

20 The Laplace Transform

Recommended Problems

P20.1

Consider the signal $x(t) = 3e^{2t}u(t) + 4e^{3t}u(t)$.

- (a) Does the Fourier transform of this signal converge?
- (b) For which of the following values of σ does the Fourier transform of $x(t)e^{-\sigma t}$ converge?
 - (i) $\sigma = 1$
 - (ii) $\sigma = 2.5$
 - (iii) $\sigma = 3.5$
- (c) Determine the Laplace transform $X(s)$ of $x(t)$. Sketch the location of the poles and zeros of $X(s)$ and the ROC.

P20.2

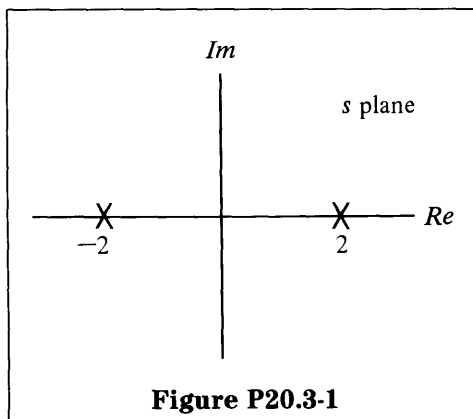
Determine the Laplace transform, pole and zero locations, and associated ROC for each of the following time functions.

- (a) $e^{-at}u(t)$, $a > 0$
- (b) $e^{-at}u(t)$, $a < 0$
- (c) $-e^{-at}u(-t)$, $a < 0$

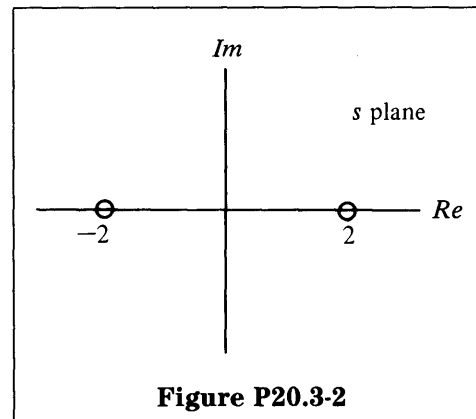
P20.3

Shown in Figures P20.3-1 to P20.3-4 are four pole-zero plots. For each statement in Table P20.3 about the associated time function $x(t)$, fill in the table with the corresponding constraint on the ROC.

(a)



(b)



(c)

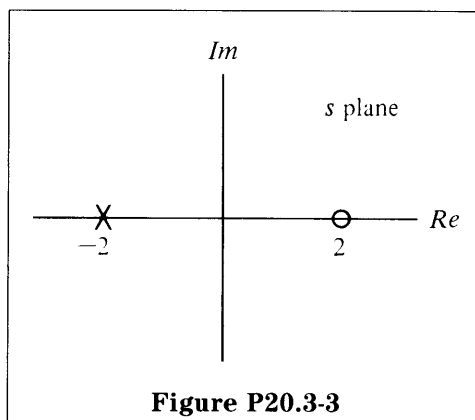


Figure P20.3-3

(d)

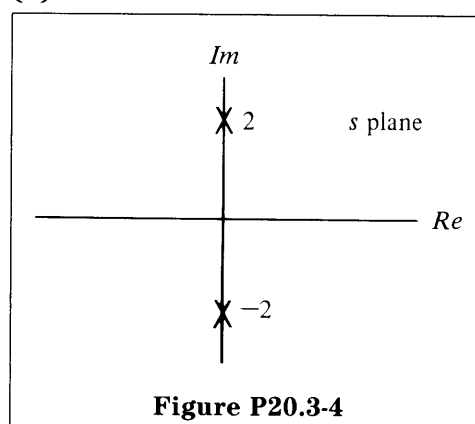


Figure P20.3-4

Constraint on ROC for Pole-Zero Pattern

$x(t)$	(a)	(b)	(c)	(d)
(i) Fourier transform of $x(t)e^{-t}$ converges				
(ii) $x(t) = 0$, $t > 10$				
(iii) $x(t) = 0$, $t < 0$				

Table P20.3

P20.4

Determine $x(t)$ for the following conditions if $X(s)$ is given by

$$X(s) = \frac{1}{(s+1)(s+2)}$$

- (a) $x(t)$ is right-sided
- (b) $x(t)$ is left-sided
- (c) $x(t)$ is two-sided

P20.5

An LTI system has an impulse response $h(t)$ for which the Laplace transform $H(s)$ is

$$H(s) = \int_{-\infty}^{+\infty} h(t)e^{-st}dt = \frac{1}{s+1}, \quad \text{Re}\{s\} > -1$$

Determine the system output $y(t)$ for all t if the input $x(t)$ is given by

$$x(t) = e^{-t/2} + 2e^{-t/3} \quad \text{for all } t.$$

P20.6

- (a) From the expression for the Laplace transform of $x(t)$, derive the fact that the Laplace transform of $x(t)$ is the Fourier transform of $x(t)$ weighted by an exponential.
- (b) Derive the expression for the inverse Laplace transform using the Fourier transform synthesis equation.

Optional Problems

P20.7

Determine the time function $x(t)$ for each Laplace transform $X(s)$.

- (a) $\frac{1}{s+1}$, $\operatorname{Re}\{s\} > -1$
- (b) $\frac{1}{s+1}$, $\operatorname{Re}\{s\} < -1$
- (c) $\frac{s}{s^2+4}$, $\operatorname{Re}\{s\} > 0$
- (d) $\frac{s+1}{s^2+5s+6}$, $\operatorname{Re}\{s\} > -2$
- (e) $\frac{s+1}{s^2+5s+6}$, $\operatorname{Re}\{s\} < -3$
- (f) $\frac{s^2-s+1}{s^2(s-1)}$, $0 < \operatorname{Re}\{s\} < 1$
- (g) $\frac{s^2-s+1}{(s+1)^2}$, $-1 < \operatorname{Re}\{s\}$
- (h) $\frac{s+1}{(s+1)^2+4}$, $\operatorname{Re}\{s\} > -1$

Hint: Use the result from part (c).

P20.8

The Laplace transform $X(s)$ of a signal $x(t)$ has four poles and an unknown number of zeros. $x(t)$ is known to have an impulse at $t = 0$. Determine what information, if any, this provides about the number of zeros.

P20.9

Determine the Laplace transform, pole-zero location, and associated ROC for each of the following time functions.

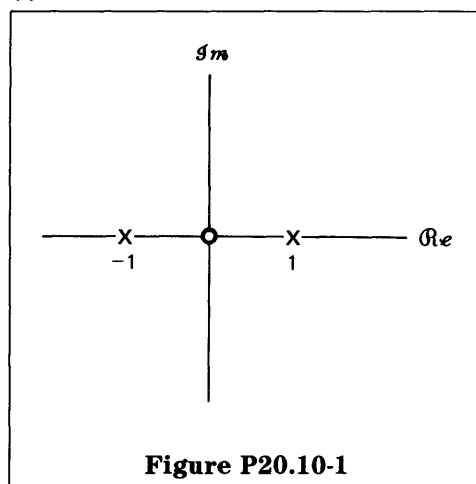
- (a) $e^{-at}u(t)$, $a < 0$
- (b) $-e^{at}u(-t)$, $a > 0$
- (c) $e^{at}u(t)$, $a > 0$
- (d) $e^{-a|t|}$, $a > 0$

- (e) $u(t)$
- (f) $\delta(t - t_0)$
- (g) $\sum_{k=0}^{\infty} a^k \delta(t - kT), \quad a > 0$
- (h) $\cos(\omega_0 t + b)u(t)$
- (i) $\sin(\omega_0 t + b)e^{-at}u(t), \quad a > 0$

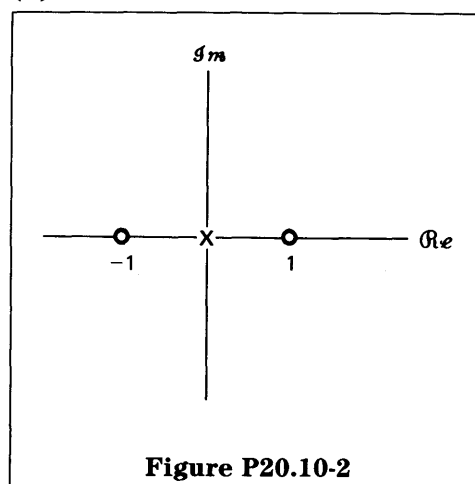
P20.10

- (a) If $x(t)$ is an even time function such that $x(t) = x(-t)$, show that this requires that $X(s) = X(-s)$.
- (b) If $x(t)$ is an odd time function such that $x(t) = -x(-t)$, show that $X(s) = -X(-s)$.
- (c) Determine which, if any, of the pole-zero plots in Figures P20.10-1 to P20.10-4 could correspond to an even time function. For those that could, indicate the required ROC.

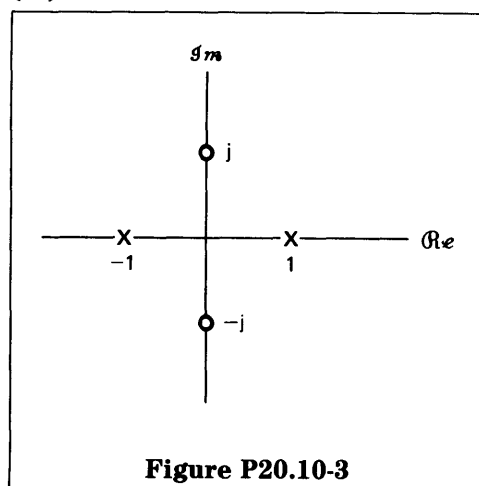
(i)



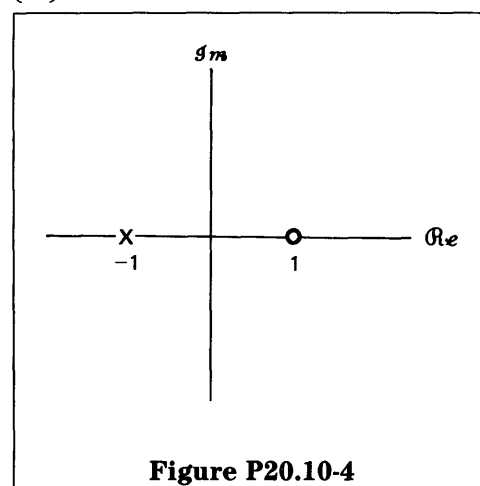
(ii)



(iii)



(iv)



- (d) Determine which, if any, of the pole-zero plots in part (c) could correspond to an odd time function. For those that could, indicate the required ROC.

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