

Variance Components Estimation

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Linear Mixed Effect model

- > model selection ==> determination of fixed effects in the model**
- > variance components ==> random effect (breeding values and error)**
- > variance components estimation tells us how phenotypic variation is partitioned among the random effects**

Genetic Variation

New trait: calf survival, mastitis resistance

Observe: phenotypic observation

In order to use a new trait in the breeding goal the variation of the phenotypic observations must in part be due to a genetic component

- ▶ Requirement for trait to be considered in breeding goal
- ▶ Breeding means improvement of next generation via selection and mating
- ▶ Only genetic (additive) components are passed to offspring
- ▶ Selection should be based on genetic component of trait
- ▶ Selection only possible with genetic variation

→ genetic variation indicates how good characteristics are passed from parents to offspring

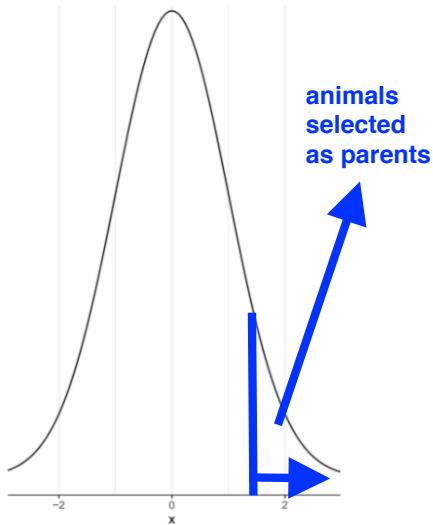
→ measured by **heritability** $h^2 = \frac{\sigma_a^2}{\sigma_p^2}$

Two Traits

no variation

cannot do any
selection of animals
as parents

with variation



Problems

- ▶ Genetic components cannot be observed or measured
- ▶ Must be estimated from data
- ▶ Data are mostly phenotypic

→ topic of variance components estimation

- ▶ Model based, that means connection between phenotypic measure and genetic component are based on certain model

$$p = g + e$$

with $\text{cov}(g, e) = 0$

- ▶ **Goal:** separate variation due to g (σ_a^2) from phenotypic variation

Example of Variance Components Separation

Simple dataset with repeated measurements of the same trait

Animal | Measurement 1 | Measurement 2 | Measurement 3

=====

1 | y_{11} | y_{12} | y_{13}

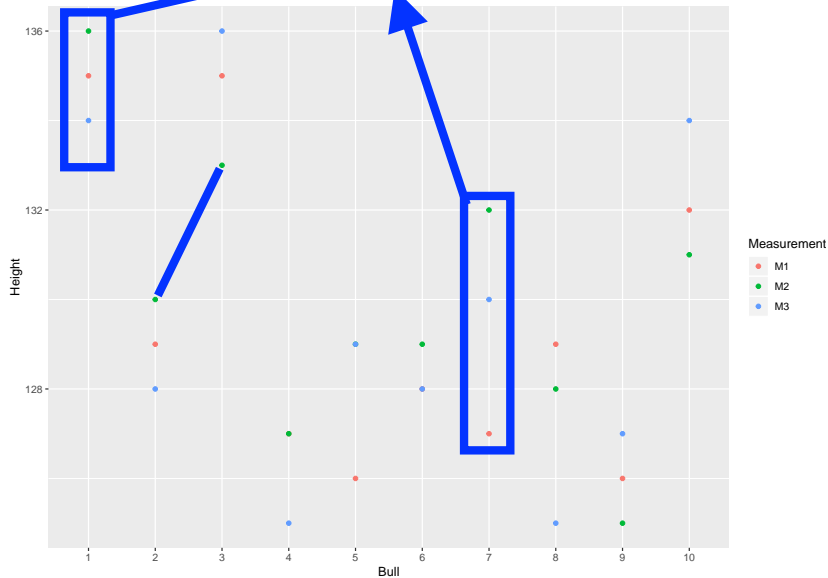
2

3

- ▶ Estimation of repeatability
- ▶ Given repeated measurements of same trait at the same animal
- ▶ Repeatability means variation of measurements at the same animal is smaller than variation between measurements at different animals

Repeatability Plot


Variation between measurements for the same animal



Model

phenotypic observation y_{ij} : height of the bull

effect that is the same for a given bull i


$$y_{ij} = \mu + t_i + \epsilon_{ij}$$

where


y_{ij} measurement j of animal i

μ expected value of y

t_i deviation of y_{ij} from μ attributed to animal i

ϵ_{ij} measurement error

Estimation Of Variance Components

- ▶ $E(t_i) = 0$  **because t_i was defined as deviation from μ**
- ▶ $\sigma_t^2 = E(t_i^2)$: variance component of total variance (σ_y^2) which can be attributed to the t -effects
- ▶ $E(\epsilon_{ij}) = 0$
- ▶ $\sigma_\epsilon^2 = E(\epsilon_{ij}^2)$: variance component attributed to ϵ -effects
- ▶ $\sigma_y^2 = \sigma_t^2 + \sigma_\epsilon^2$ **i.e., there are not covariances between t and errors**
- ▶ Repeatability w defined as:

$$w = \frac{\sigma_t^2}{\sigma_t^2 + \sigma_\epsilon^2}$$

if w is high, then repeated measurements of the same trait do not give us additional information

→ estimate of σ_t^2 needed

Analysis Of Variance (ANOVA)

ANOVA - table

| Effect | df | Sum Sq | Mean Sq | $E(\text{Mean Sq})$ |
|-------------------------|---------|-----------------|-------------------------|--|
| Bull (t) | $r - 1$ | $SSQ(t)$ | $SSQ(t)/(r - 1)$ | $\sigma_{\epsilon}^2 + n * \sigma_t^2$ |
| Residual (ϵ) | $N - r$ | $SSQ(\epsilon)$ | $SSQ(\epsilon)/(N - r)$ | σ_{ϵ}^2 |

where

SSQ: Sum of squares

**(sum of all observation)²
with N = total number of observations**

$$SSQ(t) = \left[\frac{1}{n} \sum_{i=1}^r \left(\sum_{j=1}^n y_{ij} \right)^2 \right] - \left(\sum_{i=1}^r \sum_{j=1}^n y_{ij} \right)^2 / N$$

**for each effect
in the model,
there is one row
in the anova-table**

**sum of heights
for bull i**

$$SSQ(\epsilon) = \sum_{i=1}^r \sum_{j=1}^n y_{ij}^2 - \left[\frac{1}{n} \sum_{i=1}^r \left(\sum_{j=1}^n y_{ij} \right)^2 \right]$$

**sum of squared observations where r is the number of bulls
and n is the number of measurements per bull**

Zahlenbeispiel

SSQ

ANOVA-Table obtained by R, aov()
lm.fit <- lm(height ~ bull, data = ...)
a <- aov(lm.fit);summary(a)

| | Df | Sum Sq | Mean Sq | F value | Pr(>F) |
|-------------------|----|--------|---------|---------|--|
| ## Bull | 9 | 286.7 | 31.85 | 13.85 | 8.74e-07 *** |
| ## Residuals | 20 | 46.0 | 2.30 | | |
| ## --- | | | | | |
| ## Signif. codes: | | | | | 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1 |

Setting expected values of Mean Sq equal to estimates of variance components

Computed values for the Mean Sq are set equal to the estimates of the variance components $\Rightarrow \hat{\sigma}_{\epsilon}^2 = \text{Mean Sq}(\text{error})$

$$\hat{\sigma}_{\epsilon}^2 = 2.3 \text{ and } \hat{\sigma}_t^2 = \frac{31.85 - 2.3}{3} = 9.85$$

Repeatability

$$\hat{w} = \frac{\hat{\sigma}_t^2}{\hat{\sigma}_t^2 + \hat{\sigma}_{\epsilon}^2} = 0.81$$

Same Strategy for Sire Model

Principle of sire model

- * Observations are from daughters of different sires
- * Comparable to the previous data set

- Sire model is a mixed linear effects model with sire effects s as random components

$$y = Xb + Zs + e$$

- In case where sires are not related, $\text{var}(s) = I * \sigma_s^2$
- From σ_s^2 , we get genetic additive variance as $\sigma_a^2 = 4 * \sigma_s^2$

ANOVA

| Effect | Degrees of Freedom | Sum Sq | Mean Sq | $E(\text{Mean Sq})$ |
|------------------|--------------------|------------|--------------------|-------------------------------|
| Sire ($s b$) | $r - 1$ | $SSQ(s b)$ | $SSQ(s b)/(r - 1)$ | $\sigma_e^2 + k * \sigma_s^2$ |
| Residual (e) | $N - r$ | $SSQ(e)$ | $SSQ(e)/(N - r)$ | σ_e^2 |

with

$$k = \frac{1}{r - 1} \left[N - \frac{\sum_{i=1}^r n_i^2}{N} \right]$$

r: number of sires

n_i: the number of daughters for sire i

N: total number of observations

Problem: estimates of sire variance might get negative, because it is computed as a difference between $\text{MeanSq}(\text{sire}) - \text{MeanSq}(\text{Residual}) / \dots$

Maximum Likelihood (ML)

We are forced to make an assumption of the distribution of the data



- Likelihood is defined as the conditional density of the the data (y) given the model parameters (θ)

$$L(\theta) = f(y|\theta)$$

- Normal distribution

Assumed model: $y = Xb + e$

$$L(\theta) = (2\pi)^{-1/2n} \sigma^{-n} |H|^{-1/2} * \exp \left\{ -\frac{1}{2\sigma^2} (y - Xb)^T H^{-1} (y - Xb) \right\}$$

Goal: Estimate the residual variance



with $\text{var}(y) = H * \sigma^2$ and $\theta^T = \begin{bmatrix} b & \sigma^2 \end{bmatrix}$

Maximization of Likelihood

Principle of ML: Find the values of the parameters (b , residual variance) that maximize the value of the Likelihood function. The values for the unknown parameters that maximize the likelihood function are then used as Maximum-Likelihood estimates.

- ▶ Set $\lambda = \log L$  to make computations easier
- ▶ Compute partial derivatives of λ with respect to all unknowns

$$\frac{\partial \lambda}{\partial b}$$

= 0

$$\frac{\partial \lambda}{\partial \sigma^2}$$

= 0


 produce estimates for
 b and residual variance

- ▶ Set partial derivatives to 0 and solve for unknowns
- ▶ Use solutions as estimates

Restricted Maximum Likelihood (REML)

- ▶ Problem with ML: estimate of σ^2 depends on $b \rightarrow$ undesirable
- ▶ Do transformations Sy and Qy
 - (i) The matrix S has rank $n - t$ and the matrix Q has rank t
 - (ii) The result of the two transformations are independent, that means $\text{cov}(Sy, Qy) = 0$ which is met when $SHQ^T = 0$
 - (iii) The matrix S is chosen such that $E(Sy) = 0$ which means $SX = 0$
 - (iv) The matrix QX is of rank t , so that every linear function of the elements of Qy estimate a linear function of b .

REML II

- ▶ From (i) and (ii) it follows that the likelihood L of y is the product of the likelihoods of Sy (L^*) and Qy (L^{**}) that means

L^* is the likelihood based on Sy
 L^{**} is the likelihood based on Qy

$$\lambda = \lambda^* + \lambda^{**}$$

- ▶ Variance components are estimated from λ^* which will then be independent of b



$\log L^*$

$\log L^{**}$

Bayesian Estimation

The estimation procedures so far (ANOVA, ML and REML) were all frequentist approaches

- ▶ Proposed already in the 80's
- ▶ Full implementation only in 1993
- ▶ Requirements:
 - ▶ cheap computing and
 - ▶ good pseudo-random number generators
- ▶ Bayesian estimation is based on conditional posterior distribution of unknowns given the knowns
- ▶ Conditional posterior distribution is computed from prior distribution of unknowns times the likelihood

Model

- Univariate Gaussian linear mixed model

$$y = Xb + Zu + e$$

where

- y vector of observations (length n)
- b vector of fixed effects (length p)
- u vector of random breeding values (length q)
- e vector of random residuals (length n)
- X $n \times p$ design matrix linking fixed effects to observations
- Z $n \times q$ design matrix linking breeding values to observations

Likelihood

- Data generating distribution

$$y|b, u, \sigma_e^2 \sim \mathcal{N}(Xb + Zu, I * \sigma_e^2)$$

where I is a $n \times n$ identity matrix and σ_e^2 is the variance of the random residuals.

Priors


- ▶ Prior distributions must be specified for all unknowns
- ▶ Unknowns in our example are: b, u, σ_e^2 and σ_u^2
- ▶ Prior distribution for
 - ▶ b is flat, i.e. $p(b) \propto c$
 - ▶ u Normal distribution as $u|G, \sigma_u^2 \sim N(0, G * \sigma_u^2)$
 - ▶ σ_e^2 scaled inverse χ^2 :
$$p(\sigma_e^2|\nu_e, s_e^2) \propto (\sigma_e^2)^{-\nu_e/2-1} \exp(-\frac{1}{2}\nu_e s_e^2 / \sigma_e^2)$$
 - ▶ σ_u^2 : $p(\sigma_u^2|\nu_u, s_u^2) \propto (\sigma_u^2)^{-\nu_u/2-1} \exp(-\frac{1}{2}\nu_u s_u^2 / \sigma_u^2)$
- ▶ ν_e, ν_s, s_e^2 and s_u^2 are called hyper-parameters and must be determined

Additional Terms

- Let

$$\theta^T = (b^T, u^T) = (\theta_1, \theta_2, \dots, \theta_N)$$

vector θ except the
i-th component

$$\theta_{-i} = (\theta_1, \theta_2, \dots, \theta_{i-1}, \theta_{i+1}, \dots, \theta_N)$$


- Further, let

$$s^T = (s_u^2, s_e^2)$$

and

$$\nu^T = (\nu_u, \nu_e)$$

Joint Posterior Density

The joint posterior distribution can be written as

$$p(\theta, \sigma_u^2, \sigma_e^2 | y, s, \nu) \propto \underbrace{p(\theta) * p(\sigma_u^2 | \nu_u, s_u^2) * p(\sigma_e^2 | \nu_e, s_e^2)}_{\text{prior distributions that were specified for all the unknowns}} * \underbrace{p(y | \theta, \sigma_e^2)}_{\text{likelihood}}$$

Proportional to ...

The diagram illustrates the decomposition of the joint posterior density. A red arrow points from the proportionality symbol (\propto) to the text "Proportional to ...". A blue arrow points from the bracketed prior term to the text "prior distributions that were specified for all the unknowns". A red arrow points from the bracketed likelihood term to the text "likelihood".

Fully Conditional Posterior Densities of θ

- Density of every single unknown component when setting all other components as known

$$\theta_i | y, \theta_{-i}, \sigma_u^2, \sigma_e^2, s, \nu \sim \mathcal{N}(\tilde{\theta}_i, \tilde{v}_i)$$

where $\tilde{\theta}_i = (r_i - \sum_{j=1, j \neq i}^N w_{ij} \theta_j) / w_{ii}$ and $\tilde{v}_i = \sigma_e^2 / w_{ii}$.

- vector r is the vector of right-hand side of MME
- matrix W is the coefficient matrix of MME

Fully Conditional Posterior Densities of σ_e^2

- ▶ scaled inverted chi-square distribution for σ_e^2

$$\sigma_e^2 | y, \theta, \sigma_u^2, s, \nu \sim \tilde{\nu}_e \tilde{s}_e^2 \chi_{\tilde{\nu}_e}^{-2}$$

- ▶ Parameters of the above distribution are defined as

$$\tilde{\nu}_e = n + \nu_e$$

and

$$\tilde{s}_e^2 = \left[(y - Xb - Zu)^T (y - Xb - Zu) + \nu_e s_e^2 \right] / \tilde{\nu}_e$$

Fully Conditional Posterior Densities of σ_u^2

- ▶ scaled inverted chi-square distribution for σ_u^2

$$\sigma_u^2 | y, \theta, \sigma_e^2, s, \nu \sim \tilde{\nu}_u \tilde{s}_u^2 \chi_{\tilde{\nu}_u}^{-2}$$

- ▶ Parameters of the above distribution are defined as

$$\tilde{\nu}_u = q + \nu_u$$

and

$$\tilde{s}_u^2 = \left[u^T G^{-1} u + \nu_u s_u^2 \right] / \tilde{\nu}_u$$

Implementation

for fixed effects and breeding values initial values are set to = 0

variance components can be initialised by half of the phenotypic variance

- ▶ Step 1: set starting values for θ , σ_e^2 and σ_u^2
- ▶ Step 2: draw random number for each component θ_i of θ from fully conditional distribution $\mathcal{N}(\tilde{\theta}_i, \tilde{v}_i)$ in R : `rnorm(1, mean = , sd =)`
- ▶ Step 3: draw random number for σ_e^2 from $\tilde{\nu}_e \tilde{s}_e^2 \chi_{\tilde{\nu}_e}^{-2}$
- ▶ Step 4: draw random number for σ_u^2 from $\tilde{\nu}_u \tilde{s}_u^2 \chi_{\tilde{\nu}_u}^{-2}$
- ▶ Repeat steps 2-4 many times and store random numbers
- ▶ Step 5: compute means of random numbers to get Bayesian estimates of unknowns θ , σ_e^2 and σ_u^2

Practical consideration

- * despite their ease of use, they are not commonly used
- * reason: there is no reliable software around