Task B13

Group 28

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Motivation, Aim and Preprocessing

Motivation

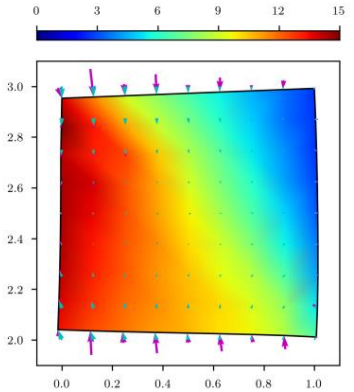
- Equation systems in realistic FEM Simulation can be extremely large → Massive computational resources
- Machine experience gained during the simulation is lost, input slightly changed → New Simulation needed!
- Machine learning models can be trained on data generated by conventional FEM tools. Wide range of other applications[1]

Project: Boundary Value Problem[2]

- Input: $\mathbf{S_i}$ [4], $\mathbf{U_i}$ [2]
- Output: $\mathbf{F_i}$ [2]
- Reference Architecture: **Time Distributed AlexNET**
- Own Architecture: **Time Distributed w/ Recurrent Layers (LSTM)**

Preprocessing

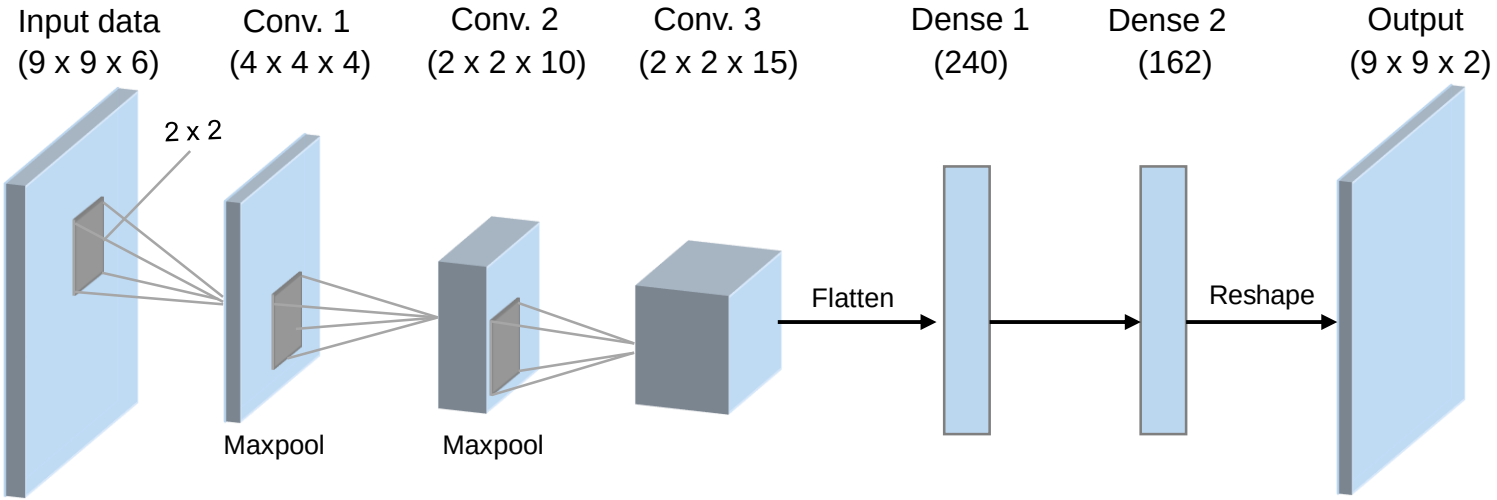
- Normalization using SD and Mean → (-3 to +3)



$$D = D(\mathbf{x}, t)$$

Time & Space Variant Data

Reference Architecture - Time Distributed AlexNET[3]



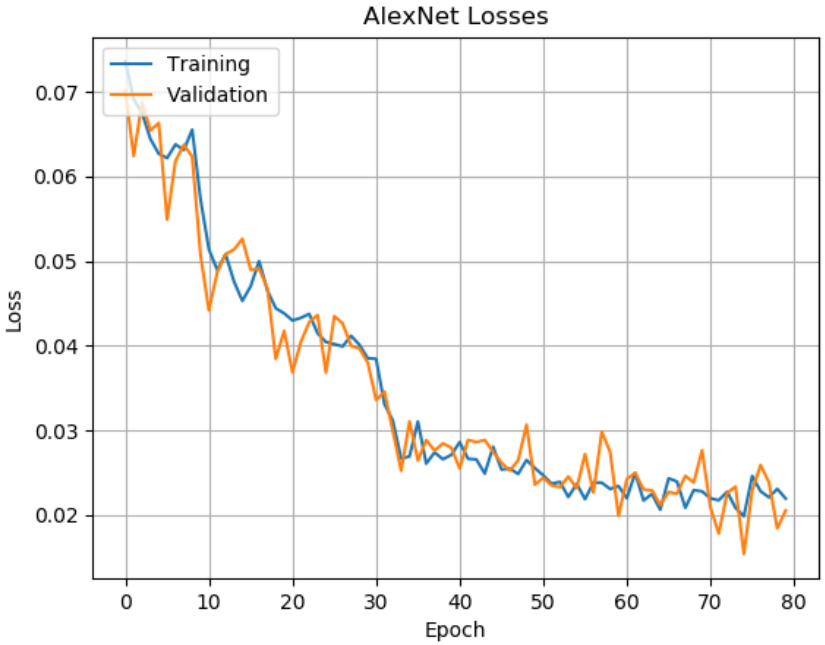
Model

- Padding = same[4]
- Activation: ReLU, linear
- Loss: mae
- Pool size: 2 x 2
- Stride = 1 x 1

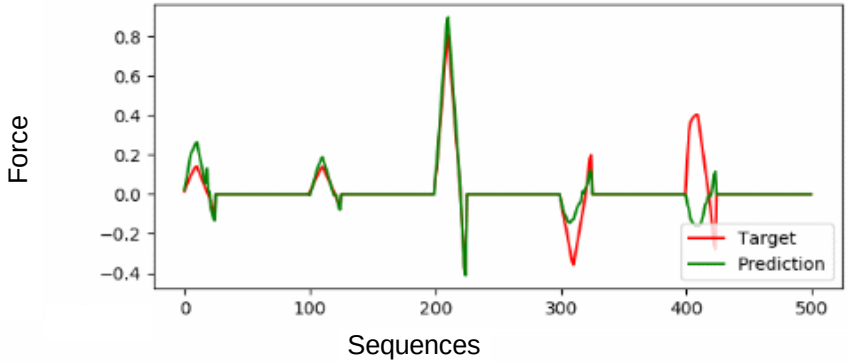
	16	64	128
0.001	0.021	0.049	0.028
0.01	0.073	0.073	0.073
0.1	0.084	0.082	0.083

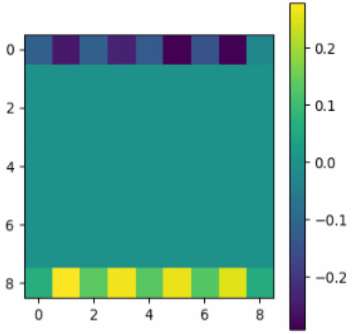
Test loss by batch size and learning rate for 80 Epochs

Reference Architecture - Time Distributed AlexNET[3]

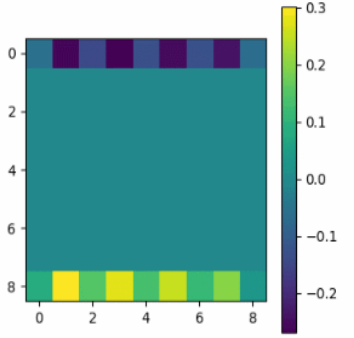


SMAPE = 0.1715%



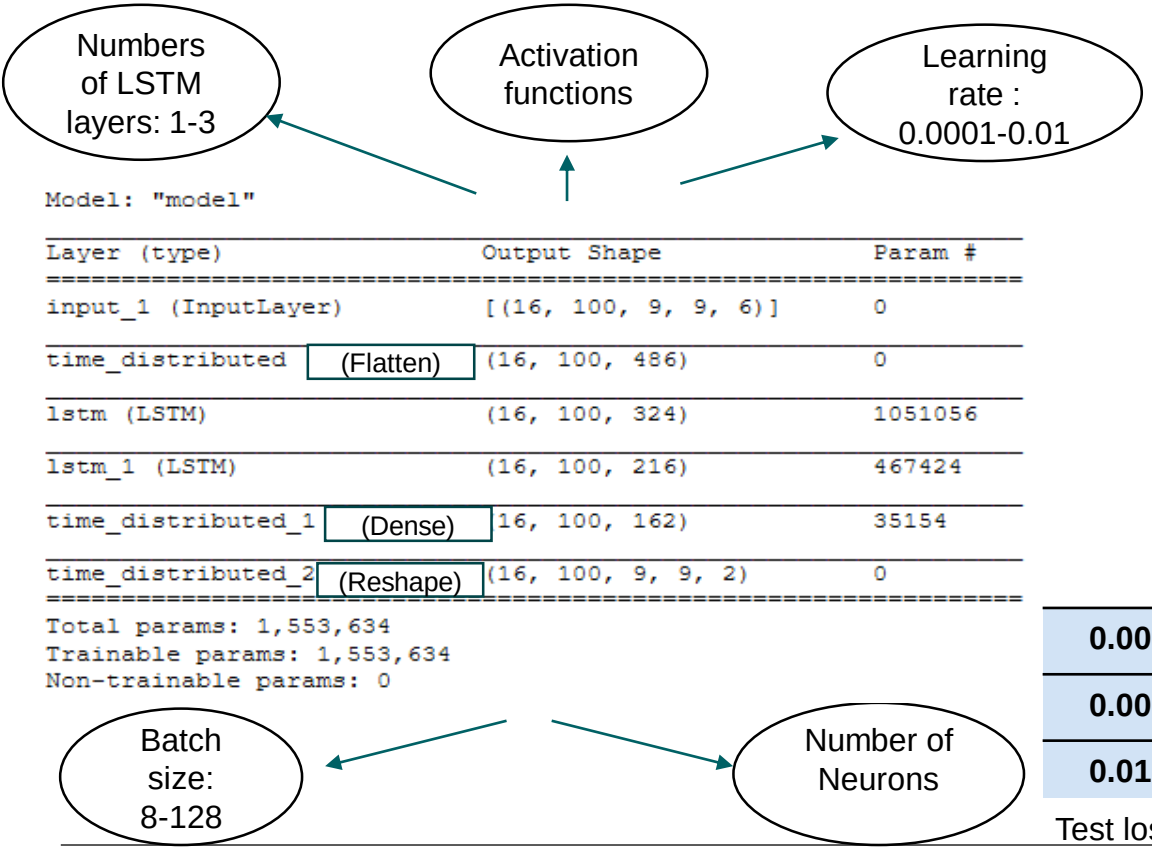


Target



Prediction

Own Architecture – LSTM RNN[5]



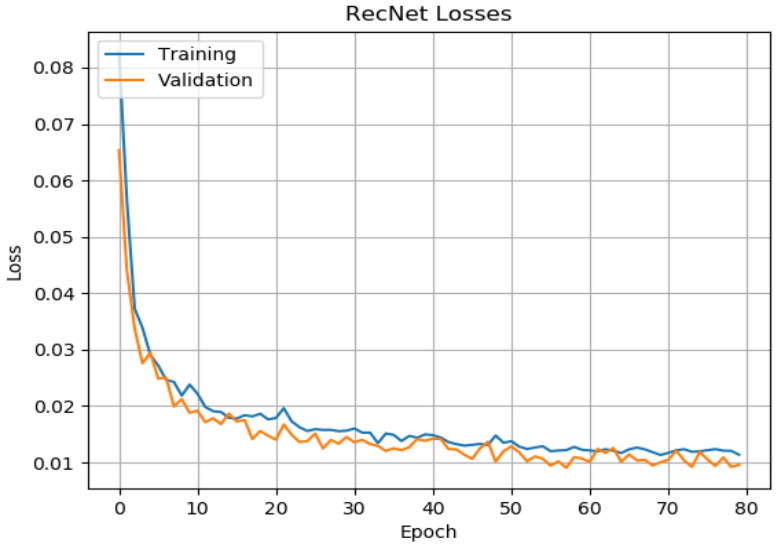
Model:

- LSTM layer: activation = tanh, returnsequence = true, Dropout = 0.2
- TimeDistributed Dense: activation = linear
- Loss: mae

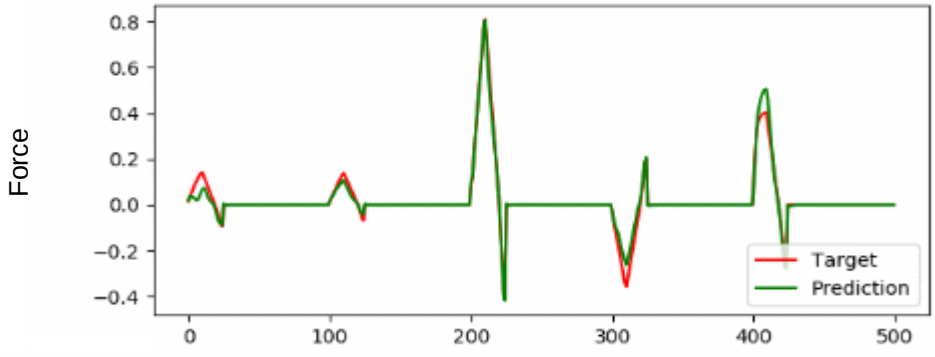
	8	16	32	64
0.0001	0.0116	0.0137	0.0171	0.0220
0.001	0.0095	0.0093	0.0096	0.0111
0.01	0.0210	0.0189	0.0176	0.0153

Test loss by batch size and learning rate for 80 Epochs

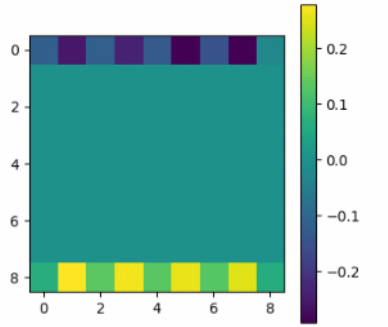
Own Architecture – LSTM RNN



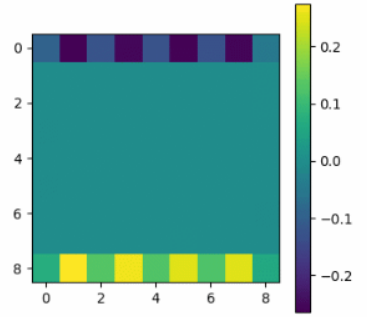
SMAPE = 0.1019%



Sequences



Target



Prediction

Discussion and Conclusion

Inferences:

- **SMAPE(AlexNET) = 0.1715%**
- **SMAPE(RNN) = 0.1019%**
- Comparing the SMAPE values and the predicted loads, it is clear that **RNN (own architecture) performs better and is more suitable for our task.**
- Slight underprediction for both networks (due to empty sequences!)
- Large dataset helped in increasing the efficacy of training

Further Work:

- Mask the empty sequences before training the models
- Test out other RNN architectures (e.g.: GRU).
- Further tuning of hyperparameters

Bibliography

1. Kononenko O, Kononenko I, 'Machine Learning and Finite Element Method for Physical Systems Modeling', 2018, https://arxiv.org/abs/1801.07337 [Accessed: 14 January 2020].
2. Lecture Notes: Computational Intelligence in Engineering.
3. A. Krizhevsky, I. Sutskever, and G. Hinton, 'Imagenet classification with deep convolutional neural networks', InNIPS, 2012
4. Tensorflow Documntation: https://www.tensorflow.org/api_docs/python/ [Accessed Jan. 2020]
5. Hochreiter S., Schmidhuber J., 'Long Short-term Memory ', Neural Computation, 9(8):1735-1780, 1997