車輛視覺系統 Tello EDU教學

日期:2019/11/22

設備介紹

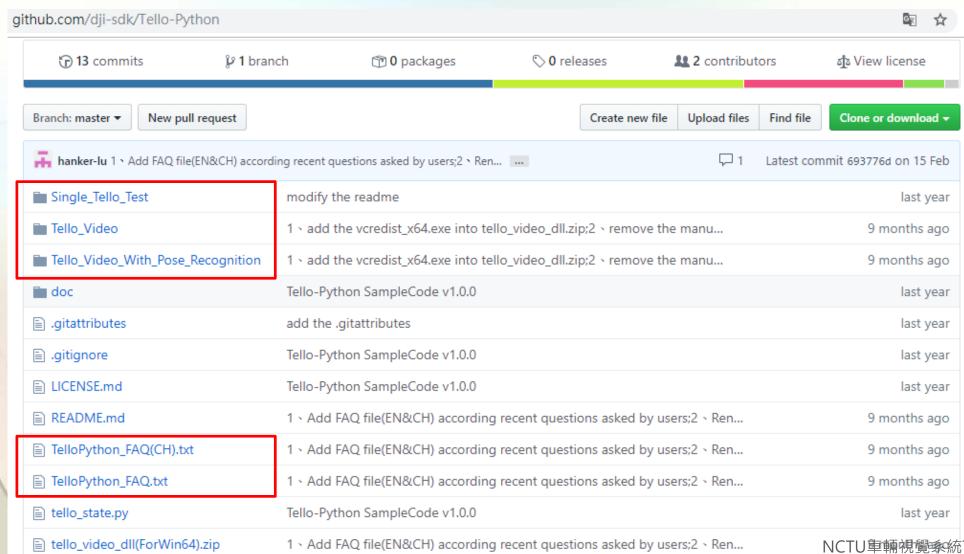
配件		數量
	飛行器	× 1
	螺旋槳 (對)	× 4
A D	獎葉保護罩 (套)	× 1
	電池	× 1
	Micro USB 傳輸線	× 1
O E	螺旋槳拆卸工具	× 1
	挑戰卡	× 4

電池管家



官方範例程式

https://github.com/dji-sdk/Tello-Python



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官方範例程式:Tello-Video

- https://github.com/dji-sdk/Tello-Python/tree/master/Tello_Video
- Written in Python 2.7
- 安裝
- Windows

Go to the "install\Windows" folder,select and run the correct "windows_install.bat" according to your computer

operating system bits.

• Linux (Ubuntu 14.04 and above)

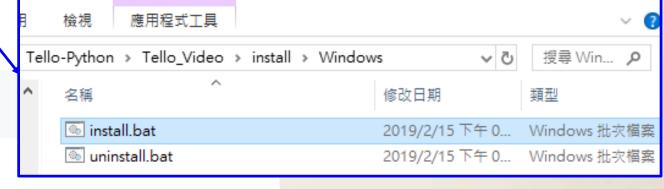
Go to the "install\Linux" folder in command line, run

chmod +x linux_install.sh
./linux_install.sh

Mac

- i. Make sure you have the latest Xcode command line tools installed. If not, you might need to update your OS X and XCode to the latest version in order to compile the h264 decoder module
- ii. Go to the "install\Mac" folder folder in command line, run

chmod a+x ./mac_install.sh
./mac_install.sh

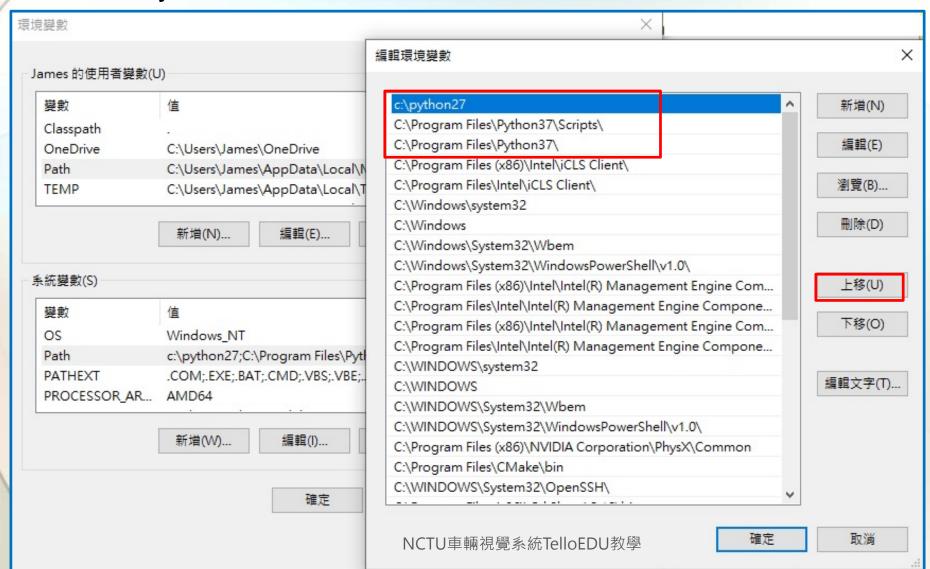


Windows

管理

官方範例程式: Tello-Video

不同版本的Python



官方範例程式:執行 Tello-Video

● 第一步。打開Tello無人機,並透過Wi-Fi將筆電連接到Tello





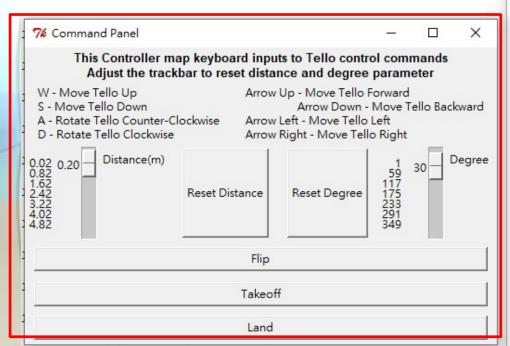
官方範例程式:執行 Tello-Video

• 第二步。在命令列打開程式所在資料夾,並輸入 python main.py



官方範例程式:執行 Tello-Video

• 第三步。將顯示一個使用者界面:





Tello API

```
self.tello.takeoff()
self.tello.land()
self.tello.flip('l')
self.tello.flip('r')
self.tello.flip('f')
self.tello.flip('b')
self.tello.rotate cw(degree)
self.tello.rotate ccw(degree)
self.tello.move forward(distance)
self.tello.move backward(distance)
self.tello.move left(distance)
self.tello.move right(distance)
self.tello.move up(dist)
self.tello.move down(dist)
```

distance和dist的單位為公尺!

所以在測試時,建議distance和 dist的數字不要設超過"1"!

Tello API

透過self.tello.read()可得到單張frame的影像

```
self.frame = self.tello.read()

cv2.imwrite(p, cv2.cvtColor(self.frame, cv2.COLOR RGB2BGR))
```

參考資料

- https://github.com/dji-sdk/Tello-Python
- https://www.esentra.com.tw/product/ryze-tello-edu-drones/
- 助教Email: jamesshiakimo@yahoo.com.tw