Definition of a generalized hourse . Given any matrix A, a generalized inverse (6) is the matrix that satisfies A.G.A = A (=) (A.G.A) = A [Recall : the invesse A was oblined as A" A = I ; A A = I $A \cdot A^{1} \cdot A = A$ I Why is generalize inverse (G) useful for us? a Given a system of equations; A.b=I the vector b=G.r is a solution, if G is a generalized werse of A. So G is defined such that A.G.A=A, the solutions are given by b=G.r) pre-multiply with A A.6 = A.G. T [A. b = A. G. A.5 => A = AGA only true if A