

# Unit 1: Calculus

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# Limits

# Definition

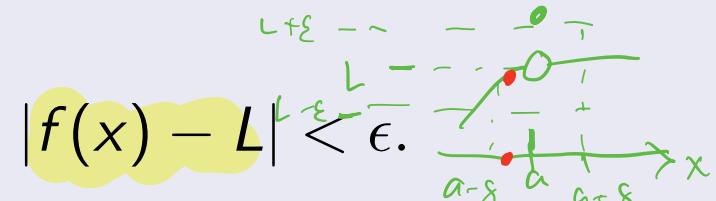
## Definition

(a) Define  $\lim_{x \rightarrow a} f(x) = L$  to mean for all  $\epsilon > 0$  there exists a  $\delta > 0$  such that

*we don't care about  $f$  at  $a$*

$$0 < |x - a| < \delta$$

implies



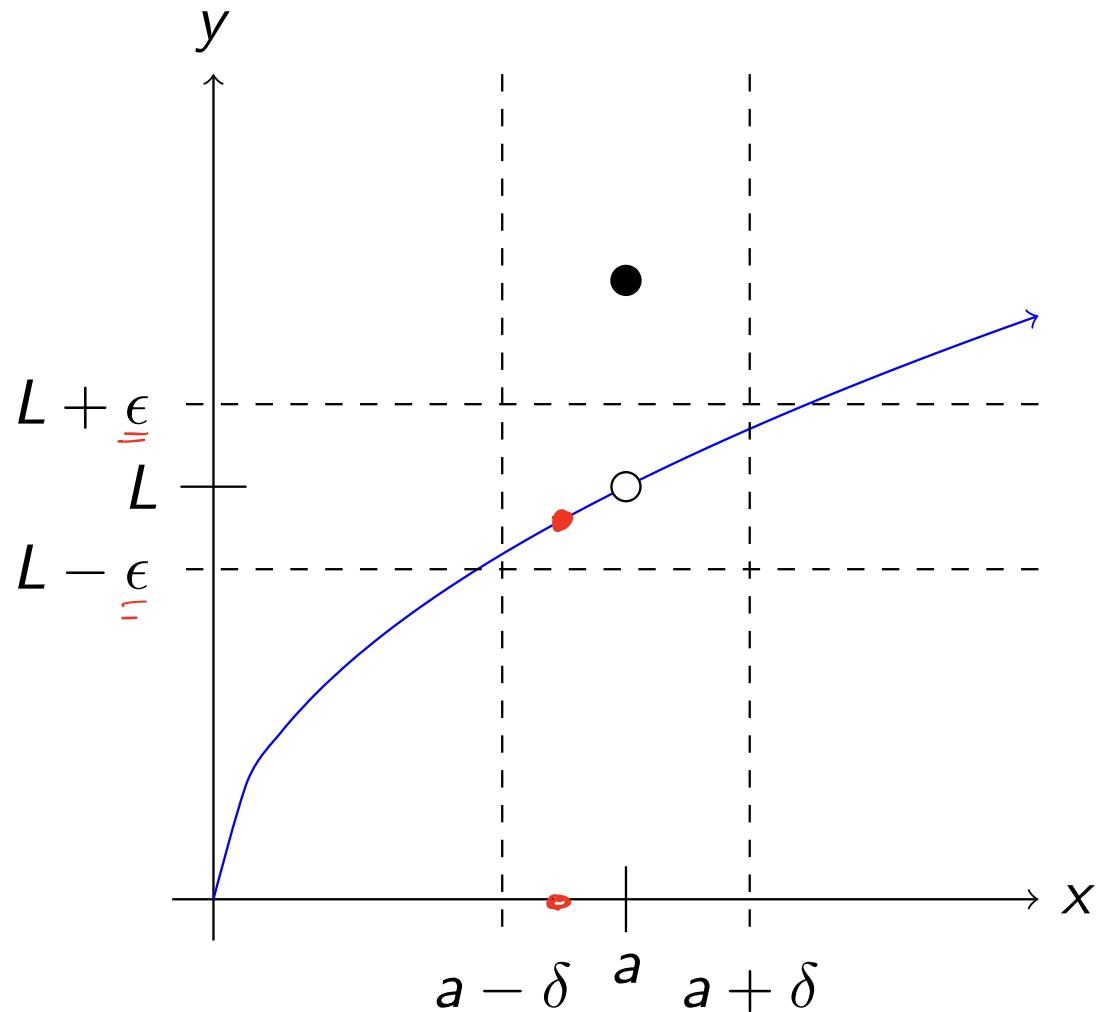
(b) Define  $\lim_{x \rightarrow \infty} f(x) = L$  to mean for all  $\epsilon > 0$  there exists an  $N$  such that

$$\underline{x} \geq \underline{N} \quad \text{implies} \quad |f(\underline{x}) - \underline{L}| < \epsilon.$$

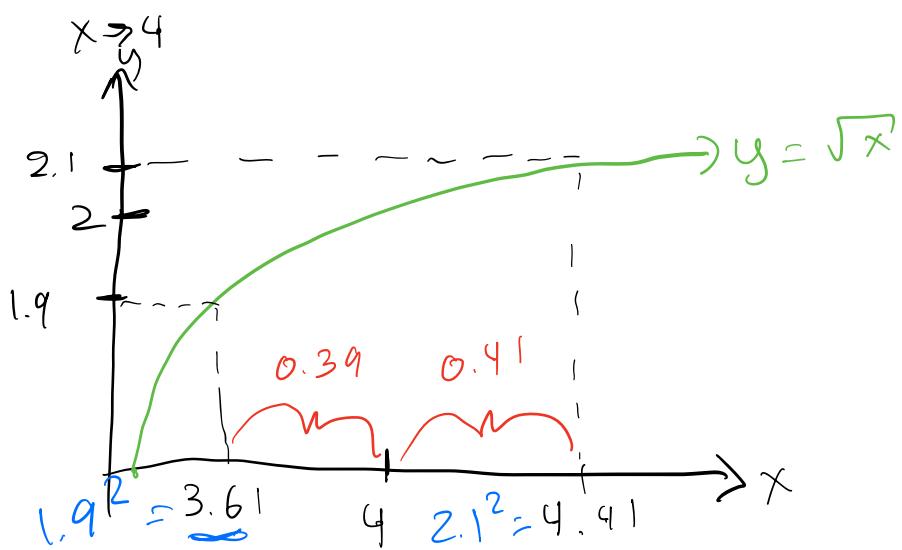
(c) Define  $\lim_{x \rightarrow -\infty} f(x) = L$  to mean for all  $\epsilon > 0$  there exists an  $N$  such that

$$\underline{x} \leq \underline{N} \quad \text{implies} \quad |f(\underline{x}) - \underline{L}| < \epsilon.$$

$$\lim_{x \rightarrow a} f(x) = L$$



$$\lim_{x \rightarrow 4} \sqrt{x} = 2$$



$$\sqrt{3.61} = 1.9$$

$$\sqrt{x} = 1.9$$

$$\Rightarrow x = 1.9^2$$

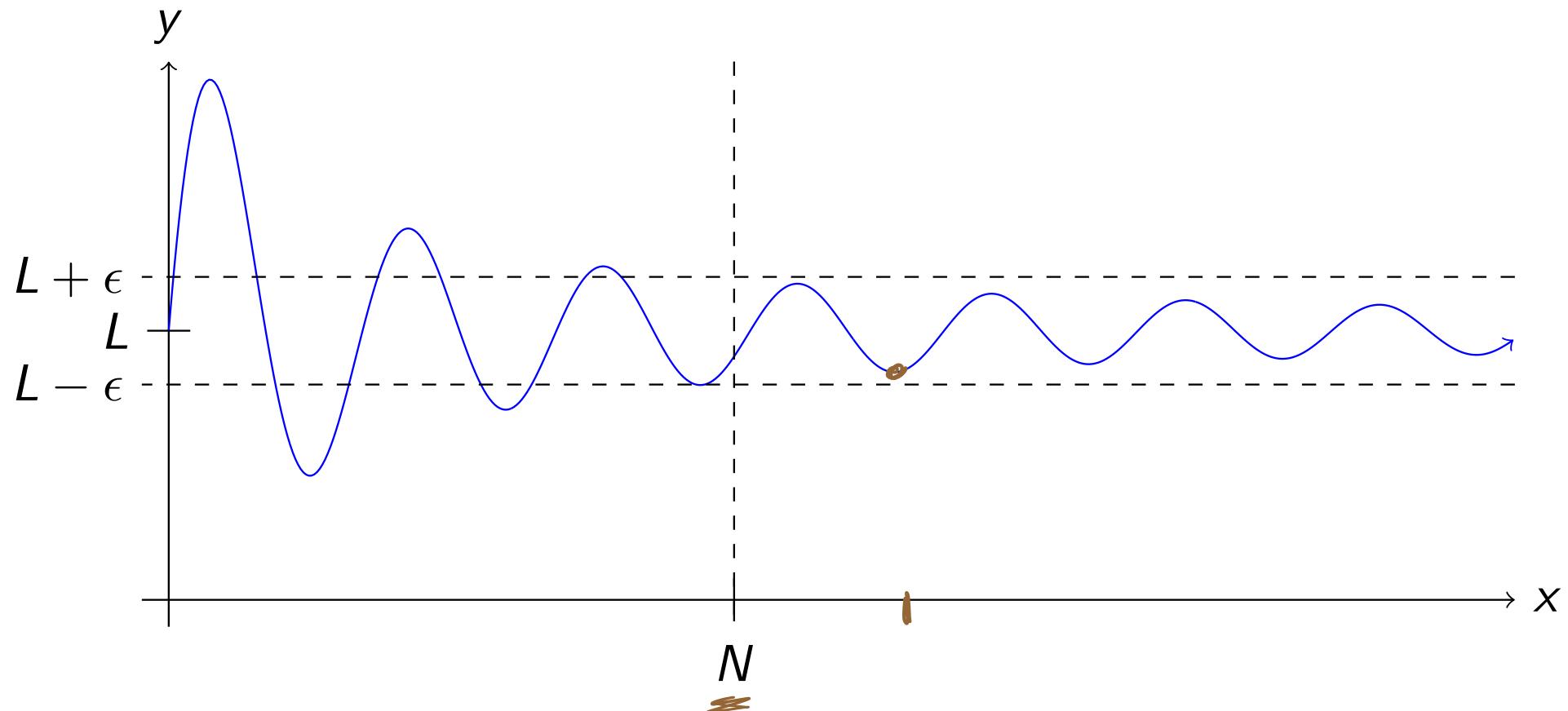
Pick  $\epsilon = 0.1$

so,  $\delta = \underline{0.39}$

$$0 < |x - 4| < 0.39 \Rightarrow |\sqrt{x} - 2| < 0.1$$

A smaller  $\delta$  would also work,  
e.g. in this case  $\delta = 0.01$ .

$$\lim_{x \rightarrow \infty} f(x) = L$$



# Using the Definition

## Example

Prove

$$\lim_{x \rightarrow \infty} \frac{1}{x^p} = 0$$

for all  $p > 0$ .

Sol The definition  $\forall \epsilon > 0 \exists N \in \mathbb{N}$  s.t..

$$x \geq N \Rightarrow \left| \frac{1}{x^p} - 0 \right| < \epsilon.$$

Pick  $\epsilon > 0$ . Then consider

$$\left| \frac{1}{x^p} - 0 \right| = \left| \frac{1}{x^p} \right| = \frac{1}{x^p} < \epsilon$$

$$\Leftrightarrow \frac{1}{\epsilon} < |x|^p \Leftrightarrow \sqrt[p]{\frac{1}{\epsilon}} < |x|$$

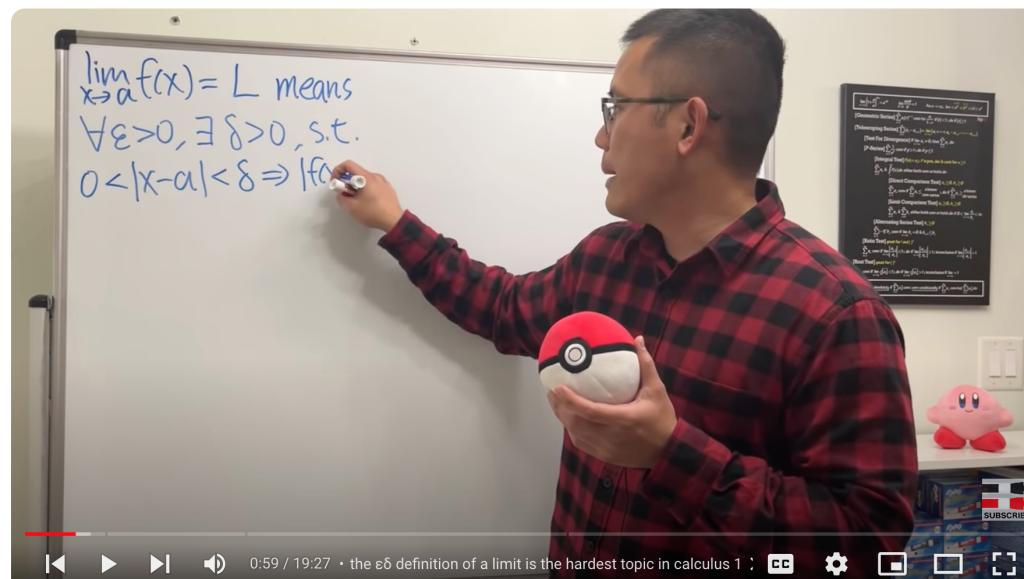
$$\text{Let } N = \lceil \sqrt[p]{\frac{1}{\epsilon}} \rceil.$$

So, we've come up with a rule.  
You give me  $\epsilon > 0$  and I can give you  
an  $N$  s.t.  $x \geq N \Rightarrow \left| \frac{1}{x^p} \right| < \epsilon$

# $\epsilon$ - $\delta$ Limit Definition on YouTube

Watch BlackPenRedPen explain the  $\epsilon$ - $\delta$  limit definition

([https://www.youtube.com/watch?v=DdtEQk\\_DHQs](https://www.youtube.com/watch?v=DdtEQk_DHQs)). There's another video where he goes over the  $x \rightarrow \infty$  case (<https://youtu.be/9JMFLzHt1jA?si=1WPW-fmaf2DBe3Ph>).



epsilon-delta definition ultimate introduction



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# Properties of Limits

## Theorem

Suppose  $a$  is in the interval  $[-\infty, \infty]$ . Let

$$\lim_{x \rightarrow a} f(x) = L_1 \quad \text{and} \quad \lim_{x \rightarrow a} g(x) = L_2.$$

- (a)  $\lim_{x \rightarrow a} \underline{\alpha f(x)} + \underline{\beta g(x)} = \underline{\alpha L_1} + \underline{\beta L_2}$  for any real constants  $\alpha$  and  $\beta$
- (b)  $\lim_{x \rightarrow a} f(x) \cdot g(x) = L_1 \cdot L_2$
- (c)  $\lim_{x \rightarrow a} \frac{1}{f(x)} = \frac{1}{L_1}$  if  $\underline{L_1} \neq 0$ .

# Useful Limits

## Theorem

Suppose  $p > 0$ .

(a)  $\lim_{x \rightarrow \infty} \frac{1}{x^p} = 0$  ✓

(b)  $\lim_{x \rightarrow \infty} p^{1/x} = 1$

(c)  $\lim_{x \rightarrow \infty} x^{1/x} = 1$

(d) If  $a > 0$ ,  $\lim_{x \rightarrow 0} \frac{a^x - 1}{x} = \ln a$

(e) If  $|r| < 1$ , then  $\lim_{x \rightarrow \infty} r^x = 0$

# Python Example

## Example

Define

$$f(x) = \begin{cases} \sin\left(\frac{1}{x}\right), & x \neq 0 \\ 0, & x = 0. \end{cases}$$

Graph  $f$  in Python to see that  $\lim_{x \rightarrow 0} f(x)$  does not exist.

# Python Example Cont.

```
# Import modules
import numpy as np
import matplotlib.pyplot as plt

# Use latex
plt.rcParams['text.usetex'] = True

# Use Seaborn style
plt.style.use('seaborn')

# Define f
f = lambda x: 0 if x == 0 else np.sin(1/x)

# Let's graph on the interval [-pi, pi]
x_vals = np.arange(-np.pi, np.pi, np.pi/200)

# Calculate the y-values
y_vals = [f(x) for x in x_vals]

# Generate the plot
plt.plot(x_vals, y_vals)

# Label the x-axis
plt.xlabel(r'$x$')

# Label the y-axis
plt.ylabel(r'$y$')

# Give the graph a title
plt.title(r'Graph of $y = f(x)$')

# Save the figure
plt.savefig(path + r'Images/ex1-1.png')

# Display the plot
plt.show()
```

By default  
in radians

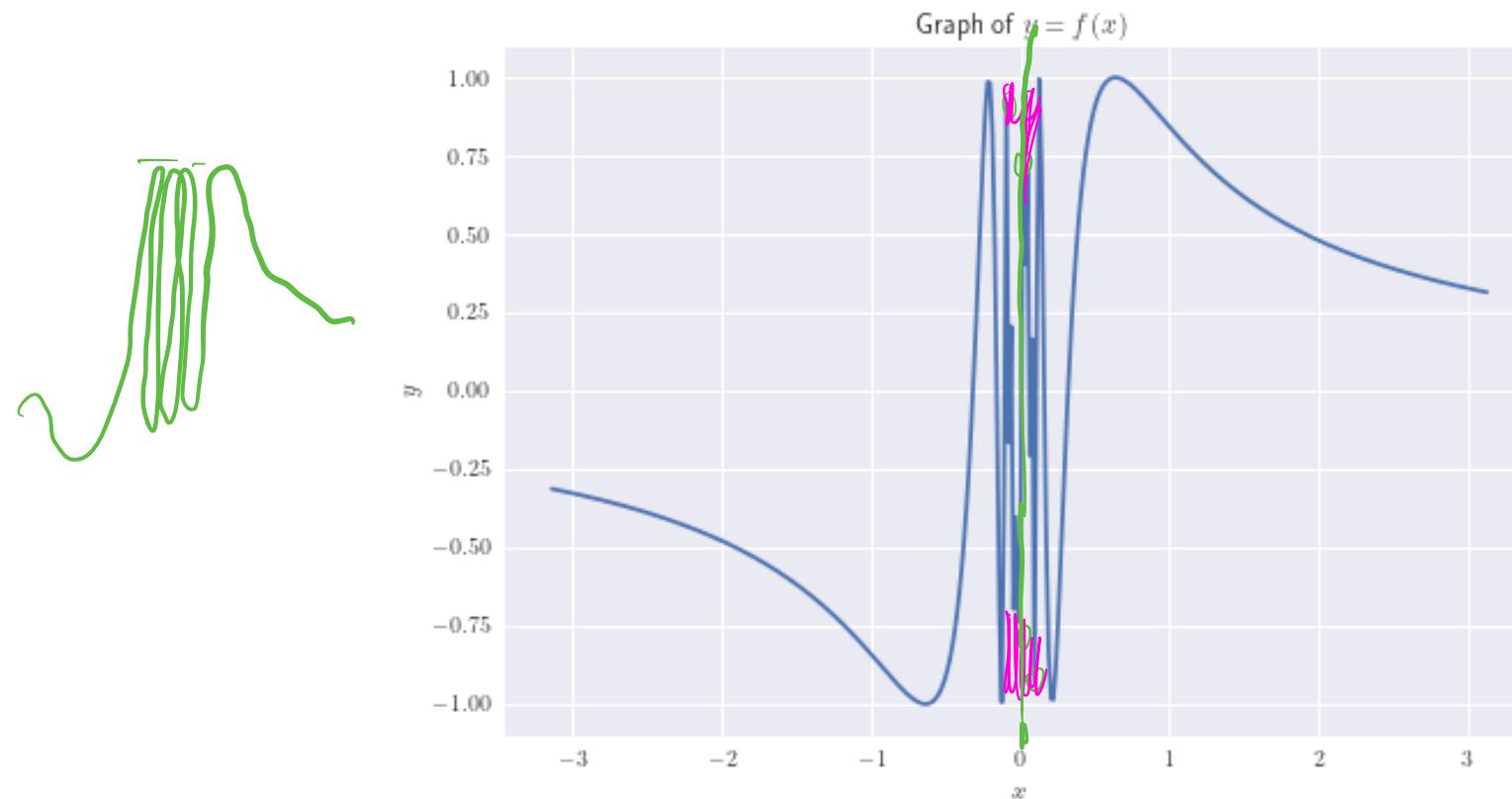
start stop  
↓ ↓  
 $\text{np.arange}(-\pi, \pi, \pi/200)$   
step size

```
def f(x):
    → If x == 0:
        → return 0
    else:
        → return np.sin(1/x)
```

# Python Example Result

The graph isn't perfect, but it's enough to see that  $f$  doesn't approach anything in particular as  $x$  approaches 0.

$$\lim_{x \rightarrow 0} f(x) = \text{DNE} \quad \begin{matrix} \leftarrow & \text{does not} \\ & \text{exist} \end{matrix}$$



# Continuity

# Continuity

## Definition

(a) A function  $f$  is continuous at  $a$  if  $\lim_{x \rightarrow a} f(x) = \underline{f(a)}$ .

(b) A function  $f$  is continuous on the set  $\underline{A}$  if

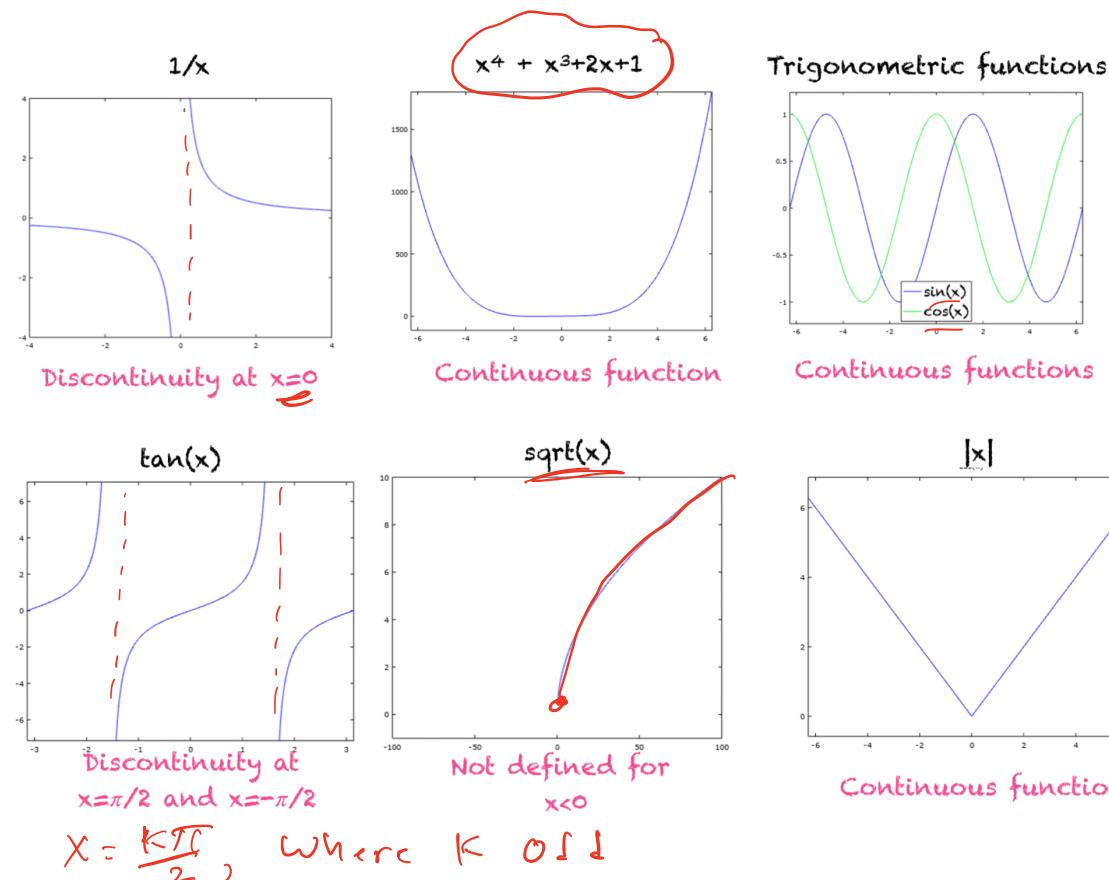
$$\cancel{a} \in \underline{A}$$

implies

$$\lim_{x \rightarrow a} f(x) = f(\cancel{a}).$$

# Continuity Idea

Continuous functions have no breaks, i.e. if you were to draw them you would never need to lift your pencil.



<https://machinelearningmastery.com/continuous-functions/>

# Useful Theorem

## Theorem

If  $f$  is continuous at  $b$  and  $\lim_{x \rightarrow a} g(x) = b$ , then

$$\lim_{x \rightarrow a} f(g(x)) = f\left(\lim_{x \rightarrow a} g(x)\right) = f(b).$$

$$\lim_{x \rightarrow a} f(\underline{g(x)}) = f\left(\lim_{x \rightarrow a} g(x)\right)$$

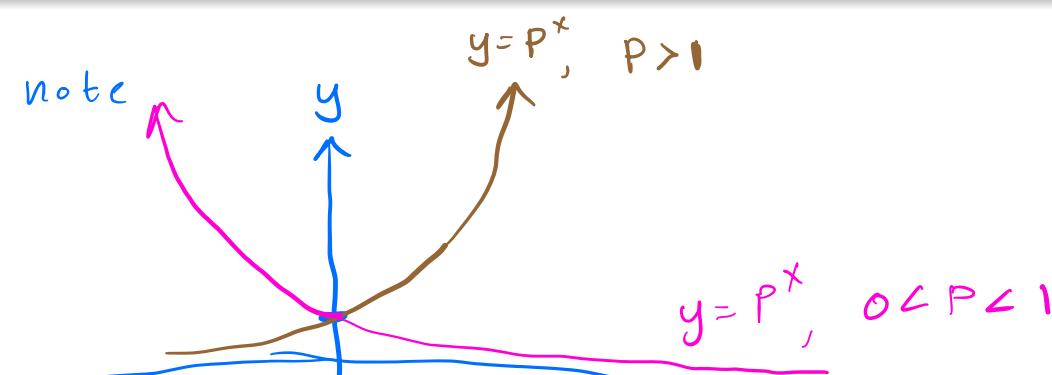
# Example

## Example

Suppose  $p > 0$ . Compute  $\lim_{x \rightarrow \infty} p^{1/x}$ .

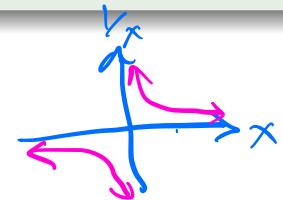
Sol

First, note



Note: For  $p > 0$ ,  $p^x$  is cont. everywhere. So ...

$$\lim_{x \rightarrow \infty} p^{1/x} = p^{\lim_{x \rightarrow \infty} 1/x} = p^0 = 1.$$



# Derivatives

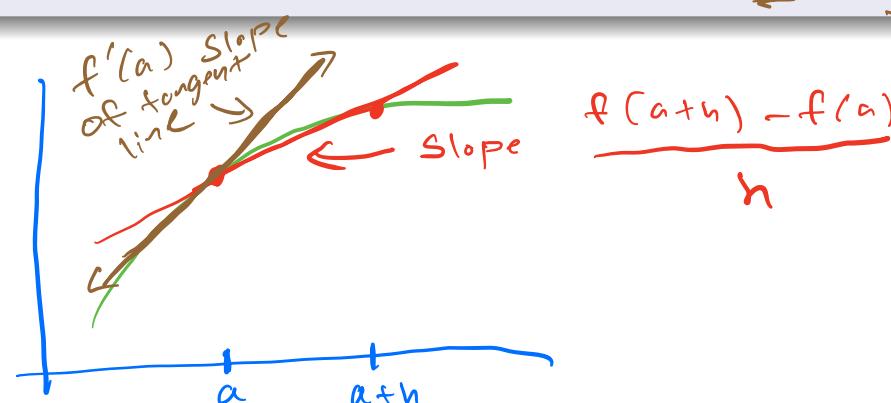
# Derivatives

## Definition

- (a) The **derivative of a function  $f$  at a number  $a$**  is

$$f'(a) = \lim_{h \rightarrow 0} \frac{f(a+h) - f(a)}{h}.$$

- (b) The function  $f$  is differentiable on a set  $A$  if  $f'(a)$  exists for all  $a$  in  $A$ .



# Notation

Leibniz notation is frequently used:

$$\frac{df}{dx} = \underline{\underline{f'(x)}} \quad \text{and} \quad \left. \frac{df}{dx} \right|_{x=a} = \underline{\underline{f'(a)}}.$$

The respective second and third derivatives are written

$$\frac{d^2f}{dx^2} = f''(x) \quad \text{and} \quad \frac{d^3f}{dx^3} = f'''(x)$$

For the  $k$ -th derivatives, where  $k > 3$ , we use the notation

$$\frac{d^k f}{dx^{\underline{\underline{k}}}} = f^{(\underline{\underline{k}})}(x).$$

# Derivatives Example

## Example

Let

$$f(x) = \begin{cases} xe^{-x^2-x^{-2}}, & x \neq 0 \\ 0, & x = 0. \end{cases}$$

Compute  $f'(0)$ .

Sol

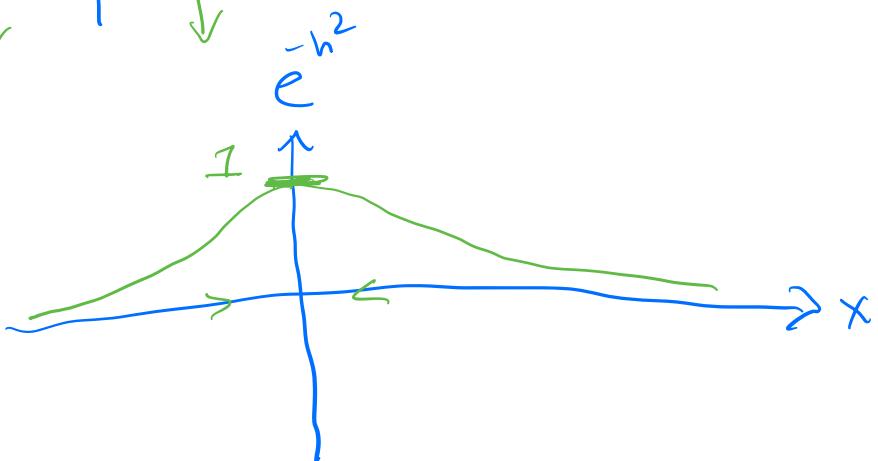
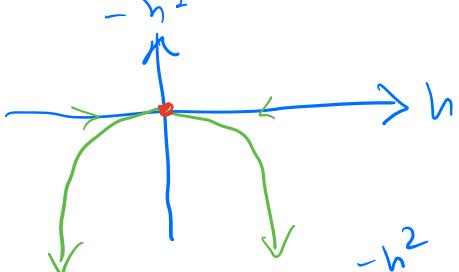
$$\begin{aligned} f'(0) &= \lim_{h \rightarrow 0} \frac{f(0+h) - f(0)}{h} = \lim_{h \rightarrow 0} \frac{xe^{-h^2-h^{-2}} - 0}{h} \\ &= \lim_{h \rightarrow 0} e^{-h^2-h^{-2}} = e^{-h^2} \cdot e^{-h^{-2}} \\ &= \lim_{h \rightarrow 0} e^{-h^2} \cdot \lim_{h \rightarrow 0} e^{-h^{-2}} = e^{-\infty} = 0 \end{aligned}$$

$$-h^{-2}$$



$$\lim_{h \rightarrow 0} e^{-h^2} = ?$$

$$\begin{aligned}\lim_{h \rightarrow 0} e^{-h^2} &= e^{\lim_{h \rightarrow 0} -h^2} \\ &= e^0 \\ &= 1\end{aligned}$$



# Numerical Approximation

It is often helpful to numerically approximate  $f'$ . This can be done by choosing a small value of  $h$  and calculating

$$\frac{f(x + h) - f(x)}{h}.$$

The value  $h$  can be positive or negative. Often, a better numerical approach is to consider positive and negative values of  $h$  at the same time and take the average:

$$\frac{1}{2} \cdot \frac{f(x + h) - f(x)}{h} + \frac{1}{2} \cdot \frac{f(x - h) - f(x)}{-h} = \frac{f(x + h) - f(x - h)}{2h}.$$

Tends to converge to  $f'$  a little faster

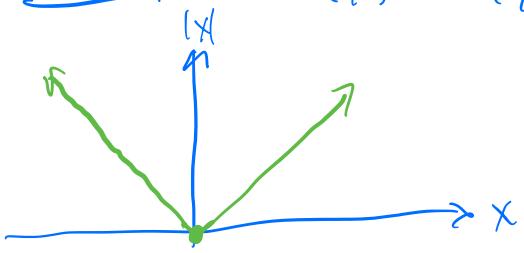
where  $h > 0$ .

Note

$$\frac{f(x+h) - f(x-h)}{2h}, \quad h > 0$$

tends to go to  $f'$  faster when  $f'$  exists. But the ratio something odd if  $f'$  doesn't exist.

Example



$$f(x) = |x|$$

$$f'(0) \text{ DNE}$$

But

$$\begin{aligned} & \frac{f(0+h) - f(0-h)}{2h} \\ &= \frac{|h| - |-h|}{2h} \\ &= \frac{h - h}{2h} \\ &= 0 \end{aligned}$$

Since  $f'(0)$  doesn't exist, we bad answer

# Python Example

## Example

Use Python to graph  $f$  and  $f'$  on the interval  $[-2, 2]$ , where

$$f(x) = \begin{cases} xe^{-x^2-x^{-2}}, & x \neq 0 \\ 0, & x = 0. \end{cases}$$

Use a numerical approximation for  $f'$  with  $h = 0.001$ .

# Python Example Cont.

```
# Import modules
import numpy as np
import matplotlib.pyplot as plt

# Use latex
plt.rcParams['text.usetex'] = True

# Use Seaborn style
plt.style.use('seaborn')

# Define f
f = lambda x: x * np.exp(-x**2 - x**-2) if
    x != 0 else 0
    means not equal
# Define h
h = 0.001

# Use numerical approximation
f_prime = lambda x: (f(x + h) - f(x - h))
    /(2 * h)

# Get the x-values
x_vals = np.linspace(-2, 2, 100)

# Get the two sets of y-values
y1_vals = [f(x) for x in x_vals]
y2_vals = [f_prime(x) for x in x_vals]
```

```
# Generate the plot for f
plt.plot(x_vals, y1_vals, label = r"$f$")

# Generate the plot for f'
plt.plot(x_vals, y2_vals, label = r"$f'$")

# Label the x-axis
plt.xlabel(r'$x$')

# Label the y-axis
plt.ylabel(r'$y$')

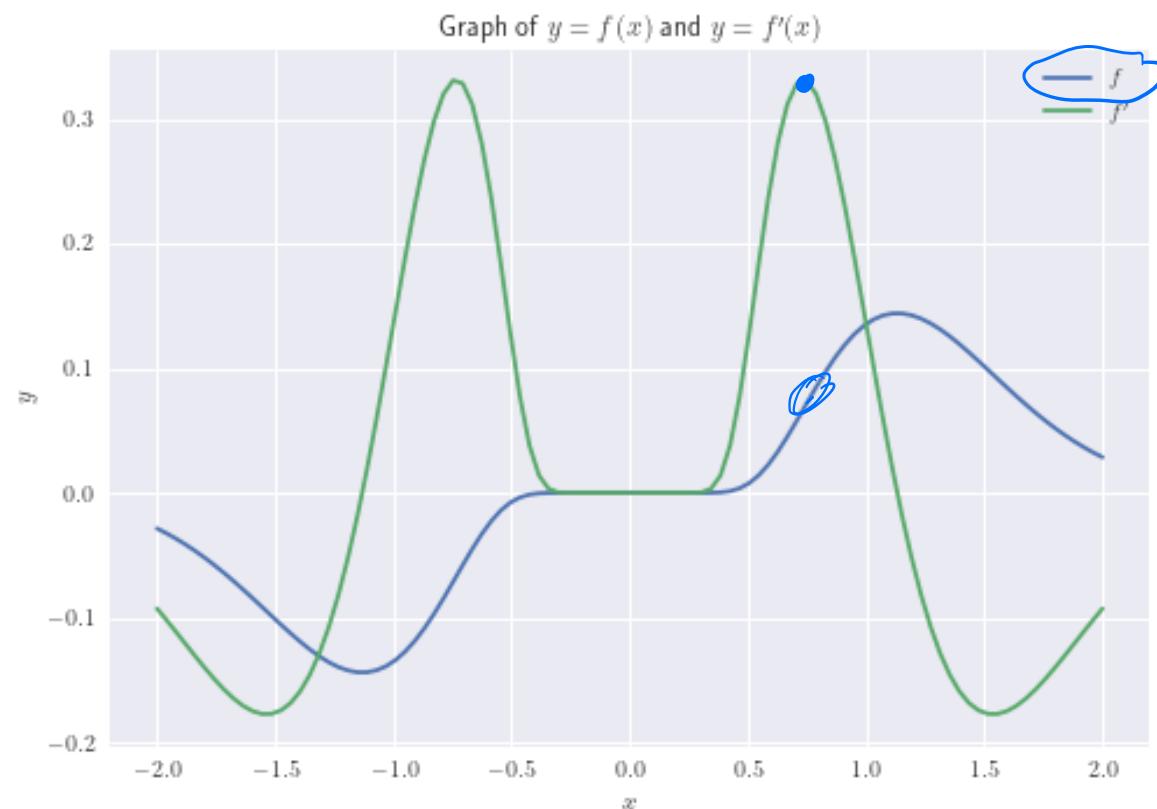
# Give the graph a title
plt.title(r"Graph of $y = f(x)$ and $y = f'(x)$")

# Create a legend
plt.legend()

# Save the figure
plt.savefig(path + r'Images/ex1-2.png')

# Display the plot
plt.show()
```

# Python Example Result



# Derivative Properties

## Theorem

Suppose  $\alpha$  and  $\beta$  are constants and  $f'$  and  $g'$  exist.

(a)  $\frac{d}{dx}(\alpha f + \beta g) = \alpha f' + \beta g'.$

(b)  $\frac{d}{dx}(f \cdot g) = g \cdot f' + f \cdot g' \leftarrow \text{Product rule}$

(c)  $\frac{d}{dx}\left(\frac{f}{g}\right) = \frac{\underline{f'} \cdot \underline{g} - \underline{f} \cdot \underline{g'}}{\underline{g^2}} \leftarrow \text{Quotient rule}$

(d)  $\frac{d}{dx}(f \circ g) = (\underline{f' \circ g}) \cdot g' \leftarrow \text{Chain rule}$

$$\frac{d}{dx}(f(u)) = f'(u) \cdot \frac{du}{dx}$$

# Useful Derivative Formulas

Suppose  $a > 0$ .

- $\frac{d}{dx}(x^n) = nx^{n-1}$
- $\frac{d}{dx}(e^x) = e^x$
- $\frac{d}{dx}(a^x) = a^x \ln a$
- $\frac{d}{dx}(\ln|x|) = \frac{1}{x}, \quad x \neq 0$
- $\frac{d}{dx}(\log_a|x|) = \frac{1}{x \ln a}, \quad x \neq 0$
- $\frac{d}{dx}(\sin x) = \cos x$
- $\frac{d}{dx}(\cos x) = -\sin x$
- $\frac{d}{dx}(\tan x) = \sec^2 x$
- $\frac{d}{dx}(\arctan x) = \frac{1}{1+x^2}$

# Derivative Example

## Example

$$\frac{d}{dx} \left( e^{1/x} \sin x \right) = \frac{1}{x^2} \left( e^{1/x} \sin x \right)$$

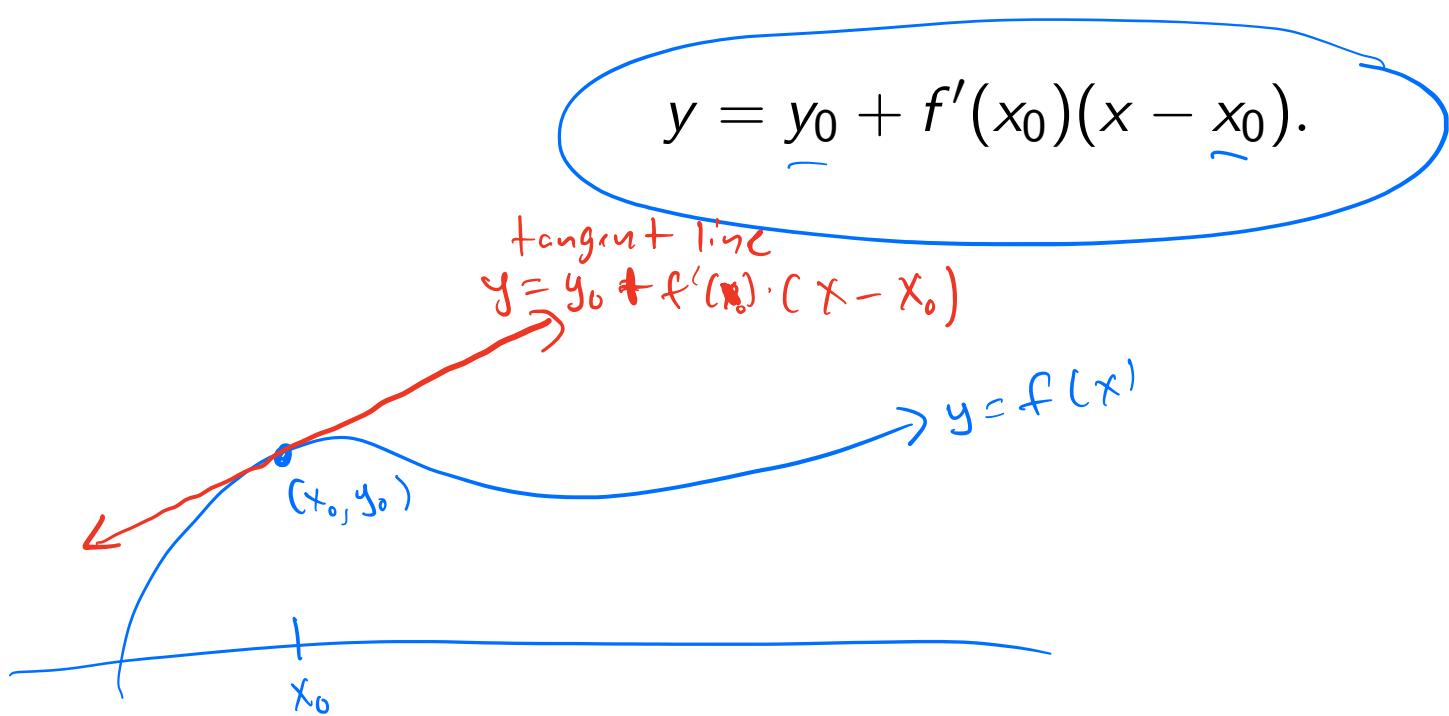
We will need

- Product rule
- Chain rule
- Power rule

$$\begin{aligned}\underline{\text{Sol}} \quad \frac{d}{dx} (e^{1/x} \sin x) &= \frac{1}{x^2} (e^{1/x}) \cdot \sin x + e^{1/x} \cdot \frac{d}{dx} (\sin x) \\ &= -\frac{1}{x^2} e^{1/x} \sin x + e^{1/x} \cos x \\ &= \boxed{\left( \cos x - \frac{\sin x}{x^2} \right) e^{1/x}}\end{aligned}$$

# Tangent Lines

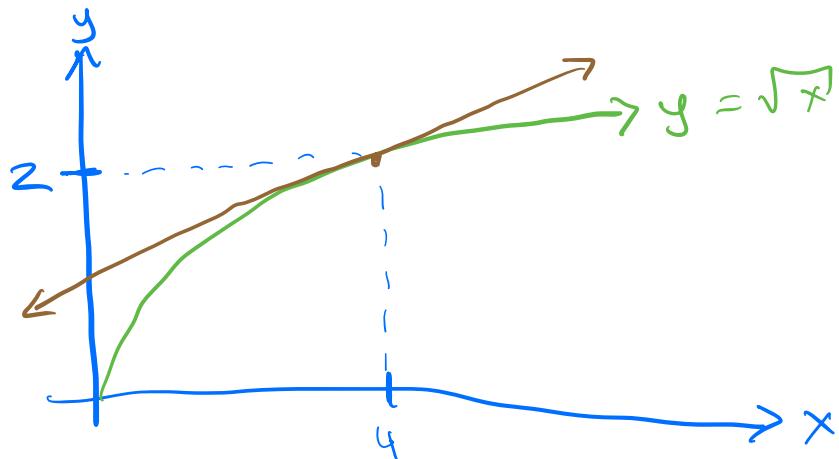
The tangent line of the graph of  $y = f(x)$  at  $(\underline{x_0}, \underline{y_0})$  is



# Tangent Line Example

## Example

Approximate  $\sqrt{3.9}$ .



Sol  $(x_0, y_0) = (4, 2)$ ;  $f(x) = \sqrt{x} = x^{1/2} \Rightarrow f'(x) = \frac{1}{2} x^{-1/2} = \frac{1}{2\sqrt{x}}$

• Calculate the tangent line at  $x=4$

• Plug in 3.9

This should give us a value close to  $\sqrt{3.9}$

$$\rightarrow f'(4) = \frac{1}{2\sqrt{4}} = \frac{1}{2 \cdot 2} = \frac{1}{4}$$

Hence our tangent line is

$$\begin{aligned}
 y &= 2 + \frac{1}{4}(x - 4) \\
 &= 2 + \frac{1}{4}x - 1 \\
 &= 1 + \frac{1}{4}x. \quad \leftarrow \text{good approx of } \sqrt{x} \text{ for } x \text{ close to 4}
 \end{aligned}$$

$$\Rightarrow \sqrt{3.9} \approx 1 + \frac{1}{4} \cdot 3.9 = 1 + 0.975 = 1.975$$

$$\begin{array}{r}
 \overset{975}{4} \overline{)3.900} \\
 -36 \\
 \hline
 30 \\
 -28 \\
 \hline
 20
 \end{array}$$

$$\underline{\text{Check: }} \sqrt{3.9} \approx 1.974\underset{1}{8}41766\dots$$

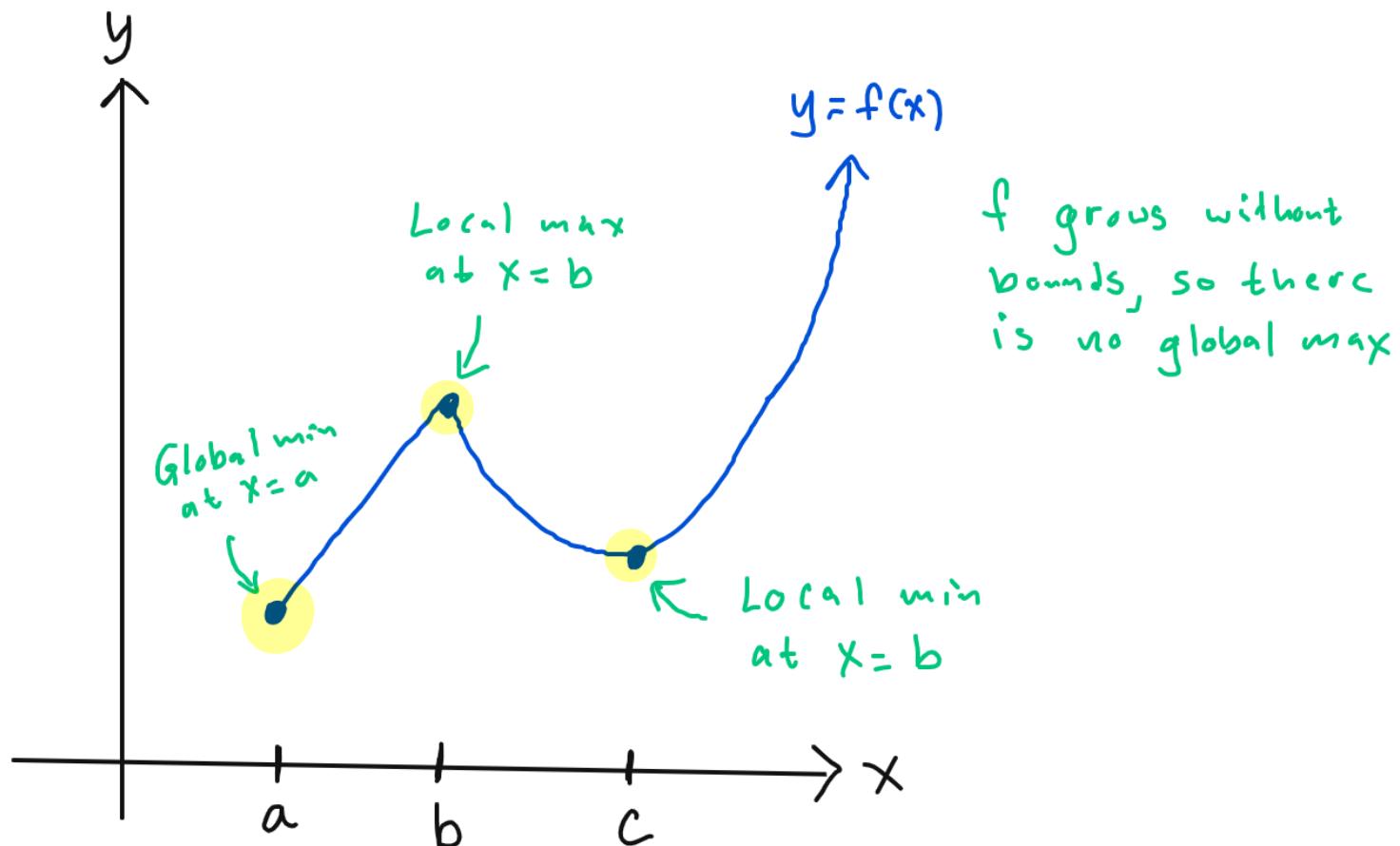
# Local and Global Extrema

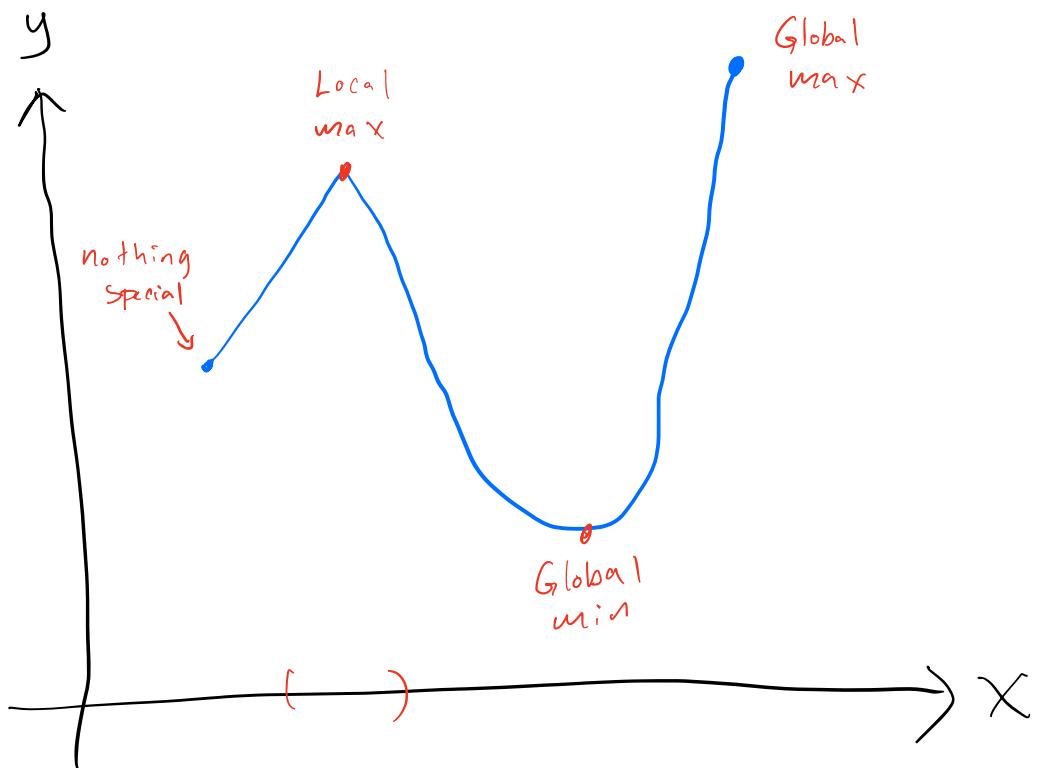
## Definition

Let  $f$  be a function defined on domain  $D$ .

- (a) The **global maximum** of  $f$  is at  $c$  if  $f(c) \geq f(x)$  for all  $x$  in  $D$ . The **global minimum** of  $f$  is at  $c$  if  $f(c) \leq f(x)$  for all  $x$  in  $D$ . The global maximum and global minimum values of  $f$  are called the **global extrema** of  $f$ .
- (b) A **local maximum** of  $f$  is at  $c$  if there is an interval  $(a, b)$  such that  $f(c) \geq f(x)$  for all  $x$  in  $(a, b)$  and  $a < c < b$ . Similarly, a **local minimum** of  $f$  is at  $c$  if there is an interval  $(a, b)$  such that  $f(c) \leq f(x)$  for all  $x$  in  $(a, b)$  and  $a < c < b$ . The local maximum and local minimum values of  $f$  are called the **local extrema** of  $f$ .

# Local and Global Extrema Example





# Extreme Value Theorem

## Theorem (Extreme Value Theorem)

If  $f$  is continuous on a closed interval  $[a, b]$ , then  $f$  attains a global maximum value  $f(c)$  and a global minimum value  $f(d)$  for some numbers  $c$  and  $d$  in  $[a, b]$ .

# Increasing and Decreasing Functions

For  $f$  differentiable.

- If  $\underline{f'(x)} > 0$ , then  $f$  is increasing at  $\underline{x}$ .
- If  $\underline{f'(x)} < 0$ , then  $f$  is decreasing at  $\underline{x}$ .

Increasing means:  $f(x+h) - f(x) > 0$  for  $h > 0$  small.

$$\Rightarrow \frac{f(x+h) - f(x)}{h} > 0$$

$$\Rightarrow f'(x) \geq 0$$

Decreasing means:  $f(x+h) - f(x) < 0$  for  $h > 0$  small

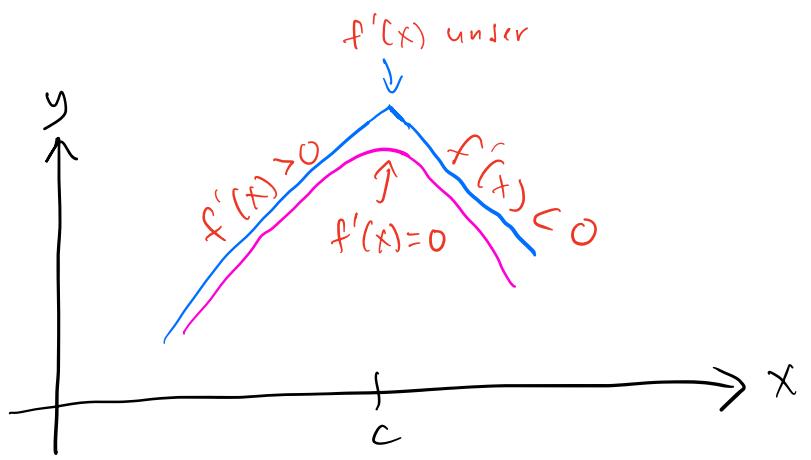
$$\Rightarrow \frac{f(x+h) - f(x)}{h} < 0$$

$$\Rightarrow f'(x) \leq 0$$

# First Derivative Test

Suppose  $x = c$  is a critical number, i.e.  $c$  is in the domain of  $f$  and  $f'(c)$  is 0 or undefined.

- (a) If  $f'$  changes from positive to negative at  $x = c$ , then  $f$  has a local maximum at  $x = c$ .
- (b) If  $f'$  changes from negative to positive at  $x = c$ , then  $f$  has a local minimum at  $x = c$ .
- (c) If  $f'$  does not change sign at  $x = c$ , then  $f$  has no local extremum at  $x = c$ .



Local max @  $x=c$   
Since  $f'$  changed from  
positive to negative at  
 $x=c$ .

Same idea for a local min.

# Optimization Example

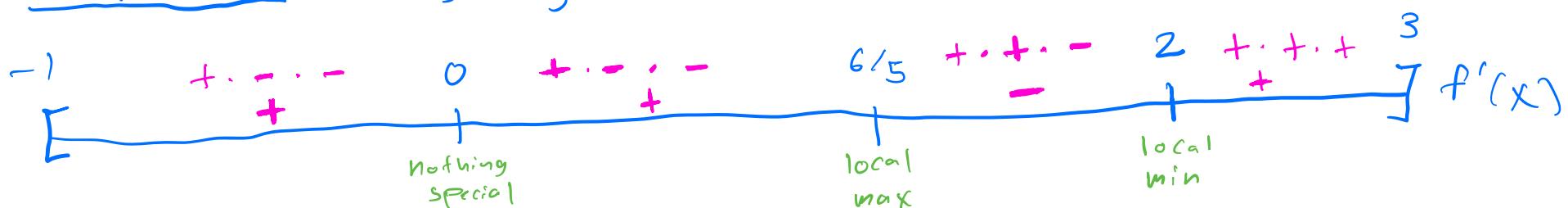
## Example

Find the local and global extrema of the function  $f(x) = x^3(x - 2)^2$ . Suppose the domain of  $f$  is the closed interval  $[-1, 3]$ .

Observation: Global extrema occur at endpoints or local extrema.  
To find local extrema, I'll use the first derivative test.

Sol  $f(x) = x^3(x - 2)^2 \Rightarrow f'(x) = 3x^2(x - 2)^2 + x^3 \cdot 2(x - 2) \cdot 1$   
 $= 3x^2(x - 2)^2 + 2x^3(x - 2)$   
 $= x^2(3(x - 2) + 2x)(x - 2)$   
 $= x^2(5x - 6)(x - 2)$

Critical numbers:  $x = 0, 6/5, 2$



$$f(x) = x^3(x-2)^2$$

$$f(-1) = (-1)^3(-3)^2 = -1 \cdot 9 = -9$$

$$\underline{f\left(\frac{6}{5}\right)} = \left(\frac{6}{5}\right)^3 \left(\frac{6}{5} - 2\right)^2 = \frac{216}{125} \cdot \frac{16}{25} \approx 1.10592$$

$$f(2) = 2^3 \cdot (2-2)^2 = 0$$

$$\underline{f(3) = 3^3 \cdot (3-2)^2 = 27}$$

Global min of  $-9$  at  $x = -1$

Global max of  $27$  at  $x = 3$

Local max of  $\approx 1.10592$  at  $x = \frac{6}{5}$

Local min of  $0$  at  $x = 2$

# Second Derivative Test

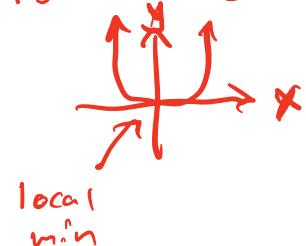
Suppose  $f'(c) = 0$ .

- (a) If  $f''(c) > 0$ , then  $f$  has a local minimum at  $x = c$ .
- (b) If  $f''(c) < 0$ , then  $f$  has a local maximum at  $x = c$ .
- (c) If  $f''(c) = 0$  or is undefined, then the test fails.



The test fails in some obvious cases.

$$f(x) = x^4$$



$$f'(x) = 4x^3 \quad \begin{matrix} \text{easy to see} \\ \text{crit. at } x=0 \end{matrix}$$

$$\Rightarrow f''(x) = 12x^2$$

$$\Rightarrow f''(0) = 0 \quad \begin{matrix} \text{test fails} \\ \therefore \end{matrix}$$

# Local Extrema Example

## Example

Find all local extrema of  $g(x) = x^4 - 4x^3$ .

Sol  $g(x) = x^4 - 4x^3 \Rightarrow g'(x) = 4x^3 - 12x^2 = 4x^2(x-3)$

The crit. values are when  $g'(x) = 0$ . So, when

$$4x^3 - 12x^2 = 0$$

$$\Rightarrow 4x^2(x-3) = 0$$

$$\Rightarrow x=0 \text{ or } x=3$$

Diff. again to find whether these are local mins or maxs:

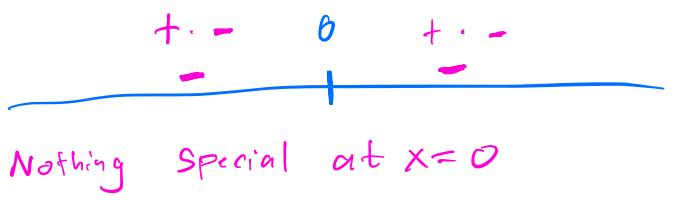
$$g''(x) = 12x^2 - 24x$$

$$g''(0) = 0$$

The test failed, let's use first deriv. test

$$g''(3) = 12 \cdot (3)^2 - 24(3) = 108 - 72 = 36$$

Since  $g''(3) > 0$ , local min at  $x=3$ .



Let's plug 3 into  $g$ , so we can find y-value of local min

$$g(3) = 3^4 - 4(3)^3$$

$$= 81 - 4 \cdot 27$$

$$= 81 - 108$$

$$= -27$$

Local min of  $-27$  at  $x=3$ .  
No local max.

# L'Hôpital's Rule

## Theorem (L'Hôpital's Rule)

Suppose  $f$  and  $g$  are differentiable on the open interval  $(a, b)$  and  $g'(x) \neq 0$  for all  $x$  in  $(a, b)$ , where  $a \leq x < b \leq \infty$ . If

$$\lim_{x \rightarrow a} \frac{f'(x)}{g'(x)} = L$$

and either

$$\lim_{x \rightarrow a} f(x) = \lim_{x \rightarrow a} g(x) = 0 \quad \text{or} \quad \lim_{x \rightarrow a} f(x) = \lim_{x \rightarrow a} g(x) = \infty,$$

then

$$\lim_{x \rightarrow a} \frac{f(x)}{g(x)} = L.$$

# L'Hôpital's Rule Cont.

## Example

Prove  $\lim_{x \rightarrow \infty} x^{1/x} = 1$ .

Sol  
 $\lim_{x \rightarrow \infty} x^{1/x} \rightarrow \infty^0$  ← not a ratio, no so clear

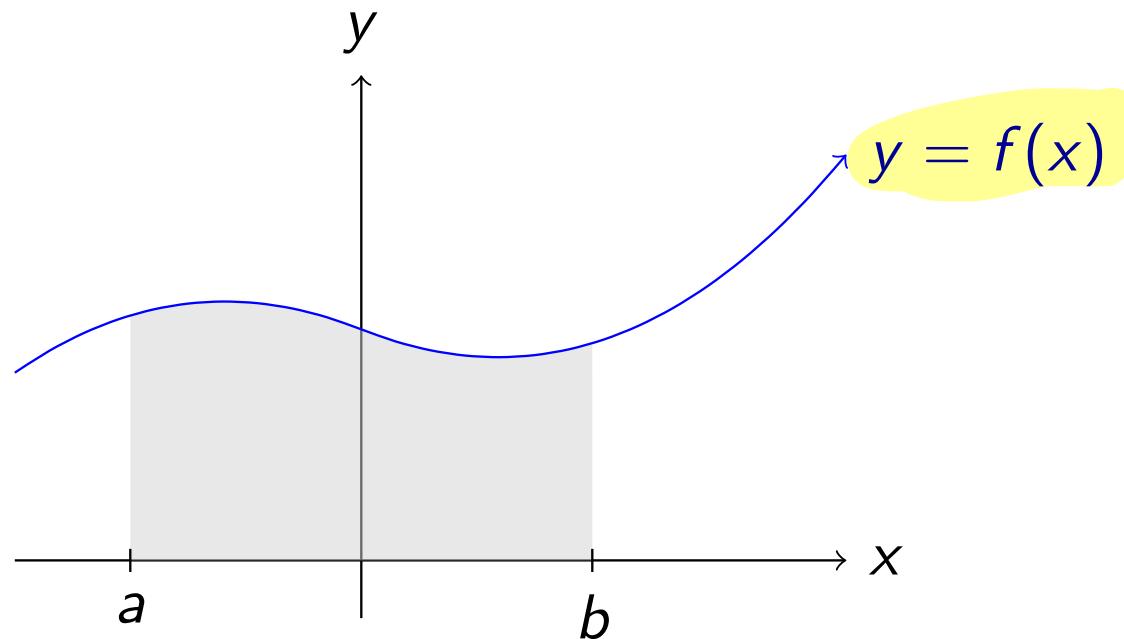
Note:  $e^{\ln x} = x$

$$\lim_{x \rightarrow \infty} x^{1/x} = \lim_{x \rightarrow \infty} (e^{\ln x})^{1/x} = \lim_{x \rightarrow \infty} e^{\ln x / x}$$

$$\begin{aligned} &= e^{\lim_{x \rightarrow \infty} \frac{\ln x}{x}} \stackrel{\text{LH}}{=} e^{\lim_{x \rightarrow \infty} \frac{1/x}{1}} = e^{\lim_{x \rightarrow \infty} 1/x} = e^0 = 1 \quad \boxed{1} \end{aligned}$$

# Integration

# Definite Integration



The motivating problem for the definite integral is finding area under the graph  $y = f(x)$  for  $a \leq x \leq b$ .

# Riemann Sum

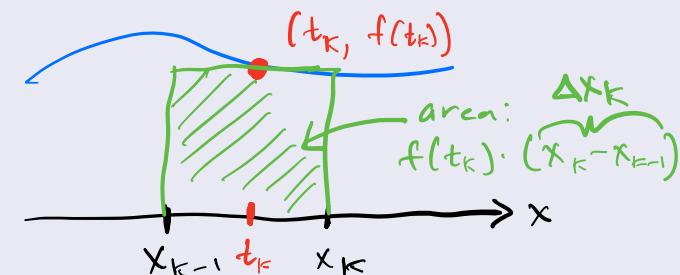
## Definition

Suppose we have a function  $f$  defined on the interval  $[a, b]$ . Consider a **partition pair**  $P$  and  $T$ ;  $P = (x_0, x_1, \dots, x_n)$  and  $T = (t_1, t_2, \dots, t_n)$ , where

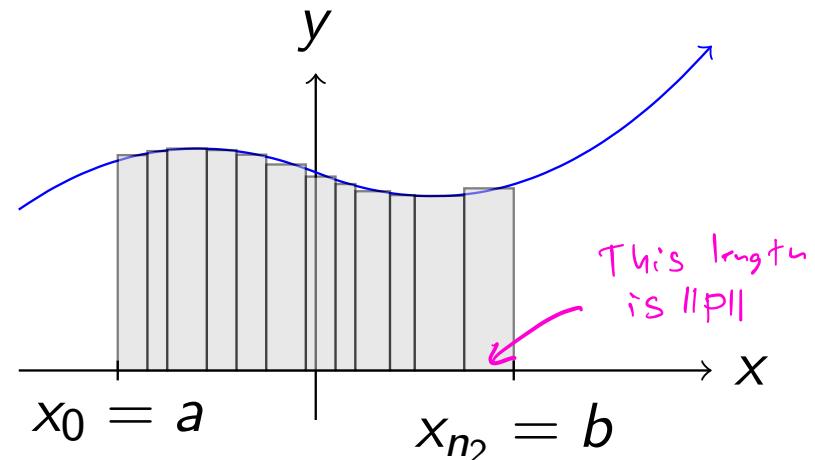
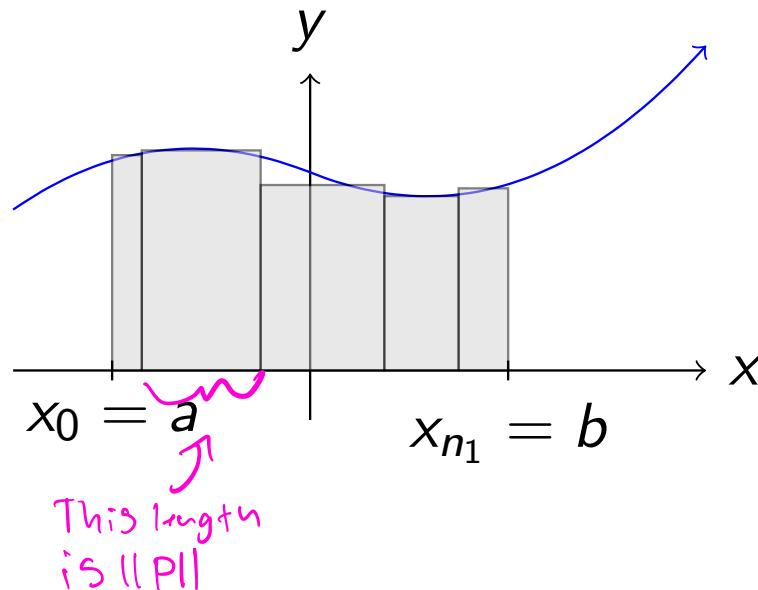
$$a = x_0 \leq t_1 \leq x_1 \leq \dots \leq x_{n-1} \leq t_n \leq x_n = b.$$

The **Riemann sum** corresponding to the partition pair  $P$  and  $T$  is defined to be

$$\sum_{k=1}^n f(t_k) \Delta x_k.$$



# Finer and Finer Partition



The rectangles in the right figure do a better job of approximating the area under the curve. This is because the partition in the second figure is “finer”, i.e. uses more  $x$ -values, than the first.

# Partition Mesh

## Definition

The **mesh** of partition  $P$  is

$$\|P\| = \max\{\Delta x_1, \Delta x_2, \dots, \Delta x_n\}.$$

As  $\|P\| \rightarrow 0$ , the approximation becomes better and better.

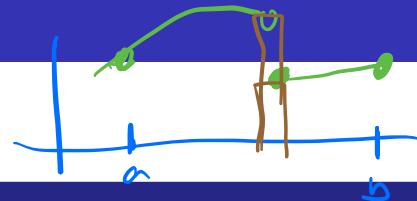
## Definition

The **Riemann integral** of  $f$  over the interval  $[a, b]$  is

$$\int_a^b f(x) \, dx = \lim_{\|P\| \rightarrow 0} \sum_{k=1}^n f(t_k) \Delta x_k$$

whenever the limit converges.

# Integral Theorems



## Theorem

A bounded function on an interval  $[a, b]$  is Riemann integrable if it is continuous for all but a finite number of points.

## Theorem

If  $f$  and  $g$  are Riemann-integrable on  $[a, b]$  and  $\alpha$  and  $\beta$  are constants, then the following hold.

$$(a) \int_a^b (\alpha f(x) + \beta g(x)) dx = \alpha \int_a^b f(x) dx + \beta \int_a^b g(x) dx$$

$$(b) \int_a^b f(x) dx = \int_a^c f(x) dx + \int_c^b f(x) dx \text{ for any } c \text{ in } [a, b]$$

# Analytic Example

## Example

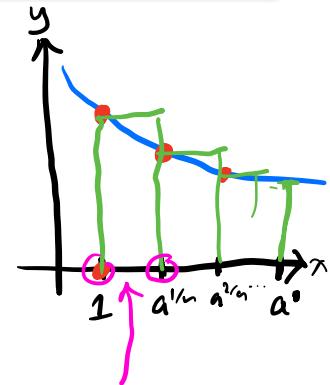
Prove  $\int_1^a \frac{dx}{x} = \ln a$  for  $a > 1$ . Use partition pairs of the form  
 $P = (1, a^{1/n}, a^{2/n}, \dots, a)$  and  $T = (1, a^{1/n}, a^{2/n}, \dots, a^{(n-1)/n})$ .

Sol

Let's compute the Riemann sum:

$$\begin{aligned}\sum_{k=1}^n f(t_k) \Delta x_k &= \sum_{k=1}^n \left( \frac{1}{a^{(k-1)/n}} \right) \cdot (a^{k/n} - a^{(k-1)/n}) \\ &= \sum_{k=1}^n \frac{a^{k/n}}{a^{(k-1)/n}} - 1 \\ &= \sum_{k=1}^n a^{1/n} - 1 \quad \text{no } k \text{ here, so just summing } a^{1/n} - 1 \text{ n-times} \\ &= n(a^{1/n} - 1)\end{aligned}$$

$$\Rightarrow \int_1^a \frac{dx}{x} = \lim_{n \rightarrow \infty} n(a^{1/n} - 1) = \lim_{n \rightarrow \infty} \frac{a^{1/n} - 1}{1/n} = \lim_{x \rightarrow \infty} \frac{a^{1/x} - 1}{1/x} \rightarrow 0$$



Recall:

$$\frac{d}{du} (a^u) = a^u \cdot u \ln a$$

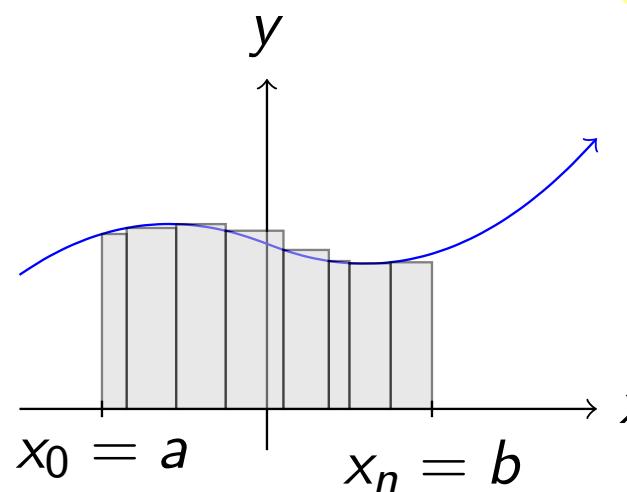
LH

$$= \lim_{x \rightarrow \infty} \frac{a^{1/x} \cdot -1/x^2 \cdot \ln a - 0}{-1/x^2}$$
$$= \lim_{x \rightarrow \infty} \frac{a^{1/x} \cdot -1/x^2 \cdot \ln a}{-1/x^2}$$
$$= \lim_{x \rightarrow \infty} a^{1/x} \cdot \ln a$$
$$= 1 \cdot \ln a$$
$$= \ln a$$

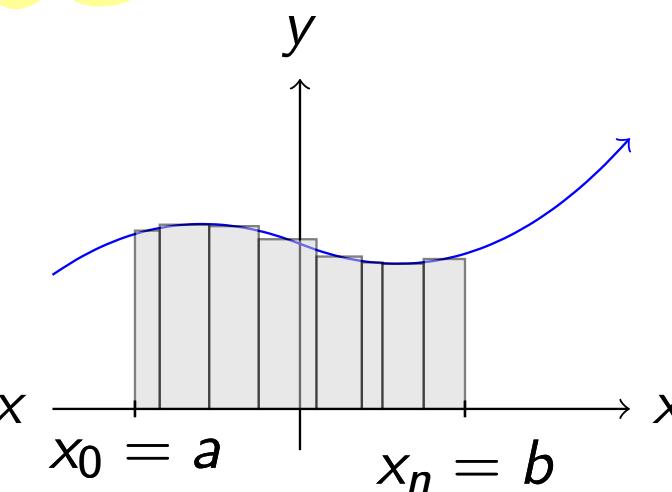
# Selection of $T$

The most common choices for  $T$  are

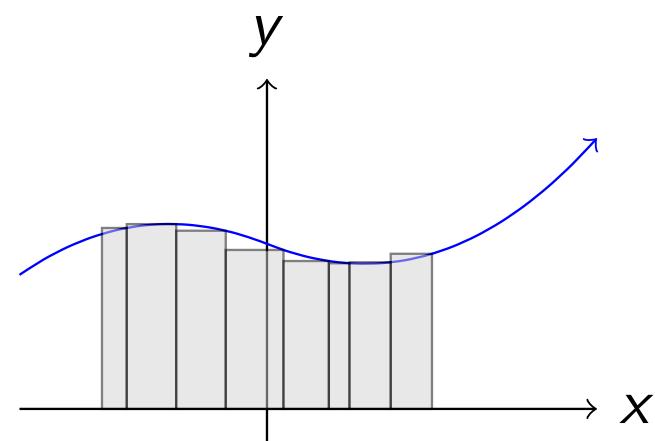
- Left endpoints:  $t_k = x_{k-1}$
- Midpoints:  $t_k = \frac{x_{k-1} + x_k}{2}$
- Right endpoints:  $t_k = x_k$



Left endpoints



Midpoints



Right endpoints

# Selection of $P$

The most common choice for  $P$ , by far, is the uniform partition

$$x_k = a + k\Delta x$$

and

$$\Delta x = \frac{b - a}{n}.$$

# Useful formulas

When working analytic problems with a uniform partition, these formulas come up a lot

$$\sum_{k=1}^n k = \frac{n(n+1)}{2}, \quad \sum_{k=1}^n k^2 = \frac{n(n+1)(2n+1)}{6},$$

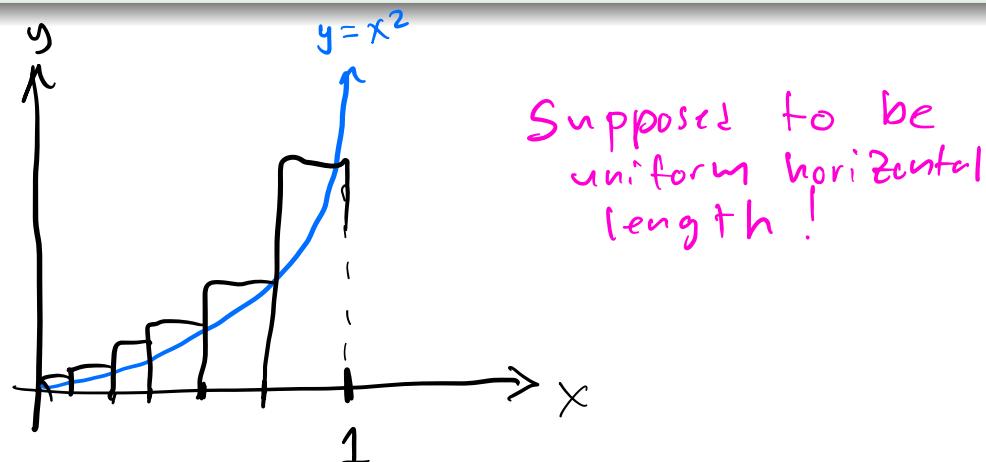
and

$$\sum_{k=1}^n k^3 = \frac{n^2(n+1)^2}{4} = \left[ \frac{n(n+1)}{2} \right]^2.$$

# Uniform Partition Example

## Example

Use uniform partitions and right endpoints to find  $\int_0^1 x^2 dx$ .



- Steps:
1. Find  $\Delta x_k = \Delta x$
  2. Find  $x_k = a + k\Delta x$  ← right endpoints
  3. Find  $f(x_k) \Delta x$
  4. Find  $\sum_{k=1}^n f(x_k) \Delta x$
  5. Find  $\lim_{n \rightarrow \infty} \sum_{k=1}^n f(x_k) \Delta x$

Sol

$$1. \Delta x = \frac{1-0}{n} = \frac{1}{n}$$

$$2. x_k = 0 + k \cdot \Delta x \leftarrow \text{right end points}$$
$$= k/n$$

$$3. f(x_k) \Delta x = (k/n)^2 \cdot \frac{1}{n} = \frac{k^2}{n^3}$$

$$4. \sum_{k=1}^n \frac{k^2}{n^3} = \frac{1}{n^3} \sum_{k=1}^n k^2 = \frac{1}{n^3} \cdot \frac{n(n+1)(2n+1)}{6}$$

$$5. \lim_{n \rightarrow \infty} \frac{1}{n^2} \cdot \frac{n(n+1)(2n+1)}{6} = \lim_{n \rightarrow \infty} \frac{\cancel{n}(n+1)(2n+1)}{6n^2} \cdot \frac{1}{\cancel{n}^2}$$
$$= \lim_{n \rightarrow \infty} \frac{(1+1/n)(2+1/n)}{6}$$

$$= \frac{(1+0)(2+0)}{6}$$

$$= \boxed{\frac{1}{3}}$$

# Python Code

```
# Define Riemann sum
def riemann_sum(f, P, pts):
    # Sort values
    P = np.sort(P) ← makes sure values are from smallest to biggest
    # Calculate Delta x
    dx_vals = np.diff(P) ← takes diff. of consecutive terms
    # Calculate the number of terms
    # Note: dx_vals has one fewer element than P
    N = len(dx_vals)

    # Define T
    if pts == 'left':
        T = [P[i] for i in range(0, N)] ← 0, 1, 2, ..., N-1 ← last value is not included
    elif pts == 'right':
        T = [P[i + 1] for i in range(0, N)] ← range(N)
    elif pts == 'mid':
        T = [0.5 * P[i] + 0.5 * P[i + 1] for i in range(0, N)]
    # Get area of rectangles
    rectangles = [f(T[i]) * dx_vals[i] for i in range(0, N)]
    # Return sum
    return np.sum(rectangles) ← height with width
    Take sum of rectangle areas to get Riemann sum
```

$P = (x_0, x_1, x_2, \dots, x_{N-1}, x_N)$

$T = \left(\frac{x_0+x_1}{2}, \frac{x_1+x_2}{2}, \dots, \frac{x_{N-1}+x_N}{2}\right)$

# Improper Integral

## Definition

- (a) If the integrals exists for every  $t \geq a$  and for every  $s \leq b$ , then

$$\int_a^{\infty} f(x) dx = \lim_{t \rightarrow \infty} \int_a^t f(x) dx$$

and

$$\int_{-\infty}^b f(x) dx = \lim_{s \rightarrow -\infty} \int_s^b f(x) dx.$$

- (b) For any  $c$  in  $\mathbb{R}$ , if both  $\int_c^{\infty} f(x) dx$  and  $\int_{-\infty}^c f(x) dx$  converge, then

$$\int_{-\infty}^{\infty} f(x) dx = \int_{-\infty}^c f(x) dx + \int_c^{\infty} f(x) dx.$$

# Python Example

## Example

Use pandas to create a data frame of Riemann sums with left endpoints, midpoints, and right endpoints, and uniform partitions to approximate  $\int_0^{\infty} e^{-x^2/2} dx$ . Consider  $n = 10, 50, 100, 500$ , and  $1000$ .

# Python Example Cont.

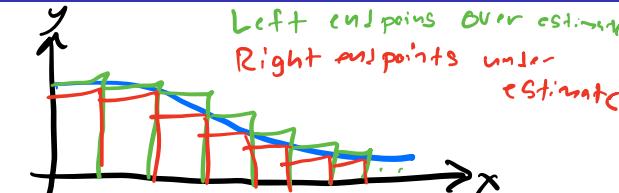
**Solution.** Since  $e^{-x^2/2}$  goes to 0 rapidly, it's safe to use  $b = \underline{10}$ .

```
# Import pandas
import pandas as pd
# Define function
f = lambda x: np.e**(-x**2/2)
# Define the n-values
n_vals = [10, 50, 100, 500, 1000]
# Define the data frame
results = pd.DataFrame(index = n_vals, columns = ['left', 'mid', 'right'])
# Loop over values
for n in n_vals:
    # We can use np.linspace for a uniform partition
    partition = np.linspace(0, 10, n + 1) ← note includes endpoints
    # Get left endpoint results
    results.loc[n, 'left'] = riemann_sum(f, partition, 'left')
    # Get midpoint results
    results.loc[n, 'mid'] = riemann_sum(f, partition, 'mid')
    # Get right endpoint results
    results.loc[n, 'right'] = riemann_sum(f, partition, 'right')
# Note: screenshot of output is ex1-3
results
```

Assume we've already imported numpy as np  $e^{-10^2/2} = e^{-50} \approx 1.93 \times 10^{-22}$

# Python Example Result

The limit as  $\|P\| \rightarrow 0$  is  $\sqrt{\pi/2} \approx 1.253$ .



$n$	left	mid	right
10	1.753314	1.253314	0.753314
50	1.353314	1.253314	1.153314
100	1.303314	1.253314	1.203314
500	1.263314	1.253314	1.243314
1000	1.258314	1.253314	1.248314

*Little big*      *Little small*

# Indefinite Integral

## Definition

The function  $F$  is an **indefinite integral** or **antiderivative** of  $f$  if  $F'(x) = f(x)$ . We write

$$\int f(x) dx = F(x)$$

to denote this.

Indefinite integrals are only unique up to a constant. For example, two antiderivatives of  $2x$  are  $x^2 + 1$  and  $x^2 - 4$ . To handle all possibilities, we write

$$2x + 0 = 2x - 0$$

$$\int 2x dx = x^2 + C.$$

# Antiderivative Theorems

## Theorem

*Let  $f$  and  $g$  be continuous functions on some domain and let  $\alpha$  and  $\beta$  be real numbers. Then*

$$\int \alpha f(x) + \beta g(x) \, dx = \alpha \int f(x) \, dx + \beta \int g(x) \, dx.$$

# Useful Antiderivative Formulas

- $\int x^n \, dx = \frac{x^{n+1}}{n+1} + C, n \neq -1$
- $\int \frac{dx}{x} = \ln|x| + C$
- $\int \frac{dx}{1+x^2} = \arctan x + C$
- $\int e^x \, dx = e^x + C$
- $\int a^x \, dx = \frac{a^x}{\ln a} + C$
- $\int \sin x \, dx = -\cos x + C$
- $\int \cos x \, dx = \sin x + C$
- $\int \tan x \, dx = -\ln|\cos x| + C$

# Fundamental Theorem of Calculus

## Theorem (Fundamental Theorem of Calculus)

Suppose  $f$  is continuous on the closed interval  $[a, b]$ . Then

(a)  $\int_a^b f(x) \, dx = F(b) - F(a)$ , where  $F'(x) = f(x)$ .

(b)  $\frac{d}{dx} \left( \int_a^x f(t) \, dt \right) = f(x)$

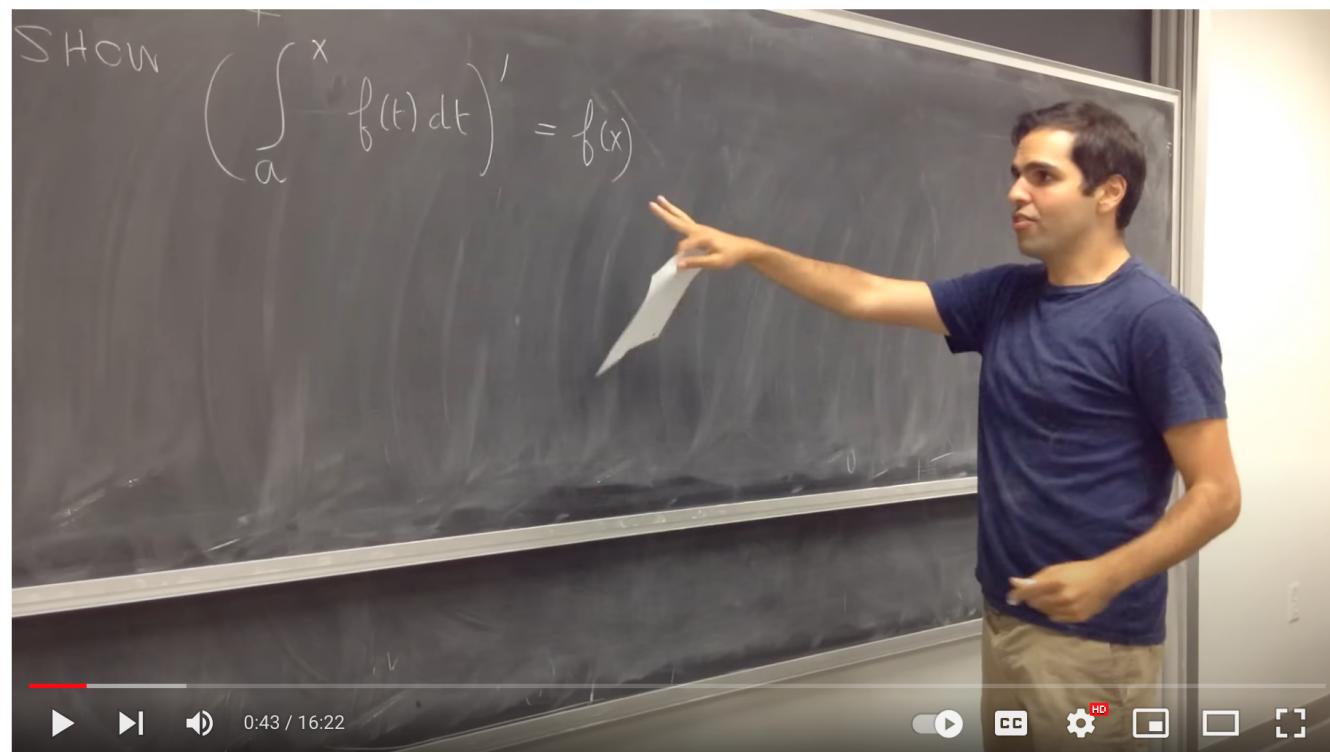
# Fundamental Theorem of Calculus Example

## Example

$$\int_0^2 \max\{x, 1\} dx =$$

# Proof of the Fundamental Theorem on YouTube

Watch Peyam prove part (b) of the Fundamental Theorem of Calculus (<https://youtu.be/4DrCKhCECHo>).



Proof of the Fundamental Theorem of Calculus (the one with differentiation)



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# u-Substitution

## Theorem (u-Substitution)

*Suppose  $g'$  is continuous on the closed interval  $[a, b]$  and  $f$  is continuous on the range of  $g$ . Then*

$$\int_a^b (f \circ g)(x) \cdot g'(x) \, dx = \int_{g(a)}^{g(b)} f(u) \, du.$$

# Example

## Example

$$\int xe^{-x^2/2} dx =$$

# Integration by Parts

## Theorem (Integration by parts)

Suppose  $F$  and  $G$  are differentiable functions,  $F'(x) = f(x)$ , and  $G'(x) = g(x)$ , where  $f$  and  $g$  are continuous. Then

$$\int F(x)g(x) \, dx = F(x)G(x) - \int f(x)G(x) \, dx.$$

# Example

## Example

$$\int \ln x \, dx =$$

# Ordinary Differential Equations

# Ordinary Differential Equations

## Definition

- (a) An **ordinary differential equation** (ODE) involves an unknown function of a single variable and some of its derivatives.
- (b) The **order** of a differential equation is the order of the highest derivative that appears in the equation.

For example,  $xy' = e^{xy}$  is a first order ordinary differential equation, while

$$\frac{d^3x}{dt^3} - 2t \frac{d^2x}{dt^2} + t^2x = \cos t$$

is a third order ordinary differential equation.

# Separable ODEs

## Definition

An ODE of the form

$$\frac{dy}{dx} = F(x, y)$$

is separable if  $F(x, y) = f(x)g(y)$ .

It's relatively easy to solve separable differential equations

$$\frac{dy}{dx} = f(x)g(y) \quad \text{implies} \quad \frac{1}{g(y)} \frac{dy}{dx} = f(x).$$

Hence,

$$\int \frac{1}{g(y)} \frac{dy}{dx} dx = \int f(x) dx \quad \text{implies} \quad \int \frac{1}{g(y)} dy = \int f(x) dx.$$

# Separable ODE Example

## Example

Solve the differential equation

$$\frac{dy}{dt} = \frac{ty + 3t}{t^2 + 1}$$

subject to the initial condition  $y(0) = 2$ .

# Linear ODEs

## Definition

A first order **linear** differential equation is one that can be written in the form

$$\frac{dy}{dx} + P(x)y = Q(x).$$

The idea behind solving these is to find  $\mu = f(x)$  such that

$$\frac{d}{dx}(\mu y) = \mu \frac{dy}{dx} + \mu P(x)y.$$

Using the product rule, it becomes clear

$$\frac{d\mu}{dx} = \mu P(x) \quad \text{implies} \quad \mu = \exp\left(\int P(x) dx\right).$$

# Linear ODEs Example

## Example

Solve the differential equation

$$x \frac{dy}{dx} + 3x^3y = 6x^3.$$

# Sequences and Series

# Sequences

## Definition

A sequence  $(a_n)_{n=1}^{\infty}$  is said to **converge**, if there is a value  $a$  in  $\mathbb{R}$  which has the property that: For all  $\epsilon > 0$ , there exists an integer  $N$  such that  $n \geq N$  implies that  $|a_n - a| < \epsilon$ . We often write

$$a_n \rightarrow a \quad \text{or} \quad \lim_{n \rightarrow \infty} a_n = a$$

when  $(a_n)_{n=1}^{\infty}$  converges to  $a$ . If  $(a_n)_{n=1}^{\infty}$  does not converge, then it **diverges**.

# Sequences Example

## Example

Determine which of the following sequences converge/diverge. If the sequence converges, find its limit.

(a)  $a_n = \frac{1}{n}$

(b)  $b_n = \sqrt{n}$

(c)  $c_n = (-1)^n$

(d)  $d_n = 1 + \frac{(-1)^n}{n}$

# Python Sequences Example

## Example

Use Python to graph the four sequences in the previous example. Graph them on separate subplots, and for the sequences that converge use horizontal lines to show their respective limits.

# Python Sequences Example Solution

```
# Import modules
import numpy as np
import matplotlib.pyplot as plt

# Use LaTeX
plt.rcParams['text.usetex'] = True

# Use Seaborn style
plt.style.use('seaborn')

# Define functions
a = lambda n: 1/n
b = lambda n: np.sqrt(n)
c = lambda n: (-1)**n
d = lambda n: 1 + (-1)**n/n

# Define the limits
a_lim, d_lim = 0, 1

# Get the n-values
n_vals = np.arange(1, 21)

# Get the sequence values
# Functions already vectorized
a_vals = a(n_vals)
b_vals = b(n_vals)
c_vals = c(n_vals)
d_vals = d(n_vals)

# Set up subplots
fig, ax = plt.subplots(2, 2, sharey = True,
                      figsize = (10, 6))

# Plot a_n and its limit
ax[0, 0].scatter(n_vals, a_vals)
ax[0, 0].axhline(y = a_lim, color = 'r',
                  linestyle = 'dashed')
ax[0, 0].set_xlabel(r'$n$')
ax[0, 0].set_ylabel(r'$a_n$')

# Plot b_n and its limit
ax[0, 1].scatter(n_vals, b_vals, label = r'$b_n$')
ax[0, 1].set_xlabel(r'$n$')
ax[0, 1].set_ylabel(r'$b_n$')

# Plot c_n and its limit
ax[1, 0].scatter(n_vals, c_vals)
ax[1, 0].set_xlabel(r'$n$')
ax[1, 0].set_ylabel(r'$c_n$')

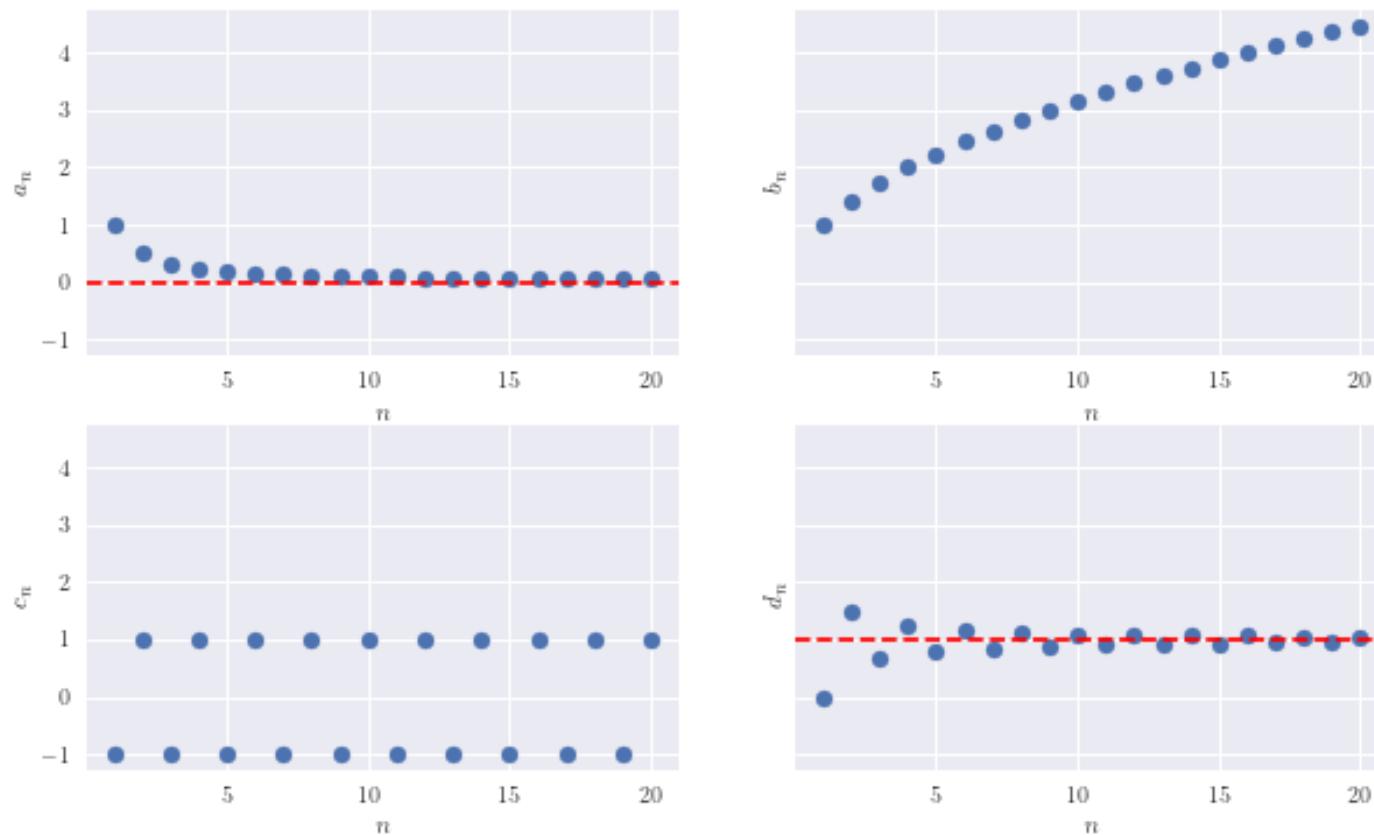
# Plot d_n and its limit
ax[1, 1].scatter(n_vals, d_vals)
ax[1, 1].axhline(y = d_lim, color = 'r',
                  linestyle = 'dashed')
ax[1, 1].set_xlabel(r'$n$')
ax[1, 1].set_ylabel(r'$d_n$')

plt.suptitle(r'Sequence Plots')

# Save the figure
plt.savefig(path + r'ex1-4.png')
plt.show()
```

# Python Sequences Example Result

Sequence Plots



# Triangle Inequality

For any real numbers  $x$ ,  $y$ , and  $z$ ,

$$|x - y| \leq |x - z| + |z - y|.$$

# Sequences

## Theorem

- (a) *The sequence  $(a_n)_{n=1}^{\infty}$  converges to  $a$  in  $\mathbb{R}$  if and only if for every  $\epsilon > 0$ , we have  $a_n$  in the interval  $(a - \epsilon, a + \epsilon)$  for all but finitely many  $n$ .*
- (b) *If  $(a_n)_{n=1}^{\infty}$  converges to both  $a$  and  $b$ , then  $a = b$ .*
- (c) *If  $(a_n)_{n=1}^{\infty}$  converges, then it is bounded. That is, convergence of  $(a_n)_{n=1}^{\infty}$  implies there exists a real number  $B$  such that  $|a_n| \leq B$  for all  $n$ .*

# Sequence Properties

## Theorem

Suppose  $(a_n)_{n=1}^{\infty}$  and  $(b_n)_{n=1}^{\infty}$  are real numbered sequences and

$$\lim_{n \rightarrow \infty} a_n = a \quad \text{and} \quad \lim_{n \rightarrow \infty} b_n = b.$$

Let  $\alpha$  and  $\beta$  be real constants.

(a)  $\lim_{n \rightarrow \infty} (\alpha a_n + \beta b_n) = \alpha a + \beta b$

(b)  $\lim_{n \rightarrow \infty} a_n b_n = ab$

(c)  $\lim_{n \rightarrow \infty} \frac{1}{a_n} = \frac{1}{a} \text{ if } a_n \neq 0 \text{ and } a \neq 0.$

# Monotonic Sequences

## Definition

- A real sequence  $(a_n)_{n=1}^{\infty}$  is **monotonically increasing** if  $a_n \leq a_{n+1}$  for all  $n$ .
- A real sequence  $(a_n)_{n=1}^{\infty}$  is **monotonically decreasing** if  $a_n \geq a_{n+1}$  for all  $n$ .

## Theorem

Suppose that  $(a_n)_{n=1}^{\infty}$  is monotonic. Then it converges if and only if it is bounded.

# Series

## Definition

Consider a series  $S = \sum_{k=1}^{\infty} a_k$ . Its  **$n$ -th partial sum** is  $S_n = \sum_{k=1}^n a_k$ . The series  $S$  **converges** if the sequence  $(S_n)_{n=1}^{\infty}$  converges, and it **diverges** otherwise.

# Example

## Example

For what values of  $r$  does the geometric series  $\sum_{k=1}^{\infty} r^{k-1}$  converge?

# Geometric Series

The geometric series is extremely important in finance. Remember these formulas.

$$\sum_{k=1}^n ar^{k-1} = \frac{a(1 - r^n)}{1 - r}$$

and

$$\sum_{k=1}^{\infty} ar^{k-1} = \begin{cases} \frac{a}{1-r}, & |r| < 1 \\ DNE, & |r| \geq 1 \end{cases}$$

# Partial Fraction Decomposition

- $\frac{ax + b}{(x - c)(x - d)} = \frac{A}{x - c} + \frac{B}{x - d}, \quad c \neq d.$
- $\frac{ax + b}{(x - c)^2} = \frac{A}{x - c} + \frac{B}{(x - c)^2}.$

# Partial Fraction Decomposition Example

## Example

Rewrite  $\frac{x - 2}{x(x - 3)}$  using partial fraction decomposition.

# Convergent Series

## Example

Show  $\sum_{k=1}^{\infty} \frac{1}{k(k+1)}$  converges.

# Divergence Test

- If  $\lim_{k \rightarrow \infty} a_k \neq 0$ , then  $\sum_{k=1}^{\infty} a_k$  diverges.
- If  $\lim_{k \rightarrow \infty} a_k = 0$ , then  $\sum_{k=1}^{\infty} a_k$  may or may not converge.

# Property of Series

## Theorem

Suppose that  $\sum_{k=1}^{\infty} a_k$  and  $\sum_{k=1}^{\infty} b_k$  converge. For any real constants  $\alpha$  and  $\beta$

$$\sum_{k=1}^{\infty} (\alpha a_k + \beta b_k) = \alpha \sum_{k=1}^{\infty} a_k + \beta \sum_{k=1}^{\infty} b_k.$$

# Dominating Series

## Theorem

If a series  $\sum_{k=1}^{\infty} b_k$  dominates a series  $\sum_{k=1}^{\infty} a_k$  in the sense that for all

sufficiently large  $k$ ,  $|a_k| \leq b_k$ , then convergence of  $\sum_{k=1}^{\infty} b_k$  implies

convergence of  $\sum_{k=1}^{\infty} a_k$ .

# Dominating Series Example

## Example

Show that the series  $\sum_{k=1}^{\infty} \frac{\sin k}{2^k}$  converges.

# Integral Test

## Theorem (Integral Test)

Suppose  $f$  is continuous and  $f(k) = a_k$ .

- (a) If  $|a_k| \leq f(x)$  for all sufficiently large  $k$  and all  $x$  in the interval  $(k - 1, k]$ , then convergence of  $\int_1^\infty f(x) dx$  implies convergence of  $\sum_{k=1}^{\infty} a_k$ .
- (b) If  $|f(x)| \leq a_k$  for all sufficiently large  $k$  and all  $x$  in the interval  $[k, k + 1)$  then divergence of  $\int_1^\infty f(x) dx$  implies divergence of  $\sum_{k=1}^{\infty} a_k$ .

# Example (p-Series)

## Example

Prove that  $\sum_{k=1}^{\infty} \frac{1}{k^p}$  converges for  $p > 1$  and diverges for  $p \leq 1$ .

# Alternating Series Test

## Theorem

Suppose the alternating series  $\sum_{k=1}^{\infty} (-1)^{k+1} b_k$  is such that  $0 \leq b_{k+1} \leq b_k$  for sufficiently large  $k$ . Then the series converges if  $\lim_{n \rightarrow \infty} b_k = 0$ .

# Alternating Series Test Example

## Example

Show that the series  $\sum_{k=1}^{\infty} \frac{(-1)^{k+1}}{k}$  converges.

# Absolutely and Conditionally Convergent Series

## Definition

A series  $\sum_{k=1}^{\infty} a_k$  is **absolutely convergent** if  $\sum_{k=1}^{\infty} |a_k|$  converges. A series is **conditionally convergent** if  $\sum_{k=1}^{\infty} a_k$  converges but  $\sum_{k=1}^{\infty} |a_k|$  does not.

For example, the series

$$\sum_{k=1}^{\infty} \frac{(-1)^{k+1}}{k}$$

is conditionally convergent but not absolutely.

# Ratio Test

## Theorem

- (a) If  $\lim_{k \rightarrow \infty} \left| \frac{a_{k+1}}{a_k} \right| = L < 1$ , then the series  $\sum_{k=1}^{\infty} a_k$  is absolutely convergent.
- (b) If  $\lim_{n \rightarrow \infty} \left| \frac{a_{k+1}}{a_k} \right| = L > 1$ , then the series  $\sum_{k=1}^{\infty} a_k$  is divergent.
- (c) If  $\lim_{n \rightarrow \infty} \left| \frac{a_{k+1}}{a_k} \right| = L = 1$ , then the test fails.

# Ratio Test Example

## Example

What can be said about the convergence of  $\sum_{k=1}^{\infty} (-1)^k \frac{k!}{k^k}$ ?

# Power Series

## Definition

A **power series** centered at  $c$  is a series of the form

$$\sum_{k=0}^{\infty} a_k(x - c)^k.$$

If the series converges for  $|x - c| < R$  and diverges for  $|x - c| > R$ , then  $R$  is the **radius of convergence**. The **interval of convergence**  $I$  is the set of all  $x$  values where the series converges.

**Remark:** We assume  $0^0 = 1$  within our power series, so the power series always converges at  $x = c$ .

# Power Series Example

## Example

Find the radius and interval of convergence of the series

$$\sum_{k=0}^{\infty} \frac{(-3)^k(x+1)^k}{\sqrt{k+1}}.$$

# Differentiation and Integration of Power Series

## Theorem

If the power series  $f(x) = \sum_{k=0}^{\infty} a_k(x - c)^k$  has radius of convergence  $R > 0$ ,

then both

(a)  $f'(x) = \sum_{k=1}^{\infty} k a_k (x - c)^{k-1}$  and

(b)  $\int f(x) dx = C + \sum_{k=0}^{\infty} a_k \frac{(x - c)^{k+1}}{k + 1}$

have radii of convergence  $R$ .

# Differentiation of Power Series Example

## Example

$$\sum_{k=1}^{\infty} \frac{k}{1.10^k} =$$

# Taylor's Theorem

## Theorem

*Suppose*

$$f(x) = \sum_{k=0}^{\infty} a_k (x - c)^k \quad \text{for} \quad |x - c| < R.$$

*Then*

$$a_k = \frac{f^{(k)}(c)}{k!}.$$

# Popular Taylor Series Centered at Zero

- $\frac{1}{1-x} = \sum_{k=0}^{\infty} x^k$  for  $x \in (-1, 1)$
- $e^x = \sum_{k=0}^{\infty} \frac{x^k}{k!}$  for  $x \in \mathbb{R}$
- $\sin x = \sum_{k=0}^{\infty} (-1)^k \frac{x^{2k+1}}{(2k+1)!}$  for  $x \in \mathbb{R}$
- $\cos x = \sum_{k=0}^{\infty} (-1)^k \frac{x^{2k}}{(2k)!}$  for  $x \in \mathbb{R}$
- $\arctan x = \sum_{k=0}^{\infty} (-1)^k \frac{x^{2k+1}}{2k+1}$  for  $x \in [-1, 1]$

# Taylor's Theorem Example

## Example

Prove  $\arctan x = \sum_{k=0}^{\infty} (-1)^k \frac{x^{2k+1}}{2k+1}$  for  $x \in [-1, 1]$ .

# Time Value of Money

# Time Value of Money

For a time  $t$  cash flow  $C_t$  discounted at rate  $r$ , the *present value* is

$$PV = \frac{C_t}{(1 + r)^t}.$$

The time  $T$  *future value* is

$$FV_T = PV \cdot (1 + r)^T = C_t \cdot (1 + r)^{T-t}.$$

# Compound Interest

We assumed that interest is compounded once per unit of time. However, if it is compounded  $n$  times per unit of time the formulas become

$$PV = \frac{C_t}{\left(1 + \frac{r}{n}\right)^{nt}} \quad \text{and} \quad FV_T = PV \cdot \left(1 + \frac{r}{n}\right)^{nT}.$$

Since

$$\lim_{n \rightarrow \infty} \left(1 + \frac{r}{n}\right)^{nt} = e^{rt}$$

for continuous compounding (i.e.  $n = \infty$ ) the formulas are

$$PV = C_t e^{-rt} \quad \text{and} \quad FV_T = PV \cdot e^{rT} = C_t \cdot e^{r(T-t)}$$

# Multiple Cash Flows

Suppose we have a sequence of cash flows  $C_0, C_1, C_2, \dots, C_T$ , where the subscript denotes the time of the cash flow, the *net present value* (NPV) of these cash flows discounted at the constant rate  $r$  is

$$NPV = C_0 + \frac{C_1}{1+r} + \frac{C_2}{(1+r)^2} + \dots + \frac{C_n}{(1+r)^T}.$$

# Time Value of Money Python Example

## Example

Time	0	1	2	3	4
Cash Flow	-100	50	20	70	10

Calculate the net present value given a continuously compounded discount rate of 5%.

# Time Value of Money Python Solution

```
# Import module
import numpy as np

# Record rate
rate = 0.05

# Record time of cash flows
time = np.array([0, 1, 2, 3, 4])

# Record cash flows
cash_flows = np.array([-100, 50, 20, 70, 10])

# Get the NPV
NPV = np.sum(cash_flows * np.exp(-rate * time))

print(f'The NPV of the cash flows is {NPV:.2f}.')
```

$$NPV \approx 34.10$$

# numpy\_finance Module

There is a `numpy_finance` module that has a net present value function (<https://numpy.org/numpy-financial/latest/npv.html>). However, we would need the annual rate to use it in the last example, i.e. we would have to use the rate

$$100\% \times (e^{0.05} - 1) \approx 5.127\%.$$

# Time Value of Money Example

## Example

Jain borrows \$1,000,000 to purchase a house. The loan is for thirty years and her first payment is one month from when she initially borrows the money. If her annualized rate is 12%, what will be her monthly payments? Ignore fees.

# Growing Payments

Suppose 1 is paid at time 1, and payments increase at a rate of  $g$  each subsequent period until a final payment of  $(1 + g)^{n-1}$  is made at time  $n$ . If cash flows are discounted at rate  $r$ , then the NPV of the cash flows is

$$\frac{1 - \left(\frac{1+g}{1+r}\right)^n}{r - g}.$$

# Growing Payments Example

## Example

Calculate the NPV of the series of end-of-year cash flows. Assume

- \$100 is paid in the first year,
- each subsequent year payments increase by 5%,
- the final payment is made at the end of year ten, and
- the discount rate is 8%.