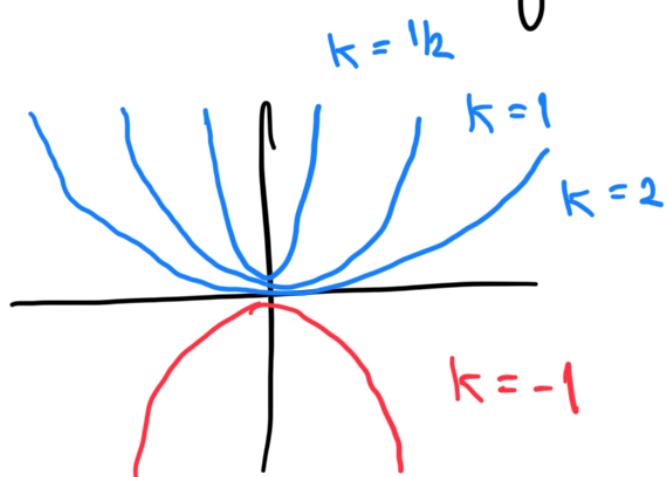
if $\vec{v} \perp \nabla f(a, b)$, thus f is
 not changing if $\vec{v} \perp \nabla f(a, b)$!

so f is constant along direction \perp to ∇f !

ex: $f(x, y) = \frac{x^2}{y}$ on domain $y \neq 0$.

Draw level curves, $\frac{x^2}{y} = k$ for constant k

means that $y = k^{-1}x^2$

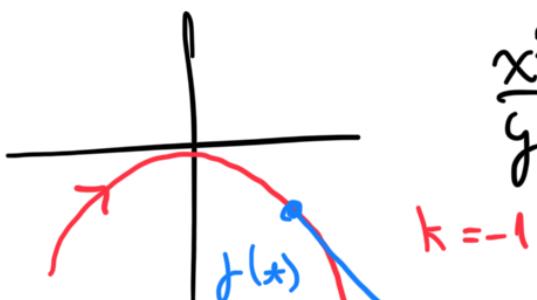


Okay, let's calculate
the gradient at a point

(a, b) .

$$\begin{aligned} (\nabla f)(a, b) &= \left(\frac{\partial f}{\partial x}(a, b), \frac{\partial f}{\partial y}(a, b) \right) \\ &= \left(\frac{2x}{y}, -\frac{x^2}{y^2} \right) \Big|_{(a, b)} = \left(\frac{2a}{b}, -\frac{a^2}{b^2} \right) \end{aligned}$$

let's choose a level curve. Say $k = -1$.



$\frac{x^2}{y} = -1$. Now you can parametrize
by $f(x) = (x, -x^2)$

so $f'(x) = (1, -2x)$

$$(\pm, -\pm^2) \quad f'(x) = (1, -2x). \quad \text{so } \vec{u}(x) = \frac{(1, -2x)}{\sqrt{1+4x^2}}$$

So now if take $(D_{\vec{u}(x)} f)(f(x))$

$$= (\nabla f)(f(x)) \cdot \vec{u}(x)$$

$$= \left(2 \frac{x}{-x^2}, -\frac{x^2}{x^4} \right) \cdot (1, -2x) / \sqrt{1+4x^2}$$

$$= \left(-\frac{2}{x}, -\frac{1}{x^2} \right) \cdot \frac{(1, -2x)}{\sqrt{1+4x^2}} = \frac{-\frac{2}{x} + \frac{2}{x}}{\sqrt{1+4x^2}} \text{ for } x \neq 0$$

that means f not changing in the direction of $f'(x)$!

(But this is not surprising at all,
it's because $f(x)$ is a level curve!)

This principle holds in general.

- the gradient is orthogonal to level curves!

Some properties: $\nabla(f \pm g) = \nabla f \pm \nabla g$

$\nabla(cf) = c\nabla f$ c constant

$$\nabla(fg) = (\nabla f)g + f(\nabla g)$$

$$\nabla\left(\frac{f}{g}\right) = \frac{g \nabla f - (\nabla g)f}{g^2}$$

$$\text{ex: } f(x, y, z) = x^2 + y^2 - z^2.$$

At the point $(1, 2, 3)$ find the direction for which f is increasing the most.

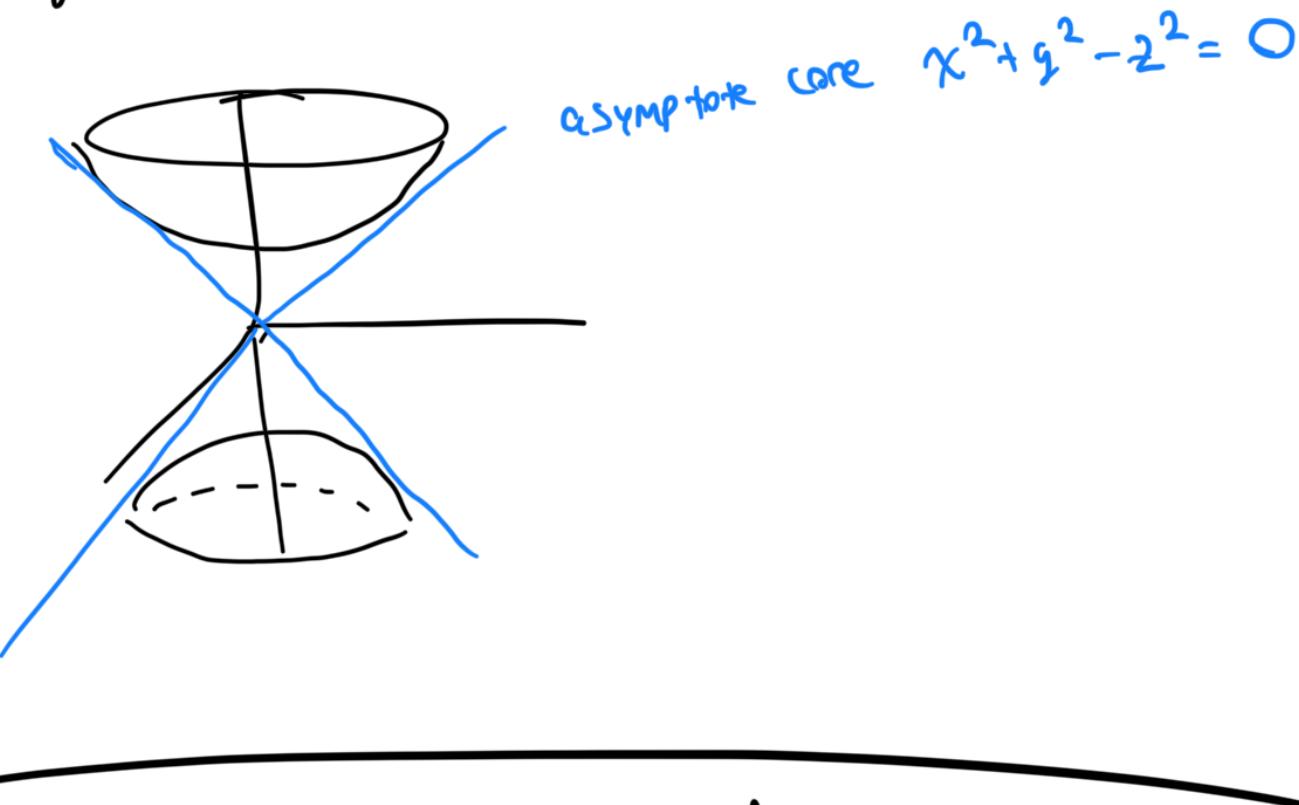
$$\nabla f = (2x, 2y, -2z) \text{ so}$$

$(\nabla f)(1, 2, 3) = (2, 4, -6)$, direction of greatest increase

$$\text{is } \frac{(2, 4, -6)}{\|(2, 4, -6)\|} = \frac{(1, 2, -3)}{\sqrt{14}}$$

Calculate a vector normal to the surface

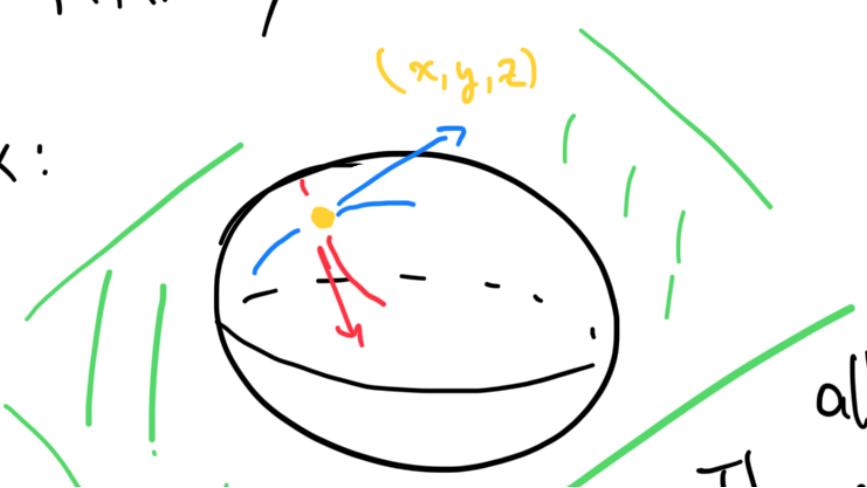
$$x^2 + y^2 - z^2 = -1. \quad (\nabla f)(x, y, z) = (2x, 2y, -2z)$$



14.6: Tangent planes and differentials

intuitively have an idea of this

ex:



consider all paths through point (x_1, y_1, z_1) on your surface S and take

all possible tangent lines.

This is your tangent plane.

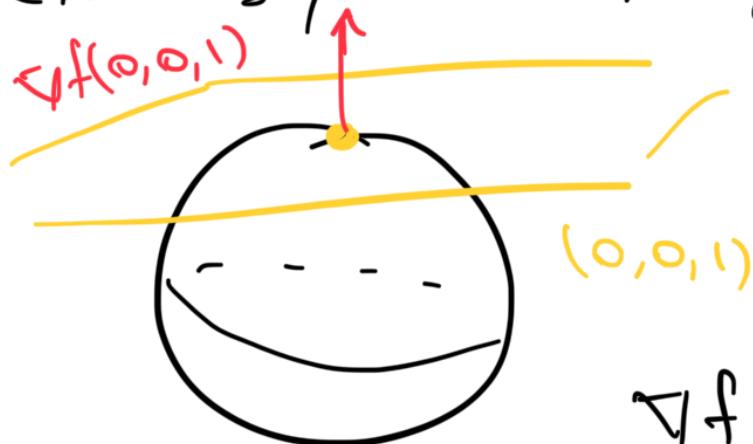
As we know a plane is also specified by a point and normal vector. So we have the following.

Let S be surface defined by $f(x, y, z) = C$.

Let (a, b, c) be a point on S . The tangent plane is going to be all lines through (a, b, c) that are \perp to $\nabla f(a, b, c)$ because $\nabla f(a, b, c)$ is \perp to level curves. So get condition

$$\nabla f(a, b, c) \cdot (x - a, y - b, z - c) = 0 \quad (\leftarrow)$$

Ex: Say have $x^2 + y^2 + z^2 = 1$



so intuitively plane is $z = 1$.
Check. $f(x, y, z) = x^2 + y^2 + z^2$

$$\nabla f = (2x, 2y, 2z)$$

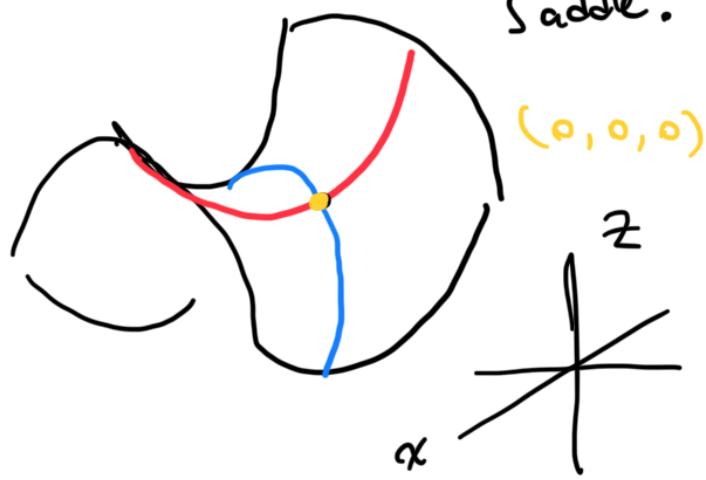
So $\nabla f(0, 0, 1) = (0, 0, 2)$ tangent plane is

$$(\nabla f)(0, 0, 1) \cdot (x - 0, y - 0, z - 1) = 0$$

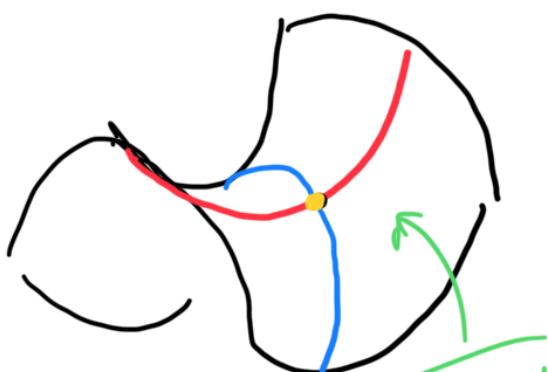
$$(0, 0, 2) \cdot (x, y, z - 1) = 0$$

$$2(z - 1) = 0 \sim z = 1 !$$

Ex: $f(x, y) = x^2 - y^2 = z$



Want tangent plane at
(0, 1, -1)



$$g(x, y, z) = f(x, y) - z \\ = (x^2 - y^2) - z$$

$$\nabla g(x, y, z) = (2x, -2y, -1) \text{ just proceed}$$

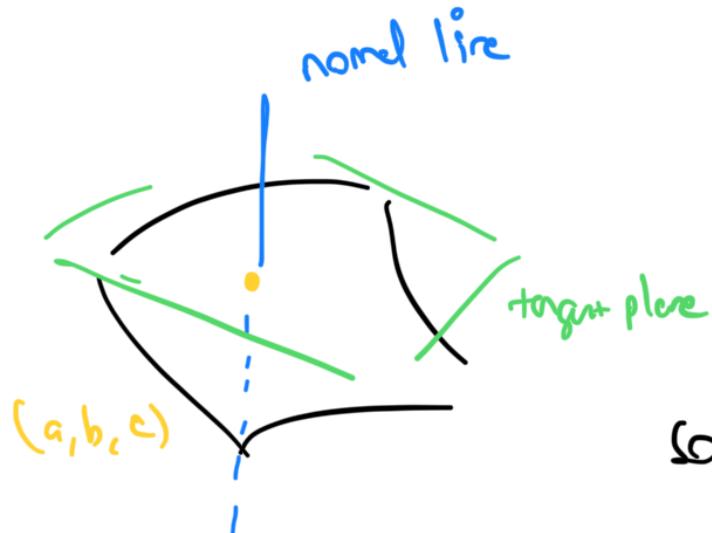
as normd.

$$\nabla g(0, 1, -1) = (0, -2, -1) = \vec{n}$$

$$\text{Se } \vec{n} \cdot (x - 0, y - 1, z - (-1)) = 0$$

$$-2(y-1) - 1(z+1) = 1 - 2 - 2 = 0$$

Want normal line through a point on a surface?



if surface is $f(x, y, z) = C$

then $\nabla f(a, b, c)$ will be
 \perp to level curve at (a, b, c) .

so normal line is

$$L(x) = (a, b, c) + \lambda \nabla f(a, b, c)$$

ex: Calculate normal line at point (0, 1, -1)
as above.

$$g(x, y, z) = x^2 - y^2 - z \quad \text{so } \nabla g = (2x, -2y, -1)$$

v

$$\text{thus } L(x) = (0, 1, -1) + x(0, -2, -1)$$

$$= (0, 1-2x, -1-x)$$

Why care about linearizing? Use it to approximate.

Recall that $\frac{df}{d\vec{v}}(a, b) = \nabla f(a, b) \cdot \vec{v}$

so we should have that $df(a, b)$ is related to
 $\nabla f(a, b) \cdot \vec{v}$ and $d\vec{v}$

Choose a small $x \approx 0$. Then we have,

$$f((a, b) + x\vec{v}) \approx f(a, b) + x \nabla f(a, b) \cdot \vec{v} \quad (\star)$$

first order taylor approximation.

so that is to say $\Delta(\vec{v}) \approx x \nabla f(a, b) \cdot \vec{v}$
(text uses df)

ex: $f(x, y) = x^2 \cos(y)$ at $(1, \pi/2)$. Want to estimate the change of f if change the point $(1, \pi/2)$

0.1 cm in the direction of $(\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2})$.

$$\vec{u} = \left(\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}\right)$$

$$(0, \pi/2) \quad \nabla f(x, y) = (2x \cos y, -x^2 \sin y)$$

$$\nabla f(1, \pi/2) = (0, 1) \text{ so } \Delta f \approx (0, 1) \cdot \left(\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}\right)$$

$$\Delta f \approx -\frac{\sqrt{2}}{20} \approx -0.0707 \dots \text{ so the answer}$$

+ \ point) - $f(0,0) \approx -0.0 +$ and in fact,

$$f\left(\left(1, \frac{11}{2}\right)(0.1)\vec{u}\right) \approx -0.08 \text{ and } f(0,0) = 0$$

So good estimate.

Another way is the tangent plane, though it's
severely the same method pretty much.

Recall

$$L(x,y) = f(a,b) + \frac{\partial f}{\partial x}(a,b)(x-a) + \frac{\partial f}{\partial y}(a,b)(y-b)$$

ex:

Say you're measuring height at some mountain
and at coordinate $(a,b) = (10m, 20m)$ you estimate
the elevation is changing -2 in the x -direction and
 $+3$ in the y -direction. (m/m^2)
if at point $(10m, 20m)$ you measure the height
to be $100m$, approximate the height at $(10.1m, 20.3m)$

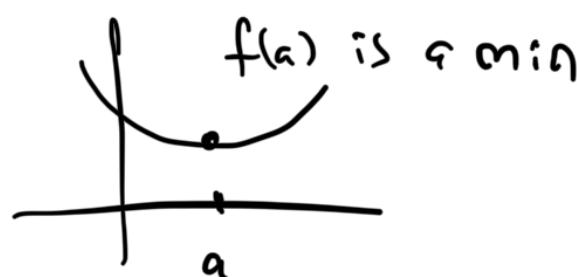
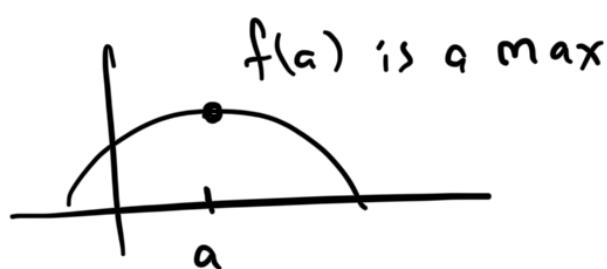
$$L(x,y) = f(10,20) + \frac{\partial f}{\partial x}(10,20)(x-10) + \frac{\partial f}{\partial y}(10,20)(y-20)$$

$$\begin{aligned} \text{so } L(x,y) &= 100 + (-2)(0.1) + (+3)(0.3) \\ &= 100 - 0.2 + 0.9 = 100.7m \end{aligned}$$

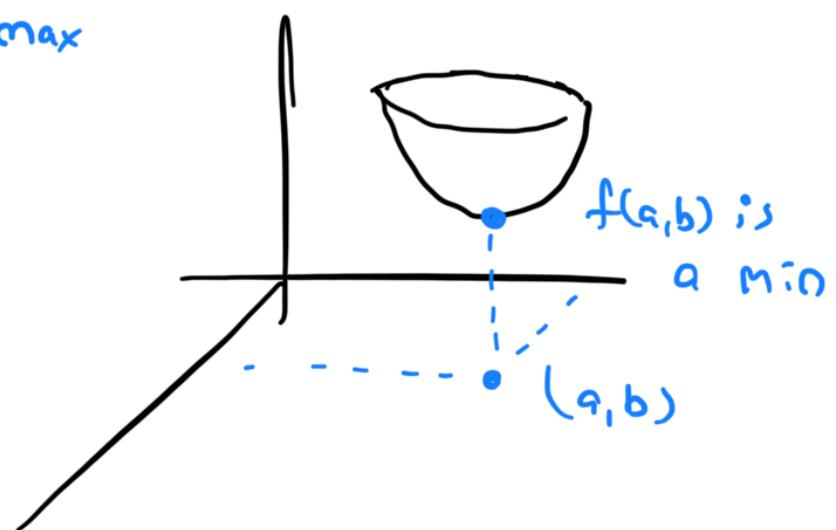
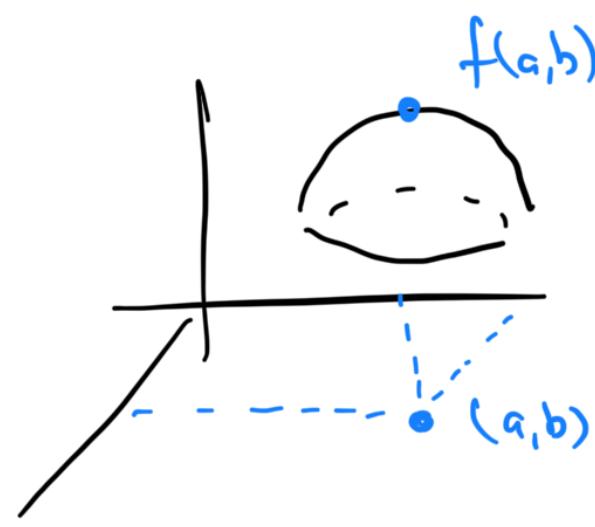
So we estimate height to be $100.7m$ at
 $(10.1m, 20.3m)$

14.7: Extreme-values and Saddle points

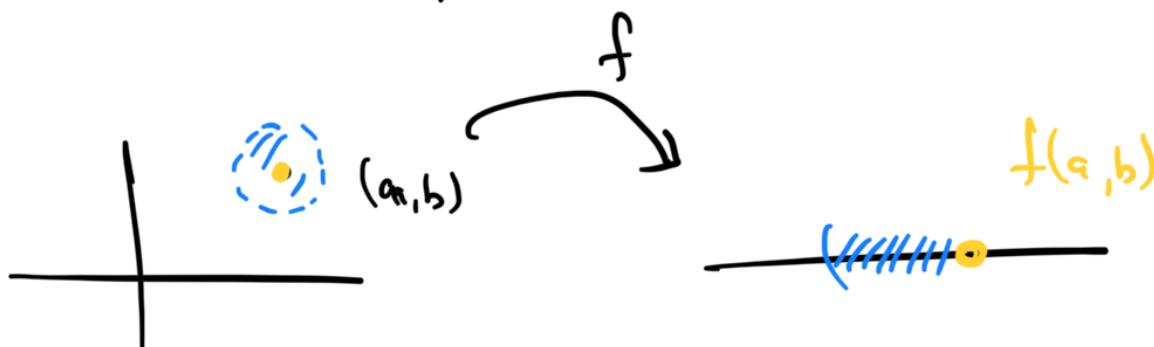
intuitively we have an idea from 1D-calc.



in 2D things are similar, but more subtle.



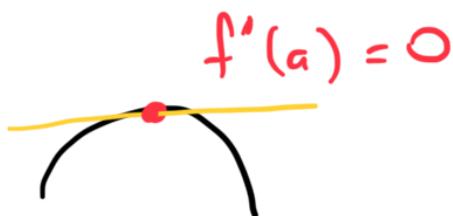
Def: A point (a,b) is a local maximum if
find a small ball about (a,b) so that
for all points (x,y) in the ball, $f(x,y) \leq f(a,b)$.



$f(a,b)$ is the local
max-value.

local min - similar picture / definition. (pg 860)

Recall from Calc 1 if $x=a$ is a max/min
then $f'(a) = 0$



Similar statement holds in 2D.

Theorem: If (a, b) is a local max/min,

at an interior point of domain, then

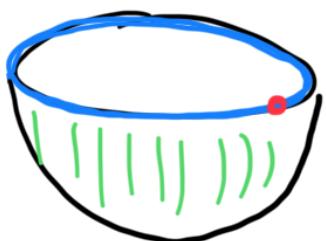
$$\frac{\partial f}{\partial x}(a, b) = \frac{\partial f}{\partial y}(a, b) = 0$$

picture to have in mind is



$Z = f(a, b)$
is tangent plane.

interior point stuff is because



$f(a, b)$ also local max

e.g.: $f(x, y) = x^2 + y^2$ on disk

$$x^2 + y^2 \leq 1.$$



boundary is local maxes, however

$\frac{\partial f}{\partial x}(a, b), \frac{\partial f}{\partial y}(a, b)$ not necessarily zero.

However at point $(a, b) = (0, 0)$, it is true that

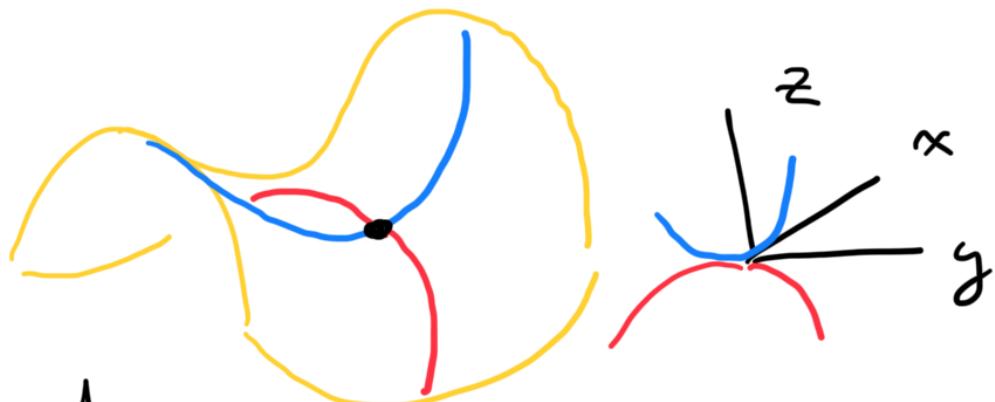
$\frac{\partial f}{\partial x}, \dots, \frac{\partial f}{\partial y}, \dots \sim \text{All zero}$

local min.

Warning! Just like in 1D, $\frac{\partial f}{\partial x}(a,b) = \frac{\partial f}{\partial y}(a,b) = 0$ does not mean (a,b) is local min/max!

e.g.: $f(x,y) = x^2 - y^2$. Certainly $f_x(0,0) = f_y(0,0) = 0$

However,



so there are points where

$f(x,y) > f(0,0)$ and points where $f(x,y) < f(0,0)$.

Def: A critical point for a function $f(x,y)$ is a point (a,b) in the interior of the domain of $f(x,y)$ where either

(i). $f_x(a,b) = f_y(a,b) = 0$ or

(ii). either $f_x(a,b)$ or $f_y(a,b)$ does

not exist.

Can think of these as 'potential' max/min.

Def: A critical point (a,b) is called a saddle point if there are points in every ball about (a,b) that evaluate to values both

bigger and less than $f(a, b)$.

How to tell if a critical point is a local max or local min?

Theorem: 2nd derivative test for $f(x, y)$.

Let (a, b) be a point where f_x and f_y are continuous around it. Assume also that

$f_x(a, b) = f_y(a, b) = 0$ so (a, b) is a critical point.

(i). if $f_{xx} < 0$ and $f_{xx}f_{yy} - f_{xy}^2 > 0$

(at (a, b)), then (a, b) is a local max

(ii). if $f_{xx} > 0$ and $f_{xx}f_{yy} - f_{xy}^2 > 0$
then (a, b) is a local min

(iii). if $f_{xx}f_{yy} - f_{xy}^2 < 0$ then (a, b) is
a saddle point

(iv). if $f_{xx}f_{yy} - f_{xy}^2 = 0$ then test is
inconclusive.

The quantity $\begin{vmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{vmatrix}$ is called the Hessian or
discriminant of f
 $= f_{xx}f_{yy} - f_{xy}^2$ at (a, b) .

Ex: $f(x, y) = x^2 + y^2 - 2$

$$f(x,y) = x + xy - y$$

$$f_x(x,y) = 2x + y \quad f_y(x,y) = x - 2y$$

$$\begin{aligned} 2x + y &= 0 \Rightarrow y = 0 \text{ and } x = 0 \text{ so} \\ x - 2y &= 0 \quad (a,b) = (0,0). \end{aligned}$$

$$f_{xx}(x,y) = 2 \quad f_{xy}(x,y) = 1 \quad f_{yy}(x,y) = -2$$

$$\text{so } f_{xx} + f_{yy} - f_{xy}^2 = -4 - 1 = -5 < 0$$

so $(0,0)$ is a saddle point.

$$\text{ex: } f(x,y) = 3x^3 + 2xy + y^2$$

$$f_x = 9x^2 + 2y \quad f_y = 2x + 2y$$

so setting both $\rightarrow 0$, get $x = -y$

$$\text{and then } 9(-y)^2 + 2y = 0 = y(9y + 2) = 0$$

$$\text{so } y = 0 \text{ or } y = -\frac{2}{9}$$

$$\text{so } (a,b) = (0,0) \text{ or } (a,b) = \left(\frac{2}{9}, -\frac{2}{9}\right).$$

$$\text{Now } f_{xx} = 18x \quad f_{xy} = 2 \quad f_{yy} = 2$$

$$\text{so } f_{xx} + f_{yy} - f_{xy}^2 = 36x - 4 = 4(9x - 1)$$

$$H(0,0) = -4 < 0 \text{ so } (0,0) \text{ is } \underline{\text{saddle}}$$

$$H\left(\frac{2}{9}, -\frac{2}{9}\right) = 4(2-1) > 0 \text{ so either max/min.}$$

$$\text{note } f_{xx}\left(\frac{2}{9}, -\frac{2}{9}\right) = 18\left(\frac{2}{9}\right) > 0$$

so local min

ex: $f(x,y) = 3x^2y - y^3$ Classify all critical points.

$$f_x(x,y) = 6xy \quad f_y(x,y) = 3x^2 - 3y^2$$

So critical points mean $6xy = 0$ and $3x^2 - 3y^2 = 0$

so either $x = 0$ & $-3y^2 = 0 \Rightarrow x = y = 0$

or $y = 0$ & $3x^2 = 0 \Rightarrow x = y = 0$

so only one option $x = y = 0$. $(a,b) = (0,0)$

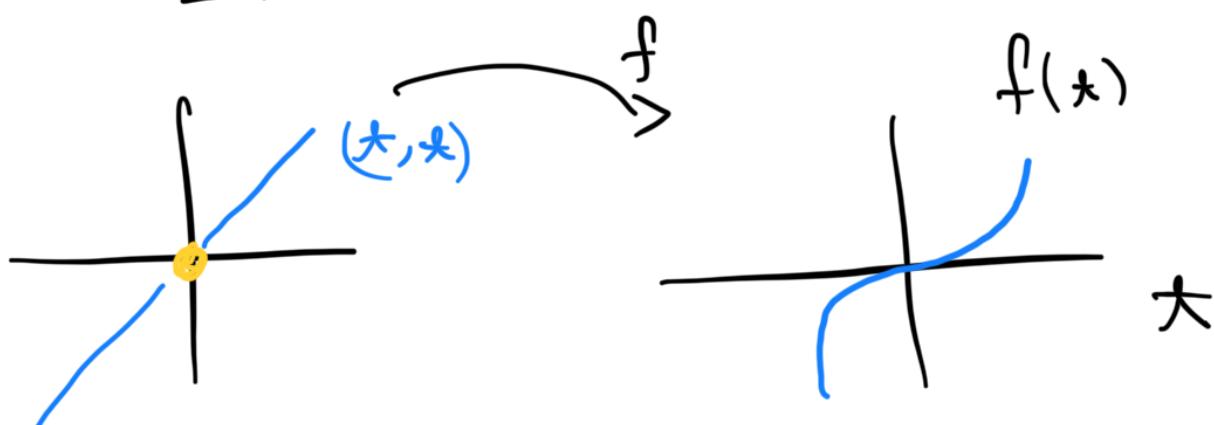
Note $f_{xx}(x,y) = 6y$, $f_{yy}(x,y) = -6y$ and
 $f_{xy}(x,y) = 6x$. Thus

$H(0,0) = 0$. inconclusive. However, note
 that $f(x,x) = 3x^3 - x^3 = 2x^3$.

so along $\gamma(t) = (t,t)$, there are points

so that $f(0,0) = 0 < f(t,t)$ if $t > 0$

and $f(0,0) = 0 > f(t,t)$ if $t < 0$.



so $(0,0)$ is a saddle.

One last example is boundary problems.

ex: Let $f(x,y) = x^2 - y^2$ on unit disk $x^2 + y^2 \leq 1$.

Calculate local max/min and saddles.

$$f_x = 2x, \quad f_y = -2y \quad = 0 \text{ if } x=y=0.$$

$$f_{xx} = 2 \quad f_{yy} = -2 \quad f_{xy} = 0 \quad \text{so}$$

$H(x,y) = -4 < 0$ so $(0,0)$ is a saddle.

What about boundary? Parameterize by

$$J(x) = (\cos x, \sin x). \quad \text{Then}$$



(0,0) saddle

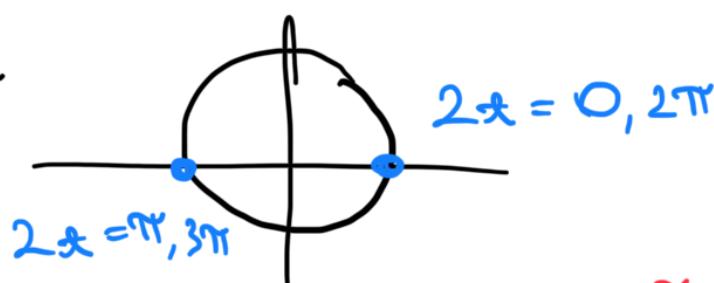
$$f(t) \text{ in white} = (\cos t, \sin t)$$

then along $f(x)$ we have

$(f \circ g)(x) = \cos^2 x - \sin^2 x$. Reche problem zu 1-drausen.

$= \cos(2x)$. Minimize/maximize by

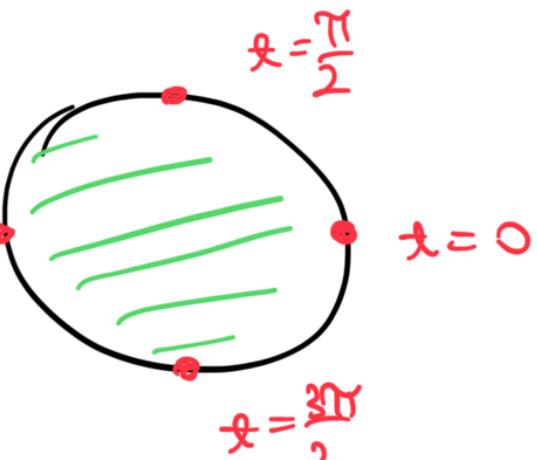
derivative or picture.



$$(f \circ g)'(x) = -2 \sin(2x)$$

$$\text{so } 2x = 0, \pi, 2\pi, 3\pi \text{ so } x = \frac{\pi}{2}$$

$$\alpha = 0, \frac{\pi}{2}, \pi, \frac{3\pi}{2}$$



Now just check

$$f(x_0)) = f(1, 0) = 1^2 - 0^2 = 1$$

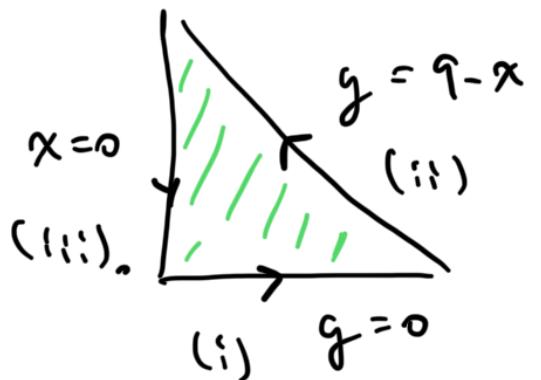
$$f(g(\pi/2)) = f(0,1) = 0^2 - 1^2 = -1 \quad \text{local max is } +1$$

$$f(g(\pi)) = f(-1,0) = 1^2 - 0^2 = 1 \quad \text{and}$$

$$f(g(\frac{3\pi}{2})) = f(0,-1) = 0^2 - (-1)^2 = -1 \quad \text{global min is } -1$$

ex: Just going to loosely explain ex 6 on Pg. 865.

$$f(x,y) = 2+2x+4y-x^2-y^2 \quad \text{on triangle}$$



(iii) you can do, just
 $f_x, f_y, \text{ etc.}$

the other things let's explain.

$$(i). \quad y=0. \quad j(x) = (x,0) \quad \text{from } x=0 \text{ to } x=9$$

$$\text{so } (f \circ j)(x) = 2+2x-x^2. \quad (f \circ j)'(x) = 2-2x=0$$

iff $x=1 \quad j(1) = \underline{(1,0)}$

add to list and $x=0$

$x=1. \quad \underline{(0,0)}, \underline{(0,9)}$

$$(ii). \quad y=9-x \quad j(x) = (9-x, x) \quad \text{from } x=0 \text{ to } x=9.$$

$$(f \circ j)(x) = 2+2(9-x)+4(x)-(9-x)^2-x^2$$

$$= -6x+20x-2x^2$$

$$(f \circ j)'(x) = 20-4x \quad \text{so } x=5, \quad j(5) = \underline{(4,5)}$$

and end points $j(0) = (9,0)$ and $j(9) = \underline{(0,9)}$

$$(iii) \quad x=0 \quad L(x) = (0, 9-x) \quad \text{from } x=0 \text{ to } x=9$$

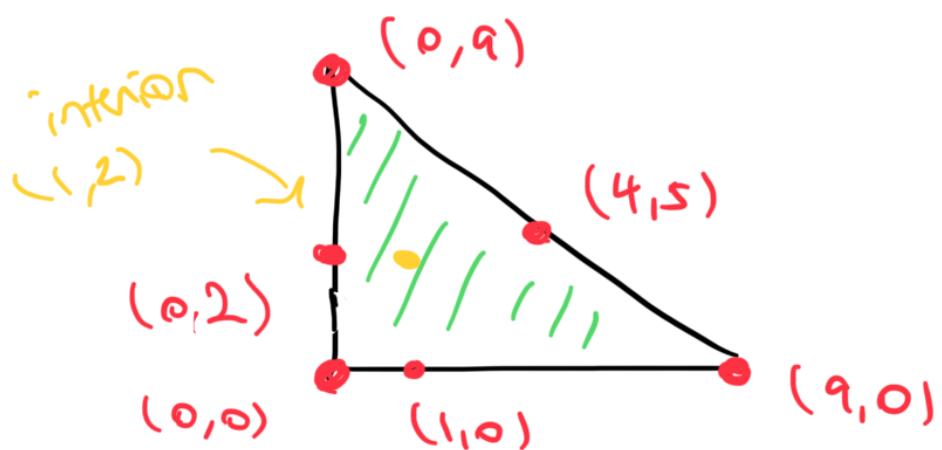
$$(f \circ g)(x) = 2 + 4(9-x) - (9-x)^2$$

$$= -4x^2 + 14x - 43$$

so $(f \circ g)'(x) = 14 - 2x = 0$ at $x =$

so $g(7) = \underline{(0, 2)}$

so list of points to on boundary are



14.8 : Lagrange Multipliers

Constrained optimization problems.

ex: Calculate the point on the plane

$$2x + 3y + z = 5 \quad \text{closest to the origin.}$$

could think of this as minimizing the function

$$f(x, y, z) = \sqrt{x^2 + y^2 + z^2} = \text{dist}((x, y, z), (0, 0, 0)).$$

minimizing \uparrow is same as minimizing the square though so

instead lets take $f(x, y, z) = x^2 + y^2 + z^2$.

However, we want our point Φ to lie in the plane

$Z = 5 - 2x - 3y$. So minimize

$$f(x, y) = x^2 + y^2 + (5 - 2x - 3y)^2$$

$$f_x = 2x + 2(5 - 2x - 3y)(-2) = 2(-10 + 5x + 6y) = 0$$

$$f_y = 2y + 2(5 - 2x - 3y)(-3) = -30 + 12x + 20y = 0$$

$$\begin{aligned} \text{so } 5x + 6y &= 10 & (x, y) &= \left(\frac{5}{14}, \frac{15}{14}\right) \\ 12x + 20y &= 30 \end{aligned}$$

Then you could check that $f_{xx} f_{yy} - f_{xy}^2 > 0$

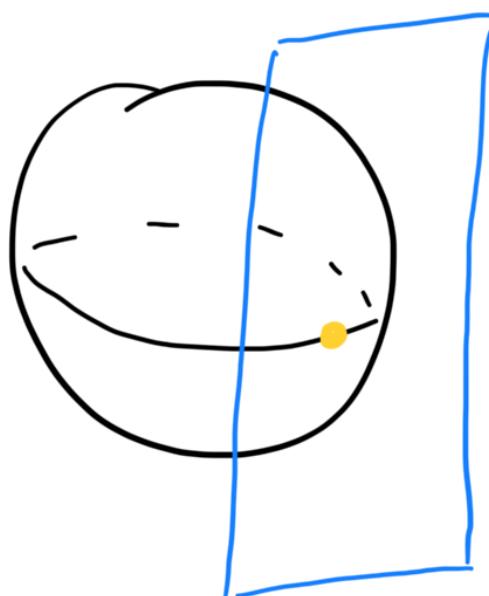
and $f_{xx} = 10 > 0$ so it's a local min,

so the point is $\left(\frac{5}{14}, \frac{15}{14}, Z = 5 - 2x - 3y\right)$
 $= \frac{5}{14}$

closest point

ex: Another way is to imagine level surfaces of

$$f(x, y, z) = x^2 + y^2 + z^2.$$



At point of contact, the two surfaces will have the same tangent plane (and therefore parallel normals).

this is expressible algebraically as

$\nabla f = \lambda \nabla g$ where f is function
of (x, y, z) that defines sphere of radius a and
 $g(x, y, z)$ equation that defines the plane.

$$f(x, y, z) = x^2 + y^2 + z^2 - a^2 = \text{sphere of radius } a$$

$$g(x, y, z) = 2x + 3y + z - 5 = \text{plane}.$$

$$\nabla f = (2x, 2y, 2z) \quad 2x = \lambda 2$$

$$\nabla g = (2, 3, 1) \quad 2y = \lambda 3 \quad \text{then solve.}$$

$$2z = \lambda 1$$

$$x = \lambda$$

$$y = \frac{3}{2}\lambda \quad \text{and we know } 2(\lambda) + 3(\frac{3}{2}\lambda) + \frac{1}{2}\lambda - 5 = 0$$

$$z = \frac{1}{2}\lambda$$

$$\lambda \left(\frac{4+9+1}{2} \right) = 5 \quad \text{so } \lambda = 5/7$$

$$\text{thus } (x, y, z) = \left(\frac{5}{7}, \frac{15}{14}, \frac{5}{14} \right)$$

Theorem of Lagrange Multipliers

Suppose $f(x, y, z)$ and $g(x, y, z)$ are differentiable
and $\nabla g \neq 0$ when $g(x, y, z) = 0$.

To find the local max/min values of f

subject to constraint $g(x, y, z) = 0$

find the values of (x, y, z) that satisfy both

$$\nabla f = \lambda \nabla g \quad \text{and} \quad g(x, y, z) = 0$$

(.1 ..) ... for ... and 2-variable

Ex 14.8.23: Find max/min to $f(x,y,z) = x - 2y + 5z$
on the sphere $x^2 + y^2 + z^2 = 30$.

Constraint $g(x,y,z) = x^2 + y^2 + z^2 - 30$

function $f(x,y,z) = x - 2y + 5z$

$$\nabla f = (1, -2, 5) \quad \nabla g = (2x, 2y, 2z)$$

$$\begin{aligned} 1 &= \lambda 2x & \lambda &= 2x & x &= \lambda/2 \\ -2 &= \lambda 2y & \text{or} & -2\lambda &= 2y & y &= -\lambda \\ 5 &= \lambda 2z & & 5\lambda &= 2z & z &= 5/2\lambda \end{aligned}$$

↓ plug into g solve λ .

$$\left(\frac{\lambda}{2}\right)^2 + (-\lambda)^2 + \left(\frac{5}{2}\lambda\right)^2 - 30 = 0$$

$$\lambda^2 \left(\frac{1}{4} + 1 + \frac{25}{4} \right) = 30$$

$$\lambda^2 \left(\frac{30}{4} \right) = 30 \quad \text{so} \quad \lambda^2 = 4, \quad \lambda = \pm 2.$$

thus $(a,b,c) = (1, -2, 5)$ or $(a,b,c) = (-1, 2, -5)$

$$\begin{aligned} f(1, -2, 5) &= 1 - 2(-2) + 25 & \& f(-1, 2, -5) &= -30 \\ &= 30 \quad \max & & & \min \end{aligned}$$

Ex: 14.8.14

temperature on plate is $T(x,y) = 4x^2 - 4xy + y^2$.

cont on circle of radius 5 about origin walks

... . At the highest / lowest temperatures.

function: $T(x, y) = 4x^2 - 4xy + y^2$

constraint: $g(x, y) = x^2 + y^2 - 25$

$$\nabla T = \lambda \nabla g \quad \nabla T = (8x - 4y, -4x + 2y)$$
$$\nabla g = (2x, 2y)$$

$$\begin{aligned} \text{so } (8x - 4y) &= \lambda 2x & 2y - 2y\lambda &= 4x \\ (-4x + 2y) &= \lambda 2y & 2y(1 - \lambda) &= 4x \\ && \frac{1}{2}y(1 - \lambda) &= x \end{aligned}$$

$$4x - 2y = \lambda x$$

$$2y(1 - \lambda) - 2y = \lambda(\frac{1}{2}y(1 - \lambda))$$

$$-4y\lambda = \lambda y(1 - \lambda)$$

$$0 = \lambda(y(1 - \lambda) + 4y) = \lambda(5y - y\lambda)$$

$$0 = y\lambda(5 - \lambda)$$

$$y = 0 \Rightarrow x^2 + y^2 = x^2 = 25 \text{ so } (\underline{-5, 0}) \text{ and } (\underline{+5, 0})$$

$$\lambda = 0 \Rightarrow \nabla T = \vec{0} \quad \begin{aligned} 8x - 4y &= 0 \\ -4x + 2y &= 0 \end{aligned} \Rightarrow y = 2x$$

$$\text{so } x^2 + 4^2x^2 = 25 \Rightarrow x = \pm \sqrt{5}$$

$$(\underline{-\sqrt{5}, -2\sqrt{5}}) \text{ or } (\underline{+\sqrt{5}, 2\sqrt{5}})$$

$$\lambda = 5 \rightarrow y(-4) = 2x \quad \text{so} \quad 4y^2 + y^2 = 25 \quad \text{so}$$

$$x = -2y$$

$$y = \pm \sqrt{5}$$

$$f(\pm\sqrt{5}, 0) = 100 \leftarrow \text{doesn't count bc } \nabla g \neq \vec{0}$$

$$f(\sqrt{5}, 2\sqrt{5}) = 0 \leftarrow \min$$

$$(\underline{2\sqrt{5}, -\sqrt{5}}) \text{ or } (\underline{-2\sqrt{5}, \sqrt{5}})$$

$$f(2\sqrt{5}, \sqrt{5}) = 125 \leftarrow \max$$

Ex: 14.5.7 (two constraints)

find max/min of $f(x, y, z) = x^2 + 2y - z^2$

subject to $2x - y = 0$ and $y + z = 0$

here $\nabla f = \lambda \nabla g + u \nabla h$

where f = above and $g = 2x - y$ $h = y + z$

$$\nabla f = (2x, 2, -2z) \quad (2x, 2, -2z) = (2\lambda, -\lambda, 0)$$

$$\nabla g = (2, -1, 0) \quad + (0, u, u)$$

$$\nabla h = (0, 1, 1) \quad 2x = 2\lambda$$

$$2 = -\lambda + u \Rightarrow u = 2 + \lambda$$

$$-2z = u$$

$$x = \lambda$$

$$2x - y = 0$$

$$u = 2 + \lambda = -2z$$

$$\text{so } 2\lambda + 2 = 0 \text{ bc } z = -y$$

$$z = -1 - \frac{\lambda}{2}$$

$$2\lambda - 1 - \frac{\lambda}{2} = 0$$

$$\frac{3\lambda}{2} = 1 \text{ so } \lambda = \frac{2}{3}$$

$$\text{and } u = \frac{8}{3}$$

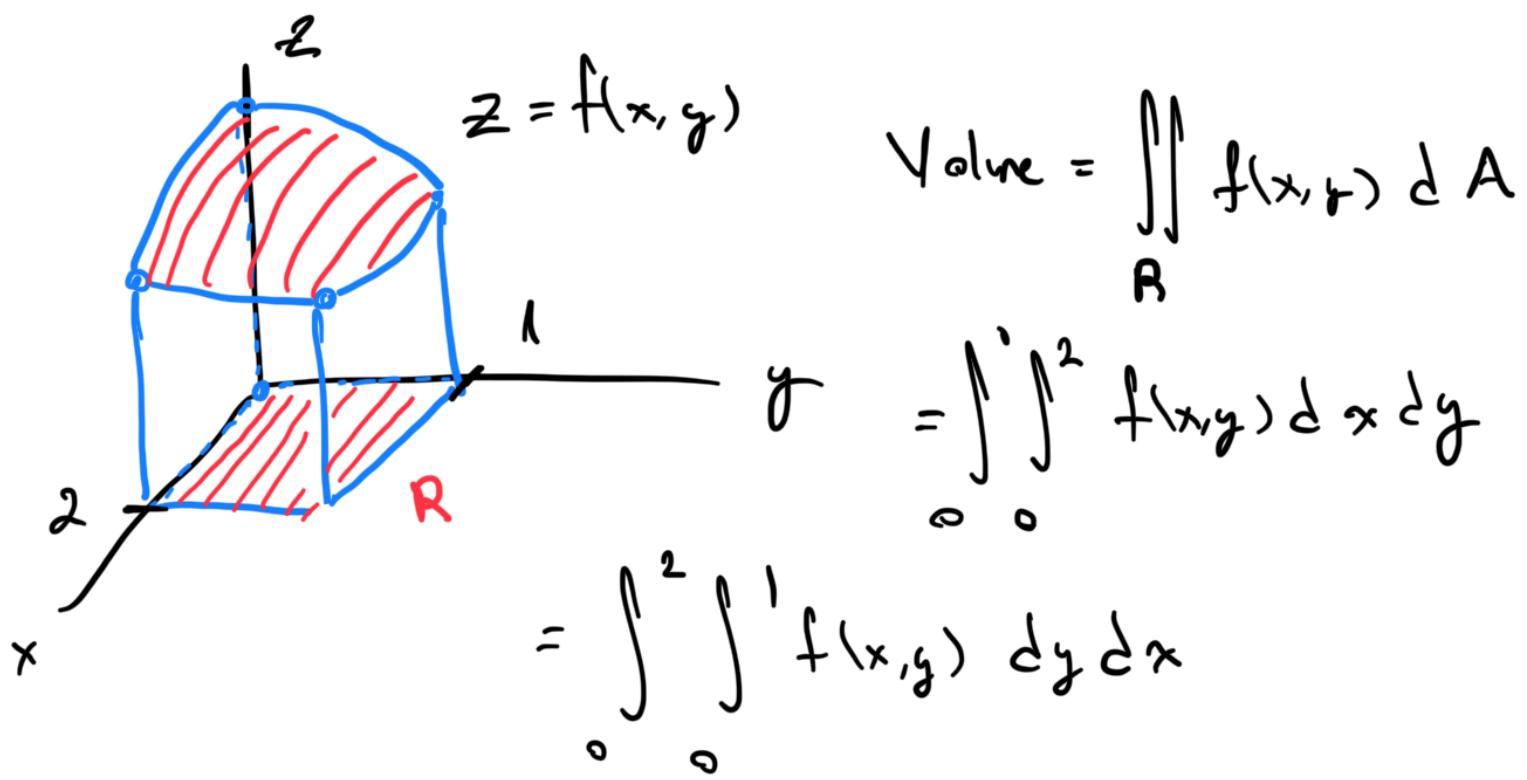
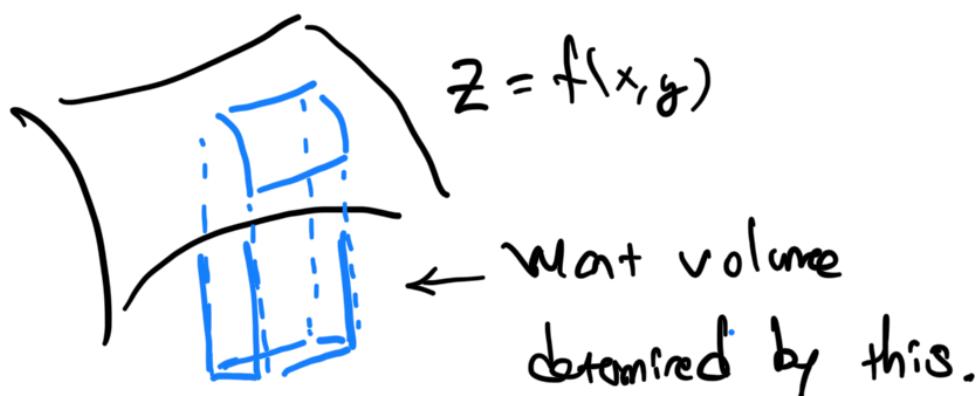
$$\text{so } x = \frac{2}{3}$$

$$z = -1 - \frac{1}{3} = -\frac{4}{3}$$

$$y = \frac{4}{3}$$

15.1: Double integrals over rectangles.

Let $z = f(x, y)$ be some function.



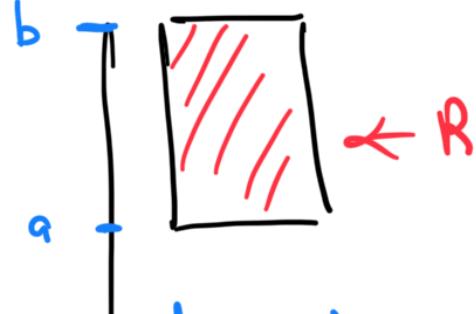
true in general: Fubini's theorem:

Let $f(x, y)$ be defined over rectangular

region R , then

$$\iint_R f(x, y) dA = \int_a^b \int_c^d f(x, y) dx dy$$

$$= \iint_{R'} f(x, y) dy dx$$





ex: $\iint_R 4-x-y^2 \text{ on region } R = 0 \leq x \leq 4$
 $0 \leq y \leq 2$

$$= \int_0^4 \int_0^2 4-x-y^2 dy dx = \int_0^4 \left[4y - xy - \frac{1}{3}y^3 \right]_0^2 dx$$

$$= \int_0^4 8 - 2x - \frac{8}{3} dx = \frac{16}{3} \int_0^4 dx - 2 \int_0^4 x dx$$

$$= \frac{16}{3} (x) \Big|_0^4 - 2\left(\frac{1}{2}x^2\right) \Big|_0^4 = \frac{16}{3} \cdot 4 - 2 \cdot 8 \\ = 16/3$$

$$\stackrel{OC}{=} \iint_0^2 4-x-y^2 dx dy = \int_0^2 \left[4x - \frac{1}{2}x^2 - y^2 x \right]_0^4 dy$$

$$= \int_0^2 16 - 8 - 4y^2 dy = 8 \int_0^2 dy - 4 \int_0^2 y^2 dy$$

$$= 8(y) \Big|_0^2 - \frac{4}{3}y^3 \Big|_0^2 = 16 - \frac{32}{3} = 16/3$$

ex: $\iint_{-1}^1 \iint_{-\pi}^{\pi} \frac{\sin(xy^2)}{1+y^2} dy dx$ 22
e.

However... $\int_{-\pi}^{\pi} \int_{-1}^{+1} \frac{\sin(xy^2)}{1+y^2} dx dy$

$$\begin{aligned}
 &= \int_{-\pi}^{\pi} \frac{-\cos(xy^2)}{y^2(1+y^2)} \Big|_{x=-1}^{x=1} dy = \int_{-\pi}^{\pi} \frac{-\cos(y^2) + \cos(-y^2)}{y^2(1+y^2)} dy \\
 &= \int_{-\pi}^{\pi} \frac{0}{y^2(1+y^2)} dy = 0 \quad (\text{Sometimes reversing order of integration helps!})
 \end{aligned}$$

15.2. Integration over general regions

We know how to integrate over rectangles.

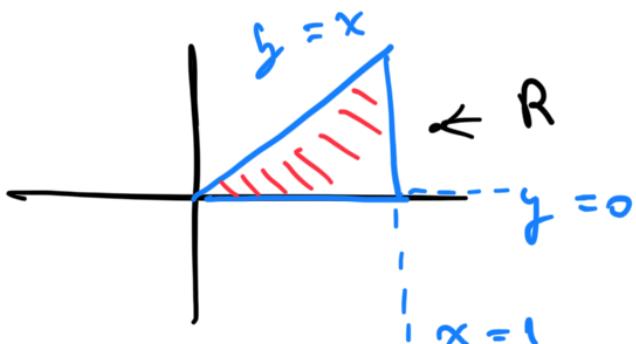
What about general regions?

e.g.

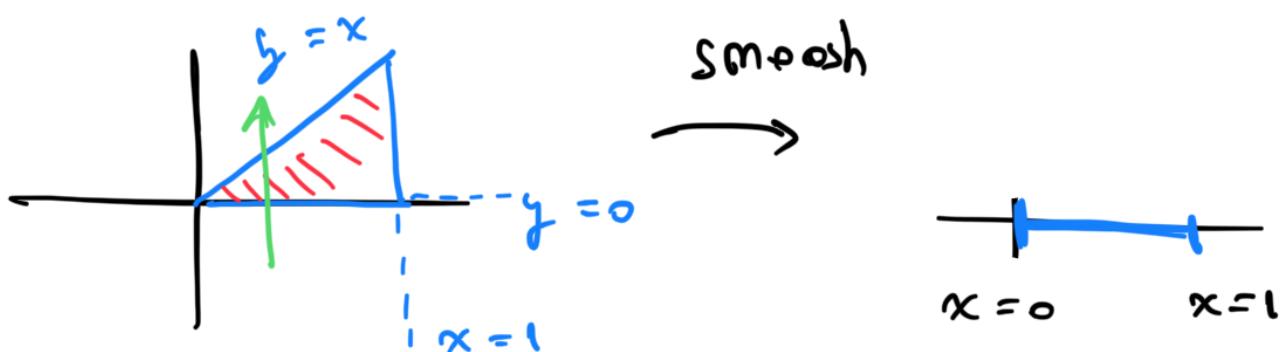


$$\iint_R f(x,y) dA = ?$$

ex: $\iint_R x+y^2 dA$ over triangle defined by
 $y=x, y=0, x=1.$



(i).



enter at $y=0$

exit at $y=x$

exit $y=x$

$\int_{\text{entr } y=0}^{\text{exit } y=x} f(x, y) dy + \text{ln}$

enter $y=0$

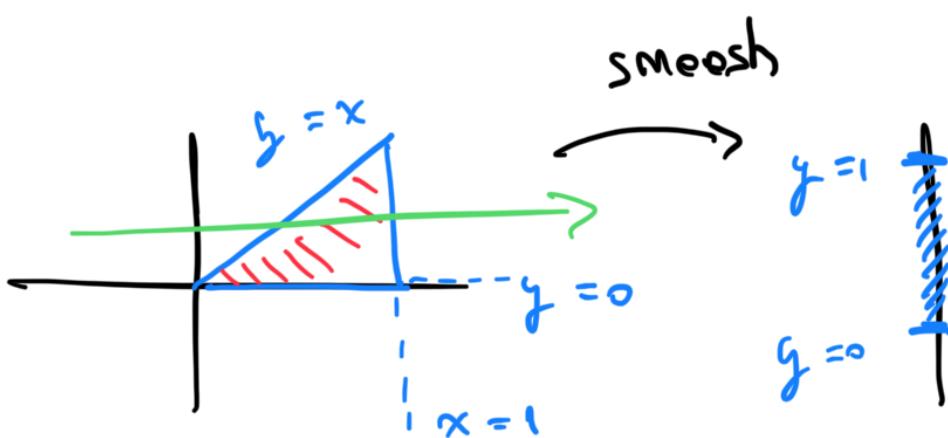
$$\int_{x=0}^{x=1} x + y^2 dy dx$$

$$\int_{y=0}^{y=x} x + y^2 dy dx$$

$$= \int_0^1 \int_0^x x + y^2 dy dx = \int_0^1 \left[xy + \frac{1}{3} y^3 \right]_0^x dx$$

$$= \int_0^1 x^2 + \frac{1}{3} x^3 dx = \left[\frac{1}{3} x^3 + \frac{1}{12} x^4 \right]_0^1 = \frac{1}{3} + \frac{1}{12} = \frac{5}{12}$$

or



exits $x=1$

$$\int_{\text{entr } x=y}^{\text{exit } x=1} f(x, y) dx + \text{ln}$$

$y=1$

exits $x=1$

$$\int_{y=0}^{y=1} f(x, y) dx dy$$

entr $x=y$

can do integral, same answer.

e x : Integrate a function $f(x, y)$ over

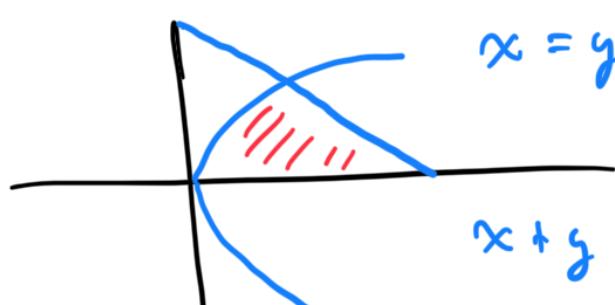
$$x = y^2$$

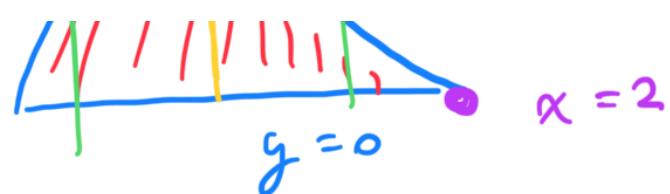
Write it in 2 ways

$$x + y = 2$$

$$x = y^2$$

$$x + y = 2$$

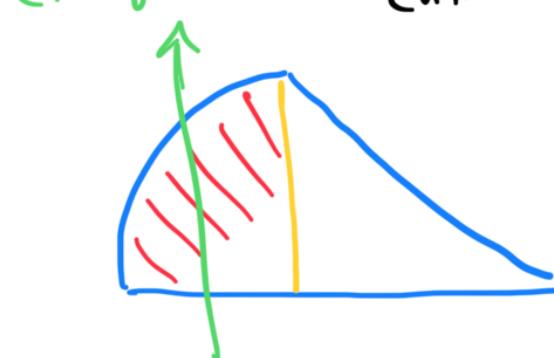




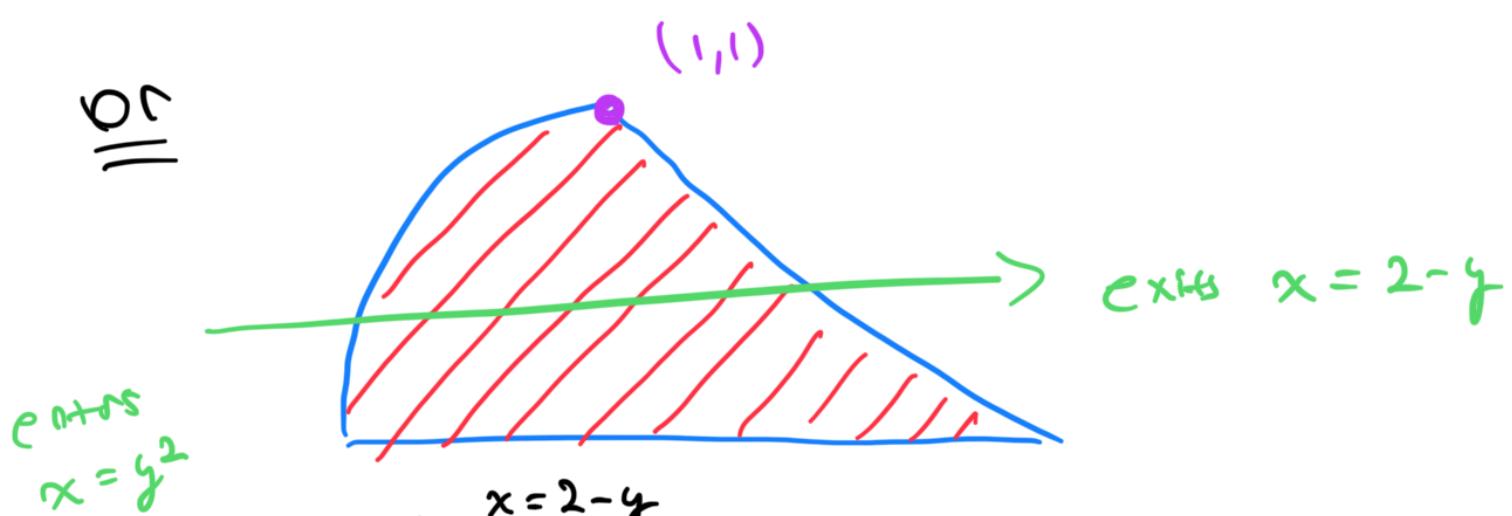
Notice where you enter and exit now depends on which x -value you're at! The point in pink is where curves intersect $y^2 = 2 - y$

$$y^2 + y - 2 = 0 \text{ solutions } y = 1 \\ = (y+2)(y-1) = 0 \text{ and } y = -2$$

$$\text{So } I = \int_0^1 \int_{y=0}^{y=\sqrt{x}} -dy dx + \int_1^2 \int_{y=0}^{y=2-x} -dy dx$$



$$\text{So } I = \int_0^1 \int_{y=0}^{y=\sqrt{x}} f(x, y) dy dx + \int_1^2 \int_{y=0}^{y=2-x} f(x, y) dy dx$$



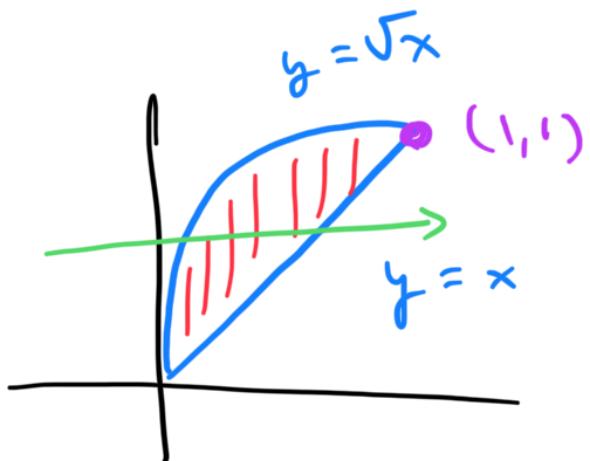
$$\text{So } I = \int_0^1 \int_{x=y^2}^{x=2-y} f(x, y) dx dy$$

In particular if $f(x, y) \equiv 1$, then we just

Get the area:

$$\text{e.g. } A = \int_0^1 \int_{y^2}^{2-y} dx dy = \int_0^1 2-y - y^2 dy$$
$$= 2y - \frac{1}{2}y^2 - \frac{1}{3}y^3 \Big|_0^1$$
$$= 2 - \frac{1}{2} - \frac{1}{3} = \frac{7}{6}$$

ex: $\int_0^1 \int_x^{\sqrt{x}} \frac{\sin(y)}{y} dy dx$



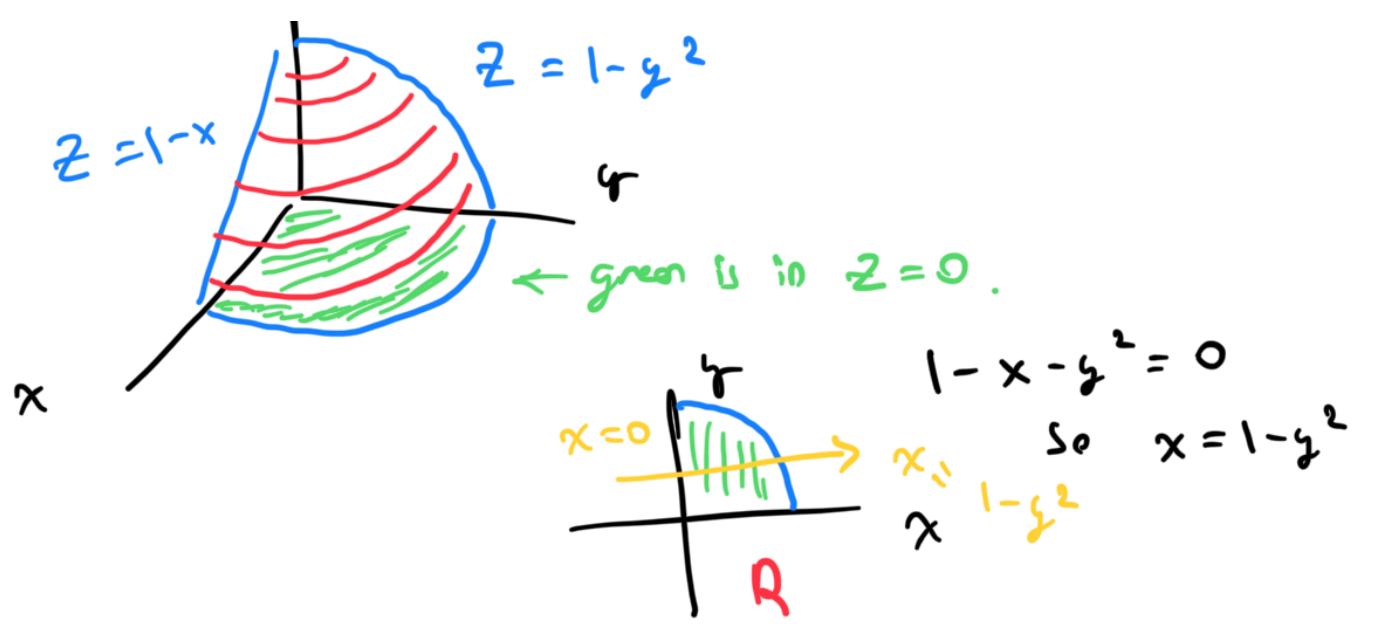
$$= \int_0^1 \int_{y^2}^y \frac{\sin(y)}{y} dx dy$$

entrs $x = y^2$ exits $x = y$

$$= \int_0^1 \frac{\sin(y)}{y} x \Big|_{y^2}^y dy = \int_0^1 \frac{\sin(y)}{y} (y - y^2) dy$$
$$= \int_0^1 \underbrace{\sin(y)}_{\text{simple}} - \underbrace{y \sin(y)}_{\text{Integration by parts}} dy = 1 - \sin(1)$$

two applications: Volume of a section of
a surface and average value.

ex: Calculate volume determined by $z = 1 - x - y^2$
in first octant bounded by $z = 0$.



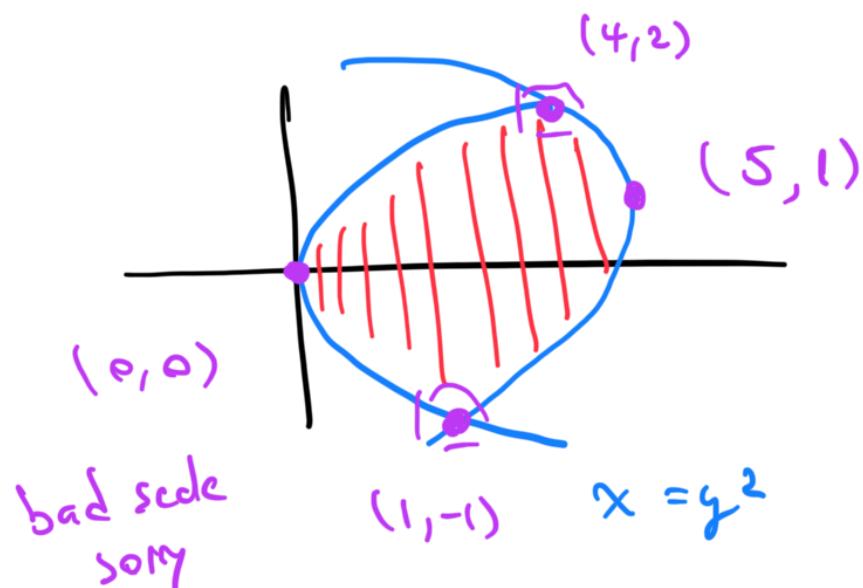
$$V = \iint_R z \, dA = \iint_0^1 \int_0^{1-y^2} 1 - x - y^2 \, dx \, dy = 4/15$$

15.3. Areas by double integrals

As mentioned earlier if integrand $f(x,y) = 1$ on a region R , you just get Area of region.

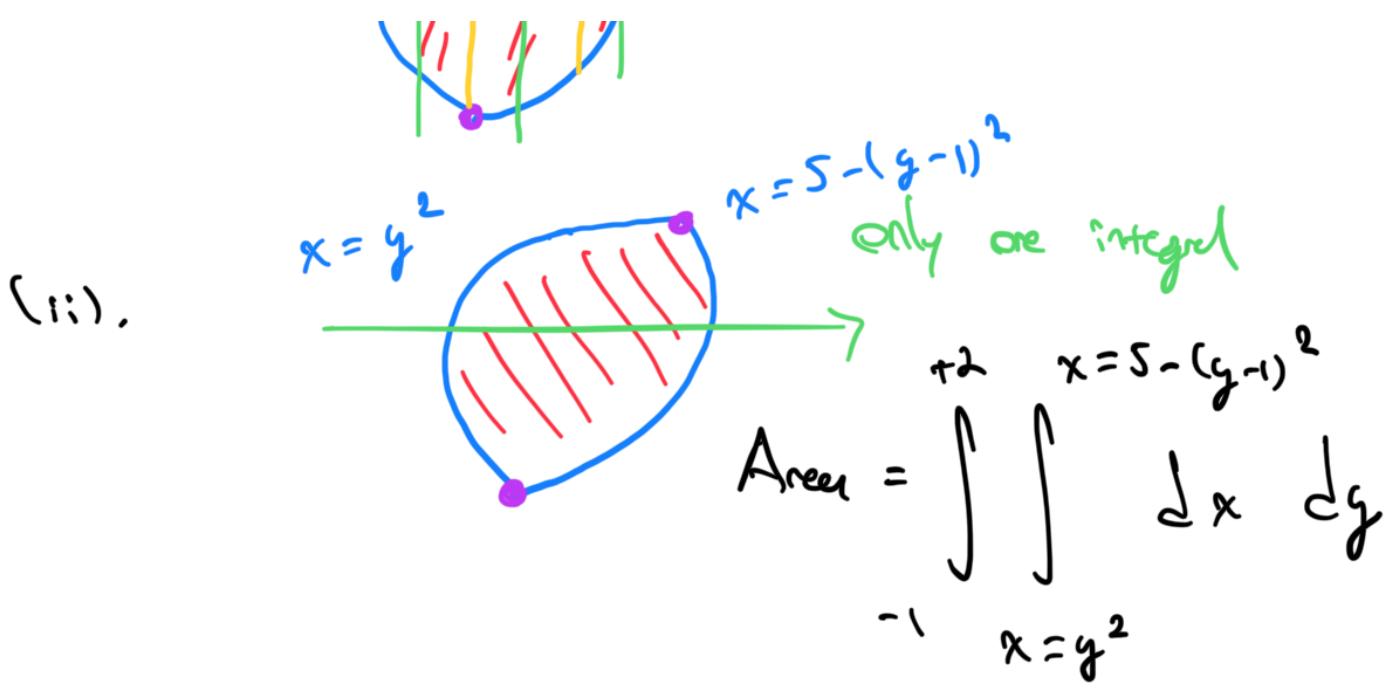
Ex: Calculate area of region defined by

$$x = y^2 \text{ and } x = 5 - (y-1)^2$$



Solve for boxed points
by setting $y^2 = 5 - (y-1)^2$.





ex: Calculate average value of a function over region R.

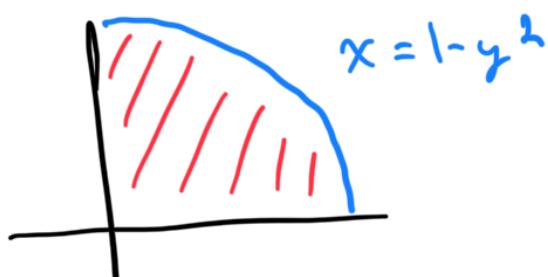
$$(\star) \text{ Avg}(f, R) = \frac{\iint_R f dA}{\text{Area of } R}$$

so for example, with $f(x,y) = 1-x-y^2$ and R from 15.2

$$\text{Avg}(f, R) = \frac{\iint_0^1 1-x-y^2 dx dy}{\iint_0^1 dx dy}$$

(i). $x = 1-y^2$

(ii).



(i). Already did, $4/15$

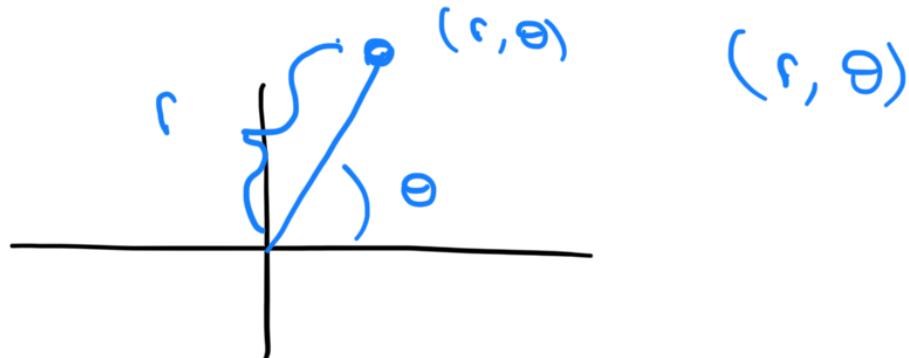
$$(ii). \int_0^1 \int_{1-y^2}^y dx dy - \int_0^1 1-y^2 dy = y - \frac{1}{3}y^3 \Big|_0^1 = 2/15$$

$$0^{\circ} 0^{\circ} - \theta = 0^{\circ} \quad \theta = 37^{\circ} 10' 15''$$

$$\text{so } \operatorname{Arg}(f, R) = \frac{4/15}{2/3} = \frac{2}{5}$$

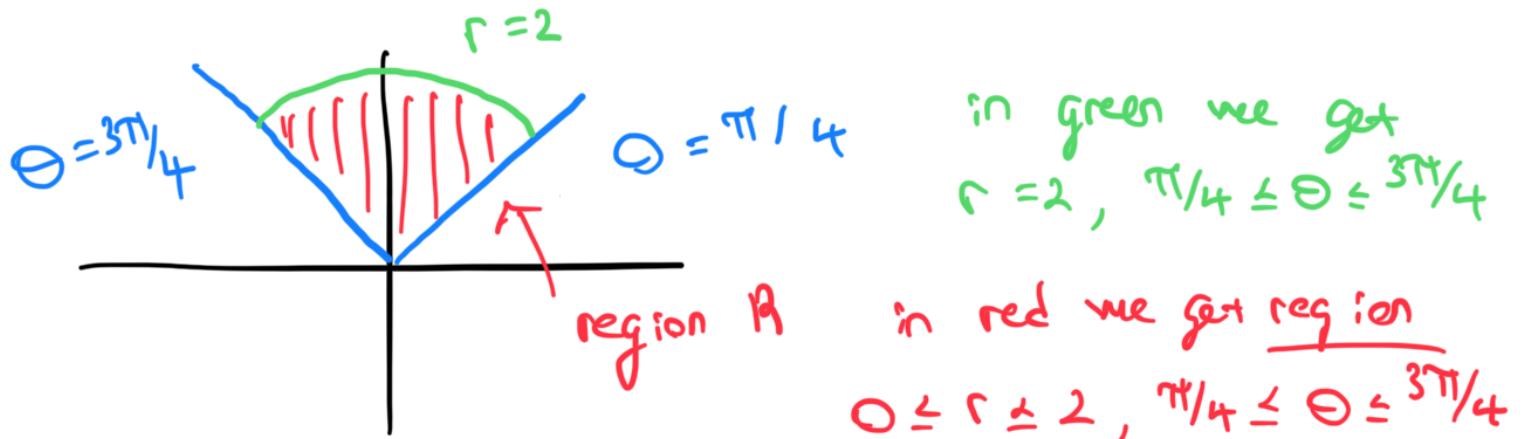
15.4: Polar Coordinate Integrals

Polar coordinates are another way of specifying points in the plane instead of (x, y) .



One issue however is that coordinates are no longer unique. e.g.: $(1, \pi/4)$ and $(1, \pi/4 + 2\pi)$ are same point. Also $(0, \pi)$ and $(0, \pi/2)$ are same point. the for any $(0, \theta)$.

ex: What does all (r, θ) with $r=2$ and $\pi/4 \leq \theta \leq 3\pi/4$ look like?



ex: What does $r = \cos \theta$ look like?

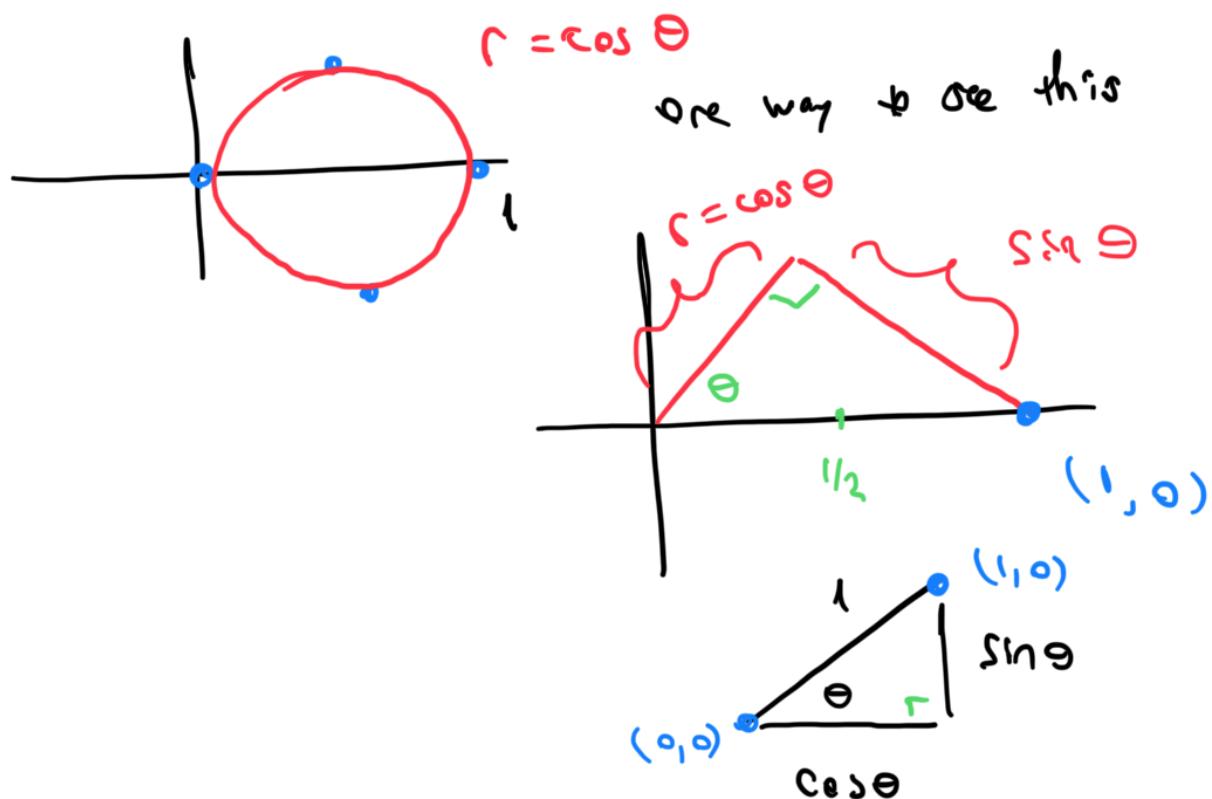
$$\theta = \pi/2, r(\pi/2) = 0$$

$$\theta = 3\pi/4, r(3\pi/4) = -\sqrt{2}/2$$

$$\theta = \pi/4, r(\pi/4) = \sqrt{2}/2$$

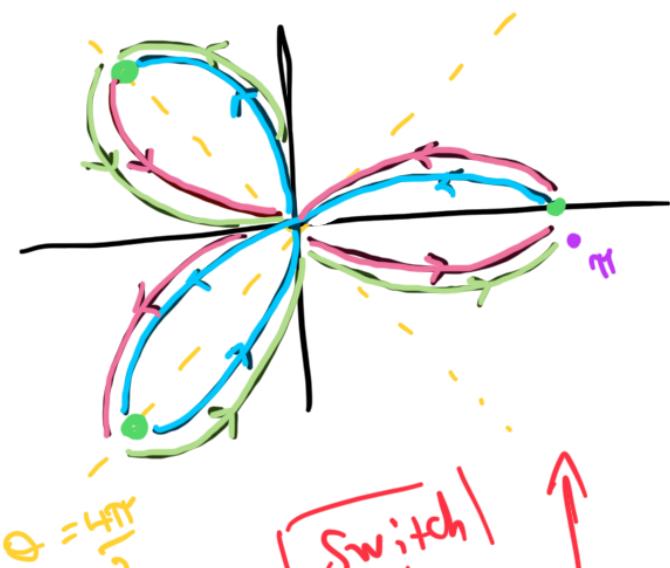
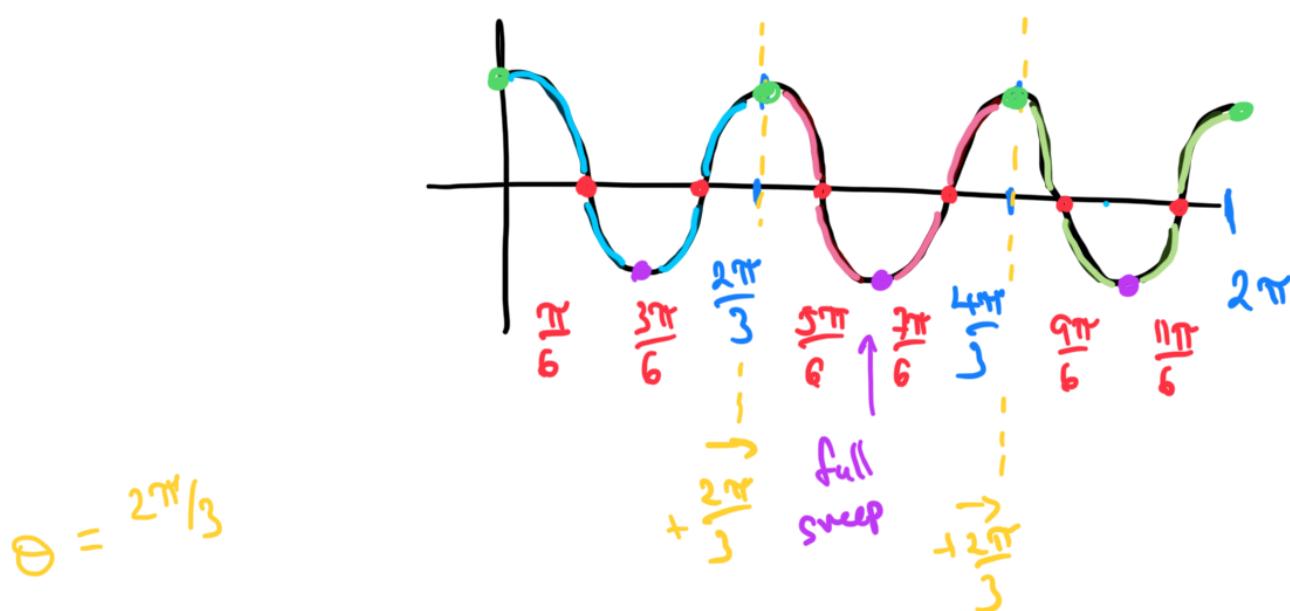
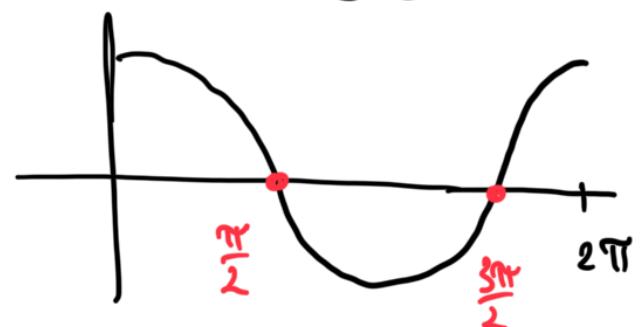


keep doing ...

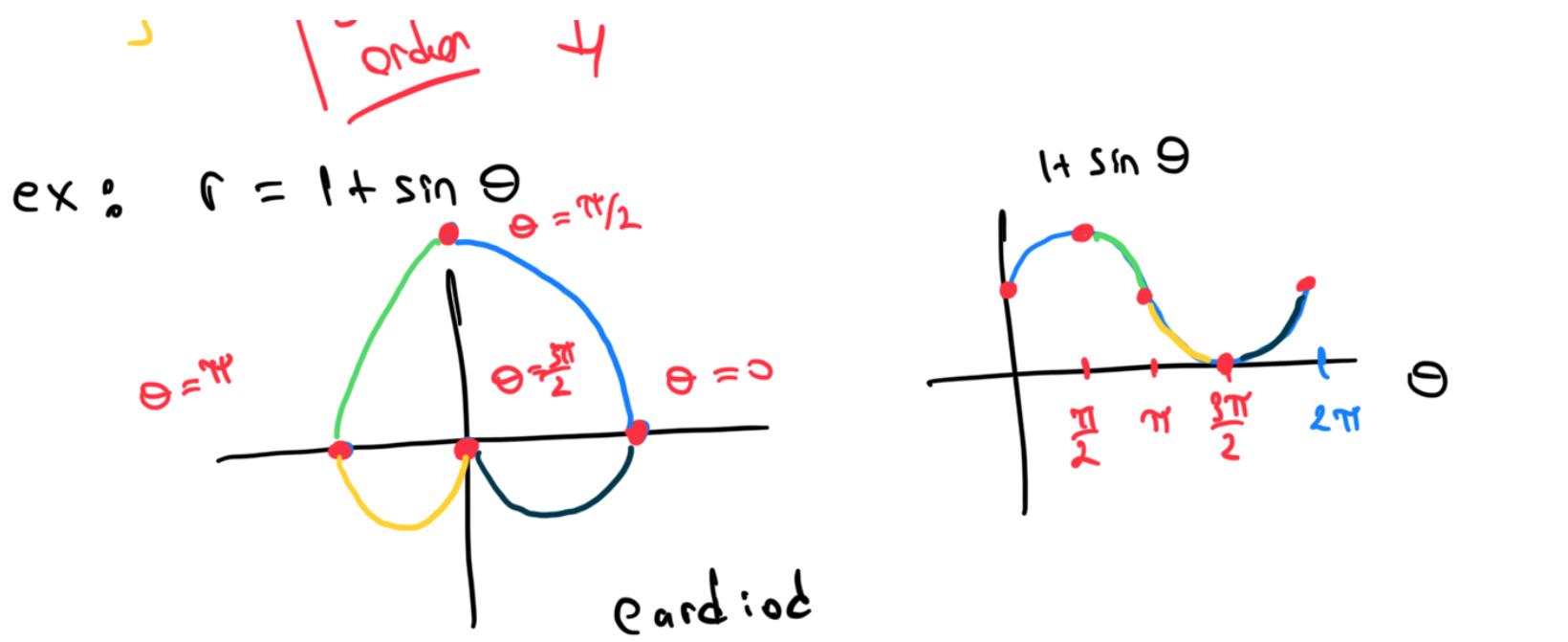


$$\text{ex: } r = \cos 3\theta$$

$\cos \theta$



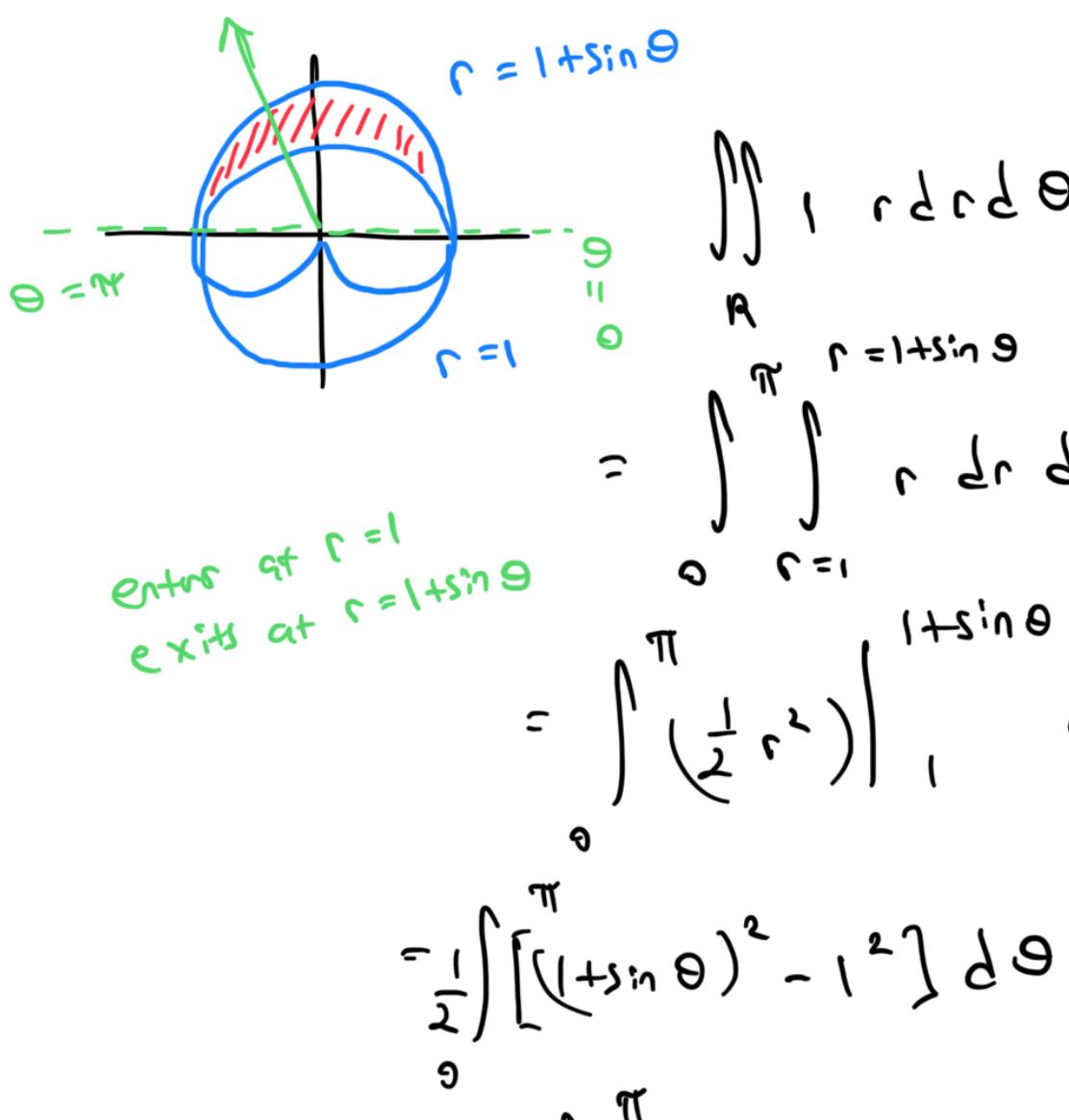
Don't sweat this example too much. Just wanted to show how this looks mostly.



Integrate functions $f(r, \theta)$ over regions R

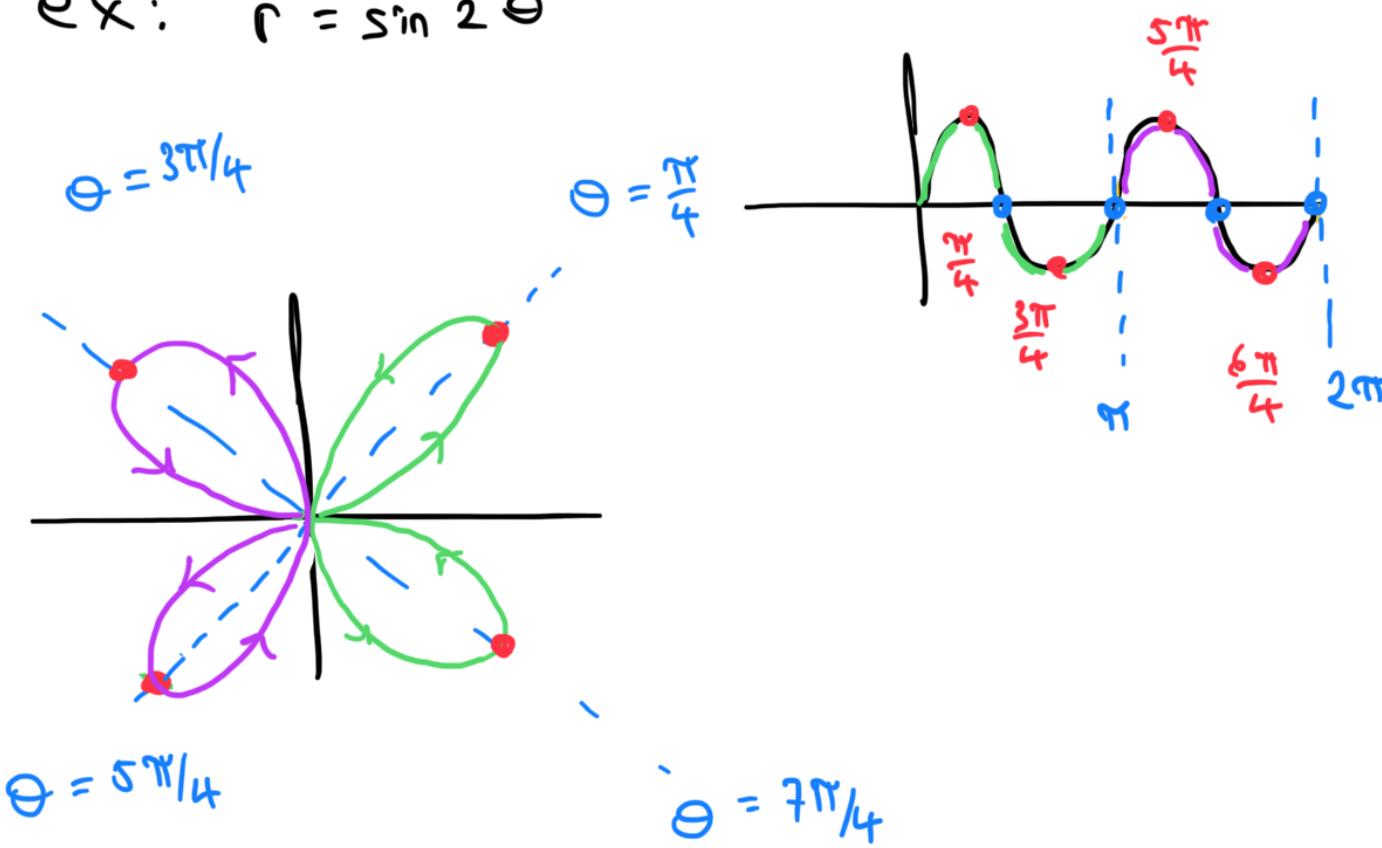
$$\iint_R f(r, \theta) dA = \int_{\theta=0}^{2\pi} \int_{r=g_1(\theta)}^{r=g_2(\theta)} f(r, \theta) r dr d\theta$$

ex: Calculate area between circle radius 1 and cardioid $r = 1 + \sin \theta$ as illustrated



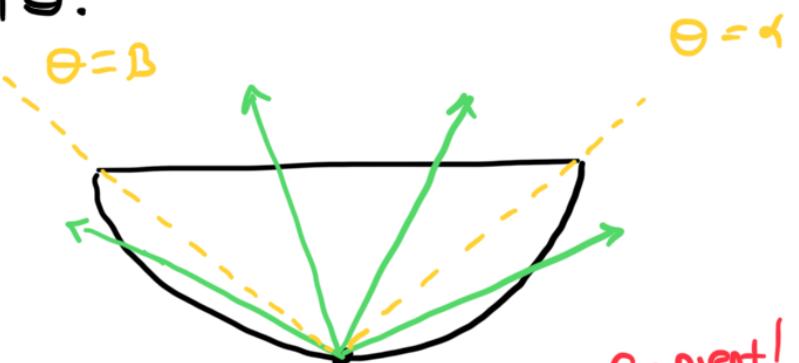
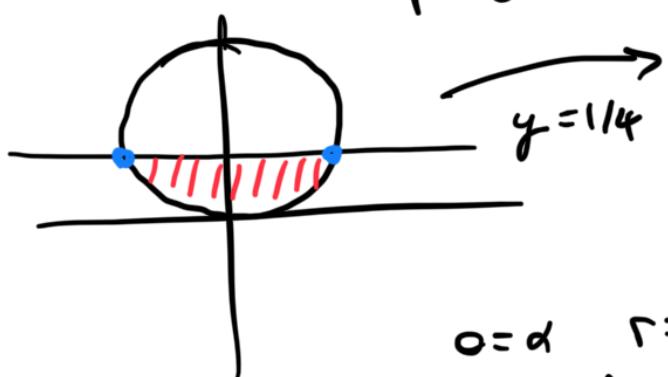
$$\begin{aligned}
 &= \frac{1}{2} \left(\int_0^{\pi} 2 \sin(\theta) + \sin^2 \theta \, d\theta \right) \\
 &= \frac{1}{2} \left(\frac{8 + \pi}{2} \right) = 2 + \frac{\pi}{4}
 \end{aligned}$$

ex: $r = \sin 2\theta$



ex: Calculate area below $y = \frac{1}{4}$ above $y = 0$

and in between $r = \sin \theta$.



$$\begin{aligned}
 \text{So Area} &= \int_{\theta=0}^{\theta=\alpha} \int_{r=0}^{r=\sin \theta} r dr d\theta + \int_{\theta=\alpha}^{\theta=\beta} \int_{r=0}^{r=\sin \theta} r dr d\theta \\
 &\quad + \int_{\theta=\beta}^{\theta=\pi} \int_{r=0}^{r=\sin \theta} r dr d\theta
 \end{aligned}$$

Cartesian to Polar and vice versa

$$x = r \cos \theta \quad y = r \sin \theta \quad r = \sqrt{x^2 + y^2}$$

$$\tan \theta = \frac{y}{x} \text{ (kinda)}$$

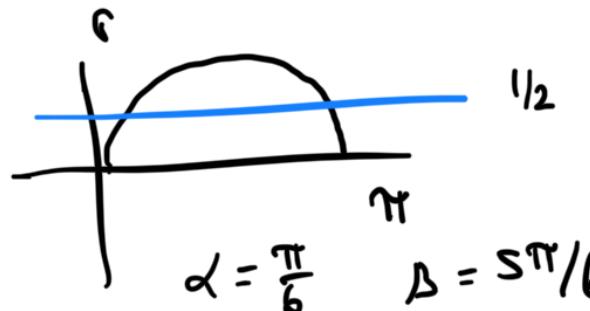
so $y = \frac{1}{4} \rightarrow r \sin \theta = \frac{1}{4} \Rightarrow r = \frac{1}{4 \sin \theta}$ so
 $\theta = \frac{\pi}{6}$ $r = \frac{1}{4 \sin \theta}$

(i) is $\int_{\theta=0}^{\pi/6} \int_{r=0}^{1/4 \csc \theta} r dr d\theta$

2. Find α and β . Then when $r = \frac{1}{4 \sin \theta} = \sin \theta$

$$\text{In other words } \frac{1}{4} = \sin^2 \theta \quad \sin \theta = \frac{1}{2}$$

$$\text{In } 0 \leq \theta \leq \pi \text{ so}$$



$$\theta = \frac{\pi}{6} \quad r = \sin(\theta)$$

$$\text{so (i)} \quad \int_{\theta=0}^{\pi/6} \int_{r=0}^{1/4 \csc \theta} r dr d\theta$$

$$\theta = 0 \quad r = 0 \quad \theta = 5\pi/6 \quad r = \frac{1}{4 \sin \theta}$$

$$(i) = \frac{1}{48} (2\pi - 3\sqrt{3})$$

$$\text{(ii).} \quad \int_{\theta=\pi/6}^{\pi/2} \int_{r=0}^{1/4 \csc \theta} r dr d\theta$$

$$(ii) = \frac{\sqrt{3}}{16}$$

$$\text{(iii).} \quad \int_{\theta=5\pi/6}^{\pi} \int_{r=0}^{1/4 \csc \theta} r dr d\theta$$

$$(iii) = \frac{1}{48} (2\pi - 3\sqrt{3})$$

so $\sum_i = \text{Area}$

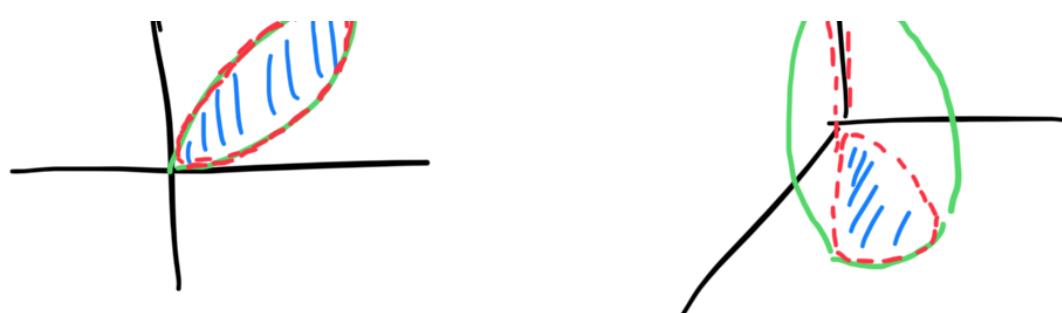
$$= \frac{1}{48} (4\pi - 6\sqrt{3})$$

ex: Calculate volume of solid bounded by

$$z = 2 - x^2 - y^2, z = 0 \quad \text{and } r = \sin 2\theta$$

in the first quadrant.

this drawing is so bad.



$$\begin{aligned}
 V &= \iint_R z \, dA = \iint_R 2-x^2-y^2 (r \, dr \, d\theta) \\
 &= \iint_0^{\sin 2\theta} \int_0^{\pi/2} (2-r^2)(r \, dr \, d\theta) = \int_0^{\sin 2\theta} r^2 - \frac{1}{4} r^4 \Big|_0^{\sin 2\theta} d\theta \\
 &= \int_0^{\sin 2\theta} \sin^2 2\theta - \frac{1}{4} \sin^4 2\theta \, d\theta
 \end{aligned}$$

(i). (ii).

$$\begin{aligned}
 (i). \quad \int_0^{\pi/2} \sin^2 2\theta \, d\theta &= \frac{\theta}{2} - \frac{1}{8} \sin(4\theta) \Big|_0^{\pi/2} \\
 &= \pi/4
 \end{aligned}$$

$$\begin{aligned}
 (ii). \quad \int_0^{\pi/2} \sin^4 2\theta \, d\theta &= \int_0^{\pi/2} \sin^2 2\theta (1 - \cos^2 \theta) \, d\theta \\
 &= \int_0^{\pi/4} \sin^2 2\theta \, d\theta - \int_0^{\pi/2} \sin^2 2\theta \cos^2 \theta \, d\theta \\
 &\quad \underbrace{\qquad\qquad\qquad}_{(\sin 2\theta \cos 2\theta)^2} \\
 &= \left(\frac{1}{2} \sin 4\theta \right)^2
 \end{aligned}$$

$$\int_0^{\pi/2} \sin^2 4\theta \, d\theta = \frac{3\pi}{16}$$

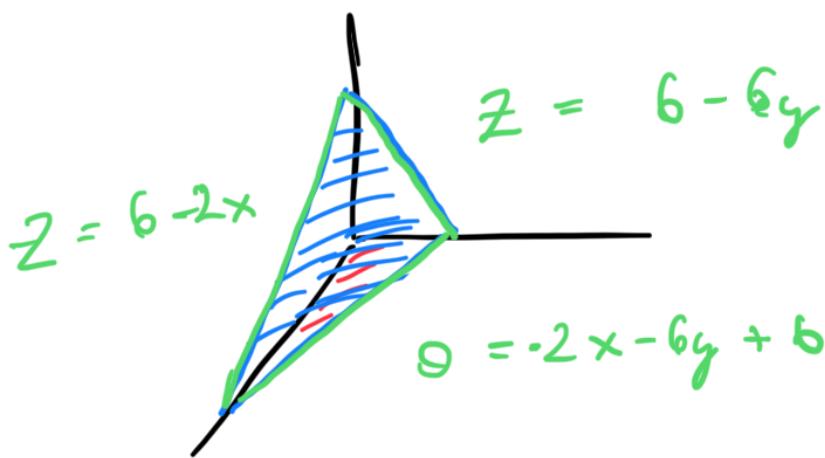
So total is

$$\frac{\pi}{4} + \left(\frac{\pi}{4} - \frac{1}{4} \left(\frac{3\pi}{16} \right) \right) = \frac{29\pi}{64}$$

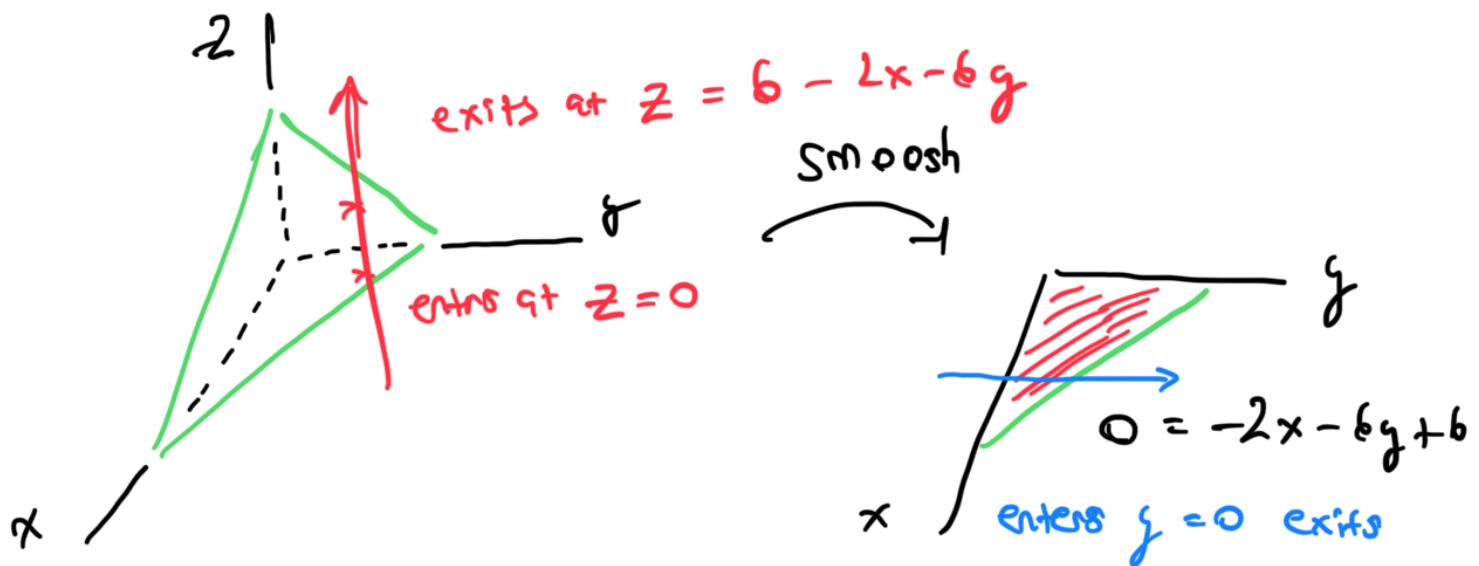
15.5: Triple Integrals in Rectangular Coordinates

Why stop at 2 variables? Why not integrate functions over space? Well that's triple integrals.

ex: Calculate the volume of the tetrahedron bounded by the 1st octant and the plane $Z = -2x - 6y + 6$.



One way is really similar to what we did before.



$$y = \frac{6-2x}{6} = 1 - \frac{1}{3}x$$

Smooch again

$$\text{So... } V = \int_{x=0}^{x=3} \int_{y=0}^y \int_{z=0}^z 1 dz dy dx$$

$$= 3$$

(Much easier way with cross products by the way!)

ex: Some examples but now switch order to

$$dy dx dz$$

$$z = 6 - 2x - 6y$$

Smooch

$$\text{enters } y = 0$$

$$\text{exits } y = 1 - \frac{1}{3}x - \frac{1}{6}z$$

$$z = 6 - 2x$$

$$z$$

$$\text{enters } x = 0$$

$$\text{exits } x = 3 - \frac{z}{2}$$

Smooch!

$$z$$

$$\begin{array}{l} z = 6 \\ z = 0 \end{array}$$

$$z = 6 \quad x = 3 - \frac{z}{2} \quad y = 1 - \frac{1}{3}x - \frac{1}{6}z$$

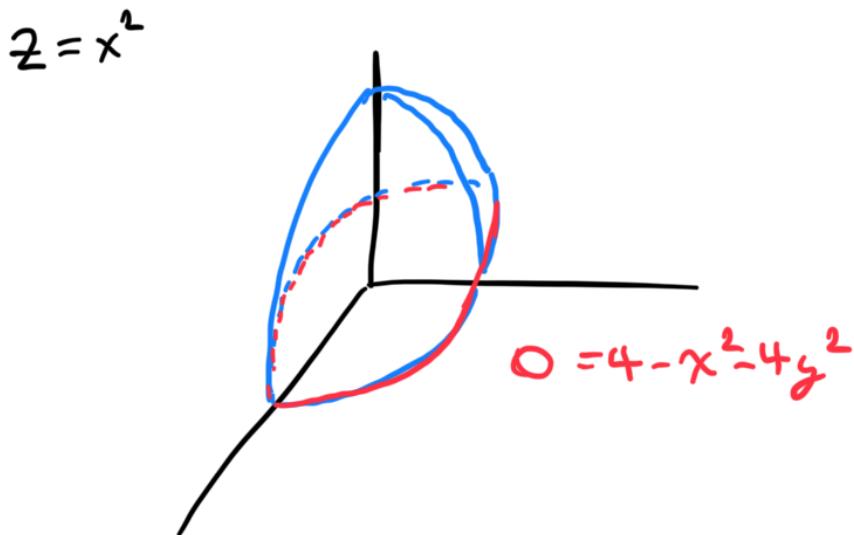
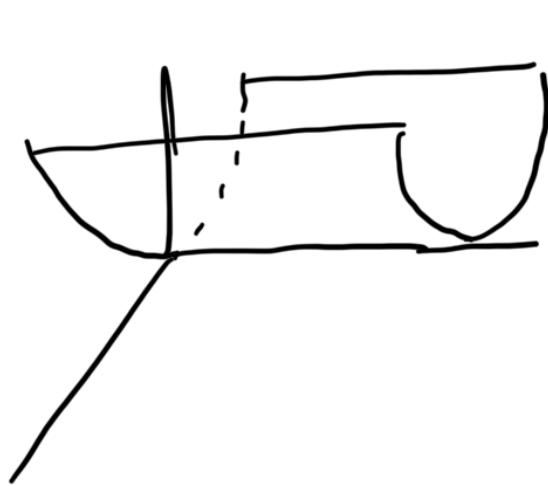
$$\text{So } V = \int_0^6 \int_0^{3-\frac{z}{2}} \int_0^1 1 dz dx dy = 3$$

$$z = 0 \quad x=0 \quad y=0 \quad \int_0^1 \int_{-y}^y dz dx dy$$

ex: Write an integral that calculates

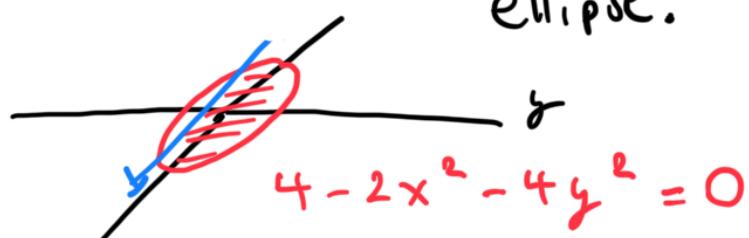
the volume of the solid region bounded

by $z = x^2$ and $z = 4 - x^2 - 4y^2$

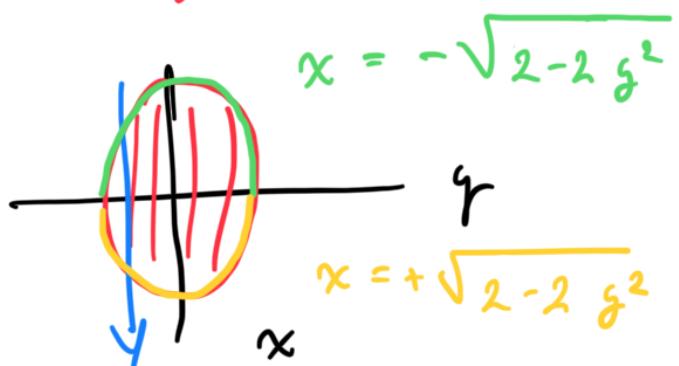


intersection is $z = x^2 = 4 - x^2 - 4y^2 \Rightarrow 2x^2 + 4y^2 = 4$

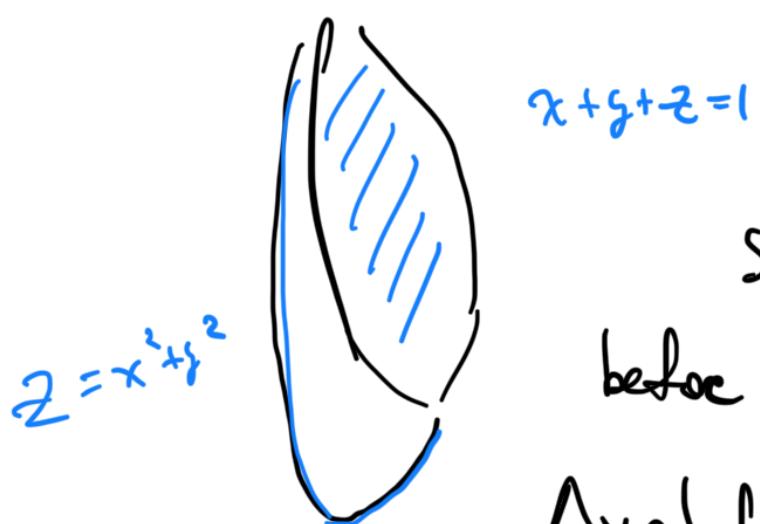
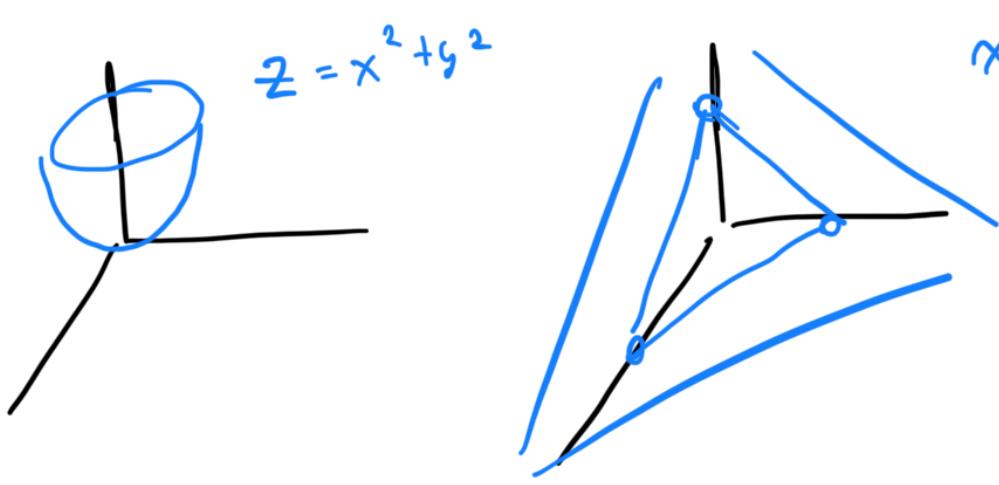
so $0 = 4 - 2x^2 - 4y^2$ which is an ellipse.



so $V = \int_{y=-1}^{y=1} \int_{x=-\sqrt{2-2y^2}}^{x=\sqrt{2-2y^2}} \int_{z=x^2}^{z=4-2x^2-4y^2} dz dx dy$



ex: Find average value of function $f(x, y, z) = x^2 + y^2$
on the solid region bounded by the plane
 $x + y + z = 1$ and the parabola $z = x^2 + y^2$.



So average value just like
before

$$\text{Avg}(f, \text{Solid } S) = \frac{\iiint_S f \, dV}{\iiint_S dV}$$

$$= \frac{\iiint_{(i)} f \, dV}{\text{Value of } (i)}$$

(i).

$$x + y + z = 1 \text{ and } z = x^2 + y^2$$

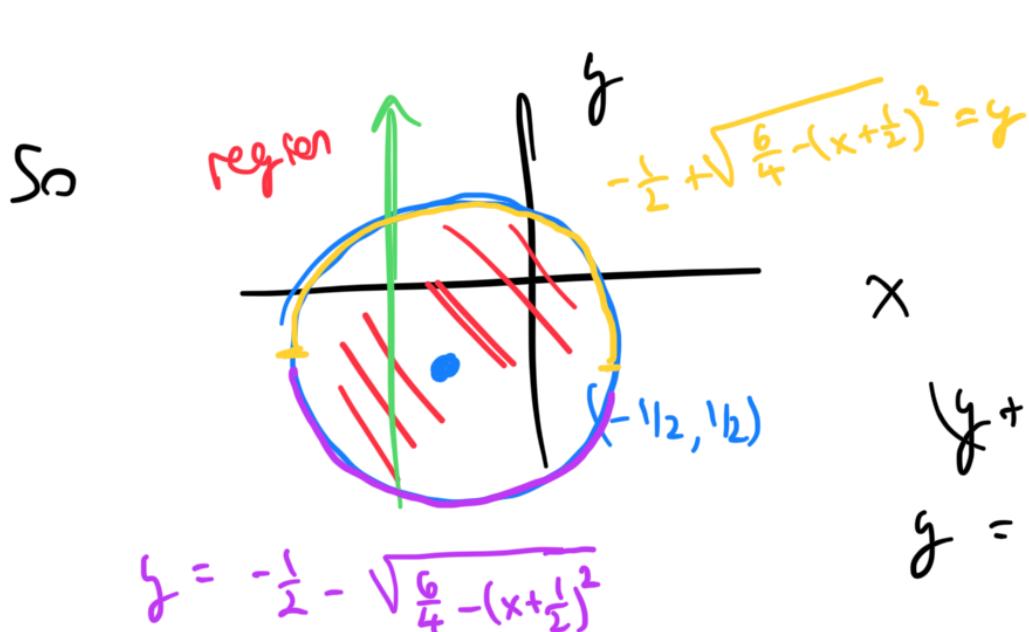
$$x + y + x^2 + y^2 = 1$$

$$(x^2 + x) + (y^2 + y) = 1$$

Circle centred
at $(-\frac{1}{2}, -\frac{1}{2})$

$$(x + \frac{1}{2})^2 + (y + \frac{1}{2})^2 = 1 + \frac{1}{4} + \frac{1}{4}$$

$$= \frac{6}{4} \text{ radius } \frac{\sqrt{6}}{2}$$

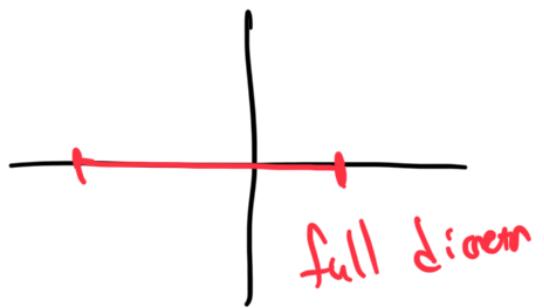


$$(y + \frac{1}{2})^2 = \frac{6}{4} - (x + \frac{1}{2})^2$$

$$y = -\frac{1}{2} \pm \sqrt{\frac{6}{4} - (x + \frac{1}{2})^2}$$

$$y = -\frac{1}{2} - \sqrt{\frac{6}{4} - (x + \frac{1}{2})^2}$$

Smooth



$$\text{Solve } y = -\frac{1}{2} \pm \sqrt{\frac{6}{4} - (x + \frac{1}{2})^2} = -\frac{1}{2}$$

$$\text{so } x = \frac{1}{2}(-1 \pm \sqrt{6})$$

$$\text{So } (i) = \int_{x = \frac{1}{2}(-1 - \sqrt{6})}^{x = \frac{1}{2}(-1 + \sqrt{6})} \int$$

$$y = -\frac{1}{2} - \sqrt{\frac{6}{4} - (x + \frac{1}{2})^2} \quad z = 1 - x - y$$

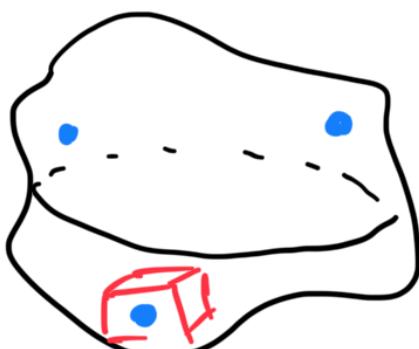
$$(x^2 + y^2) dz dy dx$$

(ii). Replace integrand above $x^2 + y^2$ with 1 to get
volume. Do not evaluate.

15.6: Mass and Moment of Inertia

Let's say have a solid body whose density modeled by $\delta(x, y, z)$

$$\delta(g) = 2 \text{ kg/m}^3$$



$$\delta(p) = 10 \text{ kg/m}^3$$

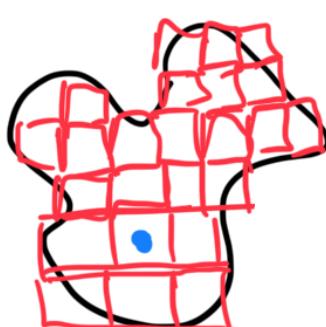
$$\text{mass of } \square \approx \delta(p) \Delta V$$

where $\Delta V = \text{volume of small cube.}$

$$\text{So Mass } \approx \sum_{\text{cubes}} \delta(p_i) \Delta V; \xrightarrow{\text{limit}} \iiint_B \delta(p) dV$$

where B is the body in question.

Similar picture in 2D



$$\text{Mass } \approx \sum_{\text{squares}} \delta(p_i) \Delta A;$$

$$\square = \delta(p) \Delta A$$

$$\text{in limit Mass} = \iint_R \delta(p) dA$$

Ex: Calculate mass of body B

$$\text{bounded by } z = 4 - x^2 - y^2 \text{ and } z = 0$$

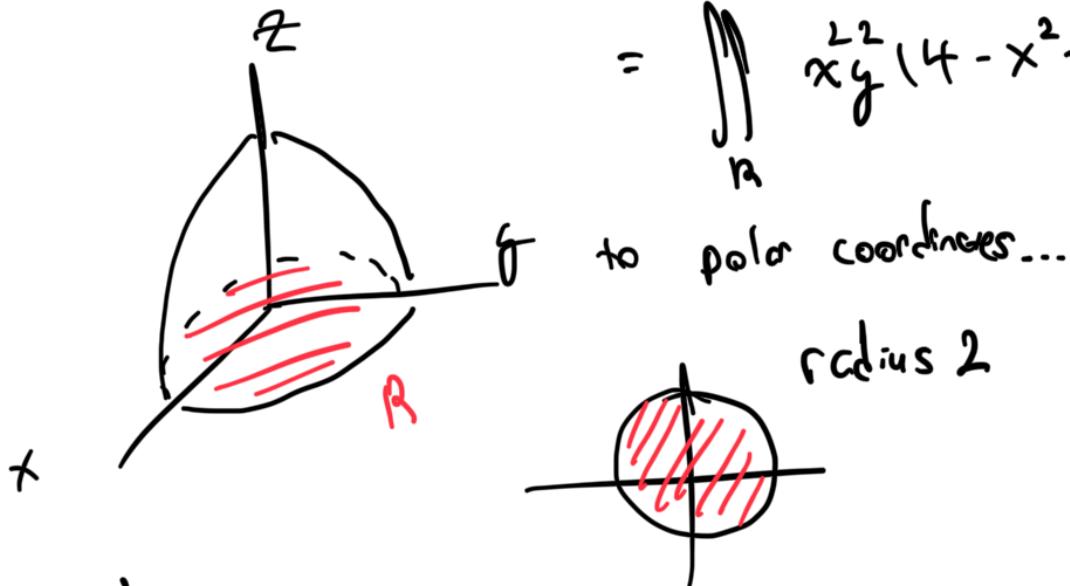
subject to density function $\rho(x, y, z) = x^2y^2$

$$M = \iiint_B \rho dV = \iiint_R x^2y^2 dz dA$$

$$z = 4 - x^2 - y^2$$

$$z=0$$

$$= \iint_R x^2y^2 (4 - x^2 - y^2) dA$$



$$\text{So } M = \iint_{r=0}^2 \int_{\theta=0}^{2\pi} (r \cos \theta)^2 (r \sin \theta)^2 (4 - r^2) r dr d\theta dA$$

$$= \int_0^2 \int_0^{2\pi} \cos^2 \theta \sin^2 \theta (r^5)(4 - r^2) dr d\theta$$

$$= \left(\int_0^2 r^5 (4 - r^2) dr \right) \left(\int_0^{2\pi} \cos^2 \theta \sin^2 \theta d\theta \right)$$

$$= \left(\int_0^2 4r^5 - r^7 dr \right) \left(\frac{1}{4} \int_0^{2\pi} \sin^2 2\theta d\theta \right)$$

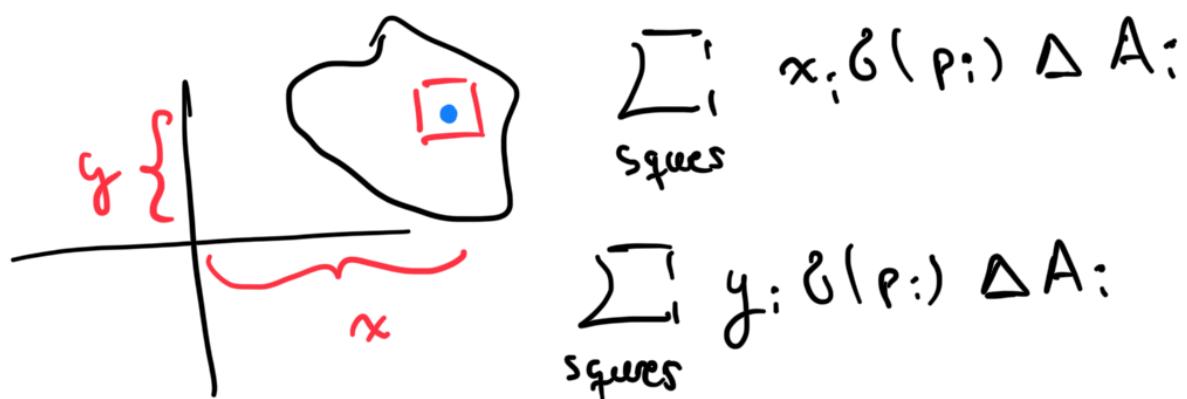
$$= \left(\frac{4}{6} r^6 - \frac{1}{8} r^8 \Big|_0^2 \right) \left(\frac{1}{4} \int_0^{2\pi} (\frac{1}{2}(1 - \cos 2\theta)) d\theta \right)$$

$$= \left(\frac{4}{6} \cdot 48 - \frac{1}{8} \cdot 128 \right) \left(\frac{1}{8} \right) (2\pi) = \left(\frac{32}{3} \right) \left(\frac{1}{8} \right) (2\pi)$$

$$= \frac{8}{3}\pi$$

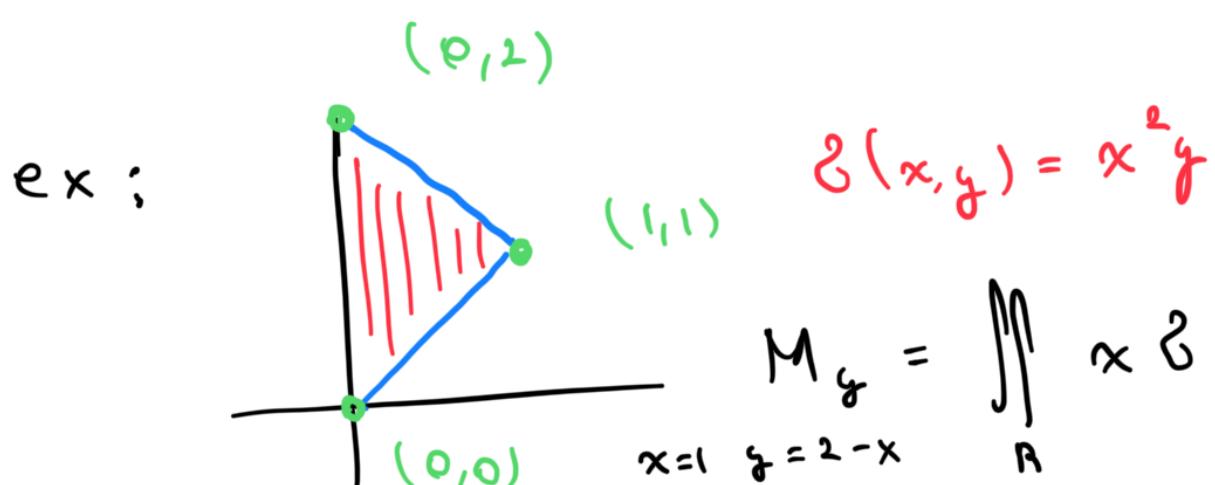
Center of Mass :

Integral that takes into account distance
and mass relative to origin.



$$\text{in limit converge to } M_y = \iint_R x \delta(p) dA$$

$$M_x = \iint_R y \delta(p) dA$$



$$M_y = \iint_R x \delta(x,y) dA$$

$$= \iint_{x=0}^{x=1} x (x^2 y) dy dx$$

$$= \int_0^1 x^3 \int_{y=x}^{y=2-x} y dy dx = \frac{1}{2} \int_0^1 x^3 [(2-x)^2 - x^2] dx$$

$$= \frac{1}{2} (1/5) = 1/10$$

Similarly, $M_x = \iint_R y (x^2 y) dy dx$

$$= \int_0^1 \int_{x^2}^{2-x} y^2 x^2 dy dx = \int_0^1 x^2 [1/3 (2-x)^3 - 1/3 x^3] dx$$

$$\int_0^1 x^2 \cdot 8x \, dx = \frac{1}{3} \left[x^3 \right]_0^1 (2-x) - x^2 \, dx$$

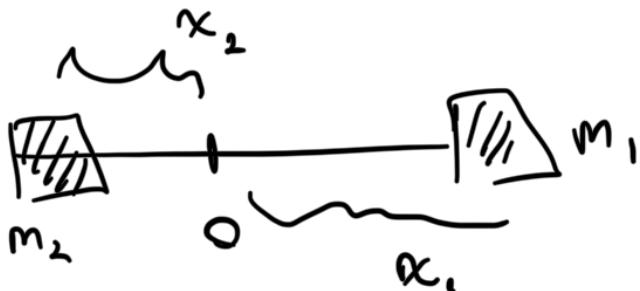
$$= \left(\frac{1}{3} \right) \left(8 \Big|_{15} \right) = \frac{8}{45}$$

Center of mass is where if you balance the object, it will remain still, under ideal circumstances.

$$\bar{x} = M_y/M \quad \bar{y} = M_x/M$$

Can think of M_x, M_y as
average of weighted mass-distances.

Called moments of
mass.



$$\bar{x} = \frac{x_1 m_1 + x_2 m_2}{m_1 + m_2}$$

ex: Above example we only need $M = \int_0^{2-x} x^2 y \, dx$

$$= \frac{1}{2} \int_0^1 x^2 ((2-x)^2 - x^2) \, dx = \left(\frac{1}{2} \right) \left(\frac{1}{3} \right) = \frac{1}{6}$$

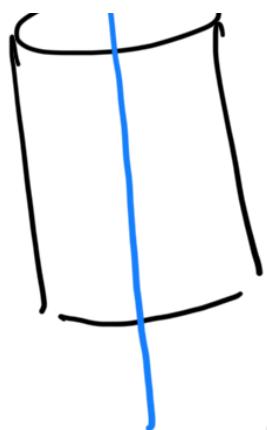
so center of mass is at $\left(\frac{M_y}{M}, \frac{M_x}{M} \right)$

$$(\bar{x}, \bar{y}) = \left(\frac{110}{116}, \frac{8/45}{116} \right) = \left(\frac{3}{5}, \frac{1}{15} \right)$$

Moment of inertia:

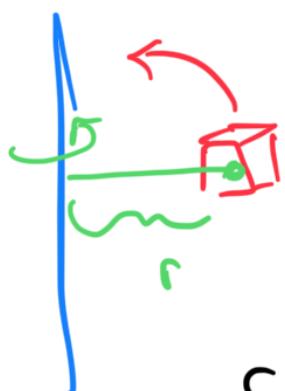
~~15~~

Consider a spinning mass about a



line, e.g., z -axis. Assume body spinning constnt rotational speed ω .

then for a mass spinning r -away from line, we have



$$KE = \frac{1}{2}mv^2, \quad \omega = \text{rotational velocity}$$

$$\omega r = v$$

$$\text{so } KE \text{ of small mass} = \frac{1}{2}m(\omega r)^2.$$

$$\begin{aligned} \text{Summing total energy} & \sum \frac{1}{2}m_i(\omega r_i)^2 \\ & \approx \sum \frac{1}{2}\rho(\rho_i)r_i^2\omega^2 dV \end{aligned}$$

$$\text{we get } KE = \frac{1}{2} \sum r_i^2 \omega^2 dV$$

$$\begin{aligned} V &= r\omega \text{ by} \\ \frac{ds}{dt} &= \frac{dx}{dt}(r\theta) \\ &= r \frac{d\theta}{dt} = r\omega \end{aligned}$$

$$= \frac{1}{2}\omega^2 \int_B^B (x^2 + y^2) \rho(r) dV$$

moment of inertia

$I_Z = \text{about line } L, \text{ in our case } Z$

You can think of I_Z as mass. It takes

$\frac{1}{2}mv^2$ energy to get a body m in motion.

I takes $\frac{1}{2}\omega^2 I_Z$ to get something to spin

about z -axis at angular velocity ω .

Similarly...

$$T = M_{\text{tot}}^2 \omega^2 I_Z dV$$

$$I_x = \iiint_B (x^2 + z^2) \rho \, dV$$

$$I_y = \iiint_B (x^2 + z^2) \rho \, dV$$

In 2 dimensions ...

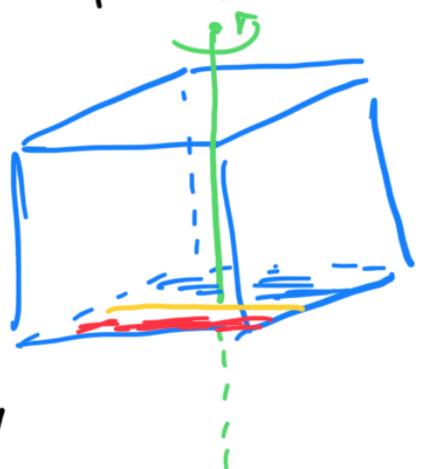
$$I_x = \iint_R y^2 \rho \, dA \quad I_y = \iint_R x^2 \rho \, dA$$

$$I_o = \iint_R (x^2 + y^2) \rho \, dA$$

Now in this context, object spinning around a point $(0,0)$ so $KE = \frac{1}{2} \omega^2 I_o$

ex: Calculate moment of inertia of a cube with vertices at $(\pm 1, \pm 1, 0)$ and $(\pm 1, \pm 1, 1)$ with density $\rho(x, y, z) = |xz|$.

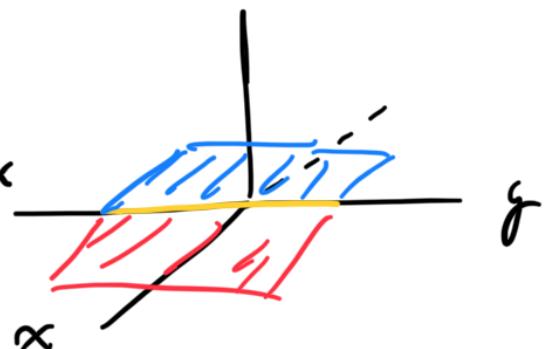
$$I_z = \iiint_B (x^2 + y^2) \rho \, dV$$



$$= \iiint_{B \text{ with } x \leq 0} (x^2 + y^2) \rho \, dV + \iiint_{B \text{ with } x \geq 0} (x^2 + y^2) \rho \, dV$$

$$= \int_{x=-1}^{x=0} \int_{y=-1}^{y=+1} \int_{z=0}^{z=1} (x^2 + y^2)(-xz) \, dz \, dy \, dx$$

(i)



$$+ \int_{x=0}^{x=1} \int_{y=-1}^{y=+1} \int_{z=0}^{z=1} (x^2 + y^2) (xz) dz dy dx \quad (\text{ii})$$

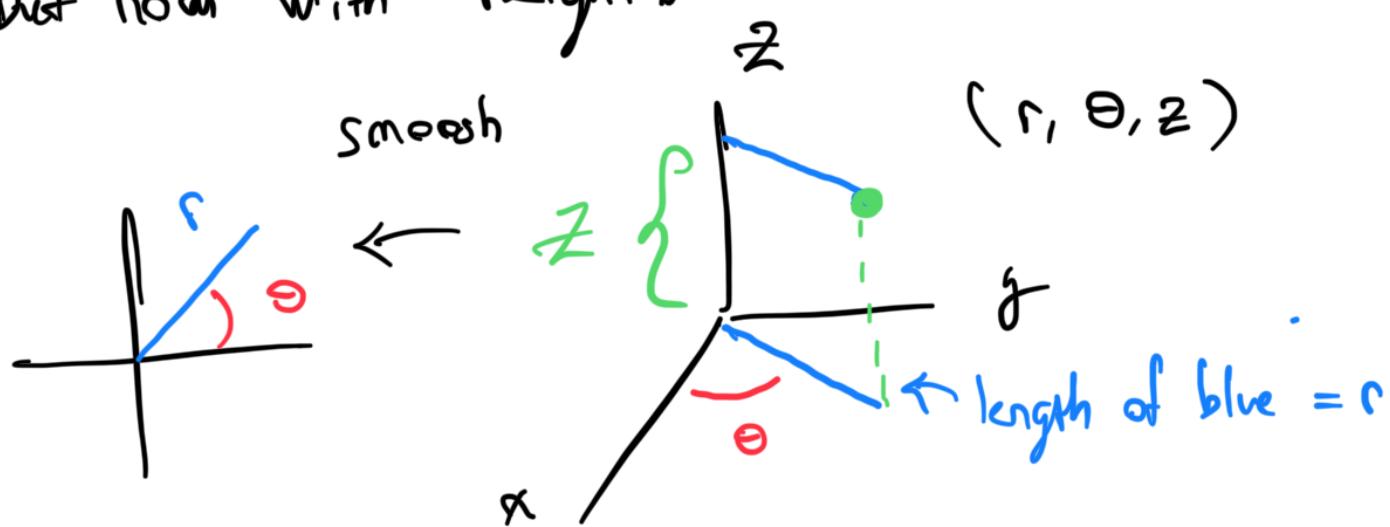
$$(\text{i}). \int_{-1}^0 \int_{-1}^1 \frac{1}{2} (x^2 + y^2) (-x) dy dx \quad (\text{ii}), \frac{5}{12}$$

$$= \int_{-1}^0 \int_{-1}^1 \frac{1}{2} (-x^3 - y^2 x) dy dx$$

$$= \int_{-1}^0 \left(-x^3 - \frac{x}{3} \right) dx = \frac{5}{12} \quad \text{so } I_z = \frac{10}{12} = \frac{5}{6}$$

15.7 : Integrals in Spherical and Cylindrical coordinates

Cylindrical coordinates : A point P in \mathbb{R}^3 is determined by (r, θ, z) . Just polar coordinates but now with height.



You can equate cartesian and cylindrical like before.

$$x = r \cos \theta \quad y = r \sin \theta \quad z = z$$

$$r^2 = x^2 + y^2 \quad \tan \theta = y/x \quad (\text{where dashed})$$

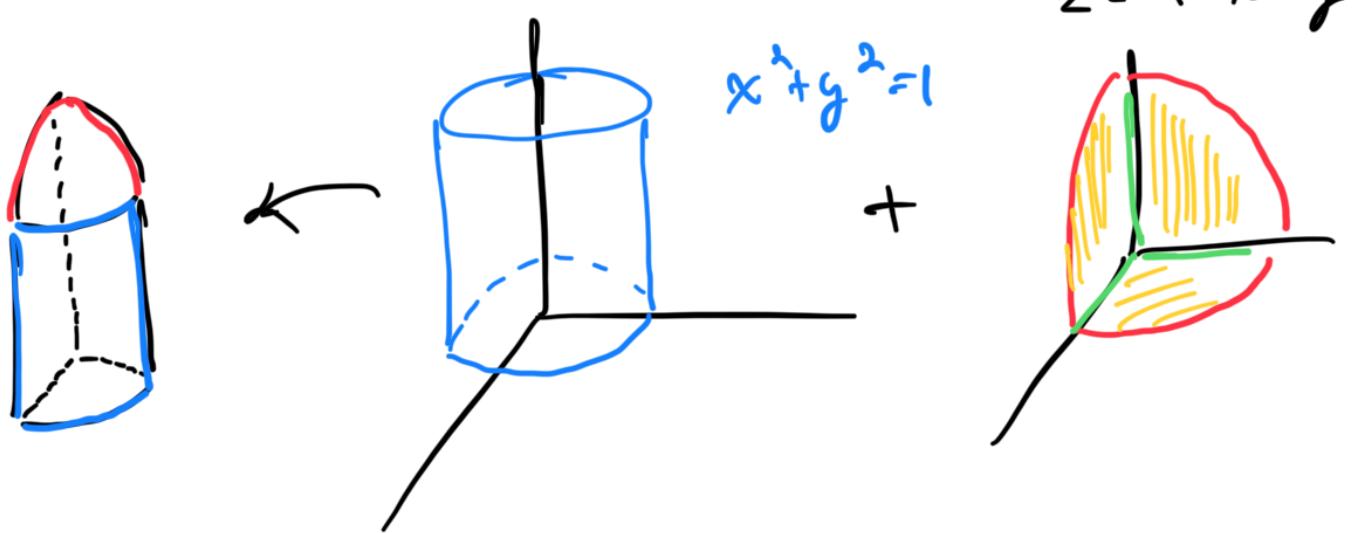
Why use them? Well good for problems where you have an axis of symmetry.

ex: Calculate volume bounded by

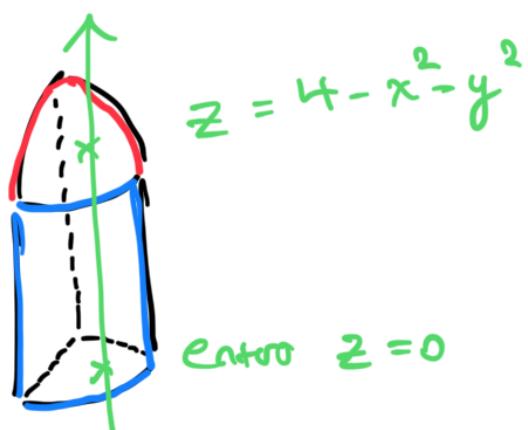
surfaces $x^2 + y^2 = 1$ and $z = 4 - x^2 - y^2$,

in the 1st octant.

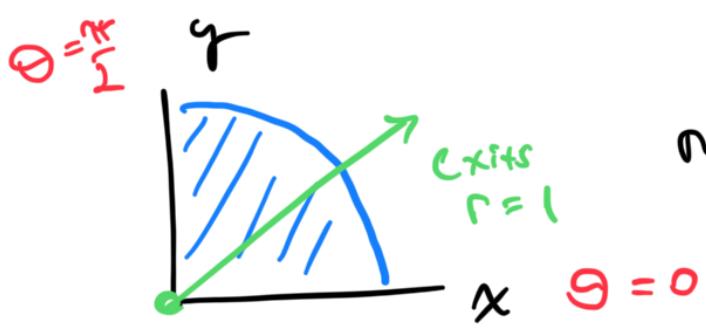
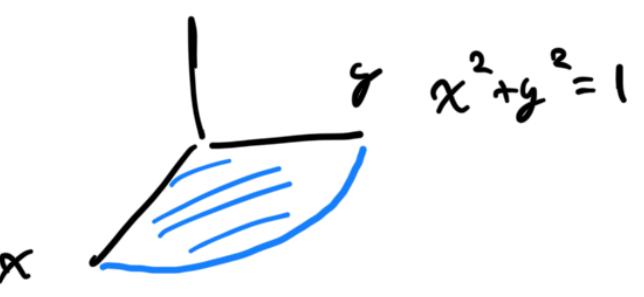
$$z = 4 - x^2 - y^2$$



Find z-limits



smooth



now do polar.

$$\theta = \pi/2, r = 1 \quad \dots \quad \pi/2, 4 - r^2$$

$$V = \iiint_{\substack{\theta=0 \\ r=0 \\ z=0}}^z r^3 dr d\theta dz$$

$z = 4 - x^2 - y^2$

$$dV = \iiint_0^{\pi/2} r(4-r^2) dr d\theta dz$$

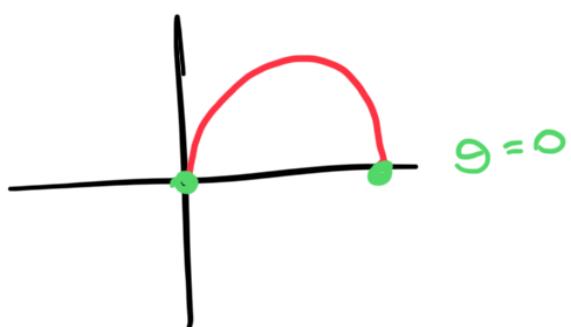
$$\begin{aligned} &= \int_0^{\pi/2} \left[2r^2 - \frac{1}{4}r^4 \right]_0^{\pi/2} d\theta \\ &= \int_0^{\pi/2} \frac{7}{4} d\theta = \frac{7\pi}{8} \end{aligned}$$

$$dV = r dz dr d\theta //$$

ex: 15. 7. 11 Calculate volume

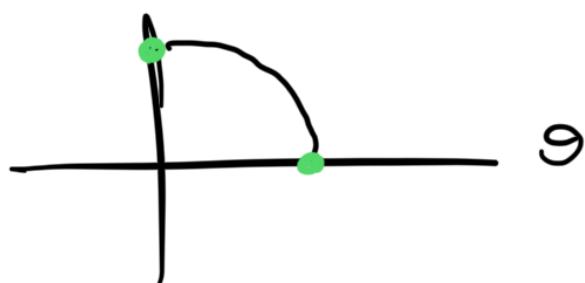
$$0 \leq r \leq 4 \cos \theta, \quad 0 \leq \theta \leq \pi/2, \quad 0 \leq z \leq r^2$$

$$\theta = \pi/2$$

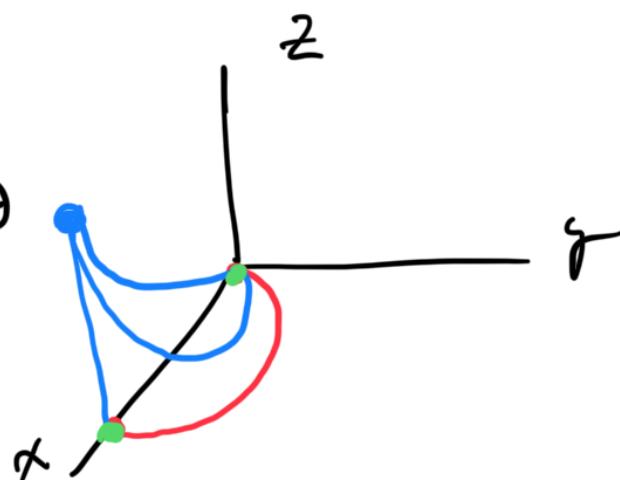


$$r(\theta)$$

$$r = 4 \cos \theta$$



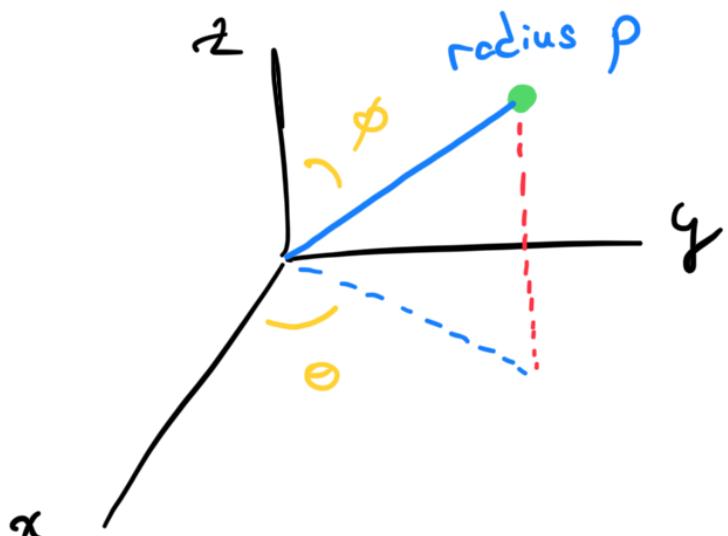
$$V = \iiint_{\substack{\theta=0 \\ r=0 \\ z=0}}^z r^3 dr d\theta dz$$



$$V = \int_0^{\pi/2} \int_0^{4 \cos \theta} r^3 dr d\theta = \int_0^{\pi/2} \frac{1}{4} (4 \cos \theta)^4 dr d\theta$$

$$= \left(\frac{1}{4}\right)(48\pi) = 12\pi$$

Spherical coordinates



$$P = (p, \phi, \theta)$$

or (p, θ, ϕ) depending
on choice. Book uses

$$(p, \phi, \theta)$$

Again have ways of going back and forth
between Cartesian and spherical,

$$x = p \sin \phi \cos \theta$$

$$p^2 = x^2 + y^2 + z^2$$

$$y = p \sin \phi \sin \theta$$

$$z = p \cos \phi$$

Can also check cylindrical and spherical

$$r = p \sin \phi$$

$$p^2 = r^2 + z^2$$

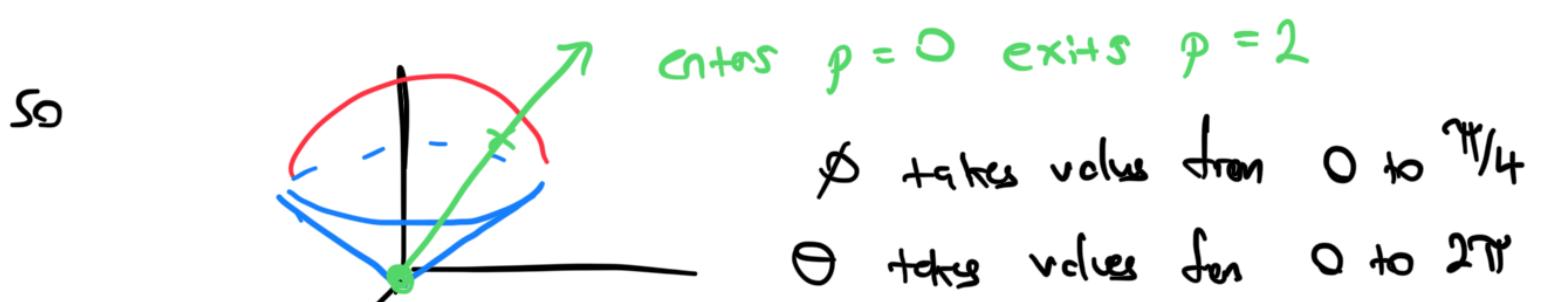
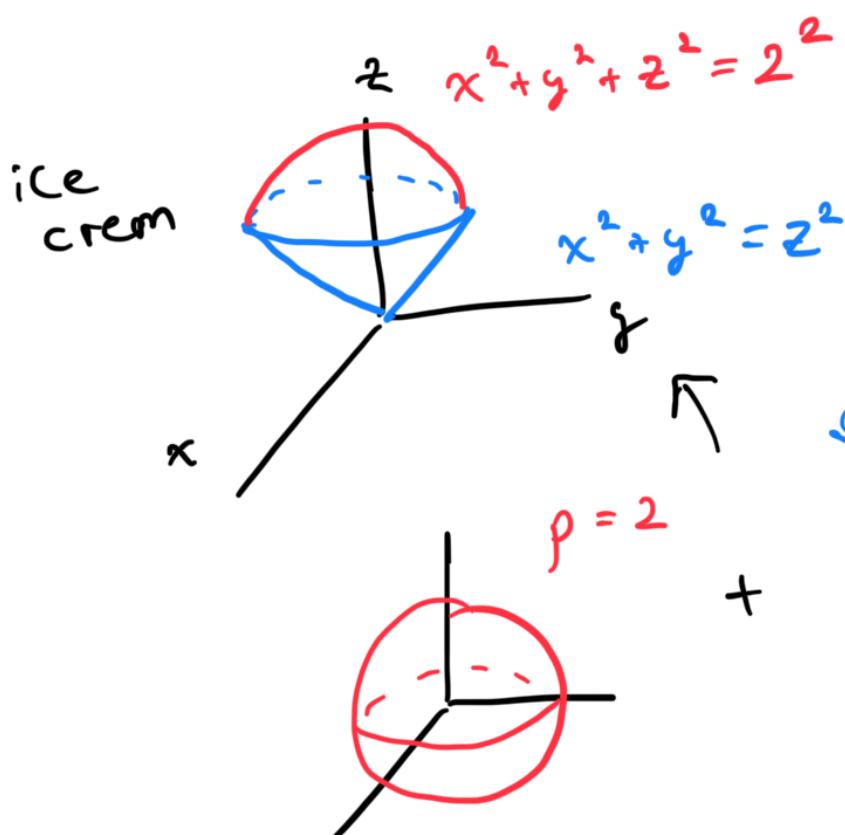
$$z = p \cos \phi$$

$$\theta = \theta$$

Why spherical coordinates? Use when you have a
point of symmetry.

ex: Calculate volume of body bounded by
by sphere of radius 2 centred at origin

and the cone $x^2 + y^2 = z^2$
and $z \geq 0$.



$$\text{So } V = \iiint_{\Theta=0, \phi=0, p=0}^{2\pi, \pi/4, 2} dV = \int_0^{2\pi} \int_0^{\pi/4} \int_0^2 \rho^2 \sin \phi \, d\rho \, d\phi \, d\theta$$

$$= \int_0^{2\pi} \int_0^{\pi/4} \frac{8}{3} \sin \phi \, d\phi \, d\theta$$

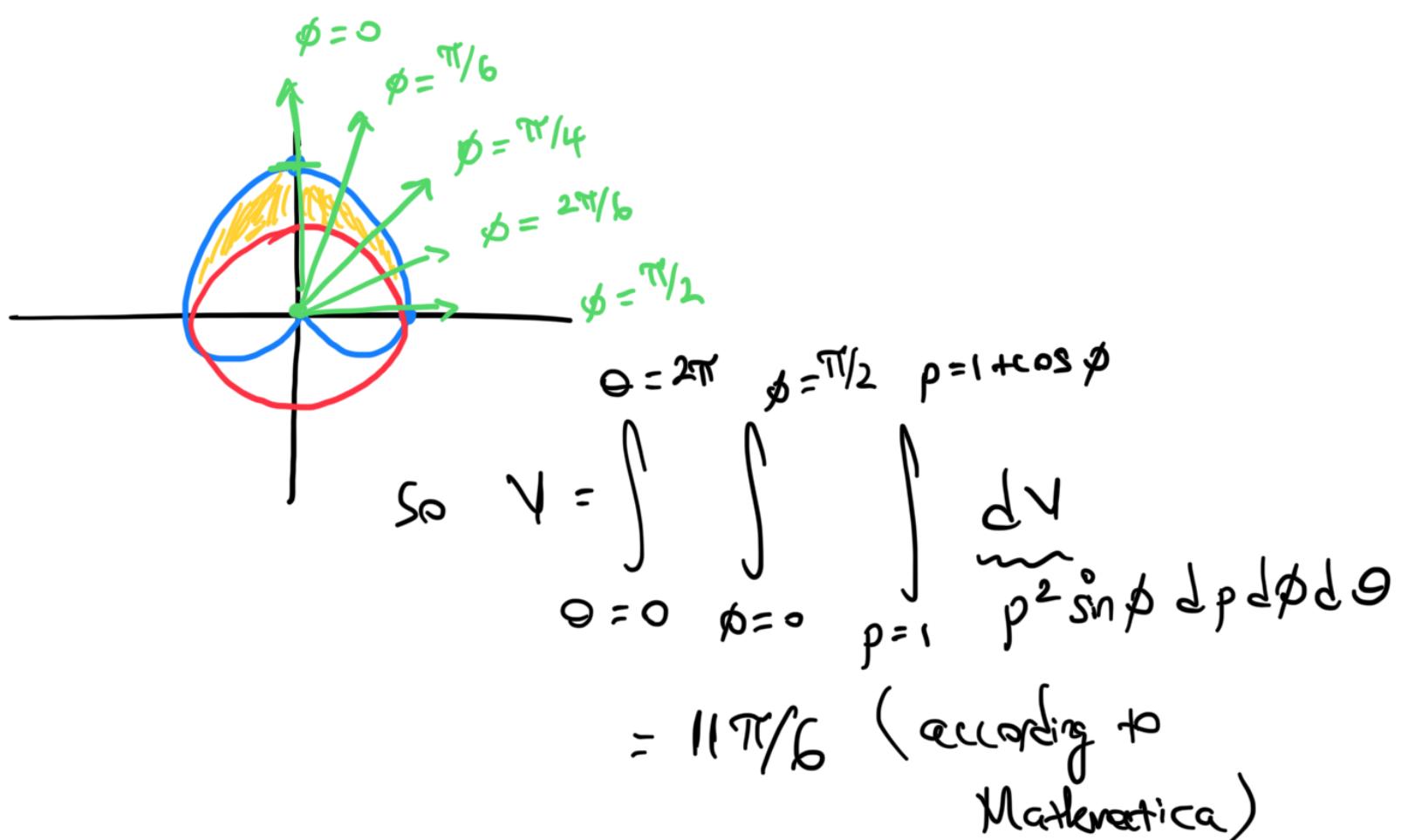
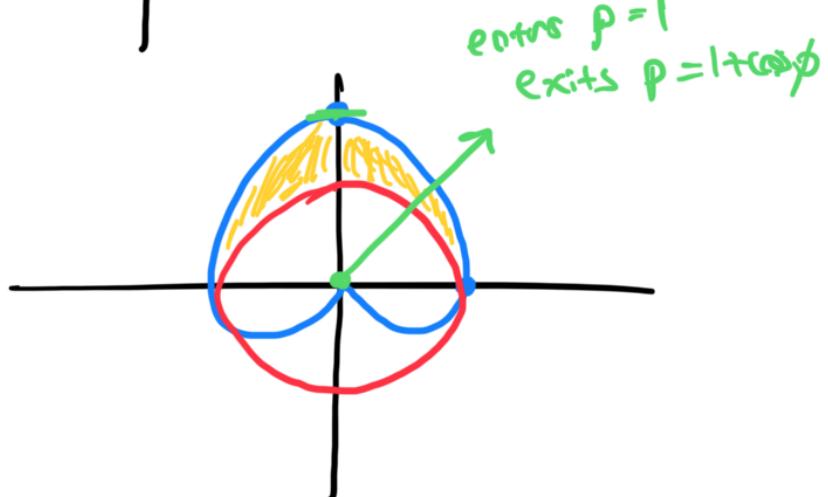
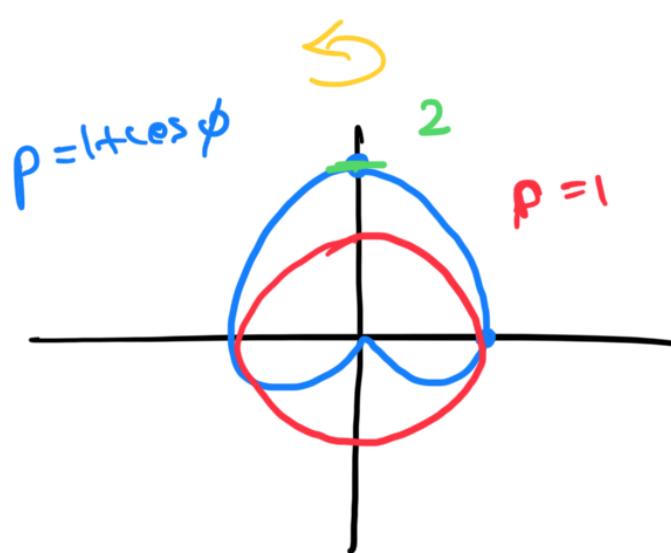
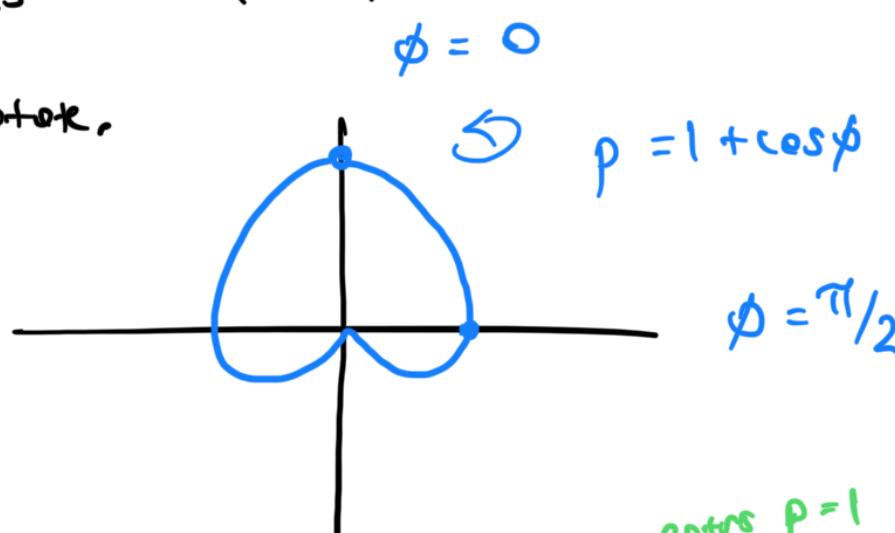
$$= \frac{8}{3} \left(1 - \frac{\sqrt{2}}{2}\right) (2\pi) = \frac{16\pi}{3} \left(1 - \frac{\sqrt{2}}{2}\right)$$

15.7.56. Find volume of solid bounded below hemisphere
 $\rho = 1$, $z \geq 0$, and above $\rho = 1 + \cos \phi$

First, what does $\rho = 1 + \cos \phi$ look like?

Well first it has Θ -symmetry. So draw

in a plane, then rotate.

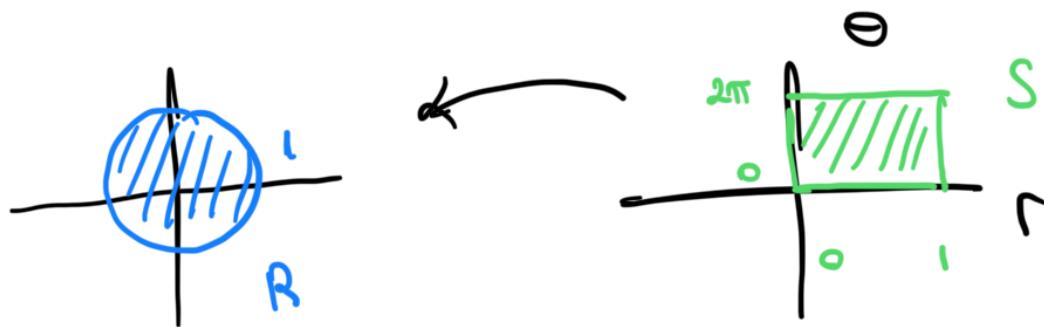


15.8 : Substitution in Multiple Integrals

When you change from one coordinate system to another, the dA or dV changes too.

You can see this in the following

$$dA = dx dy = r dr d\theta$$



$$\begin{aligned} \text{so when } \iint_R f(x, y) dx dy &= \iint_S f(x(r, \theta), y(r, \theta)) r dr d\theta \\ &= \iint_S f(r \cos \theta, r \sin \theta) r dr d\theta \end{aligned}$$

\uparrow called the Jacobian

More generally...

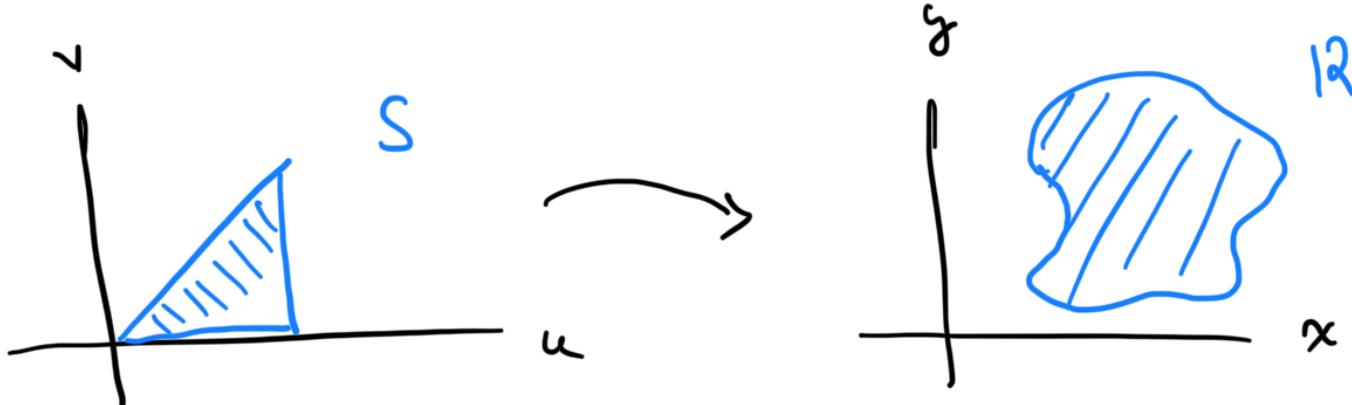
theorem: let S be in (u, v) -coordinates
and say $x = g(u, v)$ $y = h(u, v)$ for
some functions g, h so that

$$J(u, v) = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u} \neq 0$$

on S

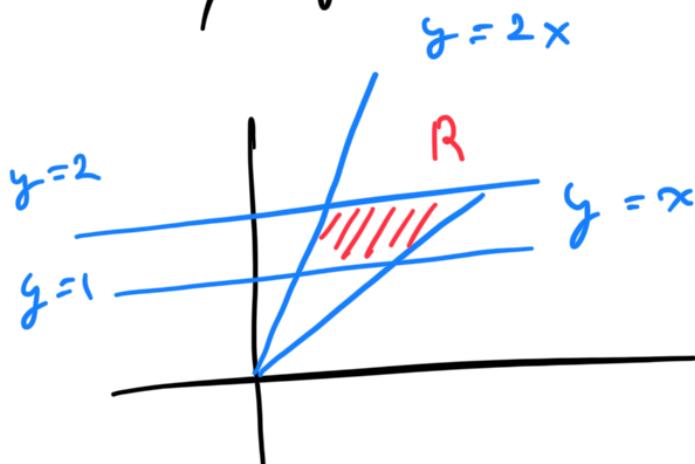
Let R denote image of S under (g, h) .

$$\iint_R f(x, y) dx dy = \iint_S f(g(u, v), h(u, v)) |J(u, v)| du dv$$



ex: Calculate integral of $\frac{x}{y} + \frac{y}{x}$
over region bounded by $y = 2x$, $y = x$

$$y = 1 \text{ and } y = 2$$



$$u = \frac{y}{x} \quad v = y$$

then solve for x and y . What is the region?

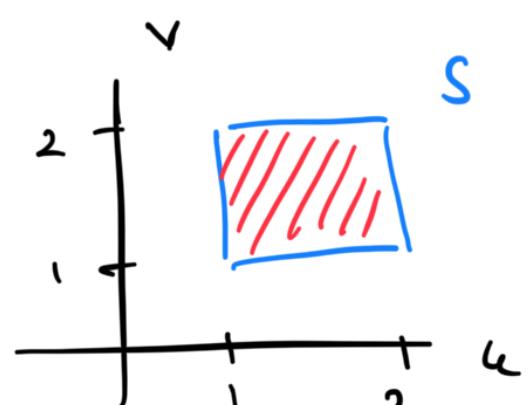
$$y = v \text{ so } x = \frac{y}{u} = \frac{v}{u}$$

$$(\therefore) \ y = 1 \sim v = 1$$

$$(\therefore) \ y = 2 \sim v = 2$$

$$(\therefore) \ y = x \sim \frac{y}{x} = 1 \sim u = 1$$

$$(\text{iv}) \ y = 2x \sim \frac{y}{x} = 2 \sim u = 2$$

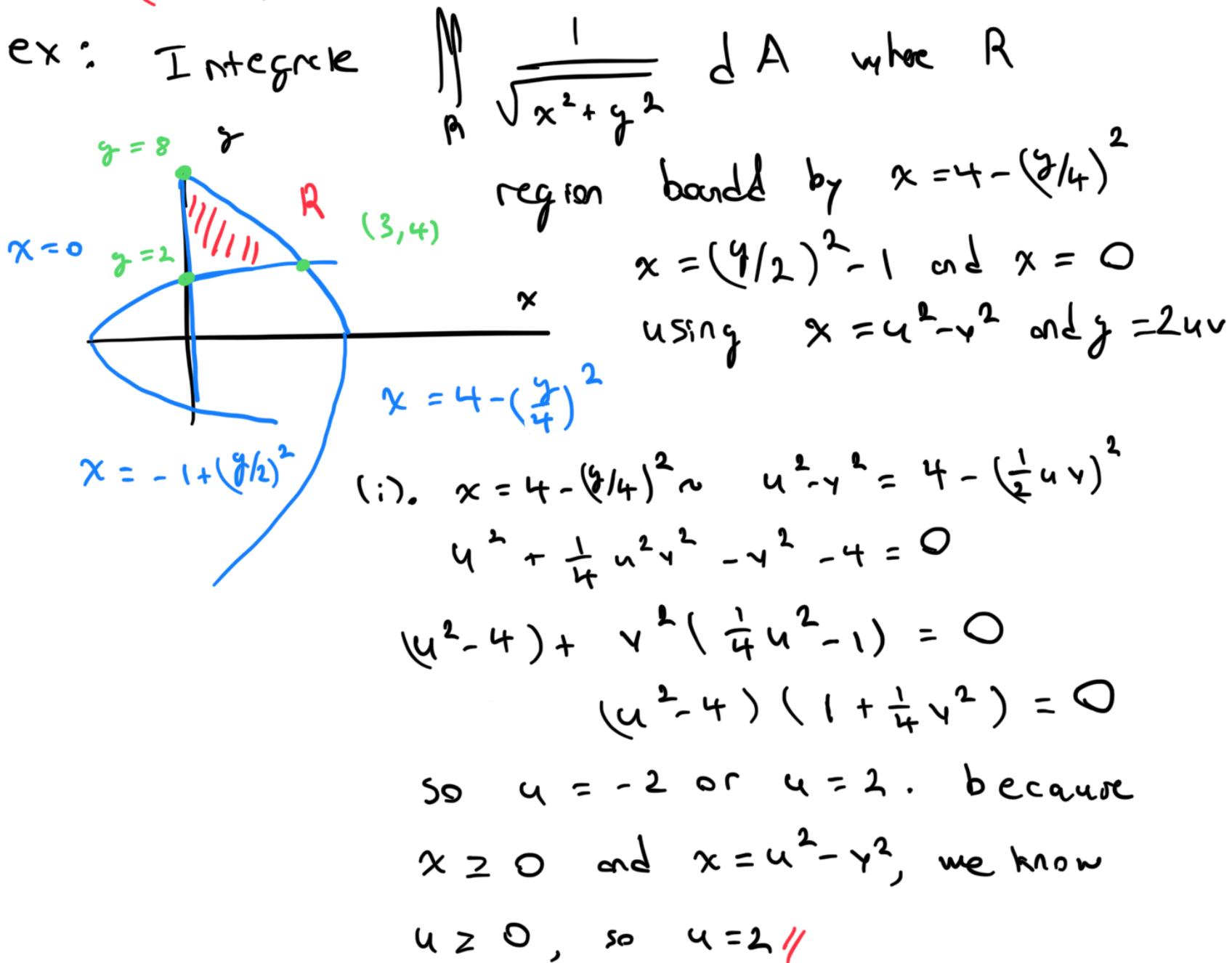


Jacobian:

$$\begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \begin{vmatrix} -v/u^2 & 1/u \\ 0 & 1 \end{vmatrix} = -v/u^2$$

$$\begin{aligned}
 S_0 & \iint_R \frac{x}{y} + \frac{y}{x} dA = \iint_S \left(y + \frac{1}{y}\right) \left| -\frac{y}{u^2} \right| dA' \\
 &= \int_1^2 \int_{-1}^1 \left(y + \frac{1}{y}\right) \frac{y}{u^2} du dy = \int_1^2 \int_{-1}^1 \frac{y^2 + y}{u^2} du dy \\
 &= 2^{3/2} \text{ (according to Mathematica)}
 \end{aligned}$$

(do this ex last!)

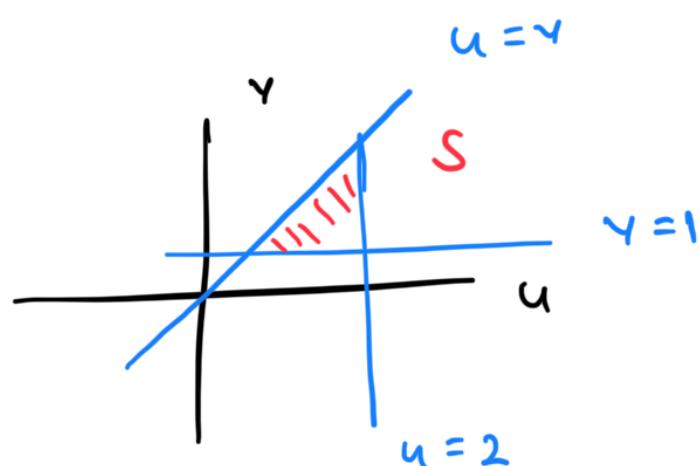


(ii). $x = -1 + (\frac{y}{2})^2 \sim u^2 - v^2 = -1 + (uv)^2$
 $u^2 - u^2v^2 - v^2 + 1 = 0$
 $u^2(1 - v^2) + (1 - v^2) = 0$

$(u^2 + 1)(1 - v^2) = 0$ so
 $1 = v$ or $-1 = v$. bc $x \geq 0$
 $u \geq 0$ like before. Also $y \geq 0$
 and $y = 2uv$ so $v \geq 0$. Thus
 $v = +1$ //

(iii). $x = 0 \sim u^2 - v^2 = 0$ so $u = v$ or $u = -v$.
 bc all $y \geq 0$ need $u = v$. //

So S bounded by



Jacobian: $J(u, v) = \begin{vmatrix} 2u & -2v \\ 2v & 2u \end{vmatrix} = 4u^2 + 4v^2$

Integrand: $\sqrt{x^2 + y^2} = \sqrt{(u^2 - v^2)^2 + (2uv)^2}$
 $= \sqrt{u^4 - 2u^2v^2 + v^4 + 4u^2v^2}^{1/2}$
 $= \sqrt{u^4 + 2u^2v^2 + v^4}^{1/2} = u^2 + v^2$

so $I = \iint_S \left(\frac{1}{u^2 + v^2} \right) (u^2 + v^2) \, du \, dv = 4 \iint_S \, du \, dv$
 ↓ integrand ↑ Jacobian $= 4 \left(\frac{1}{2} \right) = 2$

ex: Integrate $\sqrt{1+y^3}$ over region bounded

by $y=0$, $x=2y^2$, $x=1+y^2$ using

$$x = u + v^2$$

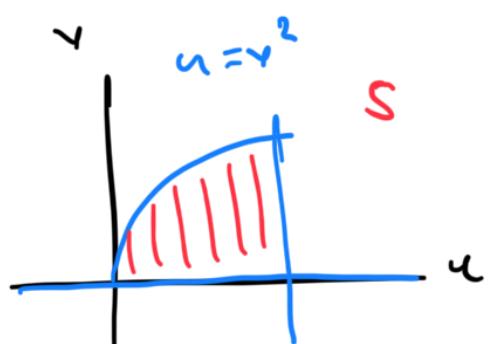
$$y = v$$

$$(i). \quad y = 0 \sim v = 0 // \quad \text{Jacobi: } J(u, v) = \begin{vmatrix} 1 & 2v \\ 0 & 1 \end{vmatrix}$$

$$(ii). \quad x = 2v^2 \sim u + v^2 = 2v^2 \\ \text{so } u = v^2 // \quad = 1$$

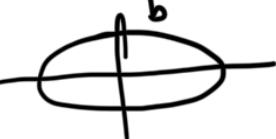
$$(iii). \quad x = 1 + v^2 \sim u + v^2 = 1 + v^2 \\ \text{so } u = 1 //$$

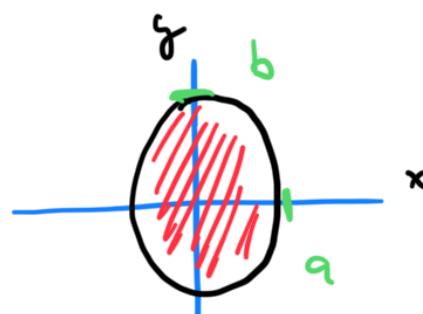
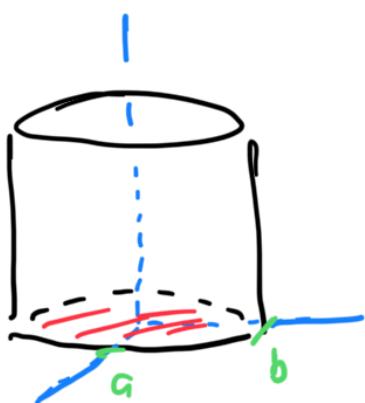
$$\text{Intgrd: } \sqrt{1+v^2}$$



$$\text{so } I = \iint_S \sqrt{1+v^2} \, 1 \, du \, dv$$

$$= \int_0^1 \int_0^{v^2} \sqrt{1+v^2} \, du \, dv = 2(2\sqrt{2}-1)/9$$

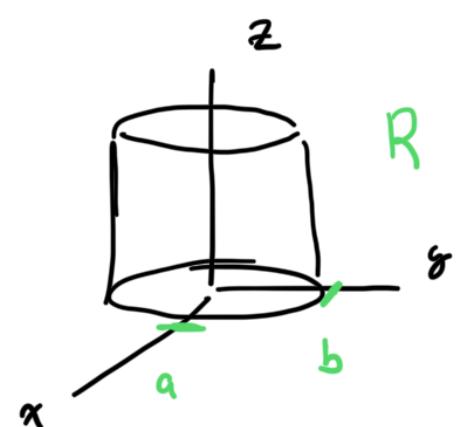
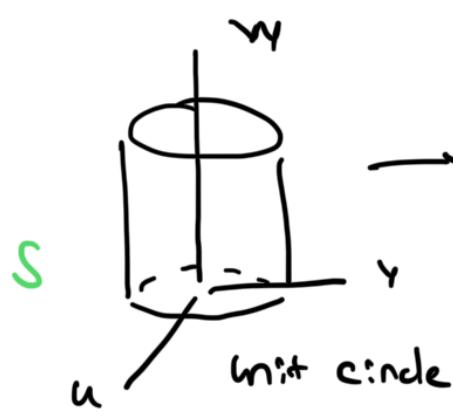
ex: Calculate volume of an elliptic cylinder
of base  and height h.

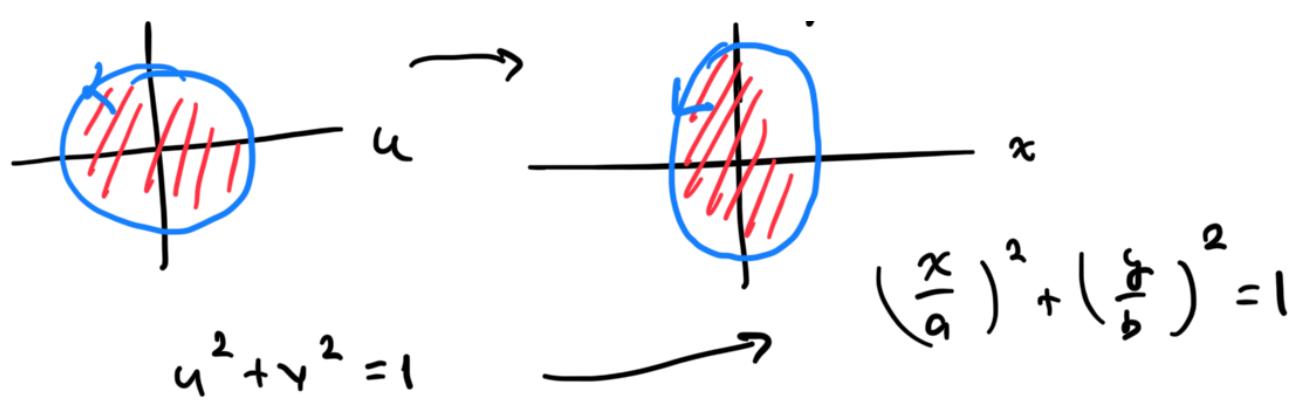


$$a \, u = x$$

$$b \, v = y \quad \text{then}$$

$$w = z$$





$$\text{Jacobin } (u, v, w) = \begin{vmatrix} x_u & x_v & x_w \\ y_u & y_v & y_w \\ z_u & z_v & z_w \end{vmatrix} = \begin{vmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & 1 \end{vmatrix}$$

$$= ab$$

so $\iiint_R dv = \iiint_S ab dv'$ $dv' = da dy dw$

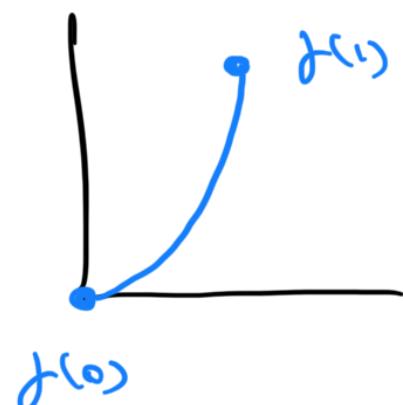
$$= ab \iiint_S dv' \leftarrow \begin{array}{l} \text{volume cylinder height } h \\ \text{unit circle base} \end{array}$$

$$= \pi abh$$

16.1: Line integrals of scalar functions

Motivator by example of mass of a wire in \mathbb{R}^2 . Say we have $\delta(x, y) = \alpha \text{ kg/m}$ and have a curve by $\gamma(t) = (t, t^2)$ for $0 \leq t \leq 1$. So want the mass of a small part of the wire

$\delta(\gamma(t_i))$ $\delta(\gamma(t_{i+1}))$
 ds so mass



$$f(x_i) \approx \delta(f(x_i)) \underbrace{(\text{length from } f(x_{i+1}) \text{ and } f(x_i))}_{\Delta s_i}$$

Mass $\approx \sum_i \delta(f(x_i)) \Delta s_i$
 bunch of pieces

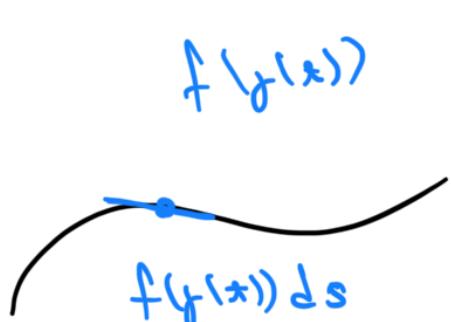
$\xrightarrow{\text{limit}}$

$$\int_0^1 \delta(f(x)) ds$$

$$ds = \sqrt{1+4x^2} dx$$

$$\begin{aligned} \text{So } M &= \int_0^1 x \cdot \sqrt{1+4x^2} dx \\ &= \int_1^5 \frac{1}{8} \sqrt{u} du \\ u(0) &= 1 & u &= 1+4x^2 \\ u(1) &= 5 & du &= 8x dx \\ &= \frac{1}{12} (3\sqrt{5} - 1) & \frac{1}{8} du &= x dx \end{aligned}$$

So in general, if C is a curve in \mathbb{R}^2 or \mathbb{R}^3 ,
 we calculate 'line integrals' of a scalar
 function f (even if C isn't a line).



$$\int_C f ds = \int_a^b f(f(x)) |\vec{v}(x)| dx$$

where $f(x)$ goes from $f(a)$ to $f(b)$.

e x: Evaluate $f(x, y, z) = x^2 + y^2 + z^2$

along the line segment from $(0, 0, 0)$ to $(1, 1, 1)$.

$$\begin{aligned} f(x) &= (x, x, x) \text{ from } x=0 \text{ to } x=1. \\ ds &= \sqrt{1^2 + 1^2 + 1^2} dx = \sqrt{3} dx \end{aligned}$$

$$\text{So } \int f ds = \int_0^1 (x^2 + x^2 + x^2) \sqrt{3} dx$$

$$= 3\sqrt{3} \left. \frac{t^3}{3} \right|_0^1 = \sqrt{3}$$

Ex: Same problem but $\alpha(t) = (\sin t, \sin t, \sin t)$
for $t=0$ to $t=\pi/2$.

$$(f \circ \alpha)(t) = 3\sin^2 t \quad ds = \sqrt{3\cos^2 t} dt \\ ds = \sqrt{3|\cos t|} dt$$

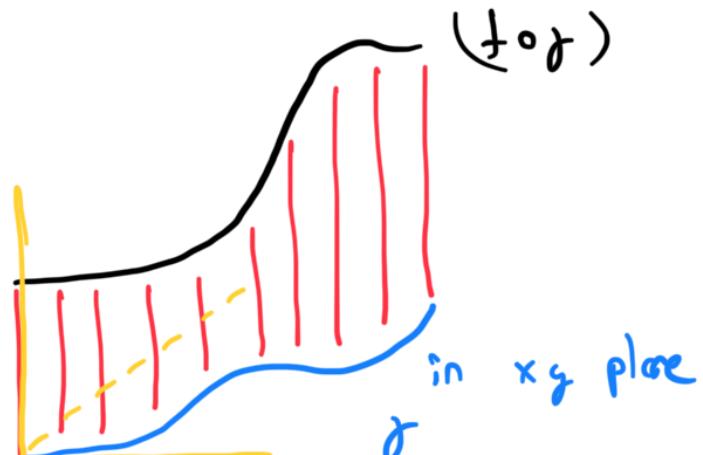
$$\text{so } \int_{\alpha} f ds = \int_0^{\pi/2} 3\sin^2 t \sqrt{3\cos t} dt \\ = \int_0^1 3\sqrt{3} u^2 du$$

$$u = \sin t \quad u(0) = 0 \\ du = \cos t dt \quad u(\pi/2) = 1 \\ = \sqrt{3}$$

Moral: Doesn't matter how you parameterize
the path, so choose most convenient!

Ex: Let $z = x^2 + y^2$ integrate function over
path $\gamma(t) = (\cos t, \sin t)$

In general:



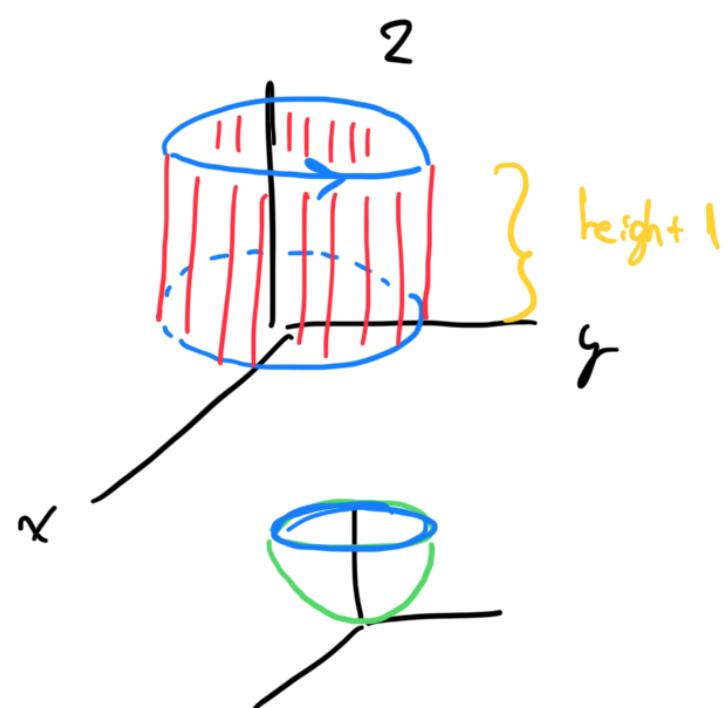
$$\text{Area} = \int_{\gamma} f ds.$$

$$\text{in our example } f(y(x)) = \cos^2 x + \sin^2 x$$

$$ds = \sqrt{\sin^2 x + \cos^2 x} dx$$

$$\text{so } ds = dx$$

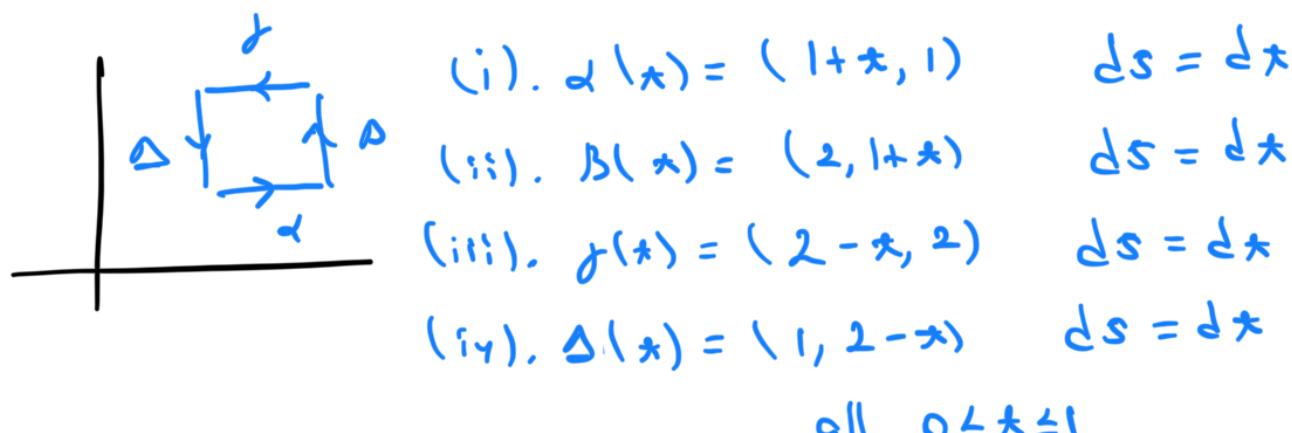
$$\text{so Area} = \int_0^{2\pi} 1 dx = 2\pi$$



ex: Say have a $\mathcal{G}(x,y) = \frac{x}{y}$.

Want to calculate mass of square with

vertices $(1,1), (2,1), (1,2), (2,2)$.



$$(i). \mathcal{G}(\alpha(x)) = \frac{1+x}{1} = 1+x \quad (ii). (\mathcal{G} \circ B)(x) = \frac{2}{1+x}$$

$$\int_0^1 (1+x) dx = \frac{3}{2} \quad \int_0^1 \frac{2}{1+x} dx = \ln(4)$$

$$(iii). (\mathcal{G} \circ f)(x) = \frac{2-x}{2} \quad (iv). (\mathcal{G} \circ \Delta)(x) = \frac{1}{2-x}$$

$$\int_0^1 1 - \frac{x}{2} dx = \frac{3}{4} \quad \int_0^1 \frac{1}{2-x} dx = \ln(2)$$

$$M_A - M_1 + M_2 - M_3 + M_4 = 9/4 + 3\ln(2)$$

ex: Let's say the wire $\gamma(t) = (\cos t, \sin t, t)$
 from $t=0$ to $t=2\pi$. Also say that
 $\rho(x, y, z) = (x^2 + y^2)e^z$. Write integrals for the
 various moments of inertia of the wire relative
 to each of the coordinate axes. Do not calculate.

$$I_x = \int_{\gamma} (y^2 + z^2) \rho ds \quad ds = \sqrt{1+1} dt \\ = \sqrt{2} dt$$

$$I_y = \int_{\gamma} (x^2 + z^2) \rho ds$$

$$I_z = \int_{\gamma} (x^2 + y^2) \rho ds$$

$$I_x = \int_0^{2\pi} (\sin^2 t + t^2) (\cos^2 t + \sin^2 t) e^t \sqrt{2} dt \\ = \sqrt{2} \int_0^{2\pi} (\sin^2 t + t^2) e^t dt$$

$$I_y = \int_0^{2\pi} (\cos^2 t + t^2) (\cos^2 t + \sin^2 t) e^t \sqrt{2} dt \\ = \sqrt{2} \int_0^{2\pi} (\cos^2 t + t^2) e^t dt$$

$$I_z = \int_e^{2\pi} (\cos^2 t + \sin^2 t) (\cos^2 t + \sin^2 t) e^t \sqrt{2} dt \\ = \sqrt{2} \int_0^{2\pi} e^t dt$$

ex: Same path as before but cosine constant

1. 2. 3. 1. center of mass of

density ρ . Calculate M_x , M_y , M_z for the wire. Intuitively $(\bar{x}, \bar{y}, \bar{z}) = (0, 0, \pi)$.

$$M_x = \int_{\gamma} x \rho ds = 2 \int_0^{2\pi} (\cos \kappa) \sqrt{2} d\kappa = 0$$

$$M_y = \int_{\gamma} y \rho ds = 2 \int_0^{2\pi} (\sin \kappa) \sqrt{2} d\kappa = 0$$

$$M_z = \int_{\gamma} z \rho ds = 2 \int_0^{2\pi} \kappa \sqrt{2} d\kappa = 2 \sqrt{2} \pi^2$$

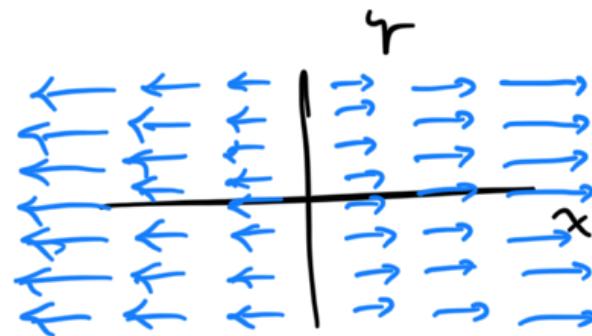
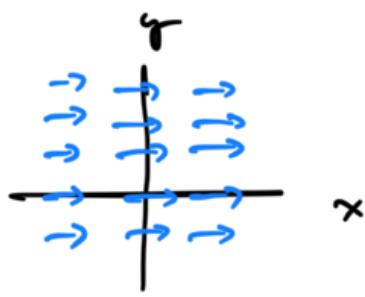
$$M = \int_{\gamma} \rho ds = 2 \int_0^{2\pi} \sqrt{2} d\kappa = 2 \sqrt{2} \pi$$

$$\text{so } (\bar{x}, \bar{y}, \bar{z}) = \frac{(0, 0, 8\sqrt{2}\pi^2)}{2\sqrt{2}\pi} = (0, 0, \pi)$$

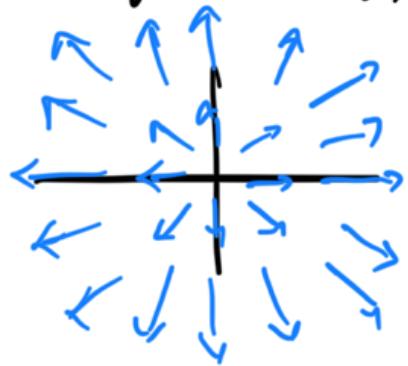
16.2: Line Integrals, Vector Fields, Work, Circulation, Flux.

A vector field is a map that associates each point (x, y) a vector $\vec{F}(x, y)$. Can visualize them by drawing a bunch of arrows.

e.g.: $\vec{F}(x, y) = (1, 0)$ e.g. $\vec{F}(x, y) = (x, 0)$



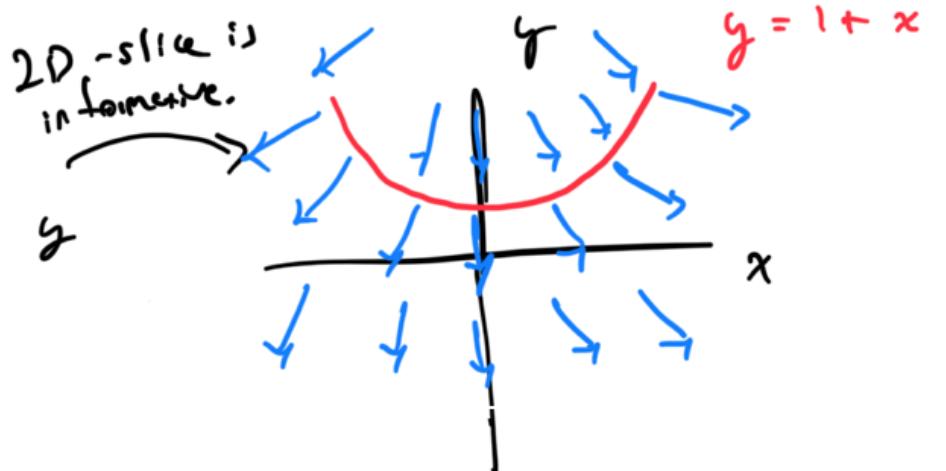
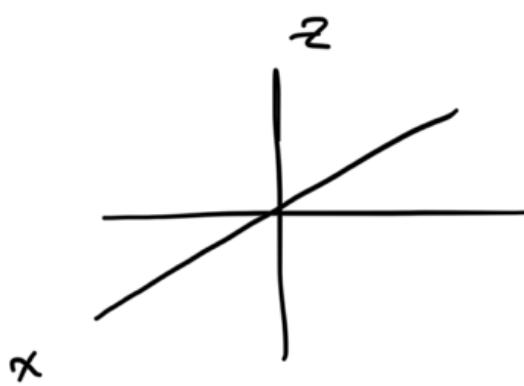
e.g. $\vec{F}(x, y) = (x, y)$



Why?: Velocity field
of wind map, Electric field
of particles, magnetic fields,
Force fields more generally, etc.

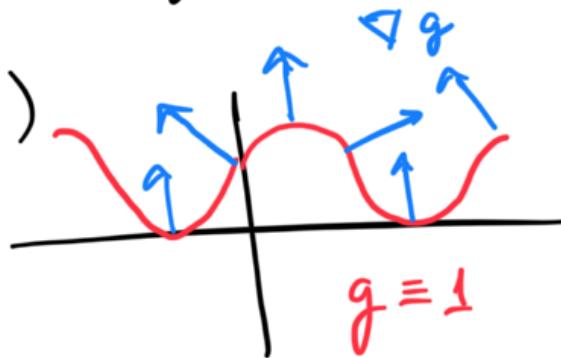
ex: Let $f(x, y, z) = x^2 - y$ then

$$\nabla f(x, y, z) = (2x, -1, 0)$$



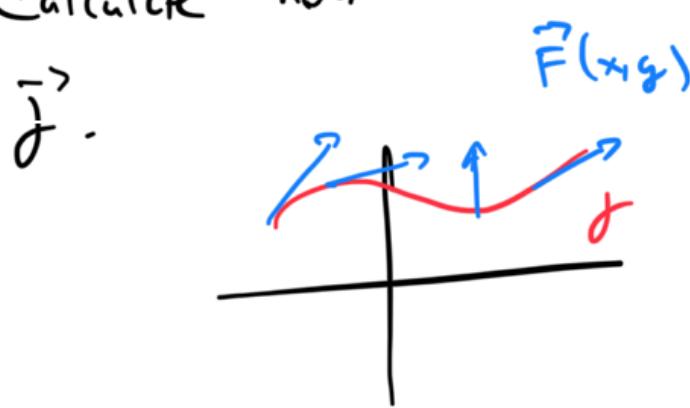
Example of a gradient vector field. Take your favorite function e.g. $g(x, y) = y - \sin(x)$

$$\text{and } \nabla g(x, y) = (-\cos(x), 1)$$

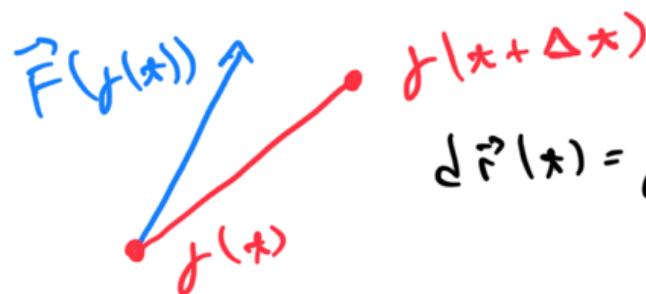


let's say have a force vector field

$\vec{F}(x, y)$. Say you have a curve γ . Want to calculate how much work it takes to do $\vec{F}(x, y)$ along γ .



at infinitesimal level...



$$d\vec{r}(t) = \gamma(t + \Delta t) - \gamma(t)$$

$$\begin{aligned} W(\gamma(t)) &\approx \vec{F}(\gamma(t)) \cdot d\vec{r}(t) \\ &\approx \vec{F}(\gamma(t)) \cdot (\gamma(t + \Delta t) - \gamma(t)) \end{aligned}$$

$$\text{So Work} = \int_{\gamma} \vec{F} \cdot d\vec{r} = \int_a^b \vec{F}(\gamma(t)) \cdot \underbrace{\frac{d\vec{r}}{dt}(t)}_{\text{we did last section.}} dt$$

ex : Consider $\vec{F}(x, y, z) = (x-y, x+y, z)$

and calculate work along straight line
from $(0, 0, 0)$ to $(1, 1, 0)$.

$$\gamma(t) = (t, t, 0) \text{ so } \frac{d\vec{r}}{dt} = (1, 1, 0)$$

$$\vec{F}(\gamma(t)) = (t-t, t+t, 0) = (0, 2t, 0)$$

$$\text{So } W = \int_0^1 (0, 2t, 0) \cdot (1, 1, 0) dt = \int_0^1 2t dt = 1 \text{ Nm} //$$

Gives rise to notion of a line integral (even though not always lines).

def: let \vec{F} be a vector field and let γ be a smooth curve parametrized by $\vec{r}(s)$. Define

$$\int_{\gamma} \vec{F} \cdot \vec{T} ds = \int_{\gamma} \vec{F} \cdot \frac{d\vec{r}}{ds} ds = \int_{\gamma} \vec{F} \cdot d\vec{r} //$$

where s is arc length parameter and \vec{T} is unit tangent vector,

ex: let $\vec{F}(x, y, z) = (y^2, 2xz, -1)$.

Calculate line integral of \vec{F} over the curve

$$\gamma(s) = (s, s^2, 1) \text{ from } (0, 0, 1) \text{ to } (1, 1, 1).$$

$$\vec{F}(\gamma(s)) = (s^4, 2s^3, -1)$$

$$\frac{d\vec{r}}{dt} = (1, 2s, 0) \quad t=0 \text{ to } t=1.$$

$$\begin{aligned} \text{So } \int_{\gamma} \vec{F} \cdot d\vec{r} &= \int_0^1 (s^4, 2s^3, -1) \cdot (1, 2s, 0) dt \\ &= \int_0^1 s^4 + 4s^4 + 0 dt = \int_0^1 5s^4 dt \\ &= 1 \end{aligned}$$

You may see differential form version that looks like

$$\int_{\gamma} M dx + N dy + P dz$$

which is just done in the following manner.

Ex: Calculate $\int_{\gamma} x dx + y dy + z dz$

along the curve $\gamma(t) = (t, t^2, t^3)$ from $t=0$ to $t=1$.

$$x = t \quad dx = dt$$

$$y = t^2 \quad dy = 2t dt$$

$$z = t^3 \quad dz = 3t^2 dt$$

so --

$$I = \int_0^1 t dt + (t^2)(2t) dt + (t^3)(3t^2) dt$$

$$= \int_0^1 (t + 2t^3 + 3t^5) dt = \frac{1}{2} + \frac{2}{3} + \frac{3}{6} \\ = 3 + 4 + 3/6 = 10/6 = 5/3$$

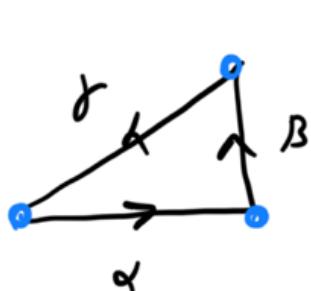
Def: if $\gamma(t)$ is a smooth curve and \vec{F} is a velocity field, e.g. velocity of water, then the flow of \vec{F} along γ is given by

$$\text{Flow} = \int_{\gamma} \vec{F} \cdot d\vec{r}$$

this is called a flow integral. If γ starts and ends at the same point, then we call the integral the circulation. Denoted \oint or \oint depending on orientation.

ex: let $\vec{F}(x,y) = (x+y)\hat{i} + (x-y)\hat{j}$ and

let γ be the triangle with vertices at $(0,0)$, $(1,0)$ and $(1,1)$. Write out integrals to calculate the circulation if path is traversed counter clockwise.



$$\begin{aligned}\alpha &= (\alpha, 0) \\ \beta &= (1, \alpha) \\ \gamma &= (1-\alpha, 1-\alpha)\end{aligned}$$

$$\alpha: d\vec{r} = (1,0)d\alpha \quad \vec{F} \cdot d\vec{r} = (\alpha, \alpha) \cdot (1,0) d\alpha$$

$$\beta: d\vec{r} = (0,1)d\alpha \quad \vec{F} \cdot d\vec{r} = (1+\alpha, 1-\alpha) \cdot (0,1) d\alpha$$

$$\gamma: d\vec{r} = (-1, -1)d\alpha \quad \vec{F} \cdot d\vec{r} = (2-2\alpha, 0) \cdot (-1, -1)d\alpha$$

$$\text{So } \int_{\alpha} \vec{F} \cdot d\vec{r} = \int_0^1 \alpha d\alpha = \frac{1}{2}$$

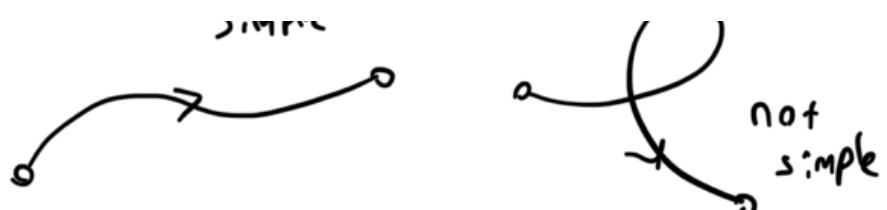
$$\int_{\beta} \vec{F} \cdot d\vec{r} = \int_0^1 1-\alpha d\alpha = \frac{1}{2} \quad \text{So } \oint_C \vec{F} \cdot d\vec{r} = \frac{1}{2} + \frac{1}{2} - 1 = 0$$

$$\int_{\gamma} \vec{F} \cdot d\vec{r} = \int_0^1 (2-2\alpha) d\alpha = -1$$

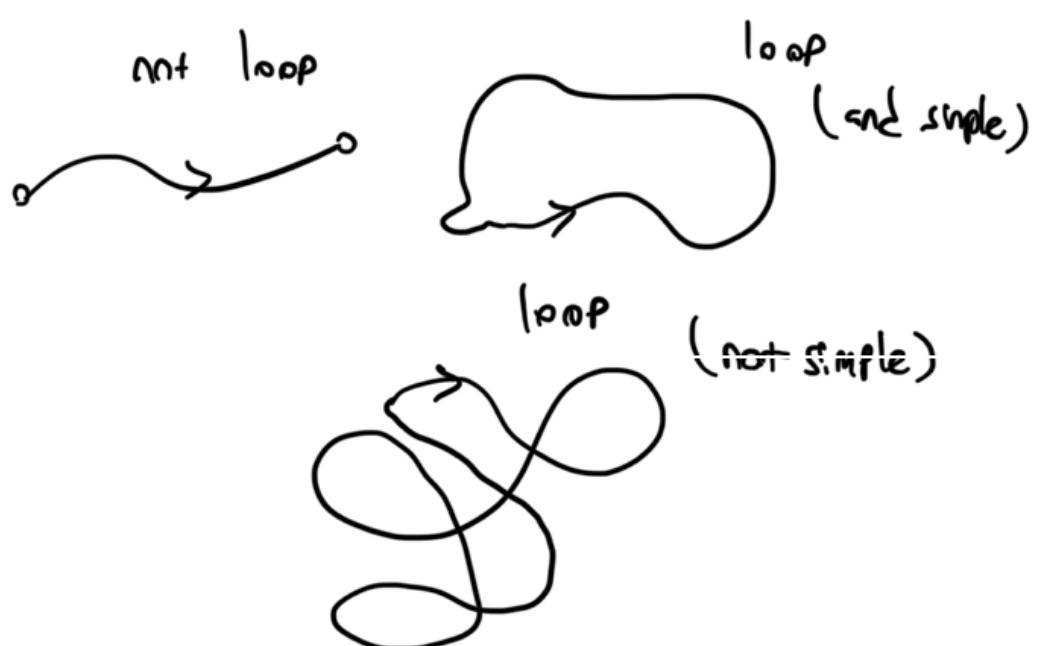
Flux integrals.

A curve in \mathbb{R}^2 is called simple if it does

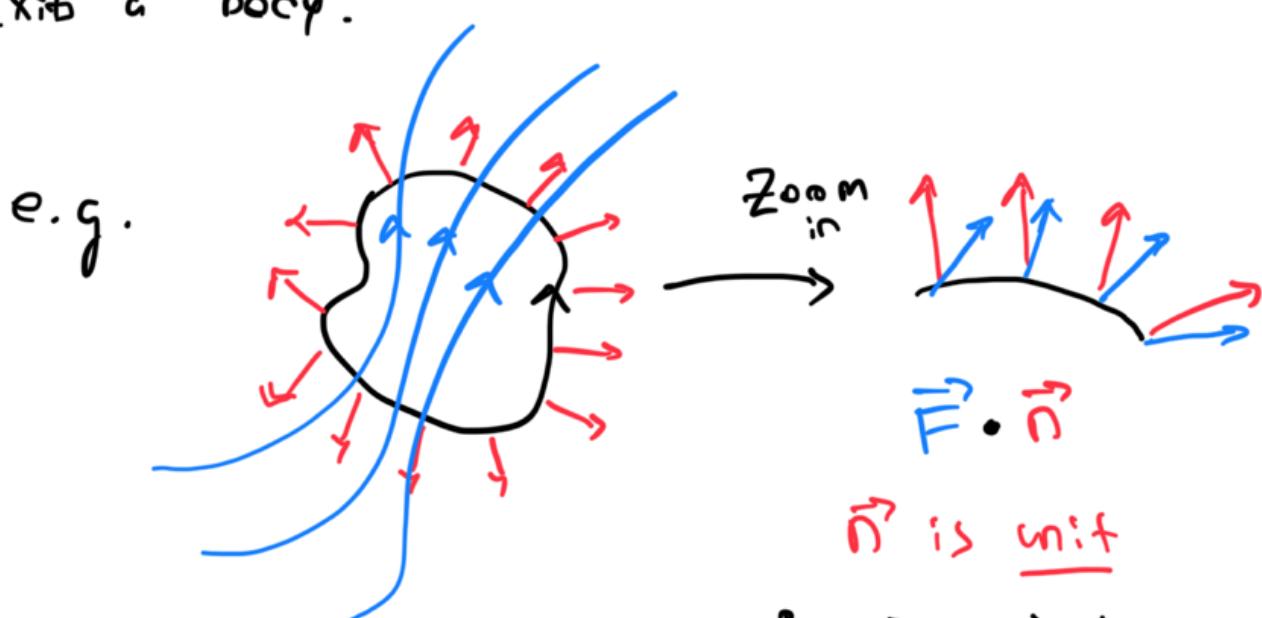
not cross itself.



A curve is called a loop if it starts and ends at the same point.



Sometimes interested in calculating how much enters a body and exits a body.



Want to add all $\vec{F} \cdot \vec{n}$

along boundary so get

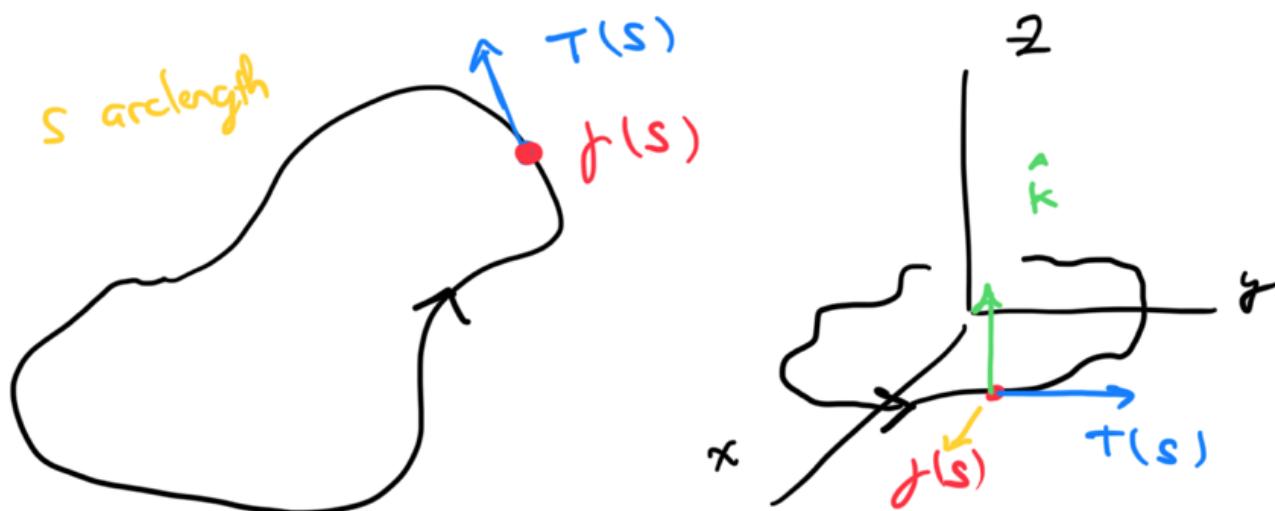
$$\text{proj}_{\vec{u}} \vec{v} = \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\|^2} \vec{u}$$

Def: let C be simple closed curve in the plane and consider vector field \vec{F} . We define the flux of \vec{F} across C to be

$$\text{Flux of } \vec{F} \text{ across } C = \int_C \vec{F} \cdot \vec{n} ds$$

where \vec{n} is unit outward normal to C .

Question: How to get unit normal?



$T \times \hat{k}$ = outward
if $\gamma(s)$ counterclockwise

In coordinates if $\gamma(s) = (x(s), y(s), 0) + t\hat{k}$

$$\vec{n}(s) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{dx}{ds} & \frac{dy}{ds} & 0 \\ 0 & 0 & 1 \end{vmatrix} = \hat{i} \left(\frac{dy}{ds} \right) - \hat{j} \left(\frac{dx}{ds} \right) + \hat{o} \hat{k}$$

$$T(s) = \left(\frac{dx}{ds}, \frac{dy}{ds}, 0 \right)$$

$$\text{so } \vec{n}(s) = \left(\frac{dy}{ds}, -\frac{dx}{ds}, 0 \right) \text{ then}$$

$$\vec{F}(x, y) \cdot \vec{n}(s) = M(x, y) \frac{dy}{ds} - N(x, y) \frac{dx}{ds}$$

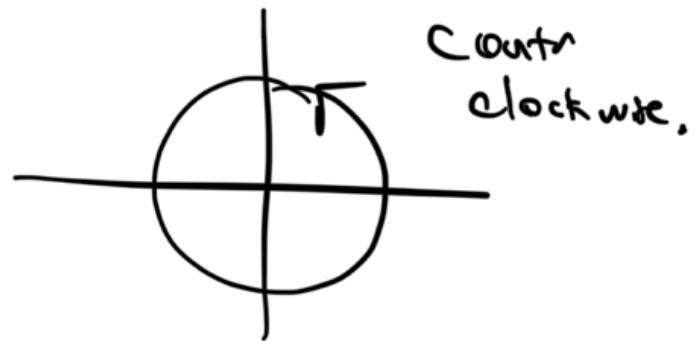
$$\vec{F}(x, y) = (M(x, y), N(x, y))$$

So ...

$$\text{Flux of } \vec{F} = \oint_C M dy - N dx$$

ex : let $\vec{F}(x, y) = (-y, x)$. Evaluate
the flux of \vec{F} across the unit circle.

$$f(x) = (\cos x, \sin x)$$

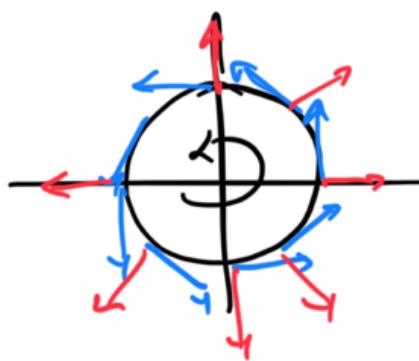


$$\text{so } dx = -\sin x \, dt$$

$$dy = \cos x \, dt \quad \text{and } \vec{F}(\cos x, \sin x) \\ = (-\sin x, \cos x)$$

$$\text{thus } \oint_C \vec{F} \cdot \vec{n} \, ds = \int_0^{2\pi} (-\sin x)(\cos x) \, dt \\ = \int_0^{2\pi} (\cos x)(-\sin x) \, dt = 0$$

why?



nothing entering or exiting.

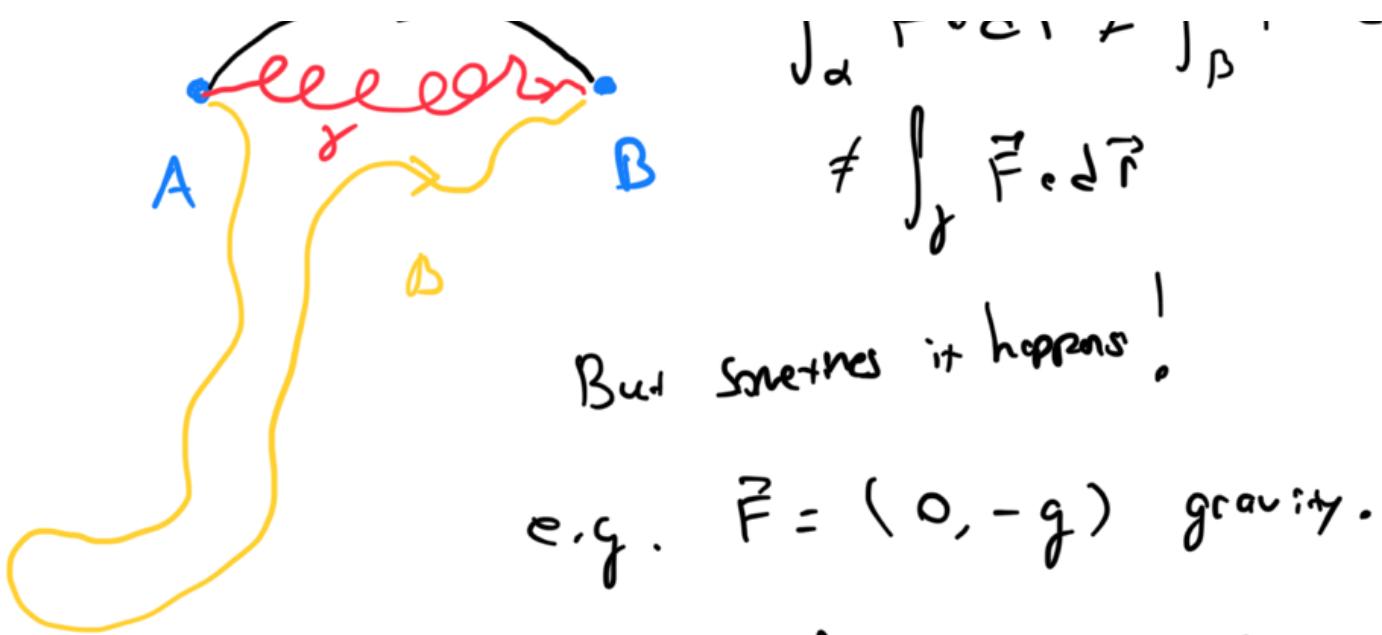
16.3 : Path independent, Conservative Fields,
and Potential Functions

Typically, if integrating vector field along a path,
it depends on which path.

typically



$$\int \vec{E} \cdot d\vec{r} + \int \vec{F} \cdot d\vec{r}$$



$$\int_{\alpha} \vec{F} \cdot d\vec{r} + \int_{\beta}$$

$$= \int_{\gamma} \vec{F} \cdot d\vec{r}$$

But sometimes it happens!

e.g. $\vec{F} = (0, -g)$ gravity.

let γ be any path from $(0, 0)$ to $(0, 1)$.

$$(x(\tau), y(\tau)) = \gamma(\tau) \text{ with } \gamma(0) = A, \gamma(1) = B$$

$$\text{then } d\vec{r} = (dx, dy) = (x'(\tau)d\tau, y'(\tau)d\tau)$$

$$\text{so } W = \int_{\gamma} \vec{F} \cdot d\vec{r} = \int_0^1 -g \frac{dy}{d\tau} d\tau$$

$$= -g(y(1) - y(0)) = -g(0 - 1)$$

$$\approx 10 \text{ Nm}$$

def: let \vec{F} be a vector field such that
for any two points A and B, and any two
paths α, β connecting them we have

$$\int_{\alpha} \vec{F} \cdot d\vec{r} = \int_{\beta} \vec{F} \cdot d\vec{r}$$

We say \vec{F} is a conservative vector field and

$\int_{\alpha} \vec{F} \cdot d\vec{r}$ is path independent.

Why did above example work and how can you
generalize more? Hence a definition and a

Consequence.

Def: if \vec{F} is a vector field such that

$\vec{F} = \nabla f$ for some scalar function f ,
we call f a potential function for \vec{F} .

e.g. gravitational potential, electrical potential.

Why these nice? Because we have

$$\int_C \vec{F} \cdot d\vec{r} = \int_C \nabla f \cdot d\vec{r} = f(B) - f(A)$$

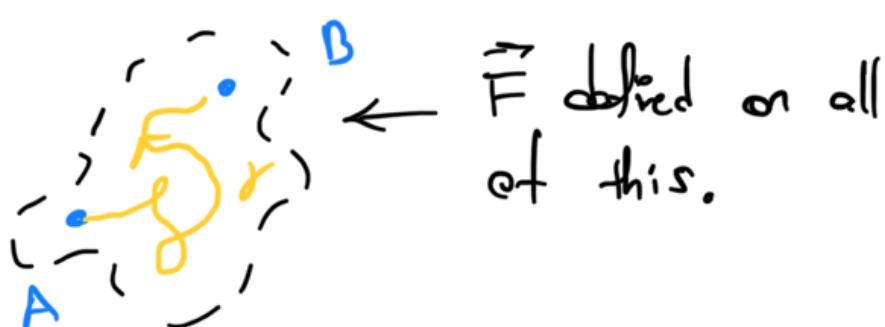
where $\gamma(0) = A$ and $\gamma(1) = B$.

In particular, $\oint_C \vec{F} \cdot d\vec{r} = 0$ for any closed loop γ .

Word of warning: Assumptions are made
on domain of \vec{F} , domain of f , derivatives,
and paths.

- We require \vec{F} to be defined on a
connected region containing path γ .

e.g.



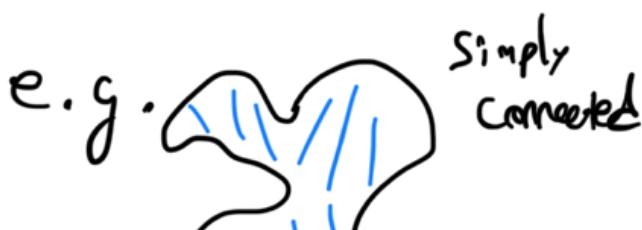
- Same for f

- Want curves to be piecewise smooth

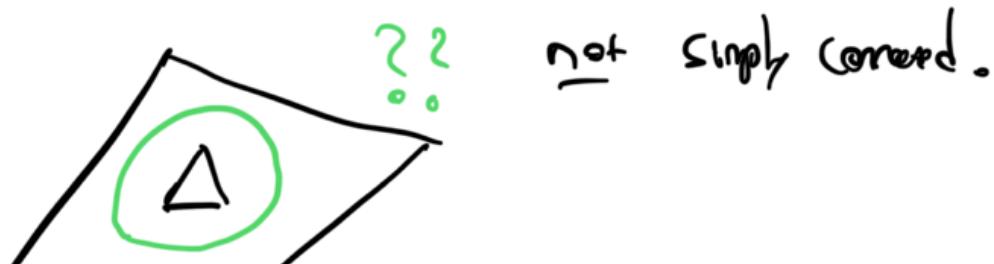
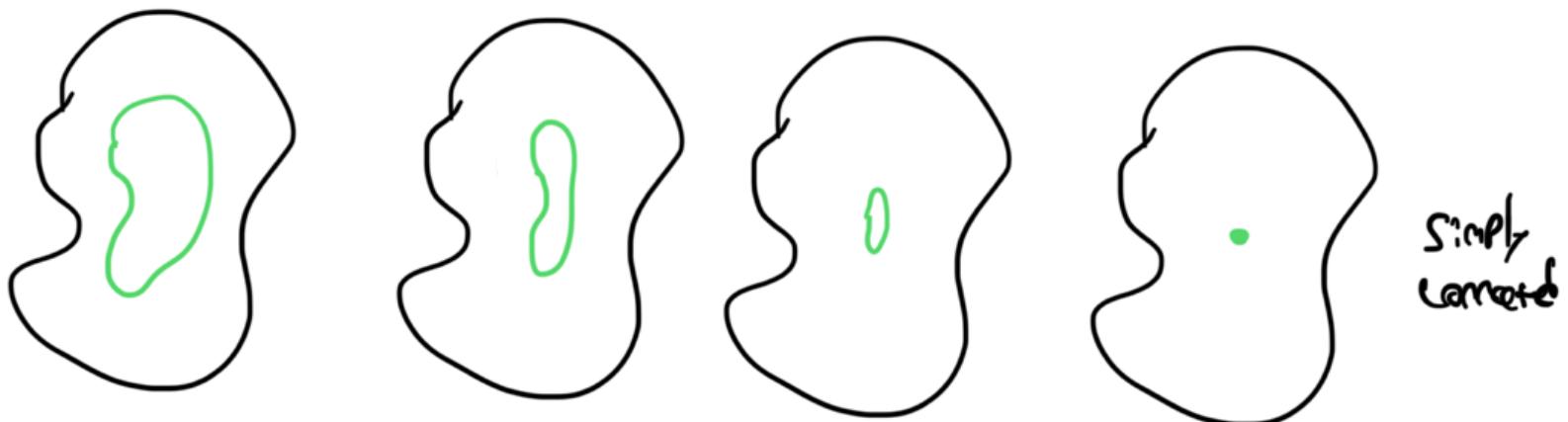
Wario! or

Mario!

- In future theorems we'll need simply connected which is a connected region 'without holes.'

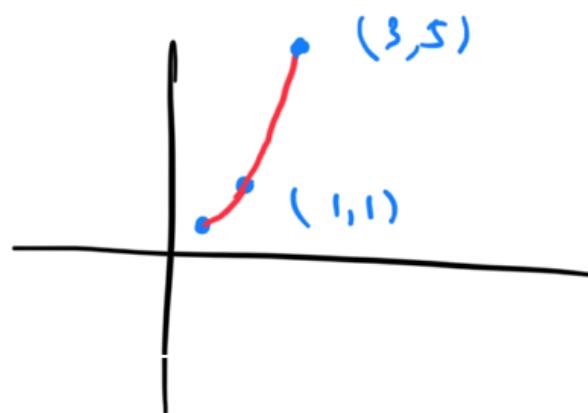


Idea is every loop can be shrunk to a point.

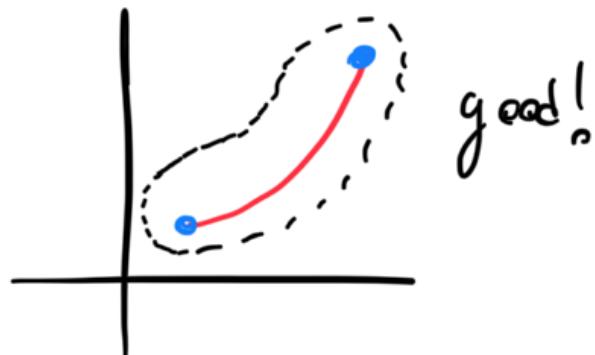


Ex: Integrate $\vec{F} = \left(\frac{2x}{x^2+y^2}, \frac{2y}{x^2+y^2} \right)$

along the parabola connecting the points
 $(1,1), (2,2)$ and $(3,5)$, from $(1,1)$ to $(3,5)$



Notice \vec{F} is 'bad' only at $(0,0)$. We can contain entire parabola in a region that avoids $(0,0)$.



May apply theorem. Now $f(x,y) = \ln(x^2+y^2)$

then $\nabla f = \left(\frac{2x}{x^2+y^2}, \frac{2y}{x^2+y^2} \right)$ so

$$\begin{aligned} \int_C \nabla f \cdot d\vec{r} &= f(B) - f(A) = \ln(3^2+5^2) \\ &\quad - \ln(1^2+1^2) \\ &= \ln(34) - \ln(2) \\ &= \ln(17) \end{aligned}$$

We saw that if \vec{F} comes from a potential function i.e. $\vec{F} \leftrightarrow$ a gradient field means path integrals are independent of path and only depend on endpoints. Under mild assumptions on domain the converse is true.

Theorem: Let \vec{F} be a vector field where component functions are continuous on an open connected region D . Then \vec{F} is conservative iff \vec{F} is a gradient field. (i.e. can solve $\vec{F} = \nabla f$ for some function f).

Corollary: $\oint_C \vec{F} \cdot d\vec{r} = 0$ for all loops in domain D iff \vec{F} is conservative on D .

Summarize as ... let D be open domain and \vec{F} be 'nice'.

$\vec{F} = \nabla f$ on D iff \vec{F} conservative on D iff $\oint_C \vec{F} \cdot d\vec{r} = 0$ for all loops in D

Two obvious questions:

1. How do you test if a vector field is conservative?

2. How do you find a potential function if \vec{F} is conservative?

Theorem: Let $\vec{F} = (M, N, P)$ all M, N, P functions of x, y, z , on simply connected domain D.

Assume nice differentiability. Then \vec{F} conservative

$$\text{iff } \nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & P \end{vmatrix} = \text{curl of } \vec{F}$$

$$= \left(\frac{\partial P}{\partial y} - \frac{\partial N}{\partial z} \right) \hat{i} - \left(\frac{\partial P}{\partial x} - \frac{\partial M}{\partial z} \right) \hat{j} + \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \hat{k} = \vec{0}$$

(should mention in 2D some deal sort of)

$\vec{F} = (M, N)$ then on simply connected domain \vec{F} conservative iff $\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} = 0$

(Just like we did before!)

ex: Determine if

$$\vec{F} = \left(\cos(y) e^{yz^2}, e^{xz^2} \cos(y) + \ln(z) - e^{xz^2} \sin(y), \right. \\ \left. 1 + \frac{y}{z} + 2e^{yz^2} xy z \cos(y) \right) \text{ is conservative}$$

on $\mathbb{Z} \geq 0$. Now \vec{F} defined everywhere on $\mathbb{Z} > 0$ simply connected, so curl test will suffice.

You can do these calculations and find out that

$$\nabla \times \vec{F} = \vec{0} \text{ so by the theorem it's conservative.}$$

Want potential function? Options.

$$1. \cos(y) e^{yz^2} \text{ wrt to } x \quad \leftarrow \text{ easiest.}$$

$$2. e^{yz^2} x z^2 \cos(y) + \ln(z) - e^{yz^2} x \sin(y) \text{ wrt to } y$$

$$3. 1 + \frac{y}{z} + 2e^{yz^2} x y z \cos(y) \text{ wrt to } z$$

$$f(x, y, z) = x \cos(y) e^{yz^2} + h(y, z).$$

$$\begin{aligned} \frac{\partial f}{\partial y} &= (-x \sin(y) + x \cos(y) z^2) e^{yz^2} + \frac{\partial h}{\partial y} \\ &= -x \sin(y) e^{yz^2} + x \cos(y) z^2 e^{yz^2} + h_y \\ &= -x \sin(y) e^{yz^2} + x z^2 \cos(y) e^{yz^2} + \ln(z) \end{aligned}$$

$$\text{so } \frac{\partial h}{\partial y} = \ln(z) \text{ so } h(y, z) = y \ln(z) + j(z).$$

$$\begin{aligned} \frac{\partial f}{\partial z} &= x \cos(y) e^{yz^2} \cdot 2yz + \frac{y}{z} + j'(z) \\ &= 1 + \frac{y}{z} + 2e^{yz^2} x y z \cos(y) \\ \text{so } j'(z) &= 1 \Rightarrow j(z) = z + C \end{aligned}$$

thus potential function is

$$1. \cos(y) e^{yz^2} x + y \ln(z) + z + C \text{ for}$$

$$f(x, y, z) = x \cos(y) + y^{\ln(z)} + C$$

const C .

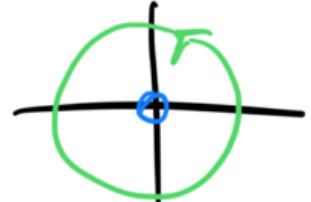
Simply connected hypothesis is necessary

$$\text{ex: } \vec{F}(x, y) = \left(-\frac{y}{x^2+y^2}, \frac{x}{x^2+y^2} \right)$$

M N

then $\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} = 0$ (can check). $f(x)$

However domain not simply connected.



Moreover if $\int_{\gamma} \vec{F} \cdot d\vec{r}$ with γ unit circle,

get $d\vec{r} = (-\sin(\theta), \cos(\theta)) d\theta$ and

$$(\vec{F} \circ r)(\theta) = \left(\frac{-\sin \theta}{\cos^2 \theta + \sin^2 \theta}, \frac{\cos \theta}{\cos^2 \theta + \sin^2 \theta} \right)$$

so $\vec{F} \cdot d\vec{r} = 1 d\theta$ and

$$\int_{\gamma} \vec{F} \cdot d\vec{r} = \int_0^{2\pi} 1 d\theta = 2\pi \text{ so}$$

not conservative.

No potential function exists!

Differential forms

Recall we had integrals of the form

$\int \dots \int \dots (2D) \text{ and}$

$$\int M dx + N dy$$

$$\int M dx + N dy + P dz \quad (3D)$$

Quantities $M dx + N dy$ or $M dx + N dy + P dz$
are called differential forms (more specifically they
are called 1-forms) You can integrate them
over curves like we've been doing.

A particularly nice type of differential form is
an exact differential form.

An exact differential form $\omega = M dx + N dy + P dz$
is one where you can find a function f so that
 $\omega = df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz$ so
 $M = \frac{\partial f}{\partial x} \quad N = \frac{\partial f}{\partial y} \quad P = \frac{\partial f}{\partial z}$

It's nice because we have for any path γ ,

$$\begin{aligned}\int_{\gamma} \omega &= \int_{\gamma} M dx + N dy + P dz = \int_{\gamma} df \\ &= \int_{\gamma} \nabla f \cdot d\vec{r} = f(B) - f(A) \quad \text{where } A \\ &\quad \text{is starting point of } \gamma \text{ and } B \text{ is the end.}\end{aligned}$$

To test if a diff form

$$\omega = M dx + N dy + P dz \text{ is exact}$$

on a simply connected domain we use the

Score test as before,

Theorem: $\omega = M dx + N dy + P dz$ is exact on

a simply connected domain if

$$\frac{\partial P}{\partial y} = \frac{\partial N}{\partial z} \quad \frac{\partial M}{\partial z} = \frac{\partial P}{\partial x} \quad \frac{\partial N}{\partial x} = \frac{\partial M}{\partial y}$$

(in 2D) $\omega = M dx + N dy$
need $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$)

Ex: Show $\omega = (2x+y) dx + x dy + 2z dz$ is exact and then find a function f so that $df = \omega$.

1. Exactness just calculate and note domain is all of \mathbb{R}^3 .

2. $\frac{\partial f}{\partial x} = 2x+y \quad \frac{\partial f}{\partial y} = x \quad \frac{\partial f}{\partial z} = 2z$
 \uparrow
why not

$$f(x, y, z) = xy + g(x, z)$$

$$\frac{\partial f}{\partial x} = y + \frac{\partial g}{\partial x} = y + 2x \quad \text{so} \quad \frac{\partial g}{\partial x} = 2x$$

$$\text{so } g(x, z) = x^2 + h(z)$$

$$\frac{\partial f}{\partial z} = 0 + 0 + h'(z) = 2z \quad \text{so} \quad h(z) = z^2 + C$$

$$\therefore \omega = x^2 + z^2 + C$$

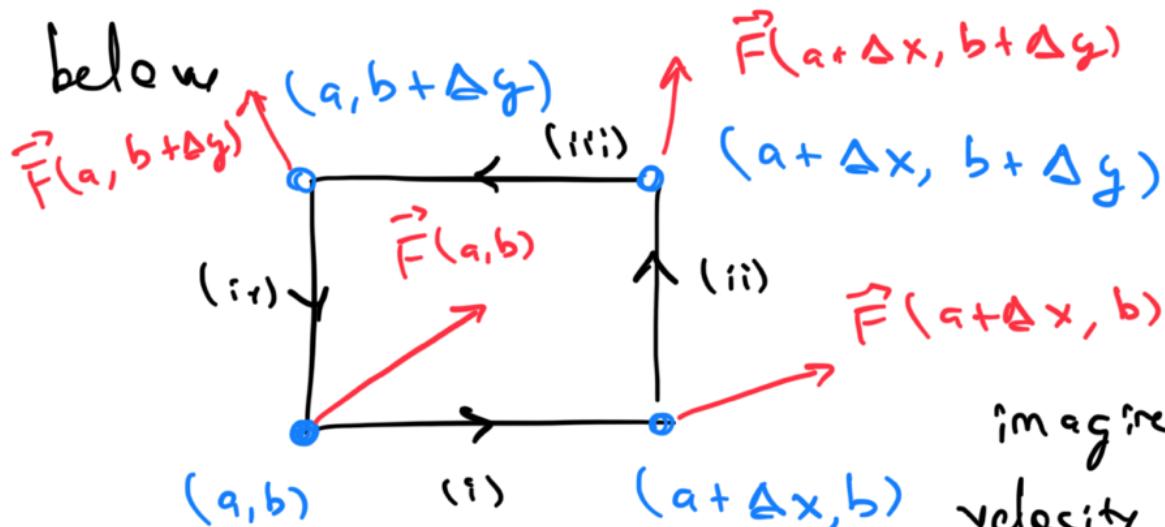
$$\text{So } f(x, y, z) = x + xy + z - 1.$$

If we want $\int_f \omega$ where f goes from $(0,0,0)$ to $(1,1,1)$ then

$$\begin{aligned}\int_f \omega &= f(1,1,1) - f(0,0,0) \\ &= 3\pi\end{aligned}$$

16.4: Green's Theorem in the Plane

Consider a force field $\vec{F} = M(x,y)\hat{i} + N(x,y)\hat{j}$ in the plane. Consider a small rectangle



imagine \vec{F} is a velocity field of a fluid.

Wish to calculate velocity along the rectangle.

$$(i). \vec{F}(a,b) \cdot d\vec{r} = M(a,b) \Delta x$$

$$(ii). \vec{F}(a+\Delta x, b) \cdot d\vec{r} = N(a+\Delta x, b) \Delta y$$

$$(iii). \vec{F}(a, b+\Delta y) \cdot d\vec{r} = M(a, b+\Delta y) (-\Delta x)$$

$$(iv). \vec{F}(a, b) \cdot d\vec{r} = N(a, b) (-\Delta y)$$

$$(i) + (iii)$$

$$= [M(a, b + \Delta y) - M(a, b)] (-\Delta x)$$

$$\approx -\frac{\partial M}{\partial y}(a, b) \Delta x \Delta y$$

$$(ii) + (iv)$$

$$= [N(a + \Delta x, b) - N(a, b)] \Delta y$$

$$\approx \frac{\partial N}{\partial x}(a, b) \Delta x \Delta y$$

$$\text{so } \sum_i (i) = \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right)(a, b) \Delta x \Delta y$$

Circulation around rectangle =

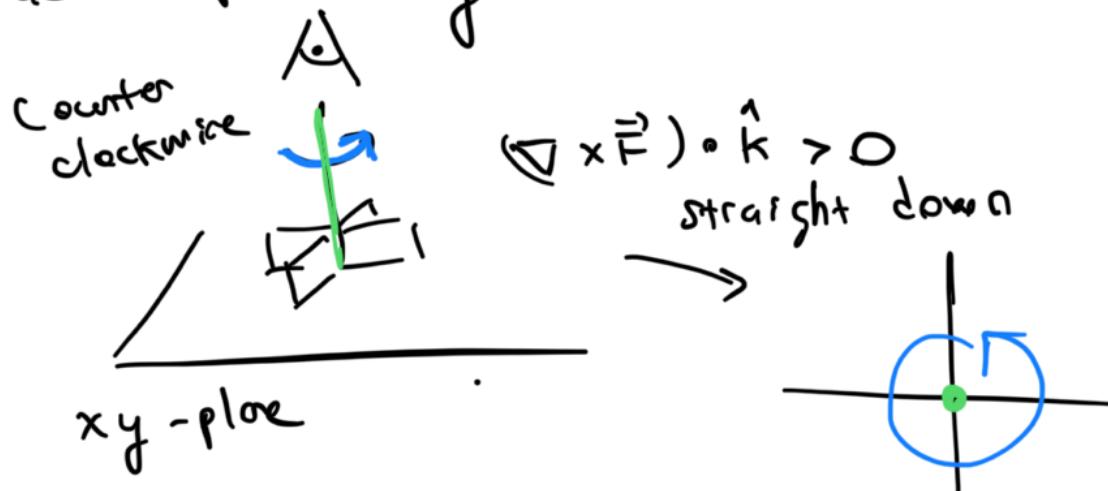
area of rectangle = $\Delta x \times \Delta y$

Call $\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}$ circulation density

$$= (\nabla \times \vec{F}) \cdot \hat{k}, \vec{F} = (M, N, 0)$$

$$\begin{vmatrix} i & j & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & 0 \end{vmatrix}$$

= measurement how fast
a paddle spins subject to \vec{F} .



Ex: Calculate the circulation density of
the below vector fields

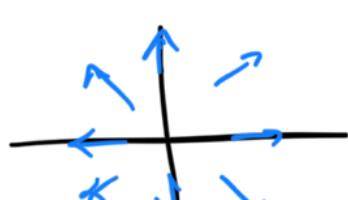
1. $\vec{F} = (x, y)$

2. $\vec{F} = (y, -x)$

3. $\vec{F} = (0, x)$

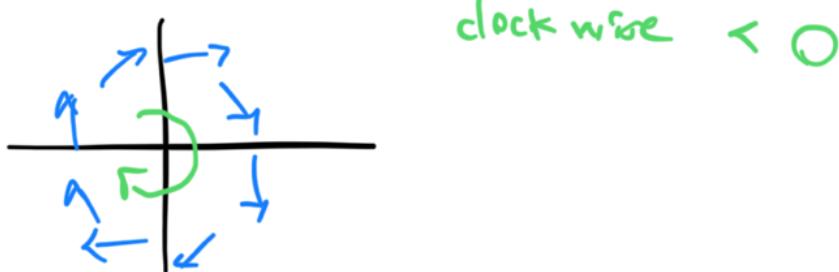
4. $\vec{F} = \left(\frac{-y}{x^2+y^2}, \frac{x}{x^2+y^2} \right)$

1. $(\nabla \times \vec{F}) \cdot \hat{k} = \frac{\partial}{\partial x} y - \frac{\partial}{\partial y} x = 0$

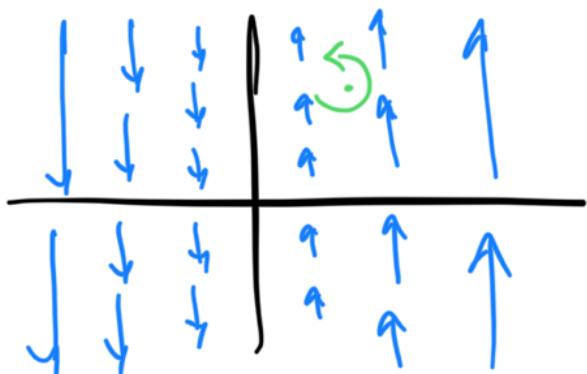


no circulation!

$$2. (\nabla \times \vec{F}) \cdot \hat{k} = \frac{\partial}{\partial x} (-x) - \frac{\partial}{\partial y} (y) = -2 < 0$$

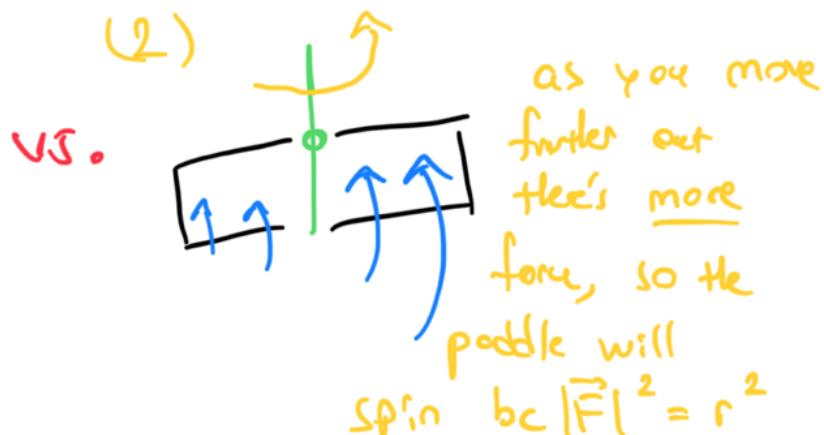


$$3. (\nabla \times \vec{F}) \cdot \hat{k} = \frac{\partial}{\partial x} (x) = 1 > 0$$



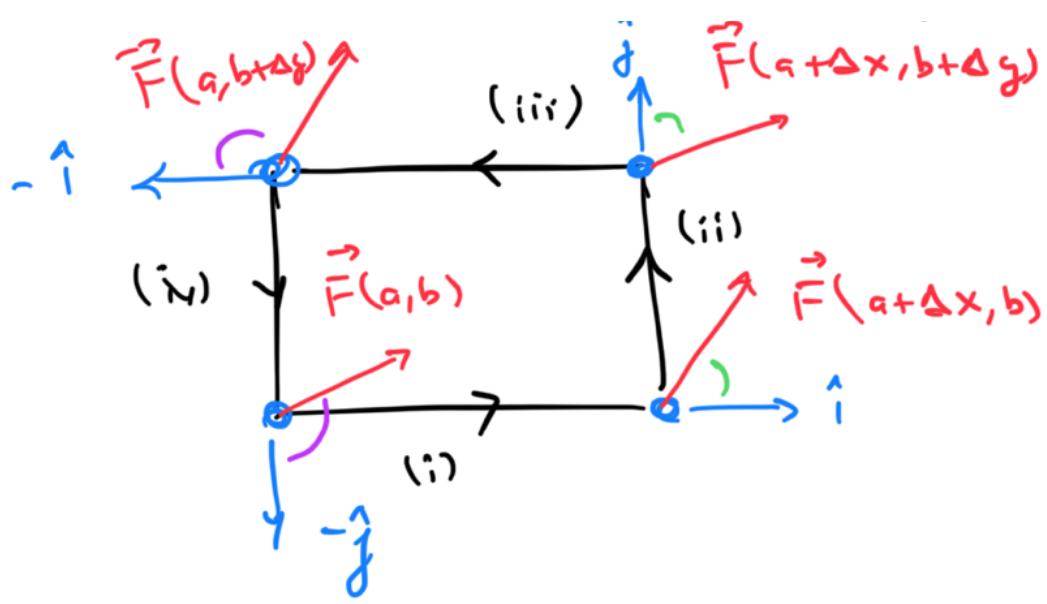
$$4. (\nabla \times \vec{F}) \cdot \hat{k} = \frac{\partial}{\partial x} \left(\frac{x}{x^2+y^2} \right) - \frac{\partial}{\partial y} \left(\frac{-y}{x^2+y^2} \right) = 0 !$$

this is weird, this is just like (2), so what gives? Nor \vec{F} not defined at $(0,0)$, but also, if you put a paddle in water, it'd be like this



Divergence

Again consider $\vec{F} = (M, N)$ now want to measure how much a fluid is leaving a small area.



$$(i). \vec{F}(a, b) \cdot \vec{n} ds = -N(a, b) \Delta x$$

$$(ii). \vec{F}(a + \Delta x, b) \cdot \vec{n} ds = M(a + \Delta x, b) \Delta y$$

$$(iii). \vec{F}(a, b + \Delta y) \cdot \vec{n} ds = N(a, b + \Delta y) (+\Delta x)$$

$$(iv). \vec{F}(a, b) \cdot \vec{n} ds = M(a, b) (-\Delta y)$$

$$(i) + (iii) = (N(a, b + \Delta y) - N(a, b)) \Delta x$$

$$\approx \frac{\partial N}{\partial y} \Delta y \Delta x$$

$$(ii) + (iv) = (M(a + \Delta x, b) - M(a, b)) \Delta y$$

$$\approx \frac{\partial M}{\partial x} \Delta x \Delta y$$

$$\text{so } \sum_i (i) = \left(\frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} \right) \Delta x \Delta y \\ = \text{flux of } \vec{F} \text{ across box}$$

$$\text{so Avg flux across area} \\ = \left(\frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} \right)(a, b) \quad \begin{matrix} \text{flux density} \\ \text{on} \\ \text{divergence} \end{matrix}$$

$$\text{Also denoted by } \nabla \cdot \vec{F} = \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y}$$

measures how much stuff is expanding or contracting at a point.

Ex: Calculate flux of vector fields below.
Explain results with pictures.

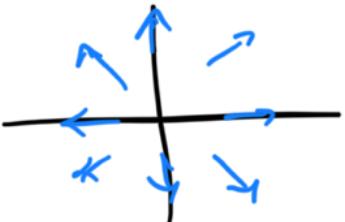
1. $\vec{F} = (x, y)$

2. $\vec{F} = (y, -x)$

3. $\vec{F} = (0, x)$

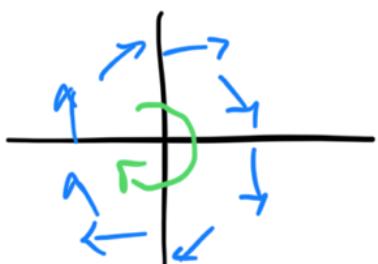
4. $\vec{F} = \left(\frac{-y}{x^2+y^2}, \frac{x}{x^2+y^2} \right)$

1.



We expect $\nabla \cdot \vec{F} > 0$. In fact,
 $\nabla \cdot \vec{F} = \frac{\partial}{\partial x}(x) + \frac{\partial}{\partial y}(y) = 2 > 0$.

2.

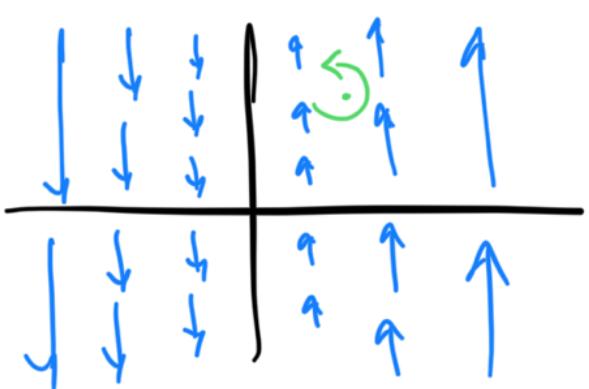


expect $\nabla \cdot \vec{F} = 0$.

$$\frac{\partial}{\partial x}(-y) + \frac{\partial}{\partial y}(x) = 0.$$

Just rotating.

3.



$$\frac{\partial}{\partial x}(0) + \frac{\partial}{\partial y}(x) = 0$$

only expanding in a
single direction. kinda like
how the area of a line is 0.

4. Similar to 2. No expansion/contraction.

Calculation on your own.

Green's Theorem

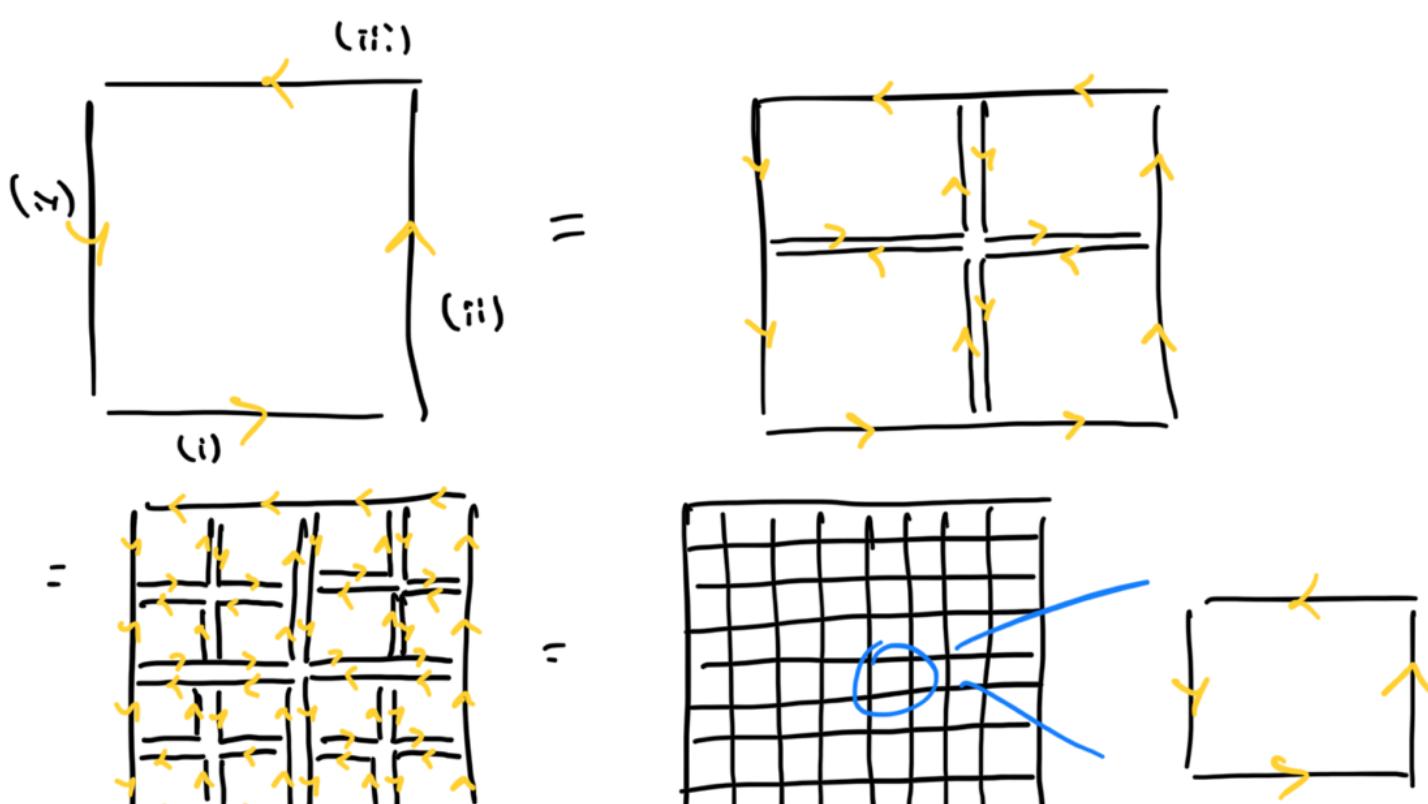
Let γ be a simple closed curve positively oriented (counter clockwise). Let $\vec{F} = M\hat{i} + N\hat{j}$ and \vec{T} and \vec{n} direct unit tangent / outward unit normal to γ . Let R denote inside of γ . Then

$$\begin{aligned}\oint_{\gamma} \vec{F} \cdot \vec{T} ds &= \oint_{\gamma} M dx + N dy = \iint_R (\nabla \times \vec{F}) dA \\ &= \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA \quad \text{version 1}\end{aligned}$$

Also ..

$$\begin{aligned}\oint_{\gamma} \vec{F} \cdot \vec{n} ds &= \oint_{\gamma} M dy - N dx = \iint_R (\nabla \cdot \vec{F}) dA \\ &= \iint_R \left(\frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} \right) dA \quad \text{version 2}\end{aligned}$$

Why $\oint_{\gamma} \vec{F} \cdot \vec{T} ds = \iint_R (\nabla \times \vec{F}) dA$?



$$\text{So } (\text{:}) + (\text{:}) + (\text{:}) + (\text{:}) = \sum \text{ circulation of all squares}$$

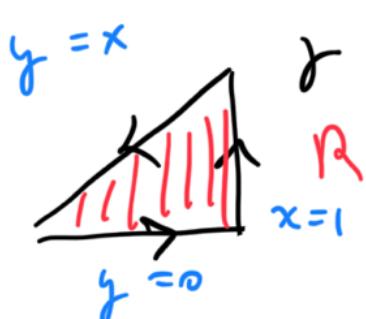
$$= \sum \frac{\text{circulation of } \square}{\text{area of } \square} \cdot \boxed{\text{area}} \rightarrow 0$$

$$\int_{\gamma} \vec{F} \cdot \vec{T} ds \rightarrow \iint_R \nabla \times \vec{F} dA$$

How you get Version 2 from Version 1 is a simple trick. Think about it! (Hint: choose the appropriate vector field)

$$\text{ex: Evaluate } \int_{\gamma} xy dx + \frac{1}{2}(x^2+y^2) dy$$

where γ is the triangle counterclockwise with vertices at $(0,0), (1,0), (1,1)$.



$$\begin{aligned} & xy dx + \frac{1}{2}(x^2+y^2) dy \\ &= (xy, \frac{1}{2}(x^2+y^2)) \cdot d\vec{r} \\ &\vec{F} = (xy, \frac{1}{2}(x^2+y^2)) \\ &= (M, N) \end{aligned}$$

so by Green's theorem...

$$I = \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA = \iint_R (x - x) dA = 0$$

(However, this is no surprise bc

$xy dx + \frac{1}{2}(x^2+y^2) dy$ is not exact diff from a simply connected domain!)

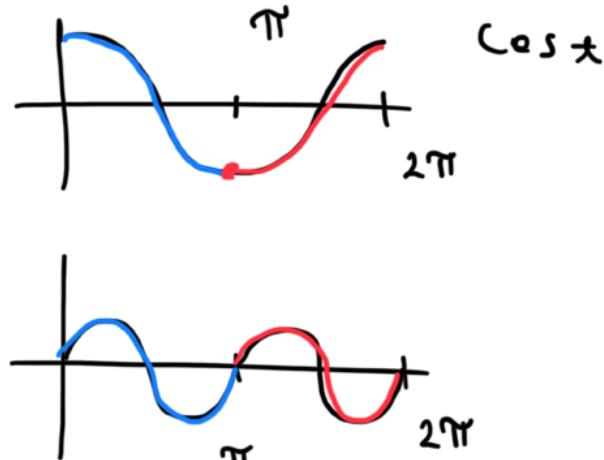
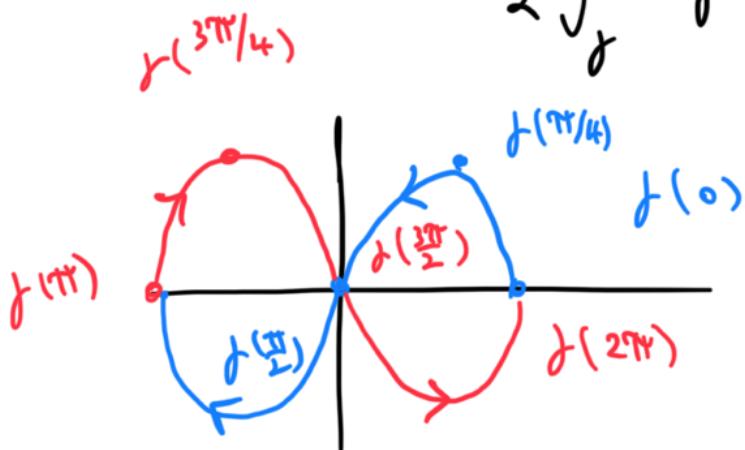
ex: Calculate the area of the region bounded by $x(z) = \cos(z)$, $y = \sin(2z)$ for $0 \leq z \leq 2\pi$.

Trick: Area of R = $\iint_R 1 dA = \iint_R \frac{1}{2} + \frac{1}{2} dA$

$$\frac{\partial N}{\partial x} = \frac{1}{2}, \quad \frac{\partial M}{\partial y} = -\frac{1}{2} \quad \text{so} \quad \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} = 1$$

$M = -y/2$, $N = x/2$ then Green's theorem says

$$\text{Area} = \frac{1}{2} \oint_C -y dx + x dy //$$



$$\text{Area} = 2(\text{left loop}) = 2 \oint_C -y dx + x dy$$

$$\text{Area left loop} = \iint_{\text{left loop}} y dx - x dy$$

$$\begin{aligned} dx &= -\sin(x) dx \\ dy &= 2 \cos(2x) dx \end{aligned}$$

$$\begin{aligned} &\int_{\pi/2}^{3\pi/2} \sin(2x) (-\sin(x)) dx \\ &\quad - \cos(x) (2 \cos(2x)) dx \\ &= 8/3 \end{aligned}$$

$$\text{So total area} = 16/3 //$$

Word of warning: Need \vec{F} to be 'nice' on
intuition of \oint to apply Green's theorem. So

be sure to double check it has derivatives and
stuff on \mathbb{R} .

16.5 : Surfaces and Areas

a curve is a map from $\mathbb{R} \xrightarrow{r} \mathbb{R}^2$ or $\mathbb{R} \xrightarrow{r} \mathbb{R}^3$

The diagram shows two separate curves. The top curve is a wavy line in a 2D plane, labeled \mathbb{R}^2 . The bottom curve is a more complex, looped line in a 3D space, labeled \mathbb{R}^3 . Both curves have arrows indicating their direction.

one-dimensional

a surface is a map from $\mathbb{R}^2 \xrightarrow{r} \mathbb{R}^3$

The diagram shows a 2D parameter plane with axes labeled u and v . A grid of red and blue lines represents curves in the u - v plane. An arrow points from this plane to a 3D surface. The surface is depicted as a wavy, twisted sheet with a grid of red and blue lines representing the image of the curves under the mapping r .

$$\vec{r}(u, v) = f(u, v)\hat{i} + g(u, v)\hat{j} + h(u, v)\hat{k}$$

We don't want our surface to self intersect.

so none of



$$\text{so } \vec{r}(u, v) \neq \vec{r}(u', v') \text{ if } (u, v) \neq (u', v')$$

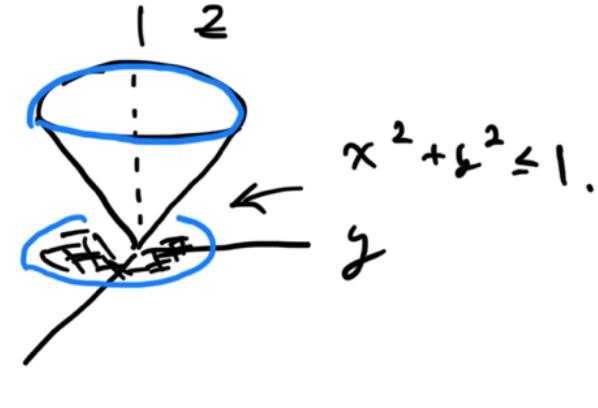
ex: Parameterize the cone

$$x^2 + y^2 = z^2 \text{ where } 0 \leq z \leq 1.$$

$$\therefore \text{solve for } z = \sqrt{x^2 + y^2}$$

One way is

so $\vec{r}(x, y) = (x, y, \sqrt{x^2 + y^2})$ where
 $x^2 + y^2 \leq 1.$



another is $\vec{s}(r, \theta) = (r \cos \theta, r \sin \theta, r)$

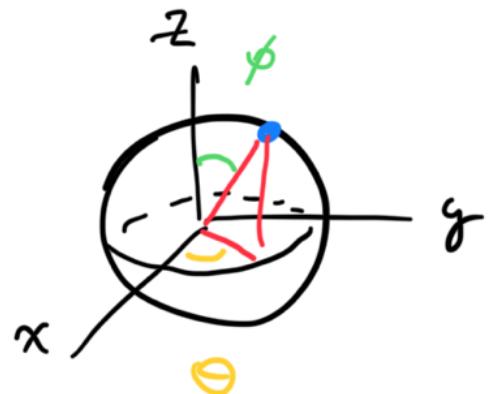
bc $x^2 + y^2 = z^2$ so $r^2 = z^2 \sim r = z$
and $(r \cos \theta, r \sin \theta)$ gives you circle.

ex: Parameterize the sphere $x^2 + y^2 + z^2 = a^2$
where $a > 0$. (spherical co-ordinates
give this to us). $p = a$

$$\text{Recall } x = p \sin \phi \cos \theta$$

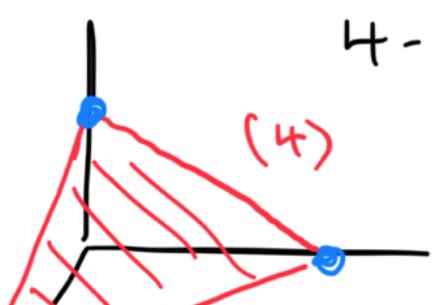
$$y = p \sin \phi \sin \theta$$

$$z = p \cos \phi$$

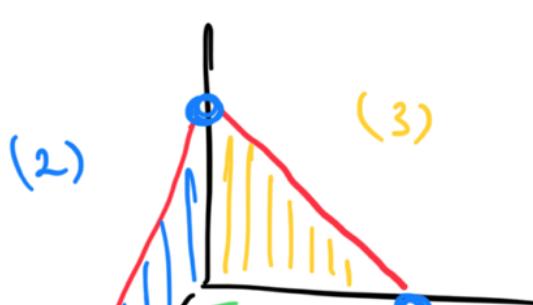


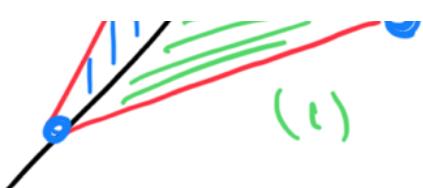
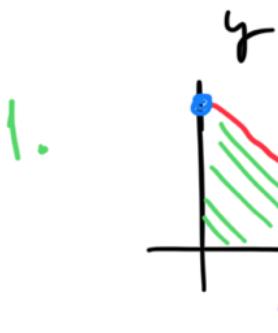
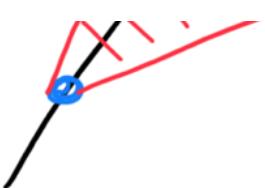
so $\vec{r}(\theta, \phi) = (a \sin \phi \cos \theta, a \sin \phi \sin \theta, a \cos \phi)$
where $0 \leq \theta \leq 2\pi$ and $0 \leq \phi \leq \pi$.

ex: Parameterize tetrahedron with vertices at
(0,0,0), (1,0,0), (0,1,0), (0,0,1).



4-pieces.



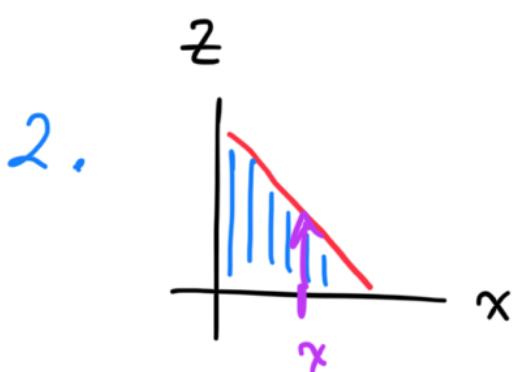


$$\vec{r}(u, v) = (u, v(g))$$

$$0 \leq u \leq 1 \quad = (u, v(1-u))$$

$$0 \leq v \leq 1$$

$$\vec{r}(u, v) = (u, v(1-u), 0) \text{ in } \mathbb{R}^3$$



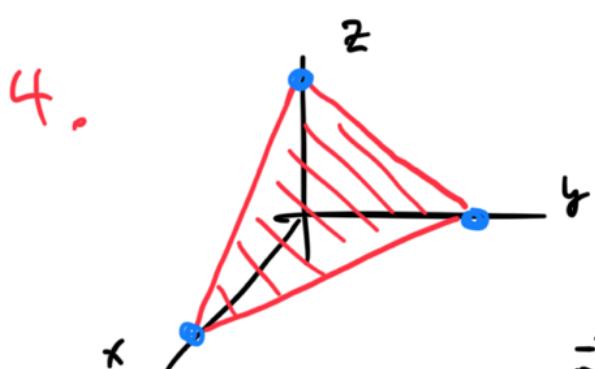
$$\vec{r}(u, v) = (u, vz)$$

$$= (u, v(1-u))$$

$$\vec{r}(u, v) = (u, 0, v(1-u))$$



$$\vec{r}(u, v) = (0, u, v(1-u))$$



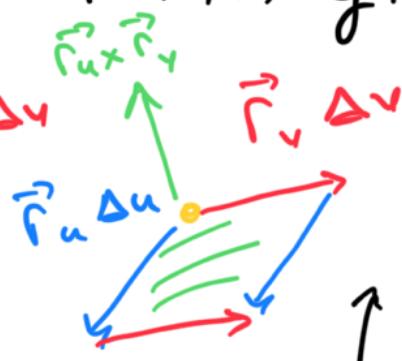
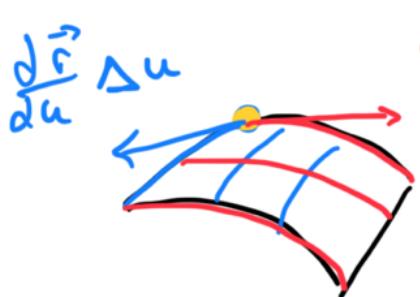
Just use (1) then add z .

$$x+y+z=1 \text{ so}$$

$$z = 1 - x - y$$

$$\vec{r}(u, v) = (u, v(1-u), 1-u-v(1-u))$$

Surface area: let's say $\vec{r}(u, v)$ gives a surface.



$$\text{area} = |\vec{r}_u \times \vec{r}_v| \Delta u \Delta v$$

outward pointing
normal.

add all these,

so get $\text{Area} = \iint |\vec{r}_u \times \vec{r}_v| dA$

Ex: A sphere $x^2 + y^2 + z^2 = a^2$

$$\text{then } \vec{r}(\theta, \phi) = (a \sin \phi \cos \theta, a \sin \phi \sin \theta, a \cos \phi)$$

$$\text{so } \frac{d\vec{r}}{d\theta} = (-a \sin \phi \sin \theta, a \sin \phi \cos \theta, 0)$$

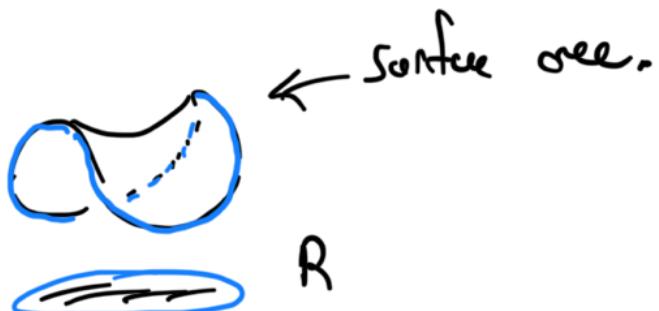
$$\frac{d\vec{r}}{d\phi} = (a \cos \phi \cos \theta, a \cos \phi \sin \theta, -a \sin \phi)$$

$$\text{so } \vec{r}_\theta \times \vec{r}_\phi = (-a^2 \cos \theta \sin^2 \phi, -a^2 \sin^2 \phi \sin \theta, -a^2 \cos \phi \sin \phi)$$

$$\text{so } |\vec{r}_\theta \times \vec{r}_\phi| = a^2 |\sin \phi| \text{ thus,}$$

$$\begin{aligned} \text{Area} &= \iint_R a^2 |\sin \phi| dA = \int_{\theta=0}^{\theta=2\pi} \int_{\phi=0}^{\phi=\pi} a^2 \sin \phi d\phi d\theta \\ &= 4\pi a^2 \end{aligned}$$

Ex: Calculate the surface area of the surface $z = x^2 - y^2$ defined on $x^2 + y^2 \leq 1$



$$\vec{s}(r, \theta) = (r \cos \theta, r \sin \theta, (r \cos \theta)^2 - (r \sin \theta)^2)$$

$$\text{so } \frac{d\vec{s}}{dr} = (\cos \theta, \sin \theta, 2r \cos(2\theta))$$

$$\frac{d\vec{s}}{d\theta} = (-r \sin \theta, r \cos \theta, -4r^2 \cos \theta \sin \theta)$$

$$\vec{s}_r \times \vec{s}_\theta = (-2r^2 \cos \theta, 2r^2 \sin \theta, r) \text{ so}$$

$$|\vec{s}_r \times \vec{s}_\theta| = \sqrt{r^2 + 4r^4}$$

$$\iint_R \sqrt{r^2 + 4r^4} dA = \int_{\theta=0}^{\theta=2\pi} \int_{r=0}^{r=1} r \sqrt{1+4r^2} dr d\theta \\ = \frac{\pi}{6} (5\sqrt{5} - 1)$$

Sometimes surfaces are defined implicitly, e.g.

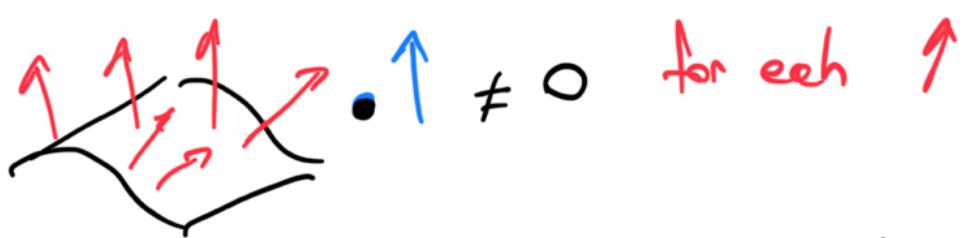
$$F(x, y, z) = c \quad \text{for some constant } c.$$

$$\text{e.g. } x^2 + y^2 - z^3 = 1$$



idea is assume $\nabla \vec{F}(x, y, z) \neq \vec{0}$ and also

$$\nabla \vec{F}(x, y, z) \cdot \hat{k} \neq 0 \text{ with a region.}$$



then one can write $\vec{r}(u, v) = u\hat{i} + v\hat{j} + h(u, v)\hat{k}$

for some function $h(u, v)$. (Implicit function theorem).

$$\text{then } \vec{r}_u = (1, 0, \frac{\partial h}{\partial u}) \quad \text{so } \vec{r}_u \times \vec{r}_v = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 0 & \frac{\partial h}{\partial u} \\ 0 & 1 & \frac{\partial h}{\partial v} \end{vmatrix} \\ \vec{r}_v = (0, 1, \frac{\partial h}{\partial v})$$

$$(-n_u, -n_v, 1)$$

However, $F(x, y, z) = c$ and around small region

$$F(u, v, h(u, v)) = 0 \text{ so}$$

$$\frac{\partial F}{\partial x} \cdot \frac{dx}{du} + \frac{\partial F}{\partial y} \cdot \frac{dy}{du} + \frac{\partial F}{\partial z} \frac{dz}{du} = 0$$

" " " so
" " " $\frac{\partial h}{\partial u}$

$$\frac{dh}{du} = - \frac{\frac{\partial F}{\partial x}}{\frac{\partial F}{\partial z}}. \text{ Similarly,}$$

$$\frac{\partial F}{\partial x} \frac{dx}{dy} + \frac{\partial F}{\partial y} \frac{dy}{dy} + \frac{\partial F}{\partial z} \frac{dz}{dy}$$

" " " so
" " " $\frac{\partial h}{\partial y}$

$$\frac{dh}{dy} = - \frac{\frac{\partial F}{\partial y}}{\frac{\partial F}{\partial z}} \text{ so}$$

$$\begin{aligned} \vec{r}_u \times \vec{r}_v &= (+F_x/F_z, +F_y/F_z, 1) \\ &= \nabla \vec{F} / F_z = \nabla \vec{F} / (\nabla \vec{F} \cdot \hat{z}) \end{aligned}$$

$$\text{So } SA = \iint_R \nabla \vec{F} / (\nabla \vec{F} \cdot \hat{z}) dA \text{ In fact,..}$$

thm: let $F(x, y, z) = c$ over a region R

parallel to xy -plane. Then

$$SA = \iint_R \frac{|\nabla \vec{F}|}{|\nabla \vec{F} \cdot \hat{z}|} dA \text{ provided } \nabla \vec{F} \cdot \hat{z} \neq 0 \text{ on } R.$$

Moreover, we also have

$$SA = \iint_R \frac{|\nabla \vec{F}|}{|\nabla \vec{F} \cdot \hat{x}|} dA \text{ provided } \nabla \vec{F} \cdot \hat{x} \neq 0 \text{ on } R \text{ in } uz\text{-plane}$$

$$SA = \iint_R \frac{|\nabla \vec{F}|}{|\nabla \vec{F} \cdot \hat{z}|} dA \quad \text{provided } \nabla \vec{F} \cdot \hat{z} \neq 0$$

on R in \mathbb{R}^2 -space.

Note in particular, if $z = f(x, y)$ then we have

$$A = \iint_R \sqrt{f_x^2 + f_y^2 + 1} dA$$

$$\text{bc } \nabla \vec{F} = (f_x, f_y, -1)$$

One issue with this is how to evaluate $\nabla \vec{F}$ if you don't know z ! (only works in really nice cases).

ex: Calculate area of cone $x^2 + y^2 = z^2$ bounded by $z \geq 0$ and square centered at $(0,0)$ side length 2.

$$F = x^2 + y^2 - z^2 \text{ so}$$



$$\nabla F = (2x, 2y, -2z)$$

$$\nabla F \cdot \hat{z} = -2z \text{ so}$$

$$|\nabla F| / |\nabla F \cdot \hat{z}| = \sqrt{4x^2 + 4y^2 + 4z^2} / 2z$$

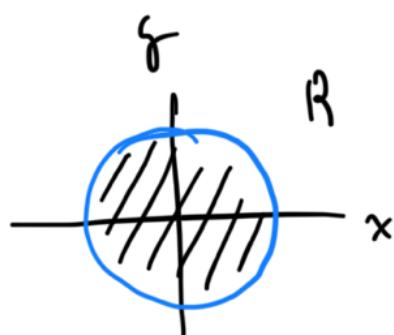
$$= \sqrt{x^2 + y^2 + z^2} \quad z = \sqrt{x^2 + y^2}$$

$$\text{So } = \sqrt{2x^2 + 2y^2} / \sqrt{x^2 + y^2} = \sqrt{2}.$$

$$\text{So } SA = \iint_R \sqrt{2} dA = \sqrt{2} (\text{Area of } R) \\ = 4\sqrt{2}$$

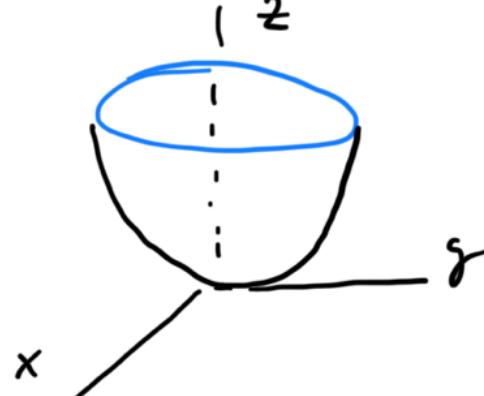
Ex: Calculate surface area of $z = x^2 + y^2$
on region bounded by $0 \leq x^2 + y^2 \leq 1$.

$$SA = \iint_A \sqrt{f_x^2 + f_y^2 + 1} dA$$



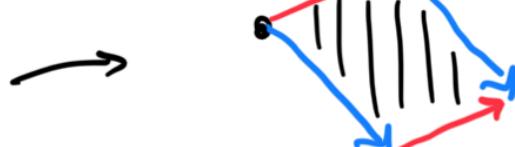
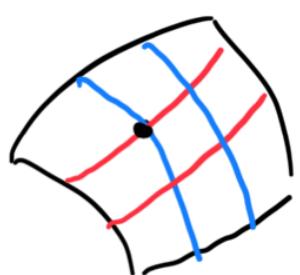
$$\begin{aligned} f_x &= 2x & \sqrt{(2x)^2 + (2y)^2 + 1} dx dy \\ f_y &= 2y & = \sqrt{4(x^2 + y^2) + 1} dx dy \\ & & = \sqrt{4r^2 + 1} r dr d\theta \end{aligned}$$

$$\text{So } SA = \int_{\theta=0}^{\theta=2\pi} \int_{r=0}^{r=1} r \sqrt{4r^2 + 1} dr d\theta = \frac{\pi}{6} (5\sqrt{5} - 1)$$



16.6 : Surface Integrals

Motivated by physical example. Say you have surface S with non-uniform density. How to calculate its mass? Or if you need to integrate x -coordinate to find 1st moment about a plane for surface. Point being we need to integrate functions over surfaces.



Differential area is denoted by $d\sigma$.

If $\vec{r}(u, v)$ parameterizes S then
 $d\sigma = |\vec{r}_u \times \vec{r}_v| du dv$ like in last section.

Ways to integrate scalar function over surface

1. Have a parameterization $\vec{r}(u, v)$, Then

$$\iint_S G d\sigma = \iint_R (G \circ \vec{r})(u, v) |\vec{r}_u \times \vec{r}_v| du dv$$

2. If S is implicitly $F(x, y, z) = c$ and satisfies $\nabla F \cdot \hat{k} \neq 0$ on region R then

$$\iint_S G d\sigma = \iint_R G \frac{|\nabla F|}{|\nabla F \cdot \hat{k}|} dA \quad (\text{similar statement for } \hat{i}, \hat{j})$$

3. If S given explicitly as $Z = f(x, y)$ then

$$\iint_S G \, d\sigma = \iint_R G(x, y, f(x, y)) \sqrt{f_x^2 + f_y^2 + 1} \, dA$$

ex: let S be a cube below. Assume its mass is given by $\rho(x, y, z) = x^2yz$. Calculate its center of mass.

$M_{yz} = 1st$ moment about yz -plane

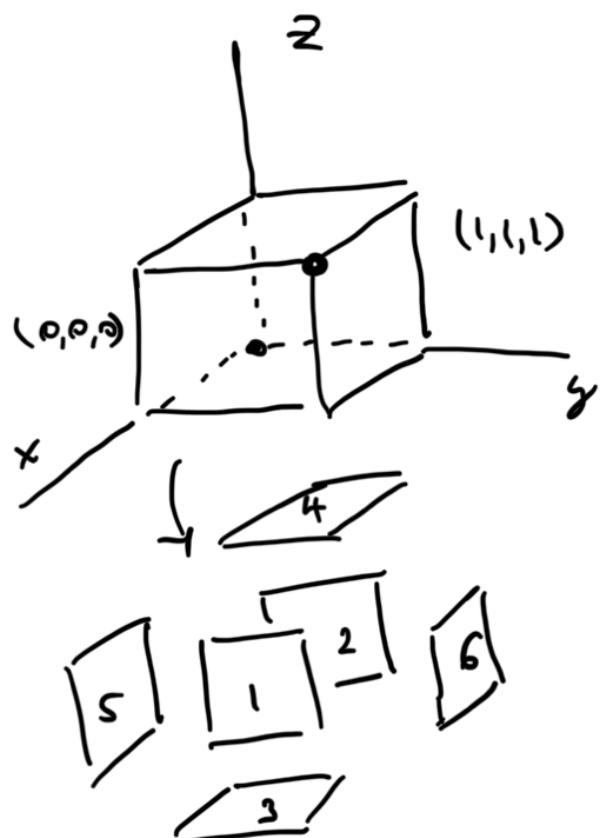
$$= \iint_S xz \, d\sigma$$

$M_{xz} = 1st$ moment about xz -plane

$$= \iint_S yz \, d\sigma$$

$M_{xy} = 1st$ moment about xy -plane

$$= \iint_S z^2 \, d\sigma$$



$$M = \iint_S \rho \, d\sigma = \iint_1 \rho \, d\sigma + \iint_2 \rho \, d\sigma + \dots + \iint_6 \rho \, d\sigma$$

Well 3 of them are zero, namely 5, 3, 2

because on 5, 3, 2, $\rho \equiv 0$ as either x, y , or $z = 0$ on them. So $\rho = x^2yz$

$$M = \iint_1 x^2yz \, d\sigma + \iint_4 x^2yz \, d\sigma + \iint_6 x^2yz \, d\sigma$$

$$\begin{aligned}
 & \iint_S z \, d\sigma = \int_1^4 \int_{y=0}^{z=1} yz \, dz \, dy \\
 & z \text{ on } 1 = 1^2 yz = yz \\
 & z \text{ on } 4 = x^2 y 1 = x^2 y \\
 & z \text{ on } 6 = x^2 1 z = x^2 z \\
 & \iint_S z \, d\sigma = \int_4^6 \int_{x=0}^{y=1} x^2 y \, dy \, dx \\
 & = 1/4 \\
 & \iint_S z \, d\sigma = \int_6^1 \int_{x=0}^{y=1} x^2 z \, dz \, dx \\
 & = 1/6
 \end{aligned}$$

M_{yz} very similar calculation.

$$\begin{aligned}
 M_{yz} &= \iint_S xz \, d\sigma = \iint_1^4 xz \, d\sigma + \iint_4^6 xz \, d\sigma + \iint_6^6 xz \, d\sigma \\
 &= \frac{1}{4} + \frac{1}{8} + \frac{1}{8} = \frac{1}{2} \text{ m kg}
 \end{aligned}$$

$$\begin{aligned}
 M_{xz} &= \iint_S yz \, d\sigma = \iint_1^4 yz \, d\sigma + \iint_4^6 yz \, d\sigma + \iint_6^6 yz \, d\sigma \\
 &= \frac{1}{6} + \frac{1}{9} + \frac{1}{6} = \frac{4}{9} \text{ m kg}
 \end{aligned}$$

$$\begin{aligned}
 M_{xy} &= \iint_S xy \, d\sigma = \iint_1^4 xy \, d\sigma + \iint_4^6 xy \, d\sigma + \iint_6^6 xy \, d\sigma \\
 &= \frac{1}{6} + \frac{1}{9} + \frac{1}{9} = \frac{4}{9} \text{ m kg}
 \end{aligned}$$

$$\text{So } (\bar{x}, \bar{y}, \bar{z}) = \left(\frac{1}{2}, \frac{4}{9}, \frac{4}{9} \right) / (7/12) = \left(\frac{6}{7} \text{ m}, \frac{16}{21} \text{ m}, \frac{16}{21} \text{ m} \right)$$

ex: let S be upper hemisphere of a sphere of radius a

whose density is $\rho(x, y, z) = z$

Calculate the various moments of inertia of S.

$$I_x = \iiint_S (y^2 + z^2) \rho d\sigma \quad I_y = \iiint_S (x^2 + z^2) \rho d\sigma \quad I_z = \iiint_S (x^2 + y^2) \rho d\sigma$$



$$x^2 + y^2 + z^2 = a^2 \quad x \quad y \quad z$$

$$\vec{S}(\phi, \theta) = (a \sin \phi \cos \theta, a \sin \phi \sin \theta, a \cos \phi)$$

where $0 \leq \theta \leq 2\pi, 0 \leq \phi \leq \pi/2$.

$$\frac{\partial \vec{S}}{\partial \phi} = (a \cos \phi \cos \theta, a \cos \phi \sin \theta, -a \sin \phi)$$

$$\frac{\partial \vec{S}}{\partial \theta} = (-a \sin \phi \sin \theta, a \sin \phi \cos \theta, 0)$$

$$\vec{S}_\phi \times \vec{S}_\theta = (a^2 \cos \theta \sin^2 \phi, a^2 \sin^2 \phi \sin \theta, a^2 \cos \phi \sin \phi)$$

$$|\vec{S}_\phi \times \vec{S}_\theta| = a^2 |\sin \phi|$$

$$\text{so } d\sigma = a^2 \sin \phi d\phi d\theta \quad (\text{bc } \sin \phi \geq 0 \text{ for } 0 \leq \phi \leq \pi)$$

$$I_x = \int_{\theta=0}^{\theta=2\pi} \int_{\phi=0}^{\phi=\pi/2} ((a \sin \phi \sin \theta)^2 + (a \cos \phi)^2) (a \cos \phi) (a^2 \sin \phi) d\phi d\theta$$

$$= 3a^5 \pi / 4$$

$$\theta = 2\pi \quad \phi = \pi/2$$

$$I_y = \int_{\theta=0}^{\theta=2\pi} \int_{\phi=0}^{\phi=\pi/2} ((a \sin \phi \cos \theta)^2 + (a \cos \phi)^2) (a \cos \phi) (a^2 \sin \phi) d\phi d\theta$$

$$= 3a^5 \pi / 4$$

$$I_z = \int_{\theta=0}^{\theta=2\pi} \int_{\phi=0}^{\phi=\pi/2} ((a \sin \phi \cos \theta)^2 + (a \sin \phi \sin \theta)^2) (a \cos \phi) (a^2 \sin \phi) d\phi d\theta$$

$$= a^5 \pi / 2 \quad \text{not } I_2 \propto I_x \text{ and } I_y$$

$$\text{and } I_x = I_y$$

I_x resists to



I_y resists to

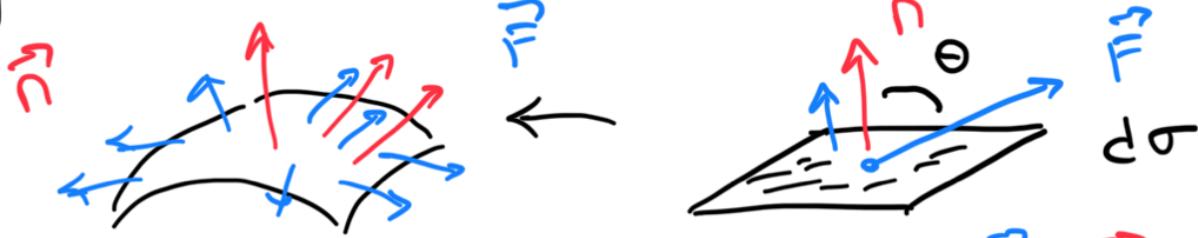


I_z resists to



Flux Integrals

Imagine a velocity vector field over a surface



$$\text{proj}_{\vec{n}} \vec{F} = \vec{F} \cdot \vec{n}$$

How much of \vec{F} goes through $d\sigma$

$$= (\vec{F} \cdot \vec{n}) d\sigma$$

so define

Flux of \vec{F}

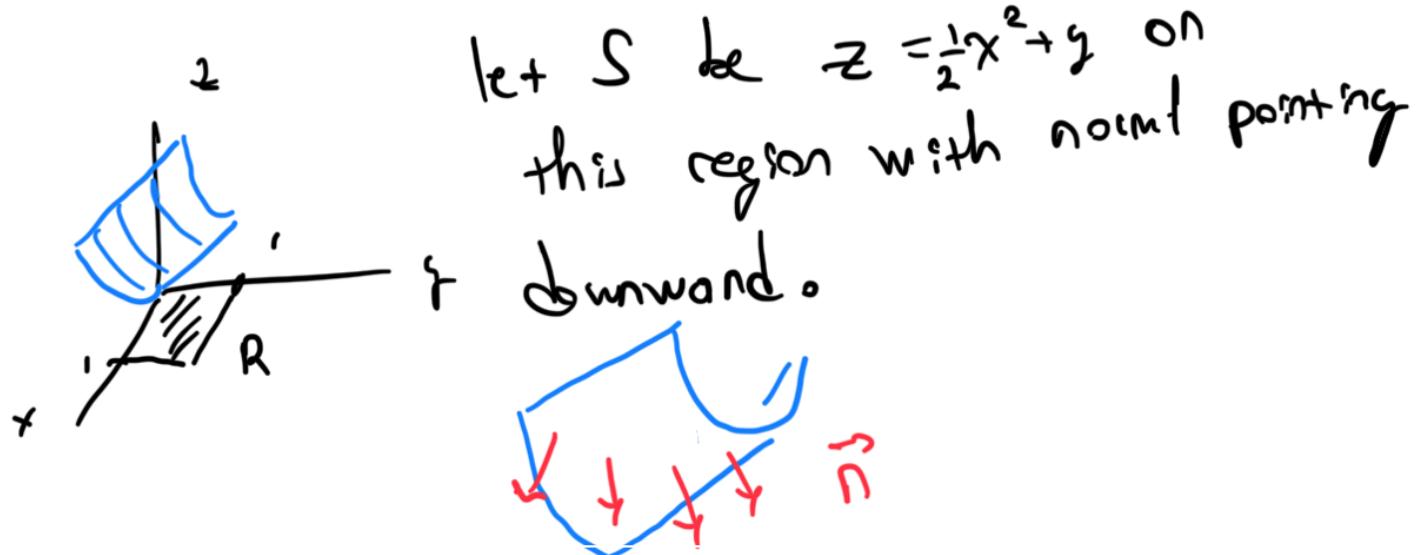
through S in
direction of \vec{n}

$$\iint_S (\vec{F} \cdot \vec{n}) d\sigma$$

(note requires S to be oriented
choice of a normal direction)

Ex: Consider the function $z = -\frac{1}{2}x^2 + y$

defined on the square $0 \leq x, y \leq 1$.



Let $\vec{F} = (y, x, z) = y\hat{i} + x\hat{j} + z\hat{k}$. Calculate flux of \vec{F} over S in direction of \vec{n} .

Let $g(x, y, z) = \frac{1}{2}x^2 + y - z$ so $\nabla g = (x, 1, -1)$
 $|\nabla g| = \sqrt{x^2 + 2}$
 $|\nabla g \cdot \hat{k}| = 1$

so $d\sigma = \sqrt{x^2 + 2} dA$

$$\vec{R} = \frac{\nabla g}{|\nabla g|} = \frac{(x, 1, -1)}{\sqrt{x^2 + 2}} \text{ note } \vec{n} \text{ has negative } z \text{ so it's pointing down.}$$

So $\vec{F} = (y, x, \frac{1}{2}x^2 + y)$ on S

$$\vec{F} \cdot \vec{n} d\sigma = \vec{F} \cdot \frac{\nabla g}{|\nabla g|} \frac{1}{|\nabla g \cdot \hat{k}|} dA$$

$$= \vec{F} \cdot \frac{\nabla g}{|\nabla g \cdot \hat{k}|} dA$$

In general, $\iint_S \vec{F} \cdot \vec{n} d\sigma = \iint_R \frac{\vec{F} \cdot \nabla g}{|\nabla g \cdot \hat{k}|} dA$ (nice to remember)

$$= \int_{x=0}^{x=1} \int_{y=0}^{y=1} (xy + x - \frac{1}{2}x^2 - y) dx dy = 1/12$$

ex: let S be surface $x^2 + y^2 = 4$ between $z=0$ and $z=1$, with normal pointing away from z -axis. Let $\vec{F} = (x+y, x-y, x^2)$. Calculate flux of \vec{F} through S in direction of \vec{n} .

Parameterize S via $\vec{r}(\theta, h) = (2\cos\theta, 2\sin\theta, h)$ where $0 \leq \theta \leq 2\pi$ and $0 \leq h \leq 1$.



Recall $\vec{r}_u \times \vec{r}_v$ normal to surface so $\vec{n} = \frac{\vec{r}_u \times \vec{r}_v}{|\vec{r}_u \times \vec{r}_v|}$ (up to a sign) and

$$d\sigma = |\vec{r}_u \times \vec{r}_v| dA$$

$$\iint_S (\vec{F} \cdot \vec{n}) d\sigma = \iint_R \vec{F} \cdot \frac{\vec{r}_u \times \vec{r}_v}{|\vec{r}_u \times \vec{r}_v|} |\vec{r}_u \times \vec{r}_v| dA$$

another helpful one to know.

$$= \iint_R \vec{F} \cdot (\vec{r}_u \times \vec{r}_v) dA //$$

$$\text{so } \vec{F}(\theta, h) = (2\cos\theta + 2\sin\theta, 2\cos\theta - 2\sin\theta, (2\cos\theta)^2)$$

$$\vec{r}_\theta = (-2\sin\theta, 2\cos\theta, 0) \quad \vec{r}_h = (0, 0, 1)$$

$$\text{so } \vec{r}_\theta \times \vec{r}_h = (2\cos\theta, 2\sin\theta, 0)$$

1 ... the obvious choice anyway!

but that was

$$\text{so } \vec{F} \cdot (\vec{r}_\theta \times \vec{r}_h) = 4 (\cos(2\theta) + \sin(2\theta))$$

$h=1 \quad \theta=2\pi$

$$\text{thus } \iint_S (\vec{F} \cdot \vec{n}) d\sigma = \int_{h=0}^1 \int_{\theta=0}^{2\pi} 4(\cos(2\theta) + \sin(2\theta)) dh d\theta = 0 !$$

Stokes' theorem 16.7

Recall for a vector field $\vec{F} = (M, N, P)$

We have

$$\nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & P \end{vmatrix} = \hat{i} \left(\frac{\partial P}{\partial y} - \frac{\partial N}{\partial z} \right) - \hat{j} \left(\frac{\partial P}{\partial x} - \frac{\partial M}{\partial z} \right) + \hat{k} \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right)$$

What is it? It's kind of like a tool that
knows how much spinning is happening in a region.

For example

$(\nabla \times \vec{F})(a, b, c) \cdot \hat{n}$ "How much particle circulates in \vec{F}
in region \perp to \hat{n} at point (a, b, c)
relative to induced orientation of \hat{n} .

(right hand rule)



$(\nabla \times \vec{F}) \cdot \hat{n} > 0$ means spinning with
red

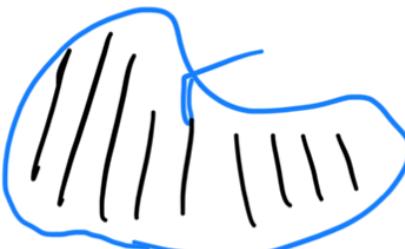
$\curvearrowleft \curvearrowup \curvearrowright \curvearrowleft$ means spinning against

$$\nabla \times \vec{F} = 0 \text{ in } \text{red}$$

$$(\nabla \times \vec{F}) \cdot \hat{n} = 0 \quad \text{no spin}$$

Recall Green's theorem says that for a planar region R with boundary Γ ,

we have $\oint_{\Gamma} \vec{F} \cdot d\vec{r} = \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA$



$$= \iint_R (\nabla \vec{F} \cdot \hat{k}) dA$$

Stokes' theorem generalizes this to non-planar regions.

$$\iint_S (\nabla \times \vec{F}) \cdot \hat{n} d\sigma$$


$$= \oint_{\Gamma} \vec{F} \cdot d\vec{r}$$

ex: let $\vec{F} = (x^2y, y^2z, z)$ and S be surface defined by hemisphere $x^2 + y^2 + z^2 = 1$ and $z \geq 0$. Let \hat{n} point upward.

Verify Stokes' theorem for this example.

$$(i). \quad \nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ xy & y^2 & z \end{vmatrix} = (0, 0, -x) = -x \hat{k}$$

$$g(x, y, z) = x^2 + y^2 + z^2 - 1$$

$$\nabla g = (2x, 2y, 2z) \quad \text{so } \hat{n} = \frac{\nabla g}{|\nabla g|} = \frac{2(x, y, z)}{2\sqrt{x^2 + y^2 + z^2}}$$

$$\nabla g \cdot \hat{k} = 2z = (x, y, z)$$

but again we knew that!

$$d\sigma = \frac{|\nabla g|}{|\nabla g \cdot \hat{k}|} dA = \frac{2\sqrt{x^2+y^2+z^2}}{2z} dA = \frac{1}{z} dA$$

so $(\nabla \times \vec{F}) \cdot \vec{n} = -xz$ and

$$\begin{aligned} \iint_S (\nabla \times \vec{F}) \cdot \vec{n} d\sigma &= \iint_{\theta=0^\circ}^{\theta=2\pi} \int_{\phi=0}^{\phi=\pi/2} (-xz) \frac{1}{z} dA = - \iint_S x dA \\ &= - \int_{\theta=0}^{2\pi} \int_{\phi=0}^{\pi/2} (\sin \phi \cos \theta) (r^2 \sin \phi d\phi d\theta) \\ &= 0 \end{aligned}$$



$$\oint_{\gamma} \vec{F} \cdot d\vec{r}, \quad \gamma(\alpha) = (\cos \alpha, \sin \alpha, 0) \\ d\vec{r} = (-\sin \alpha, \cos \alpha, 0) d\alpha$$

$$(\vec{F} \circ \gamma)(\alpha) = (\cos \alpha \sin \alpha, \sin \alpha, 0)$$

$$\text{so } \oint_{\gamma} \vec{F} \cdot d\vec{r} = \int_{\alpha=0}^{\alpha=2\pi} (-\cos \alpha \sin^2 \alpha + \cos \alpha \sin \alpha) d\alpha$$

$$= 0$$

$$\text{so } \iint_S (\nabla \times \vec{F}) \cdot \vec{n} d\sigma = \oint_{\gamma} \vec{F} \cdot d\vec{r}$$

Also note, let's change S to unit disk in xy -plane.

$$\text{then } \hat{n} = \hat{k}, \quad d\sigma = r dr d\theta$$



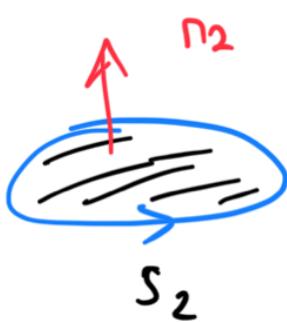
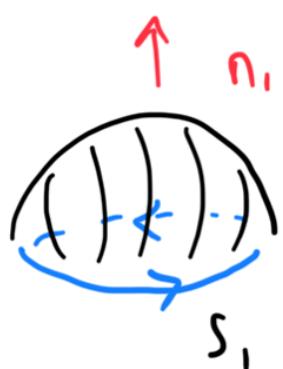
$$(\nabla \times \vec{F}) \cdot \hat{n} = (0, 0, -x) \cdot (0, 0, 1) = -x$$

$$\text{then } \iint_S (\nabla \times \vec{F}) \cdot \hat{n} d\sigma = \iint_R (-x) dA$$

$$\theta = 2\pi \quad r=1$$

$$= \int_{\theta=0}^{\theta=2\pi} \int_{r=0}^{r=1} (-r \cos \theta) r dr d\theta = 0$$

Observation: A bunch of surfaces band unit circle. Here are some,



Stokes' theorem says

$$\iint_S (\nabla \times \vec{F}) \cdot \hat{n}_1 d\sigma_1$$

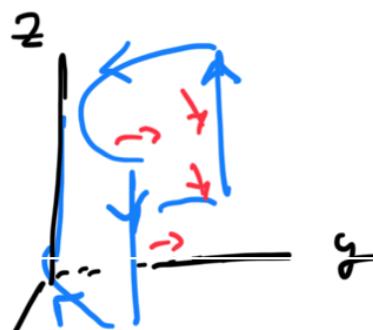
$$= \iint_{S_2} (\nabla \times \vec{F}) \cdot \hat{n}_2 d\sigma_2$$

$$= \iint_{S_3} (\nabla \times \vec{F}) \cdot \hat{n}_3 d\sigma_3$$

monot of the
story, choose
easier one!

ex: Consider surface $\vec{r}(u, v) = (u, u^2, v)$
where $-1 \leq u \leq 1$ and $0 \leq v \leq \pi/2$ with normal pointing
towards +y-axis. Verify Stokes' theorem for

$$\vec{F} = (\sin(z), x, y)$$



$$(i). \vec{r}_u = (1, 2u, 0)$$

$$\vec{r}_v = (0, 0, 1)$$

$$\vec{r}_u \times \vec{r}_v = (2u, -1, 0) \text{ so need}$$

to take $\vec{n} = -\vec{r}_u \times \vec{r}_v$ so

y - positive.

$$\nabla \times \vec{F} = (1, \cos z, 1) = \hat{i} + \cos z \hat{j} + \hat{k} \text{ so}$$

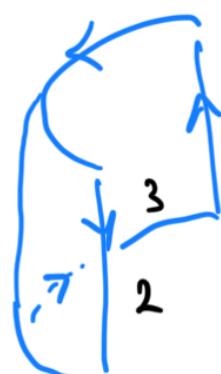
$$-(\nabla \times \vec{F}) \cdot (\vec{r}_u \times \vec{r}_v) = -2u + \cos(v)$$

$$\iint_S (\nabla \times \vec{F}) \cdot \vec{n} d\sigma = \iint_R (\nabla \times \vec{F}) \cdot (-\vec{r}_u \times \vec{r}_v) dA$$

$$= \int_{v=0}^{v=1} \int_{u=-1}^{u=\pi/2} (-2u + \cos(u)) du dv$$

$$= 2$$

(ii).



$$1: \alpha(\star) = (\star, \star^2, \pi/2) \quad -1 \leq \star \leq 1$$

$$2: \beta(\star) = (1, 1, \pi/2 - \star) \quad 0 \leq \star \leq \pi/2$$

$$3: \gamma(\star) = ((1-\star), (1-\star)^2, 0) \quad 0 \leq \star \leq 1$$

$$4: \delta(\star) = (-1, +1, \star) \quad 0 \leq \star \leq \pi/2$$

$$1. d\vec{r} = (1, 2\star, 0) d\star$$

$$(\vec{F} \circ \alpha)(\star) = (1, \star, \star^2)$$

$$\int_{\alpha} \vec{F} \circ d\vec{r} = \int_{-1}^{+1} (1 + 2\star^2) d\star = \frac{10}{3}$$

$$2. d\vec{r} = (0, 0, -1) d\star$$

$$(\vec{F} \circ \beta)(\star) = (\cos \star, 1, 1)$$

$$\oint_S \vec{F} \cdot d\vec{r} = \int_0^{\pi/2} (-1) dx = -\pi/2$$

3. $d\vec{r} = (-1, -2(1-x), 0) dx$

$$(\vec{F} \circ g)(x) = (0, (1-x), (1-x)^2)$$

$$\oint_S \vec{F} \cdot d\vec{r} = \int_0^2 -2(1-x)^2 dx = -4/3$$

4. $d\vec{r} = (0, 0, 1) dx$

$$(\vec{F} \circ g)(x) = (\sin x, -1, +1)$$

$$\oint_S \vec{F} \cdot d\vec{r} = \int_0^{\pi/2} (+1) dx = +\pi/2$$

so $\oint_{\partial S} \vec{F} \cdot d\vec{r} = \frac{10}{6} - \frac{\pi}{2} - \frac{4}{3} + \frac{\pi}{2} = 2$

so $\iint_S (\nabla \times \vec{F}) \cdot \vec{n} d\sigma = \oint_{\partial S} \vec{F} \cdot d\vec{r}$

One last bit about Stokes' theorem,

Need to assume \vec{F} and $\nabla \times \vec{F}$ are 'nice' on surface. Theorem is false if \vec{F} is badly behaved on surface.

Also another neat bit

is that $(\nabla \times \vec{F}) \cdot \hat{u} \Big|_Q = \lim_{P \rightarrow 0} \frac{\iint_S (\nabla \times \vec{F}) \cdot \vec{u} d\sigma}{\text{Area of small disk about } Q}$



$$= \lim_{P \rightarrow 0} \frac{1}{\pi P^2} \iint_S (\nabla \times \vec{F}) \cdot \vec{u} d\sigma$$

$$= \lim_{r \rightarrow 0} \frac{1}{\pi r^2} \oint_S \vec{F} \cdot d\vec{r} = \text{infinitesimal circulation density}$$

Note this means direction of greatest circulation is $\nabla \times \vec{F}$!

Also if let $\vec{F} = \nabla f$ then we have

$$\iint_S (\nabla \times \vec{F}) \cdot \hat{n} d\sigma = \oint_S \vec{F} \cdot d\vec{r}$$

$$= \oint_S \nabla f \cdot d\vec{r} = 0 \quad \text{by conservative vector field}$$

if we for any surface S

then $\nabla \times \vec{F} = \vec{0}$ (conclude by direct calculation too).

but this says

$$\nabla \times (\nabla f) = \vec{0}.$$

Finally if $\nabla \times \vec{F} = \vec{0}$ on a simply connected region S

then $\oint_S \vec{F} \cdot d\vec{r} = 0$ where γ is boundary of S .

thus on simply connected regions the following are equivalent-

1. \vec{F} conservative on D (path integrals depend only on beginning/end points)

2. $\oint_D \vec{F} \cdot d\vec{r} = 0$ for any loop γ in D

$$3. \quad \nabla \times \vec{F} = \vec{0} \quad \text{on } D$$

$$4. \quad F = \nabla f \quad \text{on } D$$

16.8: Divergence Theorem

Just like in (2D) given a vector field

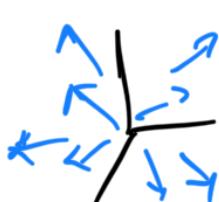
$\vec{F} = (M, N, P)$ we associate the scalar function

$$\operatorname{div} \vec{F} = \nabla \cdot \vec{F} = \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} + \frac{\partial P}{\partial z}$$

$\nabla \cdot \vec{F}$ is a measure of how much a fluid/gas is expanding / contracting at a point under the vector field \vec{F} . If $\operatorname{div} \vec{F} > 0$ expanding
 $\operatorname{div} \vec{F} < 0$ contracting
 $\operatorname{div} \vec{F} = 0$ no flux.

Measured in flux/unit volume so frequently called 'flux density'.

ex: $\vec{F} = (x, y, z)$ $\operatorname{div} \vec{F} = 1+1+1 > 0$

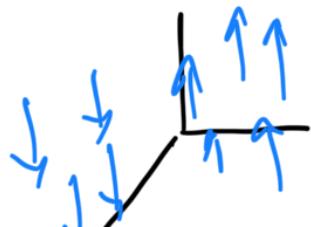


similarly $\vec{F} = (-x, -y, -z)$
then $\operatorname{div} \vec{F} = -3 < 0$

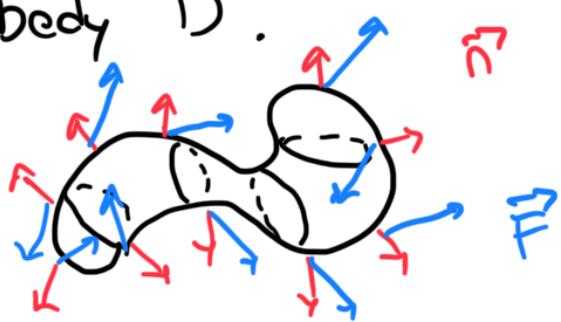
ex: $\vec{F} = (-y, x, 0)$ then $\operatorname{div} \vec{F} = 0$ because fluid just spinning



ex: $\vec{F} = (0, 0, z)$ then $\operatorname{div} \vec{F} > 0$ because stuff moving out



Divergence theorem: Let S be a closed oriented surface. The flux of \vec{F} across S in the direction of outward unit normal \vec{n} equals the integral of the divergence over the body D .



$$\begin{aligned} \text{Flux } \vec{F} \text{ over } S &= \iint_S (\vec{F} \cdot \vec{n}) d\sigma \\ &= \iiint_D (\nabla \cdot \vec{F}) dV \end{aligned}$$

ex: Verify Divergence Theorem for $\vec{F} = (y^2, x^2, 0)$ over the sphere.

$$\iint_S (\vec{F} \cdot \vec{n}) d\sigma : \text{Recall } \iint_S \vec{F} \cdot \vec{n} d\sigma = \iint_R \vec{F} \cdot (\vec{r}_\phi \times \vec{r}_\theta) dA$$

for a parameterization \vec{r} . Let $\vec{r}(\phi, \theta) = (\sin \phi \cos \theta, \sin \phi \sin \theta, \cos \phi)$

so that $\vec{r}_\phi \times \vec{r}_\theta = (\cos \theta \sin^2 \phi, \sin \theta \sin^2 \phi, \cos \phi \sin \theta)$

$$\begin{aligned} \text{thus } \vec{F} \cdot (\vec{r}_\phi \times \vec{r}_\theta) &= \cos \phi \sin^3 \phi \underline{\cos \theta \sin \theta} \\ &\quad + \underline{\cos^2(\theta) \sin(\theta) \sin^4 \phi} \\ &\quad + \underline{\cos \theta \sin^2 \theta \sin^4 \phi} \end{aligned}$$

Each blue term integrates to 0 on $0 \leq \theta \leq 2\pi$,

$$\text{So } \iint_S \vec{F} \cdot \vec{n} \, d\sigma = 0.$$

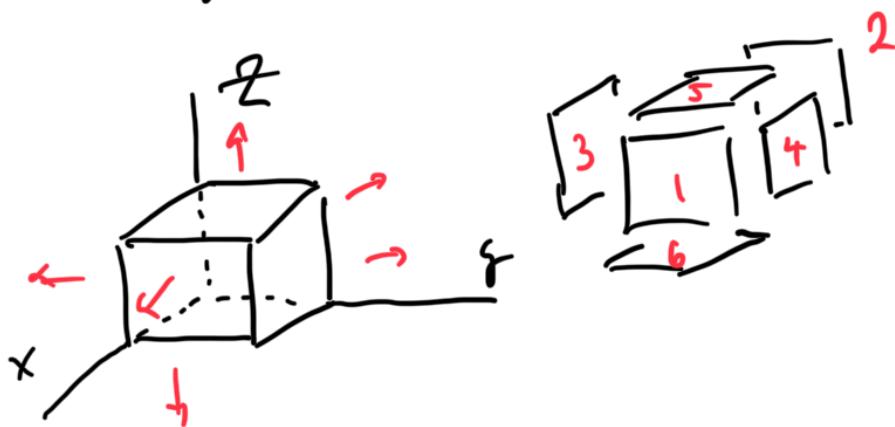
$$\text{Similarly: } \iiint_D (\nabla \cdot \vec{F}) \, dV = \iiint_D 0 \, dV = 0$$

$$\nabla \cdot \vec{F} = (0+0+0) = 0$$

ex: Calculate $\iint(F \cdot \vec{n}) \, d\sigma$ over box $0 \leq x, y, z \leq 1$

of vector field $\vec{F} = (x^2, y^2, z^2)$ in both ways

using Divergence theorem.



$$\vec{F}|_3 = (x^2, y^2, z^2) = (x^2, 0, z^2) \text{ and } \vec{n}_3 = (0, -1, 0)$$

$$\vec{F}|_6 = (x^2, y^2, 0^2) \text{ and } \vec{n}_6 = (0, 0, -1)$$

$$\vec{F}|_2 = (0^2, y^2, z^2) \text{ and } \vec{n}_2 = (-1, 0, 0)$$

$$\text{so on } 3, 6, 2 \quad \vec{F} \cdot \vec{n} = 0$$

$$\text{However, } \vec{F}|_1 = (1^2, y^2, z^2) \quad \vec{n}_1 = (1, 0, 0)$$

$$\vec{F}|_4 = (x^2, 1^2, z^2) \quad \vec{n}_4 = (0, 1, 0)$$

$$\vec{F}|_5 = (x^2, y^2, 1^2) \quad \vec{n}_5 = (0, 0, 1)$$

$$\text{so Flux} = \iint_1 1 \, dA + \iint_4 1 \, dA + \iint_5 1 \, dA$$

$$\int\int_R \nabla \cdot \vec{F} dA = \int\int_{R_4} (x+y+z) dA = 3 \cdot \text{Area of unit square} = 3.$$

On other hand, $\nabla \cdot \vec{F} = 2x + 2y + 2z$

$$\begin{aligned} & \text{So } \iint_D (\nabla \cdot \vec{F}) dV = 2 \iint_D (x+y+z) dV \\ &= 2 \int_{x=0}^{x=1} \int_{y=0}^{y=1} \int_{z=0}^{z=1} (x+y+z) dV = 2 \left(\frac{3}{2} \right) = 3 \end{aligned}$$

Relation between curl and divergence

theorem: if $\vec{F} = (M, N, P)$ with nice partial derivatives then

$$\operatorname{div}(\nabla \times \vec{F}) = \nabla \cdot (\nabla \times \vec{F}) = 0$$

Proof: Some algebra

ex: Calculate $\iint_S (\vec{F} \cdot \vec{n}) d\sigma$ over the cube in the previous example

\vec{F} is the vector field $\vec{F} = (2y - 2z, -2x + 2z, 2x - 2y)$

let's say you were having a good math day and noticed that

$$\Rightarrow \vec{n}_1, \vec{n}_2, \vec{n}_3 \text{ are } \vec{c} = (x^2 + z^2, x^2 + y^2, x^2 + y^2)$$

$$\text{then by divergence theorem,}$$

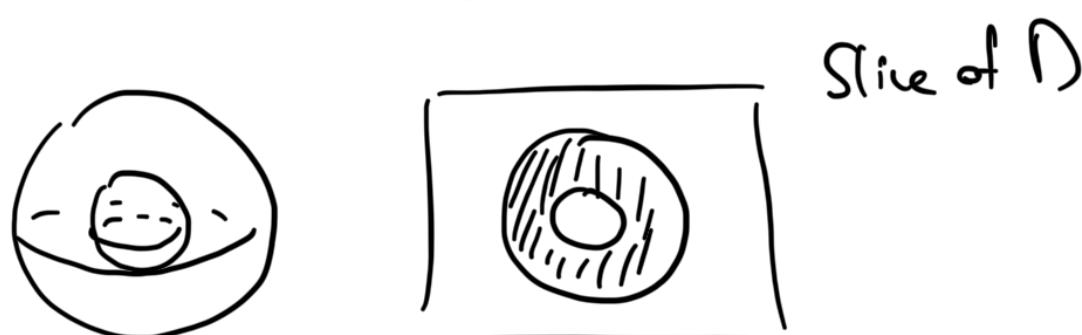
$$\iint_S (\vec{F} \cdot \vec{n}) d\sigma = \iiint_D (\operatorname{div} \vec{F}) dv = \iiint_D \operatorname{div} (\nabla \times \vec{G}) dv$$

$$= \iiint_D 0 dv = 0$$

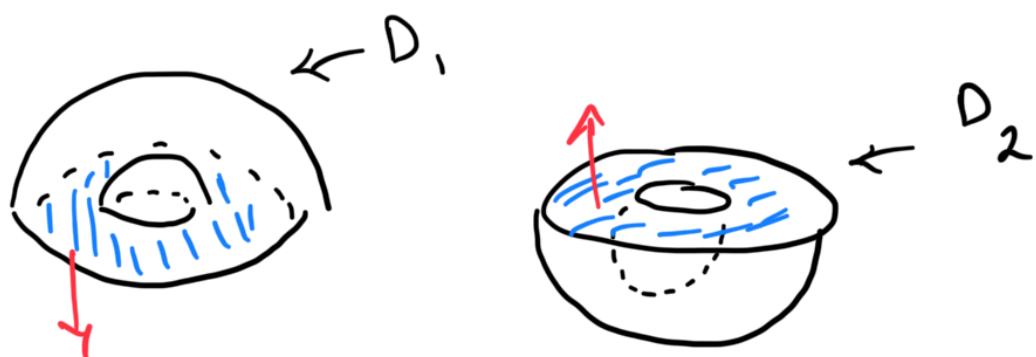
Also it's a neat way to check if $\vec{F} = \nabla \times \vec{G}$ for some \vec{G} . Ex: $\vec{F} = (x, y, z)$ has $\operatorname{div} \vec{F} \neq 0$ so no solution to $\vec{F} = \nabla \times \vec{G}$.

Divergence theorem holds for more general regions.

e.g. let D be region between two concentric spheres.



Can break D up into



S_1 = semi-outer sphere
semi-inner sphere
flat annulus

S_2 = semi-outer sphere
semi-inner sphere
flat annulus

By Divergence theorem $\iiint_D (\nabla \cdot \vec{F}) dV = \iint_{S_1} \vec{F} \cdot \vec{n} d\sigma$

and $\iiint_{D_2} (\nabla \cdot \vec{F}) dV = \iint_{S_2} \vec{F} \cdot \vec{n} d\sigma$. so

$$\iiint_D (\nabla \cdot \vec{F}) dV = \iint_{S_1} (\vec{F} \cdot \vec{n}) d\sigma + \iint_{S_2} (\vec{F} \cdot \vec{n}) d\sigma$$

$$= \iint_{\text{outer sphere}} (\vec{F} \cdot \vec{n}) d\sigma + \iint_{\text{inner sphere}} \vec{F} \cdot \vec{n} d\sigma$$

$$+ \iint_{\text{Annulus 1}} (\vec{F} \cdot \vec{n}) d\sigma + \iint_{\text{Annulus 2}} (\vec{F} \cdot \vec{n}) d\sigma$$

two could be opposite orientation!

$$\iint_{\partial D} (\vec{F} \cdot \vec{n}) d\sigma = \iiint_D (\nabla \cdot \vec{F}) dV \text{ where } \partial D \text{ is boundary of } D$$

with possibly many pieces.

Ex: let $\vec{F} = (x, y, z) / p^3$ where $p = \sqrt{x^2 + y^2 + z^2}$

and calculate the flux of \vec{F} across the boundary of

D as above. One can calculate for $p \neq 0$

that $\operatorname{div} \vec{F} = 0$ (a little weird, looks like it wouldn't)

$$\text{so } \iiint_D \operatorname{div} \vec{F} dV = \iint_{S_1} (\vec{F} \cdot \vec{n}) d\sigma + \iint_{S_2} (\vec{F} \cdot \vec{n}) d\sigma = 0$$

So $\iint_{\text{Sphere}} (\vec{F} \cdot \vec{n}) d\sigma$ independent of radius of sphere.

In fact if we choose sphere to be radius a

$$\text{then } \vec{F} \cdot \vec{n} = \frac{(x, y, z)}{a^3} \cdot \frac{(x, y, z)}{a} = \frac{x^2 + y^2 + z^2}{a^4} = \frac{1}{a^2}$$

$$\text{So Flux} = \iint_{\text{Sphere}} (\vec{F} \cdot \vec{n}) d\sigma = \iint_{\text{Sphere}} \left(\frac{1}{a^2}\right) d\sigma = \left(4\pi a^2\right) / a^2 = 4\pi$$

$$\text{Gauss' Law: let } \vec{E} = \frac{1}{4\pi \epsilon_0} q \frac{\vec{r}}{|\vec{r}|^3}$$

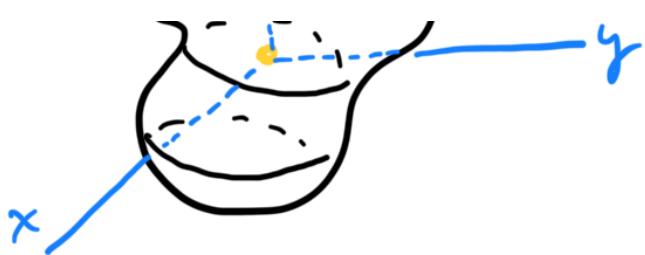
where ϵ_0 is a physical constant (electric permittivity of free space $\approx 10^{-11} \frac{\text{Coulomb}}{\text{Nm}^2}$)
 q is point charge located at origin, \vec{r} is position vector.

Note by previous calculations, $\nabla \cdot \vec{E} = 0$.

So if S is any surface containing the origin point charge

$$\text{Flux of } \vec{E} \text{ across } S = \iint_S \vec{E} \cdot \vec{n} d\sigma = 4\pi \cdot \frac{q}{4\pi \epsilon_0} = \frac{q}{\epsilon_0}$$





Note that Green's theorem from before was

$$\oint_{\Gamma} \vec{F} \cdot \vec{n} \, ds = \iint_R \left(\frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} \right) \, dA$$

So if we consider $\vec{F} = (M, N, 0)$ then $d\nu \vec{F} = \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y}$

$$\text{so } \oint_{\Gamma} (\vec{F} \cdot \vec{n}) \, ds = \iint_R (\nabla \cdot \vec{F}) \, dA$$

Similarly $(\nabla \times \vec{F}) \cdot \hat{k} = \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right)$ so

$$\oint_{\Gamma} (\vec{F} \cdot \vec{T}) \, ds = \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \, dA$$

$$= \iint_R (\nabla \times \vec{F}) \cdot \hat{k} \, dA$$

Comparing:

Tangential Green in plane: $\oint_{\Gamma} (\vec{F} \cdot \vec{T}) \, ds = \iint_R (\nabla \times \vec{F}) \cdot \hat{k} \, dA$

Stokes: $\oint_{\Gamma} (\vec{F} \cdot \vec{T}) \, ds = \iint_S (\nabla \times \vec{F}) \cdot \vec{n} \, d\sigma$

Normal Green in plane: $\oint_{\Gamma} (\vec{F} \cdot \vec{n}) \, ds = \iint_R (\nabla \cdot \vec{F}) \, dA$

$$\text{Divergence: } \iint_S (\vec{F} \cdot \hat{n}) d\sigma = \iiint_D (\nabla \cdot \vec{F})^n dV$$

All of these can be unified by a more general Stokes' Theorem. Very loosely speaking

$$\int_D \underset{\text{derivative of}}{\text{something}} = \int_{\partial D} \underset{\text{Something}}{\text{something}}$$

Something is a differential form.