

- Remark 8.11.* Using the above notation, note that an order-preserving bijection $\alpha : \pi_0(\mathcal{T}_{1,1}) \rightarrow \pi_0(\mathcal{T}_{2,1})$ automatically induces an order-preserving bijection $\beta : \pi_0(\mathcal{T}_{1,2}) \rightarrow \pi_0(\mathcal{T}_{2,2})$. Moreover, in this paper, we will only be working with intervals between a pair of points, which are usually denoted by (some form of) a, b . We will always take order-preserving to mean as one moves from the a -side to the b -side of the given intervals.

We also set one last bit of notation: Given a stable tree $T = T_e \cup T_c$ for an ϵ -setup $(\mathcal{Y}; \{a, b\})$, if $y \in \mathcal{Y} \cup \{a, b\}$, we let C_y denote the cluster containing y , and $\mu(C_y)$ the corresponding component of T_c .

The following definition contains the stability properties we want:

Definition 8.12 (Stable decomposition). Let Z be δ -hyperbolic and geodesic.

- (1) Given $N, \epsilon > 0$, two ϵ -setups $(a, b; \mathcal{Y})$ and $(a', b'; \mathcal{Y}')$ are (N, ϵ) -admissible if
 - $d_Z(N, a) > 0$, $d_Z(b, b') \leq \epsilon$, and $(a', b'; \mathcal{Y}')$ are (N, ϵ) -admissible if
 - $d_Z(\mathcal{Y}, \mathcal{Y}') \leq \epsilon$, $d_Z(\lambda(a, b)) \leq \epsilon$, $d_Z(\lambda(a', b')) \leq \epsilon$, and $(a', b'; \mathcal{Y}')$ are (N, ϵ) -admissible if
 - $d_Z(\mathcal{Y}, \mathcal{Y}') \leq \epsilon$, $d_Z(\lambda(a, b)) \leq \epsilon$, $d_Z(\lambda(a', b')) \leq \epsilon$, and $(a', b'; \mathcal{Y}')$ are (N, ϵ) -admissible if
- (2) Given an ϵ -setup $(a, b; \mathcal{Y})$, an edge decomposition of its stable interval $T =$
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- (3) Given $L > 0$, $\mathcal{Y}_0 \subset \mathcal{Y}$, and two (N, ϵ) -admissible setups $(a, b; \mathcal{Y})$ and
 - $(a', b'; \mathcal{Y}')$, we say that two edge decompositions $T_s \in \mathcal{T}_\epsilon$ and $T'_s \in \mathcal{T}'_\epsilon$ are \mathcal{Y}_0 -stably L -compatible if
 - $(a', b'; \mathcal{Y}')$, we say that two edge decompositions $T_s \in \mathcal{T}_\epsilon$ and $T'_s \in \mathcal{T}'_\epsilon$ are \mathcal{Y}_0 -stably L -compatible if
- (a) Each component of T_s and T'_s has positive integer length with end-
 - points at vertices of T_s and T'_s respectively.
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- (b) There is an order-preserving bijection $\alpha: \pi_0(T_s) \rightarrow \pi_0(T'_s)$ between
 - the sets of stable components.
 - the sets of stable components.
- (c) For each stable pair (E, E') identified by α , there exists an order-
 - preserving isometry $i_{E, E'}: E \rightarrow E'$ identified by α , there exists an order-
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- (d) For all but at most L pairs of stable components (E, E') , we have
 - $\phi(E) = \phi(E')$ and $\phi(E) = \phi(E')$ for all $x \in E$.
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- (e) For all but at most L pairs of stable components (E, E') , we have
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- (f) For all but at most L pairs of stable components (E, E') , we have
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 - $\phi(E) = \phi(E')$ and $\phi(E) = \phi(E')$ for all $x \in E$.
- (g) The induced order-preserving bijection $\beta: \pi_0(T - T_s) \rightarrow \pi_0(T' - T'_s)$
 - satisfies
 - satisfies
- (i) (Endpoints) Let D_a denote the component of $T - T_s$ containing
 - $\mu(a)$, and define $D_b, D_{a'}, D_{b'}$ similarly. Then $\beta(D_a) = D_{a'}$ and
 - $\mu(a)$, and define $D_b, D_{a'}, D_{b'}$ similarly. Then $\beta(D_a) = D_{a'}$ and
- (ii) (Identifying clusters) For any $y \in \mathcal{Y}_0$, let D_y, D'_y denote the
 - components of $T - T_s$ and $T' - T'_s$ containing $\mu(C_y)$, $\mu(C'_y)$, re-
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Remark 8.13. The above definition is a refinement of the properties contained in [DMS20, Table 1] and [Theorem 3.2], where we have set the properties to be decidable in [DMS20, §1] in the title of the algorithm, where the machinery described stable in the paper. How this process works is described below in more detail in Subsection 9.3.

paper. How we motivate some parts of the definition. Roughly speaking, the points D and D' are not for the relative projection definition. Each interval I has endpoints D and D' . The I is being labeled by some such point D . Eventually, we will collapse each of the components of I labeled D and the sub-intervals eventually (3g) says that the endpoints D and D' are identified and well as the endpoints D and D' and that the rest of the statement now says that the components of I are D and D' and bijective with each other where identifies components are isotopic if I is and the order preserving properties explain how to glue these components to obtain an interval between the endpoints D and D' . Finally, the properties to obtain (3d) and (3e) are necessary for controlling the map back into the properties HHS (see (3d) and (3e) of Theorem 9.9; for more general versions back in the [DMS20] HHS Definition 10.18 of Theorem 9.9. A more general version can be found in [DMS25, Definition 10.18].

8.5. The stable interval theorem. With Definition 8.12 in hand, we can now state the main result of this section, Theorem 8.14 below. It says that the stable intervals, for a pair of admissible setups admit compatible stable decompositions with identified pairs uniformly close, up to ignored a bounded collection of bounded length subintervals. We first state this ignored result, and then prove a corollary which gives the main result for our purposes of building stable cubical models. For a bit of setup, recall the notion of a thickening of an interval from Subsection 4.4. This was a way of taking an interval with a decomposition $T = A \cup B$ into collections of segments, and expanding and combining the collection of the segments. Our stable intervals come with a decomposition $T = T_e \cup T_c$, and we will always mean a thickening of a stable interval T to be a thickening of T along the components of the cluster forest T_c . Finally, we denote the components of the resulting thickening by $T = T_e \cup T_c$, and we note that $T_e \subset T$ and $T_c \subset T$.

Theorem 8.14 (Stable intervals). *Let Z be δ -hyperbolic and geodesic. For any $\epsilon, N > 0$ and positive integers $r_1, r_2 > 0$, there exist $L_1 = L_1(\delta, \epsilon, N) > 0$ and $L_2 = L_2(\delta, \epsilon, N, r_1, r_2) > 0$ so that the following holds. Suppose $(a, b; Y)$ and $(a', b'; Y')$ are (N, ϵ) -admissible ϵ -setups and let $T = T_e \cup T_c$ and $T' = T'_e \cup T'_c$ denote their stable intervals. Then*

- (1) *There exist $(Y \cap Y')$ -stable L_1 -compatible decompositions $T_s \subset T_e$ and $T'_s \subset T'_e$ and*
- (2) *There exist $(Y \cap Y')$ -stable L_2 -compatible edge decompositions $T_s \subset T_e$ and $T'_s \subset T'_e$ of the (r_1, r_2) -thickenings of T, T' along T_c, T'_c .*
 - *Moreover, we have $T_s \subset T$ and $T'_s \subset T'$.*

Remark 8.15: In the HHS setting, we will be able to control each of the constants $\delta, \epsilon, N, r_1, r_2$ in terms of the ambient HHS structure. We have written the statement with two conclusions because the first conclusion is a mild reformulation of the original theorem [DMS20, Theorem 3.2], while the second is what we actually need for the cubulation machine discussed in this paper. Notably, the second statement will be an easy consequence of the first.

Before we move onto the proof, we observe the following corollary, whose statement and proof motivate the statement of Theorem 8.14. In particular, this corollary will allow us to verify the interval-wise condition in Proposition 6.12 and give us the cubical isomorphism we need for the Stable Cubulations Theorem 9.9; see Subsection 9.3.