

Input/Output Ports and Interfacing

ELEC 330

Digital Systems Engineering

Dr. Ron Hayne

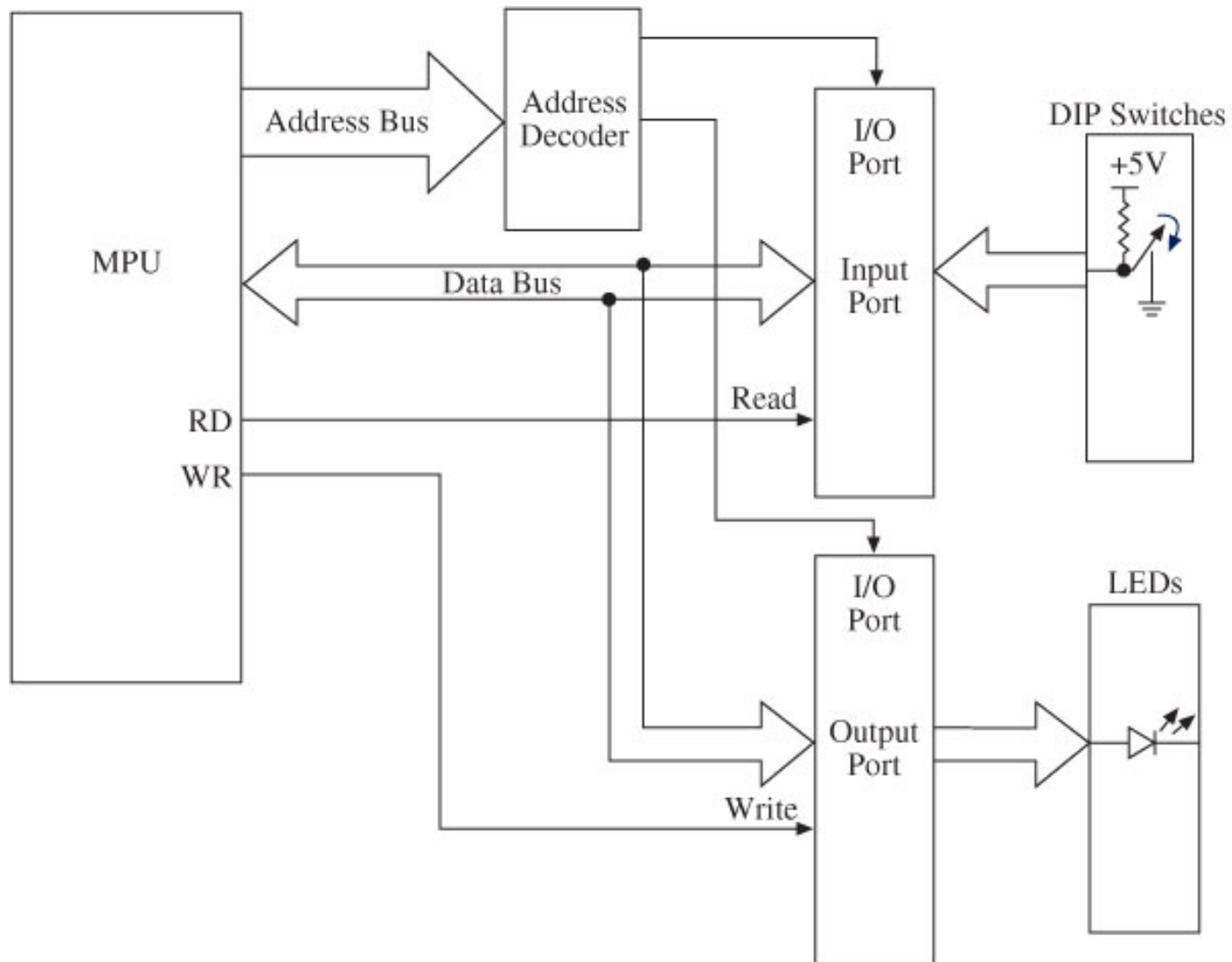
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Basic I/O Concepts

- ◆ Peripherals such as LEDs and keypads are essential components of microcontroller-based systems
- ◆ Input devices
 - Provide digital information to an MPU
 - Examples: switch, keyboard, scanner, and digital camera
- ◆ Output devices
 - Receive digital information from an MPU
 - Examples: LED, seven-segment display, LCD, and printer
- ◆ Devices are interfaced to an MPU using I/O ports

I/O Interfacing



Interfacing and Addressing

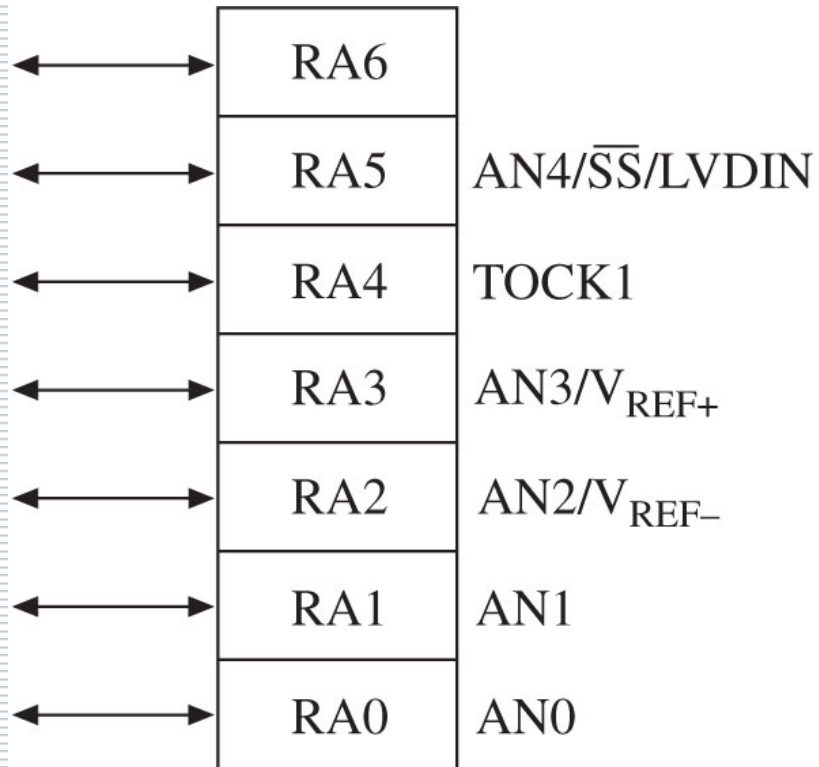
◆ I/O ports

- Buffers and latches on the MCU chip
 - Assigned binary addresses by decoding the address bus
- Generally bidirectional
 - Internal data direction registers
- To read binary data from an input peripheral
 - MPU places the address of an input port on the address bus
 - Enables the input port by asserting the RD signal
 - Reads data using the data bus
- To write binary data to an output peripheral
 - MPU places the address of an output port on the address bus
 - Places data on data bus
 - Asserts the WR signal to enable the output port

PIC18F452/4520 I/O Ports

- ◆ MCU includes five I/O ports
 - PORTA, PORTB, PORTC, PORTD, PORTE
- ◆ Ports are multiplexed
 - Can be set up to perform various functions
- ◆ Each I/O port is associated with several SFRs
 - PORT
 - Functions as a latch or a buffer
 - TRIS
 - Data direction register
 - Logic 0 sets up the pin as an output
 - Logic 1 sets up the pin as an input
 - LAT
 - Output latch similar to PORT

PIC18F452/4520 I/O Ports

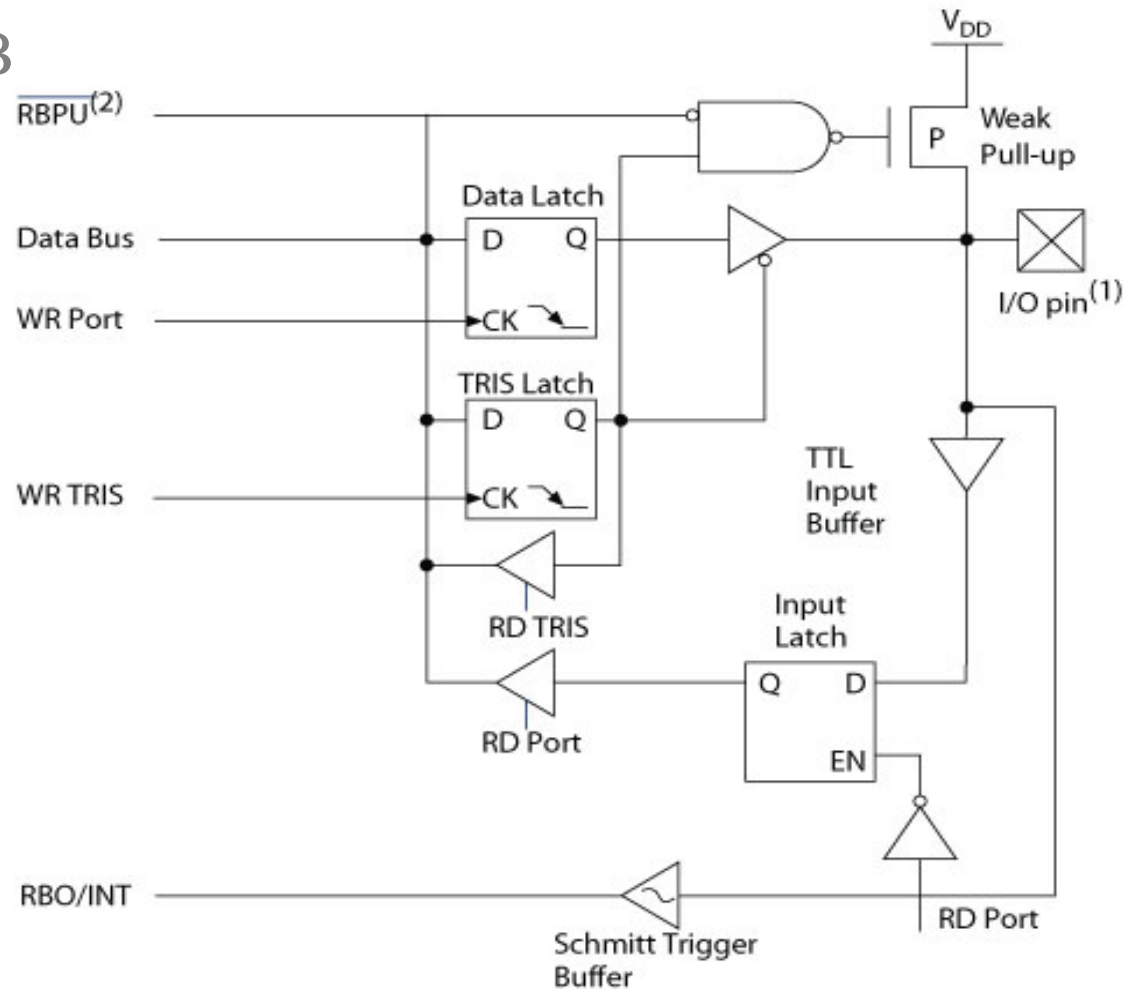


PORTA: Example of Multiple Fns

- ◆ Digital I/O: RA6-RA0
- ◆ Analog Input: AN0-AN4
- ◆ V_{REF+} : A/D Reference Plus V
- ◆ V_{REF-} : A/D Reference Minus V
- ◆ TOCK1: Timer0 Ext. Clock
- ◆ SS: SPI Slave Select Input
- ◆ LVDIN: Low V Detect Input

PIC18F452/4520 I/O Ports

◆ PORTB



Note 1: I/O pins have diode protection to V_{DD} and V_{SS} .

Note 2: To enable weak pull-ups, set the appropriate TRIS bit(s) and clear the \overline{RBPU} bit (Option_REG<7>).

I/O Example

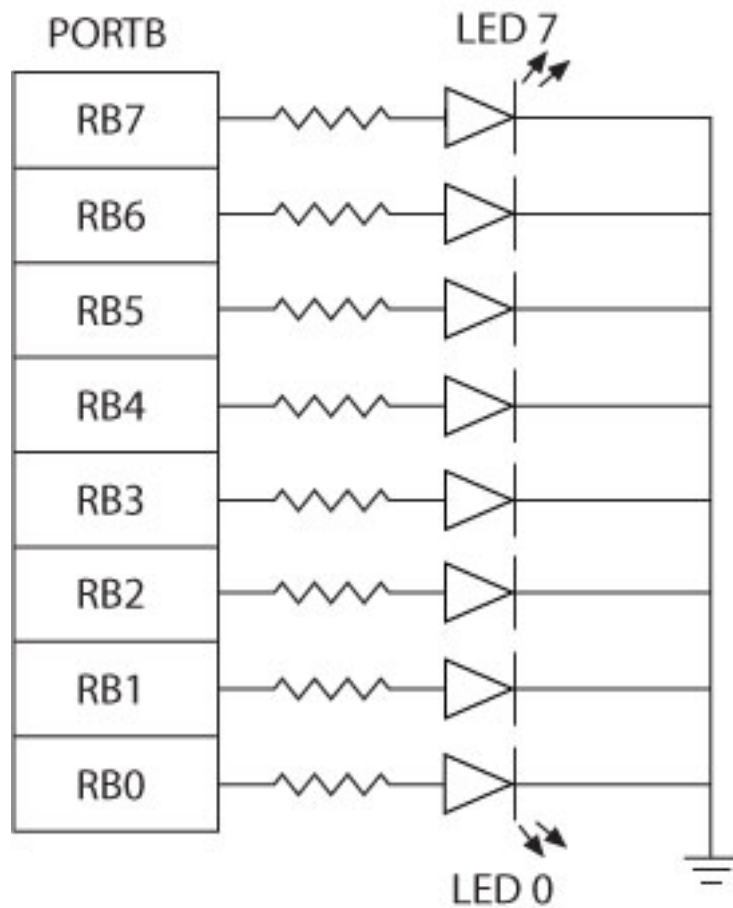
- ◆ Write instructions to set up pins RB7-RB4 of PORTB as inputs and pins RB3-RB0 as outputs

Opcode	Operands	Comments
MOVLW	0xF0	;Load B'11110000' into WREG
MOVWF	TRISB	;Set PORTB TRIS Reg

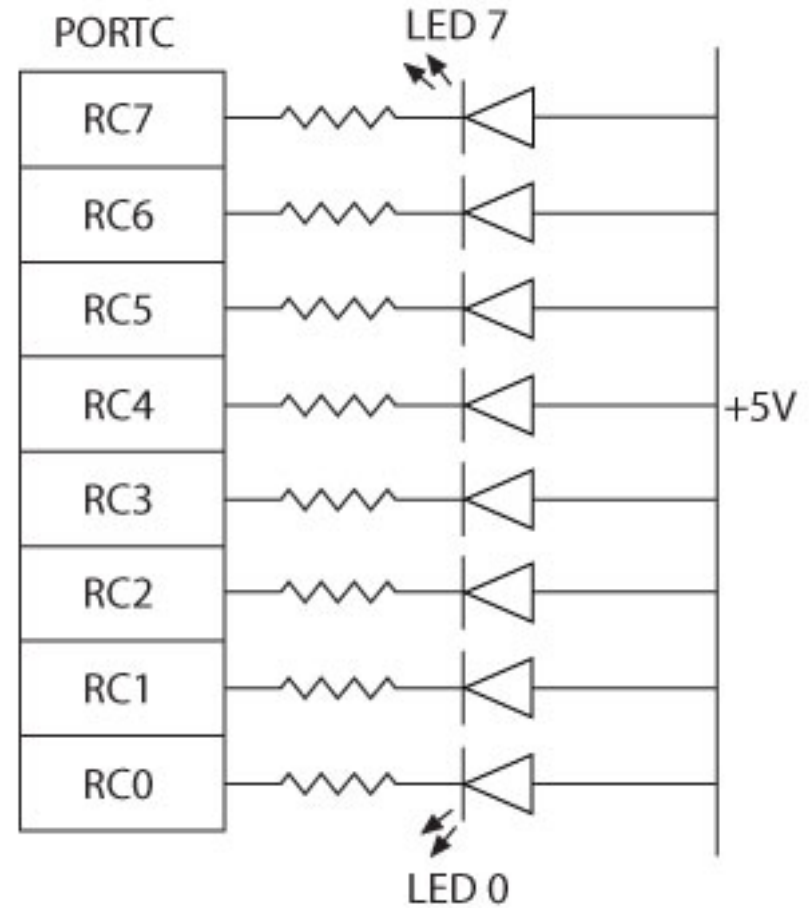
Interfacing Output Peripherals

- ◆ Commonly used output peripherals in embedded systems
 - LEDs
 - Seven-Segment Displays
 - LCDs
- ◆ Two ways of connecting LEDs to I/O ports
 - Common Cathode
 - LED cathodes are grounded
 - Logic 1 from the I/O port turns on the LEDs
 - Current is supplied by the I/O port called current sourcing
 - Common Anode
 - LED anodes are connected to the power supply
 - Logic 0 from the I/O port turns on the LEDs
 - Current is received by the chip called current sinking

Interfacing Output Peripherals



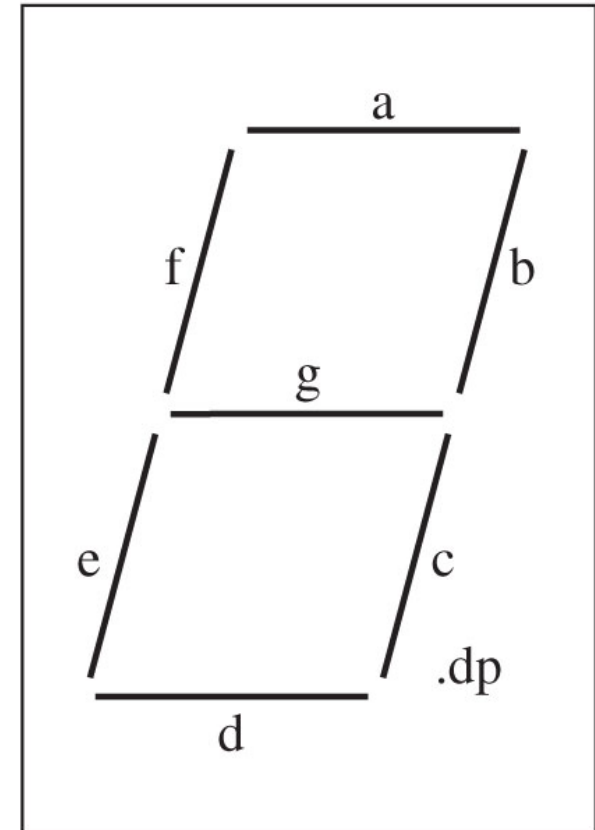
Common Cathode



Common Anode

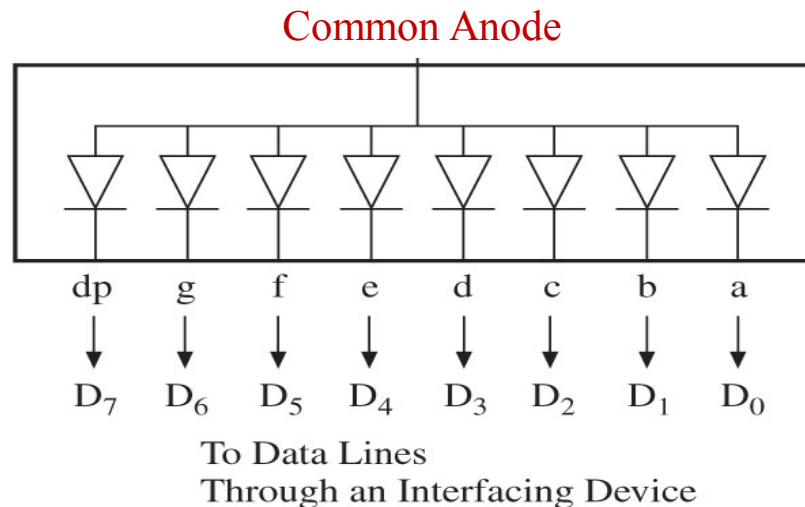
Seven-Segment Display

- ◆ Seven-segment Displays
 - Used to display BCD digits
 - 0 thru 9
 - A group of 7 LEDs physically mounted in the shape of the number eight
 - Plus a decimal point
 - Each LED is called a segment
 - 'a' through 'g'
 - Two types
 - Common anode
 - Common cathode



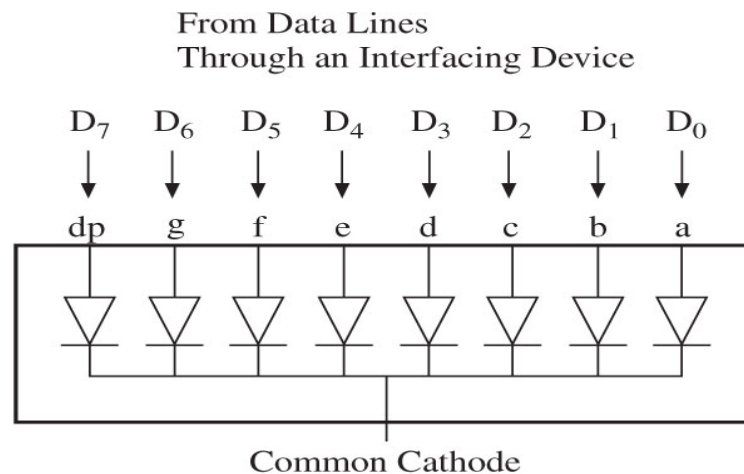
Seven-Segment Display

- ◆ Common Anode
 - All anodes are connected together to a power supply
 - Cathodes are connected to data lines
- ◆ Logic 0 turns on a segment
- ◆ Example: To display the digit 1
 - All segments except b and c should be off
 - $11111001 = F9_H$



Seven-Segment Display

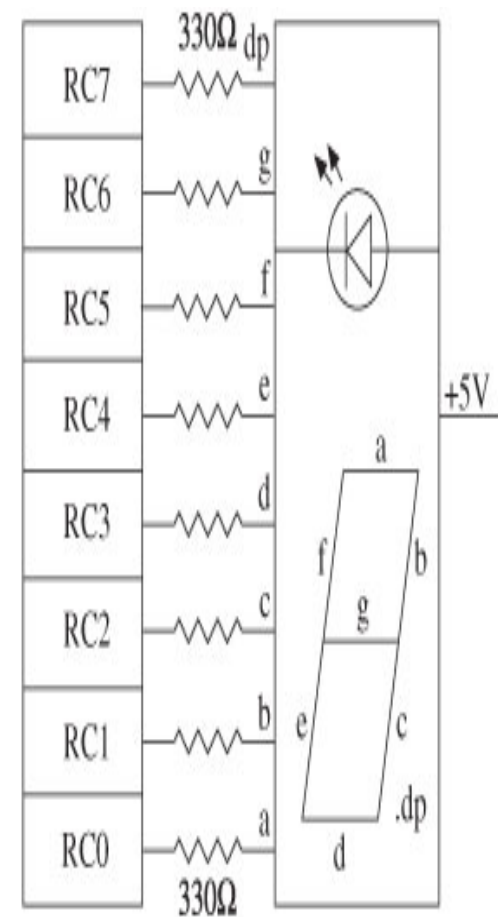
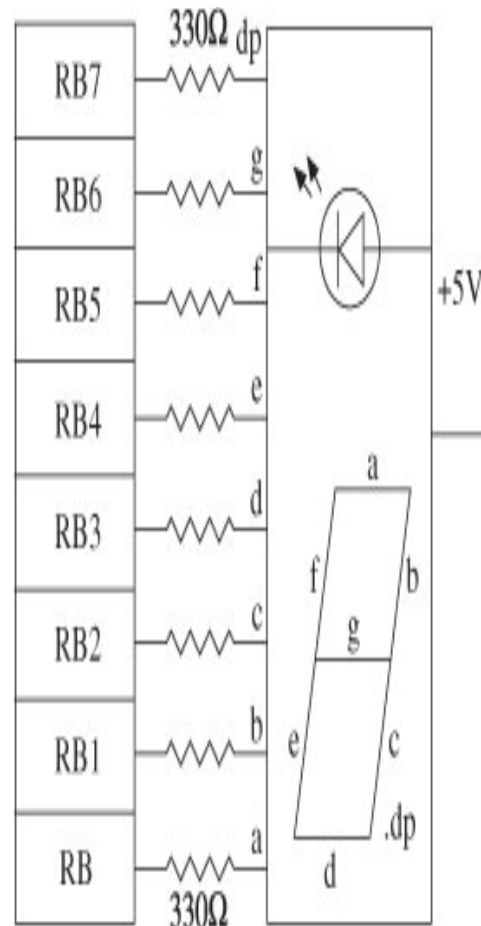
- ◆ Common Cathode
 - All cathodes are connected together to ground
 - Anodes are connected to data lines
- ◆ Logic 1 turns on a segment
- ◆ Example: To display digit 1
 - All segments except b and c should be off
 - $00000110 = 06_H$



Example 9.4

◆ Interfacing Seven-Segment Display to PORTB

- Common Anode
- Table Look-Up



Illustrative Program

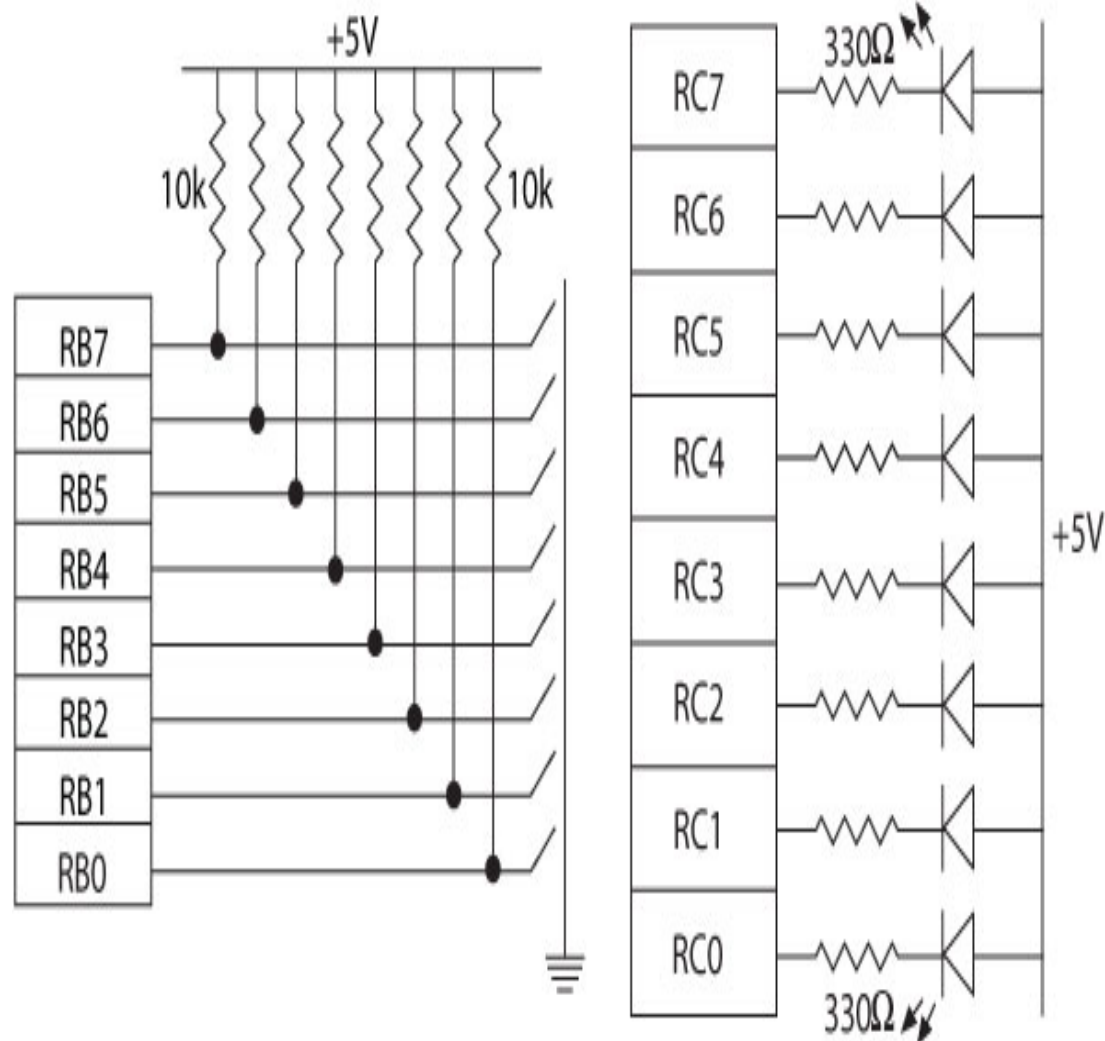
- ◆ Problem Statement

- Interface two common-anode seven-segment displays to PORTD and PORTC of the PIC18F
- Write instructions to implement an up-counter, counting from 00 to 59
- Display the count on the two seven-segment displays

Interfacing Input Peripherals

- ◆ Commonly used input peripherals
 - DIP switches, push-button keys, keyboards, and A/D converters
- ◆ DIP switch
 - One side of the switch is tied high
 - To a power supply through a resistor called a pull-up resistor
 - The other side is grounded
 - The logic level changes when the position is switched
- ◆ Push-button key
 - Same as the DIP switch except that contact is momentary

Interfacing Dip Switches



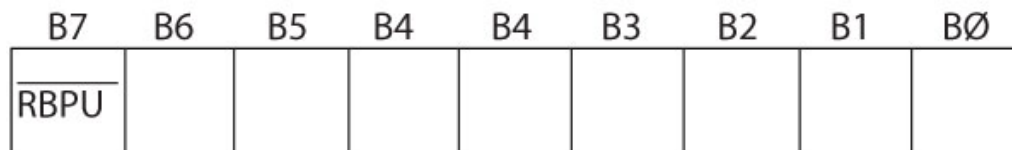
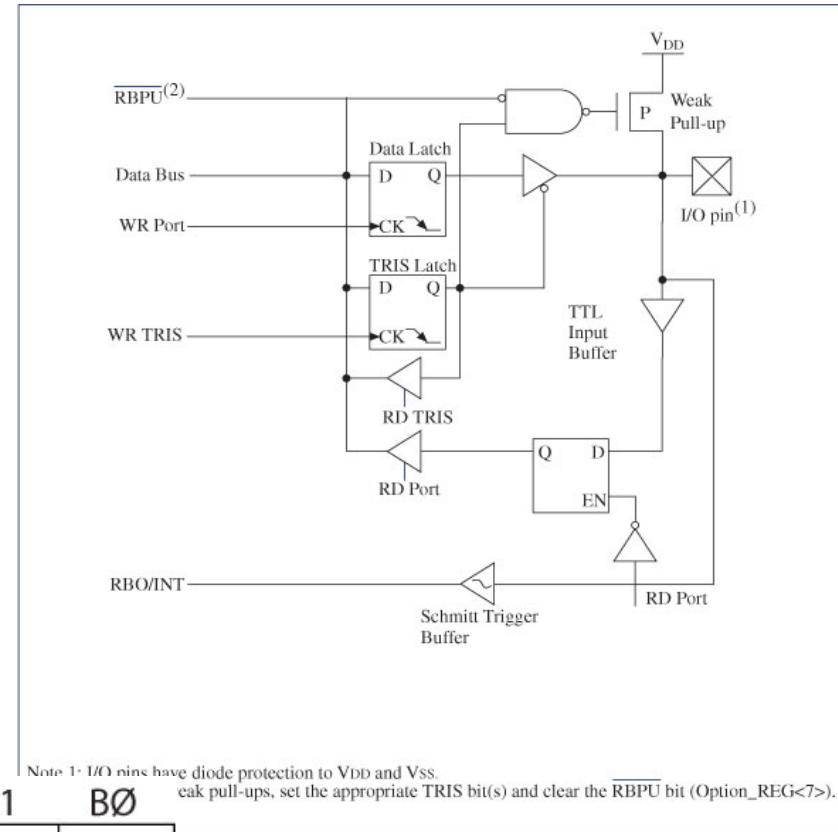
Reading from an I/O Port

- ◆ Read input switches on PORTB (RB7-RB4)
 - RB0 set HI (1)
 - Switches Open = LOW (0)
 - Switches Closed = HIGH (1)
- ◆ Display on PORTC

Opcode	Operands	Comments
MOVLW	0xF0	;Load B'11110000' into WREG
MOVWF	TRISB	;Set PORTB TRIS Reg
CLRF	TRISC	;Set PORTC as Output
BSF	PORTB,0	;Set RB0 High
MOVF	PORTB,W	;Read PORTB
MOVWF	PORTC	;Display on PORTC

Internal Pull-Up Resistor

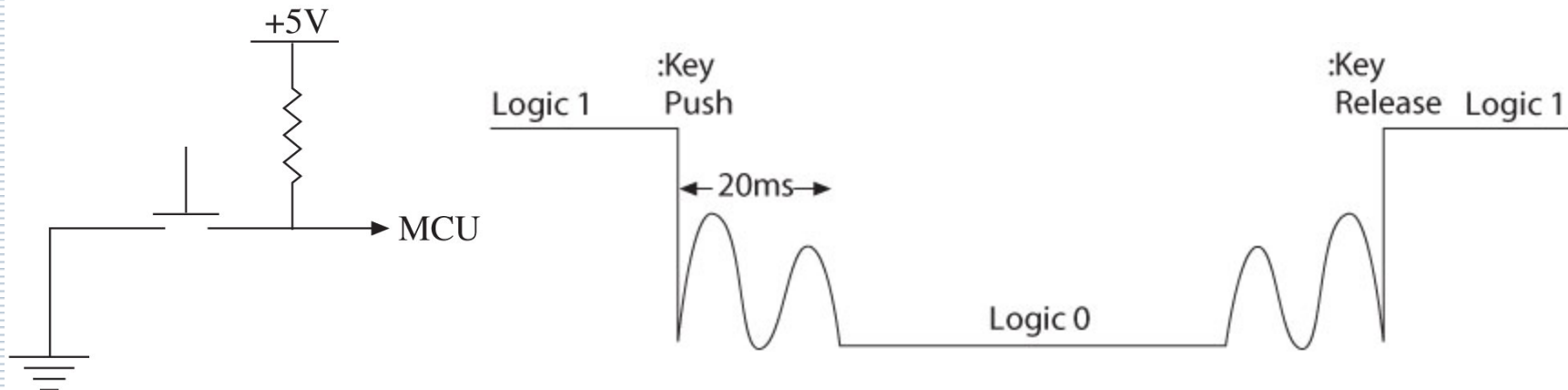
- Turning off the internal FET provides a pull-up resistor
- Bit7 (RBPU) in the INTCON2 register enables or disables the pull-up resistor
 - Instruction to Enable Pull Up Resistors:
BCF INTCON2,7



$\overline{\text{RBPU}}$ = PORTB pull-up resistor enable bit
 0 = Pull-up resistors are enabled
 1 = Pull-up resistors are disabled

Interfacing Push-Button Keys

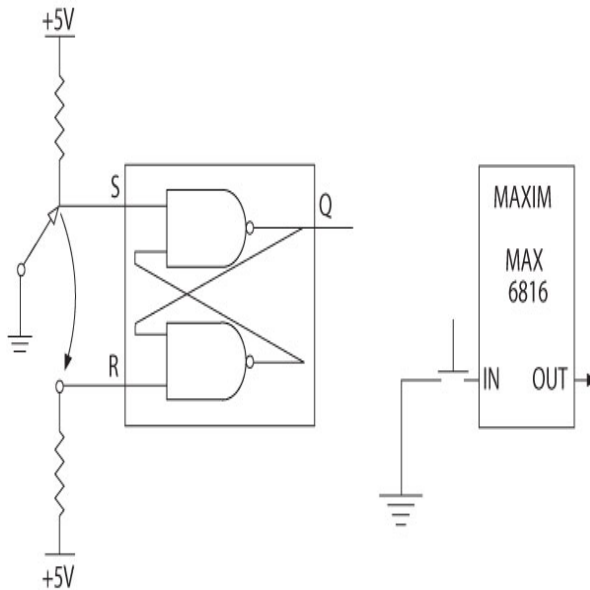
- ◆ When a key is pressed (or released), mechanical metal contact bounces momentarily and can be read as multiple inputs
- ◆ Key debounce
 - Eliminating reading of one contact as multiple inputs
 - Hardware or Software



Key Debounce Techniques

◆ Hardware technique

- Two NAND gates
 - S-R latch
- The output of the latch is a pulse without a bounce



◆ Software technique

- Wait for 10 to 20 ms after detection of a switch closure
- If the reading is still the same it is accepted

Interfacing a Matrix Keypad

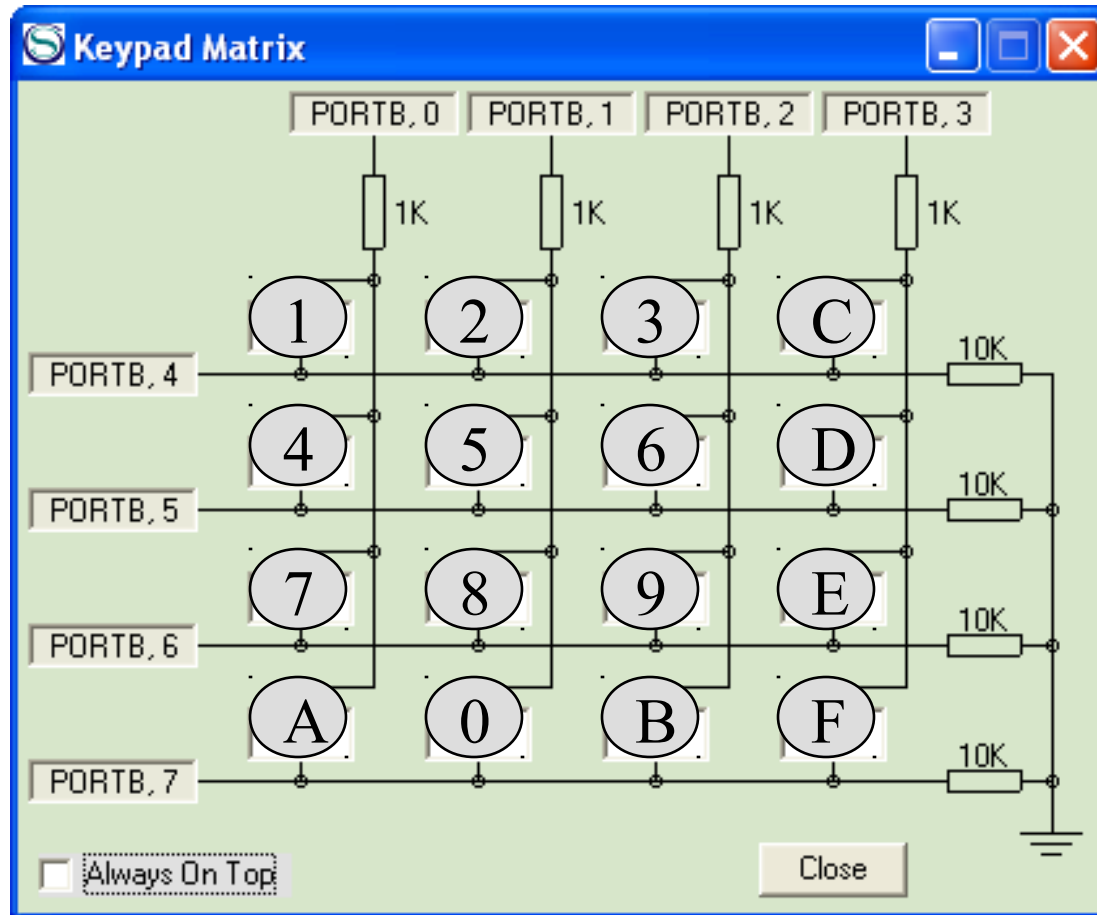
- ◆ Problem statement
 - Interface a 4 x 4 Hex keypad to PORTB
 - Write a program to recognize a key pressed and encode the key in its binary value
 - Display binary code on PORTC

Interfacing a Matrix Keypad

- ◆ Hardware (PIC18 Simulator)
 - 4 x 4 matrix keypad organized in the row and column format
 - Four columns are connected to the lower half of PORTB (RB0-RB3)
 - Four rows are connected to upper half of PORTB (RB4-RB7)
 - When a key is pressed, it makes a contact with the corresponding row and column

Interfacing a Matrix Keypad

- ◆ PIC18 Simulator Keypad Matrix



Interfacing a Matrix Keypad

- ◆ Software
 - To recognize and encode the key pressed
 - Set all the columns High by sending ones
 - Check for any key pressed (non-zero)
 - Set one column High at a time
 - ◆ Check all the rows in that column
 - Once a key is identified
 - ◆ Encode based on its position in the column

Time Multiplex Scanning Technique

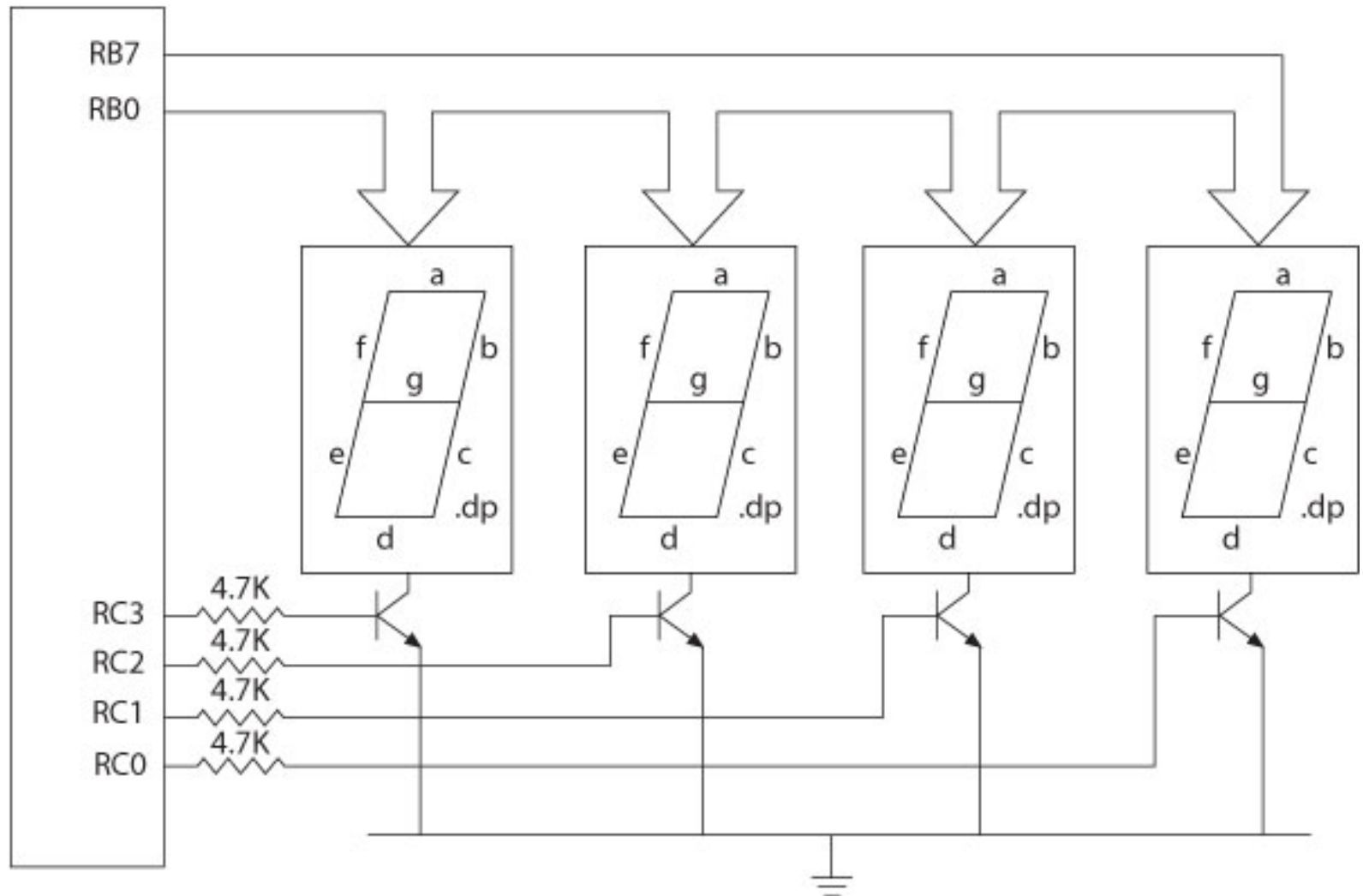
- ◆ Problem statement
 - Interface four common cathode seven-segment displays to PORTB and PORTC using the time multiplex scanning technique.
 - Write instructions to display a four-digit number stored in data registers.

Time Multiplex Scanning

◆ Hardware

- Eight data lines of PORTB are connected to the anodes of each display
- Each cathode is connected to PORTC (RC3-RC0) through a transistor
- Transistors (and LEDs) can be turned on by sending logic 1
- Each display is turned on and off in a sequence to display a digit

Time Multiplex Scanning



Time Multiplex Scanning

◆ Software

- Codes of the numbers to be displayed are stored in data registers in sequence
- The program gets the codes from the data registers by using the pointer (FSR0) and sends them out to the LED segments through PORTB
- One display at a time is turned on by sending logic 1 to the corresponding transistor connected to PORTC
- After an appropriate delay, the first display is turned off and the next display is turned on
- Turning displays on/off is repeated in sequence

Interfacing LCD

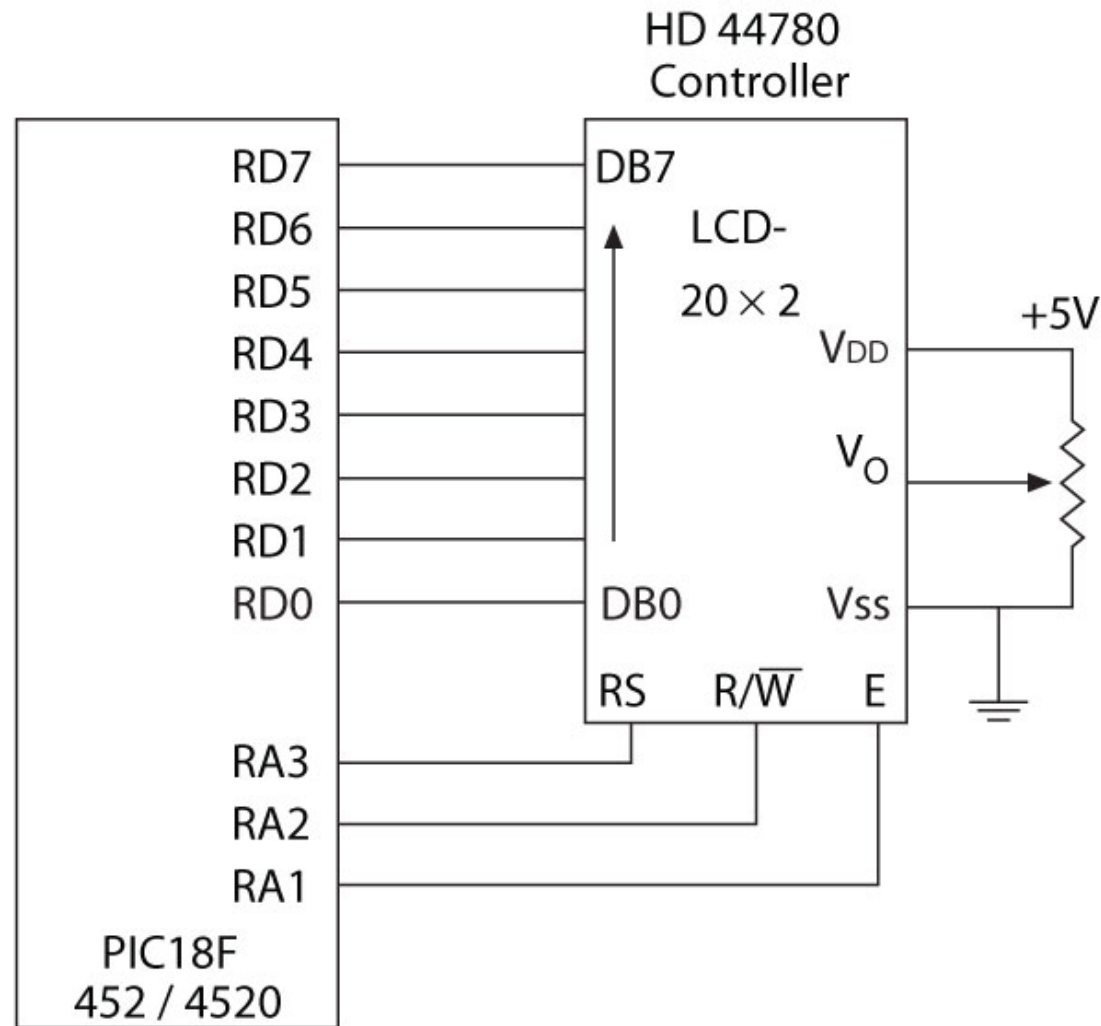
- ◆ Problem statement
 - Interface a 2-line x 20 character LCD module with the built-in HD44780 controller to I/O ports of the PIC18 microcontroller.
 - Explain the control signals necessary to read from and write to the LCD.
 - Write a program to display ASCII characters.

Interfacing LCD

◆ Hardware

- 20 x 2-line LCD display
 - Two lines with 20 characters per line
- LCD has a display Data RAM
 - Stores data in 8-bit character code
- Each register in Data RAM has its own address
 - Corresponds to its position on the line
 - ◆ Line 1 is 00_H to 13_H
 - ◆ Line 2 is 40_H to 53_H

Interfacing LCD



Interfacing LCD

- ◆ Driver HD44780
 - 8-bit data bus (RD7-RD0)
 - Three control signals
 - RS – Register Select (RA3)
 - R/W – Read/Write (RA2)
 - E – Enable (RA1)
 - Three power connections
 - Power, ground, and variable resistor to control brightness

Interfacing LCD

- ◆ Can be interfaced either in 8-bit mode or 4-bit mode
 - In 8-bit mode, all eight data lines are connected
 - In 4-bit mode, only four data lines are connected
 - Two transfers per character (or instruction) are needed
- ◆ Driver has two 8-bit internal registers
 - Instruction Register (IR) to write instructions to set up LCD
 - Table 9-3
 - Data Register (DR) to write data (ASCII characters)

Interfacing LCD

◆ LCD Operation

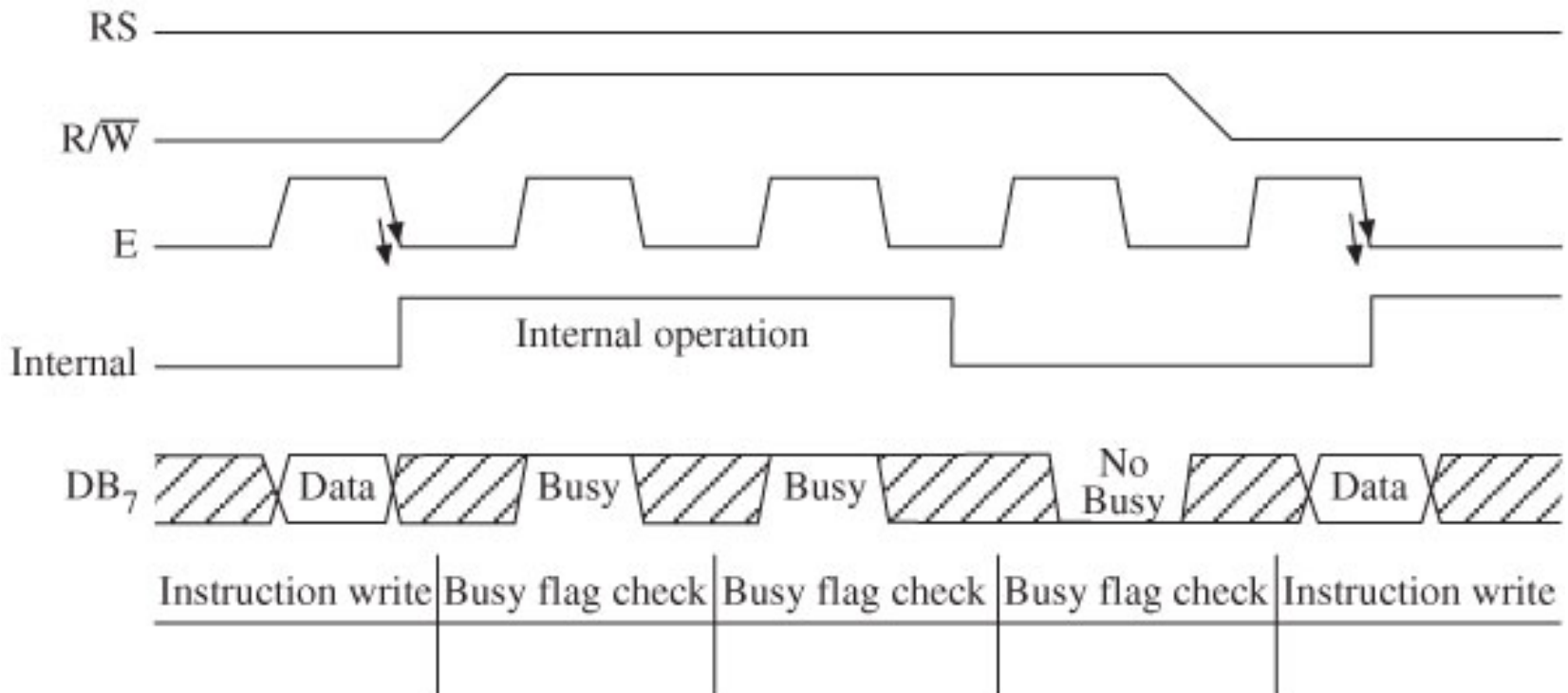
- When the MPU writes an instruction to IR or data to DR, the controller:
 - Sets DB7 high indicating that the controller is busy
 - Sets DB7 low after the completion of the operation
- The MPU should always check whether DB7 is low before sending an instruction or a data byte

Interfacing LCD

- ◆ Writing to or Reading from LCD (Table 9-4)
 - The MPU:
 - Asserts RS low to select IR
 - Asserts RS high to select DR
 - Reads from LCD by asserting the R/W signal high
 - Writes into LCD by asserting the R/W signal low
 - Asserts the E signal high and then low (toggles) to latch a data byte or an instruction

Interfacing LCD

- ◆ Timing diagram: writing to LCD



Interfacing LCD

- ◆ Software
 - To write into the LCD
 - Send the initial instructions to set up the LCD
 - ◆ 4-bit or 8-bit mode
 - Continue to check DB7 until it goes low
 - Write instructions to IR to set up LCD parameters
 - ◆ Number of display lines and cursor status
 - Write data to display a message