19 Discrete-Time Sampling

Solutions to Recommended Problems

S19.1

x[n] is given by

$$x[n] = (-1)^n = e^{j\pi n}$$

Hence, the Fourier transform of x[n] is

$$X(\Omega) = \sum_{k=-\infty}^{\infty} \delta(\Omega - \pi - 2\pi k)$$

Now p[n] can be written as

$$p[n] = \frac{1 + (-1)^n}{2}$$

Hence, its Fourier transform is given by

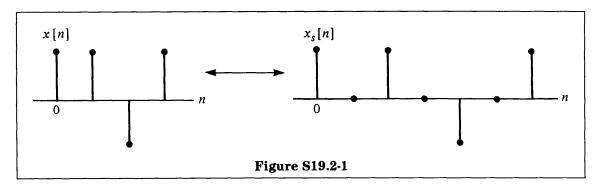
$$P(\Omega) = \frac{1}{2} \sum_{k=-\infty}^{\infty} \delta(\Omega - 2\pi k) + \frac{1}{2} \sum_{k=-\infty}^{\infty} \delta(\Omega - \pi - 2\pi k)$$

It is clear that $x_p[n] = p[n]$. Hence

$$X_n(\Omega) = P(\Omega)$$

S19.2

(a) $x_s[n]$ is x[n] "stretched" by interspersing with zeros, as indicated in Figure S19.2-1.



$$X_{s}(\Omega) = \sum_{n=-\infty}^{\infty} x_{s}[n]e^{-j\Omega n}$$

$$= \sum_{n=-\infty}^{\infty} x_{s}[2n]e^{-j\Omega 2n} + \sum_{n=-\infty}^{\infty} x_{s}[2n+1]e^{-j\Omega(2n+1)}$$

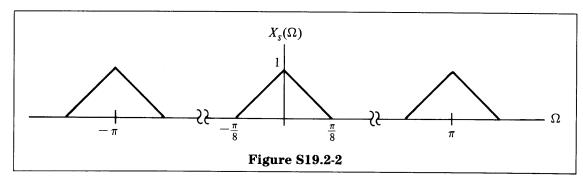
$$= \sum_{n=-\infty}^{\infty} x[n]e^{-j(2\Omega)n} + 0$$

$$= X(2\Omega)$$

(b)
$$x_d[n] = x[2n],$$

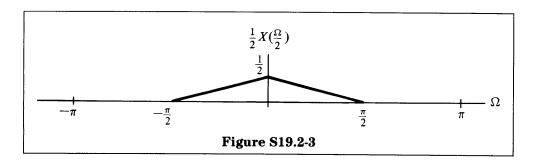
 $X_d(\Omega) = \sum_{n=-\infty}^{\infty} x_d[n]e^{-j\Omega n}$
 $= \sum_{n=-\infty}^{\infty} x[2n]e^{-j\Omega n}$
 $= \frac{1}{2} \sum_{n=-\infty}^{\infty} (x[n] + (-1)^n x[n])e^{-j\Omega n/2}$
 $= \frac{1}{2} \sum_{n=-\infty}^{\infty} x[n]e^{-j(\Omega/2)n} + \frac{1}{2} \sum_{n=-\infty}^{\infty} x[n]e^{-j[(\Omega/2)-\pi]n}$
 $= \frac{1}{2} X\left(\frac{\Omega}{2}\right) + \frac{1}{2} X\left(\frac{\Omega}{2} - \pi\right)$

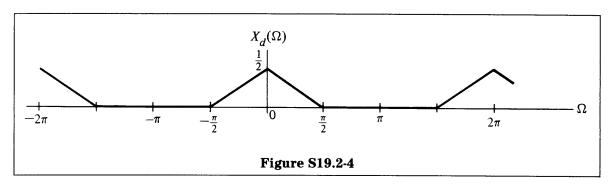
(c)
$$X_s(\Omega) = X(2\Omega)$$



$$X_d(\Omega) = \frac{1}{2} X\left(\frac{\Omega}{2}\right) + \frac{1}{2} X\left(\frac{\Omega}{2} - \pi\right)$$

 $\frac{1}{2}X(\Omega/2)$ is indicated in Figure S19.2-3. Therefore, $X_d(\Omega)$ is as shown in Figure S19.2-4.



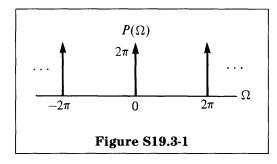


S19.3

(a) For N = 1, p[n] = 1. Hence

$$P(\Omega) = 2\pi \sum_{k=-\infty}^{\infty} \delta(\Omega - 2\pi k),$$

as shown in Figure S19.3-1.



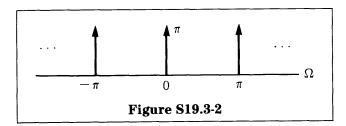
For N = 2,

$$p[n] = \sum_{k=-\infty}^{\infty} \delta[n-2k]$$

Hence

$$P(\Omega) = \pi \sum_{k=-\infty}^{\infty} \delta(\Omega - \pi k),$$

shown in Figure S19.3-2.



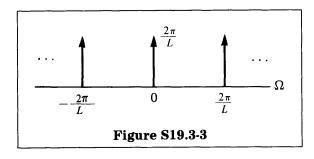
For N = L,

$$p[n] = \sum_{k=-\infty}^{\infty} \delta[n - Lk]$$

Hence

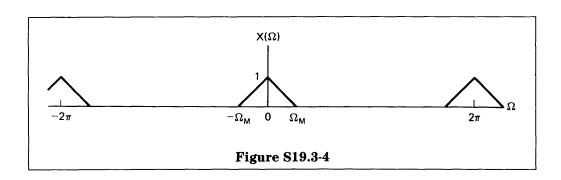
$$P(\Omega) = \frac{2\pi}{L} \sum_{k=-\infty}^{\infty} \delta \left(\Omega - \frac{2\pi k}{L} \right),$$

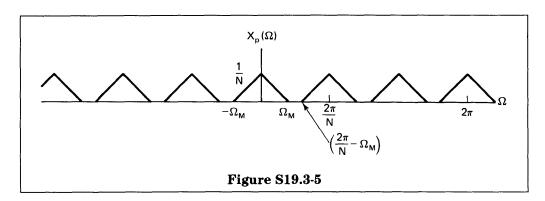
shown in Figure S19.3-3.



(b) $X_p(\Omega)$, the spectrum of $x_p[n]$, is proportional to the periodic convolution of $P(\Omega)$ and $X(\Omega)$. Consequently, with $P(\Omega)$ as indicated in Figure S19.3-3 and $X(\Omega)$ as indicated in Figure S19.3-4, $X_p(\Omega)$ is shown in Figure S19.3-5. In order that x[n] be reconstructible from $x_p[n]$ using an ideal lowpass filter, aliasing must be avoided, which requires that

$$\Omega_{\mathrm{M}} < \frac{2\pi}{N} - \Omega_{\mathrm{M}}, \quad \text{or} \quad \Omega_{\mathrm{M}} < \frac{\pi}{N}$$





(i) $\Omega_{\rm M} = 3\pi/10$. Therefore, to avoid aliasing,

$$\frac{\pi}{N} > \frac{3\pi}{10} \quad \text{or} \quad N < \frac{10}{3}$$

Since N must be an integer, we require that $N \le 3$. For N = 3, the cutoff frequency of the lowpass filter must be greater than $3\pi/10$ and less than

$$\frac{2\pi}{3} - \frac{3\pi}{10} = \left(\frac{11}{3}\right) \frac{\pi}{10}$$

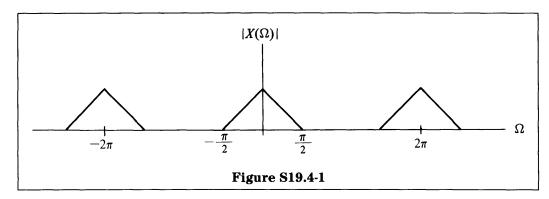
(ii) $\Omega_{\rm M} = 3\pi/5$. To avoid aliasing,

$$\frac{\pi}{N} > \frac{3\pi}{5} \quad \text{or} \quad N < \frac{5}{3}$$

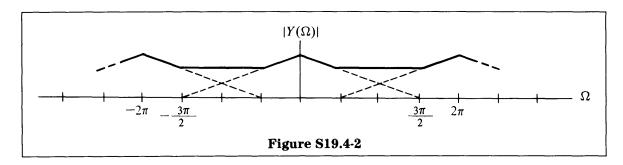
Since N must be a positive integer, this requires that N=1, i.e., x[n] cannot be sampled.

S19.4

- (a) The sampling period T_1 is 3 ms for the system in Figure P19.4-2 to be equivalent to the one in Figure P19.4-1.
- **(b)** $X(\Omega)$ is sketched in Figure S19.4-1.



From the result of part (a), $Y(\Omega)$ is as shown in Figure S19.4-2.



S19.5

(a) Consider $x_{d_1}[n]$ and $x_{d_2}[n]$, and let

$$x_{d_3}[n] = x_{d_1}[n] + \alpha x_{d_2}[n]$$

Then

$$x_{p3}[n] = \begin{cases} x_{d1}[n/N] + \alpha x_{d2}[n/N], & n = 0, \pm N, \dots, \\ 0, & \text{otherwise} \end{cases}$$

But

$$x_{pl}[n] = \begin{cases} x_{dl}[n/N], & n = 0, \pm N, \dots, \\ 0, & \text{otherwise} \end{cases}$$

And

$$\alpha x_{p2}[n] = \begin{cases} \alpha x_{d2}[n/N], & n = 0, \pm N, \dots, \\ 0, & \text{otherwise} \end{cases}$$

Hence,

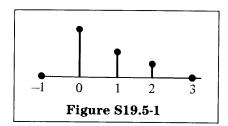
$$x_{p_1}[n] + \alpha x_{p_2}[n] = \begin{cases} x_{d_1}[n/N] + \alpha x_{d_2}[n/N], & n = 0, \pm N, \dots, \\ 0, & \text{otherwise} \end{cases}$$

and

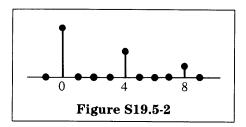
$$x_{p_3}[n] = x_{p_1}[n] + \alpha x_{p_2}[n]$$

So system A is linear.

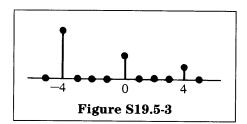
(b) Take $x_{d_1}[n]$ as shown in Figure S19.5-1, with N=4.



Then $x_{p_1}[n]$ is as shown in Figure S19.5-2.



Take $x_{d_2}[n] = x_{d_1}[n+1]$. Then $x_{p_1}[n]$ is as shown in Figure S19.5-3.



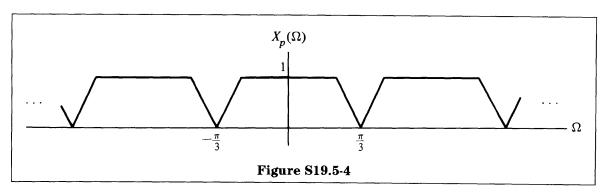
Hence, system A is not time-invariant.

(c)
$$x_p[n] = \begin{cases} x_d[n/N], & n = 0, \pm N, \dots, \\ 0, & \text{otherwise} \end{cases}$$

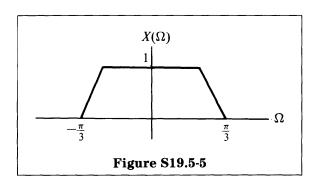
Hence

$$X_p(\Omega) = \sum_{n=-\infty}^{\infty} x_d[n] e^{-j\Omega(Nn)} = X_d(N\Omega),$$

as shown in Figure S19.5-4.

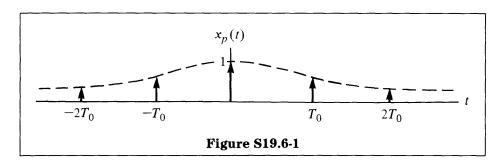


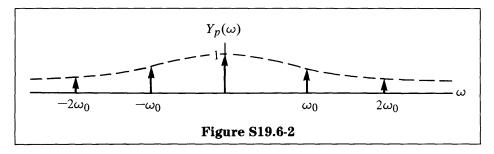
(d) $X(\Omega)$ is as shown in Figure S19.5-5 for exact bandlimited interpolation.



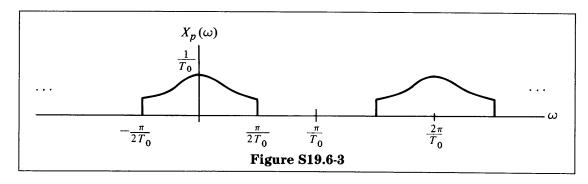
S19.6

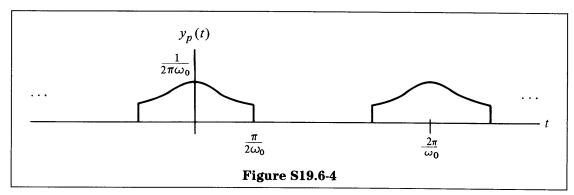
(a) $x_p(t)$ is sketched in Figure S19.6-1, and $Y_p(\omega)$ is sketched in Figure S19.6-2.





(b) $X_p(\omega)$ is sketched in Figure S19.6-3, and $y_p(t)$ is sketched in Figure S19.6-4.





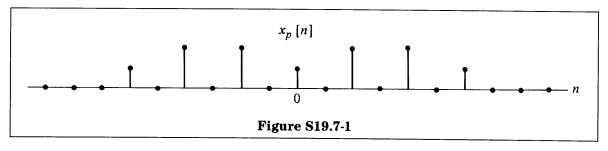
(c) Yes, $y_p(t)$ is periodic and this is reflected in $Y_p(\omega)$, which contains impulses.

Solutions to Optional Problems

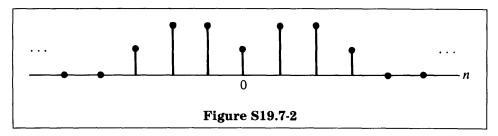
S19.7

(a)
$$x_p[n] = \begin{cases} x[n], & n = 0, \pm 2, \pm 4, \dots, \\ 0, & n = \pm 1, \pm 3, \pm 5, \dots \end{cases}$$

This is sketched in Figure S19.7-1.



Similarly, $x_d[n] = x[2n]$, as shown in Figure S19.7-2.



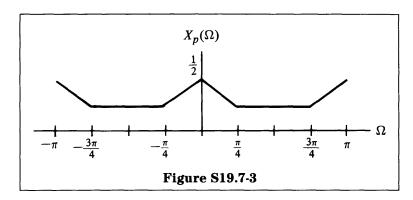
(b) $X_p(\Omega)$ is obtained as follows:

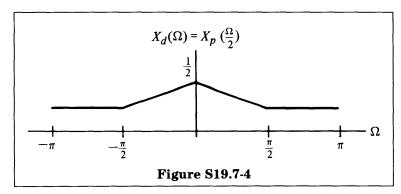
$$x_p[n] = \frac{1}{2}x[n] + \frac{1}{2}(-1)^n x[n] X_p(\Omega) = \frac{1}{2}X(\Omega) + \frac{1}{2}X(\Omega - \pi)$$

and

$$X_d(\Omega) = \frac{1}{2} X\left(\frac{\Omega}{2}\right) + \frac{1}{2} X\left(\frac{\Omega}{2} - \pi\right),$$

which are shown in Figures S19.7-3 and S19.7-4. See Problem P19.2(b).



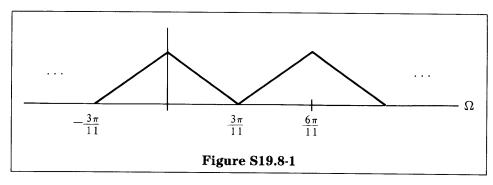


S19.8

(a) We know that the Fourier transform of p[n] is given by

$$\frac{2\pi}{N}\sum_{k=-\infty}^{\infty}\delta\left(\Omega-\frac{2\pi k}{N}\right)$$

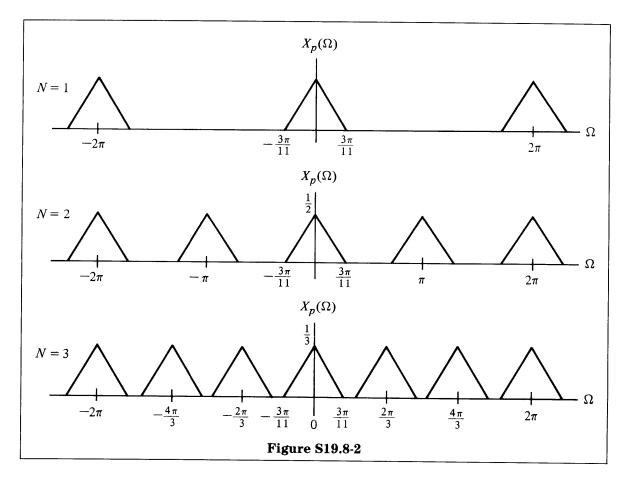
Aliasing will be just avoided when the sampled spectra will look as shown in Figure S19.8-1.



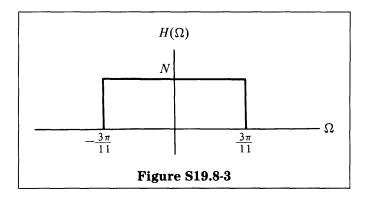
Hence, we require that

$$\frac{2\pi}{N} > \frac{6\pi}{11}$$
, or $N < \frac{22}{6} \Rightarrow N \le 3$

Consequently, aliasing is avoided if $1 \le N \le 3$. $X_p(\Omega)$ for N = 1, 2, and 3 are shown in Figure S19.8-2.



(b) An appropriate $H(\Omega)$ is shown in Figure S19.8-3.

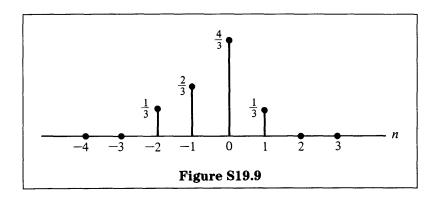


S19.9

(a)
$$y[n] = \frac{x[3n] + x[3n + 1] + x[3n + 2]}{3}$$

 $y[-4] = 0$
 $y[-3] = 0$
 $y[-2] = \frac{1}{3}x[-4] = \frac{1}{3}$
 $y[-1] = \frac{x[-3] + x[-2] + x[-1]}{3} = \frac{2}{3}$
 $y[0] = \frac{x[0] + x[1] + x[2]}{3} = \frac{4}{3}$
 $y[1] = \frac{x[3] + x[4] + x[5]}{3} = \frac{1}{3}$
 $y[2] = 0$
 $y[3] = 0$

Hence, y[n] can be sketched as in Figure S19.9.



$$z[n] = \frac{1}{3}[x[n] + x[n+1] + x[n+2]],$$
 for all n

Signals and Systems

S19-12

and

$$y[n] = z[3n],$$

we have expressed the processing as a combination of filtering and decimation

S19.10

If h[0] = 1 and h[n] = 0 for n = kN, $k \neq 0$, it is easy to see that the samples $x_0[n]$ that came from x[n] will be unaffected. Hence,

$$y[kN] = x[k],$$
 for all k

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Resource: Signals and Systems Professor Alan V. Oppenheim

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