

# Variance Components Estimation

Peter von Rohr

26.04.2021

# Genetic Variation

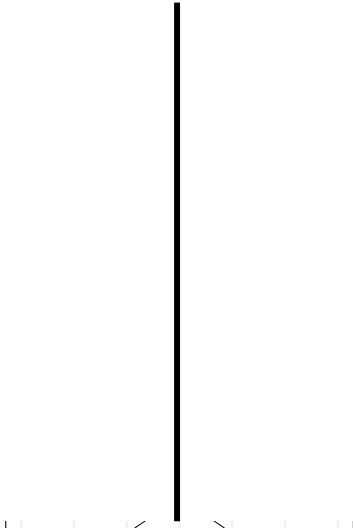
- ▶ Requirement for trait to be considered in breeding goal
- ▶ Breeding means improvement of next generation via selection and mating
- ▶ Only genetic (additive) components are passed to offspring
- ▶ Selection should be based on genetic component of trait
- ▶ Selection only possible with genetic variation

→ genetic variation indicates how good characteristics are passed from parents to offspring

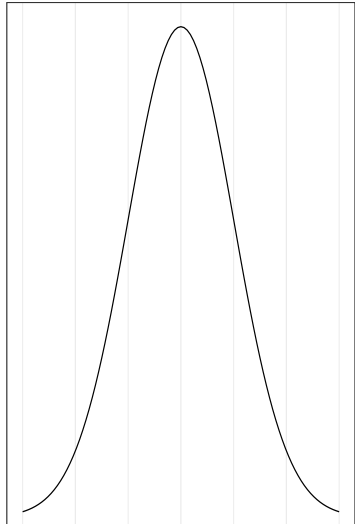
→ measured by **heritability**  $h^2 = \frac{\sigma_a^2}{\sigma_p^2}$

# Two Traits

no variation



with variation



# Problems

- ▶ Genetic components cannot be observed or measured
- ▶ Must be estimated from data
- ▶ Data are mostly phenotypic

→ topic of variance components estimation

- ▶ Model based, that means connection between phenotypic measure and genetic component are based on certain model

$$p = g + e$$

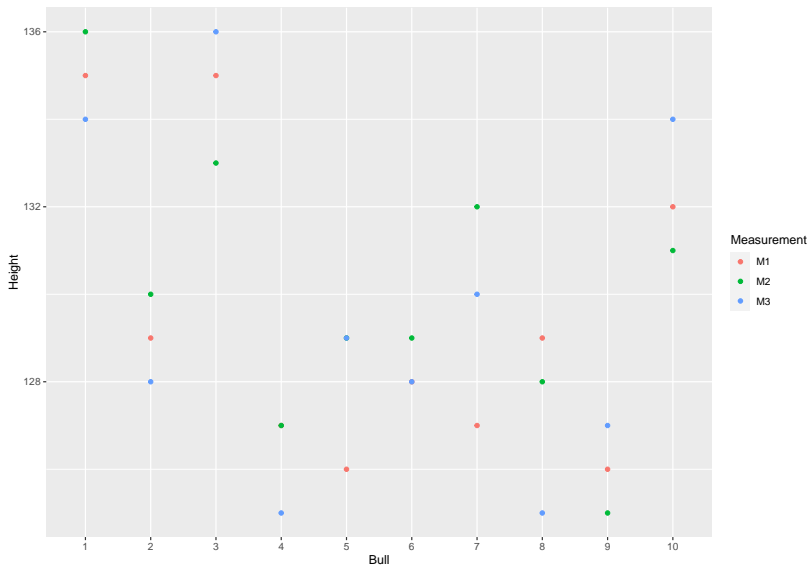
with  $\text{cov}(g, e) = 0$

- ▶ **Goal:** separate variation due to  $g$  ( $\sigma_a^2$ ) from phenotypic variation

## Example of Variance Components Separation

- ▶ Estimation of repeatability
- ▶ Given repeated measurements of same trait at the same animal
- ▶ Repeatability means variation of measurements at the same animal is smaller than variation between measurements at different animals

# Repeatability Plot



# Model

$$y_{ij} = \mu + t_i + \epsilon_{ij}$$

where

- $y_{ij}$  measurement  $j$  of animal  $i$
- $\mu$  expected value of  $y$
- $t_i$  deviation of  $y_{ij}$  from  $\mu$  attributed to animal  $i$
- $\epsilon_{ij}$  measurement error

# Estimation Of Variance Components

- ▶  $E(t_i) = 0$
- ▶  $\sigma_t^2 = E(t_i^2)$ : variance component of total variance ( $\sigma_y^2$ ) which can be attributed to the  $t$ -effects
- ▶  $E(\epsilon_{ij}) = 0$
- ▶  $\sigma_\epsilon^2 = E(\epsilon_{ij}^2)$ : variance component attributed to  $\epsilon$ -effects
- ▶  $\sigma_y^2 = \sigma_t^2 + \sigma_\epsilon^2$
- ▶ Repeatability  $w$  defined as:

$$w = \frac{\sigma_t^2}{\sigma_t^2 + \sigma_\epsilon^2}$$

→ estimate of  $\sigma_t^2$  needed



# Analysis Of Variance (ANOVA)

Effect	df	Sum Sq	Mean Sq	$E(\text{Mean Sq})$
Bull ( $t$ )	$r - 1$	$SSQ(t)$	$SSQ(t)/(r - 1)$	$\sigma_{\epsilon}^2 + n * \sigma_t^2$
Residual ( $\epsilon$ )	$N - r$	$SSQ(\epsilon)$	$SSQ(\epsilon)/(N - r)$	$\sigma_{\epsilon}^2$

where

$$SSQ(t) = \left[ \frac{1}{n} \sum_{i=1}^r \left( \sum_{j=1}^n y_{ij} \right)^2 \right] - \left( \sum_{i=1}^r \sum_{j=1}^n y_{ij} \right)^2 / N$$

$$SSQ(\epsilon) = \sum_{i=1}^r \sum_{j=1}^n y_{ij}^2 - \left[ \frac{1}{n} \sum_{i=1}^r \left( \sum_{j=1}^n y_{ij} \right)^2 \right]$$

# Zahlenbeispiel

```
##              Df Sum Sq Mean Sq F value    Pr(>F)
## Bull          9  286.7    31.85    13.85 8.74e-07 ***
## Residuals     20   46.0     2.30
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

Setting expected values of Mean Sq equal to estimates of variance components

$$\hat{\sigma}_{\epsilon}^2 = 2.3 \text{ and } \hat{\sigma}_t^2 = \frac{31.85 - 2.3}{3} = 9.85$$

Repeatability

$$\hat{w} = \frac{\hat{\sigma}_t^2}{\hat{\sigma}_t^2 + \hat{\sigma}_{\epsilon}^2} = 0.81$$

## Same Strategy for Sire Model

- ▶ Sire model is a mixed linear effects model with sire effects  $s$  as random components

$$y = Xb + Zs + e$$

- ▶ In case where sires are not related,  $\text{var}(s) = I * \sigma_s^2$
- ▶ From  $\sigma_s^2$ , we get genetic additive variance as  $\sigma_a^2 = 4 * \sigma_s^2$

# ANOVA

Effect	Degrees of Freedom	Sum Sq	Mean Sq	$E(\text{Mean Sq})$
Sire ( $s b$ )	$r - 1$	$SSQ(s b)$	$SSQ(s b)/(r - 1)$	$\sigma_e^2 + k * \sigma_s^2$
Residual ( $e$ )	$N - r$	$SSQ(e)$	$SSQ(e)/(N - r)$	$\sigma_e^2$

with

$$k = \frac{1}{r - 1} \left[ N - \frac{\sum_{i=1}^r n_i^2}{N} \right]$$

# Maximum Likelihood (ML)

- Likelihood

$$L(\theta) = f(y|\theta)$$

- Normal distribution

$$L(\theta) = (2\pi)^{-1/2n} \sigma^{-n} |H|^{-1/2} * \exp \left\{ -\frac{1}{2\sigma^2} (y - Xb)^T H^{-1} (y - Xb) \right\}$$

with  $\text{var}(y) = H * \sigma^2$  and  $\theta^T = \begin{bmatrix} b & \sigma^2 \end{bmatrix}$

# Maximization of Likelihood

- ▶ Set  $\lambda = \log L$
- ▶ Compute partial derivatives of  $\lambda$  with respect to all unknowns

$$\frac{\partial \lambda}{\partial b}$$

$$\frac{\partial \lambda}{\partial \sigma^2}$$

- ▶ Set partial derivatives to 0 and solve for unknowns
- ▶ Use solutions as estimates

# Restricted Maximum Likelihood (REML)

- ▶ Problem with ML: estimate of  $\sigma^2$  depends on  $b \rightarrow$  undesirable
- ▶ Do transformations  $Sy$  and  $Qy$ 
  - (i) The matrix  $S$  has rank  $n - t$  and the matrix  $Q$  has rank  $t$
  - (ii) The result of the two transformations are independent, that means  $\text{cov}(Sy, Qy) = 0$  which is met when  $SHQ^T = 0$
  - (iii) The matrix  $S$  is chosen such that  $E(Sy) = 0$  which means  $SX = 0$
  - (iv) The matrix  $QX$  is of rank  $t$ , so that every linear function of the elements of  $Qy$  estimate a linear function of  $b$ .

## REML II

- ▶ From (i) and (ii) it follows that the likelihood  $L$  of  $y$  is the product of the likelihoods of  $Sy$  ( $L^*$ ) and  $Qy$  ( $L^{**}$ ) that means

$$\lambda = \lambda^* + \lambda^{**}$$

- ▶ Variance components are estimated from  $\lambda^*$  which will then be independent of  $b$



# Bayesian Estimation

- ▶ Proposed already in the 80's
- ▶ Full implementation only in 1993
- ▶ Requirements:
  - ▶ cheap computing and
  - ▶ good pseudo-random number generators
- ▶ Bayesian estimation is based on conditional posterior distribution of unknowns given the knowns
- ▶ Conditional posterior distribution is computed from prior distribution of unknowns times the likelihood

# Model

- Univariate Gaussian linear mixed model

$$y = Xb + Zu + e$$

where

- $y$  vector of observations (length  $n$ )
- $b$  vector of fixed effects (length  $p$ )
- $u$  vector of random breeding values (length  $q$ )
- $e$  vector of random residuals (length  $n$ )
- $X$   $n \times p$  design matrix linking fixed effects to observations
- $Z$   $n \times q$  design matrix linking breeding values to observations

# Likelihood

- Data generating distribution

$$y|b, u, \sigma_e^2 \sim \mathcal{N}(Xb + Zu, I * \sigma_e^2)$$

where  $I$  is a  $n \times n$  identity matrix and  $\sigma_e^2$  is the variance of the random residuals.

# Priors

- ▶ Prior distributions must be specified for all unknowns
- ▶ Unknowns in our example are:  $b$ ,  $u$ ,  $\sigma_e^2$  and  $\sigma_u^2$
- ▶ Prior distribution for
  - ▶  $b$  is flat, i.e.  $p(b) \propto c$
  - ▶  $u$  Normal distribution as  $u|G, \sigma_u^2 \sim N(0, G * \sigma_u^2)$
  - ▶  $\sigma_e^2$  scaled inverse  $\chi^2$ :
$$p(\sigma_e^2 | \nu_e, s_e^2) \propto (\sigma_e^2)^{-\nu_e/2-1} \exp(-\frac{1}{2}\nu_e s_e^2 / \sigma_e^2)$$
  - ▶  $\sigma_u^2$  :  $p(\sigma_u^2 | \nu_u, s_u^2) \propto (\sigma_u^2)^{-\nu_u/2-1} \exp(-\frac{1}{2}\nu_u s_u^2 / \sigma_u^2)$
- ▶  $\nu_e$ ,  $\nu_s$ ,  $s_e^2$  and  $s_u^2$  are called hyper-parameters and must be determined

## Additional Terms

► Let

$$\theta^T = (b^T, u^T) = (\theta_1, \theta_2, \dots, \theta_N)$$

$$\theta_{-i} = (\theta_1, \theta_2, \dots, \theta_{i-1}, \theta_{i+1}, \dots, \theta_N)$$

► Further, let

$$s^T = (s_u^2, s_e^2)$$

and

$$\nu^T = (\nu_u, \nu_e)$$

## Joint Posterior Density

The joint posterior distribution can be written as

$$p(\theta, \sigma_u^2, \sigma_e^2 | y, s, \nu) \propto p(\theta) * p(\sigma_u^2 | \nu_u, s_u^2) * p(\sigma_e^2 | \nu_e, s_e^2) * p(y | \theta, \sigma_e^2)$$

# Fully Conditional Posterior Densities of $\theta$

- Density of every single unknown component when setting all other components as known

$$\theta_i | y, \theta_{-i}, \sigma_u^2, \sigma_e^2, s, \nu \sim \mathcal{N}(\tilde{\theta}_i, \tilde{v}_i)$$

where  $\tilde{\theta}_i = (r_i - \sum_{j=1, j \neq i}^N w_{ij} \theta_j) / w_{ii}$  and  $\tilde{v}_i = \sigma_e^2 / w_{ii}$ .

- vector  $r$  is the vector of right-hand side of MME
- matrix  $W$  is the coefficient matrix of MME

# Fully Conditional Posterior Densities of $\sigma_e^2$

- ▶ scaled inverted chi-square distribution for  $\sigma_e^2$

$$\sigma_e^2 | y, \theta, \sigma_u^2, s, \nu \sim \tilde{\nu}_e \tilde{s}_e^2 \chi_{\tilde{\nu}_e}^{-2}$$

- ▶ Parameters of the above distribution are defined as

$$\tilde{\nu}_e = n + \nu_e$$

and

$$\tilde{s}_e^2 = \left[ (y - Xb - Zu)^T (y - Xb - Zu) + \nu_e s_e^2 \right] / \tilde{\nu}_e$$



## Fully Conditional Posterior Densities of $\sigma_u^2$

- ▶ scaled inverted chi-square distribution for  $\sigma_u^2$

$$\sigma_u^2 | y, \theta, \sigma_e^2, s, \nu \sim \tilde{\nu}_u \tilde{s}_u^2 \chi_{\tilde{\nu}_u}^{-2}$$

- ▶ Parameters of the above distribution are defined as

$$\tilde{\nu}_u = q + \nu_u$$

and

$$\tilde{s}_u^2 = \left[ u^T G^{-1} u + \nu_u s_u^2 \right] / \tilde{\nu}_u$$

# Implementation

- ▶ Step 1: set starting values for  $\theta$ ,  $\sigma_e^2$  and  $\sigma_u^2$
- ▶ Step 2: draw random number for each component  $\theta_i$  of  $\theta$  from fully conditional distribution  $\mathcal{N}(\tilde{\theta}_i, \tilde{v}_i)$
- ▶ Step 3: draw random number for  $\sigma_e^2$  from  $\tilde{\nu}_e \tilde{s}_e^2 \chi_{\tilde{\nu}_e}^{-2}$
- ▶ Step 4: draw random number for  $\sigma_u^2$  from  $\tilde{\nu}_u \tilde{s}_u^2 \chi_{\tilde{\nu}_u}^{-2}$
- ▶ Repeat steps 2-4 many times and store random numbers
- ▶ Step 5: compute means of random numbers to get Bayesian estimates of unknowns  $\theta$ ,  $\sigma_e^2$  and  $\sigma_u^2$