• Linearity Theorem: $\Im\{K_a a(t) + K_b b(t)\} = K_a A(f) + K_b B(f)$

orem: $\Im\{x(t-t_0)\}=X(f)e^{-j2\pi ft_0}$ $\int_{-\infty}^{\infty} \chi(t-t_0)e^{-j2\pi ft_0} dt = \int_{-\infty}^{\infty} \chi(t_0)e^{-j2\pi ft_0} dt = e^{-j2\pi ft_0} \int_{-\infty}^{\infty} \chi(t_0)e^{-j2\pi ft_0} dt$ $\chi(f)$ • Time Delay Theorem: $\Im\{x(t-t_0)\} = X(f)e^{-j2\pi f t_0}$ $t_i = t - t_0$ $dt_i = dt$ As $t \rightarrow 0$, $t_i \rightarrow \infty$ $dt_i = dt$ As $t \rightarrow -0$, $t_i \rightarrow -\infty$ $dt_i = dt$ $dt_i = dt$

• Frequency Translation Theorem: $\Im^{-1}\{X(f-f_0)\} = x(t)e^{j2\pi f_0 t}$

• Convolution Theorem: $\Im\{a(t)\otimes b(t)\} = A(f)B(f)$

***** Multiplication Theorem: $\Im\{a(t)b(t)\} = A(f) \otimes B(f)$

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More Theorems

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• Differentiation Theorem: $\Im\left\{\frac{\mathrm{d}}{\mathrm{d}t}x(t)\right\} = (j2\pi f)X(f)$

• Integration Theorem: $\Im\left\{\int_{-\infty}^{t} x(\lambda)d\lambda\right\} = \left(\frac{1}{j2\pi f}\right)X(f) + \frac{1}{2}X(0)\delta(f)$

• Duality Theorem: If $\Im\{x(t)\} = X(f)$, then $\Im\{X(t)\} = x(-f)$

• Scale Change Theorem: $\Im\{x(at)\} = \frac{1}{|a|}X(\frac{f}{a})$, where a is a constant





