THE CITADEL THE MILITARY COLLEGE OF SOUTH CAROLINA

Department of Electrical and Computer Engineering

ELEC 318 Electromagnetic Fields

Exam #1 equation sheets

$$\mathbf{A} = |\mathbf{A}| = \sqrt{A_x^2 + A_y^2 + A_z^2}$$

$$\mathbf{a} = \mathbf{A}/|\mathbf{A}| = \mathbf{A}/A$$

$$\mathbf{r}_{PQ} = (x_2 - x_1)\hat{\mathbf{x}} + (y_2 - y_1)\hat{\mathbf{y}} + (y_2 - y_1)\hat{\mathbf{z}}$$

$$\mathbf{A} \cdot \mathbf{B} = \begin{cases} |\mathbf{A}||\mathbf{B}|\cos\theta = \frac{(A_xB_x) + (A_yB_y)}{AB\cos\theta} = \frac{(A_xB_x) + (A_yB_y)}{AB\sin\theta} \\ + (A_zB_z) \end{cases}$$

$$\mathbf{A} \times \mathbf{B} = \begin{cases} |\mathbf{A}||\mathbf{B}|\sin\theta \hat{\mathbf{n}} \\ AB\sin\theta \hat{\mathbf{n}} \end{cases} = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

$$x = r\cos\phi, \ y = r\sin\phi, \ z = z$$

$$\hat{\mathbf{x}} = \cos\phi \,\hat{\mathbf{r}} - \sin\phi \,\hat{\boldsymbol{\phi}} \qquad \hat{\mathbf{z}} = \hat{\mathbf{z}}$$

$$\hat{\mathbf{y}} = \sin\phi \,\hat{\mathbf{r}} + \cos\phi \,\hat{\boldsymbol{\phi}} \qquad \hat{\mathbf{z}} = \hat{\mathbf{z}}$$

$$\hat{\mathbf{y}} = \sin\phi \,\hat{\mathbf{r}} + \cos\phi \,\hat{\boldsymbol{\phi}} \qquad \hat{\mathbf{y}}$$

$$x = R \sin \theta \cos \phi, \quad z = R \cos \theta$$

$$y = R \sin \theta \sin \phi$$

$$\hat{\mathbf{x}} = \sin \theta \cos \phi \, \hat{\mathbf{R}} + \cos \theta \cos \phi \, \hat{\mathbf{\theta}} - \sin \phi \, \hat{\mathbf{\phi}}$$

$$\hat{\mathbf{x}} = \sin \theta \cos \phi \, \hat{\mathbf{R}} + \cos \theta \cos \phi \, \hat{\mathbf{\theta}} - \sin \phi \, \hat{\mathbf{\phi}}$$

$$\hat{\mathbf{x}} = \sin \theta \cos \phi \, \hat{\mathbf{x}} + \sin \theta \sin \phi \, \hat{\mathbf{y}} + \cos \theta \, \hat{\mathbf{z}}$$

$$\hat{\mathbf{y}} = \sin \theta \sin \phi \, \hat{\mathbf{R}} + \cos \theta \sin \phi \, \hat{\mathbf{\theta}} + \cos \phi \, \hat{\mathbf{\phi}}$$

$$\hat{\mathbf{\theta}} = \cos \theta \cos \phi \, \hat{\mathbf{x}} + \cos \theta \sin \phi \, \hat{\mathbf{y}} - \sin \theta \, \hat{\mathbf{z}}$$

$$\hat{\mathbf{z}} = \cos \theta \, \hat{\mathbf{R}} - \sin \theta \, \hat{\mathbf{\theta}}$$

$$\hat{\mathbf{\phi}} = -\sin \phi \, \hat{\mathbf{x}} + \cos \phi \, \hat{\mathbf{y}}$$

$$d\mathbf{l} = dx \,\hat{\mathbf{x}} + dy \,\hat{\mathbf{y}} + dz \,\hat{\mathbf{z}}$$

$$d\mathbf{l} = dr \,\hat{\mathbf{r}} + r \,d\phi \,\hat{\boldsymbol{\phi}} + dz \,\hat{\mathbf{z}}$$

$$d\mathbf{S} = dy \,dz \,\hat{\mathbf{x}}$$

$$d\mathbf{S} = r \,d\phi \,dz \,\hat{\mathbf{r}}$$

$$d\mathbf{S} = dz \,dx \,\hat{\mathbf{y}}$$

$$d\mathbf{S} = dr \,dz \,\hat{\boldsymbol{\phi}}$$

$$d\mathbf{S} = R \sin \theta \,dR \,d\phi \,\hat{\boldsymbol{\theta}}$$

$$d\mathbf{S} = R \sin \theta \,dR \,d\phi \,\hat{\boldsymbol{\theta}}$$

$$d\mathbf{S} = R \,dR \,d\theta \,\hat{\boldsymbol{\phi}}$$

$$d\mathbf{S} = R \,dR \,d\theta \,d\phi$$

$$\nabla V = \frac{\partial V}{\partial x}\hat{\mathbf{x}} + \frac{\partial V}{\partial y}\hat{\mathbf{y}} + \frac{\partial V}{\partial z}\hat{\mathbf{z}} = \frac{\partial V}{\partial r}\hat{\mathbf{r}} + \frac{1}{r}\frac{\partial V}{\partial \phi}\hat{\boldsymbol{\phi}} + \frac{\partial V}{\partial z}\hat{\mathbf{z}}$$
$$= \frac{\partial V}{\partial R}\hat{\mathbf{R}} + \frac{1}{R}\frac{\partial V}{\partial \theta}\hat{\boldsymbol{\theta}} + \frac{1}{R\sin\theta}\frac{\partial V}{\partial \phi}\hat{\boldsymbol{\phi}}$$

$$\nabla \cdot \mathbf{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z} = \frac{1}{r} \frac{\partial}{\partial r} (rA_r) + \frac{1}{r} \frac{\partial}{\partial \phi} A_\phi + \frac{\partial}{\partial z} A_z$$
$$= \frac{1}{R^2} \frac{\partial}{\partial R} (R^2 A_R) + \frac{1}{R \sin \theta} \frac{\partial}{\partial \theta} (A_\theta \sin \theta) + \frac{1}{R \sin \theta} \frac{\partial}{\partial \phi} A_\phi$$

$$\nabla \times \mathbf{A} = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix} = \begin{vmatrix} \hat{\mathbf{r}} & r \hat{\boldsymbol{\phi}} & \hat{\mathbf{z}} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ A_r & rA_{\phi} & A_z \end{vmatrix} = \begin{vmatrix} \mathbf{\hat{R}} & R \hat{\boldsymbol{\theta}} & R \sin \theta \hat{\boldsymbol{\phi}} \\ \frac{\partial}{\partial R} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ A_R & RA_{\theta} & R \sin \theta A_{\phi} \end{vmatrix}$$

$$\oint_{S} \mathbf{A} \cdot d\mathbf{S} = \int_{V} \nabla \cdot \mathbf{A} \ dV$$

$$\oint_{S} \mathbf{A} \cdot d\mathbf{S} = \int_{S} \nabla \cdot \mathbf{A} \, dv \qquad \qquad \oint_{T} \mathbf{A} \cdot d\mathbf{I} = \int_{S} (\nabla \times \mathbf{A}) \cdot d\mathbf{S}$$

$$d\mathbf{S} = dS \,\hat{\mathbf{n}}$$

$$d\mathbf{S} = dS \,\,\hat{\mathbf{n}} \qquad \qquad \Psi = \int_{S} \mathbf{A} \cdot d\mathbf{S}$$

$$\mathbf{F} = \frac{q_1 q_2}{4\pi\varepsilon_0} \cdot \frac{\mathbf{R} - \mathbf{R}'}{\left|\mathbf{R} - \mathbf{R}'\right|^3}$$

$$d\mathbf{E} = \frac{dq}{4\pi\varepsilon_0} \cdot \frac{\mathbf{R} - \mathbf{R}'}{\left|\mathbf{R} - \mathbf{R}'\right|^3}$$

$$\mathbf{E} = \frac{\mathbf{F}}{q}$$

$$\mathbf{F} = \frac{q_1 q_2}{4\pi\varepsilon_0} \cdot \frac{\mathbf{R} - \mathbf{R}'}{|\mathbf{R} - \mathbf{R}'|^3} \qquad d\mathbf{E} = \frac{dq}{4\pi\varepsilon_0} \cdot \frac{\mathbf{R} - \mathbf{R}'}{|\mathbf{R} - \mathbf{R}'|^3} \qquad \mathbf{E} = \frac{\mathbf{F}}{q} \qquad \mathbf{E} = \sum_{k=1}^{N} \frac{q_k}{4\pi\varepsilon_0} \cdot \frac{\mathbf{R} - \mathbf{R}'_k}{|\mathbf{R} - \mathbf{R}'_k|^3}$$

$$\mathbf{E} = \frac{q}{4\pi\varepsilon_0} \cdot \frac{\mathbf{R} - \mathbf{R'}}{\left|\mathbf{R} - \mathbf{R'}\right|^3}$$

$$dq = \rho_l dl$$

$$dq = \rho_s dS \qquad dq = \rho_v dv$$

$$\mathbf{E} = \frac{1}{4\pi\varepsilon_0} \int dq \, \frac{\mathbf{R} - \mathbf{R}'}{\left| \mathbf{R} - \mathbf{R}' \right|^3}$$

$$\mathbf{D} = \varepsilon \mathbf{E}$$

$$Q = \oint_{S} \mathbf{D} \cdot d\mathbf{S}$$

$$V_{AB} = \frac{W}{a} = -\int_A^B \mathbf{E} \cdot d\mathbf{l}$$

$$Q = \int \rho_l dl$$

$$\nabla \cdot \mathbf{D} = \rho_{v}$$

$$\oint_L \mathbf{E} \cdot d\mathbf{l} = 0$$

$$V_{
m charge}^{
m point} \, = \, rac{q}{4\piarepsilon_0 \left| {f R} - {f R}'
ight|}$$

$$Q = \iint \rho_s dS$$

$$\mathbf{E} = -\nabla V$$

$$\nabla \times \mathbf{E} = 0$$

$$dV = \frac{dq}{4\pi\varepsilon_0 |\mathbf{R} - \mathbf{R'}|}$$

$$Q = \iiint \rho_{v} dv$$

$$\mathbf{E}_{\text{charge}}^{\text{point}} = \frac{q}{4\pi\varepsilon_0 r^2} \hat{\mathbf{R}}$$

$$\mathbf{E}_{\text{dipole}} \approx \frac{q \cdot d \cdot \cos \theta}{2\pi\varepsilon_0 r^3} \hat{\mathbf{r}} + \frac{q \cdot d \cdot \sin \theta}{4\pi\varepsilon_0 r^3} \hat{\mathbf{\theta}}$$

$$\mathbf{E}_{\text{line charge}}^{\text{infinite}} = \frac{\rho_l}{2\pi\varepsilon_0 r} \,\hat{\mathbf{r}}$$

$$W_E = \frac{1}{2} \sum_{k=1}^{N} q_k V_k$$

$$W_E = \frac{1}{2} \int_{\mathcal{V}} \varepsilon_0 |\mathbf{E}|^2 dv$$

$$\mathbf{E}_{\text{surf charge}}^{\text{infinite}} = \frac{\rho_s}{2\varepsilon_0} \hat{\mathbf{n}}$$