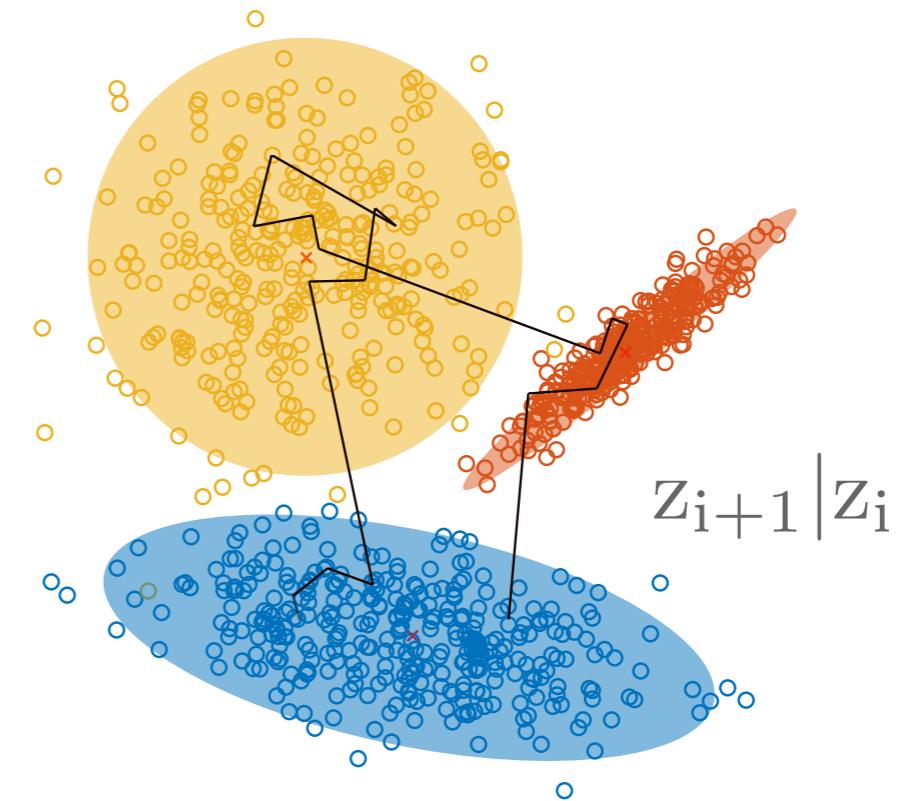
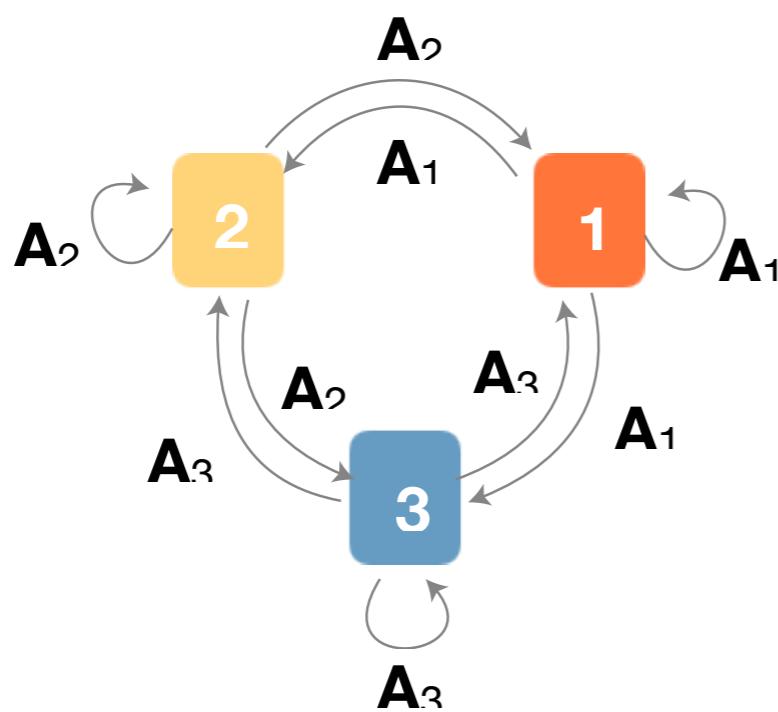


DS-GA 3001.008 Modelling time series data

L8. Introduction to Gaussian Processes

Instructor: Cristina Savin
NYU, CNS & CDS

HW3: HMMs



multivariate gaussian

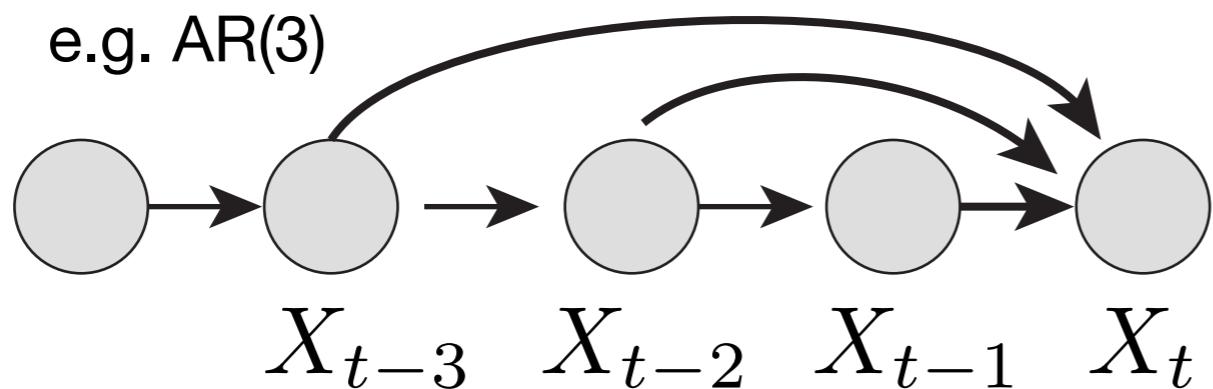
$$\alpha(z_i) = P(x_{1:i}|z_i) P(z_i) = P(x_i|z_i) \sum_{z_{i-1}} \alpha(z_{i-1}) P(z_i|z_{i-1})$$

$$\mathcal{N}(\mu, \Sigma) = (2\pi)^{-d/2} |\Sigma|^{-1/2} \exp \left[-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right]$$

different parameters for each latent $k=1,2,3$

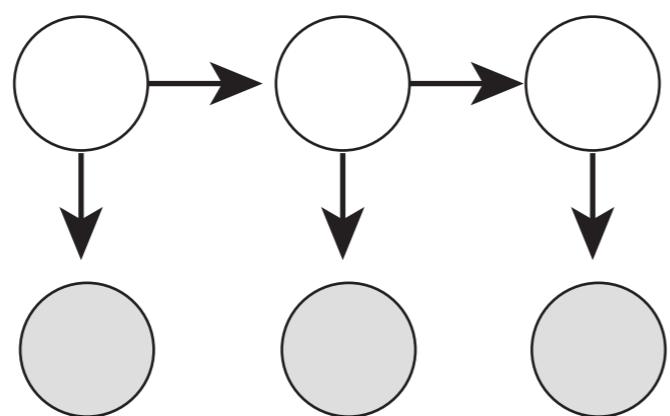
Big picture

ARIMA: directly model data statistics



simple dependencies
linear prediction

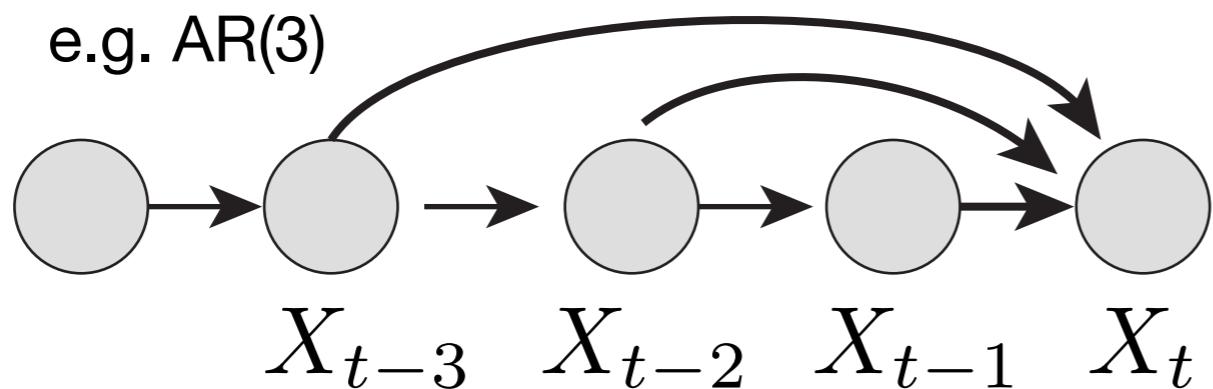
Latent state models: introduce latent variables



more complex dependencies
Markov dynamics in latent space
more complicated prediction

Big picture

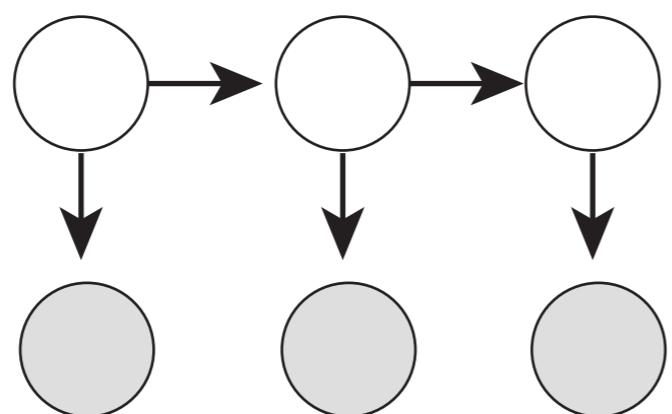
ARIMA: directly model data statistics



simple dependencies
linear prediction

GP: complex functional dependencies

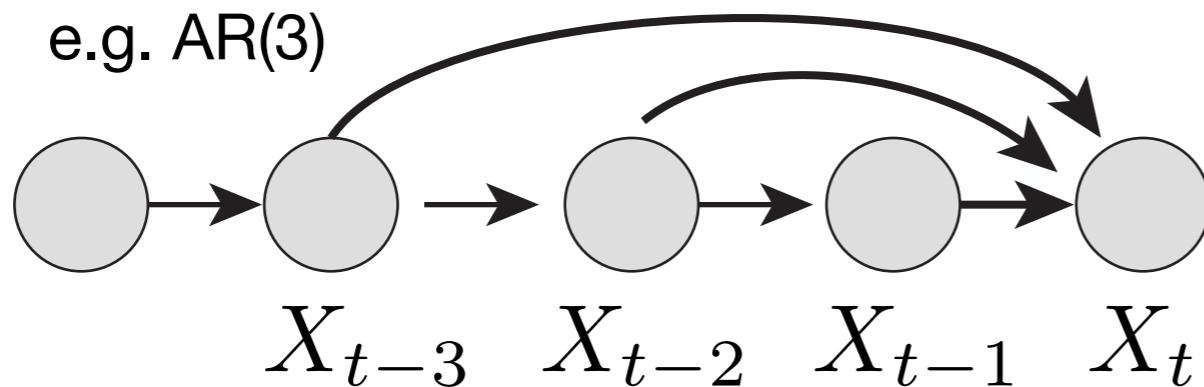
Latent state models: introduce latent variables



more complex dependencies
Markov dynamics in latent space
more complicated prediction

Big picture

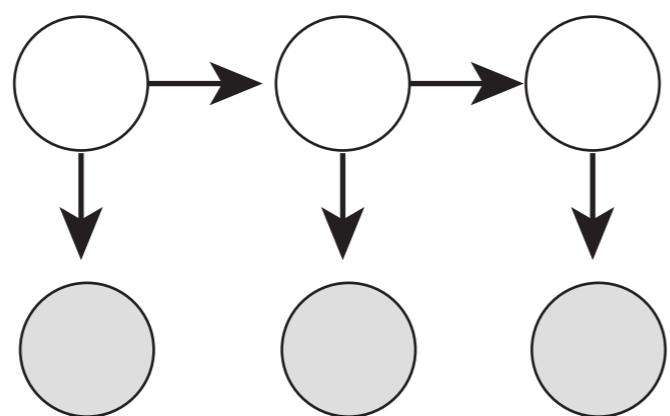
ARIMA: directly model data statistics



simple dependencies
linear prediction

GP: complex functional dependencies

Latent state models: introduce latent variables

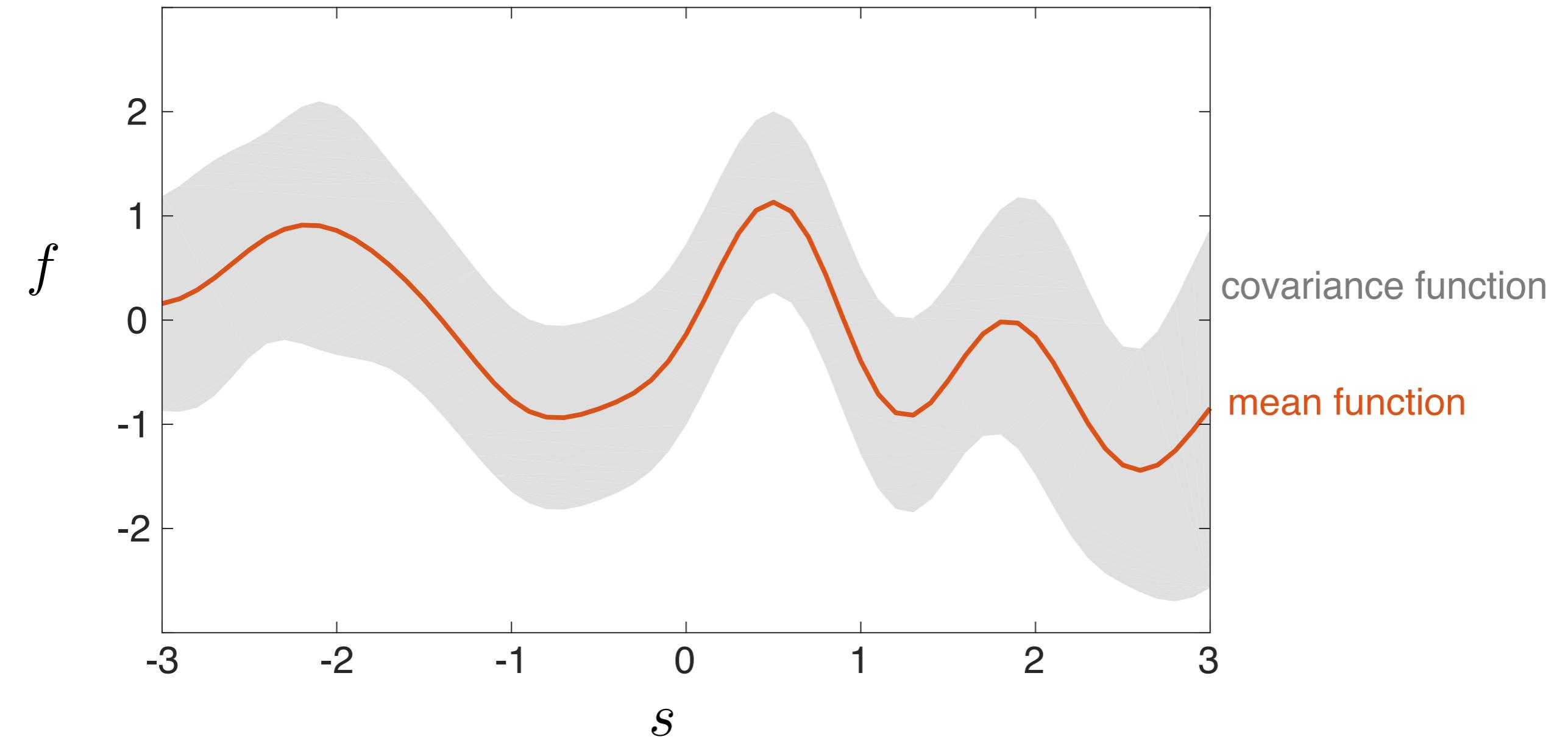


more complex dependencies
Markov dynamics in latent space
more complicated prediction

GP: complex latent dynamics

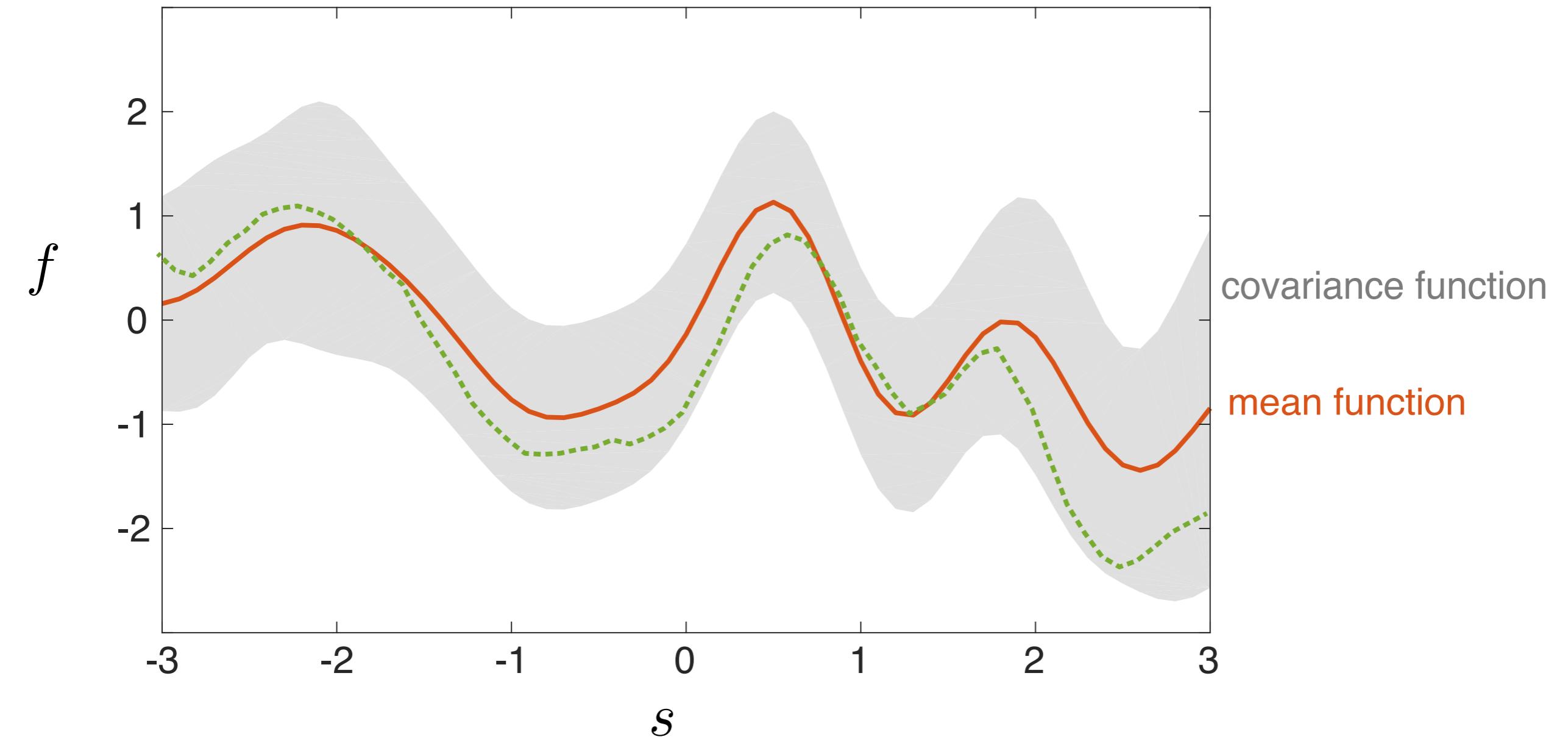
Probabilistic inference with functions

$$f \sim \text{GP} (f; \mu(s), k(s_1, s_2))$$



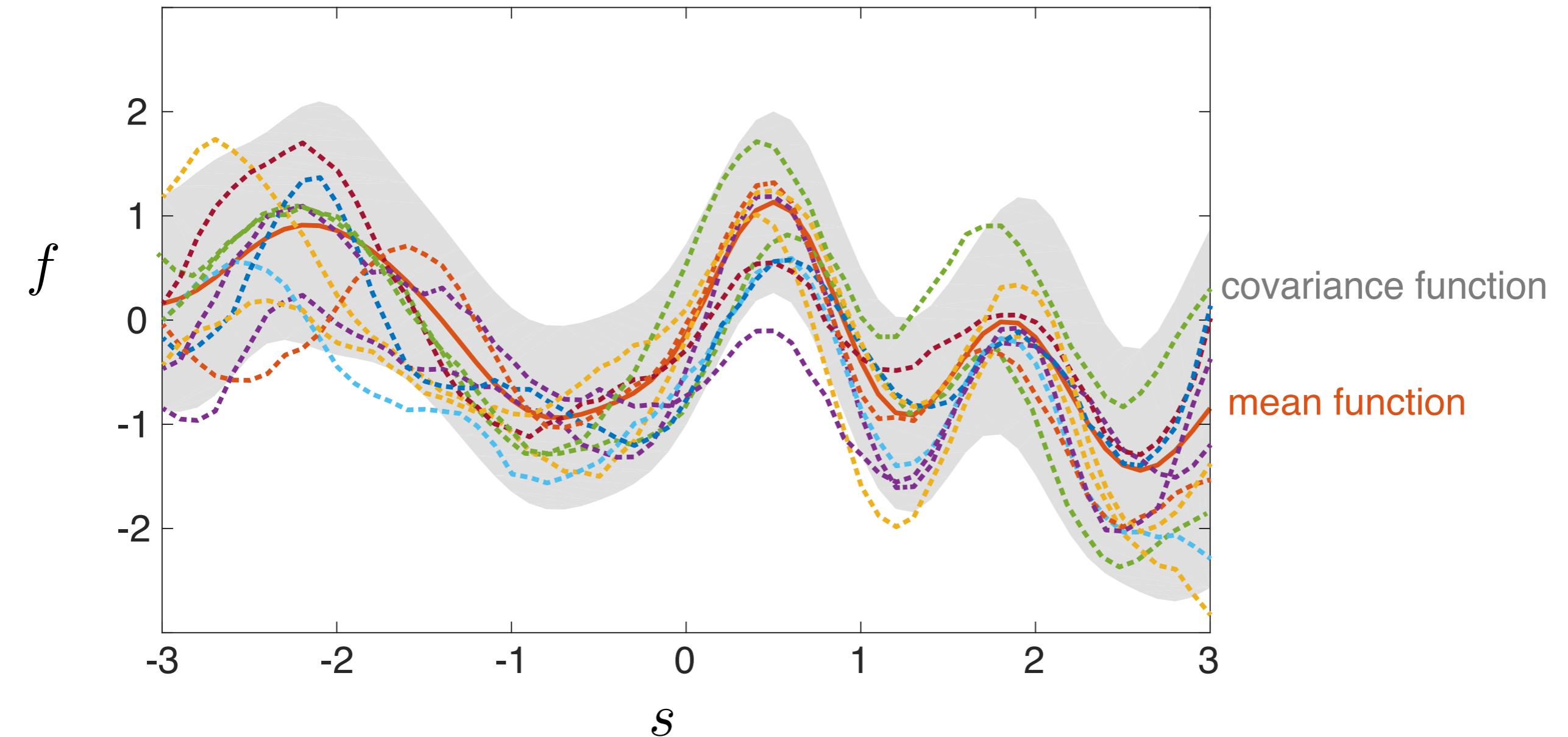
Probabilistic inference with functions

$$f \sim \text{GP} (f; \mu(s), k(s_1, s_2))$$



Probabilistic inference with functions

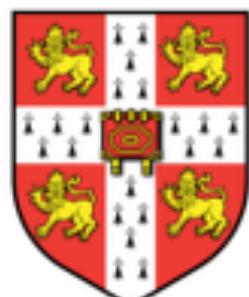
$$f \sim \text{GP} (f; \mu(s), k(s_1, s_2))$$



An introduction to Gaussian processes for probabilistic inference

Dr. Richard E. Turner (ret26@cam.ac.uk)

Computational and Biological Learning Lab, Department of Engineering,
University of Cambridge

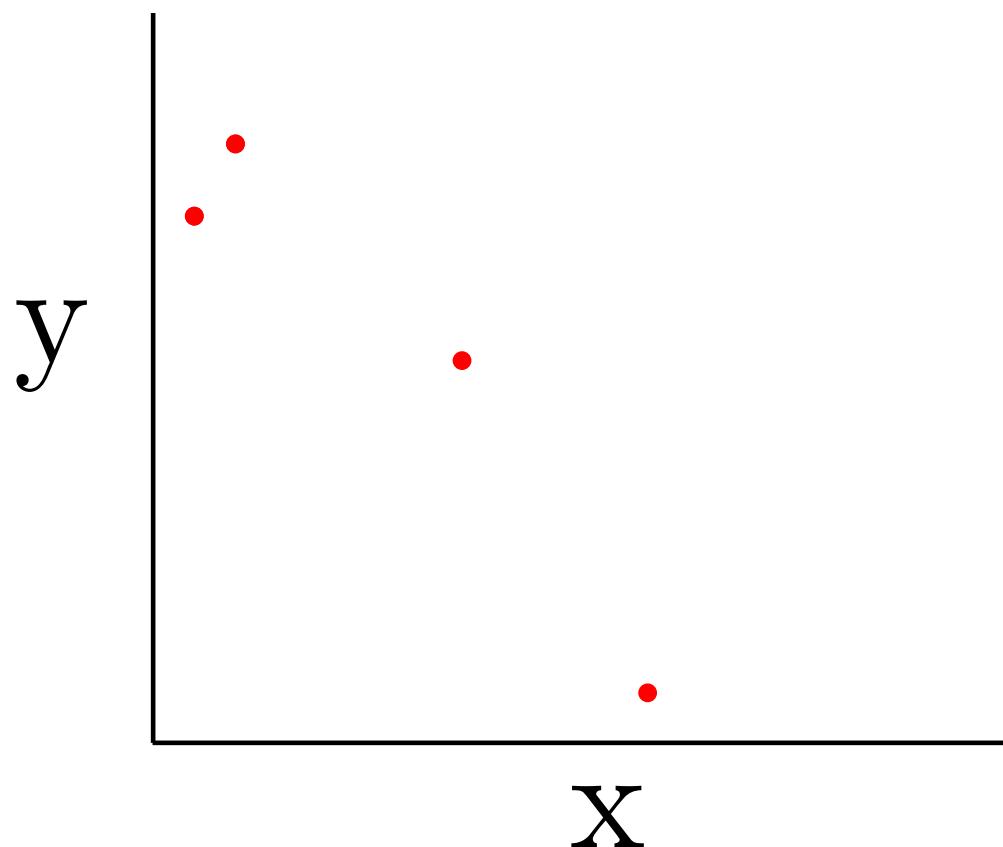


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CAMBRIDGE

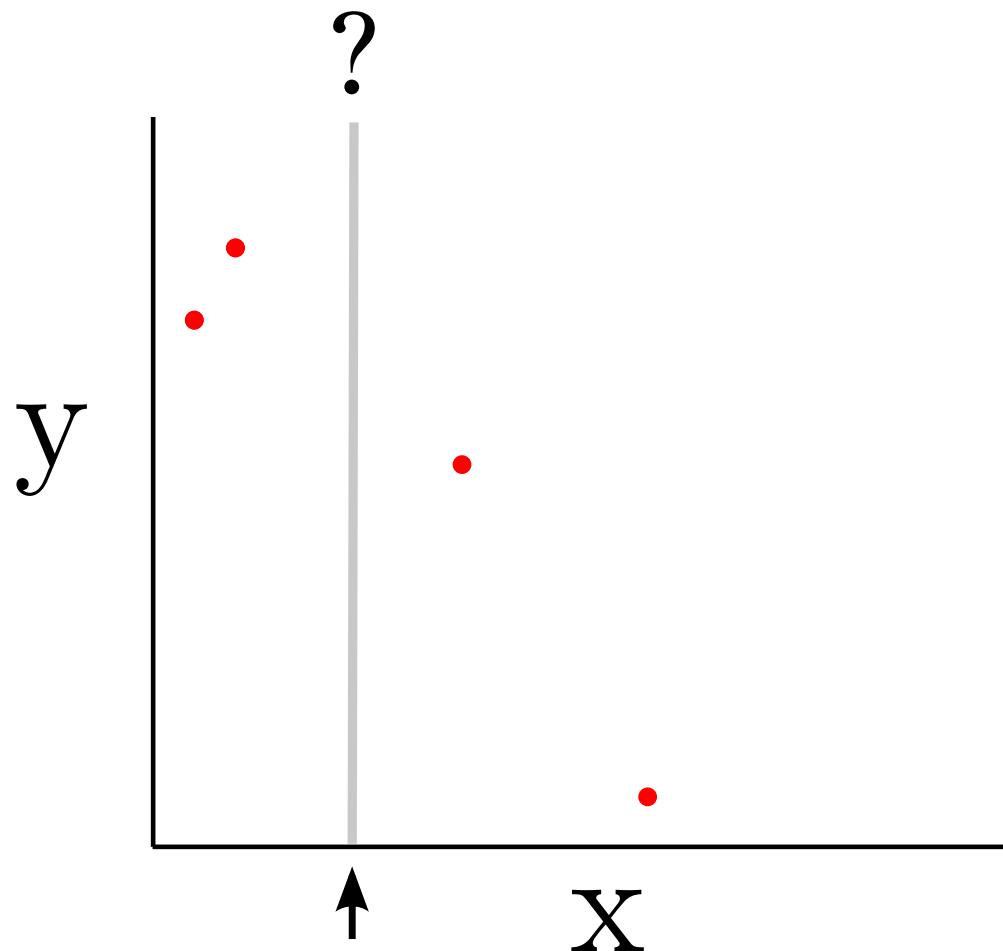


Computational and
Biological Learning

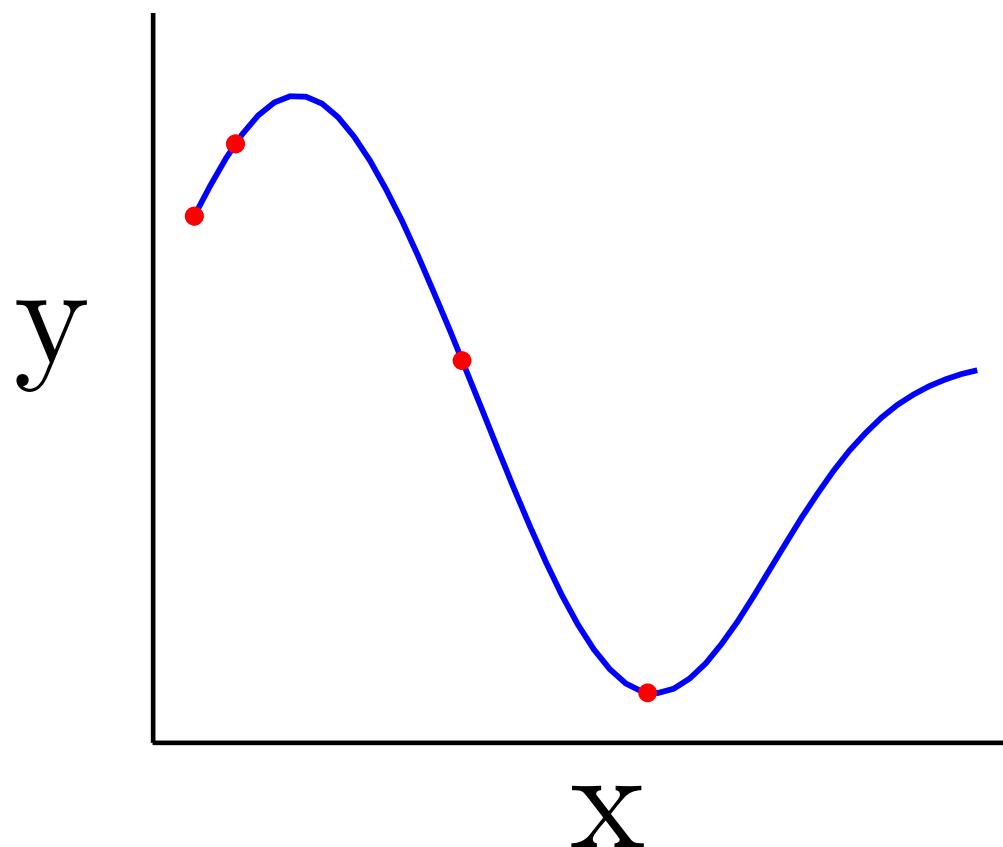
Motivation: non-linear regression



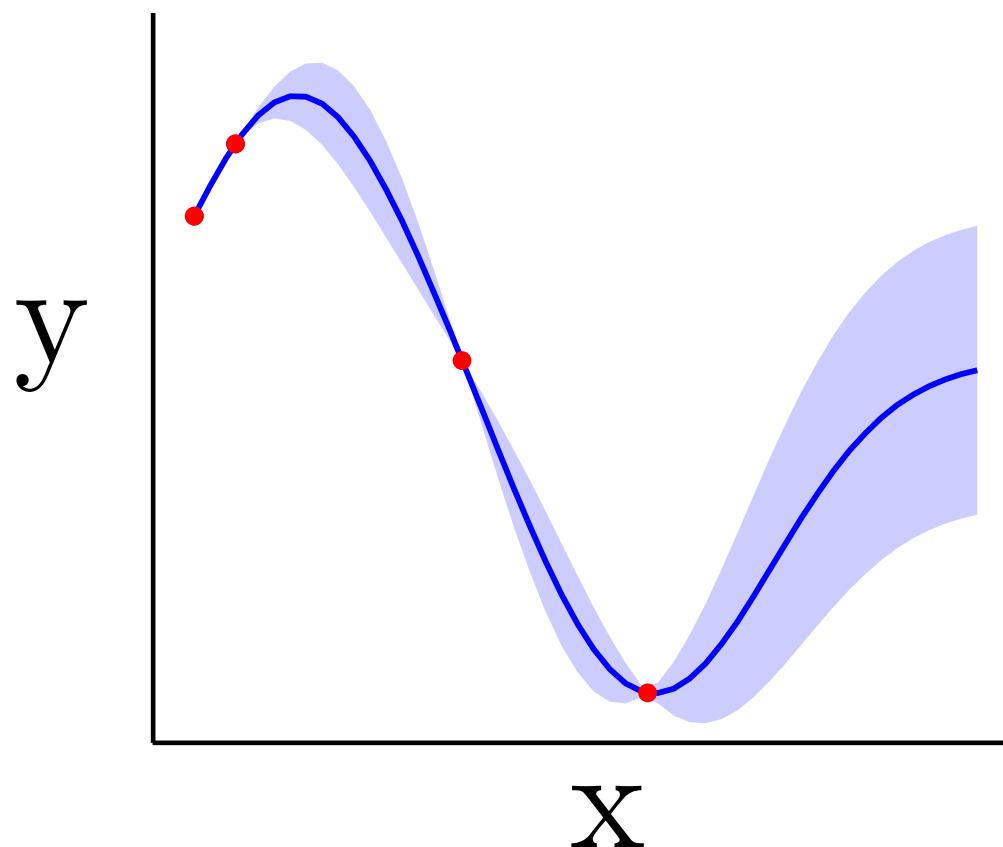
Motivation: non-linear regression



Motivation: non-linear regression

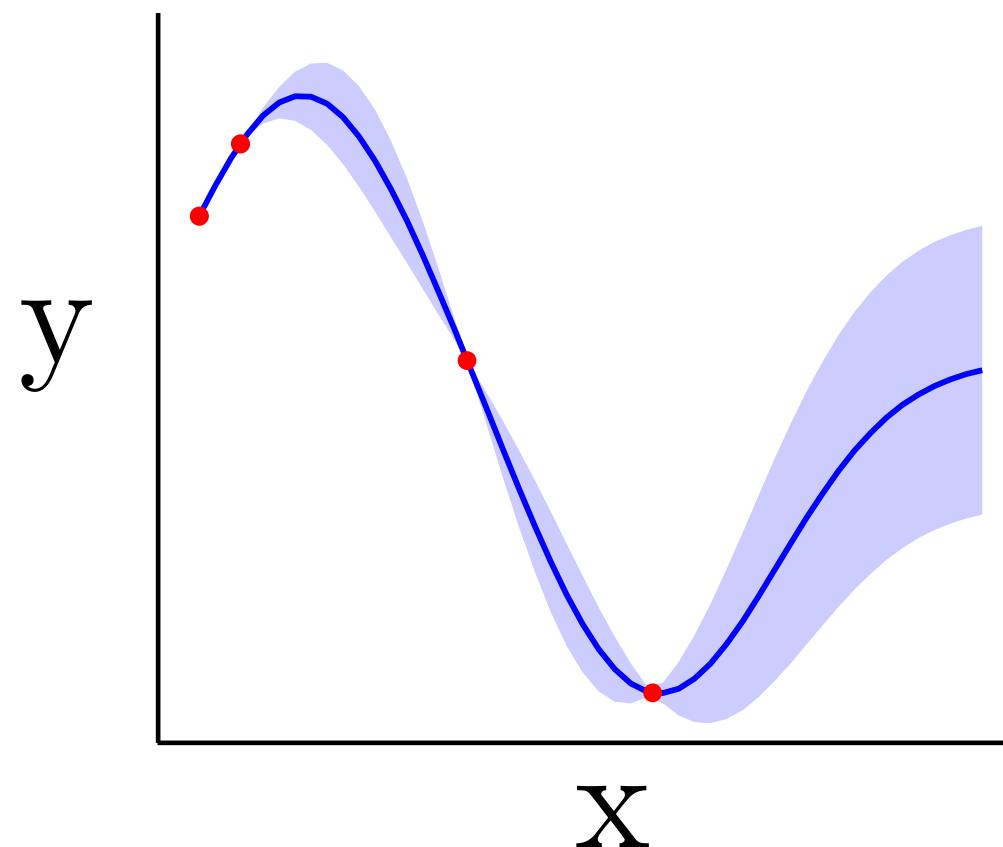


Motivation: non-linear regression



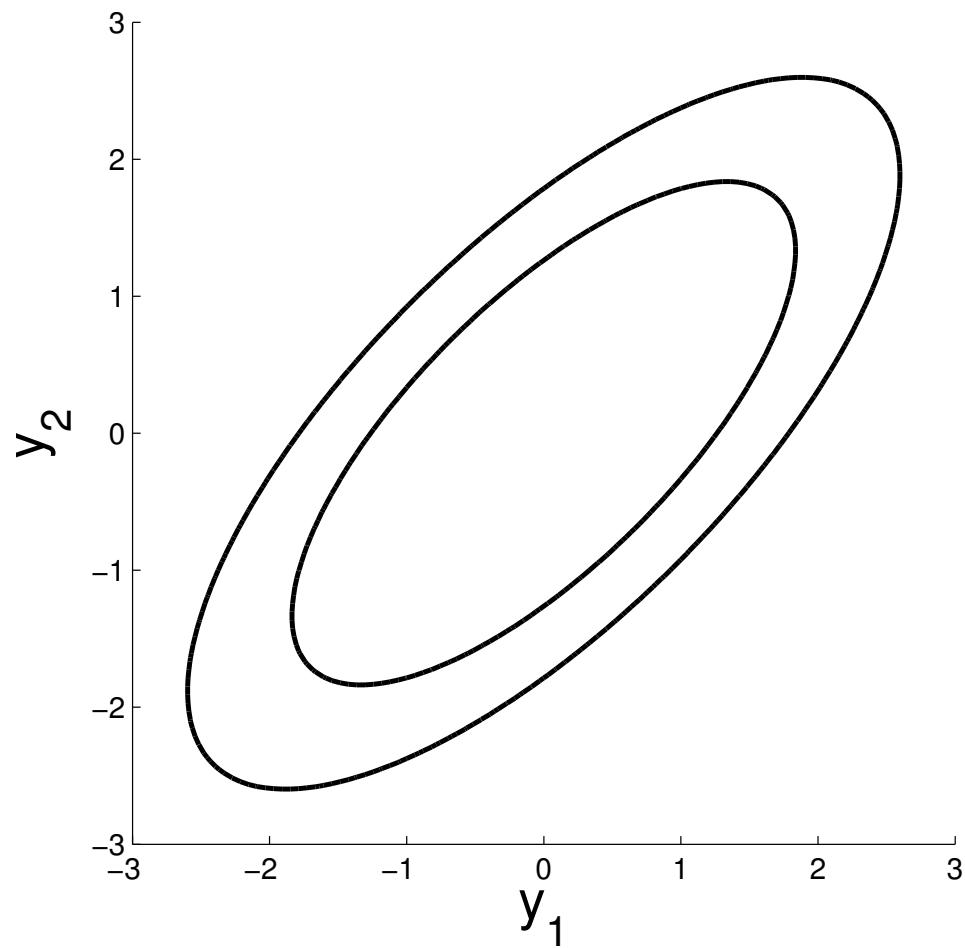
Motivation: non-linear regression

Can we do this with a plain old Gaussian?



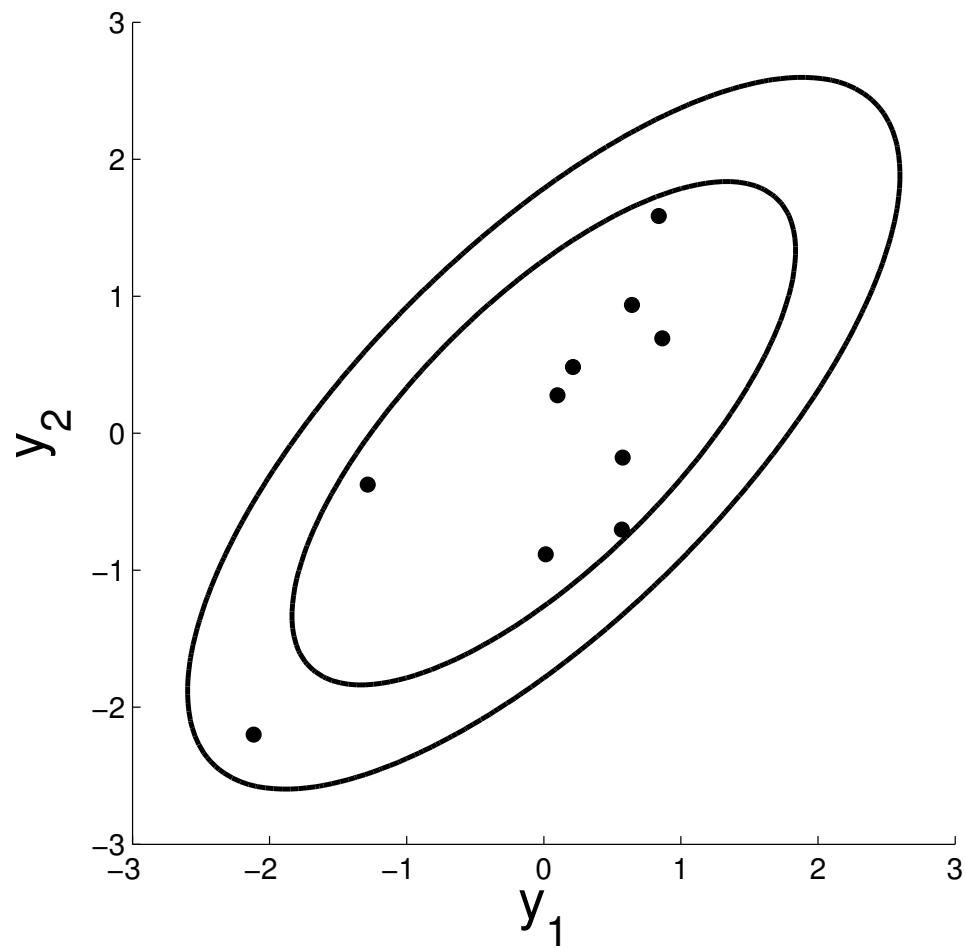
Gaussian distribution

$$p(\mathbf{y}|\Sigma) \propto \exp\left(-\frac{1}{2}\mathbf{y}^\top \Sigma^{-1} \mathbf{y}\right) \quad \Sigma = \begin{bmatrix} 1 & .7 \\ .7 & 1 \end{bmatrix}$$



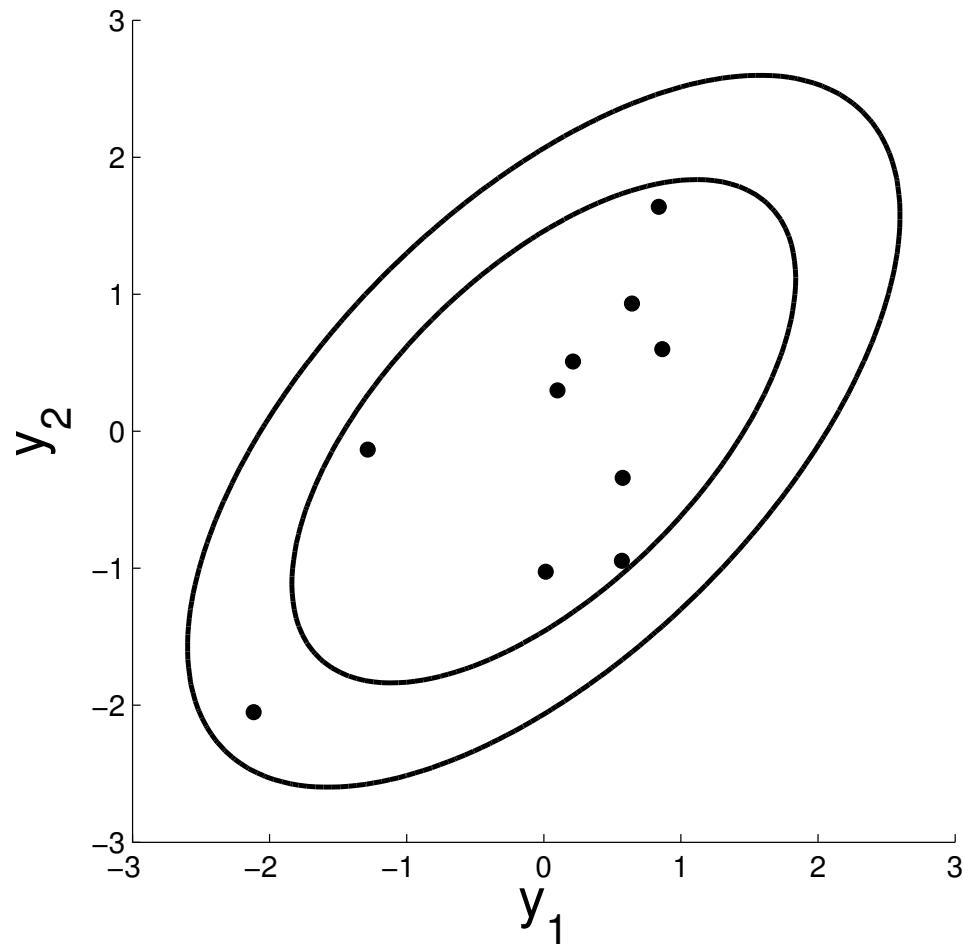
Gaussian distribution

$$p(\mathbf{y}|\Sigma) \propto \exp\left(-\frac{1}{2}\mathbf{y}^\top \Sigma^{-1} \mathbf{y}\right) \quad \Sigma = \begin{bmatrix} 1 & .7 \\ .7 & 1 \end{bmatrix}$$



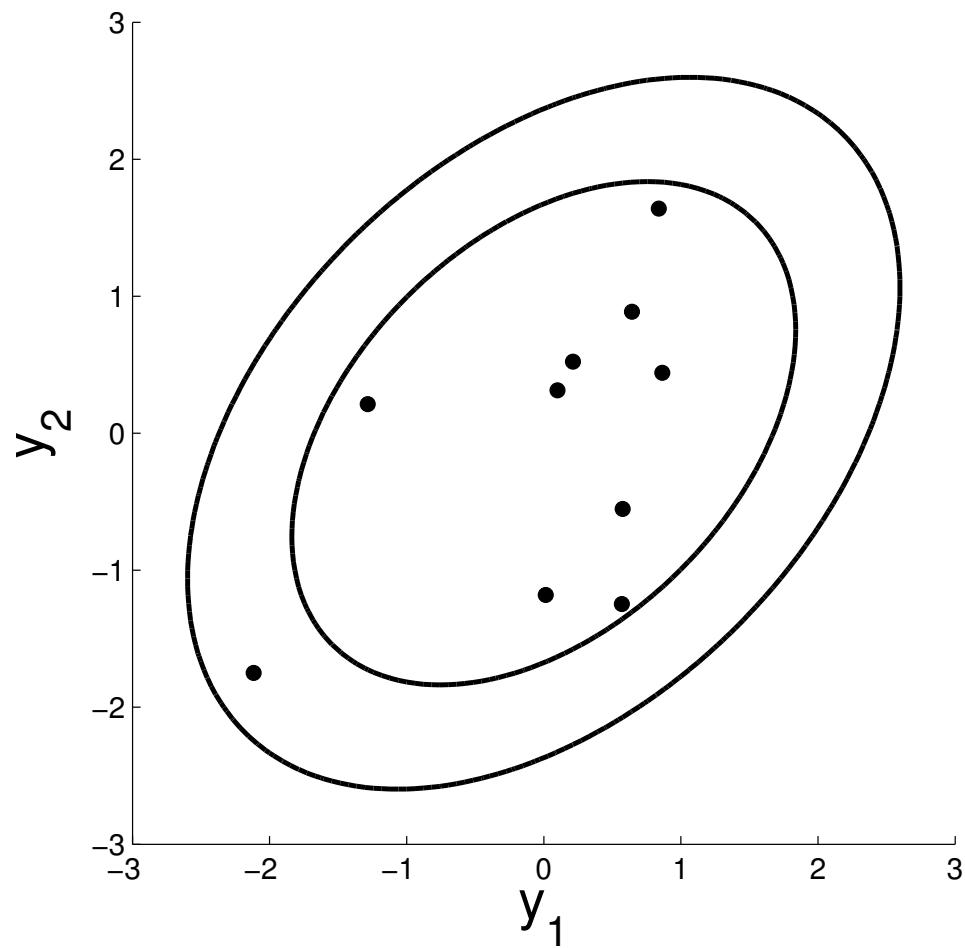
Gaussian distribution

$$p(\mathbf{y}|\Sigma) \propto \exp\left(-\frac{1}{2}\mathbf{y}^\top \Sigma^{-1} \mathbf{y}\right)$$
$$\Sigma = \begin{bmatrix} 1 & .6 \\ .6 & 1 \end{bmatrix}$$



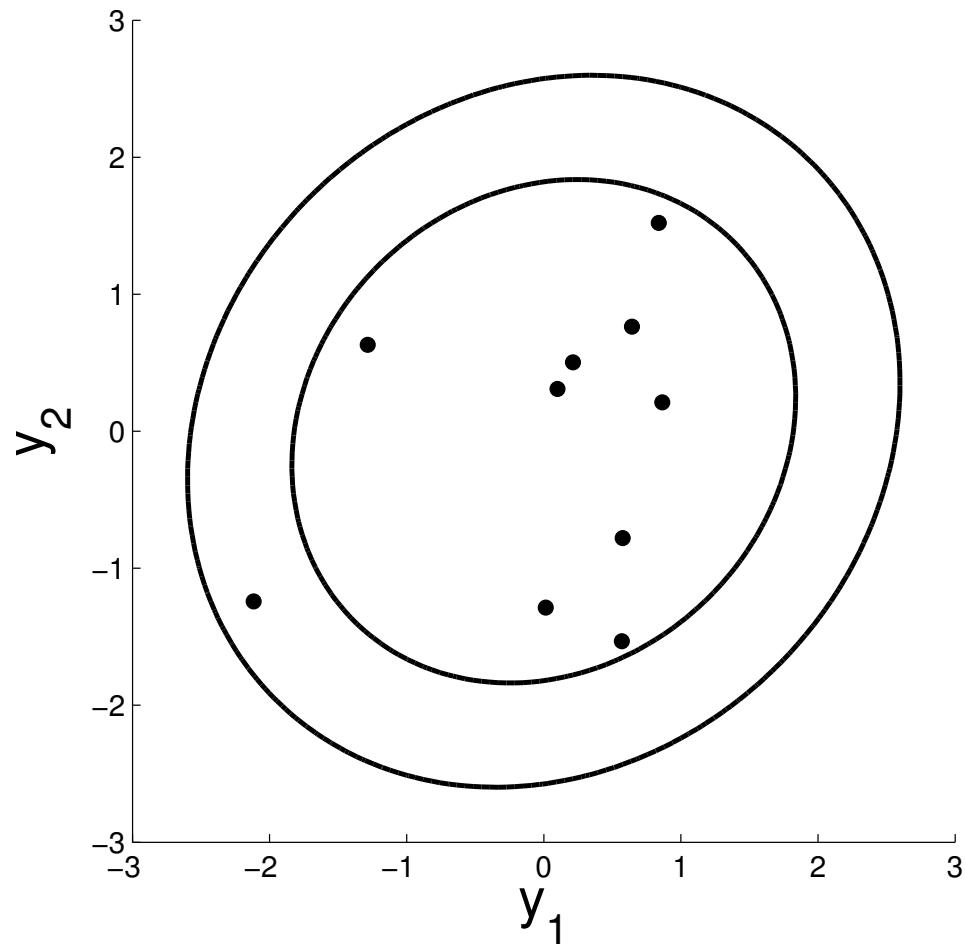
Gaussian distribution

$$p(\mathbf{y}|\Sigma) \propto \exp\left(-\frac{1}{2}\mathbf{y}^\top \Sigma^{-1} \mathbf{y}\right)$$
$$\Sigma = \begin{bmatrix} 1 & .4 \\ .4 & 1 \end{bmatrix}$$



Gaussian distribution

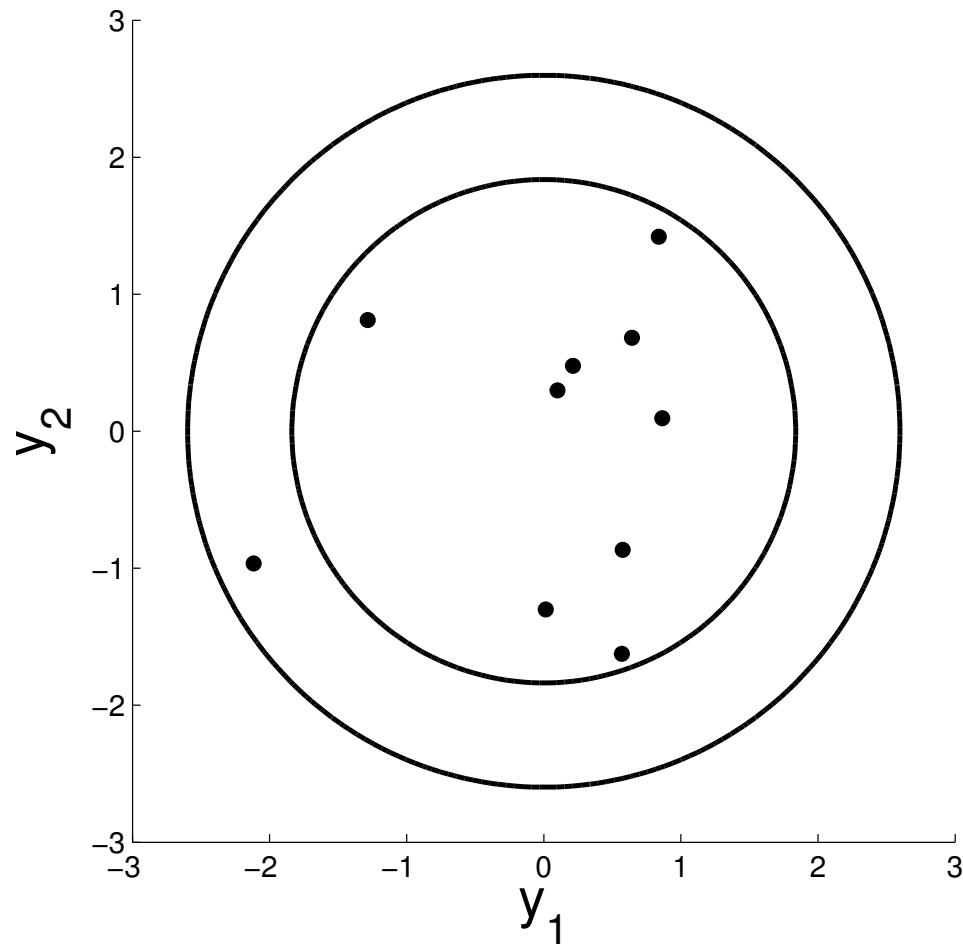
$$p(\mathbf{y}|\Sigma) \propto \exp\left(-\frac{1}{2}\mathbf{y}^\top \Sigma^{-1} \mathbf{y}\right)$$
$$\Sigma = \begin{bmatrix} 1 & .1 \\ .1 & 1 \end{bmatrix}$$



Gaussian distribution

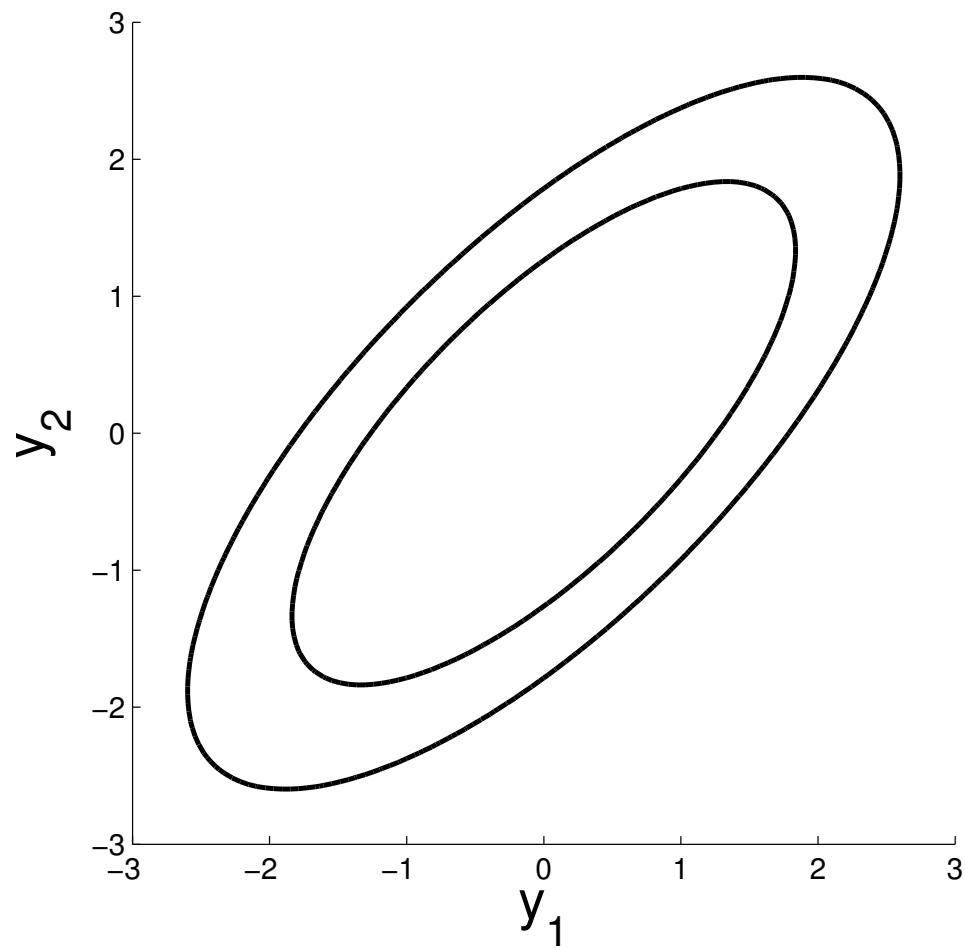
$$p(\mathbf{y}|\Sigma) \propto \exp\left(-\frac{1}{2}\mathbf{y}^\top \Sigma^{-1} \mathbf{y}\right)$$

$$\Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$



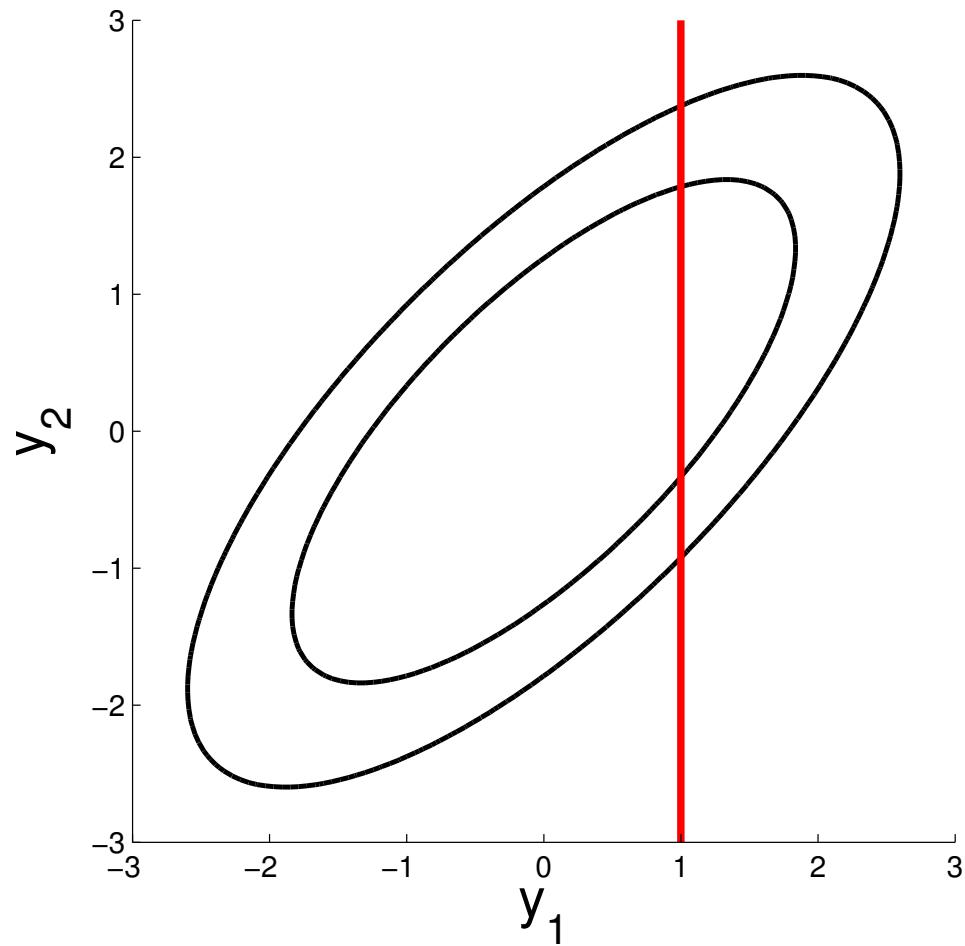
Gaussian distribution

$$p(\mathbf{y}|\Sigma) \propto \exp\left(-\frac{1}{2}\mathbf{y}^\top \Sigma^{-1} \mathbf{y}\right) \quad \Sigma = \begin{bmatrix} 1 & .7 \\ .7 & 1 \end{bmatrix}$$



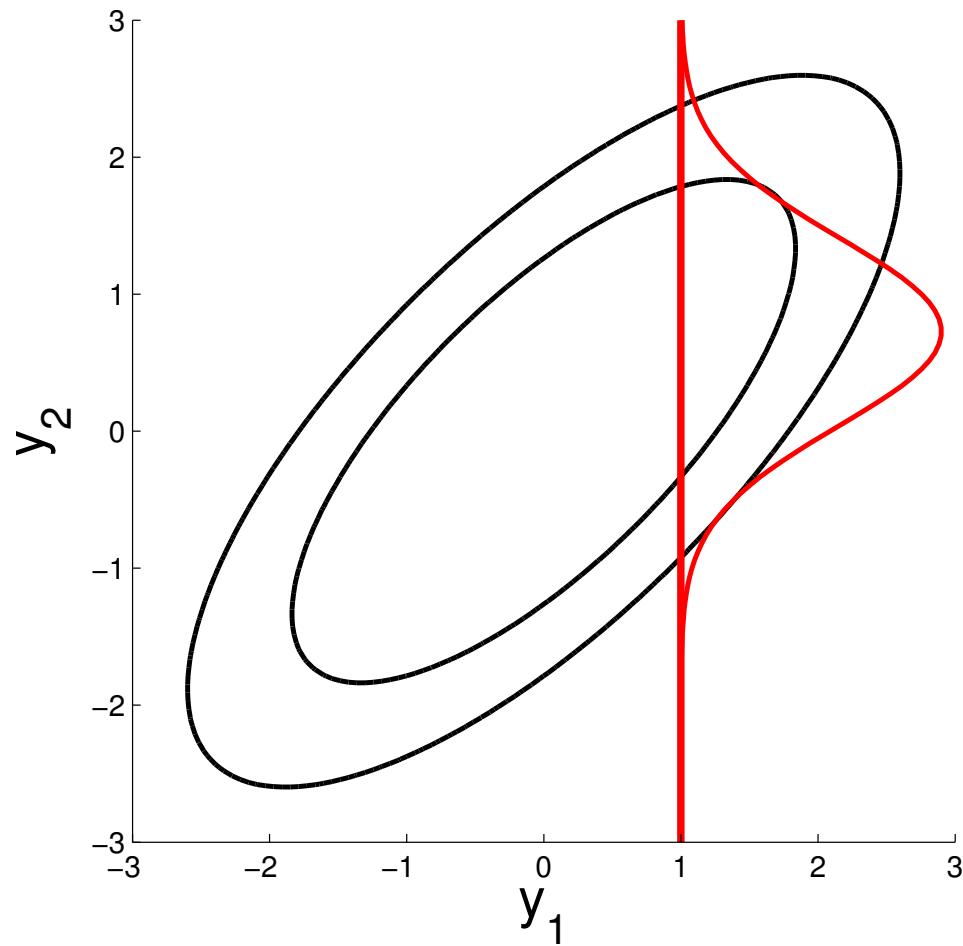
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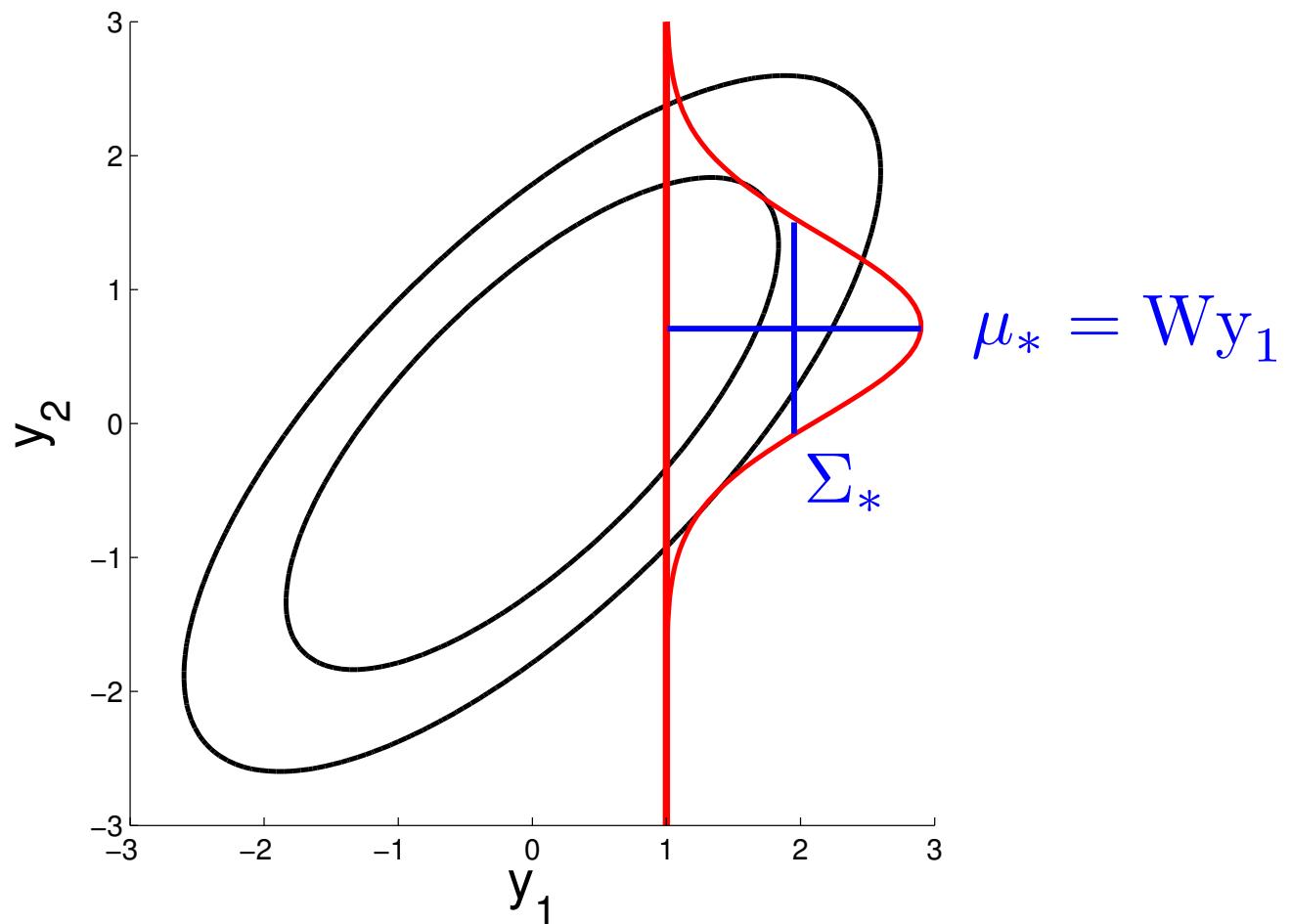
Gaussian distribution

$$p(\mathbf{y}_2|\mathbf{y}_1, \Sigma) \propto \exp\left(-\frac{1}{2}(\mathbf{y}_2 - \boldsymbol{\mu}_*) \boldsymbol{\Sigma}_*^{-1} (\mathbf{y}_2 - \boldsymbol{\mu}_*)\right)$$



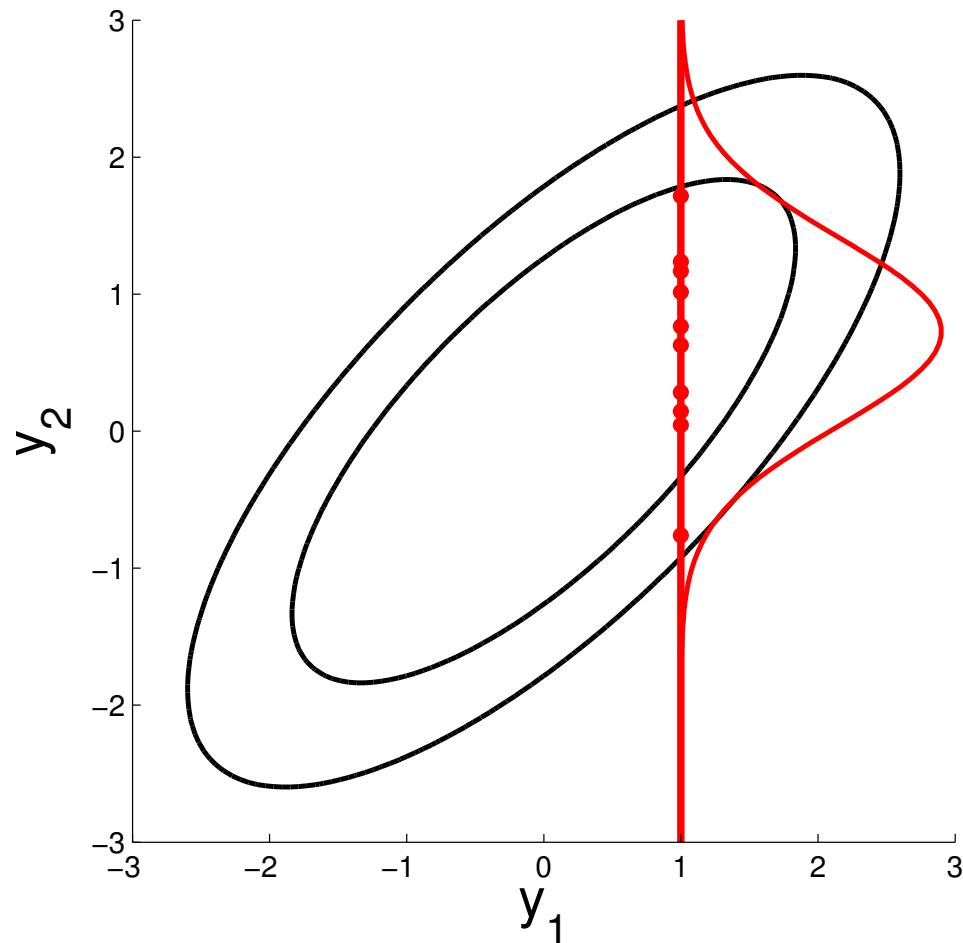
Gaussian distribution

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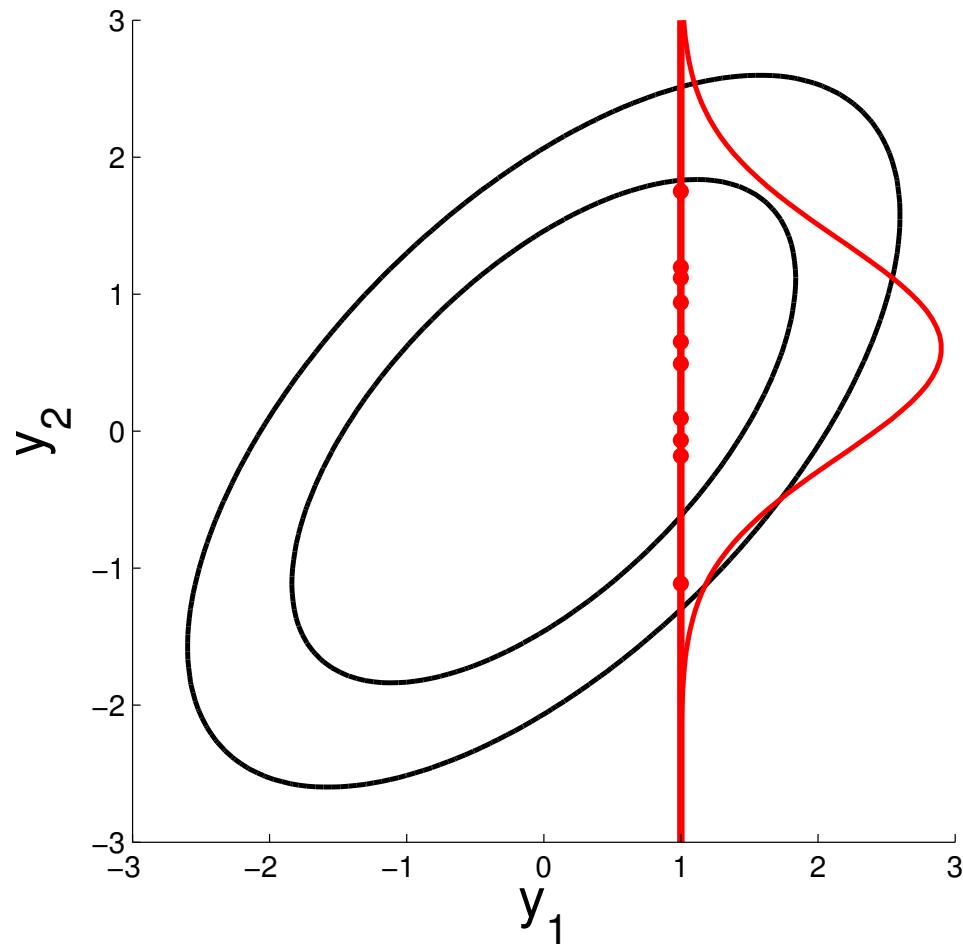
Gaussian distribution

$$p(\mathbf{y}_2|\mathbf{y}_1, \Sigma) \propto \exp\left(-\frac{1}{2}(\mathbf{y}_2 - \boldsymbol{\mu}_*)\boldsymbol{\Sigma}_*^{-1}(\mathbf{y}_2 - \boldsymbol{\mu}_*)\right)$$



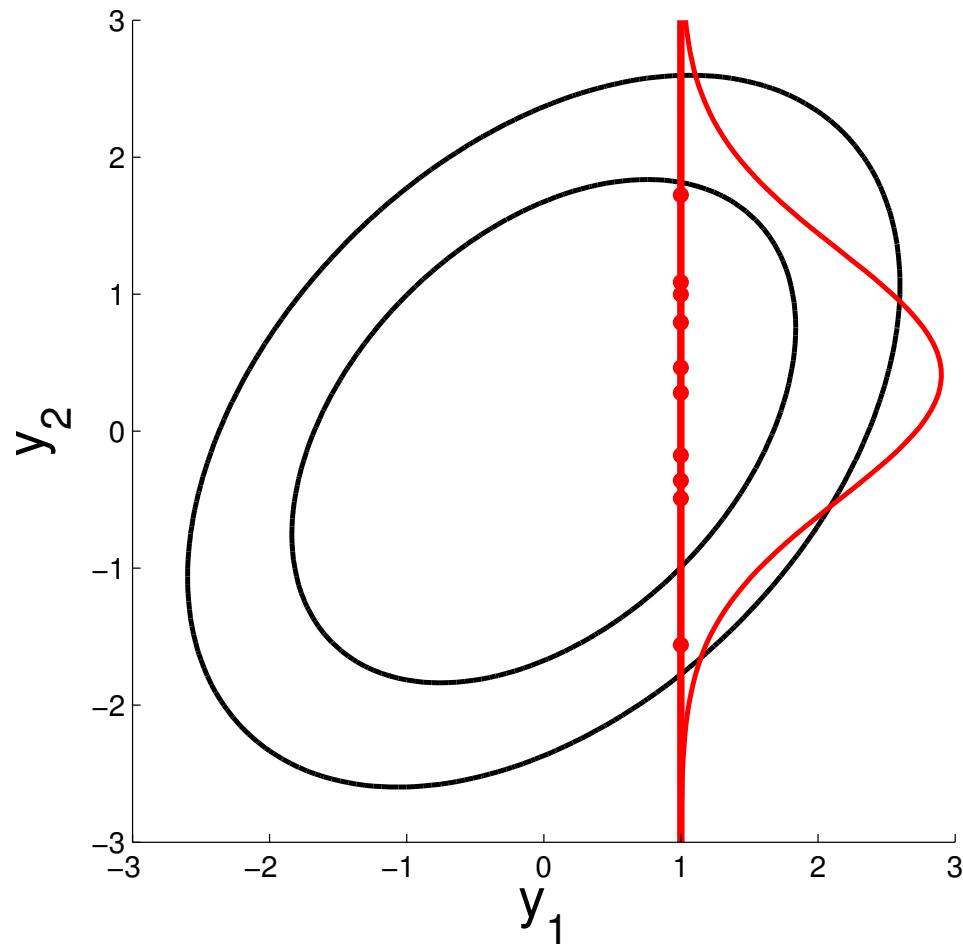
Gaussian distribution

$$p(\mathbf{y}_2|\mathbf{y}_1, \Sigma) \propto \exp\left(-\frac{1}{2}(\mathbf{y}_2 - \boldsymbol{\mu}_*) \boldsymbol{\Sigma}_*^{-1} (\mathbf{y}_2 - \boldsymbol{\mu}_*)\right)$$



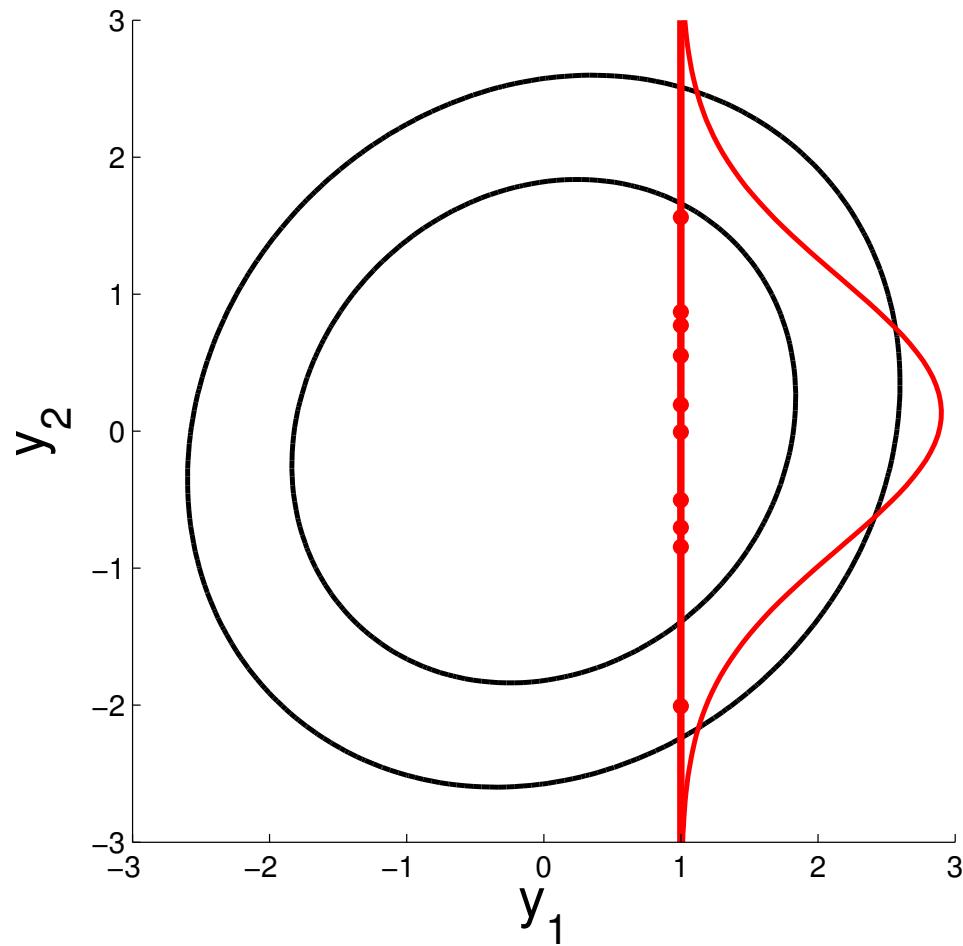
Gaussian distribution

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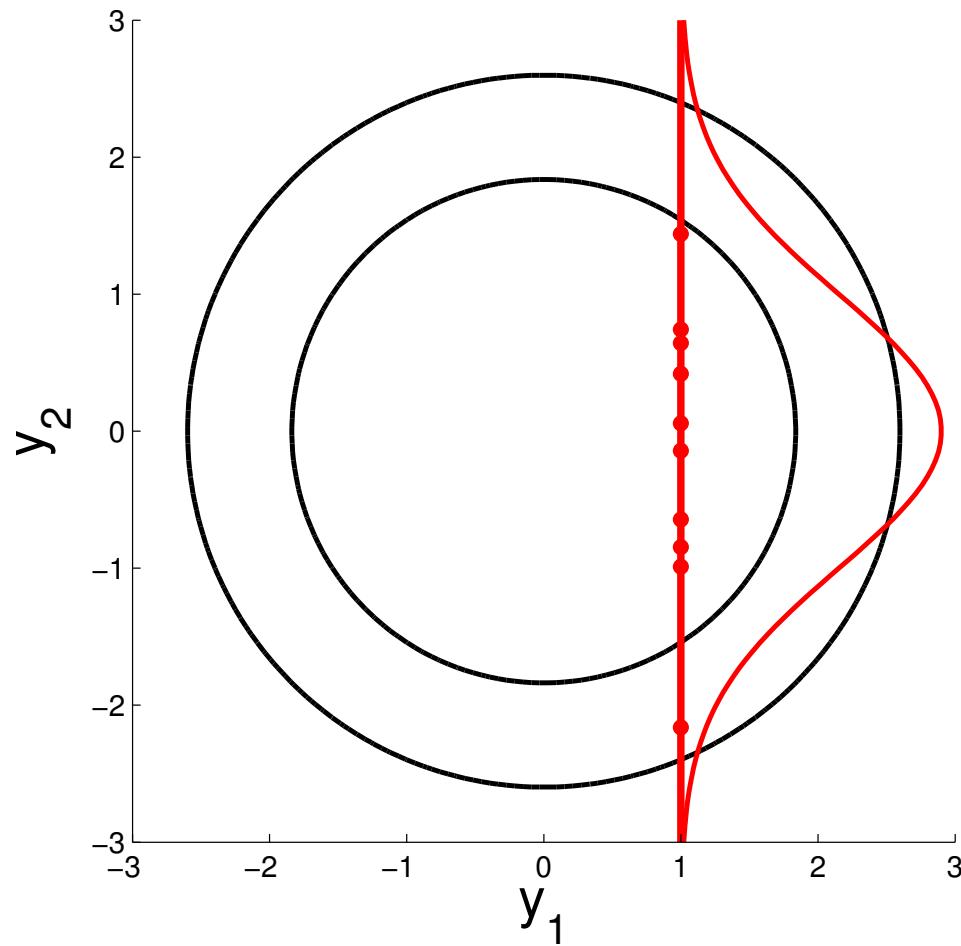
Gaussian distribution

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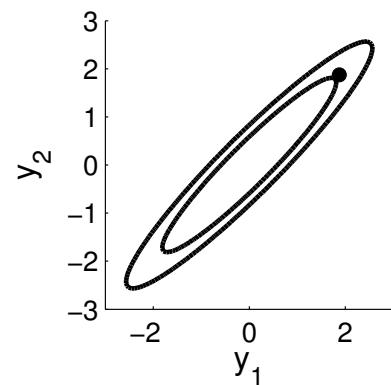


Gaussian distribution

$$p(\mathbf{y}_2|\mathbf{y}_1, \Sigma) \propto \exp\left(-\frac{1}{2}(\mathbf{y}_2 - \boldsymbol{\mu}_*)\boldsymbol{\Sigma}_*^{-1}(\mathbf{y}_2 - \boldsymbol{\mu}_*)\right)$$

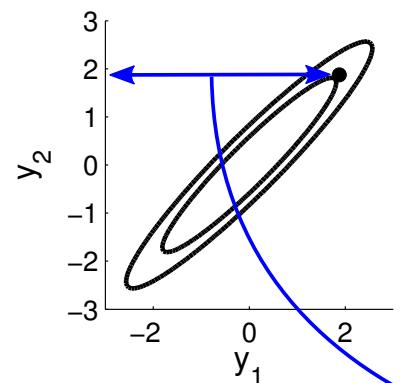


New visualisation

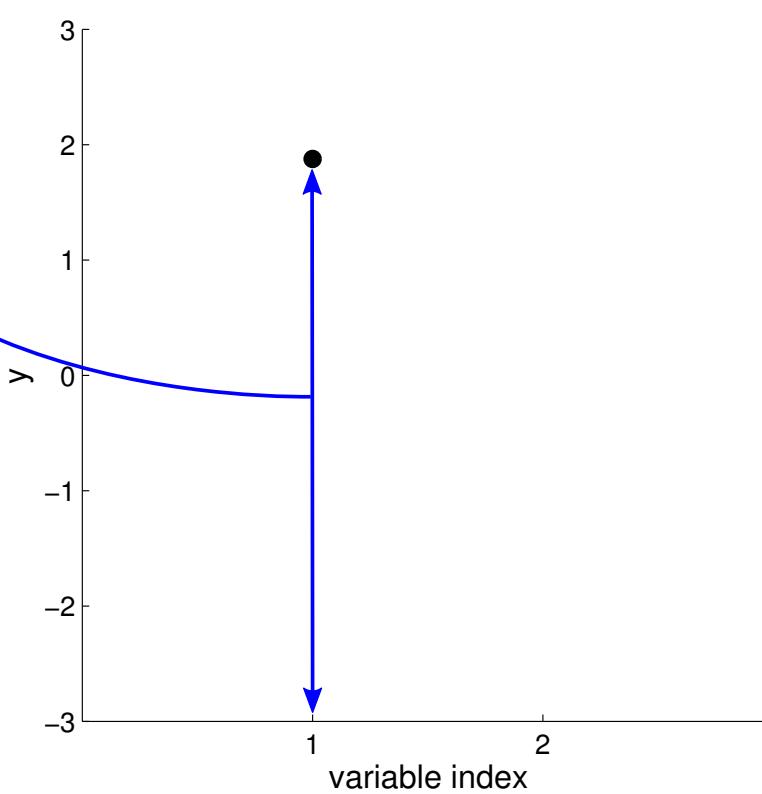


$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$

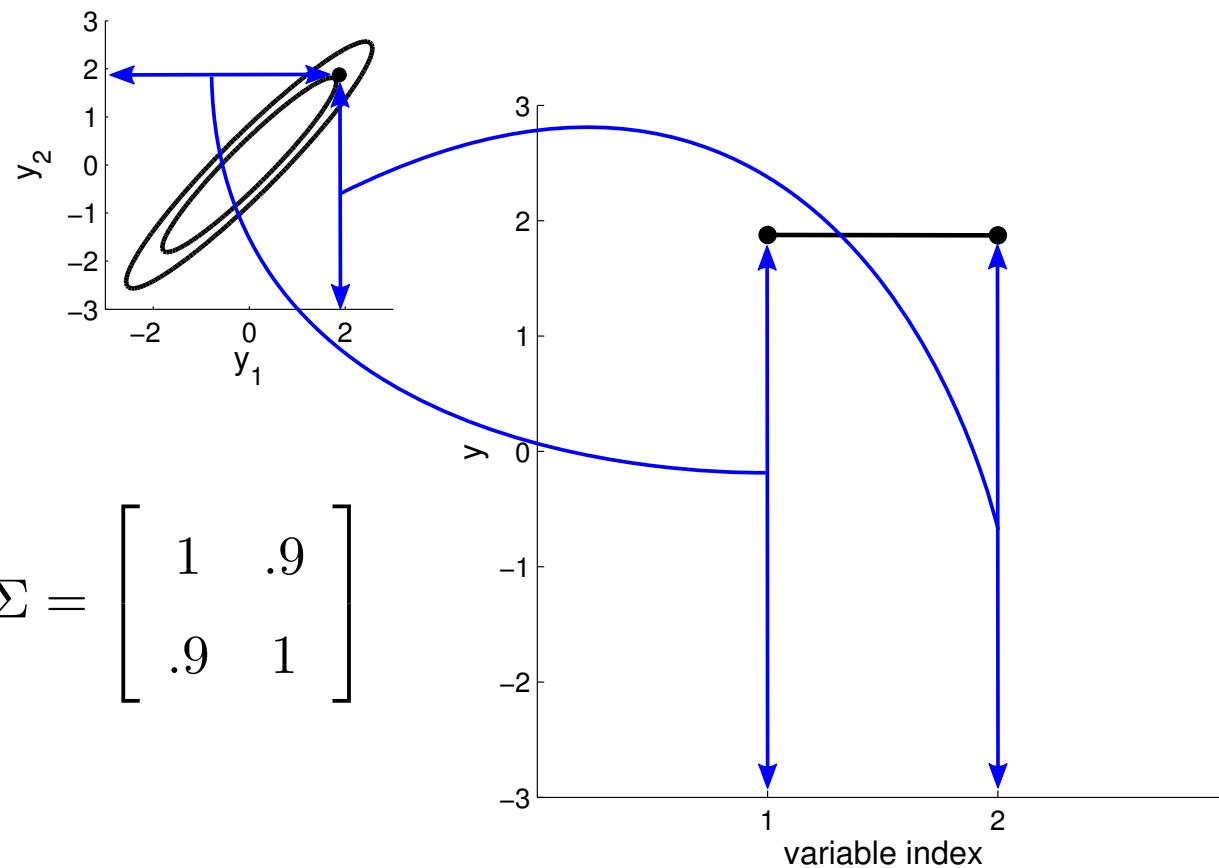
New visualisation



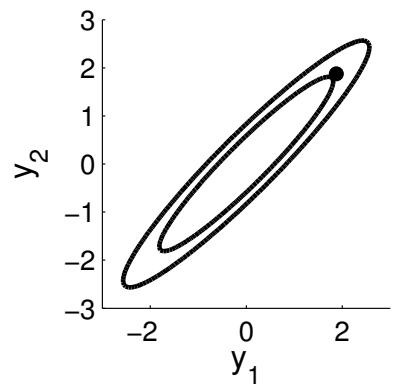
$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$



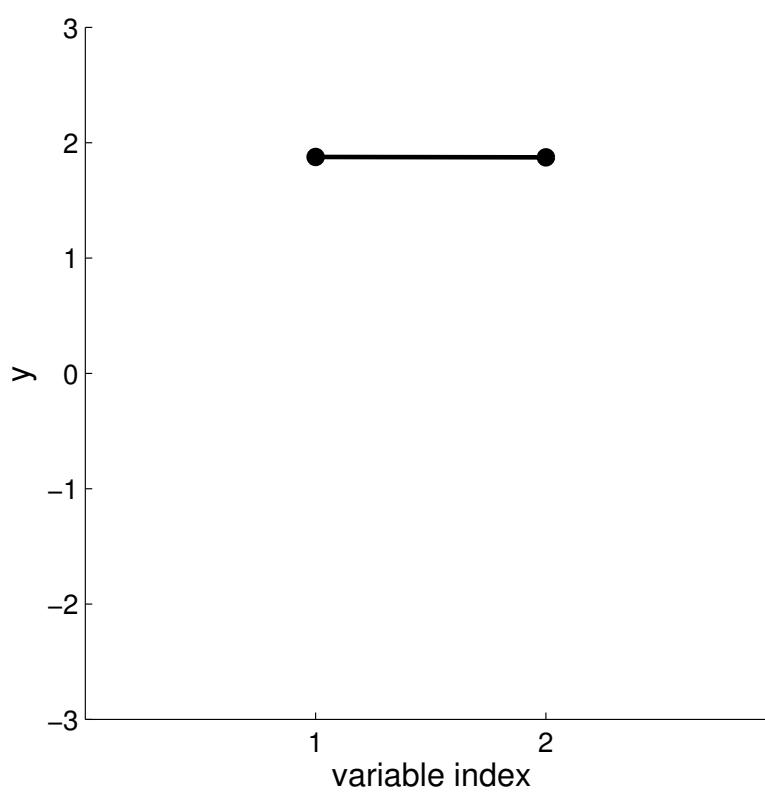
New visualisation



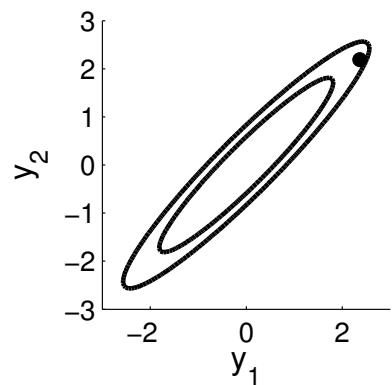
New visualisation



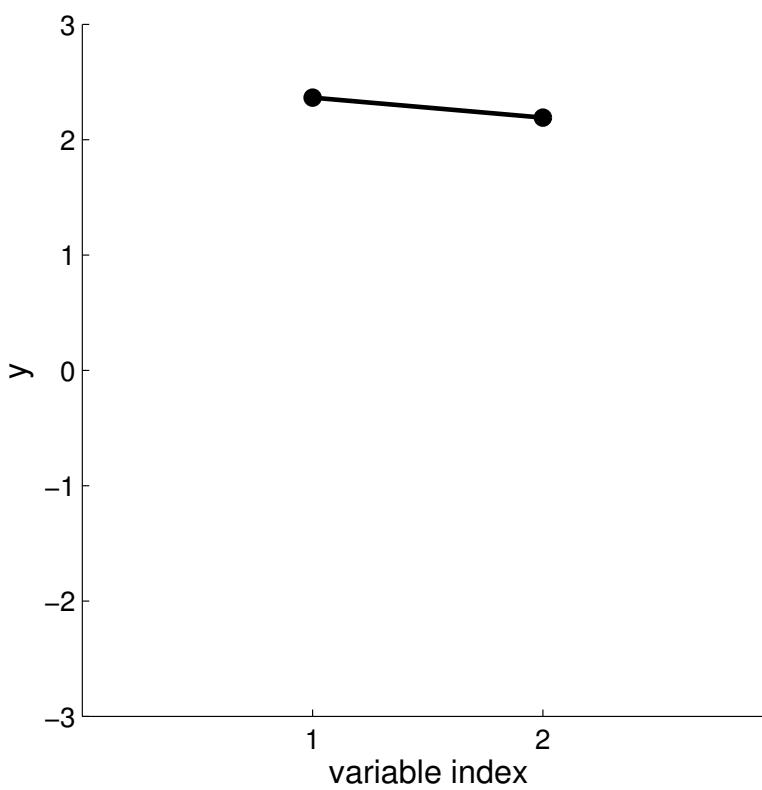
$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$



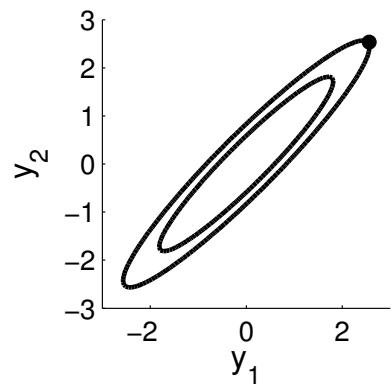
New visualisation



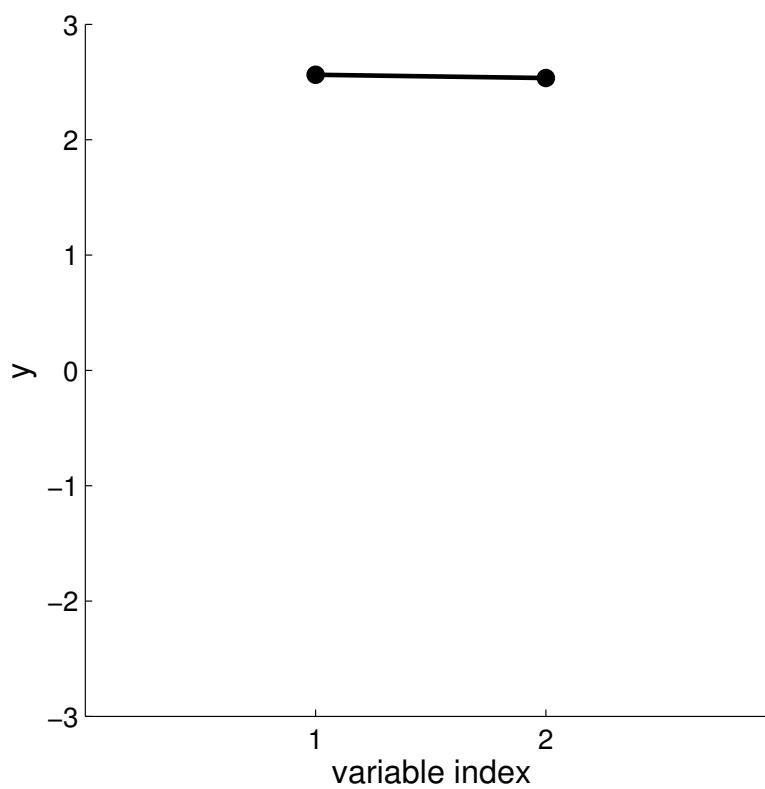
$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$



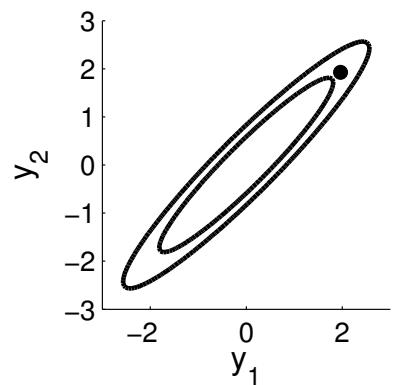
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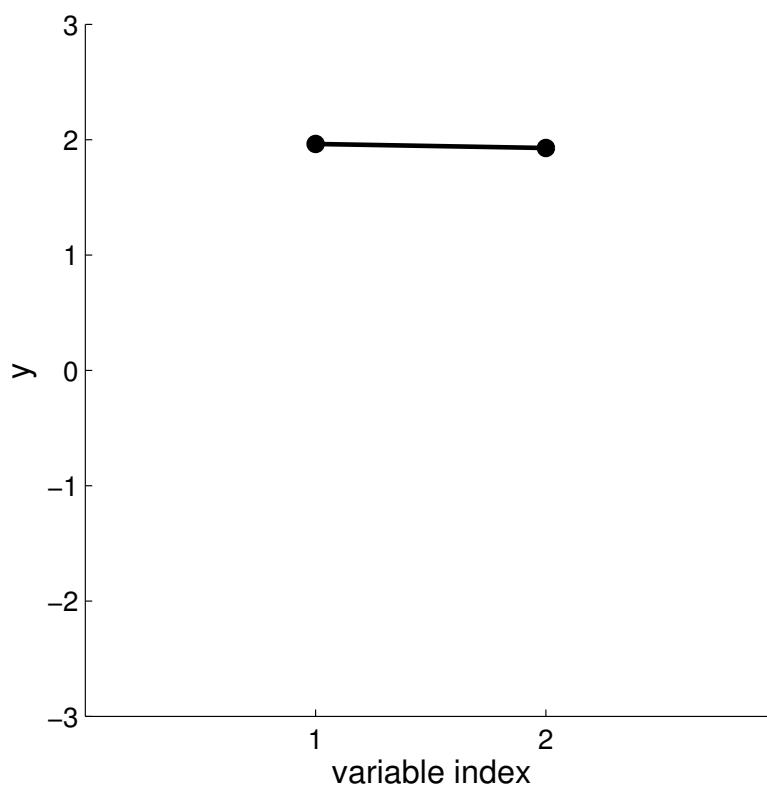
$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$



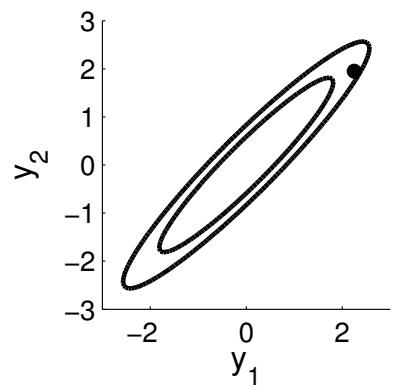
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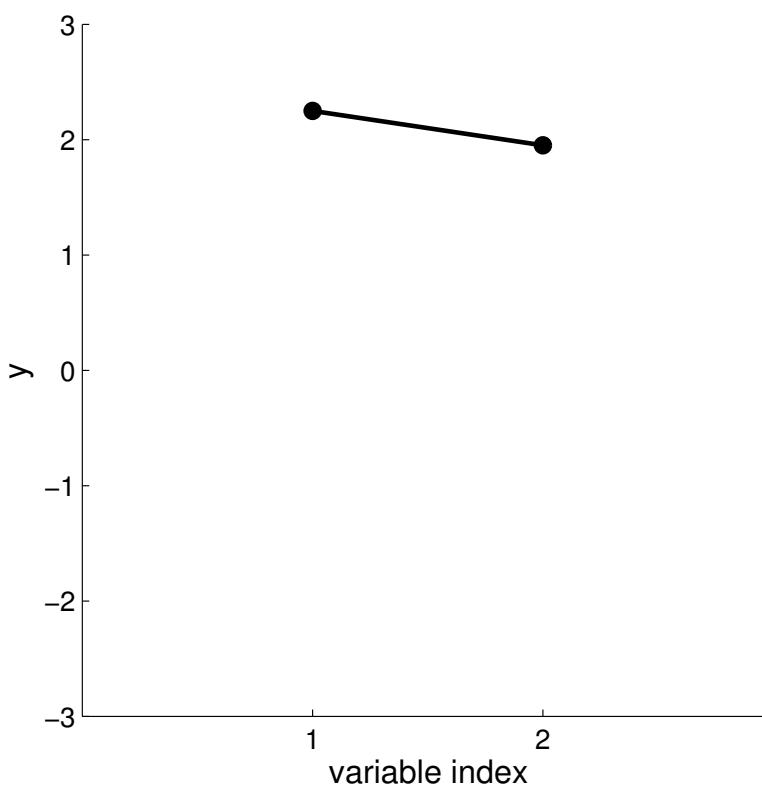
$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$



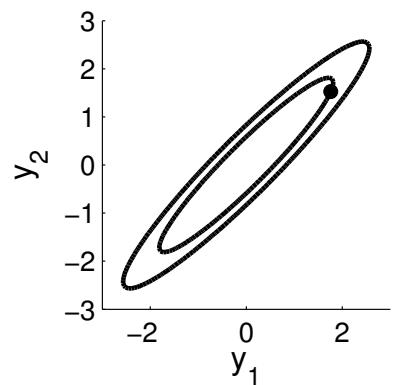
New visualisation



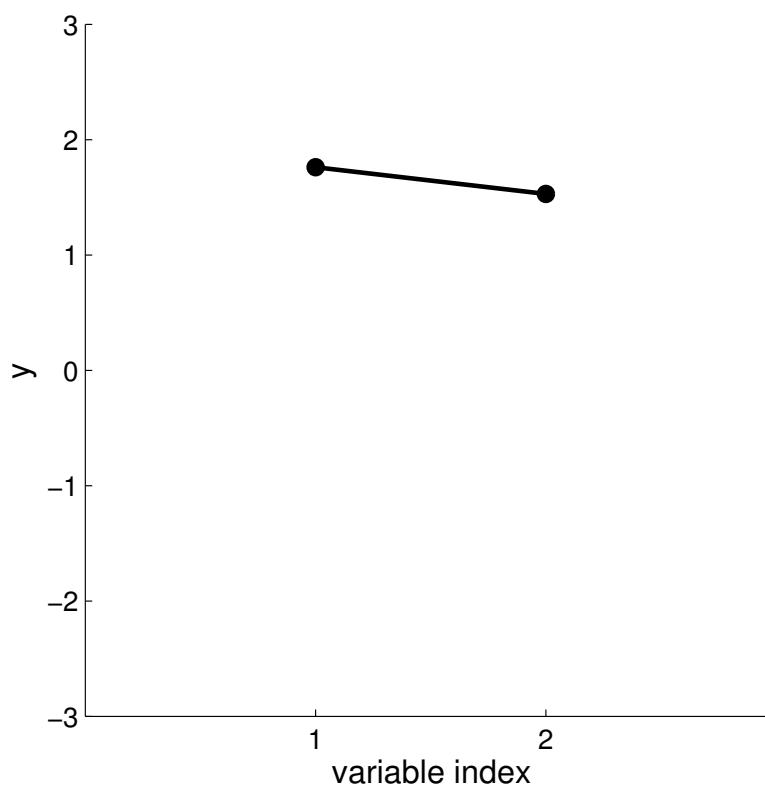
$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$



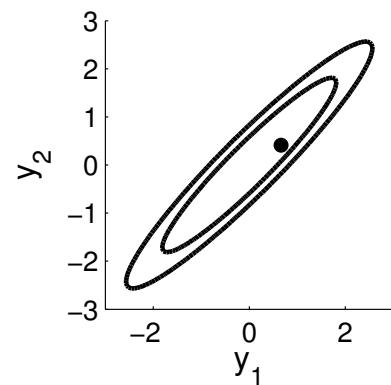
New visualisation



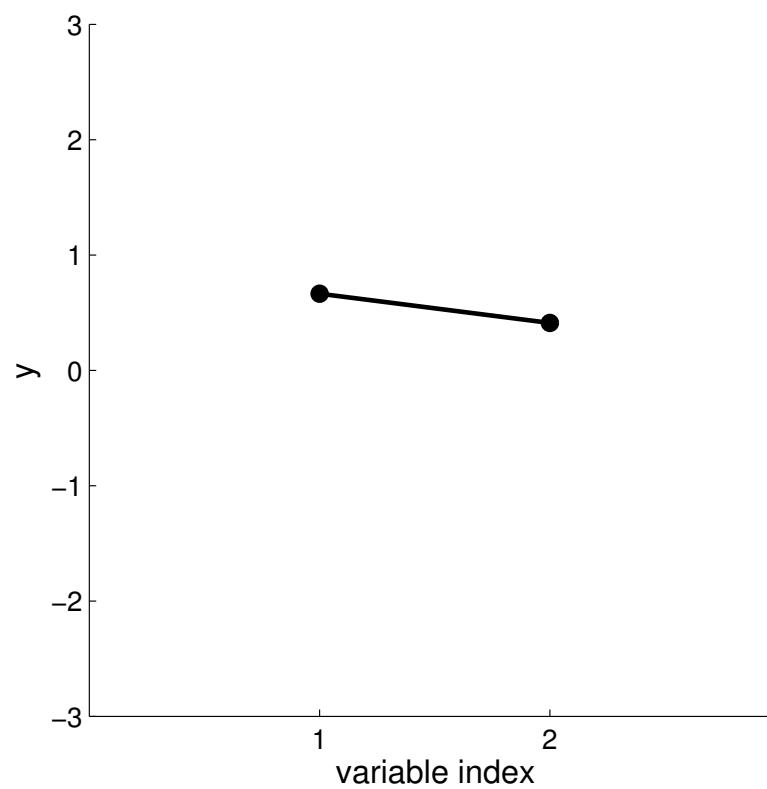
$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$



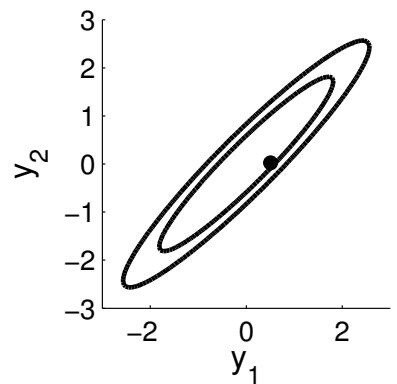
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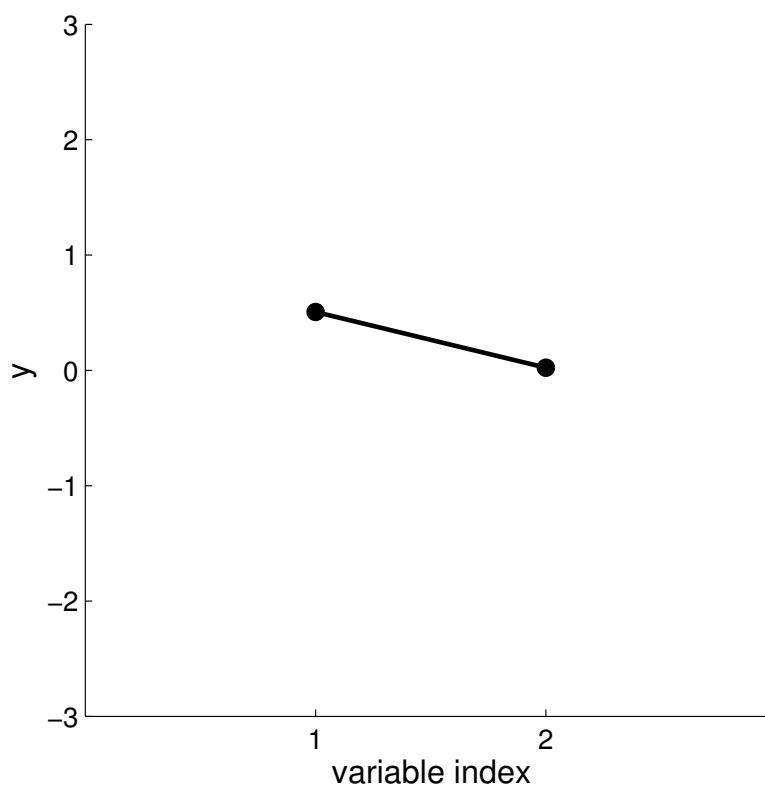
$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$



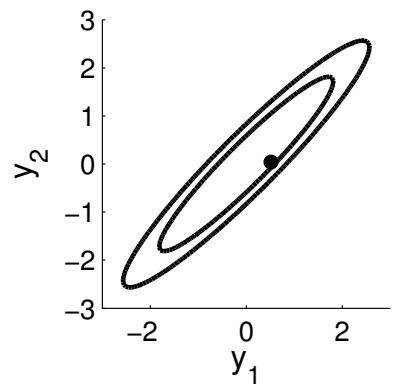
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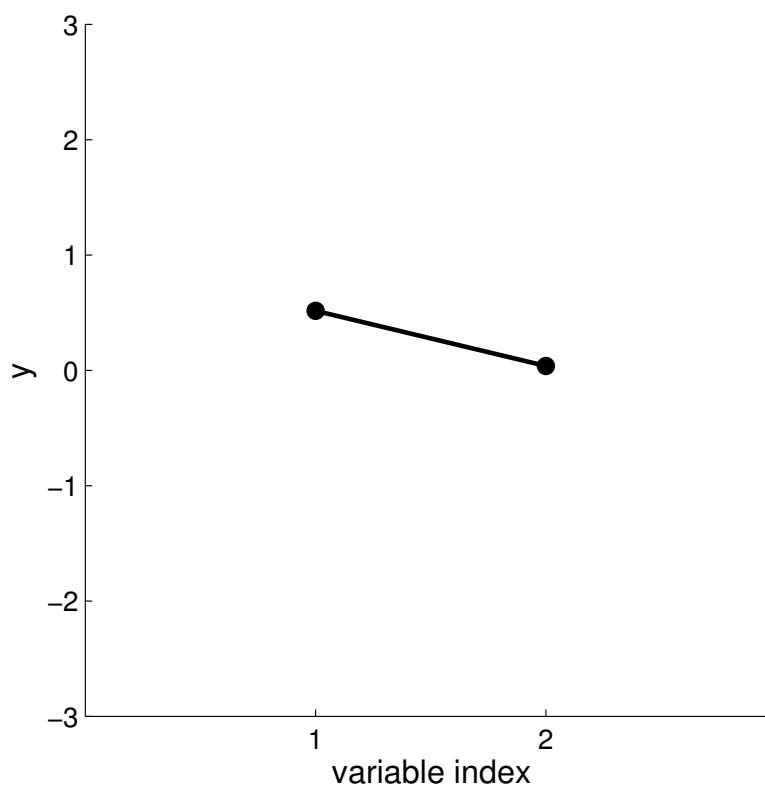
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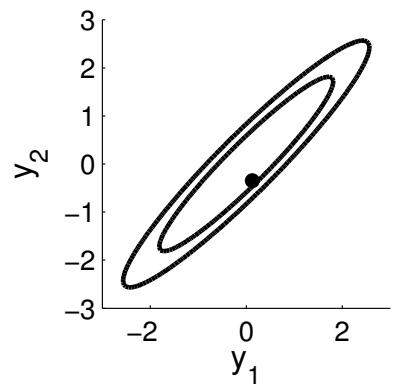
New visualisation



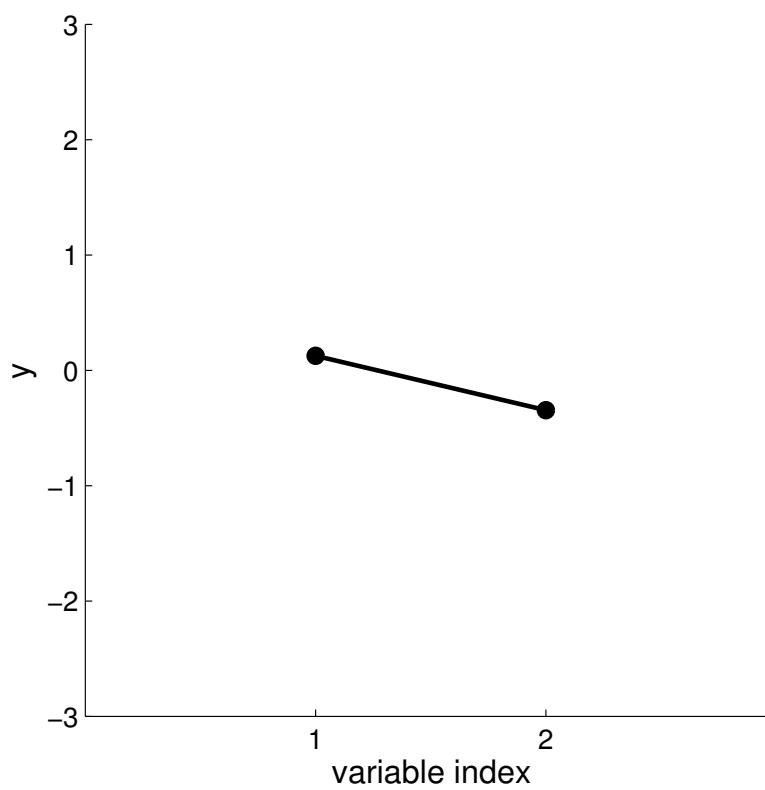
$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$



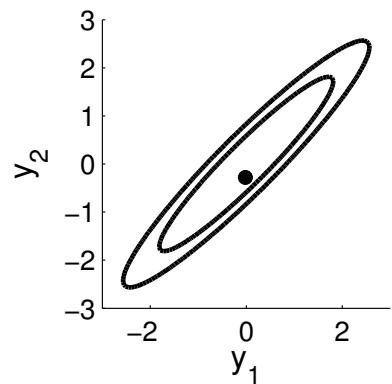
New visualisation



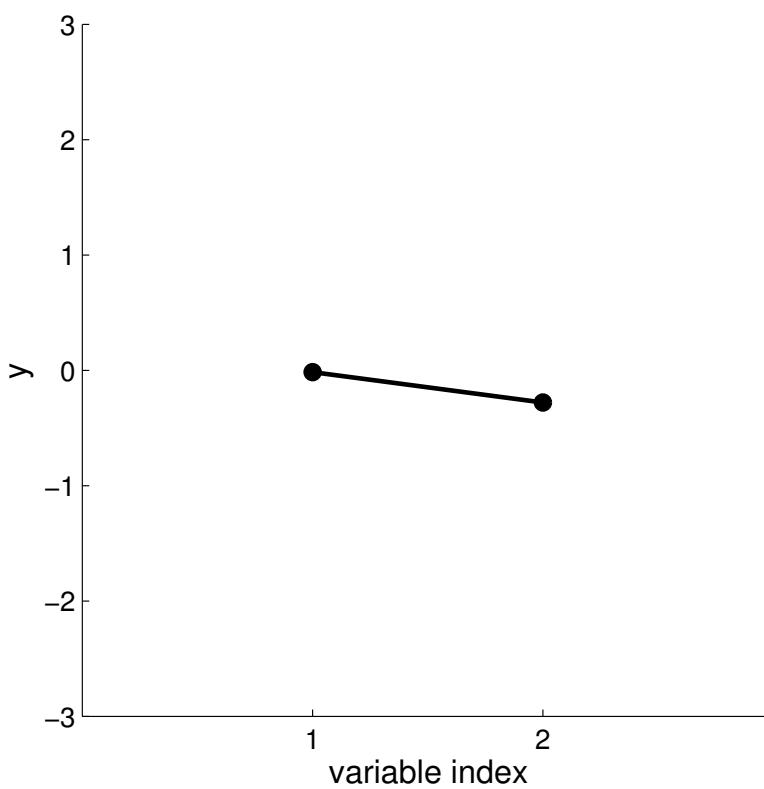
$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$



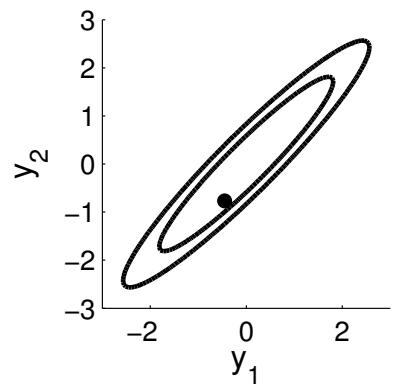
New visualisation



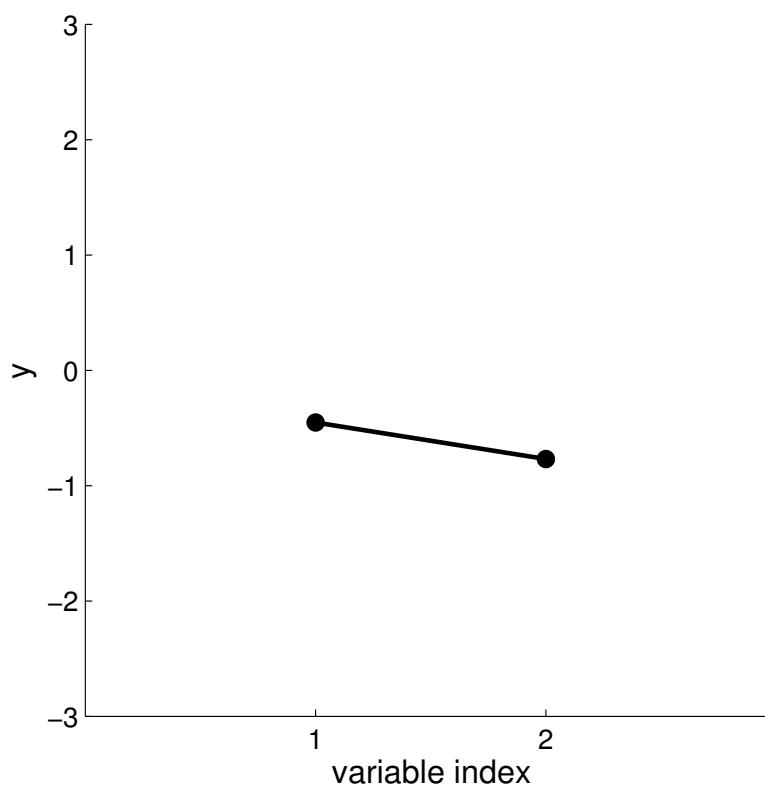
$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$



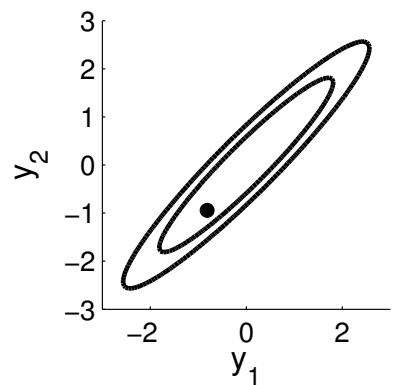
New visualisation



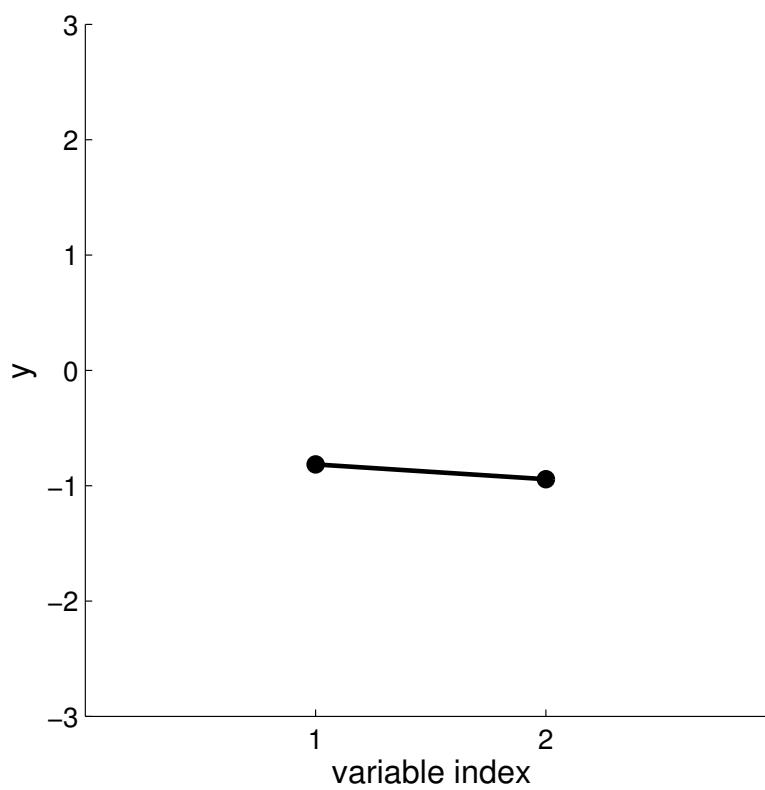
$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$



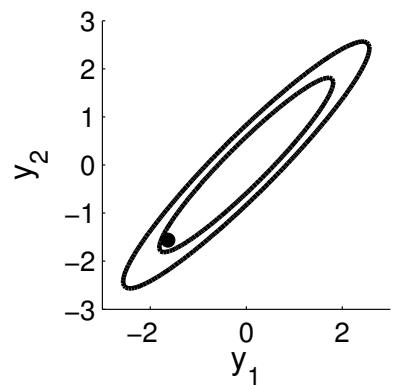
New visualisation



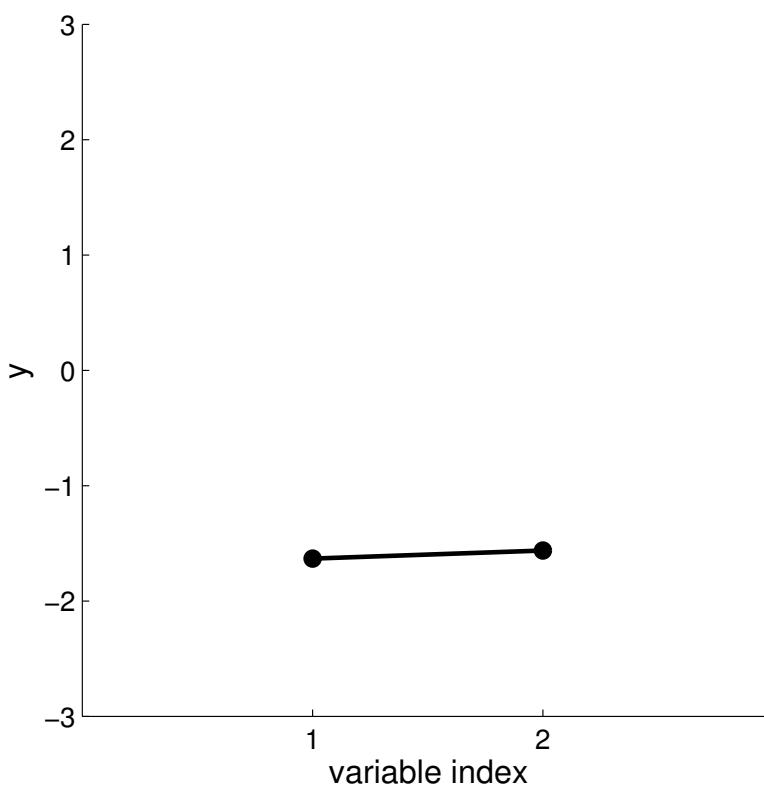
$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$



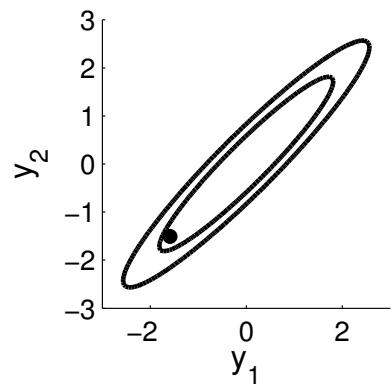
New visualisation



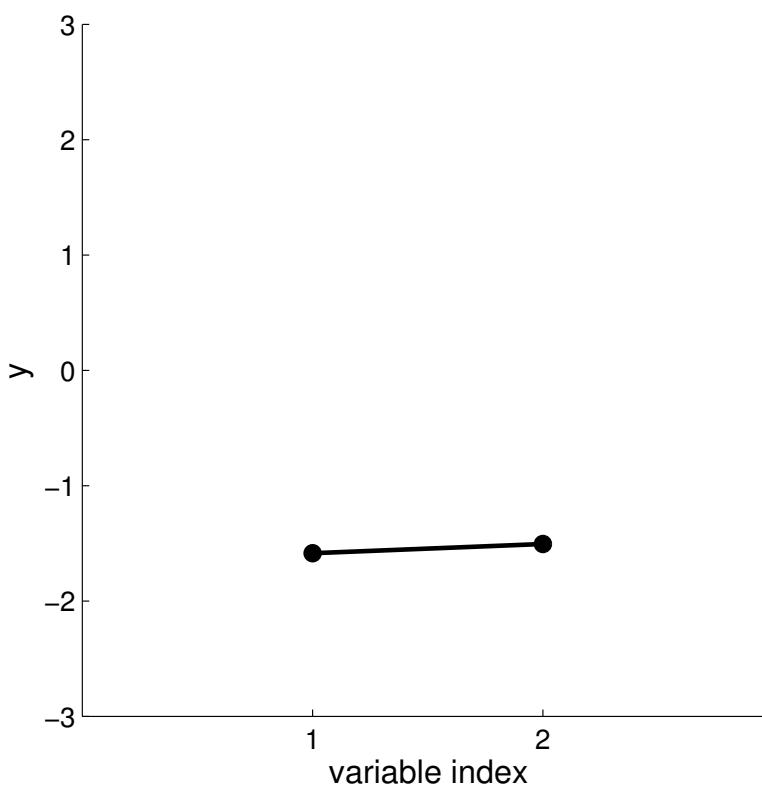
$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$



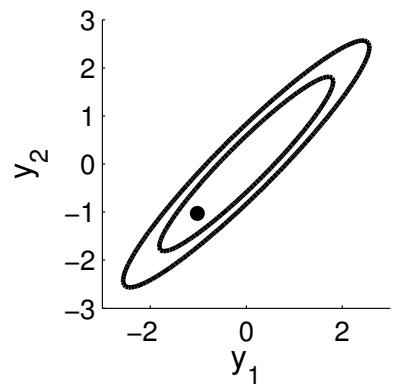
New visualisation



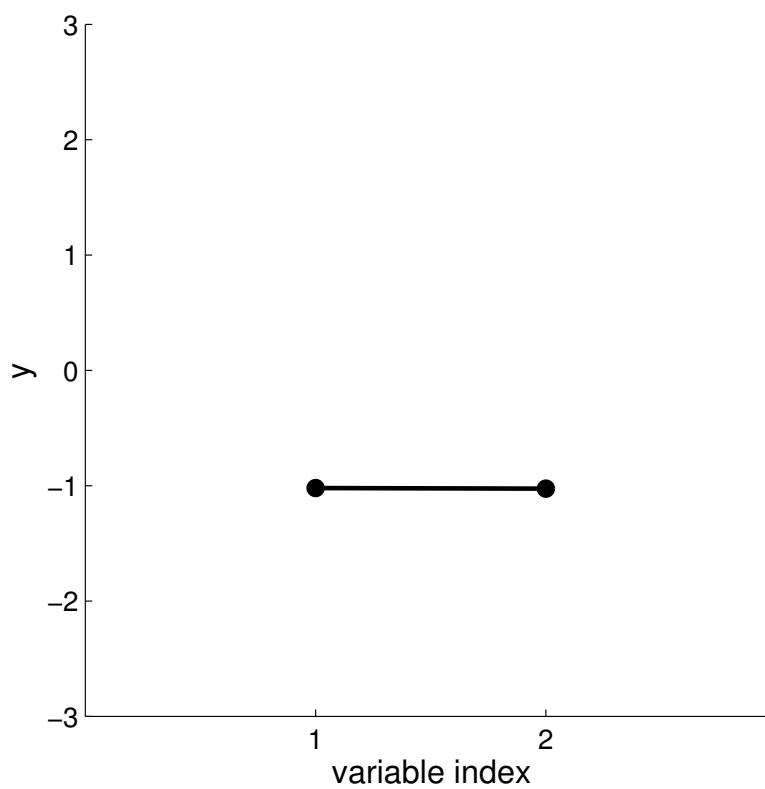
$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$



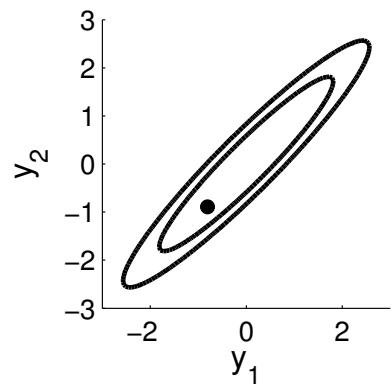
New visualisation



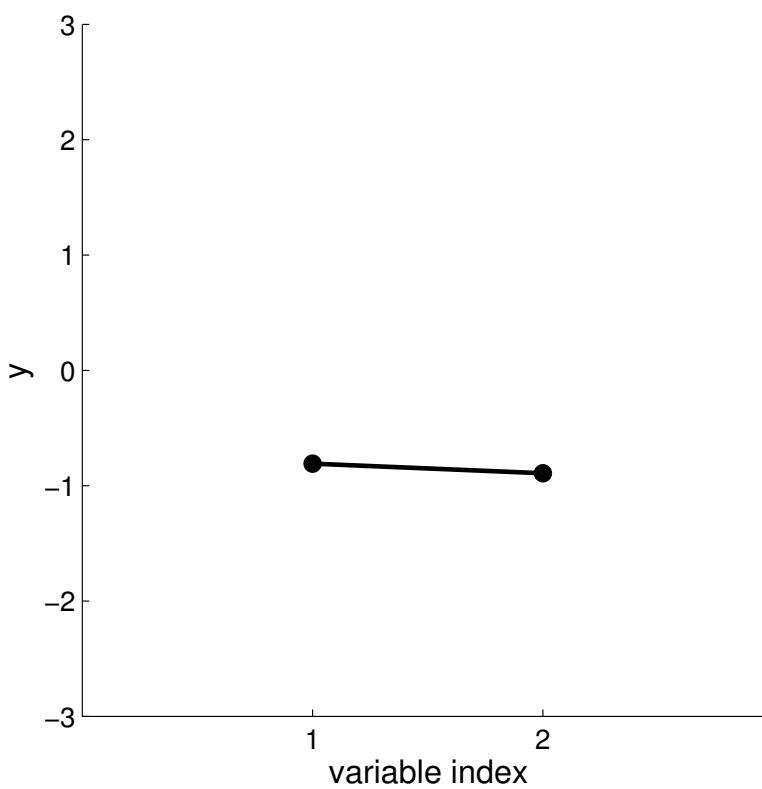
$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$



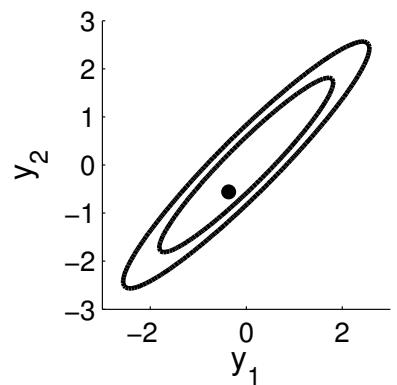
New visualisation



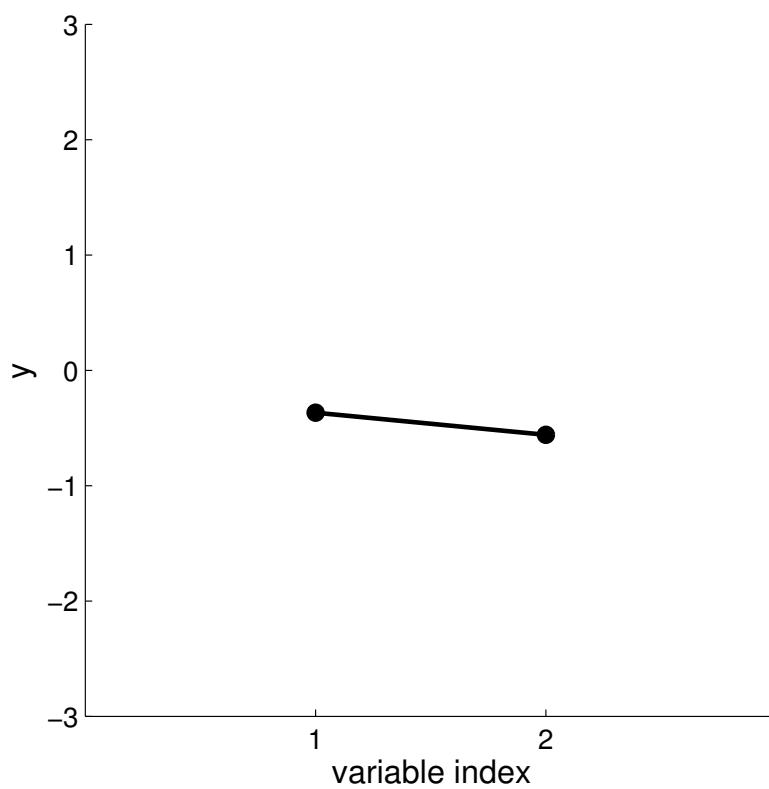
$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$



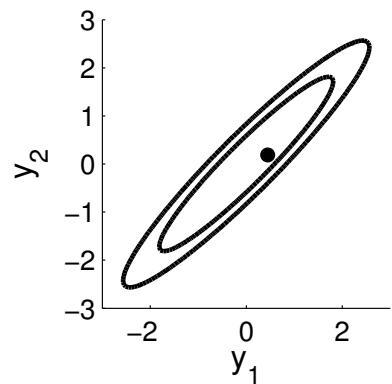
New visualisation



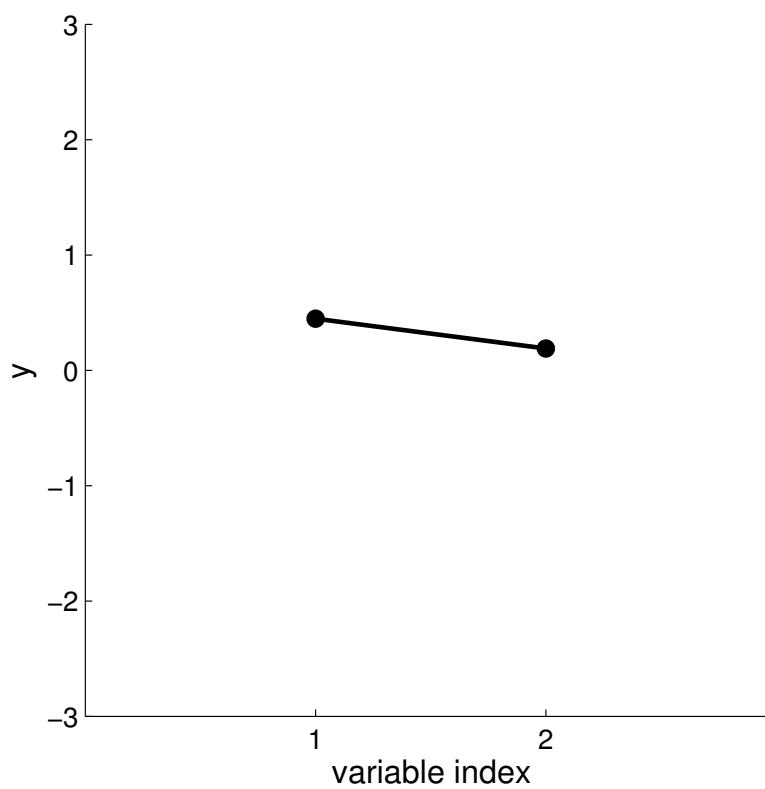
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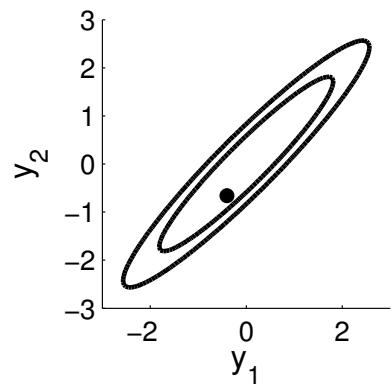
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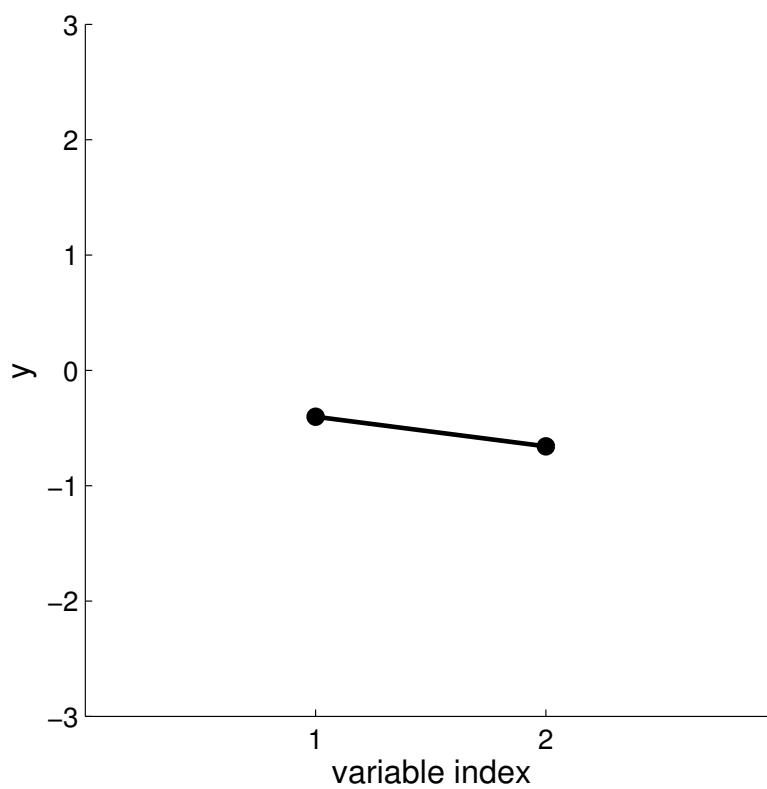
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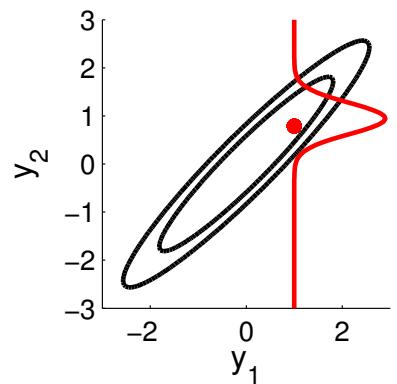
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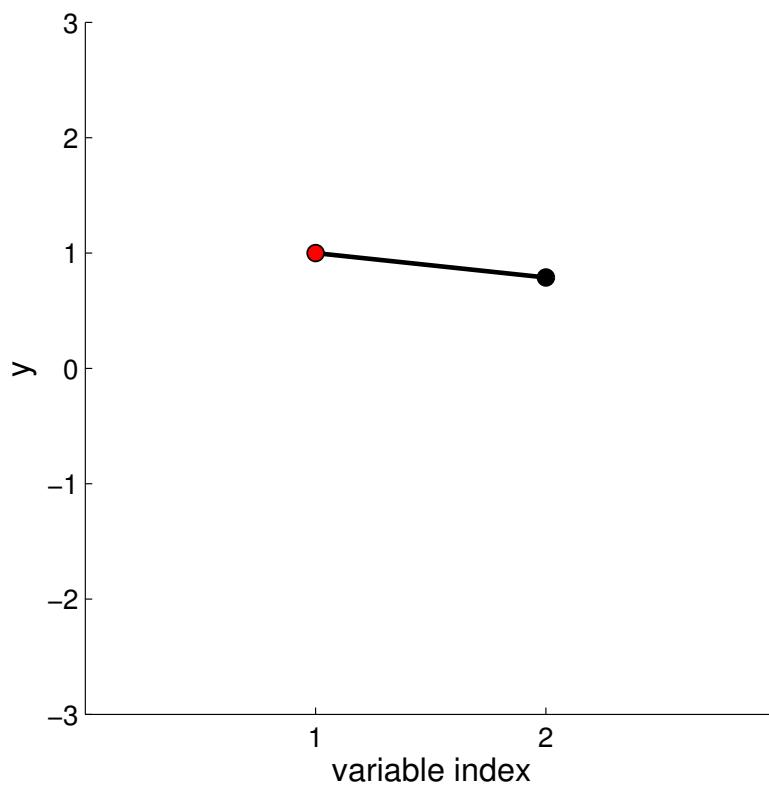
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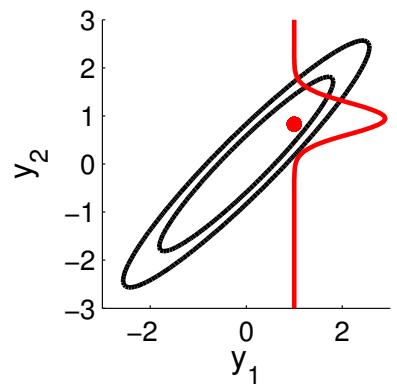
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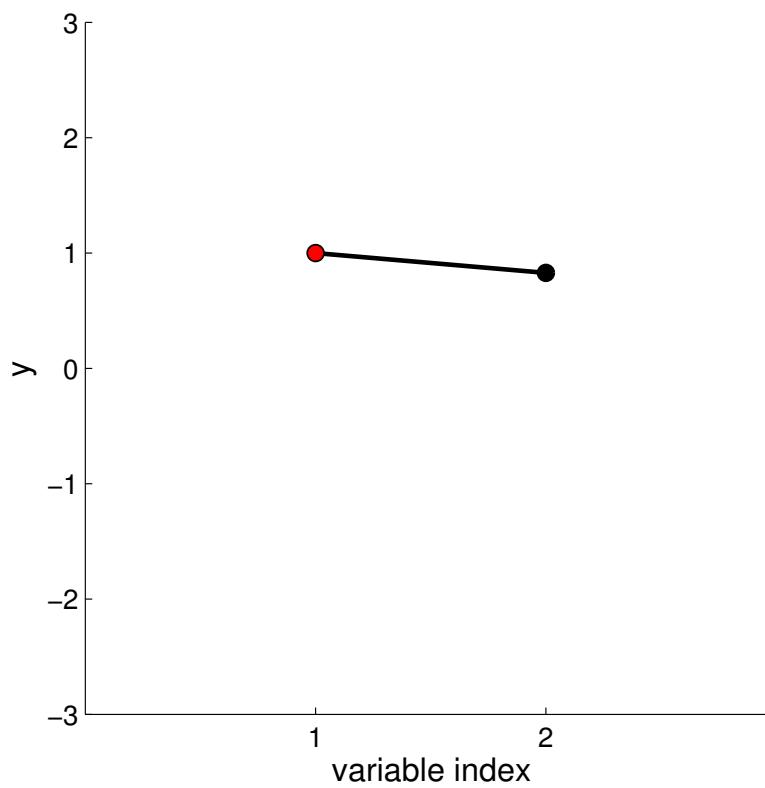
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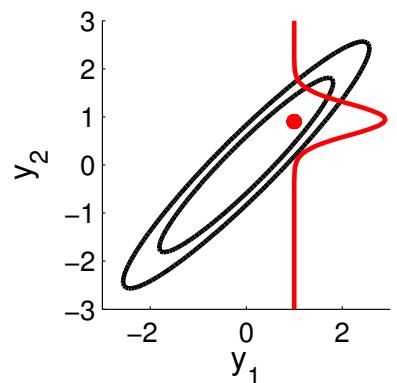
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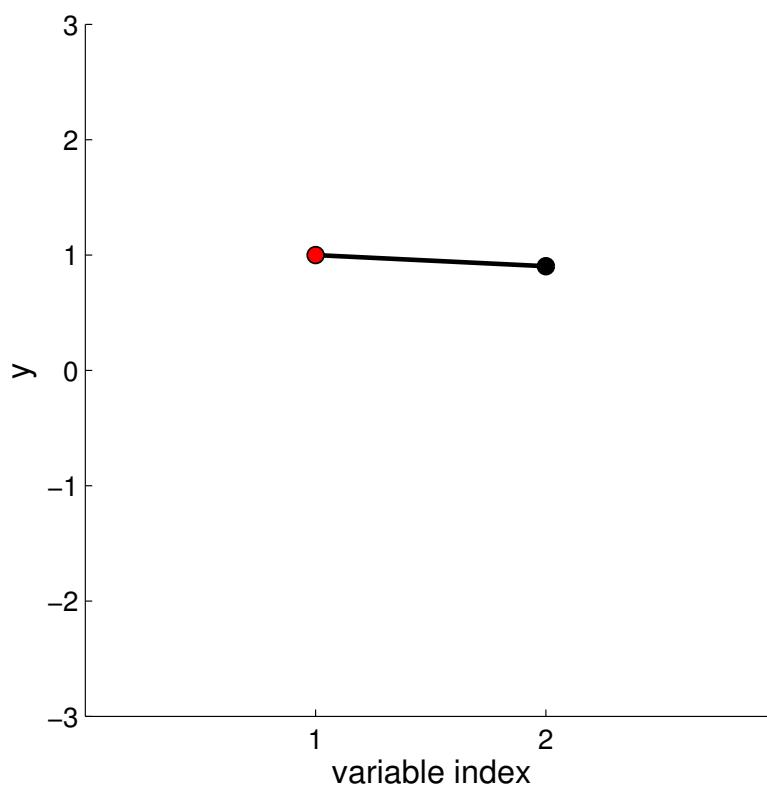
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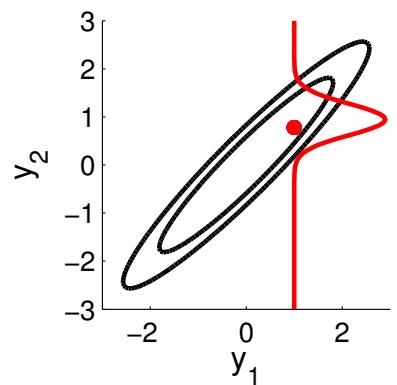
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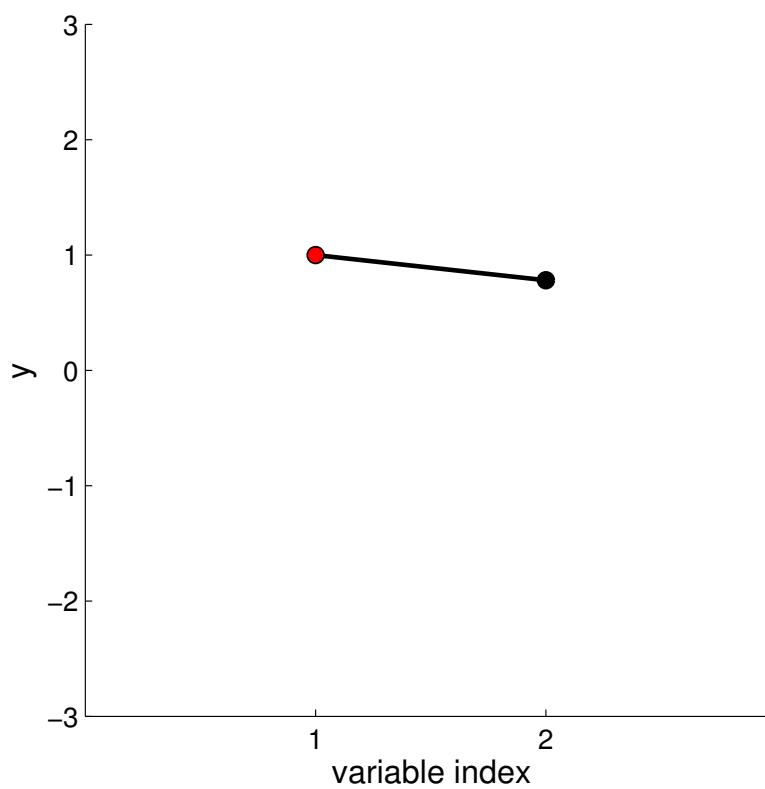
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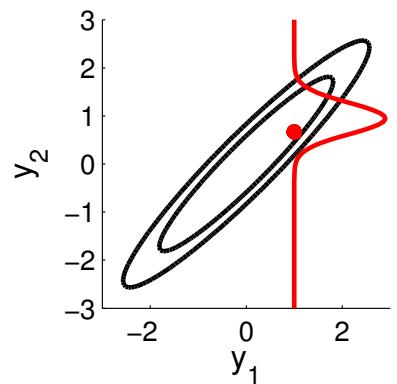
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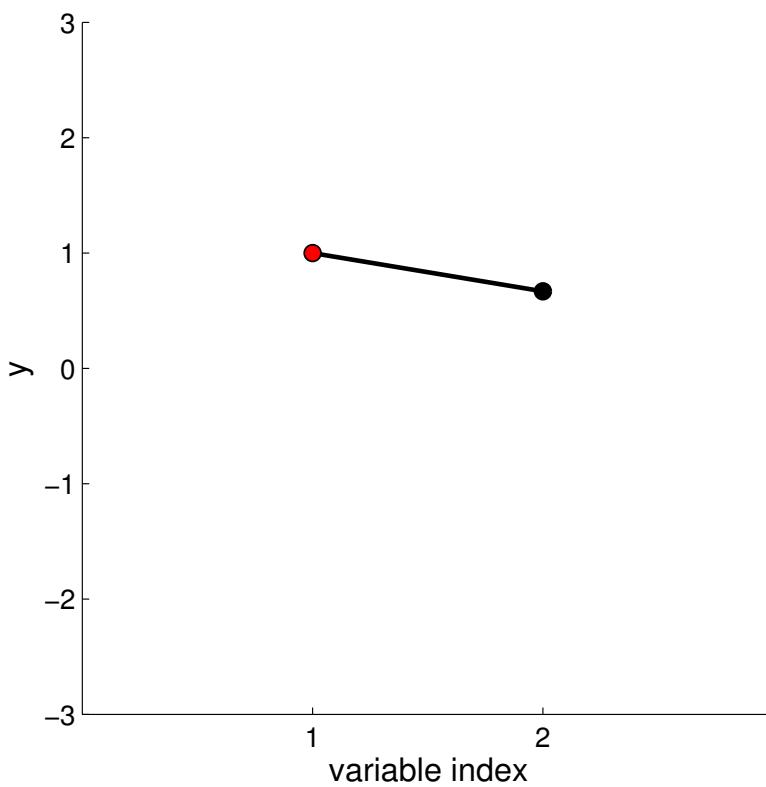
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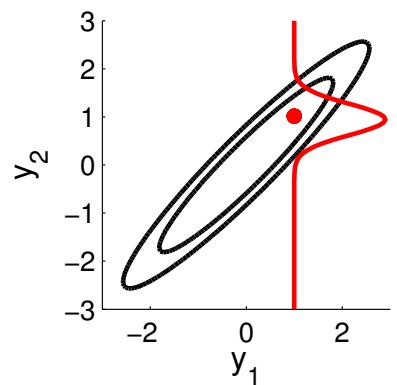
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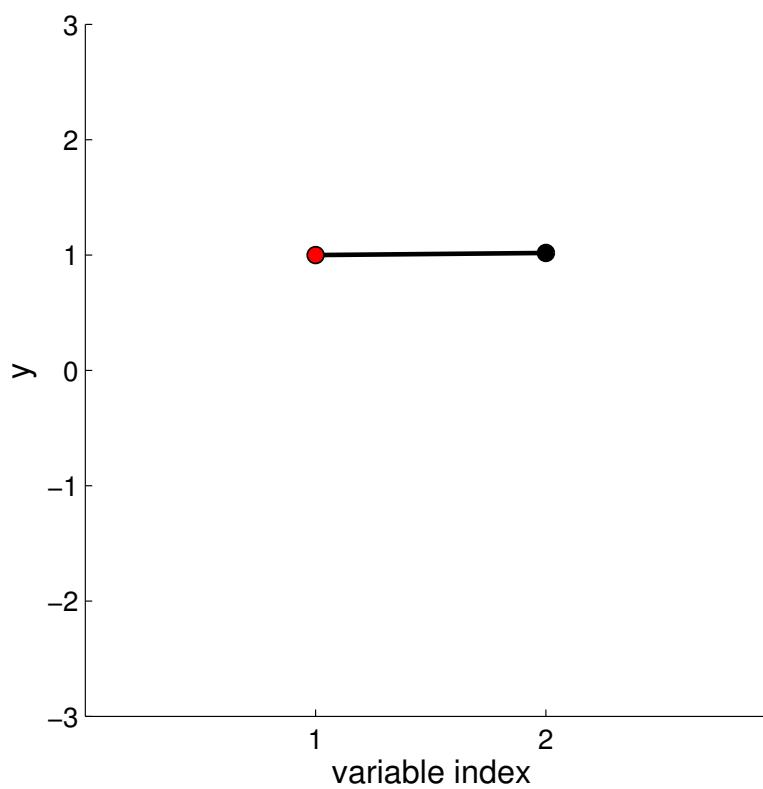
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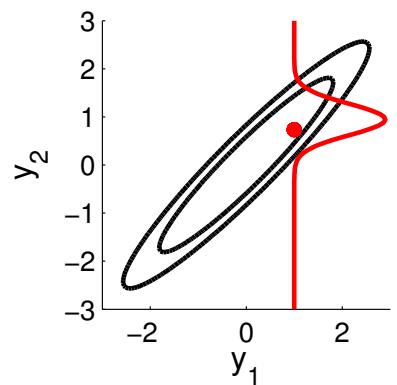
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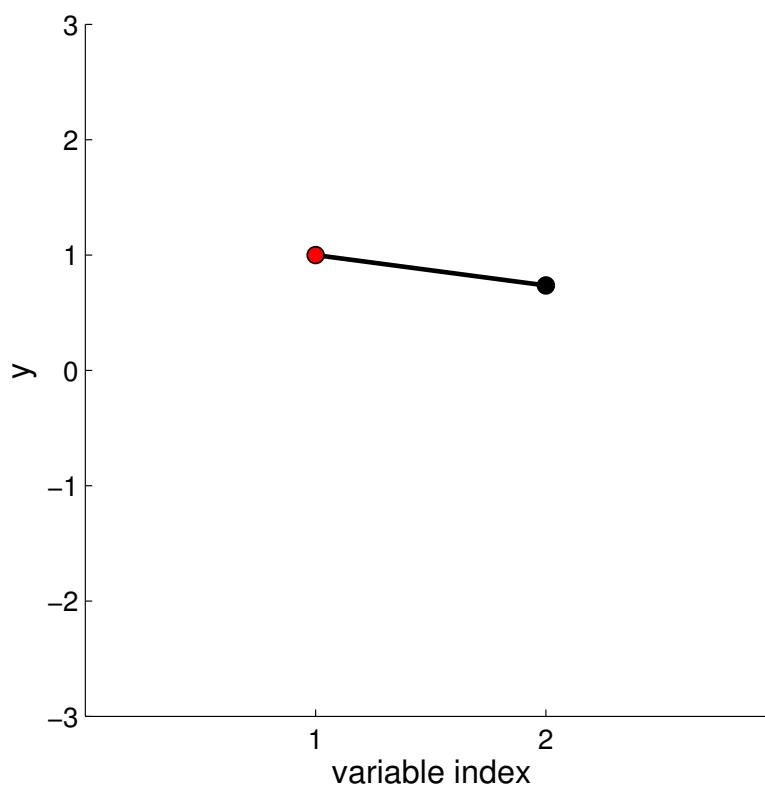
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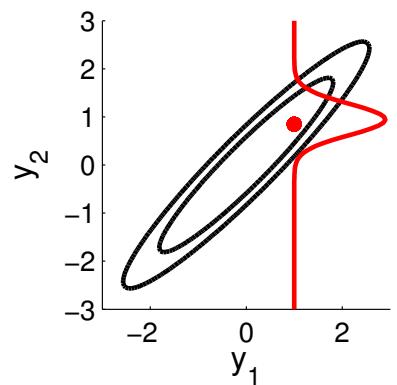
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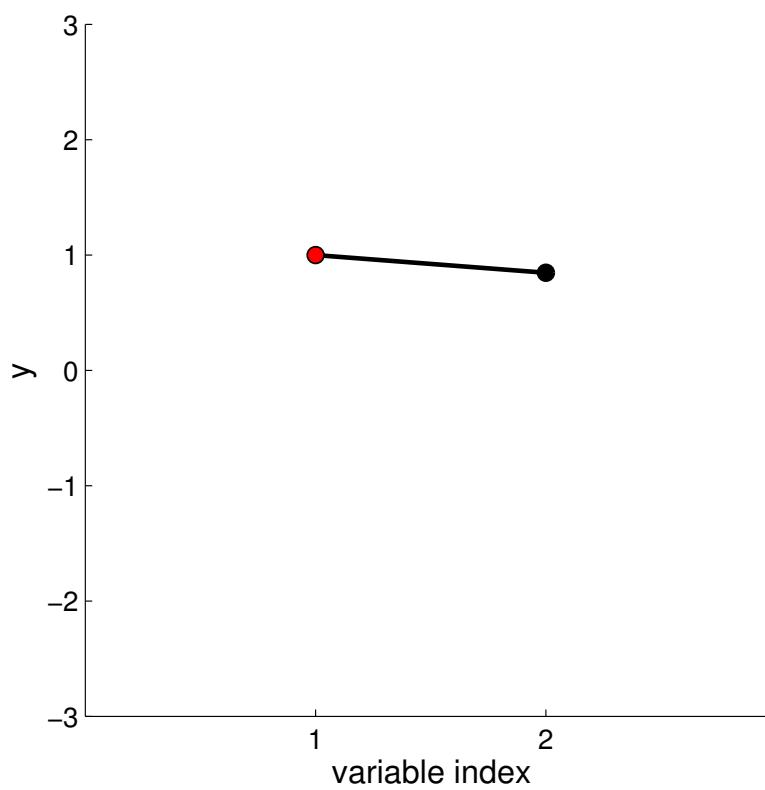
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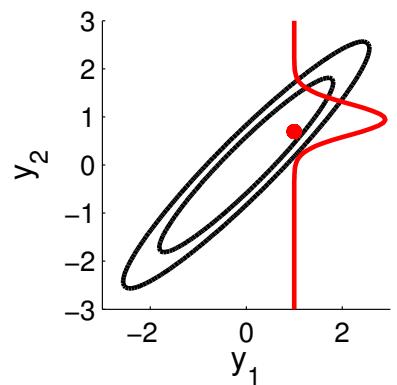
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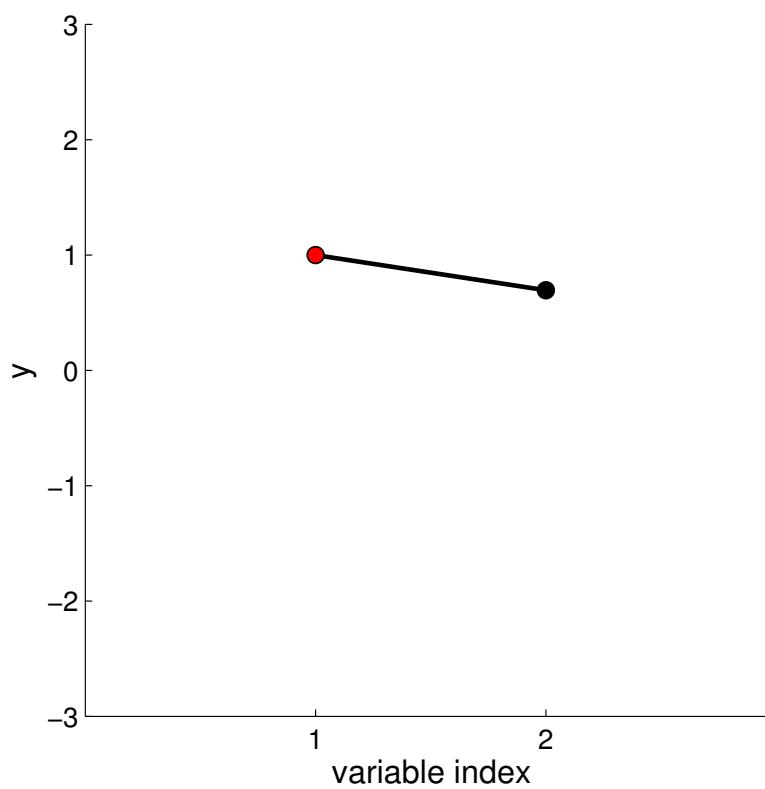
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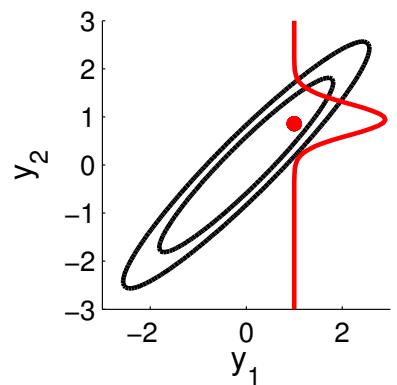
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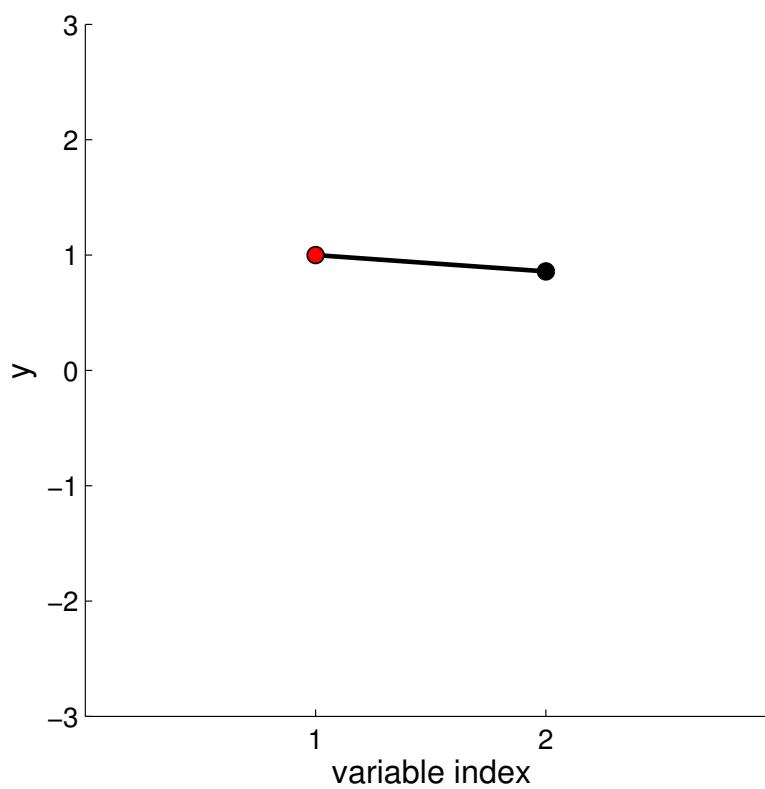
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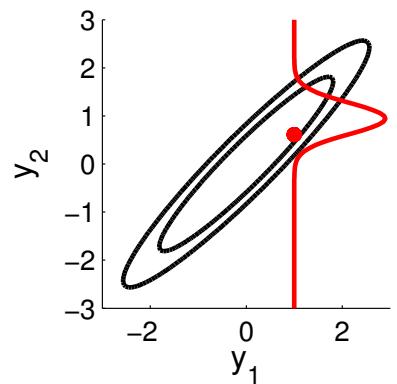
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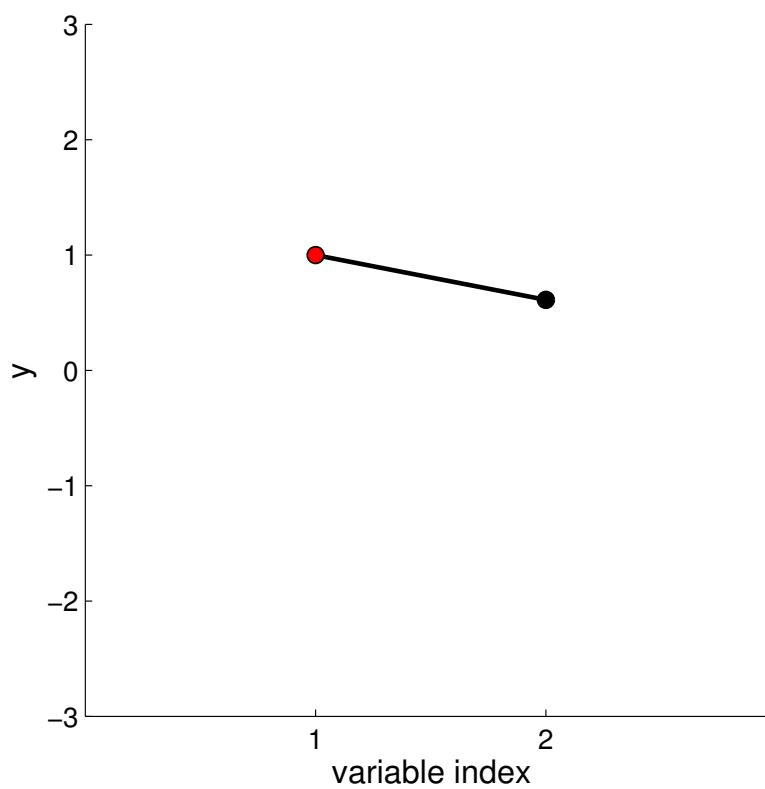
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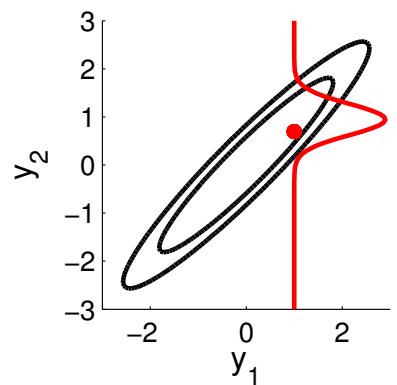
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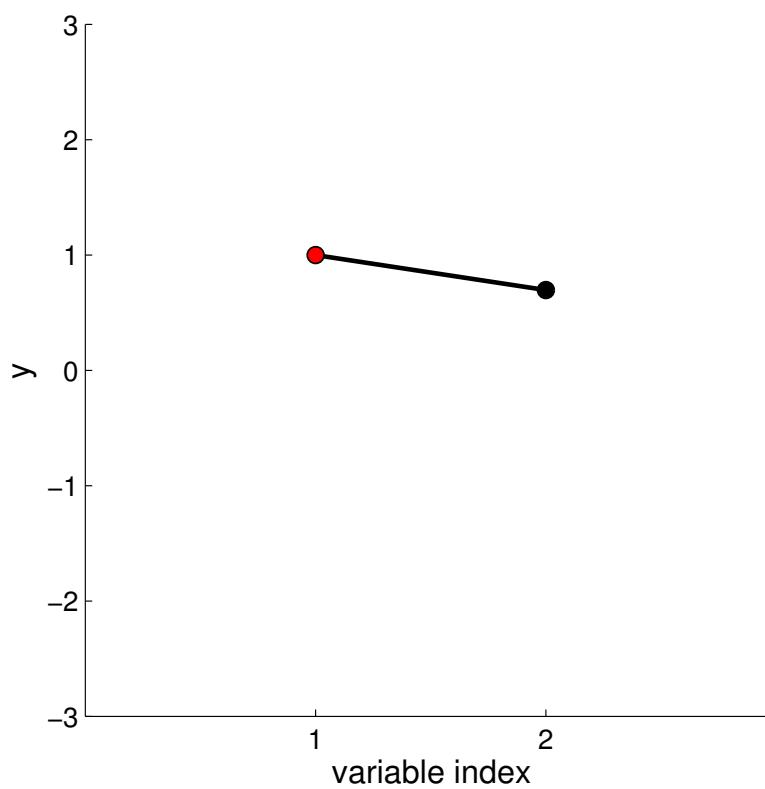
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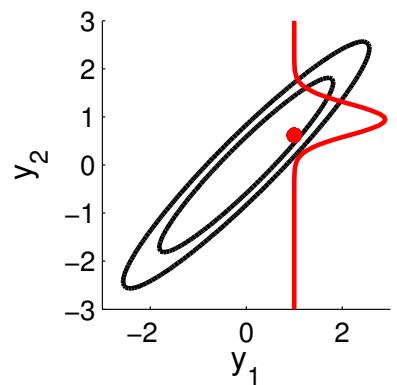
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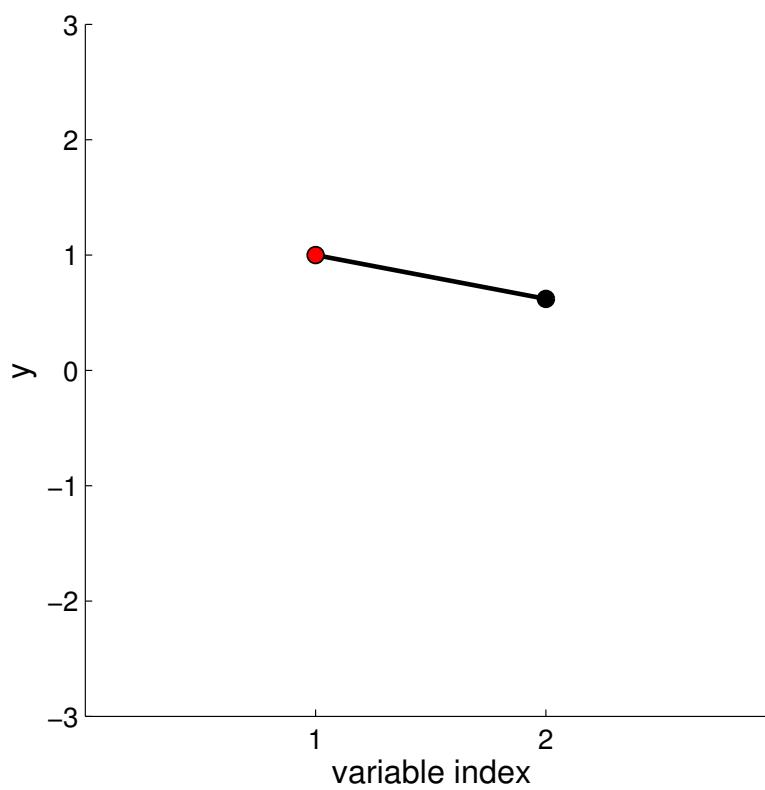
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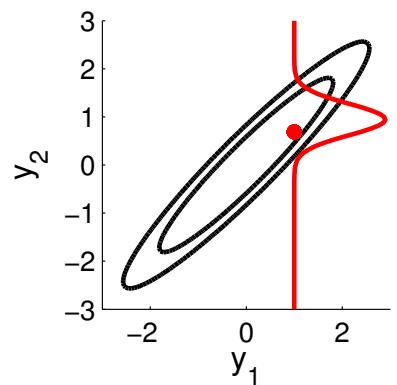
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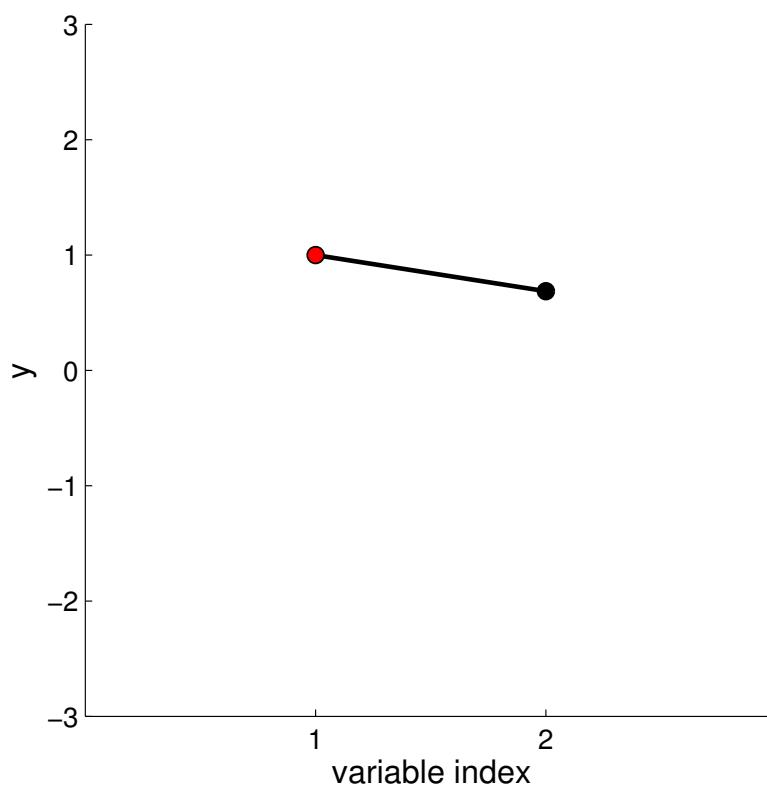
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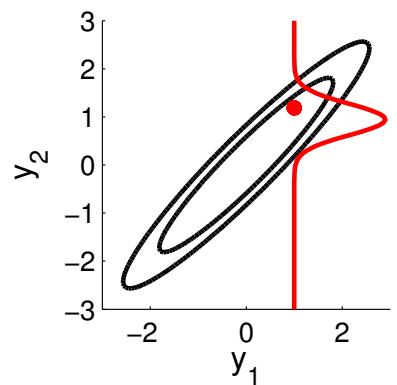
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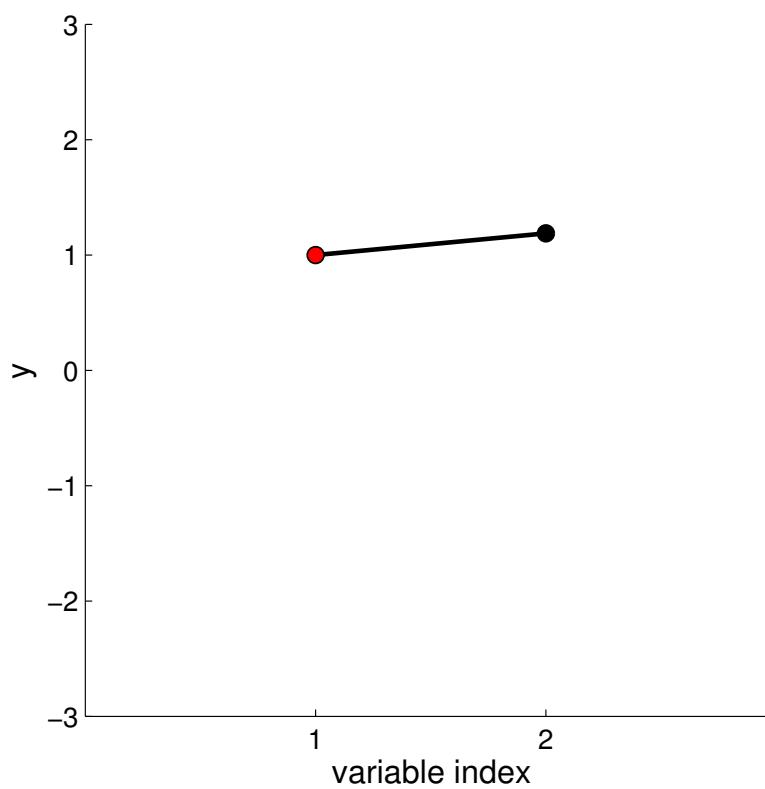
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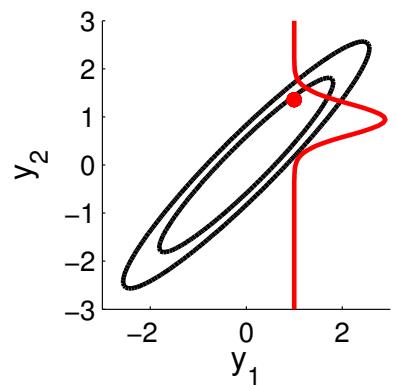
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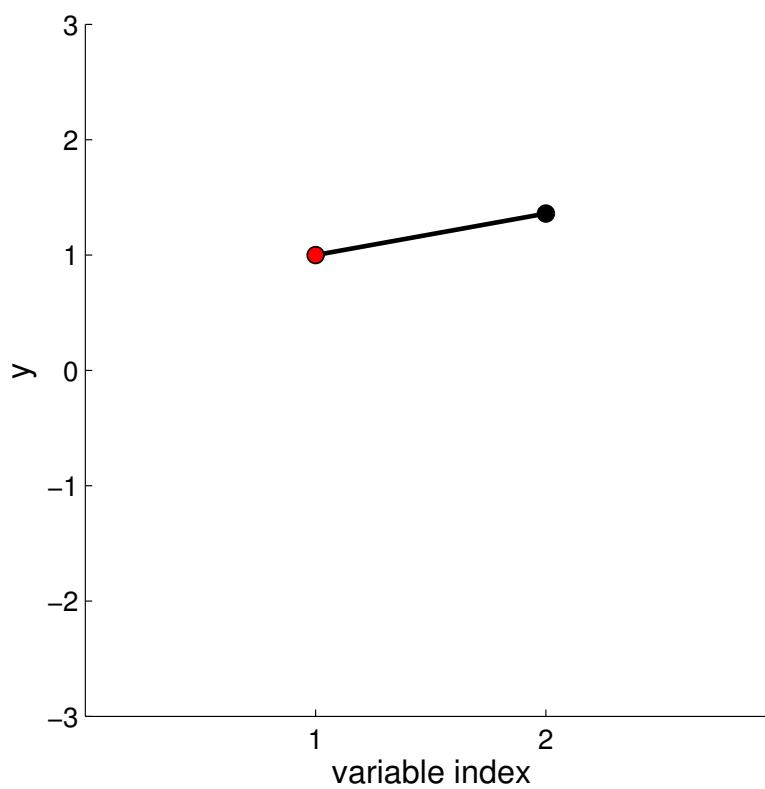
$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$



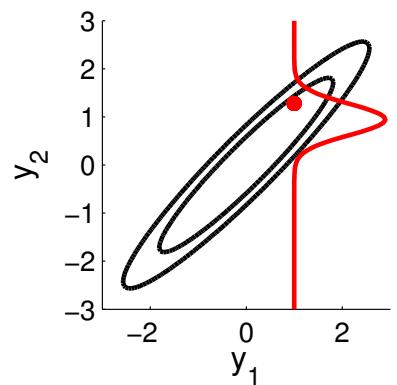
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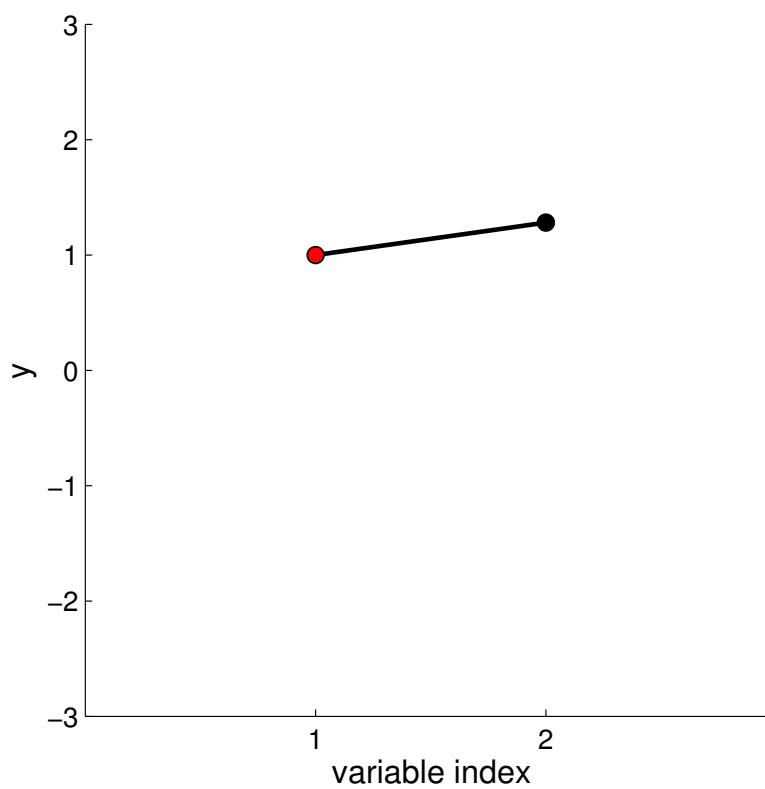
$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$



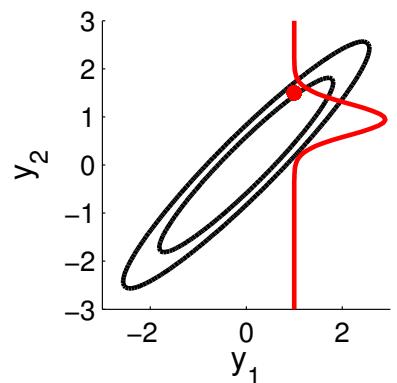
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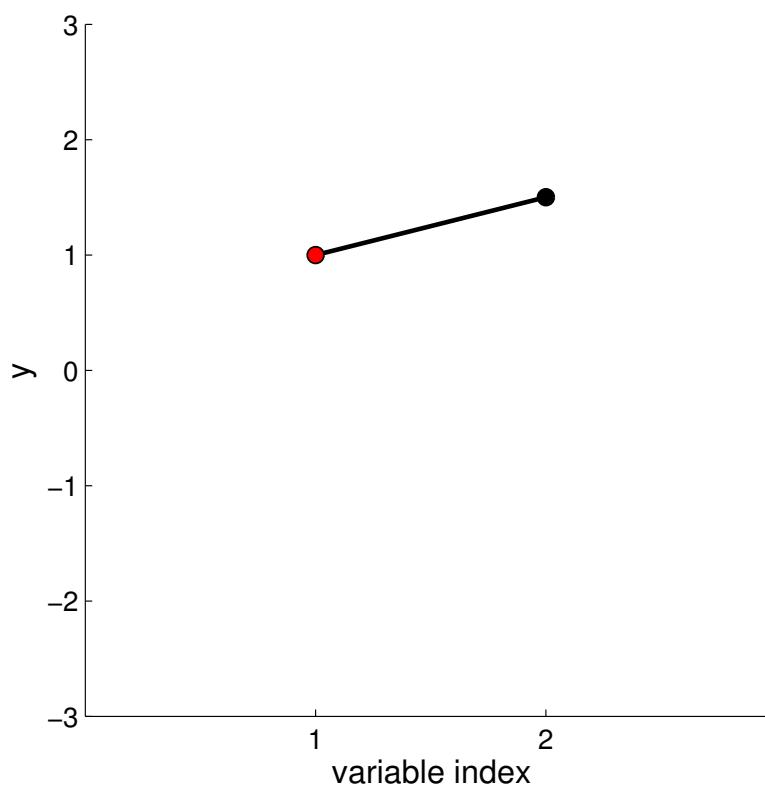
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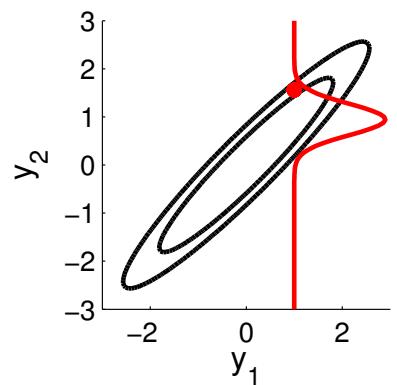
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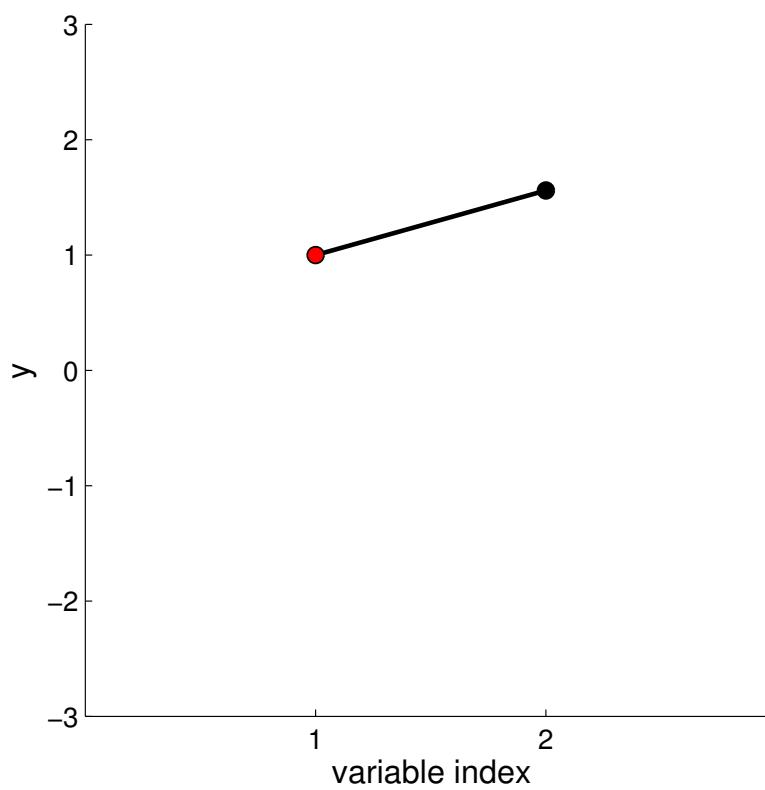
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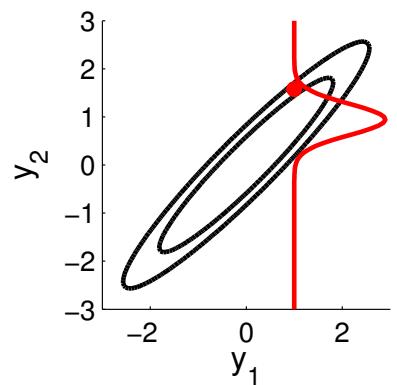
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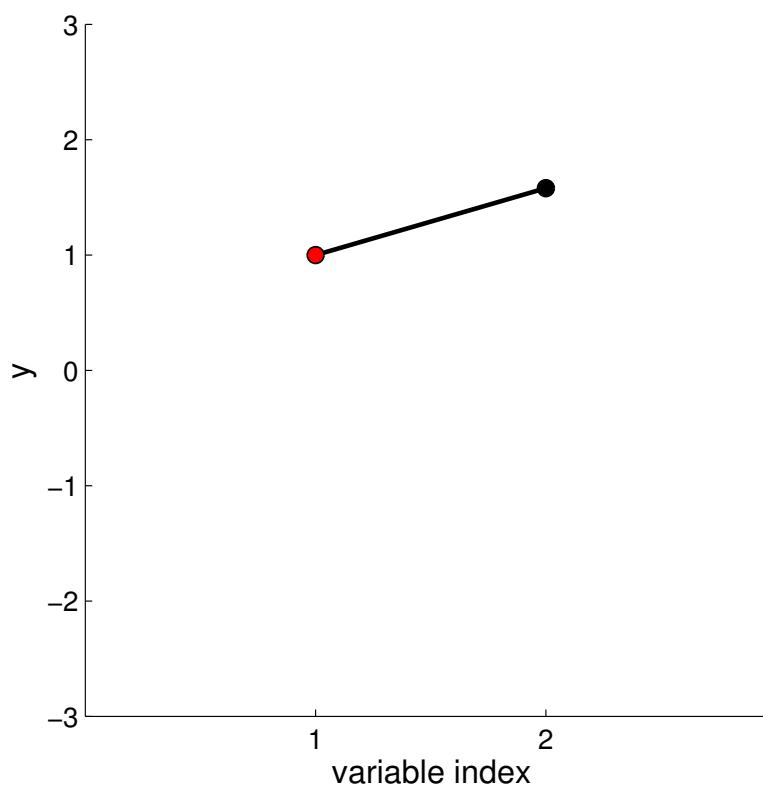
$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$



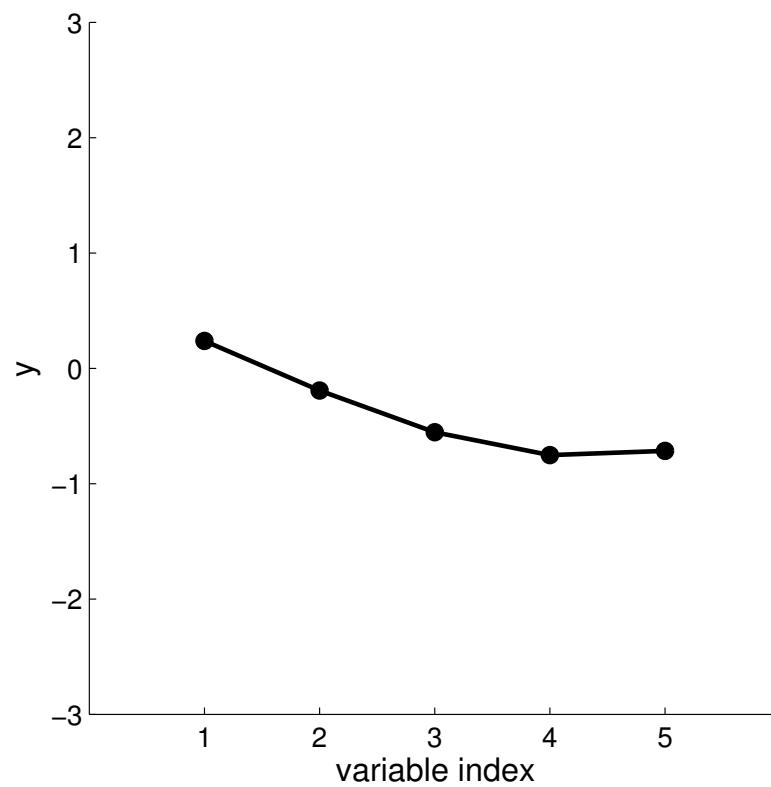
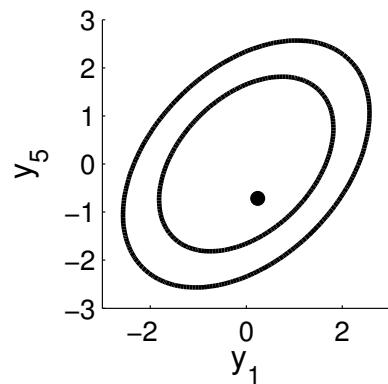
New visualisation



$$\Sigma = \begin{bmatrix} 1 & .9 \\ .9 & 1 \end{bmatrix}$$

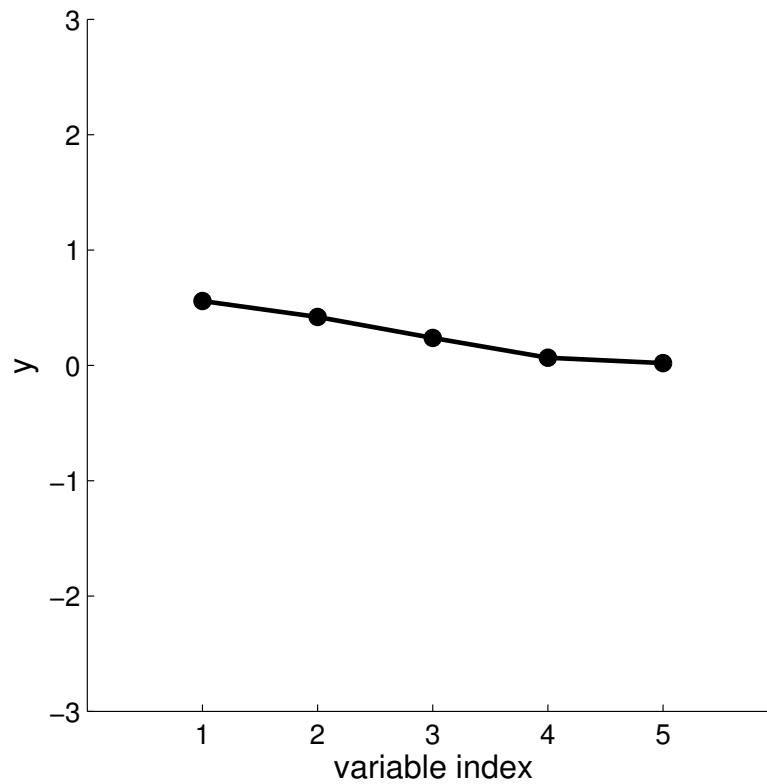
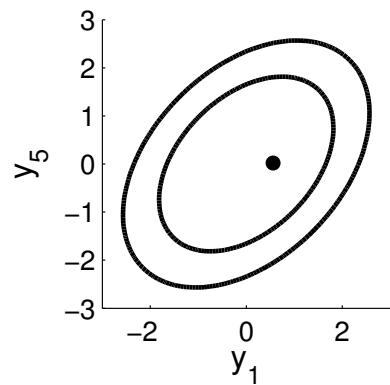


New visualisation



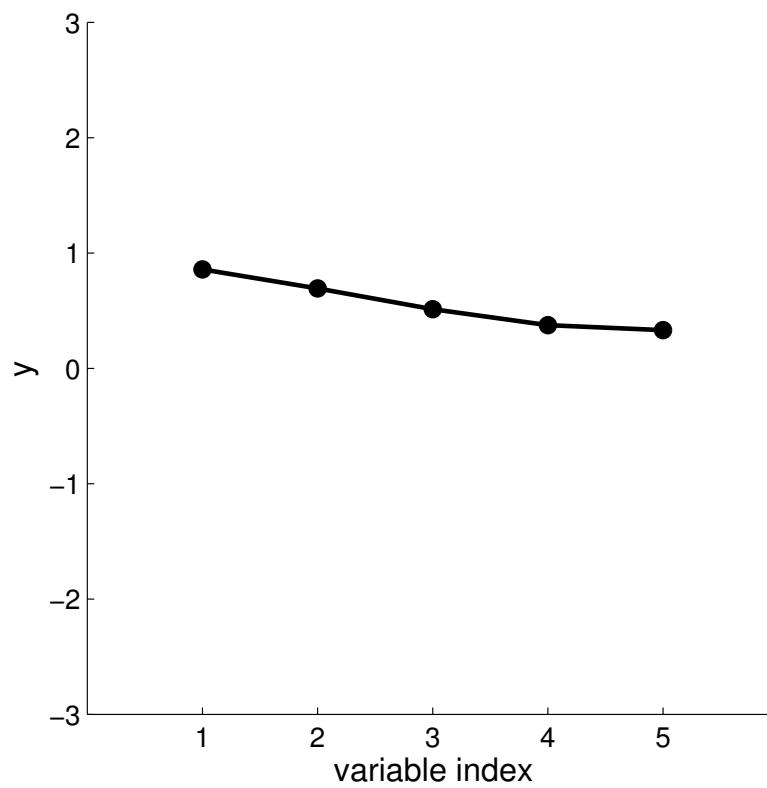
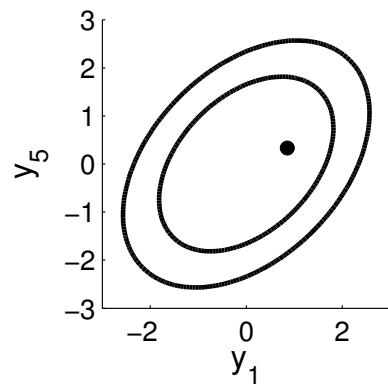
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



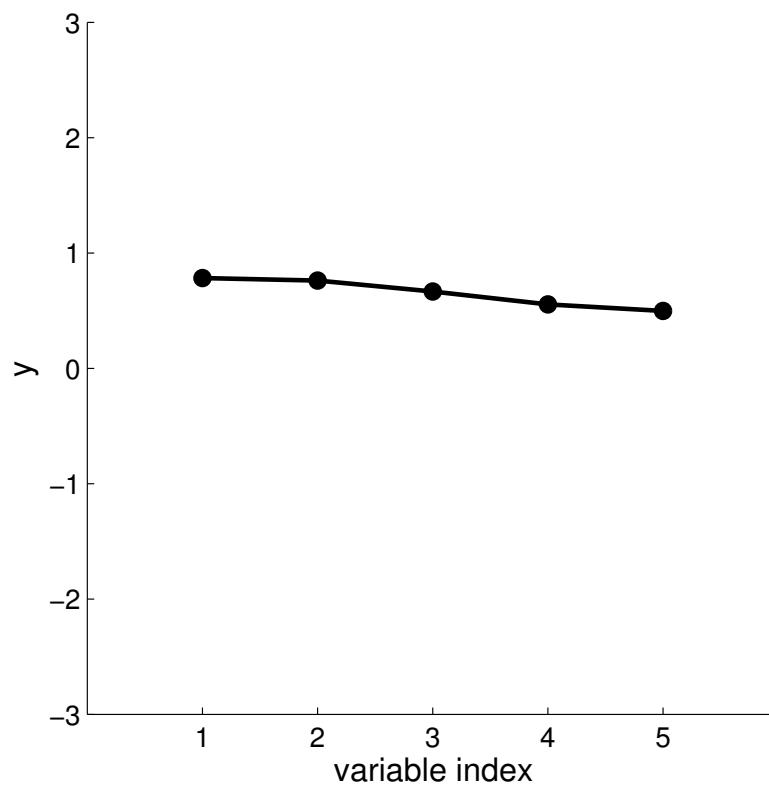
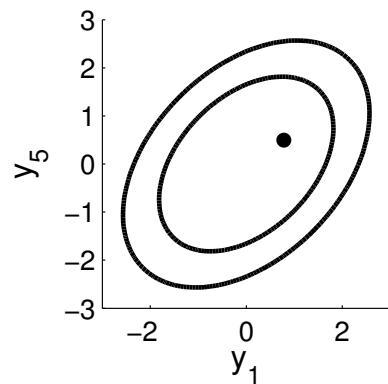
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



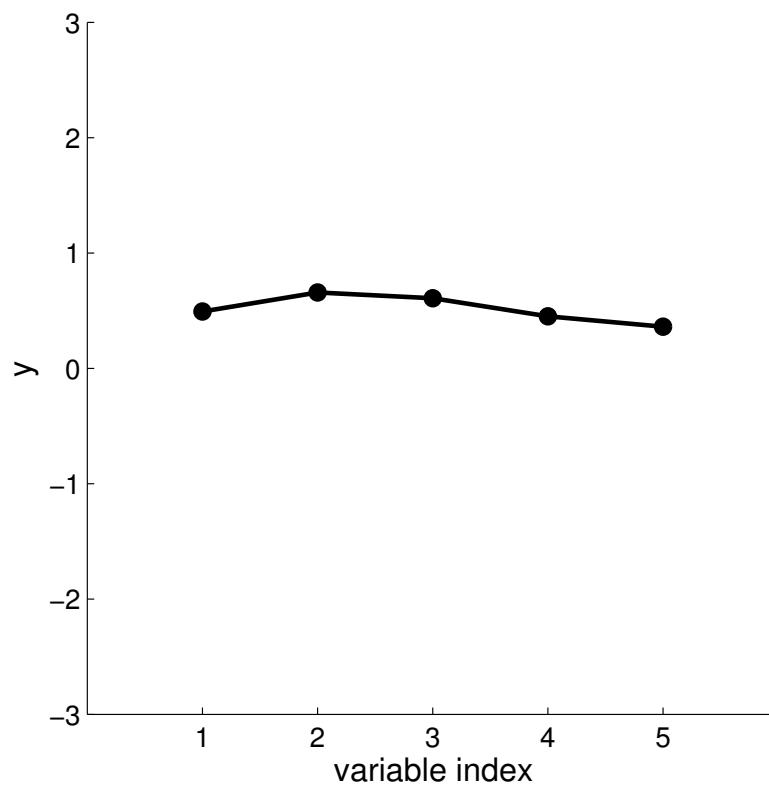
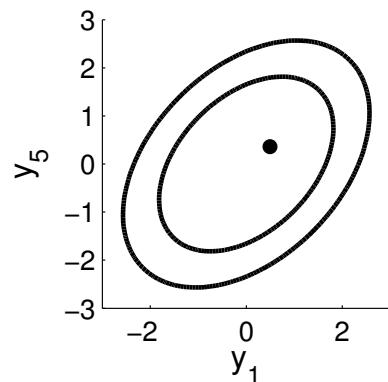
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



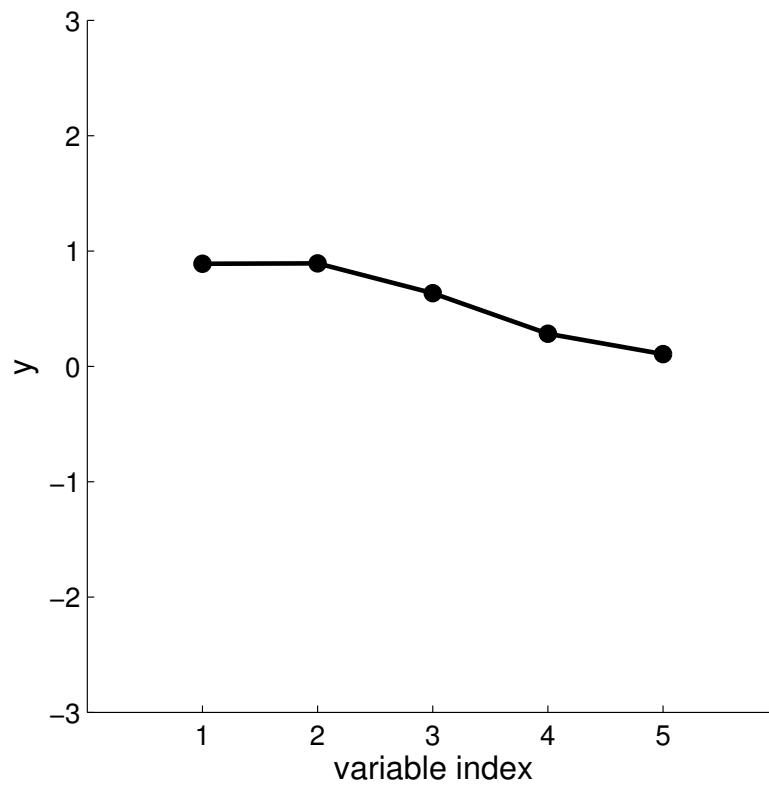
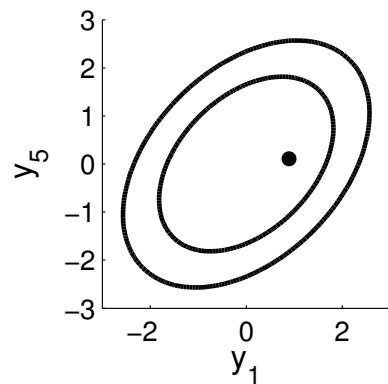
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New visualisation



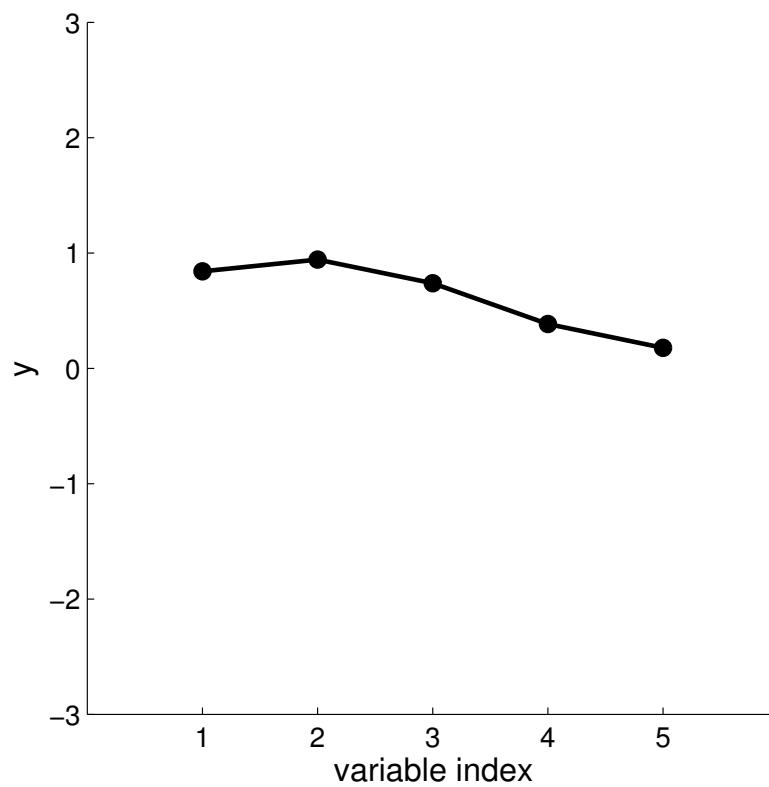
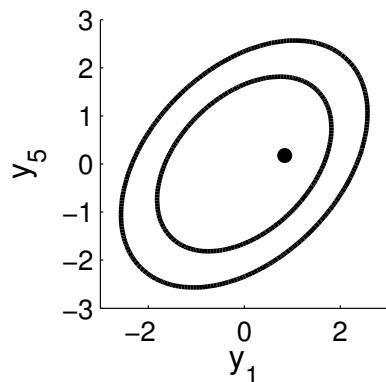
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



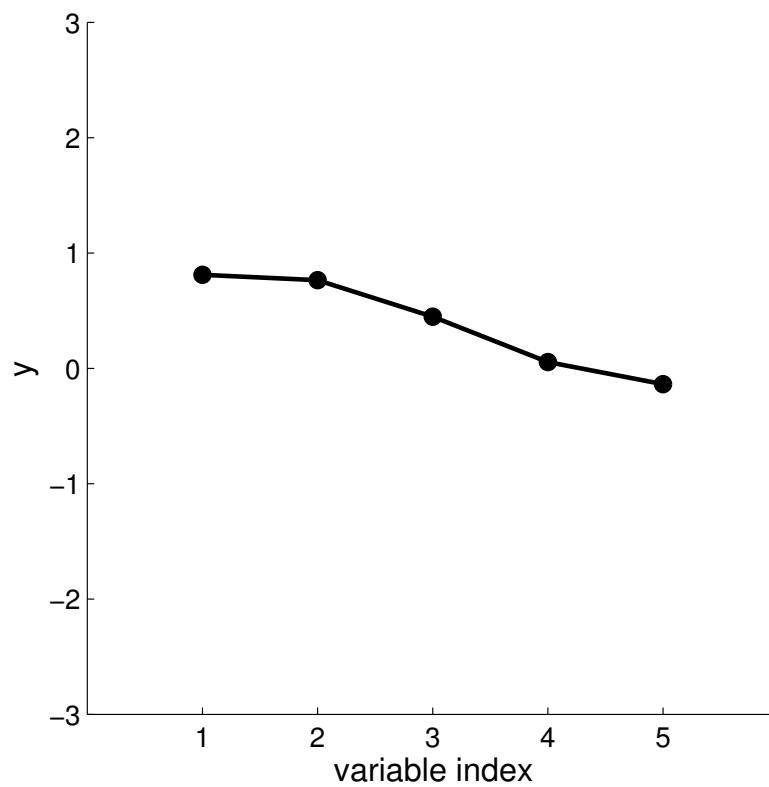
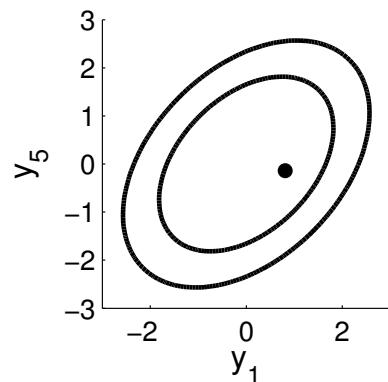
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New visualisation



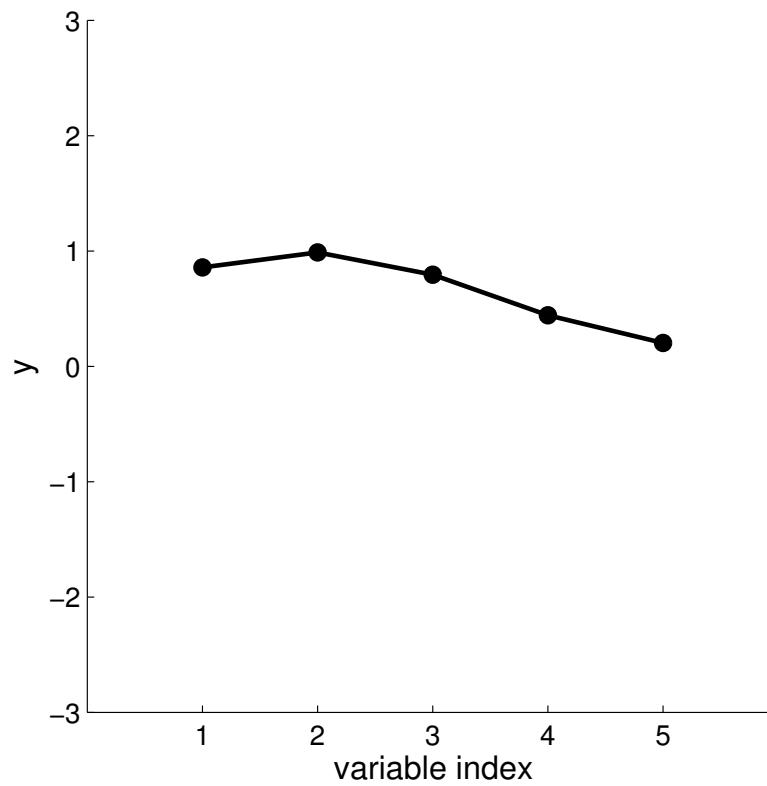
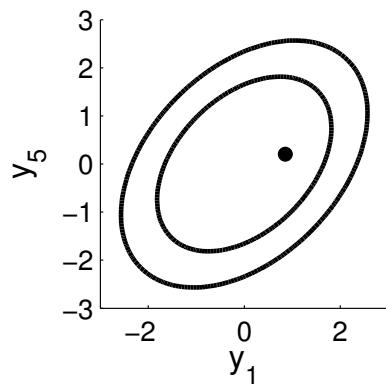
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New visualisation



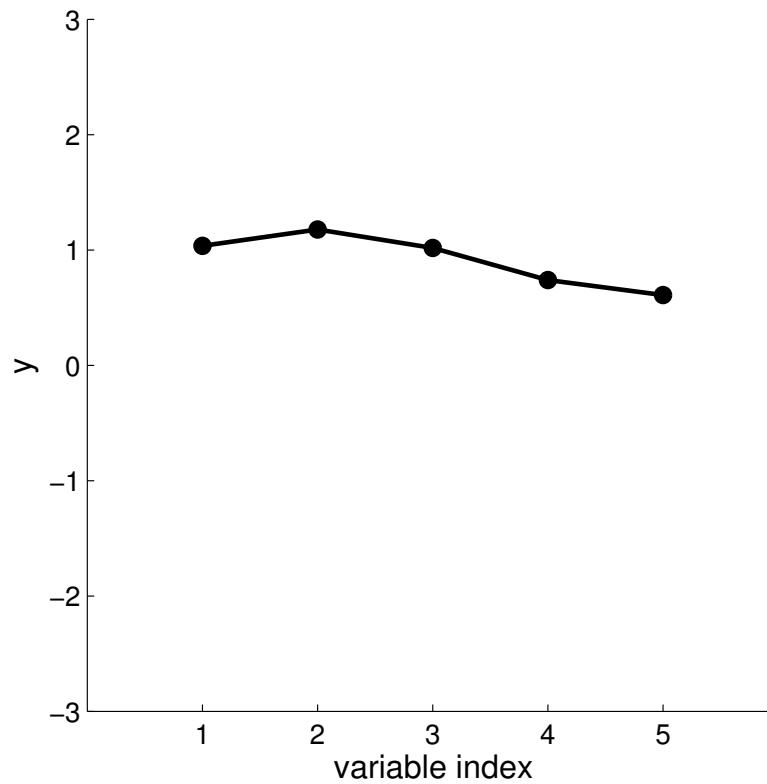
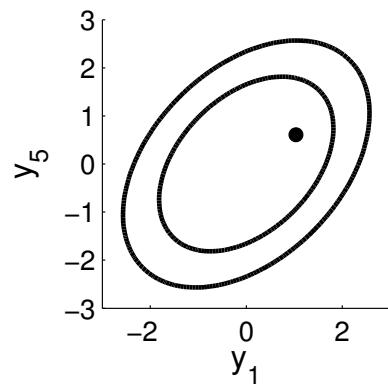
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New visualisation



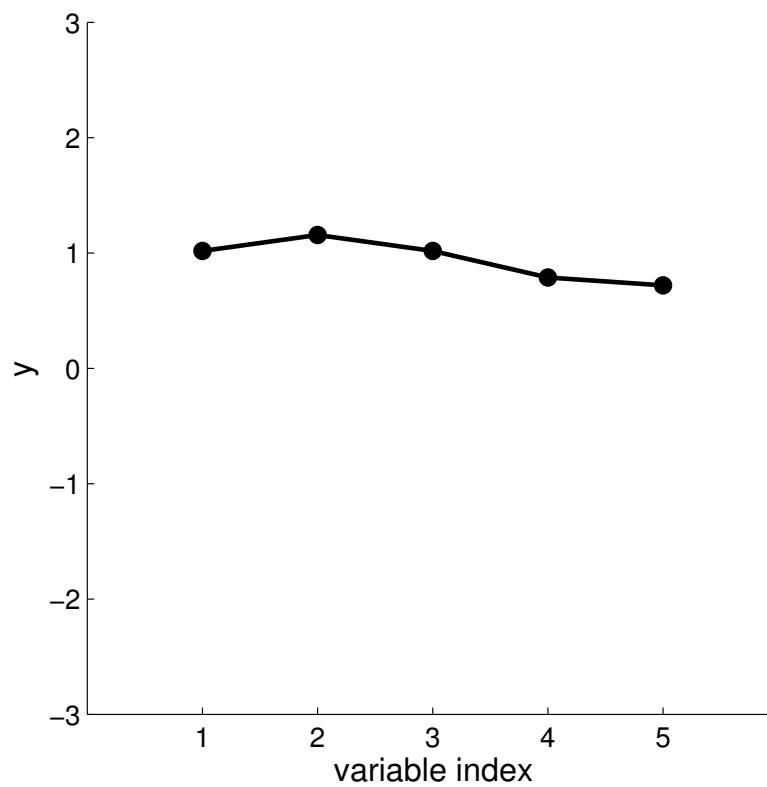
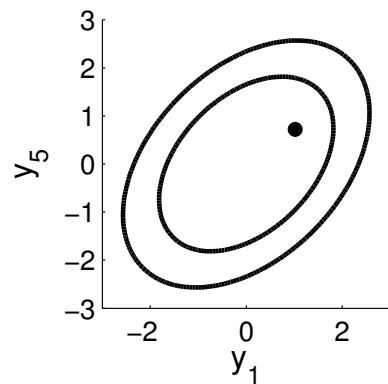
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New visualisation



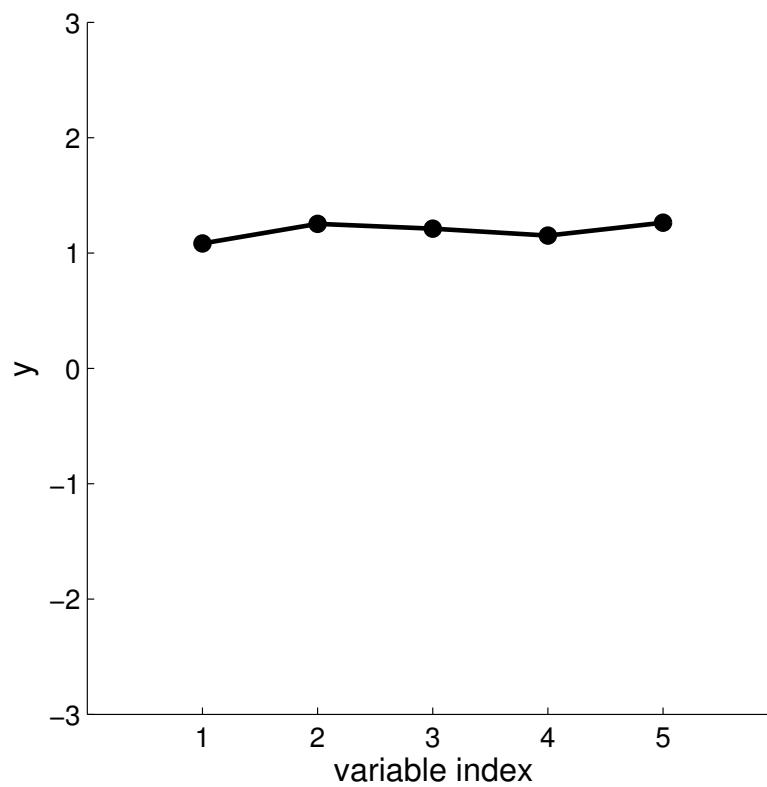
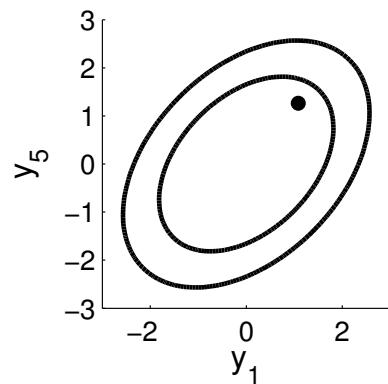
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New visualisation



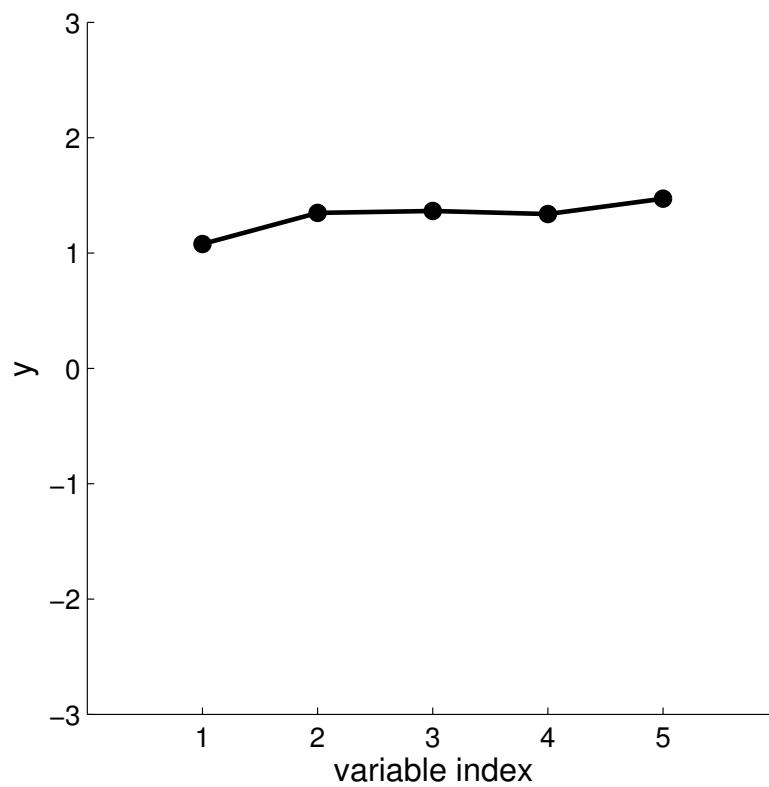
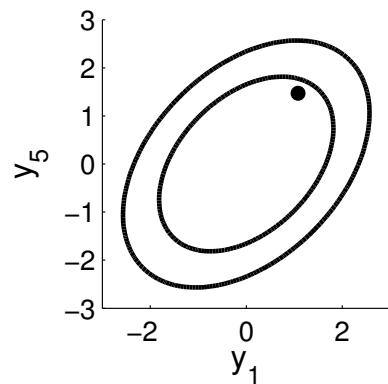
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New visualisation



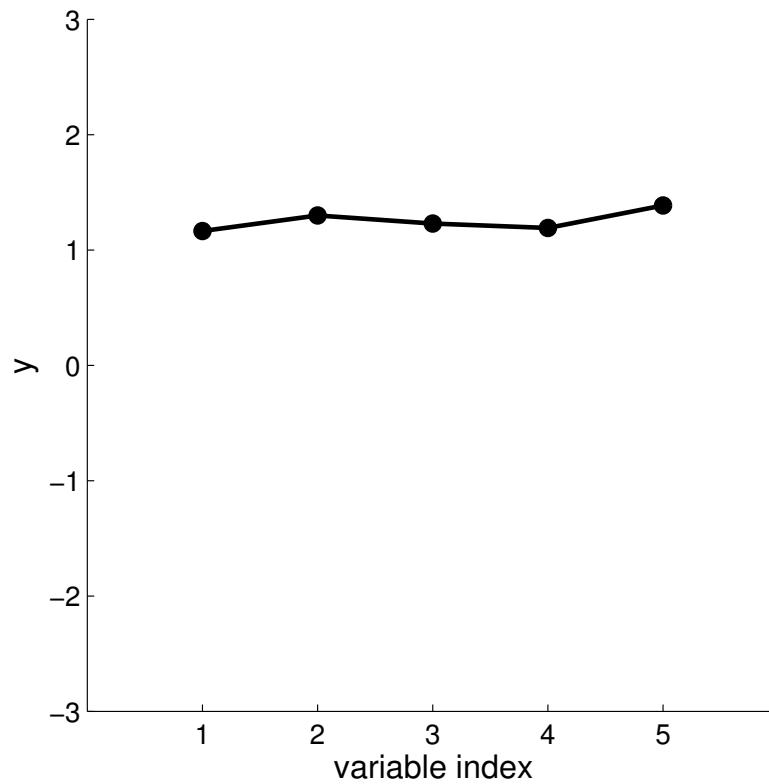
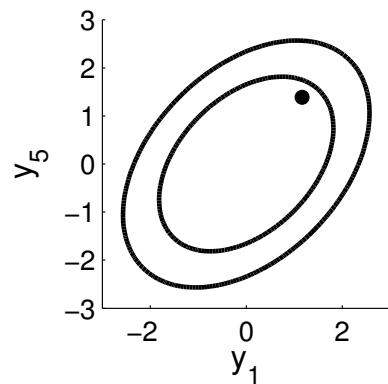
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



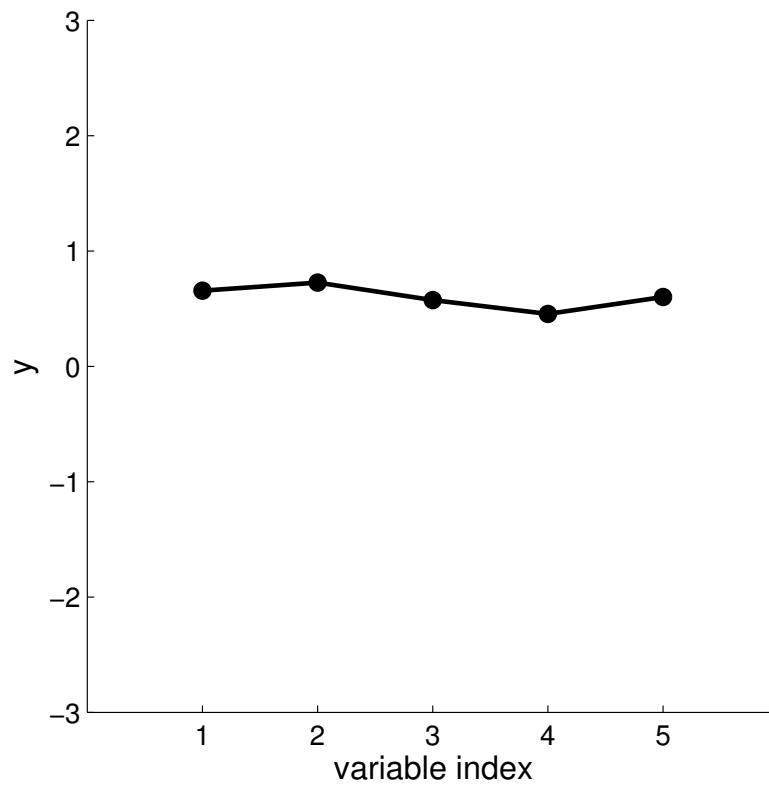
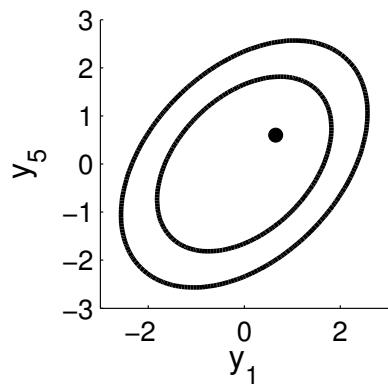
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



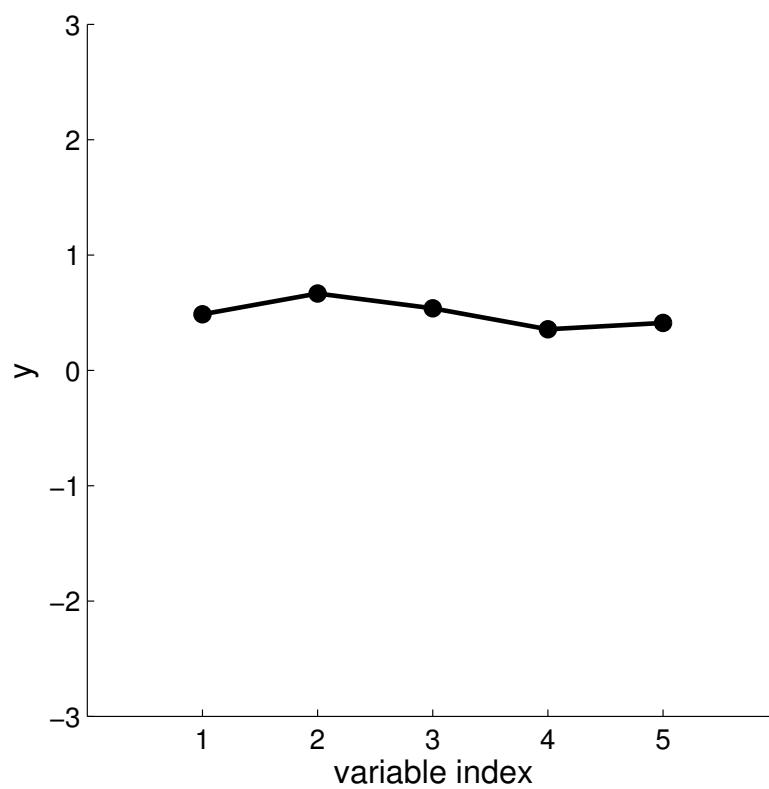
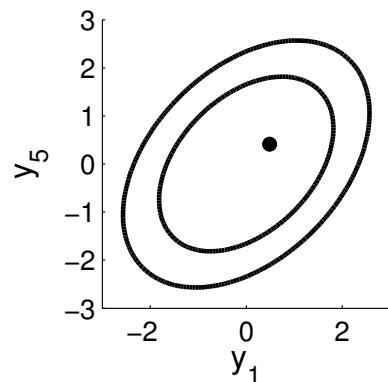
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



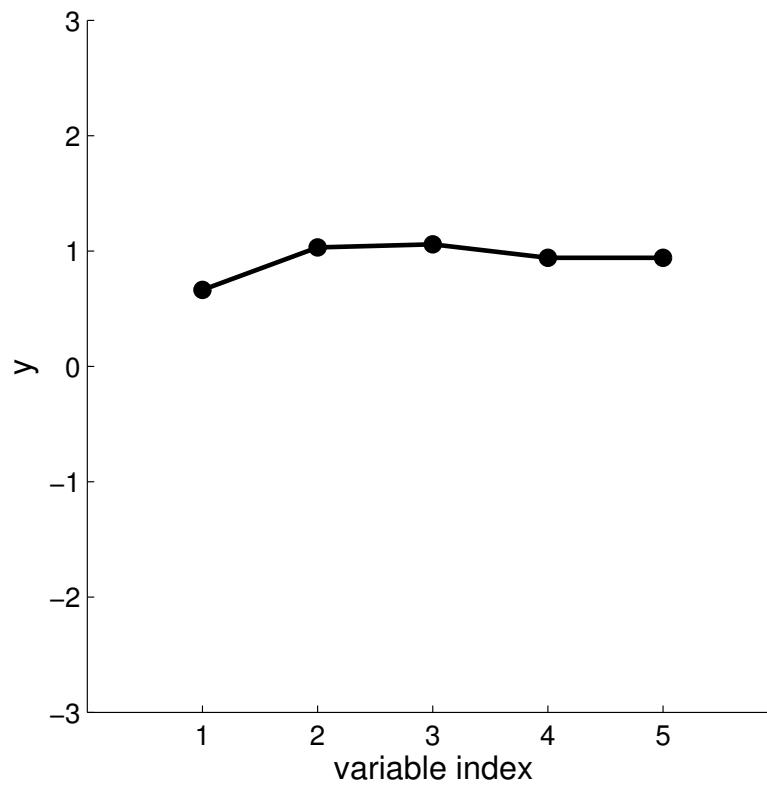
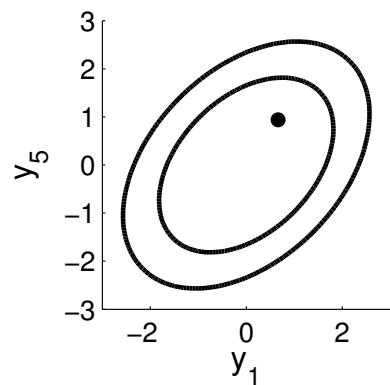
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



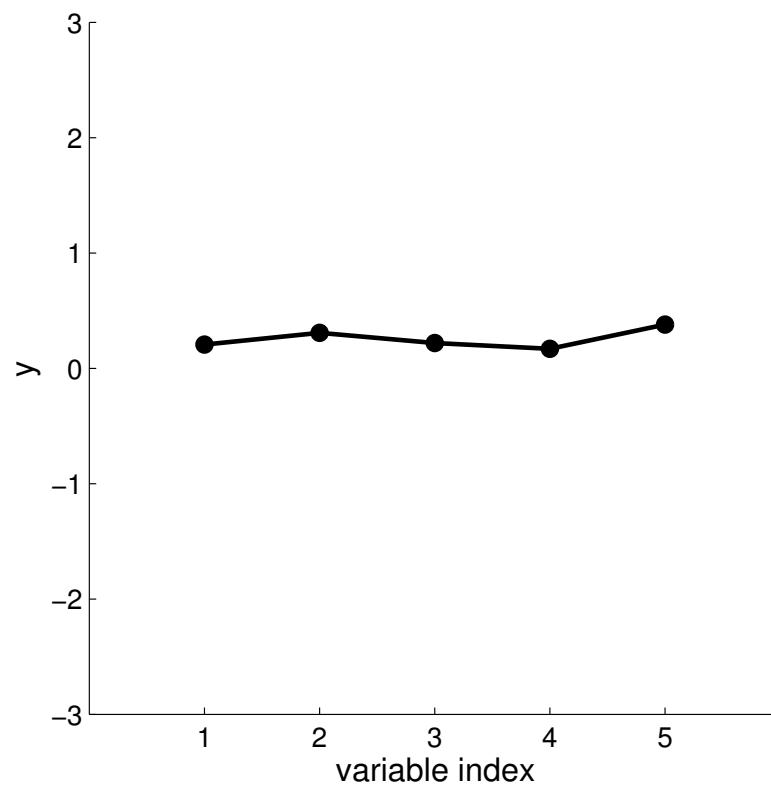
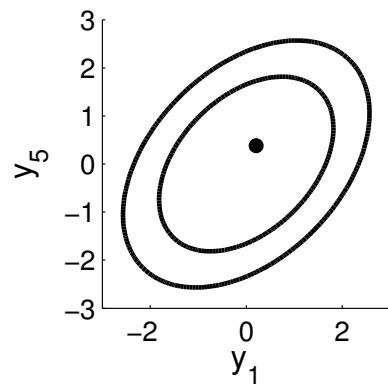
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



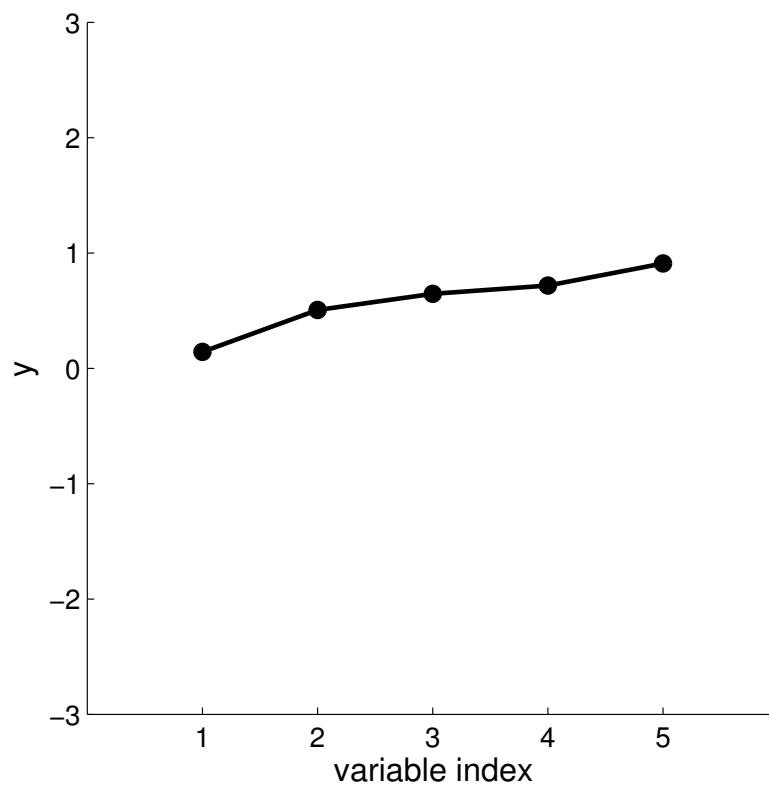
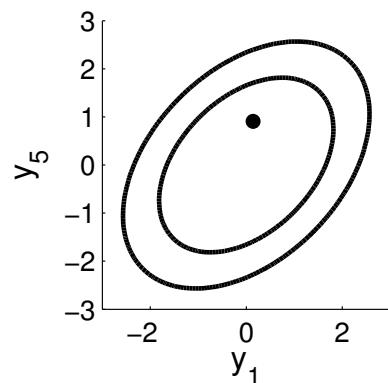
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



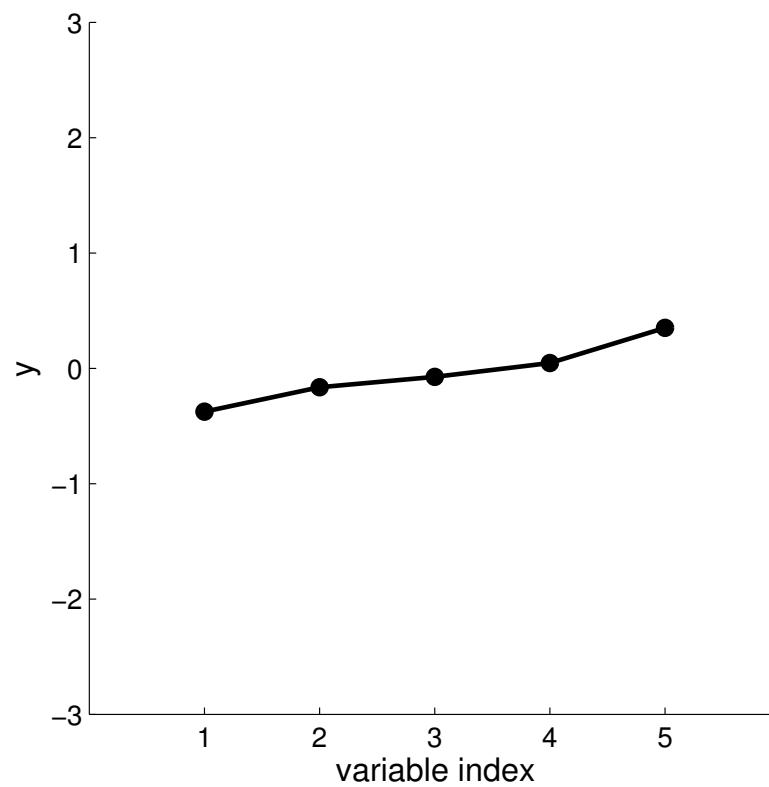
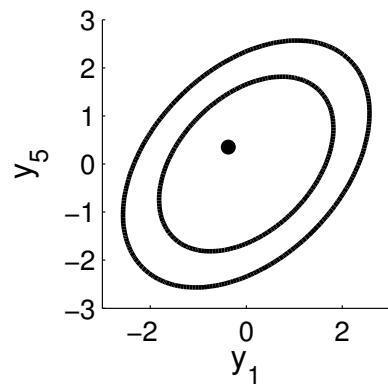
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



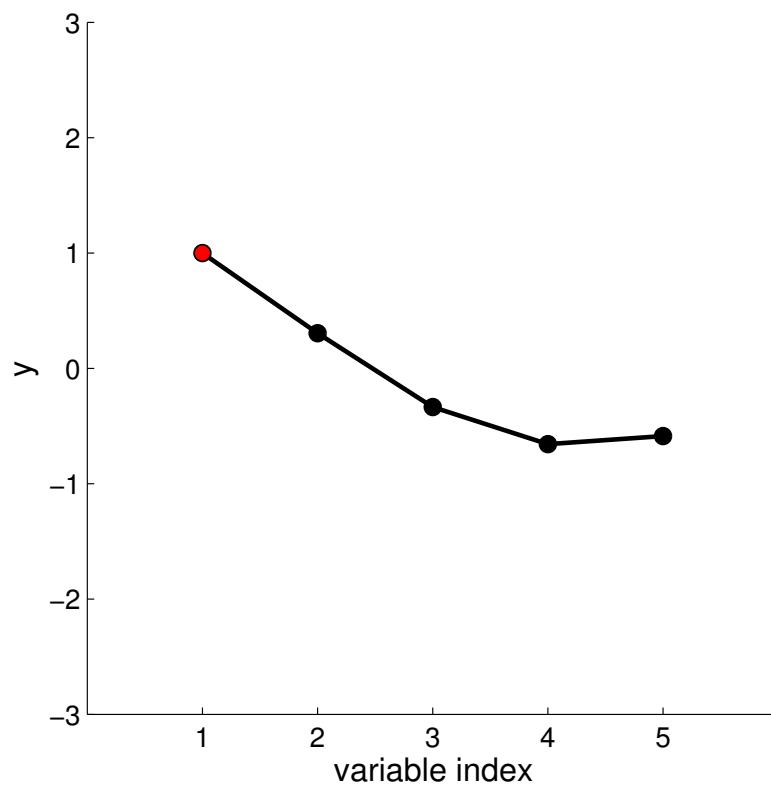
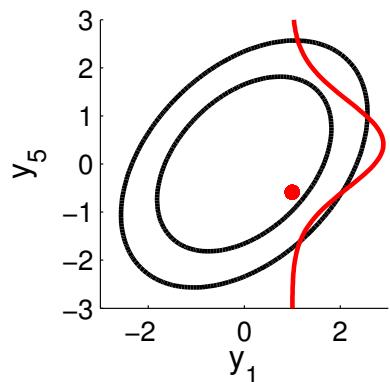
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



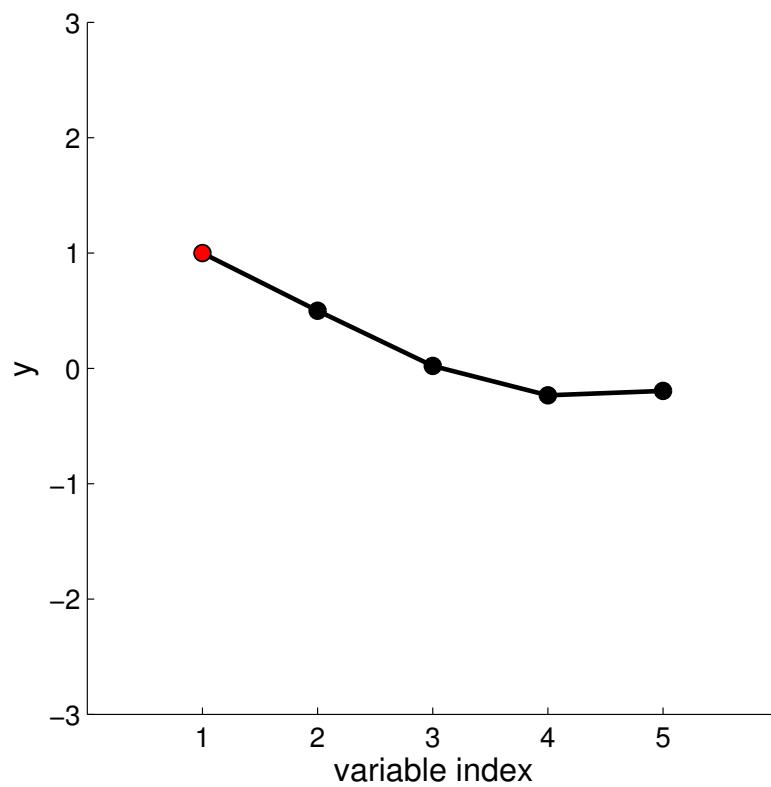
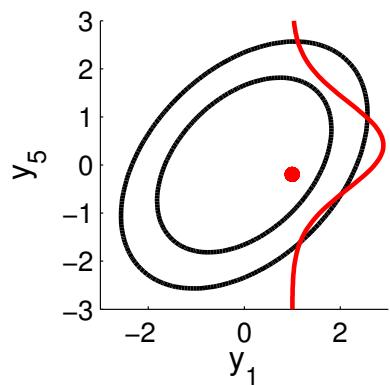
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



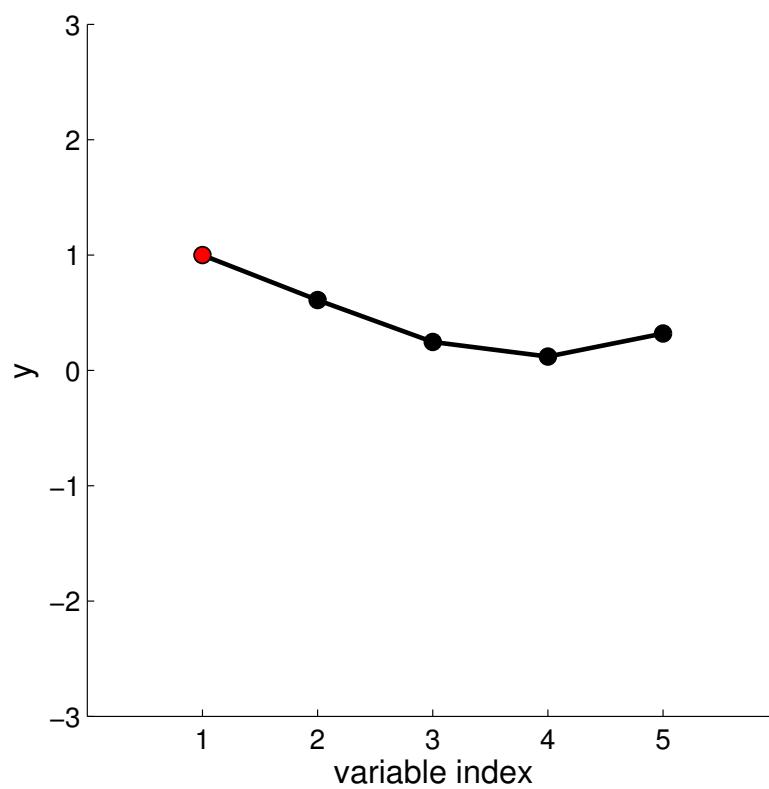
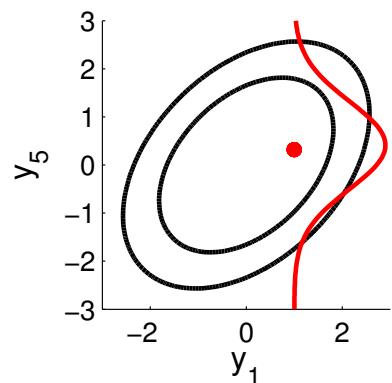
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



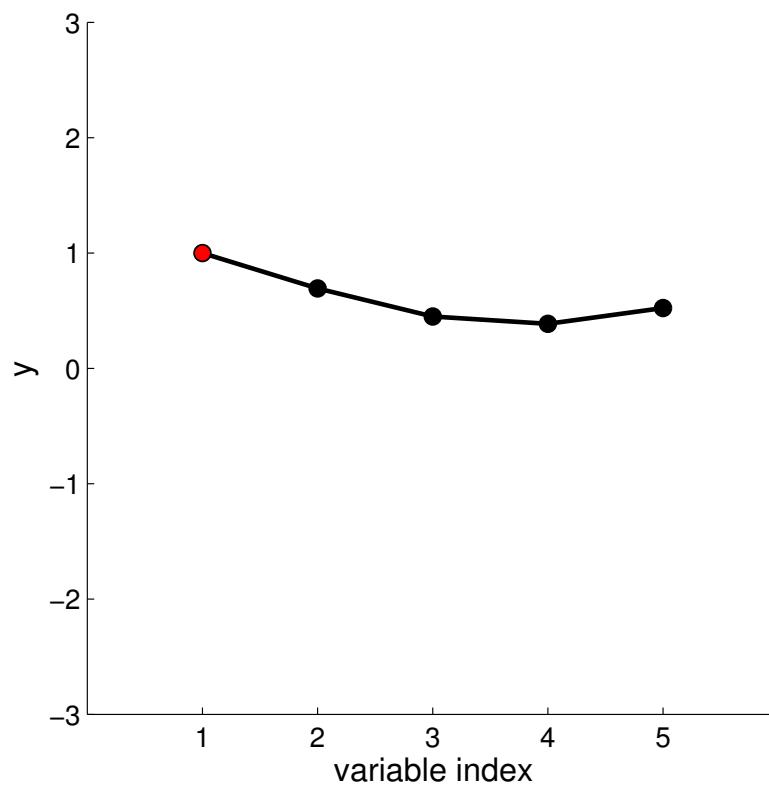
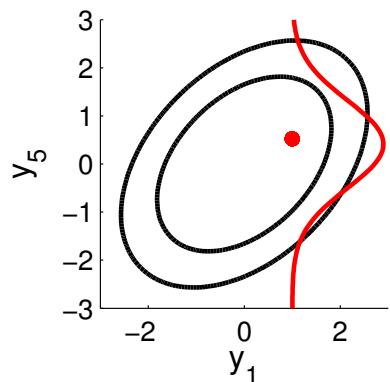
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



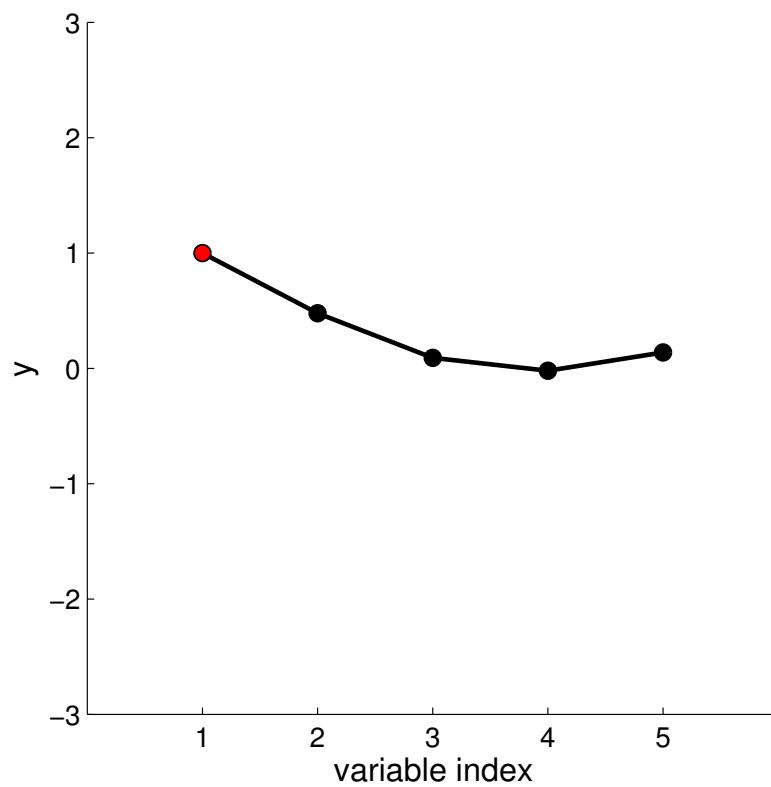
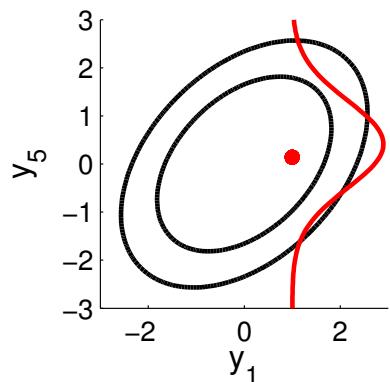
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



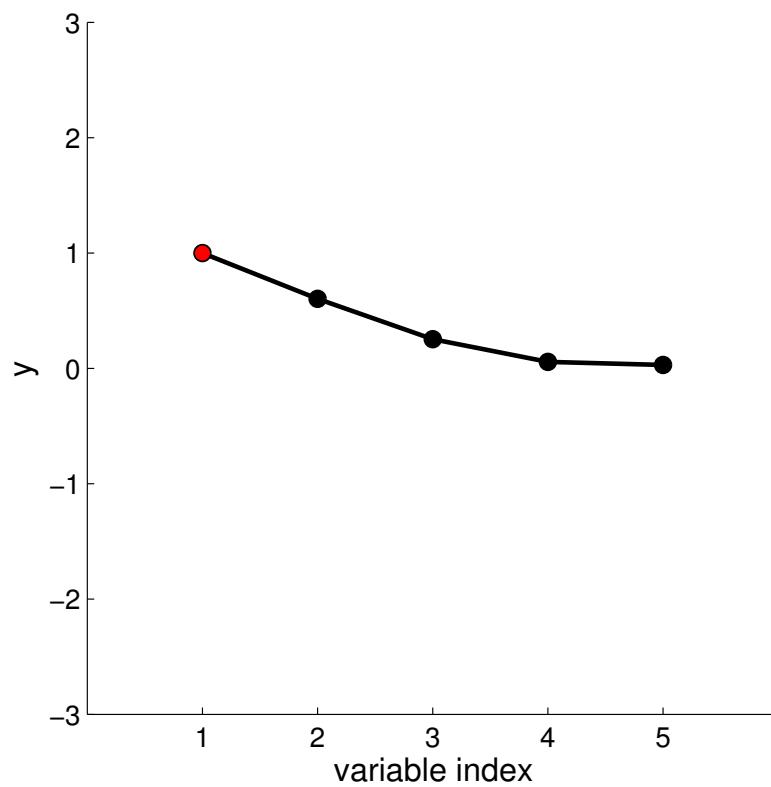
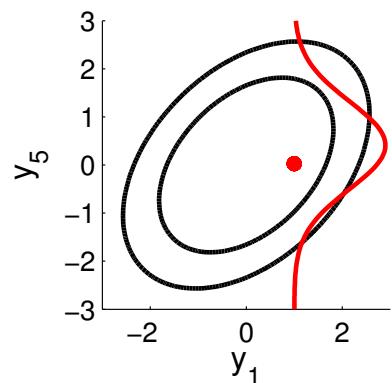
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



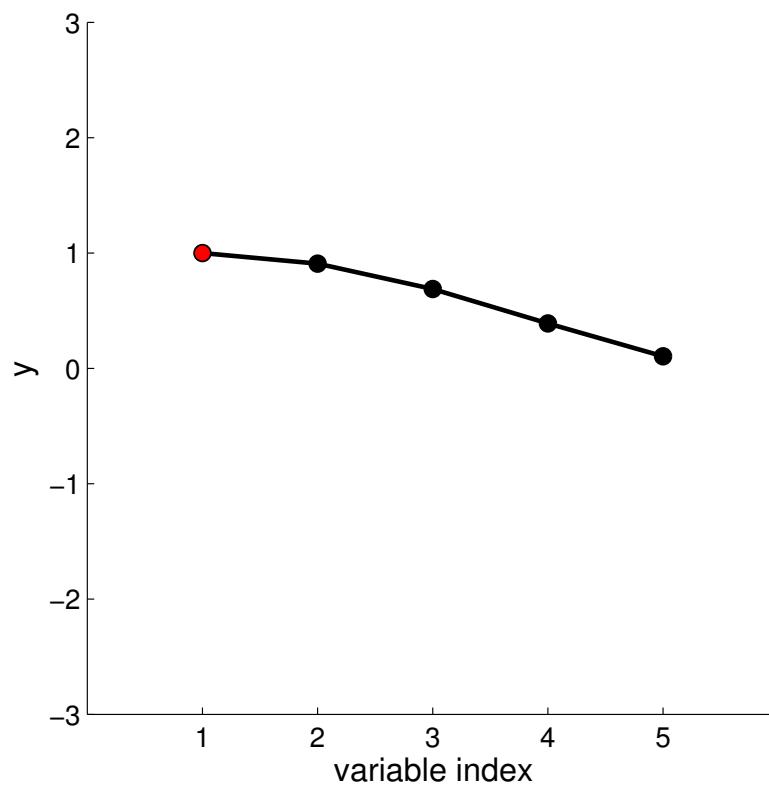
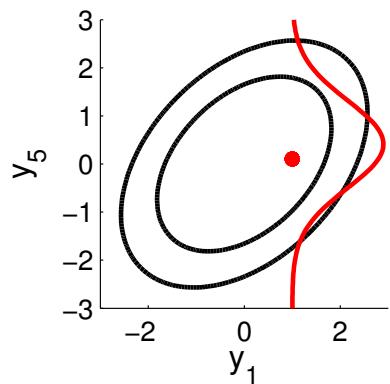
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



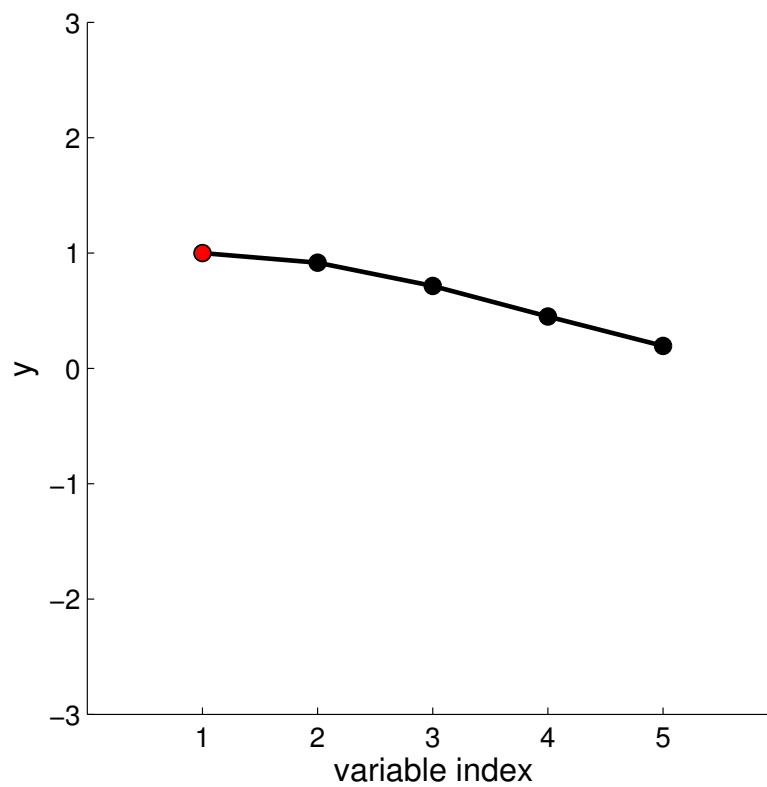
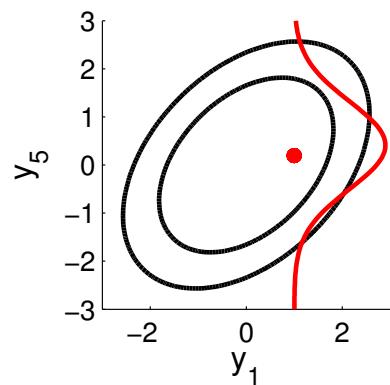
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



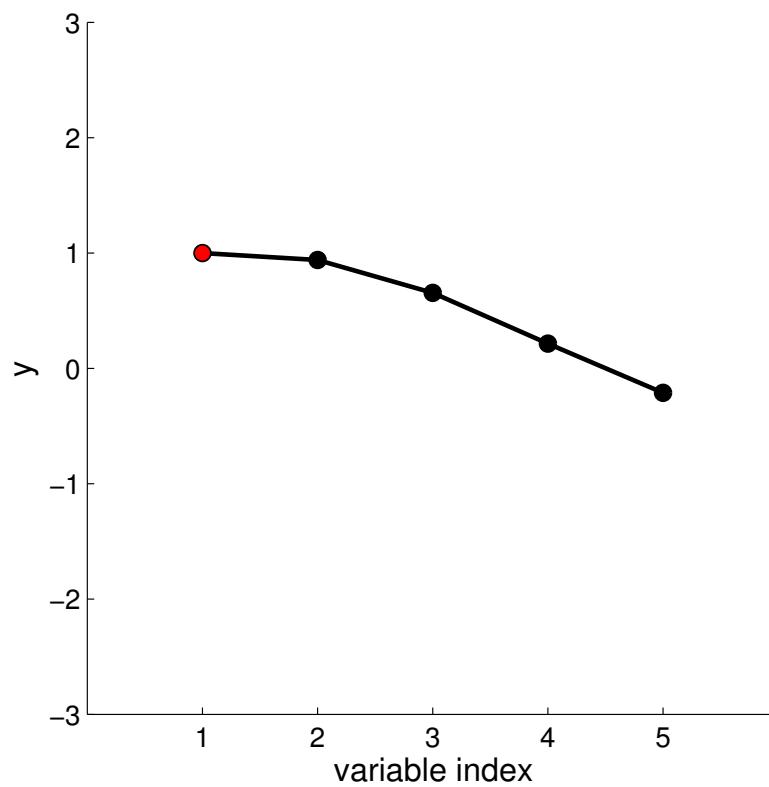
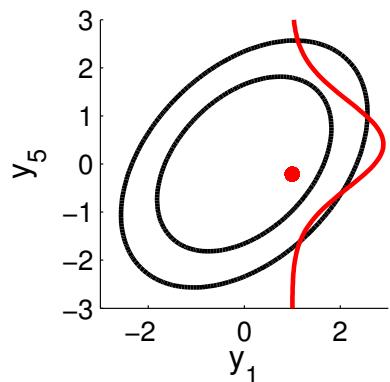
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



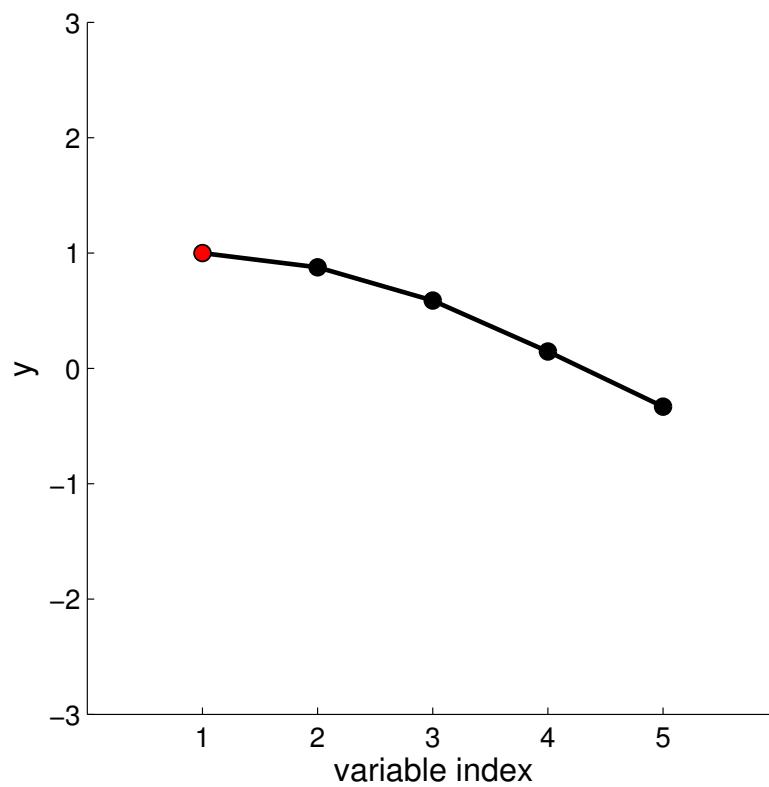
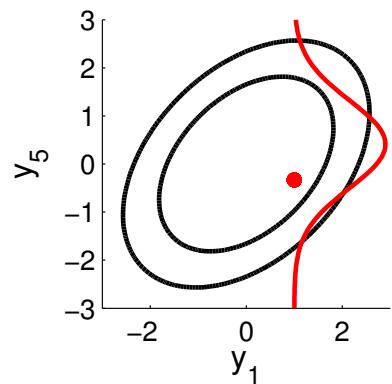
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



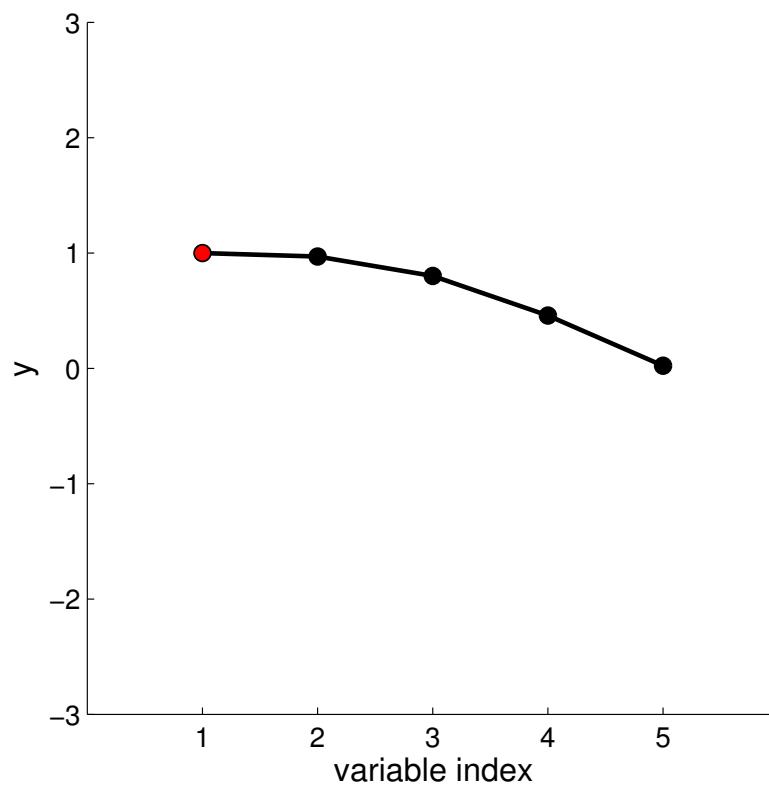
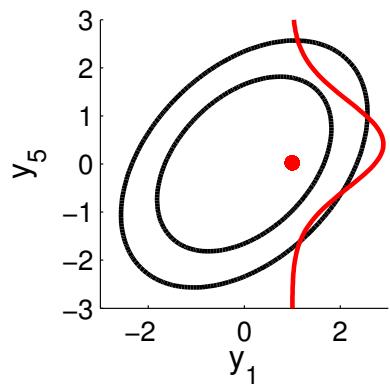
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



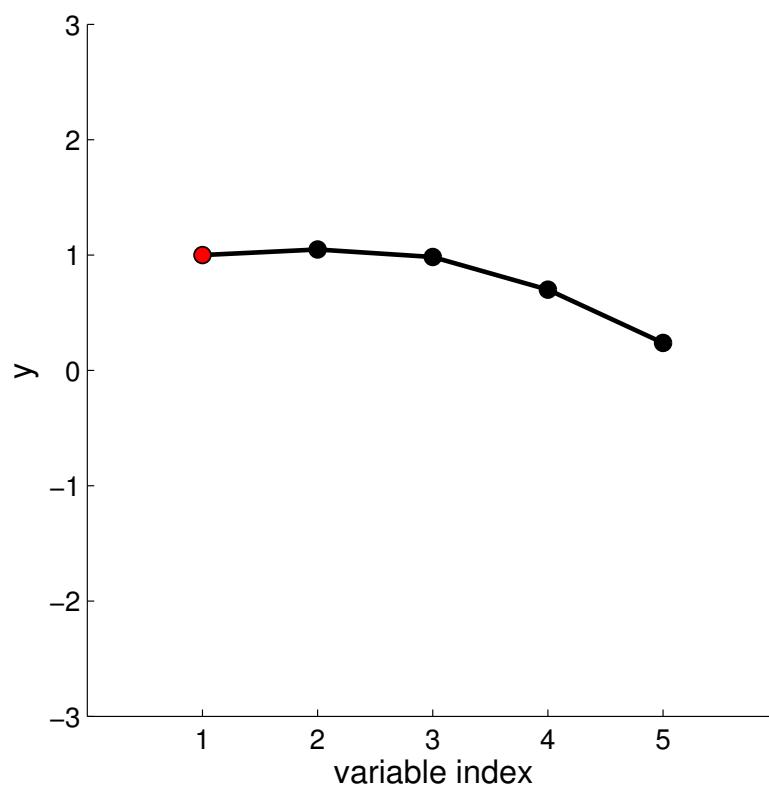
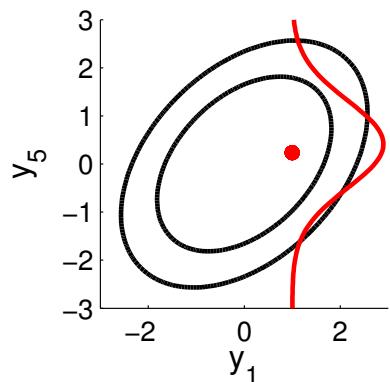
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



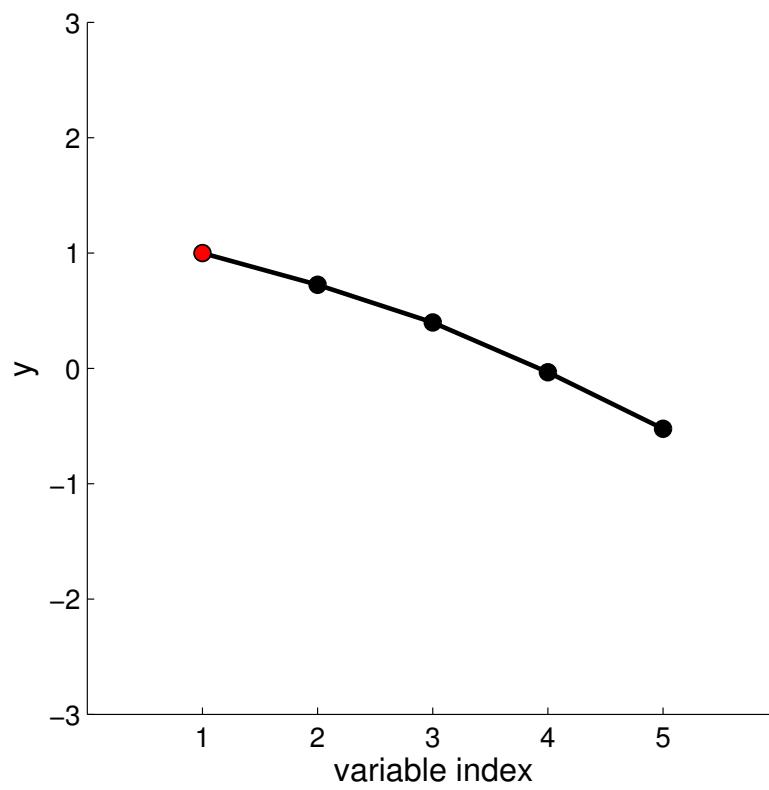
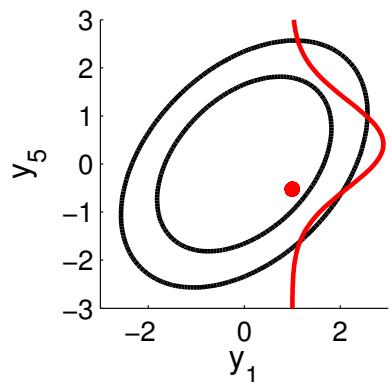
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



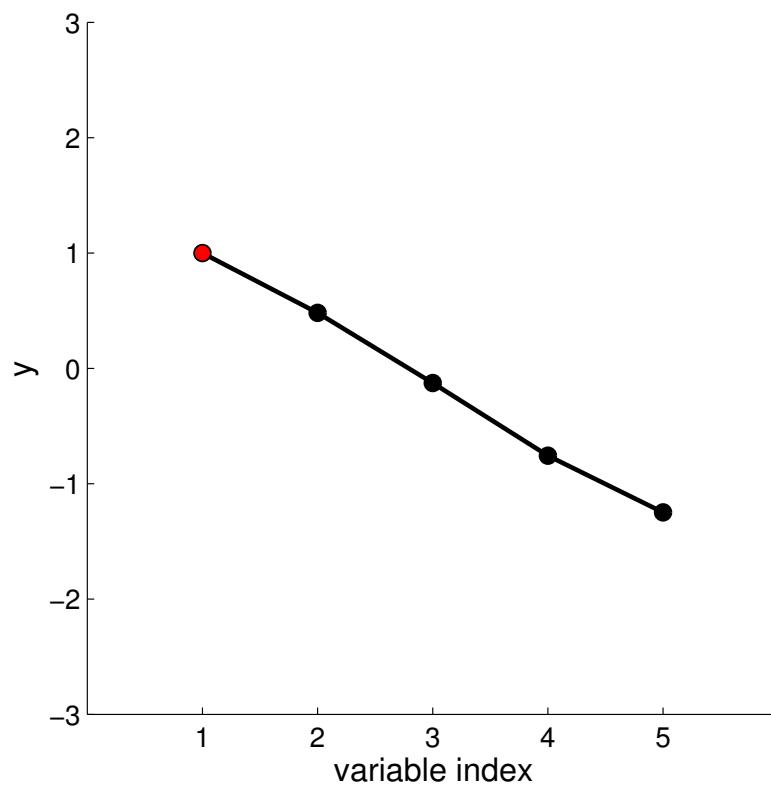
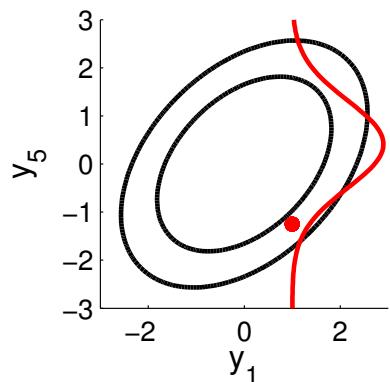
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



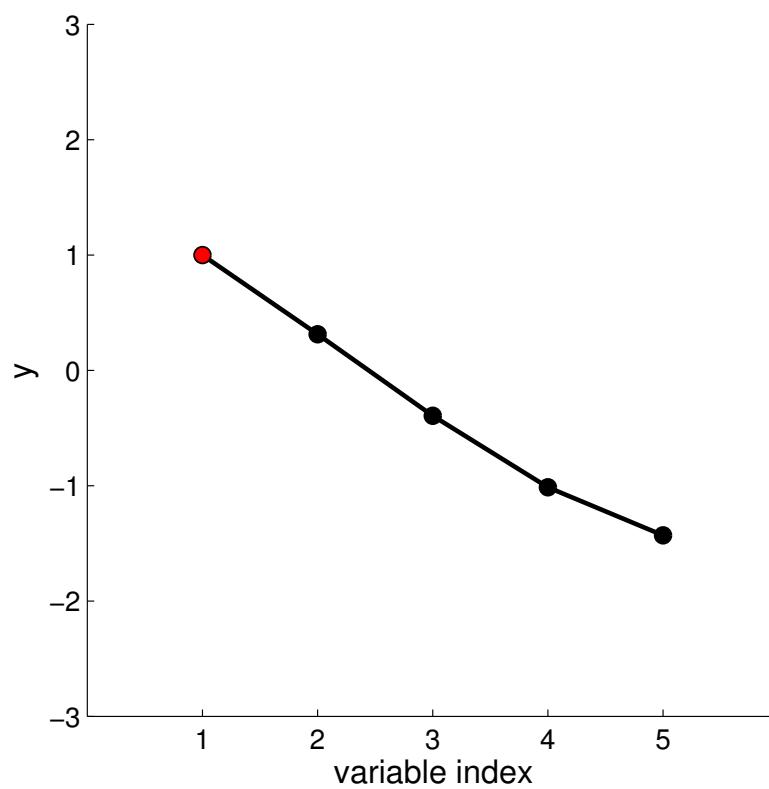
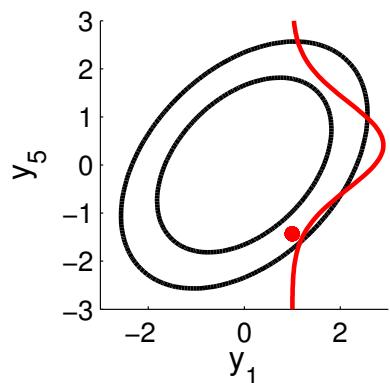
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



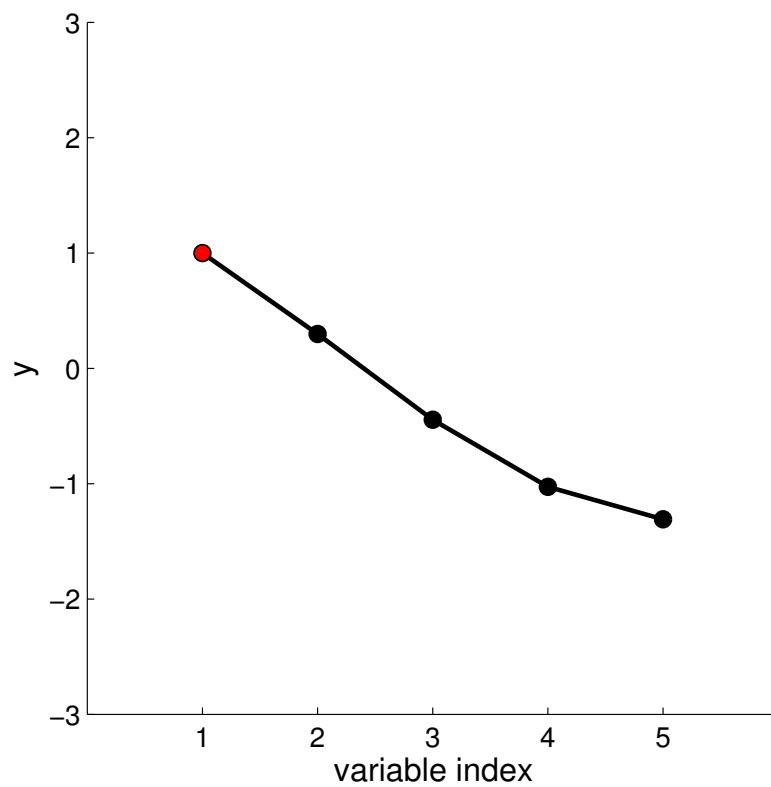
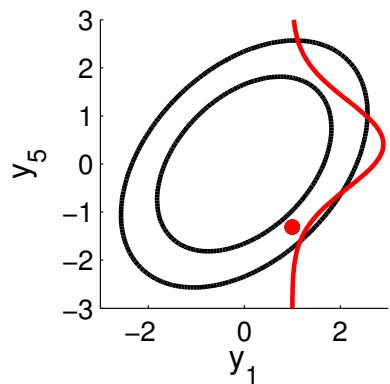
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



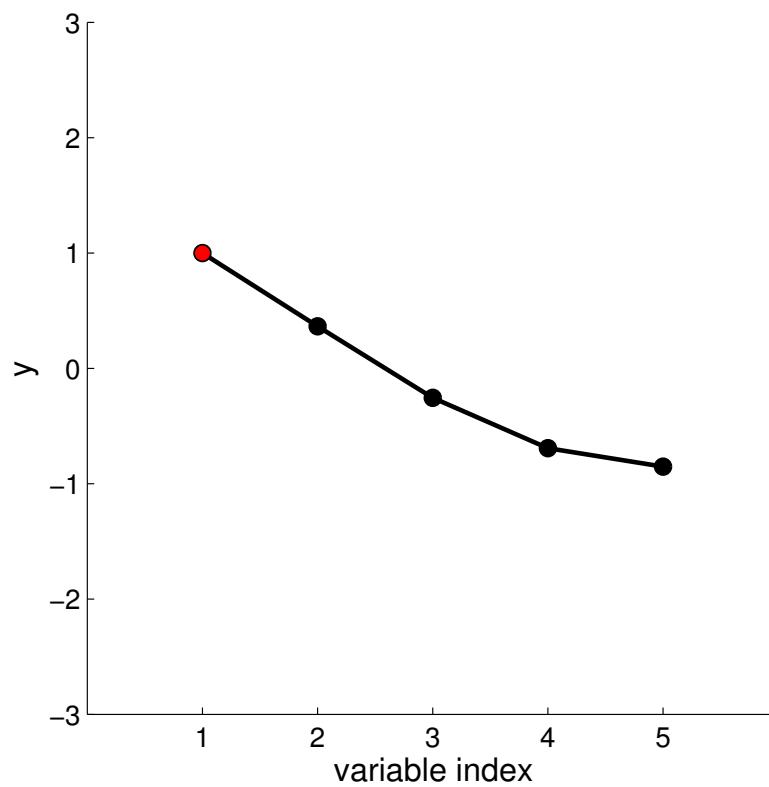
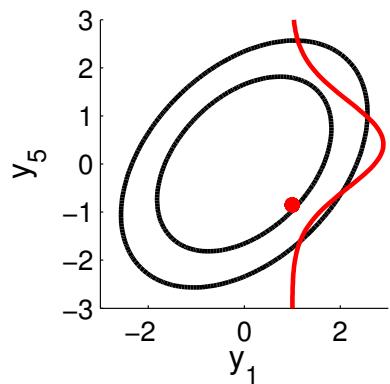
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



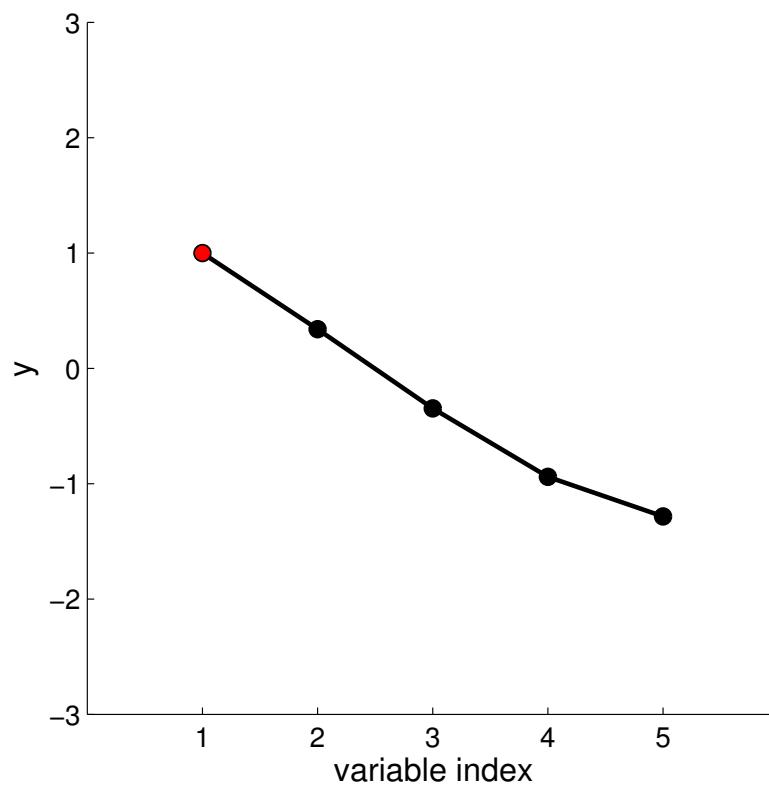
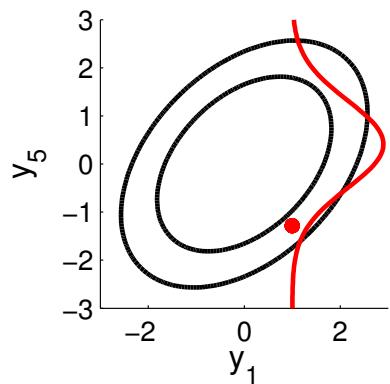
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New visualisation



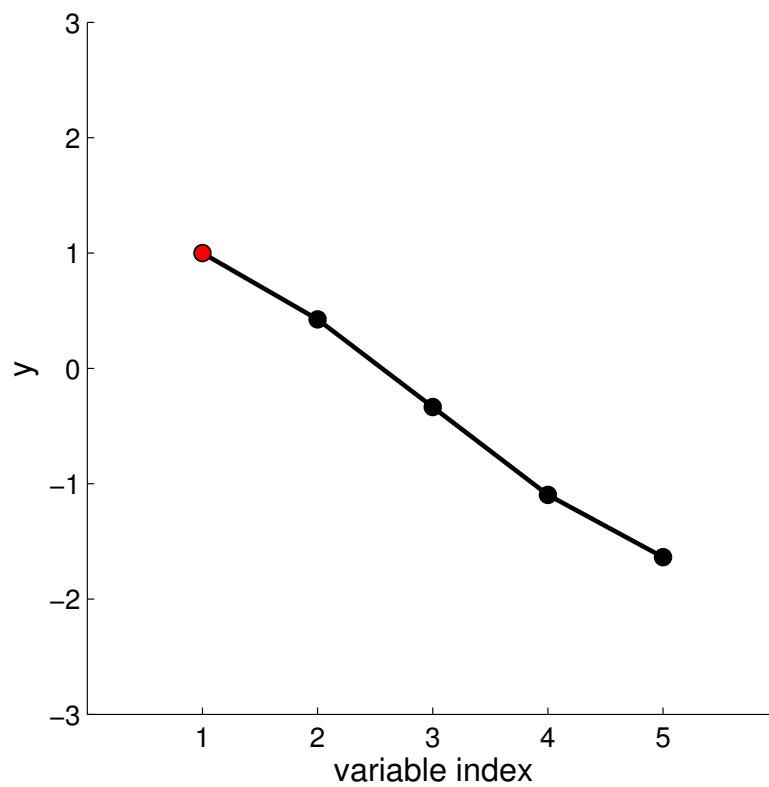
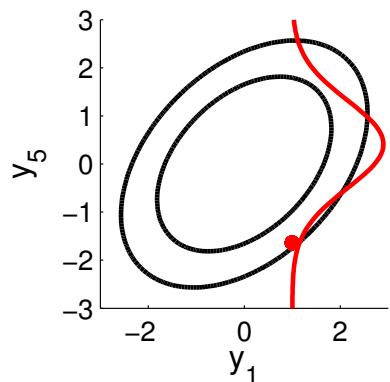
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New visualisation



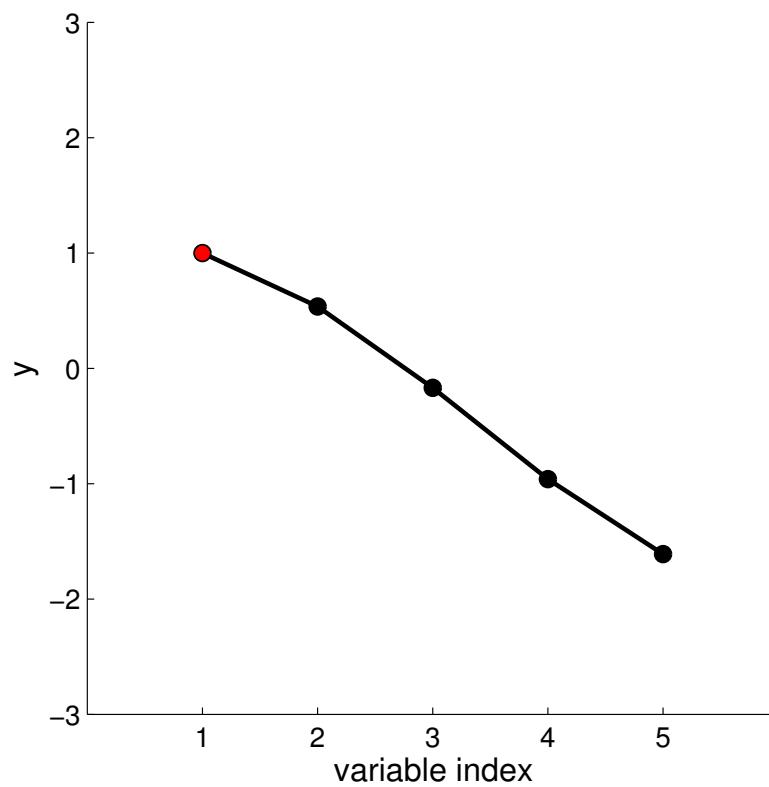
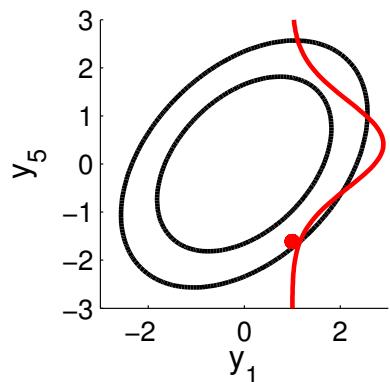
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation



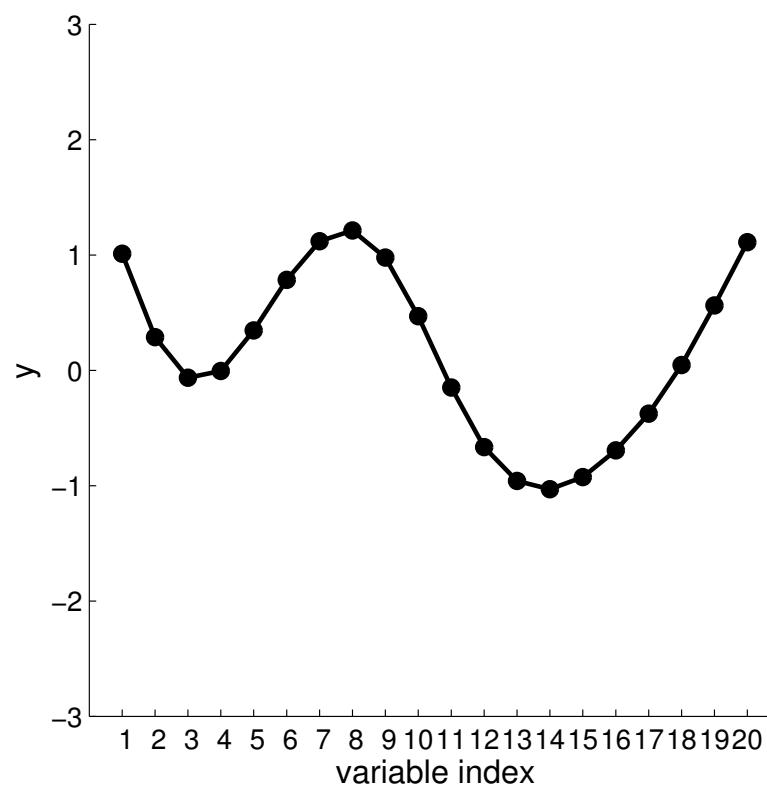
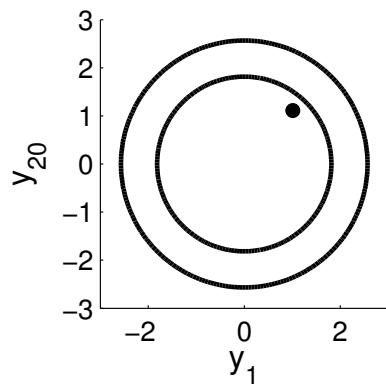
$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

New visualisation

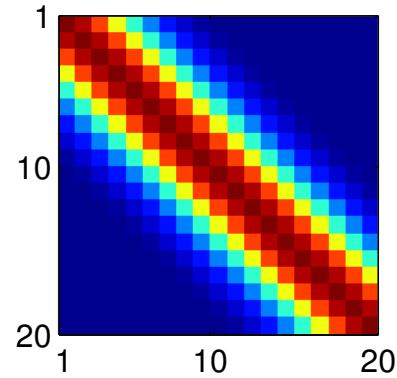


$$\Sigma = \begin{bmatrix} 1 & .9 & .8 & .6 & .4 \\ .9 & 1 & .9 & .8 & .6 \\ .8 & .9 & 1 & .9 & .8 \\ .6 & .8 & .9 & 1 & .9 \\ .4 & .6 & .8 & .9 & 1 \end{bmatrix}$$

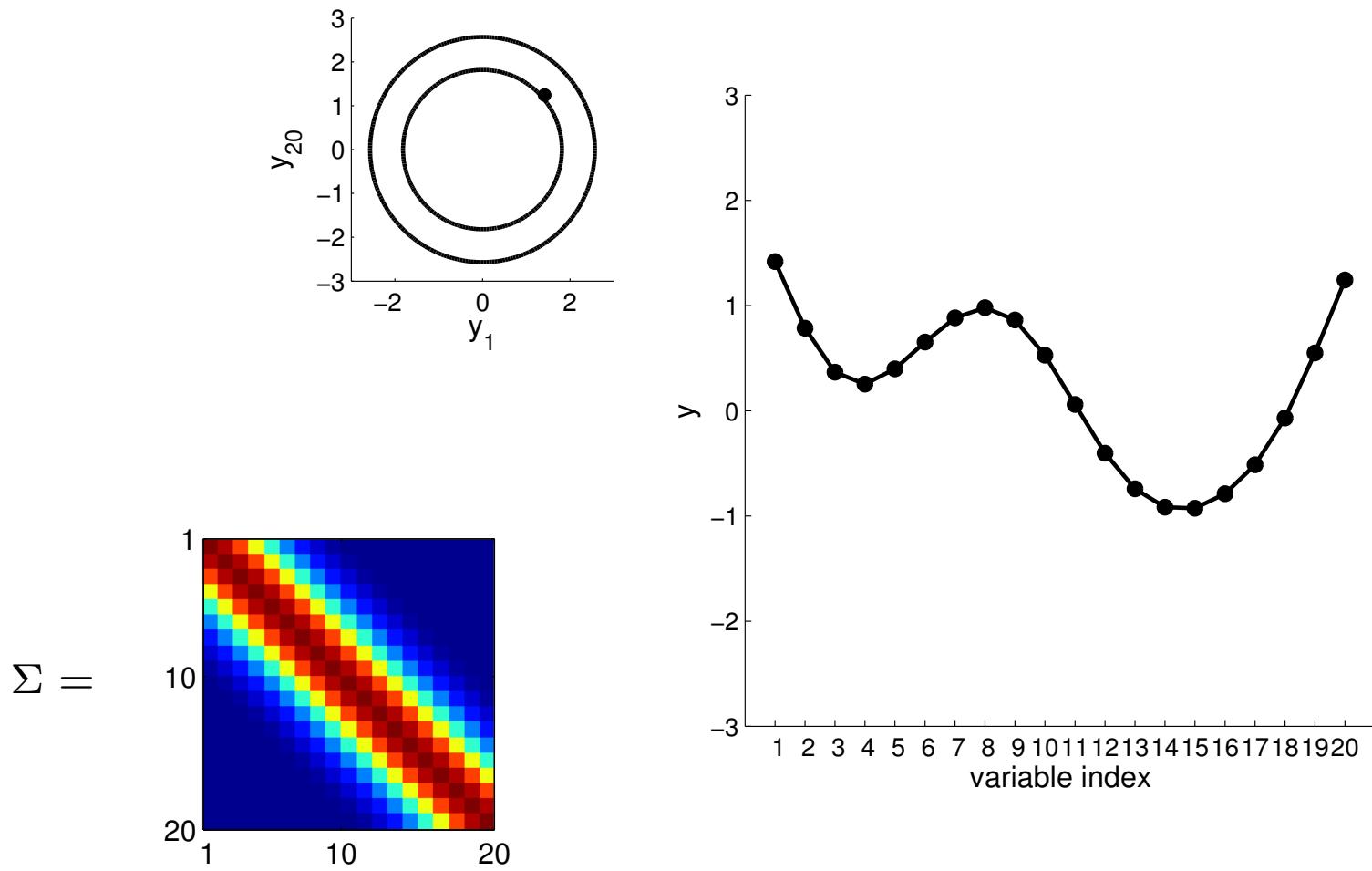
New visualisation



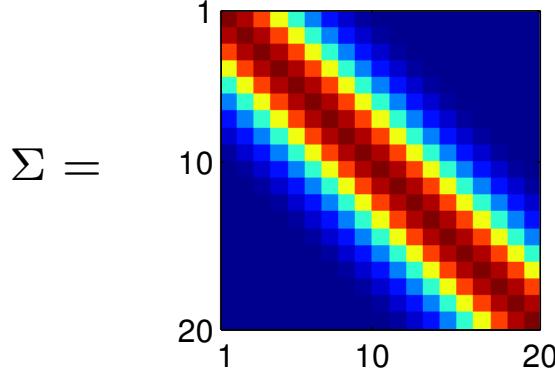
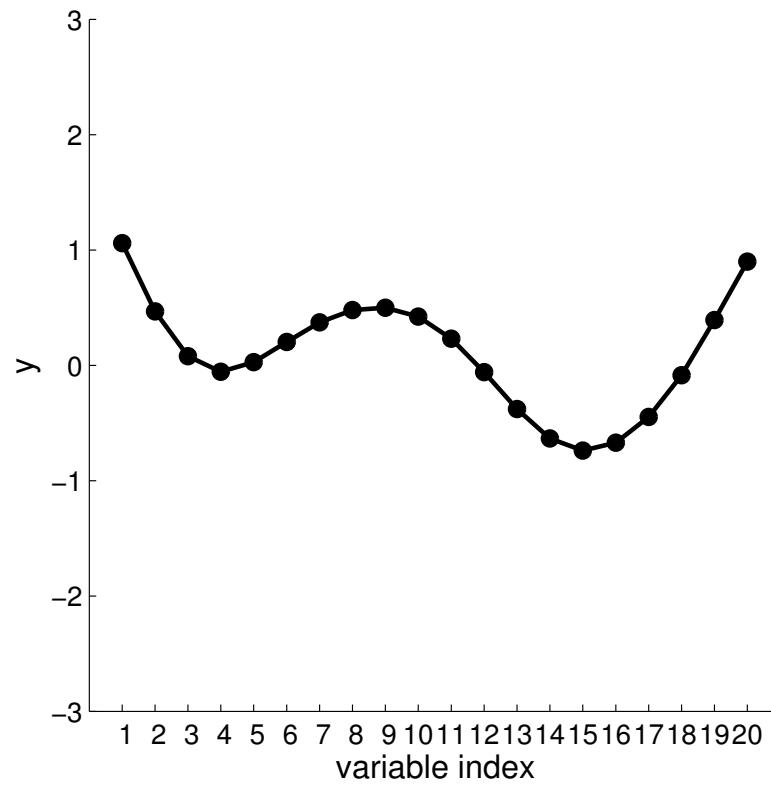
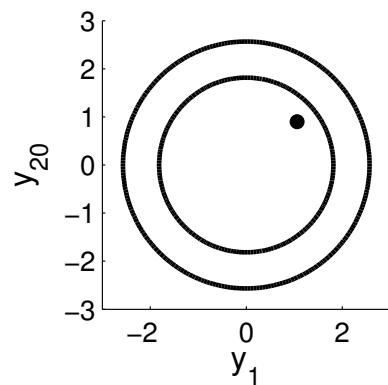
$\Sigma =$



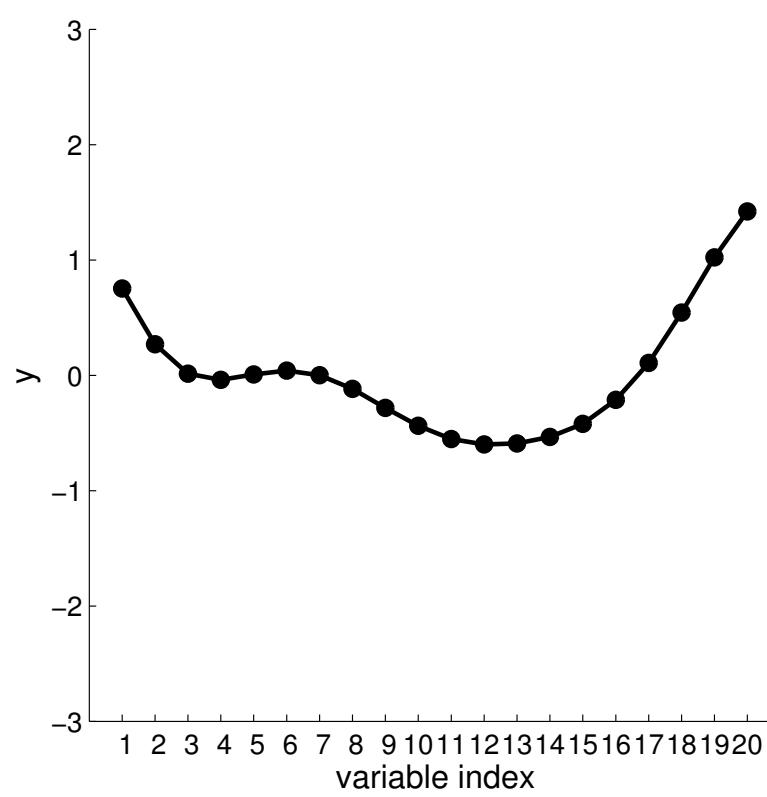
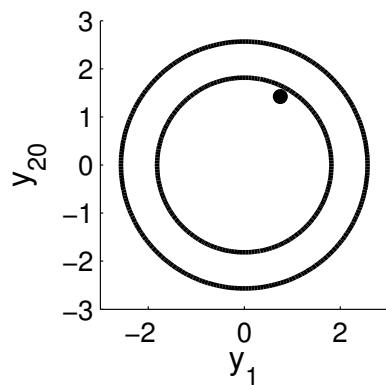
New visualisation



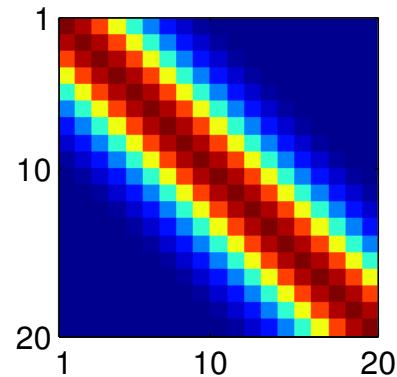
New visualisation



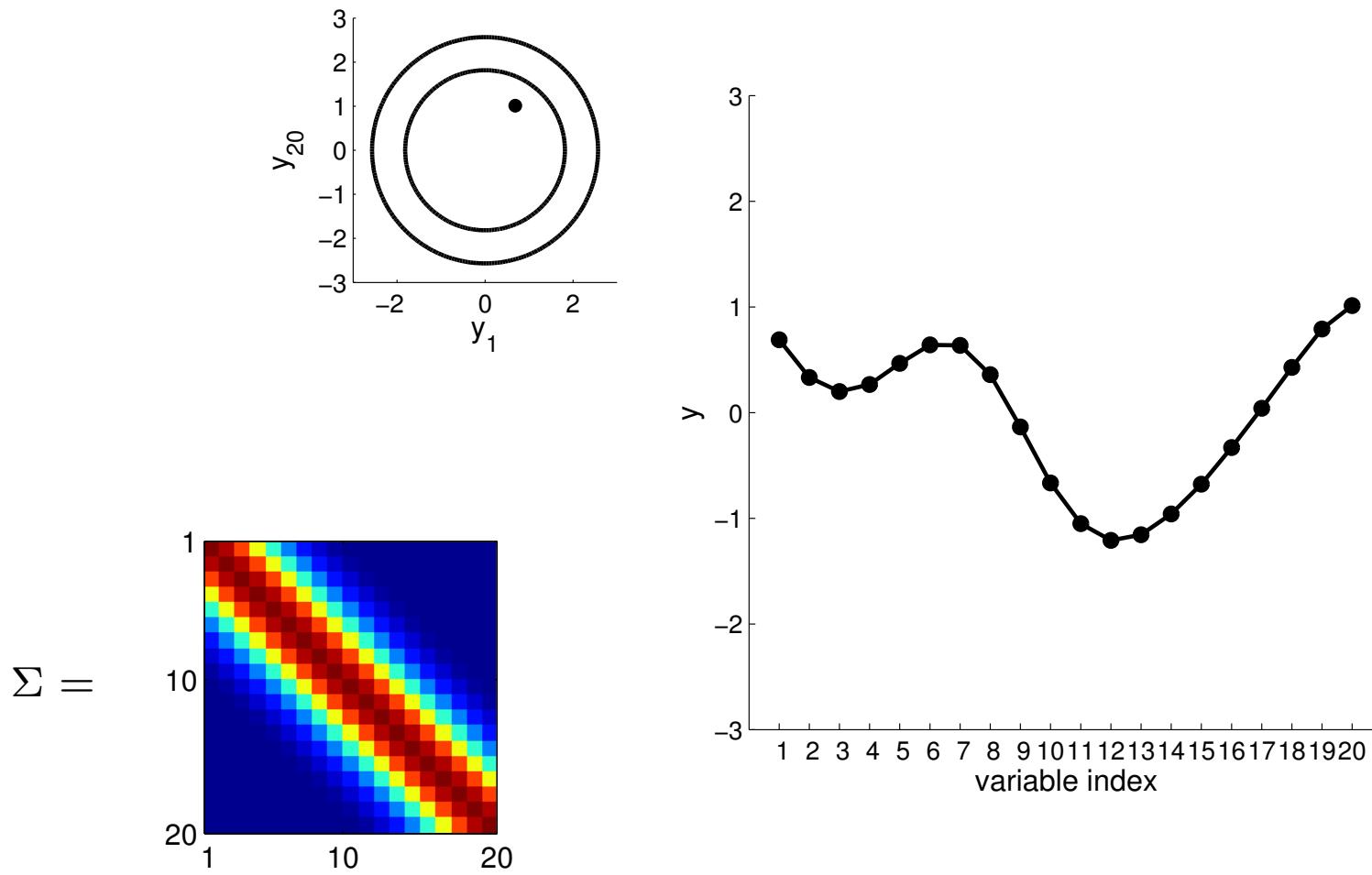
New visualisation



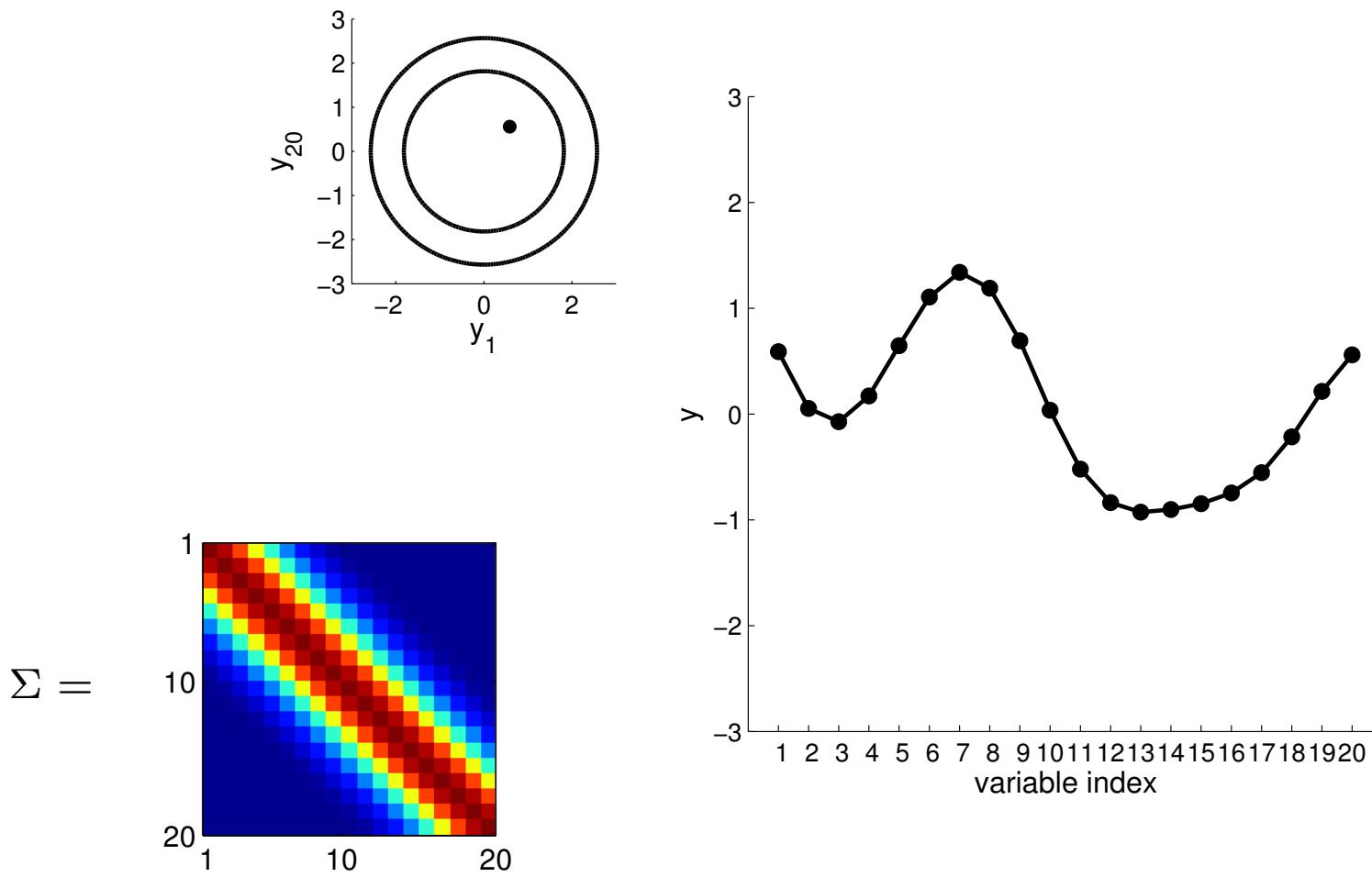
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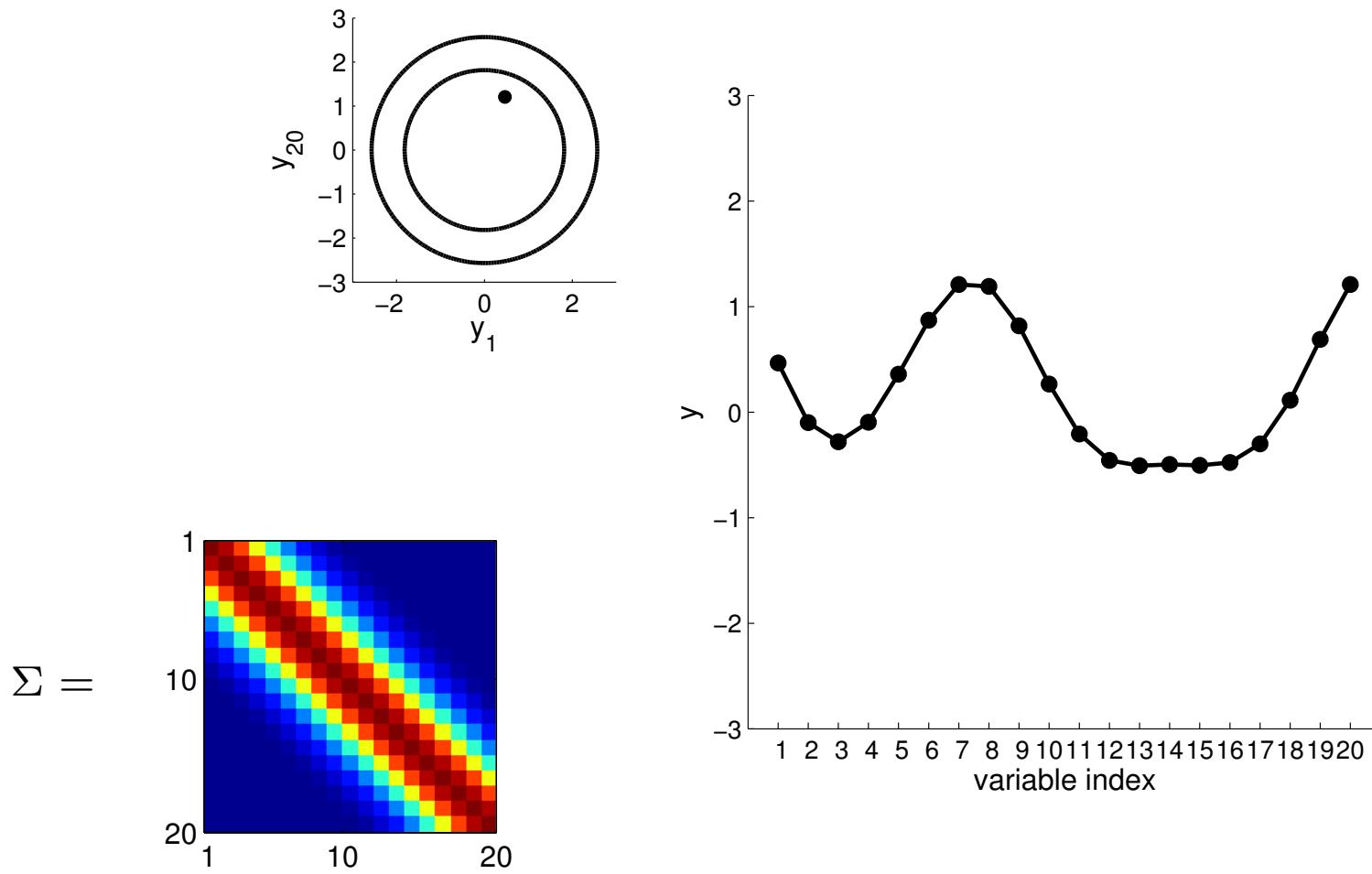
New visualisation



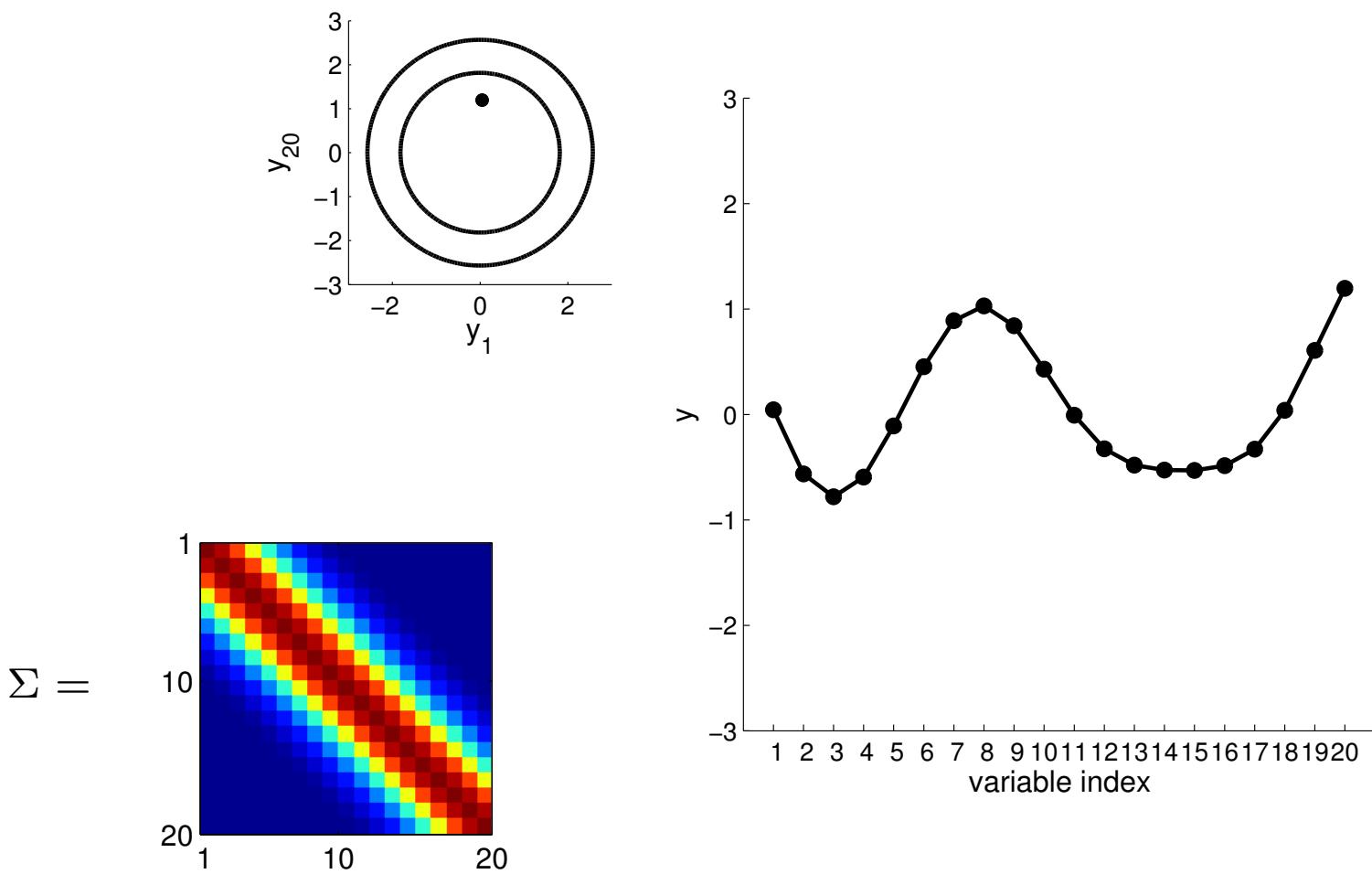
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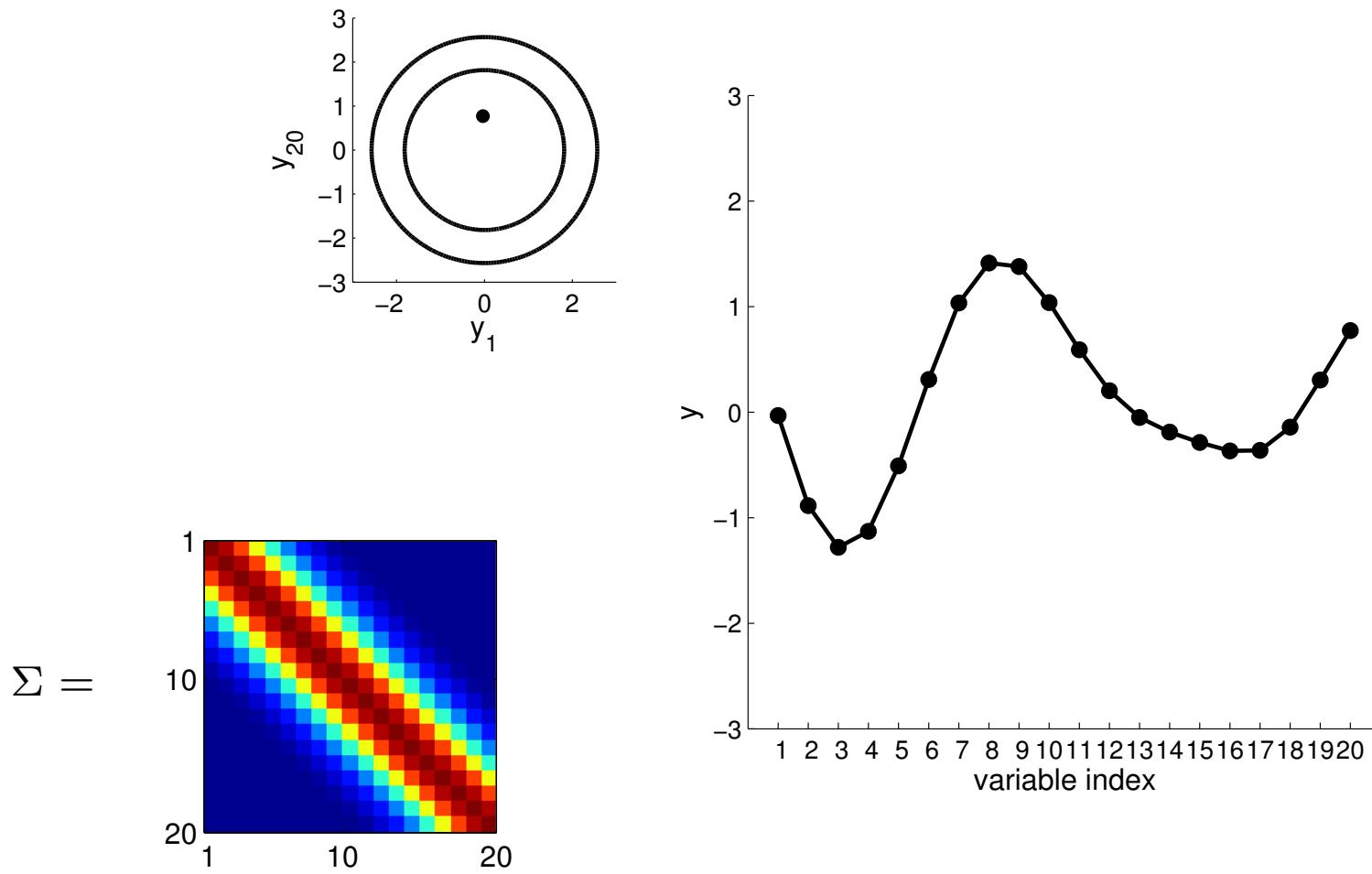
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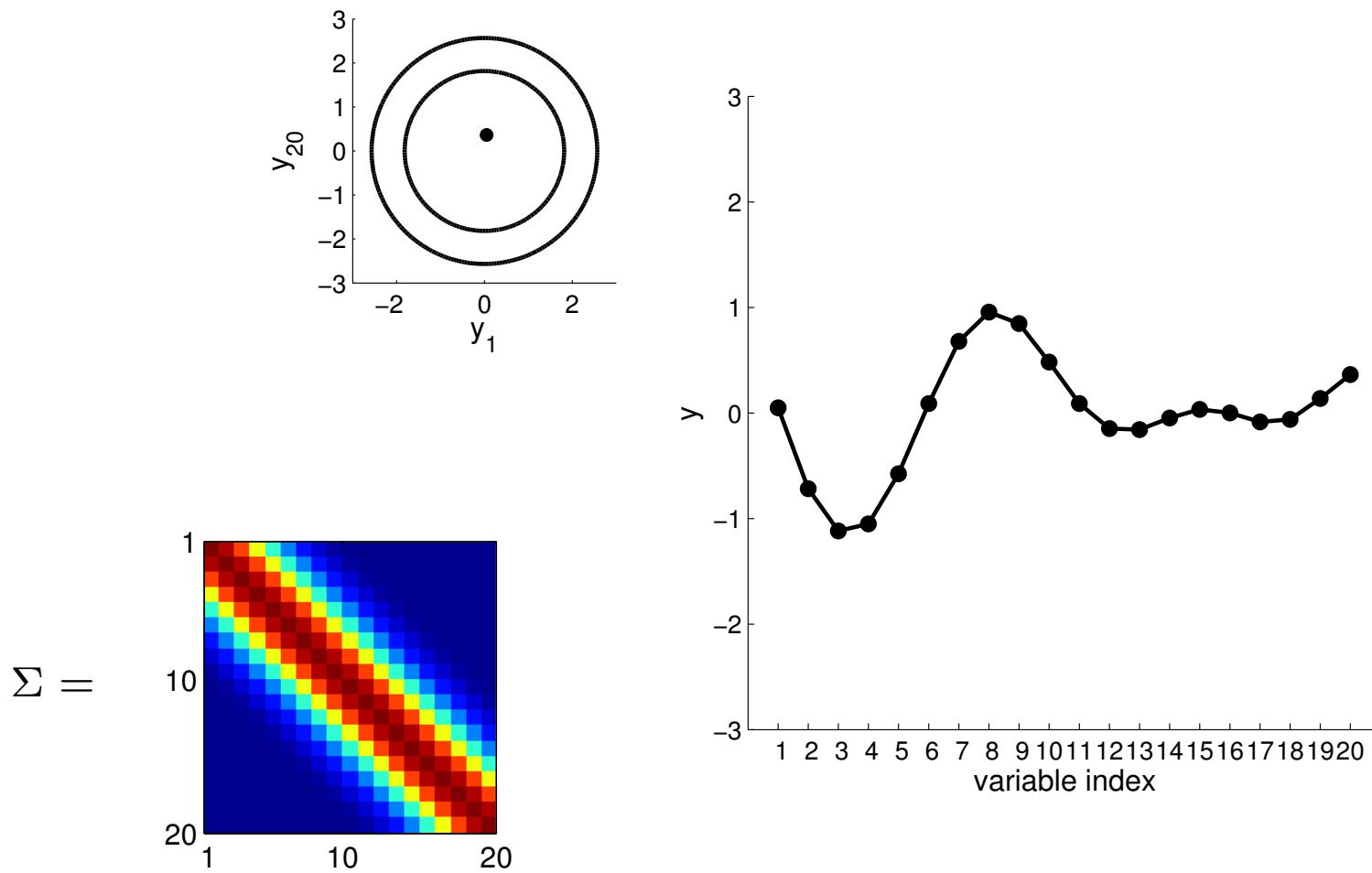
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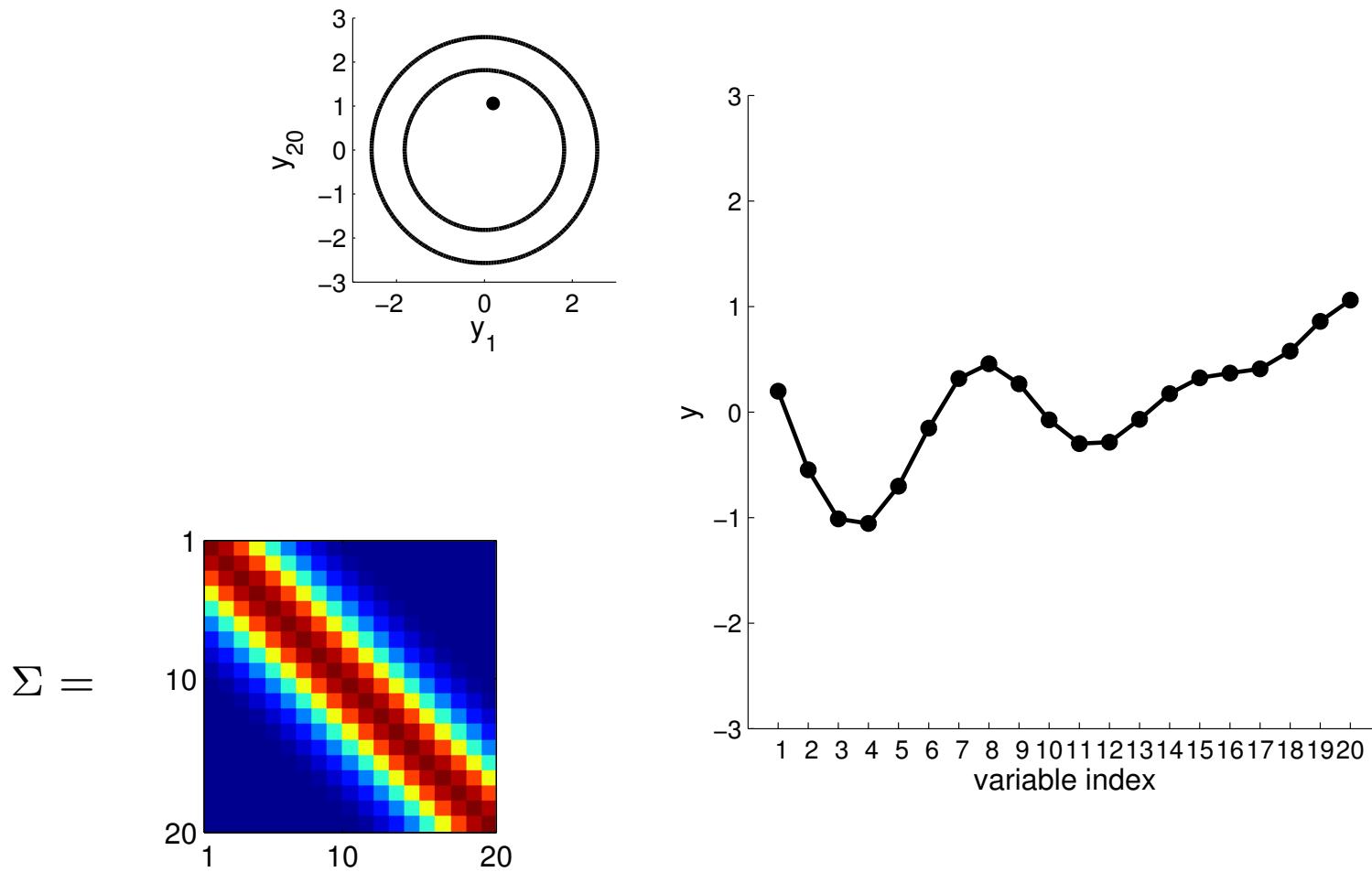
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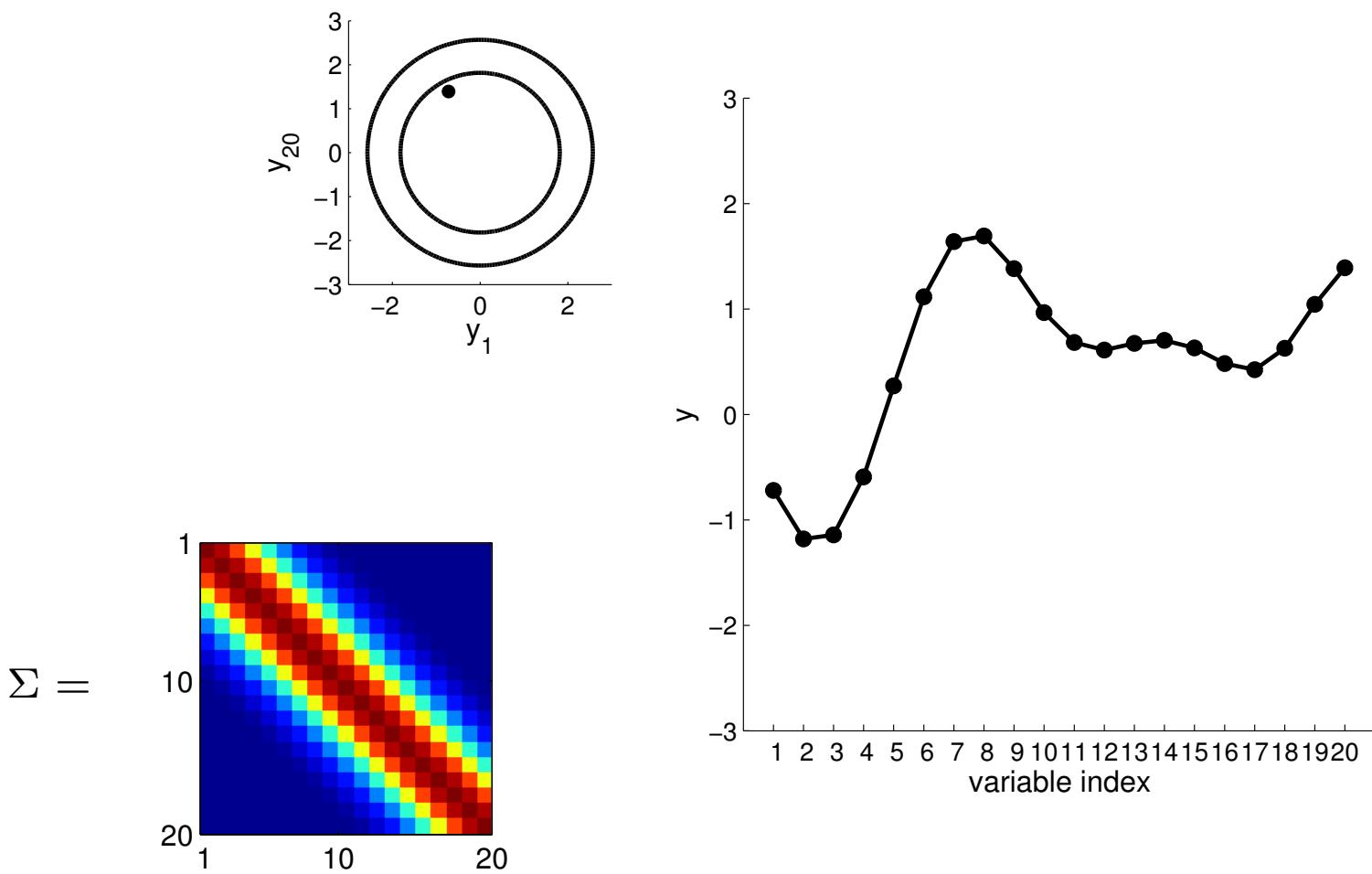
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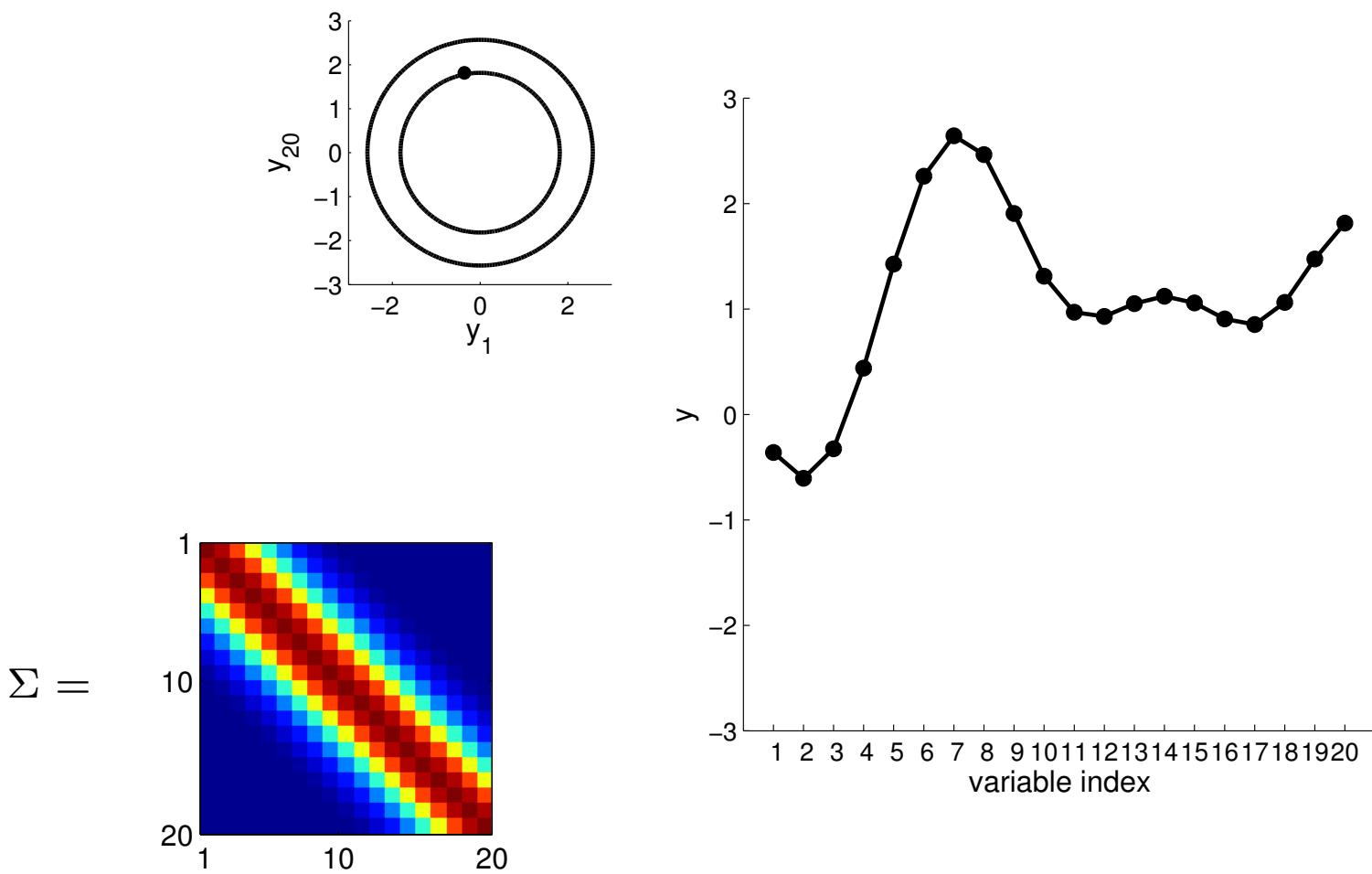
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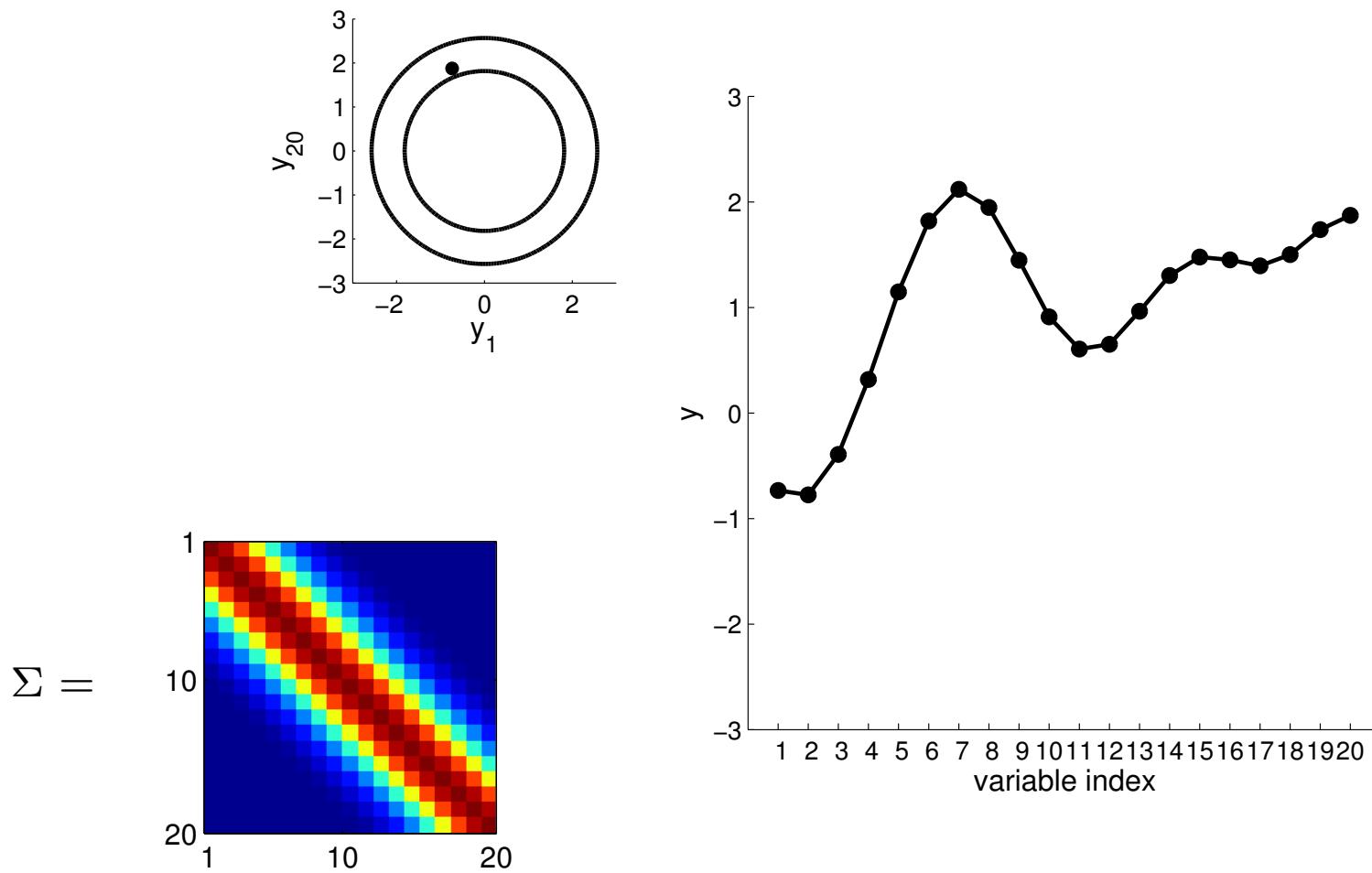
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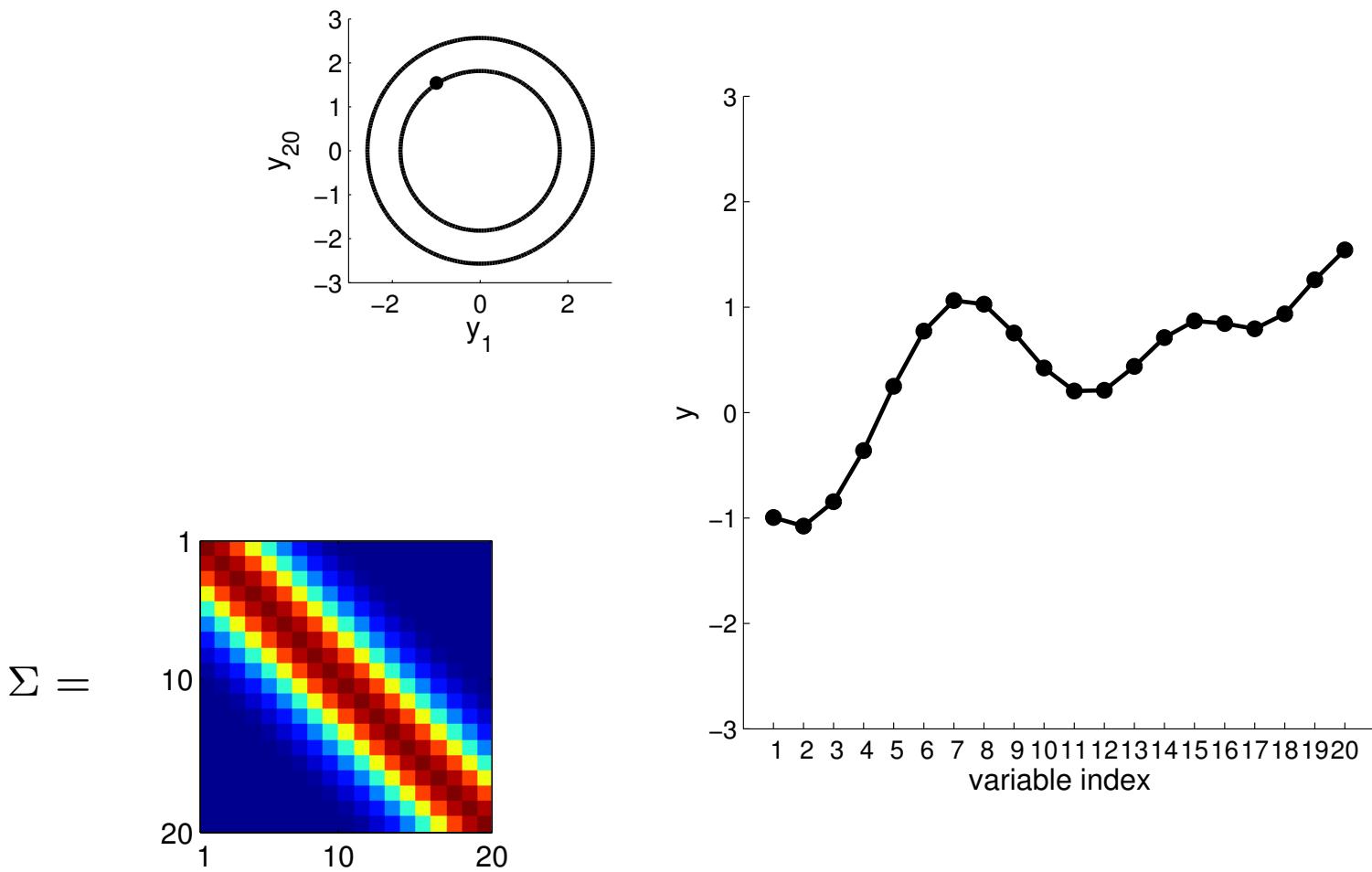
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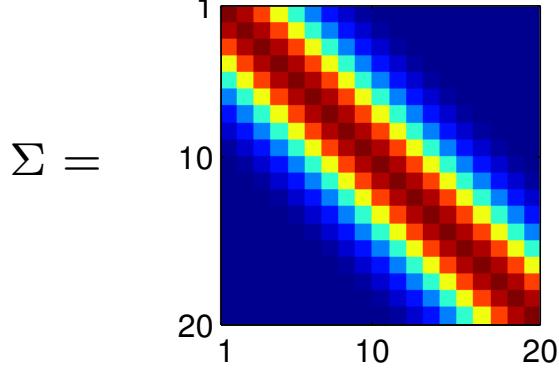
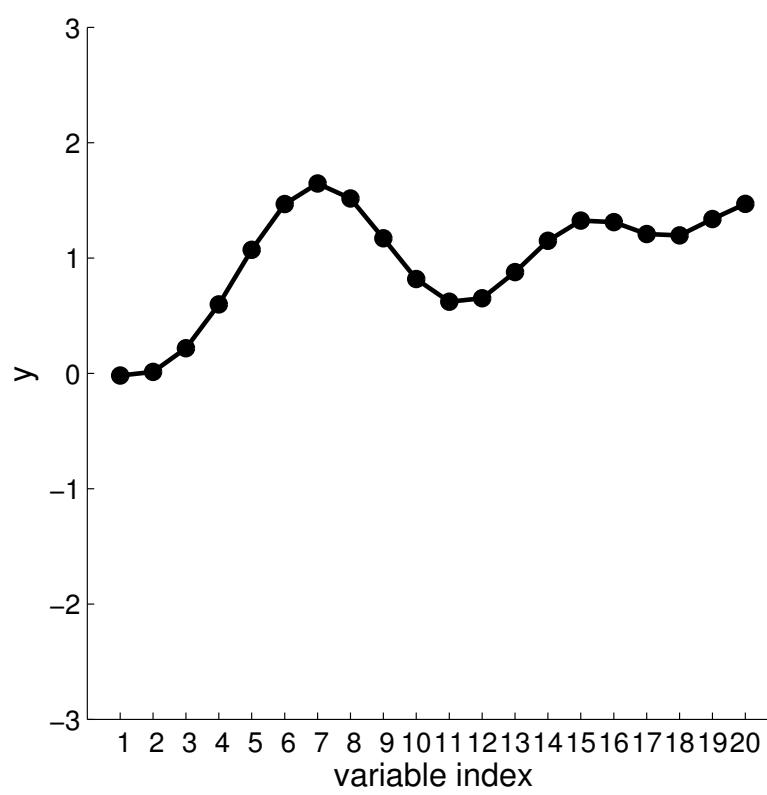
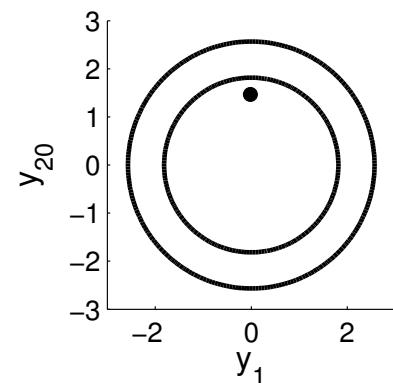
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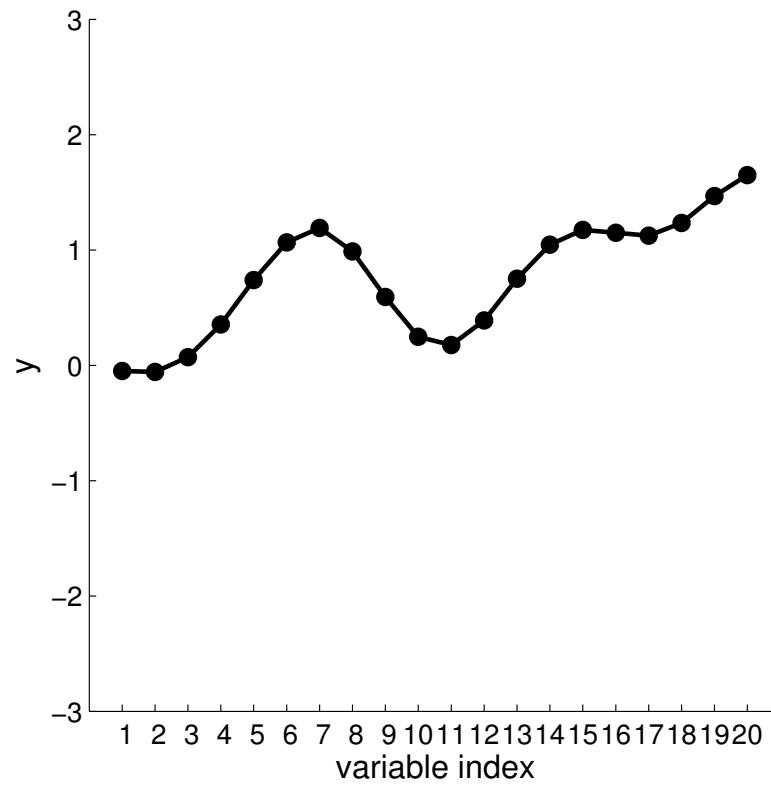
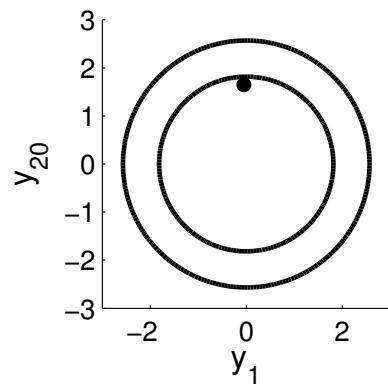
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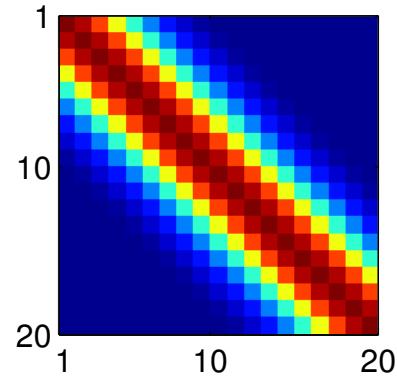
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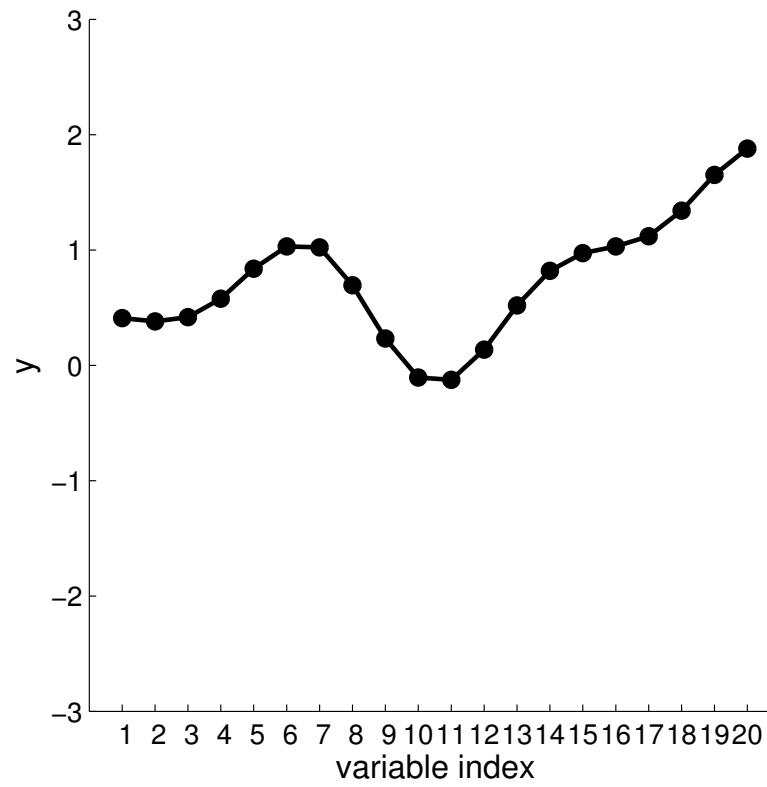
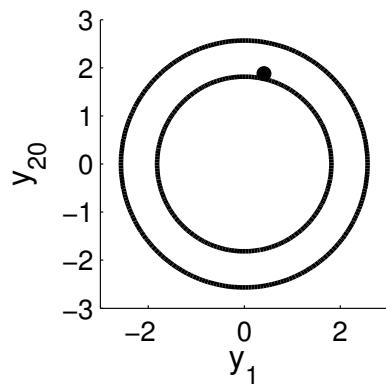
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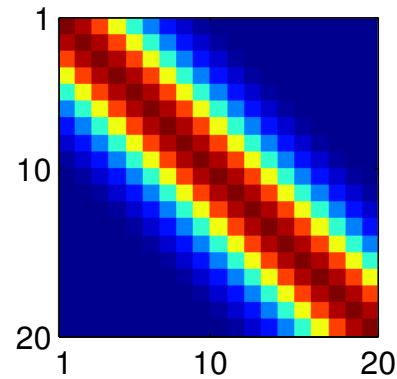
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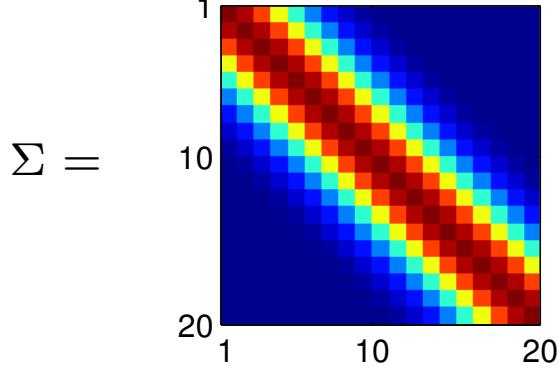
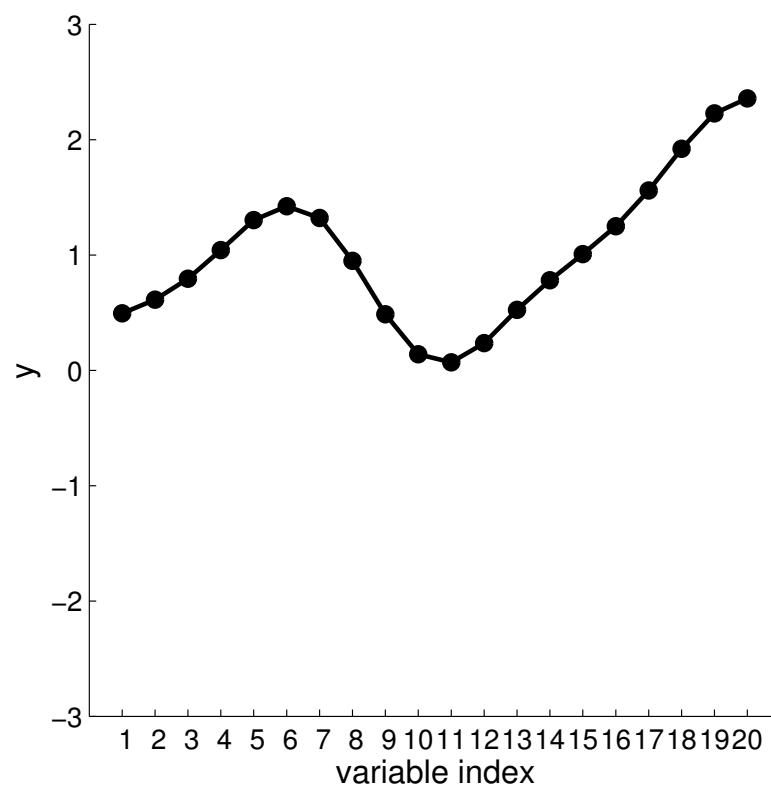
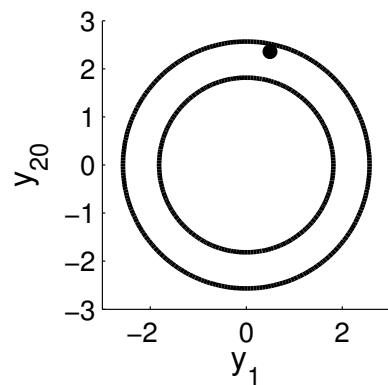
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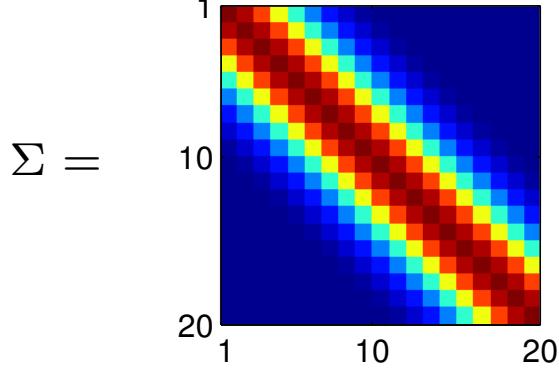
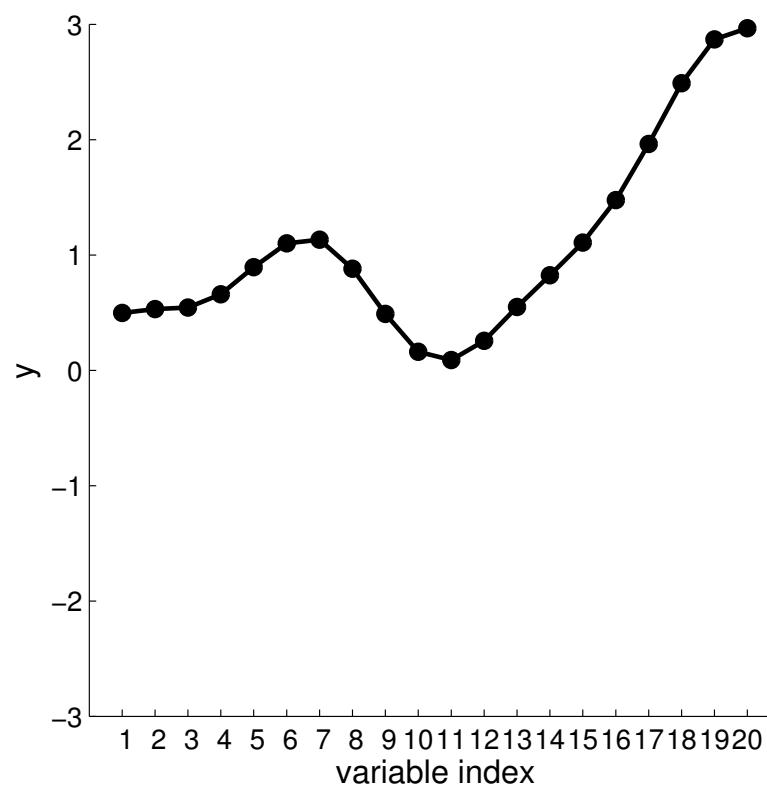
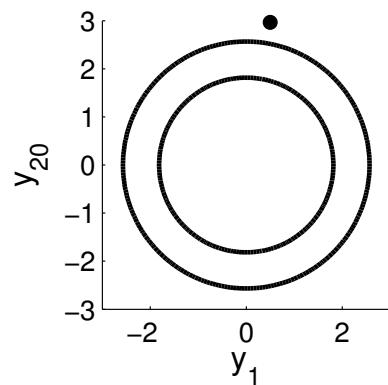
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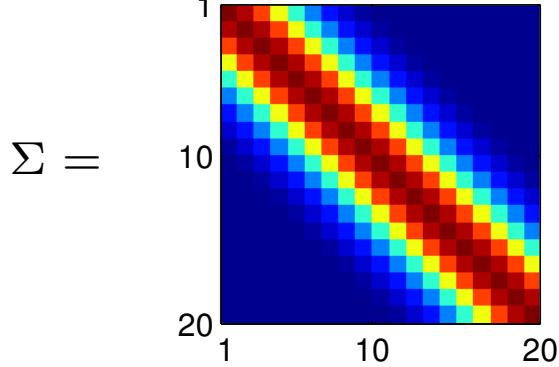
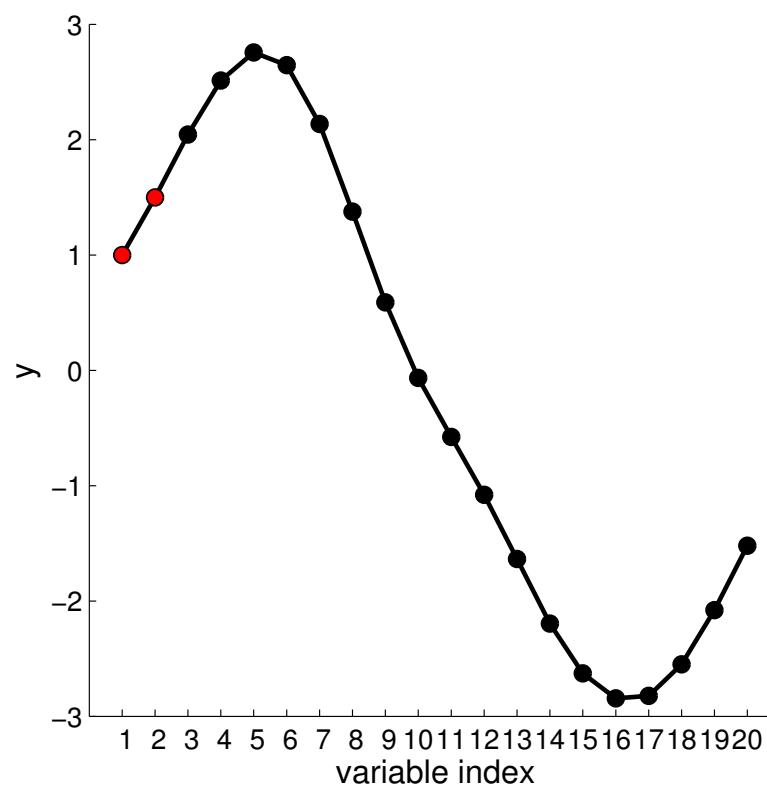
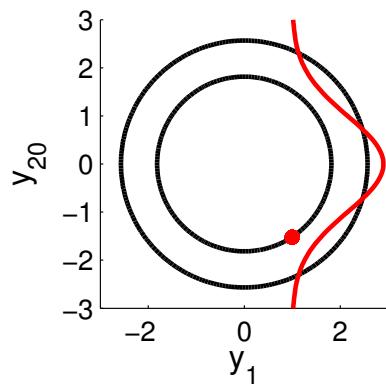
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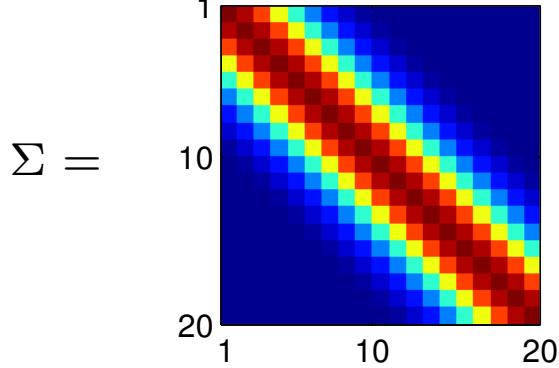
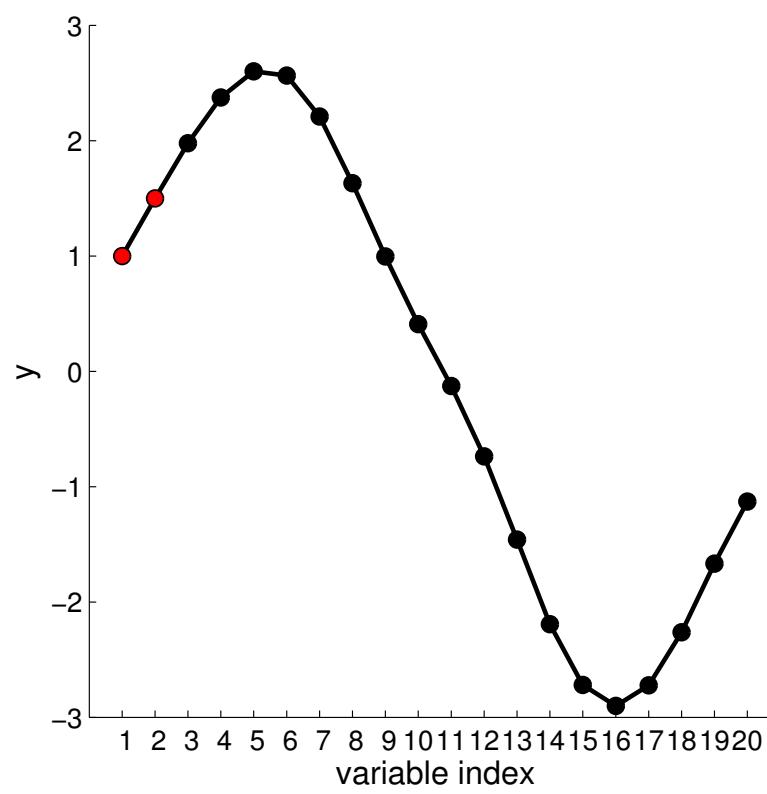
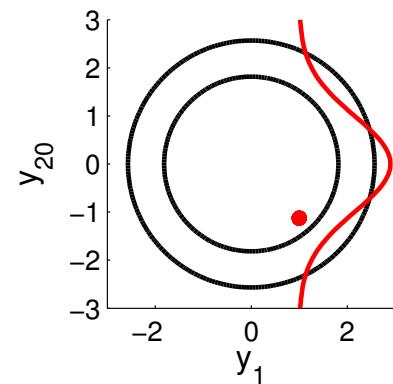
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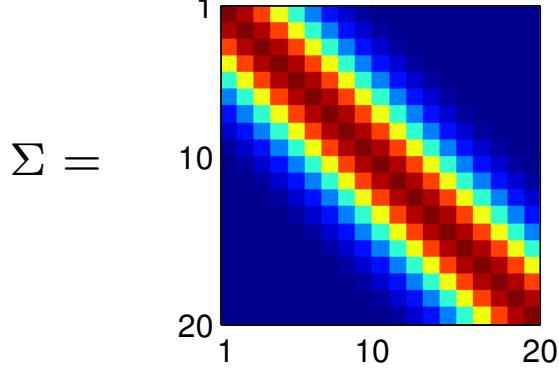
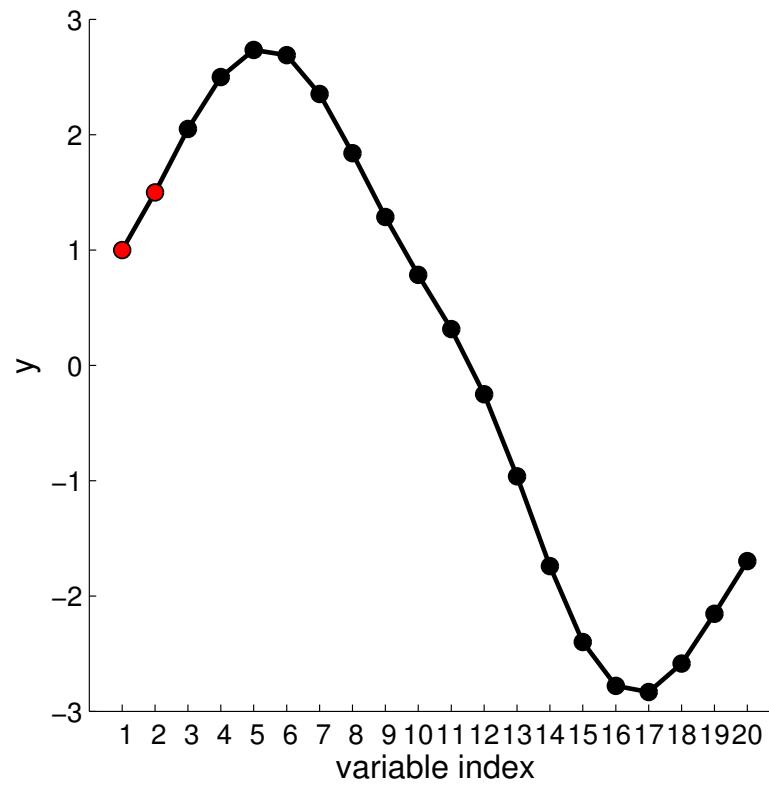
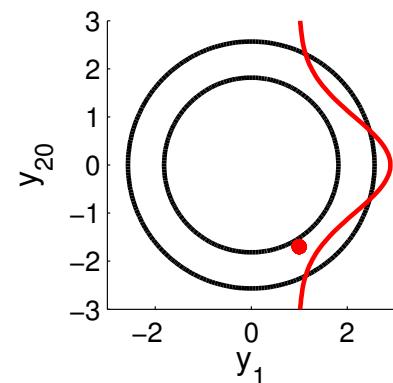
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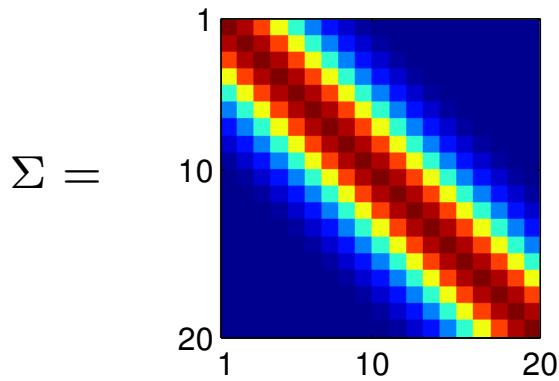
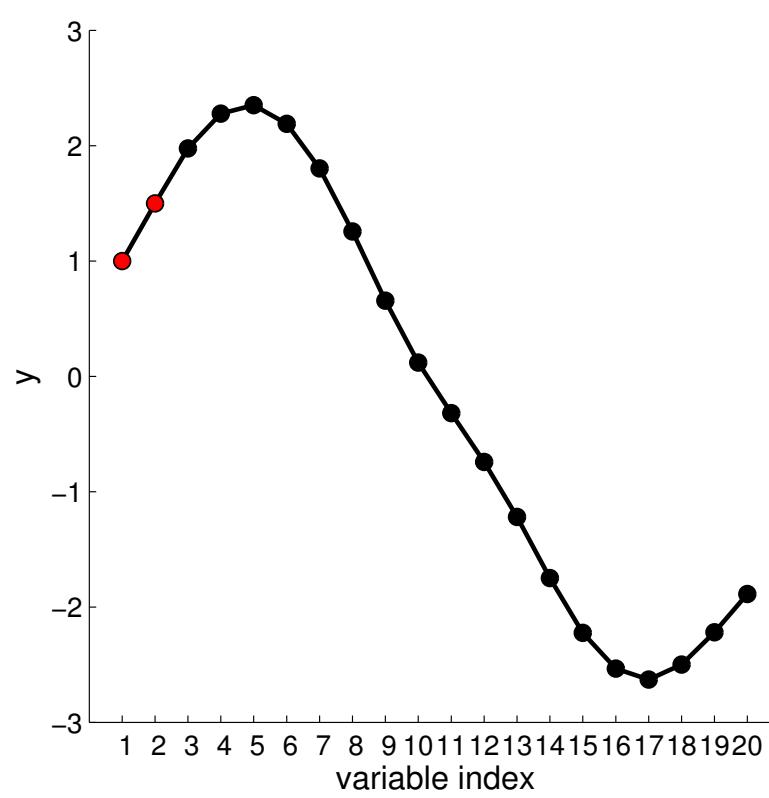
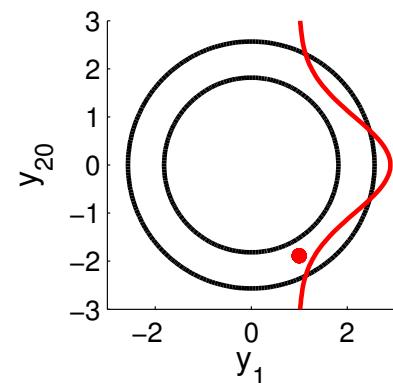
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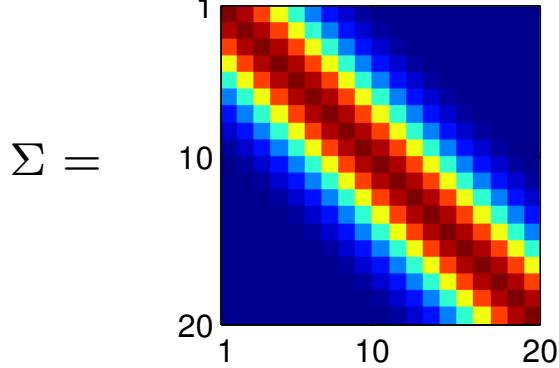
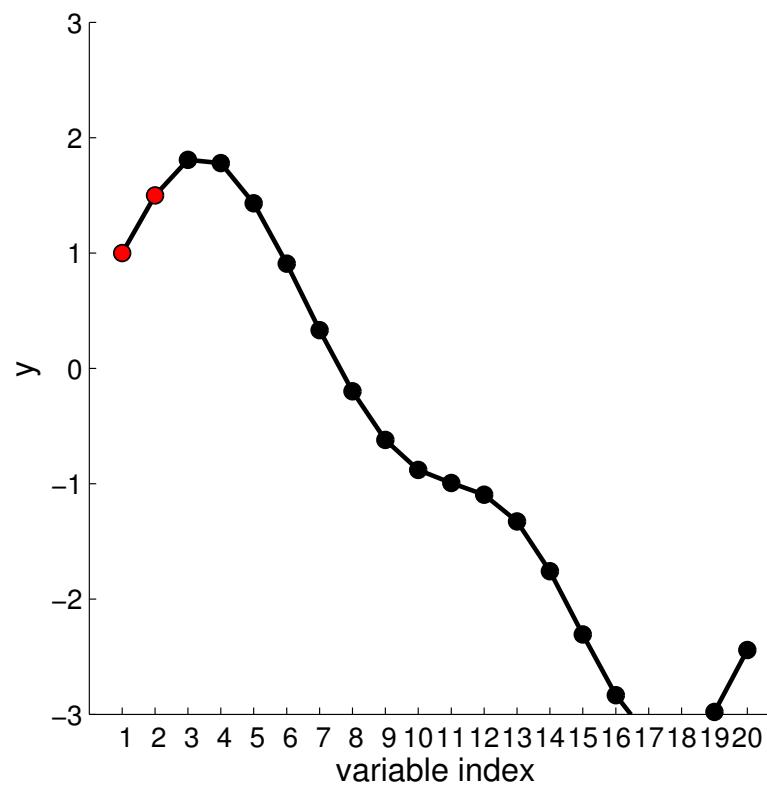
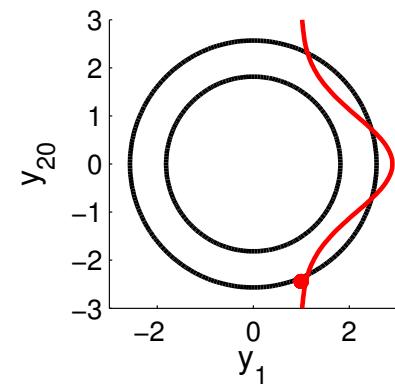
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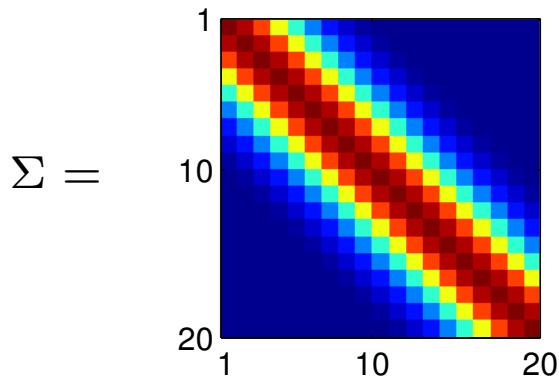
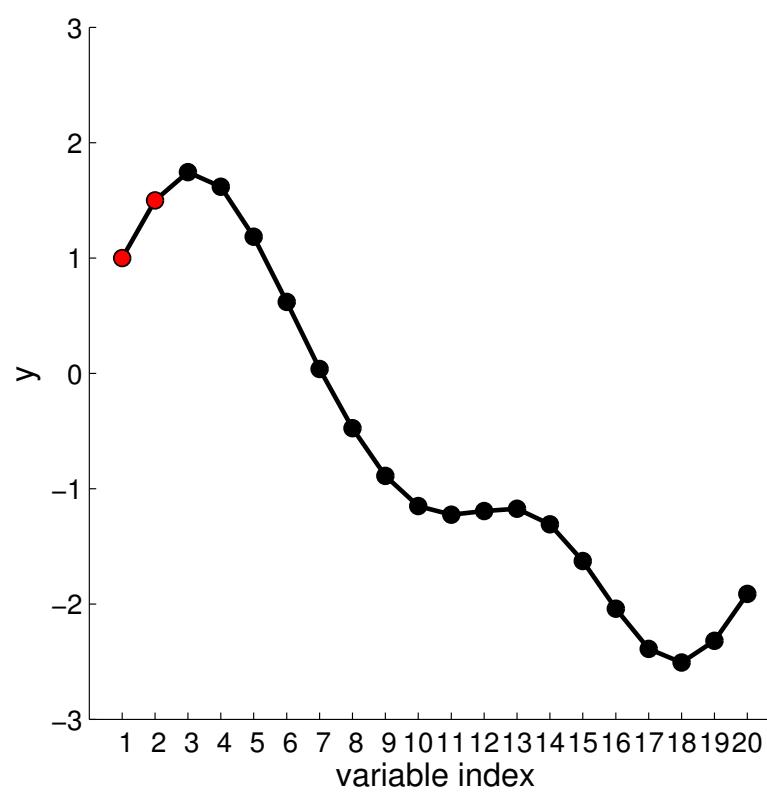
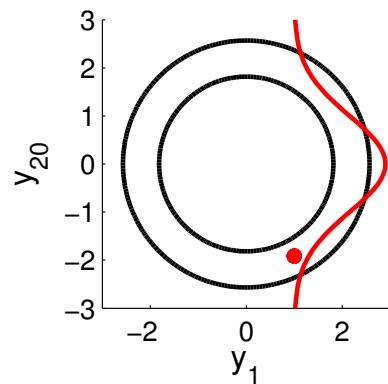
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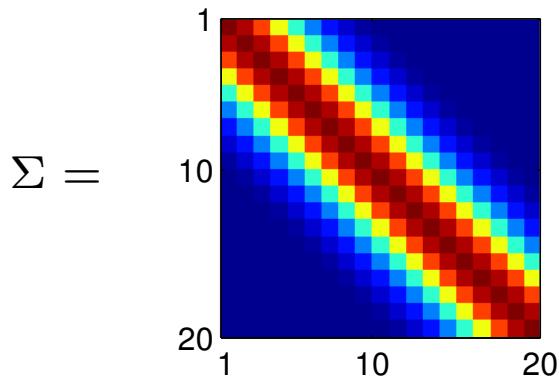
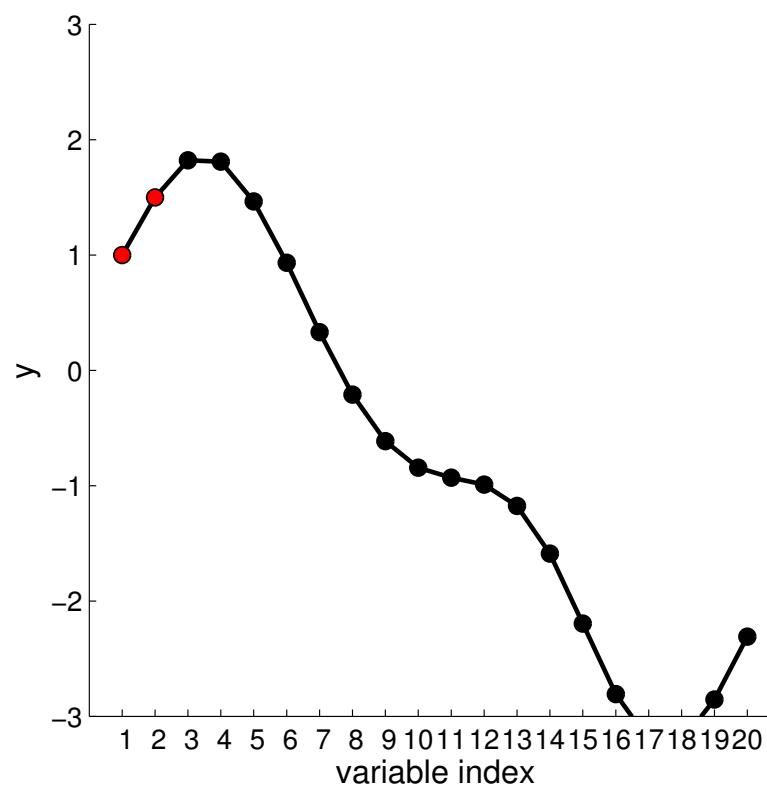
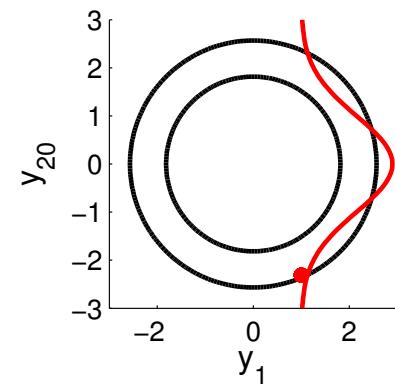
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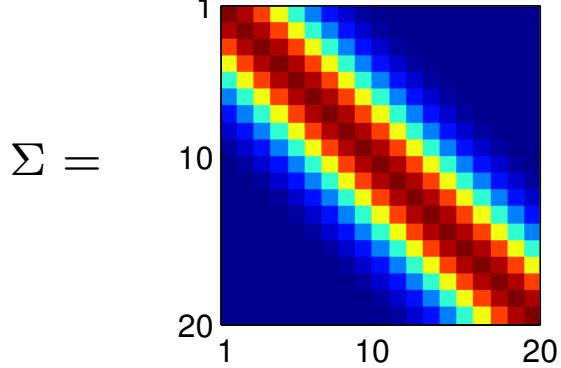
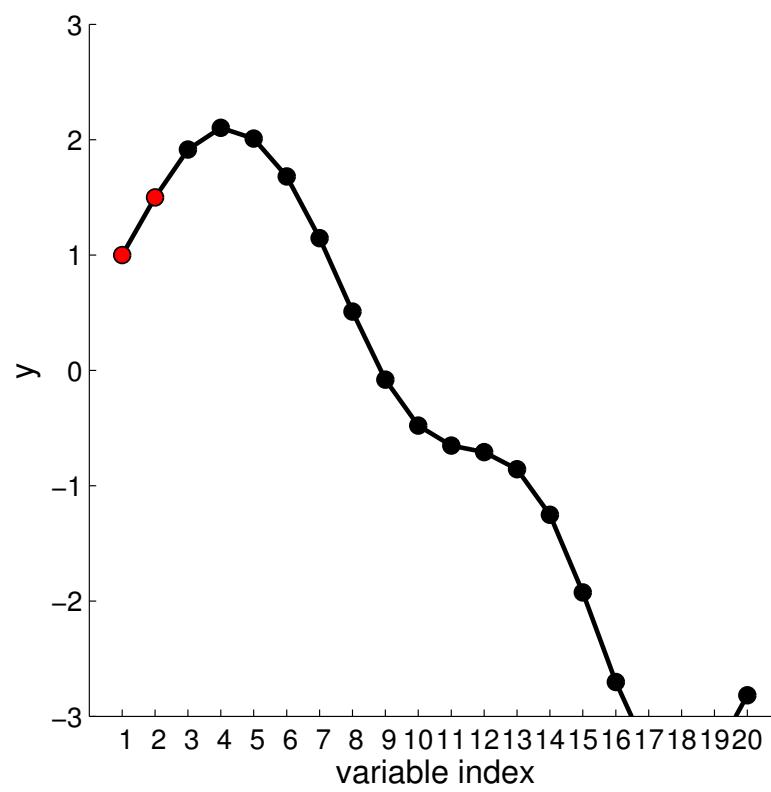
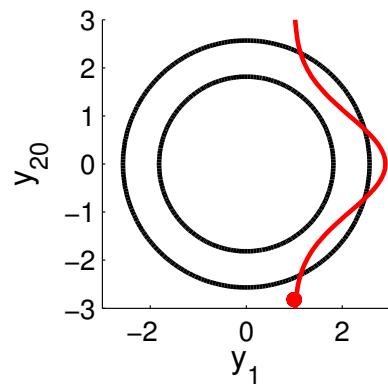
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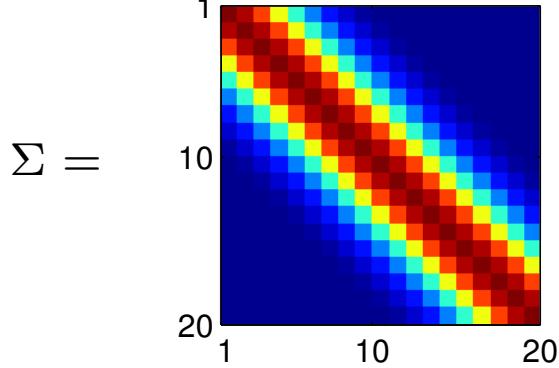
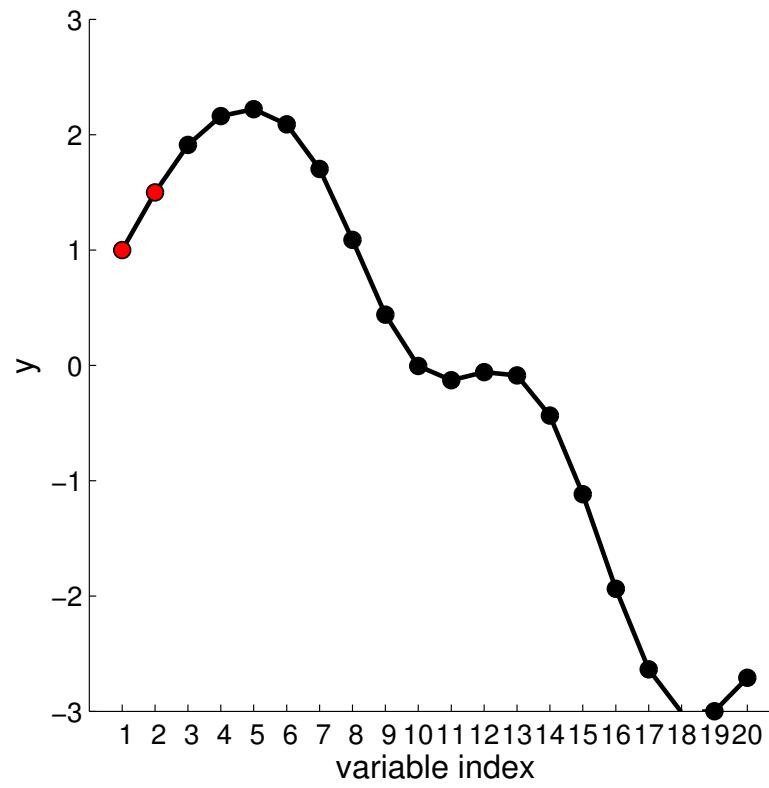
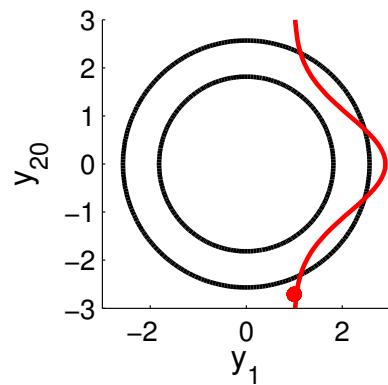
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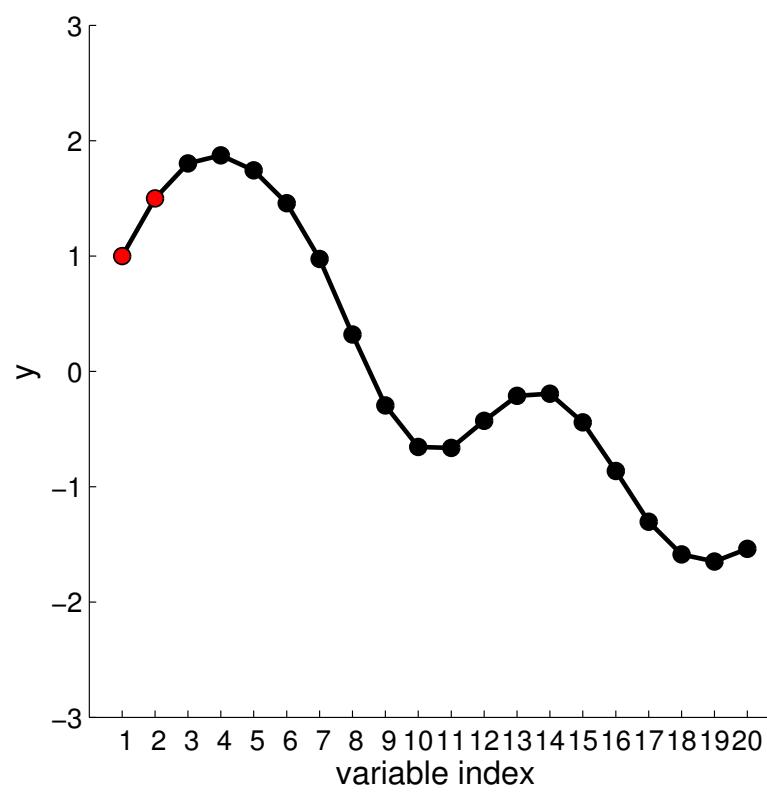
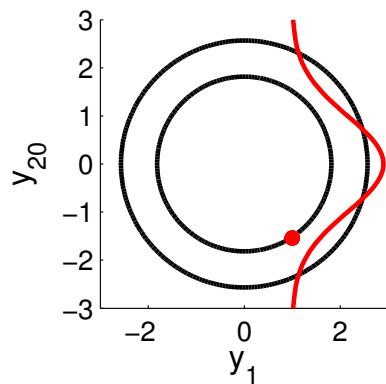
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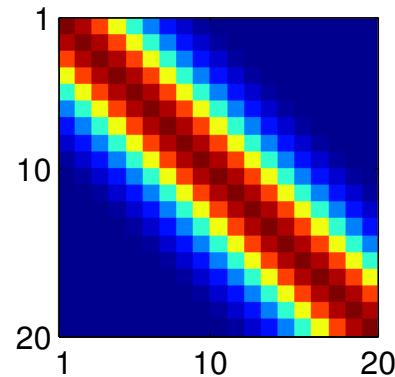
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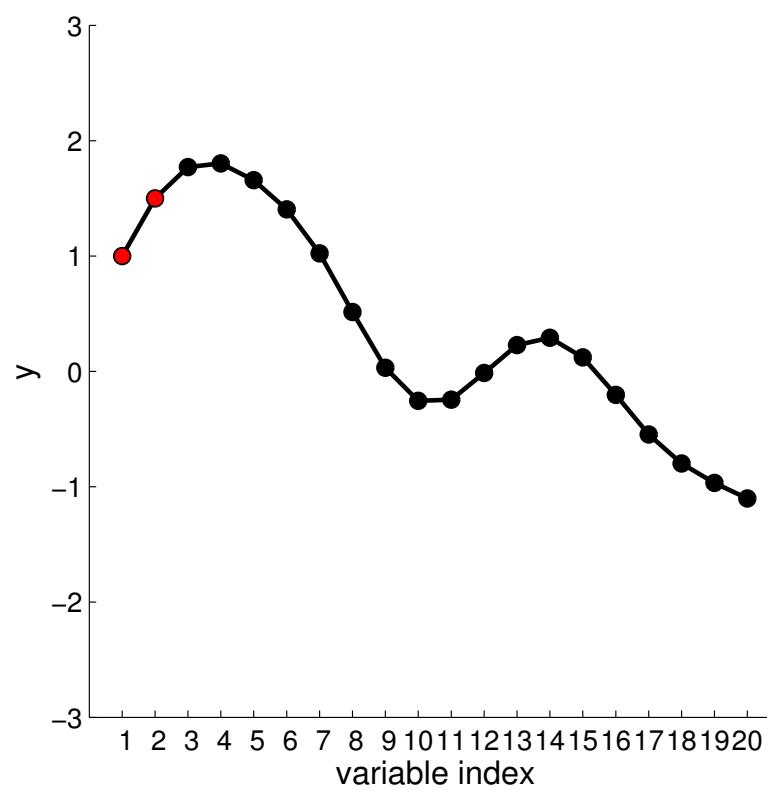
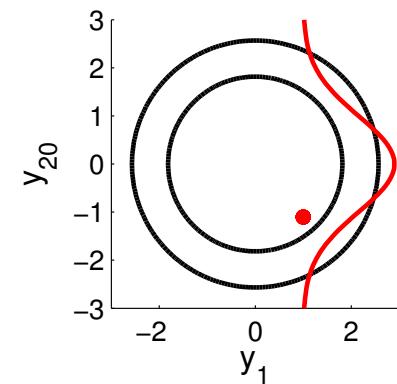
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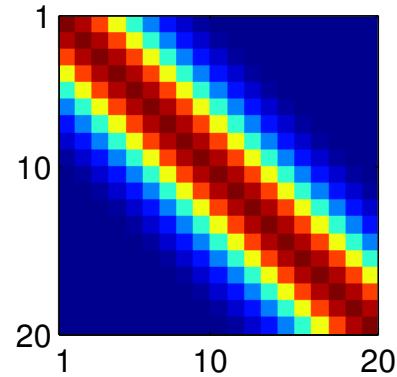
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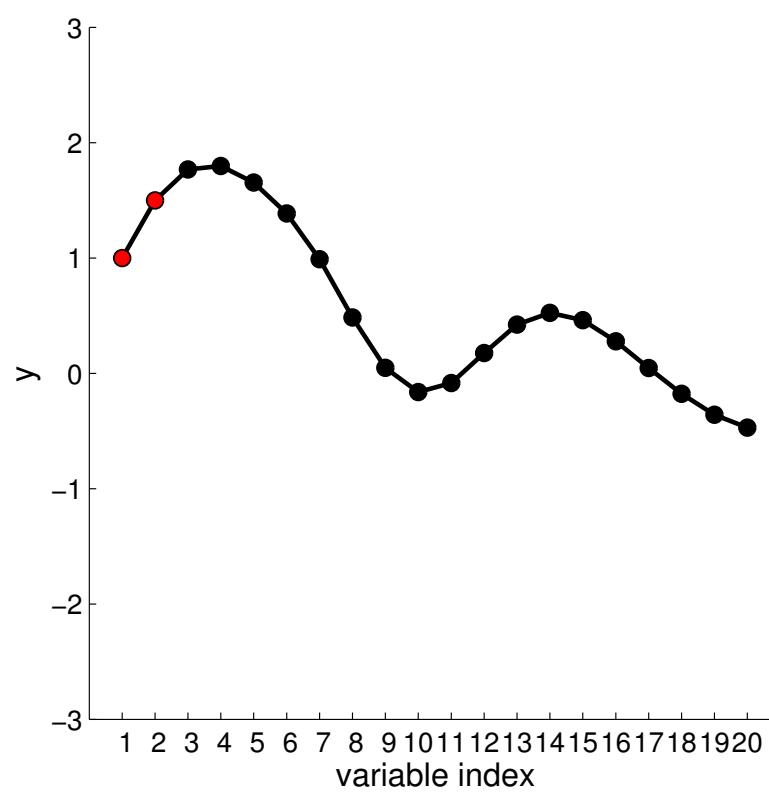
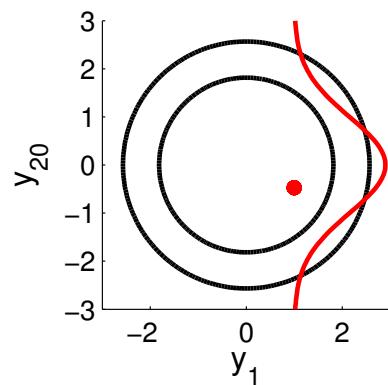
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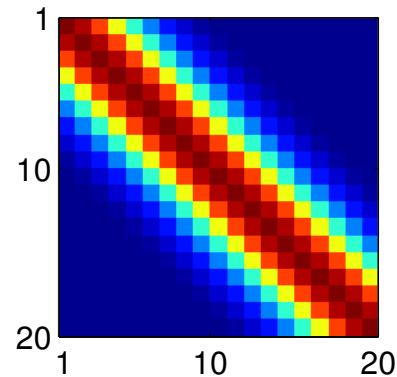
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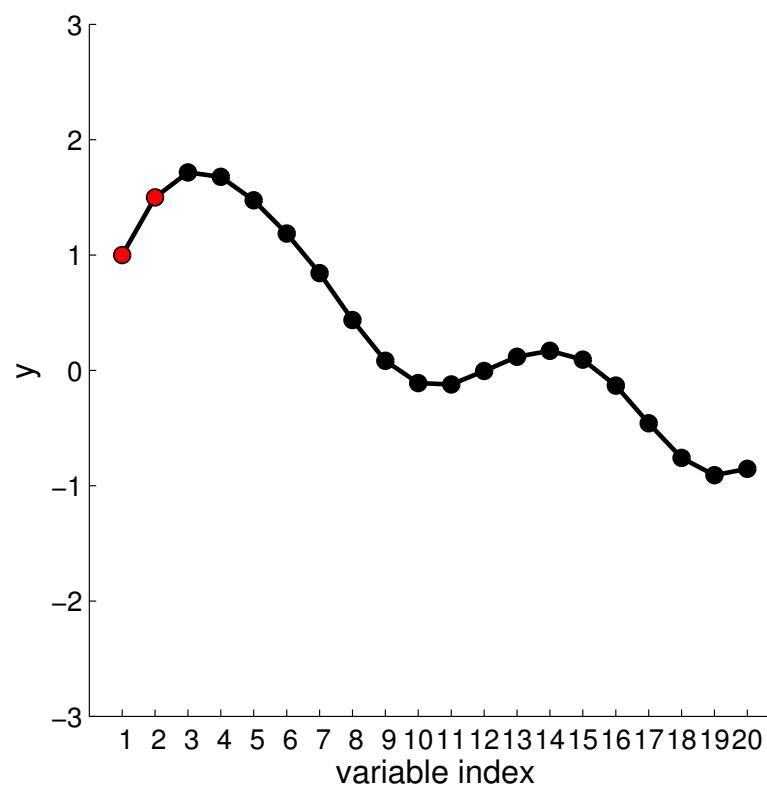
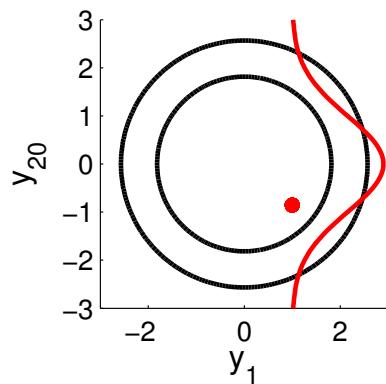
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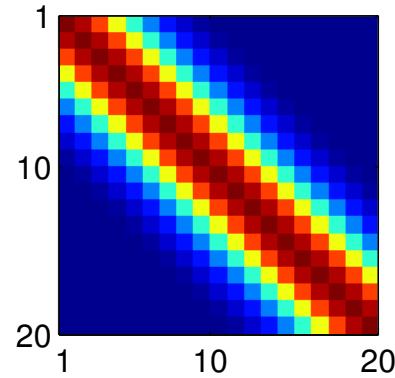
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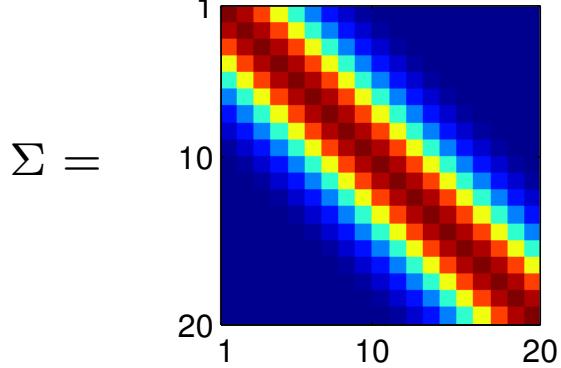
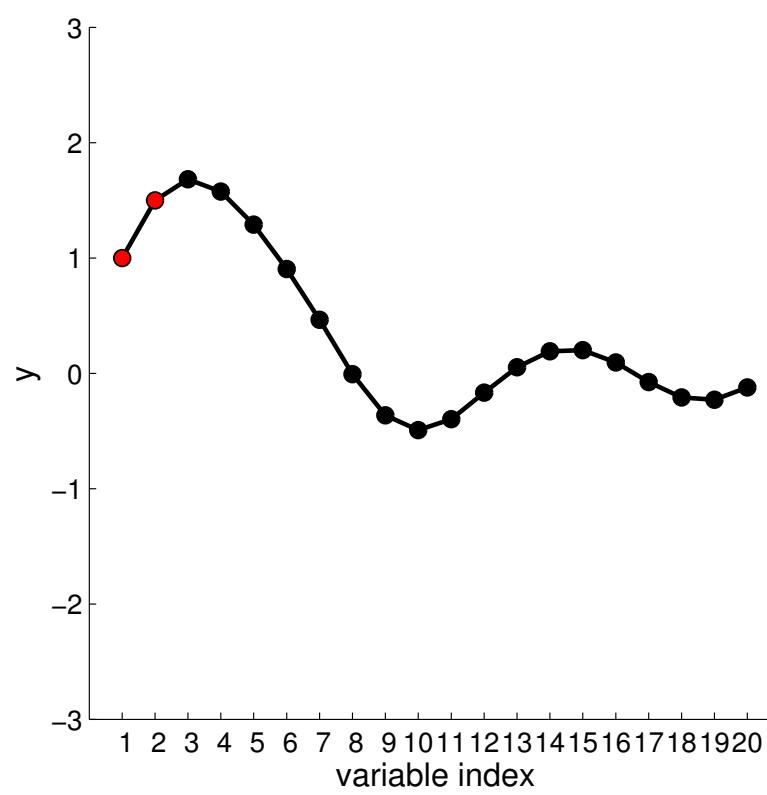
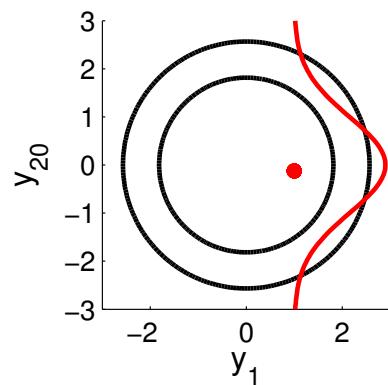
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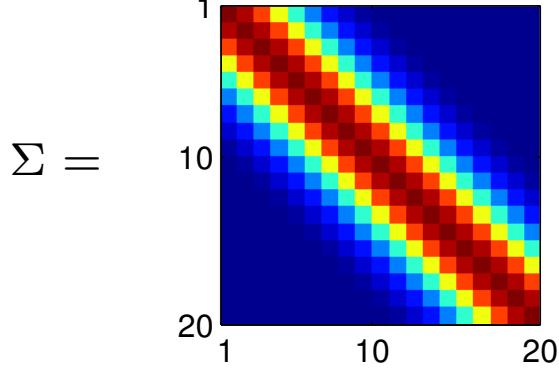
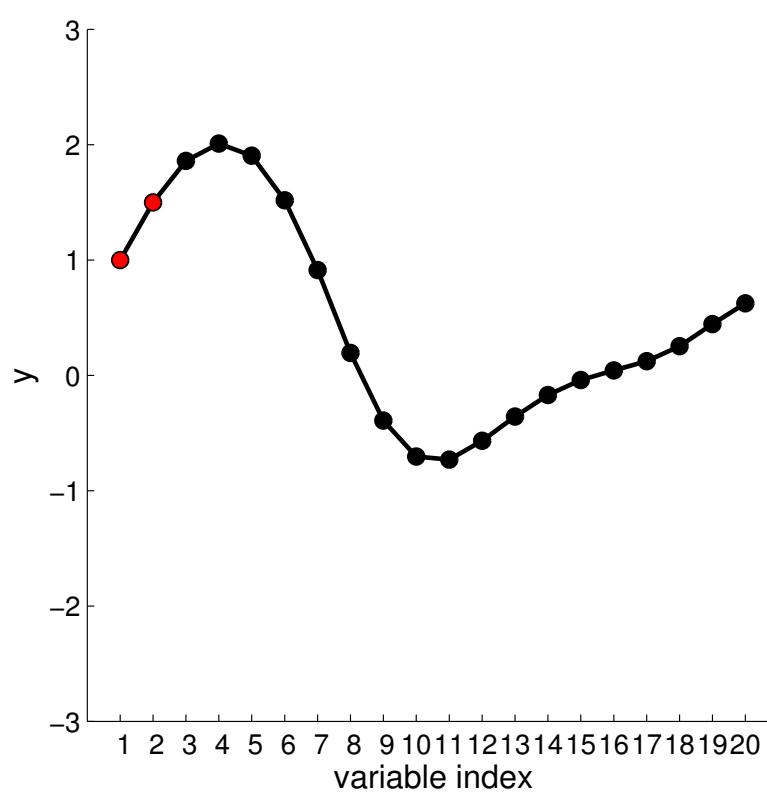
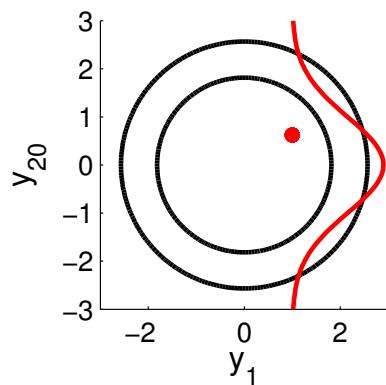
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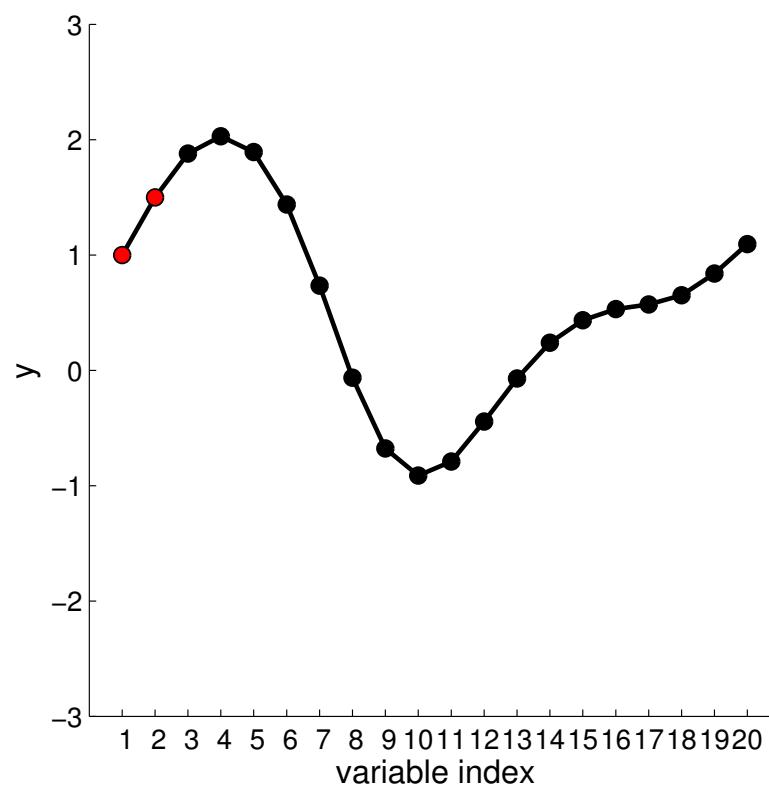
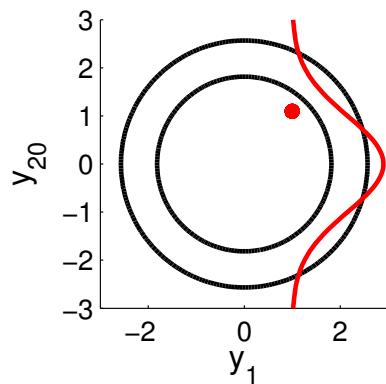
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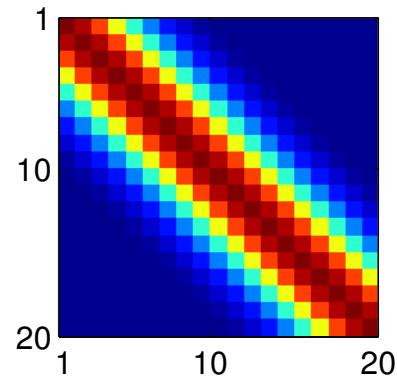
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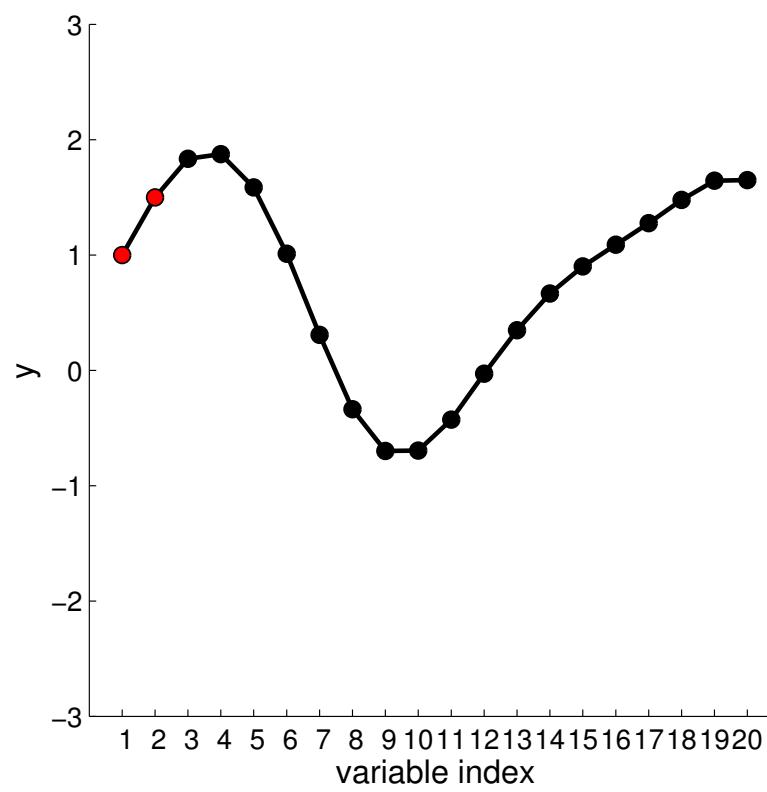
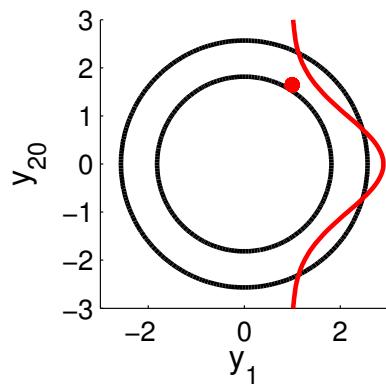
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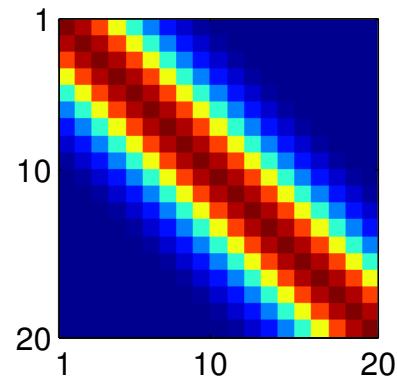
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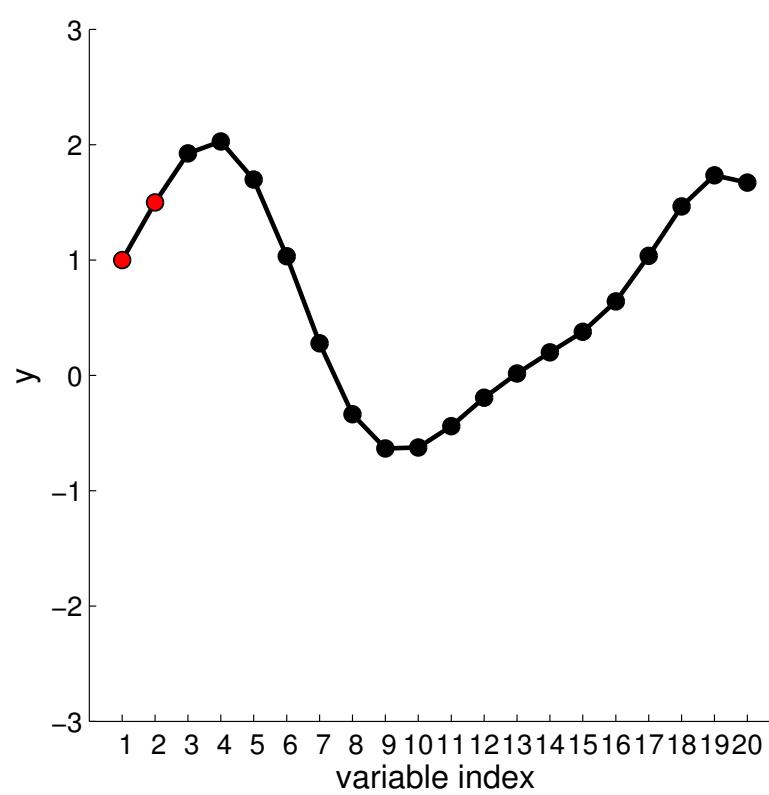
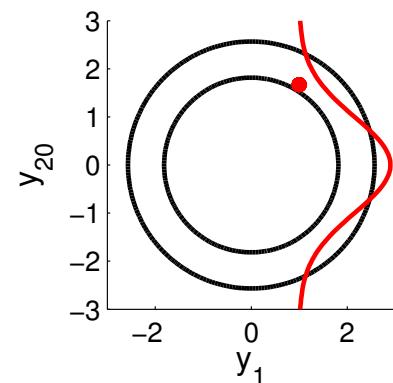
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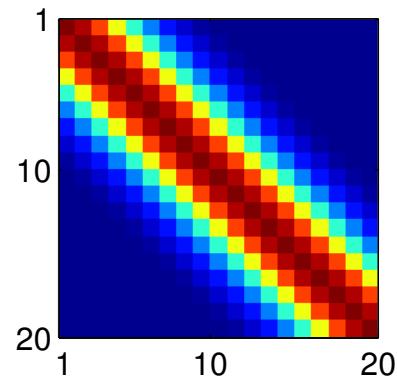
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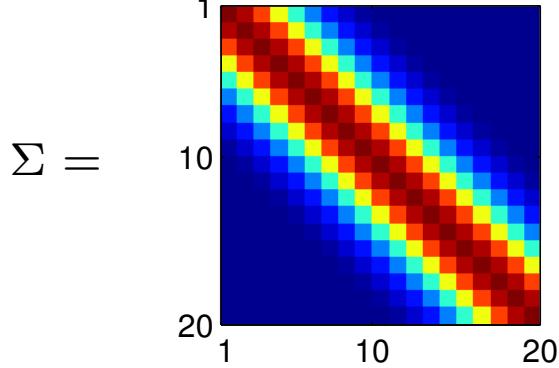
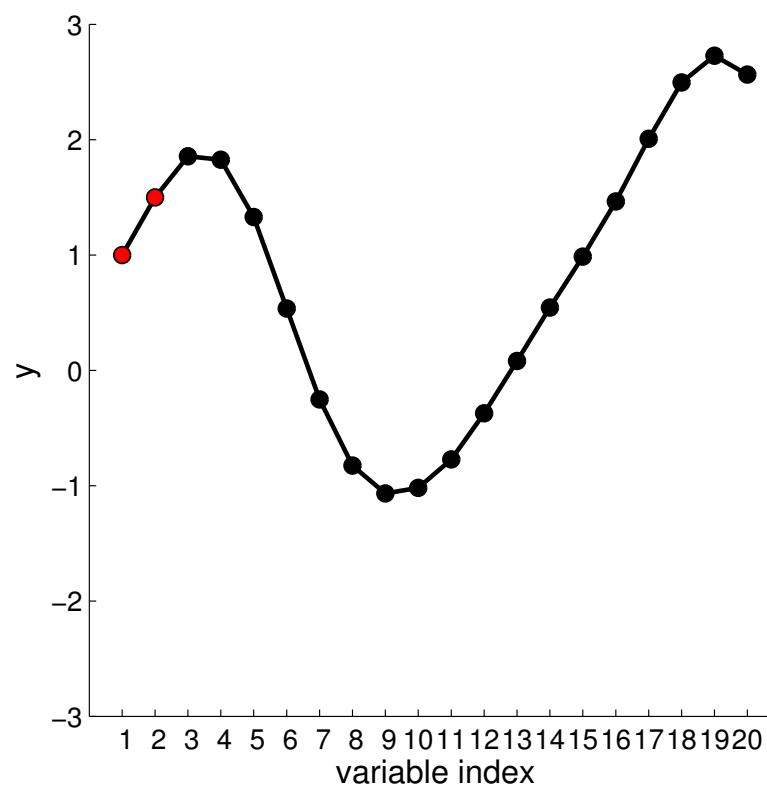
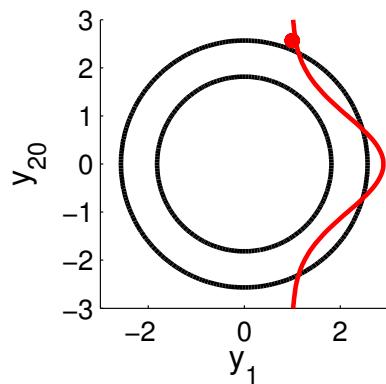
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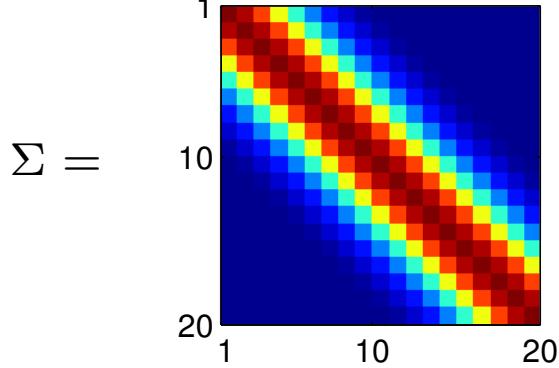
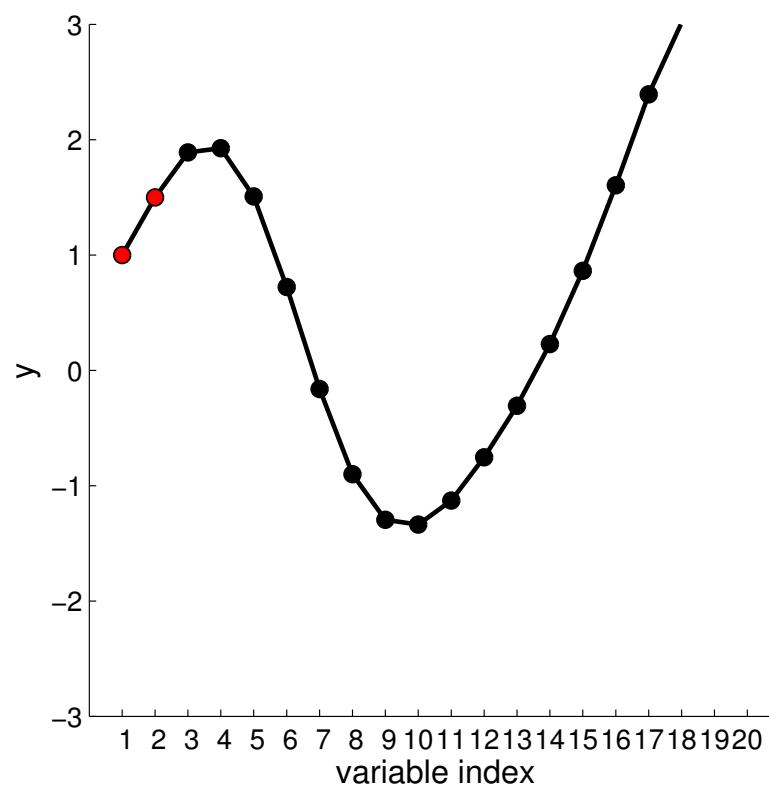
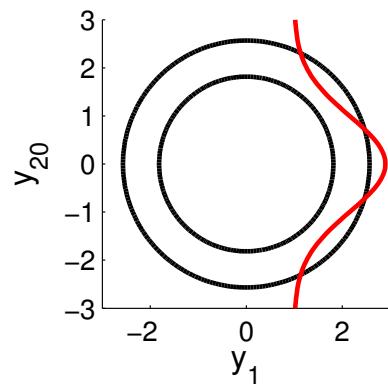
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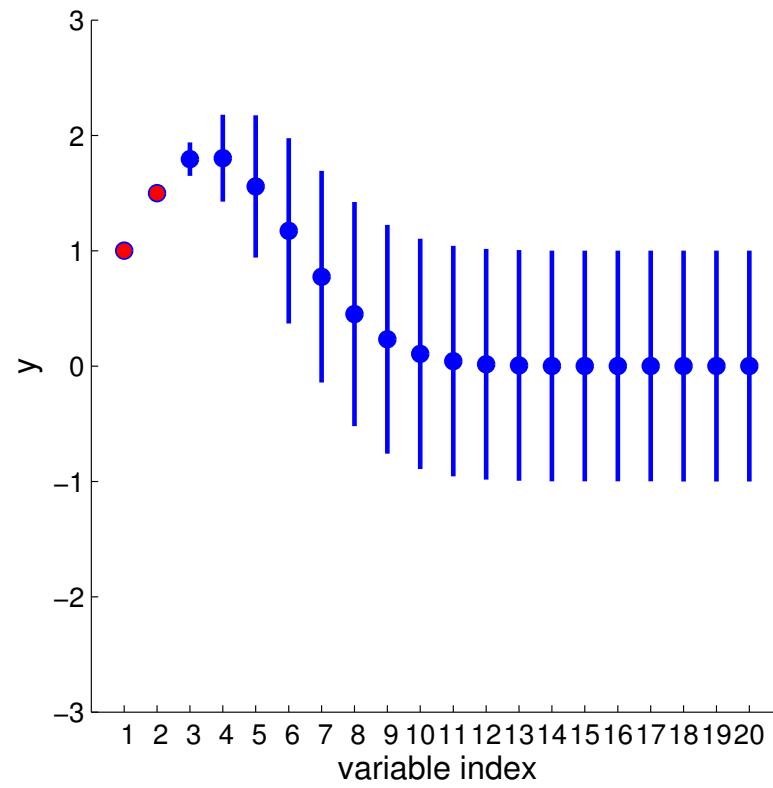
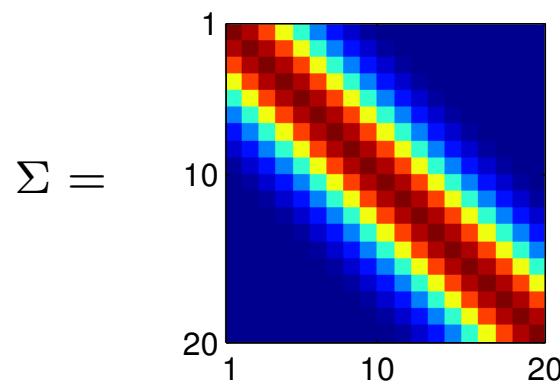
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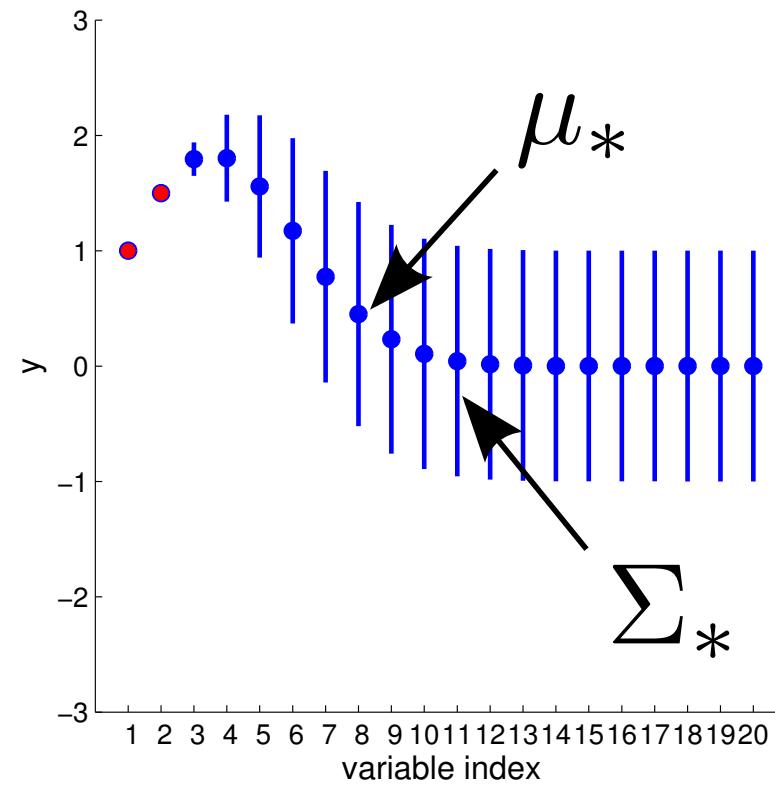
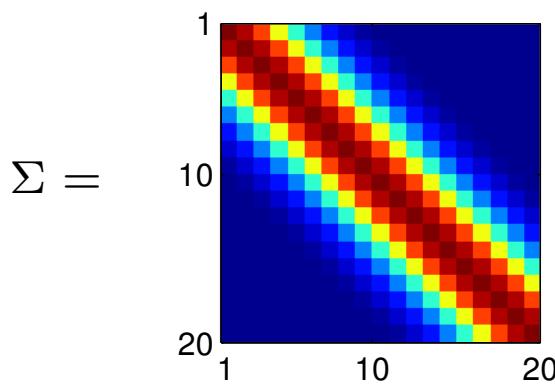
New visualisation



Regression using Gaussians

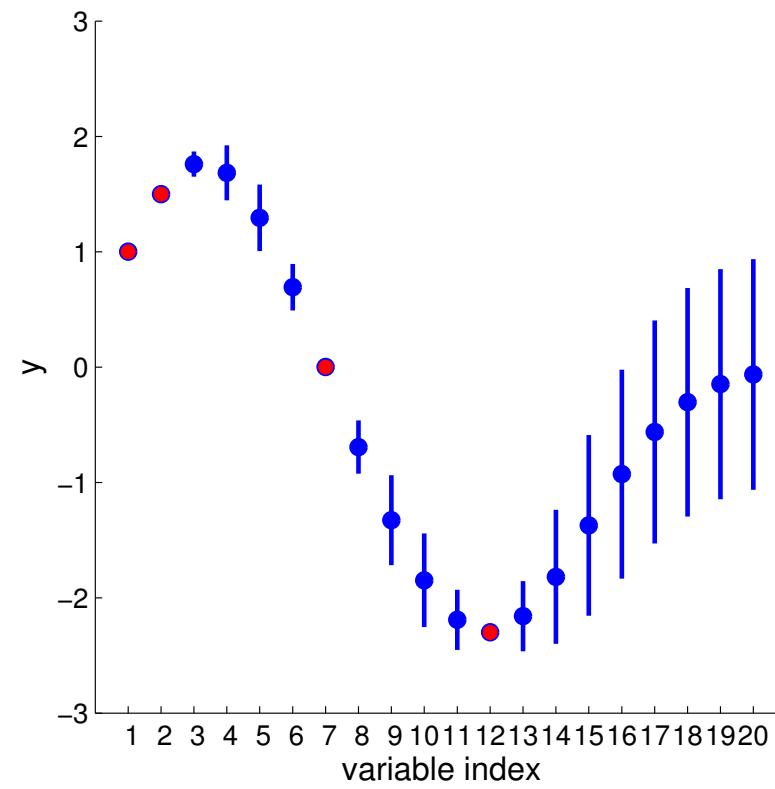
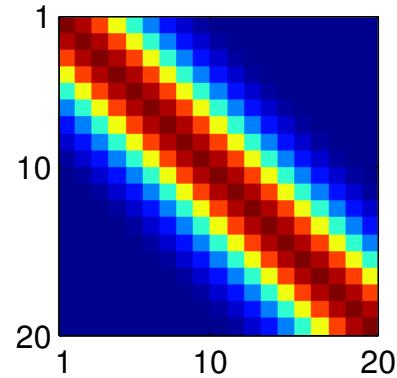


Regression using Gaussians



Regression using Gaussians

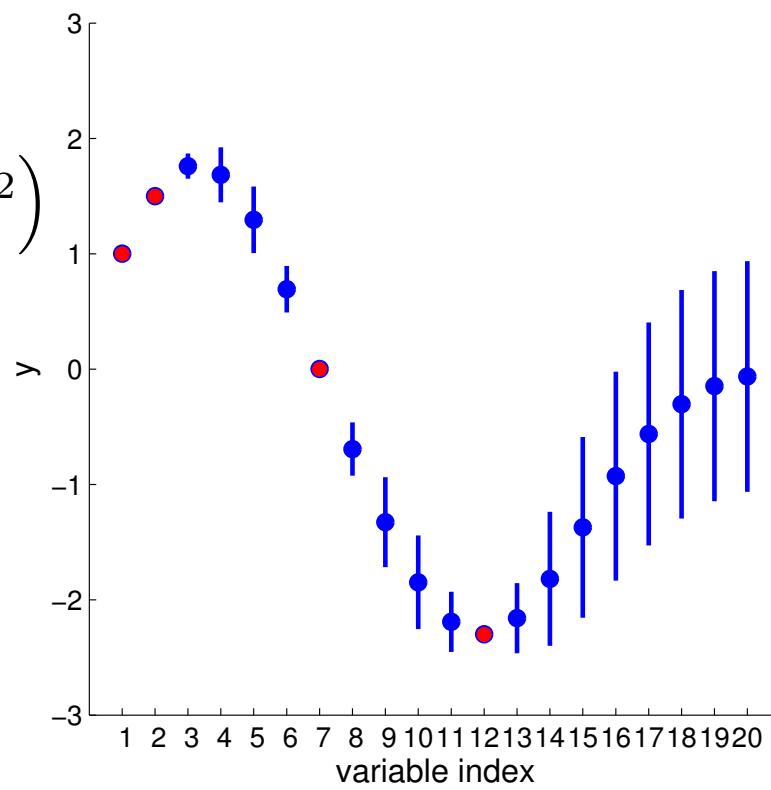
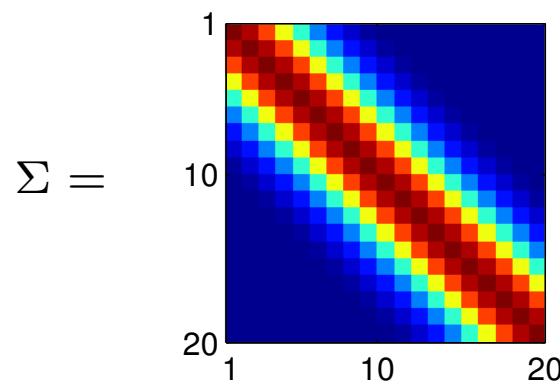
$$\Sigma =$$



Regression using Gaussians

$$\Sigma(\mathbf{x}_1, \mathbf{x}_2) = K(\mathbf{x}_1, \mathbf{x}_2) + I\sigma_y^2$$

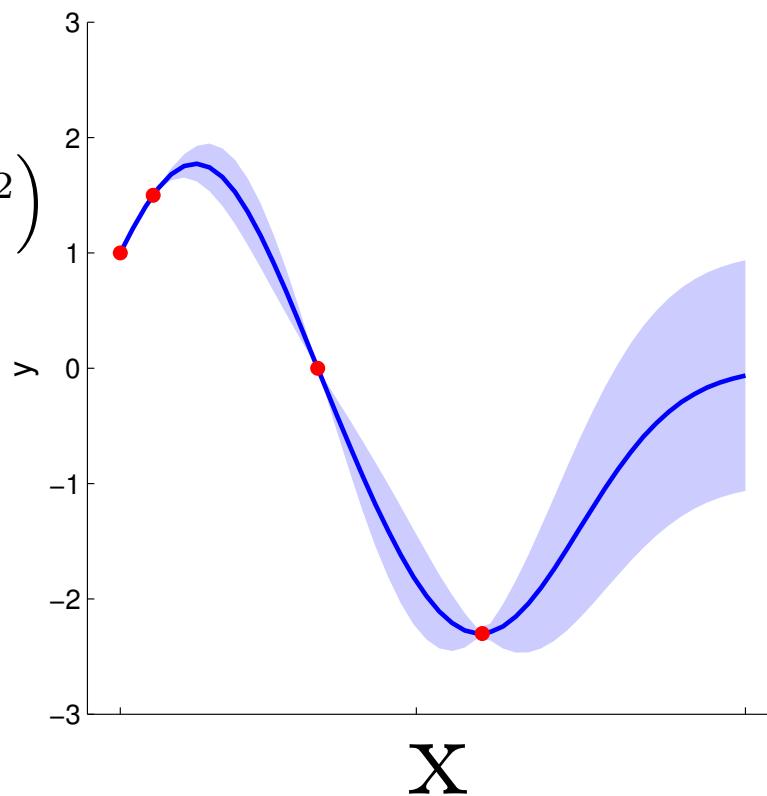
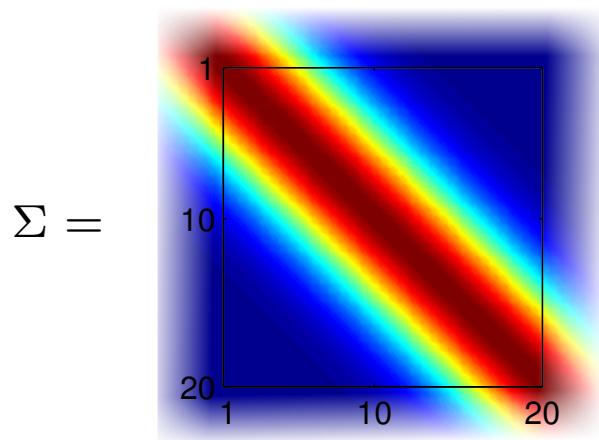
$$K(\mathbf{x}_1, \mathbf{x}_2) = \sigma^2 \exp\left(-\frac{1}{2l^2}(\mathbf{x}_1 - \mathbf{x}_2)^2\right)$$



Regression: probabilistic inference in function space

$$\Sigma(\mathbf{x}_1, \mathbf{x}_2) = K(\mathbf{x}_1, \mathbf{x}_2) + I\sigma_y^2$$

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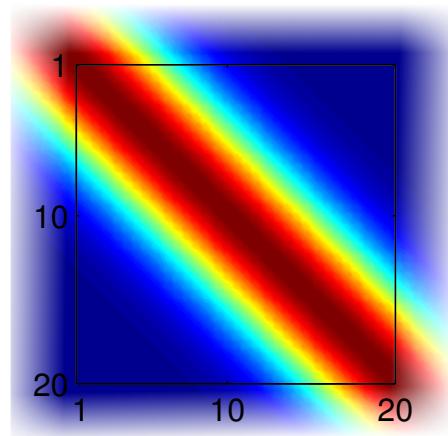
Non-parametric (∞ -parametric)

$$p(\mathbf{y}|\theta) = \mathcal{N}(0, \Sigma)$$

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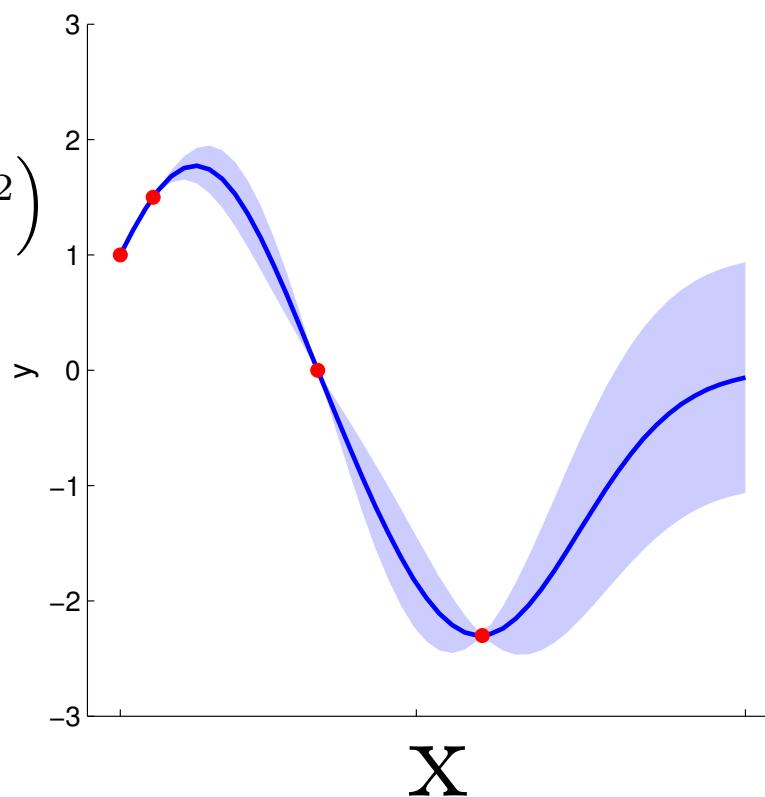
$$\Sigma =$$



Parametric model

$$\mathbf{y}(\mathbf{x}) = f(\mathbf{x}; \theta) + \sigma_y \epsilon$$

$$\epsilon \sim \mathcal{N}(0, 1)$$



Regression: probabilistic inference in function space

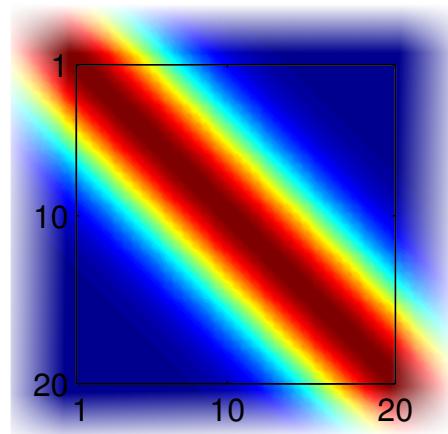
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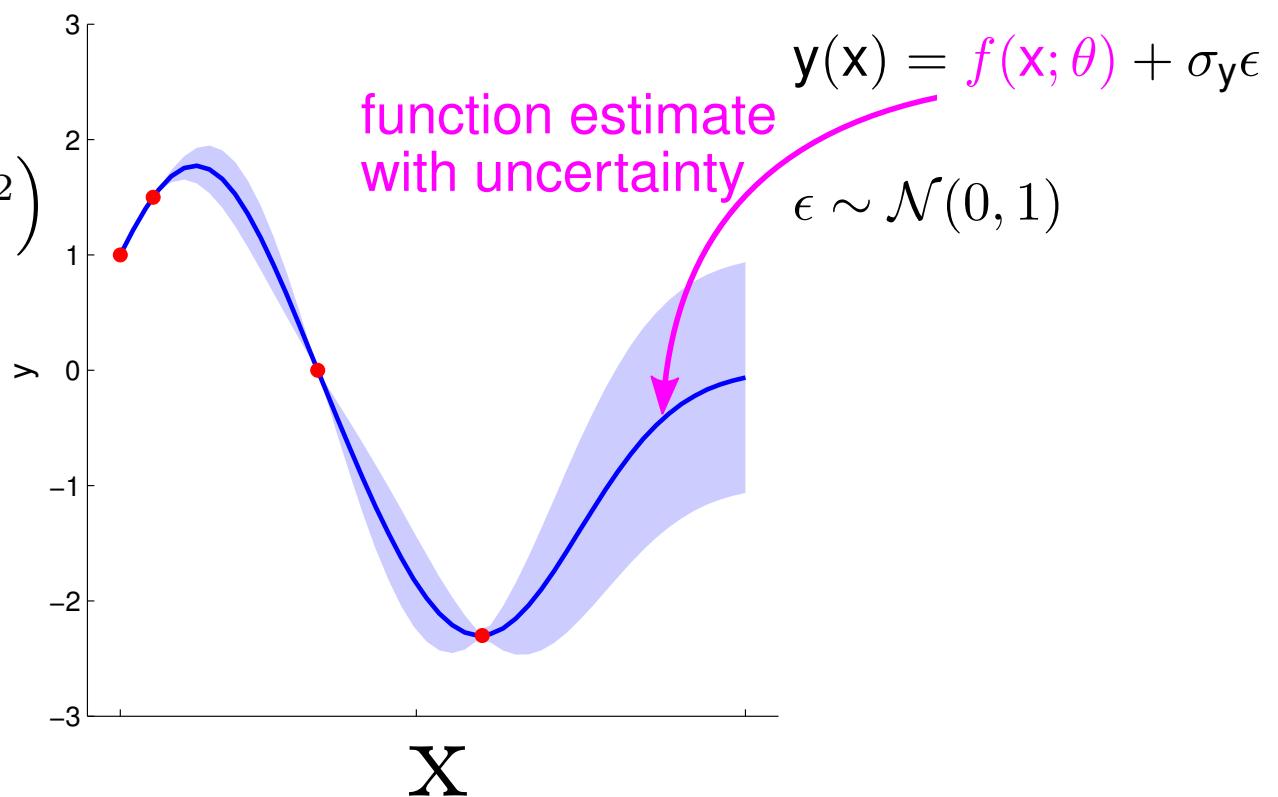
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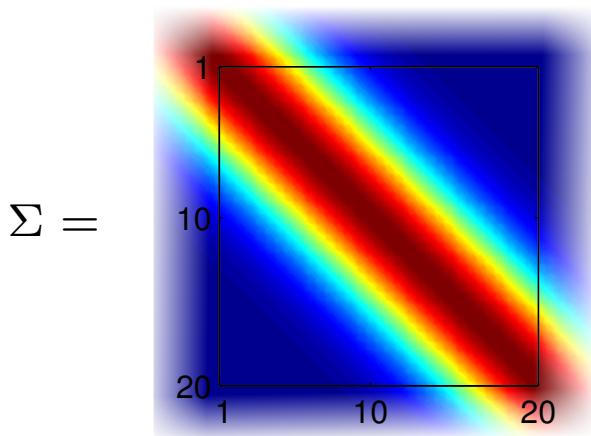
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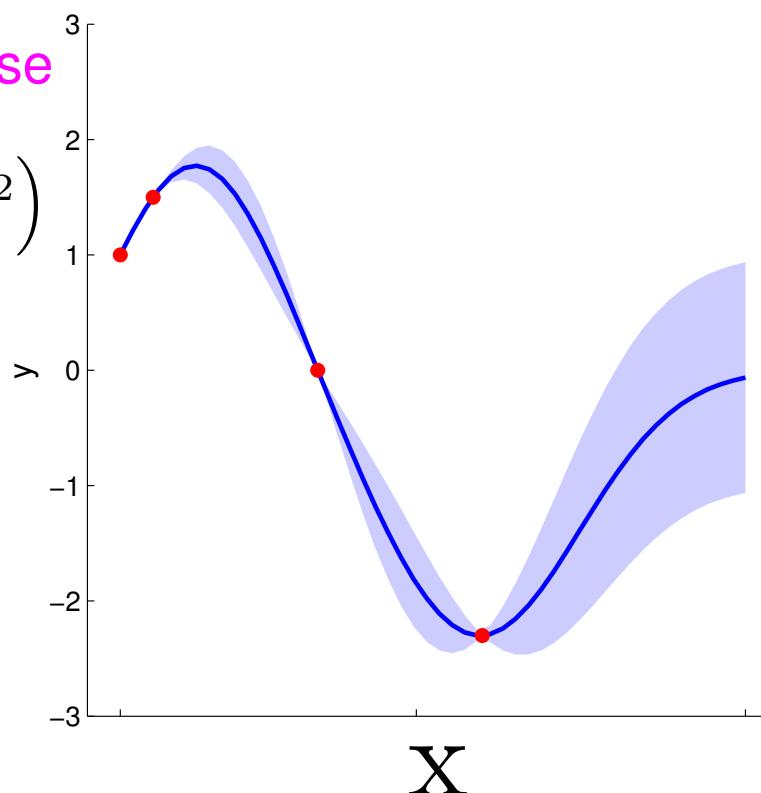


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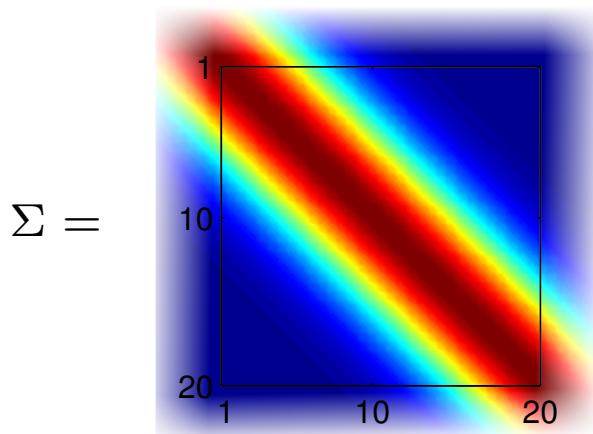
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↑
horizontal-scale

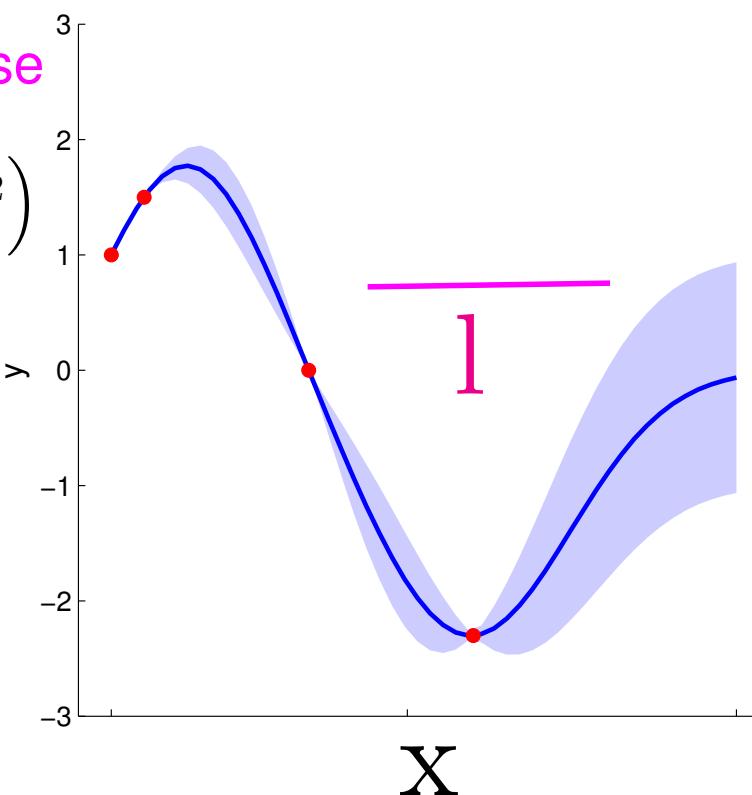


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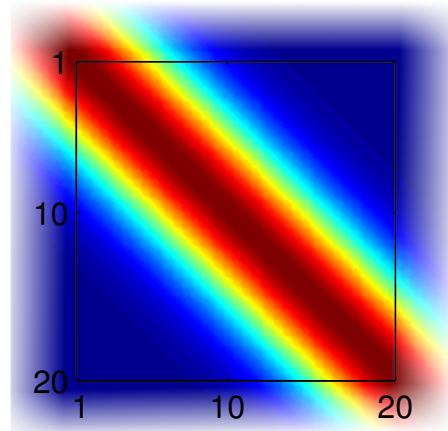
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vertical-scale horizontal-scale

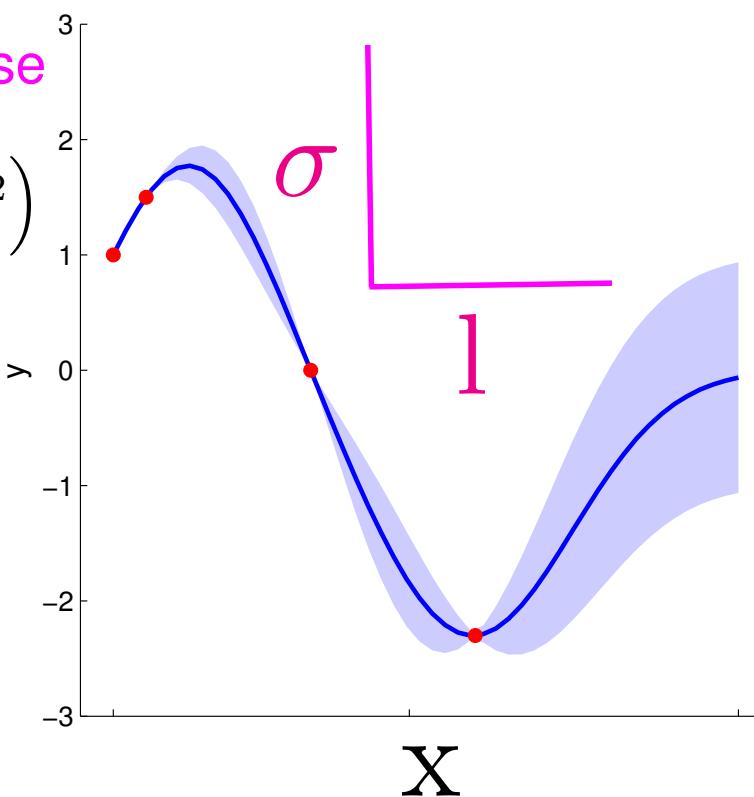
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Mathematical Foundations: Definition

Gaussian process = generalization of multivariate Gaussian distribution to infinitely many variables.

Definition: a Gaussian process is a collection of random variables, any finite number of which have (consistent) Gaussian distributions.

A Gaussian distribution is fully specified by a mean vector, μ , and covariance matrix Σ :

$$\mathbf{f} = (f_1, \dots, f_n) \sim \mathcal{N}(\mu, \Sigma), \text{ indices } i = 1, \dots, n$$

A Gaussian process is fully specified by a mean function $m(\mathbf{x})$ and covariance function $K(\mathbf{x}, \mathbf{x}')$:

$$f(\mathbf{x}) \sim \mathcal{GP}(m(\mathbf{x}), K(\mathbf{x}, \mathbf{x}')) , \text{ indices } \mathbf{x}$$

Mathematical Foundations: Marginalisation

Q1. A GP is "like" a Gaussian distribution with an infinitely long mean vector and an "infinite by infinite" covariance matrix, so how do we represent it on a computer?

Mathematical Foundations: Marginalisation

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We are saved by the marginalisation property:

$$p(\mathbf{y}_1) = \int p(\mathbf{y}_1, \mathbf{y}_2) d\mathbf{y}_2$$

$$p(\mathbf{y}_1, \mathbf{y}_2) = \mathcal{N} \left(\begin{bmatrix} \mathbf{a} \\ \mathbf{b} \end{bmatrix}, \begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{B}^\top & \mathbf{C} \end{bmatrix} \right) \implies p(\mathbf{y}_1) = \mathcal{N}(\mathbf{a}, \mathbf{A})$$

⇒ Only need to represent finite dimensional projections of GPs on computer.

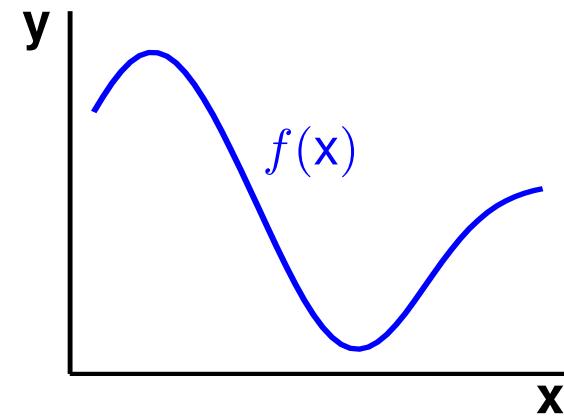
nonparametric model: complexity increases with size of the data

Mathematical Foundations: Regression

Q3. What's the formal justification for how we were using GPs for regression?

Generative model (like non-linear regression)

$$y(x) = f(x) + \epsilon\sigma_y$$



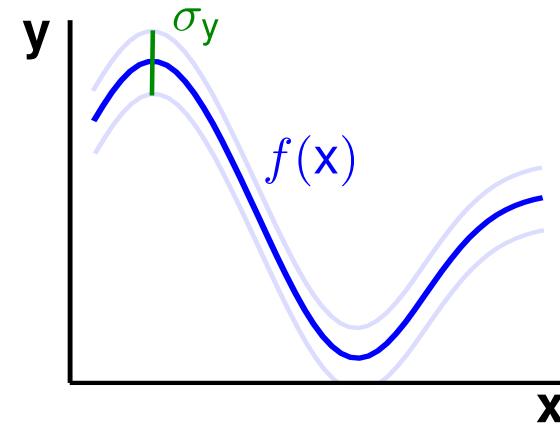
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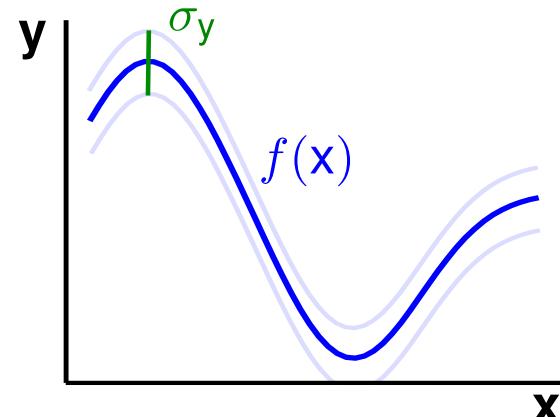
$$y(x) = f(x) + \epsilon\sigma_y$$

$$p(\epsilon) = \mathcal{N}(0, 1)$$

place GP prior over the non-linear function

$$p(f(x)|\theta) = \mathcal{GP}(0, K(x, x'))$$

$$K(x, x') = \sigma^2 \exp\left(-\frac{1}{2l^2}(x - x')^2\right) \quad (\text{smoothly wiggling functions expected})$$



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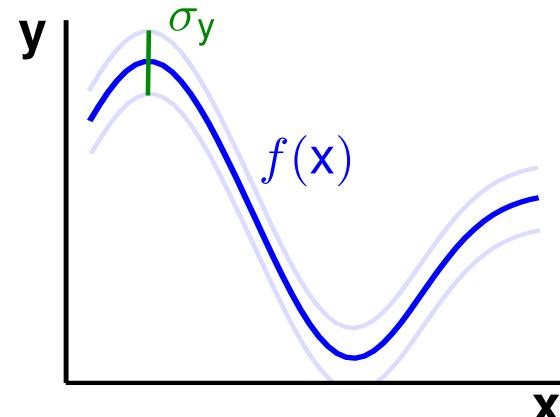
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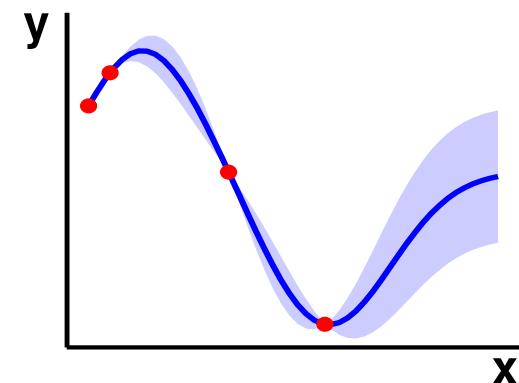
since the sum of two Gaussians is a Gaussian, the model induces a GP over $y(x)$

$$p(y(x)|\theta) = \mathcal{GP}(0, K(x, x') + I\sigma_y^2)$$



Mathematical foundations: Prediction

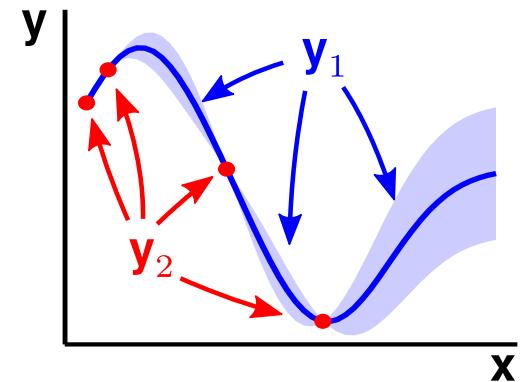
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Mathematical foundations: Prediction

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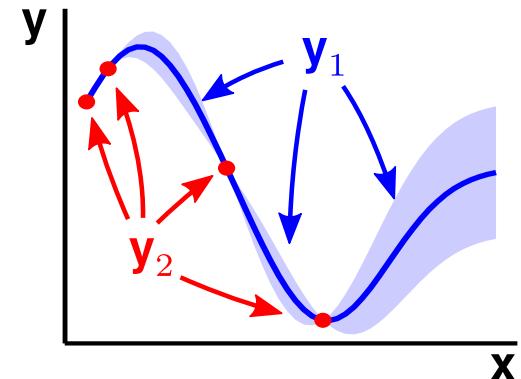
$$p(\mathbf{y}_1|\mathbf{y}_2) = \frac{p(\mathbf{y}_1, \mathbf{y}_2)}{p(\mathbf{y}_2)}$$



Mathematical foundations: Prediction

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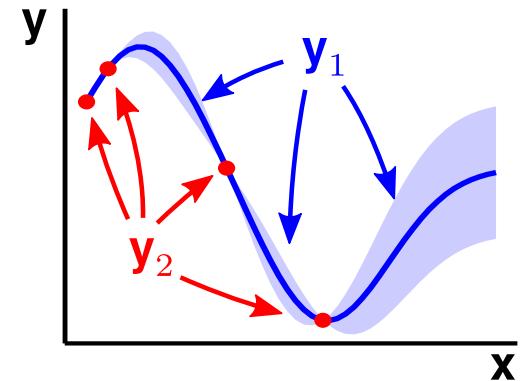
$$p(\mathbf{y}_1, \mathbf{y}_2) = \mathcal{N} \left(\begin{bmatrix} \mathbf{a} \\ \mathbf{b} \end{bmatrix}, \begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{B}^\top & \mathbf{C} \end{bmatrix} \right)$$
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Mathematical foundations: Prediction

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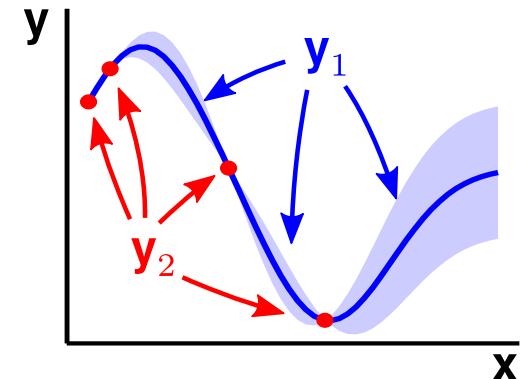
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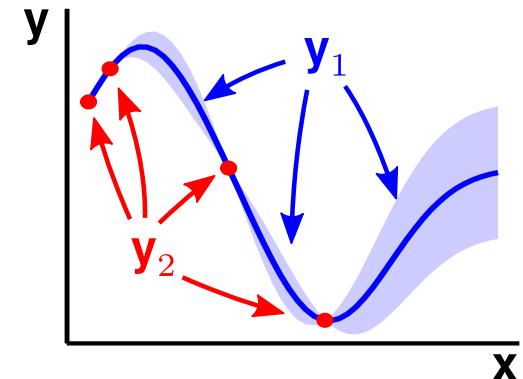


$$\implies p(\mathbf{y}_1 | \mathbf{y}_2) = \mathcal{N}(\mathbf{a} + \mathbf{B}\mathbf{C}^{-1}(\mathbf{y}_2 - \mathbf{b}), \mathbf{A} - \mathbf{B}\mathbf{C}^{-1}\mathbf{B}^\top)$$

Mathematical foundations: Prediction

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predictive mean

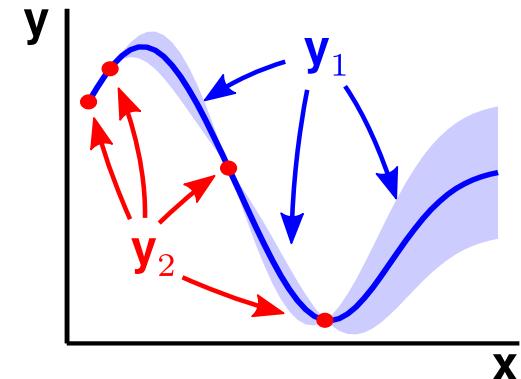
$$\begin{aligned} \mu_{\mathbf{y}_1 | \mathbf{y}_2} &= \mathbf{a} + \mathbf{B}\mathbf{C}^{-1}(\mathbf{y}_2 - \mathbf{b}) \\ &= \mathbf{B}\mathbf{C}^{-1}\mathbf{y}_2 \\ &= \mathbf{W}\mathbf{y}_2 \end{aligned}$$

linear in the data

Mathematical foundations: Prediction

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linear in the data

predictive covariance

$$\Sigma_{\mathbf{y}_1 | \mathbf{y}_2} = \mathbf{A} - \mathbf{B}\mathbf{C}^{-1}\mathbf{B}^\top$$

predictive uncertainty = prior uncertainty - reduction in uncertainty

predictions more confident than prior

What effect do the hyper-parameters have?

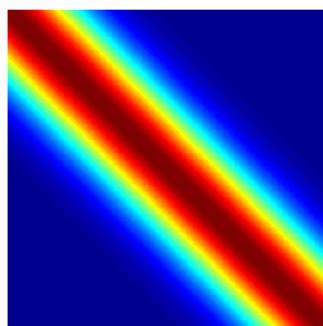
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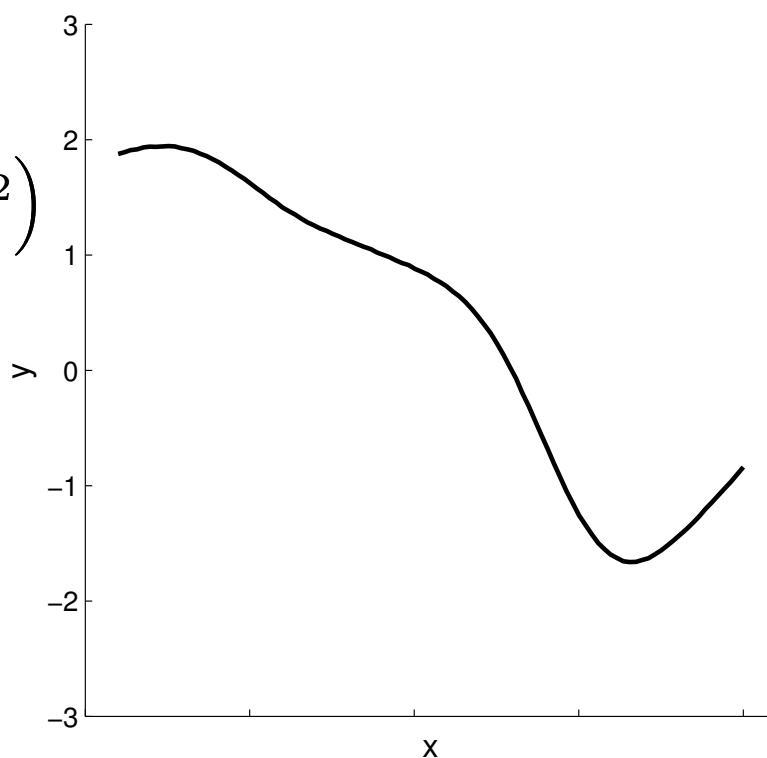
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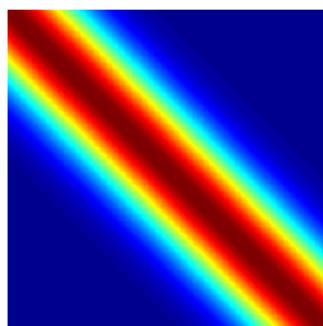
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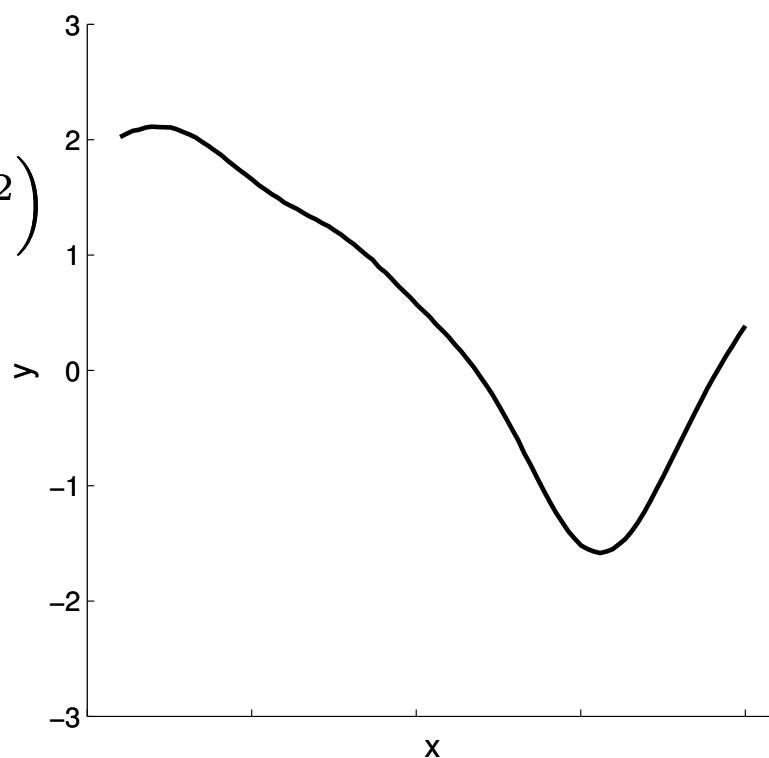
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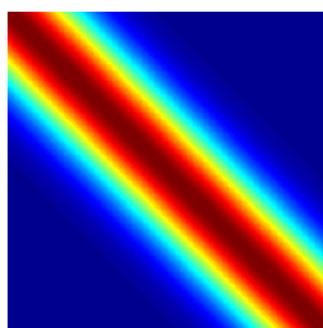
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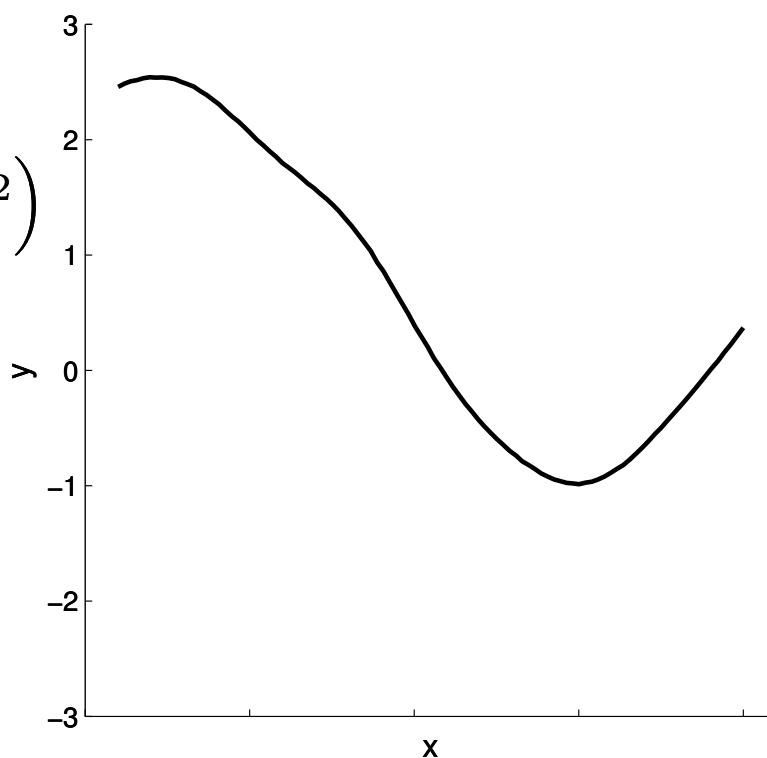
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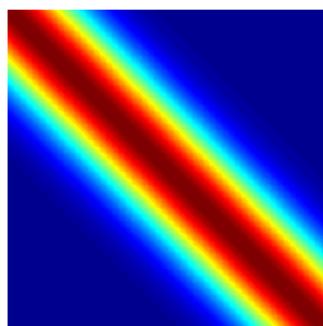
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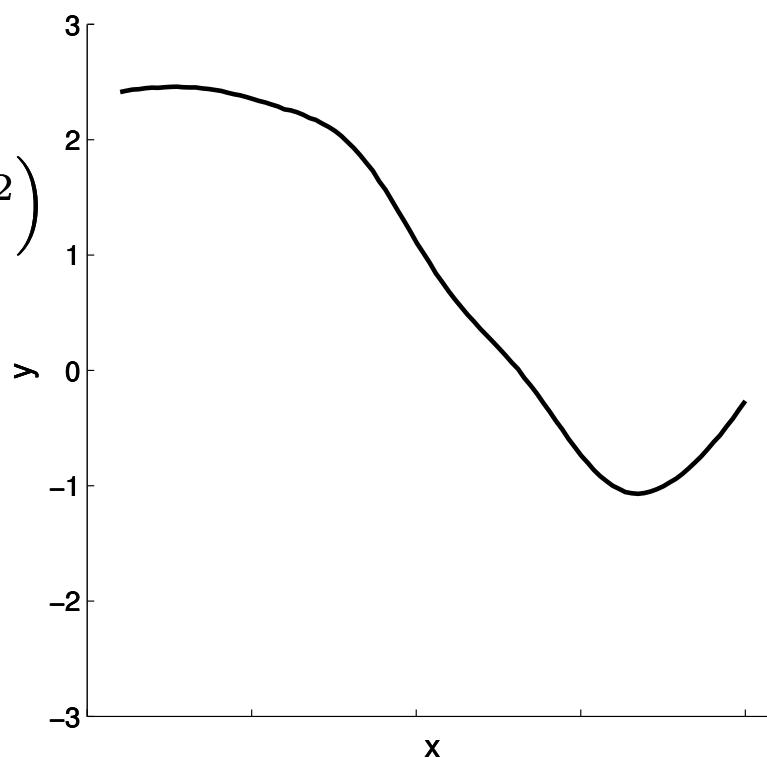
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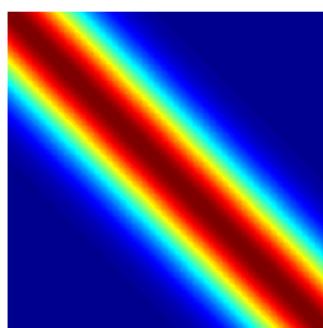
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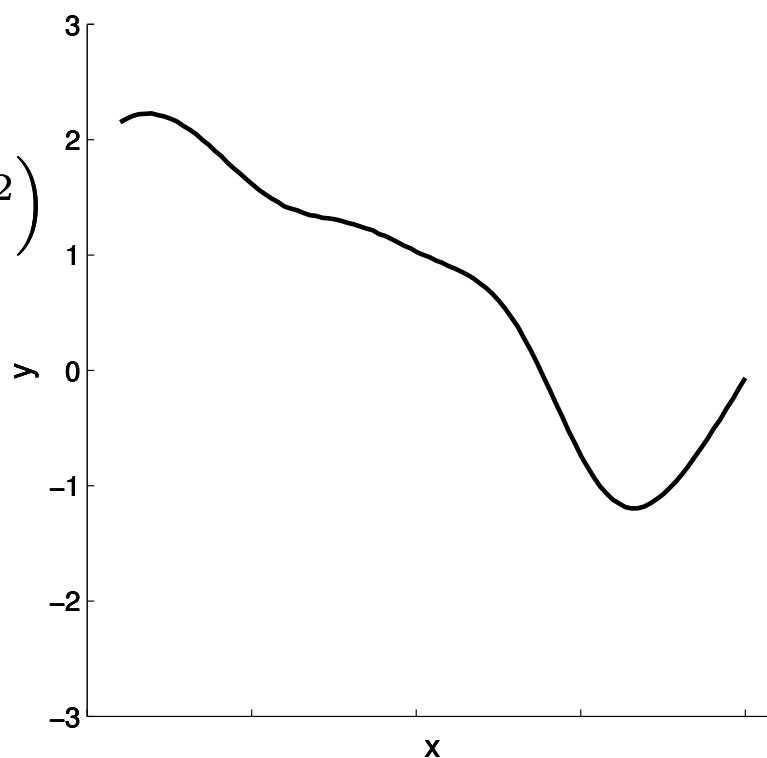
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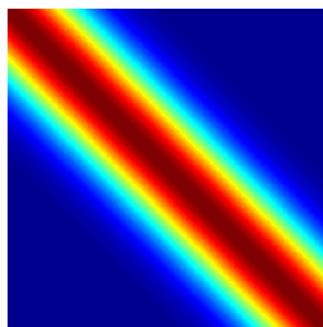
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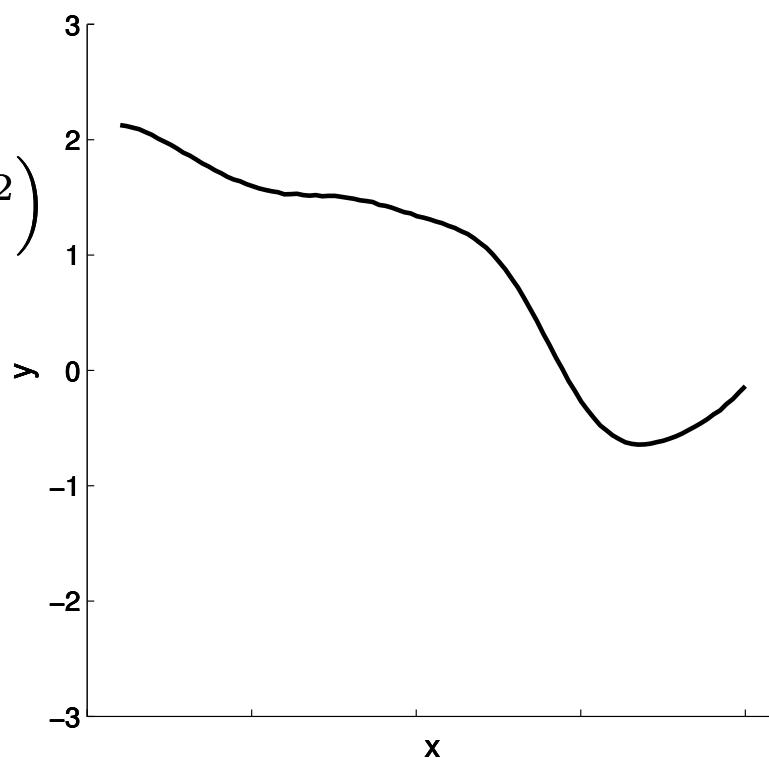
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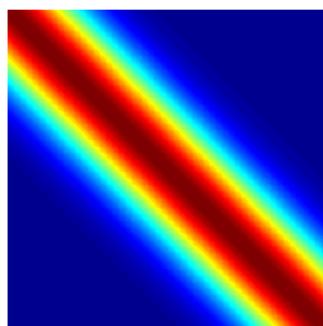
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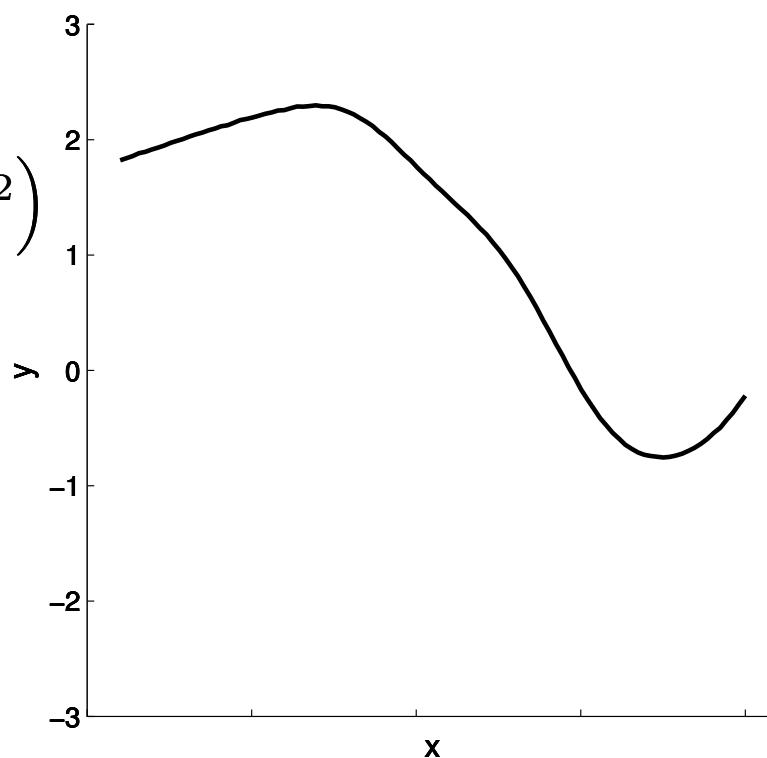
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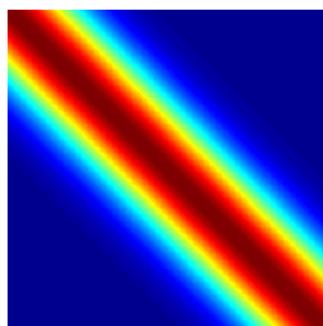
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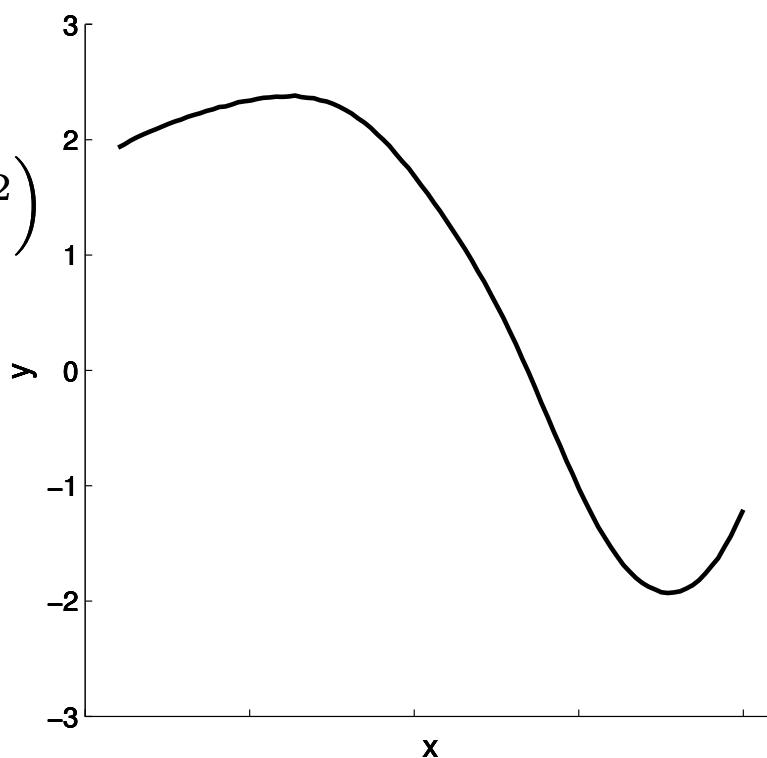
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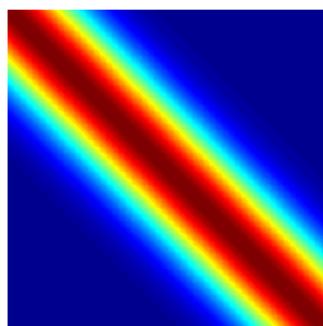
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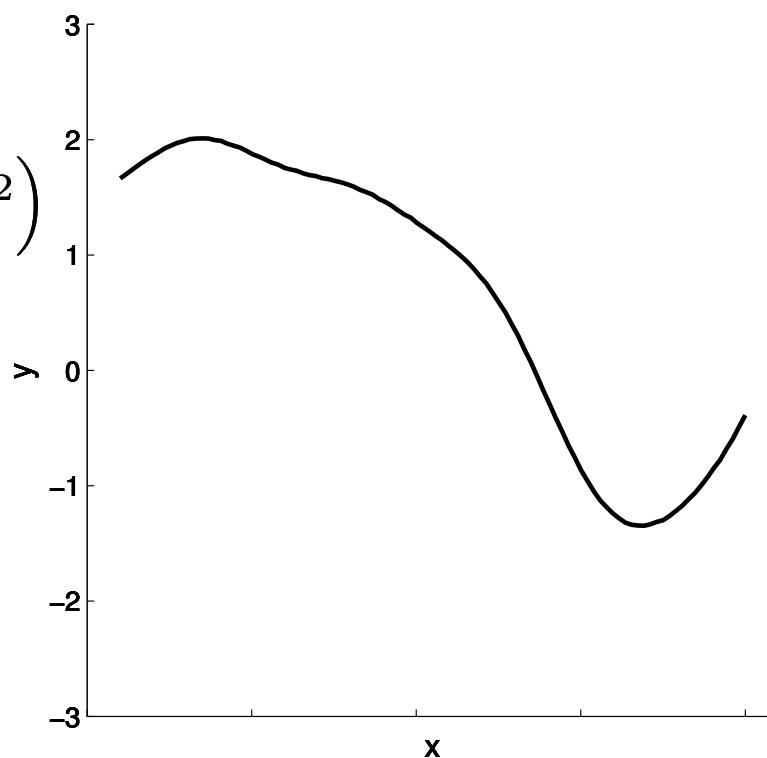
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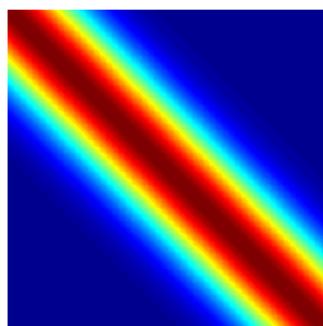
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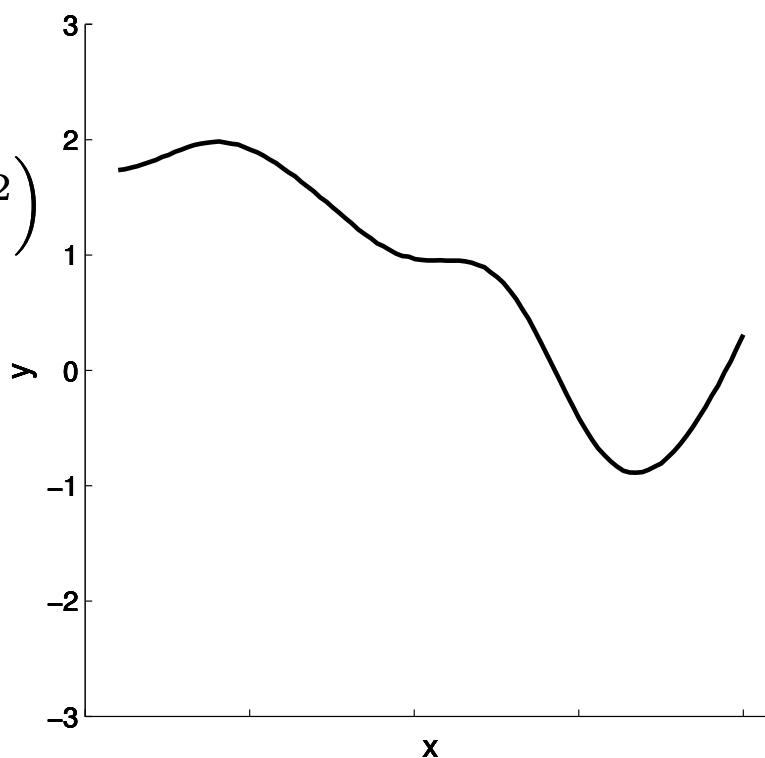
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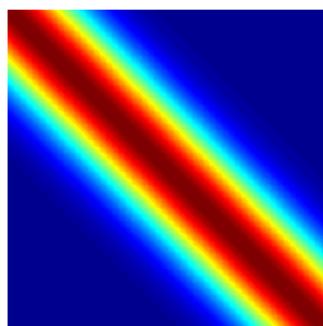
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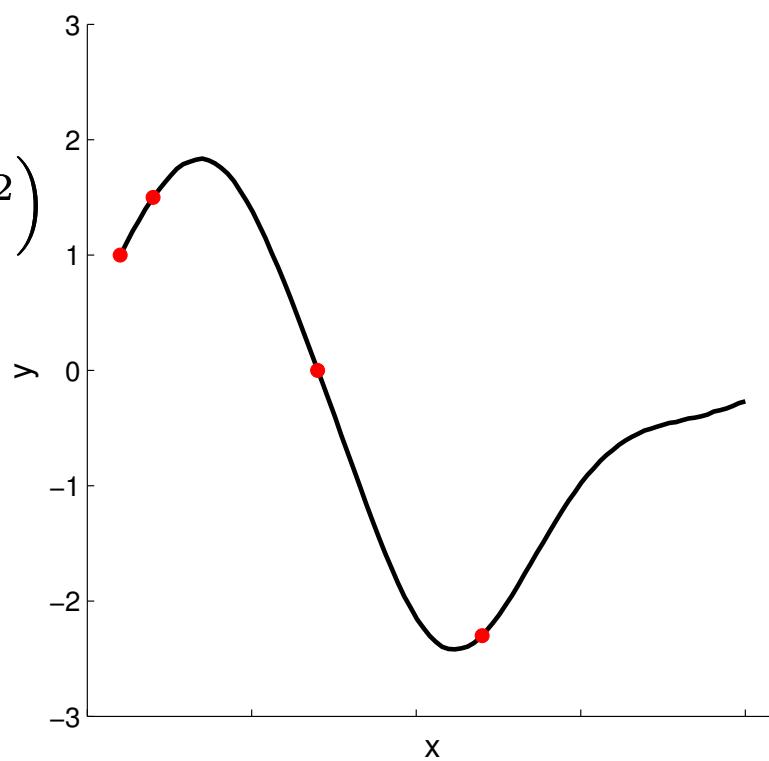
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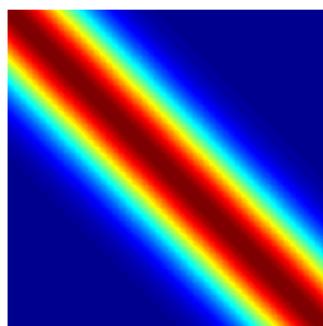
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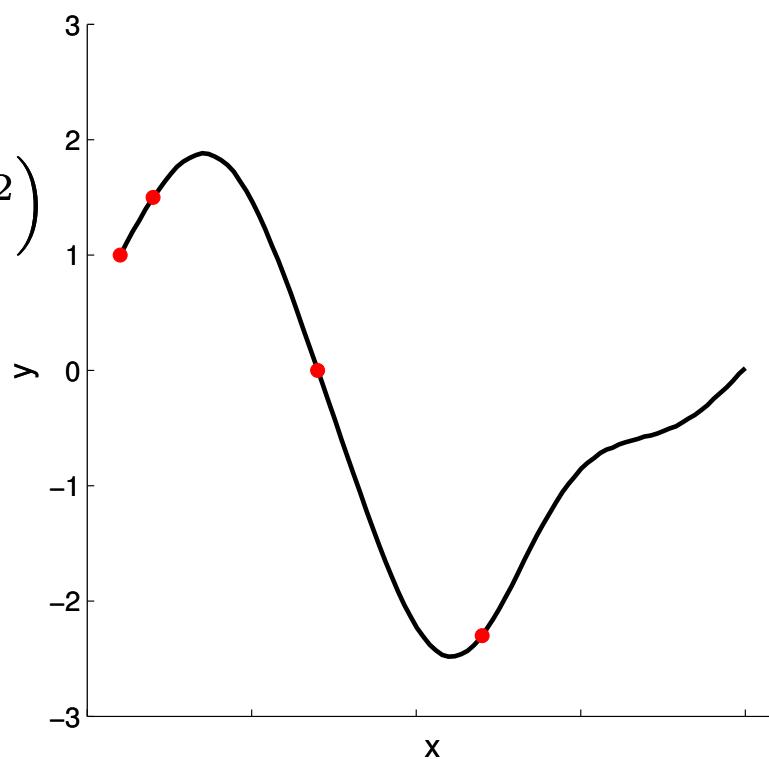
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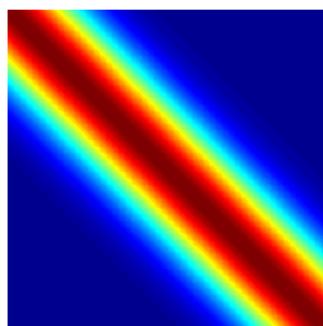
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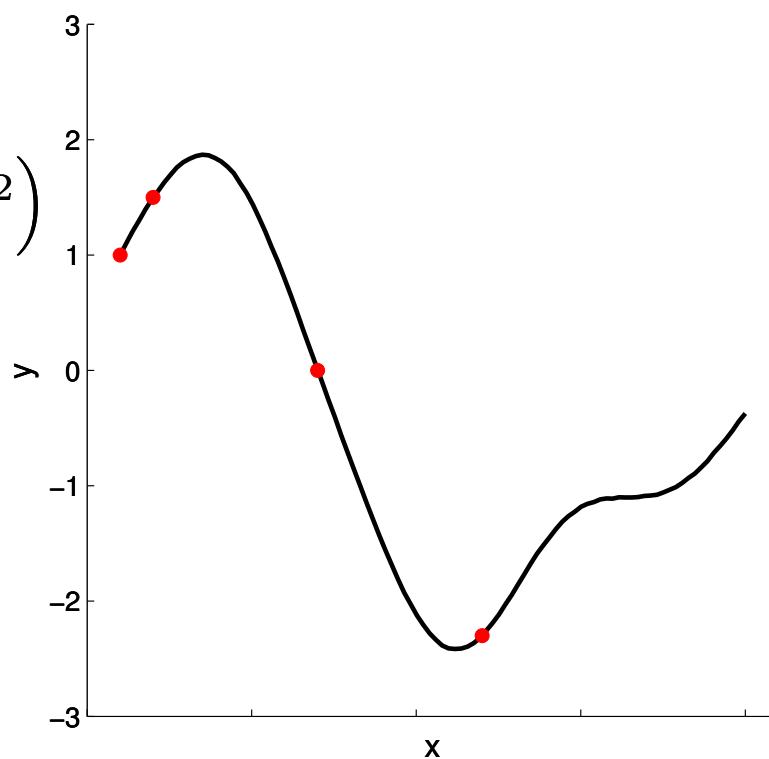
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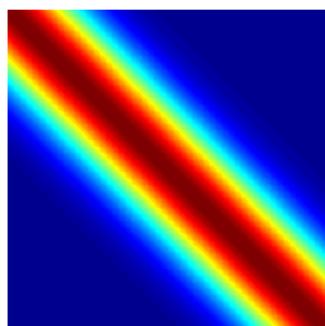
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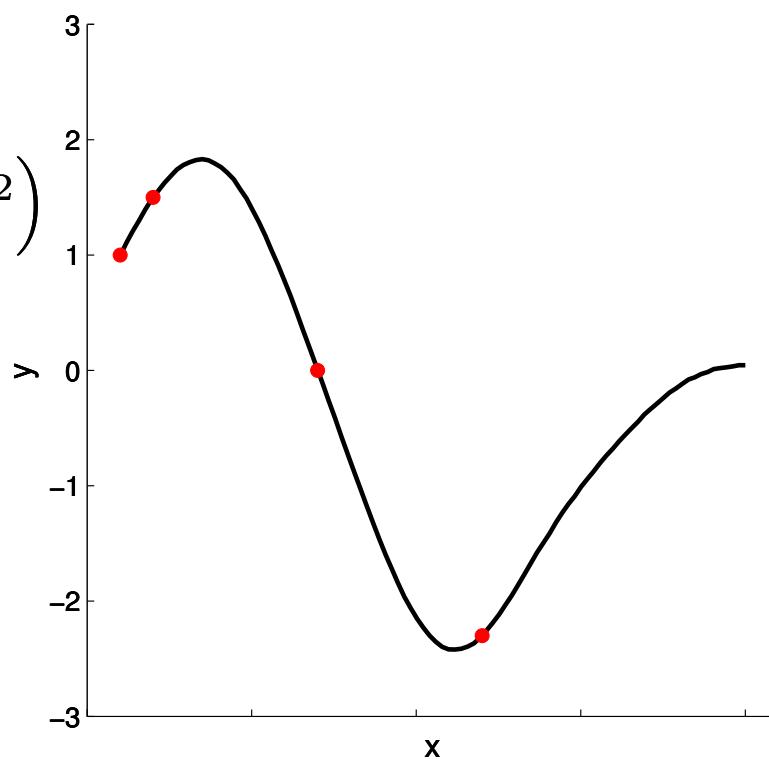
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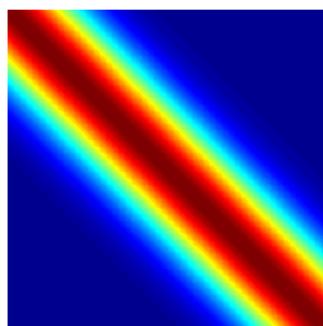
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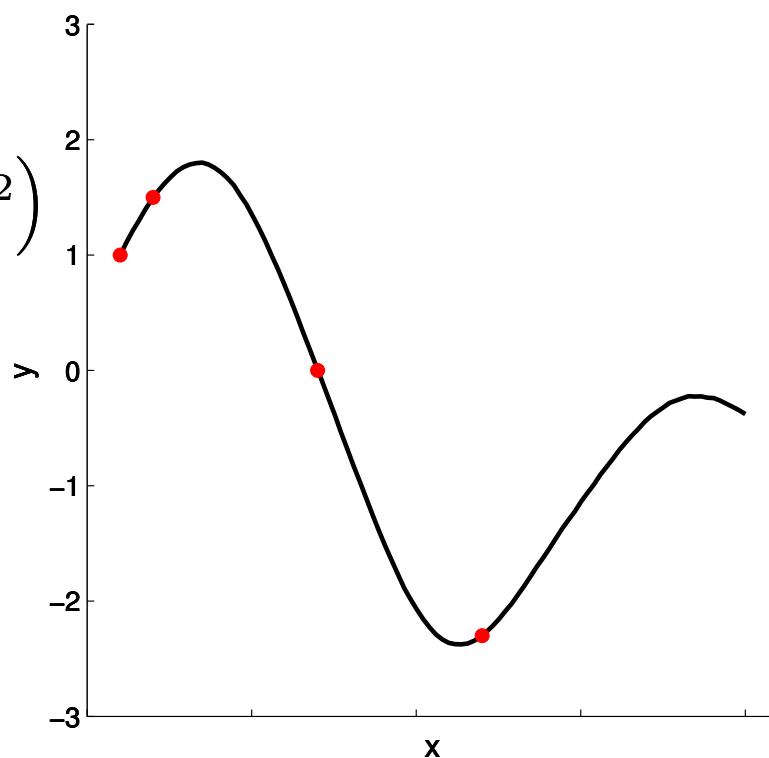
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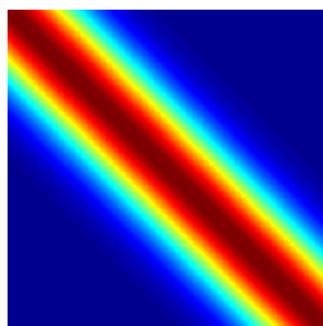
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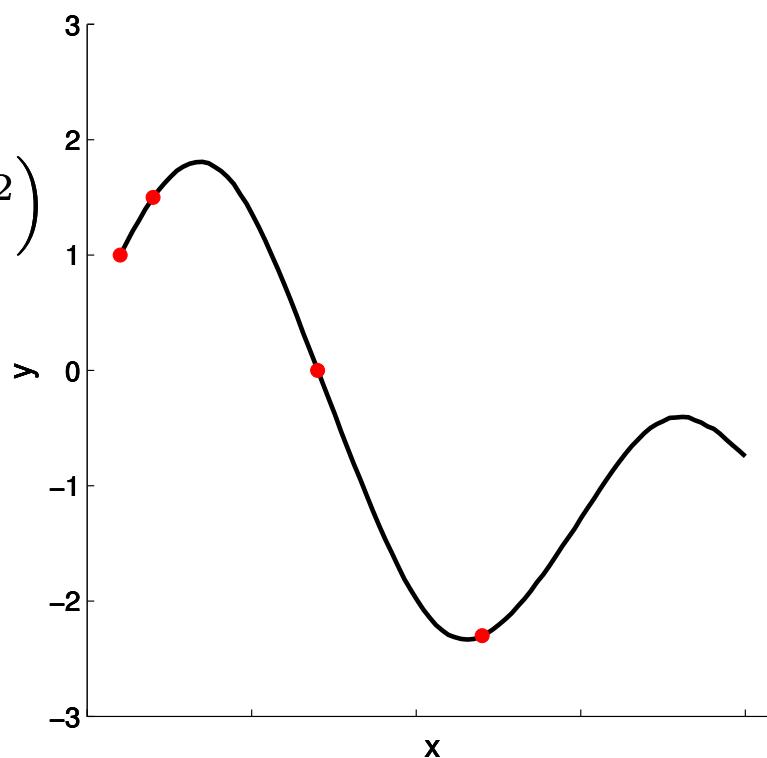
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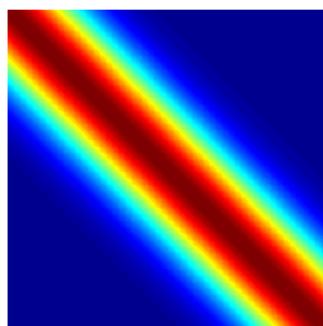
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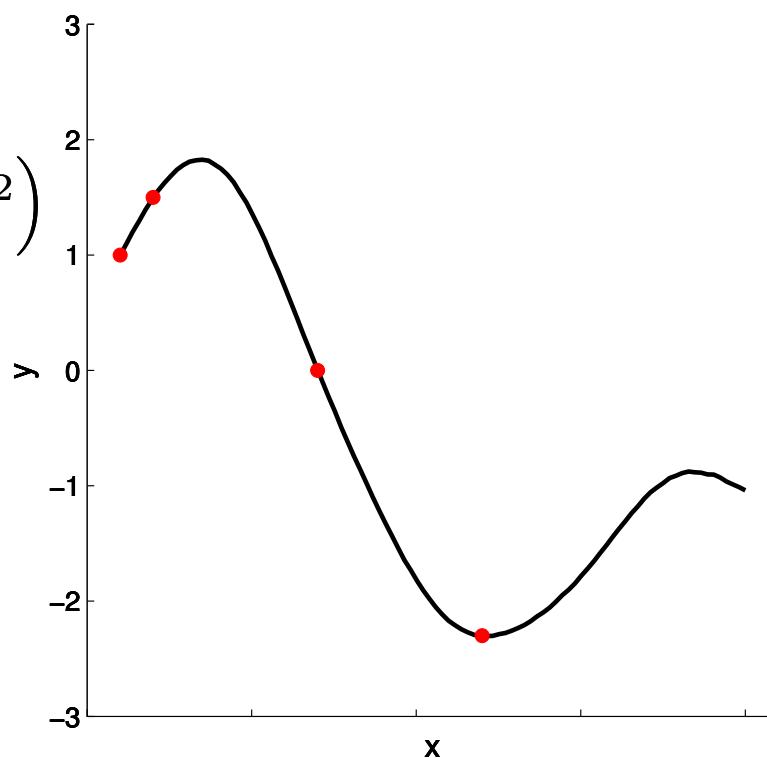
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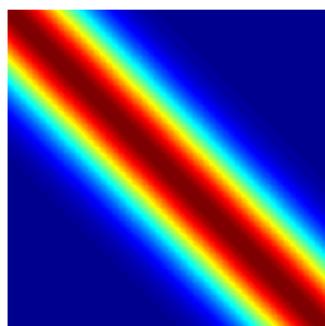
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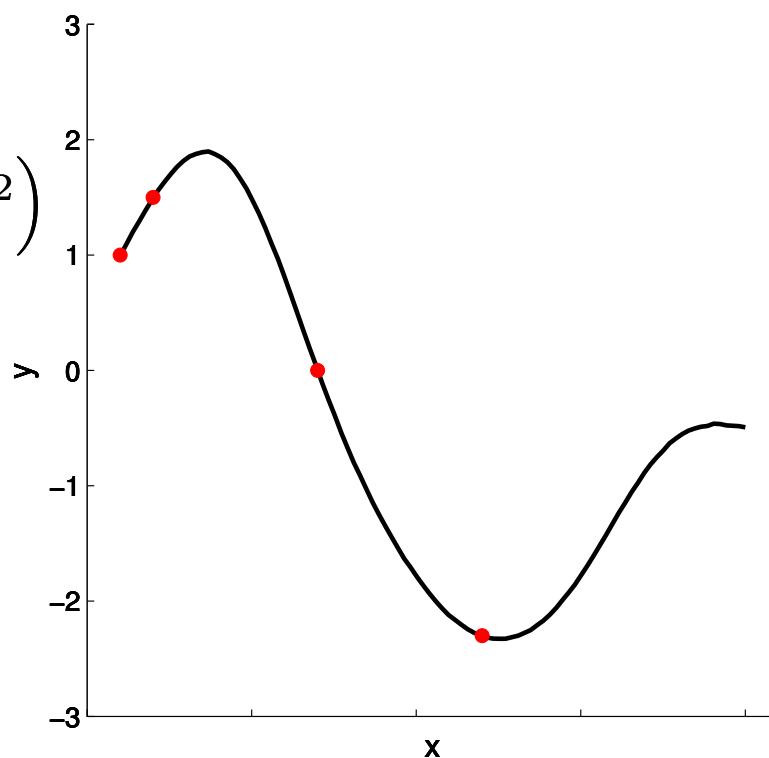
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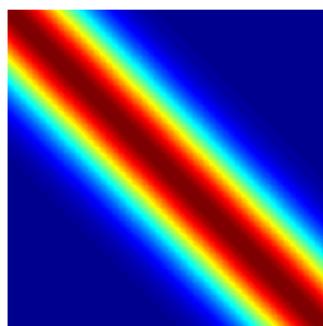
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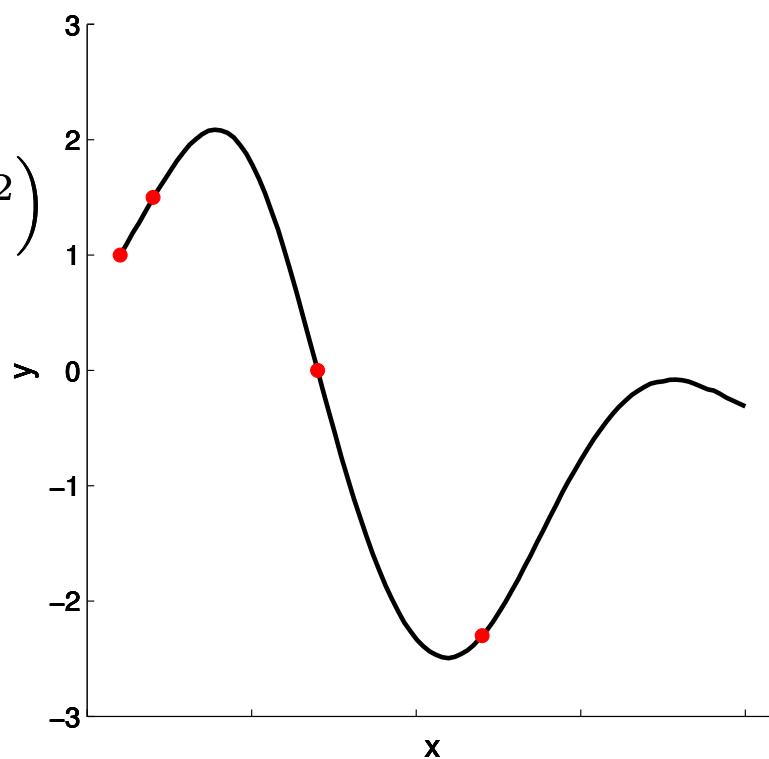
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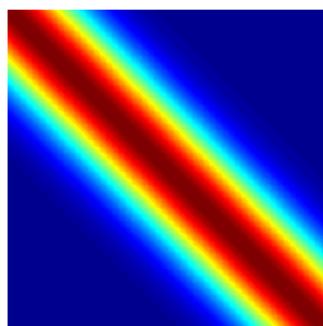
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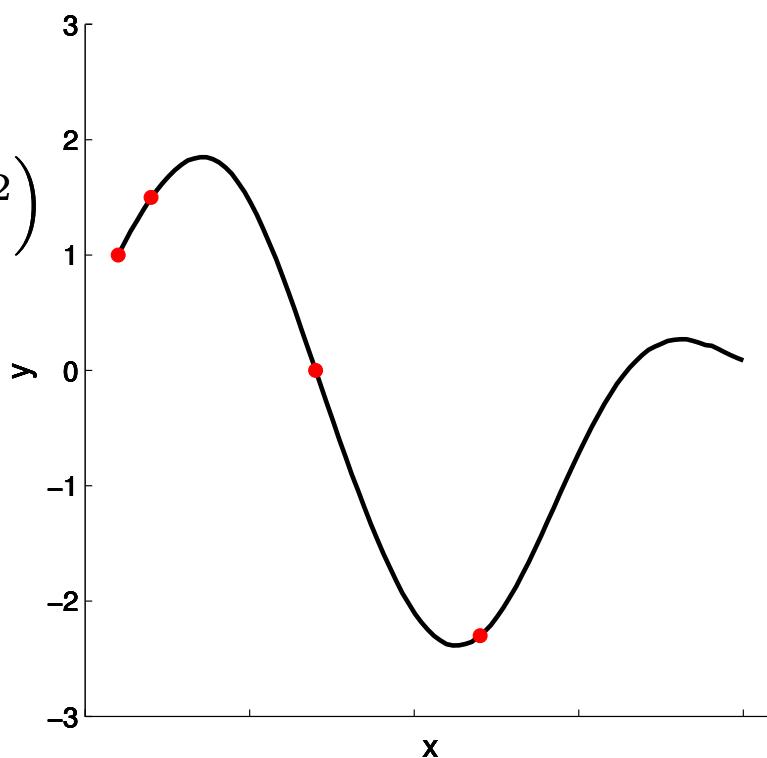
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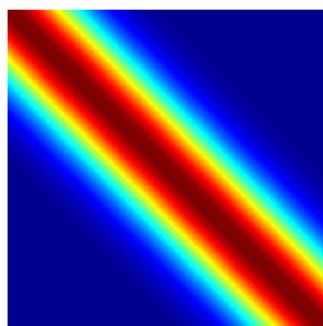
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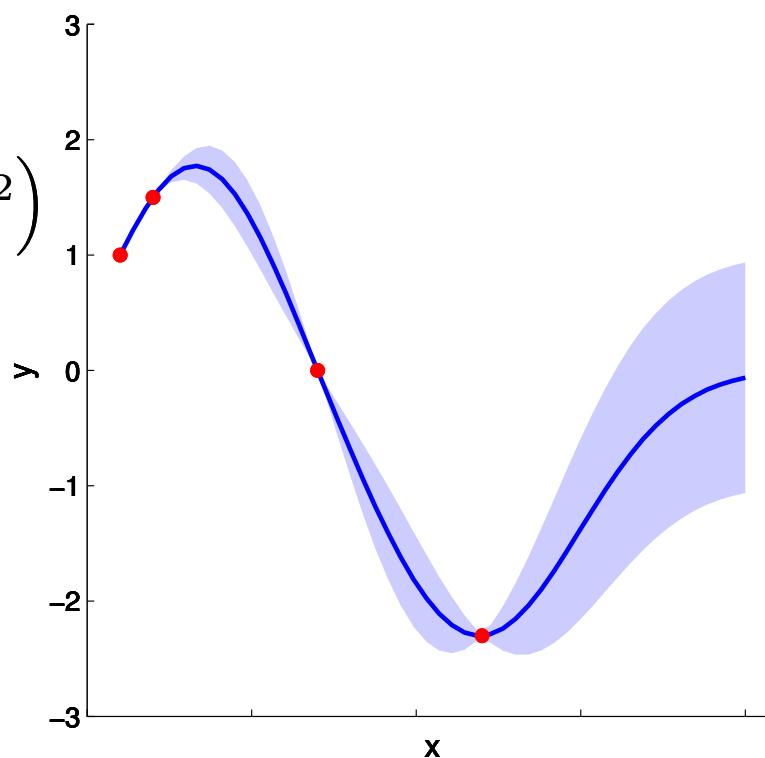
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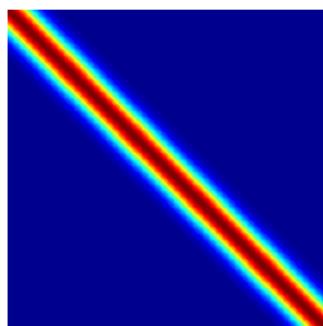
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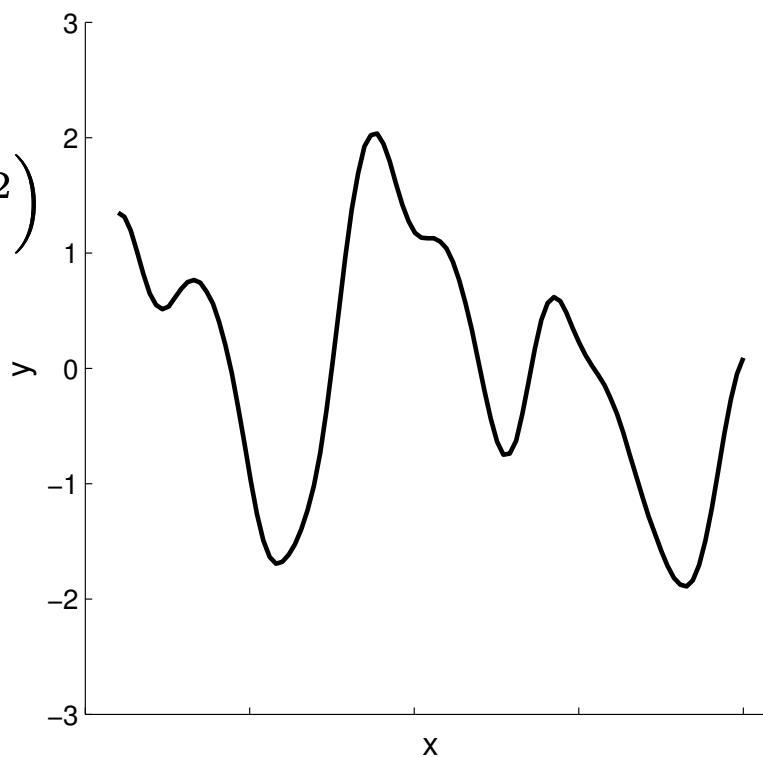


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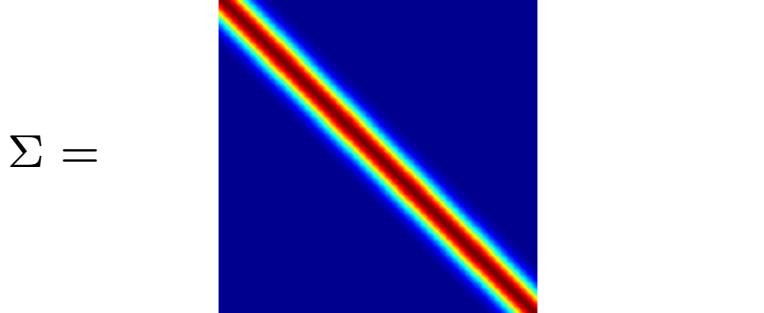
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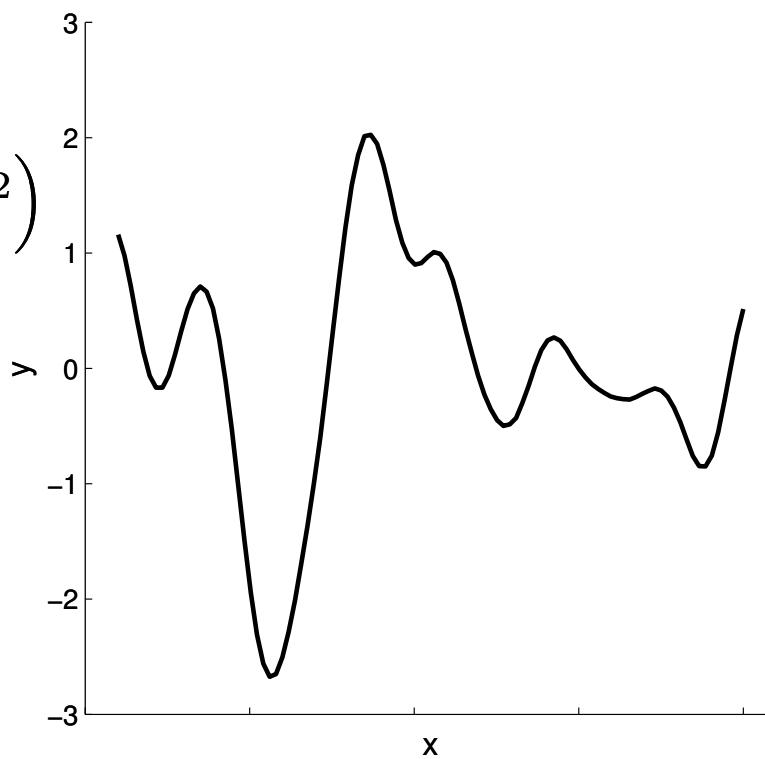


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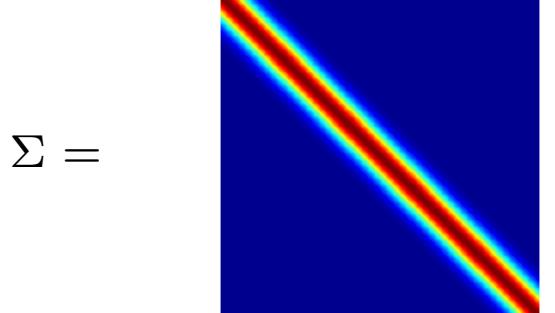
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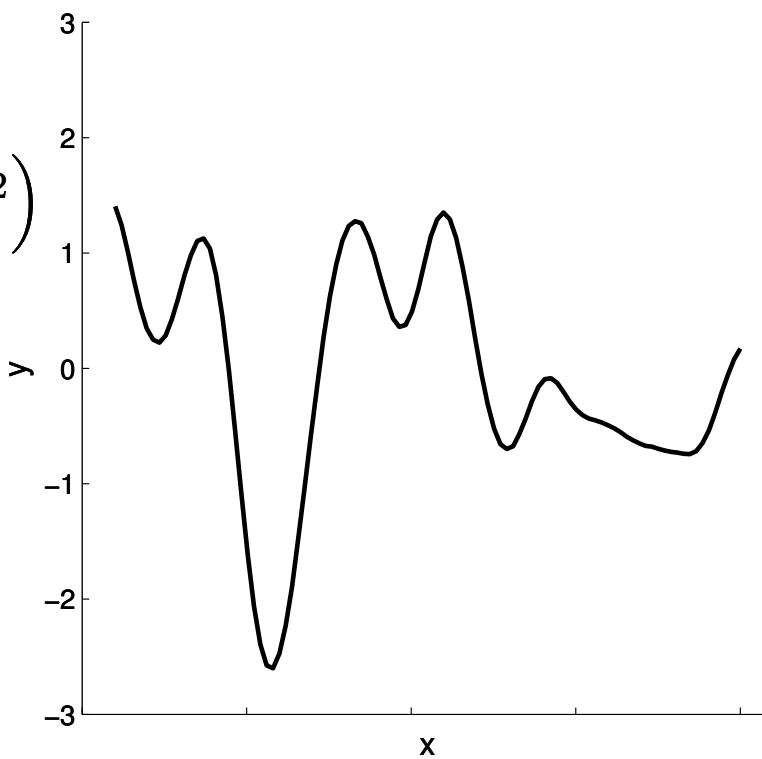


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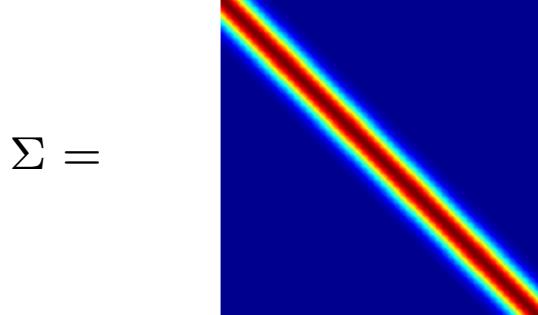
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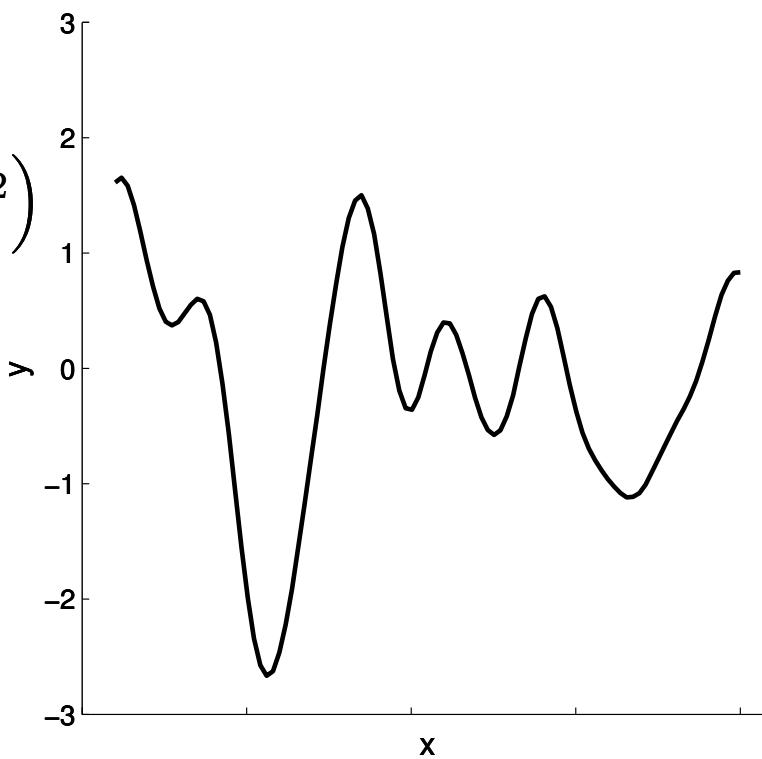


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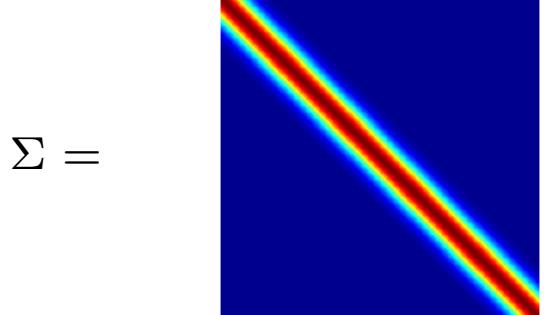
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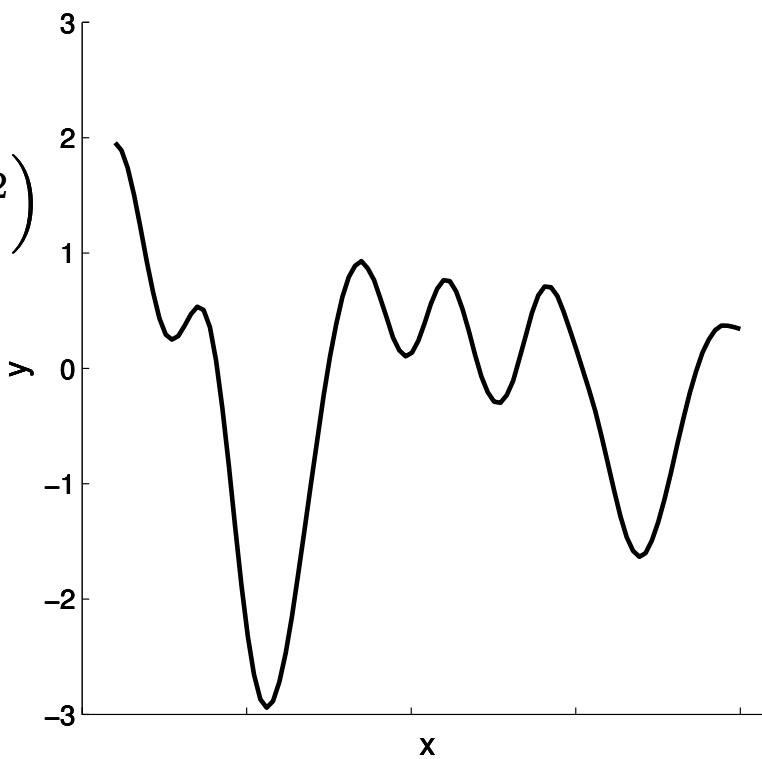


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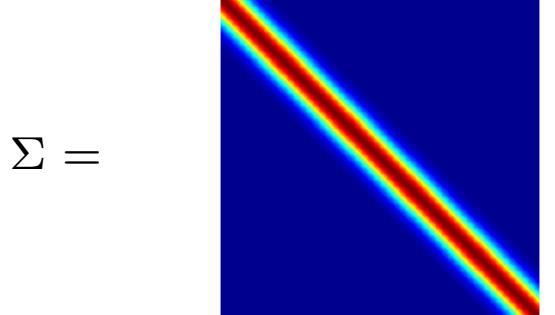
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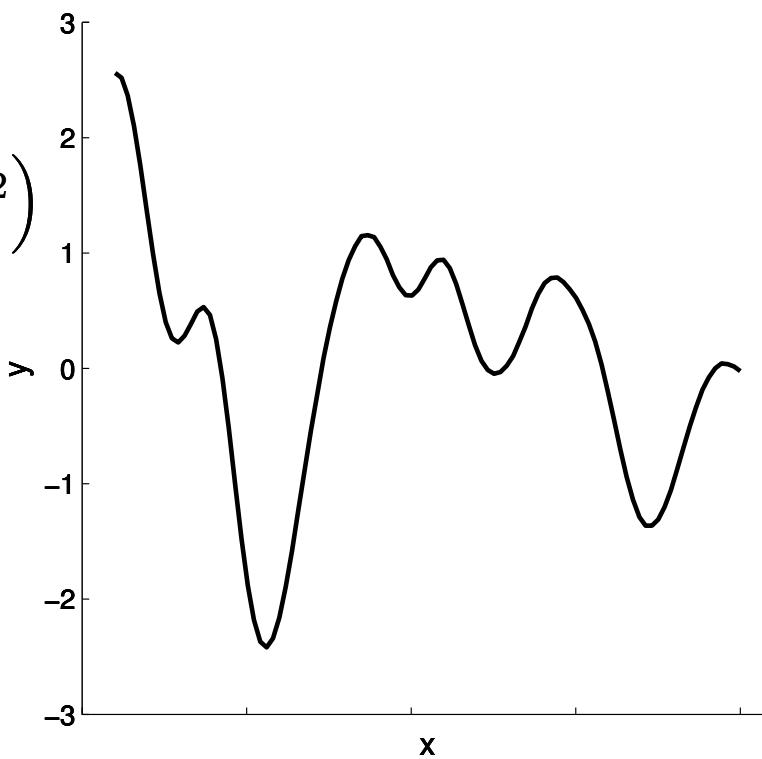


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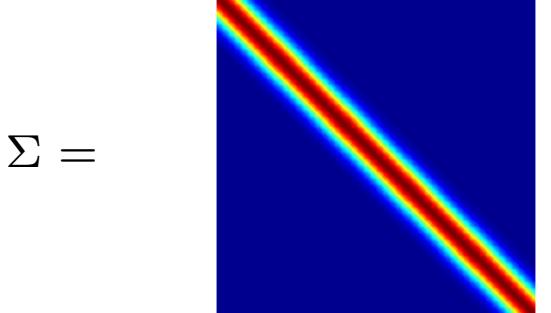
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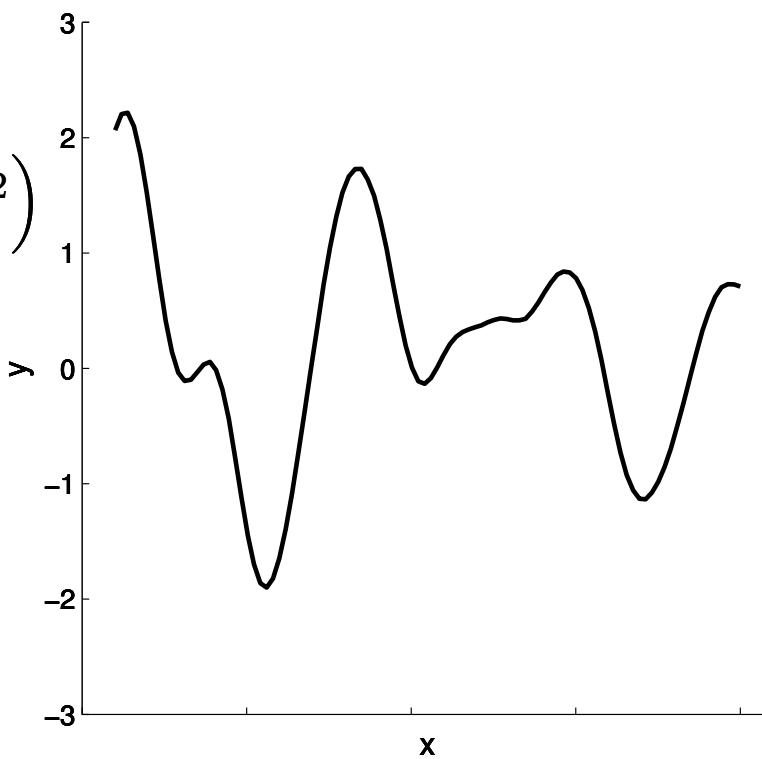


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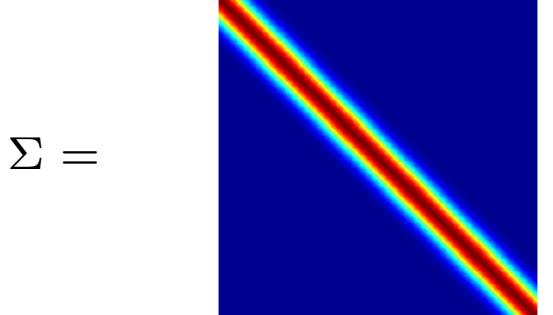
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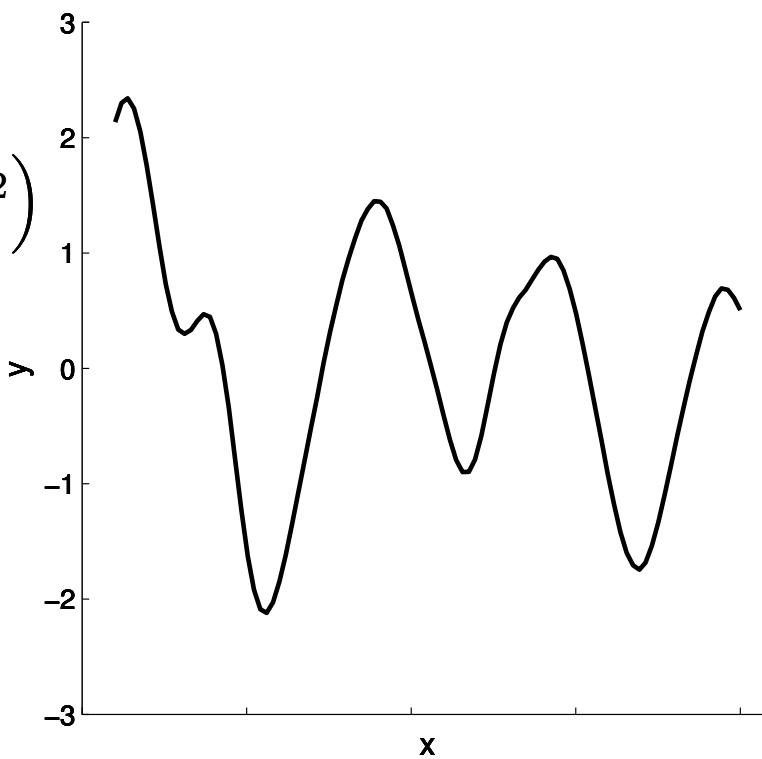


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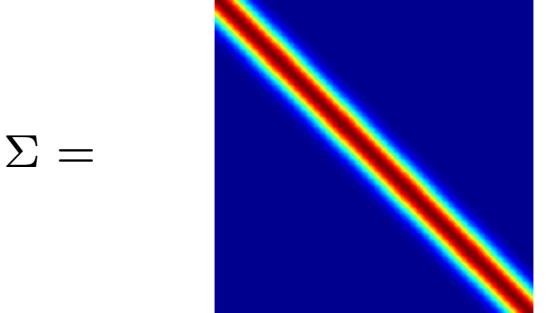
short horizontal length-scale

Non-parametric (∞ -parametric)

$$p(\mathbf{y}|\theta) = \mathcal{N}(0, \Sigma)$$

$$\Sigma(\mathbf{x}_1, \mathbf{x}_2) = K(\mathbf{x}_1, \mathbf{x}_2) + I\sigma_y^2$$

$$K(\mathbf{x}_1, \mathbf{x}_2) = \sigma^2 \exp\left(-\frac{1}{2l^2}(\mathbf{x}_1 - \mathbf{x}_2)^2\right)$$

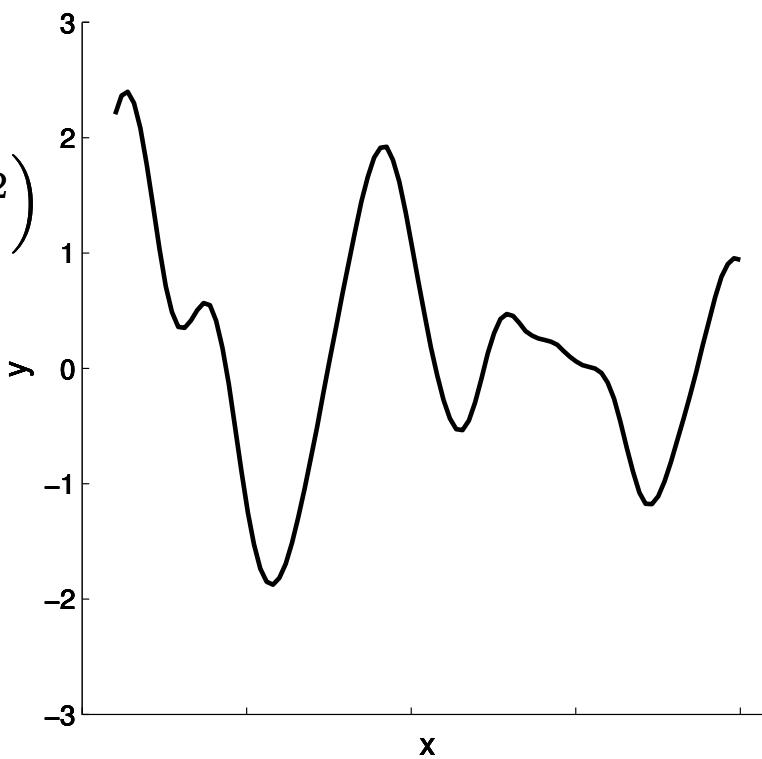


$$\Sigma =$$

Parametric model

$$y(\mathbf{x}) = f(\mathbf{x}; \theta) + \sigma_y \epsilon$$

$$\epsilon \sim \mathcal{N}(0, 1)$$



What effect do the hyper-parameters have?

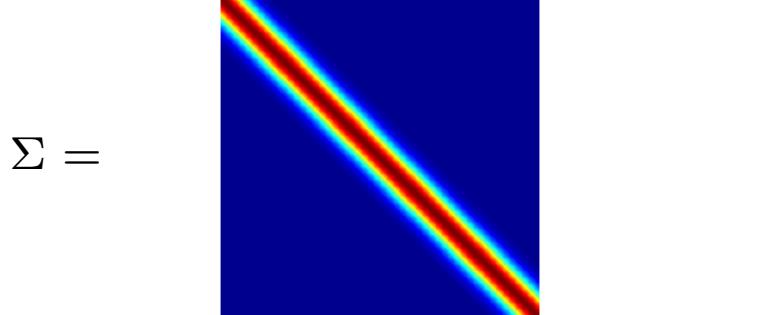
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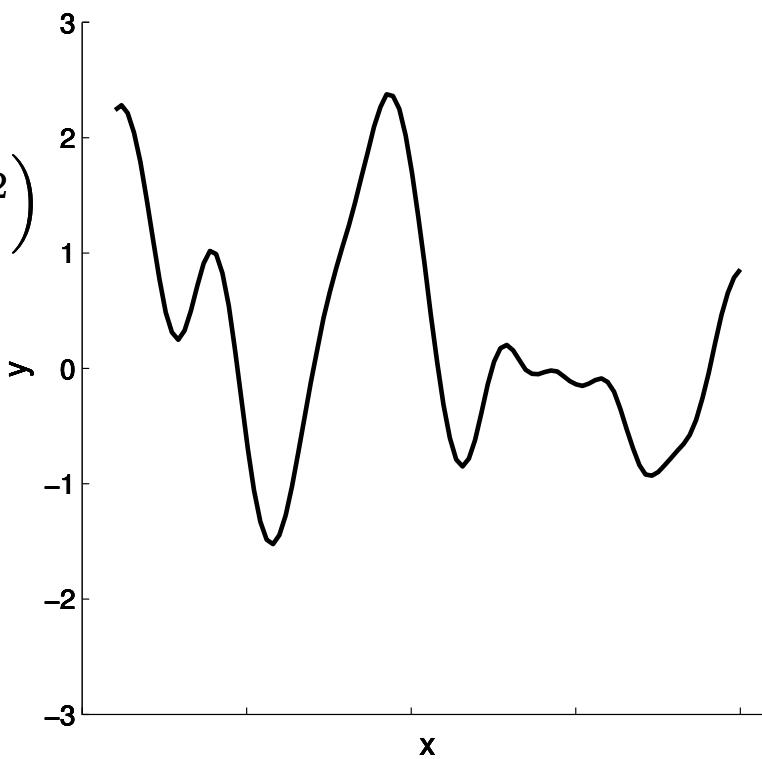


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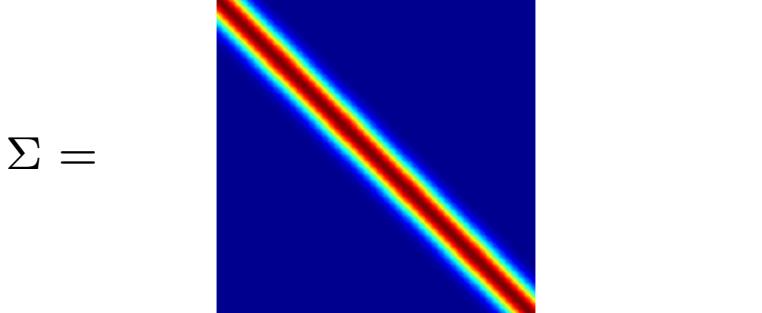
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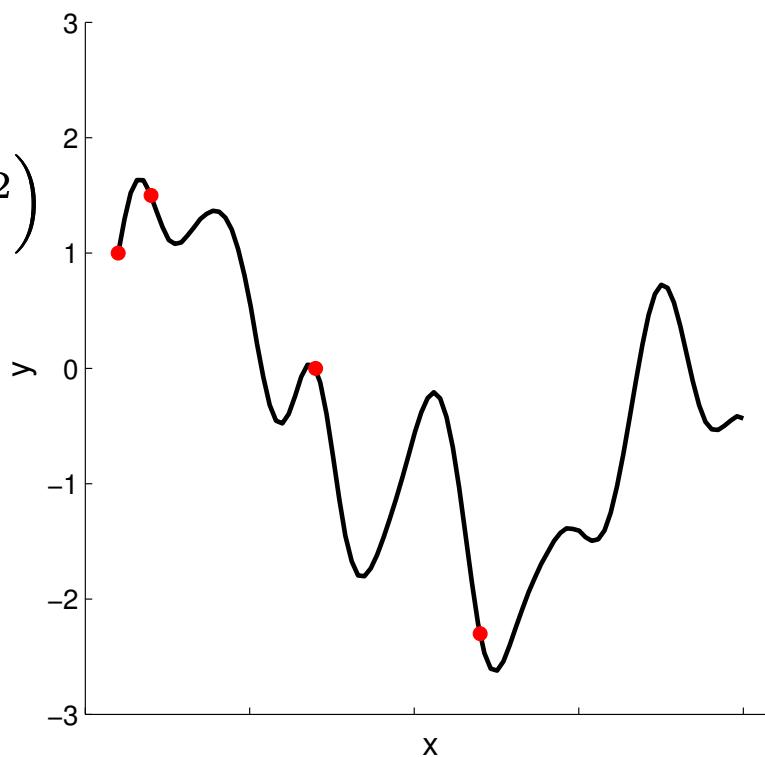


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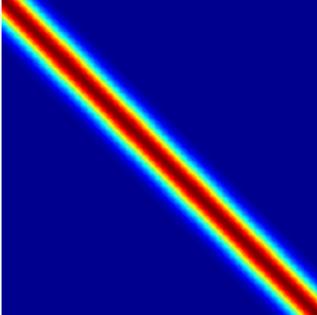
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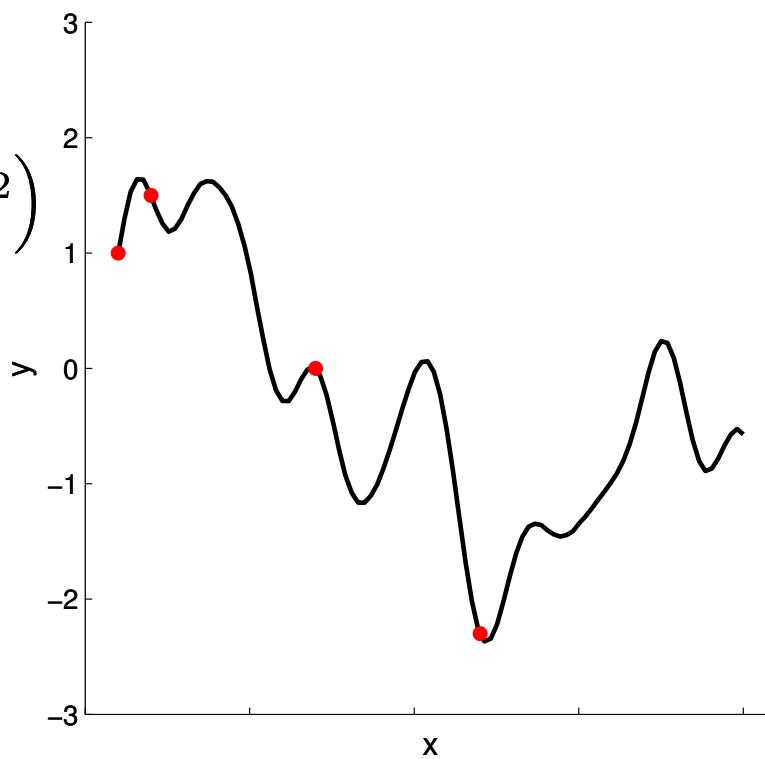
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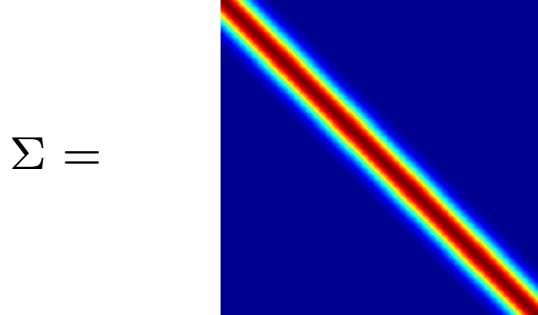
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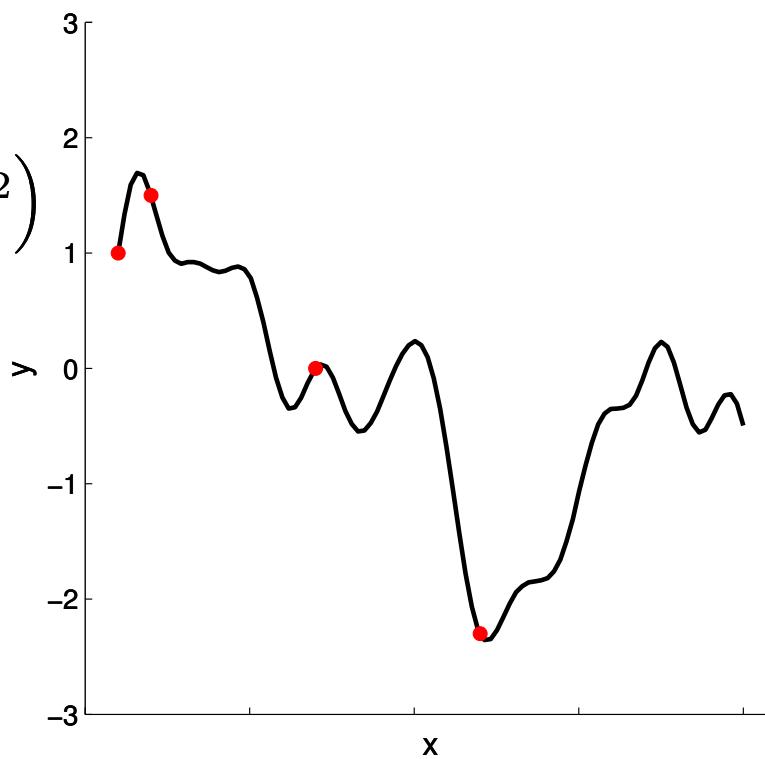


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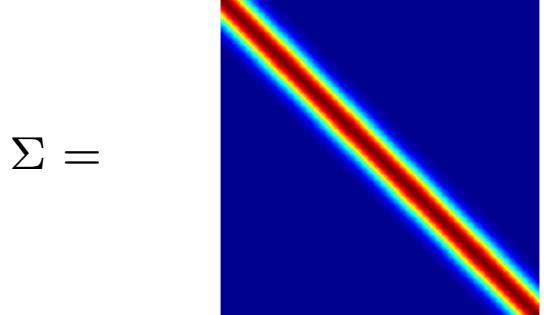
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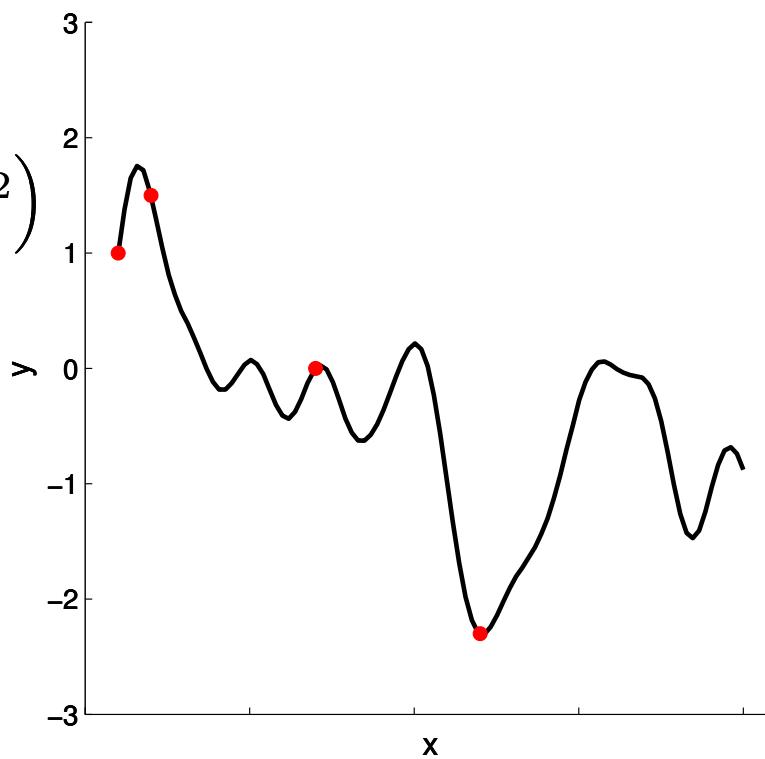


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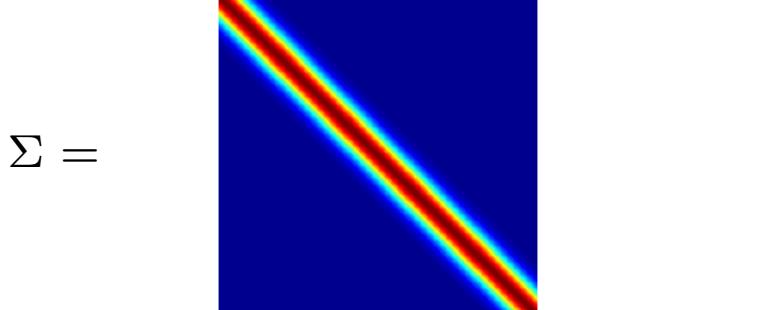
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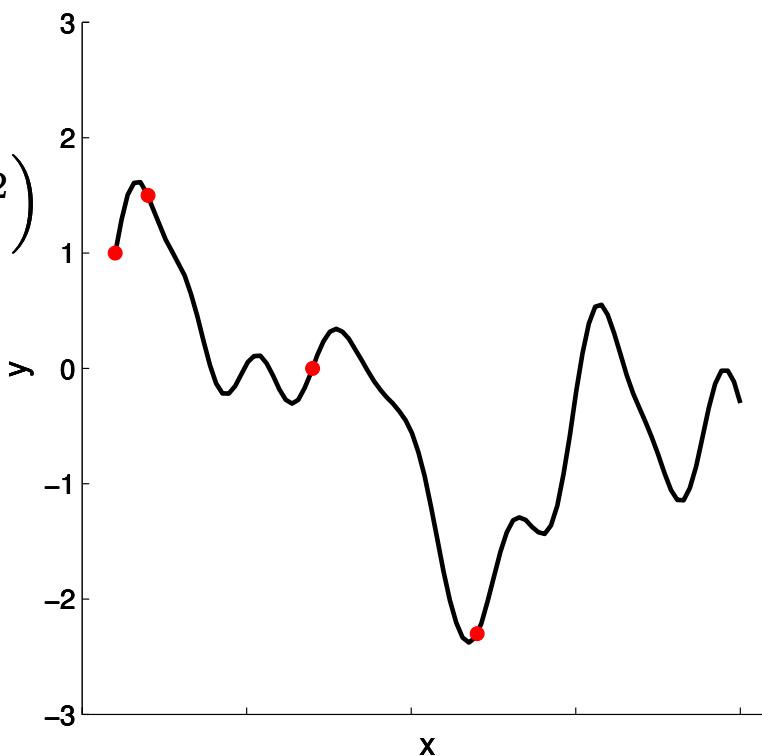


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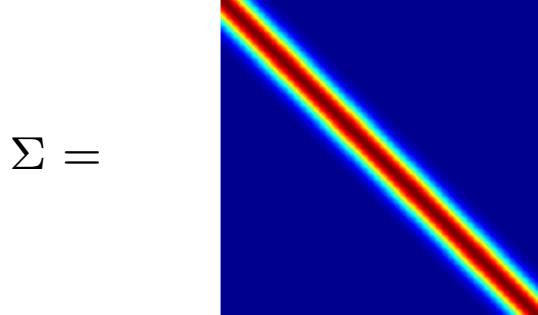
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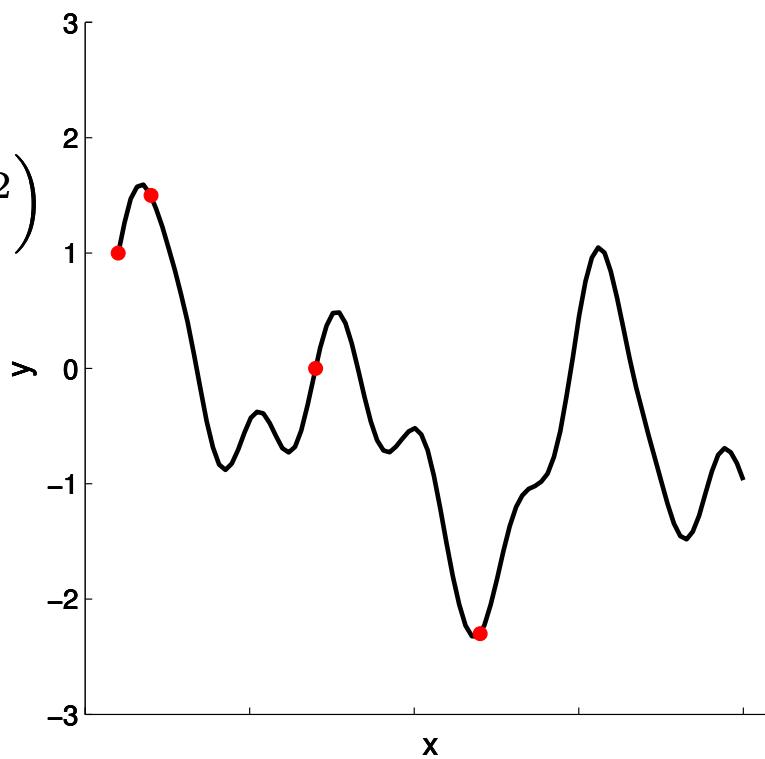


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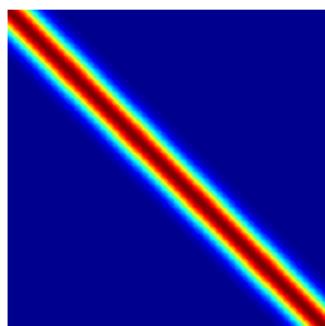
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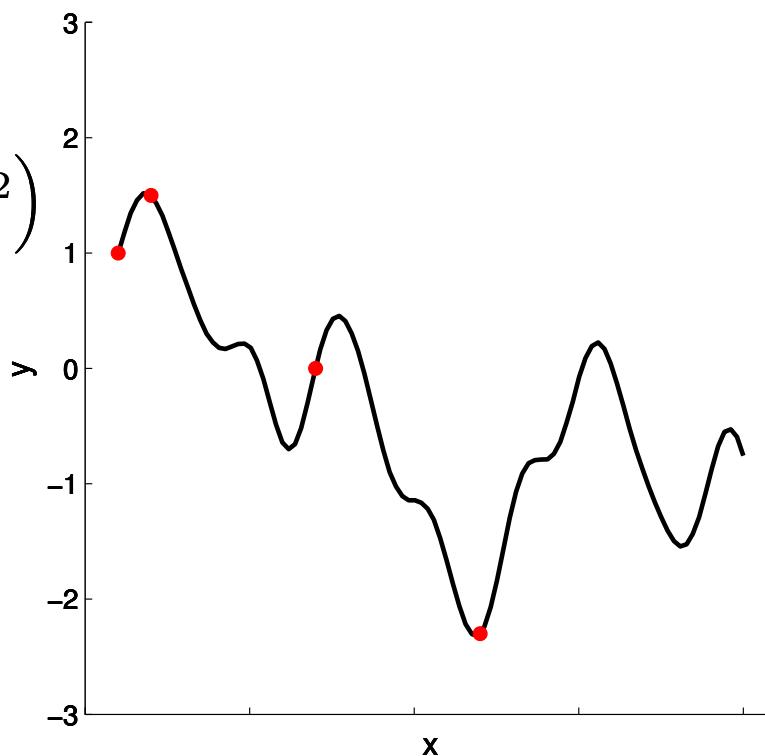
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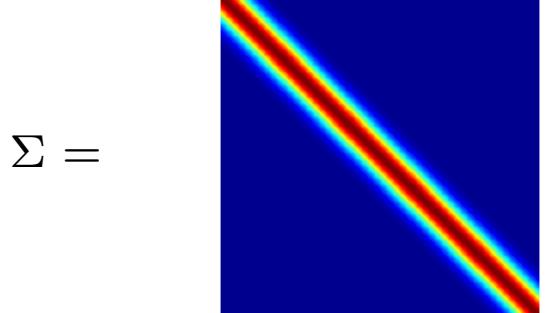
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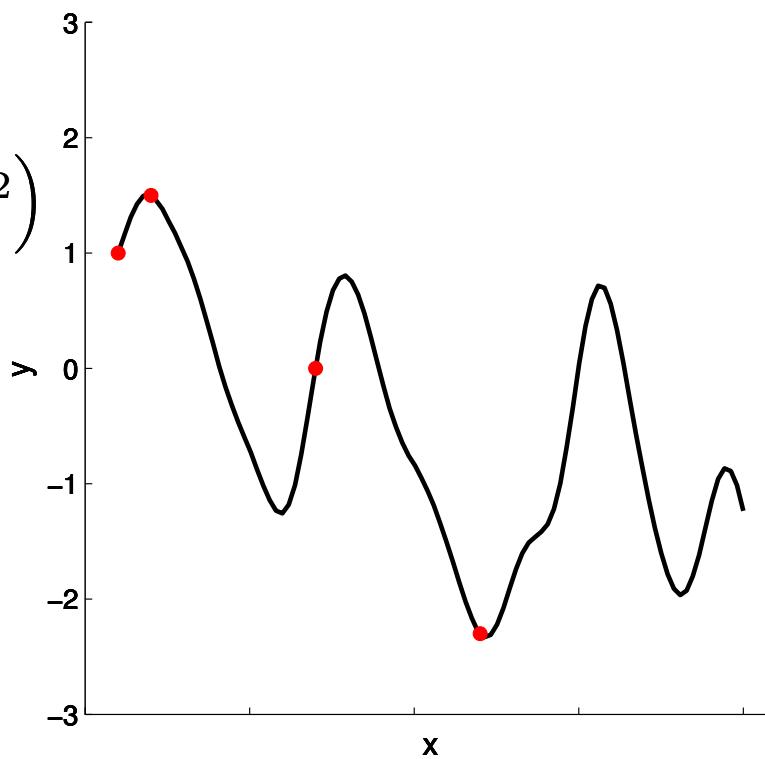


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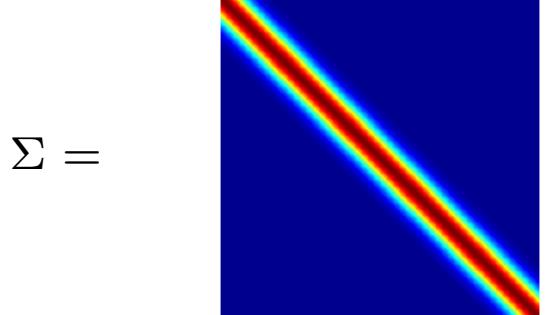
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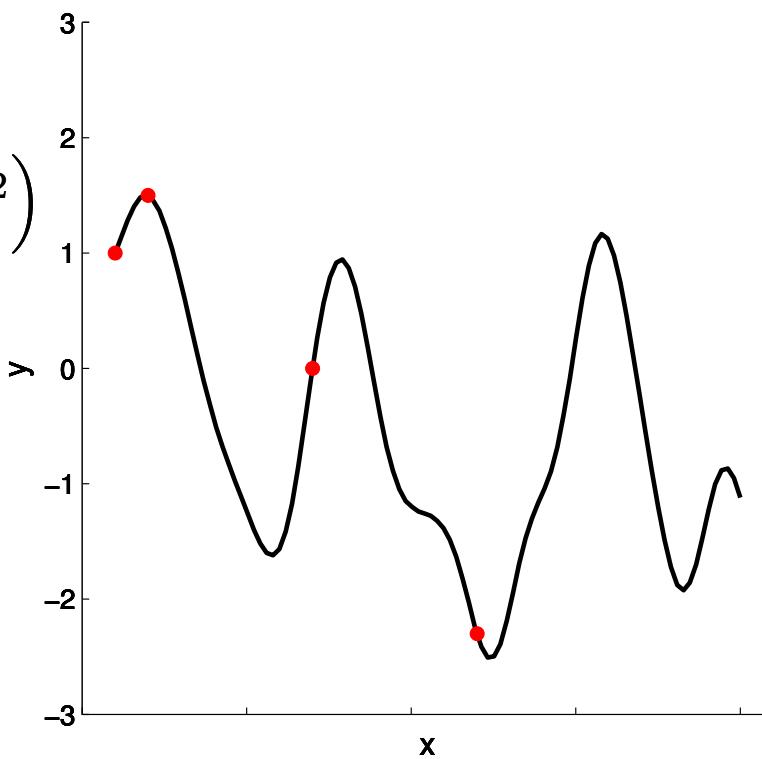


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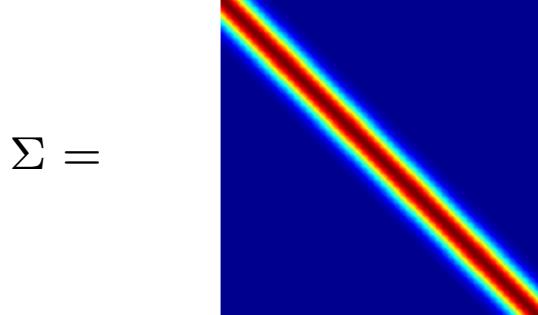
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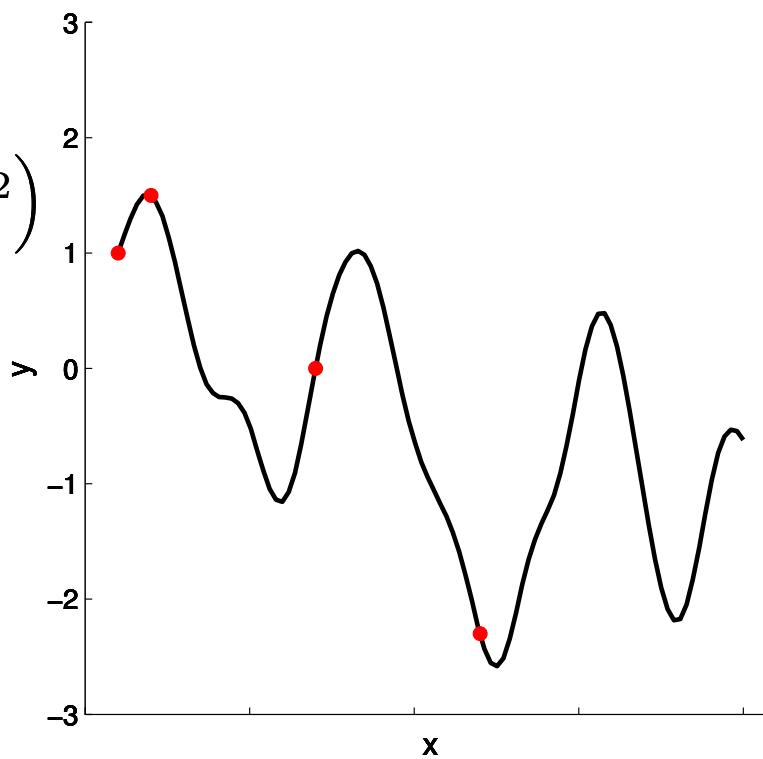


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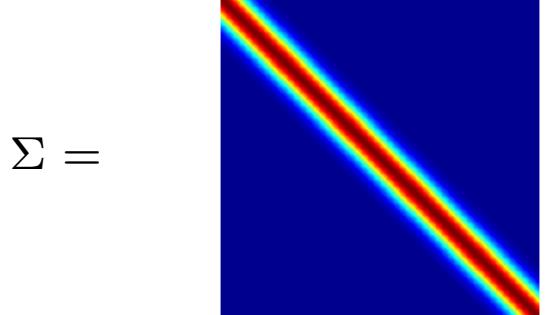
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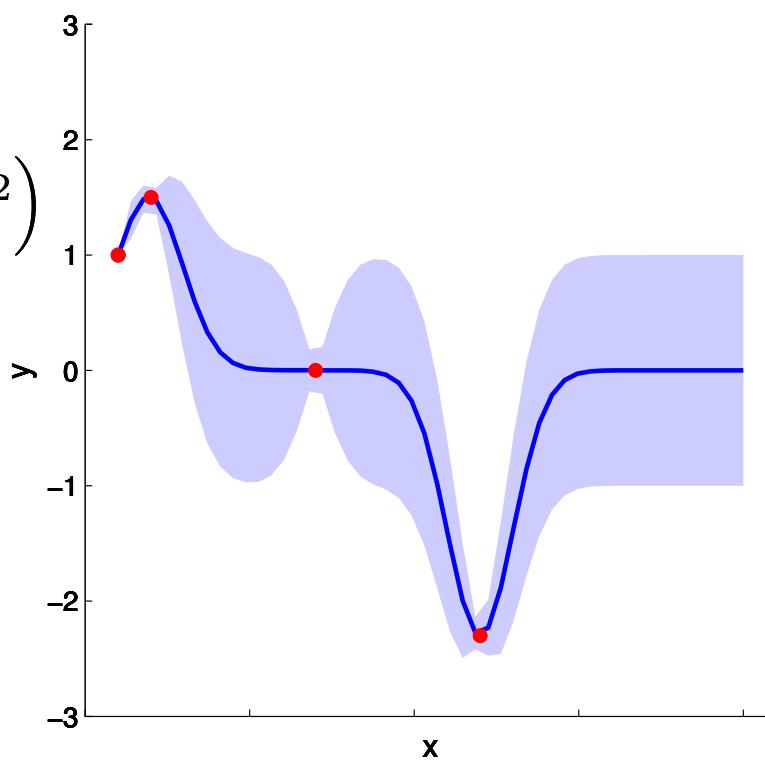


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What effect do the hyper-parameters have?

long horizontal length-scale

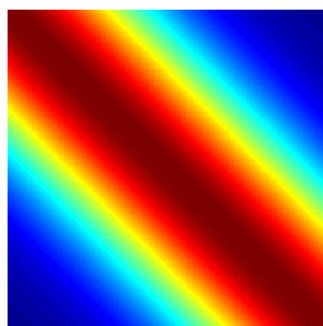
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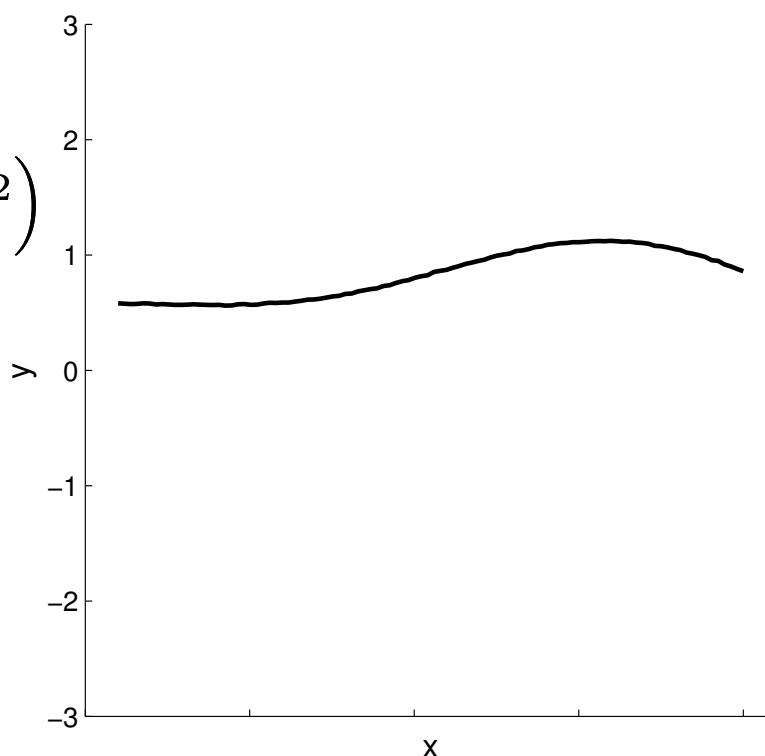
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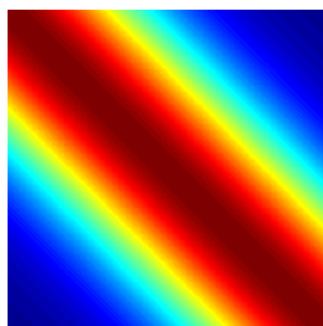
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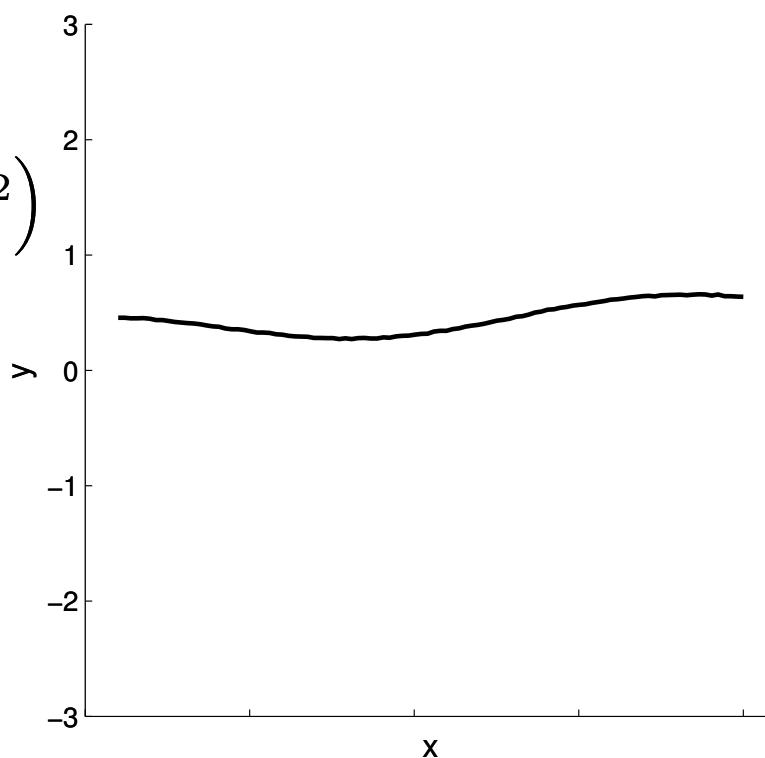
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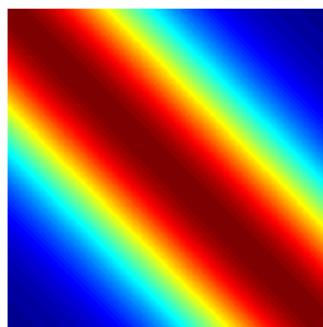
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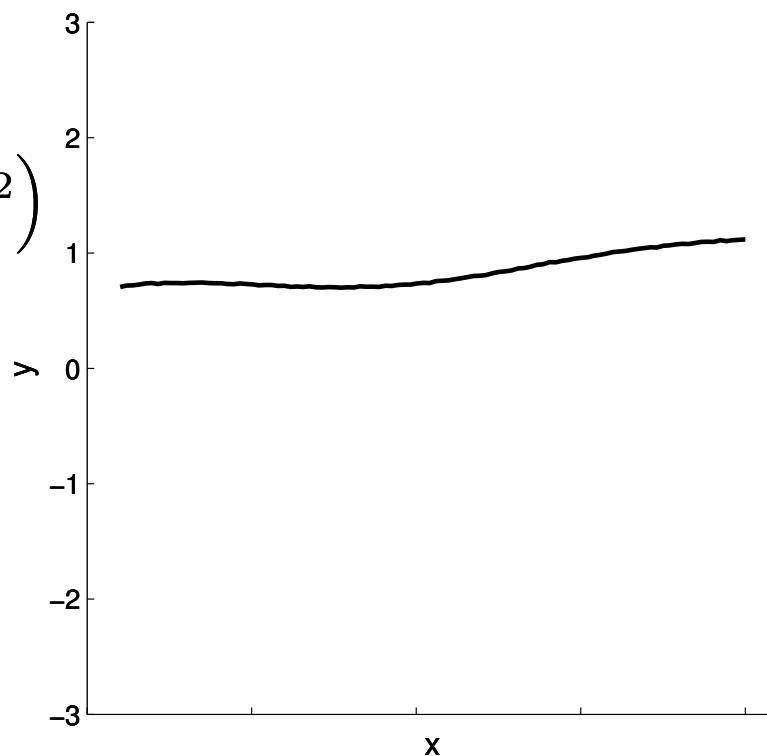
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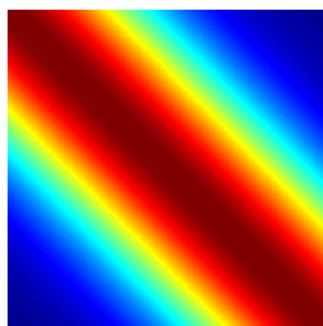
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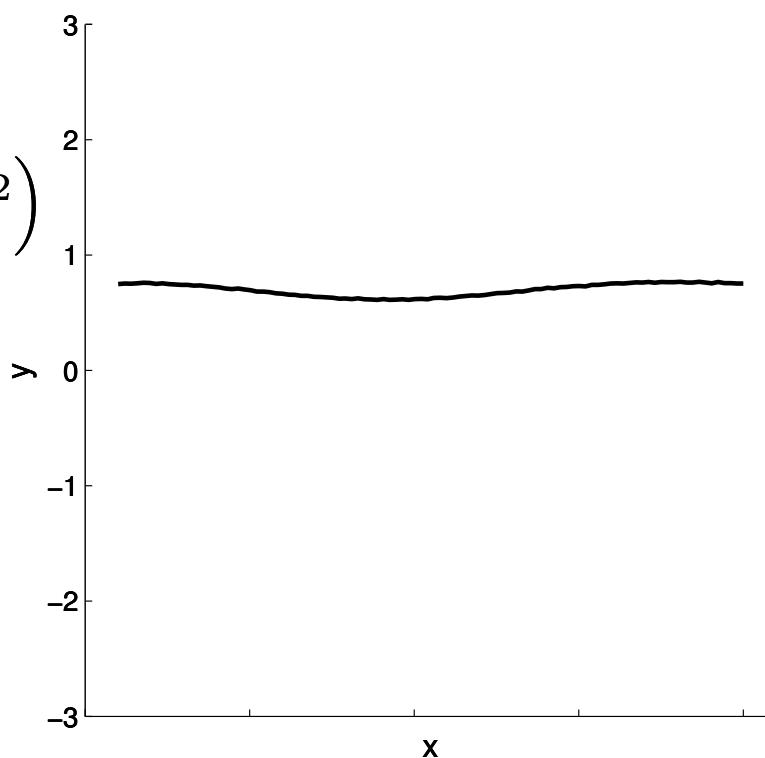
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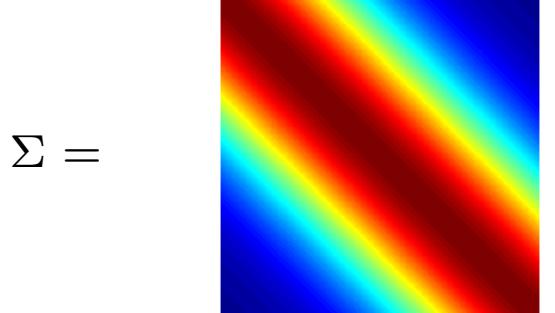
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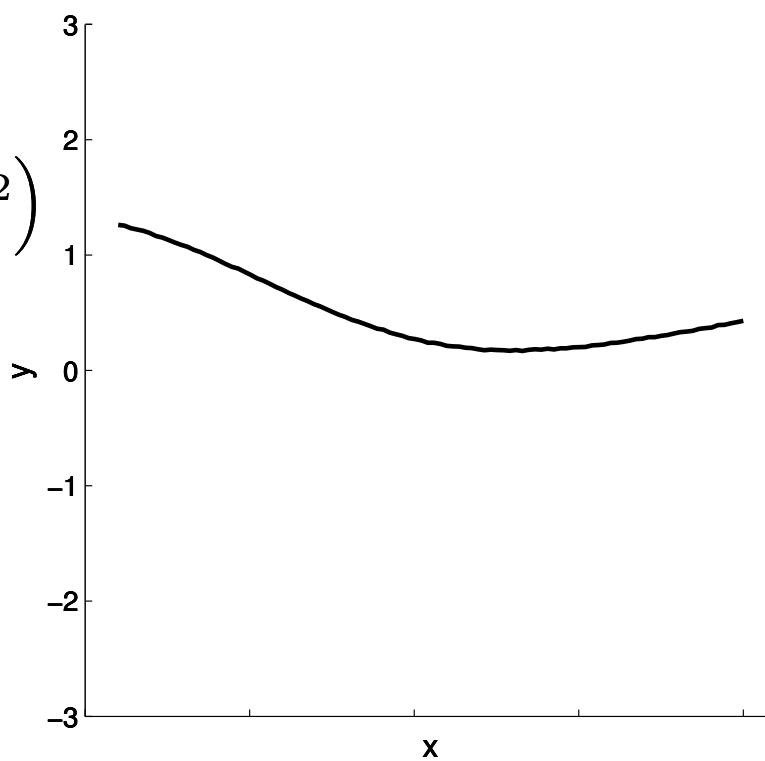


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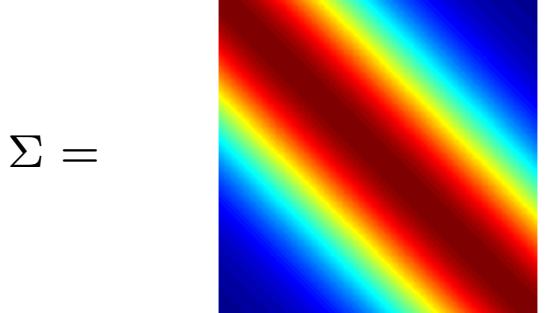
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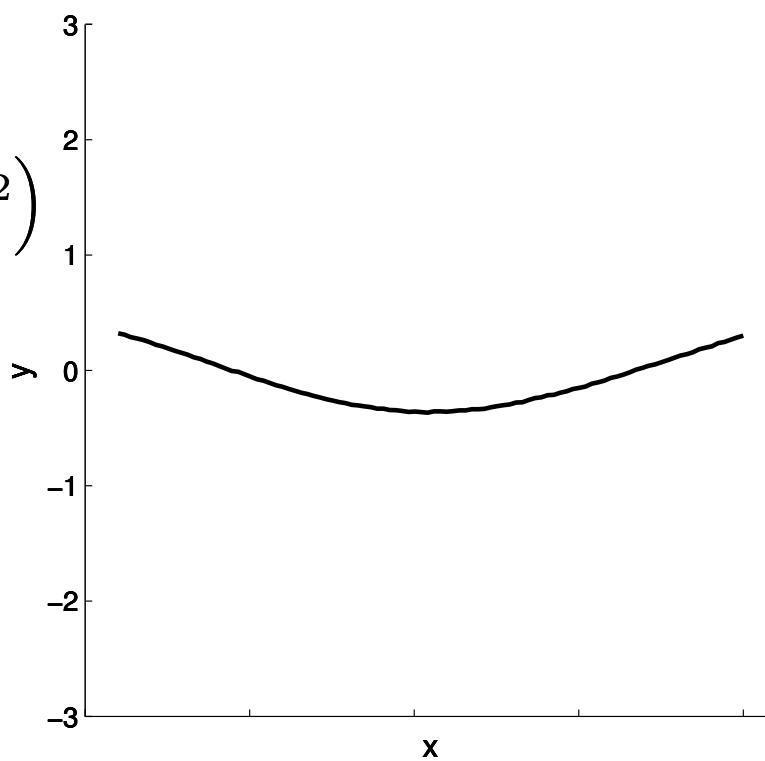


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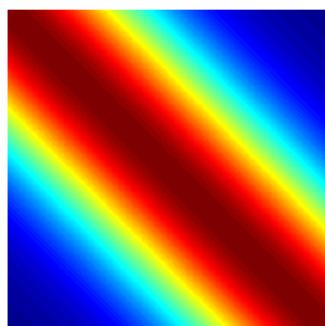
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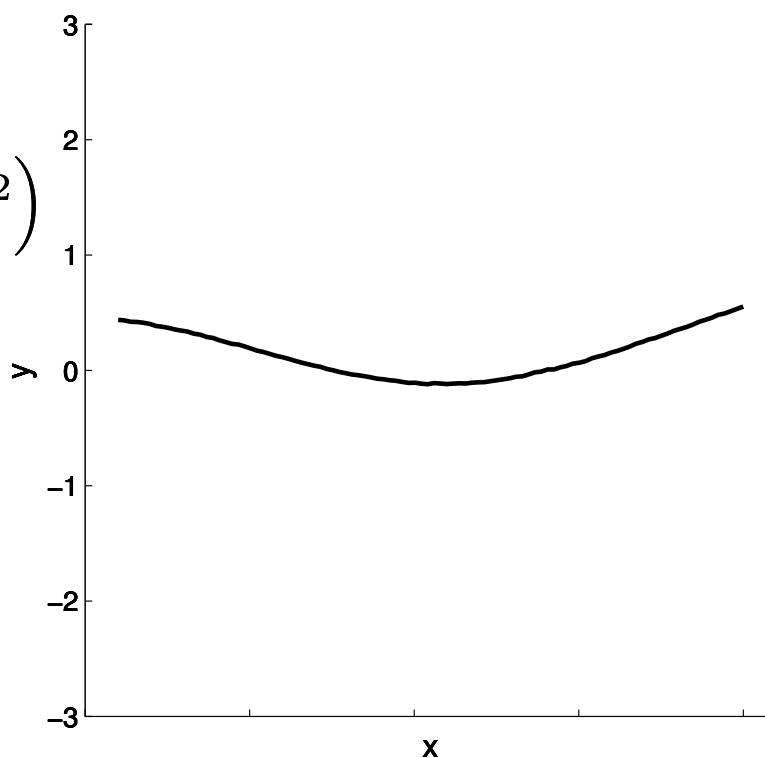


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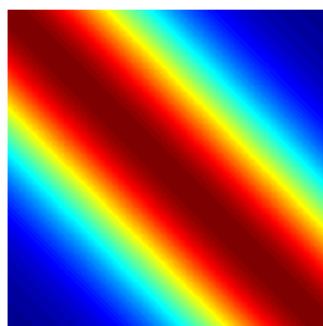
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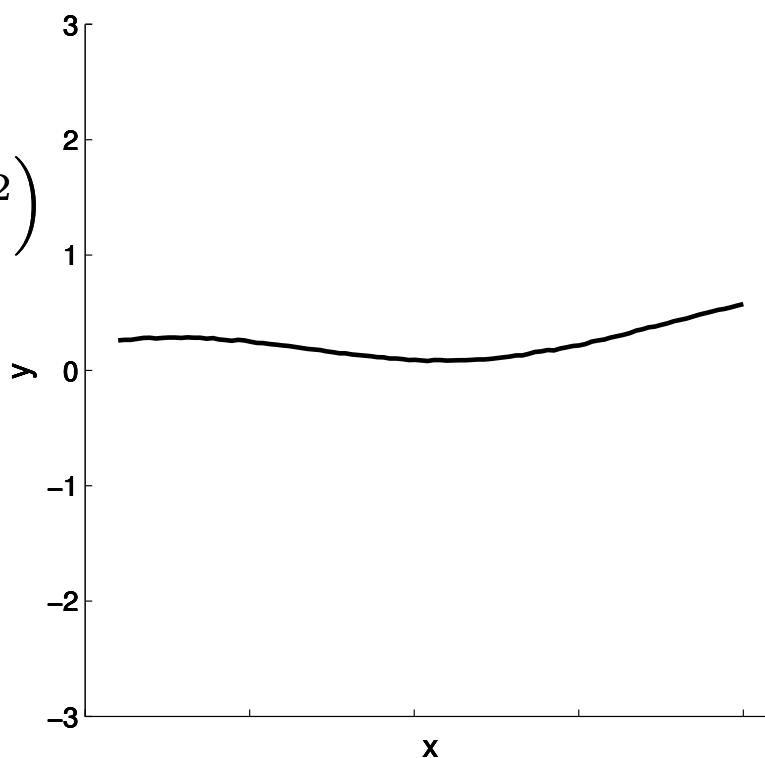
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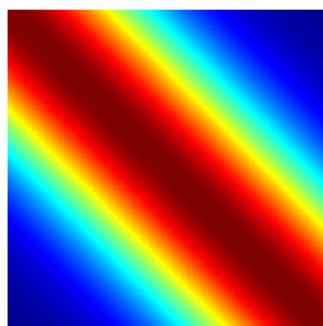
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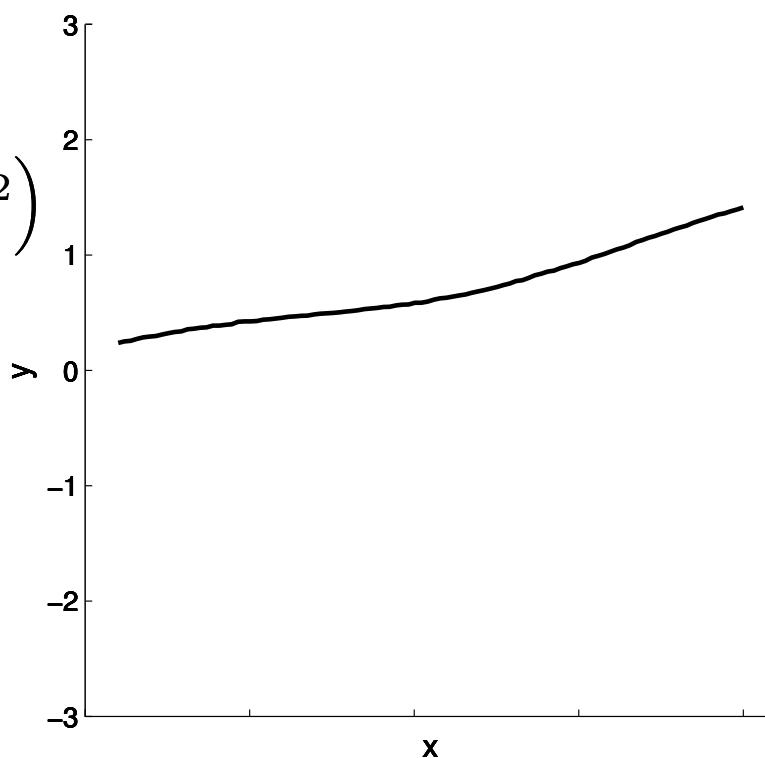
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What effect do the hyper-parameters have?

long horizontal length-scale

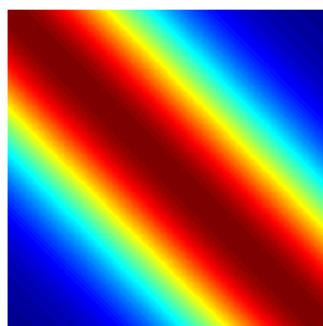
Non-parametric (∞ -parametric)

$$p(\mathbf{y}|\theta) = \mathcal{N}(0, \Sigma)$$

$$\Sigma(\mathbf{x}_1, \mathbf{x}_2) = K(\mathbf{x}_1, \mathbf{x}_2) + I\sigma_y^2$$

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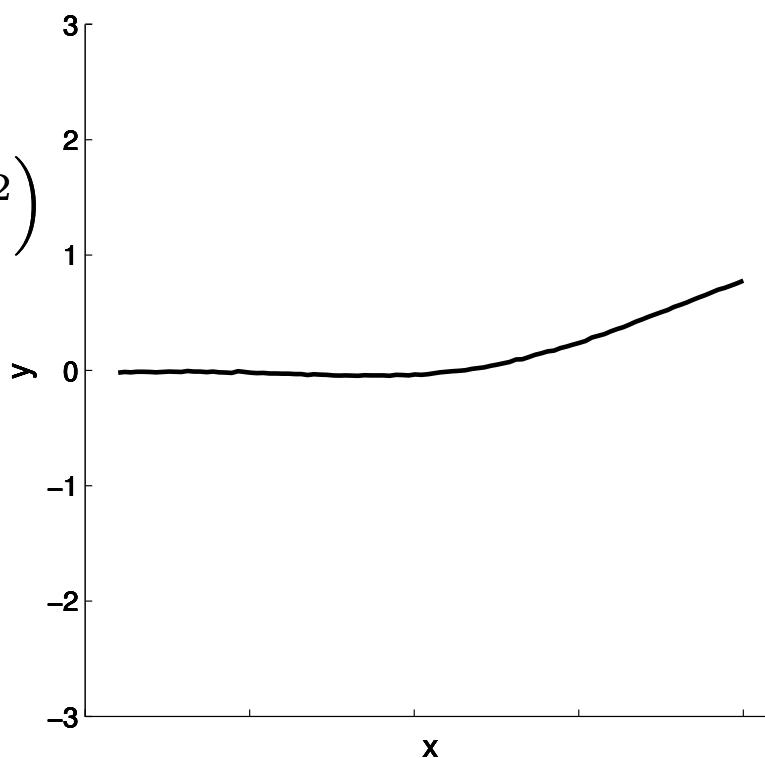
$$\Sigma =$$



Parametric model

$$y(\mathbf{x}) = f(\mathbf{x}; \theta) + \sigma_y \epsilon$$

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What effect do the hyper-parameters have?

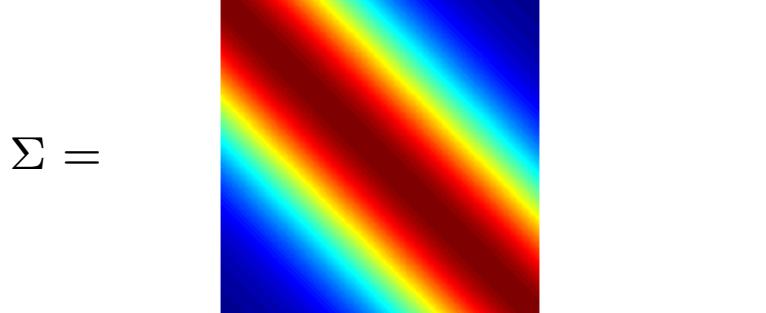
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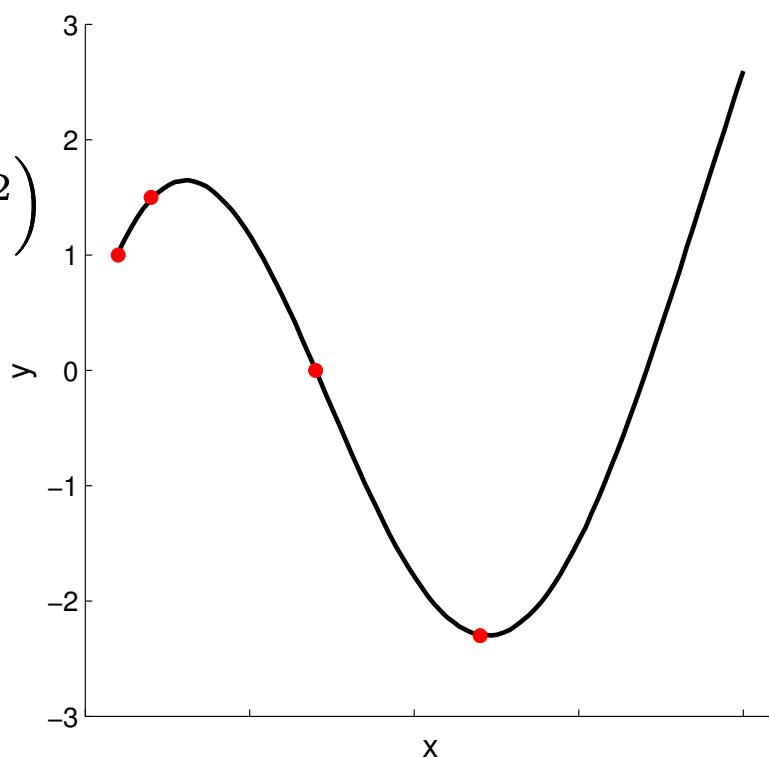
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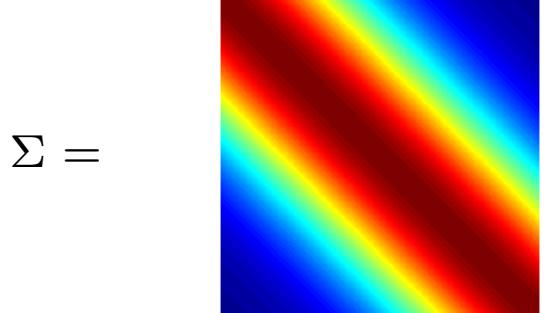
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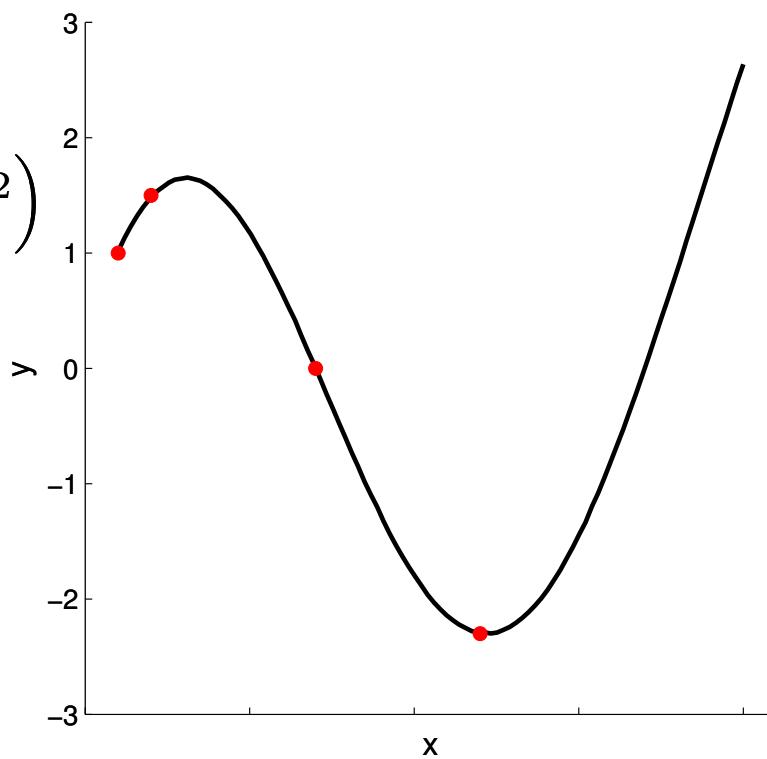
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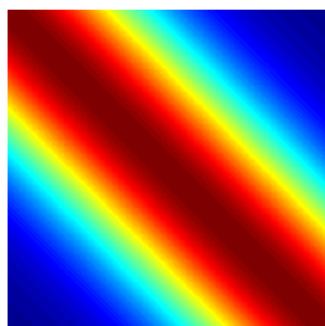
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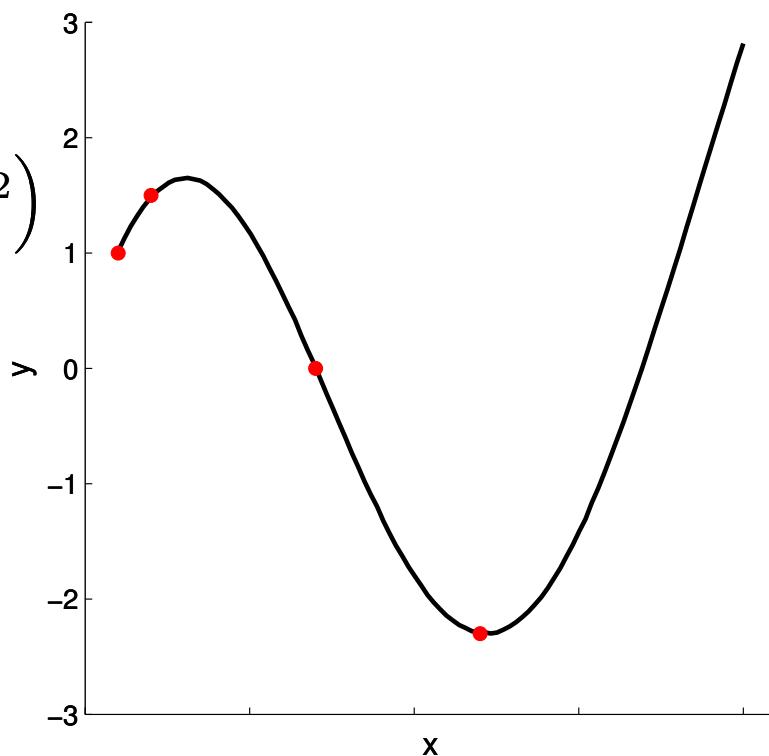
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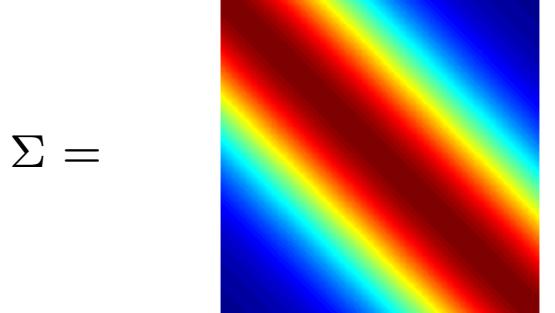
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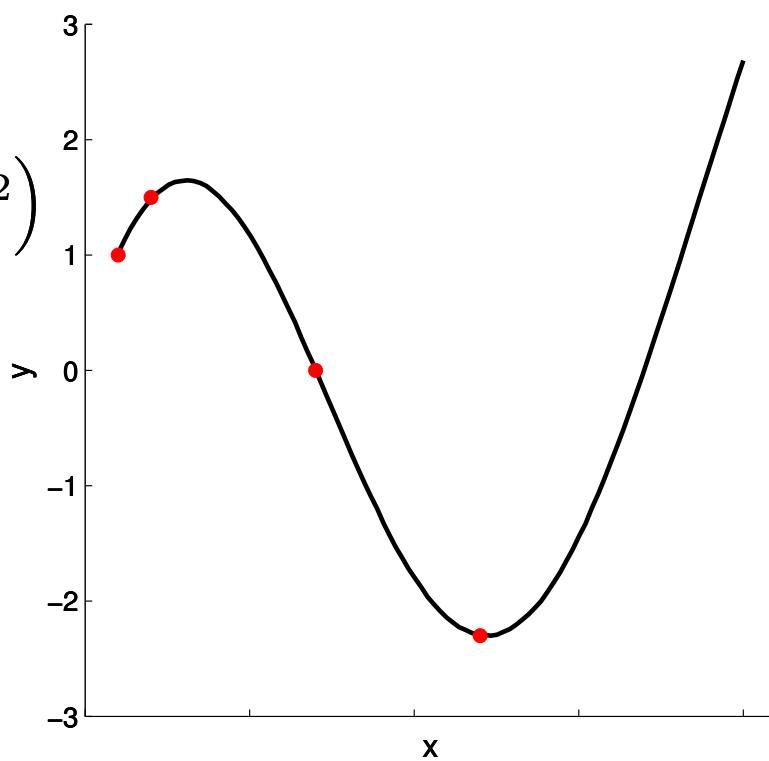
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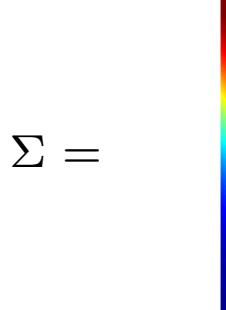
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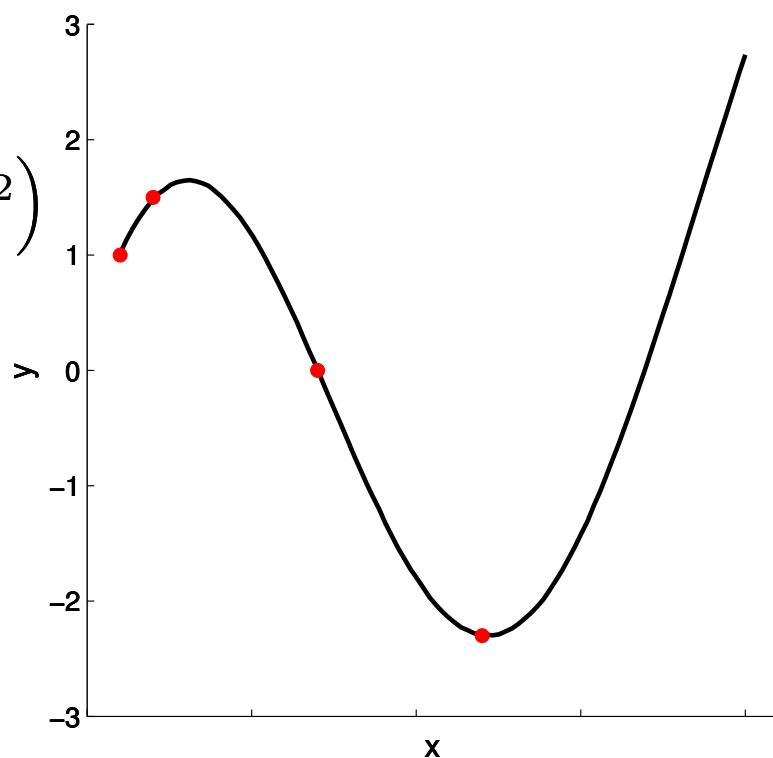
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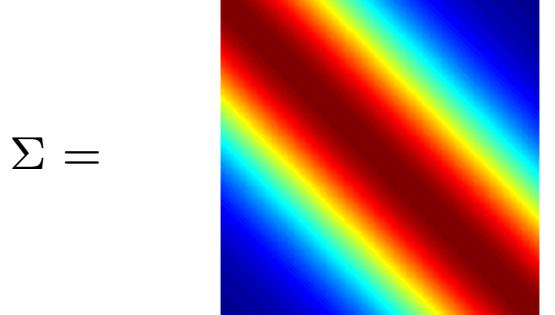
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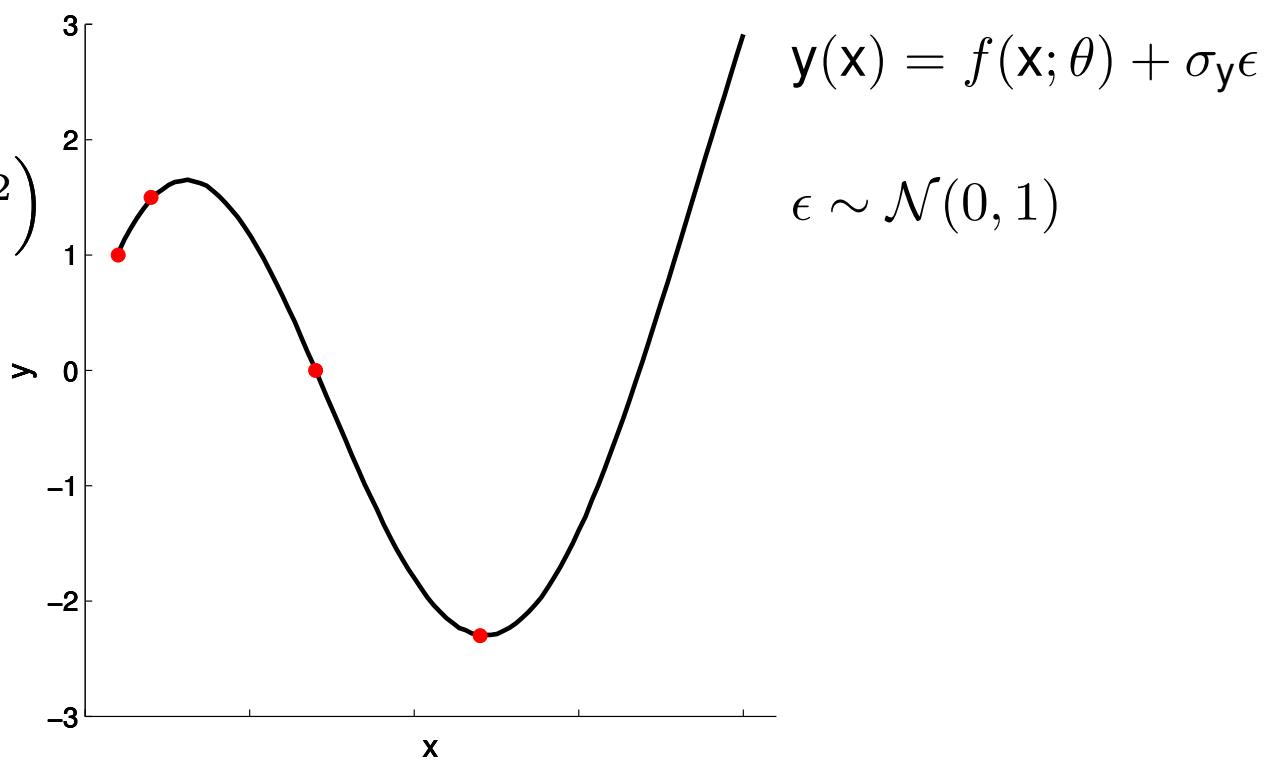
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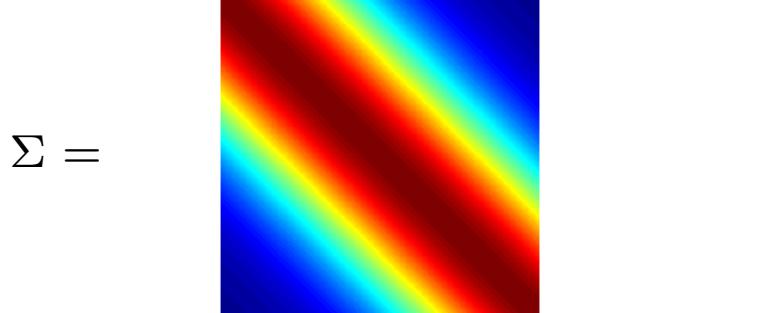
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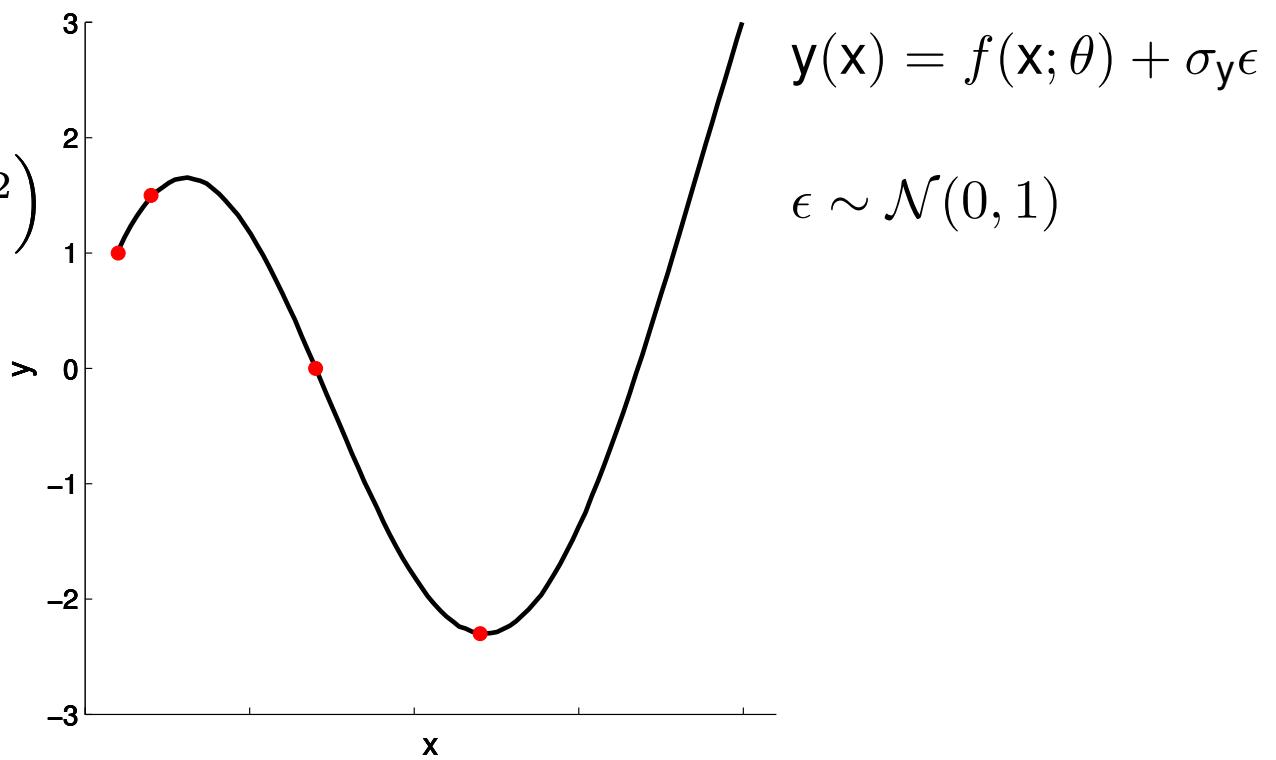
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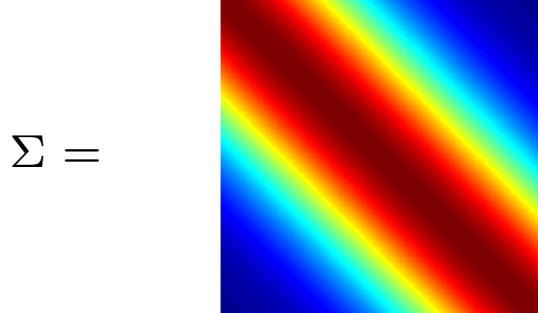
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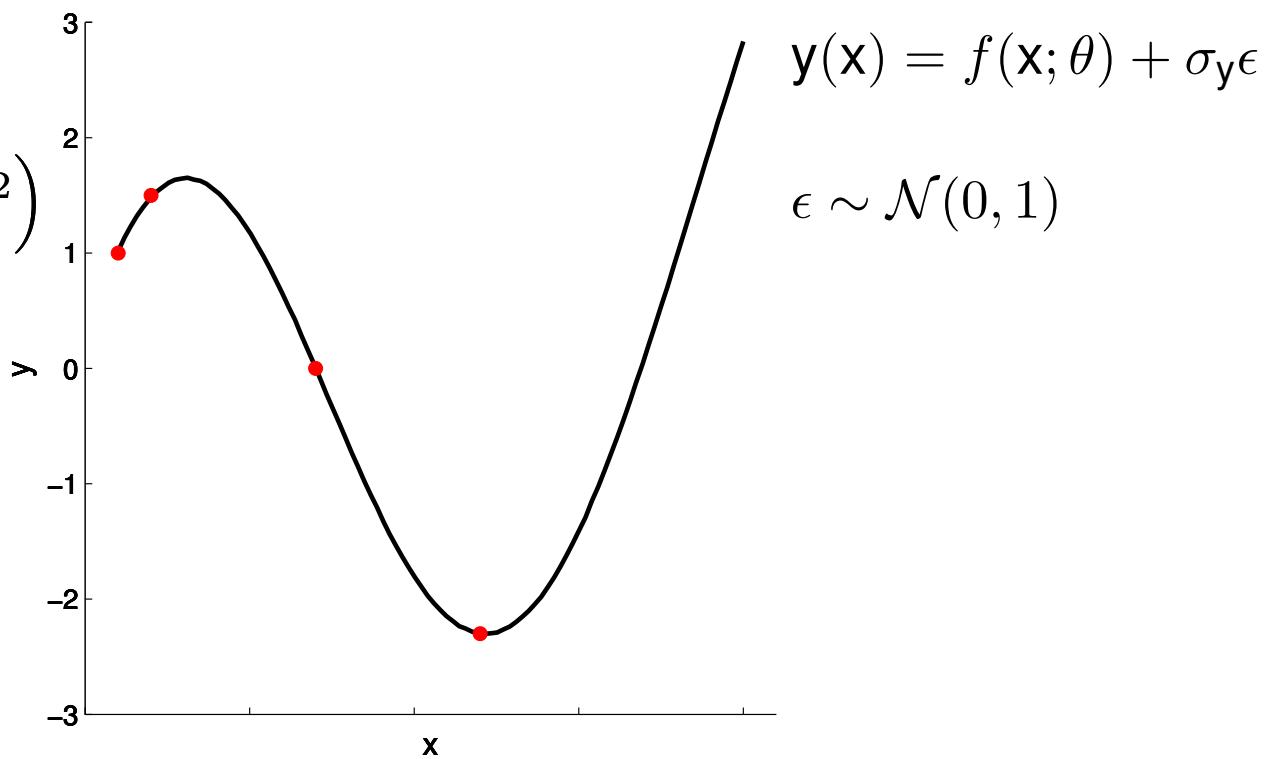
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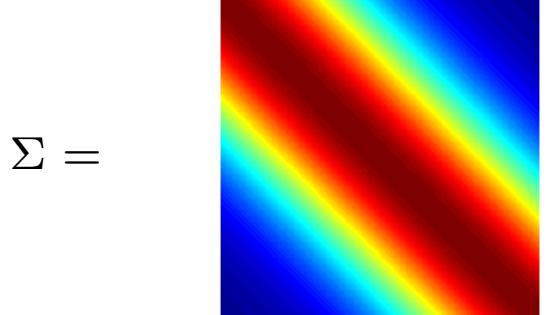
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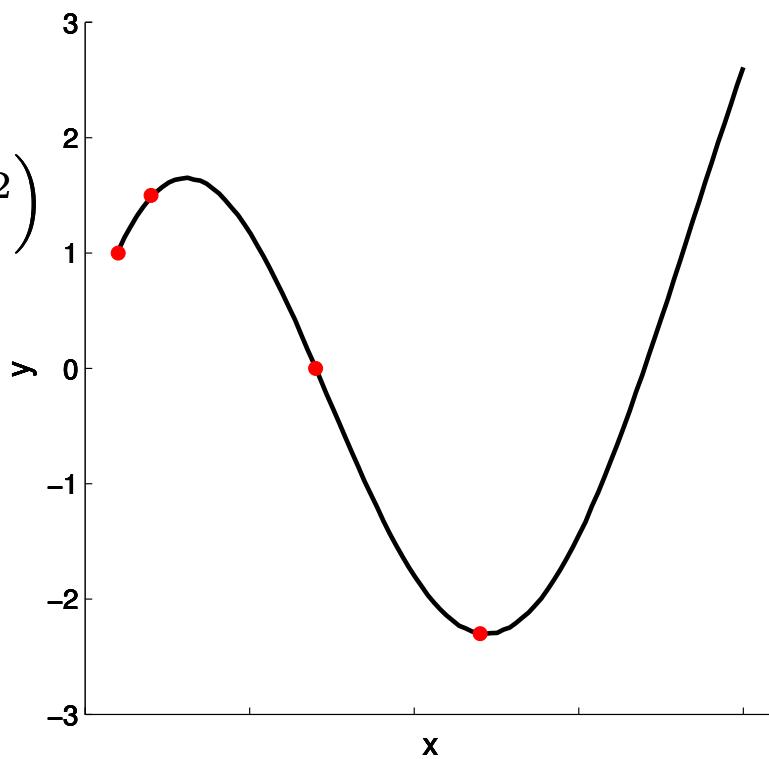
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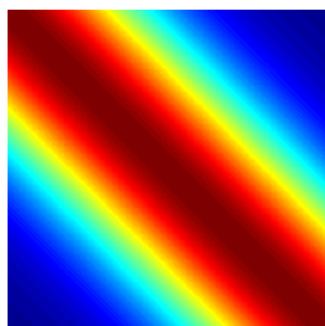
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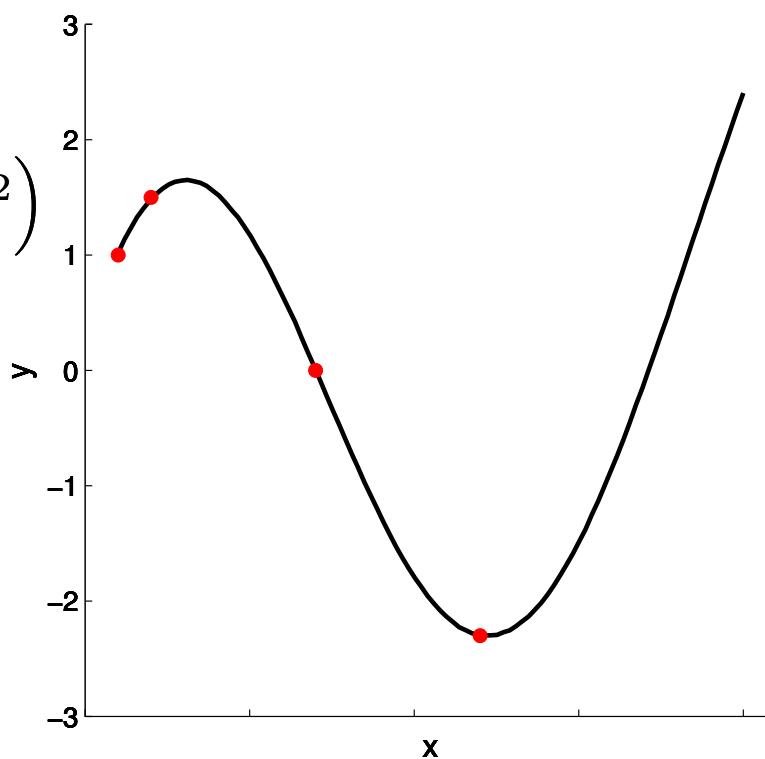
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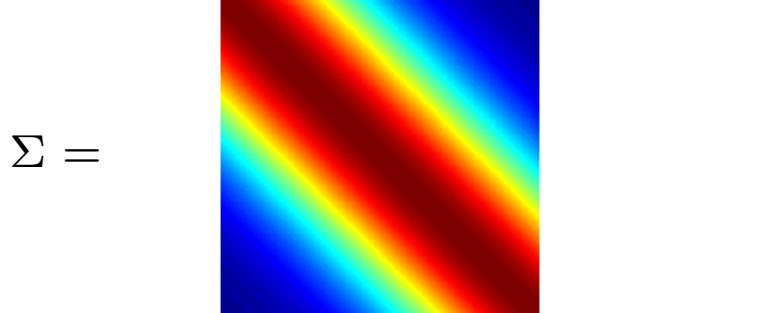
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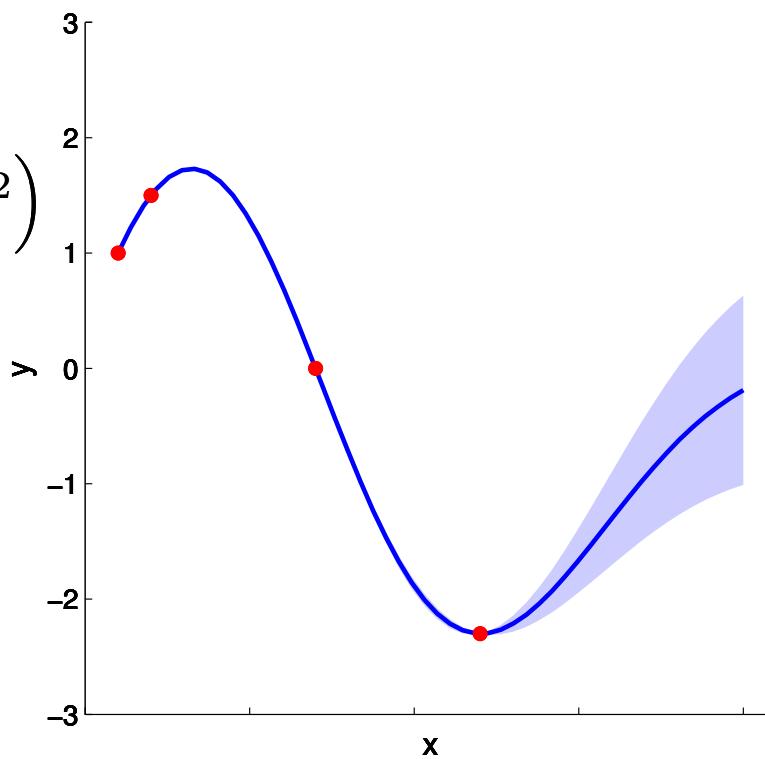


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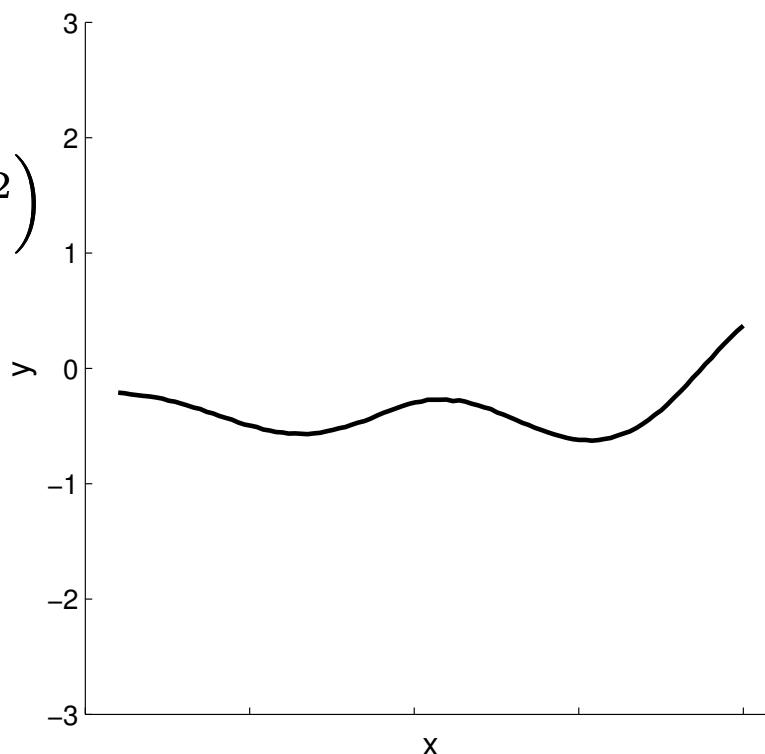


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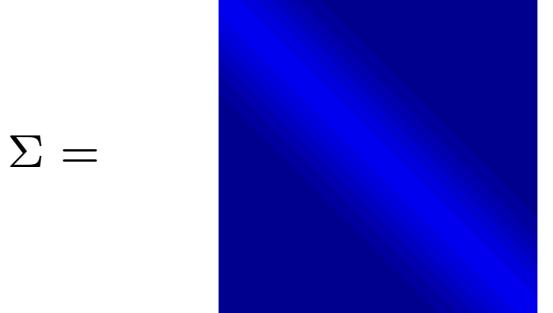
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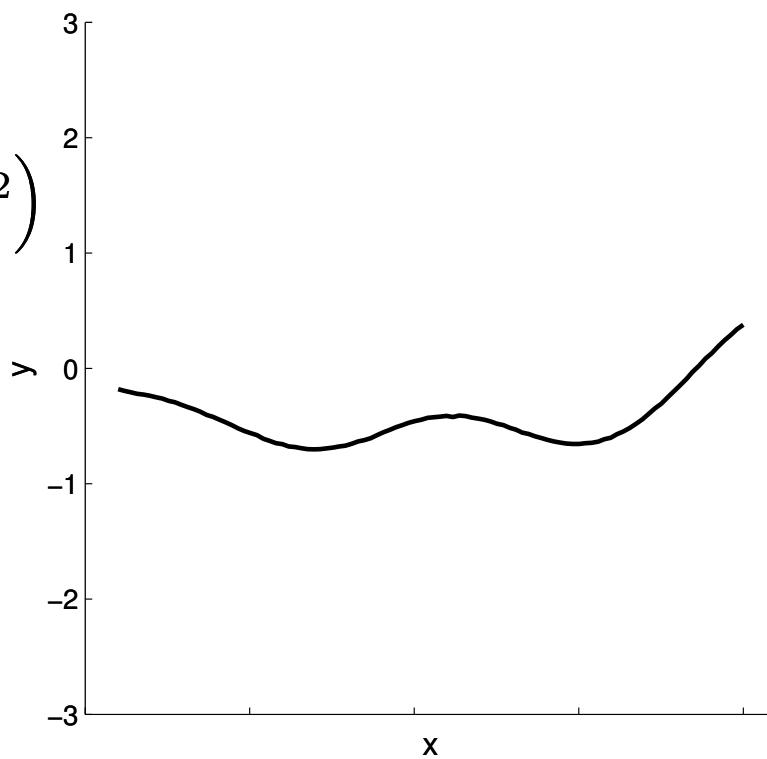


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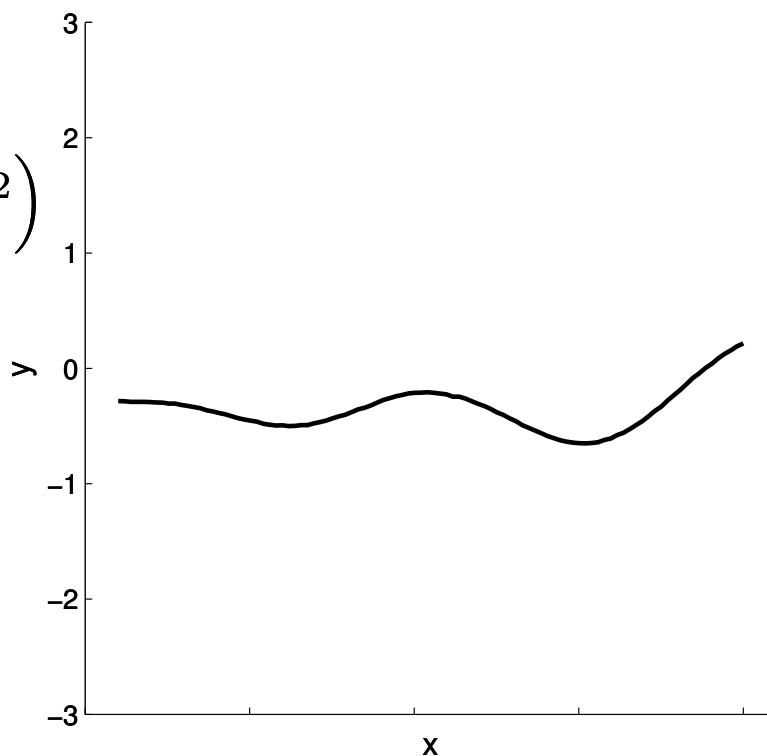


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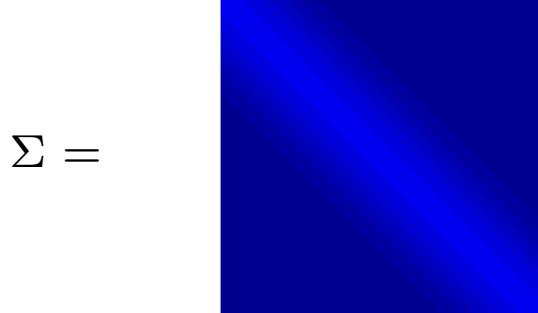
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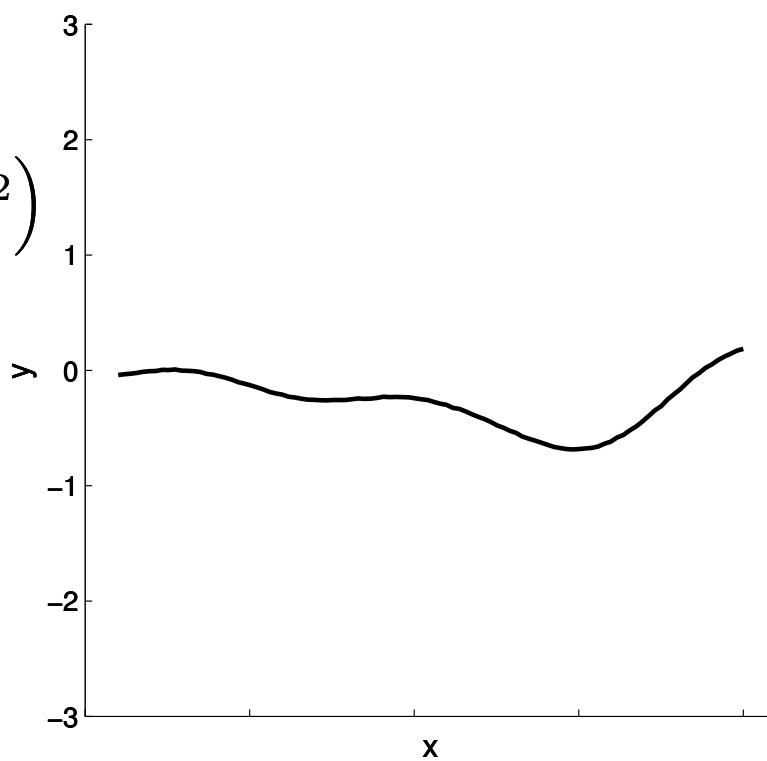


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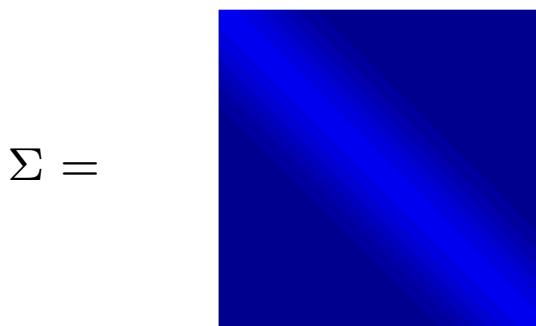
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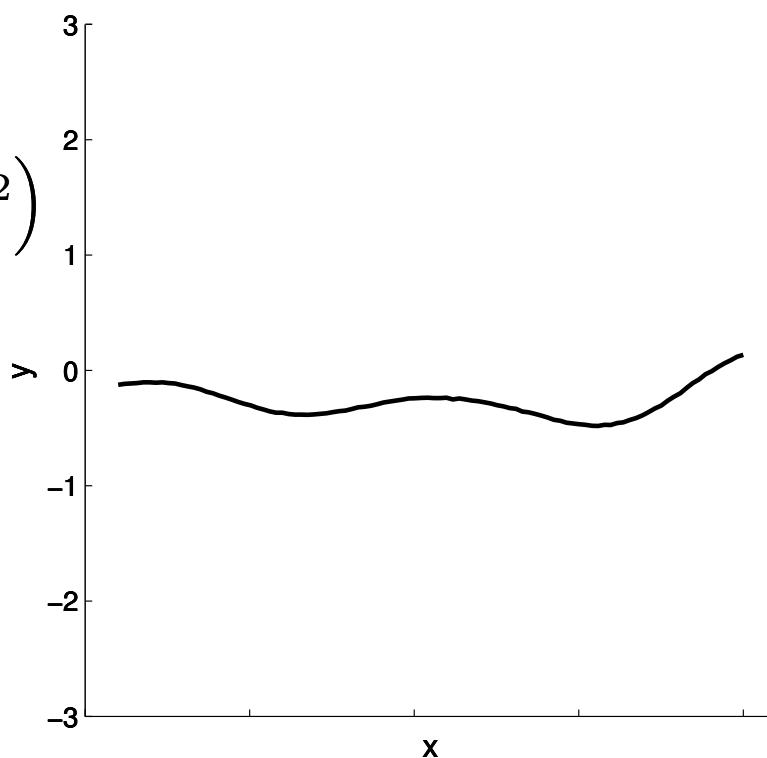


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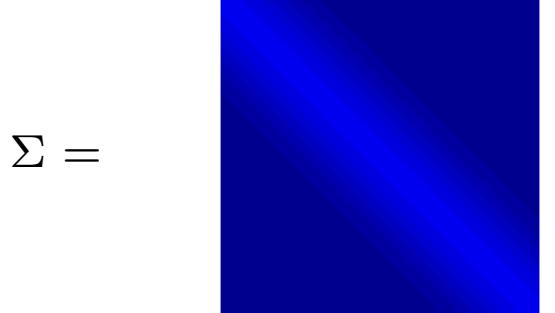
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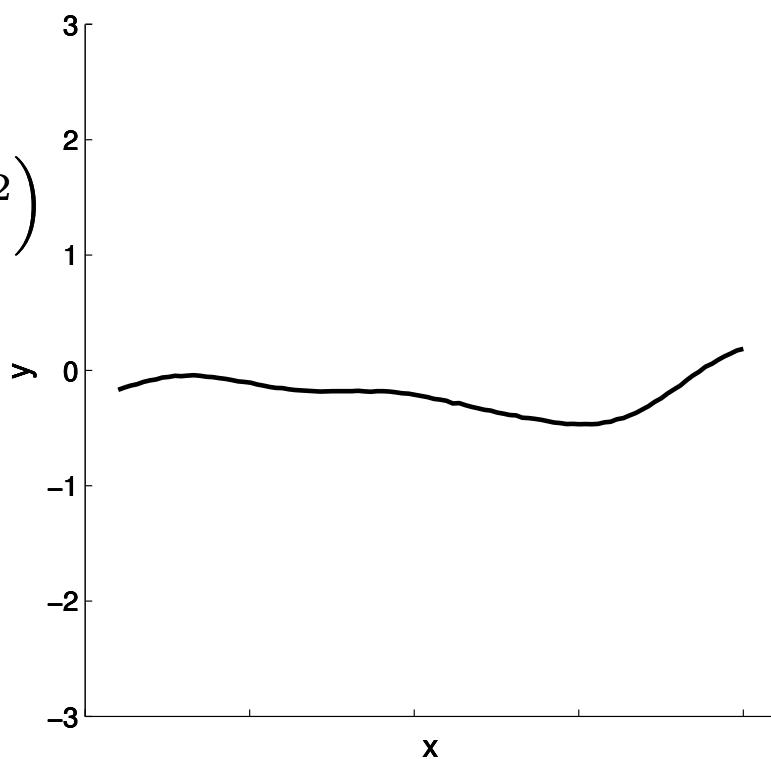


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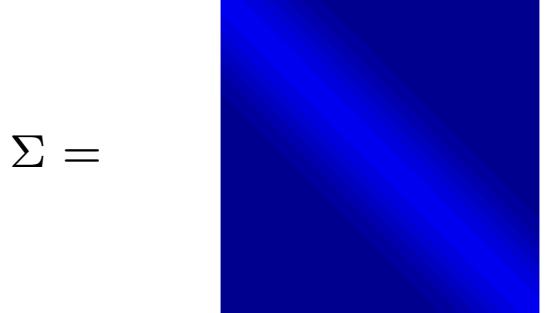
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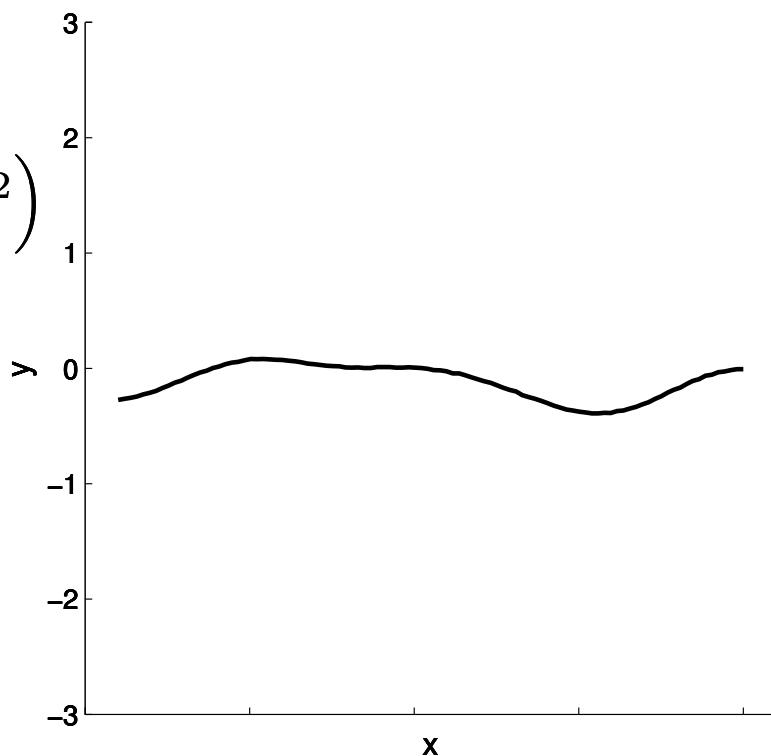


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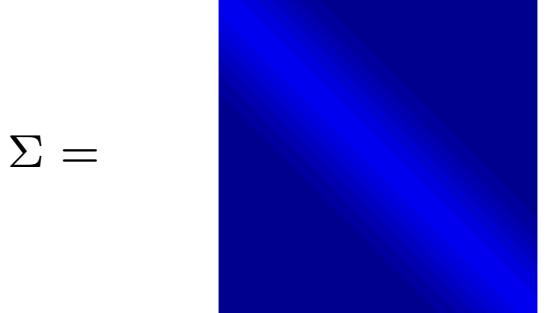
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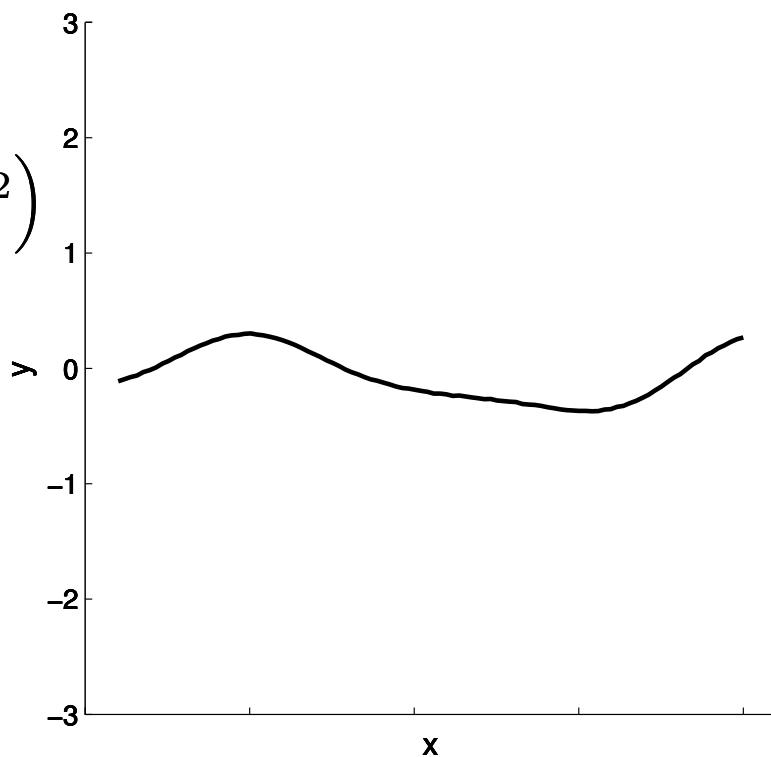


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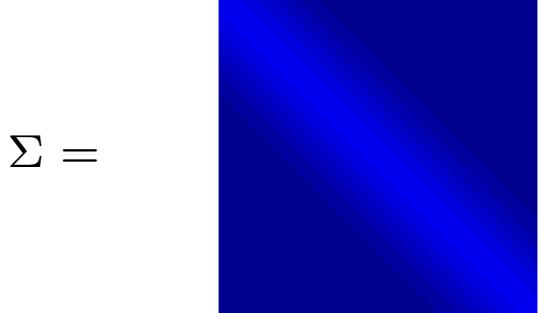
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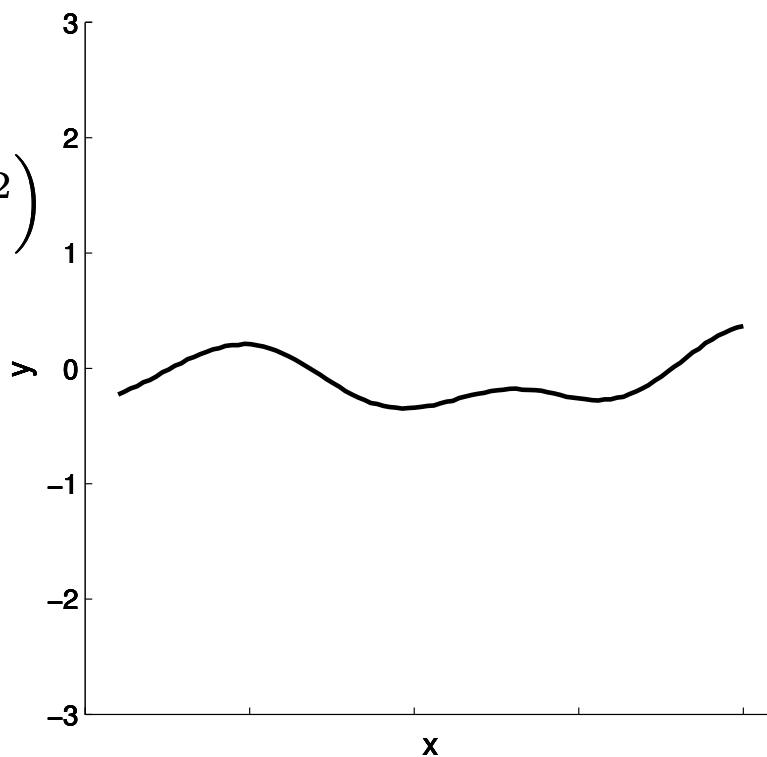


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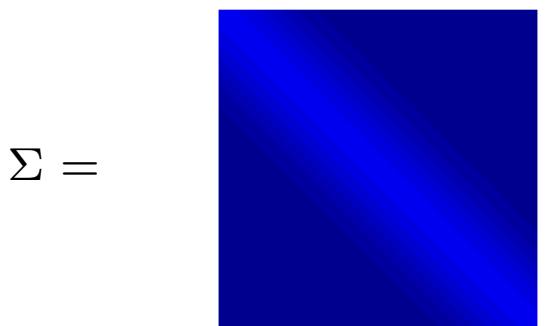
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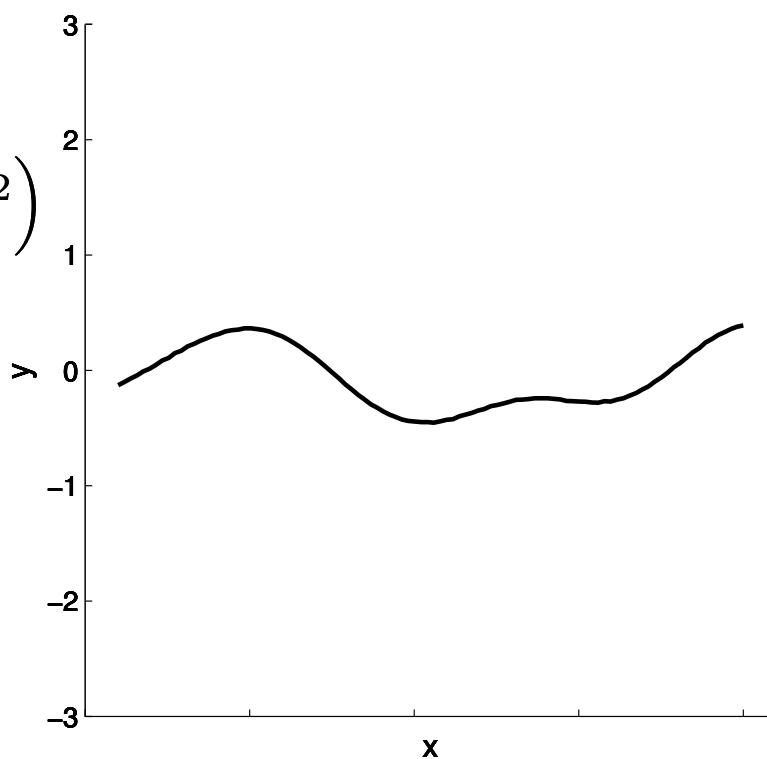


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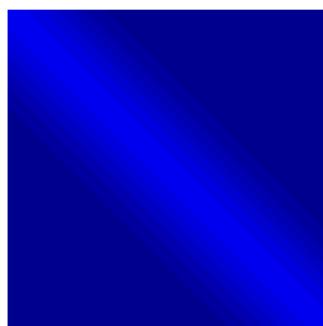
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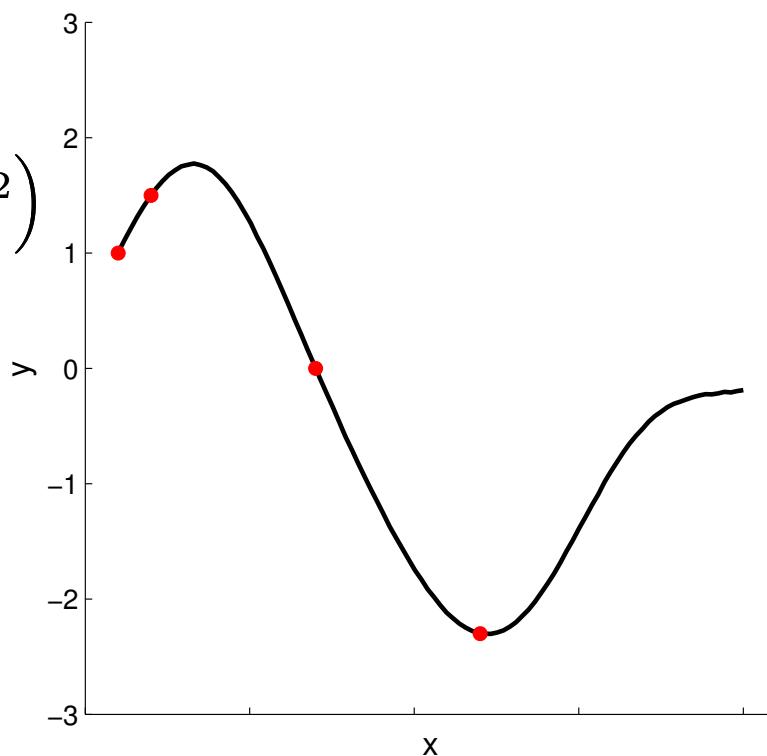
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Parametric model

$$\mathbf{y}(\mathbf{x}) = f(\mathbf{x}; \theta) + \sigma_y \epsilon$$

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What effect do the hyper-parameters have?

small vertical scale

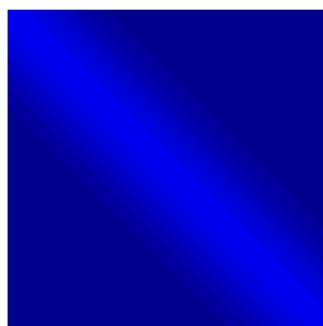
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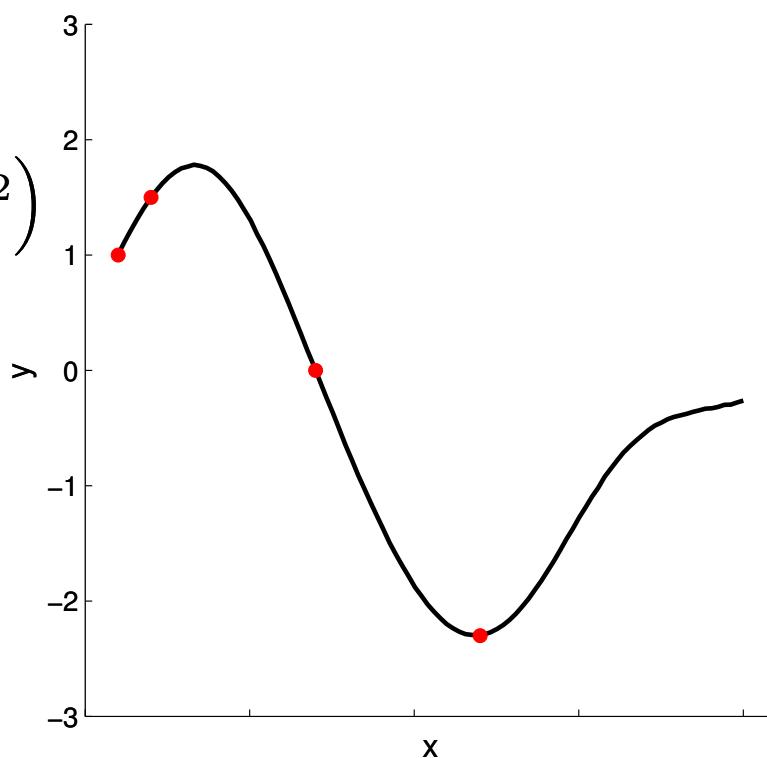
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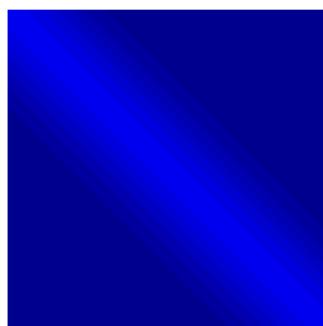
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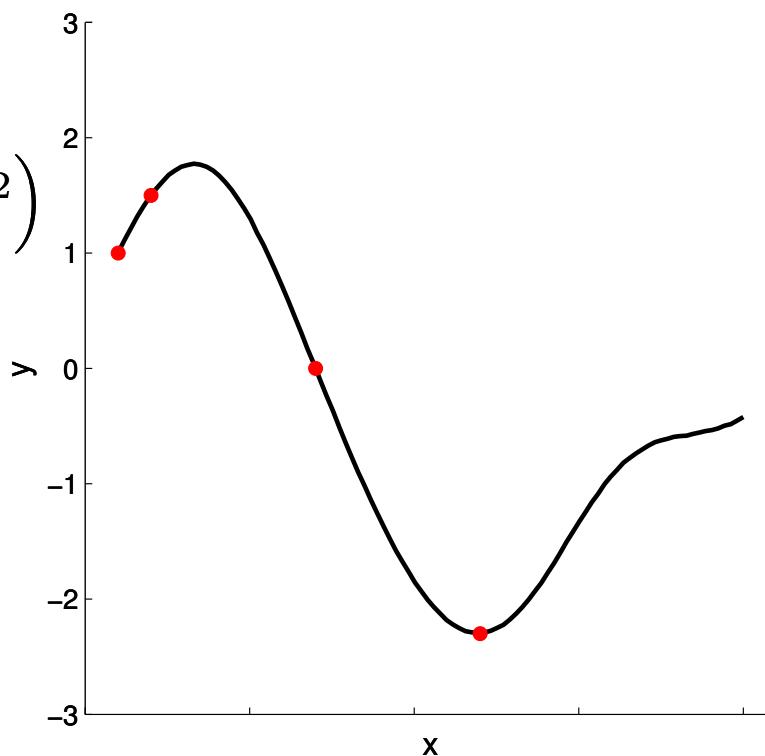
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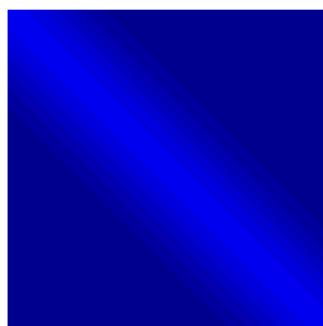
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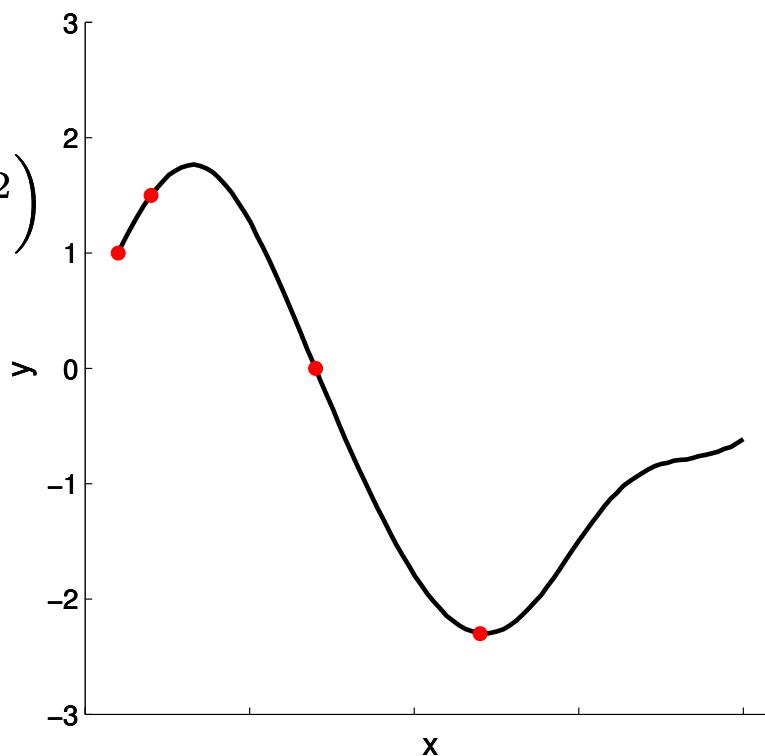
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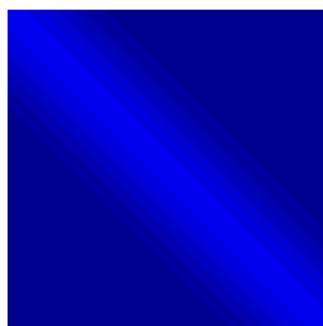
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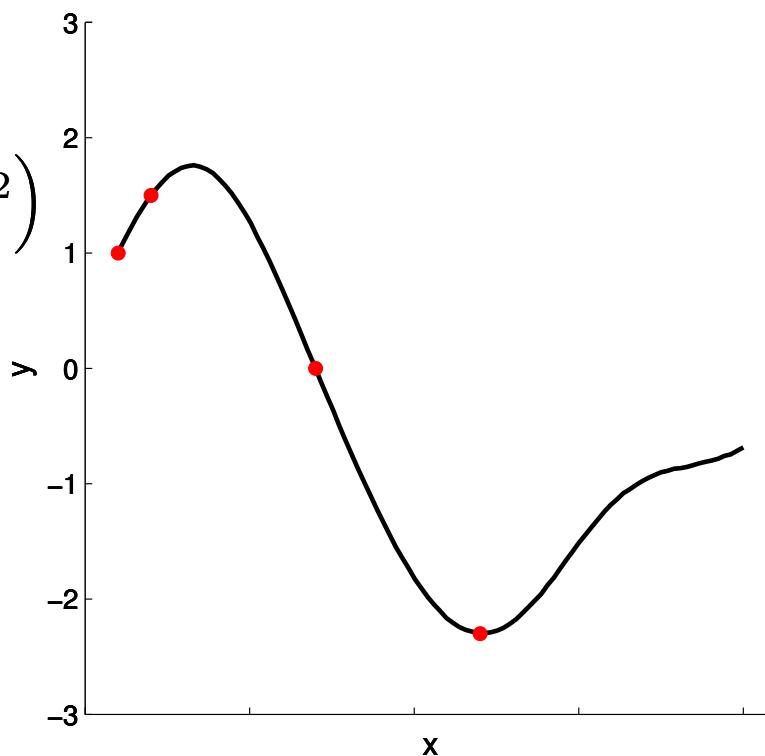
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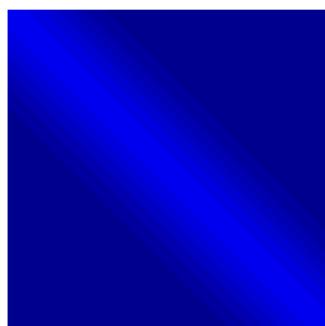
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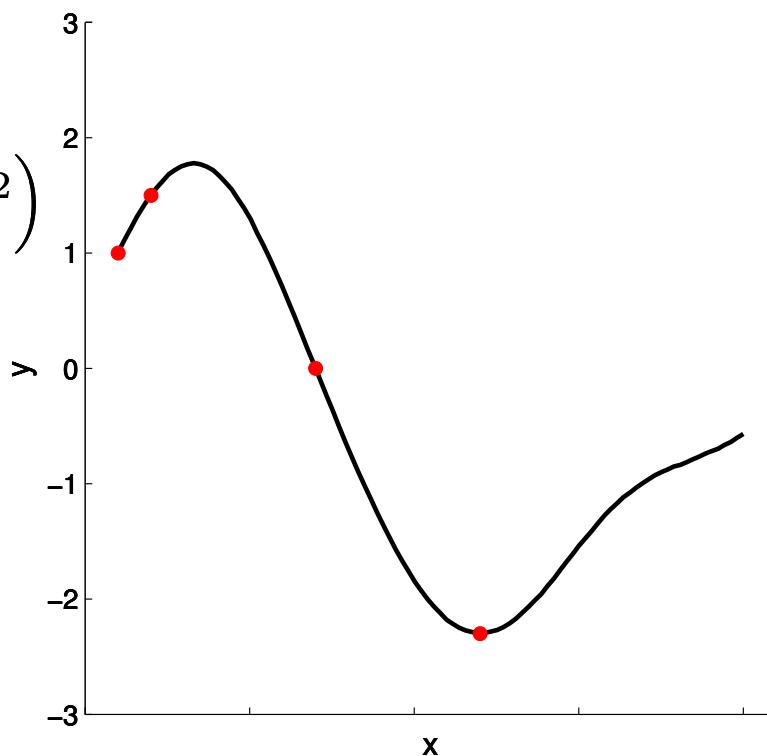
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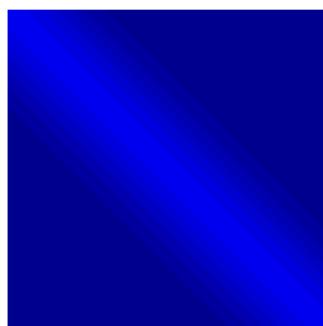
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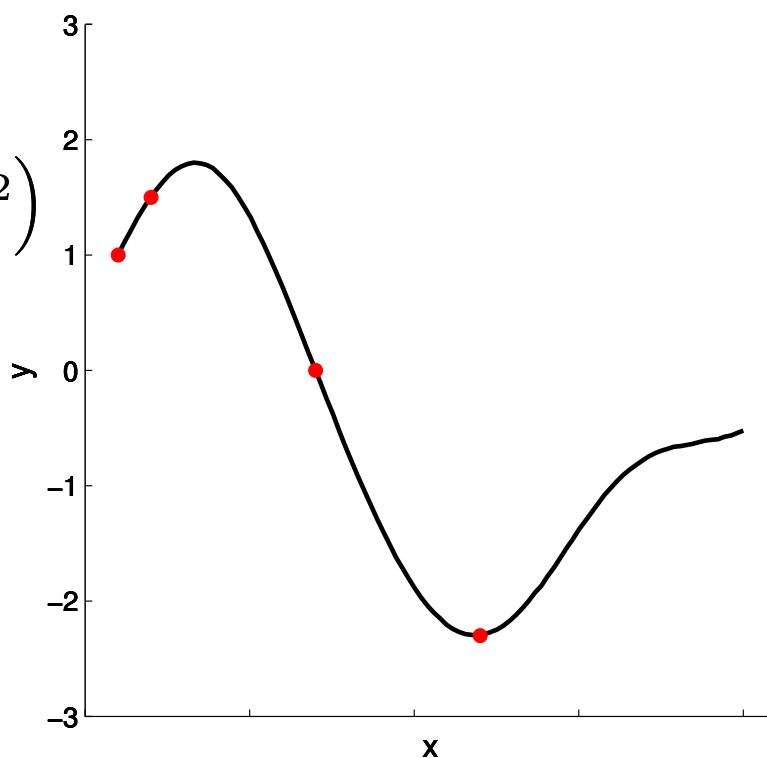
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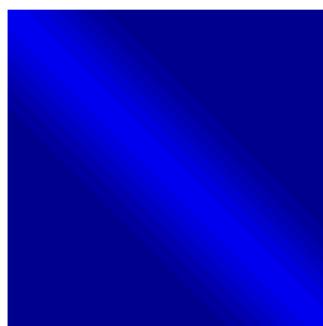
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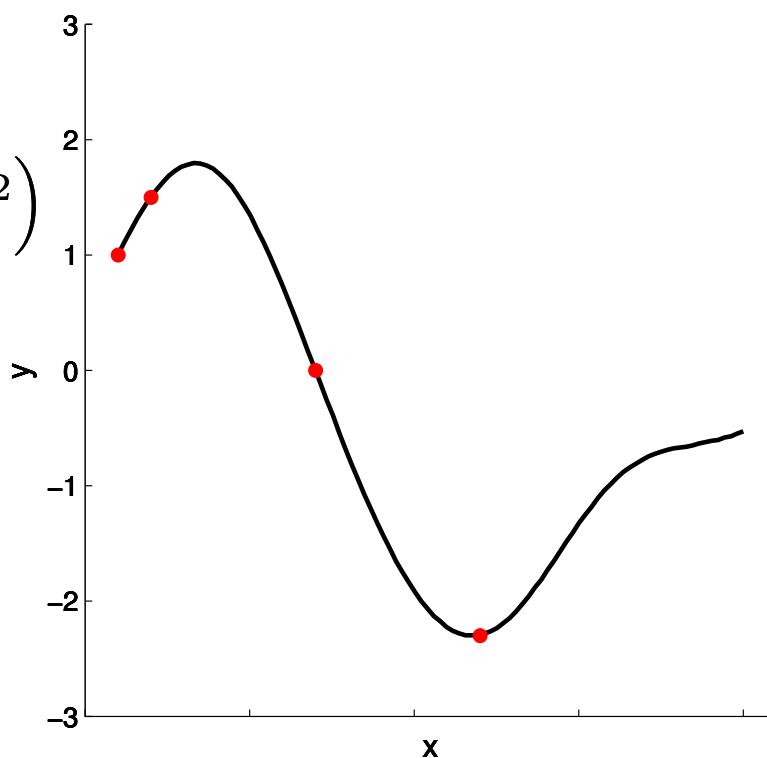
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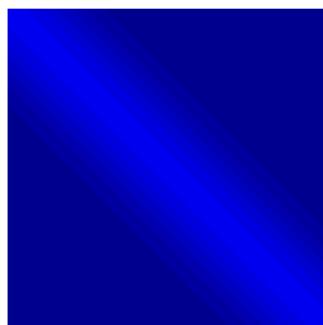
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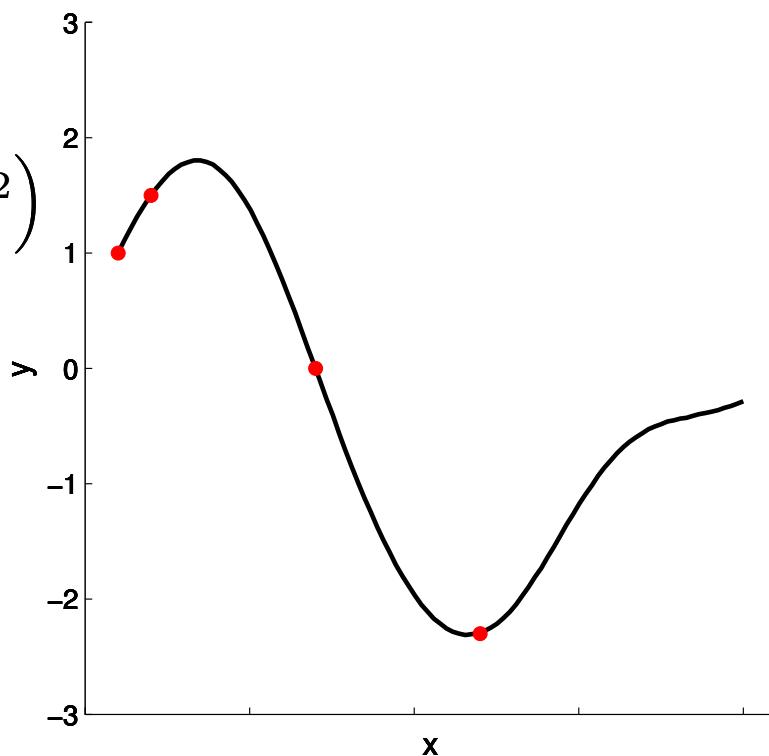
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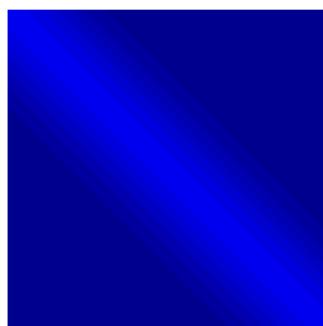
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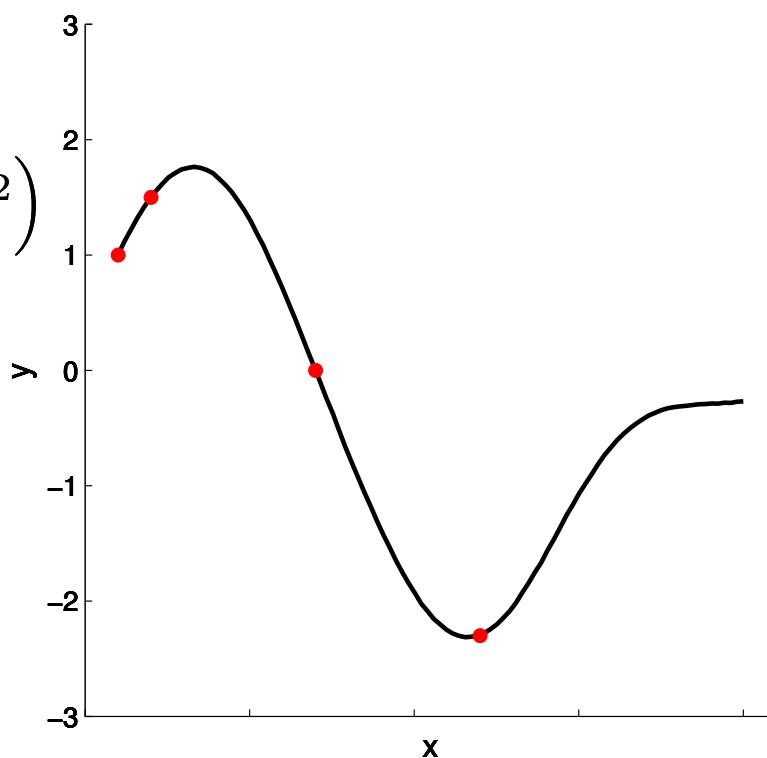
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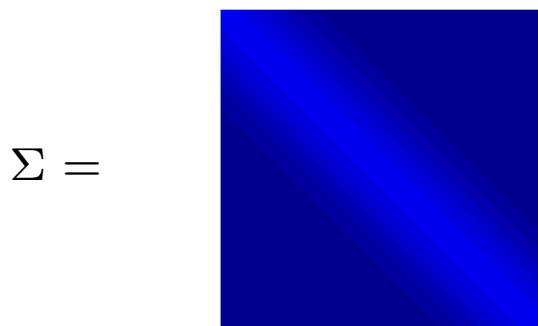
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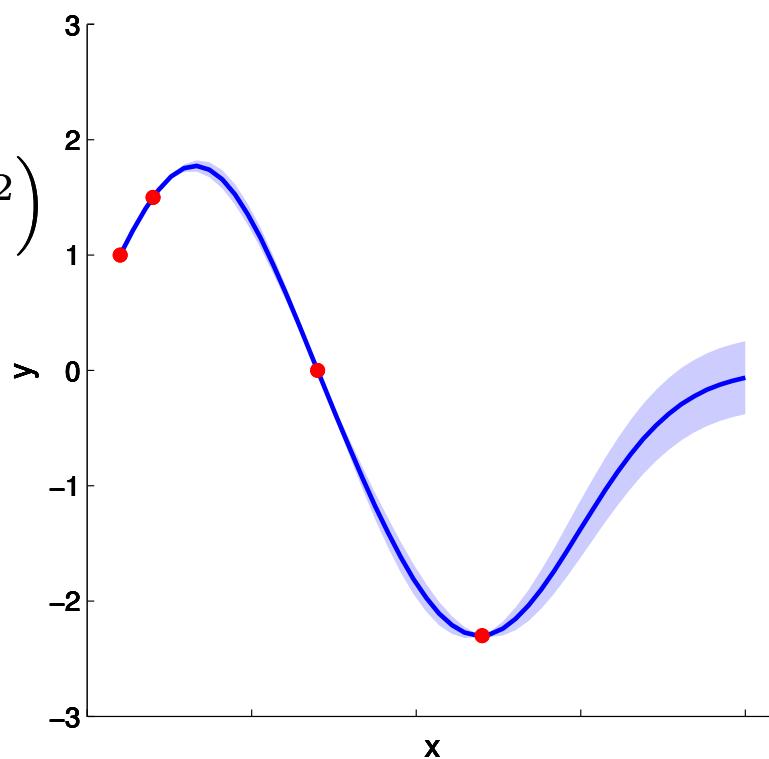
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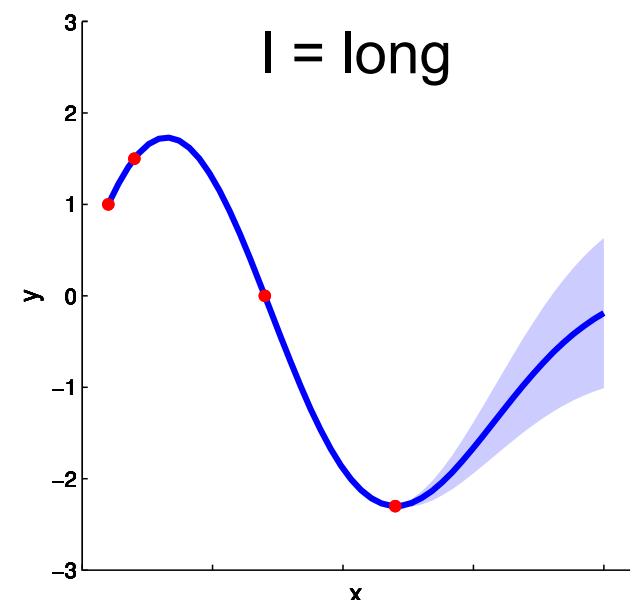
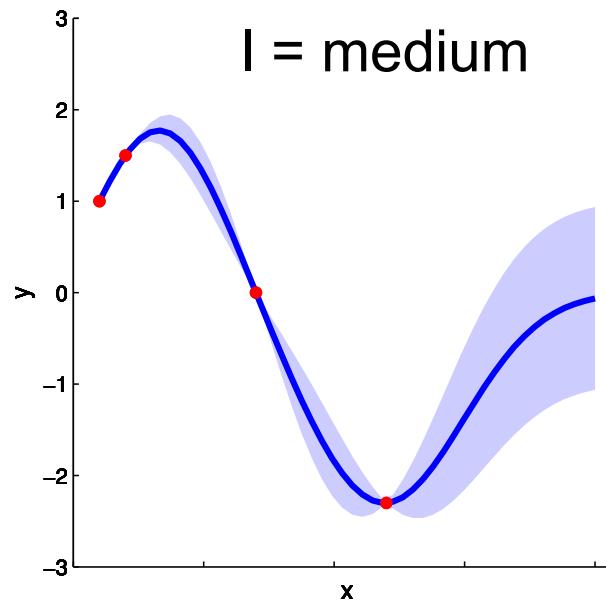
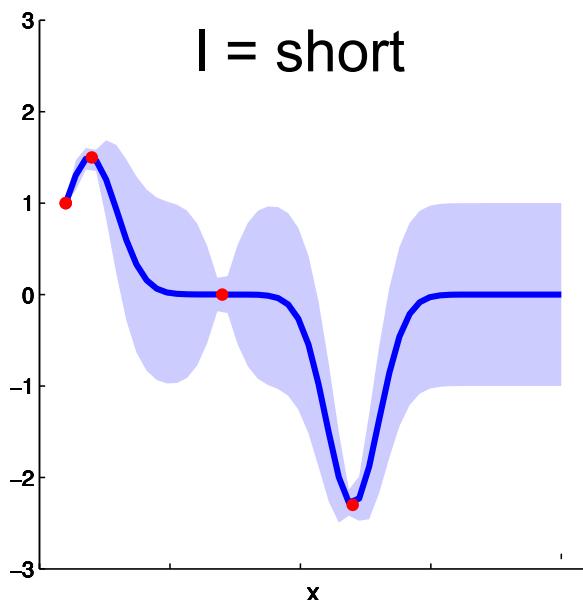
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What effect do the hyper-parameters have?

$$K(x_1, x_2) = \sigma^2 \exp\left(-\frac{1}{2l^2}(x_1 - x_2)^2\right)$$

- Hyper-parameters have a strong effect
 - l controls the horizontal length-scale
 - σ^2 controls the vertical scale of the data
- \implies we need automatic ways of learning the hyper-parameters from data



What effect does the form of the covariance function have?

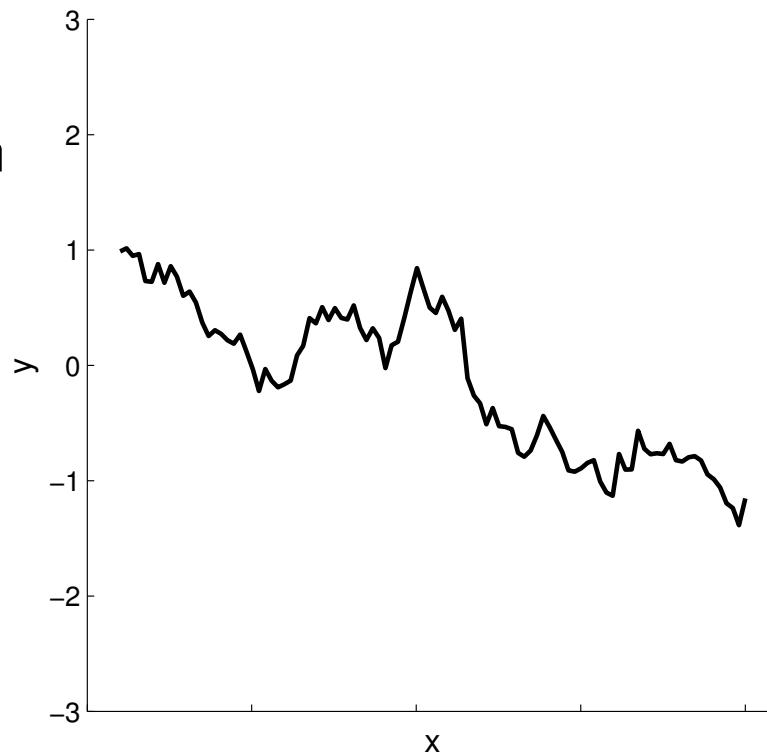
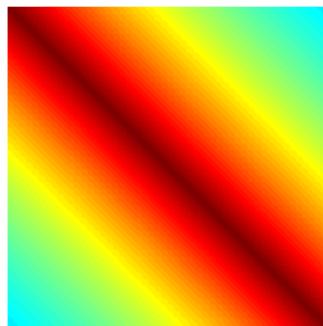
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Laplacian covariance function

Browninan motion

Ornstein-Uhlenbeck

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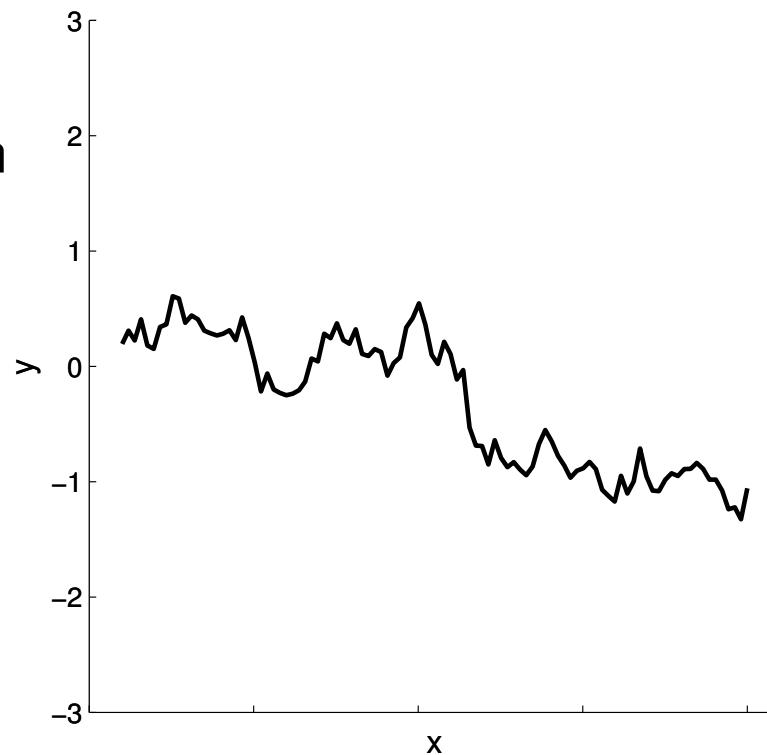
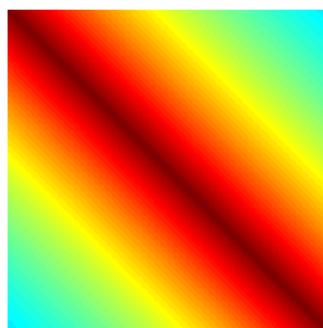
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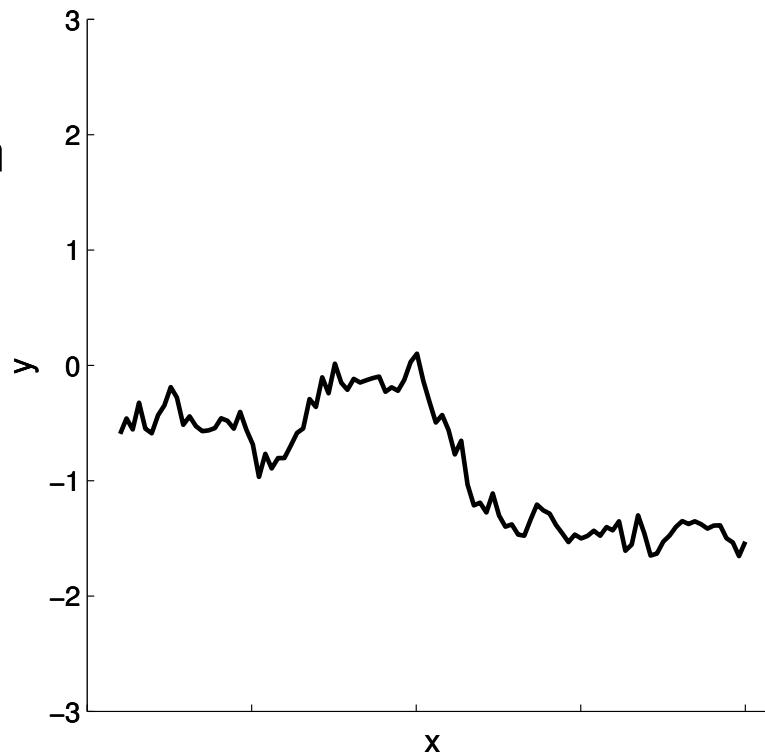
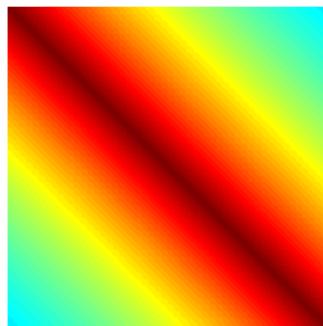
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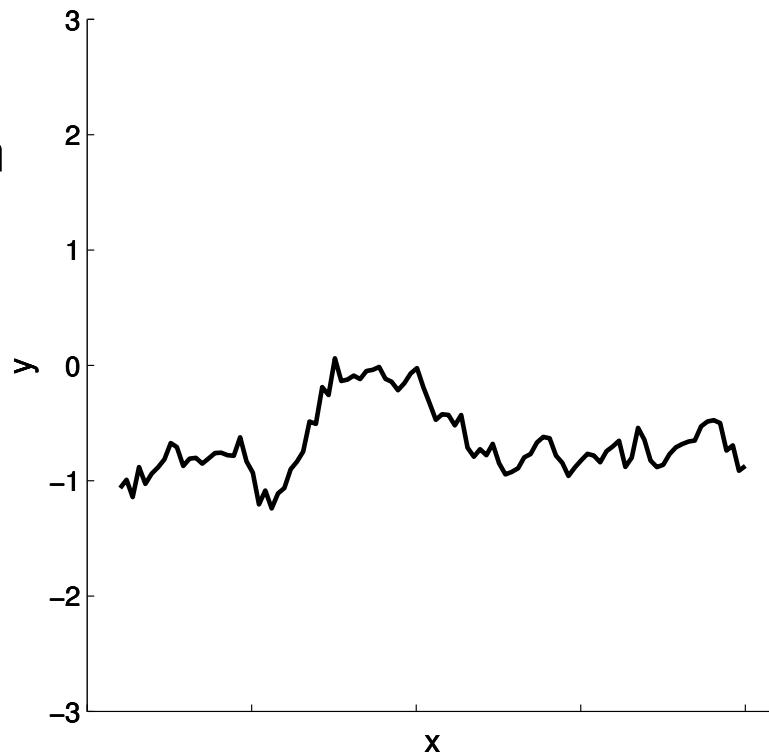
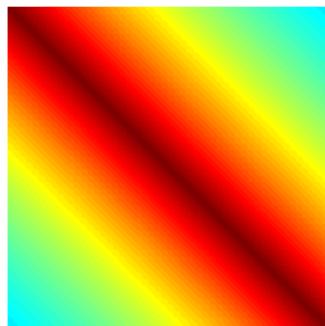
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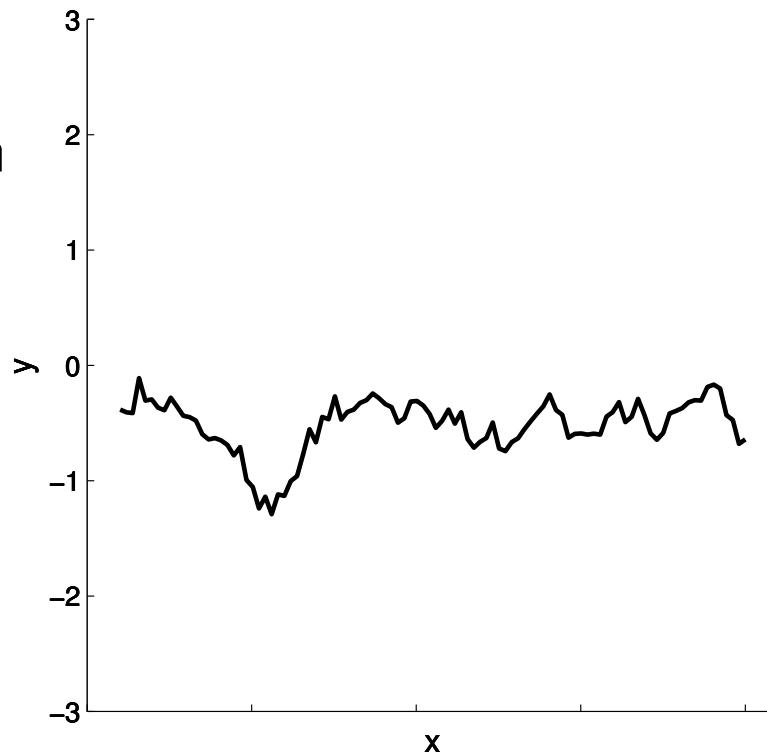
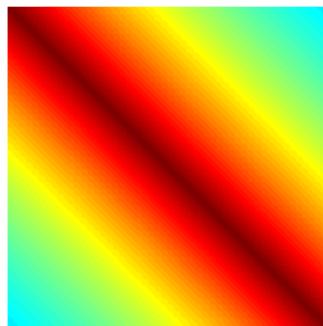
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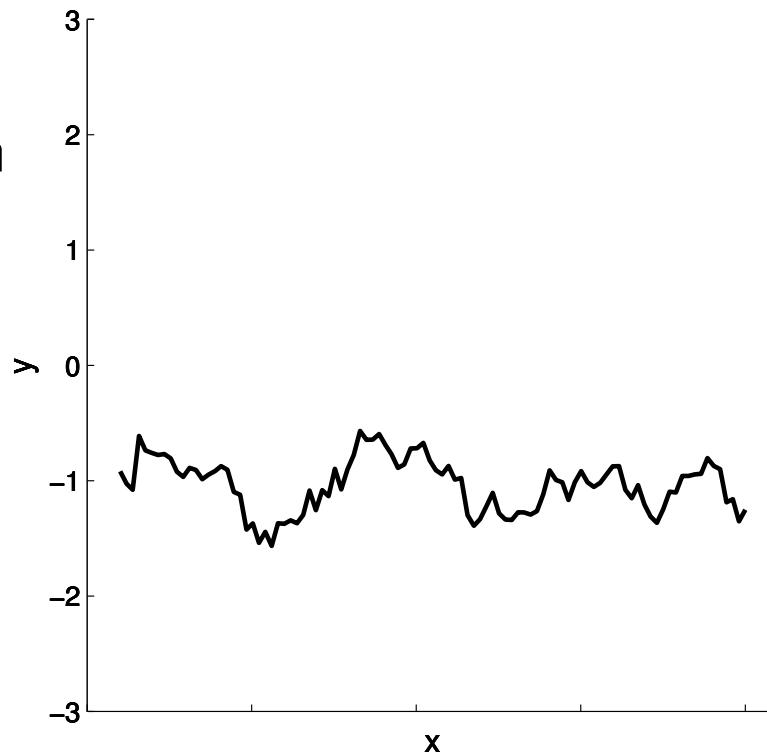
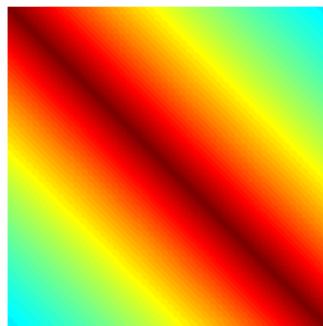
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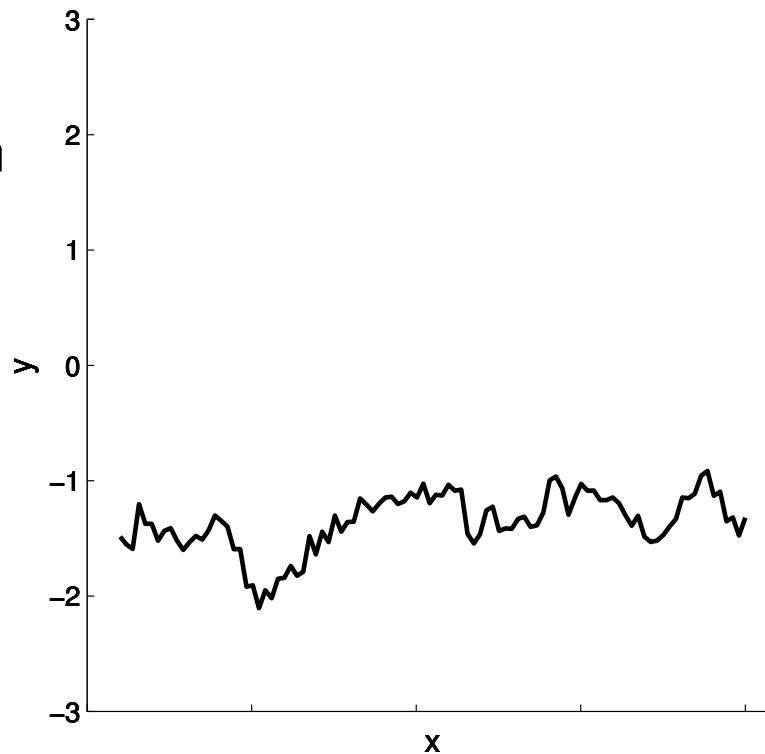
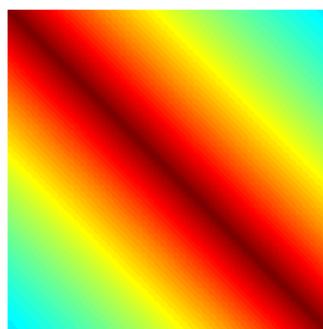
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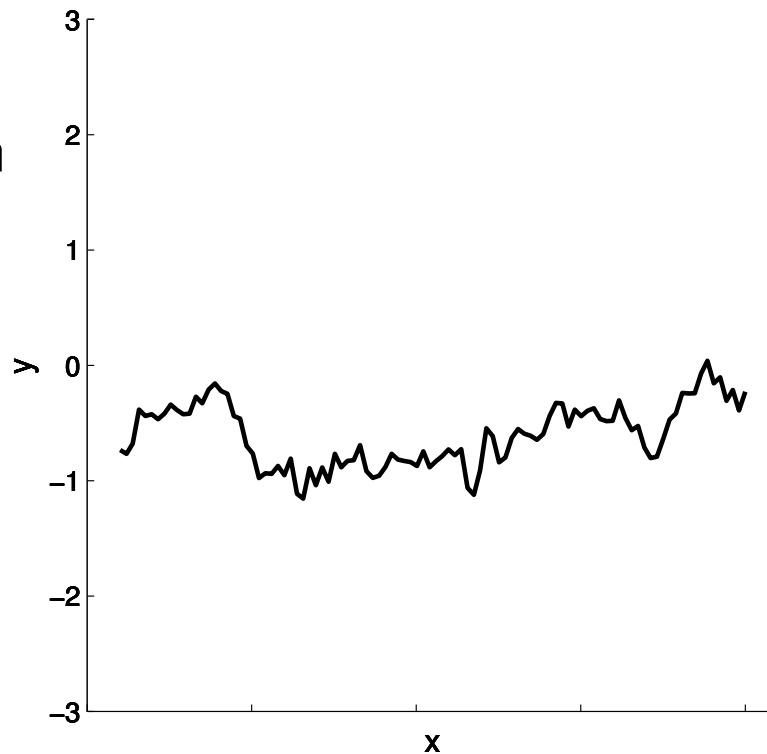
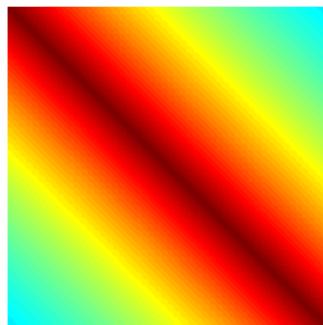
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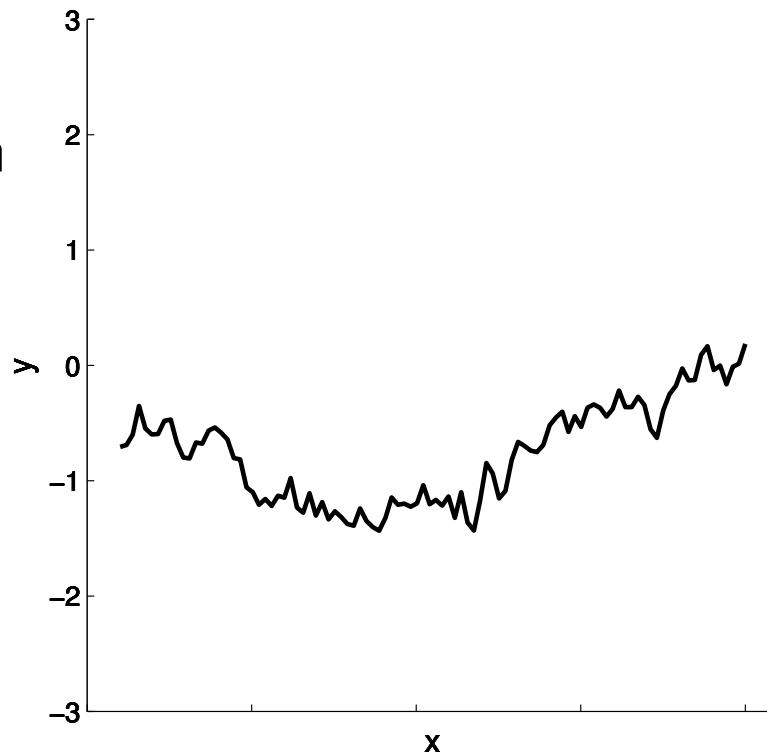
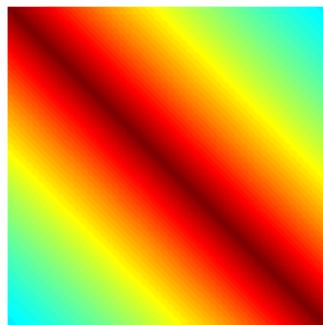
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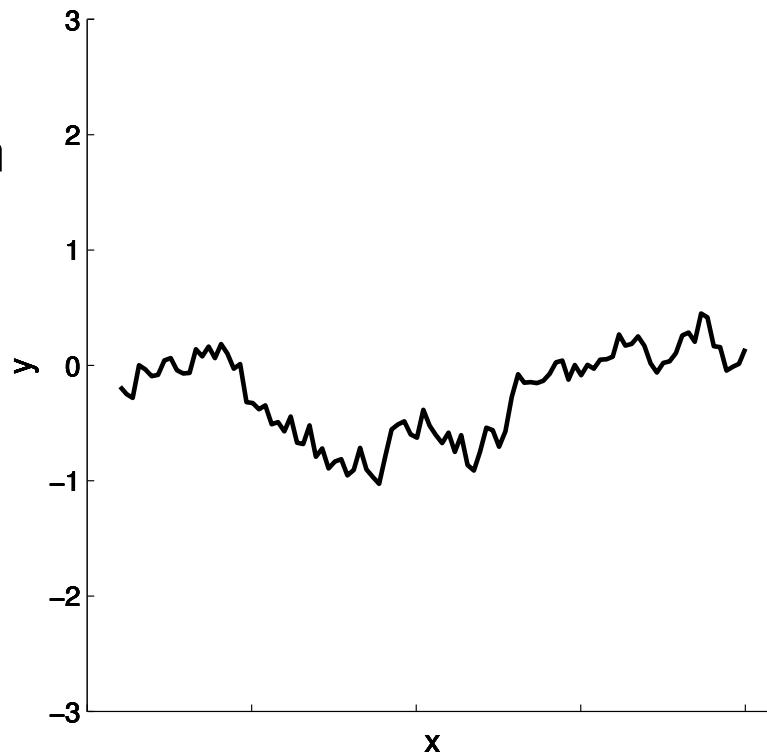
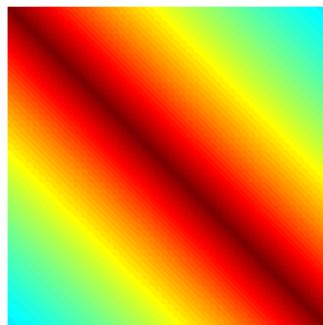
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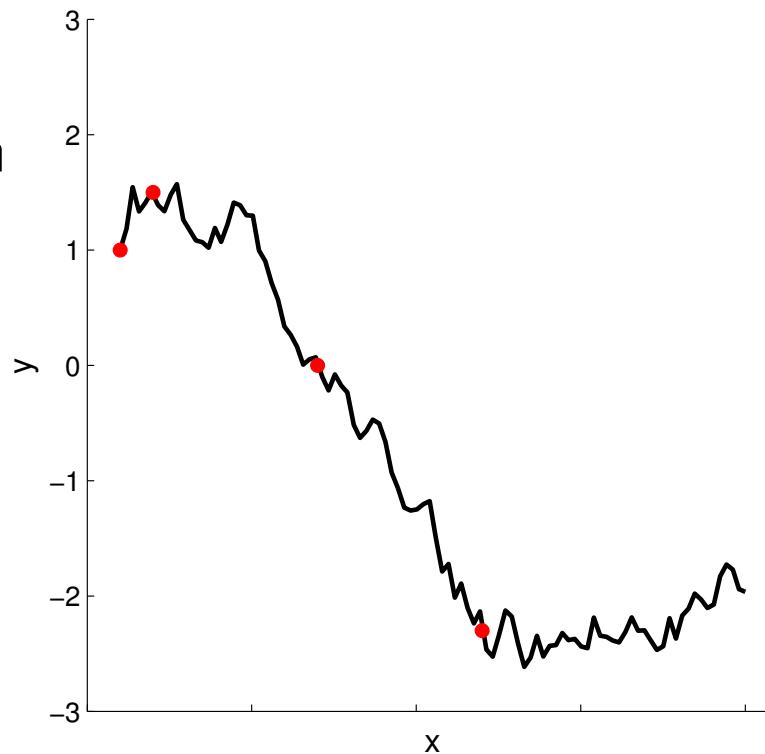
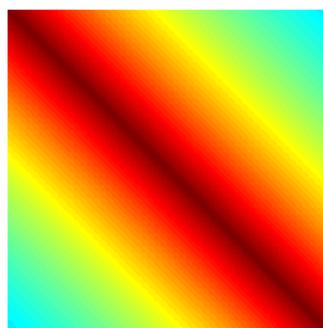
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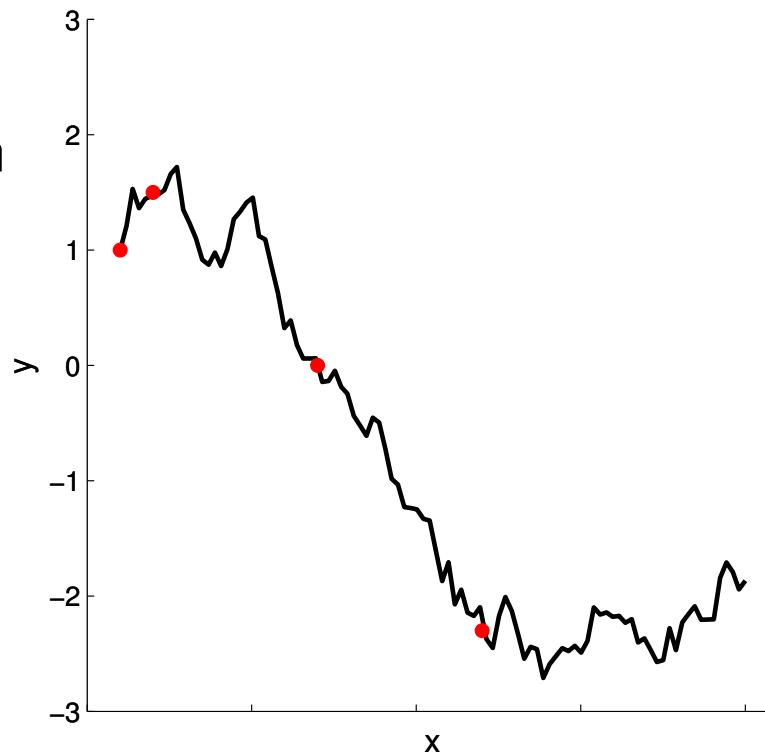
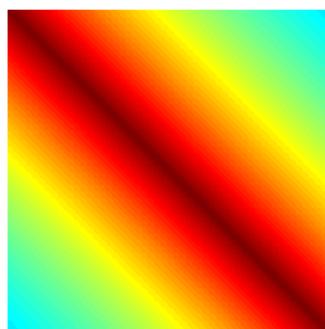
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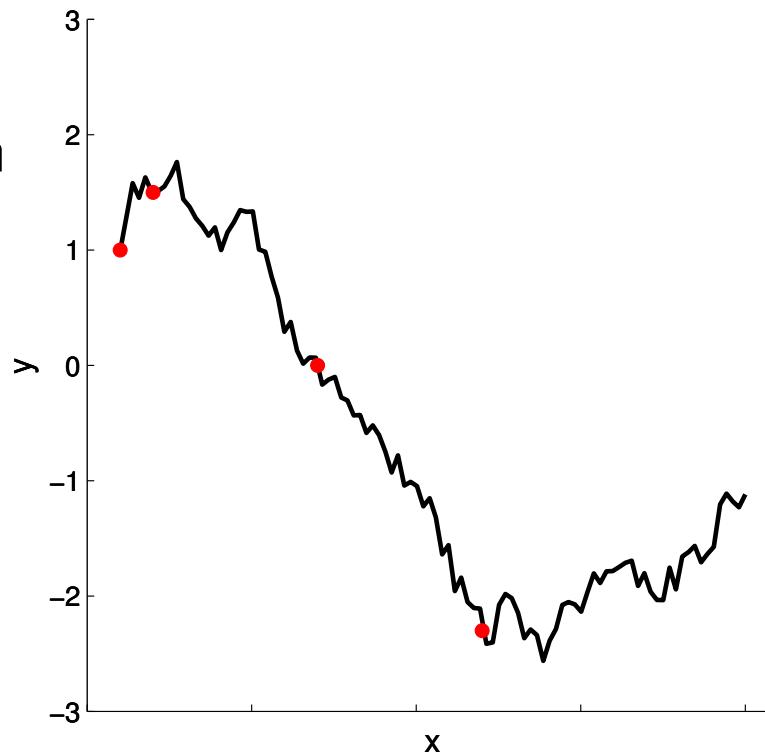
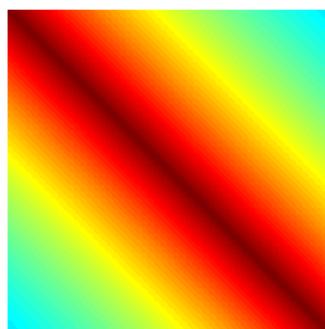
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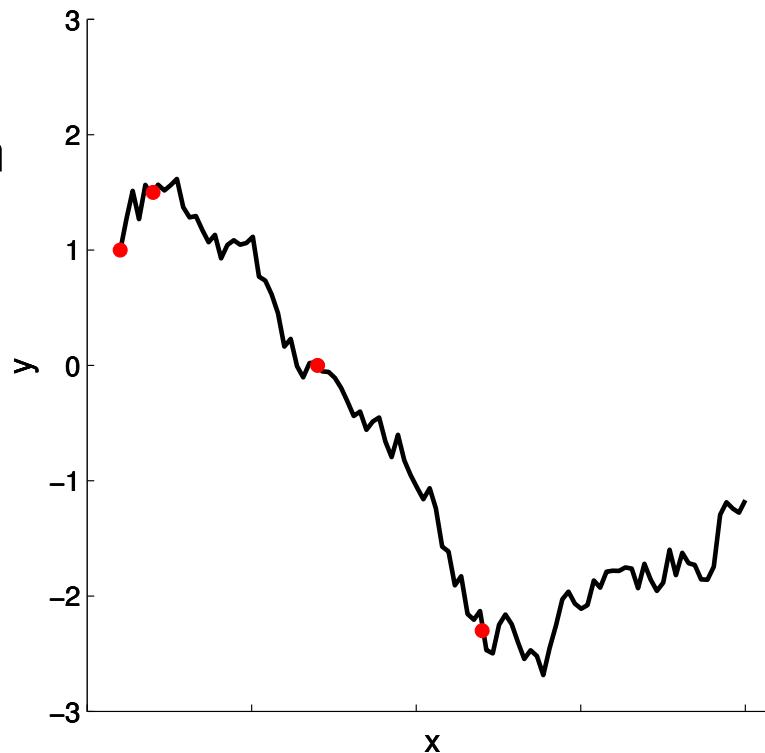
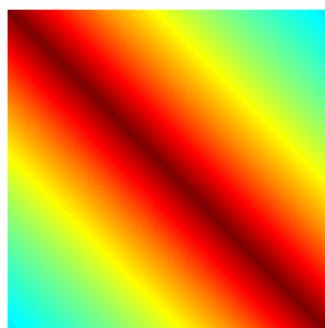
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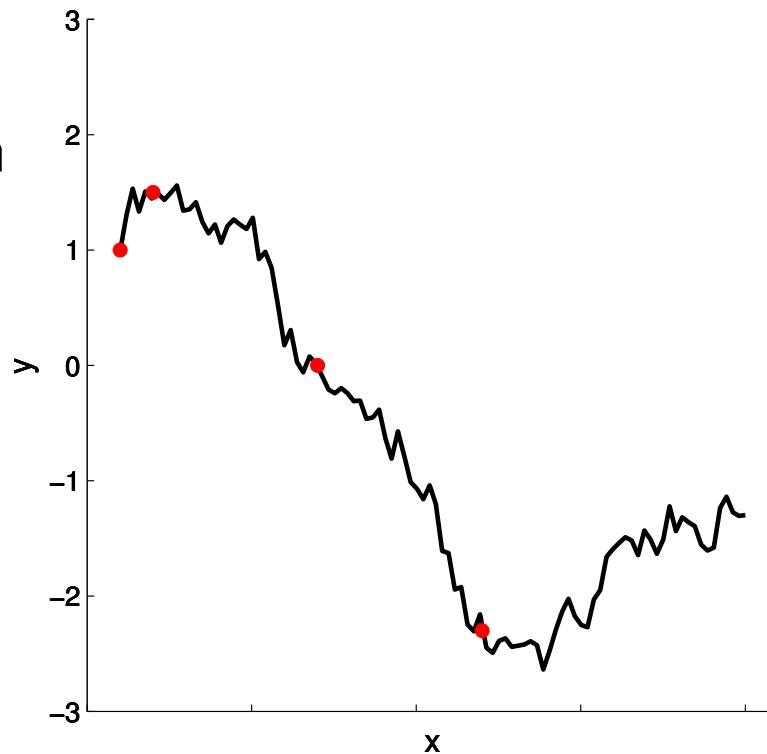
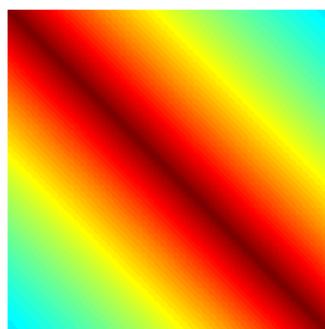
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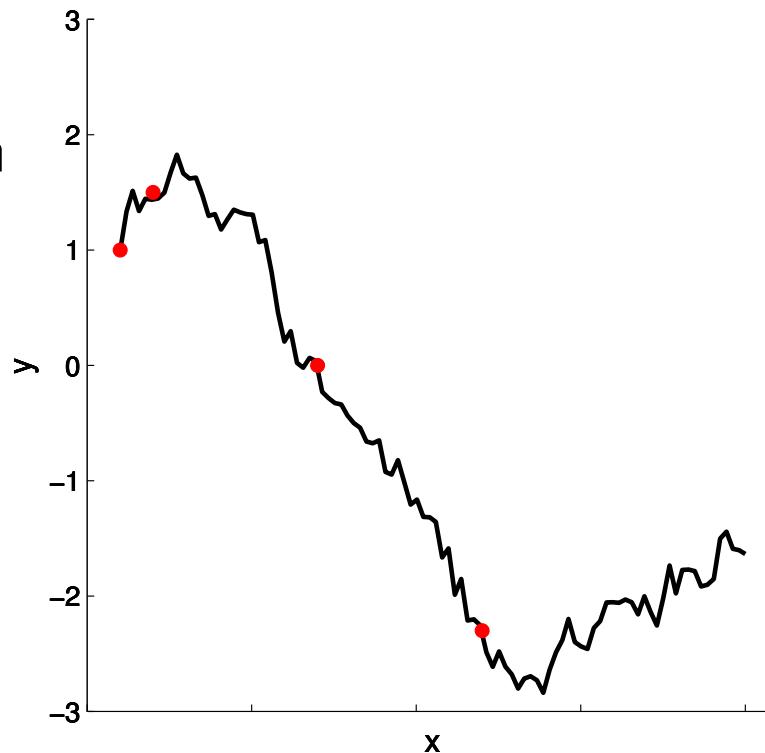
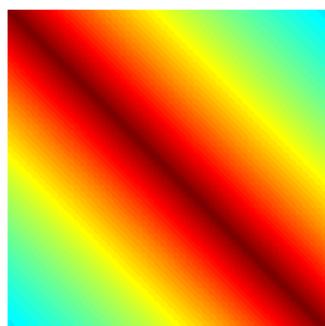
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Laplacian covariance function

Browninan motion

Ornstein-Uhlenbeck

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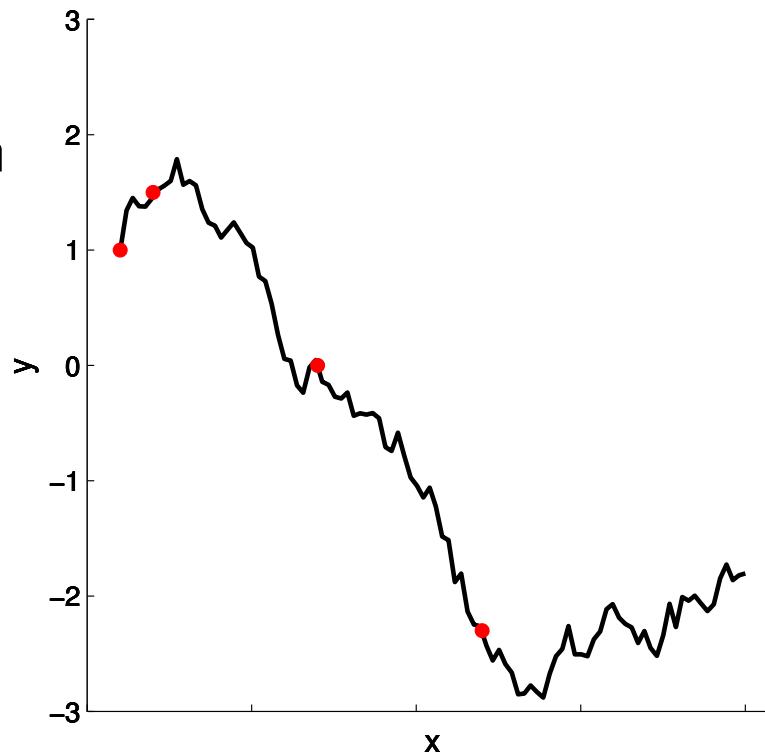
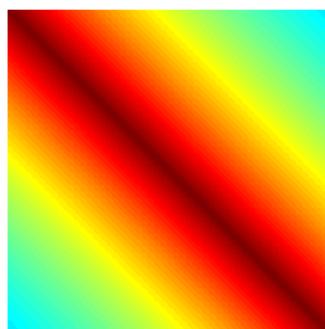
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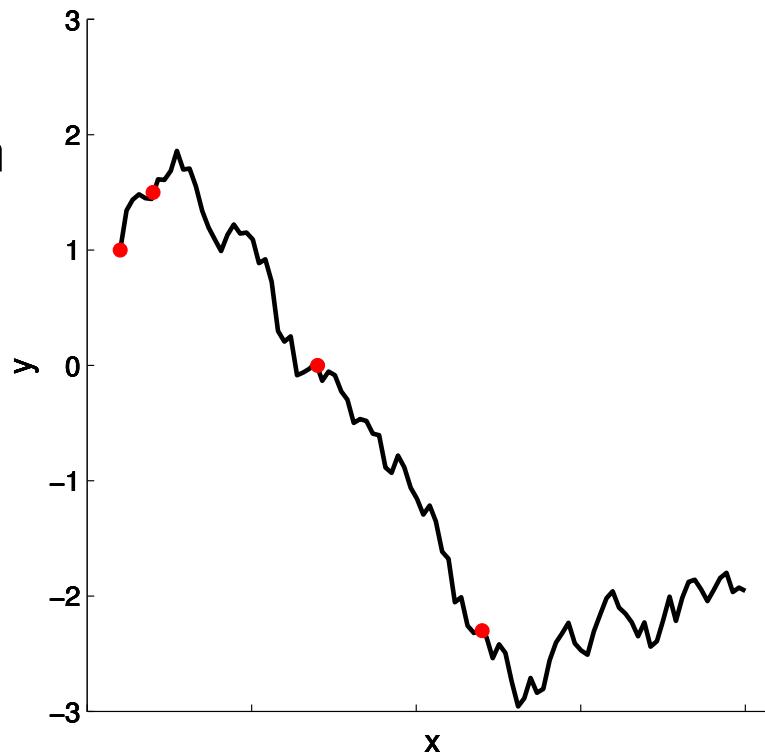
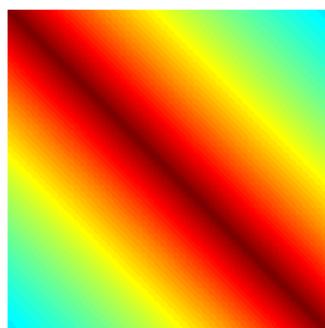
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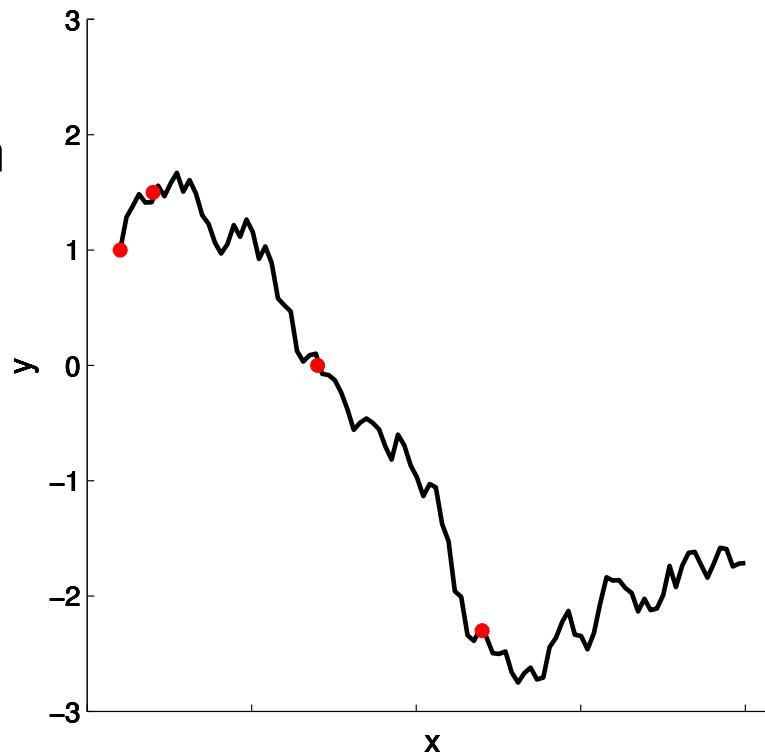
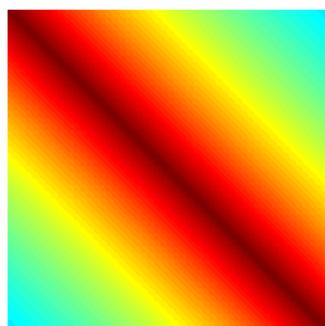
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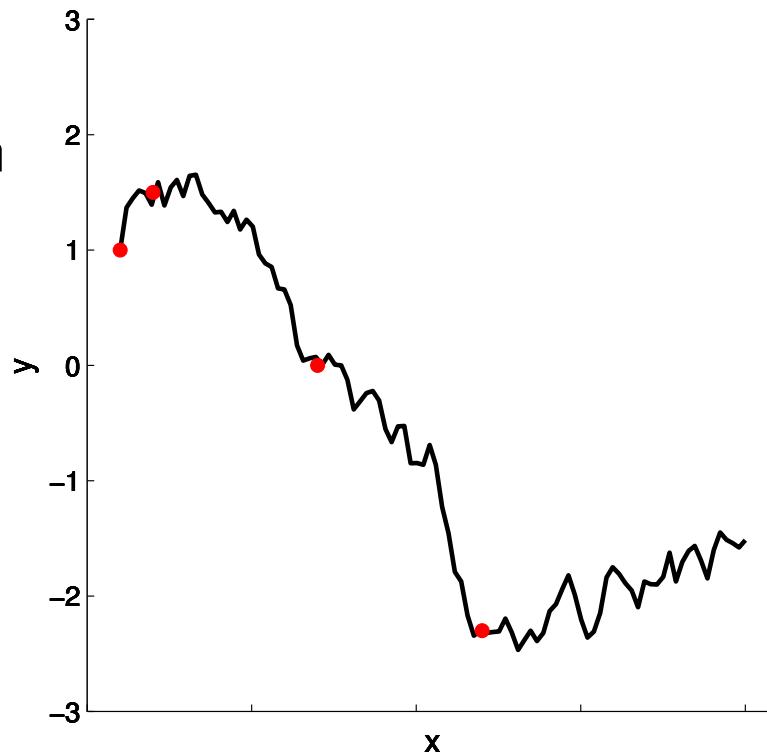
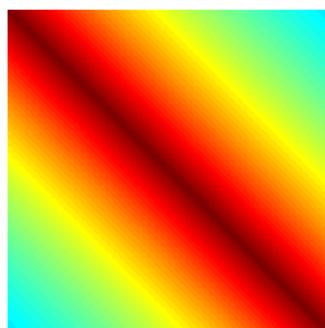
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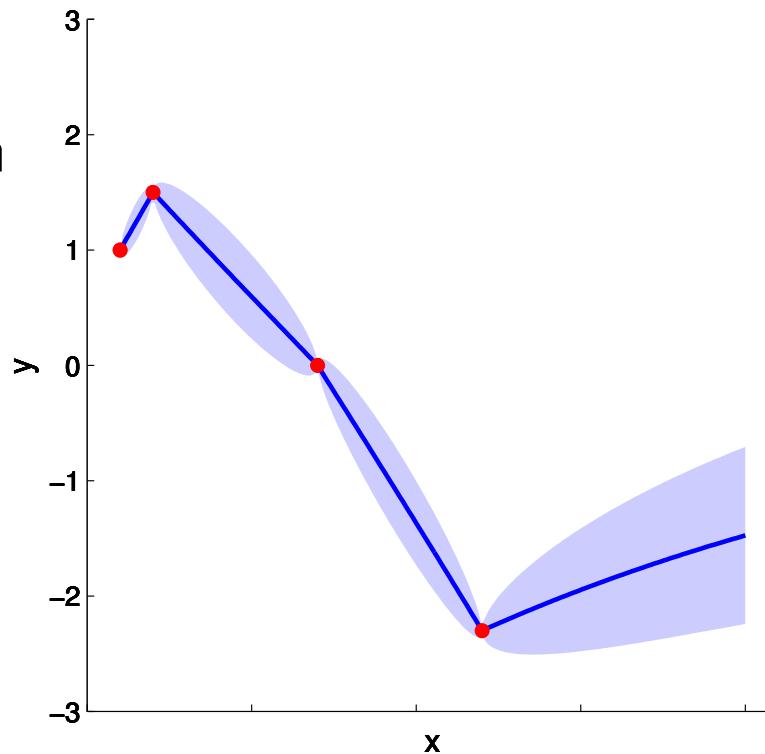
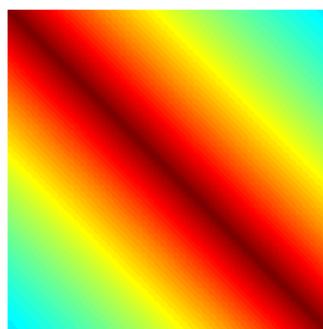
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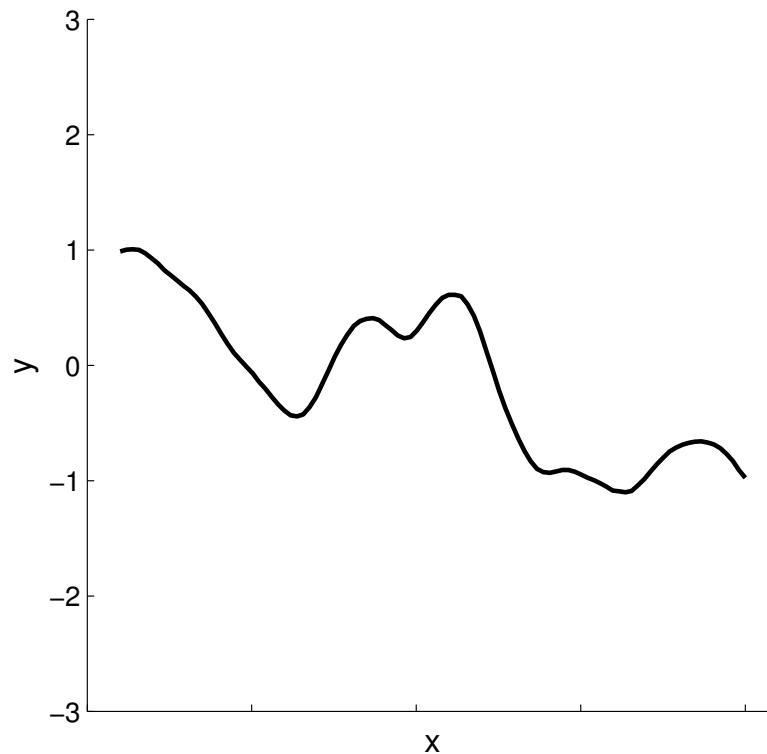
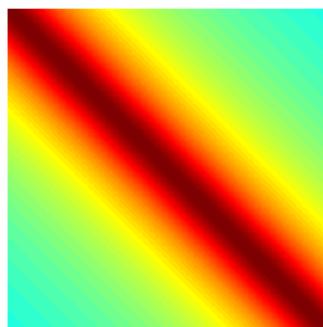


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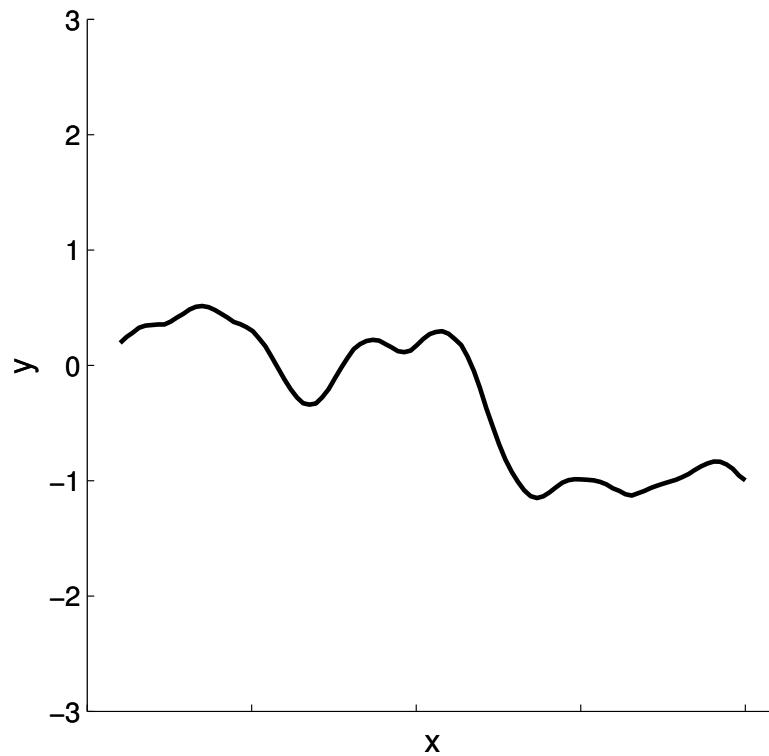
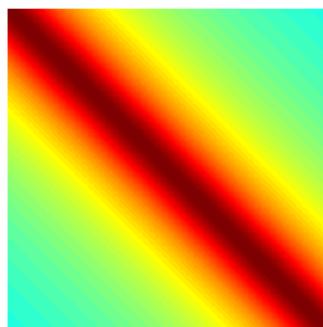


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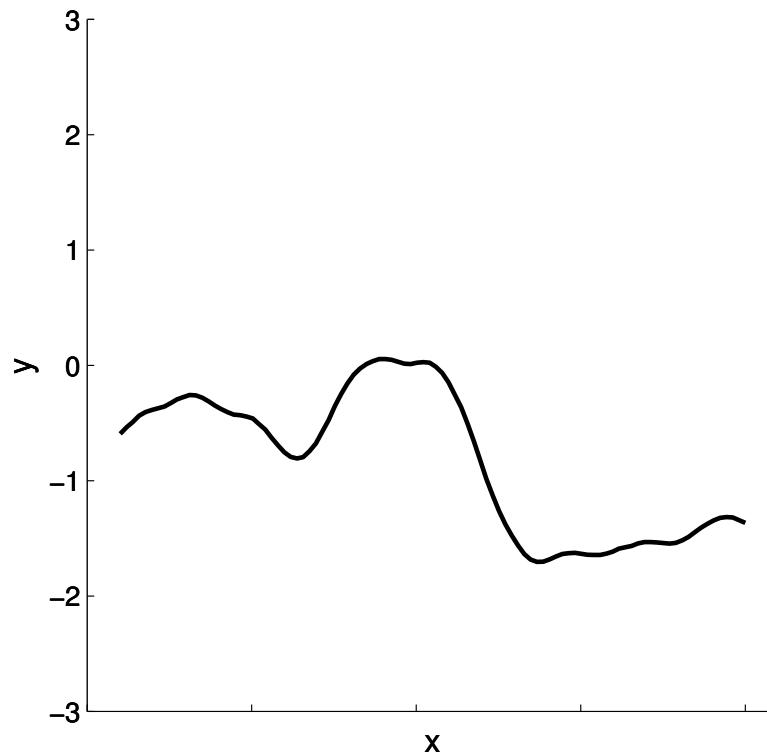
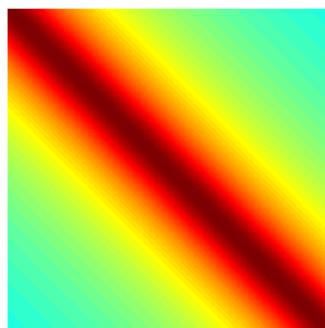


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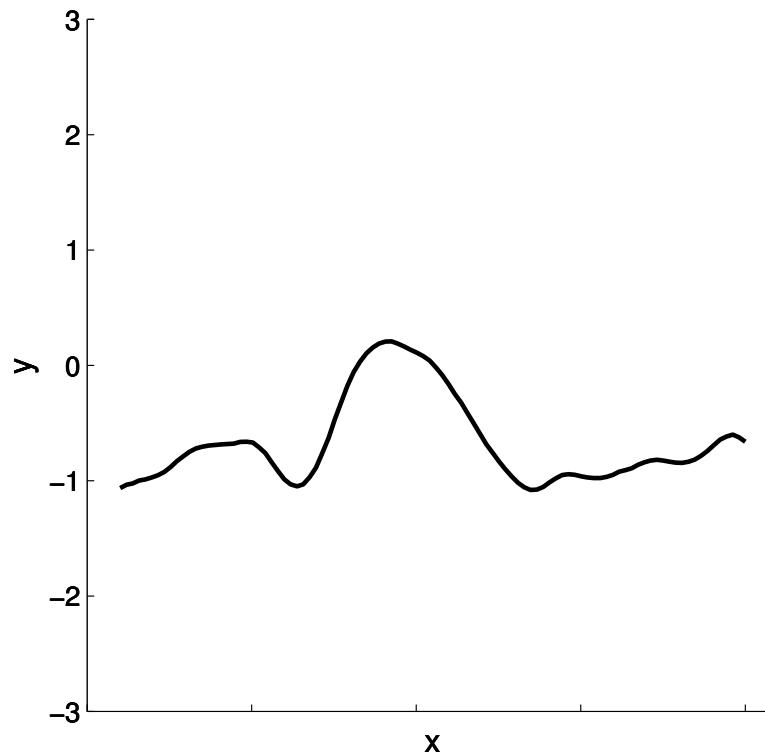
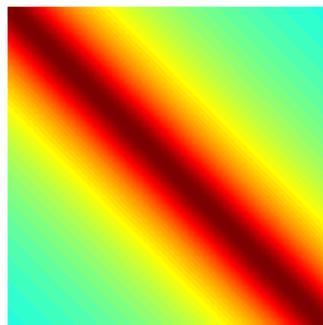


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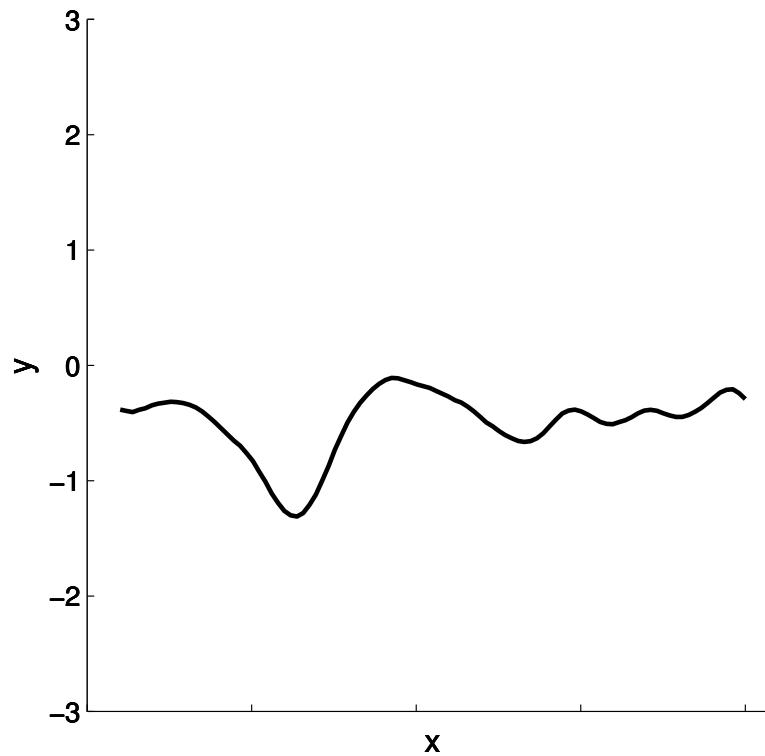
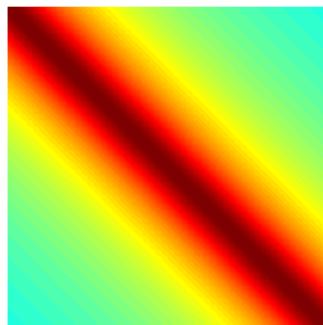


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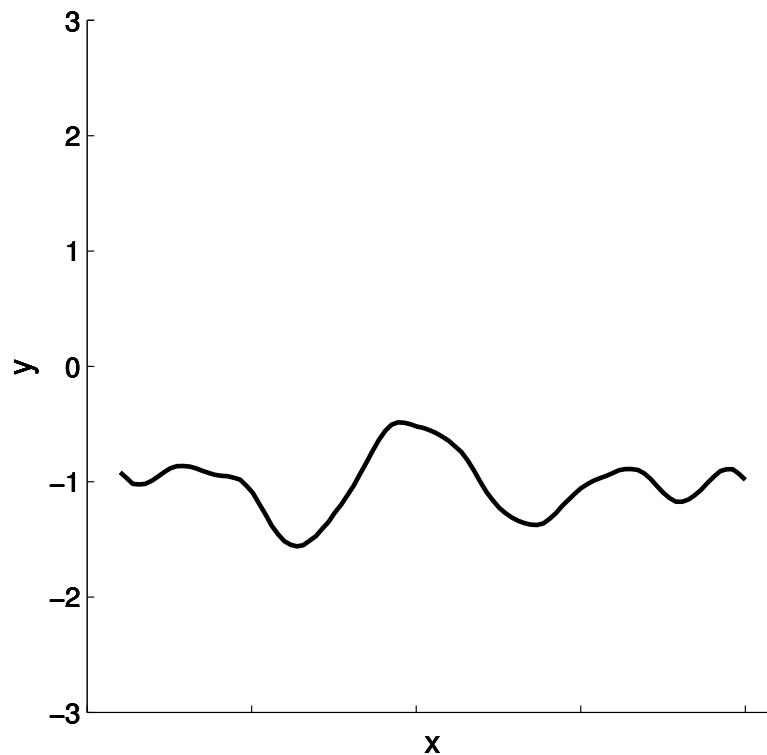
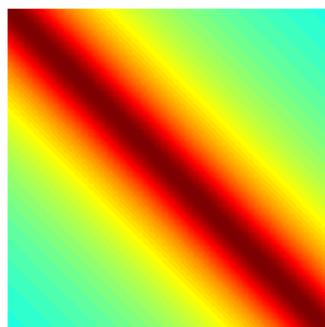


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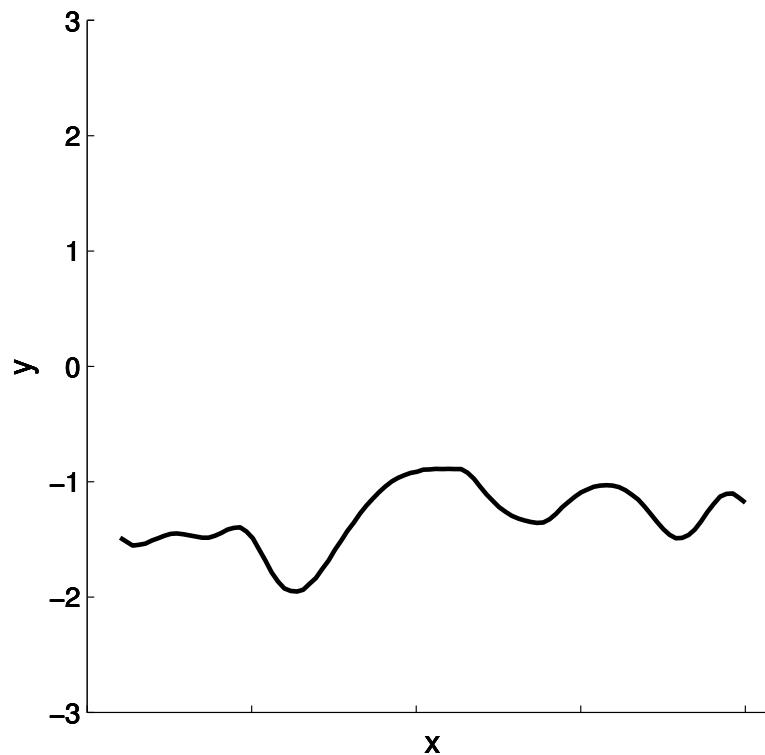
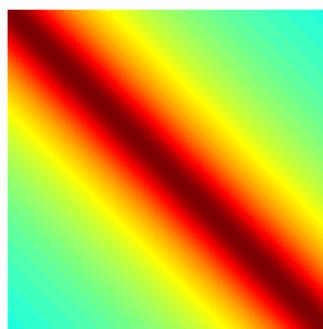


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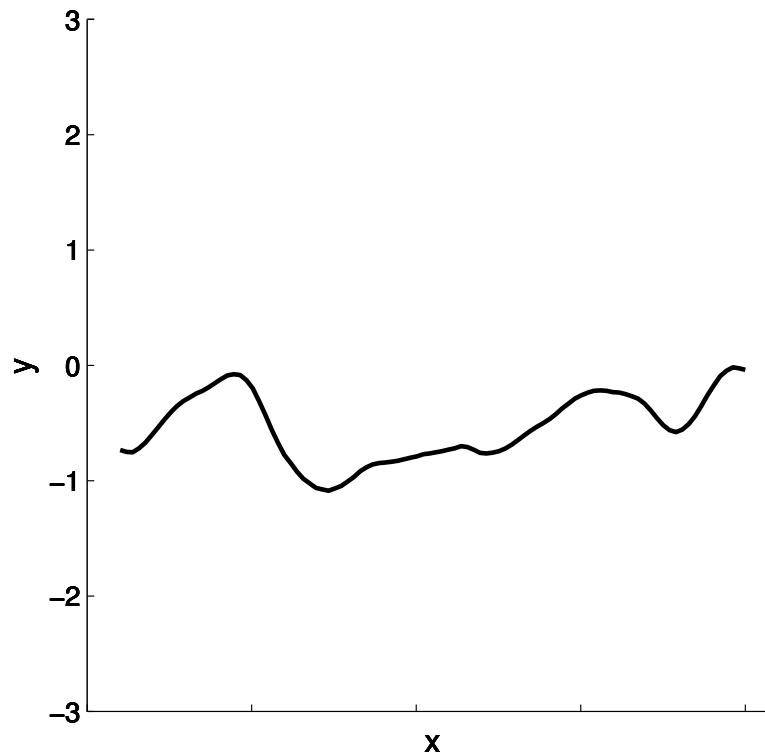
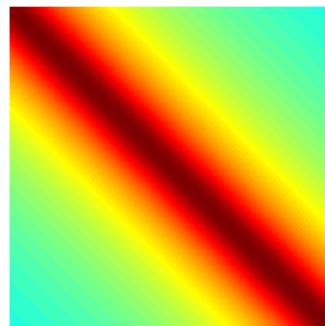


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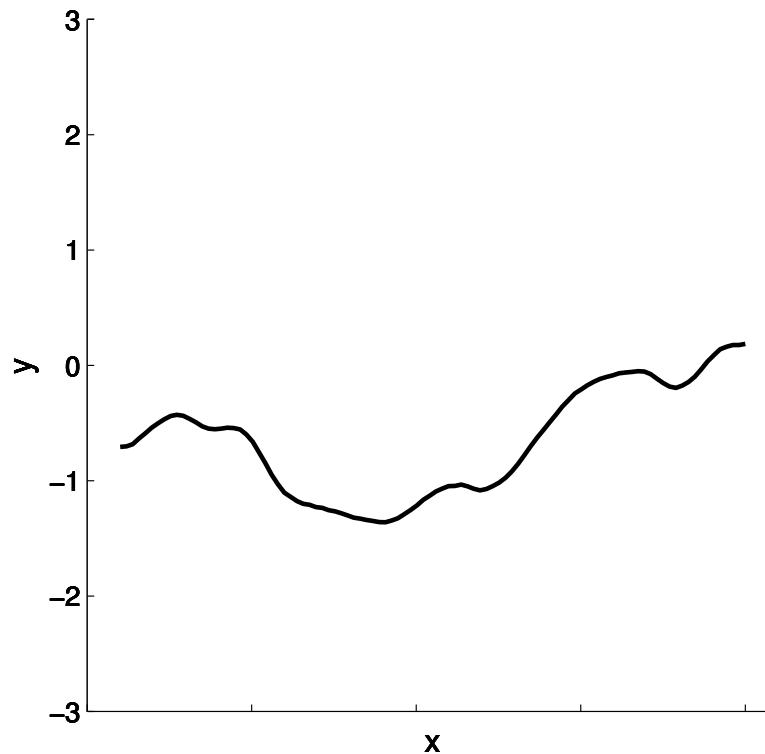
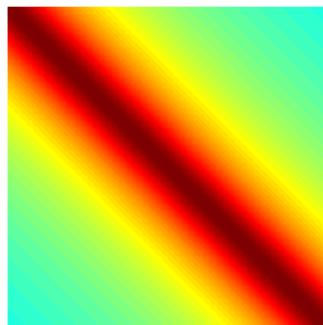


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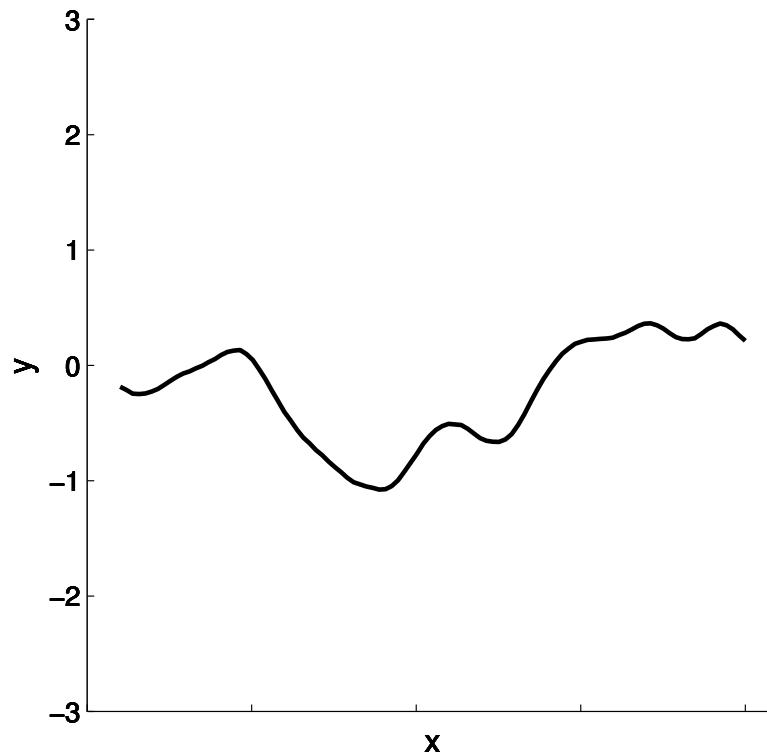
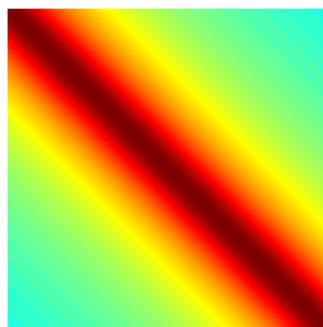


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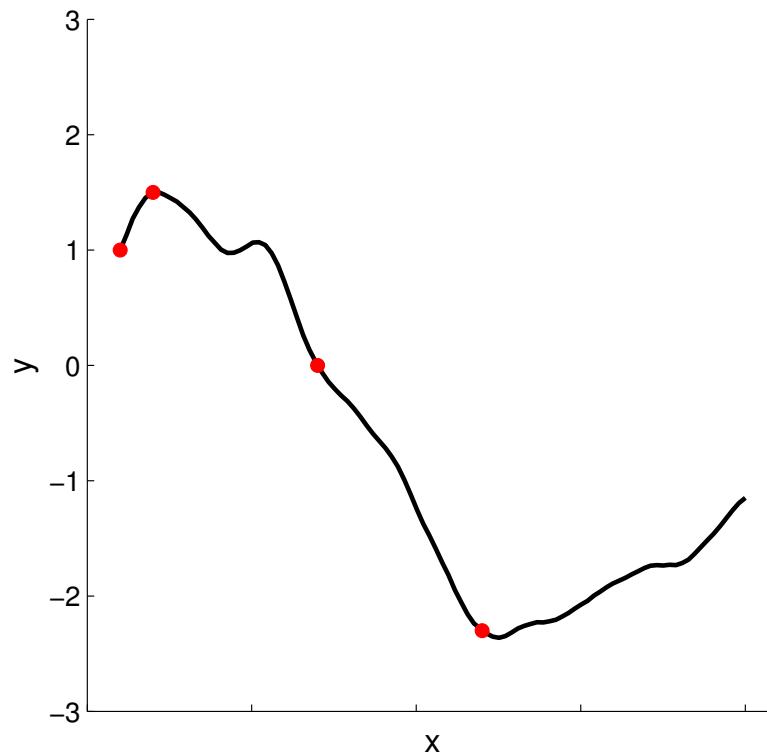
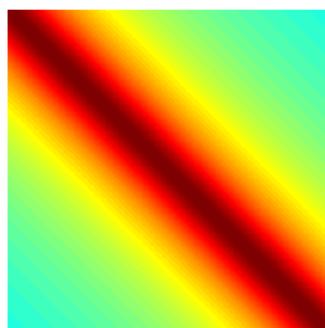


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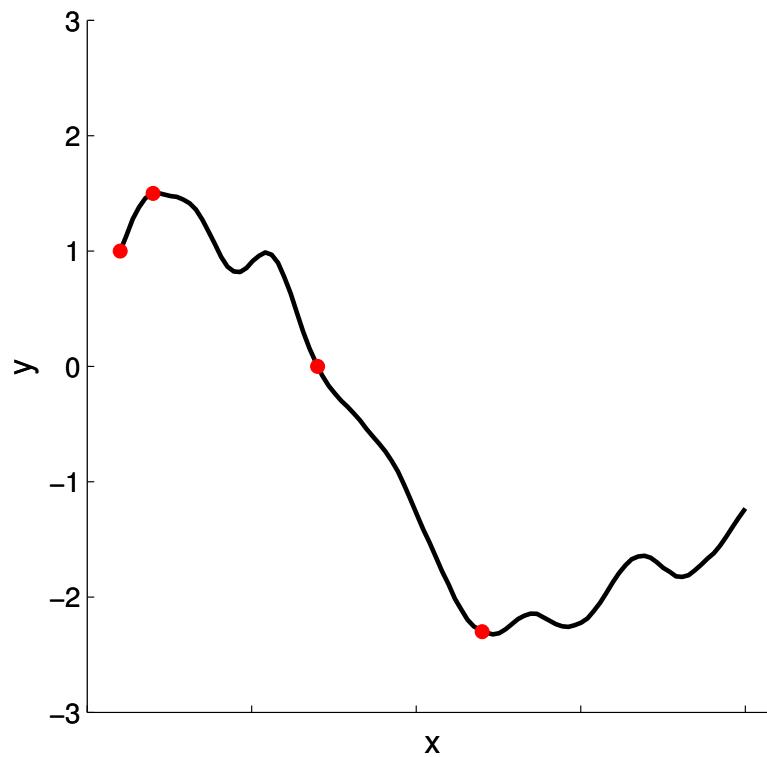
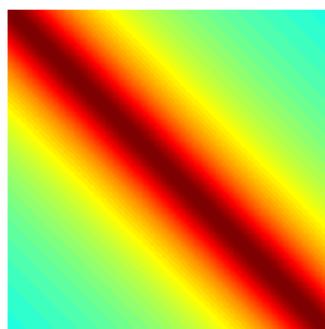


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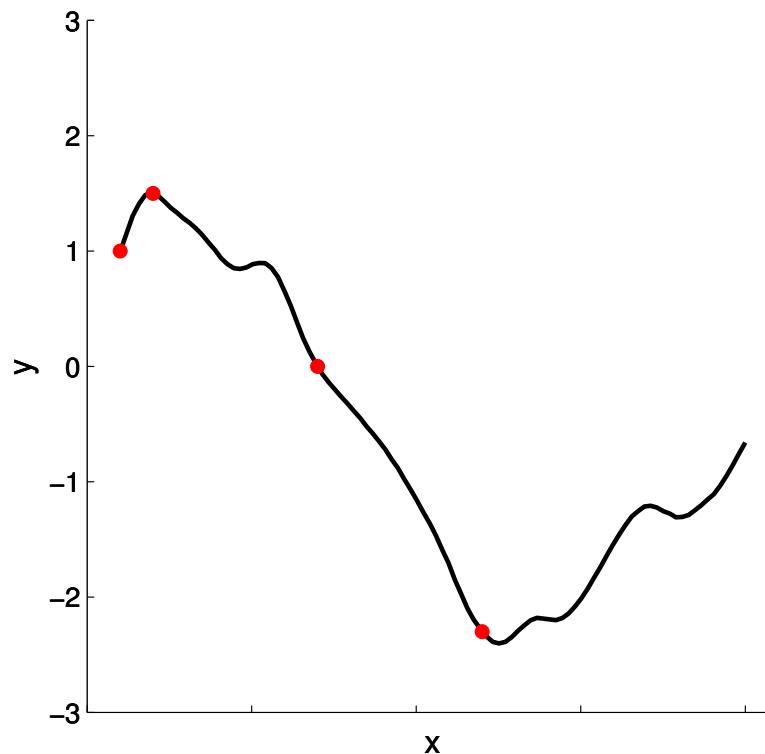
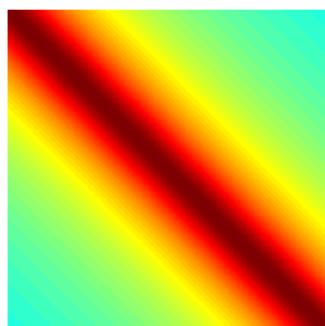


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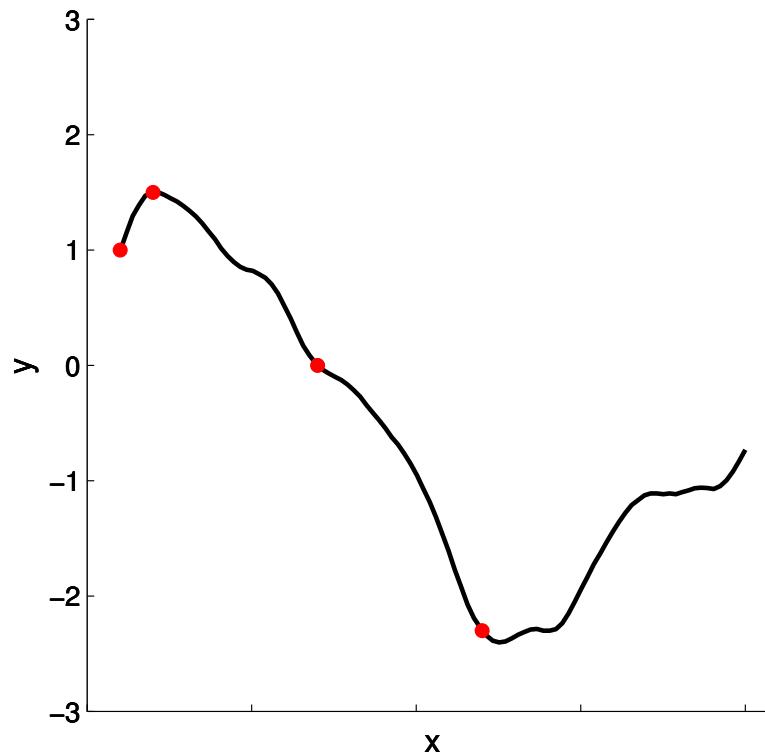
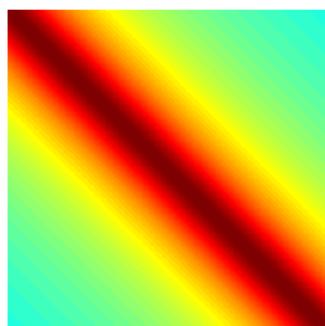


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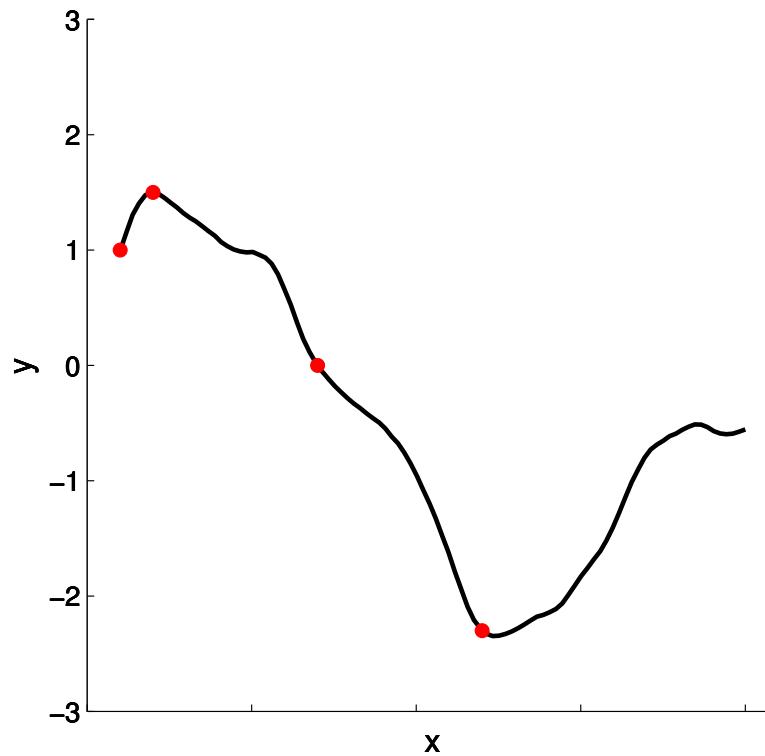
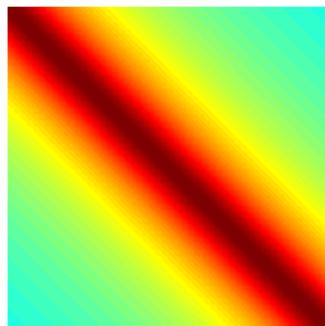


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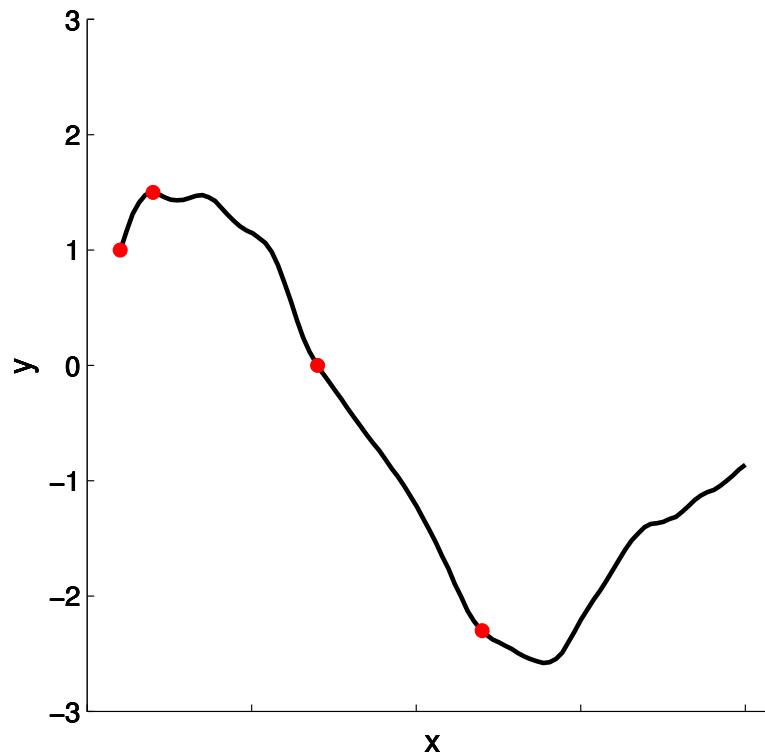
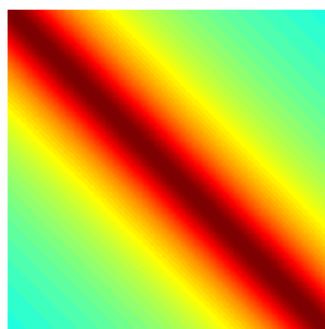


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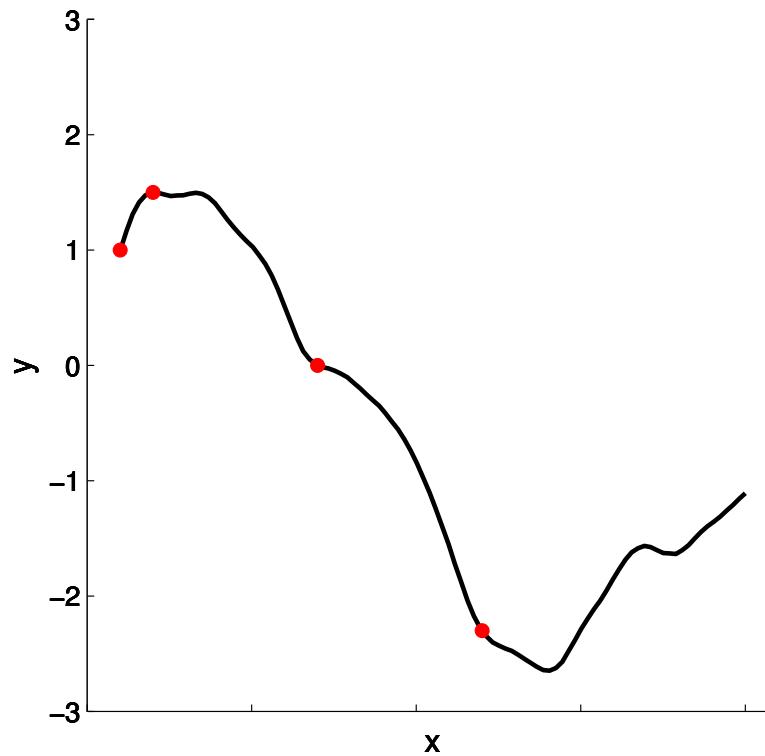
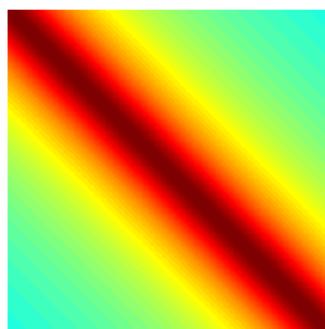


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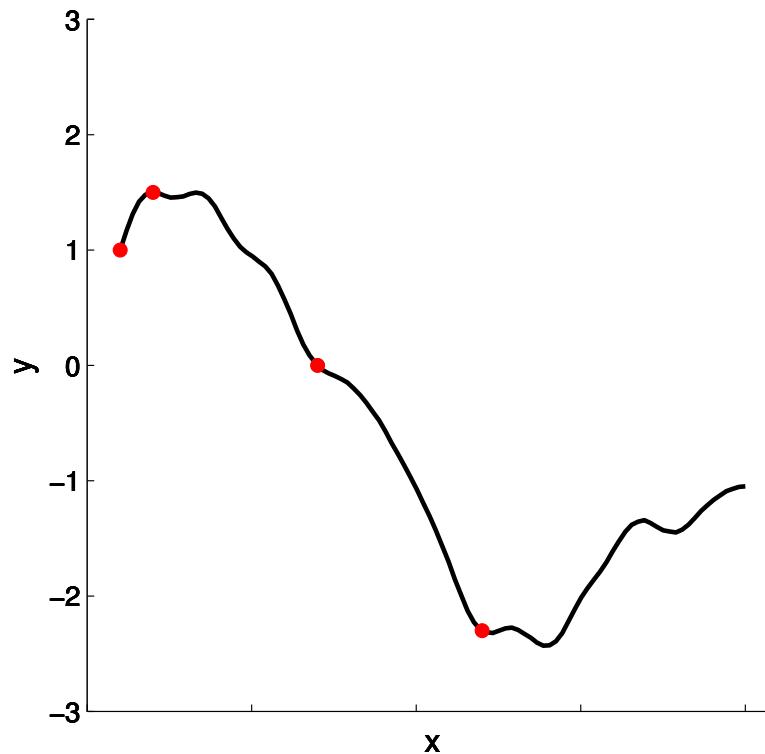
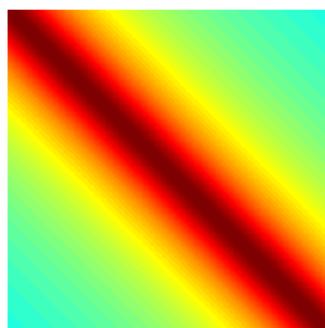


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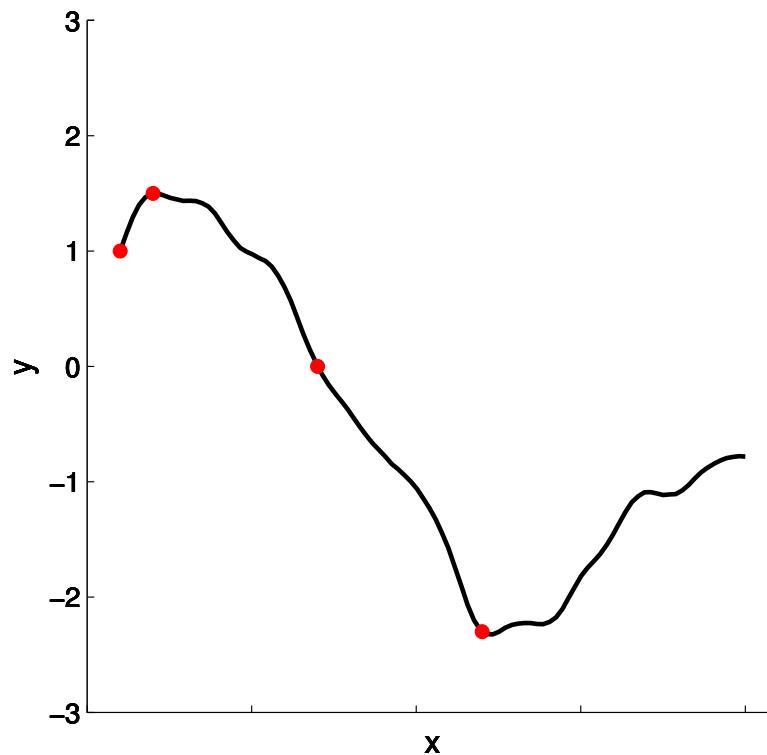
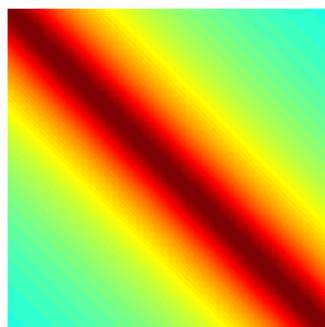


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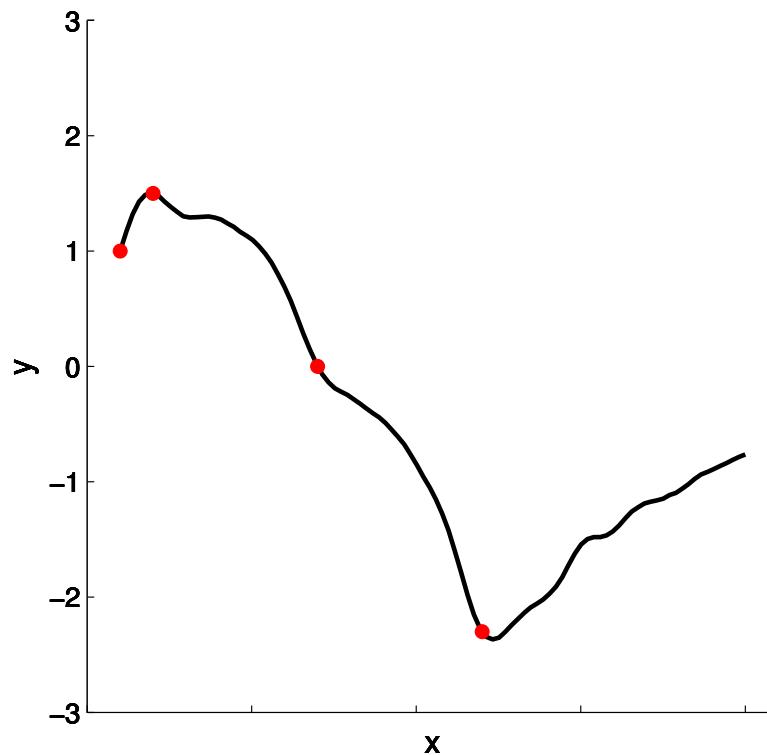
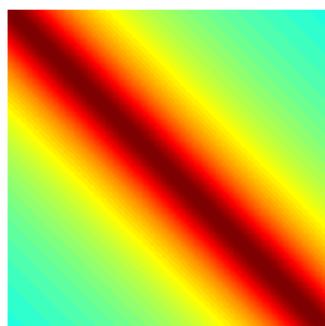


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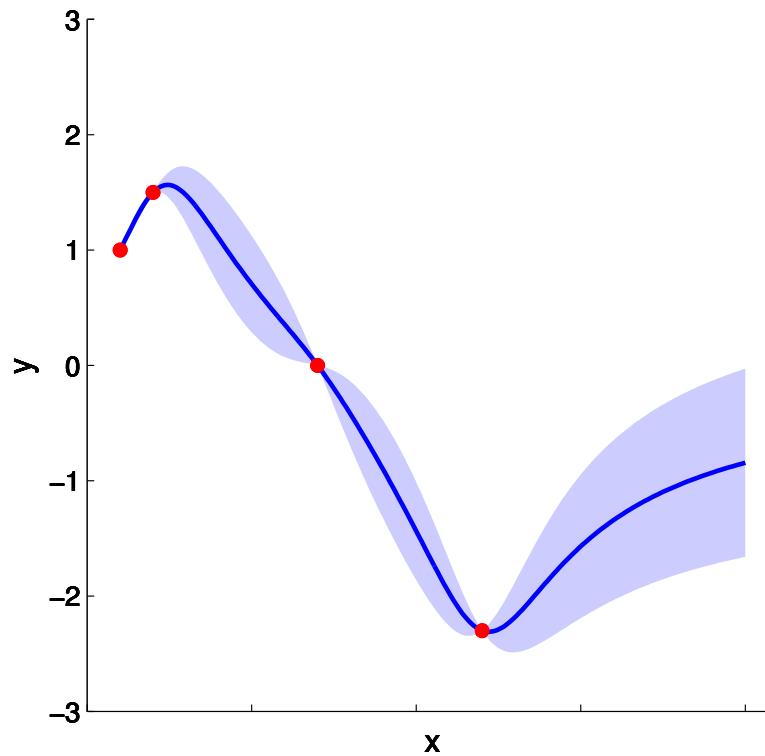
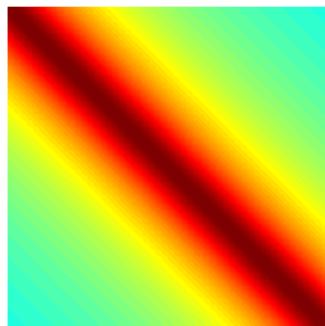


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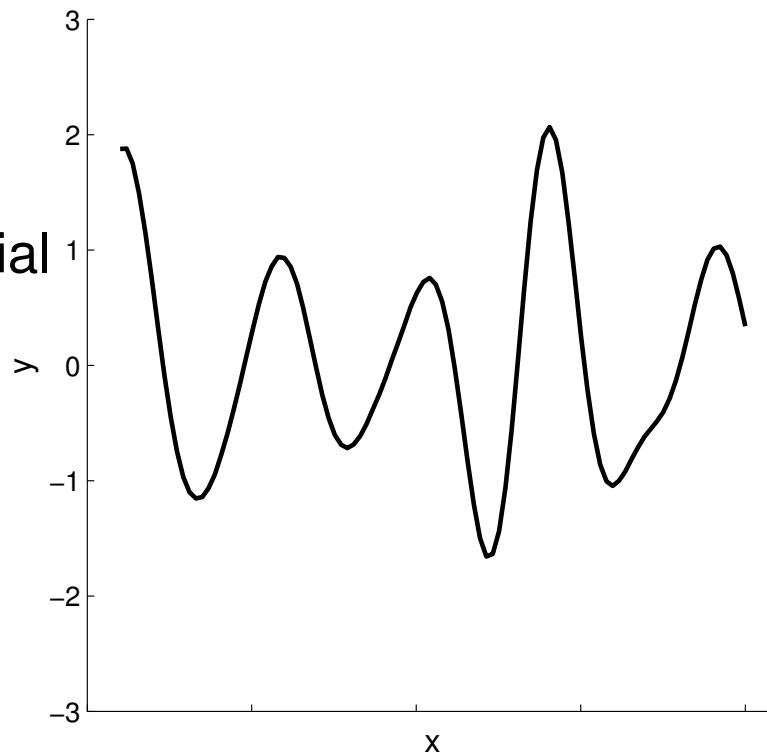
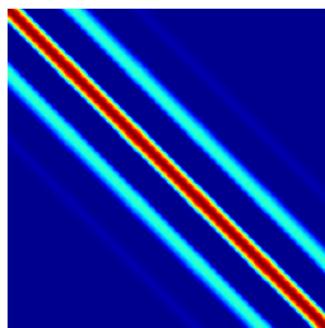
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Periodic

sinusoid \times squared exponential

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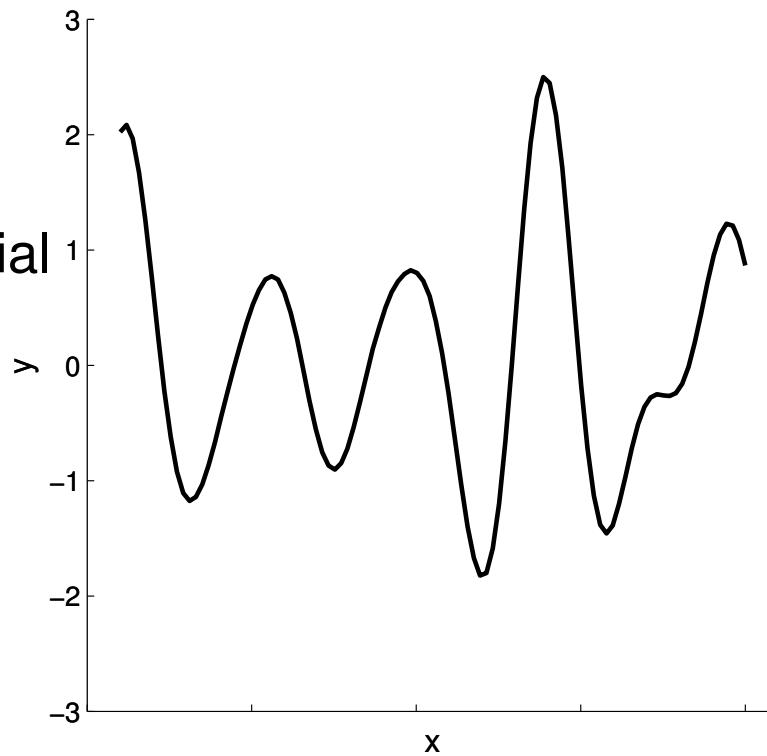
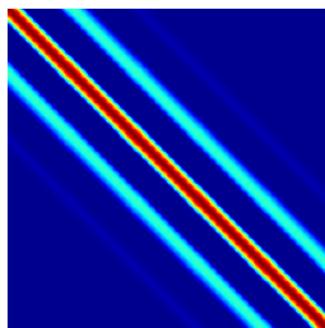
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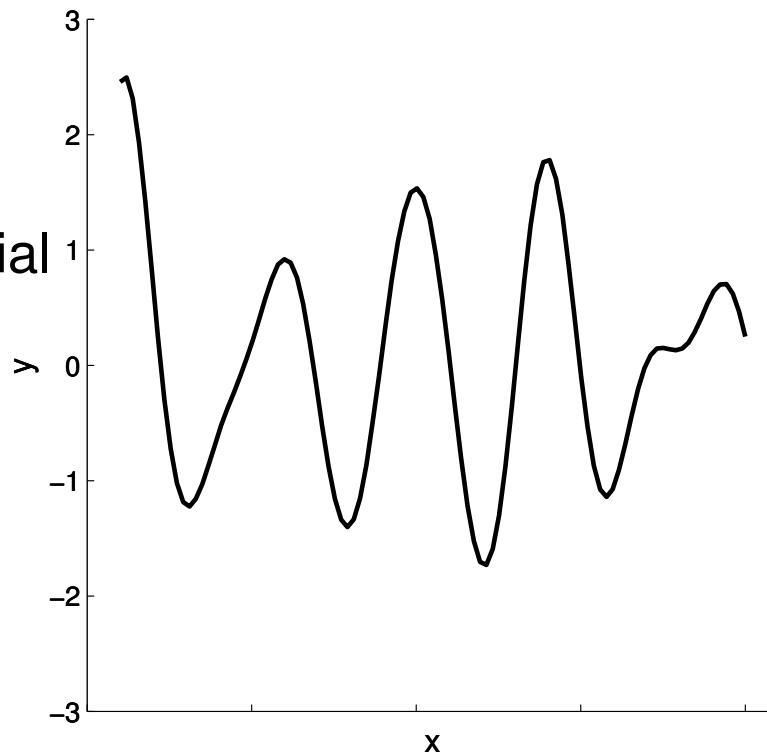
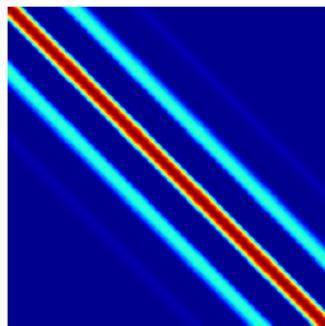
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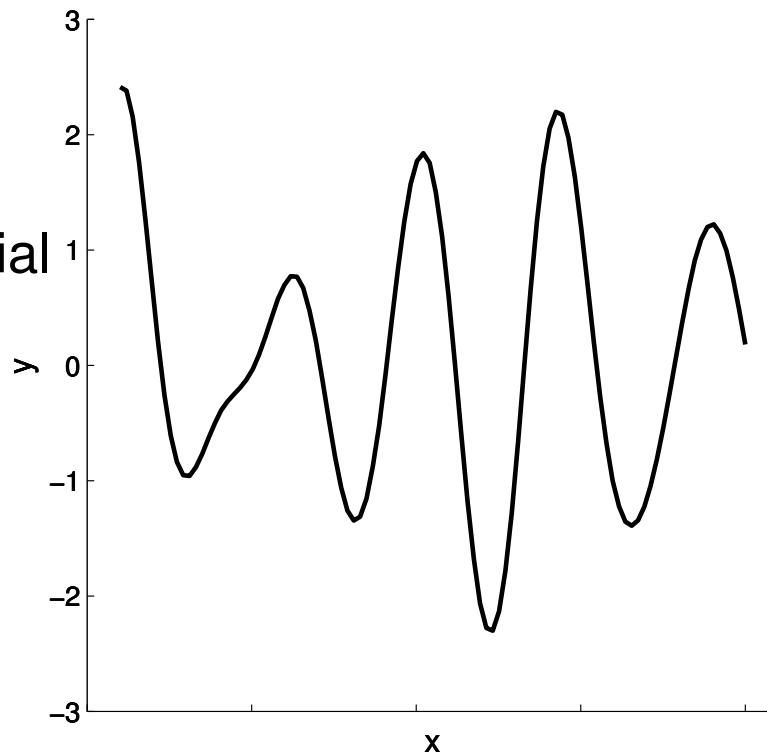
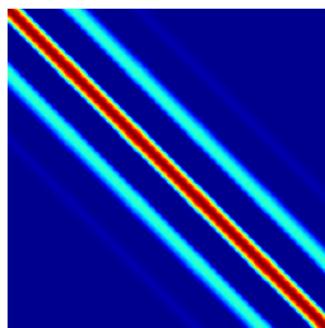
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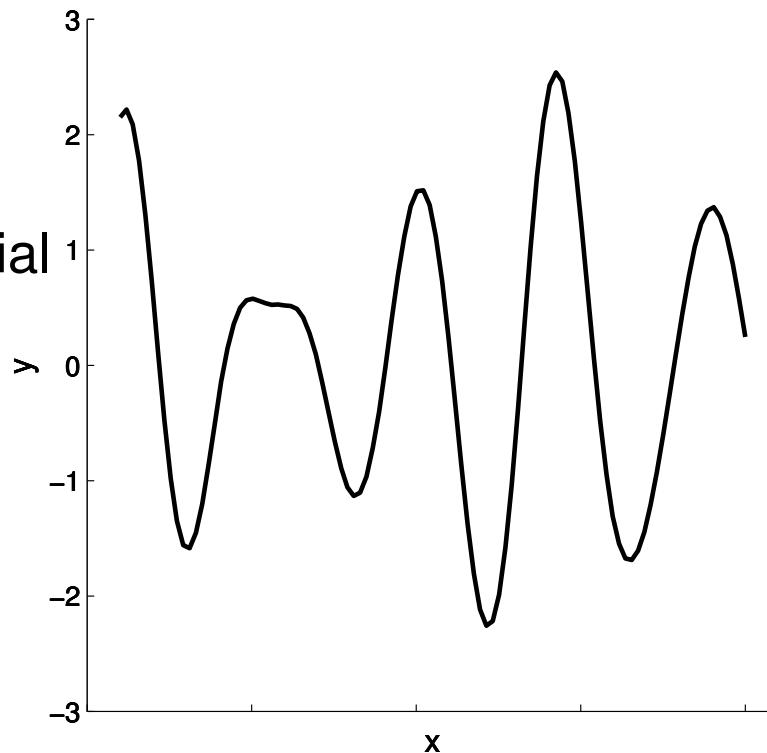
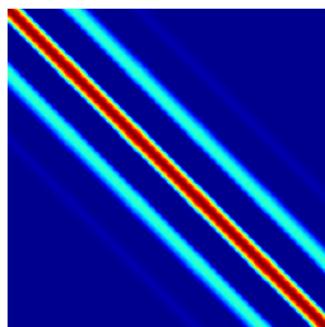
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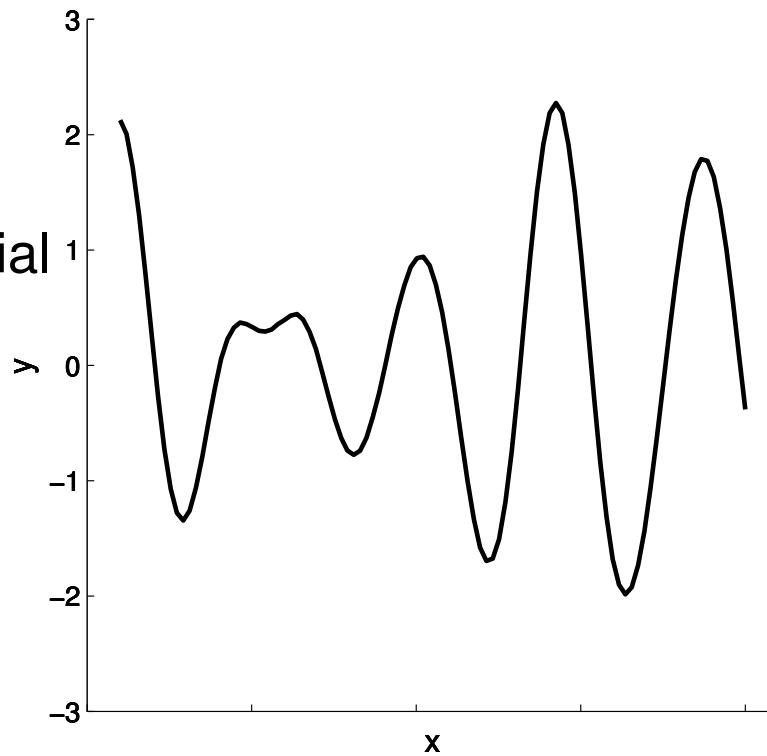
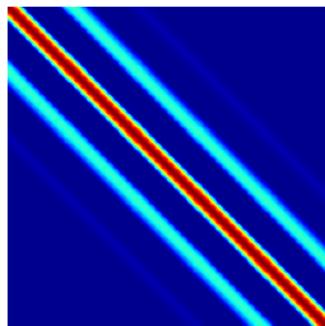
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Periodic

sinusoid \times squared exponential

$\Sigma =$



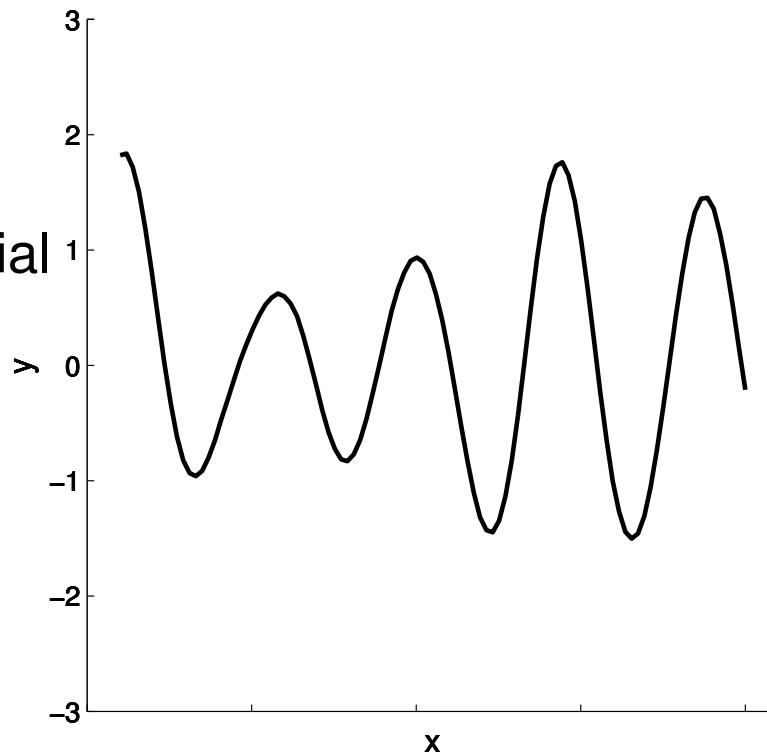
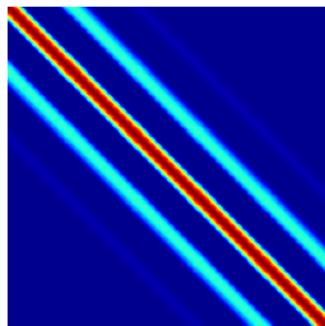
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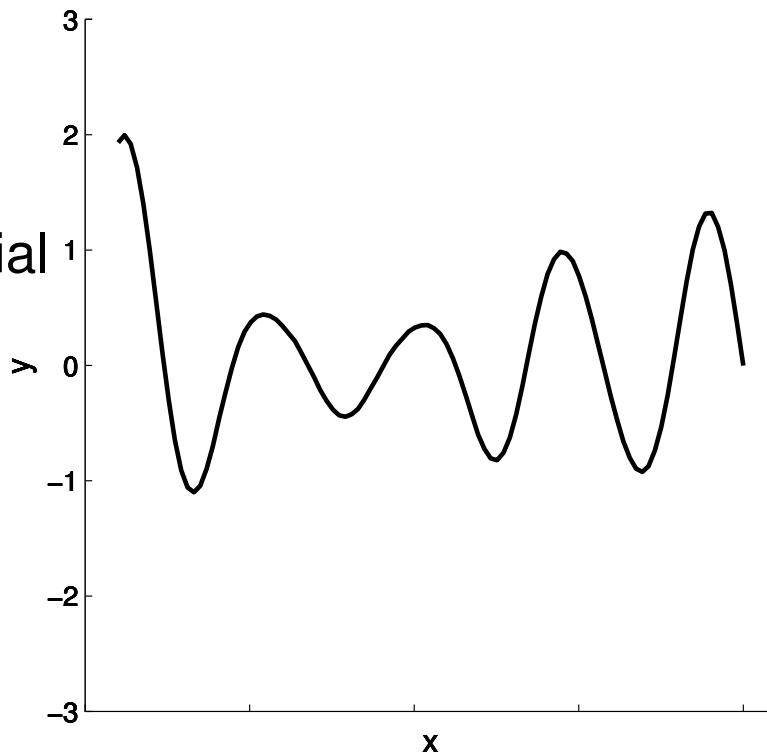
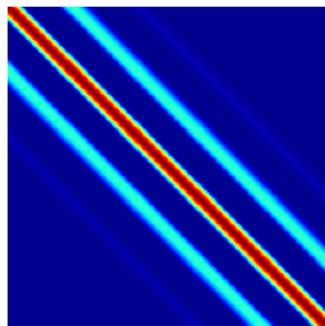
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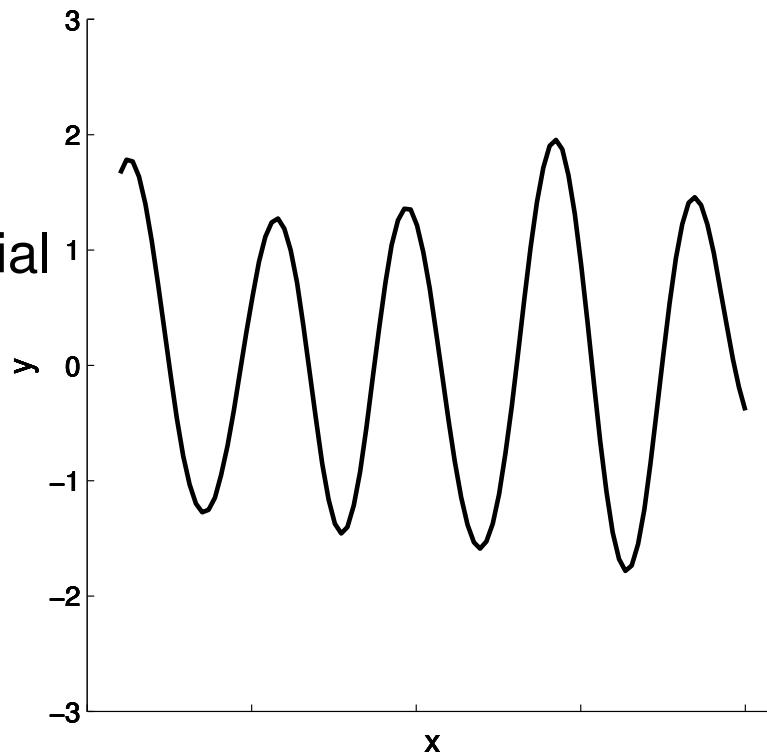
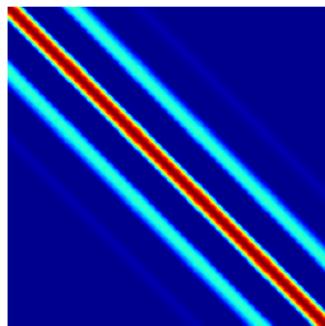
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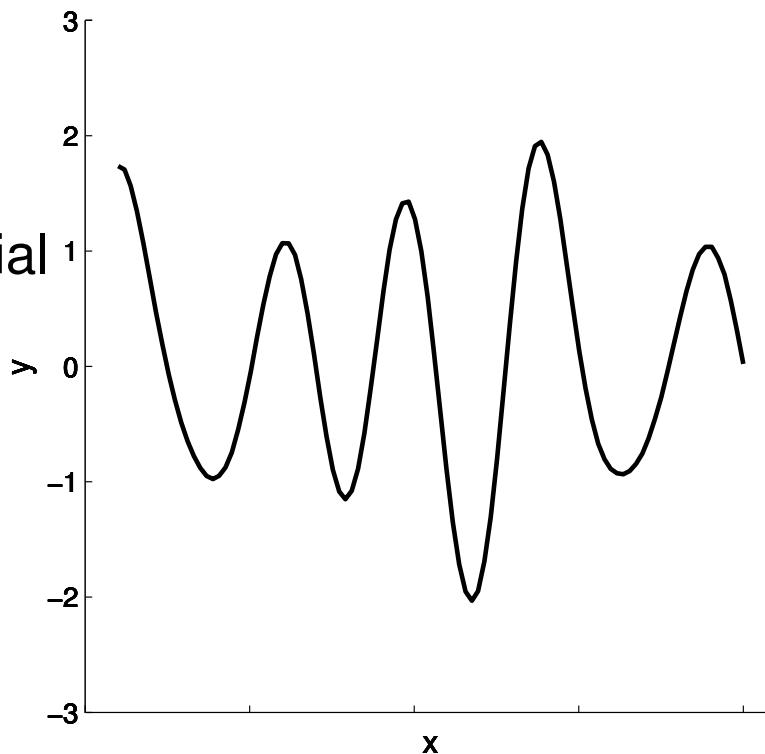
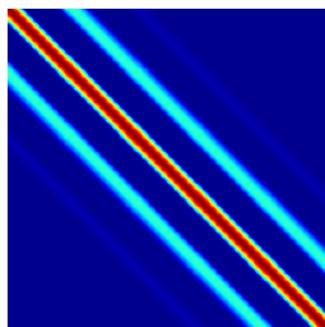
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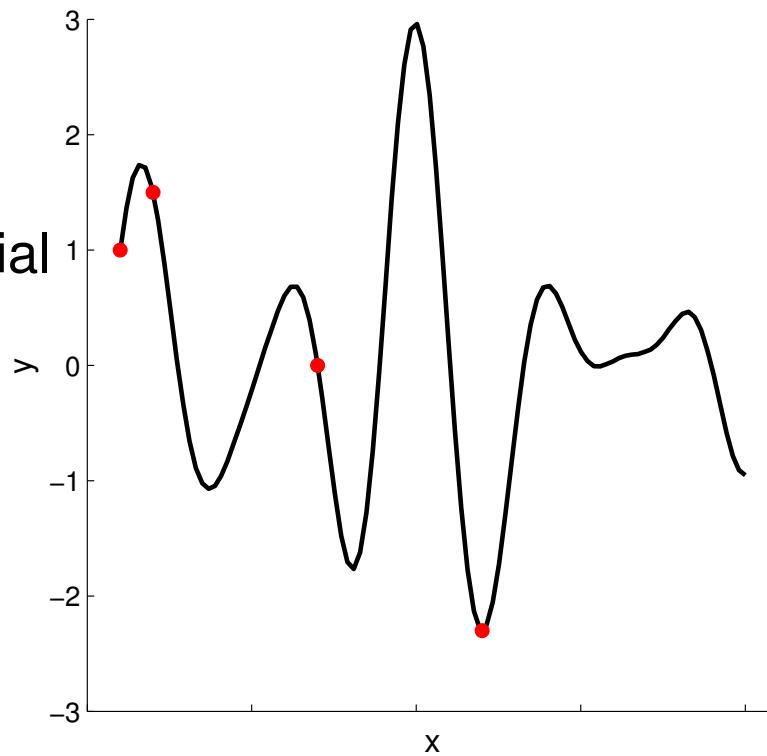
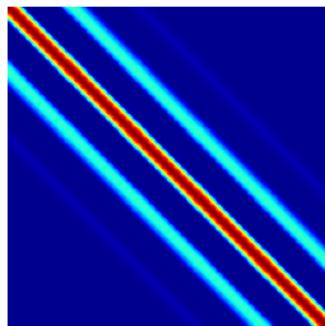
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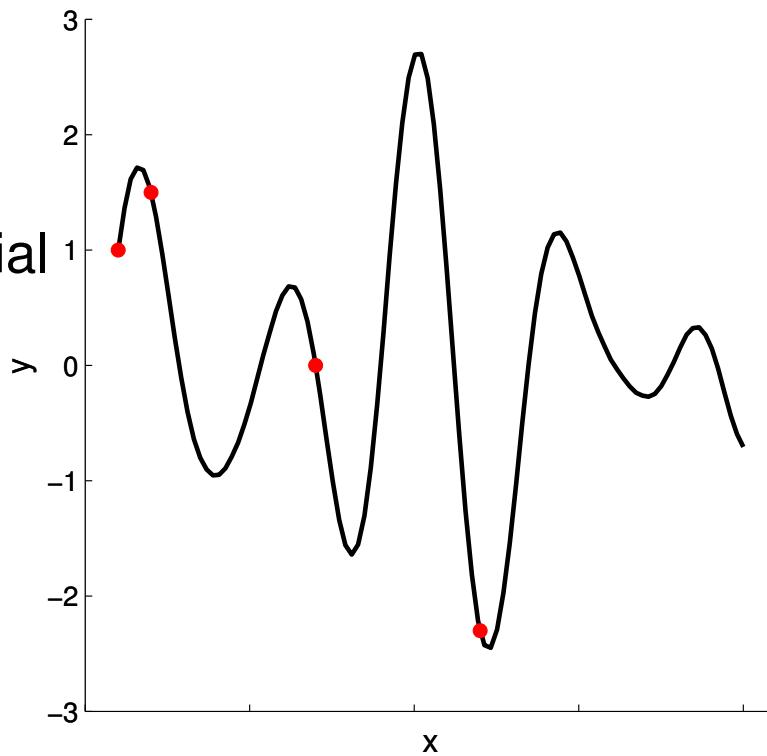
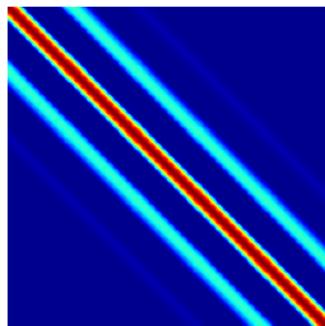
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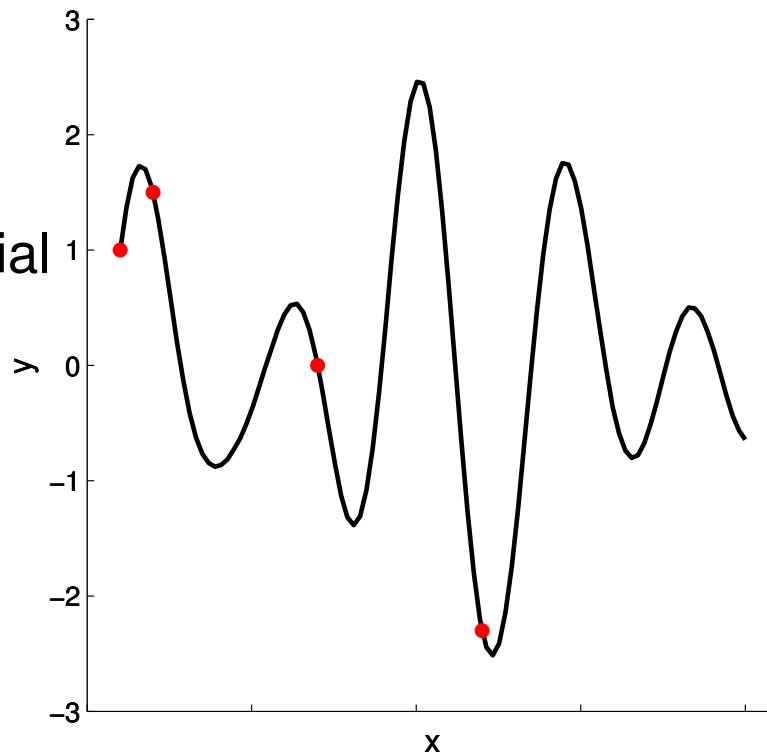
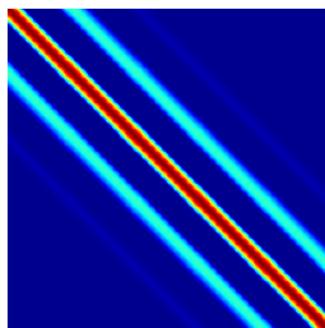
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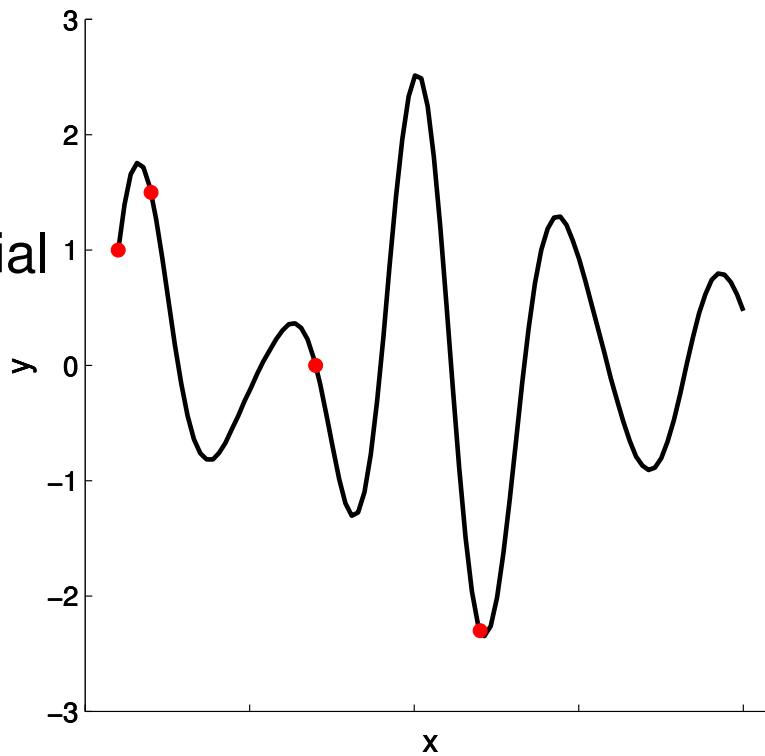
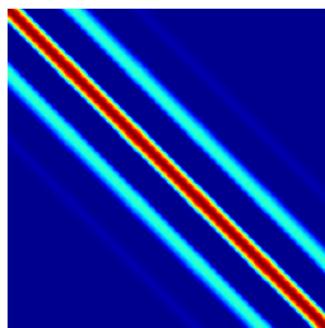
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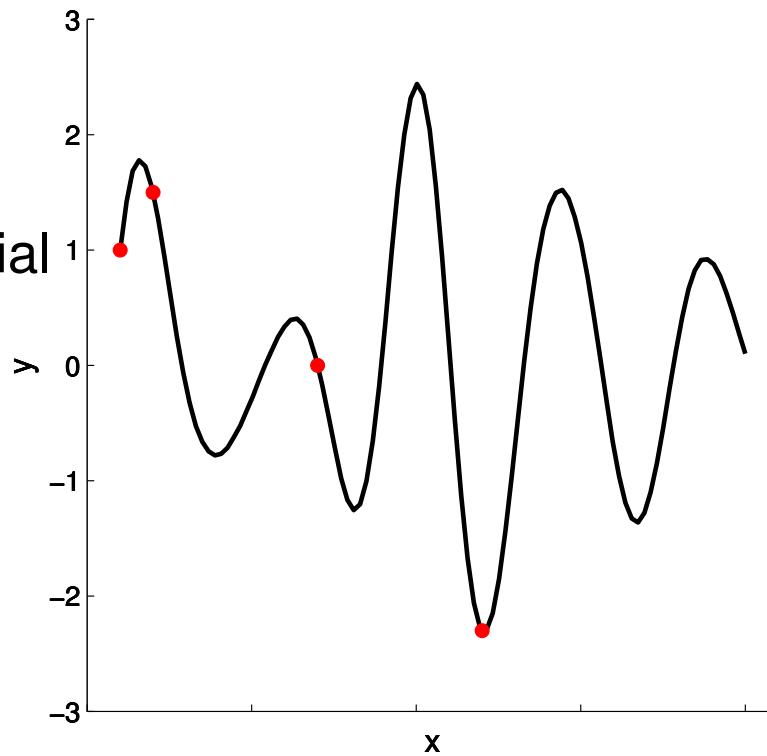
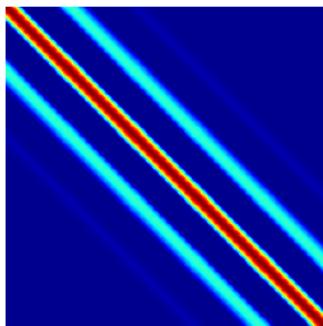
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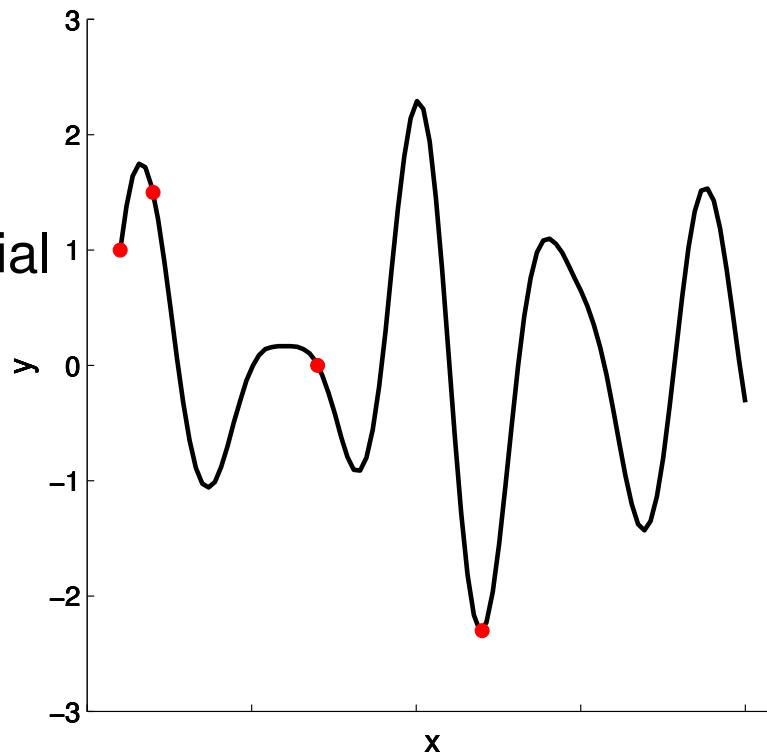
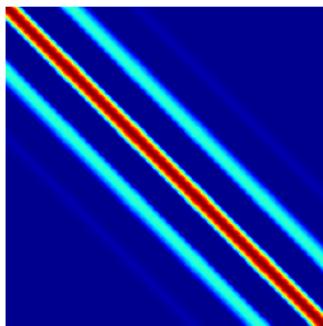
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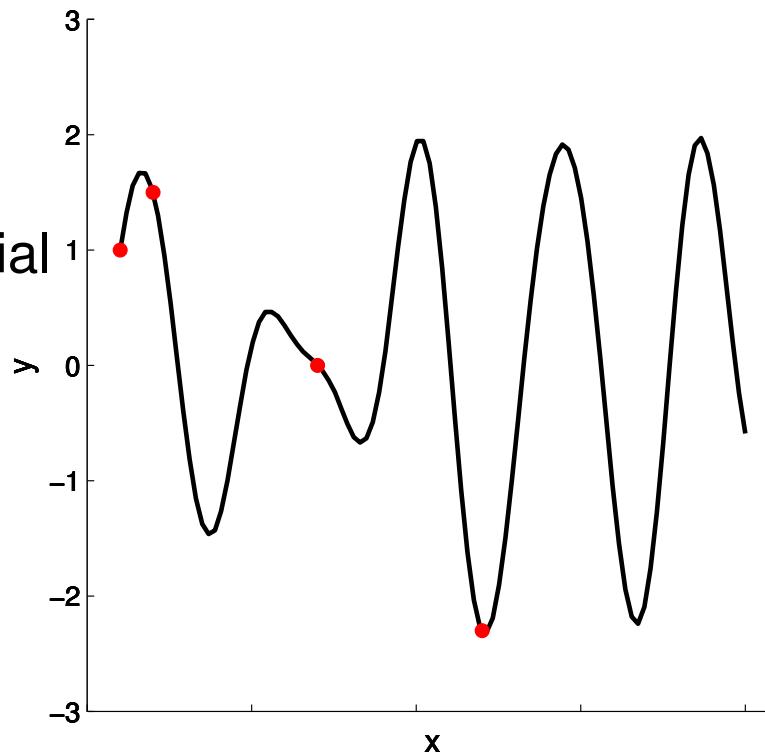
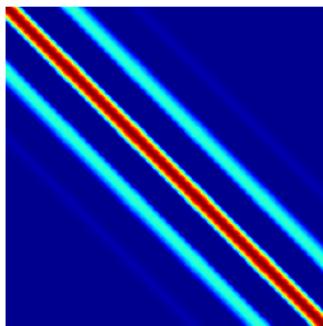
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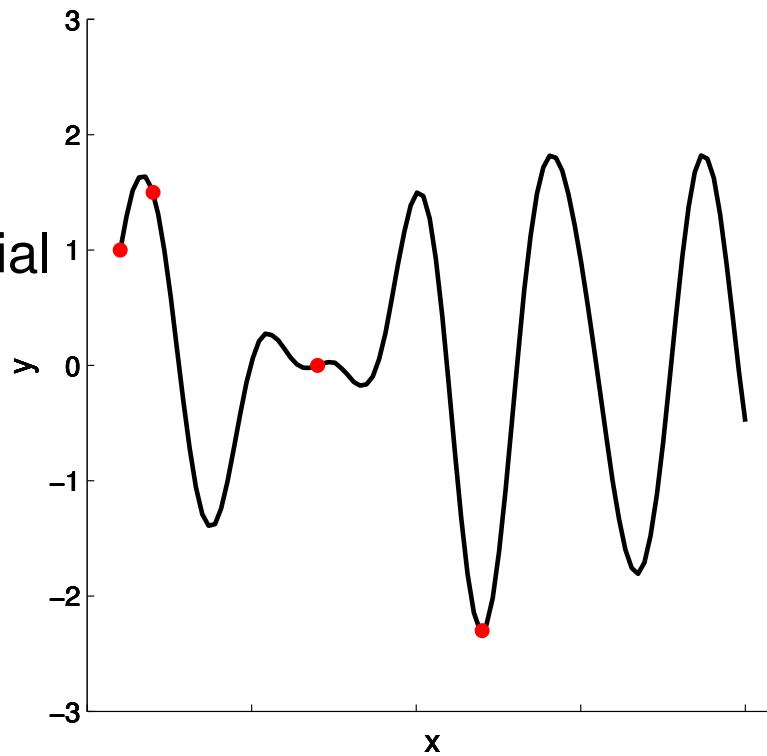
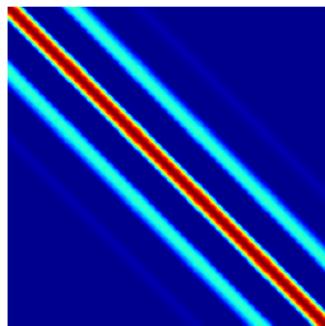
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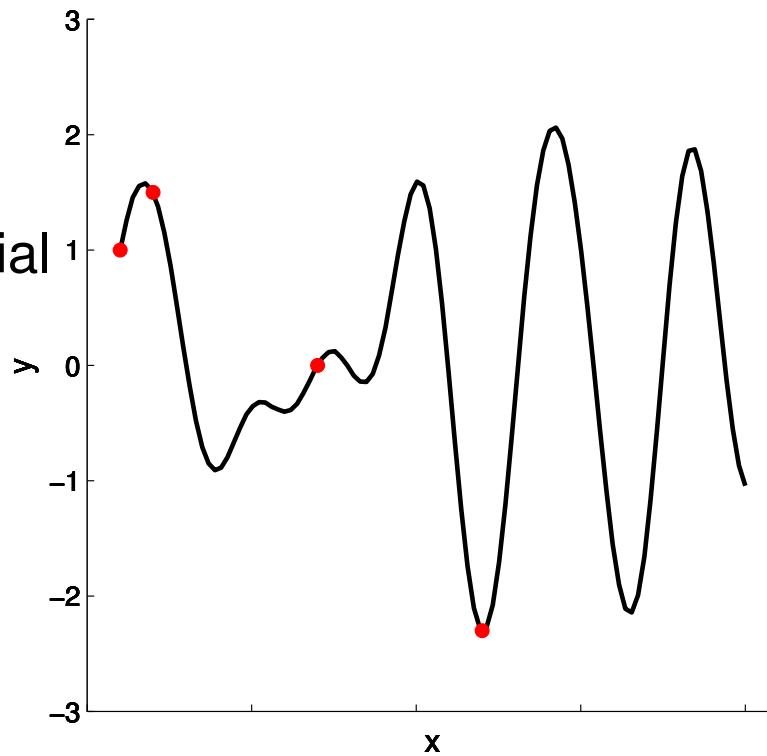
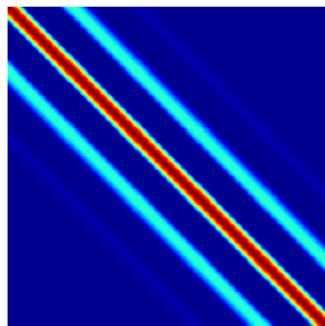
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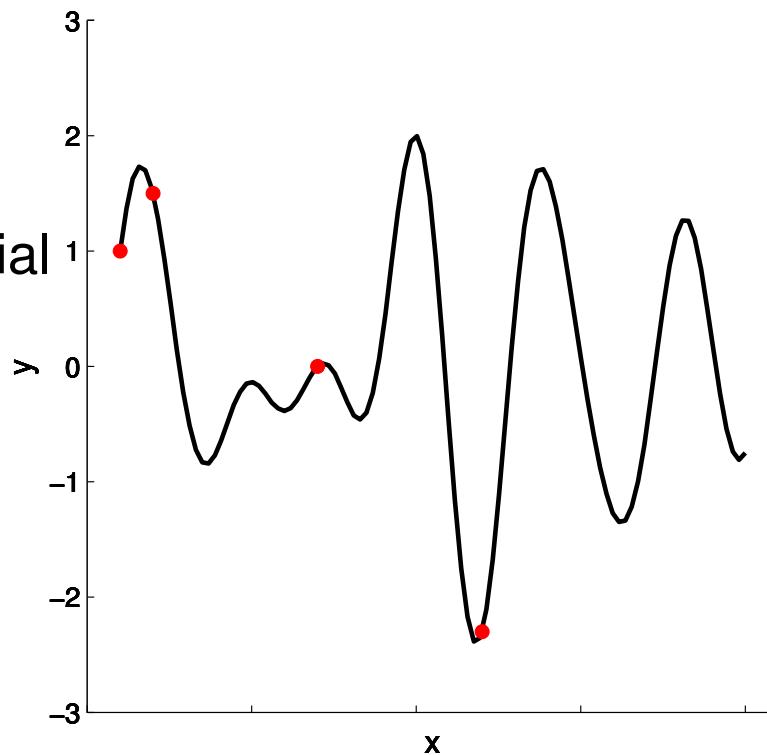
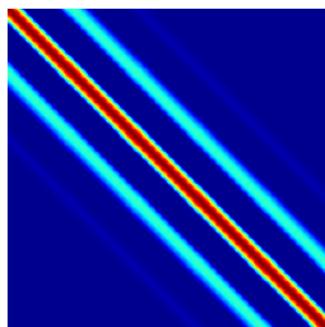
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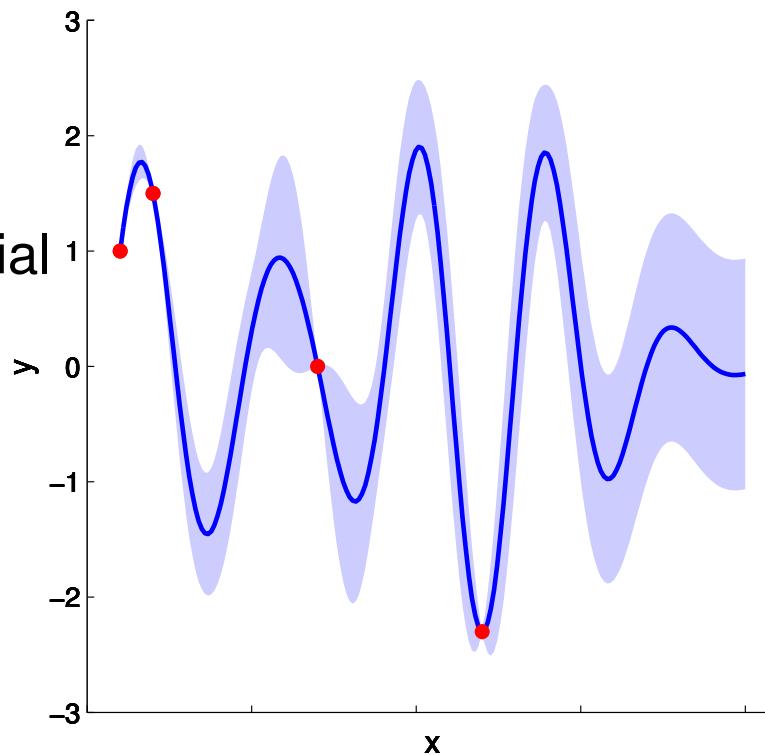
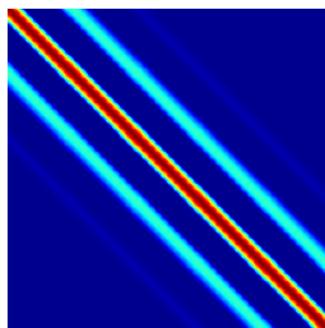
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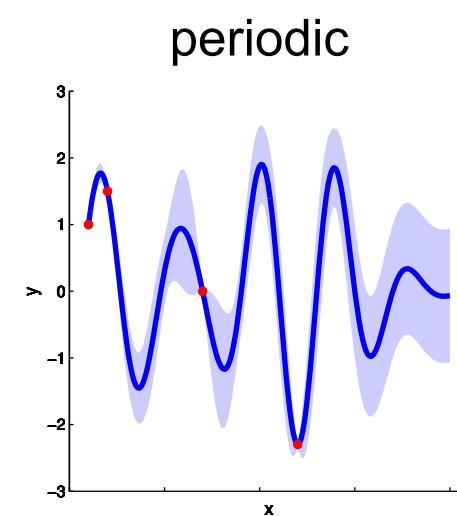
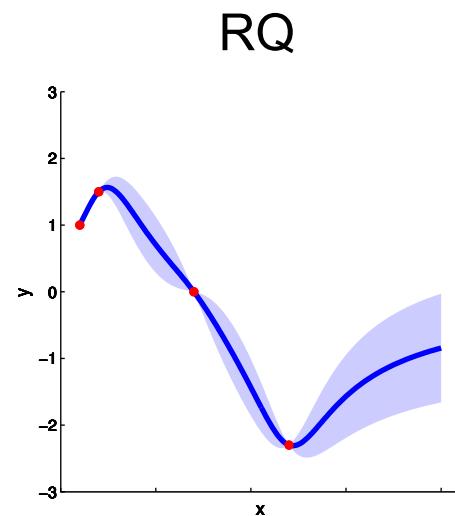
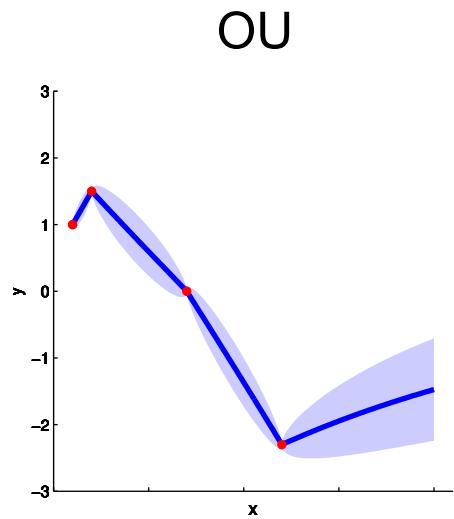
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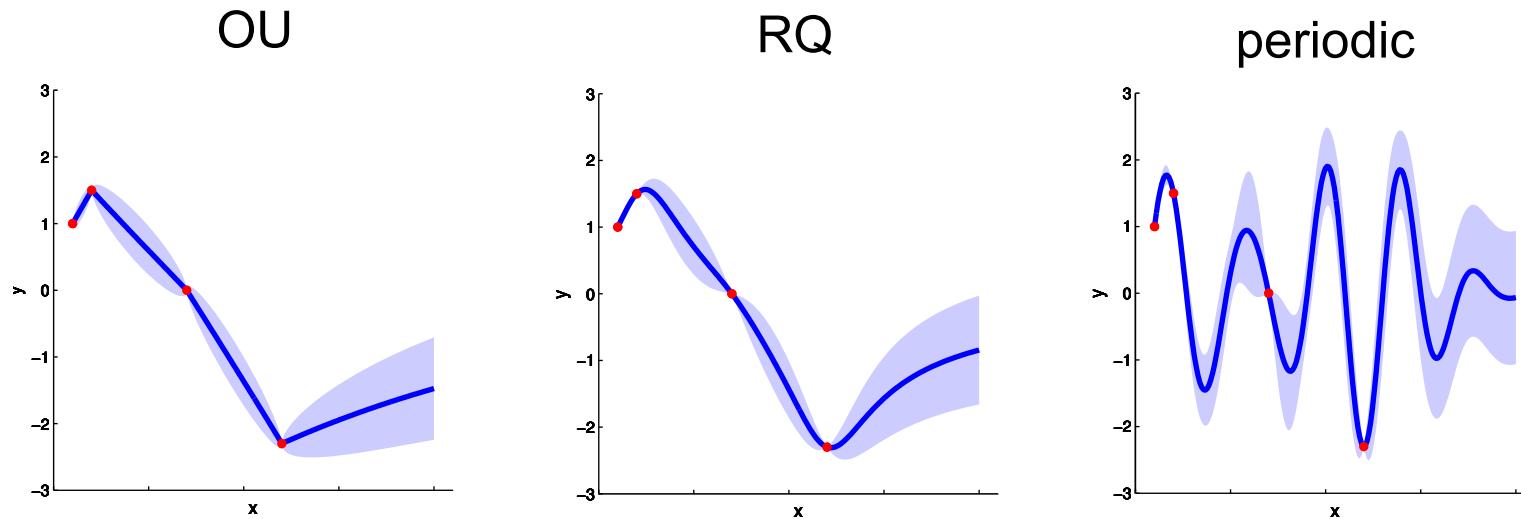
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The covariance function has a large effect



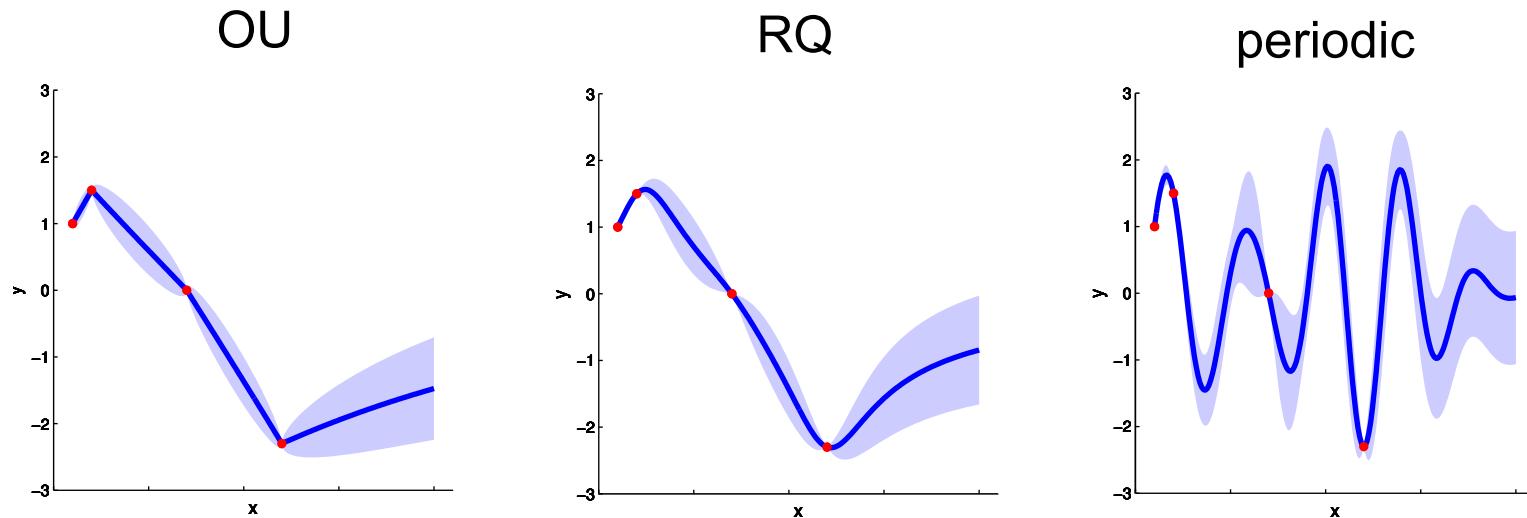
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Bayesian model comparison:

$$p(M|\mathbf{y}_{1:N}) = \frac{p(\mathbf{y}_{1:N}|M)p(M)}{\sum_{M'} p(\mathbf{y}_{1:N}|M')p(M')}$$

The covariance function has a large effect

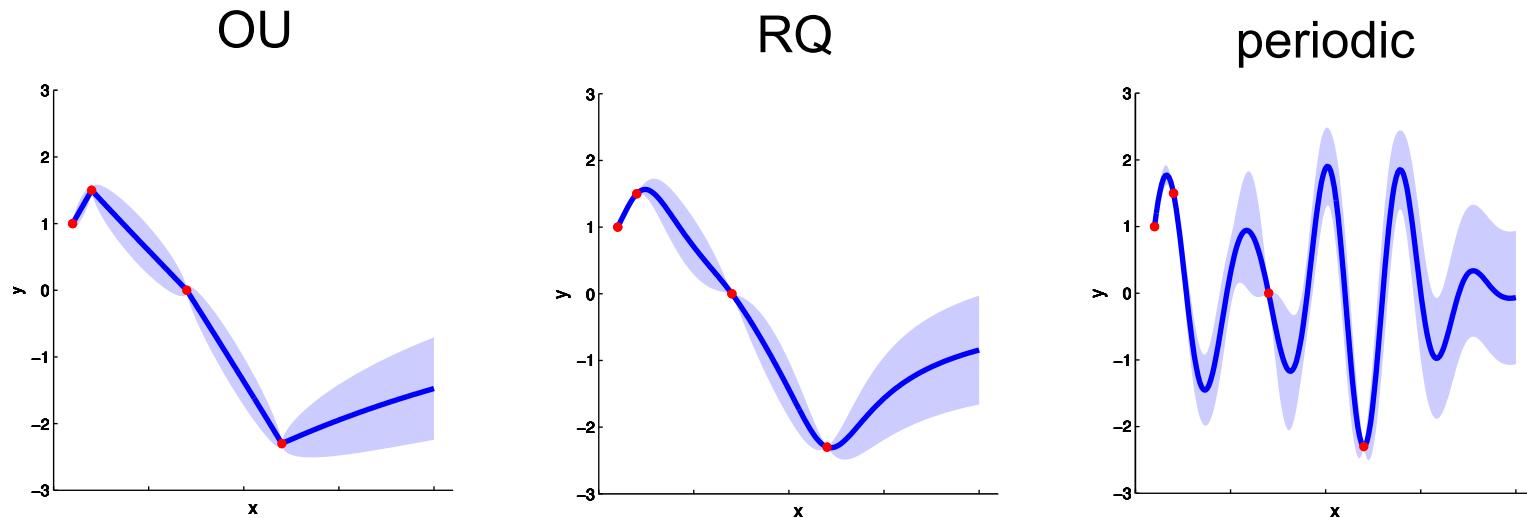


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prior over models

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marginal likelihood $p(\mathbf{y}_{1:N}|M) = \int d\theta p(\mathbf{y}_{1:N}|\theta, M)p(\theta|M)$

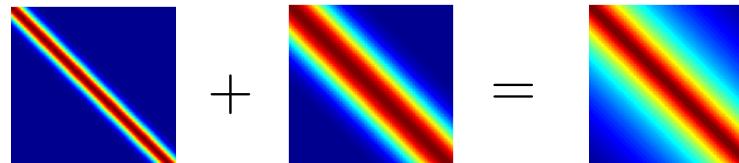
prior over models

Making new covariance functions from old

(positive) linear combinations
of covariance functions

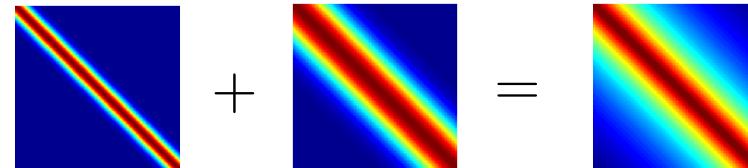
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$$\begin{array}{ccc} \text{e.g.} & \begin{array}{c} \text{scale mixture of SE} \\ + \end{array} & = \end{array} \quad \begin{array}{c} \text{rational} \\ \text{quadratic} \end{array}$$


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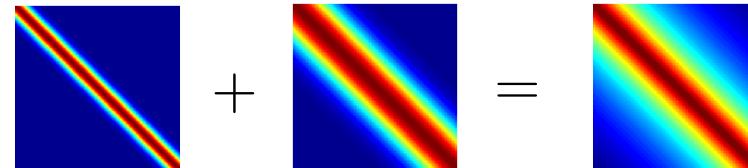


e.g. scale mixture of SE = rational quadratic

multiplication of covariance
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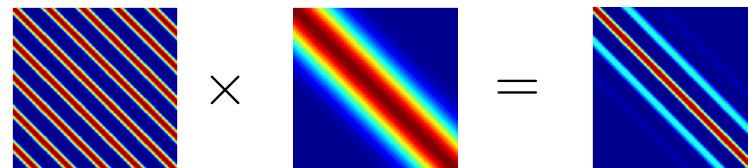
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e.g. periodic SE $\cos(\omega \Delta x) \exp(-\frac{1}{2l^2} \Delta x^2)$

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e.g. periodic \times SE = $\cos(\omega \Delta x) \exp(-\frac{1}{2l^2} \Delta x^2)$

derivative of GP = GP

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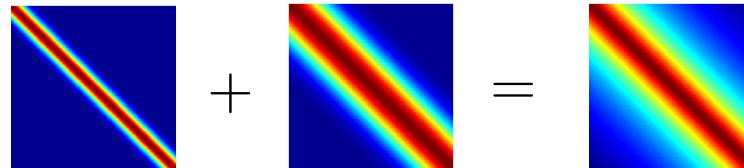
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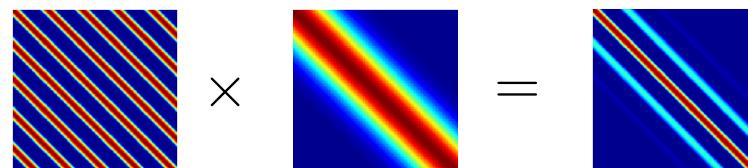
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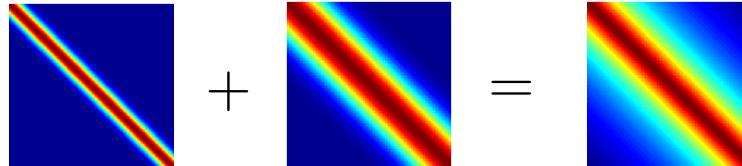
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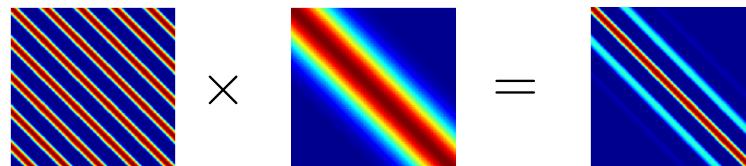
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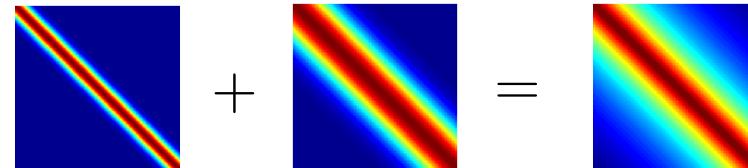
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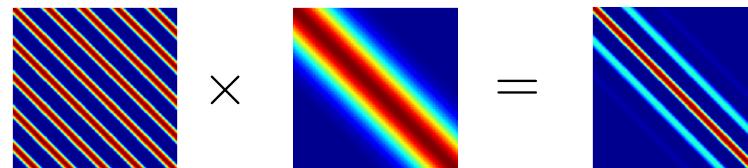
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derivative of GP = GP



filtering a GP = GP

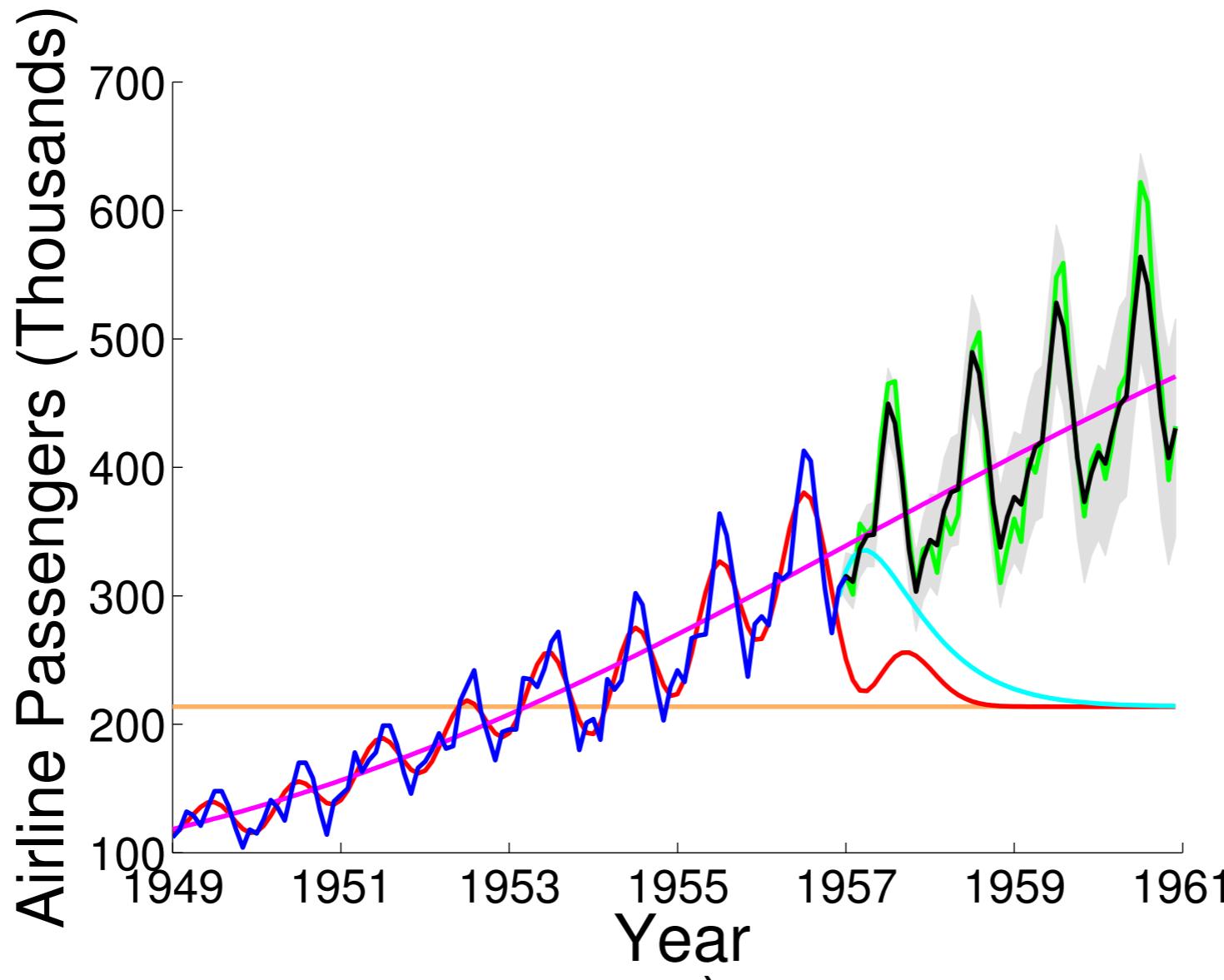
$$V(x) \otimes y(x)$$

$$K'(x, x') = V(x) \otimes K(x, x') \otimes V(x')$$

integral of GP = GP

Meta-kernel, learn which is right directly

$$k(\tau) = \sum_{q=1}^Q w_q \prod_{p=1}^P \exp\{-2\pi^2 \tau_p^2 v_q^{(p)}\} \cos(2\pi \tau_p \mu_q^{(p)}).$$



How do we choose the hyper-parameters?

idea: use probability distributions to represent plausibility
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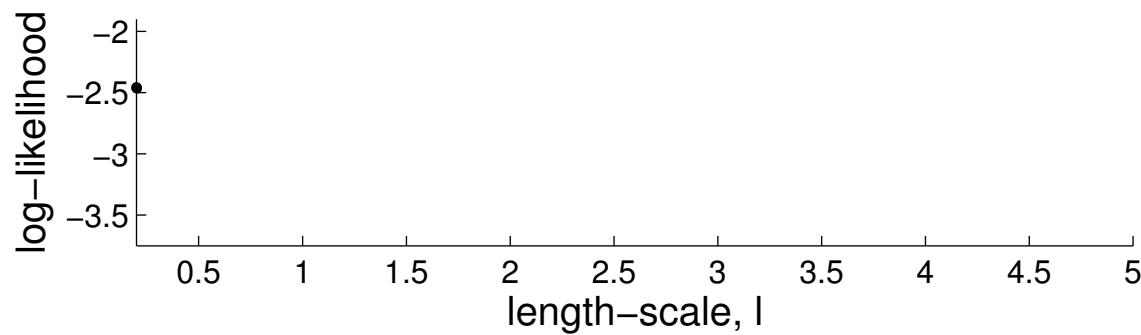
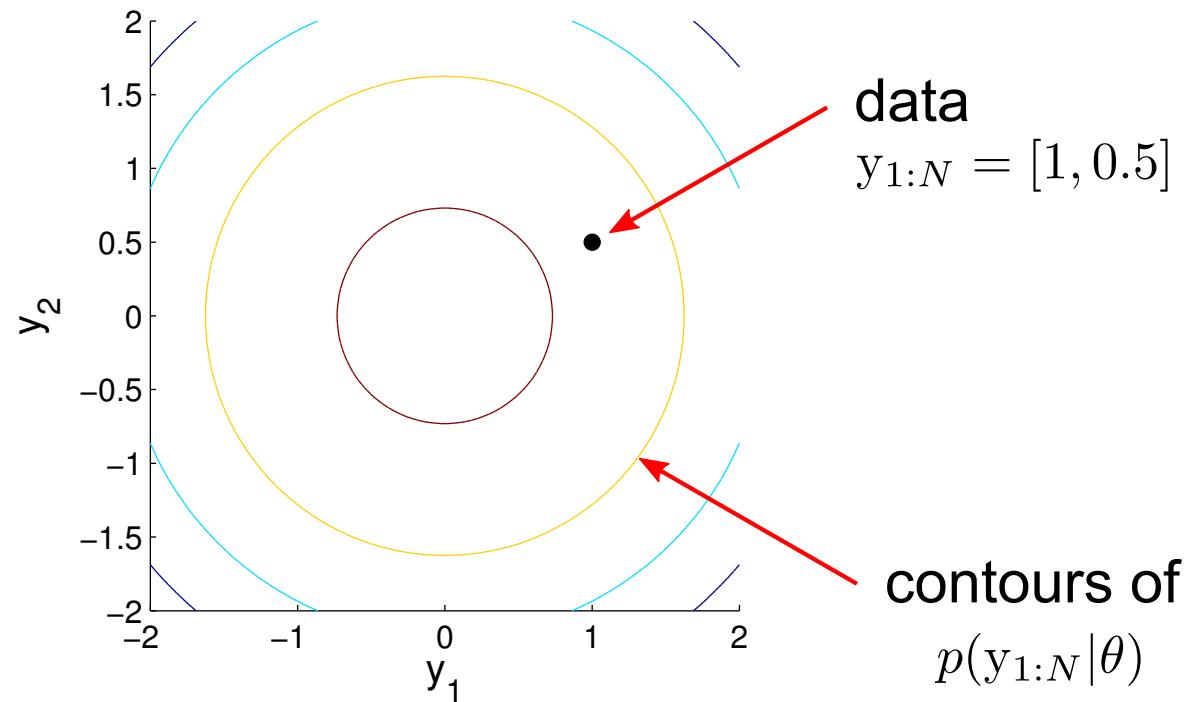
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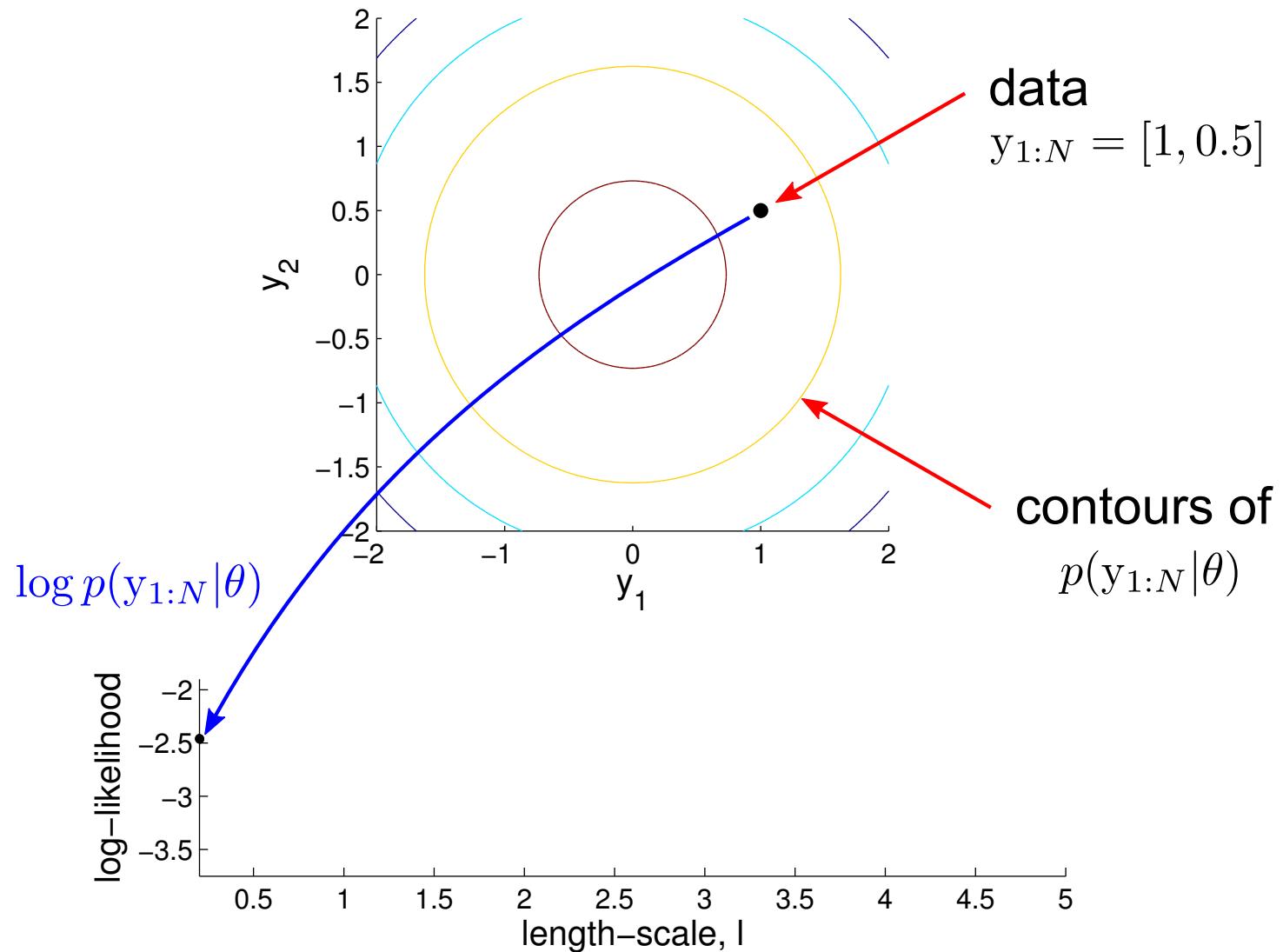
$p(\mathbf{y}_{1:N} | \theta)$ = likelihood of the parameters
= how well did θ predict the data we observed

$$p(\mathbf{y}_{1:N} | \theta) = \frac{1}{\det(2\pi\Sigma(\theta))^{-1/2}} \exp\left(-\frac{1}{2}\mathbf{y}_{1:N}^\top \Sigma^{-1}(\theta)\mathbf{y}_{1:N}\right)$$

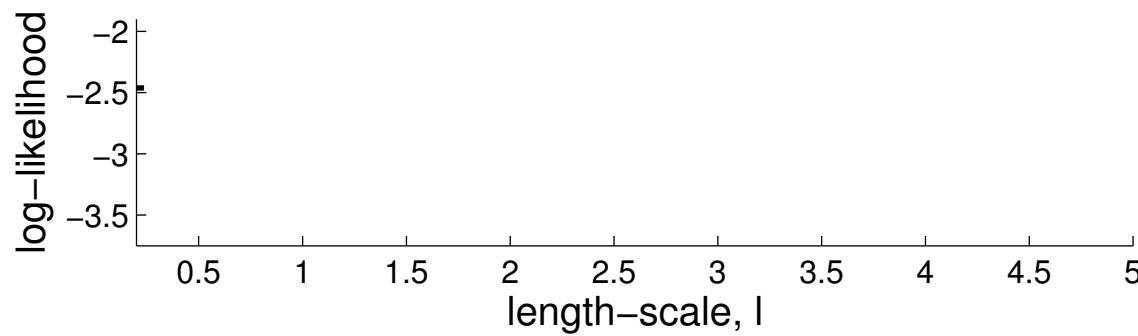
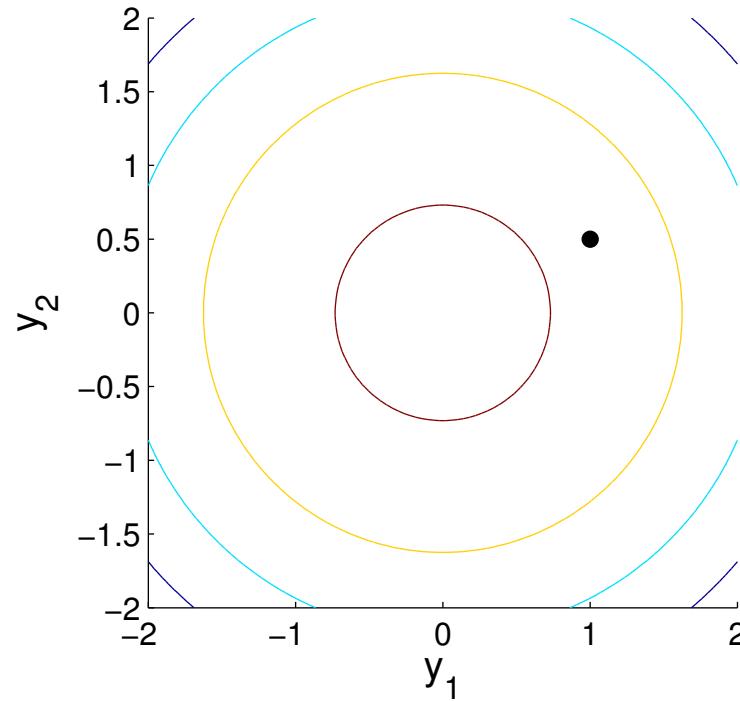
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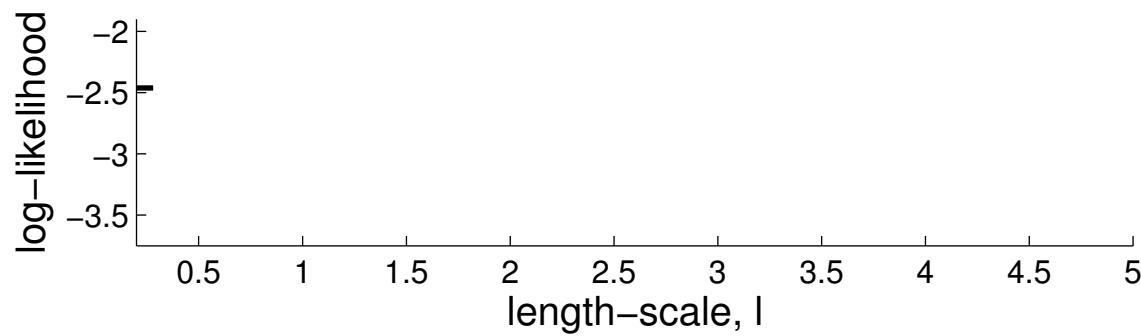
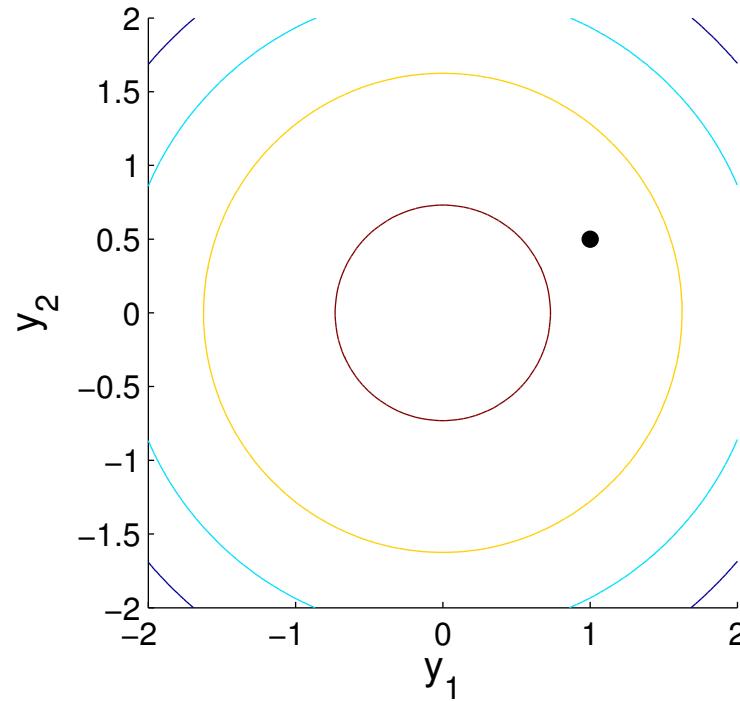
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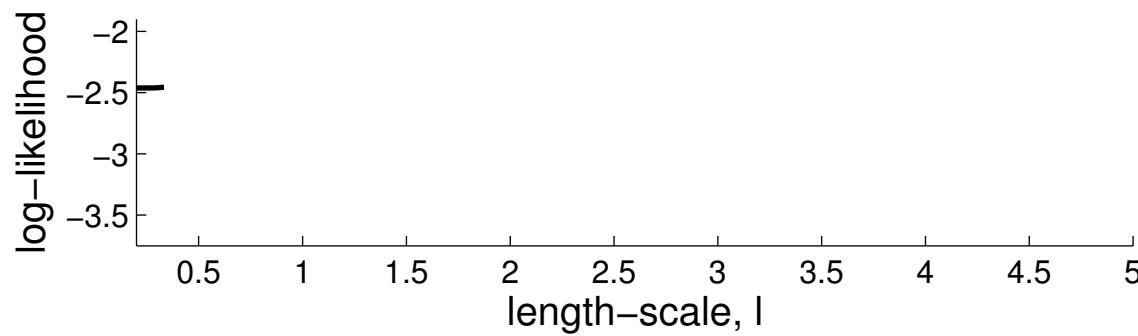
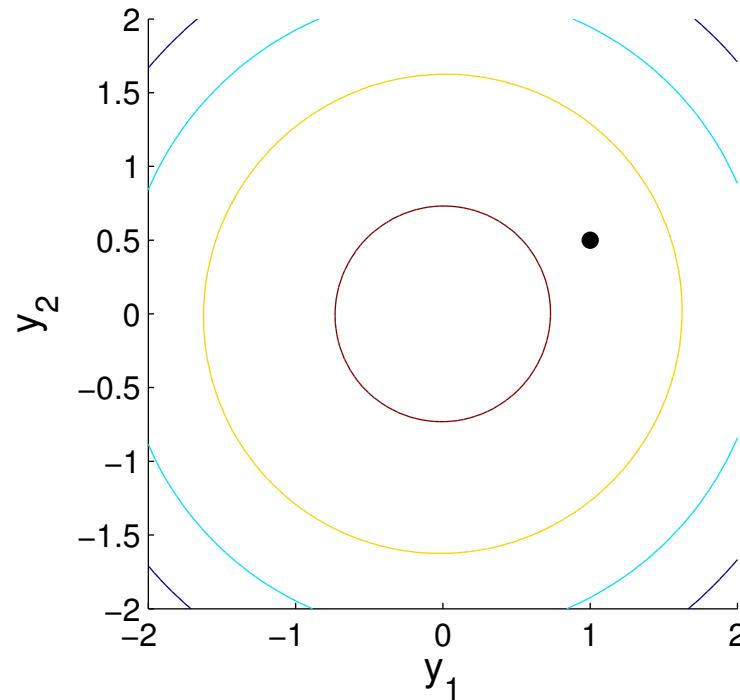
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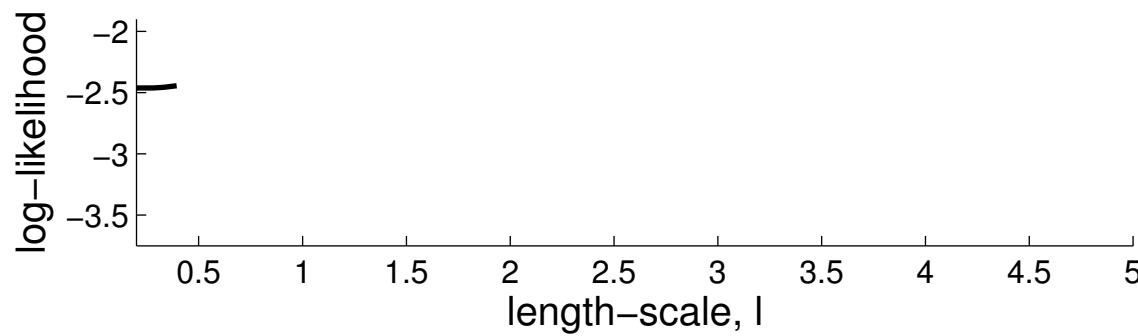
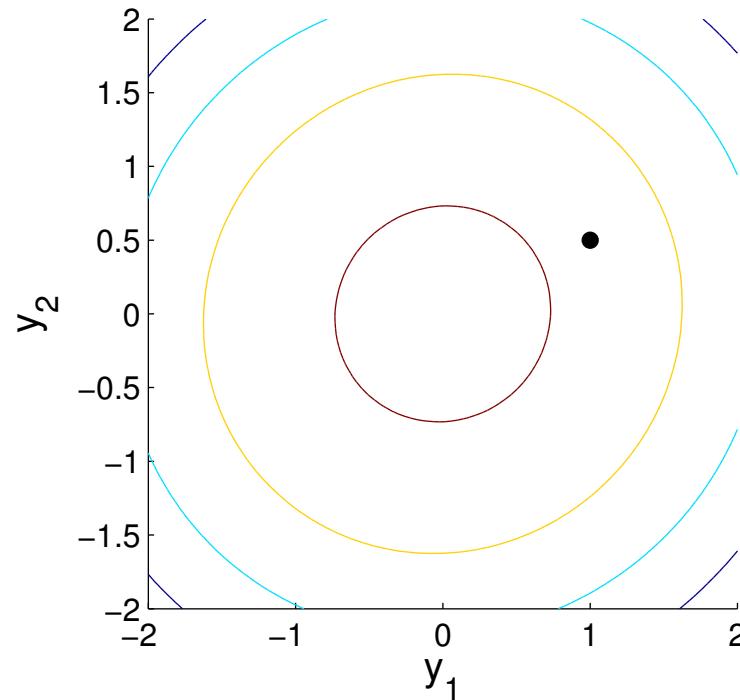
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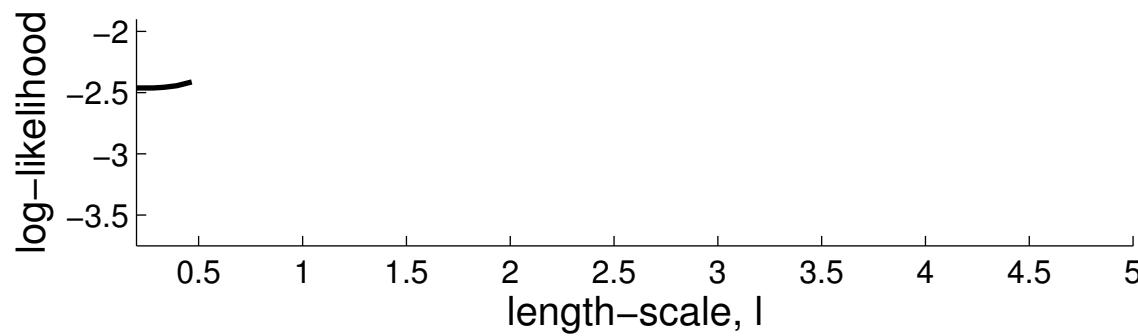
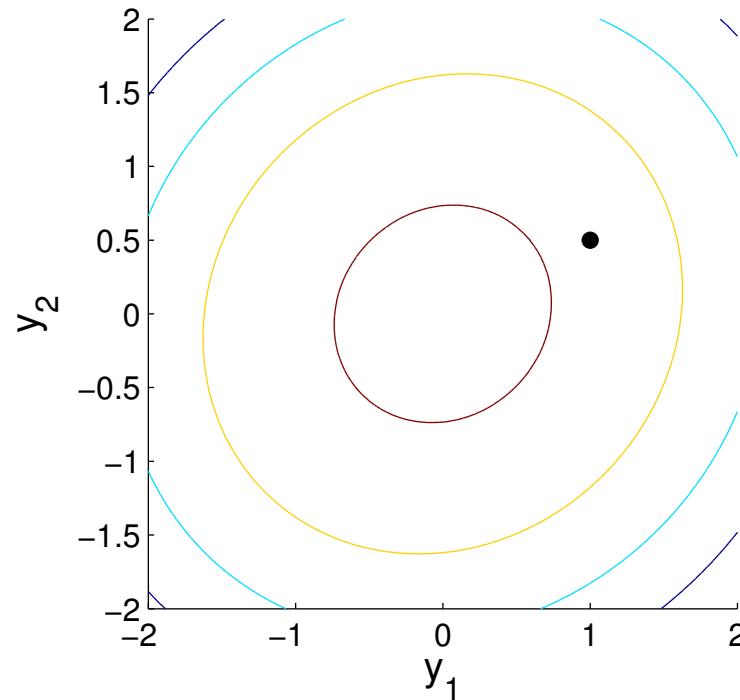
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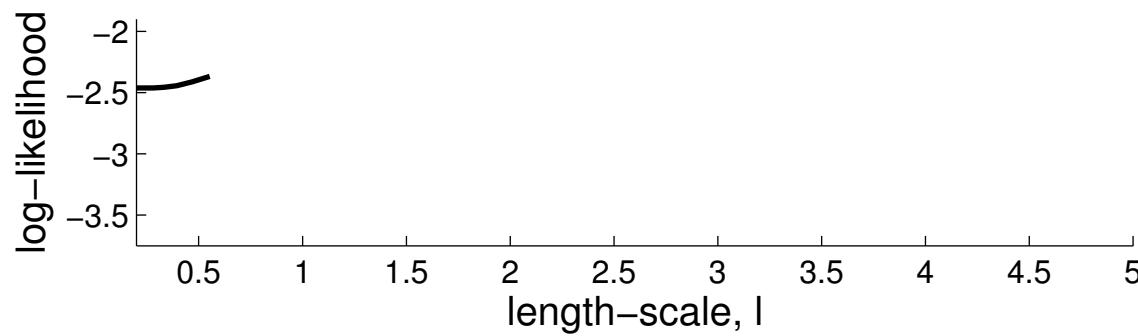
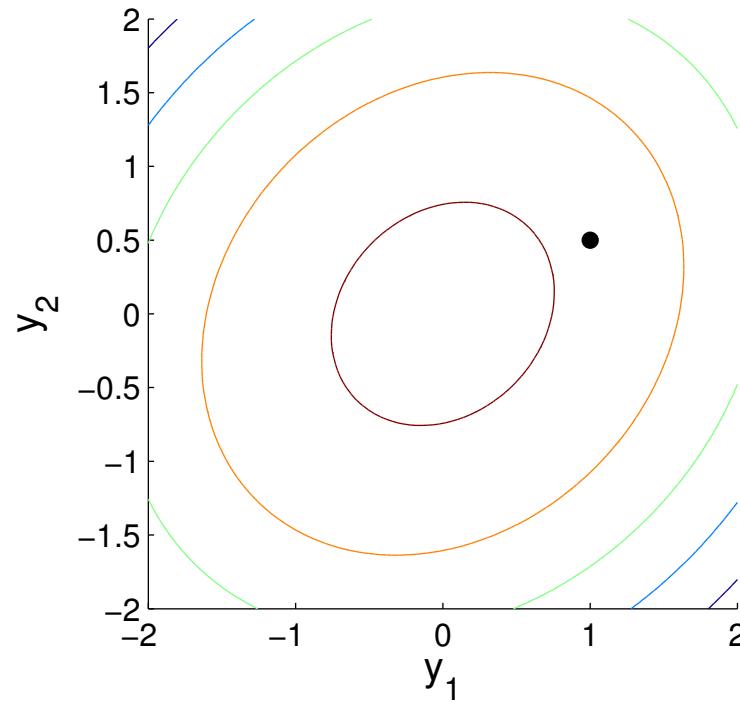
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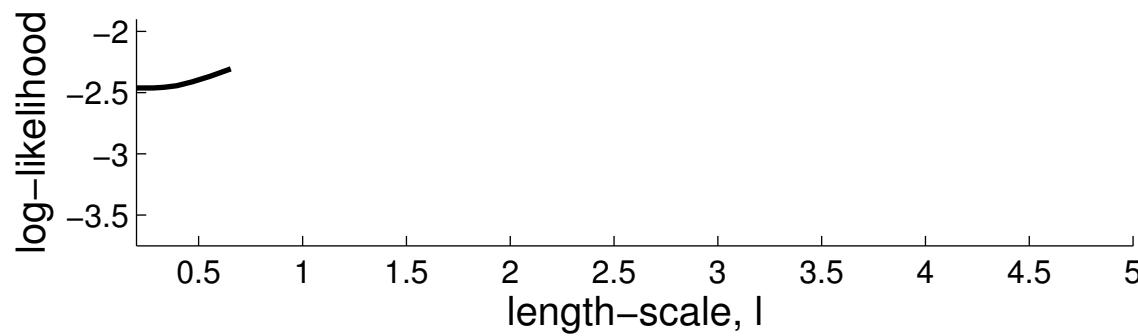
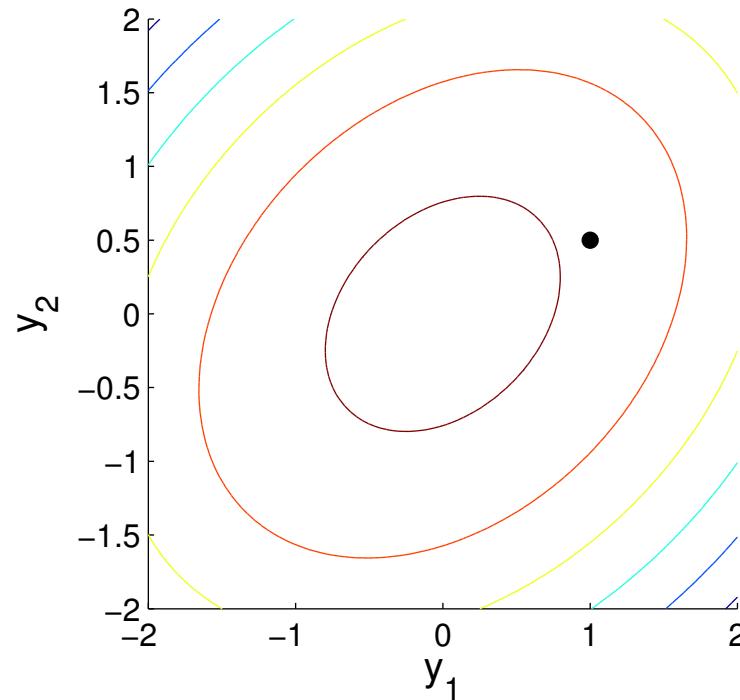
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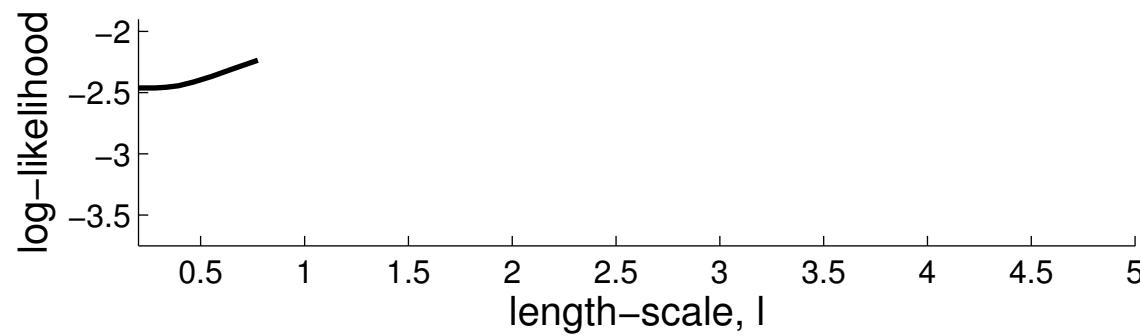
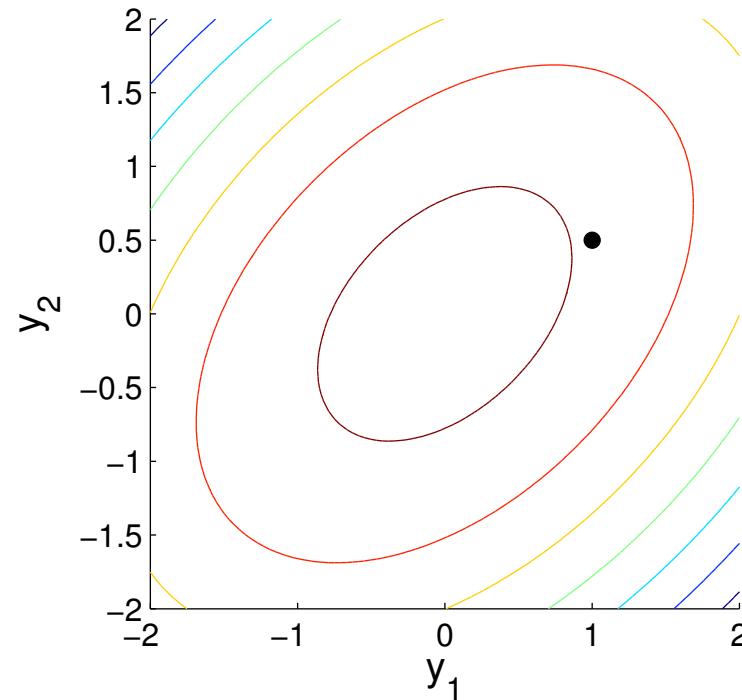
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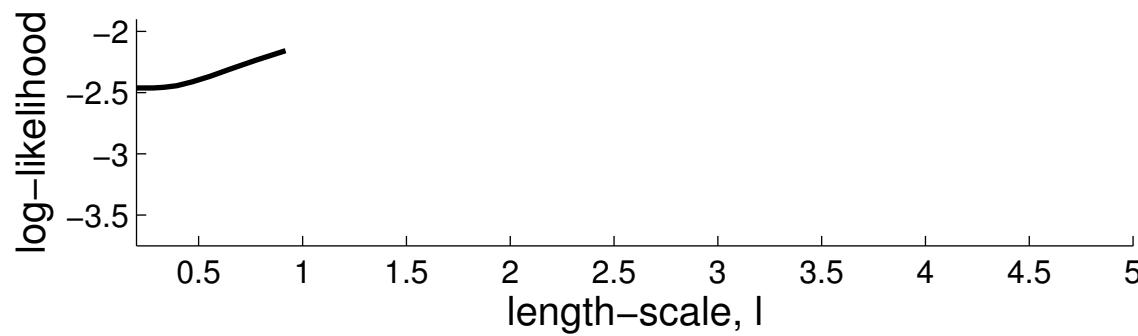
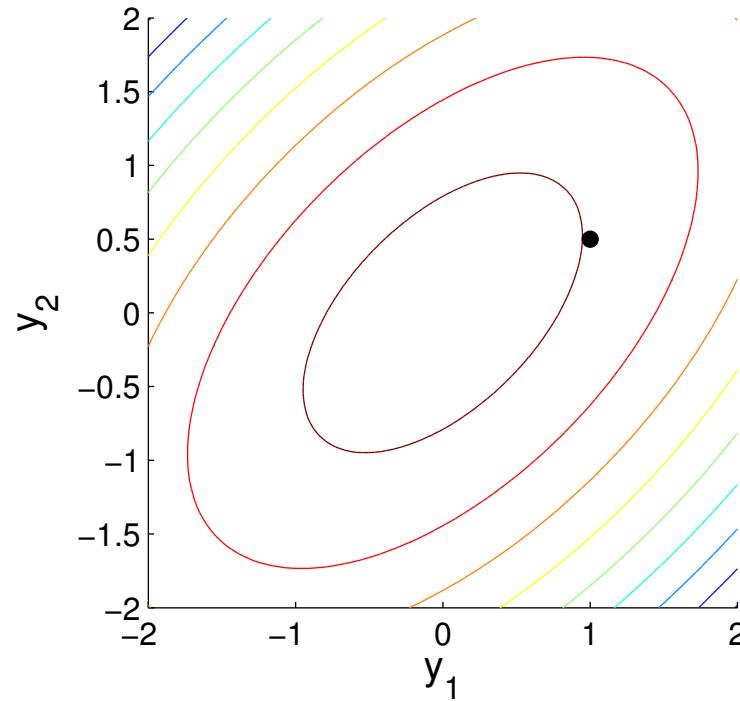
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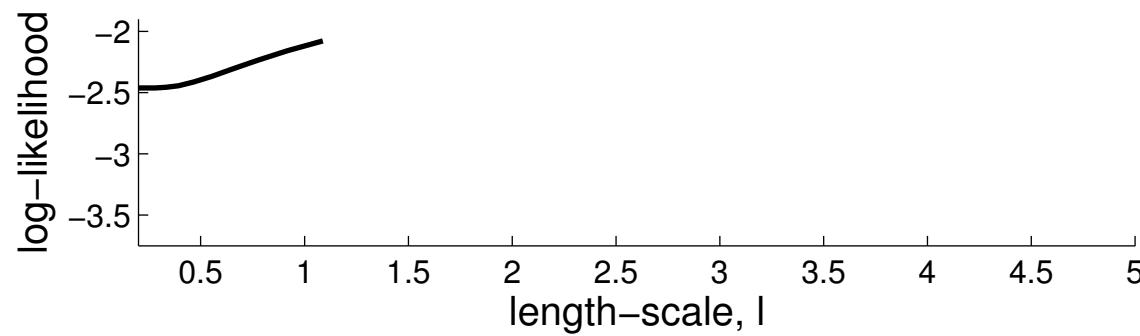
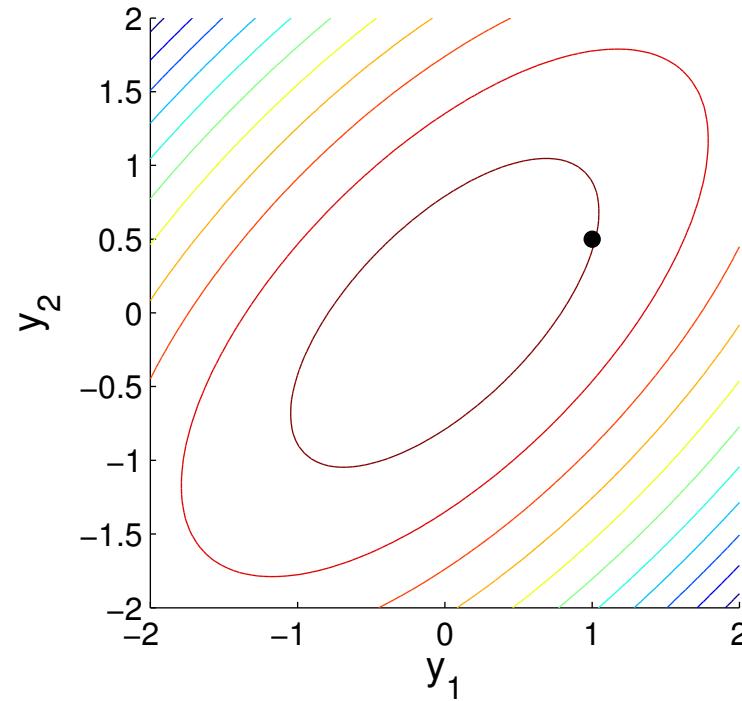
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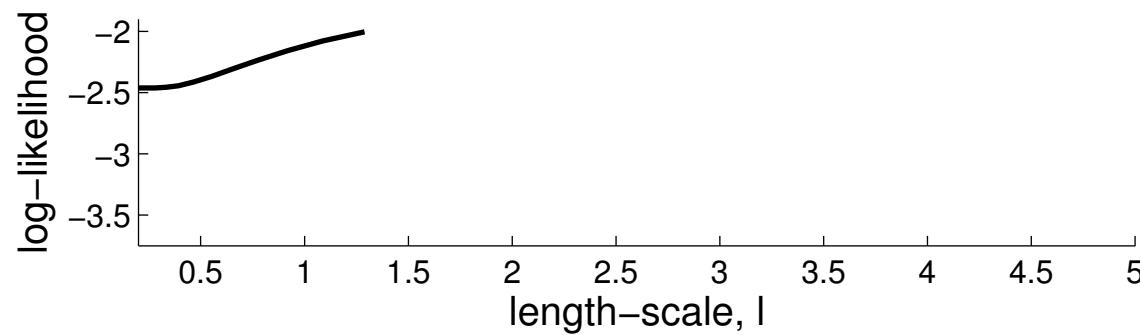
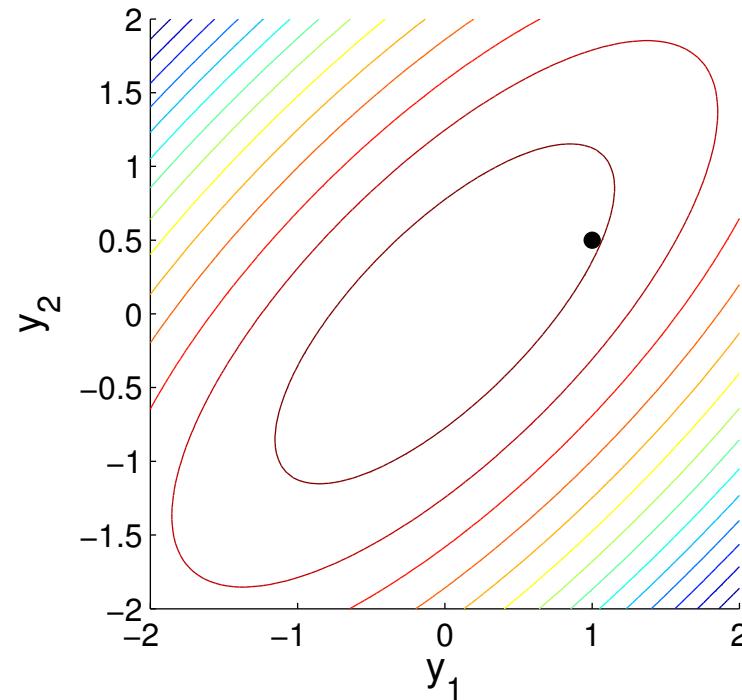
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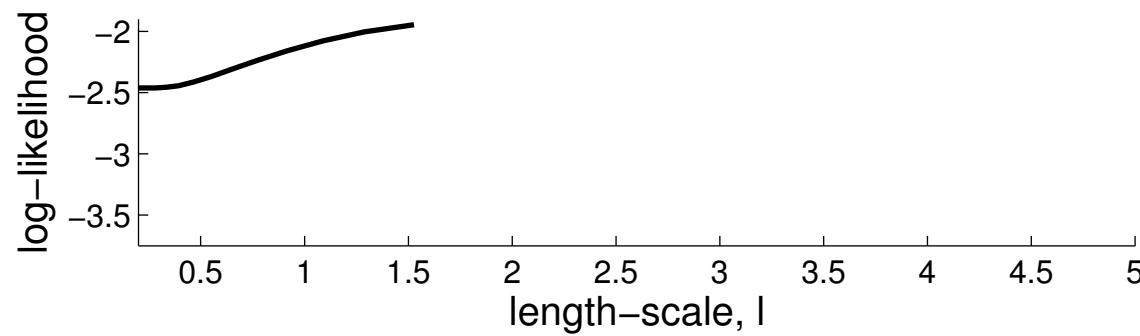
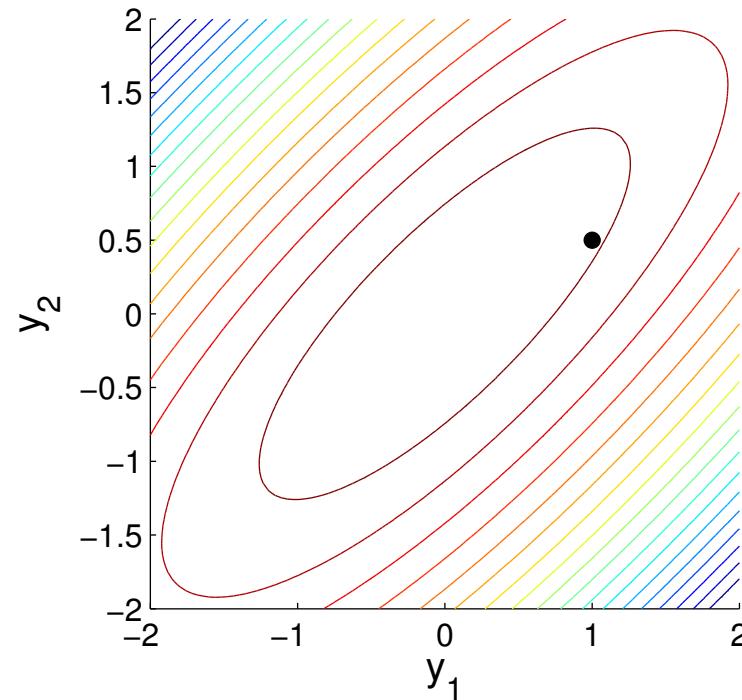
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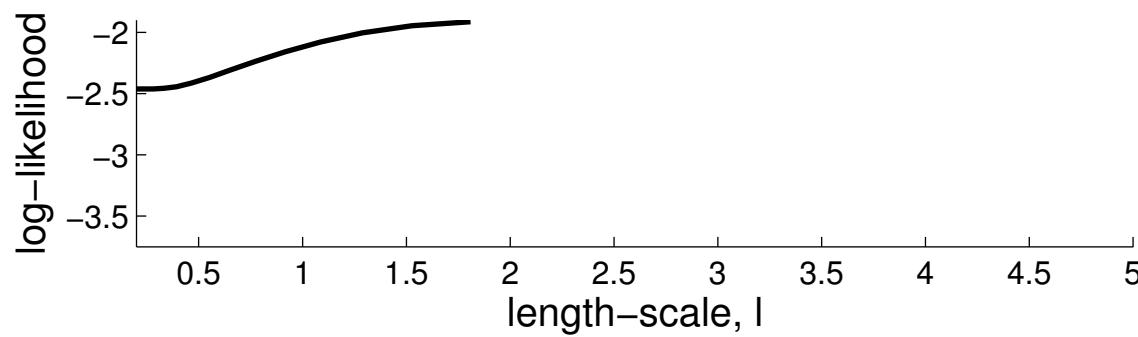
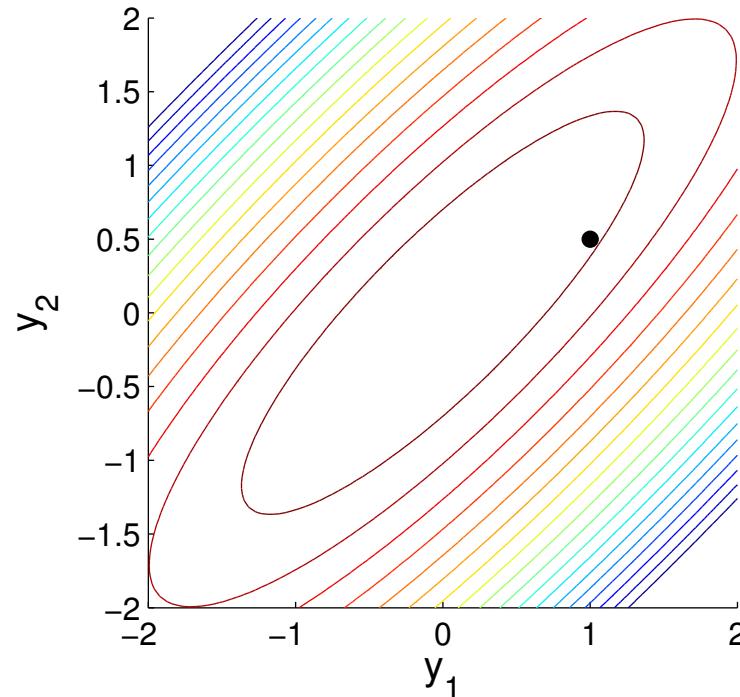
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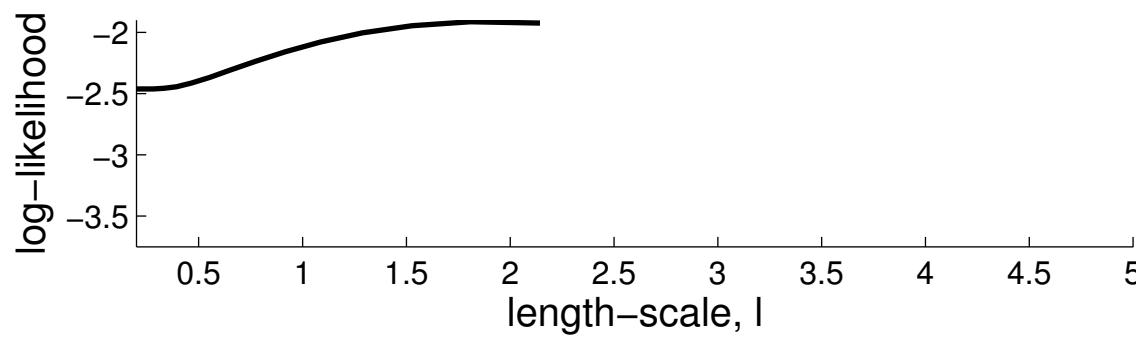
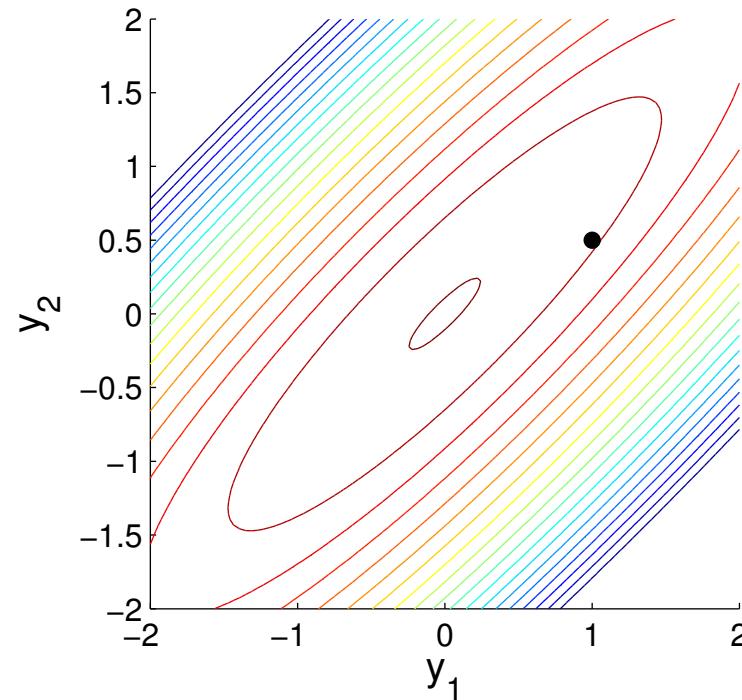
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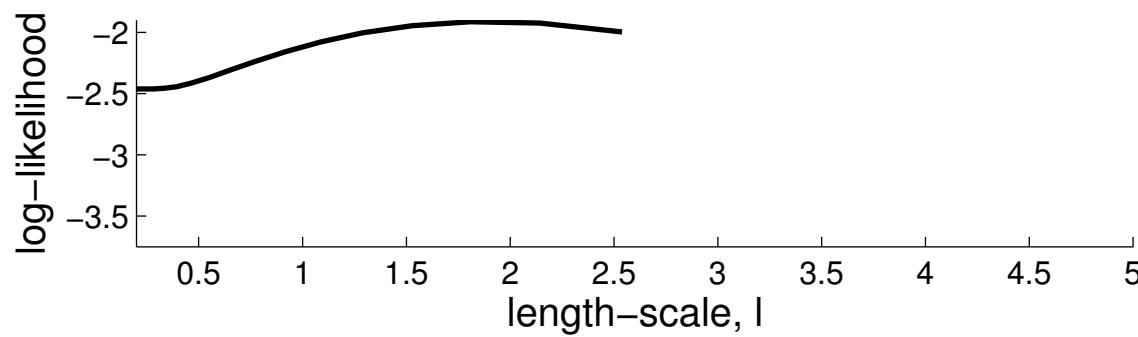
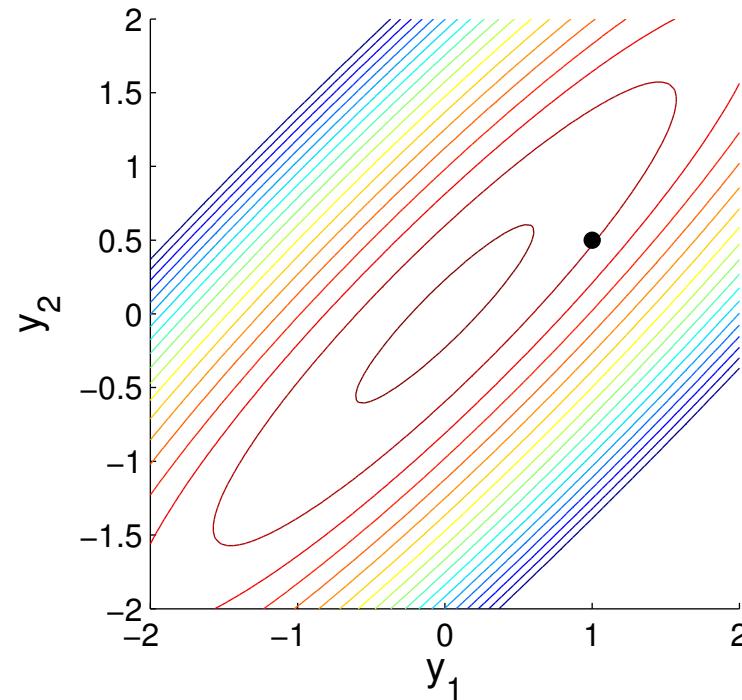
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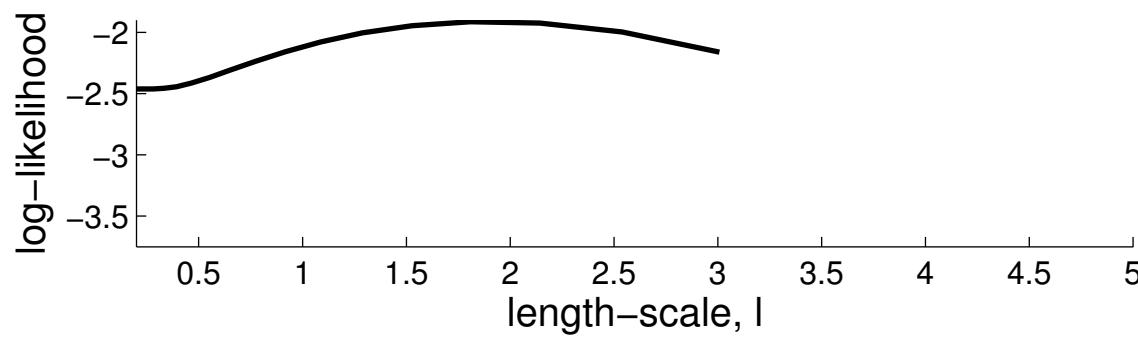
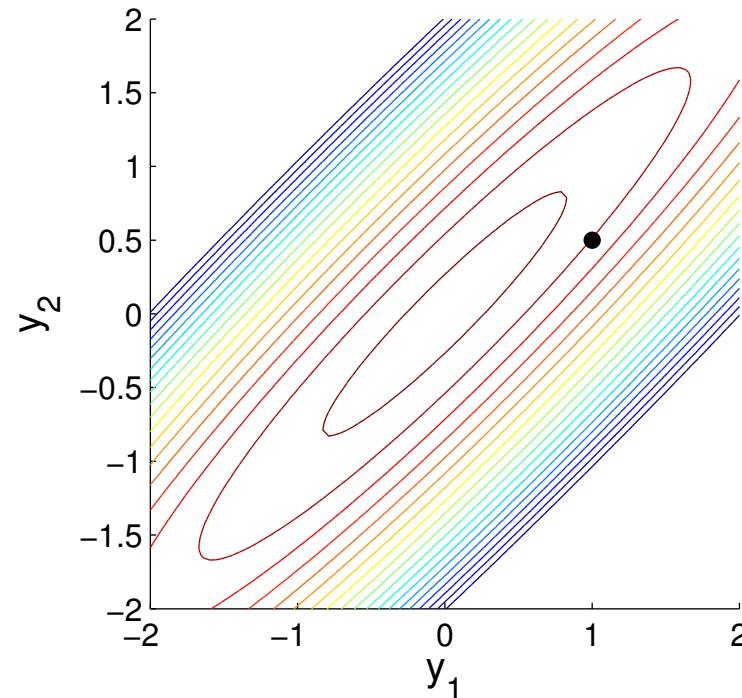
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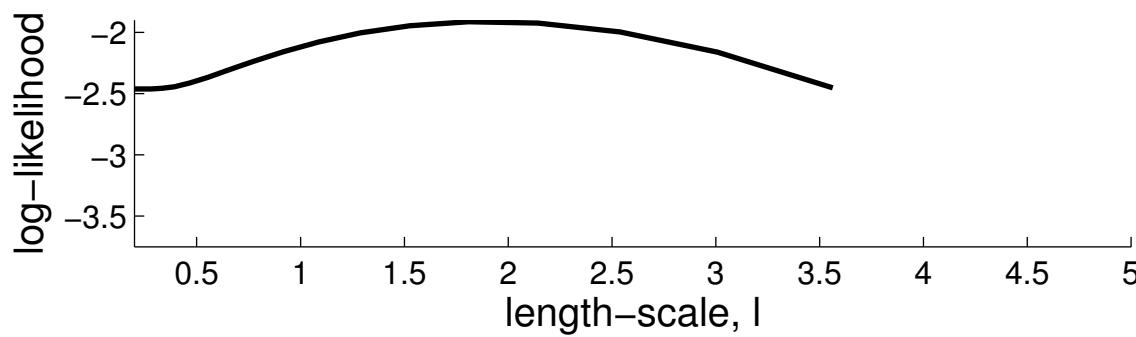
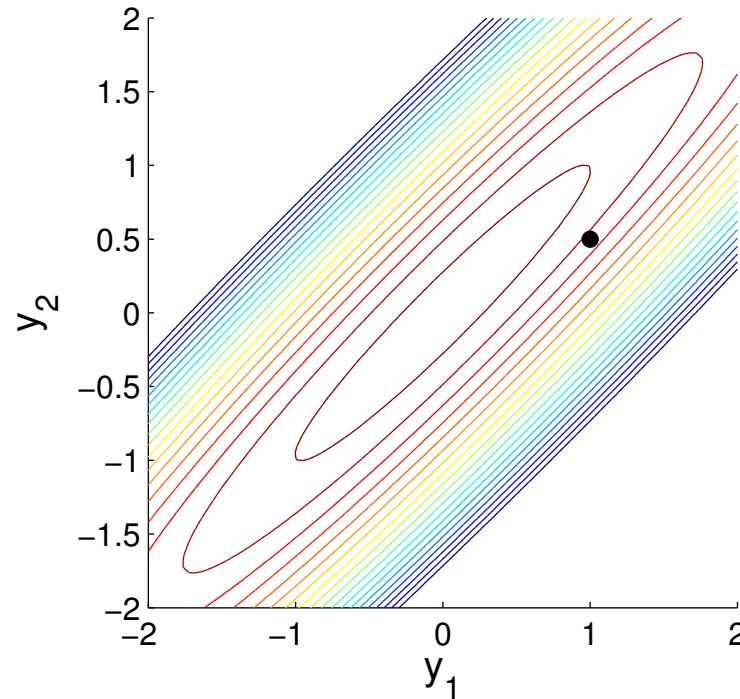
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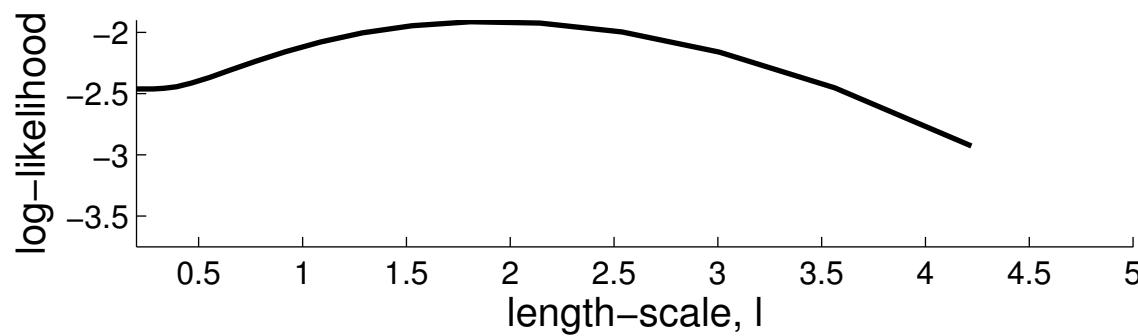
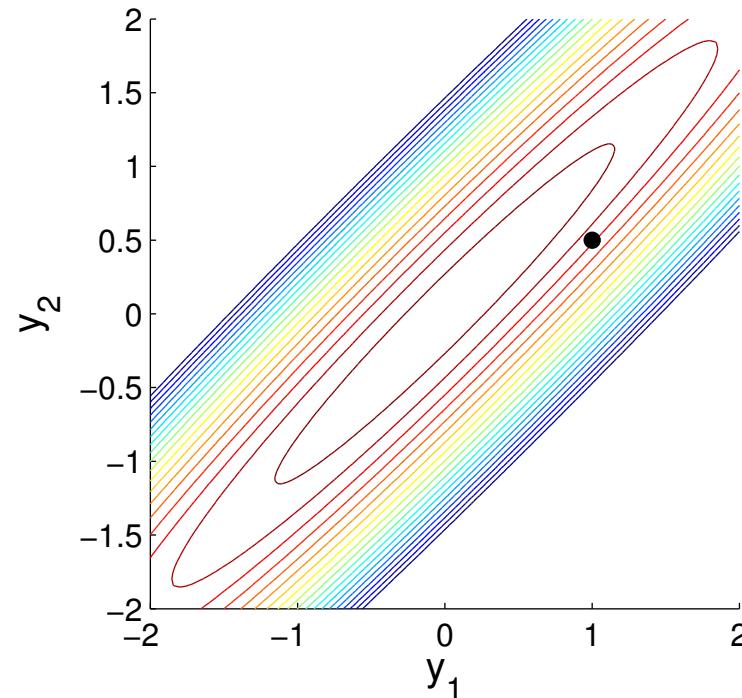
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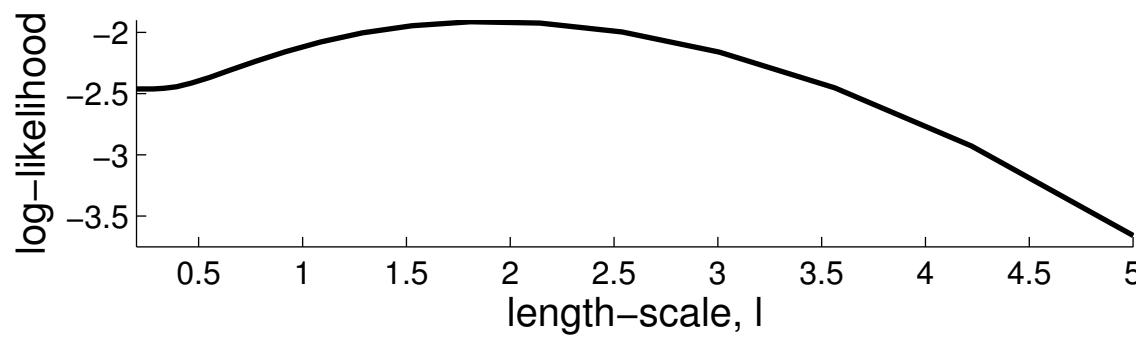
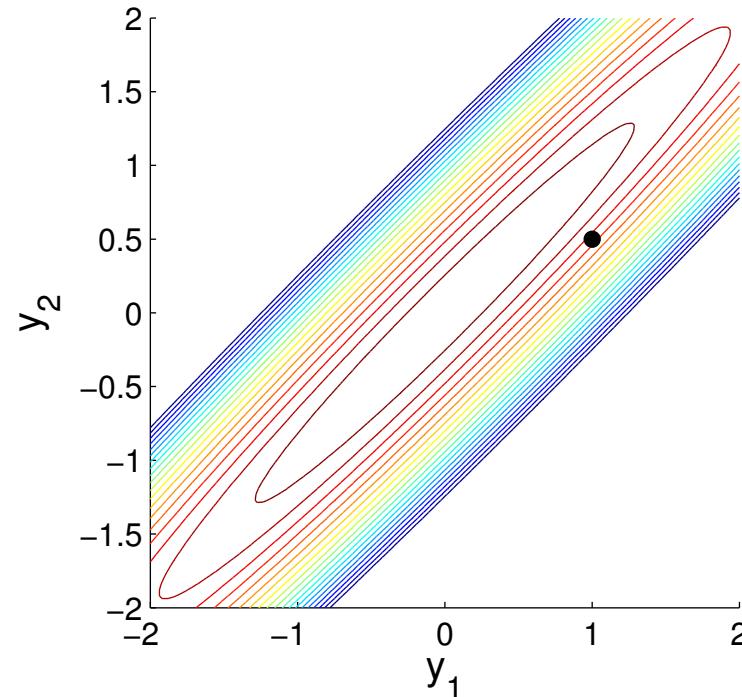
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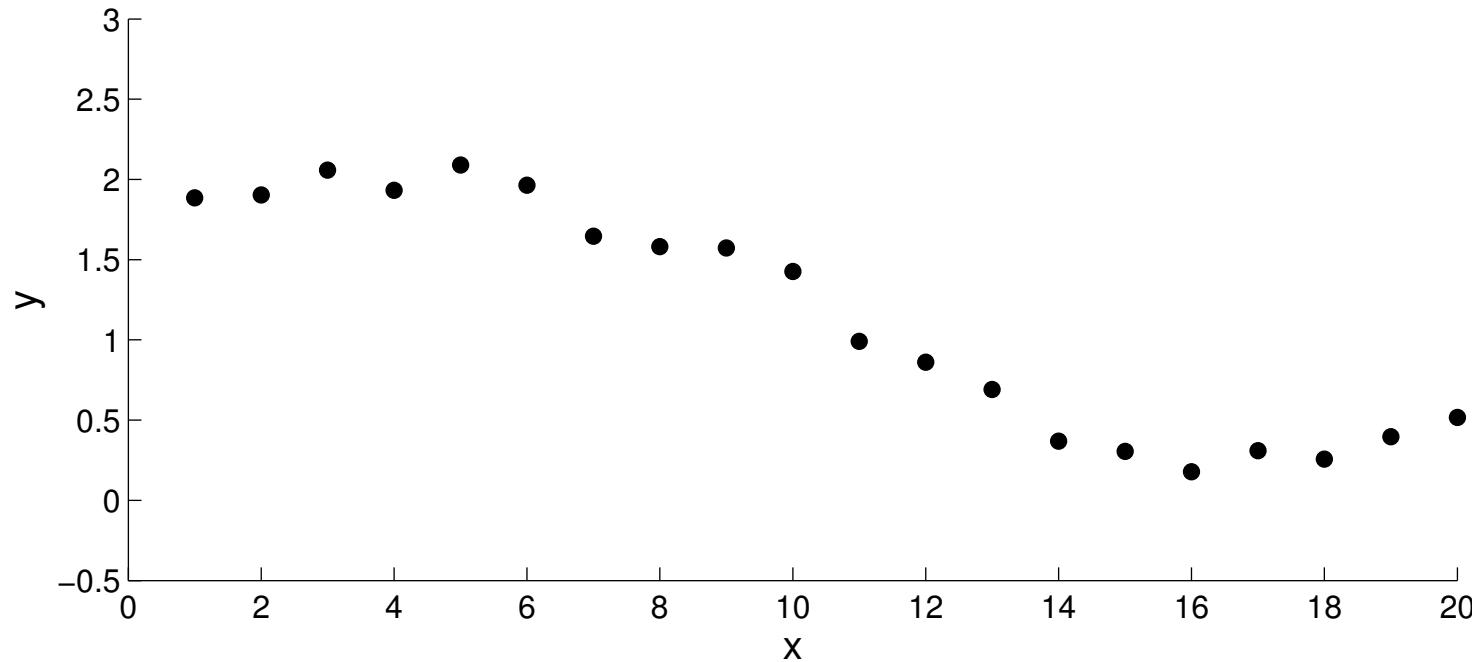
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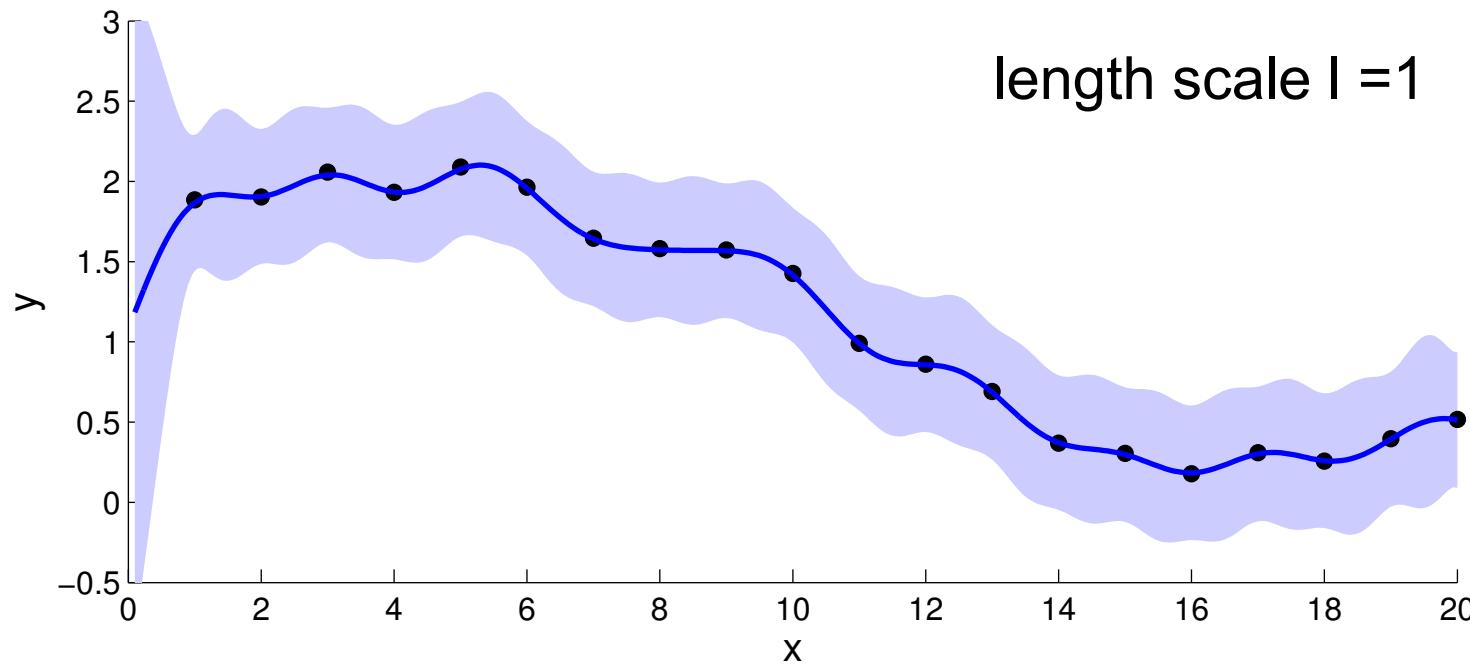
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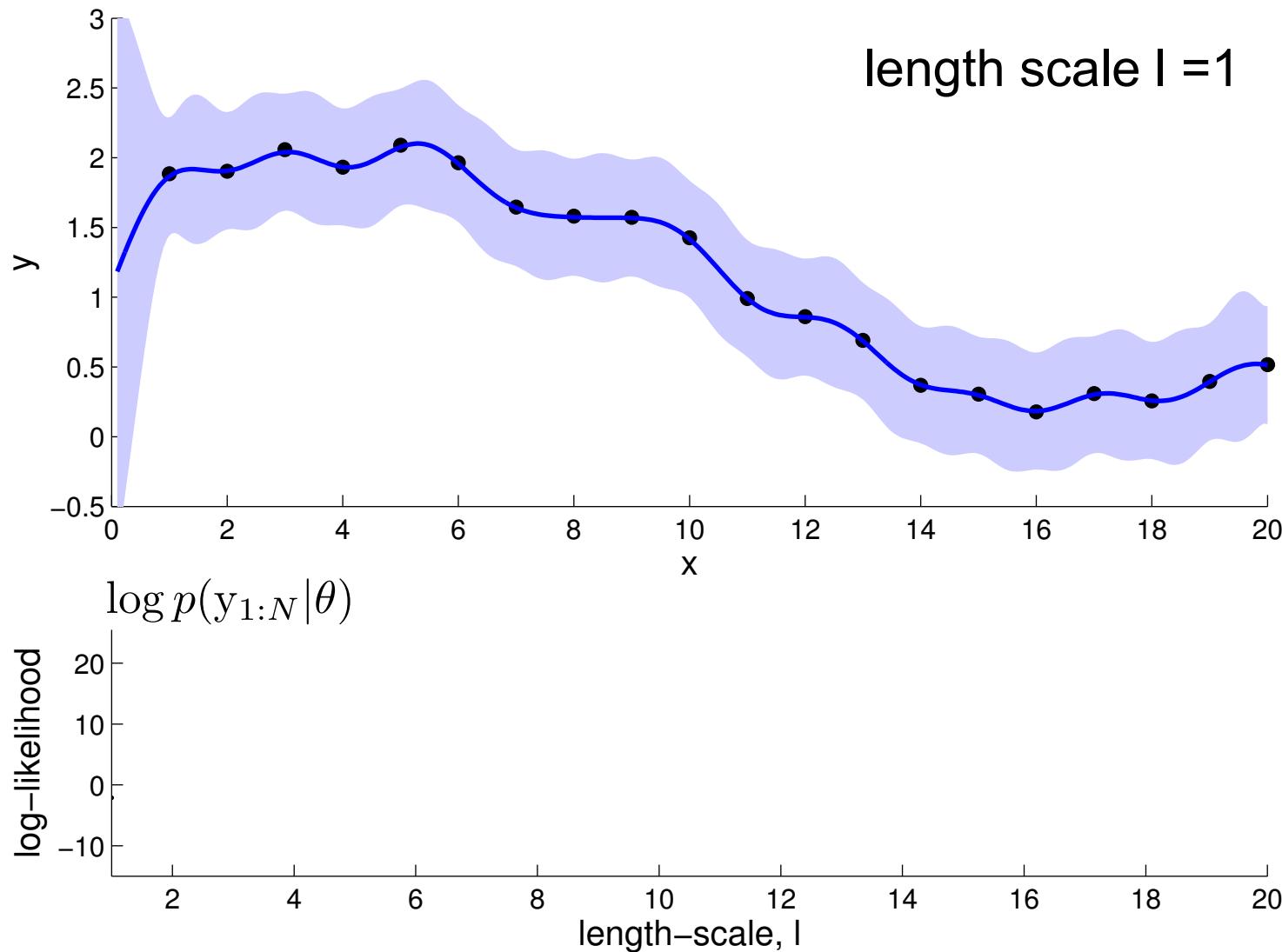
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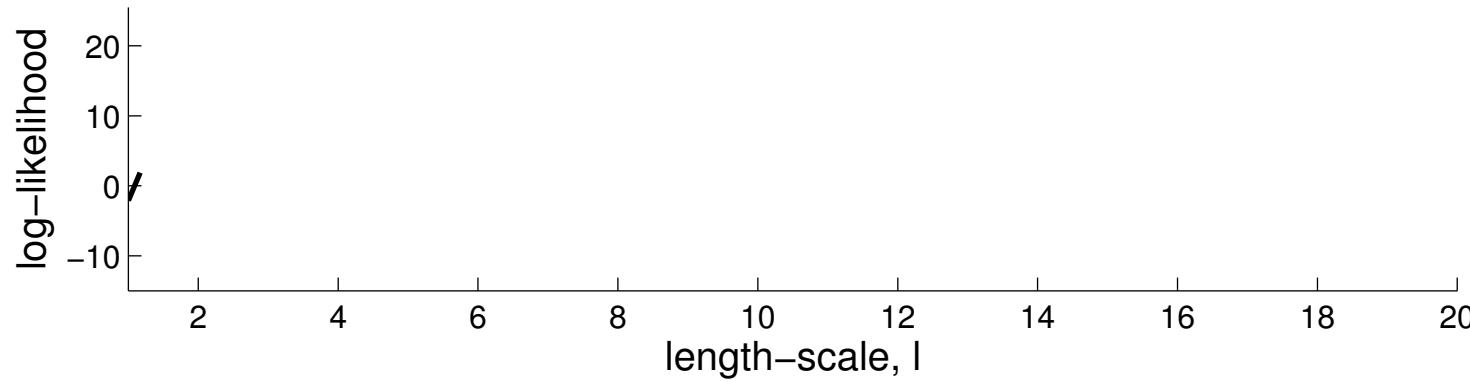
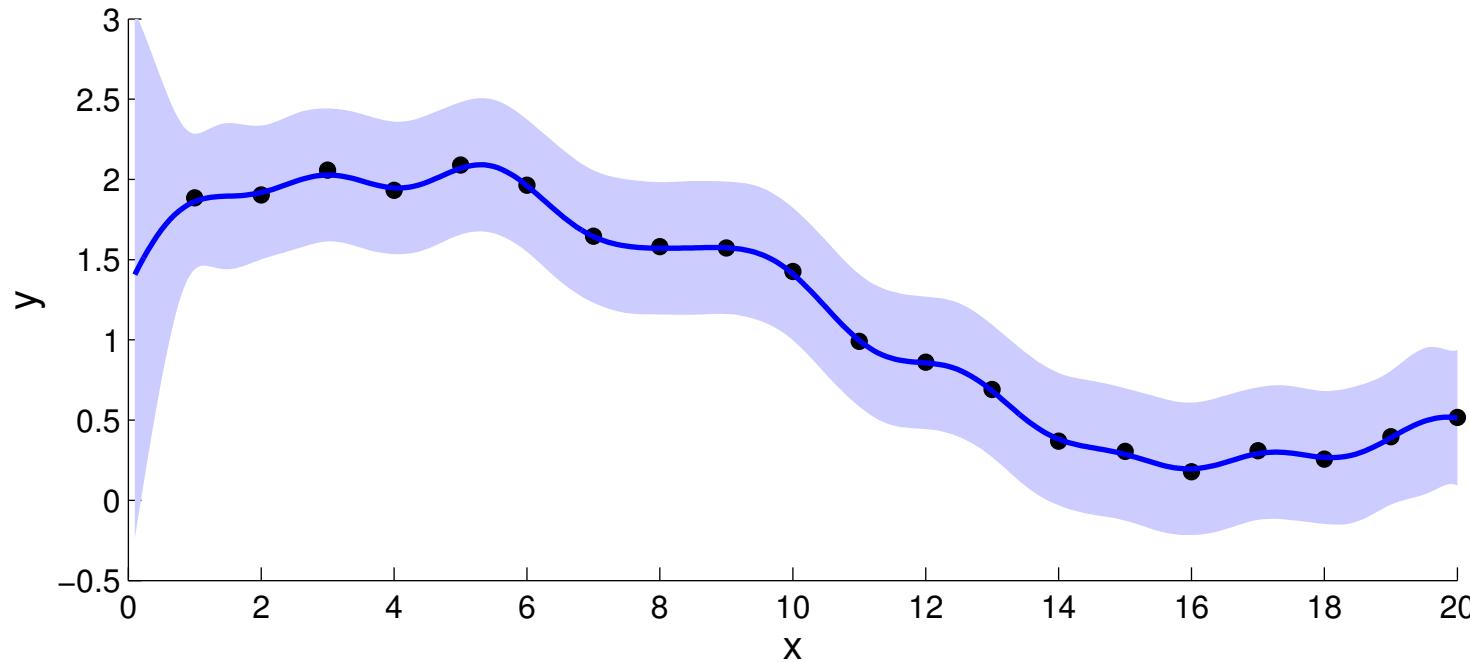
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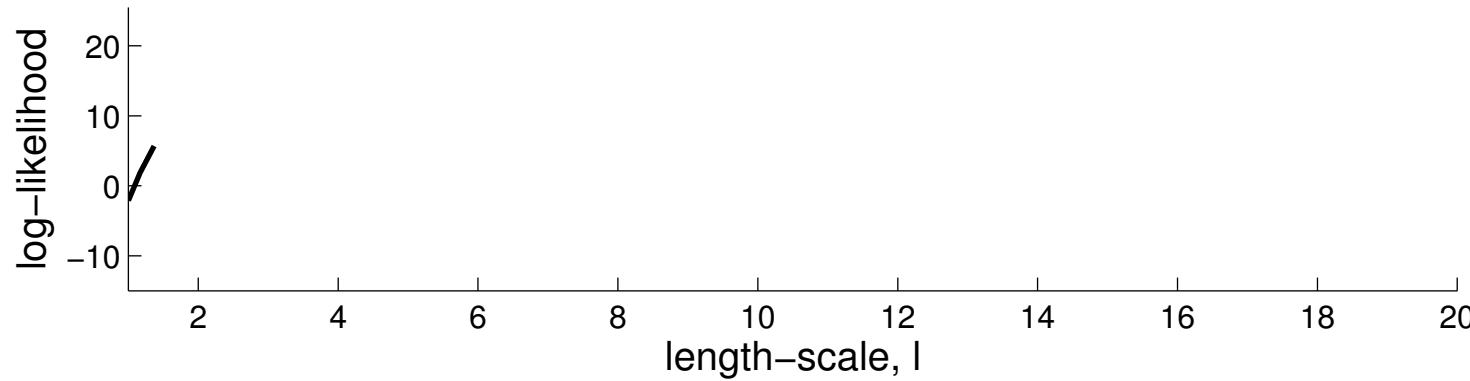
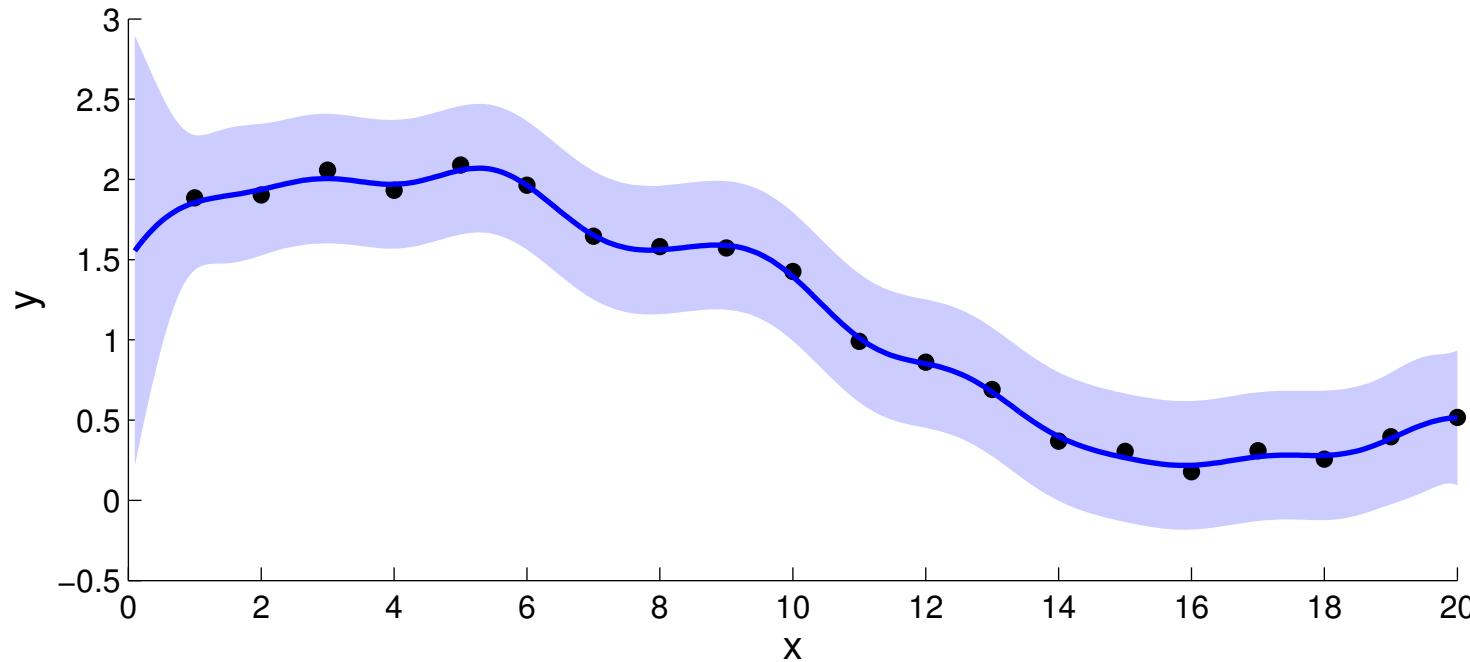
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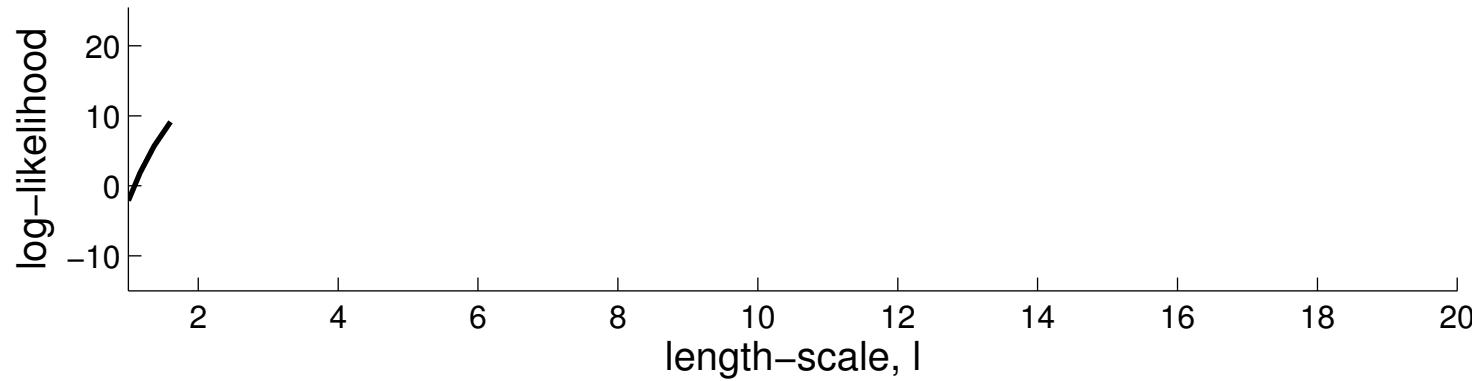
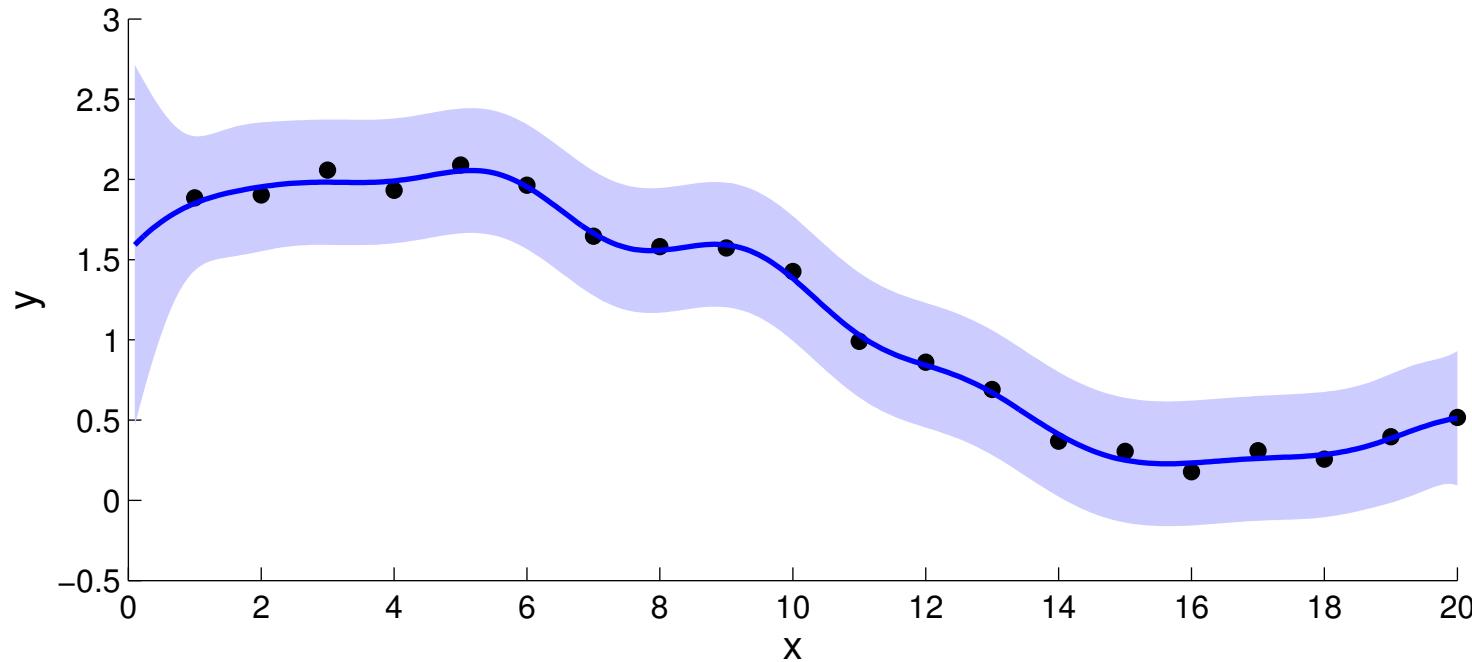
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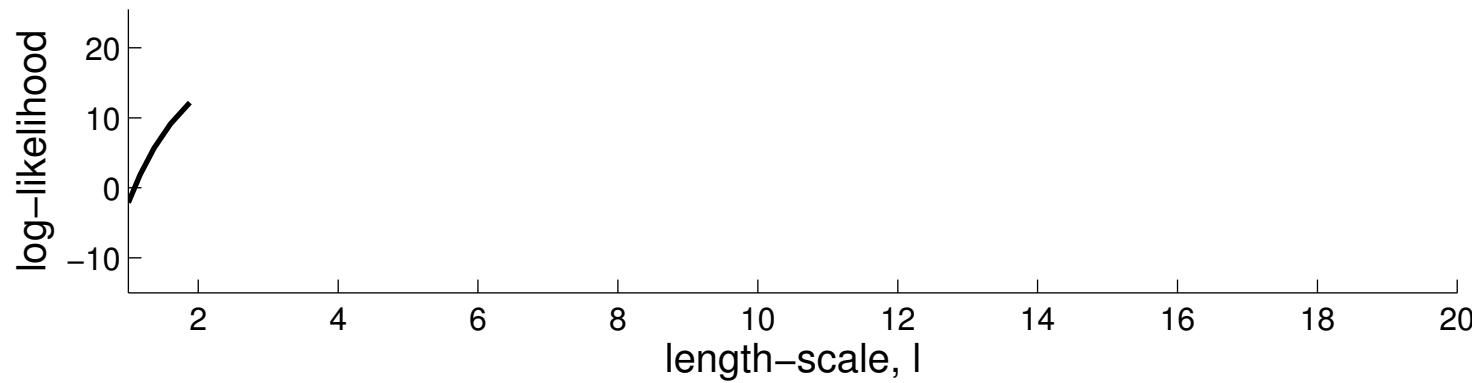
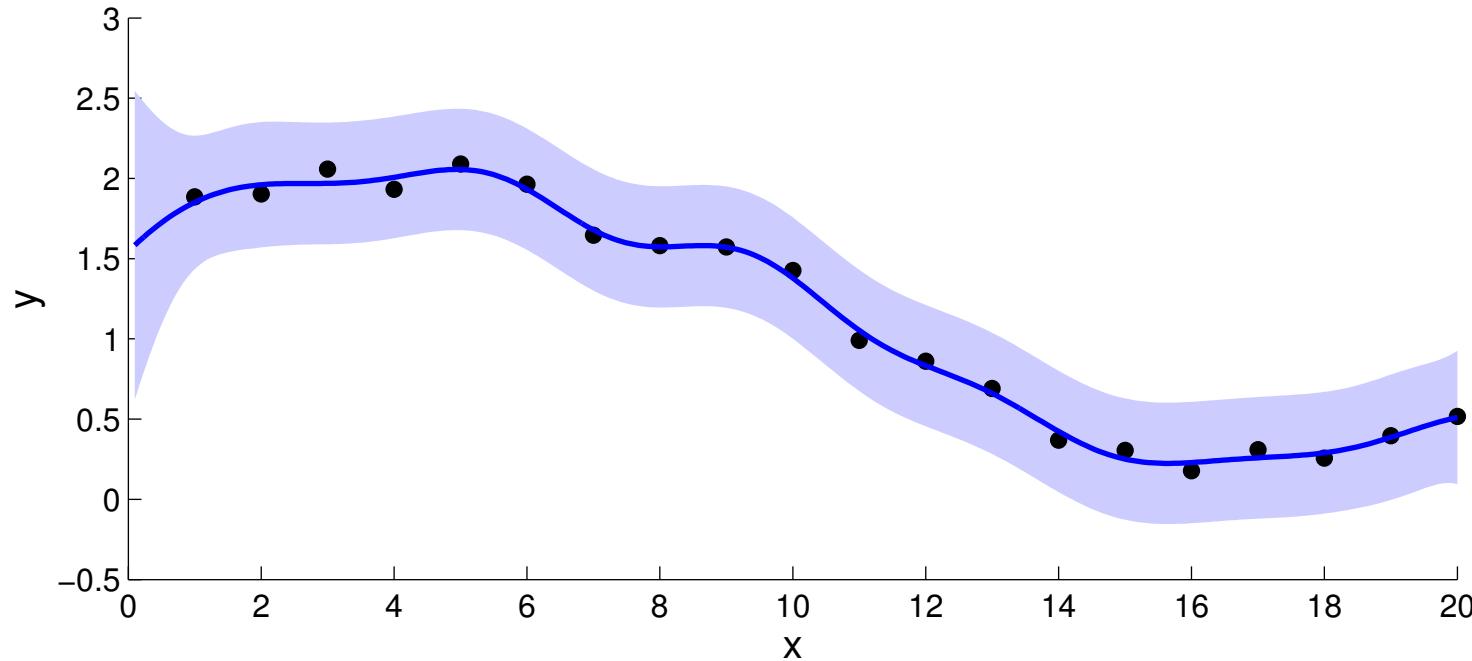
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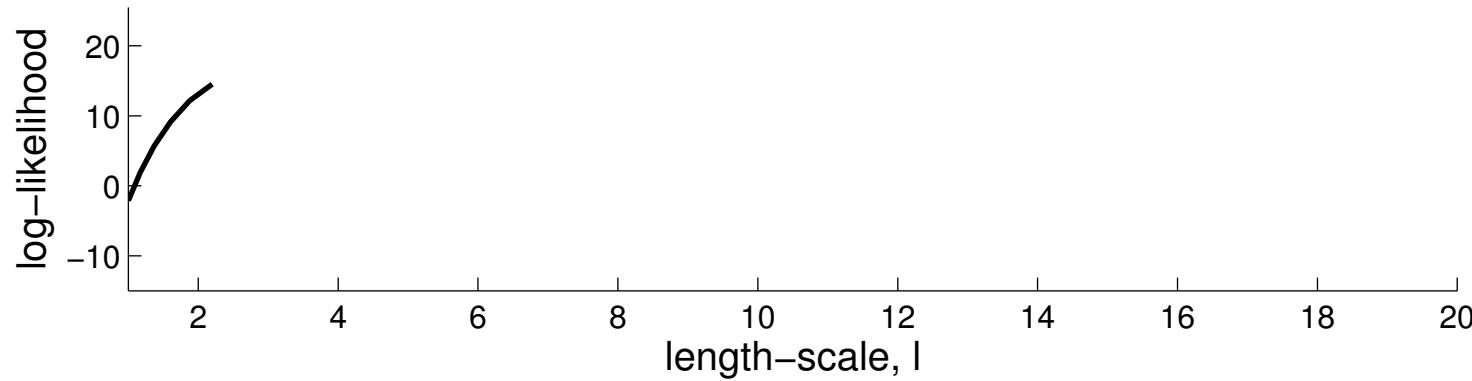
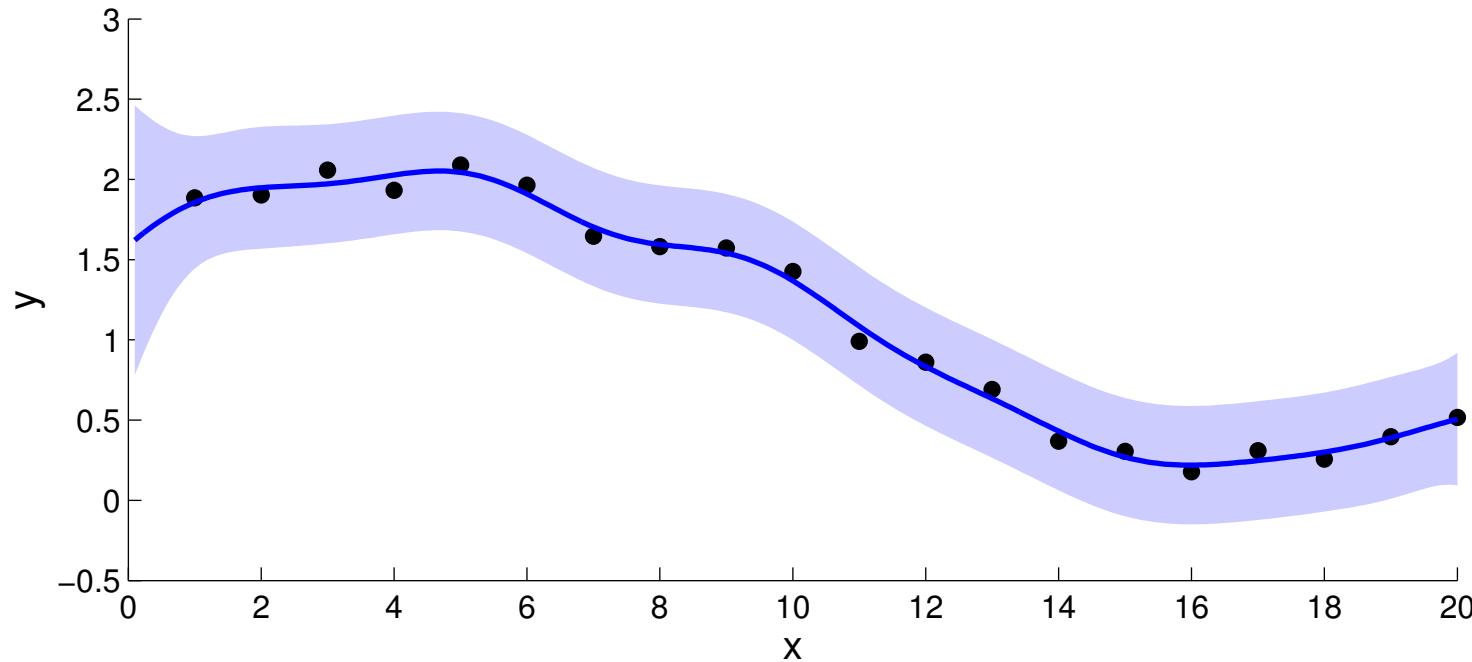
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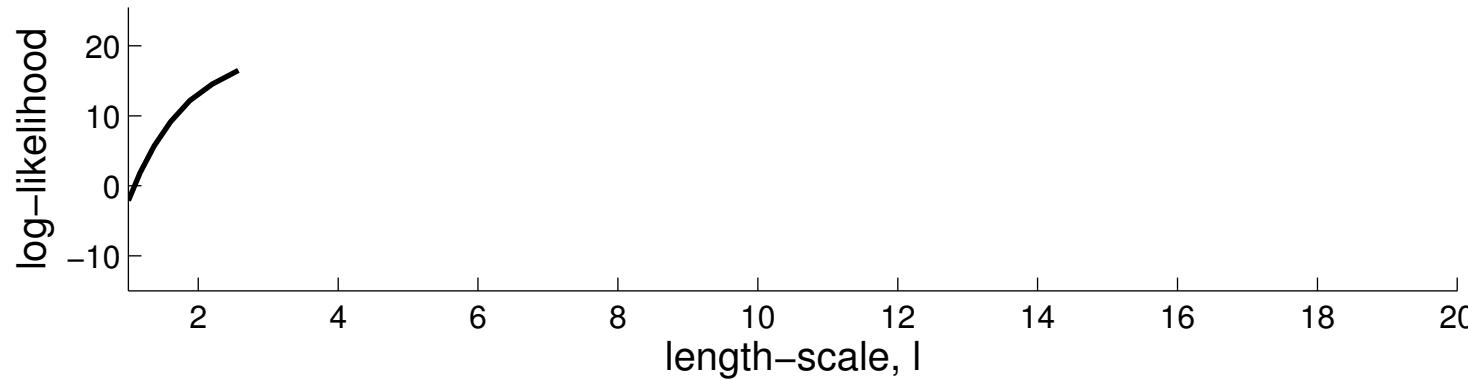
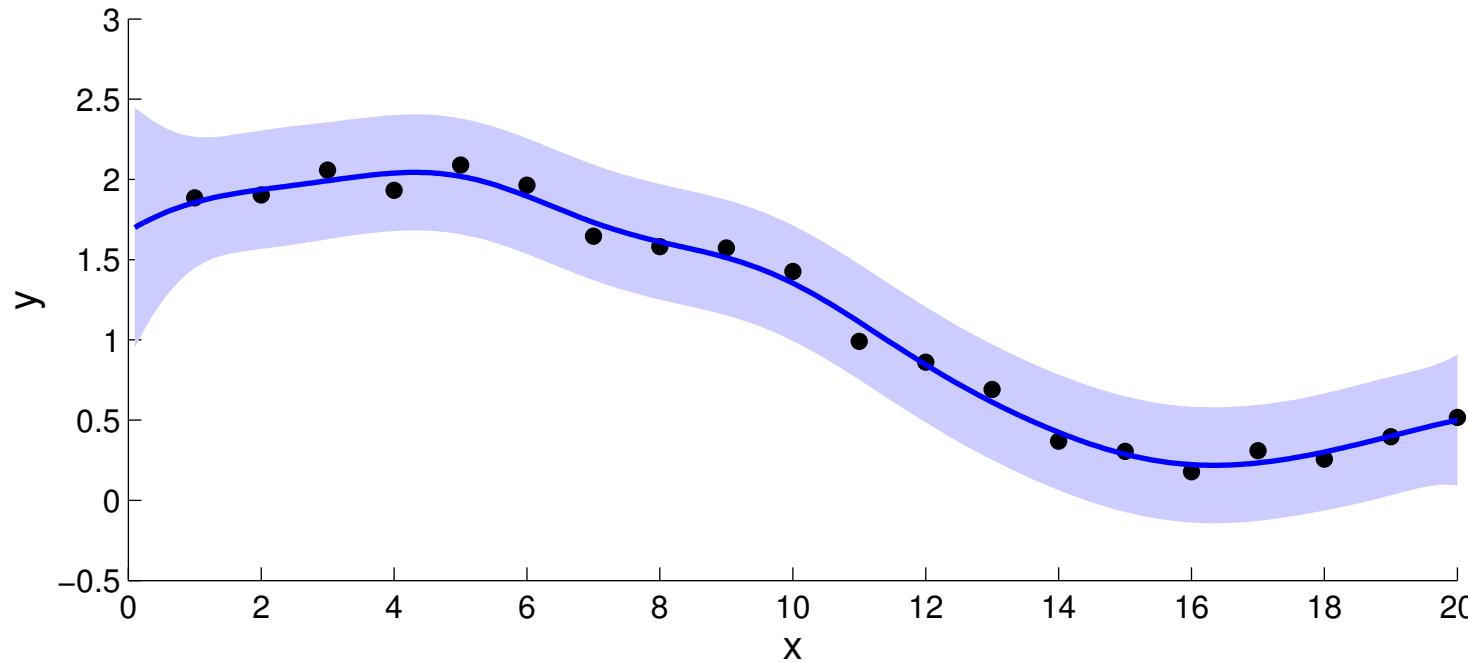
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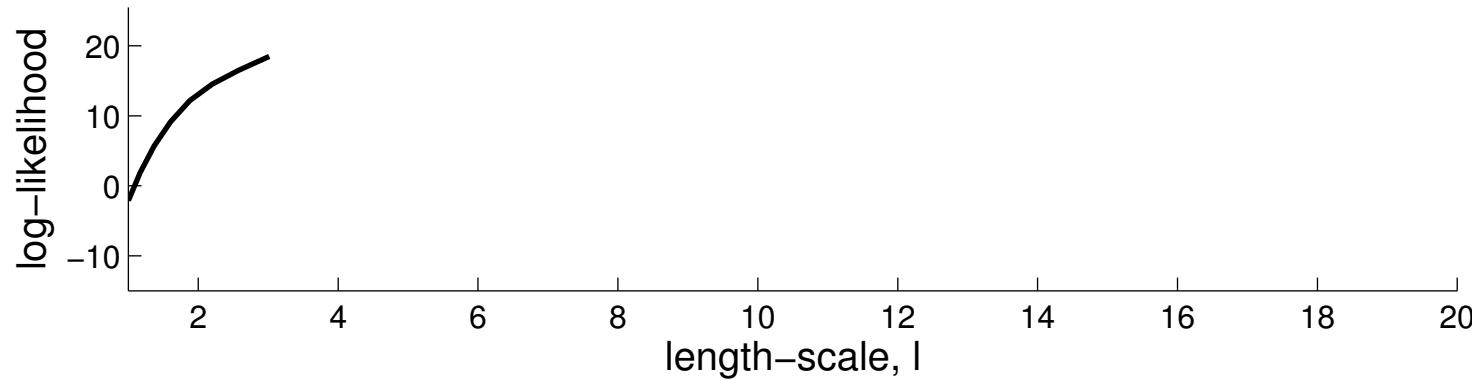
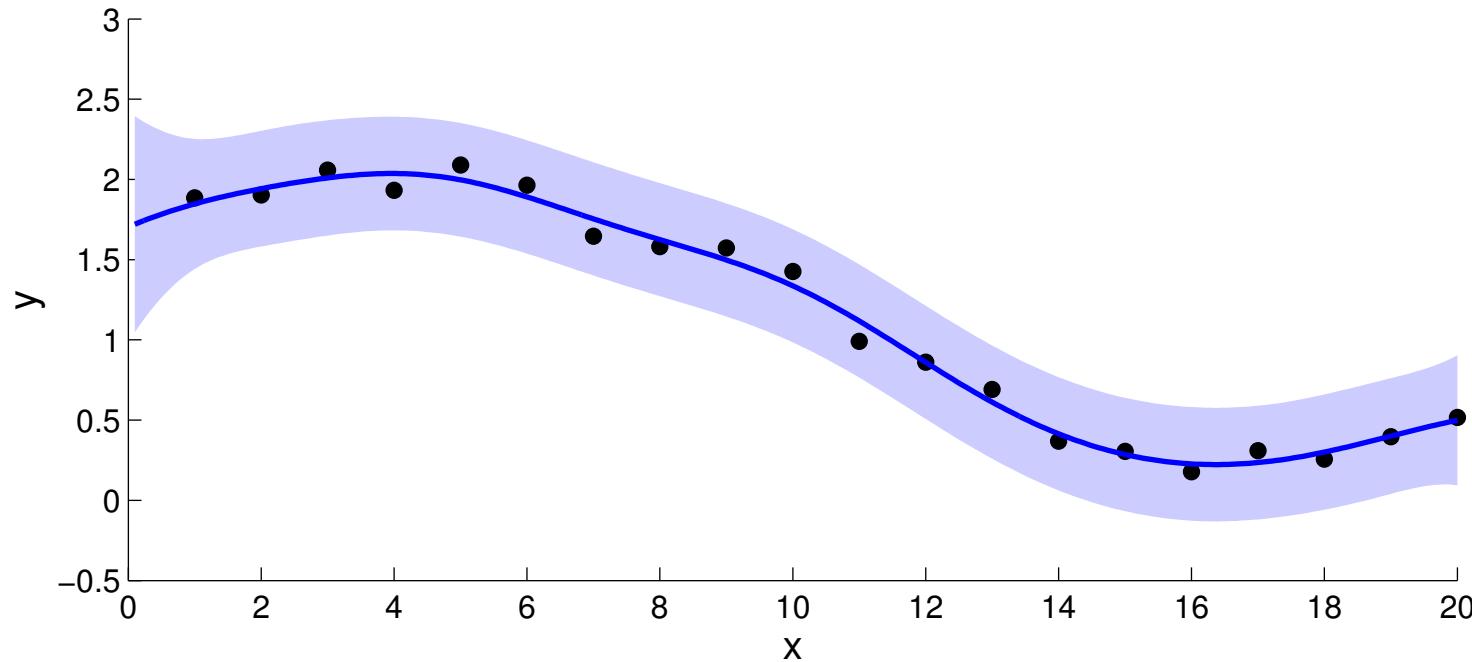
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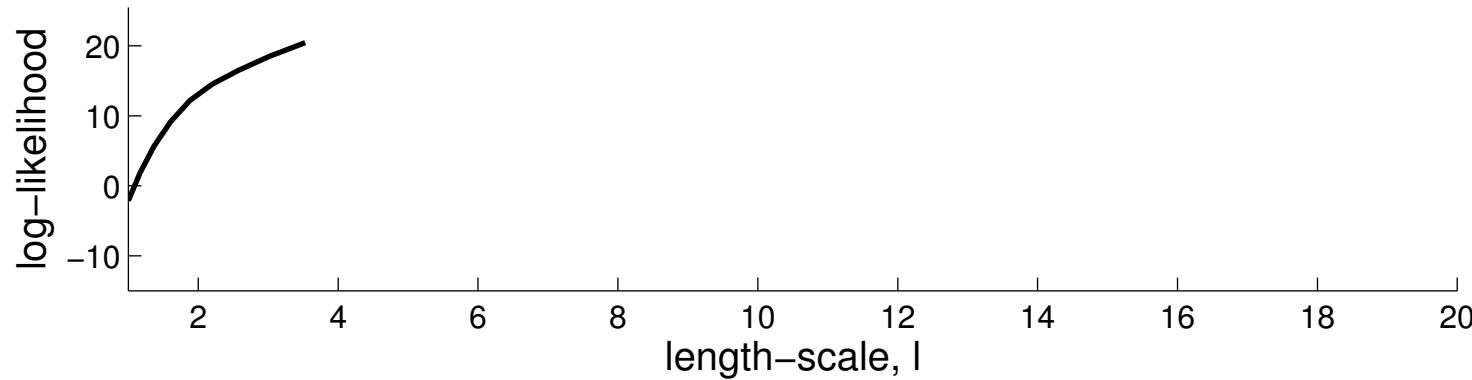
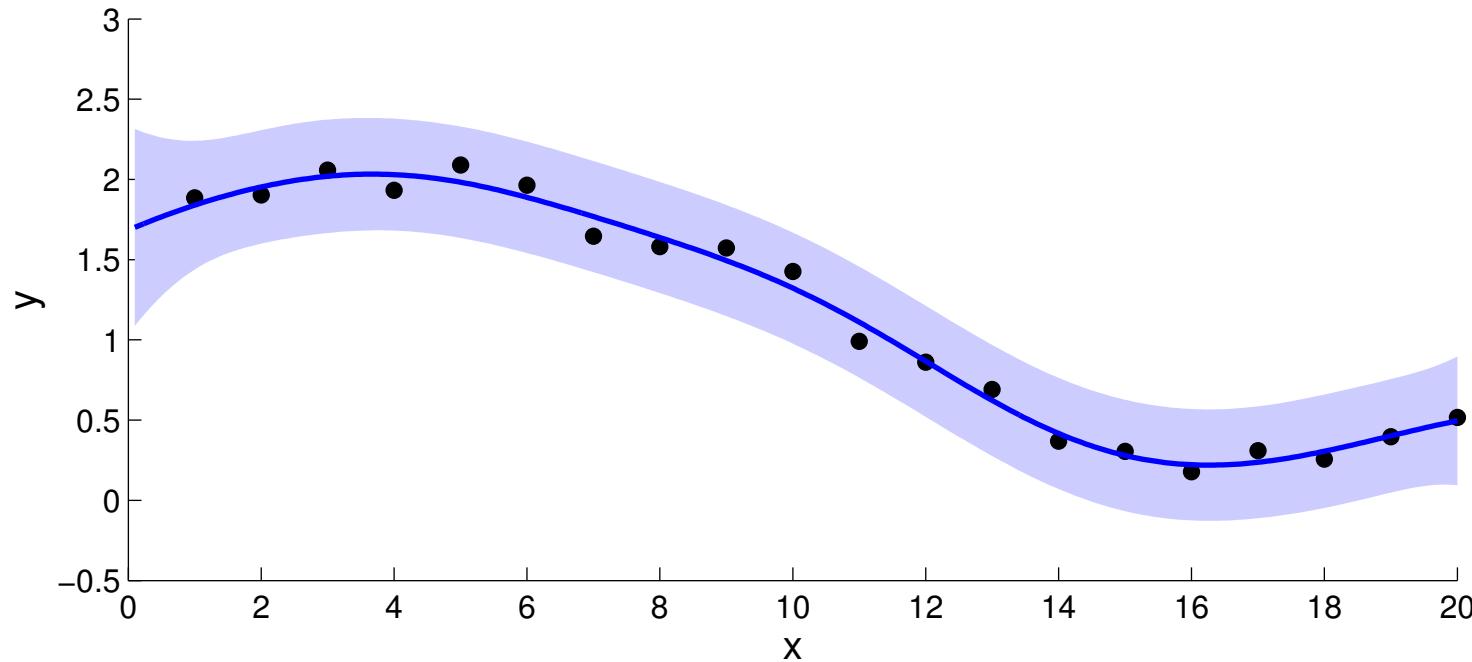
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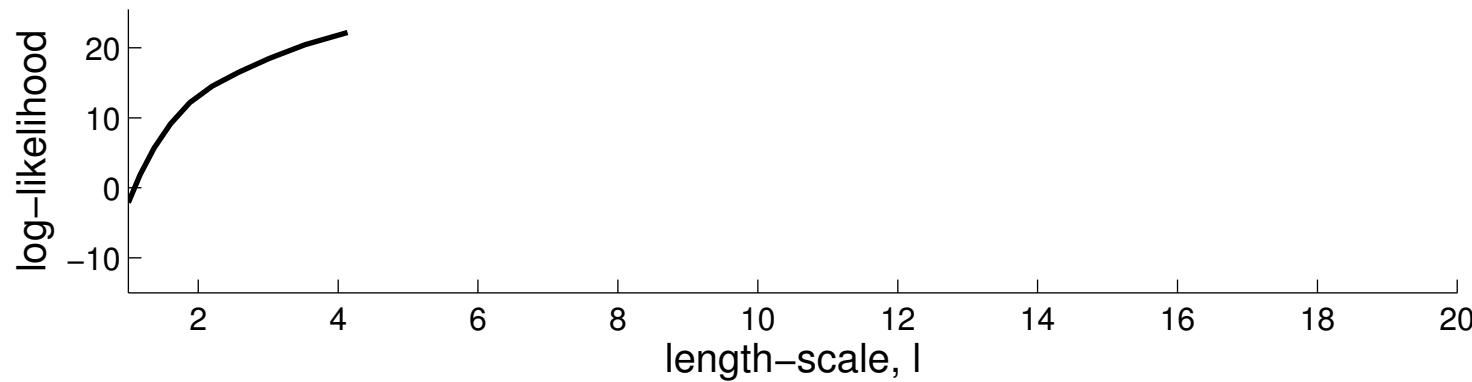
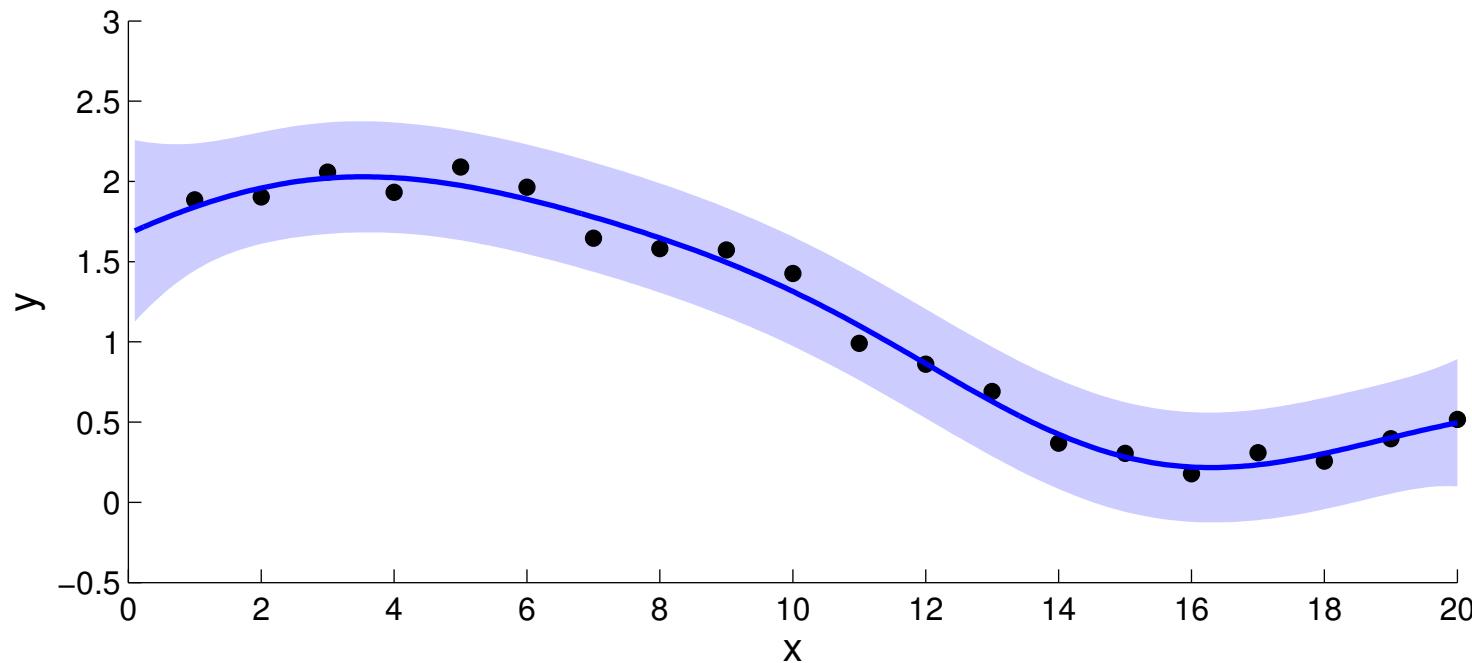
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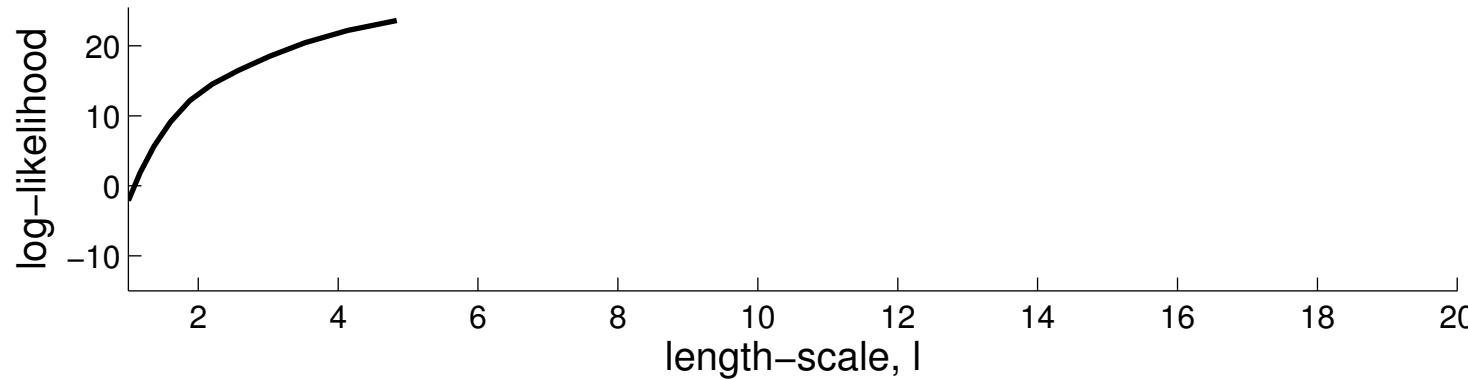
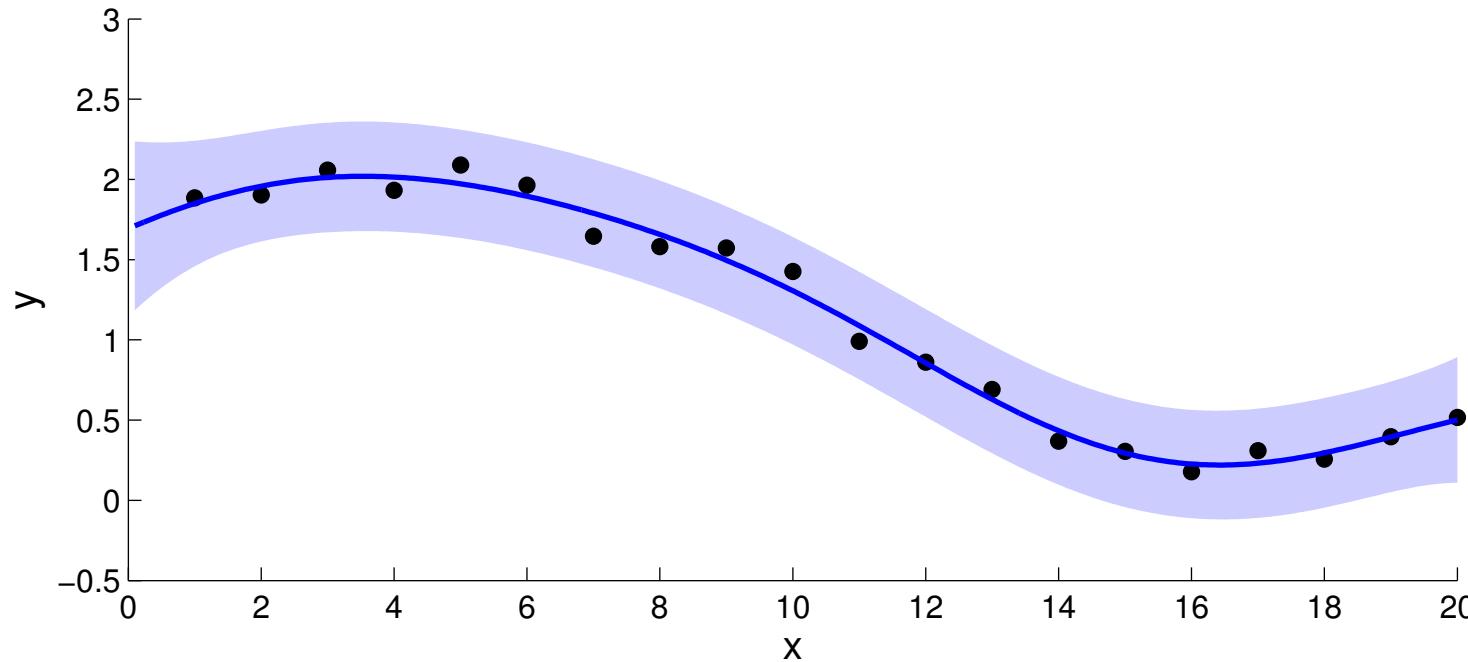
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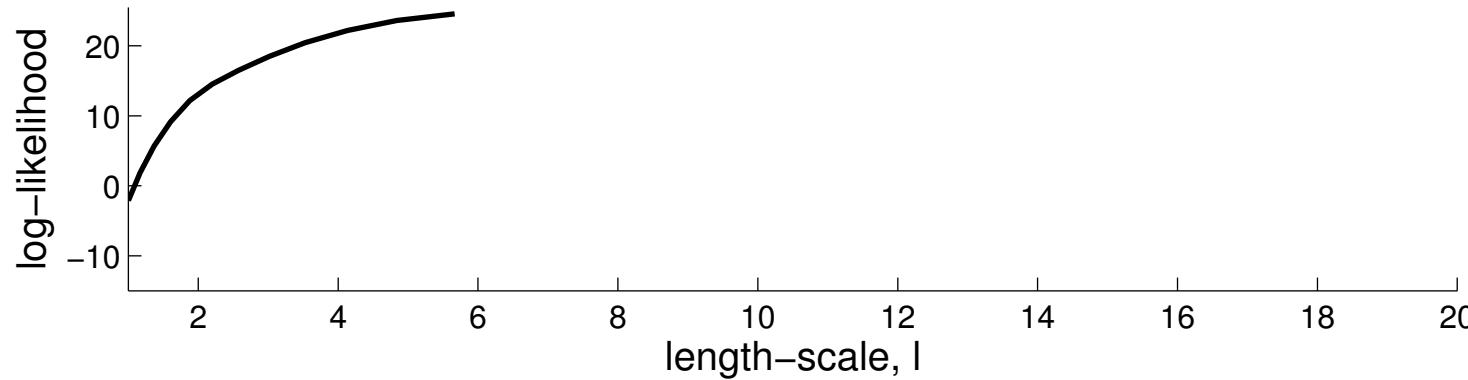
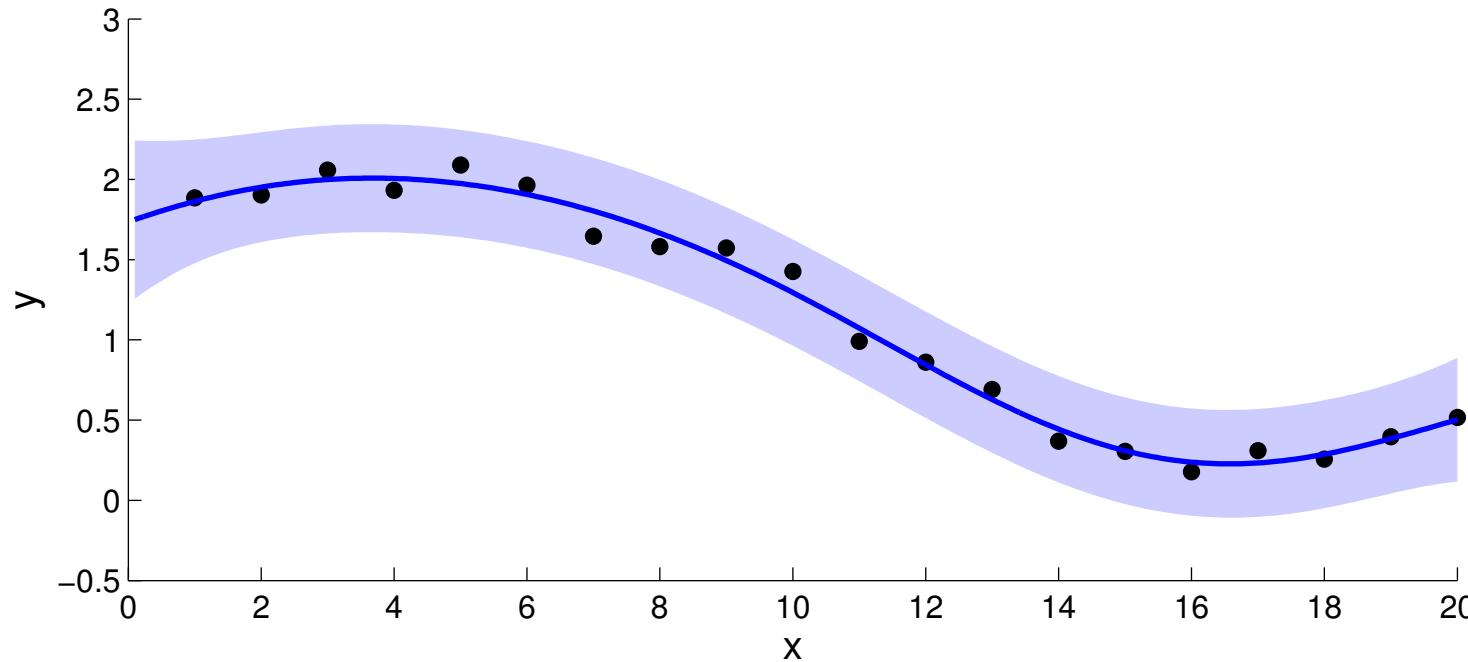
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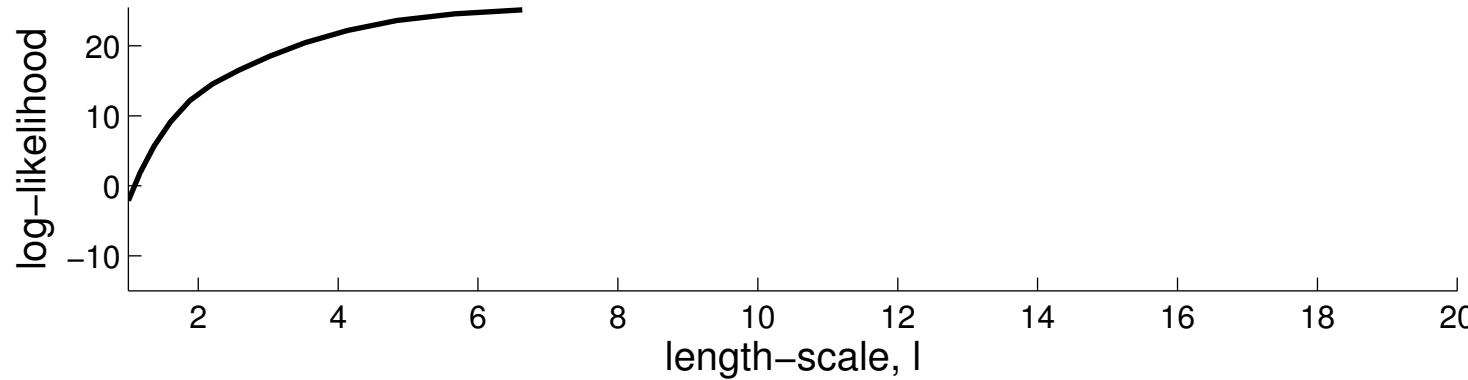
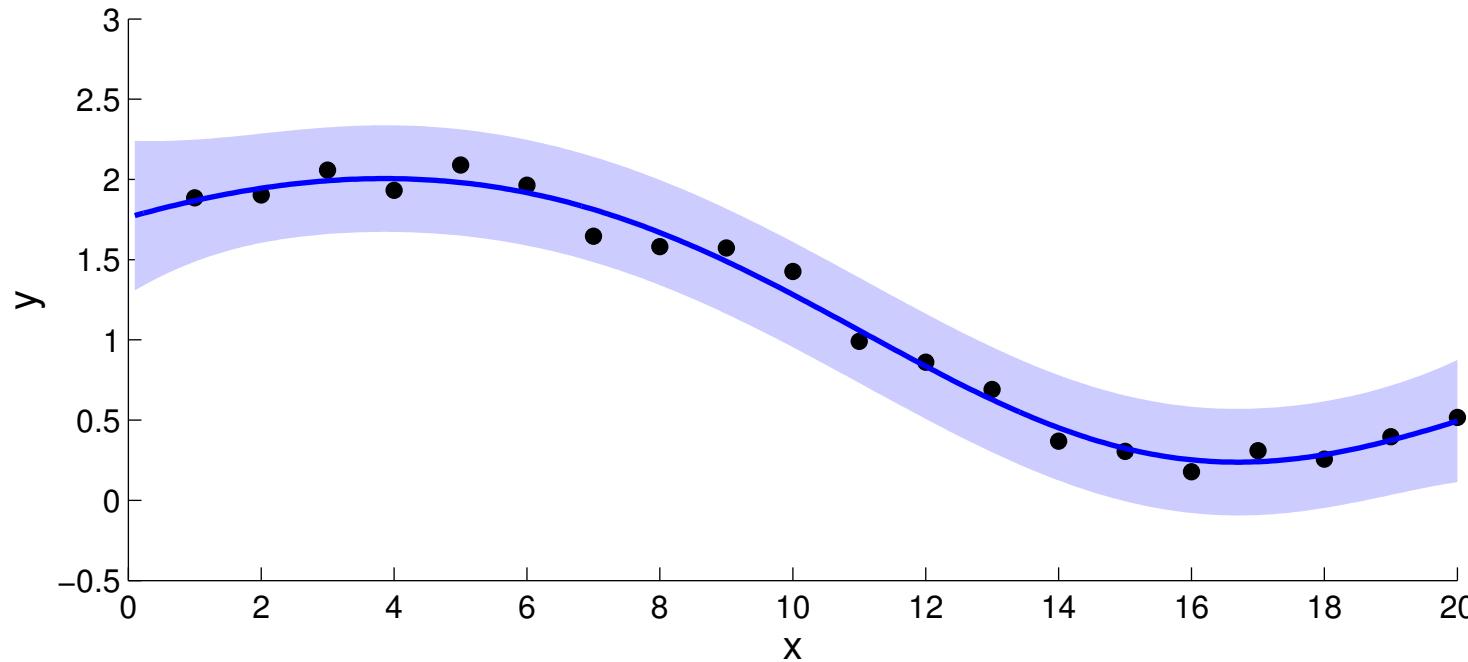
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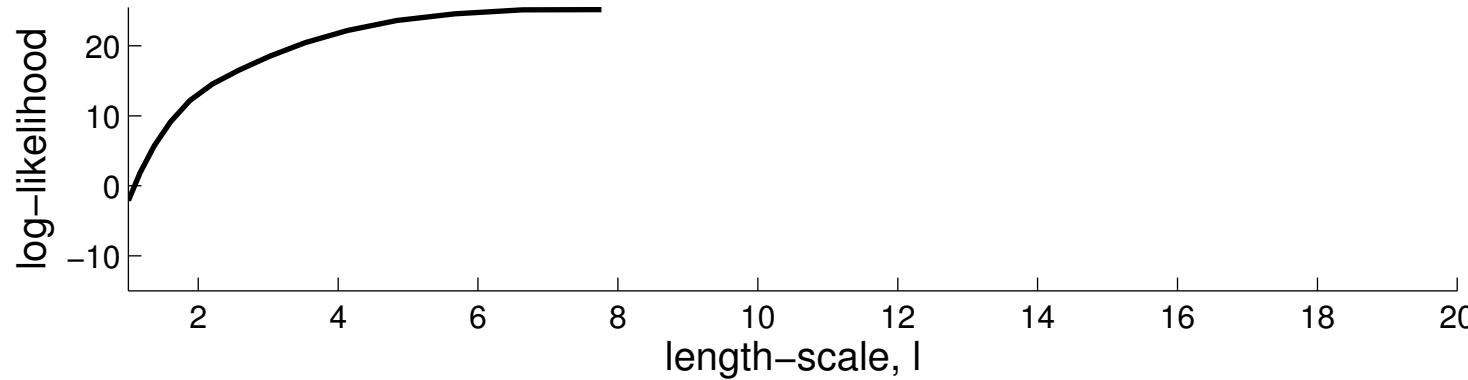
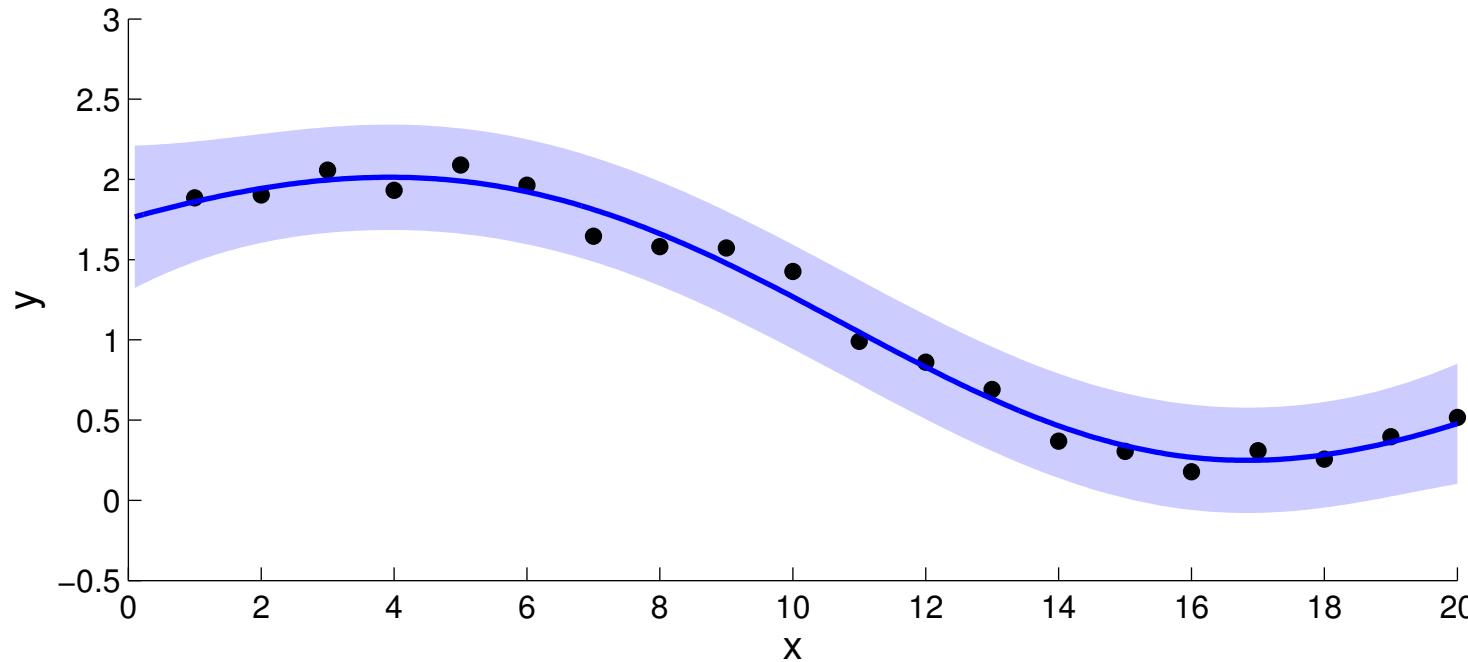
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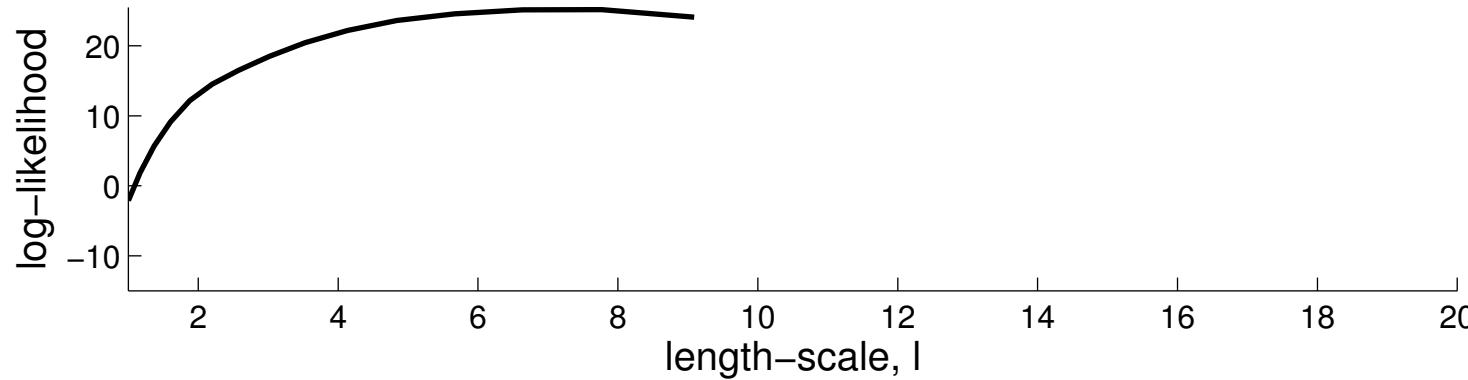
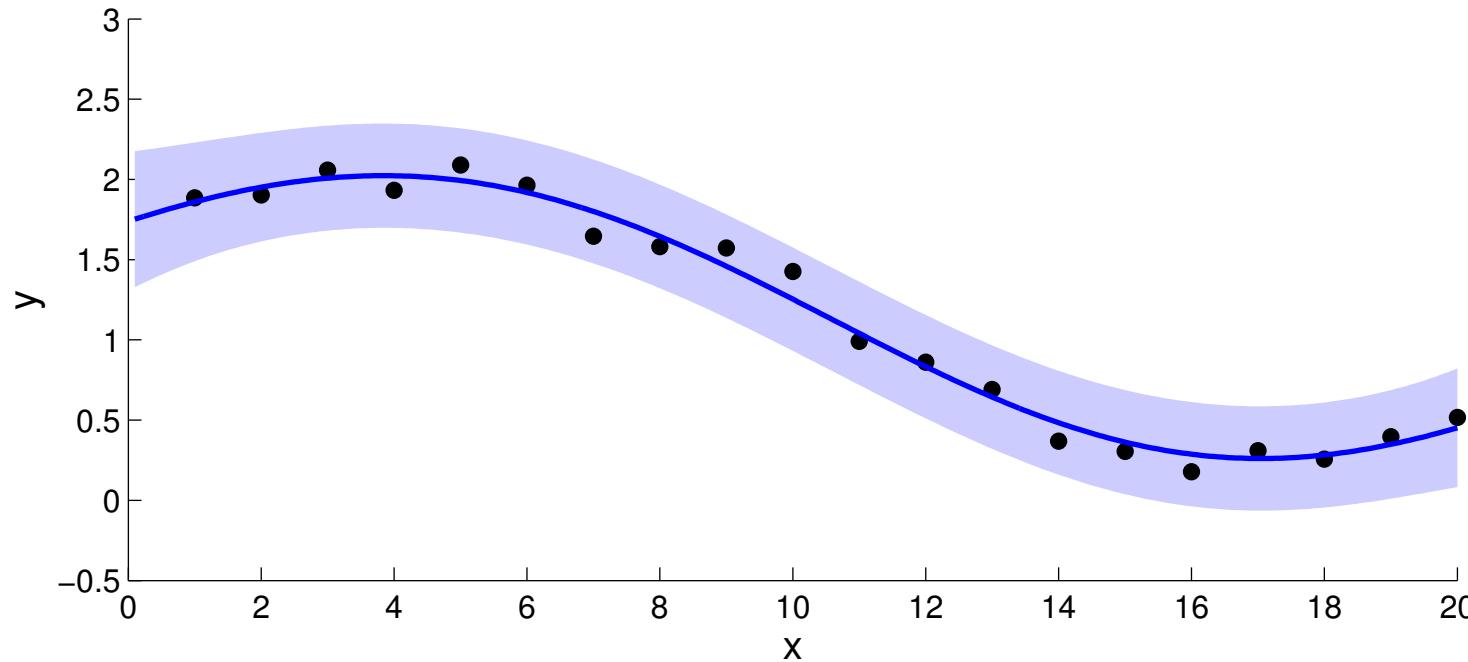
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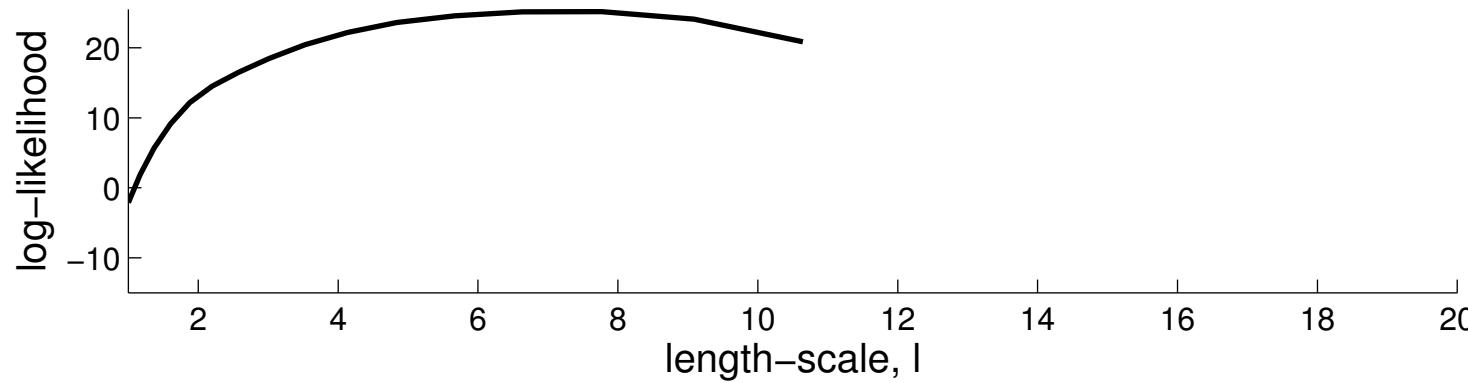
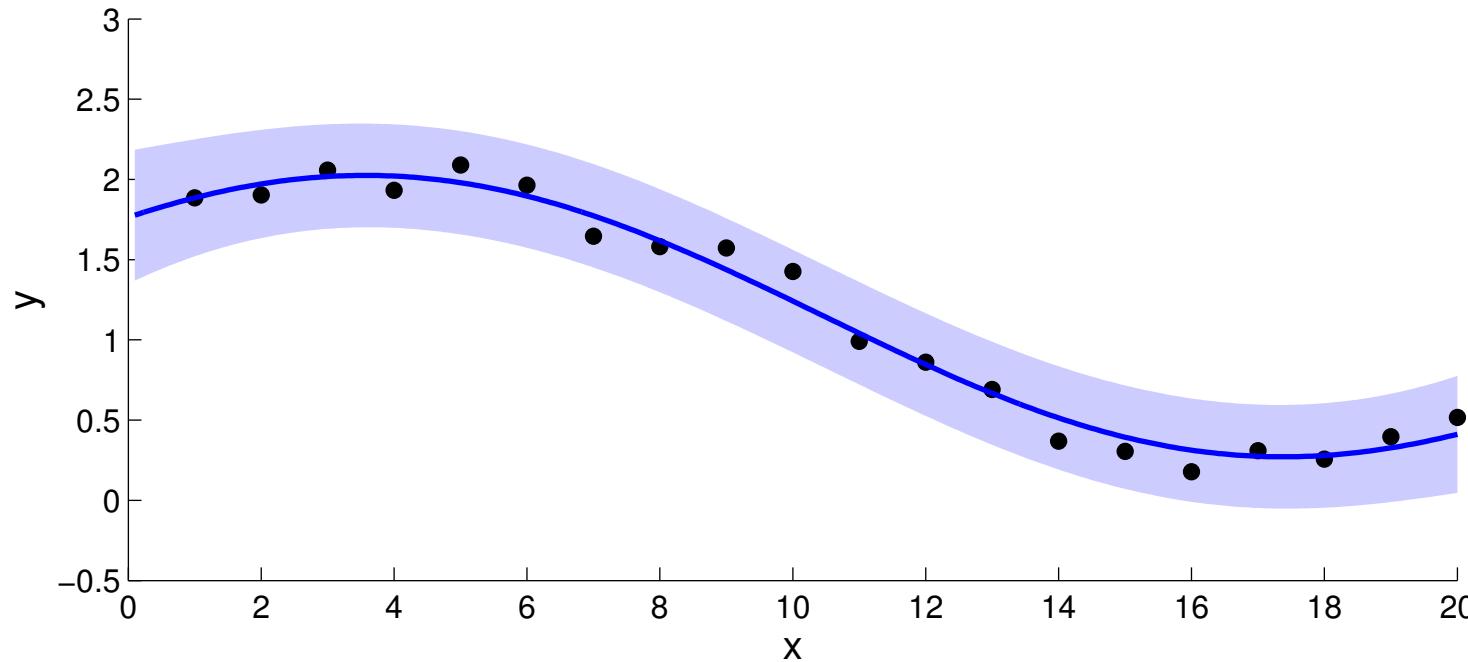
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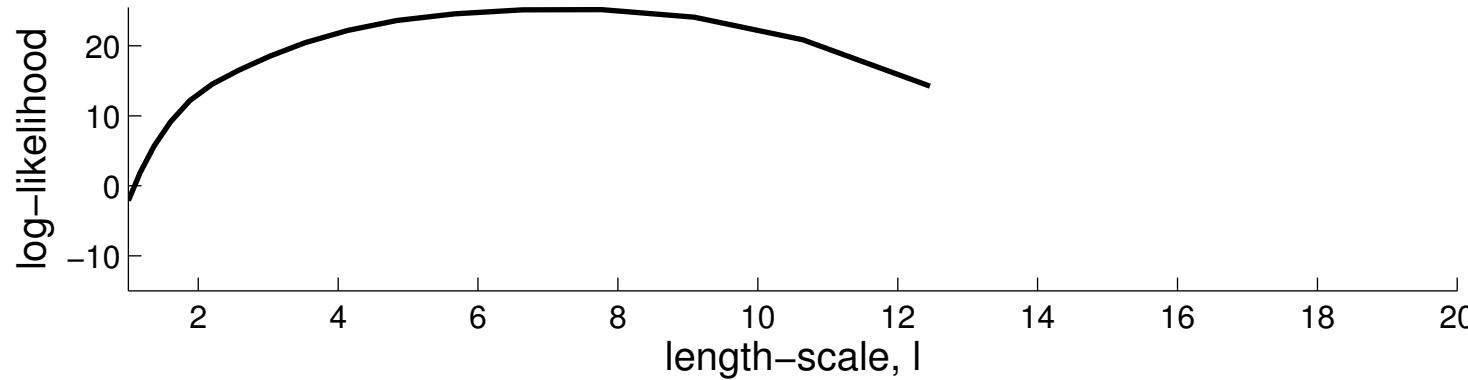
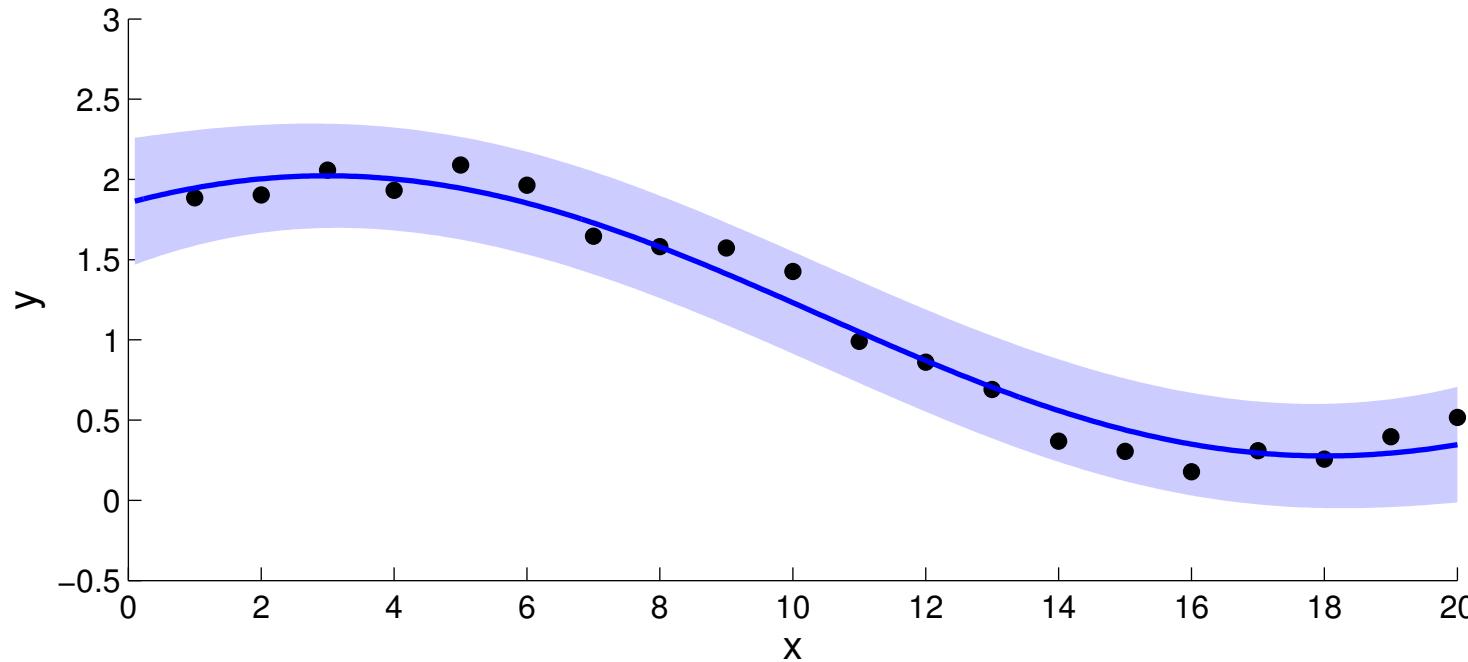
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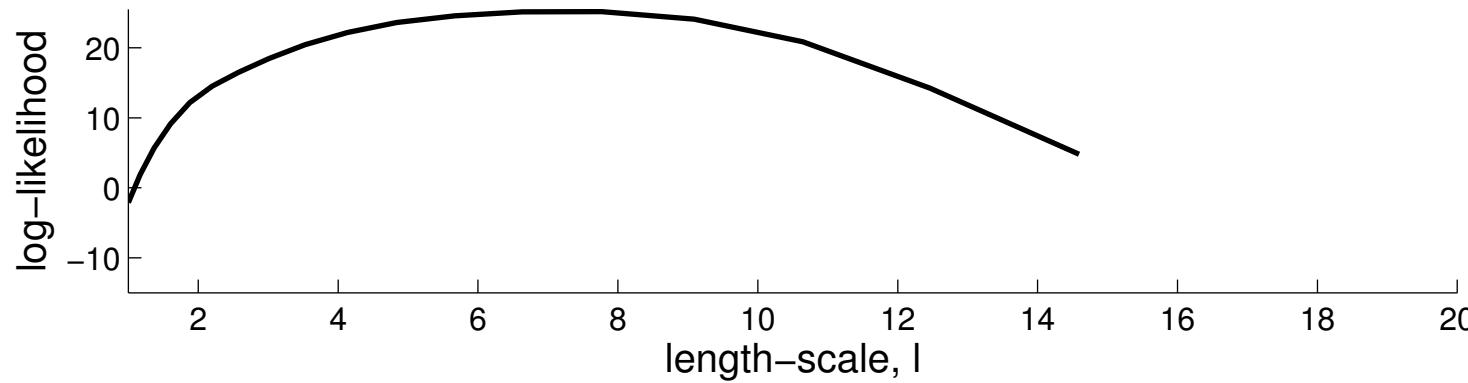
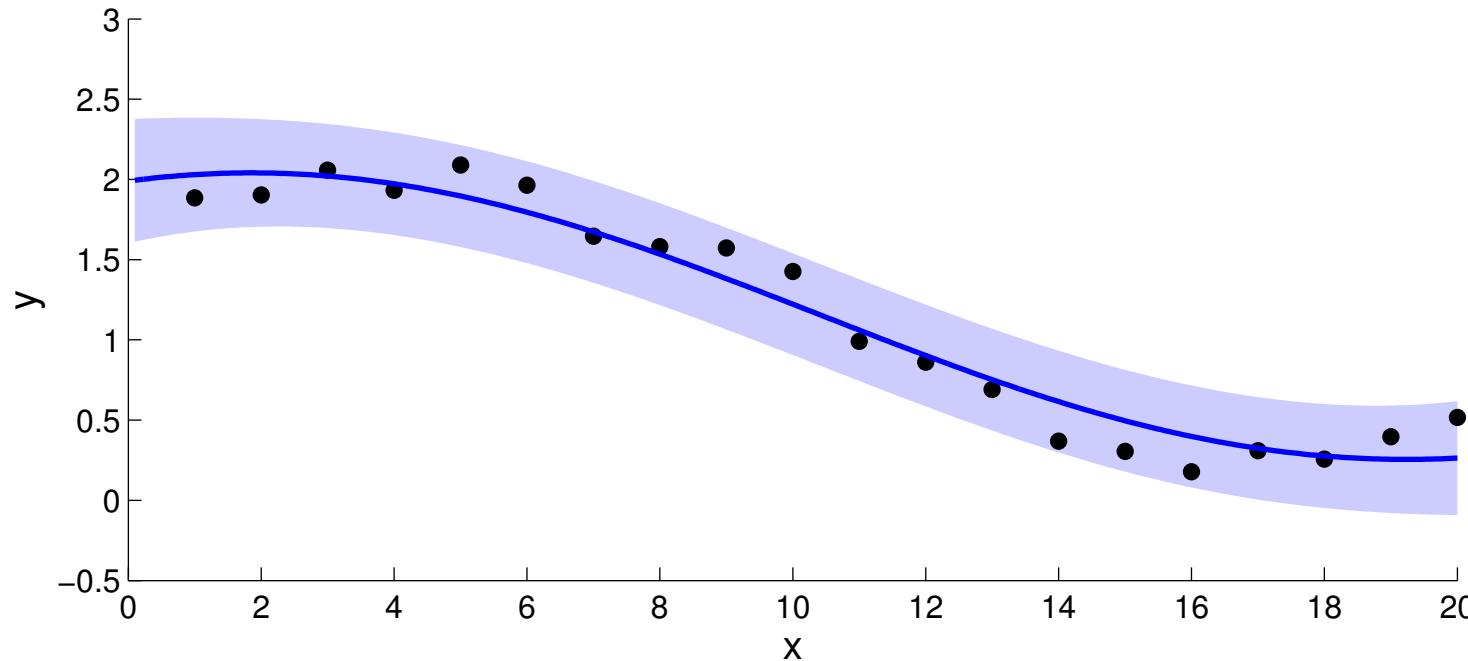
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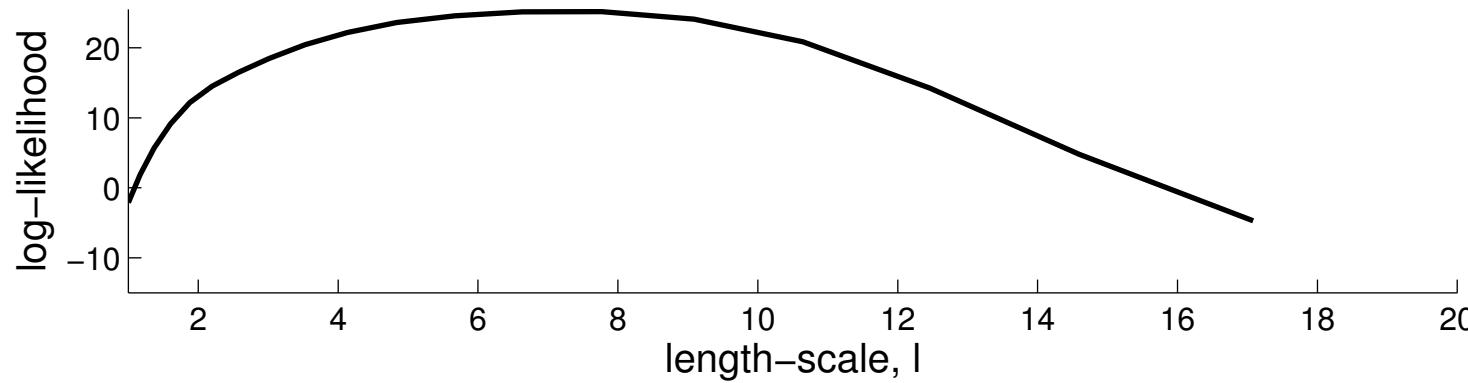
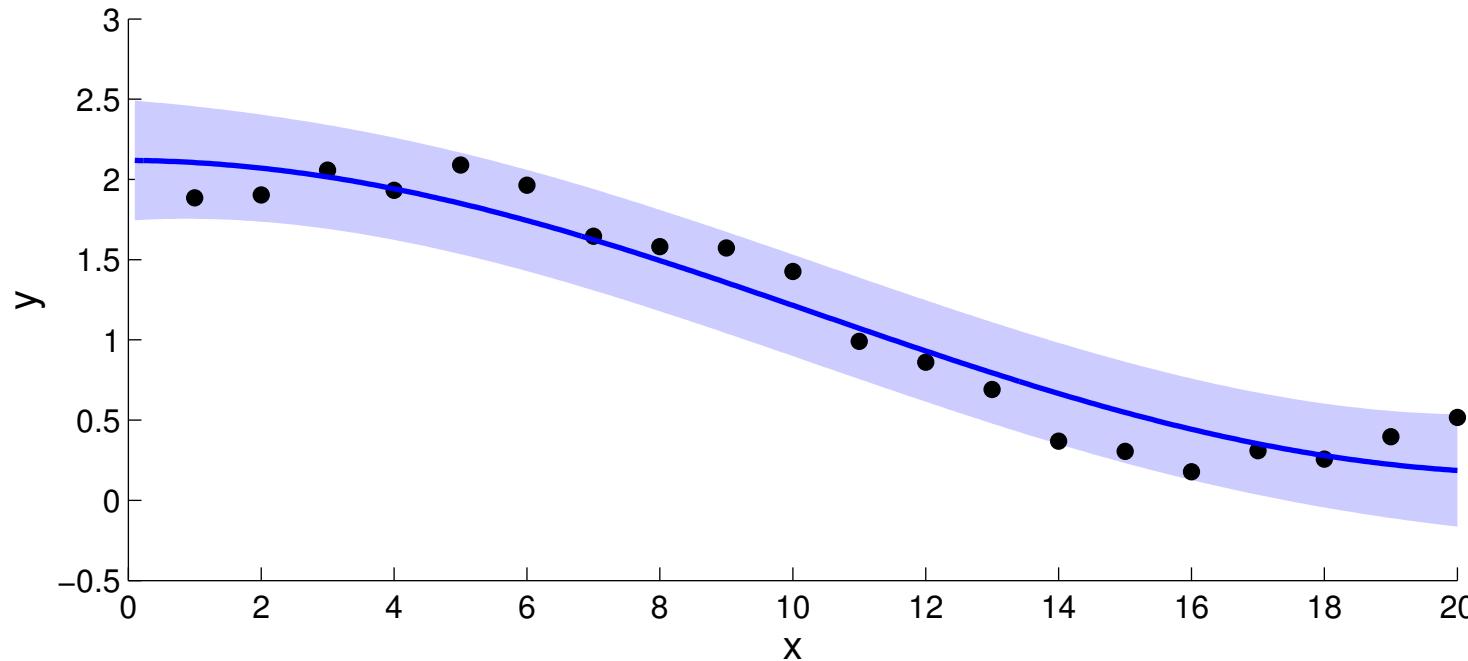
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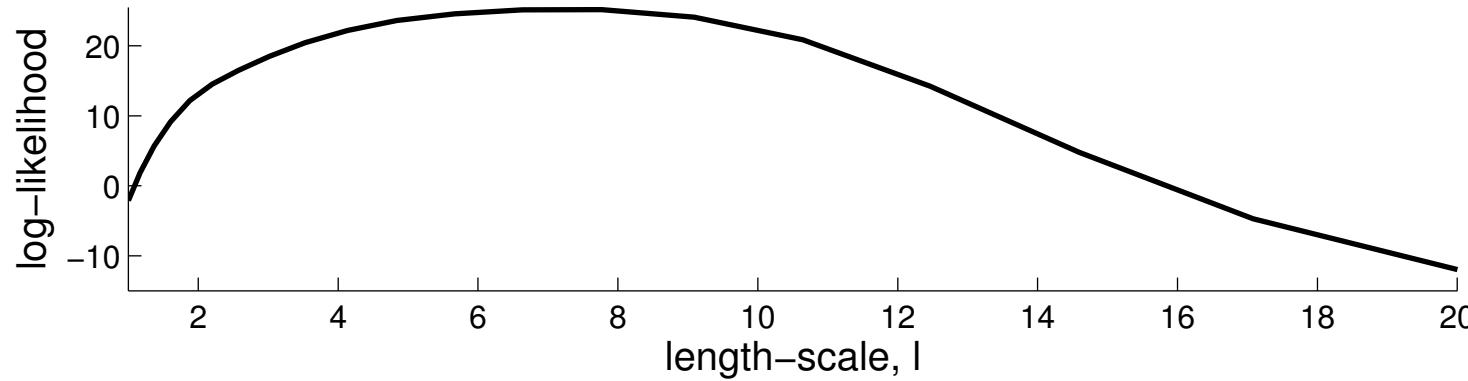
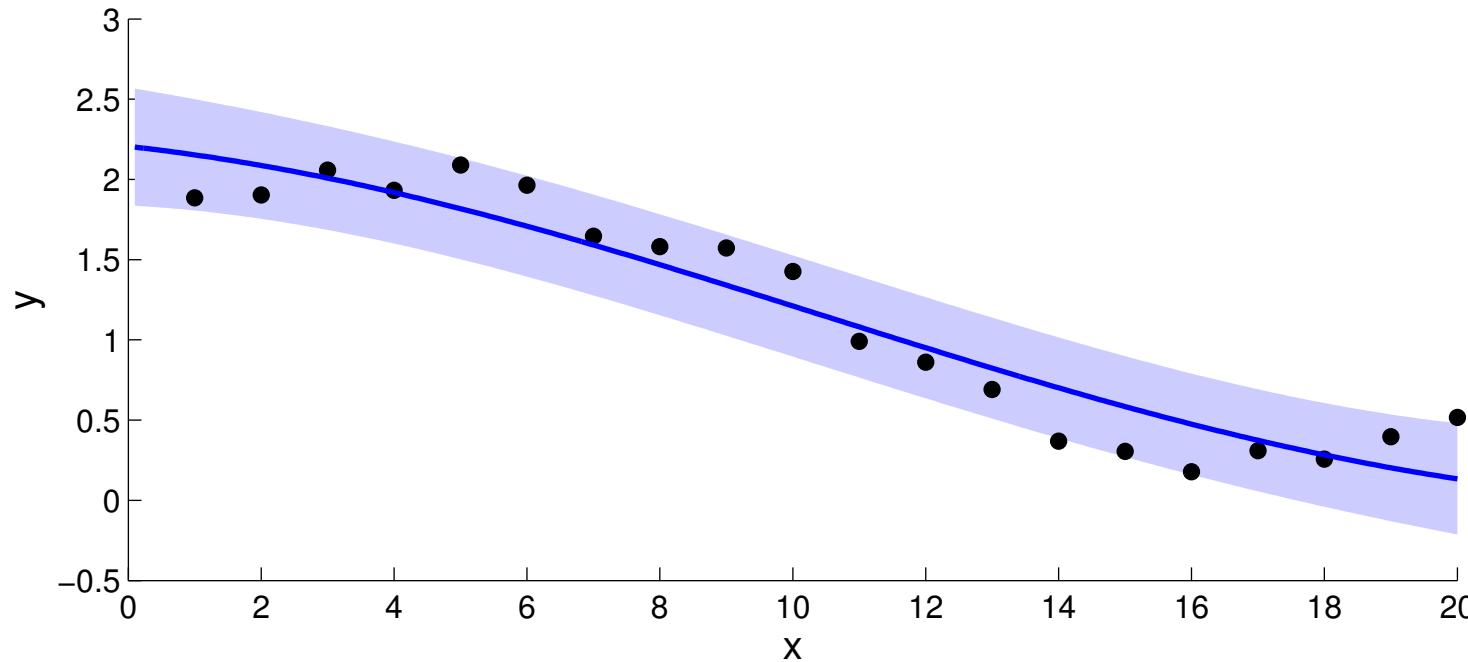
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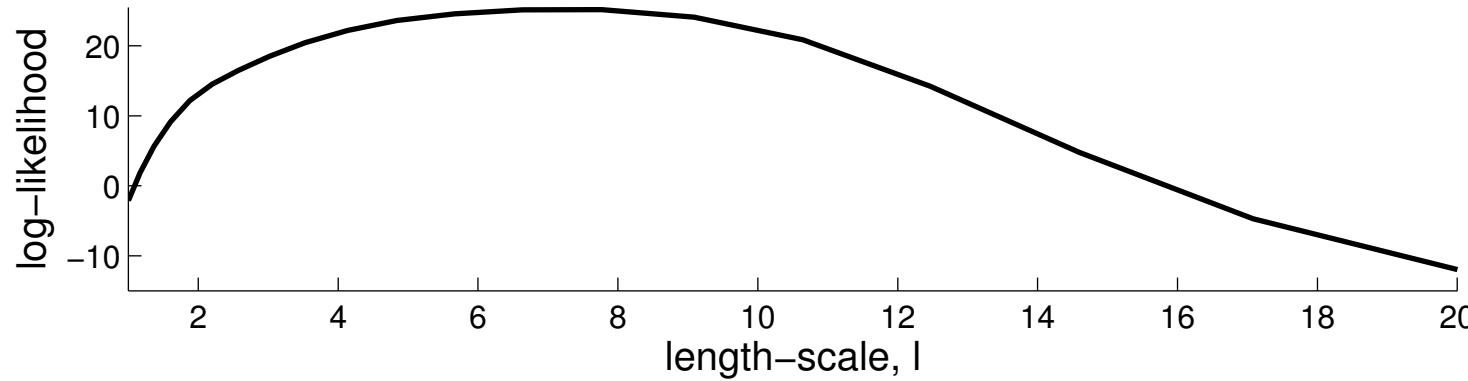
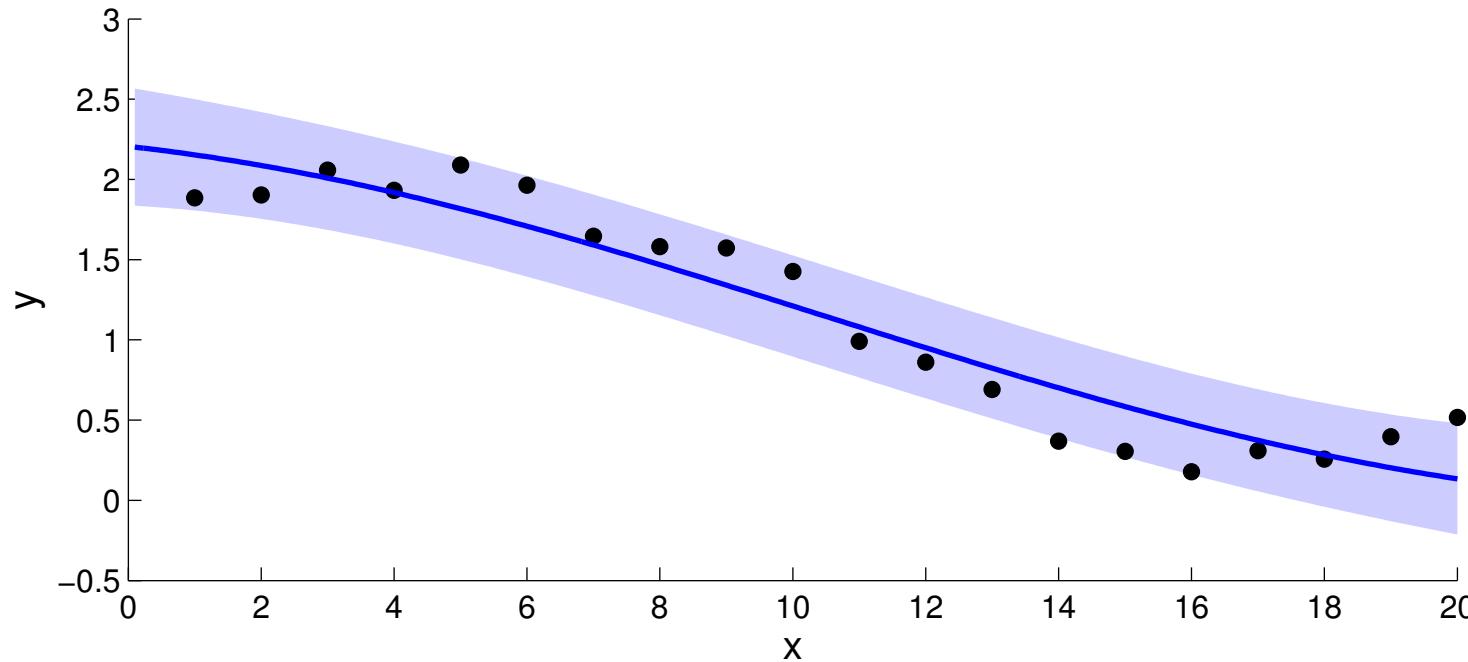
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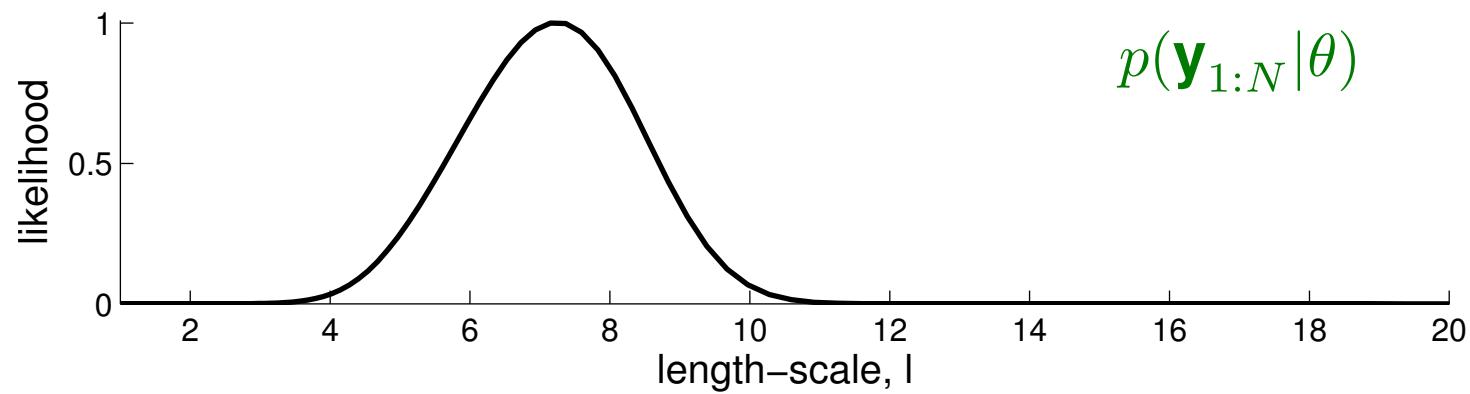
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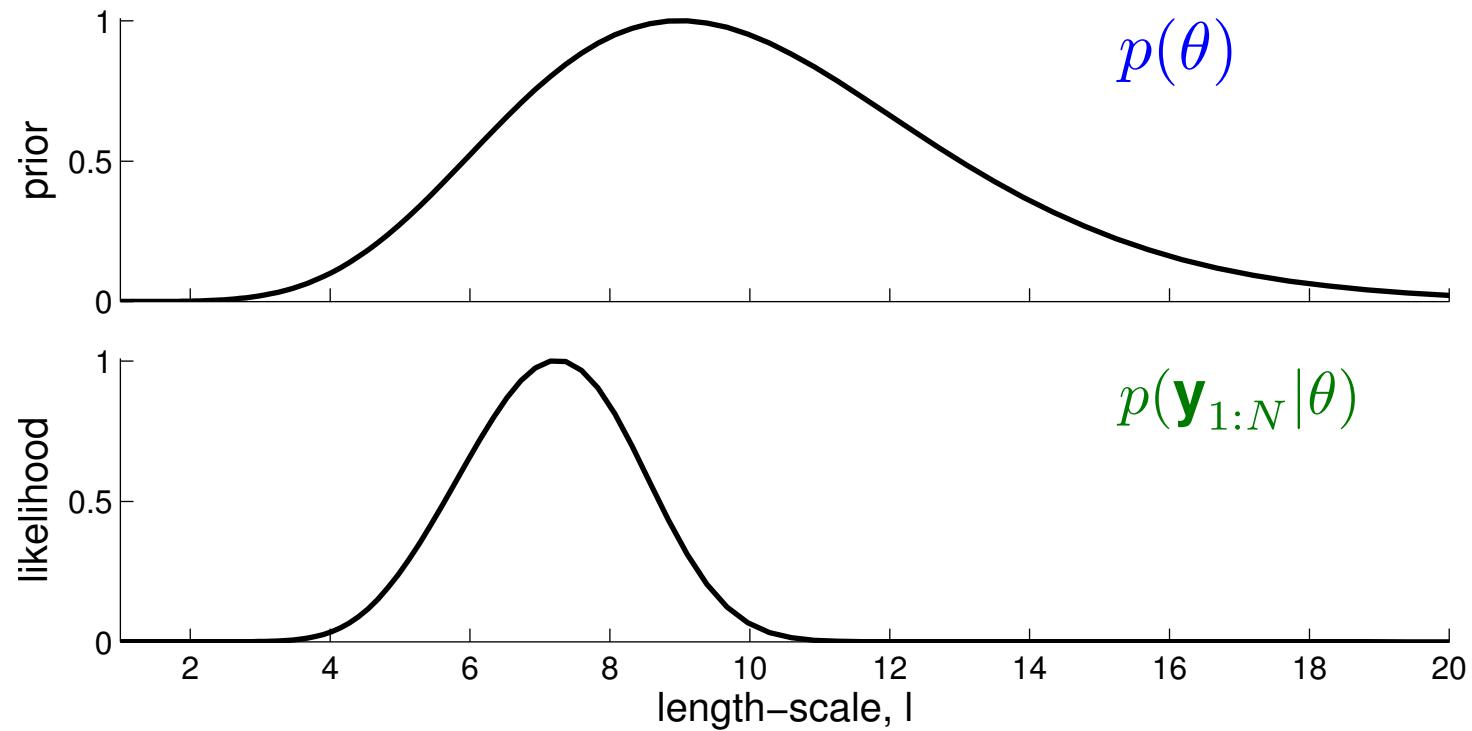
How do we choose the hyper-parameters?



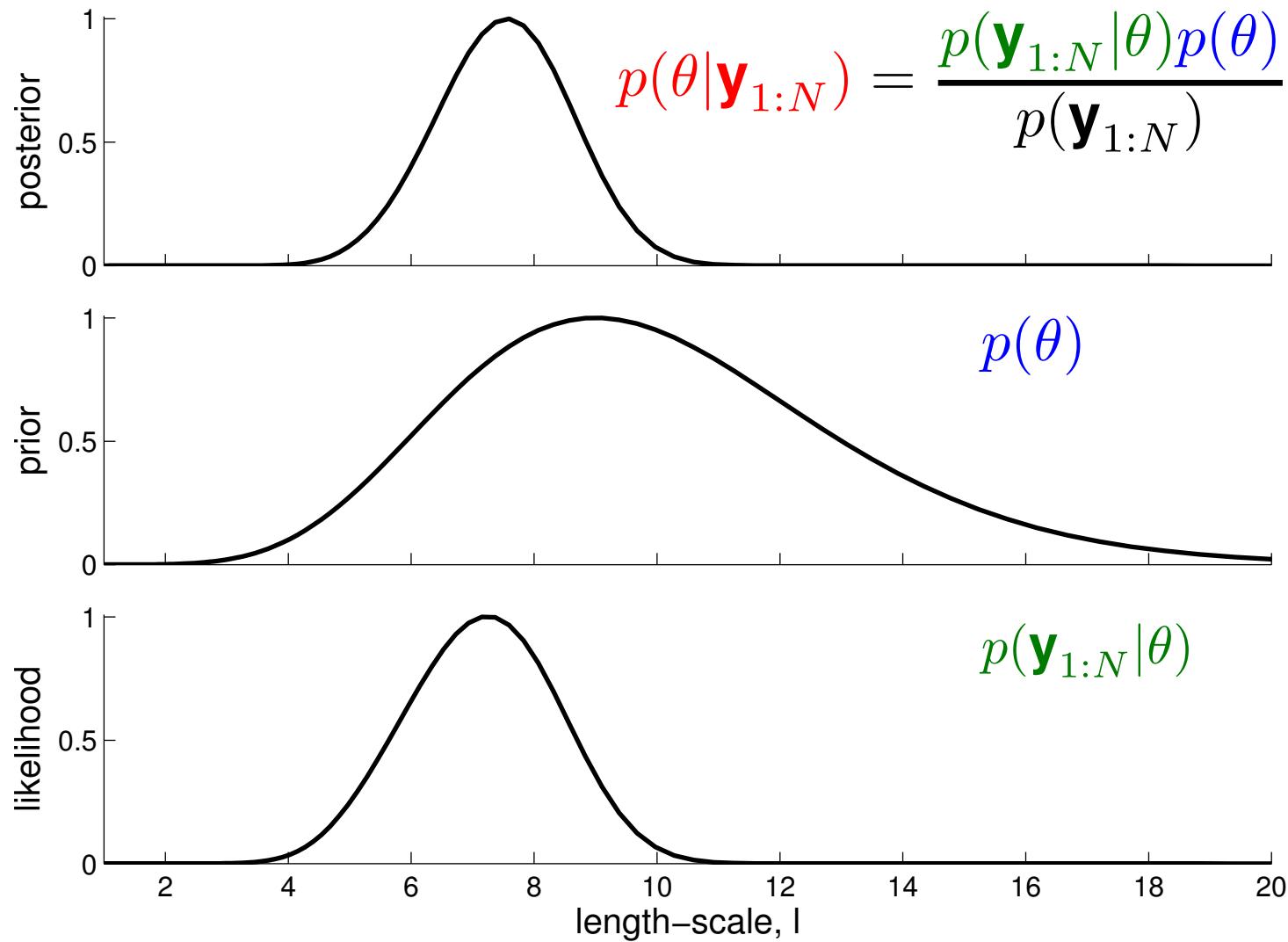
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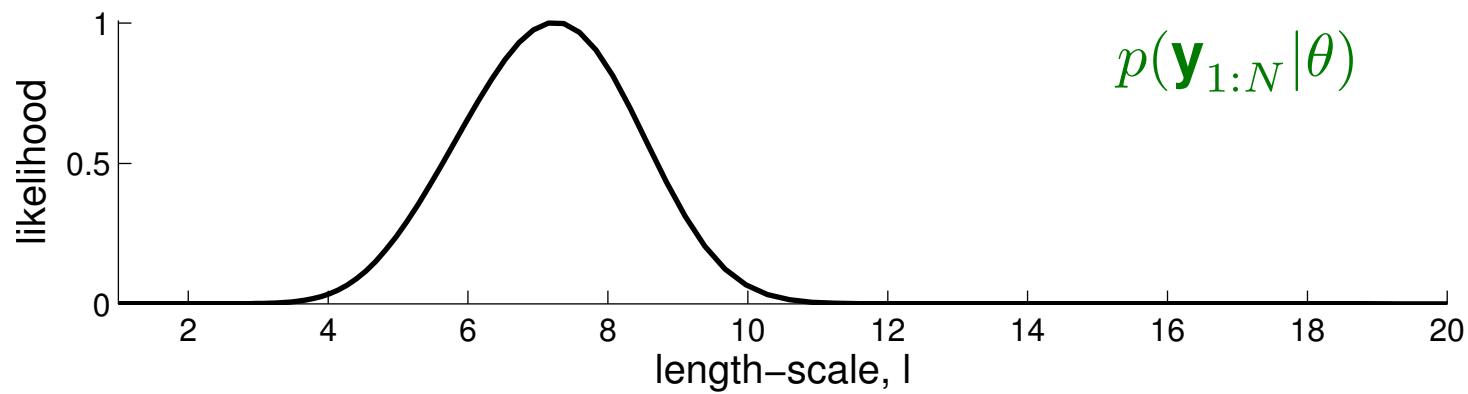
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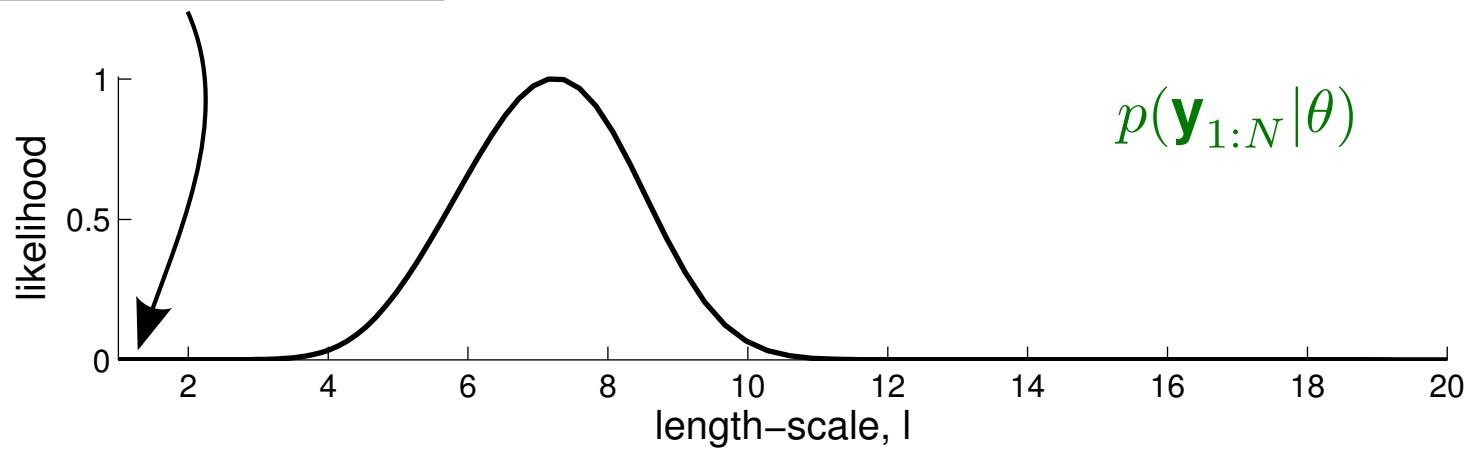
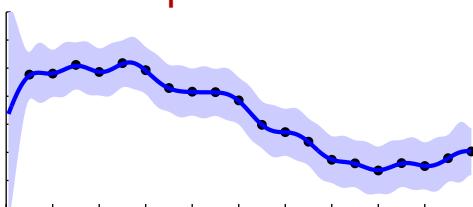


Why does Bayesian inference work?



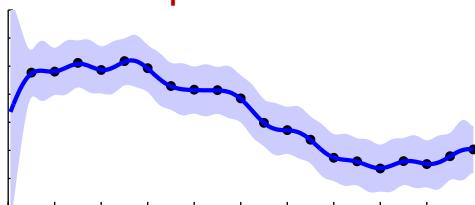
Why does Bayesian inference work?

fits every training point
"complex" model

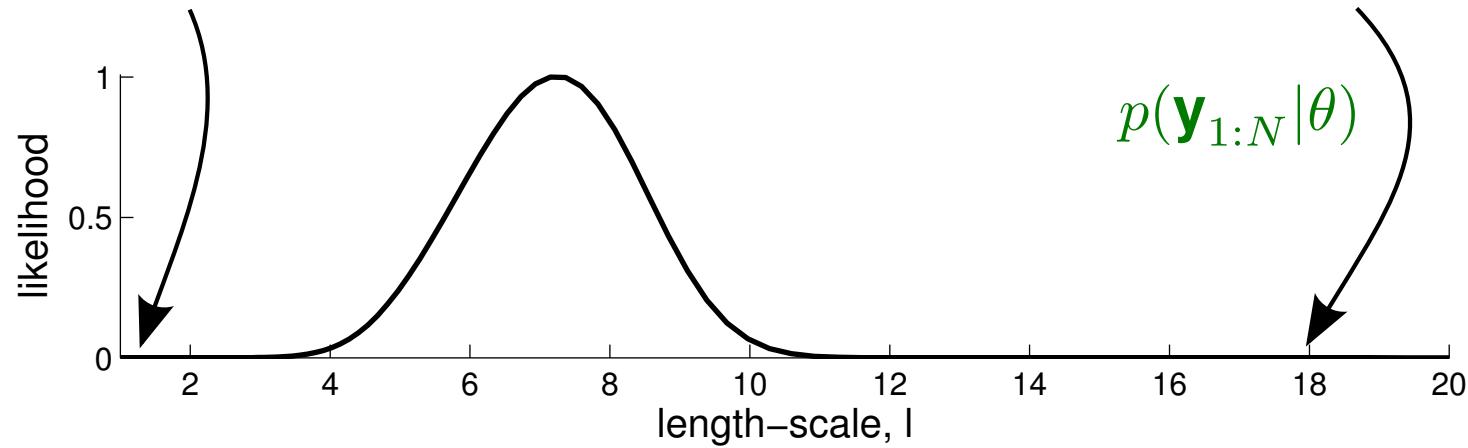
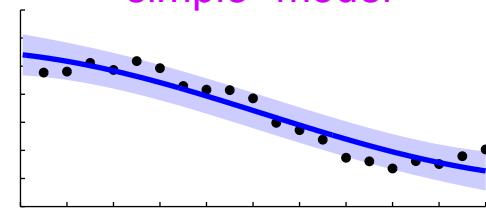


Why does Bayesian inference work?

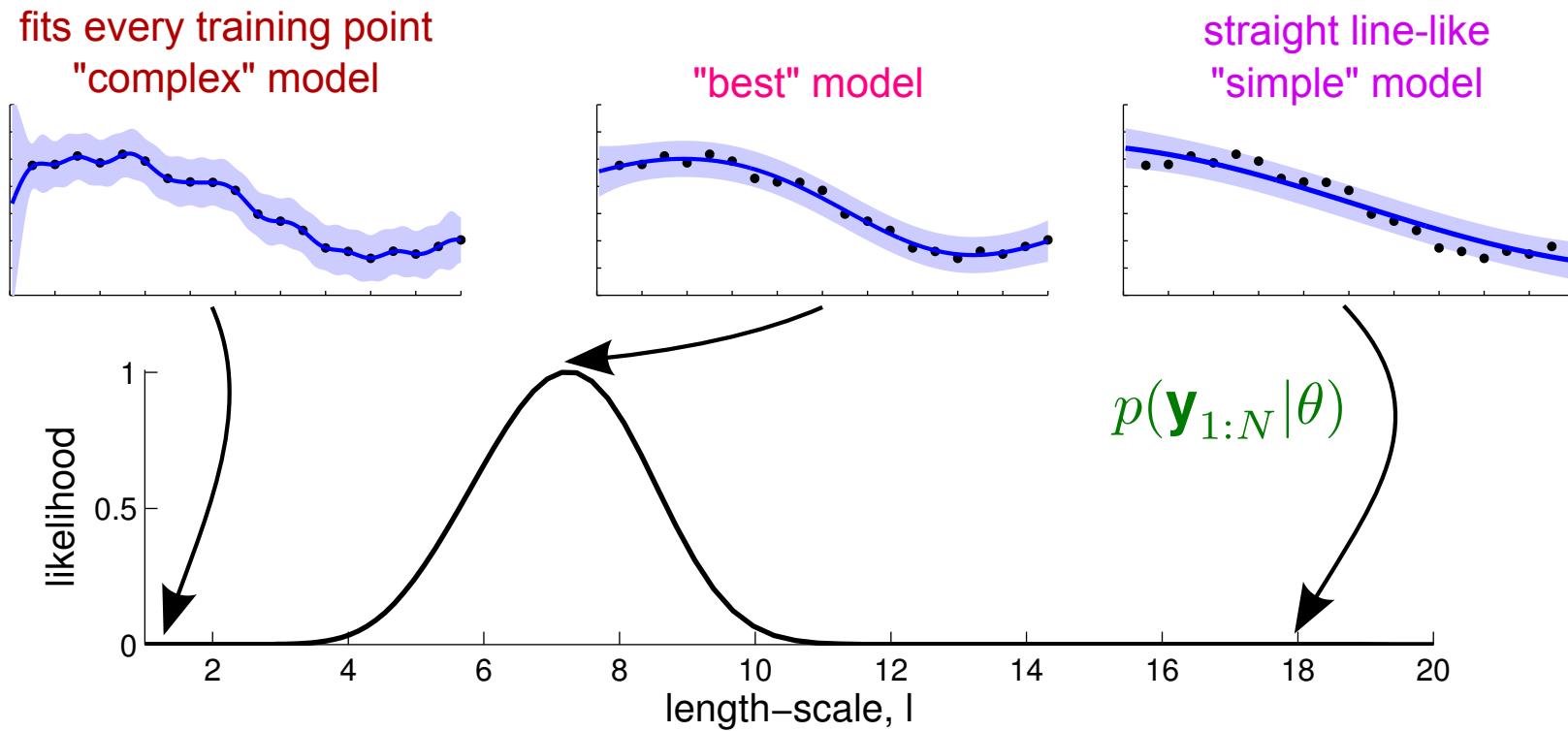
fits every training point
"complex" model



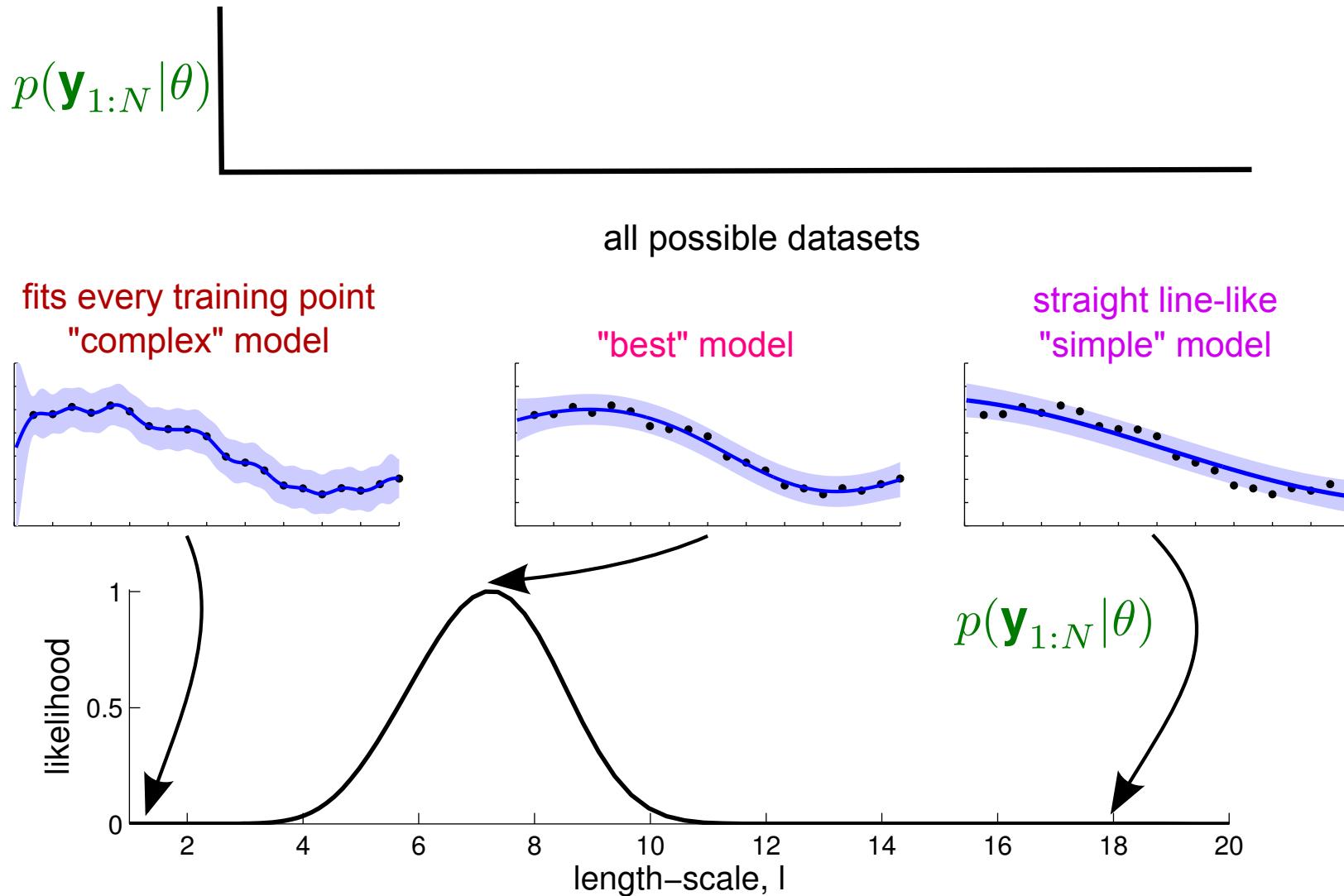
straight line-like
"simple" model



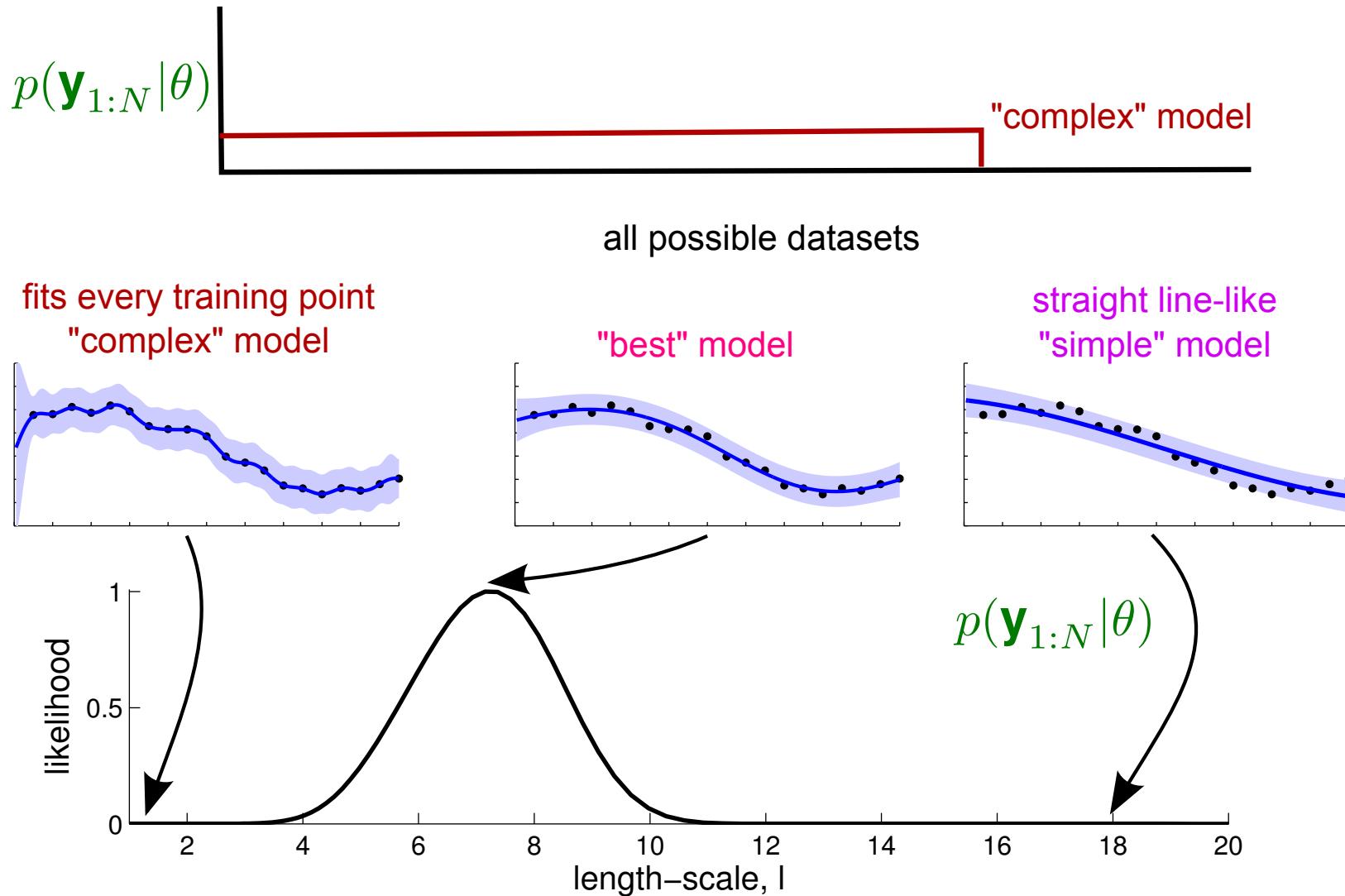
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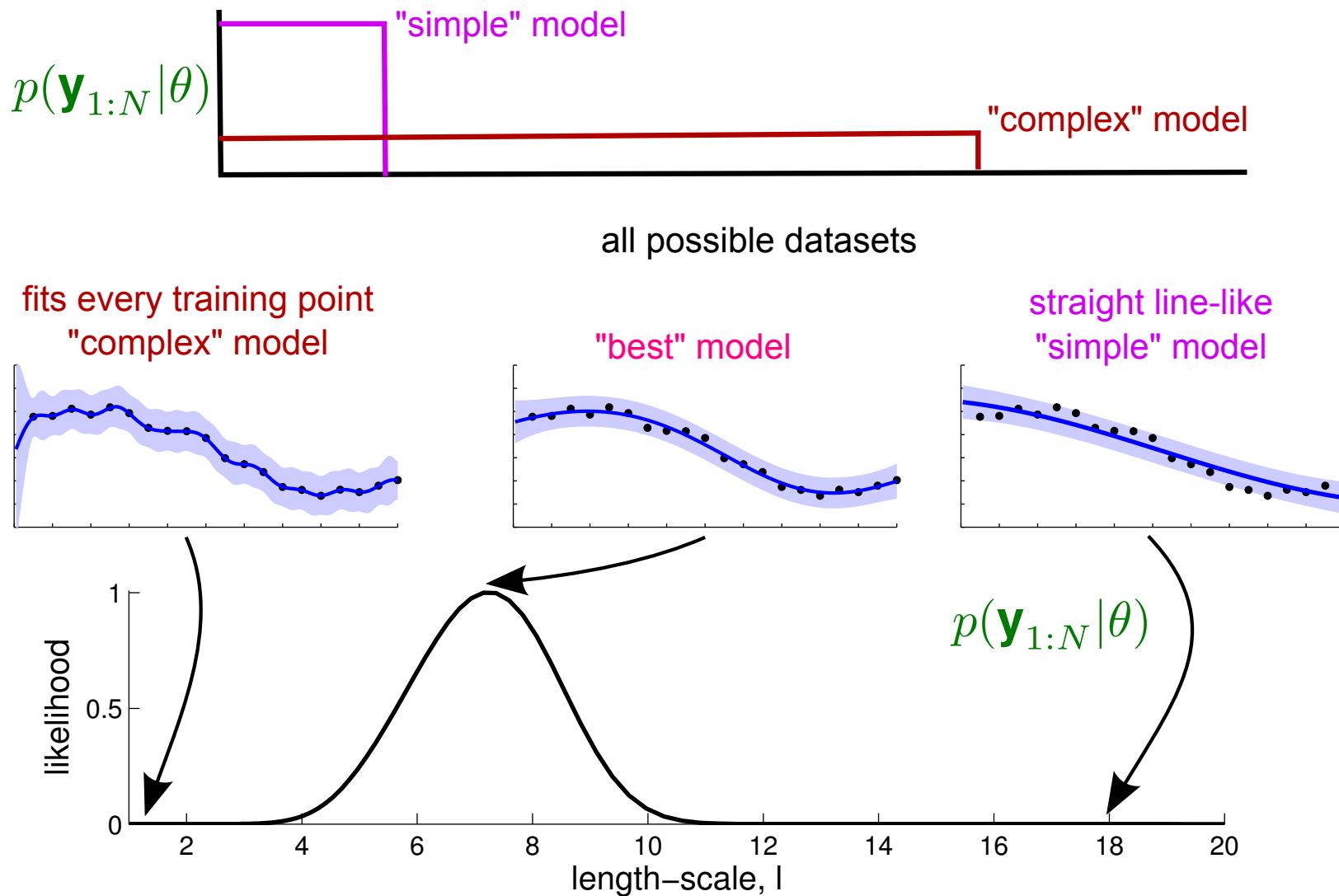
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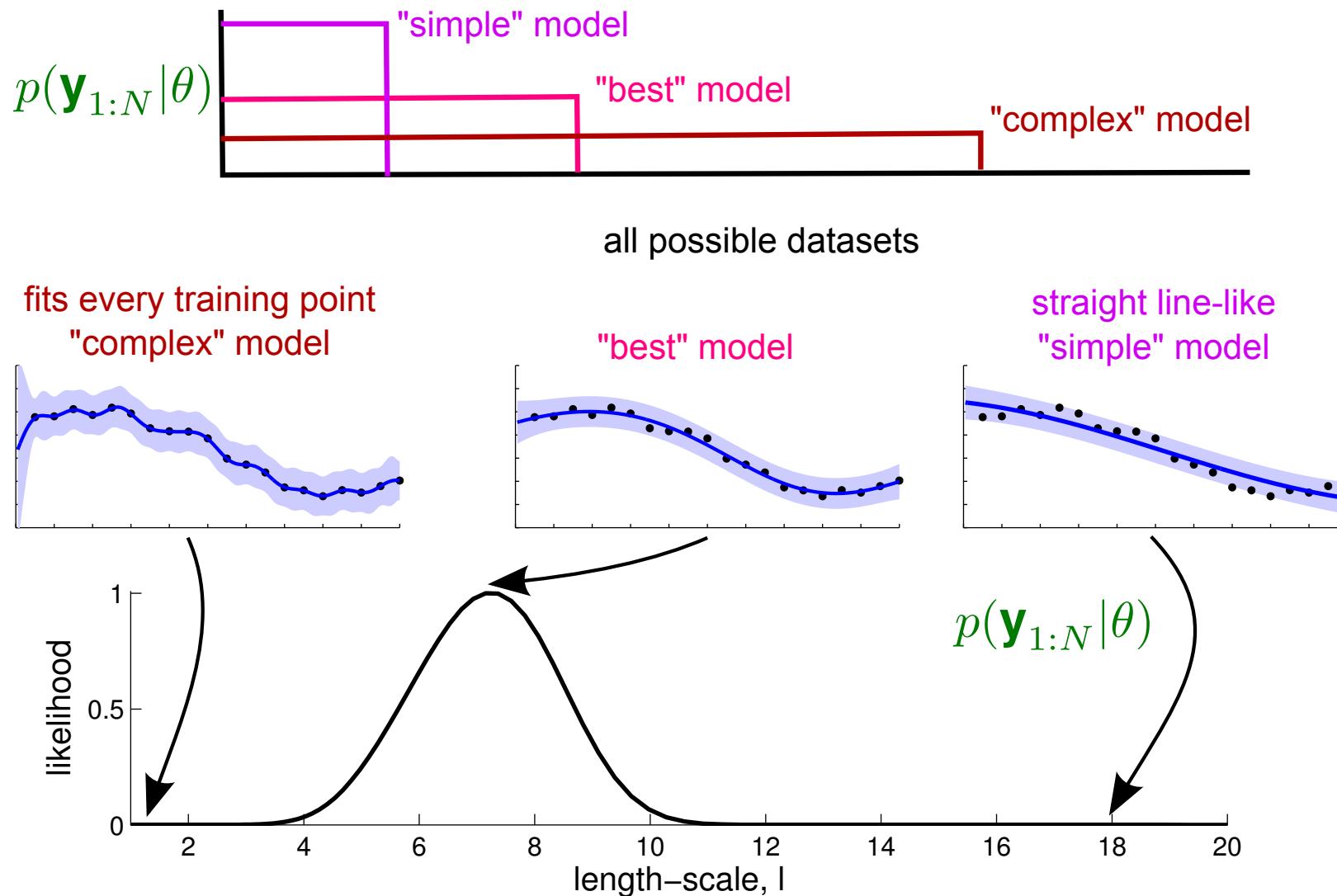
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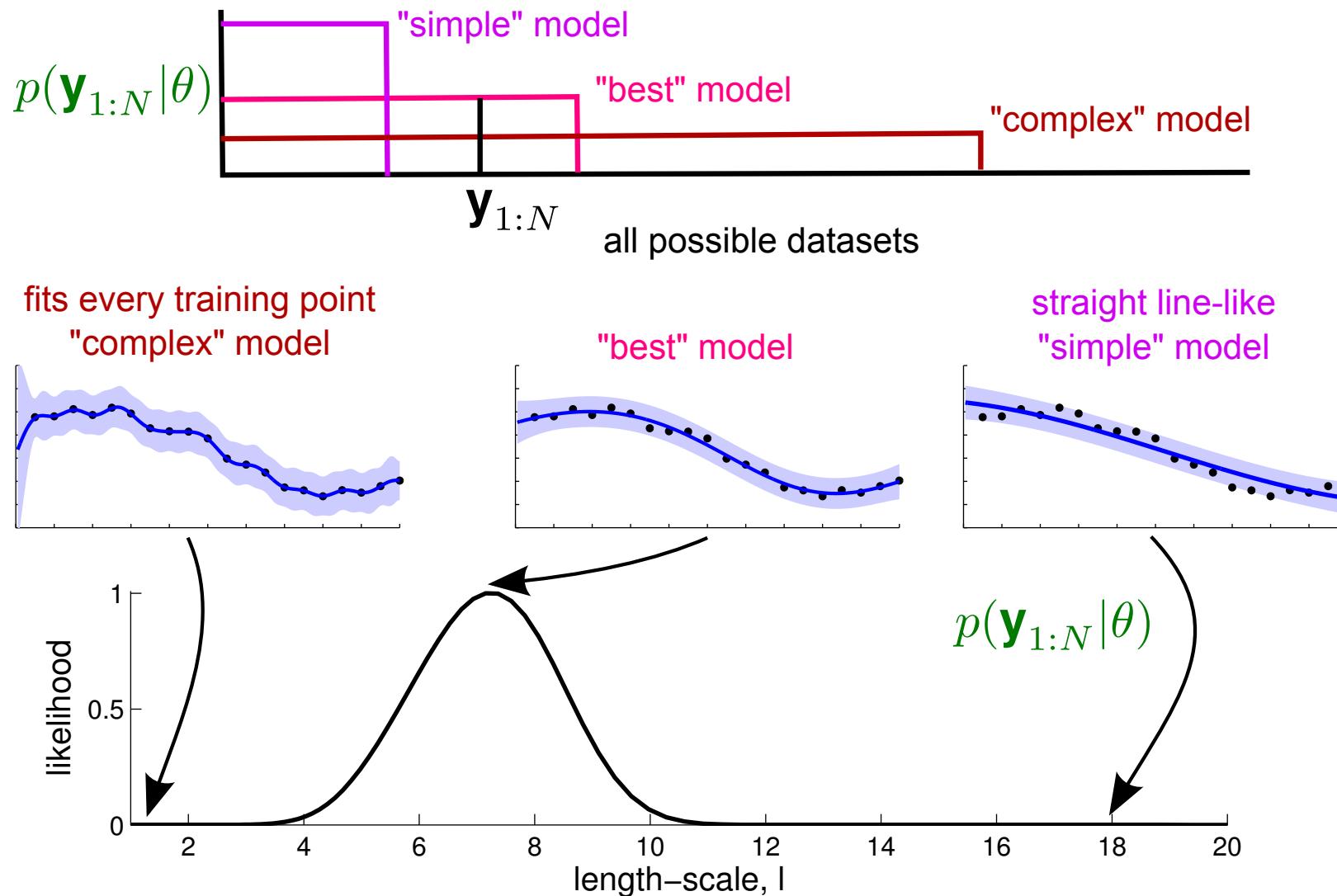
Why does Bayesian inference work?



Why does Bayesian inference work?



Why does Bayesian inference work? Occam's Razor.



Summary

- Gaussian process: **collection of random variables, any finite subset of which are Gaussian distributed**
- Easy to use
 - Predictions correspond to models with infinite numbers of parameters
- GPs have many standard methods as special cases
- Problem: N^3 complexity
 - approximation methods for $N > 2000$ or special covariance functions
- **Great reference:** Rasmussen & Williams www.gaussianprocess.org/

Beyond regression

GPs useful whenever a prior over functions is required

- dimensionality reduction
- time-series models (Kalman filter)
- clustering
- active learning
- reinforcement learning
- ...