



$$\begin{array}{cccc} T_U & T_V & T_W & \\ q_V(l_V) = \hat{x}_V & \delta_V^W = \delta_V^U(\delta_U^W) & \delta_W^V = \delta_W^U(\delta_U^V) & q_W(l_W) = \hat{x}_W \end{array}$$