

# Computer Vision

## 3. Color

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# Outline

- ▶ Color sources and reflectance
- ▶ Color perception
- ▶ Color representation
- ▶ Surface color from images

## **Textbook:**

- David A. Forsyth and Jean Ponce, Computer Vision: A Modern Approach, Prentice Hall, New Jersey, (1<sup>st</sup> Ed. 2003, 2<sup>nd</sup> Ed. 2012).

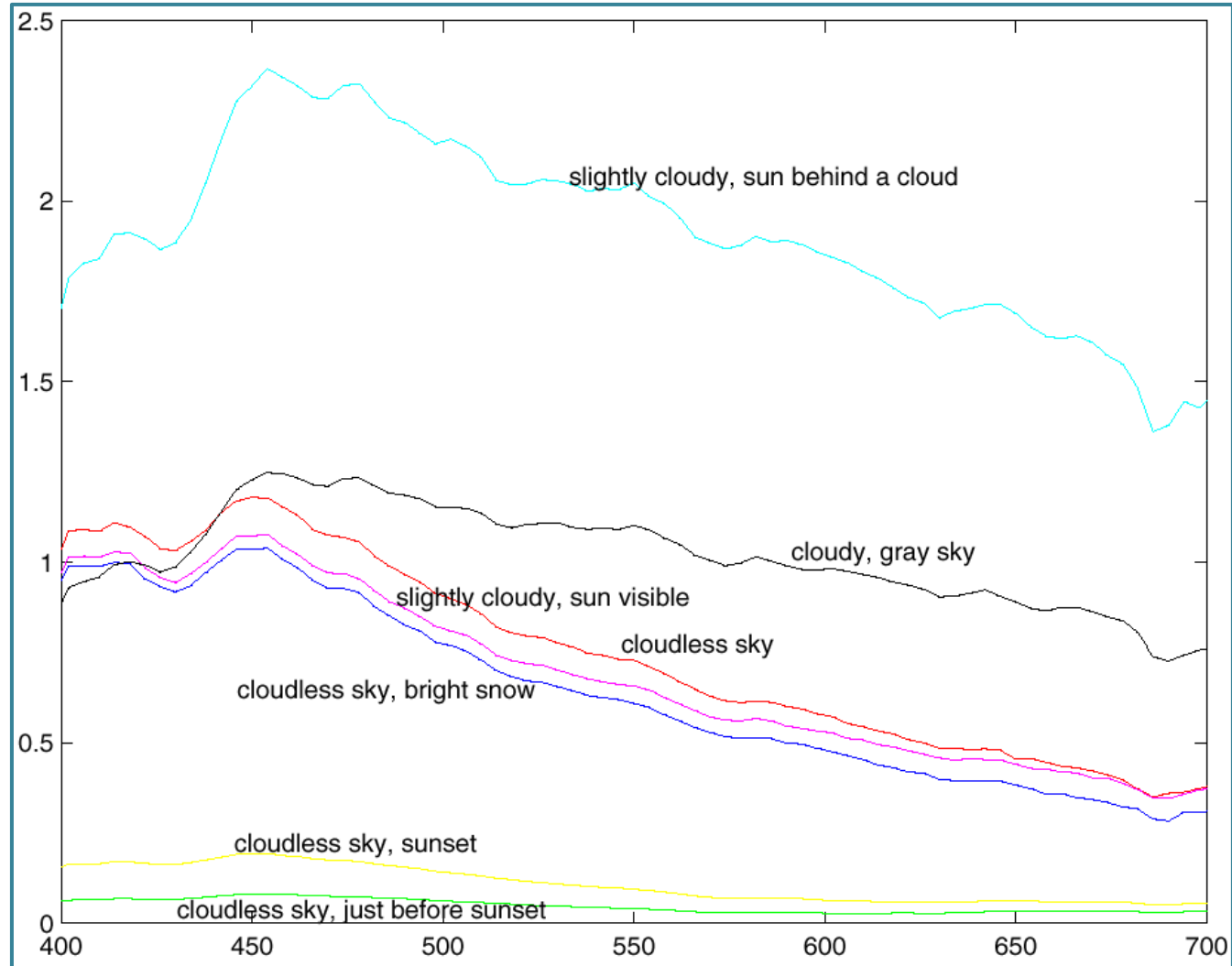
## **Some contents are from the reference lecture notes:**

- Prof. D.A. Forsyth, Computer Vision, UIUC.
- Prof. J. Rehg, Computer Vision, Georgia Inst. of Tech.
- Prof. D. Lowe, Computer Vision, UBC, CA.
- Prof. T. Darrell, Computer Vision and Applications, MIT.
- Hearn and Baker, Computer Graphics, 3rd Ed., Prentice Hall
- E. Angel, Interactive Computer Graphics, 4th Ed., Addison Wesley

# What's color?

- ▶ Light is produced in different amounts at different wavelengths by each light source.
- ▶ Light is differentially reflected at each wavelength, which gives objects their natural colors.
- ▶ The sensation of color is determined by the human visual system, based on the product of light and reflectance (or transmission).

# Illumination of sky



# Why the sky is blue?

- Light of a long wavelength can travel much farther before scattered.

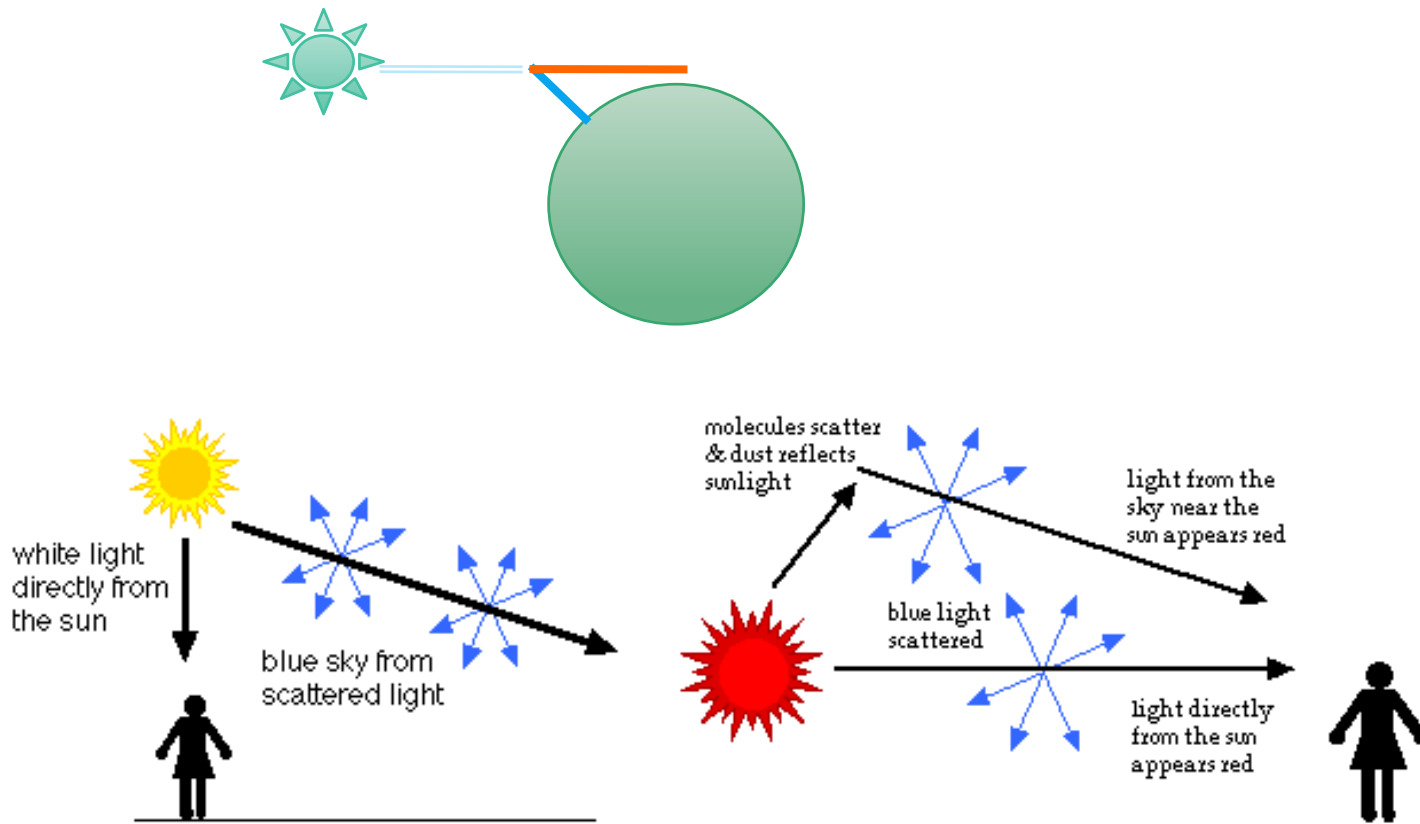
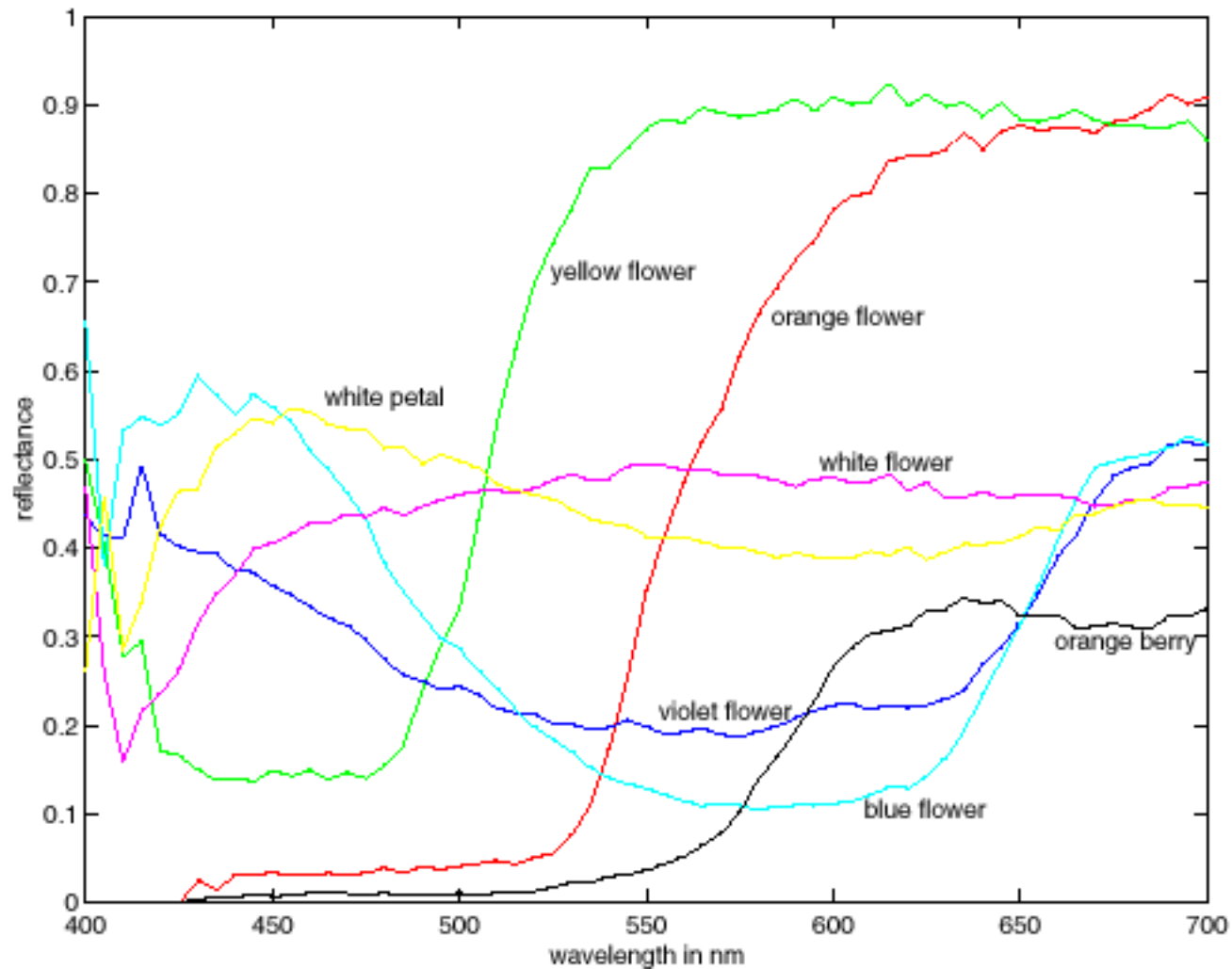
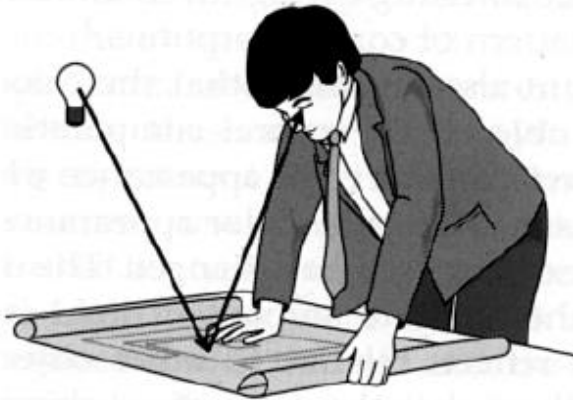


Figure from [http://www.sciencemadesimple.com/sky\\_blue.html](http://www.sciencemadesimple.com/sky_blue.html)

# Spectral albedo

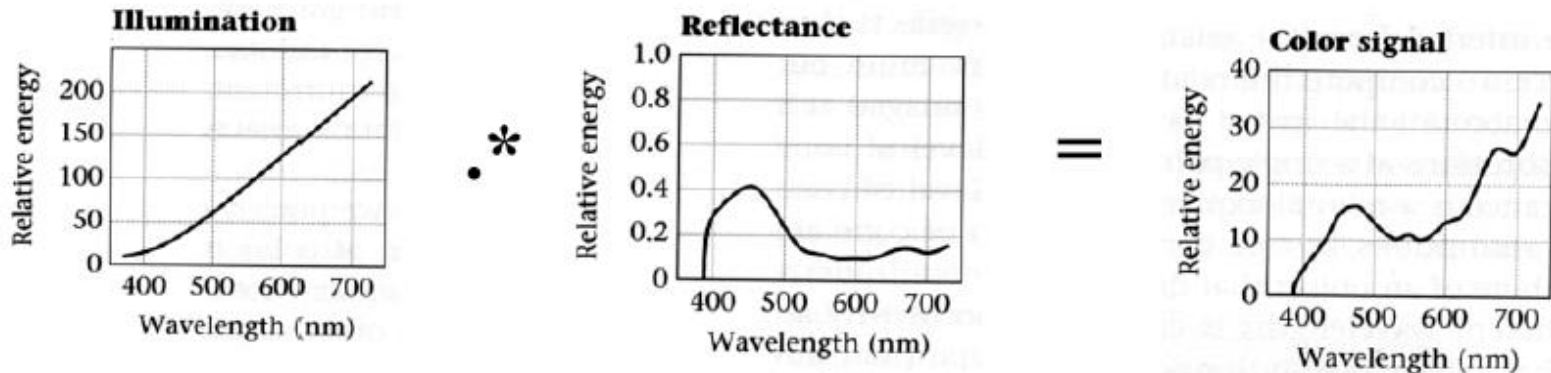


# Bidirectional reflectance distribution function

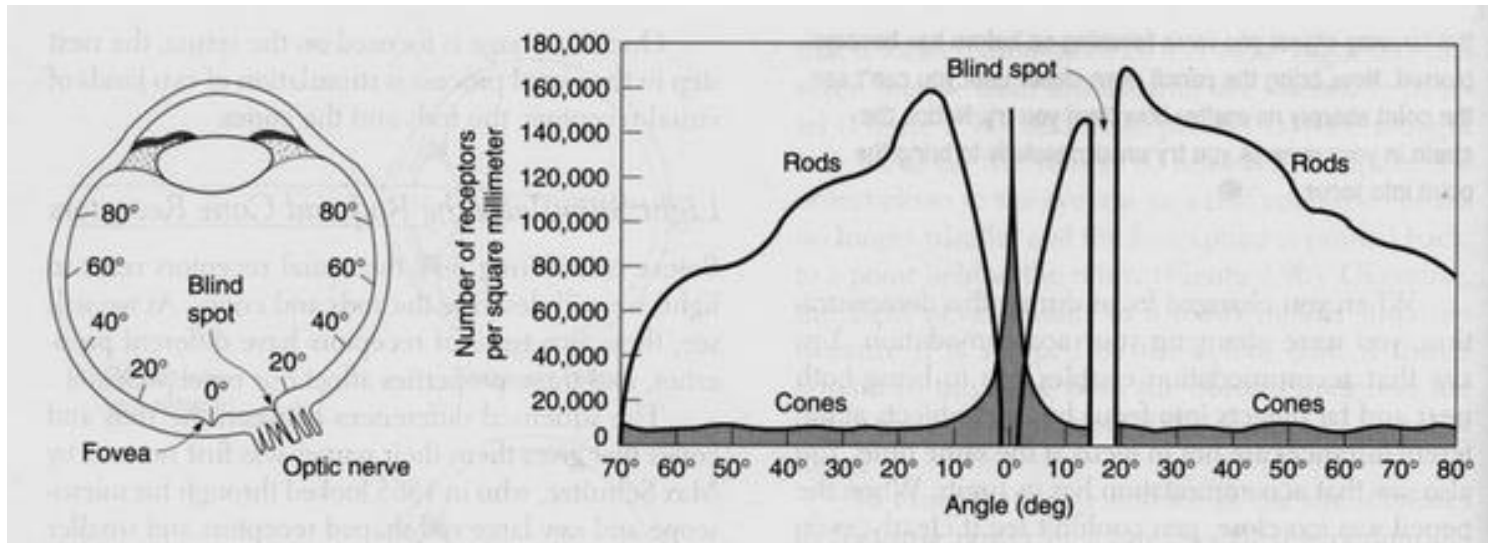


Often are more interested in relative spectral composition than in overall intensity, so the spectral BRDF computation simplifies a wavelength-by-wavelength multiplication of relative energies.

*Why do we usually use RGB?*



# Retina

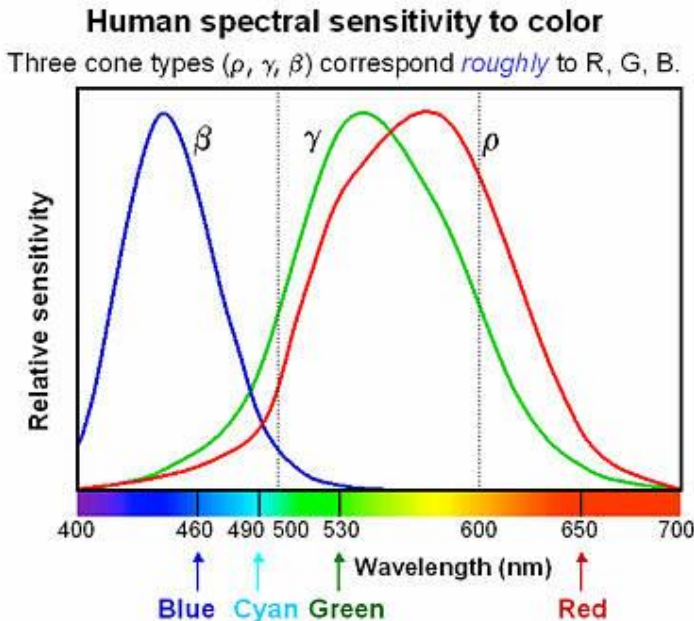


- ▶ Center of retina has most of the cones →
  - ▶ allows for high acuity of objects focused at center
- ▶ Edge of retina is dominated by rods →
  - ▶ allows detecting motion of threats in periphery



# Color perception via cones

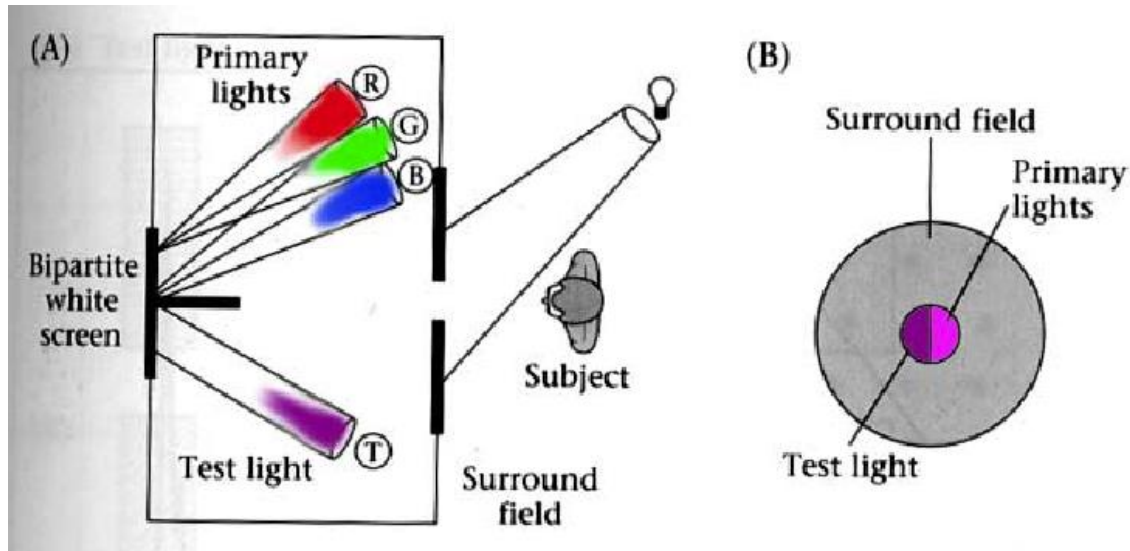
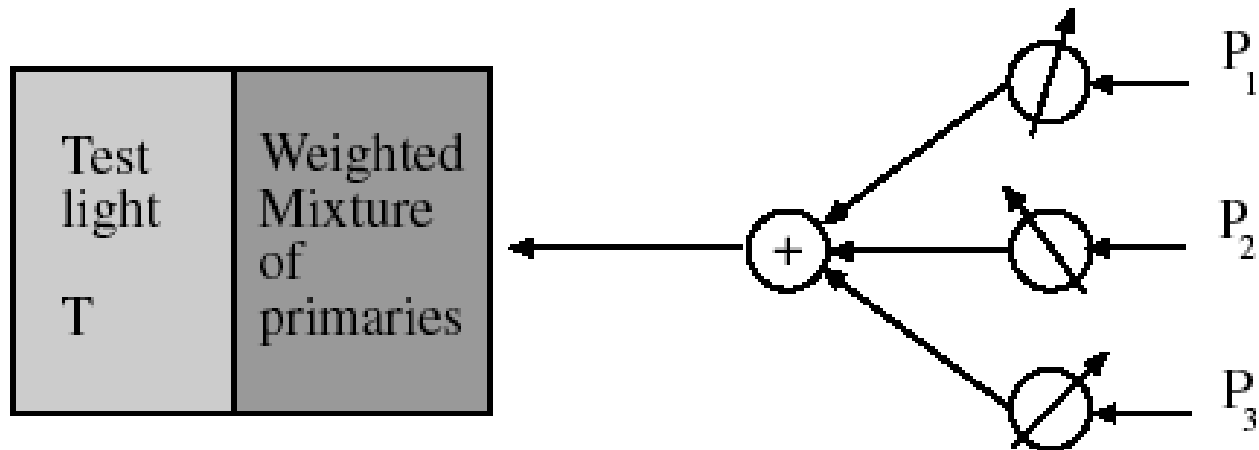
- ▶ “Photopigments” used to sense color
- ▶ 3 types: blue, green, “red” (really yellow) (or S, M, L cones)
  - ▶ each sensitive to different bands of spectrum
  - ▶ ratio of neural activity of the 3 → color
    - ▶ other colors are perceived by combining stimulation



# Distribution of photopigments

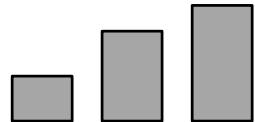
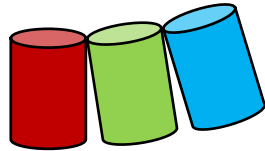
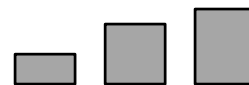
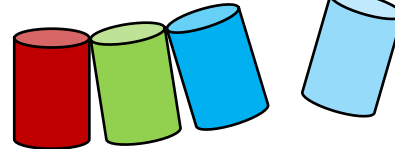
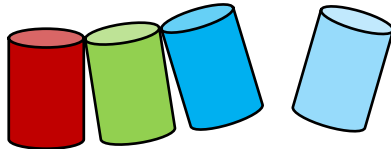
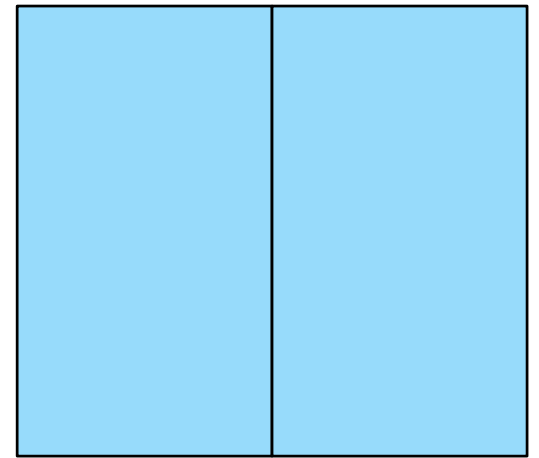
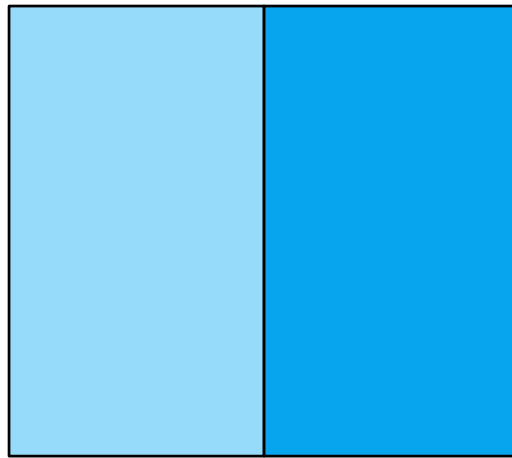
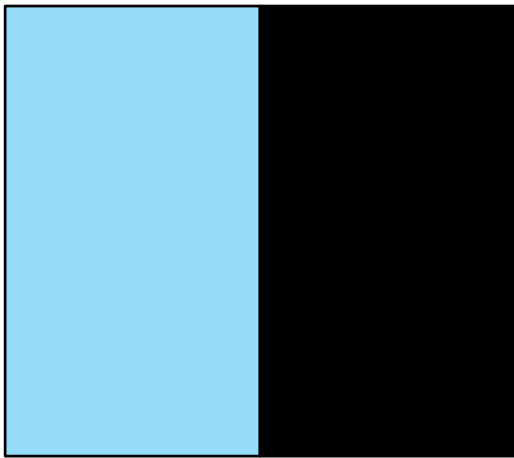
- ▶ Not distributed evenly
  - ▶ mainly reds (64%) & very few blues (4%) →
    - ▶ insensitivity to short wavelengths
      - ▶ cyan to deep-blue
- ▶ Center of retina (high acuity) has **no** blue cones →
  - ▶ disappearance of small blue objects you fixate on

# Color match experiments



Color matching experiments imply that 3 primaries are enough for most people.

# Color matching experiment



# Trichromacy

- ▶ Experimental facts:
  - ▶ Three primaries will work for most people if we allow subtractive matching
  - ▶ Exceptional people can match with two or only one .
  - ▶ Some elderly people may choose weights that differ from the norm.
  - ▶ Most people make the same matches.
- ▶ Color matching experiments imply that three good primaries are sufficient.

# Color space

- ▶ Use color matching functions to define a coordinate system for color.
- ▶ Each color can be assigned a triple of coordinates with respect to some color space (e.g. RGB).
- ▶ Devices (monitors, printers, projectors) and computers can communicate colors precisely.

# RGB color space

- ▶ Primaries are monochromatic 645.2nm, 526.3nm, 444.4nm.
- ▶ Color matching functions have negative parts
- ▶ Some colors can be matched with subtraction.

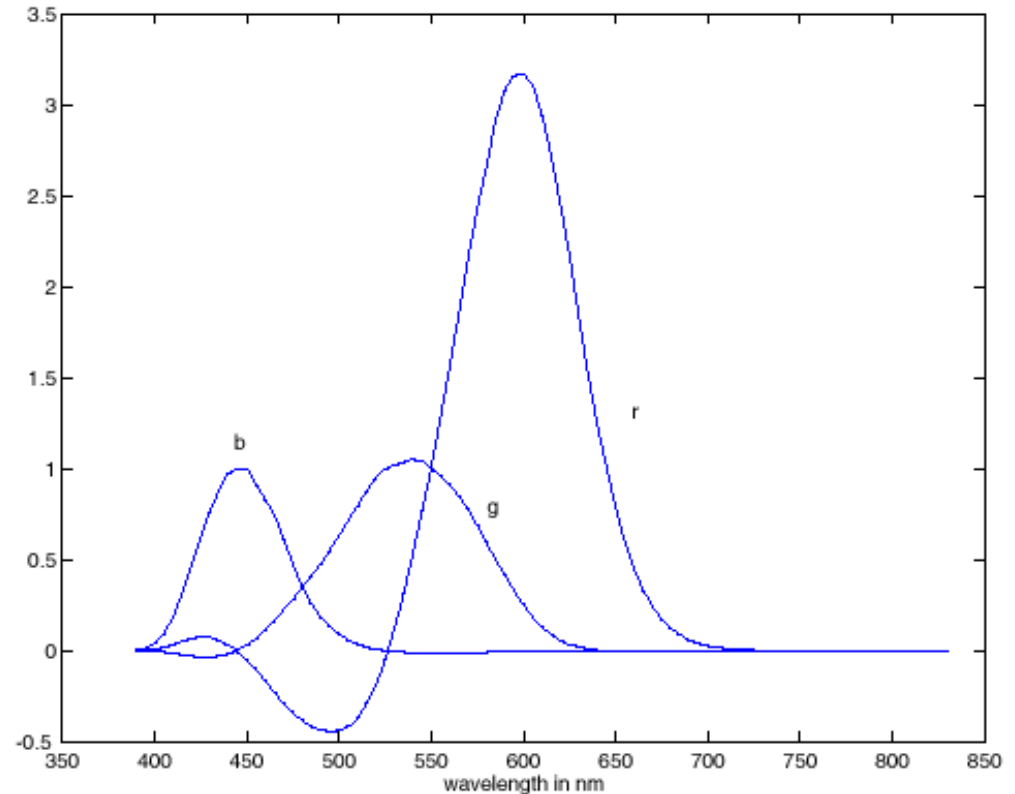
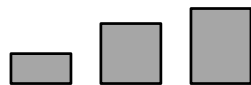
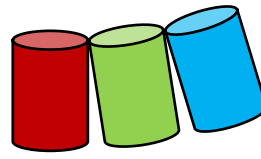
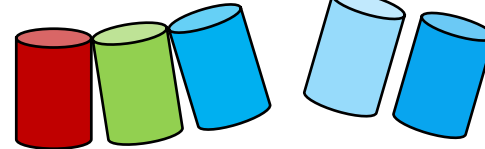
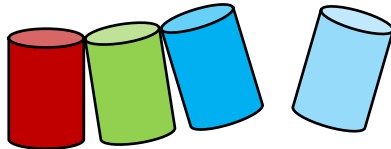
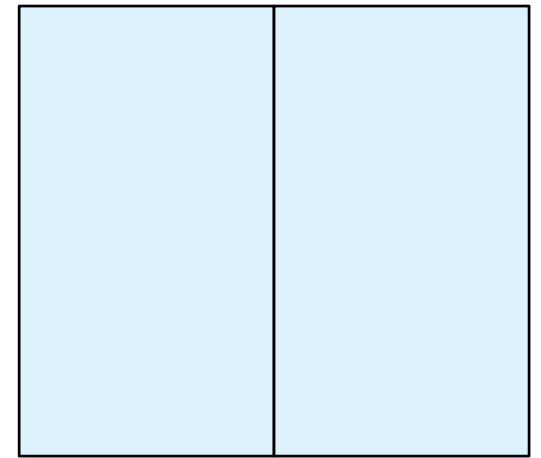
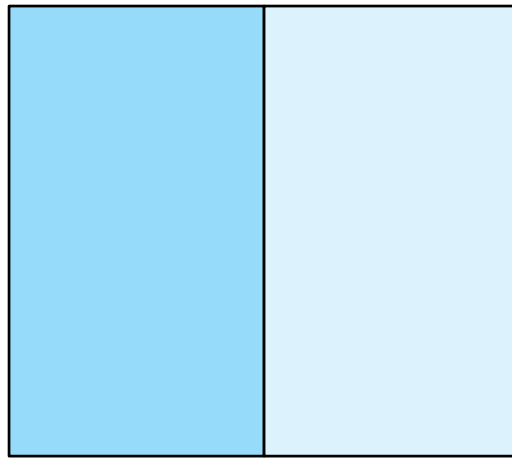
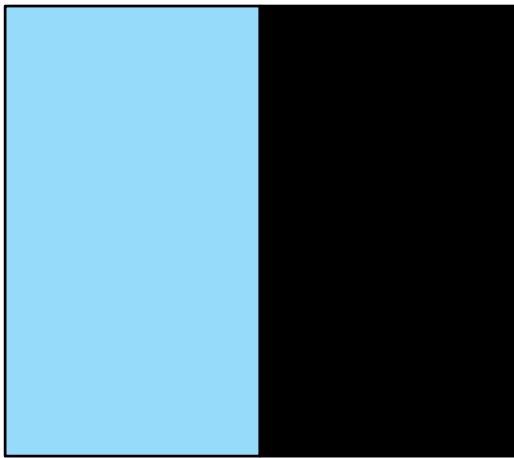


Figure courtesy of D. Forsyth

# Color matching experiment

What's the negative color?





# CIE XYZ color space

- ▶ CIE XYZ: color matching functions are positive everywhere, but primaries are imaginary.
- ▶ Usually draw  $x$ ,  $y$ , as
$$x = X/(X+Y+Z)$$
$$y = Y/(X+Y+Z)$$
- ▶ The overall brightness is ignored.

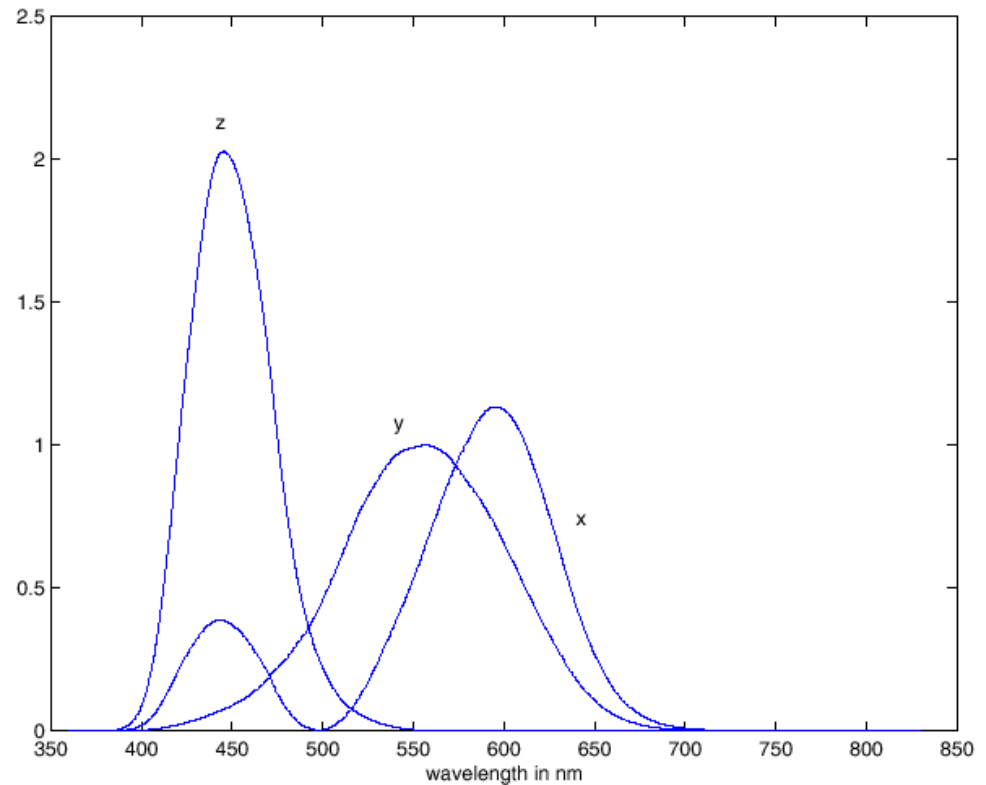
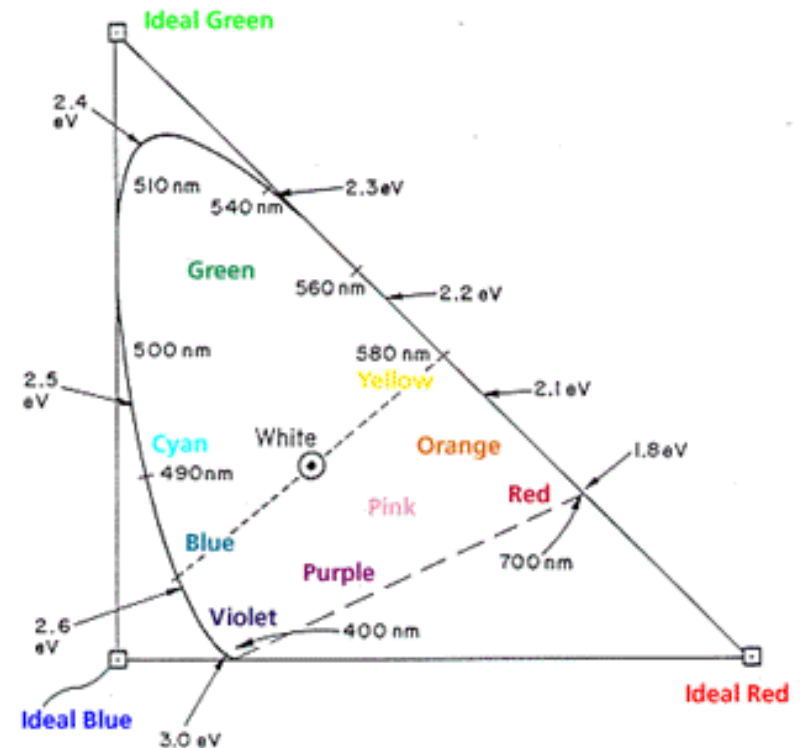


Figure courtesy of D. Forsyth

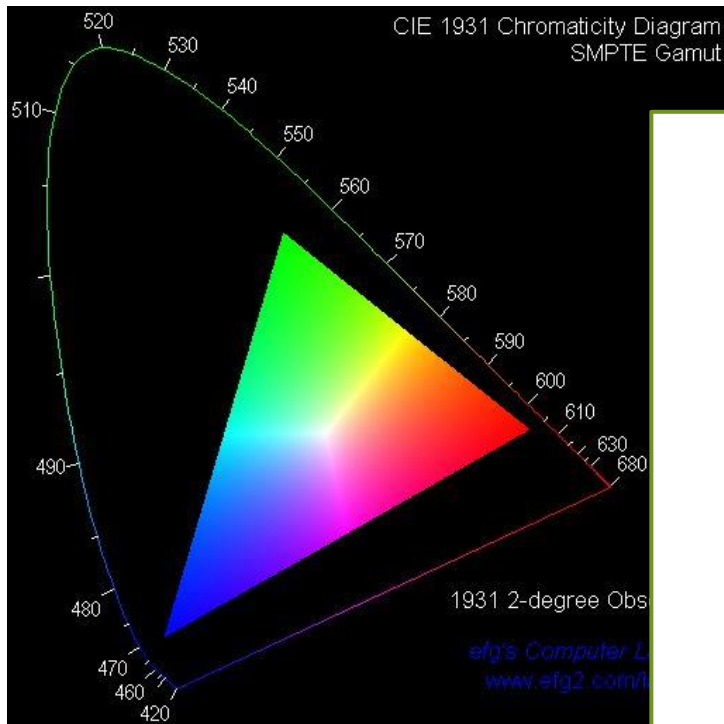
# CIE xy Color space

- ▶ White is in the center, with saturation increasing towards the boundary
  - ▶ Mixing two colored lights creates colors on a straight line
  - ▶ Mixing 3 colors creates colors within a triangle
- ▶ There are sets of (x, y) coordinates that don't represent real colors, because the primaries are not real lights.



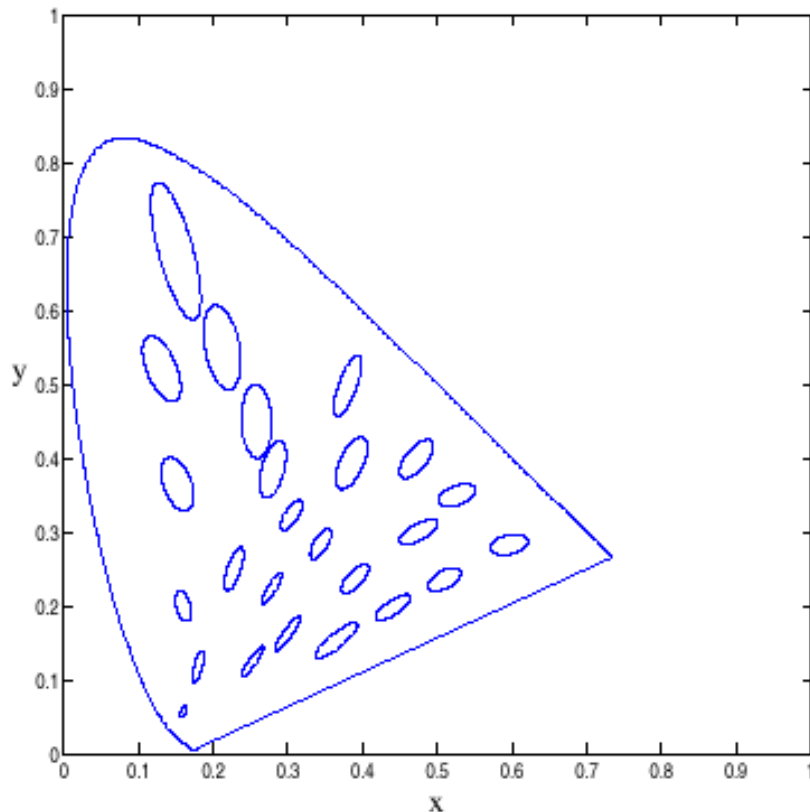
# Color display

- ▶ The colors that can be displayed on a typical computer monitor (phosphor limitations keep the space quite small)

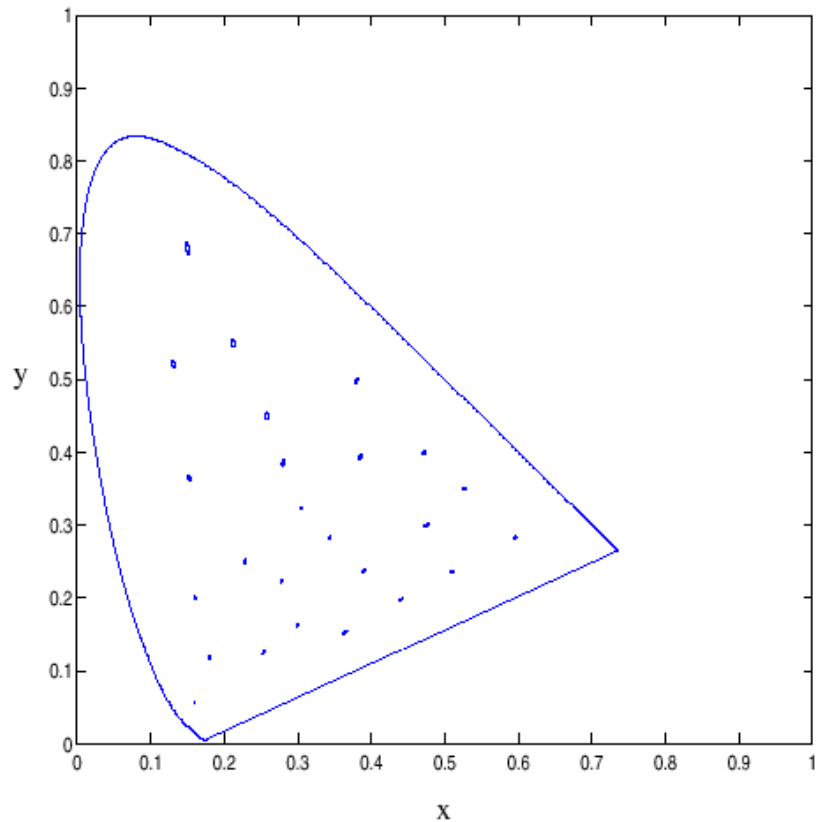


# Uniform color spaces

- MacAdam ellipses demonstrate that differences in  $x, y$  coordinates are a poor guide to differences in color



10 times of the actual size



Actual size

Figures courtesy of D. Forsyth

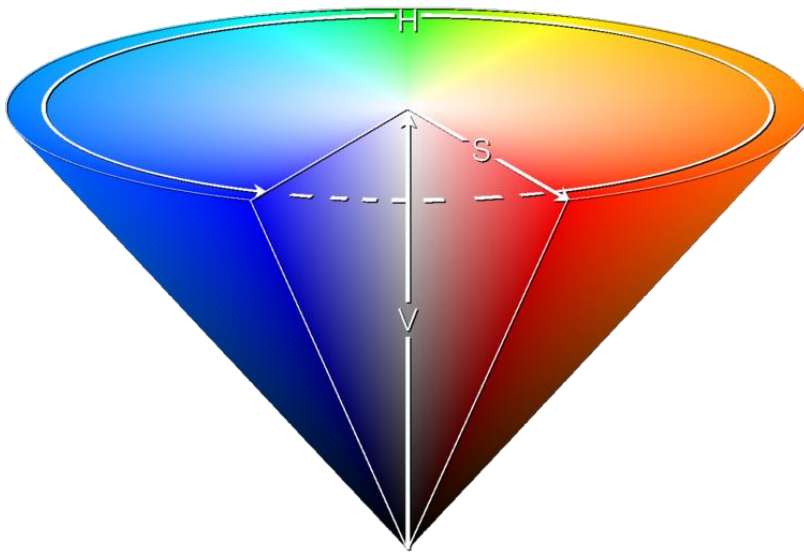
# HSV color space

- ▶ Hue
  - ▶ property of the wavelengths of light (i.e., “color”)
- ▶ Lightness (or value)
  - ▶ how much light appears to be reflected from a surface
  - ▶ some hues are inherently lighter or darker
- ▶ Saturation
  - ▶ purity of the hue
    - ▶ e.g., red is more saturated than pink
  - ▶ color is mixture of pure hue & achromatic color
    - ▶ portion of pure hue is the degree of saturation



# HSV color space (cont.)

Hue, Saturation, Value model (HSV)



[https://en.wikipedia.org/wiki/HSL\\_and\\_HSV](https://en.wikipedia.org/wiki/HSL_and_HSV)

## HSV color space (cont.)

$$H \in [0 .. 360]; S, V, R, G, B \in [0, 1]$$

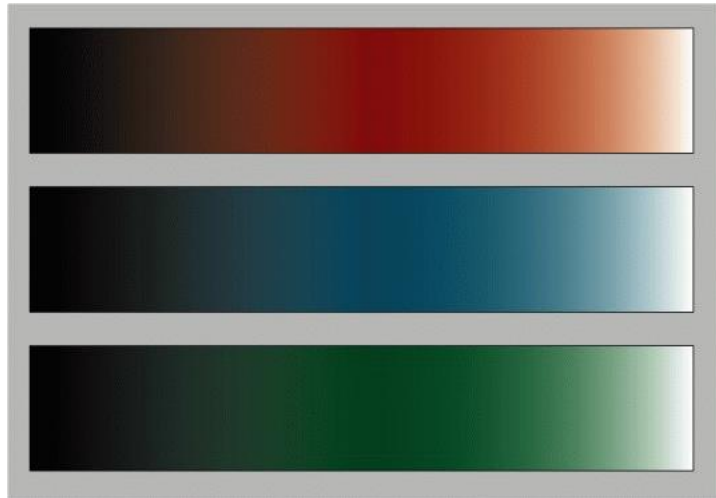
$$MAX = \max(R, G, B); MIN = \min(R, G, B)$$

$$H = \begin{cases} \text{undefined,} & \text{if } MAX = MIN \\ 60 \times \frac{G-B}{MAX-MIN} + 0, & \text{if } MAX = R \\ & \text{and } G \geq B \\ 60 \times \frac{G-B}{MAX-MIN} + 360, & \text{if } MAX = R \\ & \text{and } G < B \\ 60 \times \frac{B-R}{MAX-MIN} + 120, & \text{if } MAX = G \\ 60 \times \frac{R-G}{MAX-MIN} + 240, & \text{if } MAX = B \end{cases}$$

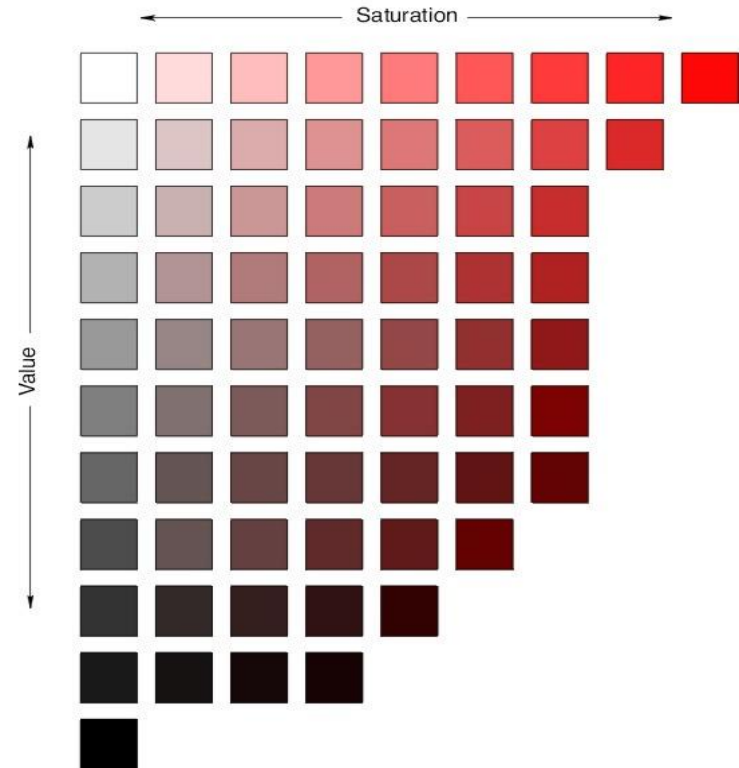
$$S = \begin{cases} 0, & \text{if } MAX = 0 \\ 1 - \frac{MIN}{MAX}, & \text{otherwise} \end{cases}$$

$$V = MAX$$

# HSV color space (cont.)



lightness



Saturation

[http://www2.ncsu.edu/scivis/lessons/colormodels/color\\_models2.html#saturation.](http://www2.ncsu.edu/scivis/lessons/colormodels/color_models2.html#saturation.)



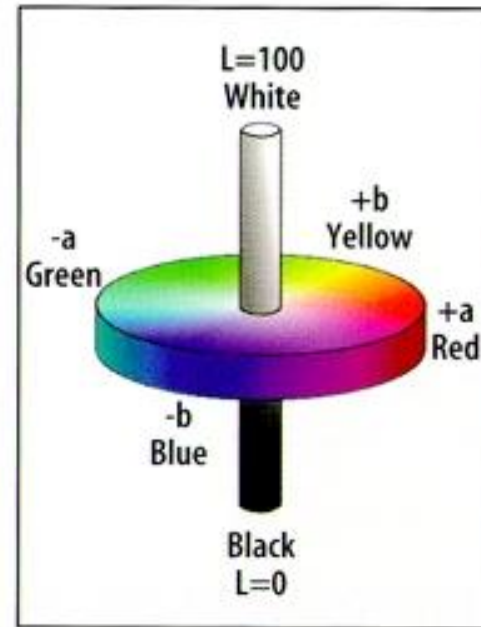
# LAB color space

- CIE LAB is the most popular uniform color space.

$$L^* = 116 \left( \frac{Y}{Y_n} \right)^{1/3} - 16$$

$$a^* = 500 \left[ \left( \frac{X}{X_n} \right)^{1/3} - \left( \frac{Y}{Y_n} \right)^{1/3} \right]$$

$$b^* = 200 \left[ \left( \frac{Y}{Y_n} \right)^{1/3} - \left( \frac{Z}{Z_n} \right)^{1/3} \right]$$



*Lab model*

# Images of real objects

- ▶ Assume that reflections are mainly due to diffuse and specular components.
- ▶ Diffuse components
  - ▶ Color of reflected light depends on both illuminant and surface.
- ▶ Specular components
  - ▶ Specularities often saturate the camera film.
  - ▶ Specularities on dielectric (non-metallic) objects mainly take the color of the light.



# Distribution of reflected lights

- ▶ T the saturate diffuse components.
- ▶ S the saturate specular components.

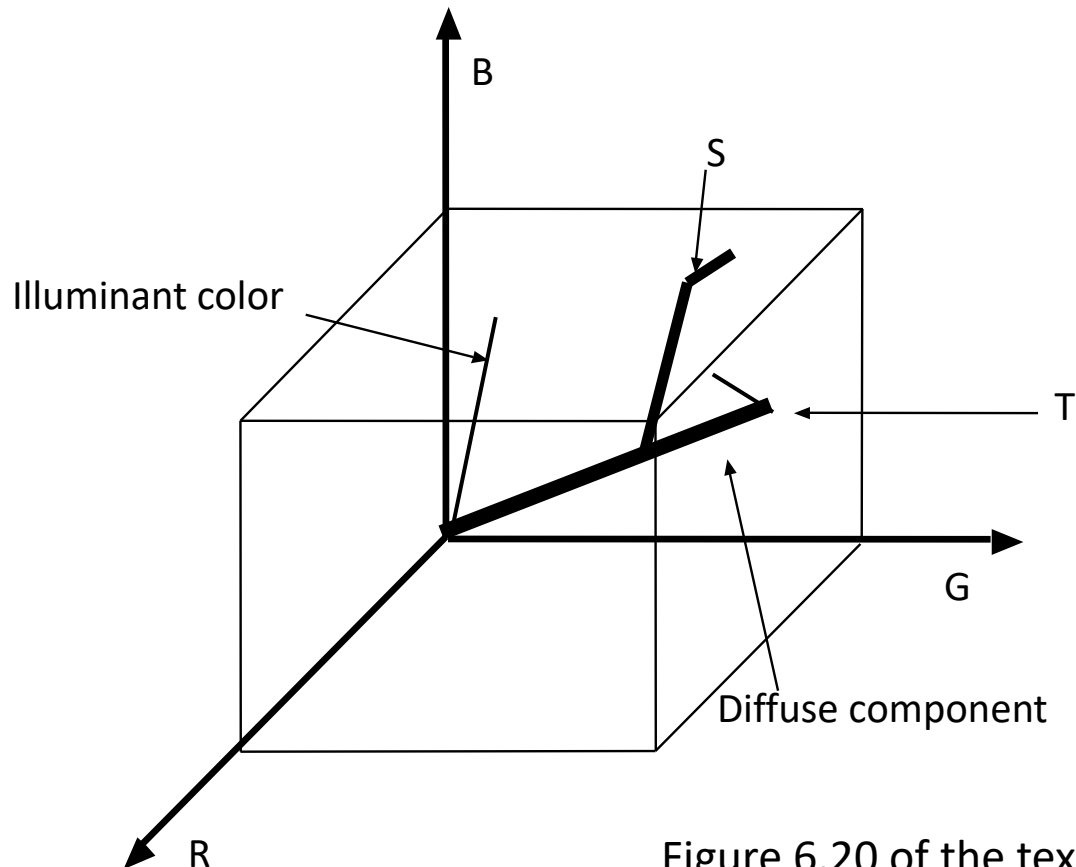


Figure 6.20 of the textbook

# Distribution of reflected lights (cont.)

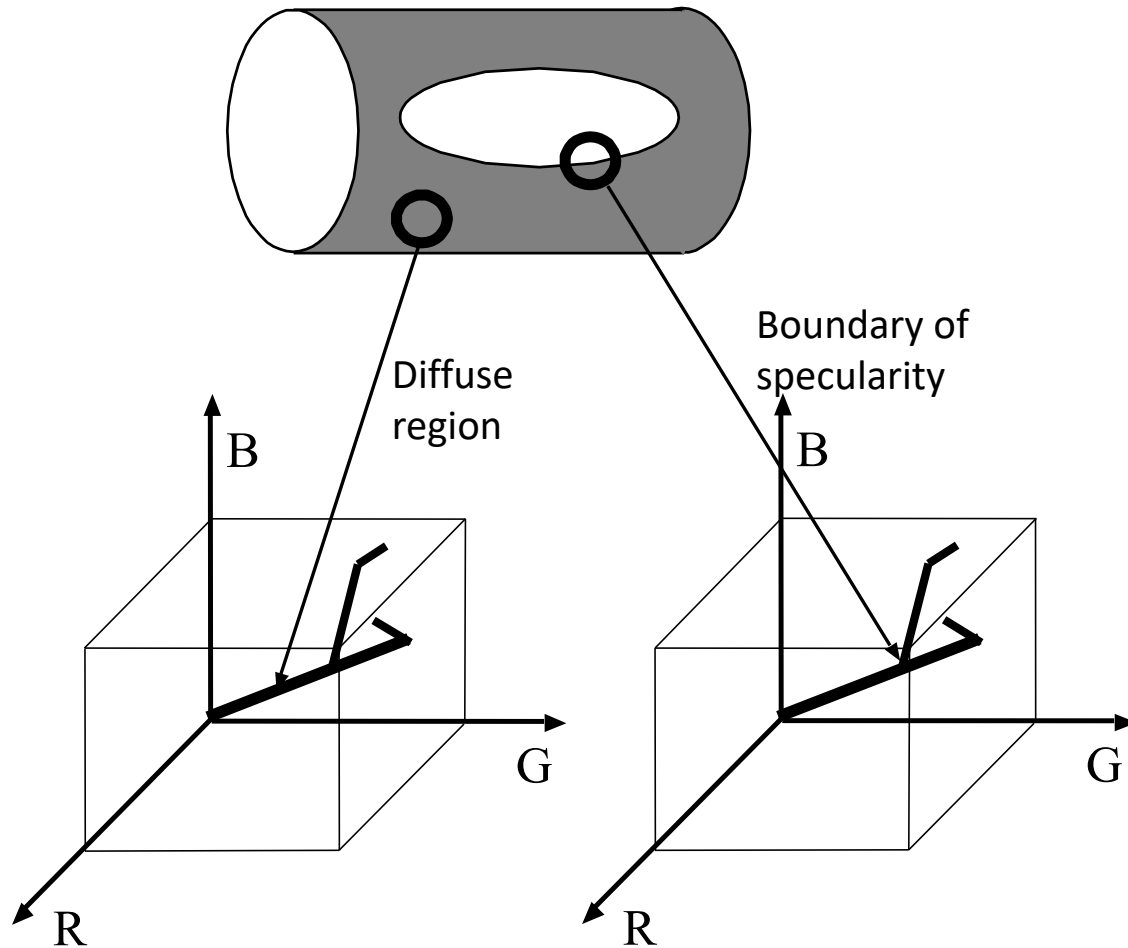


Figure 6.21 of the textbook

# Human color constancy

- ▶ Color constancy: hue and saturation
- ▶ Lightness constancy: gray-level
- ▶ Humans can perceive
  - ▶ Color that a surface would have under white light (surface color)
  - ▶ Color of reflected light (separate surface color from measured color)
  - ▶ Color of illuminant (limited)

# A simple model of lightness constancy

## ► Assumptions:

- Linear camera response
- Nearly planar frontal scene
- Lambertian reflectance

$k_c$ : Camera gain

$I$ : illumination (reflection of light on surface)

$\rho$ : albedo (material color)

$$C(x) = k_c I(x) \rho(x)$$

## ► Camera model: $\log C(x) = \log k_c + \log I(x) + \log \rho(x)$

## ► Modeling assumptions for scene

- Piecewise constant albedo
- Slowly-varying Illumination

# 1-D lightness

$p$  can be regarded as  $C/k_c$

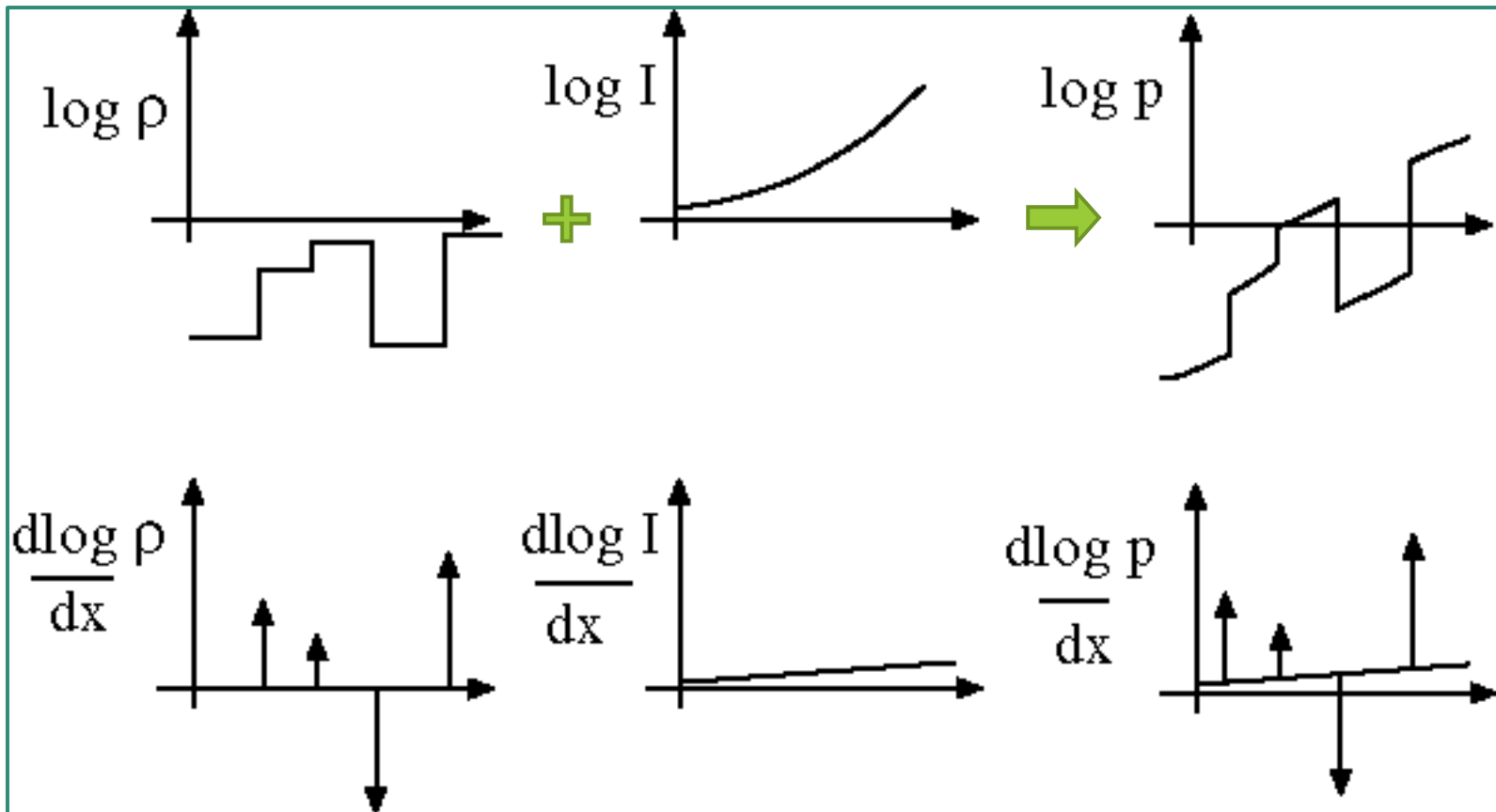
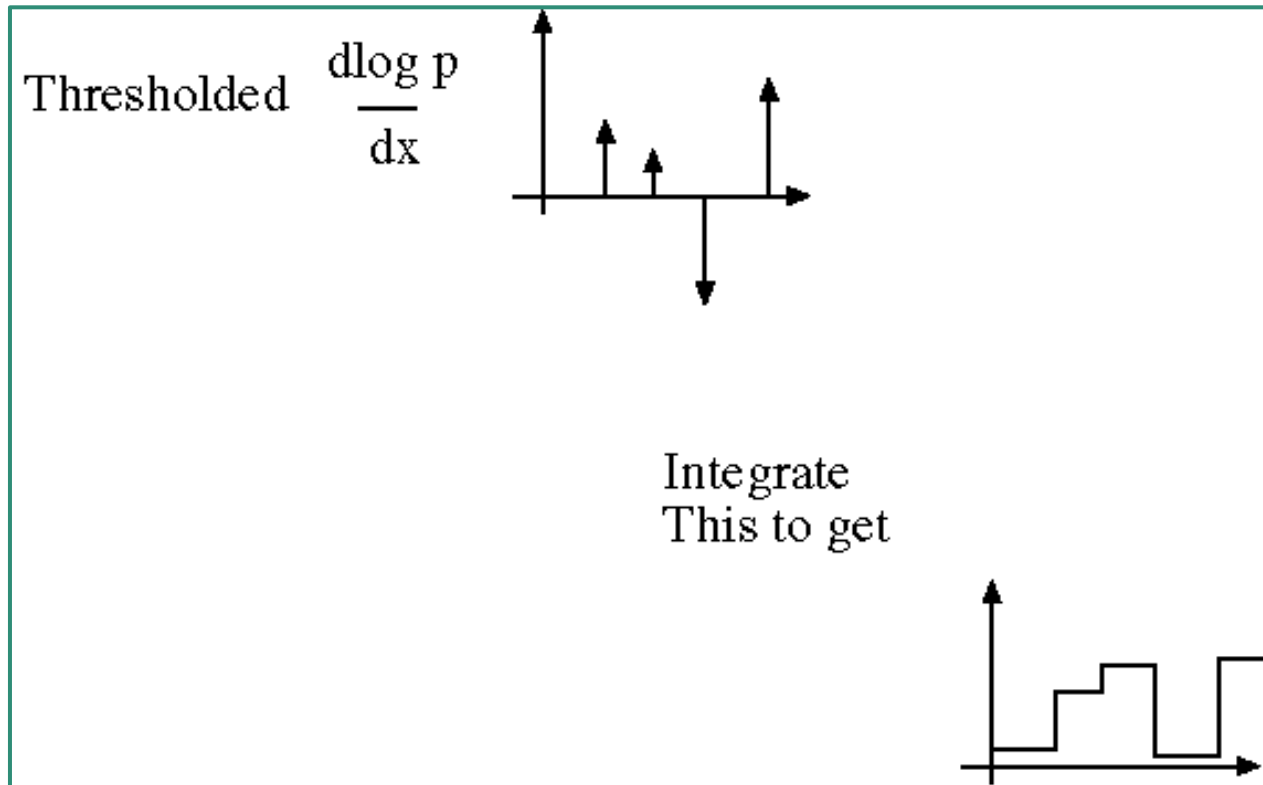


Figure 6.23 of the textbook

# 1-D lightness

- Assume that albedo changes during occlusion.
  - Derivative of  $\log \rho$  are either zero or large.





# Extending to 2D

- ▶ Spatial issues
  - ▶ Integration becomes much harder
  - ▶ Using minimization.
- ▶ Recover of absolute reference
  - ▶ Brightest patch is white
  - ▶ Average reflectance across scene is known
  - ▶ Gamut(collection of all colors) is known
  - ▶ Known reference (e.g. skin color)