



Bulbasaur's Goals for the Day

- Derive Bernoulli's Solution of the Wave Equation
- · Visualize solutions to the Wave Equation in Matlab
- Practice using formulas to solve PDE word problems

Tension constant
$$a = \sqrt{\frac{T}{R}}$$
 E Tension
 $t = \sqrt{\frac{T}{R}}$ E Tension

$$a = \sqrt{\frac{T}{\rho}}$$

Let
$$u(x,t) = vertical displacement at time t and position x$$



$$u_{tt} = a^2 u_{xx}$$

$$u(0,t)=0$$
, $u(l,t)=0$
(Dirichlet BCs

$$u(l,t)=0$$

$$u(x,0) = f(x)$$

Initial velocity of string
$$\frac{\partial u}{\partial t}(x,0) = g(x) \qquad 0 < x < L$$
If released from rest ("plucking"), $g(x) = 0$.

Assume the solution is separable.

$$u(x, t) = v(x) w(t)$$

Plug this into the PDE.

$$u_{tt} = a^{2} u_{xx}$$

$$(vw)_{tt} = a^{2} (vw)_{xx}$$

$$v w_{tt} = a^{2} v_{xx} w$$

$$\frac{v_{tt}}{a^2 w} = \frac{v_{xx}}{v} = - \sum_{constant}^{separation} Constant$$

3 cases: N is zero, negative, or positive.

$$\frac{w_{tt}}{a^{2}w} = 0$$

$$\frac{w_{tt}}{a^{2}w} = 0$$

$$v_{tt} = 0$$

$$v = C_{1}t + C_{2}$$

$$v = C_{3}x + C_{4}$$

$$v = (C_{1}t + C_{2})(C_{3}x + C_{4})$$

$$v = D_{1}tx + D_{2}x + D_{3}t + D_{4}$$

$$\frac{BC}{a(0,t)} = 0 = D_{3}t + D_{4} = 0 \Rightarrow D_{3} = D_{4} = 0$$

$$v(L_{1}t) = 0 = D_{1}tL + D_{2}L = 0 \Rightarrow D_{1} = D_{2} = 0$$

$$\Rightarrow v = 0 = 0$$

$$= 0 = 0$$

$$= 0 = 0$$

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$$= 0 = 0$$

$$\frac{1}{a^{2}} = -\alpha^{2}$$

$$\frac{w_{tt}}{a^{2}} = \alpha^{2}$$

$$w_{tt} = \alpha^{2} \alpha^{2} w$$

$$w_{tt} - \alpha^{2} \alpha^{2} w = 0$$

$$v^{2} - \alpha^{2} \alpha^{2} = 0$$

$$v^{2} = \alpha^{2} \alpha^{2}$$

$$v = -\alpha^{2} \alpha^{2}$$

$$v = -\alpha^{2} \alpha^{2} + -\alpha^{2} \alpha^{2}$$

$$v = -\alpha^{2} \alpha^{2} + -\alpha^{2} \alpha^{2}$$

$$v = -\alpha^{2} \alpha^{2} + -\alpha^{2} \alpha^{2}$$

$$\frac{\sqrt{xx}}{\sqrt{x}} = x^{2}$$

$$\sqrt{xx} = x^{2}$$

$$\sqrt{xx} - x^{2} = 0$$

$$\sqrt{x} -$$

$$N = VW = \left(C_1 e^{\alpha at} + C_2 e^{-\alpha at}\right) \left(C_3 e^{\alpha x} + C_4 e^{-\alpha x}\right)$$

$$= D_1 e^{\alpha at + \alpha x} + D_2 e^{\alpha at - \alpha x} + D_3 e^{-\alpha at + \alpha x} + D_4 e^{-\alpha at \alpha x}$$

$$= D_1 e^{\alpha at} + D_2 e^{\alpha at} + D_3 e^{-\alpha at} + D_4 e^{-\alpha at}$$

$$= \left(D_1 + D_2\right) e^{\alpha at} + \left(D_3 + D_4\right) e^{-\alpha at}$$

$$\Rightarrow D_1 + D_2 = 0 \quad \text{and} \quad D_3 + D_4 = 0$$

$$D_1 = -D_2 \qquad D_3 = -D_4$$

$$U(L,t) = 0 = D_1 e^{\alpha at + \alpha L} + D_2 e^{\alpha at - \alpha L} + D_3 e^{-\alpha at + \alpha L} + e^{-\alpha at - \alpha L}$$

$$0 = D_2 \left(-e^{\alpha at + \alpha L} + e^{\alpha at - \alpha L} \right) + D_4 \left(-e^{\alpha at + \alpha L} + e^{-\alpha at - \alpha L} \right)$$

$$D_2 = D_4 = 0 \quad \Rightarrow \quad D_1 = D_3 = 0$$

$$\Rightarrow u = 0 \quad \text{Trivial}$$

$$\frac{v_{xx}}{a^2 w} = -\alpha^2$$

$$\frac{v_{xx}}{a^2 w} = -\alpha^2$$

$$u(l_1t) = 0 = D_1e^{\alpha at+\alpha l} + D_2e^{\alpha at-\alpha l} + D_3e^{-\alpha at+\alpha l} - \frac{\alpha at+\alpha l}{p_1} - \frac{\alpha at+\alpha l}{p_2}$$

$$0 = D_2\left(-e^{\alpha at+\alpha l} + e^{-\alpha at-\alpha l}\right) + D_2\left(-e^{\alpha at+\alpha l} + e^{-\alpha at+\alpha l}\right)$$

$$D_1 = D_2 = D_2 = 0$$

$$D_2 = D_2 = 0$$

$$D_3 = -D_2$$

$$D_4 = D_3 = 0$$

$$D_4 = D_4 =$$

$$r^{2} = -\alpha^{2}\alpha^{2}$$

$$r = \pm \alpha \alpha i$$

$$w = C_{1}\cos(\alpha at) + C_{2}\sin(\alpha at)$$

$$v = C_{3}\cos(\alpha x) + C_{4}\sin(\alpha x)$$

$$u = wv = \left[C_{1}\cos(\alpha at) + C_{2}\sin(\alpha at)\right]\left[C_{3}\cos(\alpha x) + C_{4}\sin(\alpha x)\right]$$

$$\frac{BCS}{S}u(0,t) = O = \left[C_{1}\cos(\alpha at) + C_{2}\sin(\alpha at)\right]\left[C_{3}\right]$$

$$\Rightarrow C_{3} = O$$

$$u = \left[C_{1}\cos(\alpha at) + C_{2}\sin(\alpha at)\right]\left[C_{4}\sin(\alpha x)\right]$$

$$BCSu(L_{1}t) = O = \left[C_{1}\cos(\alpha at) + C_{2}\sin(\alpha at)\right]\left[C_{4}\sin(\alpha x)\right]$$

$$C_{4}\sin(\alpha L) = O$$

$$c_{4}\sin(\alpha L) = O$$

$$c_{5}\sin(\alpha L) = O$$

$$c_{6}\cos(\alpha L_{1}t) = O$$

$$c_{7}\sin(\alpha L_{2}t) = O$$

$$c_{8}\cos(\alpha L_{1}t) = O$$

$$c_{1}\cos(\alpha L_{2}t) = O$$

$$c_{1}\cos(\alpha L_{1}t) = O$$

$$c_{2}\sin(\alpha L_{2}t) = O$$

$$c_{3}\sin(\alpha L_{2}t) = O$$

$$c_{4}\sin(\alpha L_{1}t) = O$$

$$c_{5}\sin(\alpha L_{2}t) = O$$

$$c_{7}\sin(\alpha L_{2}t) = O$$

$$c_{8}\cos(\alpha L_{1}t) = O$$

$$c_{1}\sin(\alpha L_{2}t) = O$$

$$c_{2}\cos(\alpha L_{1}t) = O$$

$$c_{3}\sin(\alpha L_{2}t) = O$$

$$c_{4}\sin(\alpha L_{1}t) = O$$

$$c_{5}\sin(\alpha L_{2}t) = O$$

$$c_{7}\sin(\alpha L_{2}t) = O$$

$$c_{8}\cos(\alpha L_{1}t) = O$$

$$c_{1}\sin(\alpha L_{2}t) = O$$

$$c_{2}\cos(\alpha L_{1}t) = O$$

$$c_{3}\cos(\alpha L_{1}t) = O$$

$$c_{4}\sin(\alpha L_{1}t) = O$$

$$c_{5}\sin(\alpha L_{1}t) = O$$

$$c_{7}\sin(\alpha L_{2}t) = O$$

$$c_{8}\cos(\alpha L_{1}t) = O$$

$$c_{1}\sin(\alpha L_{1}t) = O$$

$$c_{1}\sin(\alpha L_{1}t) = O$$

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$$c_{4}\sin(\alpha L_{1}t) = O$$

$$c_{5}\cos(\alpha L_{1}t) = O$$

$$c_{7}\cos(\alpha L_{1}t) = O$$

$$c_{8}\cos(\alpha L_{1}t) = O$$

$$c_{1}\sin(\alpha L_{1}t) = O$$

$$c_{2}\cos(\alpha L_{1}t) = O$$

$$c_{1}\cos(\alpha L_{1}t) = O$$

$$c_{2}\cos(\alpha L_{1}t) = O$$

$$c_{3}\cos(\alpha L_{1}t) = O$$

$$c_{4}\cos(\alpha L_{1}t) = O$$

$$c_{1}\cos(\alpha L_{1}t) = O$$

$$c_{2}\cos(\alpha L_{1}t) = O$$

$$c_{3}\cos(\alpha L_{1}t) = O$$

$$c_{4}\cos(\alpha L_{1}t) = O$$

$$c_{5}\cos(\alpha L_{1}t) = O$$

$$c_{5}\cos(\alpha L_{1}t) = O$$

$$c_{6}\cos(\alpha L_{1}t) = O$$

$$c_{7}\cos(\alpha L_{1}t) = O$$

$$c_{7}\cos$$

$$\alpha = \frac{\Lambda^{\pi}}{L}$$

$$u_n = \left[C_1 \cos(\alpha a t) + C_2 \sin(\alpha a t) \right] \left[C_4 \sin(\alpha x) \right]$$

$$= A_{n} \cos\left(\frac{n\pi at}{L}\right) \sin\left(\frac{n\pi x}{L}\right) + B_{n} \sin\left(\frac{n\pi at}{L}\right) \sin\left(\frac{n\pi x}{L}\right)$$

$$N = \sum_{n=1}^{\infty} N_n$$

$$U = \sum_{n=1}^{\infty} \left(A_n \cos\left(\frac{n\pi\alpha t}{L}\right) \sin\left(\frac{n\pi x}{L}\right) + \beta_n \sin\left(\frac{n\pi\alpha t}{L}\right) \sin\left(\frac{n\pi x}{L}\right) \right)$$

$$\frac{IC}{u(x,0)} = f(x) \qquad \text{Initial shape at time } t=0$$

$$u(x,0) = \sum_{n=1}^{\infty} A_n \sin\left(\frac{n\pi x}{L}\right) = f(x) \quad \text{on} \quad (0,L)$$

$$fourier \quad \text{Sine} \quad \text{Series},$$

$$A_n = \frac{2}{L} \int_0^L f(x) \sin\left(\frac{n\pi x}{L}\right) dx$$

$$\frac{TC}{\partial t} \left(x, 0 \right) = g(x) \qquad \text{Initial velocity at time t-} 0$$

$$u = \sum_{n=1}^{\infty} \left[A_n \cos\left(\frac{n\pi at}{L}\right) \sin\left(\frac{n\pi x}{L}\right) + B_n \sin\left(\frac{n\pi at}{L}\right) \sin\left(\frac{n\pi x}{L}\right) \right]$$

$$\frac{\partial u}{\partial t} = \sum_{n=1}^{\infty} \left[-A_n \frac{n\pi a}{L} \sin\left(\frac{n\pi at}{L}\right) \sin\left(\frac{n\pi x}{L}\right) + B_n \frac{n\pi a}{L} \cos\left(\frac{n\pi at}{L}\right) \sin\left(\frac{n\pi x}{L}\right) \right]$$

$$\frac{\partial u}{\partial t} (x, 0) = \sum_{n=1}^{\infty} B_n \frac{n\pi a}{L} \sin\left(\frac{n\pi x}{L}\right) = g(x)$$

$$Fourier \quad \text{Sine Series} \quad \text{with an extra constant $\frac{n\pi a}{L}$}$$

$$B_n = \frac{L}{n\pi a} \quad \frac{2}{L} \int_0^L g(x) \sin\left(\frac{n\pi x}{L}\right) dx$$

$$= \frac{2}{n\pi a} \int_0^L g(x) \sin\left(\frac{n\pi x}{L}\right) dx$$

Bernoulli's Solution of the Wave Equation

$$u_{tt} = a^{2}u_{xx}$$

$$u(0,t) = 0, \quad u(L,t) = 0$$

$$u(x,0) = f(x)$$

$$\frac{\partial u}{\partial t}(x,0) = g(x)$$

$$u(x,t) = \sum_{n=1}^{\infty} \left(A_{n}\cos(\frac{n\pi at}{L}) + \beta_{n}\sin(\frac{n\pi at}{L})\right)\sin(\frac{n\pi x}{L})$$

$$A_{n} = \frac{2}{L}\int_{0}^{L} f(x)\sin(\frac{n\pi x}{L}) dx$$

$$\beta_{n} = \frac{2}{n\pi a}\int_{0}^{L} g(x)\sin(\frac{n\pi x}{L}) dx$$