last time

cache misses and C code

size of way = distance between same set

K-way set-associative caches

like K direct-mapped caches 'stapled together' still divide addresses into tag/index/offset index identifies set with K blocks store valid bit+tag for each block

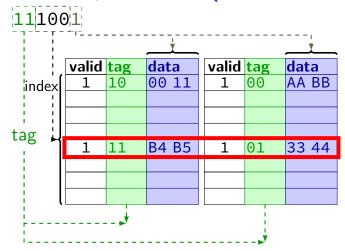
replacement policies least recently used + related

anonymous feedback (1)

"Can you explain the role of the index in a 2 way cache? It seems like since a miss with index 1 can be put into index 0 row."

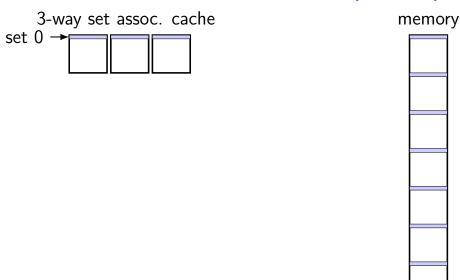
the way we've drawn 2-way caches, they have *two columns* (ways) index says which row — so miss with index 1 can only go in index 0 row ...but could go in either column (depending on replacement policy)

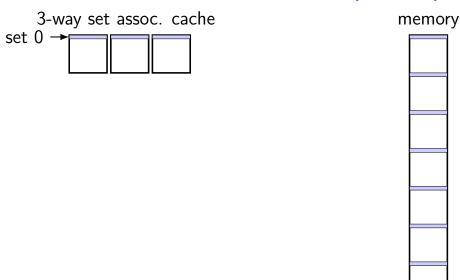
cache operation (associative)

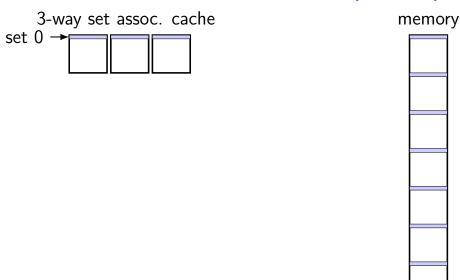


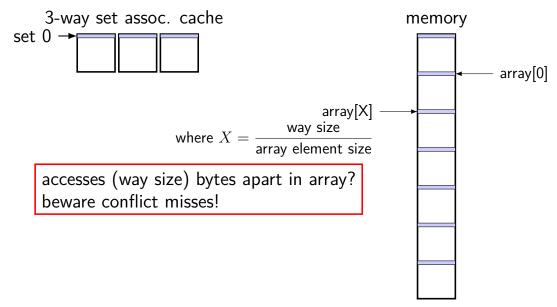
anonymous feedback (2)

"I think I speak for a lot of students when I say it doesn't feel like you're listening to our anonymous feedback. It seems like you're just posting a few on the lecture slides to give an excuse or invalidate our concerns, and not actually using it to evaluate the course and make changes where necessary. This course is extremely new, and it's expected that changes will have to be made. Here are some examples of changes that students have proposed that you've not taken: the labs are essentially a second homework and need to be started days in advance (which isn't what a 75-minute lab is meant to be); the readings are extremely disorganized and often make us more confused; and so much more."









handling writes

what about writing to the cache?

two decision points:

if the value is not in cache, do we add it?

if yes: need to load rest of block — write-allocate

if no: missing out on locality? write-no-allocate

if no: missing out on locality? write-no-allocate

if value is in cache, when do we update next level?

if immediately: extra writing write-through

if later: need to remember to do so write-back

allocate on write?

processor writes less than whole cache block

block not yet in cache

two options:

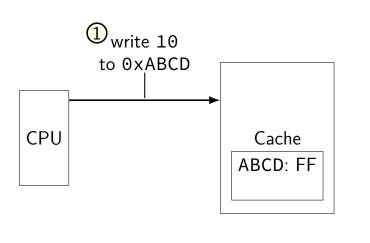
write-allocate

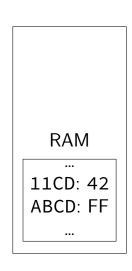
fetch rest of cache block, replace written part (then follow write-through or write-back policy)

write-no-allocate

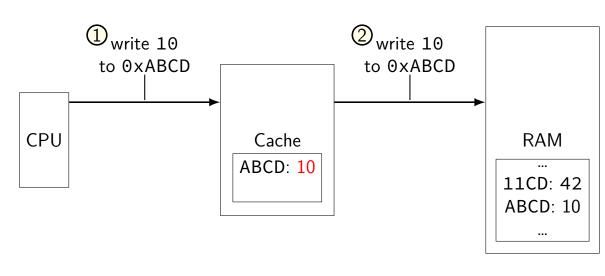
don't use cache at all (send write to memory *instead*) guess: not read soon?

option 1: write-through

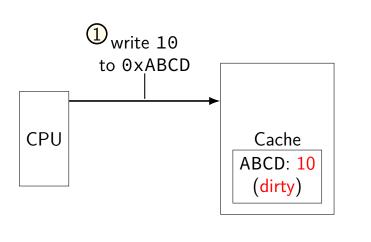


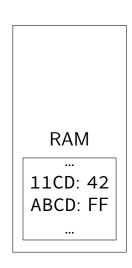


option 1: write-through

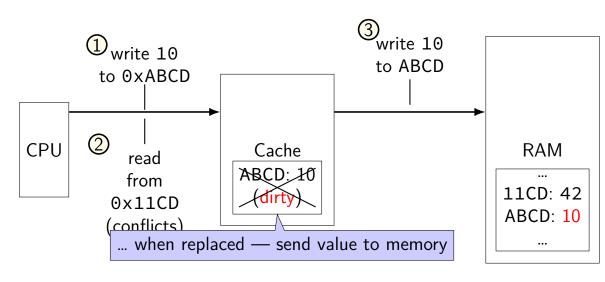


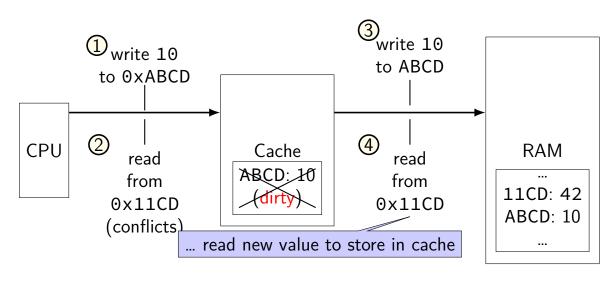
option 2: write-back





option 2: write-back





writeback policy

changed value!

2-way set associative, 4 byte blocks, 2 sets

index	valid	tag	value	dirty	valid	tag	value	dirty	LRU
0	1	000000	mem[0x00] mem[0x01]	0	1	011000	mem[0x60]* mem[0x61]*		1
1	1	011000	mem[0x62] mem[0x63]	0	0				0

1 = dirty (different than memory) needs to be written if evicted

2-way set associative, LRU, writeback

index	valid	tag	value	dirty	valid	tag	value	dirty	LRU	
0	1		mem[0x00] mem[0x01]		1		mem[0x60] mem[0x61]		1	
1	1		mem[0x62] mem[0x63]	0	0				0	

writing $\widehat{0x}FF$ into address 0x04? index 0, tag 000001

2-way set associative, LRU, writeback

index	valid	tag	value	dirty	valid	tag	value	dirty	LRU
0	1		mem[0x00] mem[0x01]	0	1		mem[0x60] mem[0x61]		1
1	1		mem[0x62] mem[0x63]	0	0				0

writing 0xFF into address 0x04?

index 0, tag 000001

step 1: find least recently used block

2-way set associative, LRU, writeback

index	valid	tag	value	dirty	valid	tag	value	dirty	LRU
0	1		mem[0x00] mem[0x01]		1	011000	mem[0x60] mem[0x61]	* 1	1
1	1		mem[0x62] mem[0x63]	0	0				0

writing 0xFF into address 0x04?

index 0, tag 000001

step 1: find least recently used block

step 2: possibly writeback old block

2-way set associative, LRU, writeback

index	valid	tag	value	dirty	valid	tag	value	dirty	LRU
0	1	000000	mem[0x00] mem[0x01]	0	1	000001	0xFF mem[0x05]	1	0
1	1		mem[0x62] mem[0x63]	0	0				0

writing 0xFF into address 0x04?

index 0, tag 000001

step 1: find least recently used block

step 2: possibly writeback old block

step 3a: read in new block – to get mem[0x05]

step 3b: update LRU information

2-way set associative, LRU, writeback

index	valid	tag	value	dirty	valid	tag	value	dirty	LRU
0	1	000000	mem[0x00] mem[0x01]	0	1	011000	mem[0x60] mem[0x61]	* 1	1
1	1	011000	mem[0x62] mem[0x63]	0	0				0

writing $\widehat{0x}FF$ into address 0x04?

step 1: is it in cache yet?

step 2: no, just send it to memory

exercise (1)

2-way set associative, LRU, write-allocate, writeback

index	valid	tag	value	dirty	valid	tag	value	dirty	LRU
0	1	001100	mem[0x30] mem[0x31]	0	1	010000	mem[0x40] mem[0x41]	* 1	0
1	1	011000	mem[0x62] mem[0x63]	0	1	001100	mem[0x32] mem[0x33]	* 1	1

for each of the following accesses, performed alone, would it require (a) reading a value from memory (or next level of cache) and (b) writing a value to the memory (or next level of cache)?

writing 1 byte to 0x33 reading 1 byte from 0x52 reading 1 byte from 0x50

exercise (2)

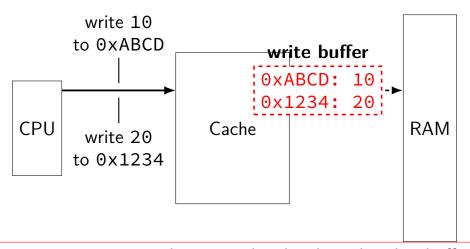
2-way set associative, LRU, write-no-allocate, write-through

index	valid	tag	value	valid	tag	value	LRU
0	1	001100	mem[0x30] mem[0x31]	1	010000	mem[0x40] mem[0x41]	0
1	1	011000	mem[0x62] mem[0x63]	1	001100	mem[0x32] mem[0x33]	1

for each of the following accesses, performed alone, would it require (a) reading a value from memory and (b) writing a value to the memory?

writing 1 byte to 0x33 reading 1 byte from 0x52 reading 1 byte from 0x50

fast writes



write appears to complete immediately when placed in buffer memory can be much slower

making any cache look bad

- 1. access enough blocks, to fill the cache
- 2. access an additional block, replacing something
- 3. access last block replaced
- 4. access last block replaced
- 5. access last block replaced

...

but — typical real programs have locality

cache optimizations

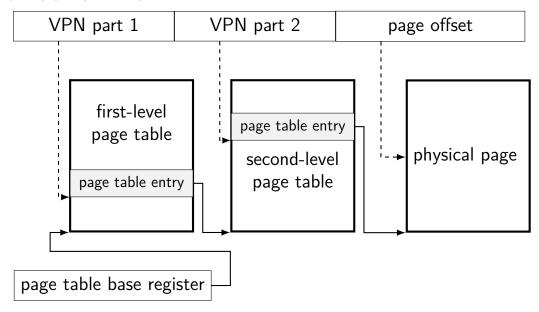
```
(assuming typical locality + keeping cache size constant if possible...)
                        miss rate hit time miss penalty
increase cache size
                        better
                                   worse
                                             worse?
increase associativity
                        better
                                   worse
increase block size
                        depends
                                   worse
                                             worse
add secondary cache
                                             better
write-allocate
                        hetter
writeback
LRU replacement
                                             worse?
                        better
prefetching
                        better
 prefetching = guess what program will use, access in advance
```

average time = hit time + miss rate \times miss penalty

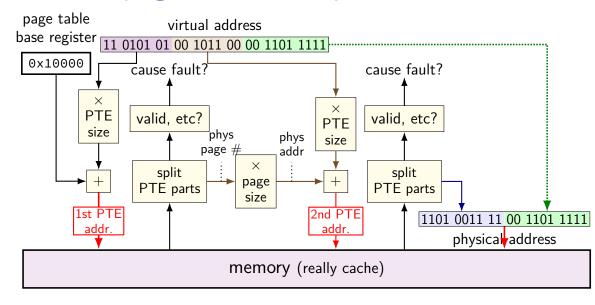
cache optimizations by miss type

(assuming other listed	parameters rem	nain constant)	
	capacity	conflict	compulsory
increase cache size	fewer misses	fewer misses	
increase associativity	_	fewer misses	
increase block size	more misses?	more misses?	fewer misses
LRU replacement	_	fewer misses	
prefetching			fewer misses

another view



two-level page table lookup



cache accesses and multi-level PTs

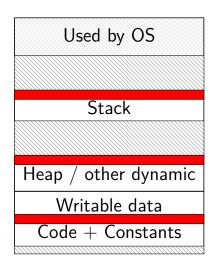
four-level page tables — five cache accesses per program memory access

L1 cache hits — typically a couple cycles each?

so add 8 cycles to each program memory access?

not acceptable

program memory active sets



0xFFFF FFFF FFFF FFFF 0xFFFF 8000 0000 0000

0x7F...

small areas of memory active at a time one or two pages in each area?

0x0000 0000 0040 0000

page table entries and locality

page table entries have excellent temporal locality typically one or two pages of the stack active typically one or two pages of code active typically one or two pages of heap/globals active

each page contains whole functions, arrays, stack frames, etc.

page table entries and locality

page table entries have excellent temporal locality

typically one or two pages of the stack active

typically one or two pages of code active

typically one or two pages of heap/globals active

each page contains whole functions, arrays, stack frames, etc.

needed page table entries are very small

page table entry cache

caled a **TLB** (translation lookaside buffer)

very small cache of page table entries

L1 cache	TLB
physical addresses	virtual page numbers
bytes from memory	page table entries
tens of bytes per block	one page table entry per block
usually thousands of blocks	usually tens of entries

page table entry cache

caled a **TLB** (translation lookaside buffer)

very small cache of page table entries

L1 cache	TLB		
physical addresses	virtual page numbers		
bytes from memory	page table entries		
tens of bytes per block	one page able entry per block		
usually thousands of block	usually te is of entries		
only caches th	only caches the page table lookup itself		
(generally) jus	(generally) just entries from the last-level page tables		

caled a **TLB** (translation lookaside buffer)

very small cache of page table entries

L1 cache		TLB
physical addresses		virtual page numbers
bytes from memory		page table entries
tens of bytes per block		one page table entry per block
usually thousands of blocks		usuraly tens of entries
	sands of blocks usualy tens of entries virtual page number divided into	
	index + tag	

caled a **TLB** (translation lookaside buffer)

very small cache of page table entries

L1 cache	TLB
physical addresses	virtual page numbers
bytes from memory	page table entries
tens of bytes per block	one page table entry per block
usually thousands of blocks	usually tens of entries

not much spatial locality between page table entries (they're used for kilobytes of data already)

caled a **TLB** (translation lookaside buffer)

very small cache of page table entries

L1 cache	TLB
physical addresses	virtual page numbers
bytes from memory	page table entries
tens of bytes per block	one page table entry per block
usually thousands of blocks	usually tens of entries

0 block offset bits

caled a **TLB** (translation lookaside buffer)

very small cache of page table entries

L1 cache	TLB
physical addresses	virtual page numbers
bytes from memory	page table entries
tens of bytes per block	one page table entry per block
usually thousands of blocks	usually tens of entries
	'

few active page table entries at a time enables highly associative cache designs

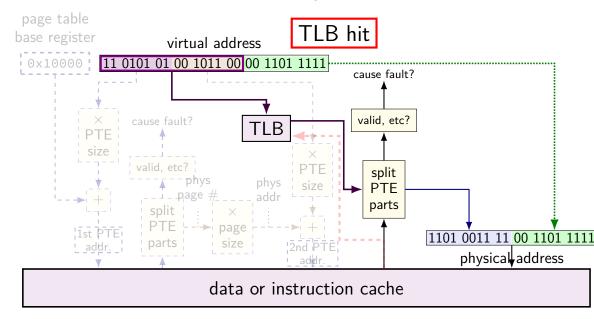
TLB and multi-level page tables

TLB caches valid last-level page table entries

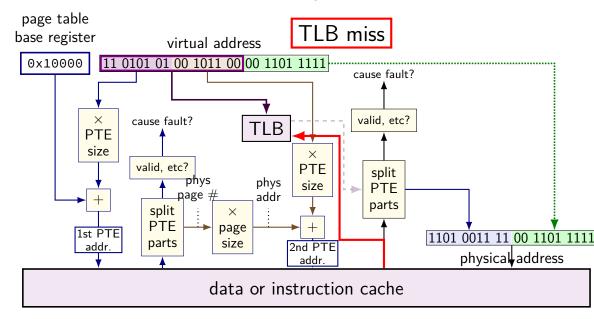
doesn't matter which last-level page table

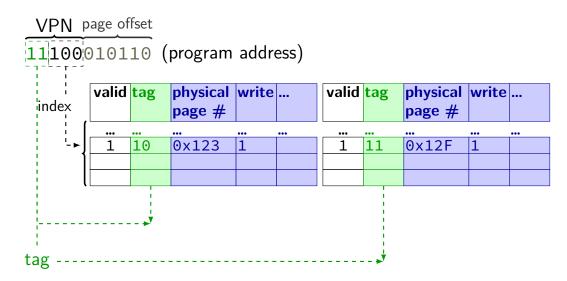
means TLB output can be used directly to form address

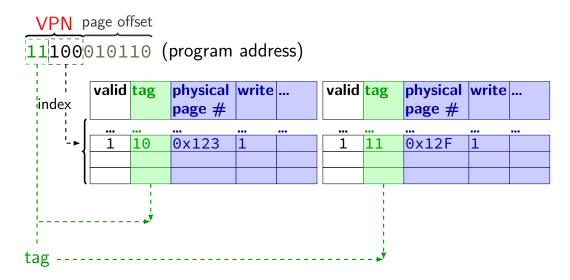
TLB and two-level lookup

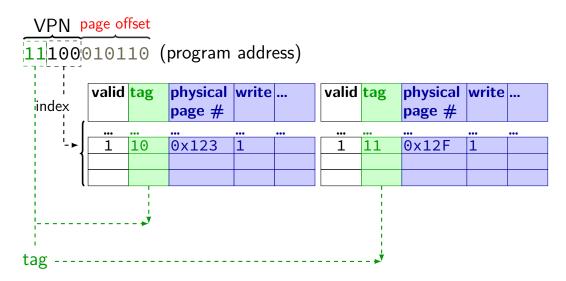


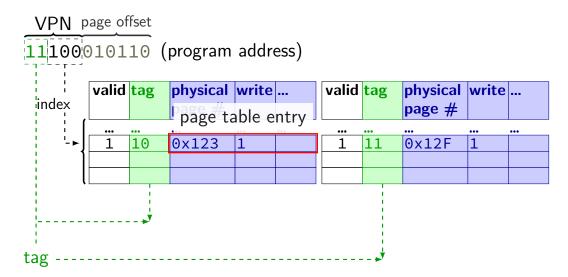
TLB and two-level lookup

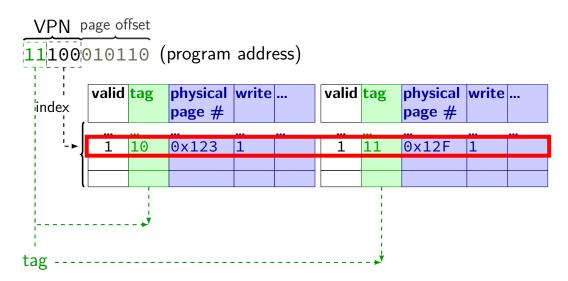












why threads?

```
concurrency: different things happening at once
one thread per user of web server?
one thread per page in web browser?
one thread to play audio, one to read keyboard, ...?
...
parallelism: do same thing with more resources
```

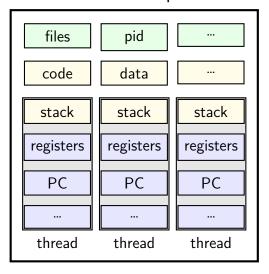
multiple processors to speed-up simulation (life assignment)

single and multithread processes

single-threaded process

pid files code data stack registers PC thread

multi-threaded process



```
void *ComputePi(void *argument) { ... }
void *PrintClassList(void *argument) { ... }
int main() {
    pthread t pi thread, list thread;
    pthread create(&pi thread, NULL, ComputePi, NULL);
    pthread_create(&list_thread, NULL, PrintClassList, NULL);
    ... /* more code */
    main()
pthread_create.
                                          ComputePi
pthread create.
                          PrintClassList
```

```
void *ComputePi(void *argument) { ... }
void *PrintClassList(void *argument) { ... }
int main() {
    pthread t pi thread, list thread;
    pthread_create(&pi_thread, NULL, ComputePi, NULL);
    pthread create(&list thread, NULL, PrintClassList, NULL);
    ... /* more code */
pthread create arguments:
thread identifier
function to run thread starts here, terminates if this function returns
```

```
void *ComputePi(void *argument) { ... }
void *PrintClassList(void *argument) { ... }
int main() {
    pthread_t pi_thread, list_thread;
    pthread_create(&pi_thread, NULL, ComputePi, NULL);
    pthread_create(&list_thread, NULL, PrintClassList, NULL);
    ... /* more code */
}
pthread create arguments:
```

thread identifier

function to run thread starts here, terminates if this function returns

```
void *ComputePi(void *argument) { ... }
void *PrintClassList(void *argument) { ... }
int main() {
    pthread t pi thread, list thread;
    pthread_create(&pi_thread, NULL, ComputePi, NULL);
    pthread create(&list thread, NULL, PrintClassList, NULL);
    ... /* more code */
pthread create arguments:
```

thread identifier

function to run thread starts here, terminates if this function returns

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void *ComputePi(void *argument) { ... }
void *PrintClassList(void *argument) { ... }
int main() {
    pthread t pi thread, list thread;
    pthread_create(&pi_thread, NULL, ComputePi, NULL);
    pthread create(&list thread, NULL, PrintClassList, NULL);
    ... /* more code */
pthread create arguments:
thread identifier
function to run thread starts here, terminates if this function returns
```

a threading race

```
#include <pthread.h>
#include <stdio.h>
void *print_message(void *ignored_argument) {
    printf("In the thread\n"); return NULL;
int main() {
    printf("About to start thread\n");
    pthread_t the_thread;
    pthread_create(&the_thread, NULL, print_message, NULL);
    printf("Done starting thread\n");
    return 0;
My machine: outputs In the thread about 4% of the time.
What happened?
```

a race

```
returning from main exits the entire process (all its threads)
     same as calling exit; not like other threads
race: main's return 0 or print message's printf first?
                                                              time
  main: printf/pthread_create/printf/return
                               print message: printf/return
                                return from main
                                 ends all threads
                                  in the process
```

fixing the race (version 1)

```
#include <pthread.h>
#include <stdio.h>
void *print_message(void *ignored_argument) {
    printf("In the thread\n");
    return NULL;
int main() {
    printf("About to start thread\n");
    pthread t the thread;
    pthread_create(&the_thread, NULL, print_message, NULL);
    printf("Done starting thread\n");
    pthread join(the_thread, NULL); /* WAIT FOR THREAD */
    return 0;
```

fixing the race (version 2; not recommended)

```
#include <pthread.h>
#include <stdio.h>
void *print_message(void *ignored_argument) {
    printf("In the thread\n");
    return NULL;
int main() {
    printf("About to start thread\n");
    pthread_t the_thread;
    pthread_create(&the_thread, NULL, print_message, NULL);
    printf("Done starting thread\n");
   pthread_exit(NULL);
```

pthread_join, pthread_exit

pthread_join: wait for thread, retrieves its return value
 like waitpid, but for a thread
 return value is pointer to anything

pthread_exit: exit current thread, returning a value
 like exit or returning from main, but for a single thread
 same effect as returning from function passed to pthread_create

sum example (only globals)

```
int values[1024];
int results[2];
void *sum_front(void *ignored_argument) {
    int sum = 0;
    for (int i = 0; i < 512; ++i) { sum += values[i]; }
    results[0] = sum;
    return NULL;
}
void *sum_back(void *ignored_argument) {
    int sum = 0;
    for (int i = 512; i < 1024; ++i) { sum += values[i]; }
    results[1] = sum;
    return NULL;
int sum_all() {
    pthread_t sum_front_thread, sum_back_thread;
    pthread create(&sum front thread, NULL, sum front, NULL);
    pthread_create(&sum_back_thread, NULL, sum_back, NULL);
    pthread_join(sum_front_thread, NULL); pthread_join(sum_back_thread, NULL);
    return results[0] + results[1];
```

sum example (only globals)

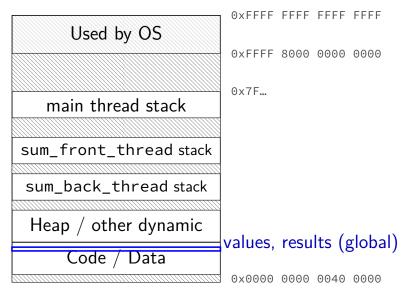
```
values, results: global variables — shared
int values[1024];
int results[2];
void *sum_front(void *ignored_argument) {
    int sum = 0;
    for (int i = 0; i < 512; ++i) { sum += values[i]; }
    results[0] = sum;
    return NULL;
}
void *sum_back(void *ignored_argument) {
    int sum = 0;
    for (int i = 512; i < 1024; ++i) { sum += values[i]; }
    results[1] = sum;
    return NULL;
int sum_all() {
    pthread_t sum_front_thread, sum_back_thread;
    pthread create(&sum front thread, NULL, sum front, NULL);
    pthread_create(&sum_back_thread, NULL, sum_back, NULL);
    pthread_join(sum_front_thread, NULL); pthread_join(sum_back_thread, NULL);
    return results[0] + results[1];
```

sum example (only globals) two different functions

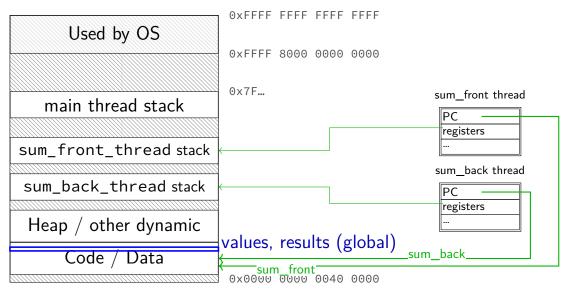
```
int values[1024];
                      happen to be the same except for some numbers
int results[2];
void *sum_front(void *ignored_argument) {
    int sum = 0;
    for (int i = 0; i < 512; ++i) { sum += values[i]; }
    results[0] = sum;
    return NULL;
}
void *sum_back(void *ignored_argument) {
    int sum = 0;
    for (int i = 512; i < 1024; ++i) { sum += values[i]; }
    results[1] = sum;
    return NULL;
int sum_all() {
    pthread_t sum_front_thread, sum_back_thread;
    pthread create(&sum front thread, NULL, sum front, NULL);
    pthread_create(&sum_back_thread, NULL, sum_back, NULL);
    pthread_join(sum_front_thread, NULL); pthread_join(sum_back_thread, NULL);
    return results[0] + results[1];
```

```
values returned from threads
        via global array instead of return value
int valu
         (partly to illustrate that memory is shared,
void *su partly because this pattern works when we don't join (later))
    int
    for (int i = 0; i < 512; ++i) { sum += values[i]; }</pre>
    results[0] = sum;
    return NULL;
void *sum_back(void *ignored_argument) {
    int sum = 0;
    for (int i = 512; i < 1024; ++i) { sum += values[i]; }
    results[1] = sum;
    return NULL;
int sum_all() {
    pthread_t sum_front_thread, sum_back_thread;
    pthread create(&sum front thread, NULL, sum front, NULL);
    pthread_create(&sum_back_thread, NULL, sum_back, NULL);
    pthread_join(sum_front_thread, NULL); pthread_join(sum_back_thread, NULL);
    return results[0] + results[1];
```

thread_sum memory layout



thread_sum memory layout



sum example (to global, with thread IDs)

```
int values[1024];
int results[2];
void *sum_thread(void *argument) {
    int id = (int) argument;
    int sum = 0;
    for (int i = id * 512; i < (id + 1) * 512; ++i) {
        sum += values[i];
    results[id] = sum;
    return NULL;
int sum_all() {
    pthread_t thread[2];
    for (int i = 0; i < 2; ++i) {
        pthread_create(&threads[i], NULL, sum_thread, (void *) i);
    for (int i = 0; i < 2; ++i)
        pthread_join(threads[i], NULL);
    return results[0] + results[1];
```

sum example (to global, with thread IDs)

```
int values[1024];
                              values, results: global variables — shared
int results[2];
void *sum_thread(void *argumenc) t
    int id = (int) argument;
    int sum = 0;
    for (int i = id * 512; i < (id + 1) * 512; ++i) {
        sum += values[i];
    results[id] = sum;
    return NULL;
int sum_all() {
    pthread_t thread[2];
    for (int i = 0; i < 2; ++i) {
        pthread_create(&threads[i], NULL, sum_thread, (void *) i);
    for (int i = 0; i < 2; ++i)
        pthread_join(threads[i], NULL);
    return results[0] + results[1];
```

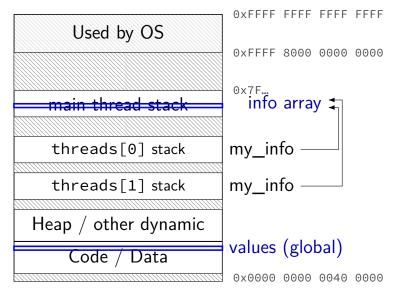
```
int values[1024];
struct ThreadInfo {
    int start, end, result;
};
void *sum_thread(void *argument) {
    struc tThreadInfo *my_info = (struct ThreadInfo *) argument;
    int sum = 0;
    for (int i = my_info->start; i < my_info->end; ++i) { sum += values[i]; }
    my_info->result = sum;
    return NULL;
int sum_all() {
    pthread_t thread[2]; struct ThreadInfo info[2];
    for (int i = 0; i < 2; ++i) {
        info[i].start = i*512; info[i].end = (i+1)*512;
        pthread_create(&threads[i], NULL, sum_thread, &info[i]);
    for (int i = 0; i < 2; ++i) { pthread_join(threads[i], NULL); }</pre>
    return info[0].result + info[1].result;
```

```
int values[1024]; values: global variable — shared
struct ThreadInfo
    int start, end, result;
};
void *sum_thread(void *argument) {
    struc tThreadInfo *my_info = (struct ThreadInfo *) argument;
    int sum = 0;
    for (int i = my_info->start; i < my_info->end; ++i) { sum += values[i]; }
   my_info->result = sum;
    return NULL;
int sum_all() {
    pthread_t thread[2]; struct ThreadInfo info[2];
    for (int i = 0; i < 2; ++i) {
        info[i].start = i*512; info[i].end = (i+1)*512;
        pthread_create(&threads[i], NULL, sum_thread, &info[i]);
    for (int i = 0; i < 2; ++i) { pthread_join(threads[i], NULL); }</pre>
    return info[0].result + info[1].result;
```

```
int values[1024];
struct ThreadInfo {
    int start, end, result;
};
void *sum_thread(void *argument) {
    struc tThreadInfo *my info =
                                  (struct ThreadInfo *) argument:
    int sum = 0;
                                  my info: pointer to sum all's stack
    for (int i = my_info->start;
                                  only okay because sum_all waits!
   my_info->result = sum;
    return NULL;
int sum_all() {
    pthread_t thread[2]; struct ThreadInfo info[2];
    for (int i = 0; i < 2; ++i) {
        info[i].start = i*512; info[i].end = (i+1)*512;
        pthread_create(&threads[i], NULL, sum_thread, &info[i]);
    for (int i = 0; i < 2; ++i) { pthread_join(threads[i], NULL); }</pre>
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        info[i].start = i*512; info[i].end = (i+1)*512;
        pthread_create(&threads[i], NULL, sum_thread, &info[i]);
    for (int i = 0; i < 2; ++i) { pthread_join(threads[i], NULL); }</pre>
    return info[0].result + info[1].result;
```

thread_sum memory layout (info struct)



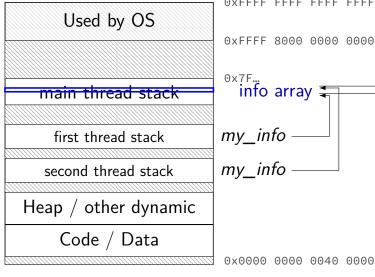
```
struct ThreadInfo { int *values; int start; int end; int result };
void *sum_thread(void *argument) {
    ThreadInfo *my_info = (ThreadInfo *) argument;
    int sum = 0;
    for (int i = my_info->start; i < my_info->end; ++i) {
        sum += my_info->values[i];
   my_info->result = sum;
    return NULL;
int sum all(int *values) {
    ThreadInfo info[2]; pthread_t thread[2];
    for (int i = 0; i < 2; ++i) {
        info[i].values = values; info[i].start = i*512; info[i].end = (i+1)*512;
        pthread_create(&threads[i], NULL, sum_thread, (void *) &info[i]);
    for (int i = 0; i < 2; ++i)
        pthread_join(threads[i], NULL);
    return info[0].result + info[1].result;
```

```
struct ThreadInfo { int *values; int start; int end; int result };
void *sum_thread(void *argument) {
    ThreadInfo *my_info = (ThreadInfo *) argument;
    int sum = 0;
    for (int i = my_info->start; i < my_info->end; ++i) {
        sum += my_info->values[i];
   my_info->result = sum;
    return NULL;
int sum all(int *values) {
    ThreadInfo info[2]; pthread_t thread[2];
    for (int i = 0; i < 2; ++i) {
        info[i].values = values; info[i].start = i*512; info[i].end = (i+1)*512;
        pthread_create(&threads[i], NULL, sum_thread, (void *) &info[i]);
    for (int i = 0; i < 2; ++i)
        pthread_join(threads[i], NULL);
    return info[0].result + info[1].result;
```

```
struct ThreadInfo { int *values; int start; int end; int result };
void *sum_thread(void *argument) {
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    for (int i = 0; i < 2; ++i)
        pthread_join(threads[i], NULL);
    return info[0].result + info[1].result;
```

```
struct ThreadInfo { int *values; int start; int end; int result };
void *sum_thread(void *argument) {
    ThreadInfo *my_info = (ThreadInfo *) argument;
    int sum = 0;
    for (int i = my_info->start; i < my_info->end; ++i) {
        sum += my_info->values[i];
   my_info->result = sum;
    return NULL;
int sum all(int *values) {
    ThreadInfo info[2]; pthread_t thread[2];
    for (int i = 0; i < 2; ++i) {
        info[i].values = values; info[i].start = i*512; info[i].end = (i+1)*512;
        pthread_create(&threads[i], NULL, sum_thread, (void *) &info[i]);
    for (int i = 0; i < 2; ++i)
        pthread_join(threads[i], NULL);
    return info[0].result + info[1].result;
```

program memory (to main stack)



0xFFFF FFFF FFFF 0xFFFF 8000 0000 0000 0x7F... values (stack? heap?) info array my_info my_info

sum example (on heap)

```
struct ThreadInfo { pthread_t thread; int *values; int start; int end; int result
void *sum thread(void *argument) {
    . . .
struct ThreadInfo *start_sum_all(int *values) {
    struct ThreadInfo *info = calloc(2, sizeof(struct ThreadInfo);
    for (int i = 0; i < 2; ++i) {
        info[i].values = values; info[i].start = i*512; info[i].end = (i+1)*512;
        pthread_create(&info[i].thread, NULL, sum_thread, (void *) &info[i]);
    return info;
int finish_sum_all(ThreadInfo *info) {
    for (int i = 0; i < 2; ++i)
        pthread_join(info[i].thread, NULL);
    int result = info[0].result + info[1].result;
    free(info);
    return result;
```

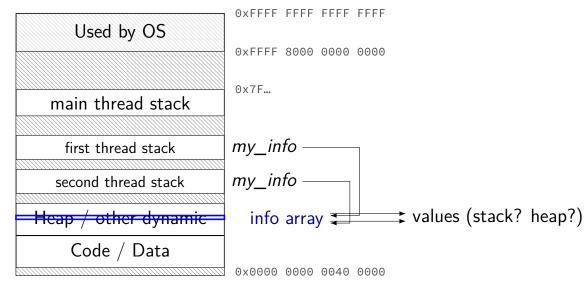
sum example (on heap)

```
struct ThreadInfo { pthread_t thread; int *values; int start; int end; int result
void *sum thread(void *argument) {
    . . .
struct ThreadInfo *start_sum_all(int *values) {
    struct ThreadInfo *info = calloc(2, sizeof(struct ThreadInfo);
    for (int i = 0; i < 2; ++i) {
        info[i].values = values; info[i].start = i*512; info[i].end = (i+1)*512;
        pthread_create(&info[i].thread, NULL, sum_thread, (void *) &info[i]);
    return info;
int finish_sum_all(ThreadInfo *info) {
    for (int i = 0; i < 2; ++i)
        pthread_join(info[i].thread, NULL);
    int result = info[0].result + info[1].result;
    free(info);
    return result;
```

sum example (on heap)

```
struct ThreadInfo { pthread_t thread; int *values; int start; int end; int result
void *sum thread(void *argument) {
    . . .
struct ThreadInfo *start_sum_all(int *values) {
    struct ThreadInfo *info = calloc(2, sizeof(struct ThreadInfo);
    for (int i = 0; i < 2; ++i) {
        info[i].values = values; info[i].start = i*512; info[i].end = (i+1)*512;
        pthread_create(&info[i].thread, NULL, sum_thread, (void *) &info[i]);
    return info;
int finish_sum_all(ThreadInfo *info) {
    for (int i = 0; i < 2; ++i)
        pthread_join(info[i].thread, NULL);
    int result = info[0].result + info[1].result;
    free(info);
    return result;
```

thread_sum memory (heap version)



what's wrong with this?

```
/* omitted: headers */
void *create_string(void *ignored_argument) {
  char string[1024];
  ComputeString(string);
  return string;
int main() {
  pthread_t the_thread;
  pthread_create(&the_thread, NULL, create_string, NULL);
  char *string ptr;
  pthread join(the thread, (void**) &string ptr);
  printf("string is %s\n", string_ptr);
```

program memory

Used by OS main thread stack second thread stack third thread stack Heap / other dynamic Code / Data

0xffff Ffff Ffff Ffff
0xffff 8000 0000 0000
0x7f...

dynamically allocated stacks string result allocated here string_ptr pointed to here

...stacks deallocated when threads exit/are joined

0x0000 0000 0040 0000

program memory

Used by OS main thread stack second thread stack third thread stack Heap / other dynamic Code / Data

0xFFFF FFFF FFFF
0xFFFF 8000 0000 0000
0x7F...

dynamically allocated stacks string result allocated here string_ptr pointed to here

...stacks deallocated when threads exit/are joined

0x0000 0000 0040 0000

thread resources

to create a thread, allocate:

new stack (how big???)

thread control block

deallocated when ...

thread resources

```
to create a thread, allocate:
```

new stack (how big???)

thread control block

deallocated when ...

can deallocate stack when thread exits

but need to allow collecting return value same problem as for processes and waitpid

pthread_detach

```
void *show_progress(void * ...) { ... }
void spawn_show_progress_thread() {
    pthread_t show_progress_thread;
    pthread_create(&show_progress_thread, NULL,
                   show progress, NULL);
    /* instead of keeping pthread t around to join thread later: */
    pthread detach(show progress thread);
int main() {
    spawn show progress thread();
    do other stuff();
           detach = don't care about return value, etc.
            system will deallocate when thread terminates
```

starting threads detached

setting stack sizes

a note on error checking

from pthread_create manpage:

ERRORS

EAGAIN Insufficient resources to create another thread, or a system-imposed limit on the number of threads was encountered. The latter case may occur in two ways: the RLIMIT_NPROC soft resource limit (set via setrlimit(2)), which limits the number of process for a real user ID, was reached; or the kernel's system-wide limit on the number of threads, /proc/sys/kernel/threadsmax, was reached.

EINVAL Invalid settings in attr.

EPERM No permission to set the scheduling policy and parameters specified in attr.

special constants for return value

same pattern for many other pthreads functions will often omit error checking in slides for brevity

error checking pthread_create

```
int error = pthread_create(...);
if (error != 0) {
    /* print some error message */
}
```

backup slides

exercise: TLB access pattern (setup)

4-entry, 2-way TLB, LRU replacement policy, initially empty

4096 byte pages

how many index bits?

TLB index of virtual address 0x12345?

exercise: TLB access pattern

4-entry, 2-way TLB, LRU replacement policy, initially empty

4096 byte pages

type	virtual	physical
read	0x440030	0x554030
write	0x440034	0x554034
read	0x7FFFE008	0x556008
read	0x7FFFE000	0x556000
read	0x7FFFDFF8	0x5F8FF8
read	0x664080	0x5F9080
read	0x440038	0x554038
write	0x7FFFDFF0	0x5F8FF0

which are TLB hits? which are TLB misses? final contents of TLB?

cache miss types

common to categorize misses: roughly "cause" of miss assuming cache block size fixed

compulsory (or cold) — first time accessing something adding more sets or blocks/set wouldn't change

 ${\it conflict} \ -- \ {\it sets aren't big/flexible enough} \\ {\it a fully-associtive (1-set) cache of the same size would have done better}$

capacity — cache was not big enough

coherence — from sync'ing cache with other caches only issue with multiple cores

thread versus process state

```
thread state
     registers (including stack pointer, program counter)
process state
     address space
     open files
     process id
     list of thread states
```

process info with threads

parent process info

```
thread 0: {PC = 0x123456, rax = 42, rbx = ...}
thread 1: {PC = 0x584390, rax = 32, rbx = ...}

page tables
open files
fd 0: ...
fd 1: ...
```

Linux idea: task_struct

```
Linux model: single "task" structure = thread pointers to address space, open file list, etc. pointers can be shared
```

e.g. shared open files: open fd 4 in one task ightarrow all sharing can use fd 4

```
fork()-like system call "clone": choose what to share
    clone(0, ...) — similar to fork()
    clone(CLONE_FILES, ...) — like fork(), but sharing open files
    clone(CLONE_VM, new_stack_pointer, ...) — like fork(),
    but sharing address space
```

Linux idea: task_struct

Linux model: single "task" structure = thread pointers to address space, open file list, etc.

```
pointers can be shared
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fork()-like system call "clone": choose what to share
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    clone(CLONE_VM, new_stack_pointer, ...) — like fork(),
    but sharing address space
```

advantage: no special logic for threads (mostly) two threads in same process = tasks sharing everything possible

aside: alternate threading models

we'll talk about kernel threads

OS scheduler deals directly with threads

alternate idea: library code handles threads

kernel doesn't know about threads w/in process

hierarchy of schedulers: one for processes, one within each process

not currently common model — awkward with multicore