view\_frames Result Recorded at time: 103.330 odom Broadcaster: /gazebo Average rate: 10.204 Hz Most recent transform: 103.300 ( 0.030 sec old) Buffer length: 4.900 sec base\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (103.330 sec old) Most recent transform: 0.000 (103.330 sec old) Most recent transform: 0.000 (103.330 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec chassis hokuyo\_laser\_link imu\_sensor\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (103.330 sec old) Most recent transform: 0.000 (103.330 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec left\_axis right\_axis Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10.225 Hz Average rate: 10.225 Hz Most recent transform: 103.300 (0.030 sec old) Most recent transform: 103.300 (0.030 sec old) Buffer length: 4.890 sec Buffer length: 4.890 sec left\_wheel\_link

right\_wheel\_link