EI5IS102 Traitement de l'Information

Lecture 3: Introduction to Machine Learning

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Machine Learning is everywhere



Series Recommenders











Self-driving cars







Image generators



Face recognition



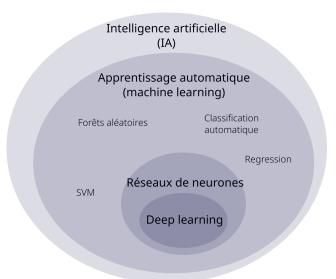
Games



Artificial Intelligence

Artificial intelligence?

- What is intelligence?
- Must have something to do with thinking
- What are the mechanisms of thinking?
- How to construct a model of thinking?



Wiki



Thinking

William Blake (English poet, 1757–1827) about thinking: "Man can only desire what he has already perceived"

Noam Chomsky (American linguist, 1928–) about intelligence: "Take two concepts and create a third one without impairing the two firsts"

Key concepts:

- Creation ex-nihilo cannot really exist
- Intelligence: the ability to assemble two ideas that seemed heterogeneous
- Thinking: finding similarity, discriminating and recognizing patterns



Learning

Past view of Al:

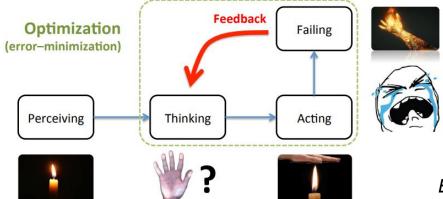
- Al was thought only about reasoning
- Programs with predefined rules
- Simulate intelligent decision-making

Current view of AI:

- Al is more about learning
- Systems that can improve through experience

Herbert Simon (American psychologist, 1916–2001) about learning:

"Learning is any process by which a system improves performance from experience"





Machine Learning algorithms:

- Programs that can learn from experience to deduce new facts

Early definition of machine learning by **Arthur Samuel** (American pioneer in AI, 1901–1990): "Field of study that gives computer the ability to learn without being explicitly programmed"

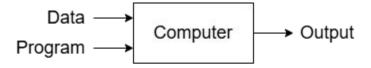
A.Samuel wrote the first self-learning program for checkers.

- Learning to improve its performance by playing against itself
- Invented alpha-beta pruning (decision tree searching)



How can we have the computer learn without being explicitly programmed?

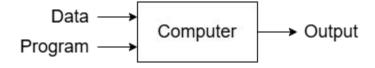
Traditional Programming



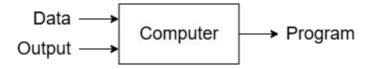


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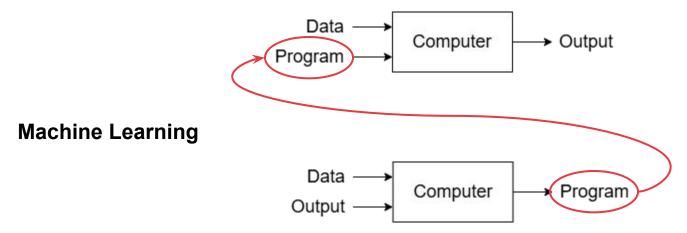
Machine Learning





How can we have the computer learn without being explicitly programmed?

Traditional Programming





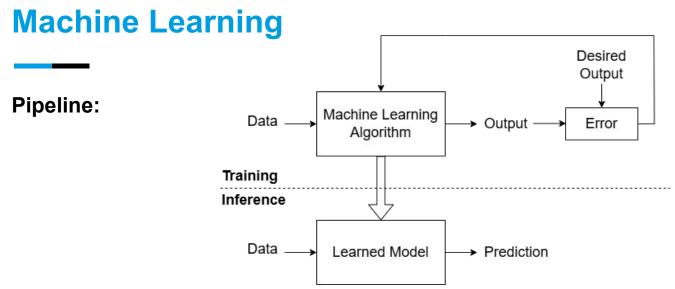
How to learn from data?

- Memorizing facts: limited by the time of observing facts, by the memory to store facts
- Generalizing: deduce new facts from old facts

Learning algorithm:

- A program that identifies patterns in data and uses those patterns to
- Programs that can infer useful information from implicit patterns in the data
- Need to figure out what those patterns are
- Then use those patterns to generate a program able to infer new data





Training phase:

- Input: a set of observations → training data
- Process: learn patterns from the training data
- Output: a model capable of identifying patterns in the data

Inference phase:

- Input: new observations → unseen data / test data
- Process: use the model to make new predictions



3 major types of learning:

Supervised learning: labeled training data

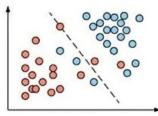
- Training: learn a function to map inputs to their labels
- Inference: predict the label of new unseen inputs

Unsupervised learning: unlabeled training data

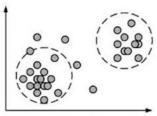
- Training: identify hidden structures in unlabeled data
- Inference: assign new inputs to the most appropriate group

Reinforcement learning: training data with global objective (actions)

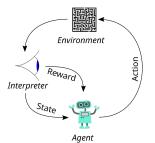
- Training: interact with an environment to maximize a cumulative reward
- Inference: make decisions to guide an agent towards an objective



Supervised Learning



Unsupervised Learning



Reinforcement Learning



Let's collect some data on fruits:

- weight, size
- labeled by fruit name



- Plum 1: [147.1g, 7.8cm]
- Plum 2: [143.2g, 7.7cm]
- Plum 3: [150.2g, 7.6cm]
- Plum 4: [155.7g, 7.7cm]
- Plum 5: [145.6g, 7.5cm]
- Plum 6: [150.8g, 8.0cm]





Peaches:

- Peach 1: [151.4g, 8.2cm]
- Peach 2: [160.5g, 8.8cm]
- Peach 3: [165.3g, 9.0cm]
- Peach 4: [164.8g, 8.6cm]
- Peach 5: [158.9g, 8.6cm]

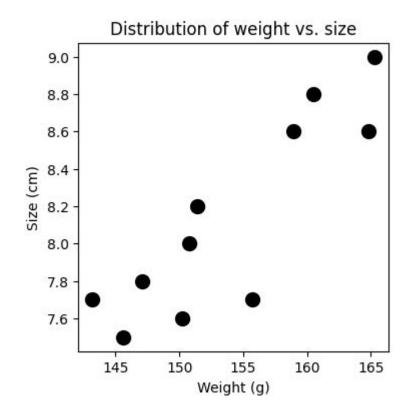


2D plot:

Can we learn patterns from data?

2 natural groups of points How to separate them?

Clustering





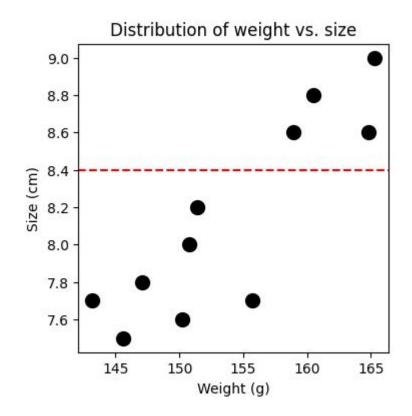
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2 natural groups of points How to separate them?

Clustering

1) Separation on size





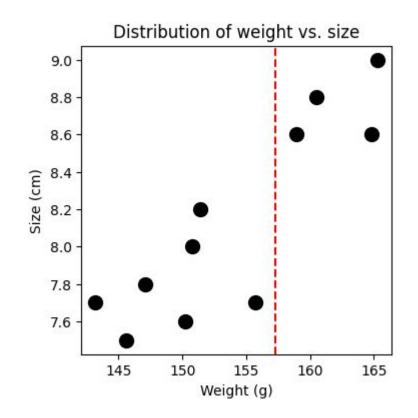
2D plot:

Can we learn patterns from data?

2 natural groups of points How to separate them?

Clustering

- 1) Separation on size
- 2) Separation on weight





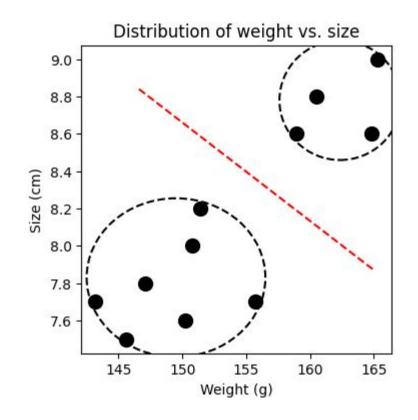
2D plot:

Can we learn patterns from data?

2 natural groups of points How to separate them?

Clustering

- 1) Separation on size
- 2) Separation on weight
- 3) Cluster into two groups using both attributes

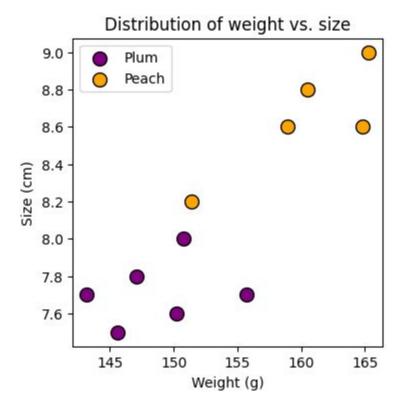




2D plot with labels:

How to take advantage of knowing the labels to divide the two groups?

Classification



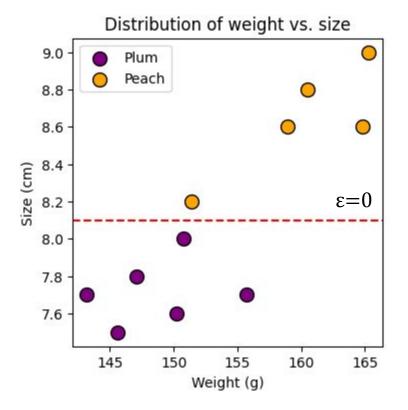


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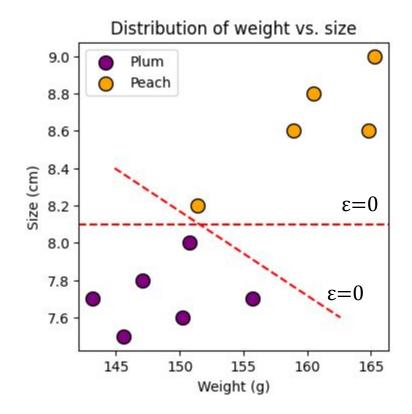


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2D plot with labels:

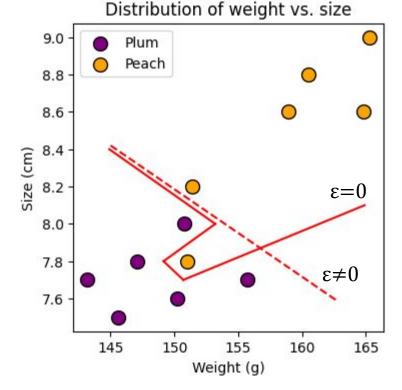
A new data point is added. Which separator do we choose?

- Dashed line: simple separator with errors
- 2) Solid line: complex separator without error

Option 2 performs well on training data But it may fail to generalize to new data

Avoid **overfitting**:

Trade-off between accuracy and simplicity





Machine Learning: learning and generalizing

Machine Learning consists in learning from examples:

- Training data: a set of examples (peaches, plums, etc.) labeled or not
- **Features**: descriptors that describe each example (weight, size, etc.)
- Distance measure: quantifies "similarity" between examples
- Objective function: evaluates the quality of any solution

During training, we aim at optimizing the objective function (minimizing or maximizing)

Machine Learning consists in generalizing on unseen data:

Test data: a set of additional examples, unknown during training

During inference, we hope to make accurate predictions on our test data



Unsupervised Learning

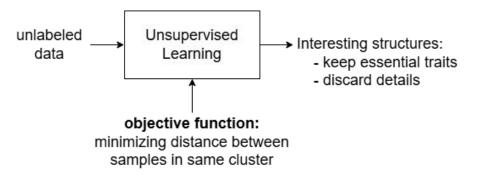
Unsupervised learning

Unsupervised learning:

- Unlabeled training data
- Goal: discover hidden structures in the data

Clustering:

- Group examples that are "close" together
- Assign the same label to all data points in each group
- Relies heavily on the choice of a distance metric
- The distance metric often matters more than the clustering algorithm itself.





Distance metric

Distances are used to measure the **similarity** or **dissimilarity** between two data points

 $d(x_i, x_j) = \sqrt[q]{|x_i^1 - x_j^1|^q + \ldots + |x_i^p - x_j^p|^q}$

Training data:

- n instances
- p features

$$X = \begin{pmatrix} x_1^1 & \dots & x_1^p \\ \vdots & \ddots & \vdots \\ x_n^1 & \dots & x_n^p \end{pmatrix}$$

Popular distance: **Minkowski**

- d=1: Manhattan distance
- d=2: Euclidean distance

Or weighted distance, ...



Clustering

K clusters $\{S_k\}$ with associate centroïds $\{C_k\}$. **Goal:** find the set S of clusters that minimize the within-cluster distance

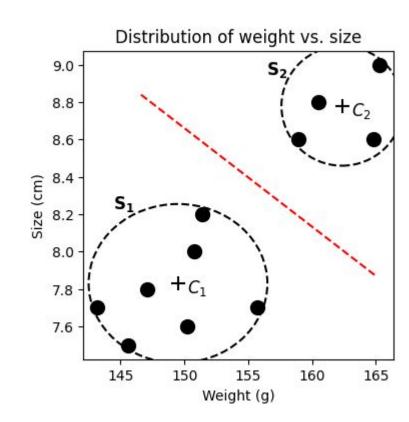
$$\underset{S}{\operatorname{arg\,min}} \sum_{k=1}^{K} \sum_{\mathbf{x}_i \in S_k} d(\mathbf{x}_i, C_k)$$

Given centroids $\{C_k\}$, associate each data point to the closest cluster:

$$\forall i, x_i \in S_k \text{ where } k = \operatorname*{arg\,min}_j d(\mathbf{x}_i, C_j)$$

Given memberships of our data, update centroïds:

$$\forall k, C_k = \frac{1}{|S_k|} \sum_{x_i \in S_k} x_i$$





K-means algorithm

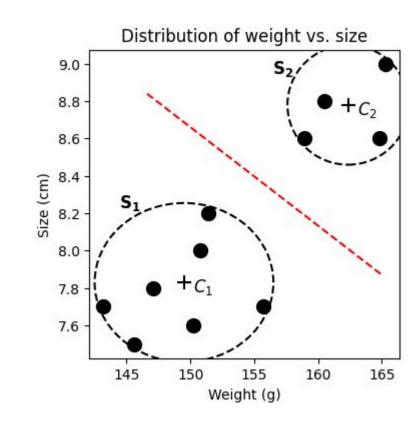
- Start with a random guess of cluster centers
- Determine the membership of each data point
- Adjust the cluster centers 3)

Stopping criterion:

- Number of iterations
- Clustering quality criterion $\rightarrow \sum \sum d(\mathbf{x}_i, C_k)$
- Evolution of the quality

$$0 \to \sum_{k=1} \sum_{\mathbf{x}_i \in S_k} d(\mathbf{x}_i, 0)$$

In practice: we stop when $\{C_i\}^{(t+1)} = \{C_i\}^{(t)}$





K-means algorithm

1) Set K the number of clusters: here K=3

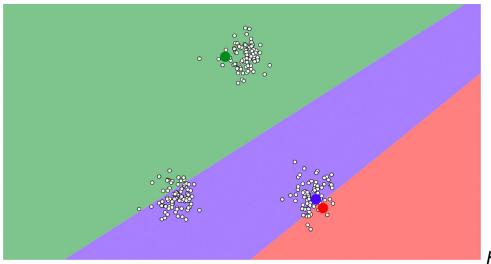






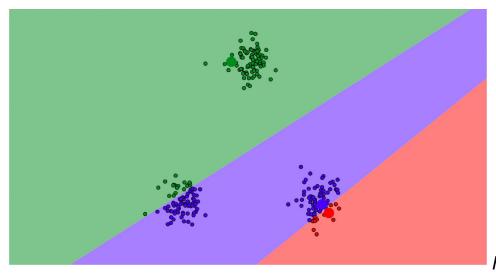


- 1) Set K the number of clusters: here K=3
- 2) Start with a random guess of cluster centers: select K random points



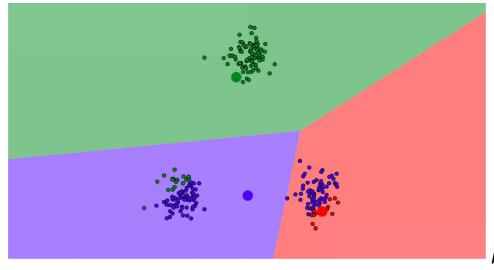


- 1) Set K the number of clusters: here K=3
- 2) Start with a random guess of cluster centers: select K random points
- 3) Associate each data point to its closest cluster



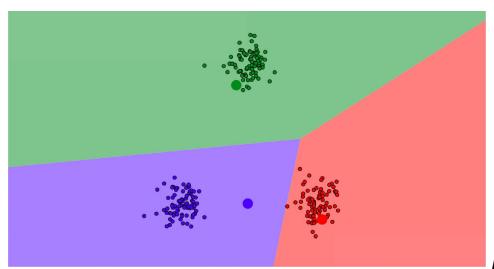


- 1) Set K the number of clusters: here K=3
- 2) Start with a random guess of cluster centers: select K random points
- 3) Associate each data point to its closest cluster
- 4) Adjust centroïds by computing their new mean



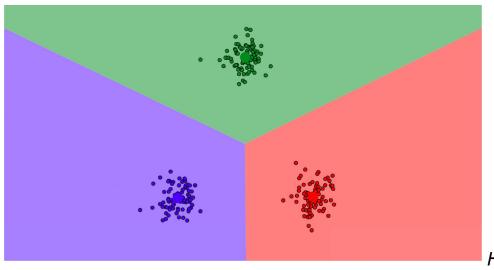


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Strengths:

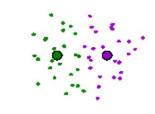
- Relatively efficient algorithm: O(nkt) with n data points, k clusters and t iterations
- Find at least a local optimum

Weaknesses:

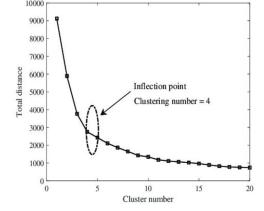
- Applicable only when the mean is defined (qualitative data?)
- Number of clusters K needs to be fixed in advance: elbow method

Variants:

K-medoids, K-modes, ect.







Hierarchical Clustering

Hierarchical Clustering:

- Uses distances between data points as clustering criteria
- Does not require to determine a number of clusters
- Agglomerative vs. divisive

Step 0 Step 1 Step 2 Step 3 Step 4 **Agglomerative** a b abcde cde d e **Divisive** Step 3 Step 2 Step 1 Step 0



Hierarchical Clustering

Agglomerative Clustering

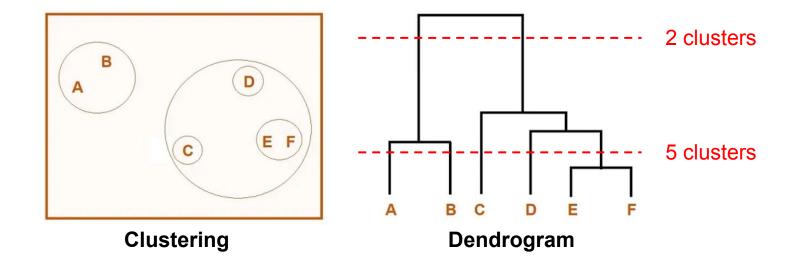
- Start with each point as individual cluster
- At each step, merge the closest pair
- Stop when only one cluster remains

Divisive Clustering

- Start with one cluster
- At each step, split a cluster
- Stop when each cluster contains a single point



How many clusters do we want?



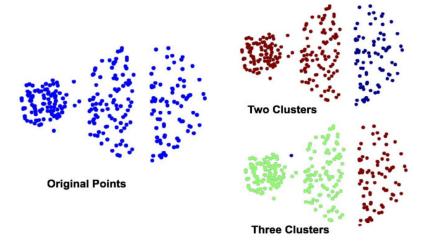


Distance between two clusters?

1) **Single-link** distance: minimum distance between any points in S_i and S_j

$$d_{sl}(S_i, S_j) = \min_{x,y} \left\{ d(x, y) | x \in S_i, y \in S_j \right\}$$

Limitations: sensitive to noise and outliers

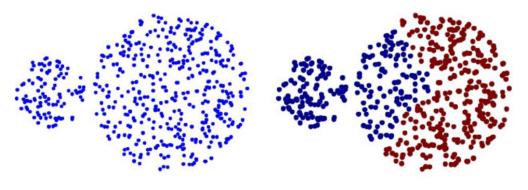




Distance between two clusters?

2) Complete-link distance: maximum distance between any points in S_i and S_j $d_{sl}(S_i, S_j) = \max_{x,y} \left\{ d(x,y) | x \in S_i, y \in S_j \right\}$

Limitations: all clusters tend to have same diameters → break large clusters





Two Clusters



Distance between two clusters?

3) **Group average** distance: average distance between any points in S_i and S_i

$$d_{ga}(S_i, S_j) = \frac{1}{|S_i| \times |S_j|} \sum_{x \in S_i, y \in S_i} d(x, y)$$

Compromise between single and complete links

4) Centroid distance

$$d_{centroids}(S_i, S_j) = d(C_i, C_j)$$

5) Ward's distance

$$d_{wards}(S_i, S_j) = \sum_{x \in S_i} (x - C_i)^2 + \sum_{x \in S_j} (x - C_j)^2 + \sum_{x \in S_i, j} (x - C_i)^2$$



Hierarchical Clustering

- Deterministic: always the same answer
- Greedy algorithm: local optima rather than global optimum
- Very long to compute

Complexity

- Space: O(n²) to store the distance matrix
- Time: O(n³)
 - n steps
 - at each step, the distance matrix of size n² must be updated



Supervised Learning

Supervised learning

Supervised learning:

- Labeled training data
- Goal: learn a function to map inputs to their labels

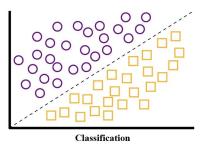
Classification:

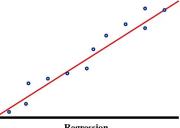
- Labels are **discrete** classes (ex: peach/plum)
- Predict the correct class for each input

Regression:

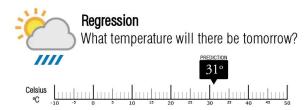
- Labels are **continuous** values of a dependent variable (ex: ordinate)
- Make the best prediction based on a set of independent variables (ex: abscissa)











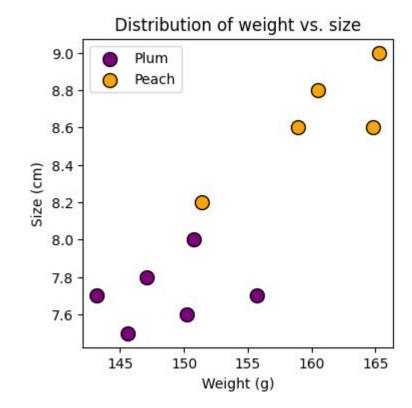
Classification

Our initial example: peaches vs. plums

- Features: weight, size

Labels: Fruit name

How to divide the space?





Classification

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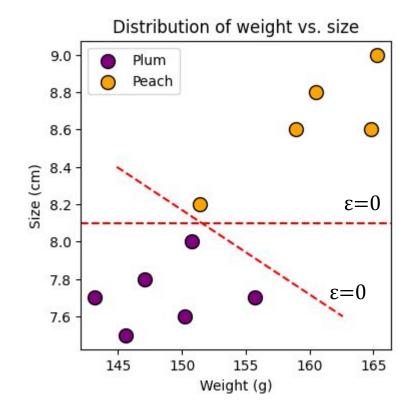
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How to divide the space?

Many perfect separators exist... How to find the best separation?

- each separator defines a "street" (margin)
- Can we find the widest street?





Classification

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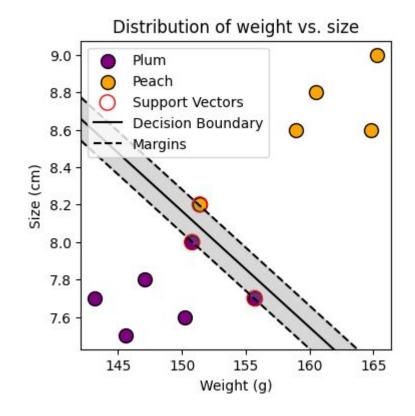
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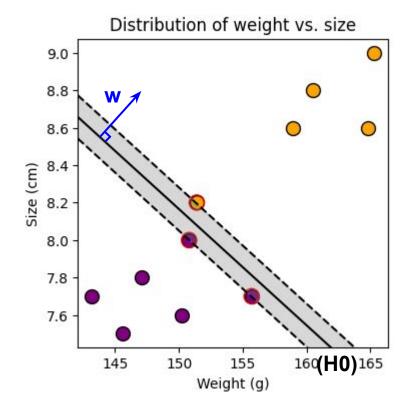
Support Vector Machines





Let's consider $\mathbf{w} \perp (H0)$:

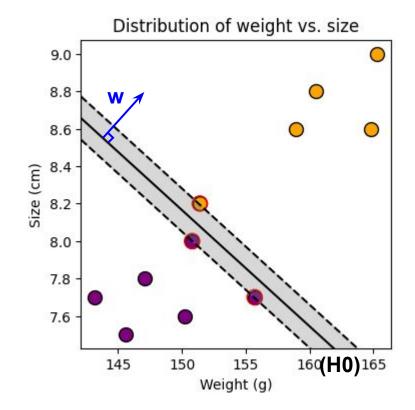
- For each point **x** in (H0): $\vec{w} \cdot \vec{x} = \mathtt{cste}$





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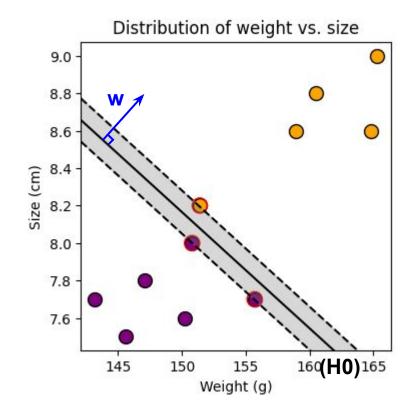
- For each point **x** in (H0): $\vec{w} \cdot \vec{x} = \text{cste}$
- So we can find b such as: $\vec{w} \cdot \vec{x} + b = 0$





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- So we can find b such as: $\vec{w} \cdot \vec{x} + b = 0$
- Thus: $\begin{cases} \vec{w} \cdot \vec{x} + b \geq 0 \Rightarrow \text{peach} \\ \vec{w} \cdot \vec{x} + b < 0 \Rightarrow \text{plum} \end{cases}$

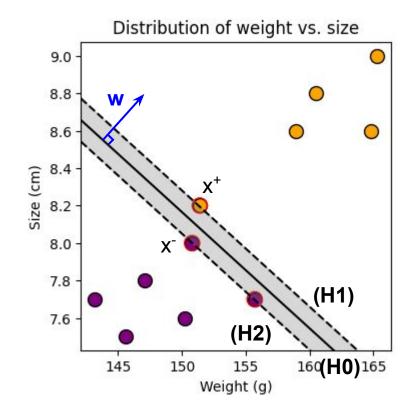




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Equations of (H1) and (H2): $\begin{cases} \vec{w} \cdot \vec{x^+} + b = +k \\ \vec{w} \cdot \vec{x^-} + b = -k \end{cases}$



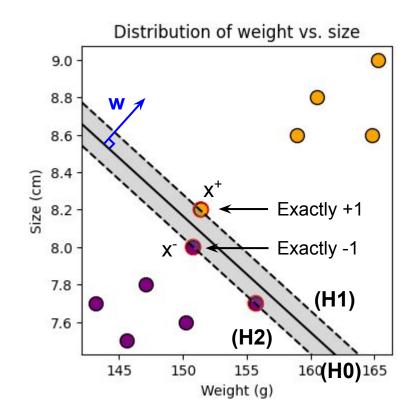


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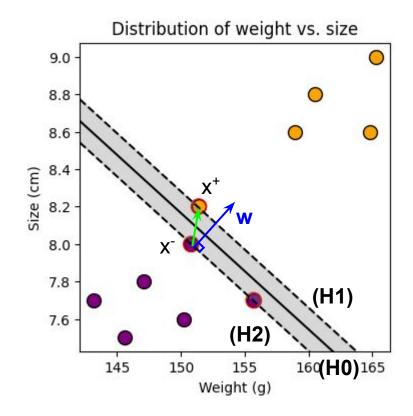
Rescaling **w** and b gives:
$$\begin{cases} \vec{w} \cdot \vec{x^+} + b = +1 \\ \vec{w} \cdot \vec{x^-} + b = -1 \end{cases}$$





SVM maximizes the width of the margin:

$$\text{width} = \frac{\vec{w}}{||\vec{w}||} \cdot (\vec{x^+} - \vec{x^-})$$





SVM maximizes the width of the margin:

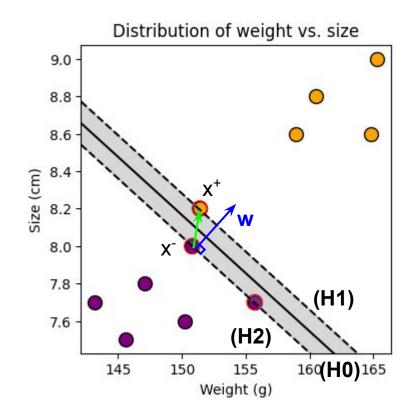
$$\text{width} = \frac{\vec{w}}{||\vec{w}||} \cdot (\vec{x^+} - \vec{x^-})$$

Also:

$$\vec{w} \cdot \vec{x^+} + b = +1$$

$$\vec{w} \cdot \vec{x^-} + b = -1$$

$$\Rightarrow \vec{w} \cdot (\vec{x^+} - \vec{x^-}) = 2$$





SVM maximizes the width of the margin:

$$\text{width} = \frac{\vec{w}}{||\vec{w}||} \cdot (\vec{x^+} - \vec{x^-})$$

Also:

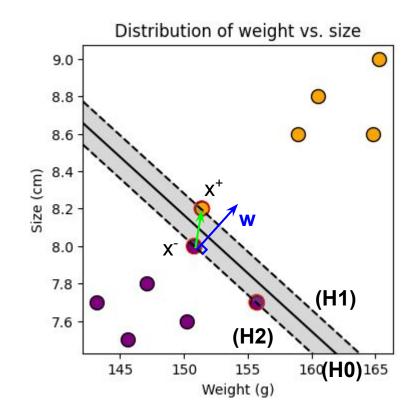
$$\vec{w} \cdot \vec{x^+} + b = +1$$

$$\vec{w} \cdot \vec{x^-} + b = -1$$

$$\Rightarrow \vec{w} \cdot (\vec{x^+} - \vec{x^-}) = 2$$

Thus:

$$\text{maximize} \longrightarrow \text{width} = \frac{2}{||\vec{w}||} \longrightarrow \text{minimize}$$





So the goal is to solve min $||\mathbf{w}||$ under +1/-1 (y_i) constraints:

- Constrained optimization problem



So the goal is to solve min $||\mathbf{w}||$ under +1/-1 (y_i) constraints:

- Constrained optimization problem
- Solved via Lagrange Multiplier:

$$\mathcal{L}(\vec{w},b) = \frac{\vec{w} \cdot \vec{w}}{2} - \sum_i \alpha_i [y_i(\vec{w} \cdot \vec{x_i} + b) - 1]$$
 constraints objective



So the goal is to solve min $||\mathbf{w}||$ under +1/-1 (y_i) constraints:

- Constrained optimization problem
- Solved via Lagrange Multiplier:

$$\mathcal{L}(\vec{w},b) = \frac{\vec{w} \cdot \vec{w}}{2} - \sum_i \alpha_i [y_i(\vec{w} \cdot \vec{x_i} + b) - 1]$$
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$$\frac{\partial \mathcal{L}}{\partial \vec{w}} = 0 \Rightarrow \vec{w} = \sum_i \alpha_i y_i \vec{x_i}$$
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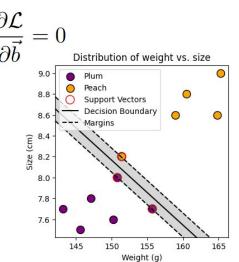
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Very beautiful result !!

- w linear combination of x,
- In practice, a lot of $\alpha_i = 0 \rightarrow$ so most points are useless
- Only points on the frontiers dictate the value of w

→ Support Vectors





The decision rule becomes:

$$|\vec{w} \cdot \vec{x} + b|$$
 $|\vec{w}| = \sum_{i} \alpha_{i} y_{i} \vec{x_{i}} \cdot \vec{x} + b|$

All we need is:

- Optimize α_{i}
- Only requires the dot product



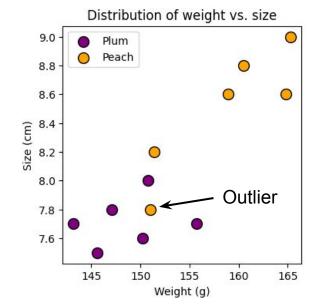
The decision rule becomes:

$$\vec{w} = \sum_{i} \alpha_{i} y_{i} \vec{x_{i}}$$
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What if there are **outliers** in the data?



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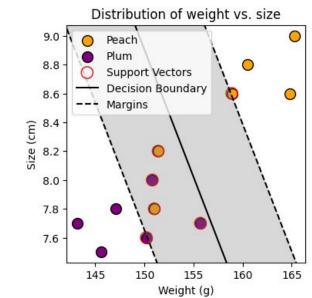
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What if there are **outliers** in the data?

- Soft margin SVM
- Constrained equations: $y_i(\vec{w} \cdot \vec{x_i} + b) \ge 1 \zeta_i$
- L1 regularization: penalizing large values of ζ_{i}
- Optimization function: $\dfrac{ec{w}\cdotec{w}}{2}+\dfrac{C}{\sum_{i}\zeta_{i}}$

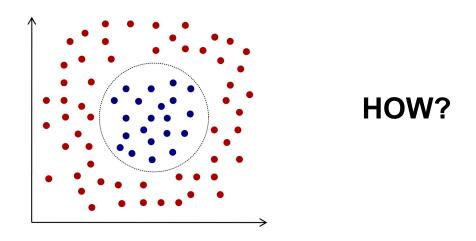




Controlling C → controlling classification error

SVM finds the best **straight** line

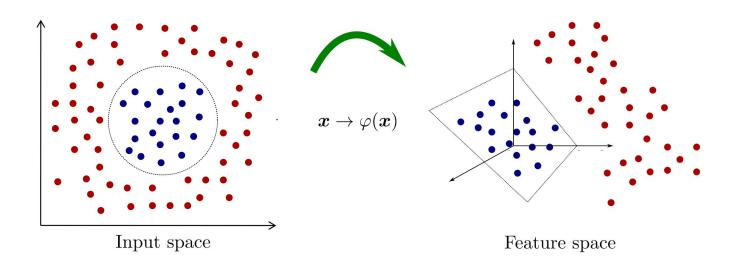
What to do when the data is **non-linearly** separable?





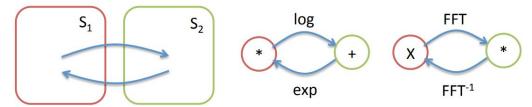
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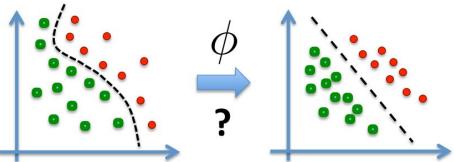




- If the problem is hard in a given space S₁
- It is usual to go to a second space S₂ where it is easier to solve
- And then apply the inverse transformation (from S₂ to S₁)



Same here: if we don't have a straight line in S₁, maybe we have one in S₂





Limitations:

- Dimensionality of Φ can be very large
- High computational costs

Solution:

- No need to compute the transform Φ
- Only need to compute its dot product!
- Kernel trick: $k(x,y) = \phi(x) \cdot \phi(y)$
- New problem formulation:

$$f(\vec{x}) = \sum_{i} \alpha_{i} y_{i} \vec{x_{i}} \cdot \vec{x} + b \Rightarrow f(\vec{x}) = \sum_{i} \alpha_{i} y_{i} \phi(\vec{x_{i}}) \cdot \phi(\vec{x}) + b$$

Solved via SMO algorithm (Sequential Minimal Optimization)



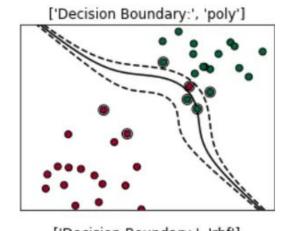
Most used kernel functions:

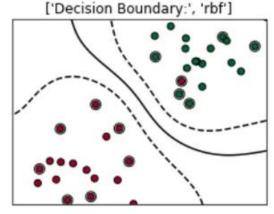
- Polynomial: $K(x,y) = (x^Ty + 1)^d$

- Gaussian: $K(x,y) = \exp(-\psi(x-y)^2)$

- Radial Basis: $K(x,y) = \exp{(rac{-||x-y||^2}{2\sigma^2})}$

- Sigmoid: $K(x,y) = \tanh(kx^Ty - \Theta)$





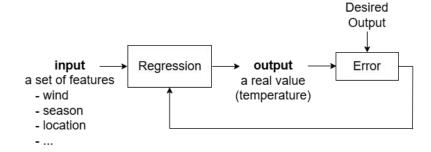


Regression

Regression:

- In classification we aim at predicting a discrete value (label)
- Here we aim at predicting a **real number** from a set of features

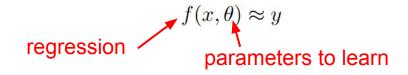






Regression

Objective: Learn a function f that predicts, for each input x, an output $f(x,\theta)$ that is closed to the desired value y



Let's assume a polynomial relationship between input and output:

$$f(x_i, \mathbf{w}) = w_0 + w_1 x_i + w_2 x_i^2 + \ldots + w_M x_i^M = \sum_{m=0}^M w_m x_i^m$$

Objective: find parameter w



Regression

Learning parameters:

- Loss function: quantifies the error between predicted and desired values to minimize

Example: Mean Square Error
$$\mathcal{L}(\boldsymbol{w}) = \frac{1}{N} \sum_{i=1}^{N} (y_i - f(x_i, \theta))^2$$



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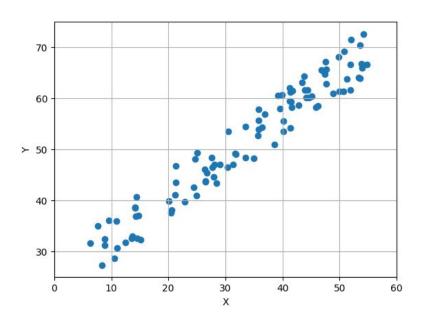
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- Iterative optimization: gradient descent
 - Compute the gradient of the loss function: $\frac{\partial \mathcal{L}}{\partial w_i}(m{w})$
 - Update parameters: $w_i \leftarrow w_i \eta \frac{\partial \mathcal{L}}{\partial w_i}$ | learning rate



Input data: pairs of coordinates (x,y)

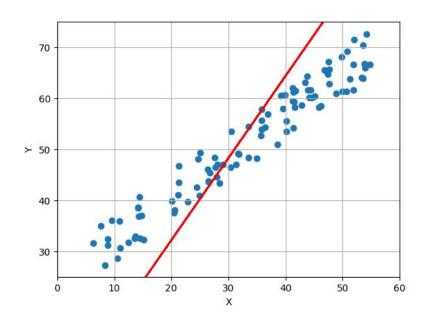
Model: f(x) = ax + b





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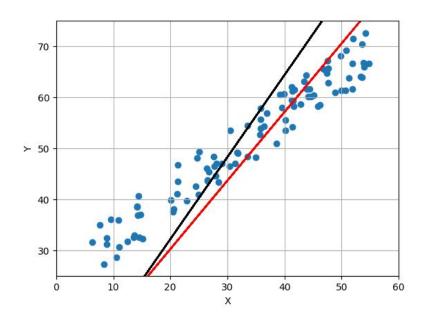
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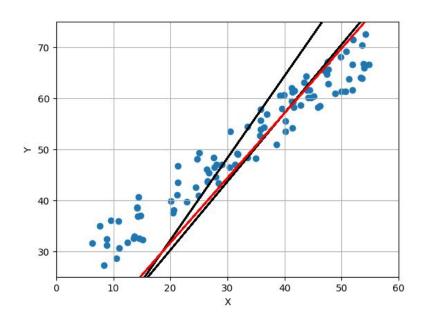
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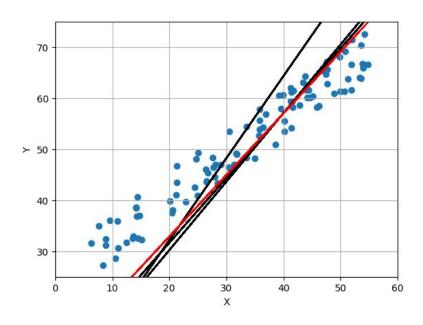
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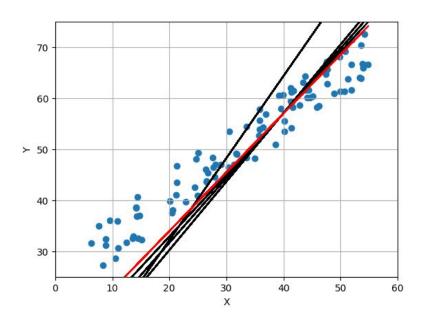
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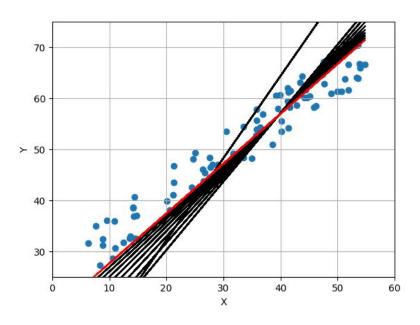
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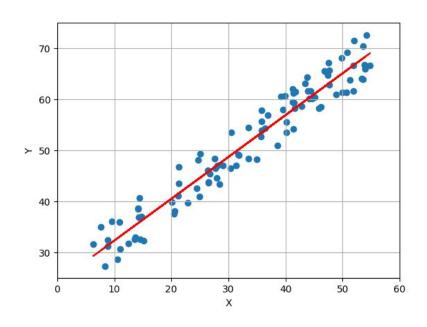
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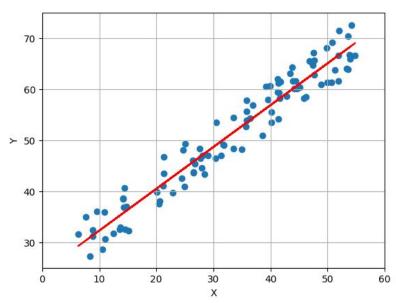




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Model: f(x) = ax + b

Learning: epoch 100



Deep Learning reuse the same methodology but with extremely nonlinear models



Methods

- Unsupervised Learning: K-means clustering, hierarchical clustering
- Supervised Learning: SVM, regression

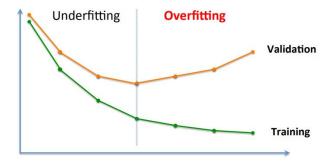


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Generalization and performance evaluation

- All methods are applied on a training set
- How do they perform on unseen data?
- Split dataset into train/dev/test sets to avoid overfitting



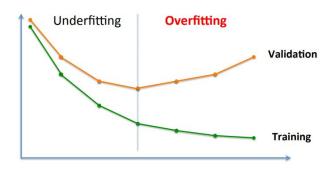


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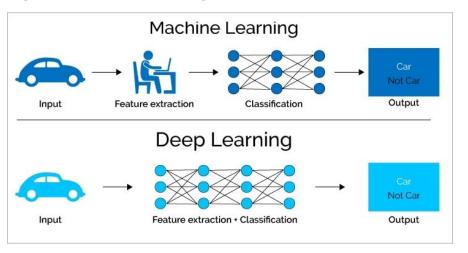


Curse of dimensionality

- We have seen that adding dimensions helps finding a separator
- Yes but overfitting!
- Growing number of features ⇒ amount of data to generalize grows exponentially!
 Maybe PCA? ⊚



From Machine Learning to Deep Learning



Going deeper:

- Apprentissage et Deep Learning (S7,S8)
- Traitement d'images (S8), Intelligence Artificielle (S8)
- Vision Artificielle (S9).



Questions?

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