

Trajectory prediction

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ABSTRACT

INTRODUCTION

As humans, we make effective predictions of pedestrian trajectories over long time horizons even when novel behavior is present [1], and continually estimate people's underlying goals or intent from subtle motion [2]. If robots are to similarly navigate and interact safely with people, reliable forecasts of human behavior are required [3]. For long-term prediction of pedestrian trajectories, two key challenges are posed for robots to emulate human performance. The first challenge is to reason about human intention given the observation history of pedestrian motion. The second challenge is to build a generative model that captures social norms and takes full advantage of intention information.

1 PROBLEM STATEMENT

Predicting human trajectory is a complex task, human can completely alter their path depending on varying situations (i.e: surroundings, crowded environment, social gathering).

We intend to predict multiple the human trajectories by varying the situation for a given starting point by observing it for some seconds and then predicting the next few seconds.

2 DATA ACQUISITION & PRE-PROCESSING

Make sure to precisely describe what you did and why. The reader of your report should be able to reproduce the steps. Therefore, it is for example not sufficient if you write "we tokenized the sentences". You need to describe how the tokenization was done exactly, i.e. which regular expression or library/method you used with which parameters.

Frameworks/libraries are mentioned in footnotes instead of in the references section. For example "we used the *TweetTokenizer* from the NLTK¹ toolkit with the default parameters to tokenize our tweets".

Reasoning is highly important. It should be obvious to the reader, why you do something in a particular way. The following subsections provide hints on what to include in your report.

(!) required
(*) if it applies to your project

2.1 Data acquisition

- source of data (!)
- means of acquisition (!)

¹<https://www.nltk.org/api/nltk.tokenize.html>

- reasoning (!) (i.e. why you chose that kind of data, that source, why you crawled it in that way, etc.)

As the datasets are mostly pre-defined (i.e. in most of the topics you do not need to acquire the data yourself), this part can be short.

2.2 Data preprocessing

- filtering / grouping / labeling (*)
- lemmatization/stemming (*)
- other (*)
- statistics on the data (!) (e.g. volume, classes, distributions, correlations, etc.)
- reasoning (!)

2.3 Feature engineering

- input x and output y of the system (*)
- feature extraction (*)
- feature transformation (*)
- reasoning (!)

3 MODEL IMPLEMENTATION

3.1 Methodology / Proposed solution / Technique

An in-depth description of your solution to the problem. (e.g. input - output, system description, ML techniques, etc.)

3.2 Experimental Setup

An in-depth description of the experimental design which enables an objective quantification of the quality of your solution. (e.g. dataset, baselines, metrics, etc.). Might be moved to the next section (Phase 4).

4 EVALUATION

4.1 Results

The evaluation of your solution by means of the experiments. Figures and statistics provide hard facts about the quality of your solution from different viewpoints.

4.2 Discussion

So what? How well could we solve the problem? What are the limitations? Open ends.

TEMPLATE INFORMATION (REMOVE THIS SECTION IN YOUR REPORT)

Instructions in the following sections are included from the original ACM template sample file. The article template's documentation,

Table 1: Frequency of Special Characters

Non-English or Math	Frequency	Comments
Ø	1 in 1,000	For Swedish names
π	1 in 5	Common in math
\$	4 in 5	Used in business
Ψ_1^2	1 in 40,000	Unexplained usage

available at <https://www.acm.org/publications/proceedings-template>, has a complete explanation and tips for effective use.

Sectioning Commands

Your work should use standard \LaTeX sectioning commands: `section`, `subsection`, `subsubsection`, and `paragraph`.

Tables

The “acmart” document class includes the “booktabs” package — <https://ctan.org/pkg/booktabs> — for preparing high-quality tables.

Table captions are placed *above* the table.

Because tables cannot be split across pages, the best placement for them is typically the top of the page nearest their initial cite. To ensure this proper “floating” placement of tables, use the environment `table` to enclose the table’s contents and the table caption. The contents of the table itself must go in the `tabular` environment, to be aligned properly in rows and columns, with the desired horizontal and vertical rules. Again, detailed instructions on `tabular` material are found in the *\LaTeX User’s Guide*.

Immediately following this sentence is the point at which Table 1 is included in the input file; compare the placement of the table here with the table in the printed output of this document.

To set a wider table, which takes up the whole width of the page’s live area, use the environment `table*` to enclose the table’s contents and the table caption. As with a single-column table, this wide table will “float” to a location deemed more desirable. Immediately following this sentence is the point at which Table 2 is included in the input file; again, it is instructive to compare the placement of the table here with the table in the printed output of this document.

Math Equations

You may want to display math equations in three distinct styles: inline, numbered or non-numbered display. Each of the three are discussed in the next sections.

Inline (In-text) Equations. A formula that appears in the running text is called an inline or in-text formula. It is produced by the `math` environment, which can be invoked with the usual `\begin . . . \end` construction or with the short form `$. . . $`. You can use any of the symbols and structures, from α to ω , available in \LaTeX [?]; this section will simply show a few examples of in-text equations in context. Notice how this equation: $\lim_{n \rightarrow \infty} x = 0$, set here in in-line math style, looks slightly different when set in display style. (See next section).

Display Equations. A numbered display equation—one set off by vertical space from the text and centered horizontally—is produced

by the `equation` environment. An unnumbered display equation is produced by the `displaymath` environment.

Again, in either environment, you can use any of the symbols and structures available in \LaTeX ; this section will just give a couple of examples of display equations in context. First, consider the equation, shown as an inline equation above:

$$\lim_{n \rightarrow \infty} x = 0 \quad (1)$$

Notice how it is formatted somewhat differently in the `displaymath` environment. Now, we’ll enter an unnumbered equation:

$$\sum_{i=0}^{\infty} x + 1$$

and follow it with another numbered equation:

$$\sum_{i=0}^{\infty} x_i = \int_0^{\pi+2} f \quad (2)$$

just to demonstrate \LaTeX ’s able handling of numbering.

Figures

The “figure” environment should be used for figures. One or more images can be placed within a figure. If your figure contains third-party material, you must clearly identify it as such, as shown in the example below.



Figure 1: 1907 Franklin Model D roadster. Photograph by Harris & Ewing, Inc. [Public domain], via Wikimedia Commons. (<https://goo.gl/VLCRBB>).

Your figures should contain a caption which describes the figure to the reader. Figure captions are placed *below* the figure.

Citations and Bibliographies

The use of *BibTeX* for the preparation and formatting of one’s references is strongly recommended. Authors’ names should be complete — use full first names (“Donald E. Knuth”) not initials (“D. E. Knuth”) — and the salient identifying features of a reference

Table 2: Some Typical Commands

Command	A Number	Comments
<code>\author</code>	100	Author
<code>\table</code>	300	For tables
<code>\table*</code>	400	For wider tables

should be included: title, year, volume, number, pages, article DOI, etc.

The bibliography is included in your source document with these two commands, placed just before the `\end{document}` command:

```
\bibliographystyle{ACM-Reference-Format}
\bibliography{bibfile}
```

where “bibfile” is the name, without the “.bib” suffix, of the *BibTeX* file.

Some examples. A paginated journal article [?], an enumerated journal article [?], a reference to an entire issue [?], a monograph (whole book) [?], a monograph/whole book in a series (see 2a in spec. document) [?], a divisible-book such as an anthology or compilation [?] followed by the same example, however we only output the series if the volume number is given [?] (so Editor00a’s series should NOT be present since it has no vol. no.), a chapter in a divisible book [?], a chapter in a divisible book in a series [?], a multi-volume work as book [?], an article in a proceedings (of a conference, symposium, workshop for example) (paginated proceedings article) [?], a proceedings article with all possible elements [?], an example of an enumerated proceedings article [?], an informally published work [?], a doctoral dissertation [?], a master’s thesis: [?], an online document / world wide web resource [? ? ?], a video game (Case 1) [?] and (Case 2) [?] and [?] and (Case 3) a patent [?], work accepted for publication [?], ‘YYYYb’-test for prolific author [?] and [?]. Other cites might contain ‘duplicate’ DOI and URLs (some SIAM articles) [?]. Boris / Barbara Beeton: multi-volume works as books [?] and [?]. A couple of citations with DOIs: [? ?]. Online citations: [? ? ?].

Appendices

If your work needs an appendix, add it before the “`\end{document}`” command at the conclusion of your source document.

Start the appendix with the “`appendix`” command:

```
\appendix
```

and note that in the appendix, sections are lettered, not numbered. This document has two appendices, demonstrating the section and subsection identification method.

REFERENCES

- [1] Dare Baldwin and Jodie Baird. 2001. Discerning intentions in dynamic human action. *Trends in Cognitive Sciences* 5 (05 2001), 171–178. [https://doi.org/10.1016/S1364-6613\(00\)01615-6](https://doi.org/10.1016/S1364-6613(00)01615-6)
- [2] Randolph Blake and Maggie Shiffrar. 2007. Perception of Human Motion. *Annual Review of Psychology* 58, 1 (2007), 47–73. <https://doi.org/10.1146/annurev.psych.57.102904.190152> arXiv:<https://doi.org/10.1146/annurev.psych.57.102904.190152> PMID: 16903802.
- [3] Andrey Rudenko, Luigi Palmieri, Michael Herman, Kris M. Kitani, Dariu M. Gavrilă, and Kai Oliver Arras. 2019. Human Motion Trajectory Prediction: A Survey. *CoRR* abs/1905.06113 (2019). arXiv:1905.06113 <http://arxiv.org/abs/1905.06113>

A RESEARCH METHODS (REMOVE IF NOT USED)

A.1 Part One

Lorem ipsum dolor sit amet, consectetur adipiscing elit. Morbi malesuada, quam in pulvinar varius, metus nunc fermentum urna, id sollicitudin purus odio sit amet enim. Aliquam ullamcorper eu ipsum vel mollis. Curabitur quis dictum nisl. Phasellus vel semper risus, et lacinia dolor. Integer ultricies commodo sem nec semper.

A.2 Part Two

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B ONLINE RESOURCES

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